

### VM3500 4, 6 or 8-CHANNEL, 5-VOLT, THIN-FILM HEAD, READ/WRITE PREAMPLIFIER with MULTIPLE SERVO WRITE CAPABILITY

June 24, 1998

### **BLOCK DIAGRAM**

#### vcc GND R/W ¦ нох Mode Select CS 🖯 ноч Read Buffer Read Preamp 6 н1х RDX Ь н1γ RDY Ь н₂х Multiplexer Ь н₂ү WDI <mark>∕</mark> нзх WDI Write Current Ь нзү Switch <sup>Ь</sup> н4х WC Write Current 5 н4ү Source H5X HS0 H5Y ~ Head Select HS1

S0

4 H6X

#### 980624

#### **FEATURES**

- General
  - Single Power Supply (5 V ± 10%)
  - Power Up/Down Data Protect Circuitry
  - Very Low Power Dissipation (3 mW Typical in Sleep Mode)
  - Reduced Write-to-Read Recovery Time
  - Head Inductance Range =  $0.2 1 \mu H (0.54 \mu H Typical)$
  - Write Unsafe Detection
- Available in 4, 6 or 8 Channels
- High Performance Reader
  - Read Gain = 300 V/V Typical
  - Input Noise = 0.5nV/ĐHz Typical
  - Low Input Capacitance = 8 pF Typical
- High Speed Writer
  - Write Current Range 5 25 mA
  - I<sub>W</sub> Rise/Fall Times = 3.3 ns \_  $(L_{H} = 0.54 \ \mu H, I_{W} = 10 \ mA \ b-p)$
  - PECL or TTL Write Data Inputs
  - Multi-Channel Servo Write
  - Write Current Range (Servo) 5 20 mA
  - **Optional Write Data Flip-Flop** -

#### DESCRIPTION

The VM3500 is a high-performance read/write preamplifier designed for use in high-end disk drives. It provides write current control, data protection circuitry, and a low-noise read preamplifier for up to eight channels.

Fault protection is provided so that during power supply sequencing the write current generator is disabled. System write-to-read recovery time is minimized by maintaining the read channel common-mode output voltage in write mode.

Very low-power dissipation from the +5V supply is achieved through use of high-speed bipolar processing and innovative circuit design techniques. When unselected, the device enters a sleep mode, with power dissipation reduced to less than 3mW. In multi-channel servo write mode, all heads are written

simultaneously. The servo mode is activated via the WUS line. The VM3500 is available in several different packages. Please

contact VTC for package availability.



Junction Temperature ..... 150°C

Storage Temperature, Tstg ...... -65° to 150°C

20-lead SSOP ..... 110°C/W

24-lead SSOP ..... 100°C/W

32-lead VSOP ..... 100°C/W

**RECOMMENDED OPERATING CONDITIONS** 

DIS

#### Power Supply Voltage:

Thermal Characteristics,  $\Theta_{IA}$ :

V <sub>CC</sub>	+5V ± 10%
Write current, I <sub>w</sub>	5 to 25mA
Head Inductance, L <sub>H</sub>	0.2 to 1µH
Junction Temperature, T <sub>J</sub> 25	°C to 125°C



#### **CIRCUIT OPERATION**

The VM3500 addresses up to eight two-terminal thin-film heads, providing write drive or read amplification. Mode control is accomplished with pins  $\overline{CS}$  and  $R/\overline{W}$  as shown in Table 1. Head selection is accomplished with pins HS0, HS1 and HS2 as shown in Table 2.

Internal pull-up resistors provided on pins  $\overline{CS}$  and  $\overline{R/W}$  force the device into a non-writing condition if either control line is opened accidentally.

#### Write Mode

The write mode configures the VM3500 as a write current switch with the write current toggled between the X and Y side of the selected head in response to transitions on the WDI/WDI PECL inputs. The write unsafe (WUS) detection circuitry is also activated at this time to drive the output to a low (Safe) condition.

VM3500: Write current is toggled on each low to high transition of WDI/WDI. A preceding read operation initializes the write data flip flop (WDFF) so that upon entering the write mode current flows into the "X" port.

VM3500F: For the VM3500F (without the WDFF), the write current polarity is defined by the levels of WDI/WDI. For WDI > WDI, current flows into the "X" port; for WDI < WDI, current flows into the "Y" port.

