

WD10C27

Data

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13

## **TABLE OF CONTENTS**

T-52-38

Section	Title		Page			
1.0	INTF	RODUCTION	13-1			
	1.1	GENERAL DESCRIPTION	13-1			
	1.2	FEATURES	13-1			
2.0	MICI	ROPROCESSOR INTERFACE	13-8			
	2.1	REGISTER DESCRIPTION	13-8			
		2.1.1 Configuration Registers	13-9			
		2.1.2 Frequency Synthesizer Registers	13-12			
		2.1.3 Window Synthesizer Registers	13-12			
		2.1.4 Skew-Symmetric Precomp.Registers	13-12			
		2.1.5 Channel Control Registers	13-13			
		2.1.6 Registers	13-13			
3.0		OLIENOV CVAITUEOIZED	÷			
3.0	3.1	QUENCY SYNTHESIZERPROGRAMMABLE FS CRYSTAL REFERENCE (XTLI)	13-17			
	3.2	ES DIVIDED OBERATION	13-17			
	3.3	FS DIVIDER OPERATION	13-17			
	0.0	PROGRAMMING THE FS DIVIDERS	13-18			
4.0	READ CHANNEL					
	4.1	ADDRESS MARK DETECTOR	13-20			
		4.1.1 Address Mark Detection Rules	13-20			
		4.1.2 Formatting to Reduce False AM Detection	13-22			
	4.2	ACQUISITION SEQUENCER	13-22			
		4.2.1 Soft Sector Sequencing	13-22			
		4.2.2 Data Acquisition and Tracking	13-23			
		4.2.3 RCLK Source	13-24			
	4.3	DATA SYNCHRONIZER	13-26			
		4.3.1 Phase-Locked Loop	13-26			
		4.3.2 Window Generation	13-27			
		4.3.3 Window Monitoring	19-27			
		4.3.4 Window Shifting	19-27			
	4.4	DECODER	12-21			
	4.5	CHANNEL CONTROL DACs	12-22			
		4.5.1 Frequency Control (FCDAC)	12_2A			
		4.5.2 Boost Control (BCDAC)	40-01 40-01			
		4.5.3 Hysteresis Control (FCDAC)	12_0 <i>A</i>			
		·	10-04			



## T-52-38

## **TABLE OF CONTENTS (Continued)**

<b>Section</b> 5.0	Title  WRITE CHANNEL  5.1 ENCODER  5.1.1 Framing in Hard Sector Formats  5.1.2 Framing in Soft Sector Formats  5.2 PATTERN DEPENDENT PRECOMPENSATION  POWER ON RESET	. 13-35 . 13-35 . 13-36 . 13-36
7.0	PERFORMANCE SPECIFICATIONS 7.1 MAXIMUM RATINGS 7.2 DC ELECTRICAL CHARACTERISTICS 7.3 AC ELECTRICAL AND TIMING CHARACTERISTICS  APPENDICES	13-40 13-40
A.0	APPLICATION NOTES  A-1 FREQUENCY SYNTHESIZER  A-2 WINDOW SHIFT SYNTHESIZER  LIST OF ILLUSTRATIONS	13-47
Figure 1-1 1-2 1-3 3-1 4-1 4-2 4-3 4-4 4-5 7-1 7-2 7-3 7-4 7-5 7-6 7-7	Title Pin Designations Variable Frequency Channel Schematic WD10C27 Block Diagram Frequency Synthesizer Block Diagram Soft Sector Timing The Acquisition Sequence Data Synchronizer Block Diagram Window Shift Synthesis Code Word to Data Word Relationship Crystal Input Timing Diagram Encoder Timing Diagram Address Mark Generation Timing Diagram Write Precompensation Timing Diagram Read Timing Diagram Microprocessor Read Timing Diagram Microprocessor Read Timing Diagram Microprocessor Write Timing Diagram	.13-6 .13-7 13-17 13-23 13-25 13-26 13-29 13-32 13-46 13-47 13-48 13-49 13-51



## LIST OF TABLES

# T-52-38

lable	ritte	Page
1-1	Pin Descriptions	13-3
2-1	Register Address Map	13-8
4-1	Address Mark Detect Sequences	13-21
4-2	Velocity Lock Time Selection	13-24
4-3	Frequency Band Selection	13-27
4-4	PWS Direction and Magnitude Selection	13-31
4-5	Expanded 1,7 RLL to NRZ Decode	13-33
5-1	Expanded NRZ to 1,7 RLL Encode	12-25
5-2	Skew Symmetric Matrix Map	13-36
5-3	Precompensation Selection	19-00
7-1	Absolute Maximum Ratings	12-40
7-2	Crystal Oscillator DC Specifications	12-40
7-3	Output Driver DC Specifications	19.41
7-4	Input Receivers DC Specifications	19-41
7-5	Data Synchronizer Internal Filter DC Specifications	10-42
7-6	Data Synchronizer Internal VCO DC Specifications	10-42
7-7	Hysteresis Control DAC Specifications	. 10-40 10 44
7-8	Frequency Control DAC Specifications	10-44
7-9	Boost Control DAC Specifications	10-40
7-10	Power Supply Specifications	10-40
7-11	Crystal Oscillator Timing Specifications	10-40
7-12	Encoder Timing Specifications	10-40
7-13	Address Mark Generation Timing Specifications	10-47
7-14	Write Precompensation Timing Specifications	10-48
<sup>7</sup> -15	Phase and Data Detection Window Timing Specifications	13-49
<sup>7</sup> -16	Read Timing Specifications	13-50
<sup>7</sup> -17	Window Shift Timing Specifications	13-50
<b>7</b> -18	Data Synchronizer PLL AC Specifications	13-50
<b>7</b> -19	Frequency Synchronizer PLL AC Specifications	13-52
<b>'-20</b>	Microprocessor Interface Timing Specifications	13-53
	The second of th	13-54

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#### 1.0 INTRODUCTION

#### 1.1 GENERAL DESCRIPTION

The WD10C27 Read/Write Channel is a fully integrated LSI device intended for variable frequency applications in conjunction with the WD61C22 Hard Disk Controller/Buffer Manager.

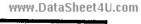
In a typical application, the WD10C27 performs all of the handling of the sensitive read/write signals between a disk controller and data drivers and receivers. Raw read data corresponds to previous write data, with added phase, frequency, and write splice noise. The fundamental purpose of the WD10C27 is to remove these noise components and present a clean digital recovered data and reference clock to the controller.

#### 1.2 Features

- General
  - Specifically designed for the WD61C22 Hard Disk Controller/Buffer Manager
  - Supports Zone Bit Recording from 7.5-27MBps with no component changes
  - 1.25 micron +5 volt only CMOS technology
  - Available in 52-pin EIAJ package
- Frequency Synthesizer
  - Programmable input reference frequency to 40 MHz
  - Multiple dividers for extremely high resolution
- Micro-Processor Interface
  - Eight bit Intel compatible multiplexed address/data port
  - Programmable test and low power modes

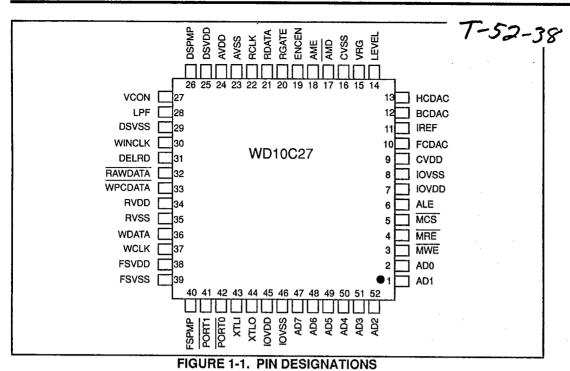
T-52-38

- Write Data Conditioner
  - Crystal controlled processing of the write data to eliminate pulse pairing
  - Programmable pattern dependent Skew Symmetric Precompensation matrix for precomp. of up to ±25% with 2<sup>-6</sup> resolution
- Encoder/Decoder
  - IBM Compatible 1,7 RLL
  - Hard/soft sector support and Address Mark Detection
- Data Synchronizer
  - Precision internal self adjusting VCO compensates for component, temperature, voltage, and aging variations
  - Internal gain/bandwidth modulation linearizes loop gain and increases phase margin across zones
  - Dual gain charge pump for faster acquisition and better jitter rejection while tracking
  - Dual mode phase/phase-frequency detector eliminating quadrature and harmonic lock
  - mP controlled Window Shift Synthesis for window shifting up to ±50% of the window
  - Window monitoring capability
- Channel Control
  - 5-bit DACs specifically designed for use with the SSI8011 and SSI3040 read channel devices
  - Bandwidth, Boost and Hysteresis Control for ZBR
  - Two Programmable Micro Processor Ports





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13-2

ADVANCE INFORMATION 5/15/91

1/2

ww.INTRODUCTION

PIN		<del> </del>	<del>  •                                     </del>	T-52-38
NUMBER (IO MAP)	MNEUMONIC	SIGNAL	1/0	
47-52,	AD7-0	NAME	A/S	FUNCTIONAL DESCRIPTION
1-2		Address/Data Bus	1/0	ADDRESS inputs used in conjunction with ALE to select the internal register to be transmitted or received on the DATA input/outputs.
3	MWE	Write Enable	1	When asserted will transmit data from the AD bus into internal registers.
4	MRE	Read Enable	1	When asserted will transmit data from internal registers onto the AD bus.
5	MCS	Chip Select	ľ	When asserted allows information to be read from or written to the AD bus.
6	ALE	Address Latch Enable		Address information is latched on the falling edge.
7,45	IOVDD	I/O Supply	S	+5 volt supply to all I/O except WPCDATA, RAWDATA, and analog pins.
8,46	IOVSS	I/O Ground	S	Dedicated ground to all I/O except WPCDATA, RAWDATA, and analog pins (designated "A").
9	CVDD	Analog Supply	S	Dedicated +5v for the Channel Control DAC circuitry.
10 (14)	FCDAC	Freq. Cti. DAC	Α	Frequency Control current DAC output.
11 (13)	IREF	Current Reference	A	External current reference used to set the compliance of IDAC. When not used, IREF should be connected to CVSS.
12 (15)	BCDAC	Boost Ctl. DAC	Α	Boost Control voltage DAC output.
13 (11)	HCDAC	Hyst. Ctl. DAC	Α	Hysteresis Control voltage DAC output.
14 (10)	LEVEL	Level	Α	External voltage used to adjust the Hysteresis DAC offset. Should be tied to CVSS when not used.
15 (12)	VRG	Voltage Reference	Α	External voltage reference used by the DAC circuits. Should be tied to CVSS when the Boost Control, Frequency Control, and Hysteresis Control DACs are not used.
16	CVSS	Analog Ground	S	Dedicated ground for the Channel Control DAC circuitry.
17 (19)	AMD	Address Mark Detect	0	In soft sector, this signal indicates to the controller that after requesting an address mark search (AME), an address mark has been detected.
18 (21)	AME	Address Mark Enable	İ	In soft sector, AME initiates an address mark search during reads, or address mark generation during writes.
19 (17)	ENCEN	Encode Enable	1	Asserted during write commands to enable the Encoder and associated write circuits.

