DATA SHEET

NEC

MOS INTEGRATED CIRCUIT

μPD753012, 753016, 753017

4-BIT SINGLE-CHIP MICROCONTROLLER

DESCRIPTION

The μPD753017 is one of the 75XL series 4-bit single-chip microcontroller chips and has a data processing capability comparable to that of an 8-bit microcontroller.

It has an on-chip LCD controller/driver with a larger ROM capacity and extended CPU functions compared with the conventional μPD75316B, and can provide high-speed operation. It can be supplied in a small plastic TQFP package (12 × 12 mm) and is suitable for small sets using LCD panels.

For details of functions refer to the following User's Manual.
μPD753017 User's Manual : U11282E

FEATURES

★
- Low voltage operation: V_{DD} = 2.2 to 5.5 V
  - Can be driven by two 1.5 V batteries
- On-chip memory
  - Program memory (ROM):
    12288 × 8 bits (μPD753012)
    16384 × 8 bits (μPD753016)
    24576 × 8 bits (μPD753017)
  - Data memory (RAM):
    1024 × 4 bits
- Capable of high-speed operation and variable instruction execution time for power saving
  - 0.95, 1.91, 3.81, 15.3 μs (at 4.19 MHz operation)
  - 0.67, 1.33, 2.67, 10.7 μs (at 6.0 MHz operation)
  - 122 μs (at 32.768 kHz operation)
- Internal programmable LCD controller/driver
- Small plastic TQFP (12 × 12 mm)
  - Suitable for small sets such as cameras
- One-time PROM: μPD75P3018

APPLICATION

Remote controllers, camera-contained VCRs, cameras, gas meters, etc.

ORDERING INFORMATION

Part number	Package
μPD753012GC-XXX-3B9	80-pin plastic QFP (14 × 14 mm)
μPD753012GK-XXX-BE9	80-pin plastic TQFP (fine pitch) (12 × 12 mm)
μPD753016GC-XXX-3B9	80-pin plastic QFP (14 × 14 mm)
μPD753016GK-XXX-BE9	80-pin plastic TQFP (fine pitch) (12 × 12 mm)
μPD753017GC-XXX-3B9	80-pin plastic QFP (14 × 14 mm)
μPD753017GK-XXX-BE9	80-pin plastic TQFP (fine pitch) (12 × 12 mm)

Remark XXX indicates a ROM code suffix.

In this document, unless otherwise specified, the description is made based on μPD753017 as typical product.

Document No. U10140EJ2V0DS00 (2nd edition)
Date Published December 1997 N
Printed in Japan

The mark ★ shows major revised points.