An internally-generated 2.5 V reference voltage is present at the WC pin. The write current magnitude is determined by an external resistor connected between the WC pin and ground and is defined by the equation:

$$I_{W} = \left(\frac{K_{W}}{R_{WC}}\right) + 0.3mA = \left(\frac{50}{R_{WC}}\right) + 0.3mA \qquad (eq. 1)$$

#### (0-peak ±10%)

Power supply fault protection improves data security by disabling the write current generator during a voltage fault or power-up. Additionally, the write unsafe circuitry will flag any of the conditions below as a high level on the open collector output pin WUS:

- · No write current
- WDI frequency too low
- Device in read or sleep mode

Two transitions on pin WDI, after the fault is corrected, may be required to clear the WUS flag.

#### **Multi-Channel Servo Write Mode**

In servo write mode, the operation is the same as described above except that all channels are written simultaneously. Servo mode is controlled using the WUS pin.

To initiate servo mode:

- 1. Enter read mode (bring R/W high).
- 2. Select Head 1 (bring HS0 high).
- 3. Supply 10mA source current into the WUS pin.
- 4. Enter servo mode (drop the R/W line low).
- Note: If any other head is selected during servo, the part will exit servo mode and write only the selected head. Unless servo is "formally" exited by removing the 10mA current, servo mode will return whenever head 1 is

selected.

To return to normal operations:

- 1. Enter read mode (bring R/W high).
- 2. Drop the WUS pin (remove the 10 mA current) and return to normal read mode.

#### Read Mode

The read mode configures the VM3500 as a low-noise differential amplifier. The write current reference remains active to minimize the write/read recovery time. The RDX and RDY outputs are emitter followers and are in phase with the "X" and "Y" head ports. These outputs should be AC-coupled to the load.

The RDX, RDY common-mode voltage is maintained in the write mode, minimizing the transient between the write mode and the read mode, thereby substantially reducing the recovery time delay to the subsequent pulse detection circuitry.

#### Sleep Mode

In sleep mode ( $\overline{CS}$  high), most of the circuit is idle and power dissipation is reduced to 3mW typical.

#### Table 1 Mode Select

R/W	CS	MODE
0	0	Write
0	0	Servo*
1	0	Read
Х	1	Idle

\* See (Multi-Channel Servo Write Mode on page 2) for additional detail.

#### Table 2 Head Selection

HS2	HS1	HS0	HEAD
0	0	0	0
0	0	1	1
0	1	0	2
0	1	1	3
1	0	0	4
1	0	1	5
1	1	0	6
1	1	1	7



#### **PIN DESCRIPTIONS**

NAME	<i>I/O</i>	DESCRIPTION
HS0 - HS2	I <sup>1</sup>	Head Selects: Selects one of up to eight heads.
H0X - H7X H0Y - H7Y	I/O	X, Y Head Terminals
WDI, WDI	<sup>1</sup>	Write Data Inputs: PECL input signal; a rising edge toggles direction of head current. (Each transition toggles the direction of head current on the "F" option without the write data flip flop.)
CS	I	Chip Select: A high level signal puts chip in sleep mode; a low level awakens chip.
R/W	<b> </b> 1	Read/Write select: A high level selects read mode. A low-level selects write mode
WUS/SE	O 1	Write Unsafe/Servo Enable: (open collector output) A high level indicates a writes unsafe condition. <b>Note:</b> The WUS pin is also used to enter servo mode. See (Multi-Channel Servo Write Mode on page 2).
WC		Write Current Adjust: A resistor adjusts level of write current.
RDX-RDY	0	Read Data Output: Differential output data.
VCC		+5 volt supply
GND		Ground

### Damping Resistor

Unless otherwise indicated, the VM3500 has damping resistors isolated by Schottky diodes. The diodes effectively remove the resistor from the circuit during the read mode, however during the write mode with the higher level input signal, the resistor provides damping for the write current waveform.



1. May be wire-OR'ed for multi-chip usage.



Recommended operating conditions apply unless otherwise specified.