TABLE 1-1. PIN DESCRIPTIONS

BIN			1	T-52-38 -
PIN NUMBER (IO MAP)	MNEUMONIC	SIGNAL NAME	I/O A/S	FUNCTIONAL DESCRIPTION
20 (22)	RGATE	Read Gate		In soft sector, RGATE responds to AMD to validate the acquisition sequence during reads. In hard sector, RGATE initiates the acquisition sequence w/o AMD qualification.
21 (18)	RDATA	Recovered Data	0	Recovered NRZ read data represents the decoded RLL raw read data with all phase and frequency noise removed.
22 (20)	RCLK	Regenerated Clock	0	Nominally at the NRZ data frequency, RCLK tracks the low frequency variations on RAW-DATA during reads, otherwise tracks the crystal reference.
23	AVSS	Main Analog Ground	S	Main ground dedicated primarily to analog support circuitry (i.e., Delay Locked Loop, PLL Phase Detectors, etc.). This supply also supports the sensitive WPCDATA and RAWDATA I/O to prevent intermodulation with IOVDD /IOVSS.
24	AVDĐ	Main Analog Supply	s	Main +5v supply dedicated primarily to analog support circuitry (i.e., Delay Locked Loop, PLL Phase detectors, etc.). This supply also supports the sensitive WPCDATA and RAWDATA I/O to prevent intermodulation with IOVDD /IOVSS.
25	DSVDD	Analog Supply	S	Dedicated +5v for the Data Synchronizer circuitry.
26 (28)	DSPMV	Data Synchronizer Pump	A	Charge pump to the data synchronizer PLL filter.
27 (30)	VCON	N-Channel Voltage Control	Α	N-channel control voltage for the internal VCO and charge pump. This voltage is the filtered output of the charge pump.
28 (26)	LPF	Low Pass Filter	Α	Controls low pass filter characteristics under zone control via the AD bus.
29	DSVSS	Analog Ground	S	Ground dedicated to the Data Synchronizer PLL.
30 (27)	WINCLK	Window Clock	0	This output, when enabled, represents the window clock at the Data Detector and may be used for window monitoring. Phase detector pump down output in test mode.
31 (33)	DELRD	Delayed Read Data	0	This output, when enabled, represents the latched RAWDATA at the Data Detector and may be used for window monitoring. Phase detector pump up output in test mode.

**TABLE 1-1. PIN DESCRIPTIONS (Continued)** 

	<del></del>	· <del>r ·- ·-</del> ·	<del>_</del> -	
PIN NUMBER (IO MAP)	MNEUMONIC	SIGNAL NAME	I/O A/S	T-52-38  FUNCTIONAL DESCRIPTION
32 (37)	RAWDATA	Raw Data	I	Disk drive raw read data from the read channel circuits. Leading edge timing, programmable polarity.
33 (31)	WPCDATA	Write Precomp Data	0	Precompensated/Conditioned encoded write data sent to the write channel drivers. Leading edge timing, programmable polarity.
34	RVDD	Analog Supply	S	Dedicated +5v supply to Ramp Locked Loop circuits.
35	RVSS	Analog Ground	S	Dedicated ground to Ramp Locked Loop circuits.
36 (41)	WDATA	Write Data		NRZ write data from the controller. This data is conditioned and precompensated and sent out on WPCDATA.
37 (32)	WCLK	Write Clock	l	Running at the NRZ data frequency. WCLK is provided from the the hard disk controller and serves as a reference clock for sampling the incoming WDATA.
38	FSVDD	Analog Supply	S	Dedicated +5v for the Frequency Synthesizer circuitry.
39	FSVSS	Analog Ground	S	Dedicated ground for the Frequency Synthesizer circuitry.
40 (42)	FSPMP	Frequency Synthesizer Pump	ata <b>S</b>	Charge pump for the frequency synthesizer PLL.
41 (36)	PORT1	Port One	0	Open drain TTL output. This output is directly programmable via the micro-processor interface.
42 (40)	PORT0	Port Zero	0	Open drain TTL output. This output is directly programmable via the micro-processor interface
43 (44*)	XTLI	Crystal Input	I	Input to active stage of integrated oscillator circuit, this frequency establishes the frequency synthesizer reference. The reference frequency is programmable via the AD bus.
44 (43*)	XTLO	Crystal Output	0	Output from active state of integrated oscillator circuit. This output is left open if an external source is desired.



**TABLE 1-1. PIN DESCRIPTIONS (Continued)** 



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<sup>\*</sup> XTLO is an inversion of XTLI through the active stage. XTLO may not be driven and sensed on XTLI.

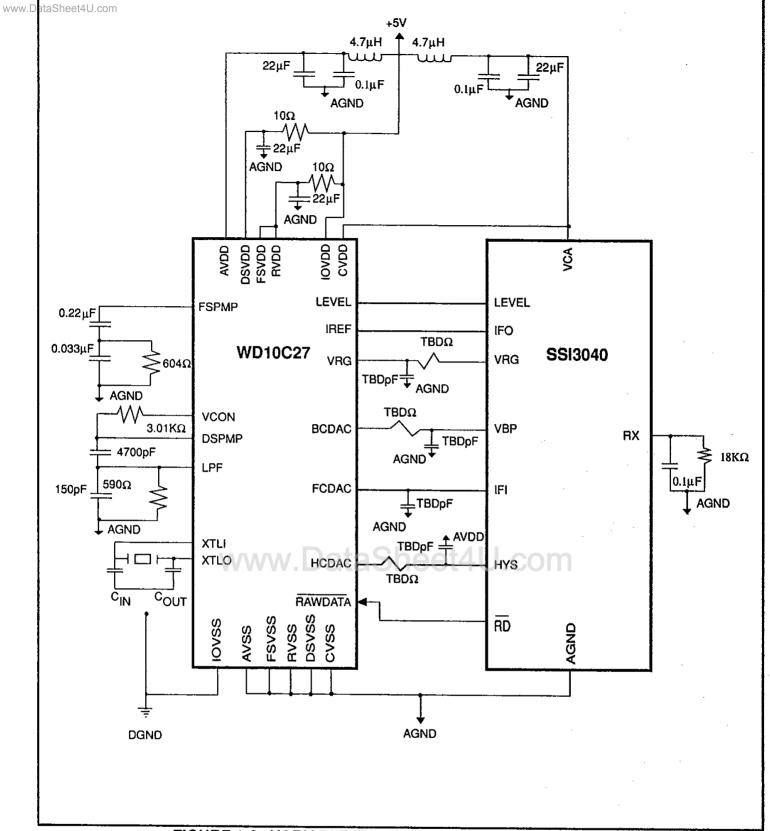
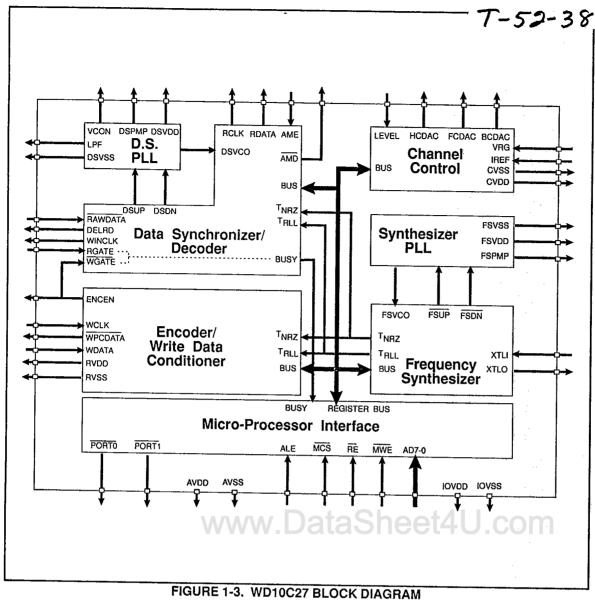


FIGURE 1-2. VARIABLE FREQUENCY CHANNEL SCHEMATIC

13-6 ADVANCE INFORMATION 5/15/91







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ADVANCE INFORMATION 5/15/91

13-7

WD10C27

#### 2.0 MICROPROCESSOR INTERFACE

The WD10C27 provides an 8- bit interface to the microprocessor for programmability. The interface is compatible with the Intel multiplexed address/data bus architecture. Virtually all of the sub-systems within the WD10C27 are accessible via this interface. The processor interface is decoupled from the input pads during disk reads/writes to reduce the possibility of unwanted disturbances to sensitive signal processing. Ensuring that de-coupling is performed is accomplished by deactivating the BZOVR (busy override) bit in the Configuration register. In either

T-52-38

configuration, registers should never be modified unless the Hard Disk Controller is not indicating a busy status.

