

# Multi-Phase Synchronous-Rectified Buck Controller for Next Generation CPU Core Power

## General Description

The uP6213A/B is a multi-phase synchronous-rectified Buck controller specifically designed to deliver high quality output voltage for high-performance Intel microprocessors. It integrates a 8-bit DAC that supports Intel VR10 and VR11 tables to set the output voltage between 0.5V and 1.6V.

The uP6213A provides programmable 3/4 phase operation. The uP6213B provides programmable 1/2 phase operation. The uP6213A/B also supports dynamic phase selection by PS1/2/3 pins. Operation with phase reduction at light load conditions achieves high efficiency over a wide range of output current.

The uP6213A/B includes programmable no-load offset and droop slope functions to adjust the output voltage as a function of the load current, optimally positioning it for a system transient.

Other features include accurate and reliable short-circuit protection, adjustable over current protection, and a delayed power OK output. The uP6213A is available in VQFN6x6-40L package and uP6213B in VQFN4x4-28L package.

## Ordering Information

Order Number	Package Type	Remark
uP6213AQAJ	VQFN6x6 - 40L	3/4 phase operation
uP6213BQJH	VQFN4x4 - 28L	1/2 phase operation

Note: uPI products are compatible with the current IPC/ JEDEC J-STD-020 requirements. They are halogen-free, RoHS compliant and 100% matte tin (Sn) plating that are suitable for use in SnPb or Pb-free soldering processes.

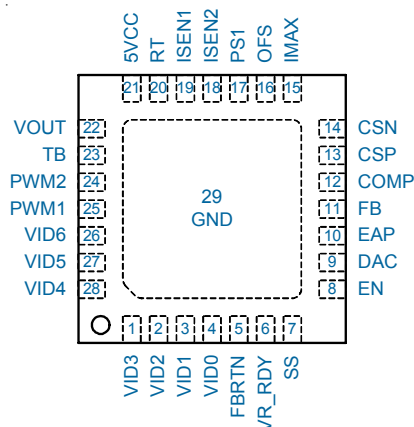
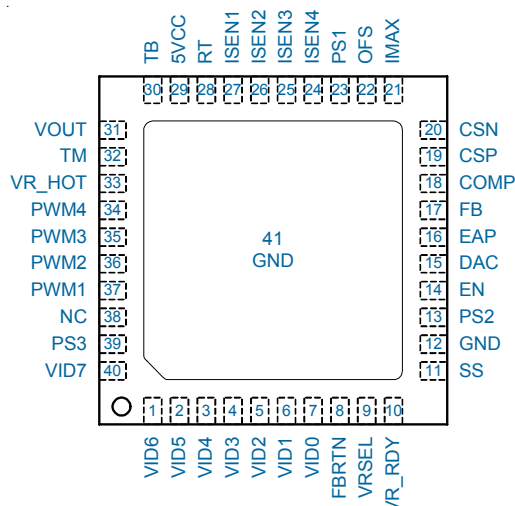
## Features

- Selectable Phase Number of Operation
  - uP6213A: 3/4 Phase
  - uP6213B: 1/2 Phase
- 8-bit DAC, Supporting Intel VR10 and VR11 CPUs
- Programmable Dynamic Power Saving Mode Operation
- Simple Single-Loop Voltage-Mode Control
- Lossless  $R_{DS(ON)}$  Current Sensing for Current Balance
- Adjustable Operation Frequency form 50kHz to 1MHz Per Phase
- External Compensation
- Adjustable Over Current Protection
- Adjustable Soft Start
- VR\_HOT and VR\_RDY Indication
- uP6213A in VQFN6x6 - 40L Package
- uP6213B in VQFN4x4 - 28L Package
- RoHS Compliant and 100% Lead (Pb)-Free

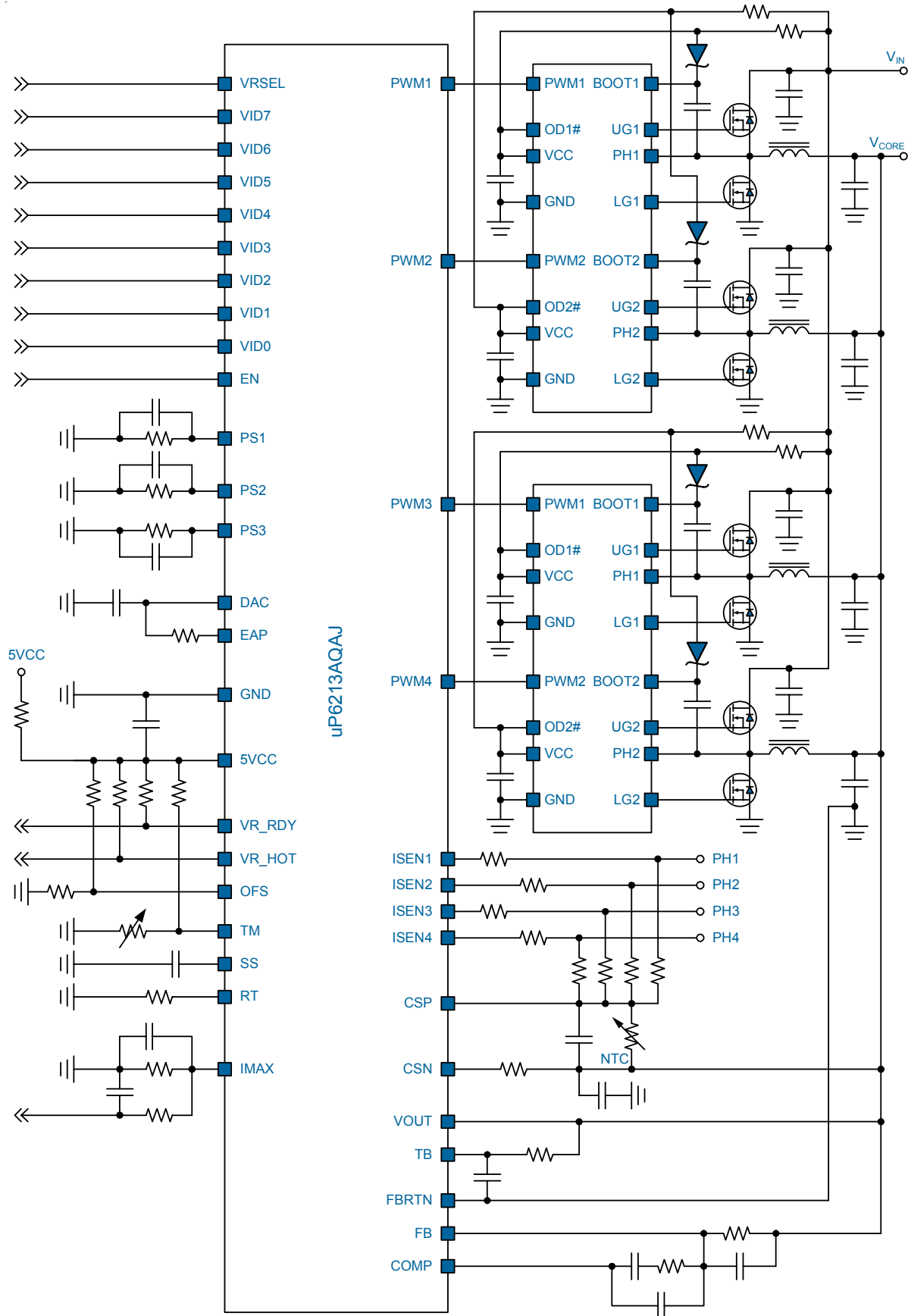
## Applications

- Desktop PC Core Power Supplies
- Middle/High End Graphic Cards
- Low Output Voltage, High Power Density DC/DC Converters
- Voltage Regulator Modules