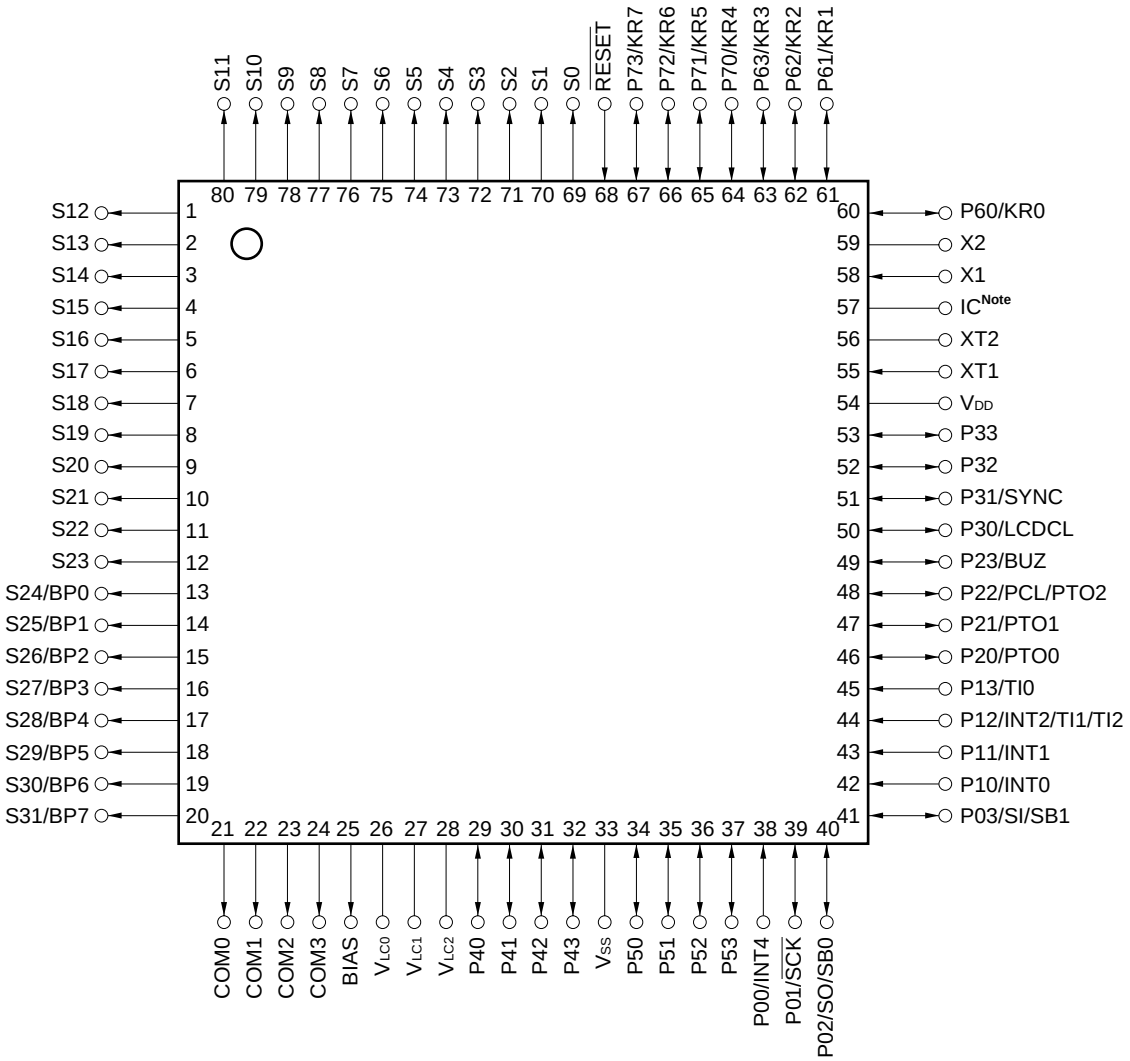
FUNCTIONAL OUTLINE

Parameter			Function
Instruction execution time			• 0.95, 1.91, 3.81, 15.3 μs (main system clock: at 4.19 MHz operation) • 0.67, 1.33, 2.67, 10.7 μs (main system clock: at 6.0 MHz operation) • 122 μs (subsystem clock: at 32.768 kHz operation)
On-chip memory	ROM		12288 × 8 bits (μPD753012)
			16384 × 8 bits (μPD753016)
			24576 × 8 bits (μPD753017)
	RAM		1024 × 4 bits
General-purpose register			• 4-bit operation: 8 × 4 banks • 8-bit operation: 4 × 4 banks
Input/output port	CMOS input	8	On-chip pull-up resistors can be specified by using software: 23
	CMOS input/output	16	
	CMOS output	8	Also used for segment pins
★	N-ch open-drain input/output	8	Withstands 13 V, on-chip pull-up resistors can be specified by using mask option
	Total	40	
LCD controller/driver			• Segment number selection : 24/28/32 segments (can be changed to CMOS output port in 4 time-unit; max. 8) • Display mode selection : Static 1/2 duty (1/2 bias) 1/3 duty (1/2 bias) 1/3 duty (1/3 bias) 1/4 duty (1/3 bias)
			On-chip split resistor for LCD drive can be specified by using mask option