#### 2.1 REGISTER DESCRIPTION

Registers are accessed by placing the correct address word on the AD bus and latching this address on the falling edge of ALE. Subsequent reads/writes will access the addressed registers. Read/writes are performed when MCS is low and the MRE/MWE lines are strobed.

7 ADDRESS 0	SYMBOL	REGISTER ACCESSED
11000000	TEST0	Test Modes Zero
11000001	TEST1	Test Modes One
11000010	TEST2	Test Modes Two
11000011	-	Unused
11000100	-	Unused
11000101	WSCOD	Window Synthesizer Clock Oscillator Divider
11000110	WSVCOD	Window Synthesizer VCO Divider
11000111	SAM	Window Synthesizer Amplifier
11001000	FCDAC	Frequency Control DAC
11001001	BCDAC	Boost Control DAC
11001010	HCDAC	Hysteresis Control DAC
11001011	TSTADD1	Test Address 1
11001100	TSTADD2	Test Address 2
11001101	•	Unused
11001110	FSCOD	Frequency Synthesizer Clock Oscillator Divider
11001111	FSVCOD	Frequency Synthesizer VCO Divider
11010000	WPC10	Write Precompensation One/Zero
11010001	WPC32	Write Precompensation Three/Two
11010010	WPC54	Write Precompensation Five/Four
11010011	WPC76	Write Precompensation Seven/Six
11010100	WPC98	Write Precompensation Nine/Eight
11010101	WPC1110	Write Precompensation Eleven/Ten
11010110	WPC1312	Write Precompensation Thirteen/Twelve
11010111	WPC1514	Write Precompensation Fifteen/Fourteen
11011000	WPC1716	Write Precompensation Seventeen/Sixteen
11011001	WPC1918	Write Precompensation Nineteen/Eighteen

**TABLE 2-1. REGISTER ADDRESS MAP** 

13-8

ADVANCE INFORMATION 5/15/91



7 ADDRESS 0	SYMBOL	REGISTER ACCESSED
11011010	WFC2021	Write Precompensation Twenty/Twenty-One
11011011	-	Unused
11011100	CFG0	Configuration Zero
11011101	CFG1	Configuration One
11011110	CFG2	Configuration Two
11011111	CFG3	Configuration Three

**TABLE 2-1. REGISTER ADDRESS MAP (Continued)** 

All registers in the WD10C27 are read/write registers, with the exception of the Version ID Register. As previously stated, register access is limited to times when read and write operations are inactive. Register bits correspond to bits 7-0 of the AD bus such that the most significant maps to AD7, the least significant to AD0.

The internal read data bus utilizes a repeater which will latch this bus to the value of the register which was last read and for which the address is not "unused." All registers load asynchronously, thereby requiring no clocks to the device. Exceptions are the Frequency Synthesizer and the Window Shift Synthesizer Registers.

For the Frequency Synthesizer, reads/writes are performed to a master stage. The slave will not be updated however until synchronization circuitry has deemed it appropriate. This requires XTLI and Frequency Synthesizer VCO clocks.

The WSS will not allow loads to its registers when WSSEN is active.

At power up, the ARSTPDN bit in the Configuration register will be set (see section 6.0, "Power On Reset") and all other register bits placed in their specified initial state (see ARSTPDN and RSTPDN bits in section 2.1.1).

Following a soft reset/power down mode, a reset must be issued and all registers re-loaded.

There are eight main registers banks in the WD10C27:

- Configuration

- Frequency Synthesizer Dividers
- Window Synthesizer Control
- Skew Symmetric Precompensation
- Channel Control
- Test

## 2.1.1 Configuration Registers

The configuration (CFG) registers control the basic functions of the sub-circuits. These registers are eight bits wide.

### **CFG0 Register:**

7:RLLEN 6:WPCEN 5:WSSEN	4:PWSEN	3:PWSI 2:PWS0	1:FBS1	0:FBS0	
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- Bit 0: Frequency Band Select Zero. In conjunction with FBS1, FBS0 controls the Data Synchronizer, Frequency Synthesizer, and Ramp Lock Loop characteristics. See "Table 4-3 Frequency Band Selection" for band selection.
- Bit 1: Frequency Band Select One. See Bit 0 above.
- Bit 2: Percentage Window Shift Zero. Used in conjunction with PWS1, PWS0 controls the direction of window shift when PWSEN is



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- active. (See "Table 4-3 PWS Direction and Magnitude Selection").
- Bit 3: Percentage Window Shift One. Used in conjunction with PWS0, PWS1 controls the magnitude of window shift when PWSEN is active. (See "Table 4-3 PWS Direction and Magnitude Selection").
- Bit 4: Percentage Window Shift Enable. When active, this bit enables the PWS system.
- Bit 5: Window Shift Synthesis Enable. When active, this bit enables the WSS system.

  Must be inactive during loads to the WSS registers. (See section 4.3.4, "Window Shifting").
- Bit 6: Write Precompensation Enable. When active, this bit enables the Pattern Dependent Precompensation system (RLLEN must be set to utilize fine resolution capabilities). (See section 5.2, "Pattern Dependent Precompensation").
- Bit 7: Ramp Locked Loop Enable. This bit, when set in conjunction with WPCEN, activates the fine resolution capabilities of the write precompensation sub-circuit. (See section 5.2, "Pattern Dependent Precompensation").

#### CFG1 Register:

STEN	ORT1	ОВТО	STPDN	STPDN	ZOVR	MAP	ZEN
7:TS	6:PO	5:PO	4:ARS	3:RS1	2:BZ(	1:ION	0:HIZ

Bit 0: High Impedance Enable Test. When active, this bit will cause all output drivers and analog pins to be placed in a high impedance state. Exceptions include the micro-processor pins and XTLO. The micro-processor outputs may be tri-stated by asserting either RGATE or ENCEN with BZORV inactive.

- T-52-38

  Bit 1: Input/Output Mapping. When set, this bit will configure the WD10C27 input/output in accordance with the I/O map. IOMAP will be logically or'd with HIZEN to ensure all outputs and analog pins are tri-stated during I/O mapping. (See "Table 1-1- Pin Description").
- Bit 2: Busy Override. When active, this bit defeats the decoupling of the AD7-0 pads from the Micro-Processor Interface during disk read/write operations. Override mode is not recommended. Busy should be defeated during certain test modes. (See section 2.1.6, "Test Registers".)
- Bit 3: Reset/Power Down. When active, this bit will reset/power down all functions and set all register bits to a logic zero for initialization and/or reduced power. All outputs will be held in their inactive states, and the crystal oscillator stopped. Exceptions include: FCDAC, HCDAC, and BCDAC registers and related functions, all of which are not effected by this bit; the COD and VCOD registers in both the Frequency and Window Shift Synthesizers, which are set to logic ones; and PORT0/1, which are not effected. The micro-processor interface is operable during rest/power down, and reset/power down remains active until the RSTPDN bit is written off.
- Bit 4: All Reset/Power Down. This bit, when active, performs the same functions as the RSTPDN bit, with the addition that it will reset/power down the FCDAC, HCDAC and BCDAC registers and circuitry, as well as the RSTPDN bit itself. This bit will be set on power up. (See section 6.0, "Power On Reset").
- Bit 5: Port Zero. This bit is used to set or reset the PORTO open drain output. Note that setting this bit forces PORTO low.
- Bit 6: Port One. This bit is used to set or reset the PORT1 open drain output. Note that setting this bit forces PORT1 low.
- Bit 7: Test Enable. When active, this bit enables the activation of test modes based on the

T-52-38

Bit 7: High Frequency Clock Enable. When ac-

tive, this bit will divide the XTLI frequency

by two at the HFCOD prior to the division

which occurs at the FSCOD. (See section 3.0, "Frequency Synthesizer").

contents of TEST0-3 registers. When not 7 active, this bit serves to lockout all test modes. (See section 2.1.6, "Test Registers").

#### CFG2 Register:

7:HFCEN	6:VLOCK1	5:VLOCK0	4:WPCPOL	3:RAWPOL	2:WMEN	1:ERRPAT	):DECERR
7	9	5:	4		2	<del></del>	0:1

Bit 0: Decoder Error. When set, this bit represents an error detected in the RAWDATA bit stream into the Decoder. This bit should be cleared via a soft reset or an explicit write to this bit. (See section 4.4, "Decoder").

Bit 1: Error Pattern. When high, forces the Decoder to output NRZ ones when illegal 1,7 codes sequences are encountered on the RAWDATA input When low, NRZ zeros will be output for illegal sequences.

Bit 2: Window Monitor Enable. When set, this bit enables the DELRD and WINCLK outputs for window monitoring capabilities. (See section 4.3.3, "Window Monitoring").

Bit 3: Raw Data Polarity. When set, this bit selects active high leading edge polarity on the RAWDATA output. When not set, active low leading edge polarity is selected.

Bit 4: Write Precomp. Data Polarity. When set, this bit selects active high leading edge polarity on the WPCDATA output. When not set, active low leading edge polarity is selected.

Bit 5: Velocity Lock Zero. In conjunction with VCLOCK1, this bit set the velocity lock time for the acquisition sequence. (See section 4.2, "Acquisition Sequencer").

Bit 6: Velocity Lock One. See Velocity Lock Zero above.

CFG3 Register:

:VID3	6:VID2	:VID1	:VID0	:Unused	:Unused	:ENODD	:AMODD
7	9:	5:	4.	3:1	2:1	1:1	0:7

The upper four bits of this register are read only.

Bit 0: AME Odd. This bit controls relationship between the AME input and the NRZ code word boundary. With AMODD active, the code word is assumed to start on an odd bit in the NRZ synchronization byte (i.e. the first non-zero bit is bit 1,3,5,7); when inactive, the code word starts on an even bit (i.e., 0,2,4,6).