## Pin Configuration



## Typical Application Circuit



### Typical Application Circuit



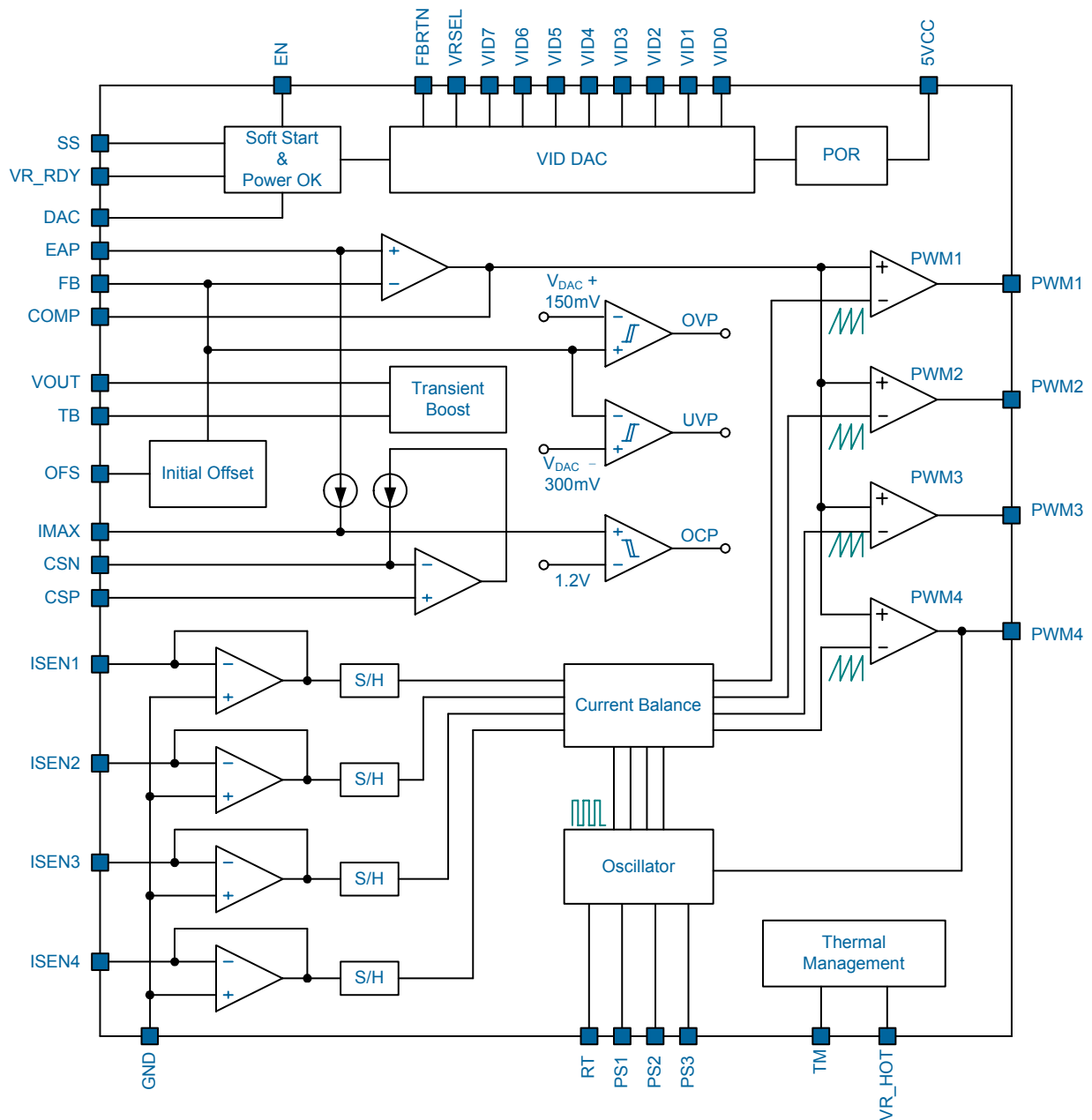
## Functional Pin Description

No.		Name	Pin Function
VQFN6x6	VQFN4x4		
1	26	VID6	Bit 6 of DAC Input.
2	27	VID5	Bit 5 of DAC Input.
3	28	VID4	Bit 4 of DAC Input.
4	1	VID3	Bit 3 of DAC Input.
5	2	VID2	Bit 2 of DAC Input.
6	3	VID1	Bit 1 of DAC Input.
7	4	VID0	Bit 0 of DAC Input.
8	5	FBRTN	<b>Return for the DAC Circuit.</b> Connect this pin to the point where output voltage is to be regulated.
9	NA	VRSEL	<b>VID Table Selection.</b> Connect this pin to 5VCC for VR11 VID table, and to GND for VR10 VID table.
10	6	VR_RDY	<b>VR Ready Indication.</b>
11	7	SS	<b>Soft Start.</b> Connect a capacitor from this pin to GND to set the soft start time.
12	NA	GND	<b>Ground.</b>
13	NA	PS2	<b>Power Saving Mode Setting Input 2.</b> Connect a resistor from this pin to GND to set the phase reduction threshold level.
14	8	EN	<b>Chip Enable.</b> Pulling this pin lower than 0.4V shuts down the device.
15	9	DAC	<b>DAC Output.</b> Output of the internal DAC. Connect a resistor from this pin to EAP to set the load line slope.
16	10	EAP	<b>Non-Inverting Input of the Error Amplifier.</b> Connect a resistor from this pin to DAC to set the load line slope.
17	11	FB	<b>Feedback Pin.</b> This pin is the inverting input of the error amplifier.
18	12	COMP	<b>Compensation Output.</b> This pin is the output of the error amplifier
19	13	CSP	<b>Positive Input of the Current Sensing GM Amplifier.</b>
20	14	CSN	<b>Negative Input of the Current Sensing GM Amplifier.</b>

## Functional Pin Description

Pin No.		Name	Pin Function
VQFN6x6	VQFN4x4		
21	15	IMAX	<b>Output Current Indication.</b> Connect a resistor from this pin to GND to set the over current protection level.
22	16	OFS	<b>Zero Current Offset.</b> Connect a resistor from this pin to 5VCC or GND to set the output offset voltage.
23	17	PS1	<b>Power Saving Mode Setting Input 1.</b> Connect a resistor from this pin to ground to set the phase reduction threshold level.
24	NA	ISEN4	<b>Current Sensing for Phase4.</b>
25	NA	ISEN3	<b>Current Sensing for Phase 3.</b>
26	18	ISEN2	<b>Current Sensing for Phase 2.</b>
27	19	ISEN1	<b>Current Sensing for Phase 1.</b>
28	20	RT	<b>Switching Frequency Programming.</b> Connect a resistor from this pin to GND to set the switching frequency.
29	21	5VCC	<b>5V Supply Input.</b> This pin receives a 5V voltage source to power the control circuit. Connect this pin to ATX 5VCC.
30	23	TB	<b>Transient Boost.</b> This pin along with the VOUT pin set the transient boost behavior.
31	22	VOUT	<b>Output Voltage Sensing.</b> This pin along with the TB pin set the transient boost behavior.
32	NA	TM	<b>Thermal Monitoring.</b> Connect NTC network to this pin for thermal monitoring.
33	NA	VR_HOT	<b>VR HOT Output.</b>
34	NA	PWM4	<b>PWM Output of Phase 4.</b> Connect this pin to input pin of the companion gate driver, such as uP6281.
35	NA	PWM3	<b>PWM Output of Phase 3.</b> Connect this pin to input pin of the companion gate driver, such as uP6281.
36	24	PWM2	<b>PWM Output of Phase 2.</b> Connect this pin to input pin of the companion gate driver, such as uP6281.
37	25	PWM1	<b>PWM Output of Phase 1.</b> Connect this pin to input pin of the companion gate driver, such as uP6281.
38	NA	NC	<b>Not Internally Connected.</b>
39	NA	PS3	<b>Power Saving Mode Setting Input 3.</b> Connect a resistor from this pin to GND to set the phase reduction threshold level.
40	NA	VID7	<b>Bit 7 of DAC Input.</b> This pin is internally pulled high for uP6213B.
Exposed Pad GND			<b>Ground.</b> Tie this pin to the ground island/plane through the lowest impedance connection available.

**Functional Block Diagram**



## Functional Description

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The uP6213A provides programmable 3/4 phase operation. The uP6213B provides programmable 1/2 phase operation. The uP6213A/B also supports dynamic phase selection by PS1/2/3 pins. Operation with phase reduction at light load conditions achieves high efficiency over a wide range of output current.

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### Supply Input and Power on Reset

The 5VCC pin receives a well-decoupled 5V voltage source to power the internal control circuit. Place a minimum 1uF ceramic capacitor physically near the 5VCC pin for locally bypassing the 5VCC voltage. The 5VCC voltage is continuously monitored for power on reset. The POR level is typical 4.2V at 5VCC rising.

### Operation Phase Selection

The uP6213A supports 3/4 phase operation and uP6213B supports 1/2 phase operation. PWM4 and PWM2 status is checked at POR for operation phase selection. Connect PWM4 to 5VCC for 3-phase operation of uP6213A and connect PWM2 to 5VCC for 1-phase operation of uP6213B. Let the unused current sensing pins ISEN4 or ISEN2 float or short them to GND when selecting 3/1-phase operation. (See the related section for Dynamic Phase Reduction.)

### VID Table Selection

The uP6213A supports both VR10 and VR11 VID tables. Pulling the VRSEL pin lower than 0.4V select VR10 table as shown in Table 2 while pulling the VRSEL pin higher than 0.8V select the VR11 table as shown in Table 1. The uP6213B supports only VR11 table with VID7 = High.

### Oscillation Frequency Programming

A resistor  $R_{RT}$  connected to RT pin programs the oscillation frequency as:

$$f_{OSC} = 300 \left( \frac{33k\Omega}{R_{RT}(k\Omega)} \right)^{0.92} \quad (kHz)$$

Figure 1 shows the relationship between oscillation frequency and  $R_{RT}$ .

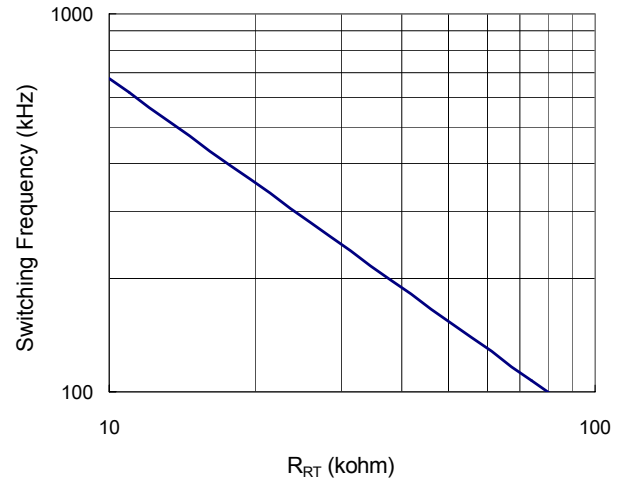


Figure 1. Switching Frequency vs.  $R_{RT}$

### Output Current Sensing

Figure 2 illustrates the output current sensing block of the uP6213A/B. The voltage  $V_{CS}$  across the current sensing capacitor  $C_{CS}$  can be expressed as:

$$V_{CS} = I_{OUT} \times DCR/P$$

if the following condition is true.

$$P \times L / DCR = R_{CSP} \times C_{CS}$$

where  $P$  is the phase number of operation ( $P = 3$  for three phase operation,  $P = 4$  for four phase operation),  $L$  is the output inductor of the buck converter,  $DCR$  is the parasitic resistance of the inductor,  $R_{CSP}$  and  $C_{CS}$  are the external RC network for current sensing.