PARAMETER	SYM	CONDITIONS	MIN	ΤΥΡ	МАХ	UNITS
Power Supply Voltage	V <sub>cc</sub>		4.5	5.0	5.5	V
		Read Mode		34 + 0.05l <sub>w</sub>	50	
		Write Mode, Normal, I <sub>w</sub> = 10mA		34 + 1.05l <sub>w</sub>	60	
VCC Supply Current	I <sub>cc</sub>	Write Mode, Servo, I <sub>w</sub> = 10mA (4-Channel)		55 + 4.3l <sub>w</sub>	125	mA
		Write Mode, Servo, I <sub>w</sub> = 10mA (6-Channel)		100 + 8.6I <sub>w</sub>	225	
		Write Mode, Servo, I <sub>w</sub> = 10mA (8-Channel)		100 + 8.6I <sub>w</sub>	225	
		Sleep Mode		0.5	3	
Power Supply Power Dissipation		Read Mode		175	275	
		Write Mode, Normal, I <sub>w</sub> = 10mA		225	330	- mW
	PD	Write Mode, Servo, I <sub>w</sub> = 10mA (4-Channel)		490	688	
		Write Mode, Servo, I <sub>w</sub> = 10mA (6-Channel)		930	1240	
		Write Mode, Servo, I <sub>w</sub> = 10mA (8-Channel)		930	1240	
		Sleep Mode		3	16.5	
Input High Voltage	V <sub>IH</sub>		2		V <sub>CC</sub> +0.3	V
Input Low Voltage	V <sub>IL</sub>		-0.3		0.8	V
Input High Current	I <sub>IH</sub>	V <sub>IH</sub> = 2.7V			80	μA
Input Low Current	Ι <sub>IL</sub>	$V_{IL} = 0.4V$	-160			μA
WDI, WDI Input High Voltage	V <sub>IH</sub>	Pseudo ECL	V <sub>CC</sub> - 1.5		V <sub>cc</sub> - 0.1	V
WDI, WDI Input Low Voltage	V <sub>IL</sub>	Pseudo ECL	V <sub>IH</sub> - 1.5		V <sub>IH</sub> - 0.25	V
WDI, WDI Input High Current	I <sub>IH</sub>	$V_{IH} = V_{CC} - 0.7V$			100	μA
WDI, WDI Input Low Current	IL	$V_{\rm IH} = V_{\rm CC} - 1.6V$			80	μA
WUS Output Low Voltage	V <sub>OL</sub>	I <sub>OL</sub> = 4.0mA		0.35	0.5	V
WUS Output High Current	I <sub>OH</sub>	V <sub>OH</sub> = 5.0V		13	100	μA
VCC Value for Write Current Turn Off		I <sub>H</sub> < 0.2mA	3.3	3.6	4.0	V
WUS Servo Enable	I <sub>SE</sub>		10	1	20	mA

1. The typical value for servo activation is 6 mA. The minimum value at which servo activation is guaranteed is 10 mA.



#### WRITE CHARACTERISTICS

Recommended operating conditions apply unless otherwise specified;  $L_{H} = 0.54 \mu H$ ,  $R_{H} = 20$ <sup>3</sup>/<sub>4</sub>,  $I_{W} = 10 mA$ ,  $f_{DATA} = 5 MHz$ .

PARAMETER	SYM	CONDITIONS	MIN	TYP <sup>1</sup>	MAX	UNITS
WC Pin Voltage	$V_{WC}$			2.5		V
I <sub>WC</sub> to Head Current Gain	A			20		mA/mA
Write Current Constant	K <sub>w</sub>	$V_{CC} = 5V \pm 10\%$	45	50	55	V
Write Current Range	I <sub>W</sub>	10.64k¾ > R <sub>WC</sub> > 2k¾	5		25	mA
Write Current Tolerance	$\Delta I_W$	V <sub>CC</sub> ±10%	-10		+10	%
Write Current Tolerance Servo	$\Delta I_W$	V <sub>CC</sub> ±10%	-14		+14	%
Differential Head Voltage Swing	$V_{\text{DH}}$	Open head @ VCC = 4.5V	5.4	6.0		Vp-p
WDI Transition Frequency for Safe Condition	f <sub>DATA</sub>	WUS = low	1			MHz
Differential Output Capacitance	C <sub>OUT</sub>				10	pF
Differential Output Resistance	R <sub>OUT</sub>		3.2			k¾
Unselected Head Current	I <sub>UH</sub>	I <sub>W</sub> = 25mA		0.15	0.5	mA(pk)
RDX, RDY Common Mode Output Voltage	V <sub>CM</sub>			V <sub>CC</sub> - 2.7		V