Bit 1: ENCEN Odd. This bit controls relationship between the ENCEN input and the NRZ code word boundary. With ENODD active, the code word is assumed to start on an odd bit in the NRZ synchronization byte (i.e., the first non-zero bit is bit 1,3,5,7); when inactive, the code word starts on an even bit (i.e., 0,2,4,6).Unused. May be read/written. This bit reflects the code word boundary for GAP prior to address mark in ID fields, as well as the sync. byte following the synchronization field in DATA fields. this implies that the GAP data and synchronization byte must have the same code word odd/even boundary.



Bit 2: Unused. May be read/written.

Bit 3: Unused. May be read/written.

Bit 4: Version Identification Zero. VID3-0 are used to store a binary number which represents the version number of the device. The version number may be used to verify the cor-

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ADVANCE INFORMATION 5/15/91

13-11

rect iteration by the system. This bit is read only.

Bit 5: Version Identification One. See VID0 above.

Bit 6: Version Identification Two. See VID0 above.

Bit 7: Version Identification Three. See VID0 above.

#### 2.1.2 Frequency Synthesizer Registers

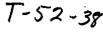
The Frequency Synthesizer is controlled by the Clock Oscillator Divider (FSCOD) and the VCO Divider (FSVCOD) which are programmed via the contents of the FSCOD and FSVCOD registers. These registers hold eight bit unsigned integers. Programming is performed using the information given in section 3.3, "Programming the FS Dividers". Pre-scaling of the input to the FSCOD is performed based on the state of the HFCEN bit in the Configuration registers.

#### **FSCOD** Register:

7:Divide 128	6:Divide 64	5:Divide 32	4:Divide 16	3:Divide 8	2:Divide 4	1:Divide 2	0:Divide 1	
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should be programmed using the information given in section 4.3.4, "Window Shift Synthesis."

#### **WSCOD** Register:



3:Divide 8	2:Divide 4	j.Divide 2	0:Divide 1
3:5	2:[	1:1	1:0

#### **WSVCOD Register:**

4:Divide 16 3:Divide 8	2:Divide 4	1:Divide 2	0:Divide 1
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#### **SAM Register:**

8	4	2	1
3:SAM	2:SAM	1:SAM	0:SAM

#### **FSVCOD** Register:

7:Divide 128	6:Divide 64	5:Divide 32	4:Divide 16	3:Divide 8	2:Divide 4	1:Divide 2	0:Divide 1
--------------	-------------	-------------	-------------	------------	------------	------------	------------

#### 2.1.3 Window Synthesizer Registers

The Window Synthesizer Clock Oscillator Divider (WS-COD), VCO Divider (WSVCOD), and Shift Amplifier are controlled by the WSCOD, WSVCOD, and SAM registers respectively. The WSCOD, WSVCOD, and SAM registers hold four and five bit unsigned integers. These registers

## 2.1.4 Skew-Symmetric Precomp. Registers

There are twenty-two 4 bit wide nibbles which control the magnitude of precompensation for the Skew-Symmetric Precompensation system. Each nibble corresponds to a phase shift value in percent of the code bit window, T, for a given three bit sequence. The upper two bits are programmed to generate a coarse setting, while the lower two bits generate a fine setting. Eleven registers are used to hold the complete precompensation matrix, each register holding two consecutive nibbles. Note that WPC2021 has the nibbles reversed. See section 5.2, "Pattern Dependent Precompensation."

13-12

ADVANCE INFORMATION 5/15/91

1/2

#### wwwWPC0=101Registers:

_	0			7	0		
Se	rse	-	0	rse	ည္က	-	0
1 8	ars	a)	as l	ars	.oCoarse	ம	as l
Ř	Ř	HiFine	ا چَر	oCoar	Ö	Fine	.oFine
¥	¥	<u> </u>	岸	ŏ	0	P P	씽
7:HiCoa	6:HiCoa	5:1	4:HiFine	3:1	2:F	1:Lof	0:1
				()			0

#### 2.1.5 Channel Control Registers

The Channel Control registers consist of registers for controlling the three on board DACs. These registers and their associated functions will remain unaffected by the RSTPDN bit. Resetting and power reduction are accomplished by the ARSTPDN bit.

The DAC registers hold five bit unsigned integers representing the DAC conversion values for each of the three DACs. In addition, each register has a bit which can be used to disable the DAC for reduced power. The HCDAC has one additional bit for function control. See section 6.0, "Power On Reset" for details.

#### **FCDAC & BCDAC Registers:**

5:DACEN 4:DAC 16	3:DAC 8	2:DAC 4	1:DAC 2	0:DAC 1
---------------------	---------	---------	---------	---------

#### **HCDAC Registers:**

6:HCTL 5:DACEN	4:DAC 16	3:DAC 8	2:DAC 4	1:DAC 2	0:DAC 1	
-------------------	----------	---------	---------	---------	---------	--

#### 2.1.6 Test Registers

There are three registers which control test functions on the WD10C27 called TEST0-2. TSTEN must be active in the Configuration register before the test modes will be invoked. 

7-52-38

Each bit in the TEST registers represents a unique mode which has been created to ensure the quality of the product through design for testability. Some of the test modes provide synchronization of otherwise asynchronous circuits, while others provide visibility of internal logic structures to ensure high fault coverage.

See "Appendix B - Using the Test Modes" for a detailed explanation of these test features.

#### **TESTO** Register:

7:PATREC 6:WPCDC 5:PORTST	4:CNTRS 3:FSSYNC	2:FSFDN	1:FSFUP	0:PDIO
---------------------------------	---------------------	---------	---------	--------

Phase Detector I/O Test. This test takes the Frequency Synthesizer's phase detector pump up and pump down outputs to AD0-1 respectively, the Frequency Synthesizer's phase detector inputs (the FSVCOD and FSCOD outputs) to AD2-3 respectively, the Window Synthesizer's phase detector pump up and pump down outputs to AD4-5 respectively, and the Window Synthesizer's phase detector inputs (the WSVCOD and WSCOD outputs) to AD6-7 respectively during reads of the special address, TSTADD1. Note that BSOVR must not be active.



Bit 1: Frequency Synthesizer Frequency Up Test. This test forces a DC pump up error in the Frequency Synthesizer by gating off the FSCOD input to the phase detector. When both FSFUP and FSFDN are set, neither test is activated. Also see NLBTST and RLBTST modes.



ADVANCE INFORMATION 5/15/91

13-13

- Test. This test forces a DC pump down error in the Frequency Synthesizer by gating off the FSVCOD input to the phase detector. When both FSFUP and FSFDN are set, neither test is activated. Also see NLBTST and RLBTST modes.
  - Bit 3: Frequency Synthesizer Synchronization
    Test. This test takes the output of the
    HFCOD to the input of the FSVCOD as
    well as to the Frequency Synthesizer output for synchronous open loop testing.
    The ring oscillator is halted.
  - Bit 4: Frequency Synthesizer and Window Shift Synthesizer COD/VCOD Counts. This test takes each of the eight counts out of the Frequency Synthesizer's FS-COD to the AD bus during reads of the FSCOD, each of the eight counts out of the Frequency Synthesizer's FSVCOD to the AD bus during reads of the FSV-COD, each of the four counts of the Window Shift Synthesizer's WSCOD to AD0-3 during reads of the WSCOD, and each of the five counts of the Window Shift Synthesizer's WSVCOD to AD0-4 during reads of the WSVCOD. Note that BSOVR must not be active.
  - Bit 5: Power On Reset Test. When active, this bit will force the POR RC circuit to discharge, thereby activating POR and latching the ARSTPDN bit in the Configuration register (see ARSTPDN in section 2.1.1, "Configuration Registers"). This is the only way to reset the PORT0/1 bits in the Configuration register, excluding a normal POR issued upon power up. Note that PORTST will reset (via the ARSTPDN bit) both TSTEN and PORTST itself, leaving the WD10C27 in a post-POR state identical to that of a normal power up generated POR.
  - Bit 6: WPCDATA DC Test. When active, this bit causes the output on WPCDATA to remain inactive during disk write operations, resulting in DC erasure of the media. This bit will not affect the internal

- WPCDATA signal used during loopback testing. 7-52-38
- Bit 7: Pattern Recognizer Test. When active, this bit allows special control of the precompensation circuits. Used in conjunction with a read from any of the WPC registers, the Pattern Recognizer's register selection will be dynamically directed to the AD4-0, with AD4 reflecting precompensation direction (high is late. low is early). Used in conjunction with writes to any of the WPC registers, the value written on AD4-0 will subsequently be used as a constant precompensation value, thus bypassing the Pattern Recognizer. Writes must be at least two T long, and must not be followed by a read unless XTLI is temporarily stopped.

#### **TEST1 Register:**

7:NLBTST 6:RLBTST 5:DLLTST 4:WSUSDTST 3:WSLSDTST 1:WSFDNTST
---

- Bit 0: Window Shift Synthesizer Frequency Up Test. This test forces a DC pump up error in the Window Shift Synthesizer by gating off the WSCOD input to the phase detector. When both WSFUPTST and WSFDNTST are set, neither test is activated.
- Bit 1: Window Shift Synthesizer Frequency Down Test. This test forces a DC pump down error in the Window Shift Synthesizer by gating off the WSVCOD input to the phase detector. When both WSFUPTST and WSFDNTST are set, neither test is activated.
- Bit 2: Window Shift Synthesizer Synchronization Test. This test takes the input of the WSCOD to the input of the WSVCOD for synchronous open loop testing.