The GM amplifier will source a current  $I_{AVG}$  to the CSN pin to let its inputs virtually short circuit.

$$I_{AVG} \times R_{CSN} = V_{CS}$$

Therefore the output current signal  $I_{AVG}$  can be expressed as:

$$I_{AVG} = \frac{I_{OUT} \times DCR}{P \times R_{CSN}}$$

The output current signal  $I_{AVG}$  is used as droop turning and output over current protection. Please see the related section for details.

**Note that the constant  $P$  is only dependent of the power stage topology. It is programmed by the PWM4/PWM2 configuration. Dynamic phase reduction will not affect the value of  $P$ .**

## Functional Description

Table 1. VR11 VID Table (VRSEL = 5VCC)

VID7	VID6	VID5	VID4	VID3	VID2	VID1	VID0	Voltage
0	0	0	0	0	0	0	0	OFF
0	0	0	0	0	0	0	1	OFF
0	0	0	0	0	0	1	0	1.60000
0	0	0	0	0	0	1	1	1.59375
0	0	0	0	0	1	0	0	1.58750
0	0	0	0	0	1	0	1	1.58125
0	0	0	0	0	1	1	0	1.57500
0	0	0	0	0	1	1	1	1.56875
0	0	0	0	1	0	0	0	1.56250
0	0	0	0	1	0	0	1	1.55625
0	0	0	0	1	0	1	0	1.55000
0	0	0	0	1	0	1	1	1.54375
0	0	0	0	1	1	0	0	1.53750
0	0	0	0	1	1	0	1	1.53125
0	0	0	0	1	1	1	0	1.52500
0	0	0	0	1	1	1	1	1.51875
0	0	0	1	0	0	0	0	1.51250
0	0	0	1	0	0	0	1	1.50625
0	0	0	1	0	0	1	0	1.50000
0	0	0	1	0	0	1	1	1.49375
0	0	0	1	0	1	0	0	1.48750
0	0	0	1	0	1	0	1	1.48125
0	0	0	1	0	1	1	0	1.47500
0	0	0	1	0	1	1	1	1.46875
0	0	0	1	1	0	0	0	1.46250
0	0	0	1	1	0	0	1	1.45625
0	0	0	1	1	0	1	0	1.45000
0	0	0	1	1	0	1	1	1.44375
0	0	0	1	1	1	0	0	1.43750
0	0	0	1	1	1	0	1	1.43125
0	0	0	1	1	1	1	0	1.42500
0	0	0	1	1	1	1	1	1.41875
0	0	1	0	0	0	0	0	1.41250
0	0	1	0	0	0	0	1	1.40625
0	0	1	0	0	0	1	0	1.40000
0	0	1	0	0	0	1	1	1.39375
0	0	1	0	0	1	0	0	1.38750
0	0	1	0	0	1	0	1	1.38125
0	0	1	0	0	1	1	0	1.37500
0	0	1	0	0	1	1	1	1.36875
0	0	1	0	1	0	0	0	1.36250
0	0	1	0	1	0	0	1	1.35625
0	0	1	0	1	0	1	0	1.35000
0	0	1	0	1	0	1	1	1.34375
0	0	1	0	1	1	0	0	1.33750

Table 1. VR11 VID Table (Cont.) (VRSEL = 5VCC)

VID7	VID6	VID5	VID4	VID3	VID2	VID1	VID0	Voltage
0	0	1	0	1	1	0	1	1.33125
0	0	1	0	1	1	1	0	1.32500
0	0	1	0	1	1	1	1	1.31875
0	0	1	1	0	0	0	0	1.31250
0	0	1	1	0	0	0	1	1.30625
0	0	1	1	0	0	1	0	1.30000
0	0	1	1	0	0	1	1	1.29375
0	0	1	1	0	1	0	0	1.28750
0	0	1	1	0	1	0	1	1.28125
0	0	1	1	0	1	1	0	1.27500
0	0	1	1	0	1	1	1	1.26875
0	0	1	1	1	0	0	0	1.26250
0	0	1	1	1	0	0	1	1.25625
0	0	1	1	1	0	1	0	1.25000
0	0	1	1	1	0	1	1	1.24375
0	0	1	1	1	1	0	0	1.23750
0	0	1	1	1	1	0	1	1.23125
0	0	1	1	1	1	1	0	1.22500
0	0	1	1	1	1	1	1	1.21875
0	1	0	0	0	0	0	0	1.21250
0	1	0	0	0	0	0	1	1.20625
0	1	0	0	0	0	1	0	1.20000
0	1	0	0	0	0	1	1	1.19375
0	1	0	0	0	1	0	0	1.18750
0	1	0	0	0	1	0	1	1.18125
0	1	0	0	0	1	1	0	1.17500
0	1	0	0	0	1	1	1	1.16875
0	1	0	0	1	0	0	0	1.16250
0	1	0	0	1	0	0	1	1.15625
0	1	0	0	1	0	1	0	1.15000
0	1	0	0	1	0	1	1	1.14375
0	1	0	0	1	1	0	0	1.13750
0	1	0	0	1	1	0	1	1.13125
0	1	0	0	1	1	1	0	1.12500
0	1	0	0	1	1	1	1	1.11875
0	1	0	1	0	0	0	0	1.11250
0	1	0	1	0	0	0	1	1.10625
0	1	0	1	0	0	1	0	1.10000
0	1	0	1	0	0	1	1	1.09375
0	1	0	1	0	1	0	0	1.08750
0	1	0	1	0	1	0	1	1.08125
0	1	0	1	0	1	1	0	1.07500
0	1	0	1	0	1	1	1	1.06875
0	1	0	1	1	0	0	0	1.06250
0	1	0	1	1	0	0	1	1.05625

## Functional Description

Table 1. VR11 VID Table (Cont.) (VRSEL = 5VCC)

VID7	VID6	VID5	VID4	VID3	VID2	VID1	VID0	Voltage
0	1	0	1	1	0	1	0	1.05000
0	1	0	1	1	0	1	1	1.04375
0	1	0	1	1	1	0	0	1.03750
0	1	0	1	1	1	0	1	1.03125
0	1	0	1	1	1	1	0	1.02500
0	1	0	1	1	1	1	1	1.01875
0	1	1	0	0	0	0	0	1.01250
0	1	1	0	0	0	0	1	1.00625
0	1	1	0	0	0	1	0	1.00000
0	1	1	0	0	0	1	1	0.99375
0	1	1	0	0	1	0	0	0.98750
0	1	1	0	0	1	0	1	0.98125
0	1	1	0	0	1	1	0	0.97500
0	1	1	0	0	1	1	1	0.96875
0	1	1	0	1	0	0	0	0.96250
0	1	1	0	1	0	0	1	0.95625
0	1	1	0	1	0	1	0	0.95000
0	1	1	0	1	0	1	1	0.94375
0	1	1	0	1	1	0	0	0.93750
0	1	1	0	1	1	0	1	0.93125
0	1	1	0	1	1	1	0	0.92500
0	1	1	0	1	1	1	1	0.91875
0	1	1	1	0	0	0	0	0.91250
0	1	1	1	0	0	0	1	0.90625
0	1	1	1	0	0	1	0	0.90000
0	1	1	1	0	0	1	1	0.89375
0	1	1	1	0	1	0	0	0.88850
0	1	1	1	0	1	0	1	0.88125
0	1	1	1	0	1	1	0	0.87500
0	1	1	1	0	1	1	1	0.86875
0	1	1	1	1	0	0	0	0.86250
0	1	1	1	1	0	0	1	0.85625
0	1	1	1	1	0	1	0	0.85000
0	1	1	1	1	0	1	1	0.84375
0	1	1	1	1	1	0	0	0.83750
0	1	1	1	1	1	0	1	0.83125
0	1	1	1	1	1	1	0	0.82500
0	1	1	1	1	1	1	1	0.81875
1	0	0	0	0	0	0	0	0.81250
1	0	0	0	0	0	0	1	0.80625
1	0	0	0	0	0	1	0	0.80000
1	0	0	0	0	0	1	1	0.79375
1	0	0	0	0	1	0	0	0.78750
1	0	0	0	0	1	0	1	0.78125
1	0	0	0	0	1	1	0	0.77500

Table 1. VR11 VID Table (Cont.) (VRSEL = 5VCC)

VID7	VID6	VID5	VID4	VID3	VID2	VID1	VID0	Voltage
1	0	0	0	0	1	1	1	0.76875
1	0	0	0	1	0	0	0	0.76250
1	0	0	0	1	0	0	1	0.75625
1	0	0	0	1	0	1	0	0.75000
1	0	0	0	1	0	1	1	0.74375
1	0	0	0	1	1	0	0	0.73750
1	0	0	0	1	1	0	1	0.73125
1	0	0	0	1	1	1	0	0.72500
1	0	0	0	1	1	1	1	0.71875
1	0	0	1	0	0	0	0	0.71250
1	0	0	1	0	0	0	1	0.70625
1	0	0	1	0	0	1	0	0.70000
1	0	0	1	0	0	1	1	0.69375
1	0	0	1	0	1	0	0	0.68750
1	0	0	1	0	1	0	1	0.68125
1	0	0	1	0	1	1	0	0.67500
1	0	0	1	0	1	1	1	0.66875
1	0	0	1	1	0	0	0	0.66250
1	0	0	1	1	0	0	1	0.65625
1	0	0	1	1	0	1	0	0.65000
1	0	0	1	1	0	1	1	0.64375
1	0	0	1	1	1	0	0	0.63750
1	0	0	1	1	1	0	1	0.63125
1	0	0	1	1	1	1	0	0.62500
1	0	0	1	1	1	1	1	0.61875
1	0	1	0	0	0	0	0	0.61250
1	0	1	0	0	0	0	1	0.60625
1	0	1	0	0	0	1	0	0.60000
1	0	1	0	0	0	1	1	0.59375
1	0	1	0	0	1	0	0	0.58750
1	0	1	0	0	1	0	1	0.58125
1	0	1	0	0	1	1	0	0.57500
1	0	1	0	0	1	1	1	0.56875
1	0	1	0	1	0	0	0	0.56250
1	0	1	0	1	0	0	1	0.55625
1	0	1	0	1	0	1	0	0.55000
1	0	1	0	1	0	1	1	0.54375
1	0	1	0	1	1	0	0	0.53750
1	0	1	0	1	1	0	1	0.53125
1	0	1	0	1	1	1	0	0.52500
1	0	1	0	1	1	1	1	0.51875
1	0	1	1	0	0	0	0	0.51250
1	0	1	1	0	0	0	1	0.50625
1	0	1	1	0	0	1	0	0.50000
1	1	1	1	1	1	1	0	OFF
1	1	1	1	1	1	1	1	OFF