Timer			5 channels • 8-bit timer/event counter: 3 channels (can be used for 16-bit timer/event counter, carrier generator, or timer with gate) • Basic interval timer/watchdog timer: 1 channel • Watch timer: 1 channel
Serial interface			• 3-wire serial I/O mode ... MSB or LSB can be selected for transferring top bit • 2-wire serial I/O mode • SBI mode
Bit sequential buffer			16 bits
Clock output (PCL)			• Φ, 524, 262, 65.5 kHz (main system clock: at 4.19 MHz operation) • Φ, 750, 375, 93.8 kHz (main system clock: at 6.0 MHz operation)
Buzzer output (BUZ)			• 2, 4, 32 kHz (main system clock: at 4.19 MHz operation or subsystem clock: at 32.768 kHz operation) ★ • 2.93, 5.86, 46.9 kHz (main system clock: at 6.0 MHz operation)
Vectored interrupts			External: 3, Internal: 5
Test input			External: 1, Internal: 1
System clock oscillator			• Ceramic or crystal oscillator for main system clock oscillation • Crystal oscillator for subsystem clock oscillation
Standby function			STOP/HALT mode
★ Power supply voltage			V_{DD} = 2.2 to 5.5 V
Package			• 80-pin plastic QFP (14 × 14 mm) • 80-pin plastic TQFP (fine pitch) (12 × 12 mm)