- Decode Test. This test takes the Window Shift Synthesizer's lower eight of sixteen SAM decode values to the AD bus during reads of the SAM register. The decode is active low. Note that if both Upper and Lower SAM Decode tests are selected, neither will be excepted. Note that BSOVR must not be active.
  - Bit 4: Window Shift Synthesizer Upper SAM
    Decode Test. This test takes the Window
    Shift Synthesizer's upper eight of sixteen
    SAM decode values to AD bus during
    reads of the SAM register. The decode is
    active low. Note that if both Upper and
    Lower SAM Decode tests are selected,
    neither will be excepted. Note that
    BSOVR must not be active.
  - Bit 5: Delay Locked Loop Test. When set, this bit forces the DLL control voltages to the rails and bypasses the RLL, allowing low frequency functional testing without concern for DLL/RLL frequency limitations. RAW-DATA and WPCDATA pulse forming are disabled.
  - Bit 6: RLL Loop Back Test. When set, this bit will internally connect the RDATA/RCLK outputs to the WDATA/WCLK inputs for simultaneous testing of the Data Synchronizer, Decoder, Encoder, and Write Data Conditioner functions by driving RLL RAW-DATA and inspecting RLL WPCDATA. When both NLBTST and RLBTST are set, neither test is activated and FSFUP/FSFDN and DSFUPTST /DSFDNTST drive the charge pump circuits directly, requiring no digital stimulation to test pump currents. Note that loop-back tests do not use the polarity bit in the configuration register.
  - Bit 7: NRZ Loop Back Test. When set, this bit will internally connect the WPCDATA output to the RAWDATA input for simultaneous testing of the Encoder, Write Data Conditioner, Data Synchronizer, and Decoder functions by driving NRZ WDATA/WCLK and inspecting NRZ RDATA/RCLK. When both NLBTST and RLBTST are set,

neither test is activated and FSFUP /FSFDN and DSFUPTST /DSFDNTST drive the charge pump circuits directly, requiring no digital stimulation to test pump currents. Note that loopback tests do not use the polarity bit in the configuration register.

T-52-38

#### **TEST2** Register:

7:PDMXTST 6:DSPLKTST 5:DSVLKTST 4:XVCOTST	3:OLPTST 2:DSFDNTST	1:DSFUPTST	
---	------------------------	------------	--

- Bit 0: Acquisition Sequencer Test. This test takes the Acquisition Sequencer outputs DET6, DET9, HFDET, TIMEOUT, PLOCK, FRAMED, FIFORST, and DECERR to AD0-7 respectively during reads of the special address, TSTADD2. If the PWSD test has also been selected, neither test mode will be activated Note that BSOVR must not be active.
- Bit 1: Data Synchronizer Frequency Down Test.
  This test force a DC pump up error in the Data Synchronizer by gating off the data input to the phase detector. When both DSFUPTST and DSFDNTST are set, neither are activated. Also see NLBTST and RLBTST modes.
- Bit 2: Data Synchronizer Frequency Up Test. This test force a DC pump down error in the Data Synchronizer by gating off the VCO input to the phase detector. When both DSFUPTST and DSFDNTST are set, neither are activated. Also see NLBTST and RLBTST modes.



Bit 3: Open Loop Test. This test disconnects the Data Synchronizer's charge pump output, DSPMP, from the VCON pin to allow for testing of the charge pump and VCO characteristics. It also disables the voltage clamps on both the Data Synchronizer's

www.DataSheet4\and Frequency Synthesizer's VCOs. The ring oscillators are not affected.

- Bit 4: External VCO Enable Test. When active, this bit allows for an external VCO signal to be applied on the LPF pin. The VCO signal should be at TTL levels and at a frequency which equals three times the NRZ data rate. The ring oscillator is halted.
- Bit 5: Data Synchronizer Velocity Lock Test. This test will force the Data Synchronizer to remain in Velocity Lock mode by stalling the Acquisition Sequencer prior to entering Phase Lock.
- **Bit 6**: Data Synchronizer Phase Lock Test. This test will force the Acquisition Sequencer and Data Synchronizer charge pump and

filter into phase lock configuration to allow for testing of the PLL tracking characteristics without the need to stimulate the Acquisition Sequencer or Address Mark Detector. VCO clocks will still be required to synchronize phase lock to the digital circuits.

7-52-38

Bit 7: Phase Detection Multiplex Enable Test.
When active, this bit directs the phase detector frequency up/down error signals to the DELRD/WINCLK outputs respectively. The WMEN bit must be set in the configuration register. (See section 2.1.1, "Configuration Registers").

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#### ww3.0ataShFREQUENCY SYNTHESIZER

The frequency synthesizer output serves as the "crystal" reference for several sub-circuits: the Delay Locked Loop and Ramp Locked Loop circuits for scaling with data rate; the Data Synchronizer for reference when the PLL is not locked to RAWDATA; the Address Mark Detector and Acquisition Sequencer; and the Write Data Conditioner/Encoder for processing of sensitive write signals.

The WD10C27 utilizes a dual divider frequency synthesizer architecture to generate frequencies at an extremely high resolution. Given this, and the flexibility of the programmable crystal input frequency, highly efficient use of zones may be accomplished.

## 3.1 PROGRAMMABLE FS CRYSTAL REFERENCE (XTLI)

The crystal input is designed to accept input frequencies up to 16 MHz when using the active

stage, or up to 40 MHz when an external source is provided. If an external source is used, XTLO is left open. The crystal input frequency should never exceed 20 MHz unless HFCEN is active in the Configuration register.

#### 3.2 FS DIVIDER OPERATION

The digital portion of the synthesizer consists of a High Frequency Clock Oscillator Divider, a Clock Oscillator Divider to divide the input reference (XTLI), and a VCO Divider to divide the VCO output. The crystal input frequency is divided down based on the contents of the HFCEN bit in the Configuration registers, and the contents of the FSCOD register. The VCO output frequency from the PLL is similarly divided, based on the contents of the FSVCOD register, to match the frequency output of the FSCOD output.

The PLL architecture is almost identical to that of the Data Synchronizer. Phase-frequency locked

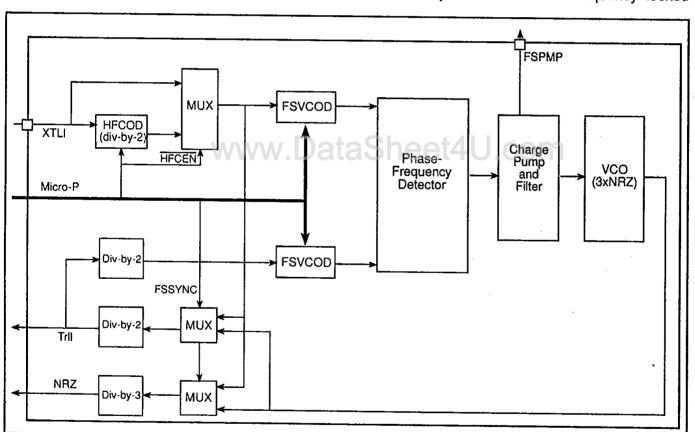




FIGURE 3-1. FREQUENCY SYNTHESIZER BLOCK DIAGRAM

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ADVANCE INFORMATION 5/15/91

13-17

www.Datlooptsynchronization is performed on the output of the FSCOD. The Charge Pump drives a VCO which utilizes a ring oscillator architecture at three times the NRZ data rate. The output of the charge pump is filtered at a very low bandwidth for high jitter rejection, while the VCO gain is modified based on the current zonal frequency to establish loop gain constancy. At the output of the Frequency Synthesizer, the VCO is operating at three times the NRZ data frequency. The NRZ and channel rate frequencies are ultimately steered to the other sub-circuits as their "crystal references". The coded rate, channel rate, or window clock, is herein referred to as T<sub>RLL</sub>. The period, T<sub>r</sub> of the window clock defines the width of the phase and data detection windows. The frequency of TRLL defined with respect to the NRZ data rate (FNRZ), is therefore given by

where

and

Finally, the 3X NRZ VCO output is divided by two and used as the input to the FSVCOD.

#### 3.3 PROGRAMMING THE FS DIVIDERS

Programming the Frequency Synthesizer is accomplished by programming the FSCOD and FSVCOD registers such that the equality

$$\frac{3/4 \times Fnrz}{FSVCOD + 1} = \frac{Fhfcod}{FSCOD + 1} = Fspli$$

is satisfied, where Ffspll is the Frequency Synthesizer PLL operating frequency range and is given by

EQ. 5.0 
$$7-52-38$$
  
95 KHz  $\leq$  Ffspil  $\leq$  105 KHz

Rearranging EQ. 4.0,

EQ. 6.0  
Fnrz = 
$$(4)$$
 x Fhfcod x  $(FSVCOD + 1)$   
(3) (FSCOD + 1)

it can easily be seen that the NRZ frequency is simply a ratio of the crystal reference frequency which may be pre-scaled in the HFCOD.

Because each side of EQ. 4.0 must not only satisfy the equality, but satisfy EQ. 5.0, selection of VCOD value can now be determined based on the NRZ data rate and the preferred crystal frequency. Note that to program a value of N, the registers must be loaded with a value of N-1.

The FSCOD and FSVCOD registers are eight bits, allowing for division up to 256 In both dividers. In addition, if the HFCEN (high frequency clock enable) bit in the Configuration registers is active, the XTLI frequency is divided by two in the HFCOD prior to entering the FSCOD. This results in the FSCOD values effectively being doubled, allowing for division of the input from 2 up to 512 in multiples of 2. HFCEN will be active on power up.