## Functional Description

Table 1. VRD10 + VID6 VID Table (VRSEL = GND)

VID4	VID3	VID2	VID1	VID0	VID5	VID6	Voltage
0	1	0	1	0	1	1	1.60000
0	1	0	1	0	1	0	1.59375
0	1	0	1	1	0	1	1.58750
0	1	0	1	1	0	0	1.58125
0	1	0	1	1	1	1	1.57500
0	1	0	1	1	1	0	1.56875
0	1	1	0	0	0	1	1.56250
0	1	1	0	0	0	0	1.55625
0	1	1	0	0	1	1	1.55000
0	1	1	0	0	1	0	1.54375
0	1	1	0	1	0	1	1.53750
0	1	1	0	1	0	0	1.53125
0	1	1	0	1	1	1	1.52500
0	1	1	0	1	1	0	1.51875
0	1	1	1	0	0	1	1.51250
0	1	1	1	0	0	0	1.50625
0	1	1	1	0	1	1	1.50000
0	1	1	1	0	1	0	1.49375
0	1	1	1	1	0	1	1.48750
0	1	1	1	1	0	0	1.48125
0	1	1	1	1	1	1	1.47500
0	1	1	1	1	1	0	1.46875
1	0	0	0	0	0	1	1.46250
1	0	0	0	0	0	0	1.45625
1	0	0	0	0	1	1	1.45000
1	0	0	0	0	1	0	1.44375
1	0	0	0	1	0	1	1.43750
1	0	0	0	1	0	0	1.43125
1	0	0	0	1	1	1	1.42500
1	0	0	0	1	1	0	1.41875
1	0	0	1	0	0	1	1.41250
1	0	0	1	0	0	0	1.40625
1	0	0	1	0	1	1	1.40000
1	0	0	1	0	1	0	1.39375
1	0	0	1	1	0	1	1.38750
1	0	0	1	1	0	0	1.38125
1	0	0	1	1	1	1	1.37500
1	0	0	1	1	1	0	1.36875
1	0	1	0	0	0	1	1.36250
1	0	1	0	0	0	0	1.35625
1	0	1	0	0	1	1	1.35000
1	0	1	0	0	1	0	1.34375
1	0	1	0	1	0	1	1.33750
1	0	1	0	1	0	0	1.33125
1	0	1	0	1	1	1	1.32500
1	0	1	0	1	1	0	1.31875

Table 1. VRD10 + VID6 VID Table (Cont.) (VRSEL = GND)

VID4	VID3	VID2	VID1	VID0	VID5	VID6	Voltage
1	0	1	1	0	0	1	1.31250
1	0	1	1	0	0	0	1.30625
1	0	1	1	0	1	1	1.30000
1	0	1	1	0	1	0	1.29375
1	0	1	1	1	0	1	1.28750
1	0	1	1	1	0	0	1.28125
1	0	1	1	1	1	1	1.27500
1	0	1	1	1	1	0	1.26875
1	1	0	0	0	0	1	1.26250
1	1	0	0	0	0	0	1.25625
1	1	0	0	0	1	1	1.25000
1	1	0	0	0	1	0	1.24375
1	1	0	0	1	0	1	1.23750
1	1	0	0	1	0	0	1.23125
1	1	0	0	1	1	1	1.22500
1	1	0	0	1	1	0	1.21875
1	1	0	1	0	0	1	1.21250
1	1	0	1	0	0	0	1.20625
1	1	0	1	0	1	1	1.20000
1	1	0	1	0	1	0	1.19375
1	1	0	1	1	0	1	1.18750
1	1	0	1	1	0	0	1.18125
1	1	0	1	1	1	1	1.17500
1	1	0	1	1	1	0	1.16875
1	1	1	0	0	0	1	1.16250
1	1	1	0	0	0	0	1.15625
1	1	1	0	0	1	1	1.15000
1	1	1	0	0	1	0	1.14375
1	1	1	0	1	0	1	1.13750
1	1	1	0	1	0	0	1.13125
1	1	1	0	1	1	1	1.12500
1	1	1	0	1	1	0	1.11875
1	1	1	1	0	0	1	1.11250
1	1	1	1	0	0	0	1.10625
1	1	1	1	0	1	1	1.10000
1	1	1	1	0	1	0	1.09375
1	1	1	1	1	0	1	OFF
1	1	1	1	1	0	0	OFF
1	1	1	1	1	1	1	OFF
1	1	1	1	1	1	0	OFF
0	0	0	0	0	0	1	1.08750
0	0	0	0	0	0	0	1.08125
0	0	0	0	0	1	1	1.07500
0	0	0	0	0	1	0	1.06875
0	0	0	0	1	0	1	1.06250
0	0	0	0	1	0	0	1.05625

## Functional Description

Table 1. VRD10 + VID6 VID Table (Cont.) (VRSEL = GND)

VID4	VID3	VID2	VID1	VID0	VID5	VID6	Voltage
0	0	0	0	1	1	1	1.05000
0	0	0	0	1	1	0	1.04375
0	0	0	1	0	0	1	1.03750
0	0	0	1	0	0	0	1.03125
0	0	0	1	0	1	1	1.02500
0	0	0	1	0	1	0	1.01875
0	0	0	1	1	0	1	1.01250
0	0	0	1	1	0	0	1.00625
0	0	0	1	1	1	1	1.00000
0	0	0	1	1	1	0	0.99375
0	0	1	0	0	0	1	0.98750
0	0	1	0	0	0	0	0.98125
0	0	1	0	0	1	1	0.97500
0	0	1	0	0	1	0	0.96875
0	0	1	0	1	0	1	0.96250
0	0	1	0	1	0	0	0.95625
0	0	1	0	1	1	1	0.95000
0	0	1	0	1	1	0	0.94375
0	0	1	1	0	0	1	0.93750
0	0	1	1	0	0	0	0.93125
0	0	1	1	0	1	1	0.92500
0	0	1	1	0	1	0	0.91875
0	0	1	1	1	0	1	0.91250
0	0	1	1	1	0	0	0.90625
0	0	1	1	1	1	1	0.90000
0	0	1	1	1	1	0	0.89375
0	1	0	0	0	0	1	0.89750
0	1	0	0	0	0	0	0.88125
0	1	0	0	0	1	1	0.87500
0	1	0	0	0	1	0	0.86875
0	1	0	0	1	0	1	0.86250
0	1	0	0	1	0	0	0.85625
0	1	0	0	1	1	1	0.85000
0	1	0	0	1	1	0	0.84375
0	1	0	1	0	0	1	0.83750
0	1	0	1	0	0	0	0.83125

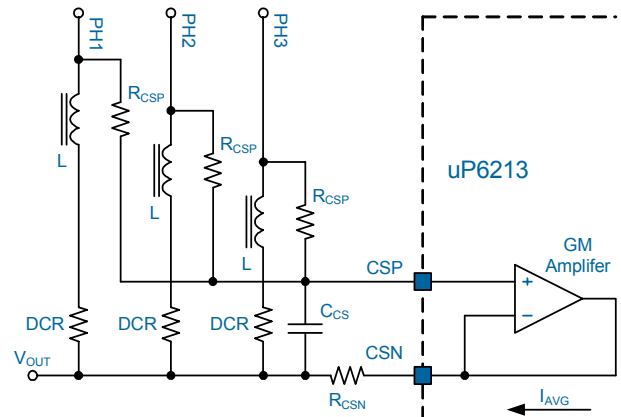


Figure 2. Output Current Sensing of uP6213A/B.

### Voltage Control Loop

Figure 3 illustrates the voltage control loop of the uP6213A/B. FB and EAP are negative and positive inputs of the Error Amplifier respectively. The Error Amplifier modulates the COMP voltage  $V_{COMP}$  and the duty cycle of buck converter to force FB voltage  $V_{FB}$  follows  $V_{EAP}$ .

As shown in Figure 3,  $V_{DAC}$  is output of the internal VID table. The slew rate of  $V_{DAC}$  is limited by the capacitor connected to SS pin during soft start and VID on the fly transition. The sensed current signal is mirrored to the EAP pin and creates voltage at EAP pin as:

$$V_{EAP} = V_{DAC} - R_{DRP} \times I_{AVG}$$

where  $V_{DAC}$  is a slew rate limited voltage source,  $I_{AVG}$  is a current source proportional to output current, and  $R_{DRP}$  is an external resistor for adjusting load line slope.

On the other hand, the inverting input voltage  $V_{FB}$  can be written as:

$$V_{FB} = V_{OUT} - R_{FB} \times I_{OFS}$$

where  $V_{OUT}$  is the output voltage,  $I_{OFS}$  is a current source for initial offset adjustment,  $R_{OFS}$  is an external resistor.

Therefore, the output voltage will be:

$$V_{OUT} = V_{DAC} - R_{DRP} \times I_{AVG} + R_{FB} \times I_{OFS}$$

$$V_{OUT} = V_{DAC} - \frac{I_{OUT} \times DCR \times R_{DRP}}{P \times R_{CSN}} + R_{FB} \times I_{OFS}$$

Please see the related section for details.