1. Typical values are given at  $V_{CC}$  = 5V and  $T_{A}$  = 25°C.

#### **SERVO WRITE**

PARAMETER	SYM	CONDITIONS	MIN	ΤΥΡ	MAX	UNITS
Write Current Matching Between Channels	$\Delta I_W$	5mA < I <sub>w</sub> < 20mA			10	%
Duty Cycle (20mA/head)		$T_A = 25^{\circ}C, t_{s-on} < 50ns^{-1}$			50	%

1. The ambient temperature  $(T_A)$  and servo-on time  $(t_{s-on})$  limitations are consistent with keeping the peak junction temperature under 125°C.



#### **READ CHARACTERISTICS**

Recommended operating conditions apply unless otherwise specified;  $C_L$  (RDX, RDY) < 20pF,  $R_L$  (RDX, RDY) = 1k<sup>3</sup>/<sub>4</sub>.

PARAMETER	SYM	CONDITIONS	MIN	TYP <sup>1</sup>	MAX	UNITS
Differential Voltage Gain	A <sub>v</sub>	V <sub>IN</sub> = 1mVrms, 1MHz	250	300	350	V/V
Pondwidth	D\M	-1dB  Zs  < 5¾, V <sub>IN</sub> = 1mVp-p	50	55		
Danuwium	DVV	-3dB  Zs  < 5¾, V <sub>IN</sub> = 1mVp-p	90	100		INITIZ
Input Noise Voltage	e <sub>in</sub>	BW = 20MHz, $L_{H} = 0, R_{H} = 0$		0.5	0.65	nV/ÐHz
Differential Input Capacitance	C <sub>IN</sub>	V <sub>IN</sub> = 1mVp-p, f = 5MHz		8	12	pF
Differential Input Resistance	R <sub>IN</sub>	$V_{IN} = 1mVp-p, f = 5MHz$	300	750		3⁄4
Dynamic Range	DR	AC input where $A_{\rm V}$ is 90% of gain at 0.2mVrms input	2			mV P-P
Common Mode Rejection Ratio	CMRR	V <sub>IN</sub> = 100mVp-p @ 5MHz	50			dB
Power Supply Rejection Ratio	PSRR	100mVp-p @ 5MHz on V <sub>CC</sub>	45			dB
Channel Separation	CS	Unselected channels: $V_{IN} = 20mVp-p @ 5MHz$ $V_{IN} = 0$ on selected head	45			dB
Output Offset Voltage	V <sub>os</sub>	Steady state read	-300		+300	mV
RDX, RDY Common Mode Output Voltage	V <sub>OCM</sub>	Read/Write Mode		V <sub>CC</sub> - 2.0		
RDX, RDY Common Mode Output Voltage Difference Between Modes	$\Delta V_{OCM}$		-350		+350	mV
Single-Ended Output Resistance	$R_{SEO}$	f = 5 MHz			35	3⁄4
Output Current	Ι <sub>ο</sub>	AC-coupled load, RDX to RDY	±1			mA

1. Typical values are given at  $V_{CC} = 5V$  and  $T_A = 25^{\circ}C$ .



#### SWITCHING CHARACTERISTICS

Recommended operating conditions apply unless otherwise specified;  $I_W = 10mA$ ,  $f_{DATA} = 5MHz$ ,  $L_H = 0.54\mu$ H,  $R_H = 20$ <sup>3</sup>/<sub>4</sub>,  $C_L$  (RDX, RDY) ð 20pF (see Figures 1 and 2).