Minimum and maximum divider values are determined from EQ. 3.0 through EQ. 5.0 as follows. For the legal range of FSVCOD values, given the NRZ frequency range and the FS PLL range, we have

ww**EQ!**
$$a$$
**7** $a$ **0**\* $a$ **1** $d$ **1** $d$ **1** $d$ **2** $d$ **3** $d$ **3** $d$ **3** $d$ **4** $d$ **5** $d$ **5** $d$ **1** $d$ **5** $d$ **5** $d$ **5** $d$ **5** $d$ **5** $d$ **6** $d$ **6** $d$ **7** $d$ **9** $d$ **1** $d$ **9** $d$ **1** $d$ **1** $d$ **1** $d$ **1** $d$ **1** $d$ **2** $d$ **3** $d$ **3** $d$ **4** $d$ **5** $d$ **5** $d$ **1** $d$ **1** $d$ **1** $d$ **1** $d$ **2** $d$ **3** $d$ **3** $d$ **4** $d$ **5** $d$ **6** $d$ **6** $d$ **7** $d$ **8** $d$ **9** $d$ 

For the FSCOD values, the legal maximum is constrained by the maximum frequency of the crystal reference. This reference may never exceed 40 MHz Since the HFCEN bit must be set for crystal reference frequencies greater than 20

MHz, the output of the HFCOD will never exceed 20 MHz. T-52-38

Therefore, we have

**EQ. 8.0**

$$\frac{\text{Fhfcod (min)}}{\text{Fpll (max)}} \leq \text{FSCOD} + 1 \leq \frac{\text{Fhfcod (max)}}{\text{Fpll (min)}}$$

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#### 4.1 ADDRESS MARK DETECTOR

The Acquisition Sequencer is initiated off of  $\overline{AMD}$  in soft sector formats. When AME is asserted and ENCEN is not active, pulse formed raw read data is synchronized to  $T_{RLL}$  and sent to the Address Mark Detection circuitry. The previously written address mark (AM) is matched,  $\overline{AMD}$  is asserted and the AM search is complete. At this time, the hard disk controller should respond by asserting RGATE and de-asserting AME.

#### 4.1.1 Address Mark Detection Rules

Address mark detection is assumed to be successful only when specific pattern sequences have been detected on the synchronized raw read data. The patterns must be found in sequence according to the following rules, and only following assertion of AME. (See "Table 4-1, Address Mark Detect Sequences"):

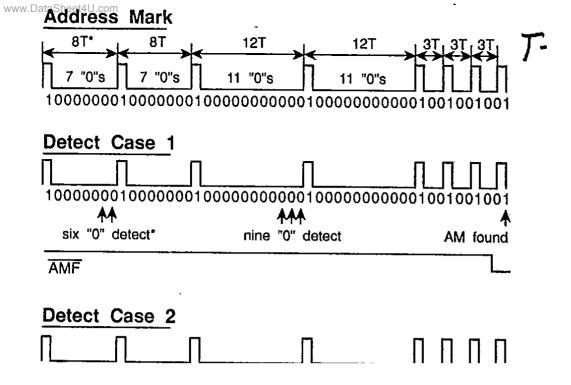
- 1. Detect a "1" followed by at least six consecutive "0"s (i.e., 1...00000...)
- 2. Detect a "1" followed by at least nine consecutive "0"s (i.e., 1...000000000...) no more than 3 NRZ byte times following detection of sequence 1.

 Detect a "1" followed by at least three consecutive high frequency (HF) intervals (i.e., ...1001001001) no more than 3NRZ byte times following detection of sequence 2.

Address marks are formatted with several unique qualities which are important in ensuring high probability of correct detection. The AM used by the WD10C27 is formatted as 8T8T12T12T3T3T3T. The leading "1" in the AM is always formatted preceding the first 8T interval in order to guarantee the interval width.

The 8T8T part of the AM is a sequence that, although not in violation of the d,k code constraints, is not possible by virtue of the encode rules (see section 5.1, "Encoder"). Detection of at least six "0"s allows for asynchronisms between the raw read data and TRLL. As six "0"s may be detected in either 8T interval, redundancy is ensured.

The selection of the 12T12T portion of the AM is an illegal run length and in violation of the k constraint in the 1,7 code. Once again two intervals ensure redundancy. In addition, the second 12T interval will significantly reduce the effects of intersymbol interference which, given only on 12T interval, would tend to shorten the interval.



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## www.Datafir.24U.Formatting to Reduce False AM Detection

When AME is asserted during disk write operations, the AM is "jammed" into the serial encoded bit stream. This is necessary to ensure that the AM placement is exact and does not depend upon synchronization to a previous interval. Jamming of the AM therefore will create an arbitrary run length between the user programmed gap and the AM. This may result in a violation of the d constraints of the 1,7 code, such that a 1T interval is created.

In the event that a 1T interval is created at the leading edge of the AM, the second of the two "1"s will be suppressed, and the AM sent to the write electronics will be

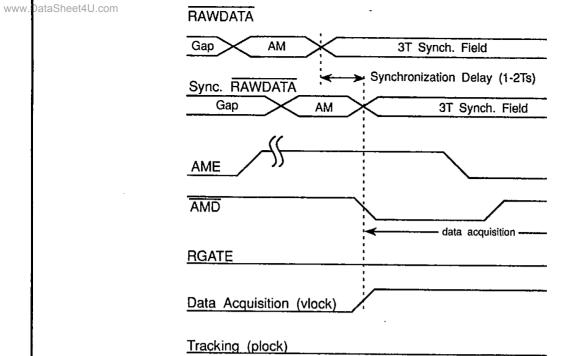
9T8T12T12T3T3T3T.

long enough that occur within the re accomplished by less than 3 NRZ b

In summary, forn bytes of 5T gap pr the susceptibility t be done with a re tern.

#### 4.2 ACQUISITI

The WD10C27 support formats. The accordance when either RGAT than the Address acquisition off of a tinctions between the support format in the Address acquisition of the support format in the Address acquisition of the support format in the Address acquisition of the support format in 
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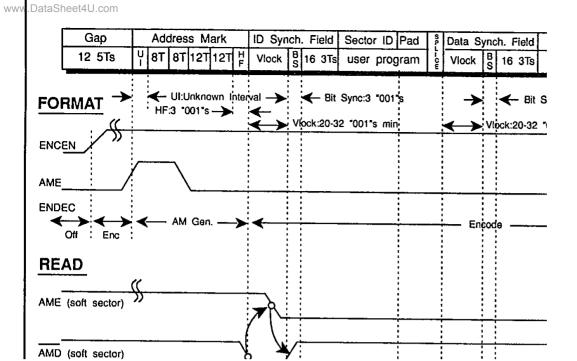
www.D	VLOCK1	VLOCK0	Vlock Time Tvlk
	0	0	60 T (4 NRZ Bytes)
	0	1	72T (5 NRZ Bytes)
	1	0	84T (6 NRZ Bytes)
	1	1	96T (7 NRZ Bytes)

TABLE 4-2. VELOCITY LOCK TIME SELECTION

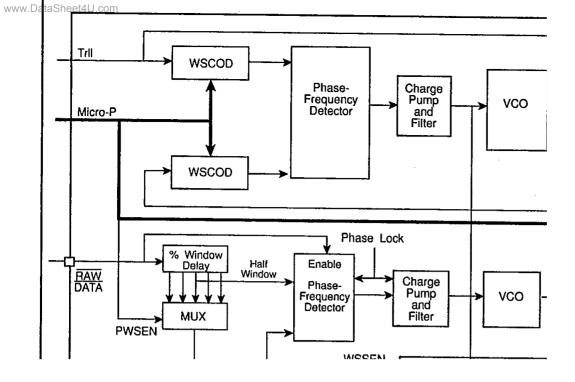
#### 4.2.3 RCLK Source

In the WD10C27 architecture, it is assumed that the hard disk controller will be using RCLK during write commands as its NRZ reference clock, WCLK. To accommodate write times (i.e., Fassertion), RCLK reference without sociated with as Synchronizer's relonset and termina cy Synthesizer of divided down to the RCLK output tion, RCLK will be clock cycles to pevide a glitch-free F

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wwwThesVOO ring oscillator architecture is fully integrated, allowing for precise compensation of temperature, voltage, processing, and aging effects. The VCO operates at three times the NRZ data rate (two times the channel rate) and is divided down to the NRZ data rate at the RCLK output.

The WD10C27 optimizes loop gain and bandwidth using fre-quency information obtained via the processor interface. PLL characteristics are modified at pre-determined frequency bands, selectable via the frequency band selection bits FBS0 and FBS1 in the CFG register.

#### 4.3.2 Window Generation

The Data Synchronizer utilizes Western Digitals proven DLL technology to generate precision

#### 4.3.3 Window Moi

Window monitoring I spection of the DE Window centering rising edges are cer of WINCLK. With th multiplex test) bit acl outputs will reflect to ut of the phase defrequency up errors, frequency down errors signals may be us amplifier envelope ding.

Window monitoring WMEN bit in the c WMEN is not set, the puts will be held low

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www.Ddataerate.m Both methods may be used simultaneously.

#### Window Shift Synthesizer

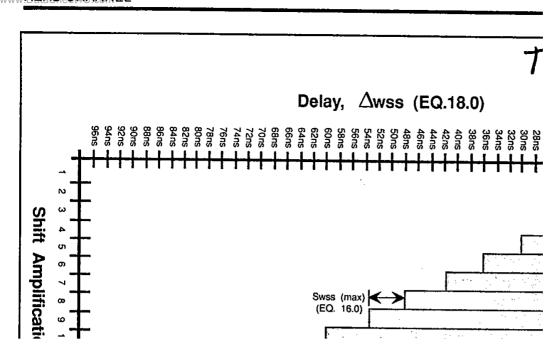
The Window Shift Synthesis (WSS) system employed on the WD10C27 uses information programmed through the micro-processor interface to synthesize virtually any value of window shift which may be desired. Synthesis is achieved in a manner similar to the Frequency Synthesizer.

The WSS, using T<sub>RLL</sub> as its reference, synthesizes the user selected delay value in a servo controlled delay element. Delay elements may be

programmed esser range of 2ns to 6ns are chained backdelay line which se mable amplification the servo delay ele of 2ns to 96ns is delayed raw data leading edge of the

WSS is enabled by the CFG register.

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### www.DWSS Divider/Shift Amp. Operation

The digital portion of the synthesizer consists of a Clock Oscillator Divider to divide the input reference (T<sub>RLL</sub>), and a VCO Divider to divide the VCO output. The T<sub>RLL</sub> input frequency is divided down based on the contents of the WSCOD register. The VCO output frequency from the PLL is similarly divided, based on the contents of the WSVCOD register, to match the frequency output of the WSCOD.