## Functional Description

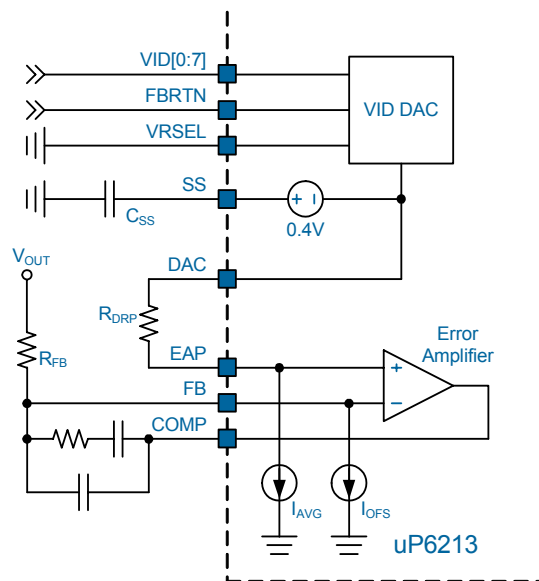


Figure 3. Voltage Control Loop.

## Initial Offset Adjustment

Connect a resistor  $R_{OFS}$  from OFS pin to 5VCC or GND to set the initial offset voltage. The OFS voltage  $V_{OFS}$  is  $5_{VCC} - 1.6V$  or  $0.4V$  when connected to 5VCC or GND respectively. There the current source  $I_{OFS}$  can be calculated as:

$$I_{OES} = 0.4V / R_{OES} \text{ sourcing, } R_{OES} \text{ to GND, positive offset}$$

$$I_{OES} = 1.6V / R_{OES} \text{ sinking, } R_{OES} \text{ to } 5VCC, \text{ negative offset.}$$

The offset current source  $I_{\text{OFS}}$  is mirrored and injected to FB pin for initial offset adjustment. Please see the *Voltage Control Loop* section for details.

## Soft Start and Power OK

Figure 4 illustrates typical VR11 compliant soft start cycle of uP6213A/B. A capacitor  $C_{SS}$  connected to SS pin is used to adjust the soft start cycle.

A limited current source  $I_{SS}$  is used to charge/discharge  $C_{SS}$  when  $V_{ID}$  changes. Since  $V_{DAC}$  is 0.4V higher than  $V_{SS}$ , this limit the slew rate of  $V_{SS}$  and  $V_{DAC}$  during soft start and  $V_{ID}$  on the fly period. This consequently limits the output voltage ramp up/down slew rate.

The uP6213A/B is POR and enabled at T0. There is a 800us time delay (T0 ~ T1) before the current source  $I_{SS}$  begins charging the  $C_{SS}$ . The DAC voltage  $V_{DAC}$  and output voltage  $V_{OUT}$  is kept zero during (T0 ~ T2). The  $V_{DAC}$  and  $V_{OUT}$  ramps up to boot up voltage  $V_{BOOT}$  during time delay TD2. The uP6213A/B inserts a time delay TD3 for the VID to get valid. The  $V_{DAC}$  and  $V_{OUT}$  ramps to its target value according to VID status during TD4. The uP6213A/B asserts soft start end and set VR\_RDY to high impedance status at T6.

Before time delay TD3 ends, the  $I_{ss}$  is limited to 10uA. After that, the  $I_{ss}$  is limited to 160uA. Consequently, critical time periods are calculated as:

$$(T2 - T1) = 0.4V \times C_{ss} / 10\mu A$$

$$TD1 = T2 - T0 = 800\mu s + 0.4V \times C_{ss} / 10\mu A$$

$$TD2 = V_{\text{BOOT}} \times C_{\text{SS}} / 10\mu\text{A} = 1.1\text{V} \times C_{\text{SS}} / 10\mu\text{A}$$

$$TD4 = |V_{VID} - V_{BOOT}| / 160\mu A$$

Time Delay ( $T_1 - T_0$ ) = 800us, TD3 = 800us and TD5 = 800us are fixed delay and can not be adjusted externally.

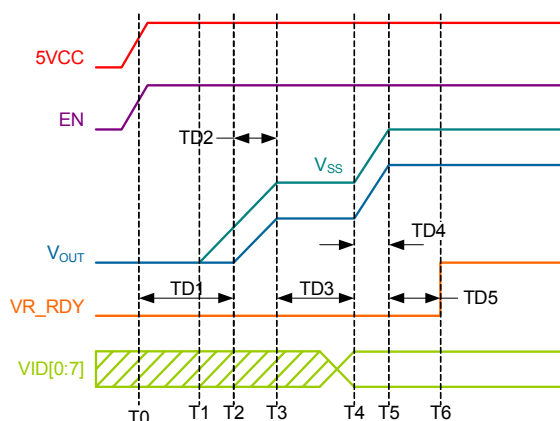


Figure 4. Soft Start Cycle of uP6213.

## Transient Boost Mechanism

The uP6213A/B features a novel transient boost mechanism that turns on all high side MOSFETs during a large step load transient as shown in Figure 5. The V<sub>OUT</sub> and TB are inverting and non-inverting inputs of the transient boost comparator respectively. At steady state, an internal 10uA current source creates a voltage drop between V<sub>OUT</sub> and V<sub>TB</sub>:

$$V_{OUT} - V_{TB} = 10\mu A \times R_{TB}$$

$R_{TB}$  and  $C_{TB}$  form a low pass filter for the  $V_{TB}$ . During large step load transient,  $V_{OUT}$  abruptly drops while the  $V_{TB}$  keeps relatively constant. Once  $V_{OUT}$  is smaller than  $V_{TB}$ , the transient boost mechanism is activated and turns on all high side MOSFETs to provide current to output capacitors as fast as possible.

Select  $R_{TB}$  to decide a suitable threshold level for transient boost. For example, a  $4.7k\Omega$   $R_{TB}$  will triggered the transient boost mechanism if output voltage is abruptly drops by around 50mV. Also keep the  $R_{TB} \times C_{TB}$  time constant around 2us.

## Functional Description

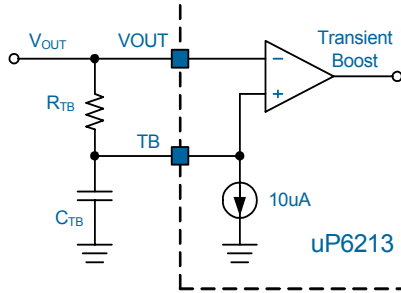


Figure 5. Transient Boost Mechanism

### Channel Current Sensing

The uP6213A/B extracts phase currents for current balance and over current protection by parasitic on-resistance of the lower switches when turn on as shown in Figure 6. The ISEN1/2/3/4 pins sense the corresponding phase current when the low side MOSFETs are turned on.

$$I_{SENX} = ((I_{PHX} \times R_{DS(ON)}) + V_{DC}) / R_{SENX}$$

where  $I_{SENX}$  is the sampled and held phase current signal,  $I_{PHX}$  is phase current,  $R_{DS(ON)}$  is the on-resistance of the low side MOSFETs, and  $V_{DC} = 20mV$  is an offset voltage for the current balance circuit. The current balance circuit increases the duty cycle of the phase whose phase current is smaller than others and decrease the duty cycle of the phase whose phase current is larger than others.

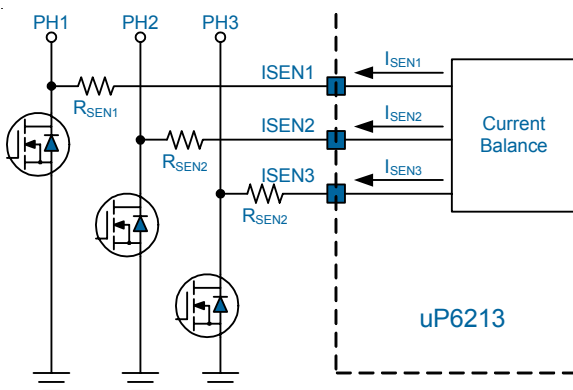


Figure 6. Phase Current Sensing and Current Balance.

Select  $R_{SENX}$  to set the current balance gain. A rule of thumb is to keep  $I_{SENX} = 5uA$  at rated output current.

### Output Over Current Protection

$I_{AVG}$  is mirrored and injected to the IMAX pin and create a voltage  $V_{IMAX}$  at IMAX pin.

$$V_{IMAX} = R_{IMAX} \times I_{AVG} = R_{IMAX} \times I_{OUT} \times DCR / R_{CSN} / P$$

The over current protection is activated and shuts down the uP6213A/B if the IMAX voltage is higher than 1.2V.

### Output Over Voltage Protection

The OVP is activated and turns on the low side MOSFETs if  $(V_{FB} - V_{DAC}) > 160mV$

The uP6213A/B turns on the lower gate drivers when OVP is detected. The over voltage protection is latch-off and can only be reset by POR or toggling the EN pin.

### Under Voltage Protection

The under voltage protection is activated if FB voltage  $V_{FB}$  is 300mV lower than the DAC voltage  $V_{DAC}$ . The uP6213A/B turns off both higher and lower gate drivers when UVP is detected. The under voltage protection is latch-off and can only be reset by POR or toggling the EN pin.