PARAMETER	SYM	CONDITIONS	MIN	TYP <sup>1</sup>	МАХ	UNITS	
R/W Read to Write Delay	t <sub>RW</sub>	$R/\overline{W}$ to 90% $I_W$		0.06	0.15	μs	1
R/W Write to Read Delay	t <sub>WR</sub>	R/W to 90% of 100mV, 10 MHz read signal envelope		0.2	0.4	μs	MINAL
CS Unselect to Select Delay	t <sub>IR</sub>	$\overline{\text{CS}}$ to 90% I <sub>w</sub> or 90% of 100mV, 10MHz read signal envelope			0.6	μs	2 - TER V/12V PF
CS Select to Unselect Delay	t <sub>RI</sub>	$\overline{\text{CS}}$ to 10% of I <sub>w</sub>			0.6	μs	5
HS0 - HS3 any Head Delay	t <sub>HS</sub>	HS0 - HS3 to 90% of 100mV, 10MHz read signal envelope			0.6	μs	]
WUS Safe to Unsafe Delay	t <sub>D1</sub>		0.6		3.6	μs	
WUS Unsafe to Safe Delay	t <sub>D2</sub>	I <sub>w</sub> = 10mA			1.0	μs	
Head Current Propagation	t <sub>D3</sub>	$L_H = 0$ , $R_H = 0$ , from 50% points			30	ns	
Head Current Asymmetry	A <sub>SYM</sub>	50% duty cycle on WDI, 1ns rise/fall time; $L_{H} = 0$ , $R_{H} = 0$			0.5	ns	
Head Current Rise/Fall Time		10% to 90% points, $L_H = 0$ , $R_H = 0$ , $I_W = 10mA$		1.0	2.0	20	
	ւ <sub>r</sub> / Լ <sub>f</sub>	10% to 90% points, $L_{H} = {}_{540}nH$ , $I_{W} = 10mA$ , $R_{H} = 20\%$		3.3	5.0	115	

1. Typical values are given at  $V_{CC} = 5V$  and  $T_A = 25^{\circ}C$ .



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Figure 2 Write Mode Timing Diagram for VM3500F (without write data flip flop)



# LIST OF SPECIFIC PART VARIATIONS

(described on the following pages)

PART VARIATION	Page Location
VM357830 <sup>1</sup>	10
VM355830	11
VM355830 (28-lead package)	12
VM356630 <sup>1</sup>	13
VM355635	14
VM355630	15
VM355435	16
VM355430	17

1. This part is non-conventional. See the specific page for details.



#### 8-Channel Connection Diagram



Note: This part is non-conventional in the following aspects:

- It has an alternate pin-out (CS is in a different location).
- It has a bank servo mode where 4 heads are written at a time based on the head selected. (See below.)
- It has a nominal damping resistor value of 250  $\Omega$  (Schottky isolated).

#### **Specific Characteristics**

See the general data sheet for common specification information.

#### Multi-Channel Servo Write Mode

In servo write mode, the operation is the same as described in the general datasheet except that four channels are written simultaneously as shown in the table below.

HEAD SELECTED	HEADS WRITTEN
0 or 1	none
2	odd (1,3,5 and7)
3	even (0,2,4 and 6)



#### 8-Channel Connection Diagram



#### **Specific Characteristics**



### VM355830 (28-lead package)

#### 8-Channel Connection Diagram



#### **Specific Characteristics**



#### 6-Channel Connection Diagram



Note: This part is non-conventional in one aspect:

 It has TTL single-ended write data input. Write current is toggled on each high-to-low transition of WDI.

#### **Specific Characteristics**

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#### 6-Channel Connection Diagram



#### **Specific Characteristics**

See the general data sheet for common specification information.

• 350 V/V read gain.

PARAMETER	SYM	CONDITIONS	MIN	ΤΥΡ	MAX	UNITS
Differential Voltage Gain	A <sub>V</sub>	V <sub>IN</sub> = 1mVrms, 1MHz	292	350	408	V/V
Differential Input Capacitance	C <sub>IN</sub>	V <sub>IN</sub> = 1mVp-p, f = 5MHz		10	14	pF
Single-Ended Output Resistance	$R_{SEO}$	f = 5 MHz			50	3⁄4



#### 6-Channel Connection Diagram



**Specific Characteristics** 



#### **4-Channel Connection Diagram**



#### **Specific Characteristics**

See the general data sheet for common specification information.

• 350 V/V read gain.

PARAMETER	SYM	CONDITIONS	MIN	ΤΥΡ	MAX	UNITS
Differential Voltage Gain	$A_{V}$	V <sub>IN</sub> = 1mVrms, 1MHz	292	350	408	V/V
Differential Input Capacitance	C <sub>IN</sub>	V <sub>IN</sub> = 1mVp-p, f = 5MHz		10	14	pF
Single-Ended Output Resistance	$R_{SEO}$	f = 5 MHz			50	3⁄4



#### **4-Channel Connection Diagram**



<u>Specific Characteristics</u> See the general data sheet for common specification information.