The VCO design utilizes 4.5 double inverting stages in a ring oscillator architecture. When phase-frequency lock is achieved on the output of the WSCOD, the delay through each VCO stage will be precisely controlled. These stages are duplicated in the Shift Amplifier to generate a precision delay line. The delay may be applified

**EQ. 12.0** 18.52 MHz

Note that to proga value of N-1 mu

The WSCOD and bits respectively. values are detern 12.0 as follows.

For the legal rang WSS VCO range have

EQ 13.0 <u>Fwsvco (min) ≤ V</u> Fwspll (max)

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Fwsvco = 
$$\frac{1000}{9 \times \delta wss}$$

Combining EQ. 2.0, EQ. 4.0, and EQ. 15.0, we derive the relationship

EQ. 16.0 
$$\delta$$
wss =  $\left(\frac{\text{Trll}}{9}\right) \left(\frac{\text{WSCOD} + 1}{\text{WSVCOD} + 1}\right)$ 

Since the SAM may amplify  $\delta wss$  from one to sixteen times, the legal SAM values are bounded by

**EQ. 17.0** 
$$1 \le SAM + 1 \le 16$$

### Percentage Windo

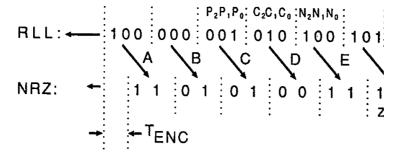
The Percentage W allows for window s window, T. This sysimple to use and Window shifting car 12.5% of T using thi

PWS is enabled by the CFG register, v are selected by p PWS1 bits in the CF

PWS1	PWS0
0	0
0	1

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## Code Word Relationship



## Decode Table Entry

	$P_1 P_0 C_2 C_1 C_0 N_2 N_1 \longrightarrow Z_1 Z_0$
A) Case 9	XX10000-11
A) Case 9 B) Case 1 C) Case 2	$\begin{array}{c} 0000000 \longrightarrow 01 \\ 0000101 \longrightarrow 01 \end{array}$

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www.D	ataSheet4l	1,7 RLL Code Word			NRZ Data Word
	No.	Previous P <sub>1</sub> P <sub>0</sub>	Current C <sub>2</sub> C <sub>1</sub> C <sub>0</sub>	Next N <sub>2</sub> N <sub>1</sub>	NRZ Z <sub>1</sub> Z <sub>0</sub>
	1	00	000	00	01
	2	00	000	01	01
	3	00	000	10	01
	4	00	001	00	01
	5	00	001	01	01
	6	00	010	00	11
	7	00	010	01	10
	8	00	010	10	10
	9	00	100	00	11
	10	00	100	01	11
	11	00	100	10	11

If the Decoder se decode word, the N either a "00" or "11 ERRPAT bit in the (DECERR bit will be error has occurred. legal RLL seque 8T8T...8T, 8T7T, 37 these sequences at encode rules. Since the decode, these states in the decode

The NRZ data word the channel rate Synchronizer. The I the Data Synchroniz at the RDATA outp

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www.appropriatem DAC registers and activating the DACEN bit.

# 4.5.1 Frequency Control (FCDAC)

The Frequency Control DAC, FCDAC, has been specifically designed to allow for bandwidth optimization of the read channel. In a typical variable frequency application, selection of the channel bandwidth is made based on signal-to-noise ratio and recording frequency considerations.

FCDAC is a current DAC whose compliance is set by an external current reference applied at the IREF input. FCDAC is enabled and programmed via the FCDAC register described in section 2.1.5, "Channel Control Registers." progression. When SSI3040, this state will assume a nomi

Note that after ARS zero count but will without modifying boost configuration

### 4.5.3 Hysteresis

Hysteresis Contro specifically designe controlled threshold DAC whose compliratio of the voltage LEVEL voltage and tional to the VRG

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#### www.5.0aSheeWRITE CHANNEL

The Write Data Conditioner processes the NRZ write data (WDATA) from the hard disk controller. Encoded data is resynchronized from the encoder off of the crystal reference from the Frequency Synthesizer (TRLL) to remove any sources of timing jitter. The re-conditioned write data is sent out to the write channel electronics on the WPCDATA pin, where high-to-low transitions represent the accurate crystal controlled timing edges. When WGATE is inactive, the Write Data Conditioner sleeps to conserve power. WPCDATA is held high during this time.

#### 5.1 ENCODER

Upon assertion of ENCEN and after some synchronization delay, WDATA is shifted into a

ENODD is inactive ( such that the NRZ da N<sub>0</sub>N<sub>7</sub>, etc., are enco transition on WDATA 0.

Case	NRZ Data Wo	
No.	Current C <sub>1</sub> C <sub>0</sub>	
1	00	
2	00	-
3	00	
4	00	_
5	00	_

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www. Since ENCEN is asserted prior to gap during formats, and prior to data fields during writes, the odd/even framing requirement must be consistent. This implies that the synchronization byte usually written just after the synchronization field and the gap data must both have either odd or even framing.

# 5.1.2 Framing in Soft Sector Formats

Framing must be re-established following the insertion of address marks via AME. While ENODD is used to establish framing following assertion of ENCEN, AMODD is similarly used following assertion of AME.

Following the address mark generation, WDATA is once again encoded and shifted out to WPCDATA Because WDATA must be could be less than a could be c

Framing following have to be the synchronization by data fields, framin This is due to the sistent between synchronization by consistent following fields) or ENCEN (c

# 5.2 PATTERN [ PRECOMP!

Write precompens plementation of a metric precompens matrix is defined diagonal while be

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""One exception to the skew-symmetric rule is the inclusion of the 2T/2T pulse period pair. This pair has a matrix entry to account for write induced peak shift on 2T runs. Also note that although entries exist for 7T8T and 8T7T pulse period pairs, these are pairs which cannot be realized by virtue of the encode rules (8T8T is another such pair, although it has no entry due to its position along the diagonal). These entries may however be utilized at the gap-to-Address Mark transition.

The Pattern Recognizer has been designed to recognize two special cases of run length violations which can occur in soft sector applications during formats: pulse periods greater than 8T (i.e. 12T) generated in the Address Mark; pulse periods less than 2T or greater than 8T (i.e. 1T or 9T) generated at the gap-to-Address Mark transi-

dress Mark transit well as WPCDATA

Coarse	Coarse
1	0
0	0
0	0
0	0
0	0
0	1
0	1
0	1
0	1
1	0

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Write precompensation is enabled through the micro-processor interface by activating the WPCEN bit in the CFG register. Precompensation takes place by means of a pattern detector which determines the distance of the previous and next bits to the current bit. The pulse period pair which has been detected addresses the WPC registers, keeping track of the order of the pulse periods, or sign. This information is passed to the Write Precompensation circuits for appropriate phase shifting of the WPCDATA output.

The WPC registers have two bits for coarse precompensation selection and two bits for fine resolution, both based on a percentage of the code bit window, T. The value of the coarse setting will be summed with the value of the fine

setting to produce value, as depicted i Selection".

RLLEN must be se to utilize the fine re is disabled, the Rai performs fine resolution powered down and the WPC registers in needs time to acquience, this bit shoul of a write operation specifications of the

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# www6.0 a Sheep OWER ON RESET

The Power On Reset (POR) circuit in the WD10C27 has been designed to guarantee configuration upon activation of the system +5 volt power supply. POR provides a reset pulse derived from a time-lag circuit which slaves off of the power supply ramp.

POR is used to set the ARSTPDN bit in the Configuration register. (See section 2.1.1, "Configuration Registers"). In this way, the WD10C27 will be

guaranteed to powith all registers the PORT0/1 bit which are otherwi

ARSTPDN must configured before mence.

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# www.7.0 SheePERFORMANCE SPECIFICATIONS

#### 7.1 MAXIMUM RATINGS

Maximum limits indicate where permanent device damage occurs. Contir is not intended and should be limited to those conditions specified in the

PARAMETER	RATING	UNIT
V <sub>DD</sub> with respect to V <sub>SS</sub>	+7	٧
Voltage on any pin with respect to Vss (ground)	-0.5 to +7	٧
Ambient Operating Temperature (T <sub>A</sub> )	0 to 70	.C

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SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS
PIN(S): A	MD, RDATA, RCLK	EDATA, RCLK         put High Voltage       2.4       V         put Low Voltage       0.4       V         put Leakage Current       -10       +10       μA         put Rise Time       2.5       nS         put Fall Time       2.1       nS         K, DELRD, WPCDATA			
VoH	Output High Voltage	2.4			V
Vol	Output Low Voltage			0.4	V
lork	Output Leakage Current	-10		+10	μА
T <sub>RF</sub>	Output Rise Time			2.5	nS
PIN(S): AMD, RDATA, RCLK           VOH         Output High Voltage         2.4           VOL         Output Low Voltage         0.4           IOLK         Output Leakage Current         -10         +10           TRF         Output Rise Time         2.5           TFL         Output Fall Time         2.1           PIN(S): WINCLK, DELRD, WPCDATA	nS				
PIN(S): W	INCLK, DELRD, WPCDATA	l	<u></u>	<u> </u>	<u></u>
Vон	Output High Voltage	2.4			V

www.	SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS
	PIN(S): AI WCLK	D7-0, MWE, MRE, MCS, ALE,	AME, EN	CEN, F	RGATE,	LPF (te
	ViH	Input High Voltage	2.0	1.4		٧
	VIL	Input Low Voltage		1.4	0.8	V
	lilk	Input Leakage Current	-10		+10	μΑ