### Operation Phase Selection

The uP6213A/B sources 10uA current sources out of PS1, PS2 and PS3 pins. Connecting resistors  $R_{PS1}$ ,  $R_{PS2}$  and  $R_{PS3}$  at PS1, PS2 and PS3 pins creates voltage levels  $V_{PS1}$ ,  $V_{PS2}$  and  $V_{PS3}$  for power saving mode operation.

$$V_{PS1} = 10uA \times R_{PS1}$$

$$V_{PS2} = 10uA \times R_{PS2}$$

$$V_{PS3} = 10uA \times R_{PS3}$$

Table 3 shows the operation phase of uP6213A according to  $V_{IMAX}$ ,  $V_{PS1}$ ,  $V_{PS2}$ ,  $V_{PS3}$  and PWM3/PWM4 status. The uP6213A/B operates in 4-phase configuration if all PWM outputs are connected to inputs of respective pre-drivers, in 3-phase of PWM4 is connected 5VCC, in 2-phase if PWM3/PWM4 are connected to 5VCC.

The uP6213 also supports dynamic phase-selection according to PS1, PS2 and PS3 status.

Let  $PS1/PS2/PS3 > 0.8V$  to force the uP6213A/B into single phase operation. Let  $PS1/PS2/PS3 < 0.2V$  to force the uP6213A/B into full-phase operation (set by PWM3/PWM4).

### Automatic Phase Reduction

The uP6213A/B compares  $V_{IMX}$  with  $V_{PS1}/V_{PS2}/V_{PS3}$  to decide the operation dynamically. if  $V_{IMX} < V_{PS1}$  the uP6213 operates in single phase regardless the status of  $V_{PS2}$  and  $V_{PS3}$ ; if  $V_{PS1} < V_{IMX} < V_{PS2}$  the uP6213 operates in dual phase regardless the status of  $V_{PS3}$ . Take PWM4 = 5VCC,  $V_{PS1} = 0.2V$ ,  $V_{PS2} = 0.3V$ ,  $V_{PS3} = 0.2V$  and  $V_{IMAX} = 0.25V$  for example, the uP6213 turns off phase 3 and operates the converter in 2-phase.

The uP6213A/B always keeps out-of-phase interleaved operation. When operating in 3 phase, Phase1/2/3 are kept 120° out-of phase. When operating in 2 phase, Phase 1/2 are kept 180° of phase.

**When setting PS1, PS2 and PS3, always keep  $V_{PS1} < V_{PS2}$ ,  $V_{PS3}$  with difference larger than 80mV. Violating**

Table 3. Operation Phase Selection.

		PS1	PS2	PS3	Operation Phase
2-Phase Configuration, PWM3, PWM4 to VCC5	Auto PSI Mode	$PS1 > V_{IMAX}$	open		1
		$V_{IMAX} > PS1$	open		2
	Forced 1 phase	< 0.2V			1
	Forced 2-phase	> 0.8V			2
3-Phase Configuration, PWM4 to VCC5	Auto PSI Mode	$PS2, PS1 > V_{IMAX}$		open	1
		$PS2 > V_{IMAX} > PS1$		open	2
		$V_{IMAX} > PS2, PS1$		open	3
	Forced 1-phase	< 0.2V			1
	Forced 3-phase	> 0.8V			3
4-Phase Configuration	Auto PSI Mode	$PS3, PS2, PS1 > V_{IMAX}$			1
		$PS3, PS2 > V_{IMAX} > PS1$			2
		$PS3 > V_{IMAX} > PS2, PS1$			3
		$V_{IMAX} > PS3, PS2, PS1$			4
	Forced 1-phase	< 0.2V			1
	Forced 4-phase	> 0.8V			4
Always Keep PS1 < PS2 < PS3					

this rule may lead to unknown status and should be avoided.

The automatic phase reduction reduces the switching and conduction losses at light load condition and enables high efficiency over a wide range of output current.

Short PS1, PS2 and PS3 to GND to disable the automatic phase reduction.

#### Temperature Monitoring

The uP6213 monitors the converter temperature at TM pin as shown in Figure 7. VR\_HOT is activated if  $V_{TM} < 28\%$  of 5VCC and sets the VR\_HOT pin high impedance. VR\_HOT is pulled low if  $V_{TM} > 33\%$  of 5VCC.

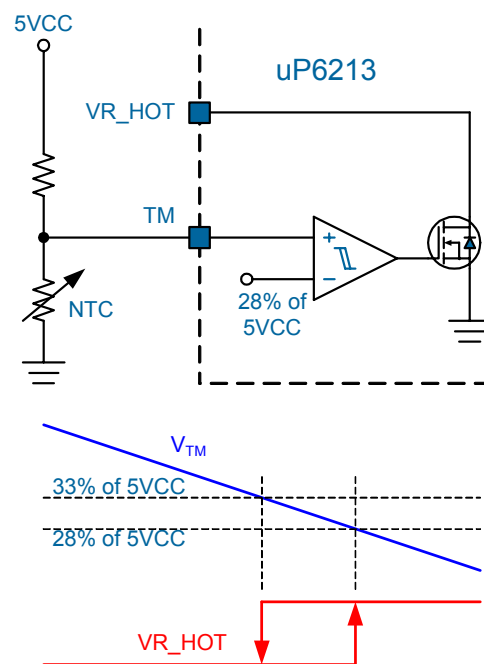


Figure 7. Temperature Monitoring of uP6213.

## Absolute Maximum Rating

Supply Input Voltage, 5VCC (Note 1)	-0.3V to +6V
Other Pins	-0.3V to +5VCC + 0.3V
Storage Temperature Range	-65°C to +150°C
Junction Temperature	150°C
Lead Temperature (Soldering, 10 sec)	260°C
ESD Rating (Note 2)	
HBM (Human Body Mode)	2kV
MM (Machine Mode)	200V

## Thermal Information

Package Thermal Resistance (Note 3)

VQFN6x6 - 40L $\theta_{JA}$	35°C/W
VQFN4x4 - 28L $\theta_{JA}$	40°C/W
VQFN6x6 - 40L $\theta_{JC}$	3°C/W
VQFN4x4 - 28L $\theta_{JC}$	4°C/W

Power Dissipation,  $P_D$  @  $T_A = 25^\circ\text{C}$

VQFN6x6 - 40L	2.8W
VQFN4x4 - 28L	2.5W

## Recommended Operation Conditions

Operating Junction Temperature Range (Note 4)	-40°C to +125°C
Operating Ambient Temperature Range	-40°C to +85°C
Supply Input Voltage, $V_{CC5}$	4.5V to 5.5V

## Electrical Characteristics

(5VCC = 5V,  $T_A = 25^\circ\text{C}$ , unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
<b>Supply Input</b>						
Supply Input Voltage	$V_{CC5}$		4.5	--	5.5	V
Supply Current	$I_{CC5}$	PWMx open; Switching	2	4	6	mA
5VCC POR Threshold	$V_{CC5RTH}$	$V_{CC5}$ Rising.	4.0	4.2	4.4	V
5VCC POR Hysteresis	$V_{CC5HYS}$		--	0.4	--	V
<b>Soft Start</b>						
Soft Start Current	$I_{SS}$	$V_{SS} = 0V$	9.0	10.4	11.8	uA
VID on the Fly Maximum Current	$I_{SS}$		--	160	--	uA
<b>Transient Boost (TB)</b>						
TB Sinking Current	$I_{TB}$		9	10	11	uA
<b>Thermal Management</b>						
VR_HOT Threshold Level			26	28	30	% $V_{CC5}$
VR_HOR Hysteresis			--	5	--	% $V_{CC5}$

## Electrical Characteristics

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
Total Current Sensing						
Maximum Sourcing Current			100	--	--	uA
Input Offset Voltage			-0.4	0.6	1.6	mV
IMAX Current Mirror Accuracy		I <sub>IMAX</sub> /I <sub>AVG</sub>	95	100	105	%
Droop Current Mirror Accuracy		I <sub>DRP</sub> /I <sub>AVG</sub>	95	100	105	%
Enable Control						
Logic Low Threshold	V <sub>IL</sub>		--	--	0.4	V
Logic High Threshold	V <sub>IH</sub>		0.8	--	--	V
Oscillator						
Switching Frequency	f <sub>OSC</sub>	R <sub>RT</sub> = 24kΩ	270	300	330	kHz
Adjustable Frequency Range			50	--	1000	kHz
Ramp Amplitude			--	4	--	V
Maximum Duty			70	75	80	%
RT Pin Voltage	V <sub>RT</sub>		0.97	1.02	1.07	V
PWM Output						
Output Low Voltage	V <sub>OL</sub>	I <sub>SINK</sub> = 4mA	--	--	0.2	V
Output High Voltage	V <sub>OH</sub>	I <sub>SRC</sub> = 4mA	4.7	--	--	V
Reference Voltage and DAC						
DAC Accuracy	V <sub>FB</sub>	0.5V to 0.8V	-10	--	10	mV
		0.8V to 1.0V	-8	--	8	
			1.0V to 1.6V	-0.5	--	0.5
DAC Input Logic Low Threshold	V <sub>IL</sub>		--	--	0.4	V
DAC Input Logic High Threshold	V <sub>IH</sub>		0.8	--	--	V
OFS Voltage		R <sub>OFS</sub> = 10kΩ to 5VCC. V <sub>CC5</sub> - V <sub>OFS</sub>	1.49	1.62	1.75	V
		R <sub>OFS</sub> = 10kΩ to GND.	0.38	0.41	0.44	
Error Amplifier						
Open Loop DC Gain	AO	Guaranteed by Design	70	80	--	dB
Gain-Bandwidth Product	GBW	C <sub>LOAD</sub> = 5pF.	30	--	--	MHz
Slew Rate	SR	Guaranteed by Design	3	6	--	V/us
Trans-conductance	GM	R <sub>LOAD</sub> = 20kΩ	1400	1800	--	uA/V
Maximum Current (Source & Sink)	I <sub>COMP</sub>	V <sub>COMP</sub> = 1.6V	300	360	--	uA

## Electrical Characteristics

Parameter	Symbol	Test Conditions	Min	Typ	Max	Unit
<b>Power Saving Mode</b>						
PS1/PS2/PS3 Sourcing Current	$I_{PSX}$	$R_{PS1} = R_{PS2} = R_{PS3} = 47k$	9	10	11	µA
<b>Protection</b>						
Total Current Protection Threshold	$V_{IMAX}$		1.1	1.2	1.3	V
FB Over Voltage Protection		$V_{FB} - V_{DAC}$	130	160	190	mV
FB Under Voltage Protection		$V_{FB} - V_{DAC}$	-380	-300	-250	mV
Over Temperature Protection Threshold			--	160	--	°C
Over Temperature Protection Hysteresis			--	20	--	°C
<b>Output Pin Capability</b>						
VR_HOT Sinking Capability	$V_{HOT}$	$I_{HOT} = 4mA.$	--	0.05	0.2	V
VR_RDY Sinking Capability	$V_{RDY}$	$I_{RDY} = 4mA.$	--	0.05	0.2	V

**Note 1.** Stresses listed as the above "Absolute Maximum Ratings" may cause permanent damage to the device. These are for stress ratings. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may remain possibility to affect device reliability.