CONTENTS

1. PIN CONFIGURATION (TOP VIEW)

- 80-pin plastic QFP (14 × 14 mm)
  μPD753012GC-XXX-3B9, 753016GC-XXX-3B9,
  μPD753017GC-XXX-3B9
- 80-pin plastic TQFP (fine pitch) (12 × 12 mm)
  μPD753012GK-XXX-BE9, 753016GK-XXX-BE9,
  μPD753017GK-XXX-BE9

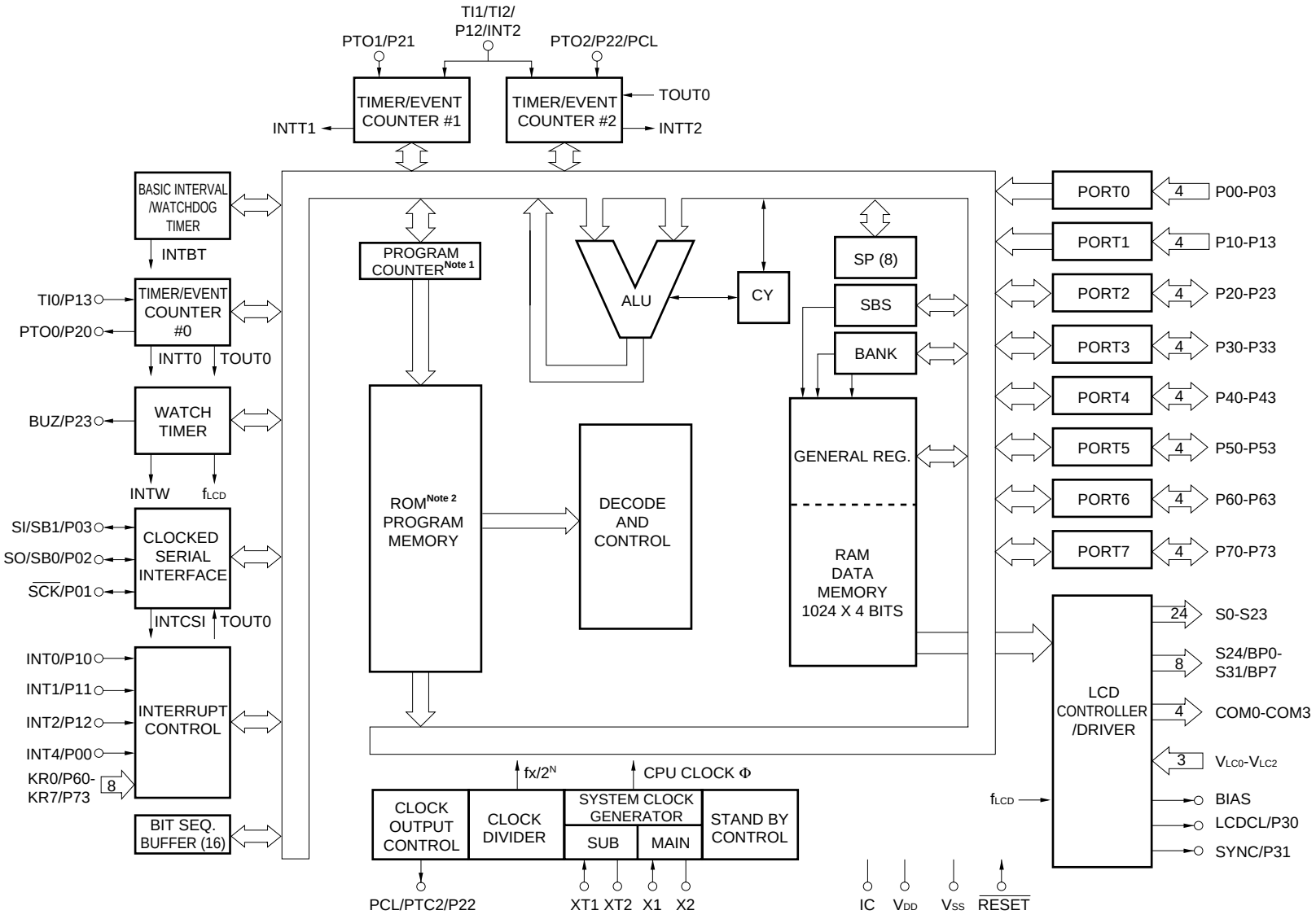


Note Connect the IC (Internally Connected) pin directly to V_{DD}.

Pin Name

P00-P03 : Port 0
P10-P13 : Port 1
P20-P23 : Port 2
P30-P33 : Port 3
P40-P43 : Port 4
P50-P53 : Port 5
P60-P63 : Port 6
P70-P73 : Port 7
BP0-BP7 : Bit Port
KR0-KR7 : Key Return
$\overline{SCK}$: Serial Clock
SI : Serial Input
SO : Serial Output
SB0, SB1 : Serial Bus 0, 1
$\overline{RESET}$: Reset Input
S0-S31 : Segment Output 0-31
COM0-COM3 : Common Output 0-3

V_{LC0}-V_{LC2} : LCD Power Supply 0-2
BIAS : LCD Power Supply Bias Control
LCDCL : LCD Clock
SYNC : LCD Synchronization
TI0-TI2 : Timer Input 0-2
PTO0-PTO2 : Programmable Timer Output 0-2
BUZ : Buzzer Clock
PCL : Programmable Clock
INT0, INT1, INT4 : External Vectored Interrupt 0, 1, 4
INT2 : External Test Input 2
X1, X2 : Main System Clock Oscillation 1, 2
XT1, XT2 : Subsystem Clock Oscillation 1, 2
V_{DD} : Positive Power Supply
V_{SS} : Ground
IC : Internally Connected



Notes 1. μPD753012 and 753016 have a 14-bit configuration, and μPD753017 has a 15-bit configuration.