TABLE 7-4. INPUT RECEIVERS DC SPECIFICA

SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS
--------	----------------	-----	-----	-----	-------

www.	DSYMBOLO T	CHARACTERISTIC	MIN	TYP	MAX	UNITS
	<b>PIN(S):</b> DS	SPMP, VCON	<u> </u>	·	<u> </u>	<u> </u>
	VHFCA	VCO High Freq. Clamp Act. Voltage †	TBD		TBD	V
	VHFCD	VCO High Freq. Clamp De- act. Voltage †	TBD		TBD	V
	V <sub>LFC</sub>	VCO Low Frequency Clamp Voltage ‡	TBD		TBD	٧
	IHFC	VCO High Frequency Clamp Current †	TBD		TBD	mA
	ILFC	VCO Low Frequency Clamp Current ‡	TBD		TBD	mA

TABLE 7-6. DATA SYNCHRONIZER INTERNAL VCO DC 5

SYMBOL SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS
PIN(S): V	RG, LEVEL, HCDAC				·
V <sub>RG</sub>	External Voltage Reference	2.2			V
V <sub>RC</sub> †	Internal Level Shift Accuracy				mV
VLEV	LEVEL Input Voltage - VRC	0	+0.7		V
Voffset	Output Offset Voltage (code zero)		15		mV mV
LSB	Resolution (5-bit)		V <sub>LEV</sub> /31		V
GAIN	Gain Accuracy		-		%
INL	Integral Non-Linearity				LSB
DNI	Differential Non-Linearity	<u> </u>			LCD

WWW.DataShactal cor	CHARACTERISTIC	MIN	TYP	MAX	UNITS
PIN(S): IR	EF, VRG, FCDAC			<u> </u>	
V <sub>RG</sub>	External Voltage Reference	2.2		2.45	٧
IREF	External Current Reference	45	60	96	μА
VIREF	IREF Voltage Accuracy			±30	mV
LSB	Resolution (5-bit)		IREF /93		μА
INITIAL	Zero Code Current	7.5	8	8.5	LSB
GAIN	Gain Accuracy			3.5	%
INL	Integral Non-Linearity			±0.5	LSB
DNL	Differential Non-Linearity			±0.5	LSB
C <sub>EXT</sub> †	FCDAC Filter Capacitance	<u> </u>		TRD	nF

#### www703aSheaACcELECTRICAL AND TIMING CHARACTERISTICS

The following specifications are over  $T_A = 0^{\circ}C$  to  $70^{\circ}C$ ,  $T_J = 0^{\circ}C$  to  $90^{\circ}C$ ,  $V_{IM} = 0.4$  (max of 100mV p-p ripple),  $V_{OH} = 2.0$ V,  $V_{OL} = 0.8$ V,  $V_{IL} = 0.4$ V,  $V_{IH} = 2.4$  otherwise specified. When indicated (\*), limits represent characterized value

SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS
IDDA	Active Power Supply Current		20 50	30 75	mA mA
IDDLP1	Power Down Supply Current		15	TBD	mA
IDDLP2	All Power Down Supply Current		13	TBD	mA
T <sub>RDY</sub> *	Time from valid configuration to full operating capability (e.g., lockup of PU s)			3	ms

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www.D	at <b>SYMBOL</b>	CHARACTERISTIC	MIN	TYP	MAX	UNITS
	PIN(S): A	ME, ENCEN, WDATA, WCLK, W	PCDAT	Ā	1	<u> </u>
	tswc	Setup of ENCEN and WDATA to WCLK Rising	5	·		ns
	thwc	Hold of ENCEN and WDATA from WCLK Rising	5			ns
	fNRZ	WCLK Frequency (1/T <sub>NRZ</sub> )	7.5		27	MHz
	tENCON1	ENCEN Rising to Encode On	tswc		tswc +1	T <sub>NRZ</sub>
	tencoff	ENCEN Falling to WPCDATA Off	tswc		tSWC +2	TNRZ
	tENC	WDATA to WPCDATA Encode Delay	15		22	T <sub>NRZ</sub>

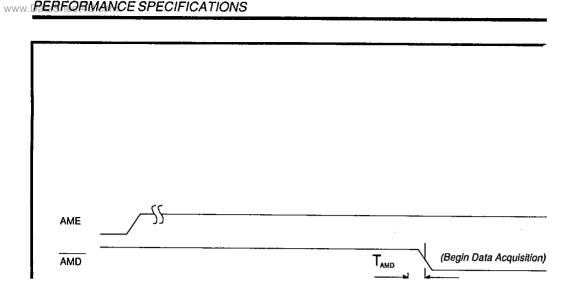
www.D	SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS
	PIN(S): AN	ME, ENCEN, WDATA, WCLK, W	PCDAT	Ā		_
	tswc	Setup of AME to WCLK Rising	5			ns
	thwc	Hold of AME from WCLK Rising	5			ns
	tame	AME Pulse Width	1	·		T <sub>NRZ</sub>
	tENCON2	AME Rising to Encode On			36	T <sub>NRZ</sub>
	tdam	AME to AM on WPCDATA Delay	10		13	T <sub>NRZ</sub>
	tsamg	Setup of AME to End of Gap on WDATA	0			ns
	tam	Address Mark Length			50	T <sub>NRZ</sub>

www.	SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS	
	PIN(S): V	VPCDATA	·	·		L	L
	LSB	Resolution		T <sub>RLL</sub> /64	·		for
ļ	INL	Integral Non-Linearity			±0.5	LSB	
	DNL	Differential Non-Linearity			±0.5	LSB	
	twpc	WPCDATA Pulse Width	11/16		17/16+x	T <sub>RLL</sub>	x is
	twru‡	WPCDATA Timing Jitter			100	ps	one
	twtu‡	WPCDATA Timing Jitter		TBD		ps	one 100 ripr
				TBD		ps	one

www.Data	YMBOL	CHARACTERISTIC	MIN	TYP	MAX	UN
	PIN(S): R	AWDATA, RDATA, RCLK				<u> </u>
t	lDWL	Data Detection Window Loss			+250	F
t	DWC	Data Detection Window Centering Error			± 1.	Ç
t	PWC	Phase Detection Window Centering Error			±2	¢

TABLE 7-15. PHASE & DATA DETECTION WINDOW TII

SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UN
PIN(S): AN	ME AMD RAWDATA ROATA R	ICI K	<del>-</del>		



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NITS	CO
A/rad Ph	nase Lo
A/ A/	rad Pl

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SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS	Γ-
PIN(S): F	SPMP		l			<u> </u>
K <sub>DO</sub> †	Phase Detector Gain. BAND0	TBD		TBD	μΑ/rad	F
K <sub>D1</sub> †	Phase Detector Gain. BAND1	TBD	_	TBD	μ <b>A</b> /rad	P
K <sub>D2</sub> †	Phase Detector Gain. BAND2	TBD		TBD	μΑ/rad	P
K <sub>D3</sub> †	Phase Detector Gain. BAND3	TBD		TBD	μ <b>A</b> /rad	P
Ko <sub>0</sub> †	VCO Gain, BAND0	TBD	_	TBD	rad/s-V	

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SYMBOL	CHARACTERISTIC	MIN	TYP	MAX	UNITS			
PIN(S): ALE, MCS (Chip Select), MRE (Read), MWE (Write), AD7-0 (Add								
TALw	ALE pulse width high	15			ns			
TASALI	Address setup to ALE low	10			ns			
Tahidali	Address hold after ALE low	5			ns			
T <sub>AzRDI</sub>	Read low to Address tri-state			15	ns			
T <sub>RDw</sub>	Read pulse width	110			ns			
TRDhALh	Read high to next ALE high	15			ns			
T <sub>RDax</sub>	Read (data) access time	18		90	ns			
Тимирия	Data hold after Read high	5			ne			

Address Valid

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#### **APPENDIX**

# T-52-

#### A.0 APPLICATION NOTES

#### A-1 FREQUENCY SYNTHESIZER

As discussed in section 3.0, "Frequency Synthesizer", the Frequency Synthesizer utilizes one divider to divide the crystal reference (COD) and one for the VCO (VCOD). This leads to some confusion as to the resolution which can be expected in generating the NRZ data rate.

As can be seen from EQ. 6.0, the output of the Synthesizer is simply a ratio of the crystal input frequency pre-scaled by the HFCOD. That is, for any given crystal frequency, there is a set of ratios

is 1/90. This phenomena repeat ratios. In fact, it can be show tha similarly degrades around multiple a much lesser degree. This prowith the resolution around multiple better an 1/2, but worse than 1/4, 6

Following this same pattern, the I thesizer will have resolutions whic and around integer ratios of the V it can be said that the worst pos will be equal to 1/COD, in the sam

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## www.ARPLICATION NOTES

```
#include <stdio.h, math.h. string.h>
main(argc, argv)
int argc;
char *argv[];
       float fxtli = 0.0;
       float fxtlicod
                           = 0.0;
       float fvco
                           = 0.0;
       float fnrz
                           = 0.0;
       float cod
                           = 1.0;
       float vcod
                          = 1.0;
       char *fxtliptr;
```

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#### A-2 WINDOW SHIFT SYNTHESIZER

For discussion of the resolution, refer to "A-1 Frequency Synthesizer". The following C program is provided to assist in programming the Synthesizer. The program requires as its input the expected data rate. The output will be the exhaustive set of all possible data rates along with the necessary COD and VCOD values. Taking the output of this program and sorting based on the first column (NRZ data rate) produces a convenient look up table of data rates for the given crystal frequency.

#include <stdio.h, math.h, string.h
main(argc, argv)</pre>

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```
fvco = ftclkcod*vcod;
    delta = (1000.0/fvco)/9.0;
    if ((delta <= 6) && (delta >= 2))
    {
        while (SAM 16)
        {
            delay = (SAM*delta);
            wsi = (int) (delay/tclk);
            wsf = (float) wsi;
            ws = 100*(((tclk/2) * ((2*wsf printf("%02f percent (delay = cod =%02f vcod =%02f SAM = %02f/n".ws, delay (vcod-1), (SAM-1)):
            SAM=SAM+1.0;
```