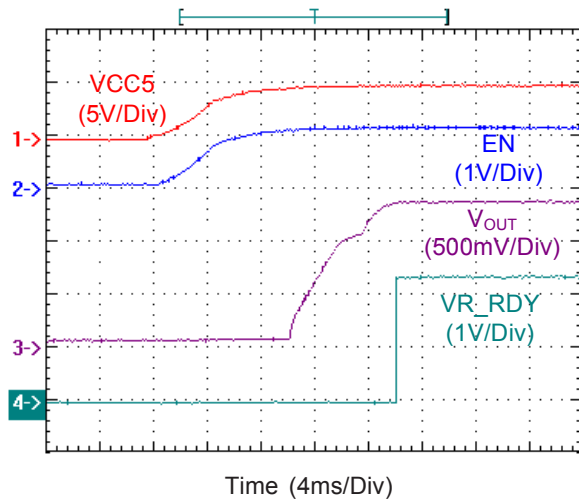
**Note 2.** Devices are ESD sensitive. Handling precaution recommended.

**Note 3.**  $\theta_{JA}$  is measured in the natural convection at  $T_A = 25^{\circ}C$  on a low effective thermal conductivity test board of JEDEC 51-3 thermal measurement standard.

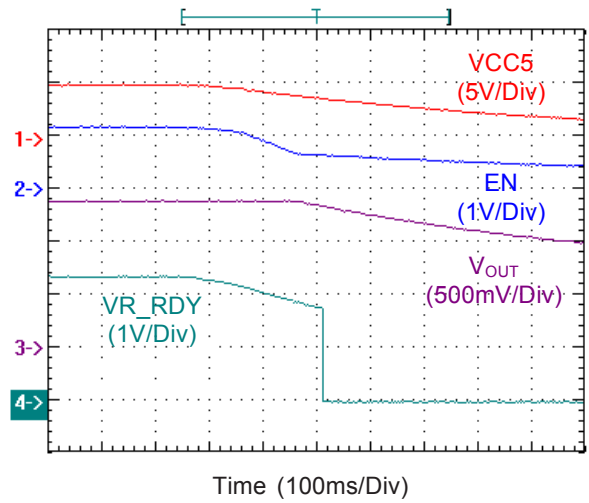
**Note 4.** The device is not guaranteed to function outside its operating conditions.

## Typical Operation Characteristics

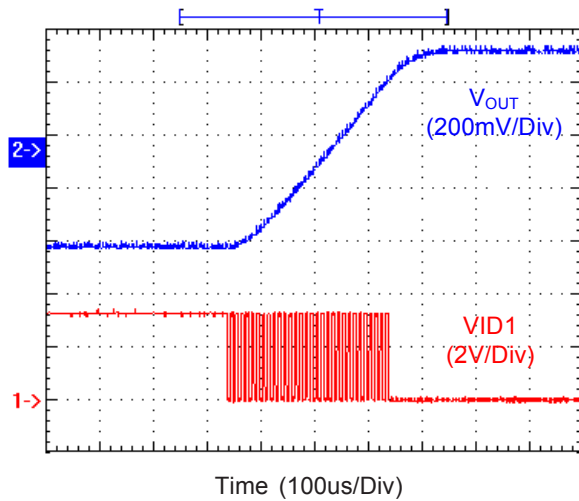
**Power On Waveforms**



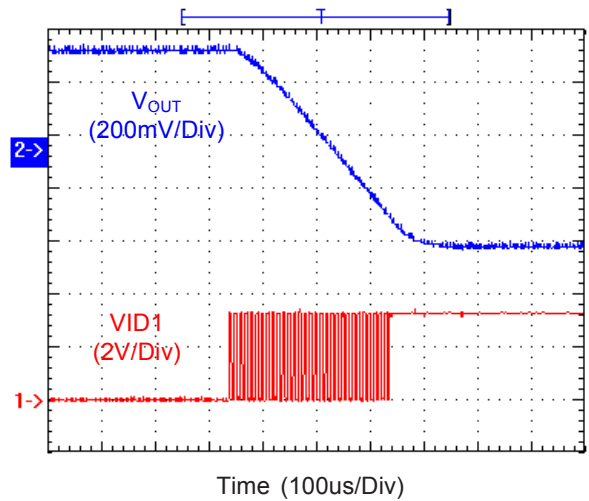
**Power Off Waveforms**



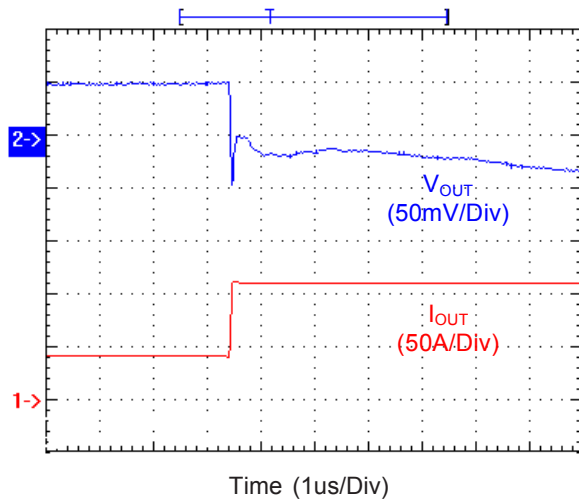
**DVID Rising**



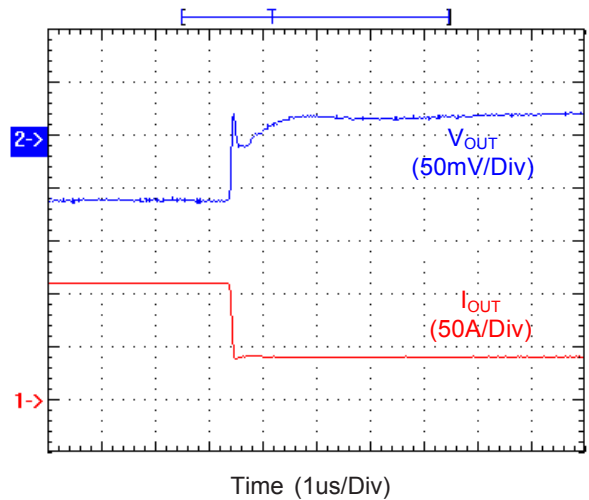
**DVID Falling**



**Load Transient Response Rising**

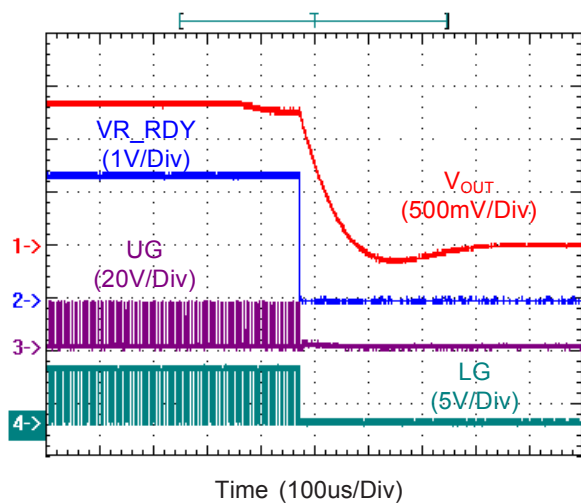


**Load Transient Response Falling**

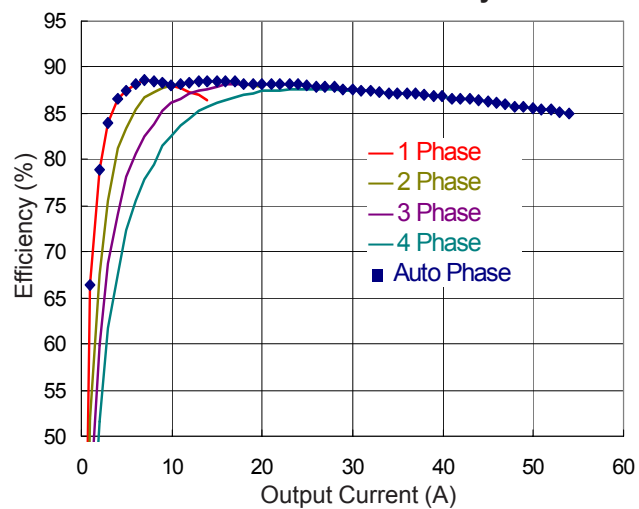


## Typical Operation Characteristics

Over Current Protection



Auto Phase Efficiency



### Total Current Sensing

In the real application, PCB traces are not ideal and have certain parasitic resistances  $R_{PCB1}$  and  $R_{PCB2}$  as shown in Figure 1. When these parasitic resistances are not identical, the voltages at inductor terminals are not the same, contributing measurement error on total current sensing. Two  $1\Omega$  resistors, connecting directly to inductor terminals are recommended to eliminate the effects of parasitic resistance.