2. Capacity of the ROM depends on the product.

3. PIN FUNCTION

3.1 Port Pins (1/2)

Pin Name	Input/Output	Dual Function Pin	Function	8-bit I/O	At Reset	I/O Circuit TYPE Note 1
P00	Input	INT4	4-bit input port (PORT0). For P01 to P03, on-chip pull-up resistors can be specified in software in 3-bit units.	×	Input	Ⓑ
P01	Input/Output	$\overline{SCK}$				Ⓕ-A
P02	Input/Output	SO/SB0				Ⓕ-B
P03	Input/Output	SI/SB1				Ⓜ-C
P10	Input	INT0	4-bit input port (PORT1). On-chip pull-up resistors can be specified in software in 4-bit units. Noise eliminator can be selected (Only P10/INT0)	×	input	Ⓑ-C
P11		INT1				
P12		TI1/TI2/INT2				
P13		TI0				
P20	Input/Output	PTO0	4-bit input/output port (PORT2). On-chip pull-up resistors can be specified in software in 4-bit units.	×	Input	E-B
P21		PTO1				
P22		PCL/PTO2				
P23		BUZ				
P30	Input/Output	LCDCL	Programmable 4-bit input/output port (PORT3). This port can be specified input/output in bit units. On-chip pull-up resistor can be specified in software in 4-bit units.	×	Input	E-B
P31		SYNC				
P32		–				
P33		–				
★ P40-P43 Note 2	Input/Output	–	N-ch open-drain 4-bit input/output port (PORT4). A pull-up resistor can be contained bit-wise (mask option). Withstand voltage is 13 V in open-drain mode.	○	High level (when pull-up resistors are contained) or high impedance	M-D
★ P50-P53 Note 2	Input/Output	–	N-ch open-drain 4-bit input/output port (PORT5). A pull-up resistor can be contained bit-wise (mask option). Withstand voltage is 13 V in open-drain mode.		High level (when pull-up resistors are provided) or high impedance	M-D

Notes 1. Circled characters indicate the Schmitt-trigger input.

2. If on-chip pull-up resistors are not specified by mask option (when used as N-ch open-drain input port), low level input leakage current increases when input or bit manipulation instruction is executed.

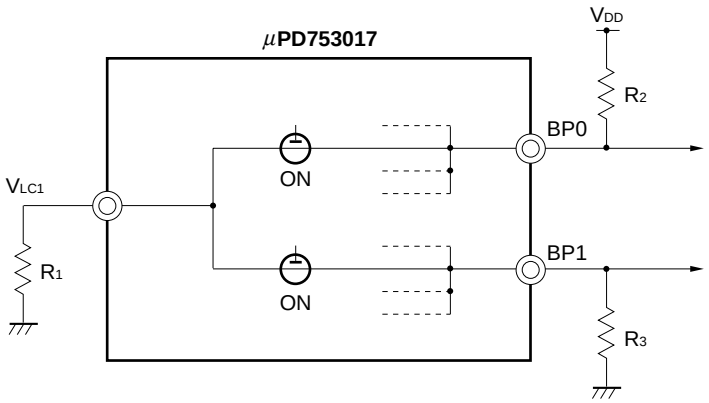
3.1 Port Pins (2/2)

Pin Name	Input/Output	Dual Function Pin	Function	8-bit I/O	At Reset	I/O Circuit TYPE Note 1
P60	Input/Output	KR0	Programmable 4-bit input/output port (PORT6). This port can be specified for input/output bit-wise. On-chip pull-up resistors can be specified in software in 4-bit units.	○	Input	Ⓕ-A
P61		KR1				
P62		KR2				
P63		KR3				
P70	Input/Output	KR4	4-bit input/output port (PORT7). On-chip pull-up resistors can be specified in software in 4-bit units.		Input	Ⓕ-A
P71		KR5				
P72		KR6				
P73		KR7				
★ BP0	Output	S24	1-bit output port (BIT PORT) Also used for segment output pins.	×	**Note 2**	H-A
BP1		S25				
BP2		S26				
BP3		S27				
BP4	Output	S28				
BP5		S29				
BP6		S30				
BP7		S31				

Notes 1. Circled characters indicate the Schmitt-trigger input.

★ **2.** For BP0 to BP7, V_{LC1} is selected as an input source.
The output levels differ depending on BP0 to BP7 and the external circuit of the V_{LC1}.