A  $0.1\mu\text{F}$  capacitor  $C_{BYP}$  is also recommended to bypassing noise when the uP6213A/B is far away from the output inductors. Place the  $C_{BYP}$  physically near the IC.

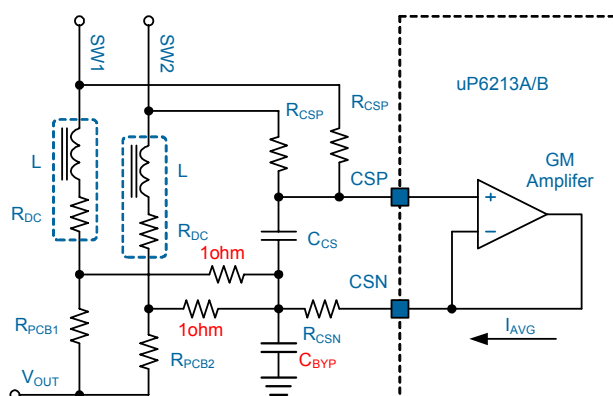
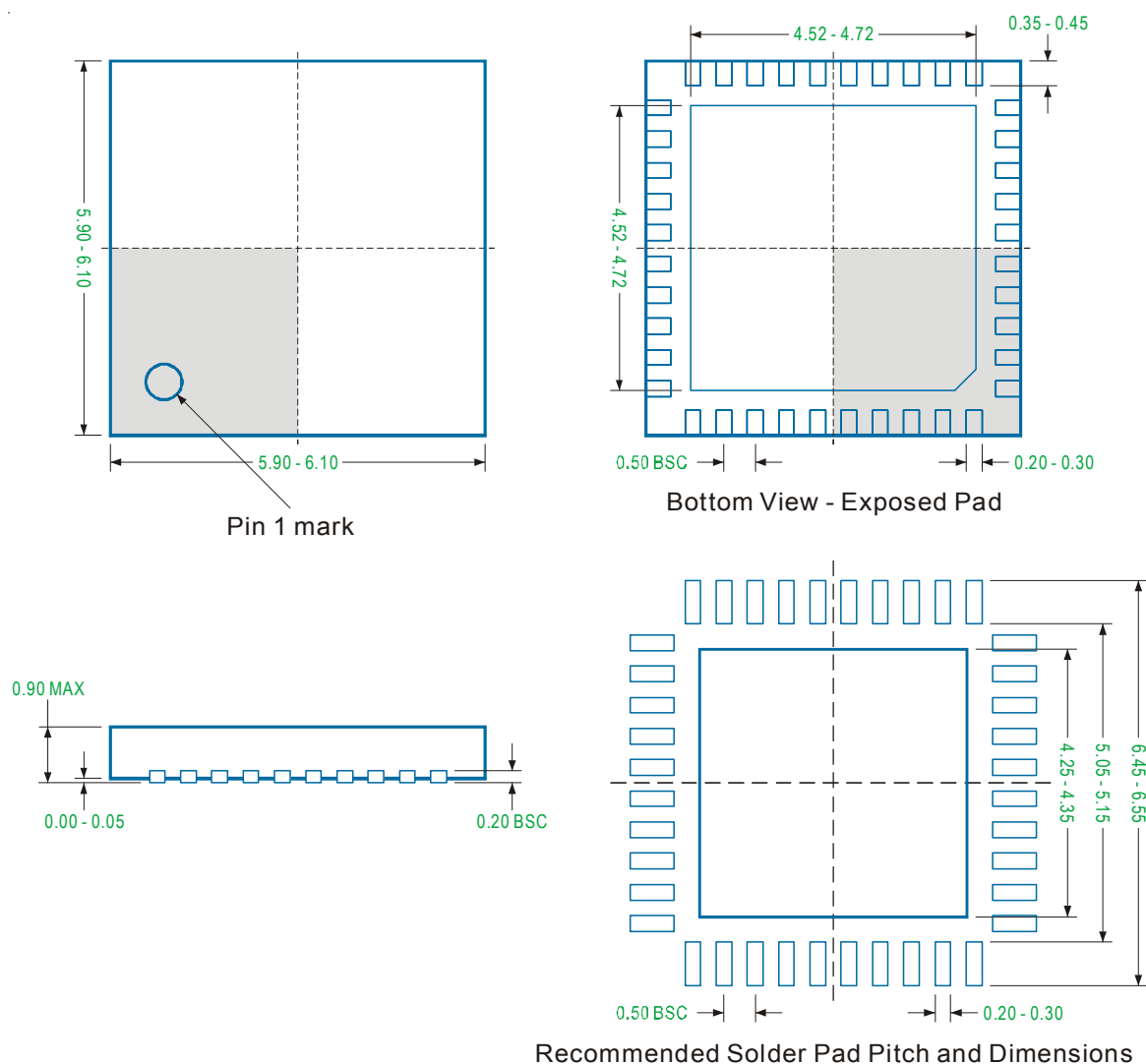


Figure 1. Parasitic Resistance of PCB

## Package Information

### VQFN6x6 - 40L Package



#### Note

##### 1. Package Outline Unit Description:

BSC: Basic. Represents theoretical exact dimension or dimension target

MIN: Minimum dimension specified.

MAX: Maximum dimension specified.

REF: Reference. Represents dimension for reference use only. This value is not a device specification.

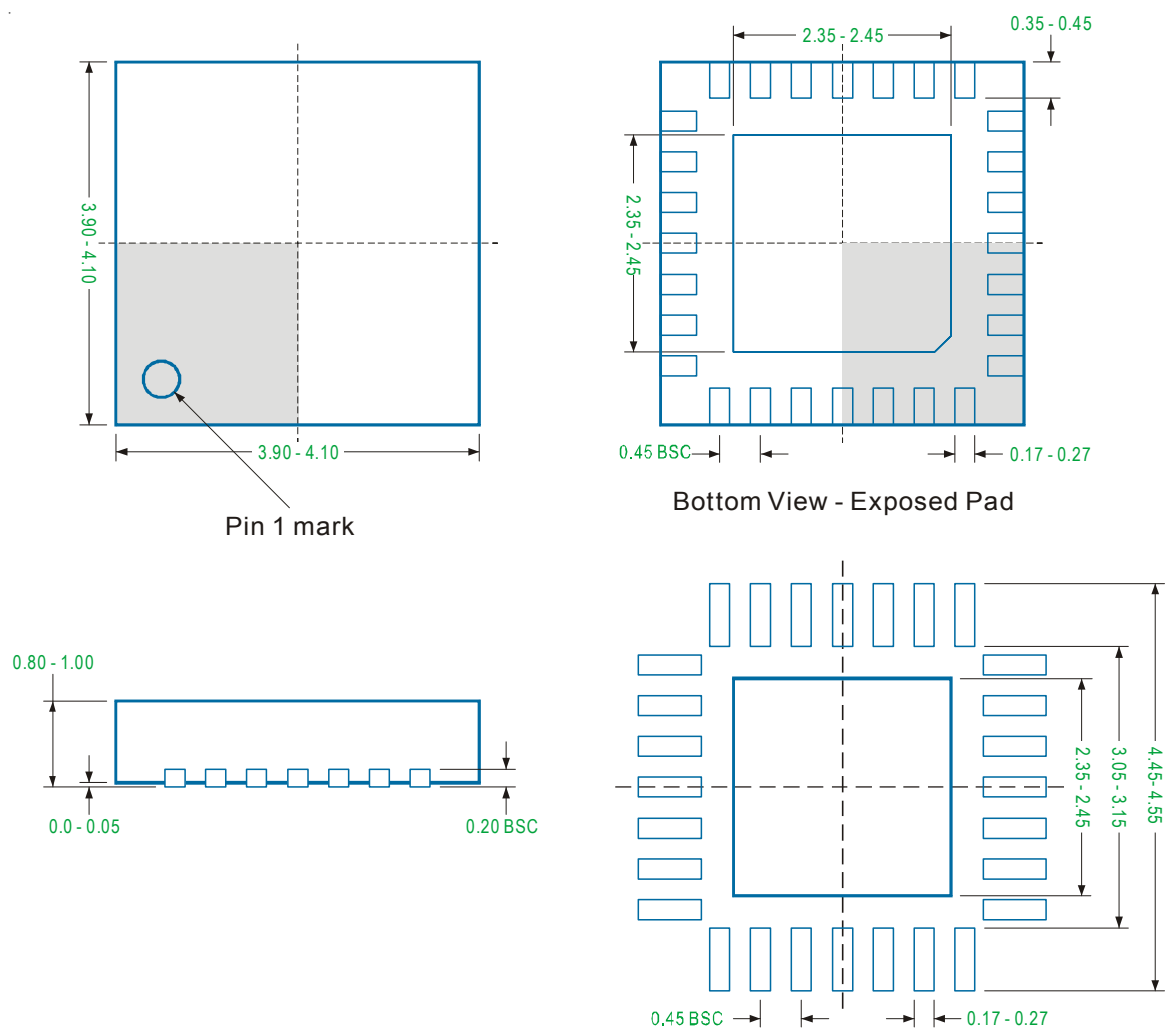
TYP: Typical. Provided as a general value. This value is not a device specification.

##### 2. Dimensions in Millimeters.

##### 3. Drawing not to scale.

##### 4. These dimensions do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm.

VQFN4x4 - 28L Package



**Note**

**1. Package Outline Unit Description:**

BSC: Basic. Represents theoretical exact dimension or dimension target

MIN: Minimum dimension specified.

MAX: Maximum dimension specified.

REF: Reference. Represents dimension for reference use only. This value is not a device specification.

TYP: Typical. Provided as a general value. This value is not a device specification.

**2. Dimensions in Millimeters.**

**3. Drawing not to scale.**

**4. These dimensions do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm.**