★ **Example** BP0 to BP7 are connected each other internally in the μPD753017 as shown below. Therefore, the output levels of BP0 to BP7 are determined by the levels of R_1, R_2, and R_3



3.2 Pins Other than Port Pins (1/2)

Pin Name	Input/Output	Dual Function Pin	Function		At Reset	I/O Circuit TYPE Note 1
TI0	Input	P13	Inputs external event pulses to the timer/event counter.		Input	Ⓑ-C
TI1		P12/INT2				
TI2						
PTO0	Output	P20	Timer/event counter output		Input	E-B
PTO1		P21				
PTO2		P22/PCL				
PCL		P22/PTO2	Clock output			
BUZ		P23	Any frequency output (for buzzer output or system clock trimming)			
$\overline{SCK}$	Input/Output	P01	Serial clock input/output		Input	Ⓕ-A
SO/SB0		P02	Serial data output Serial bus data input/output			Ⓕ-B
SI/SB1		P03	Serial data input Serial bus data input/output			Ⓜ-C
INT4	Input	P00	Edge detection vectored interrupt input (both rising edge and falling edge detection)		Input	Ⓑ
INT0	Input	P10	Edge detection vectored interrupt input (detection edge can be selected) Noise eliminator can be selected. (Only P10/INT0)	With noise eliminator asynchronous selection possible	Input	Ⓑ-C
INT1		P11		Asynchronous		
INT2	Input	P12/TI1/TI2	Edge-detection-testable input	Asynchronous	Input	Ⓑ-C
KR0-KR3	Input	P60-P63	Falling edge detection testable input		Input	Ⓕ-A
KR4-KR7	Input	P70-P73	Falling edge detection testable input		Input	Ⓕ-A
S0-S23	Output	–	Segment signal output		**Note 2**	G-D
S24-S31	Output	BP0-BP7	Segment signal output		**Note 2**	H-A
COM0-COM3	Output	–	Common signal output		**Note 2**	G-B
V_{LC0}-V_{LC2}	–	–	LCD drive power On-chip split resistor is enable (mask option).		–	–
BIAS	Output	–	Output for external split resistor disconnect		**Note 3**	–
LCDCL Note 4	Output	P30	Clock output for externally expanded driver		Input	E-B
SYNC Note 4	Output	P31	Clock output for externally expanded driver sync		Input	E-B
X1	Input	–	Crystal/ceramic connection pin for the main system clock oscillator. When inputting the external clock, input the external clock to pin X1, and the reverse phase of the external clock to pin X2.		–	–
X2	–					

Notes 1. Circled characters indicate the Schmitt trigger input.

2. Each displays output selects the following V_{LCX} as input source.
S0-S31: V_{LC1}, COM0-COM2: V_{LC2}, COM3: V_{LC0}.

3. When a split resistor is contained ..... Low level
When no split resistor is contained ..... High impedance

4. These pins are provided for future system expansion. At present, these pins are used only as pins P30 and P31.

3.2 Pins Other than Port Pins (2/2)

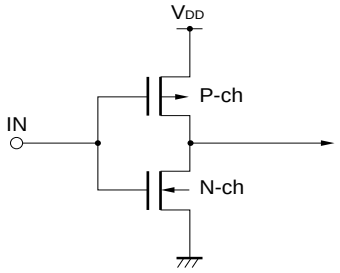
Pin Name	Input/Output	Dual Function Pin	Function	At Reset	I/O Circuit TYPE Note
XT1	Input	–	Crystal connection pin for the subsystem clock oscillator. When the external clock is used, input the external clock to pin XT1. In this case, pin XT2 must be left unconnected. Pin XT1 can be used as a 1-bit input (test) pin.	–	–
XT2	–				
$\overline{\text{RESET}}$	Input	–	System reset input (low level active)	–	Ⓑ
IC	–	–	Internally connected. Connect directly to V_{DD}.	–	–
V_{DD}	–	–	Positive power supply	–	–
V_{SS}	–	–	GND	–	–

Note Circled characters indicate the Schmitt trigger input.

3.3 Pin Input/Output Circuits

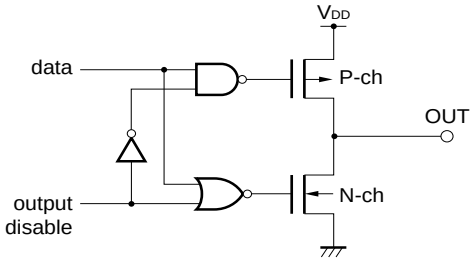
The μPD753017 pin input/output circuits are shown schematically.

TYPE A



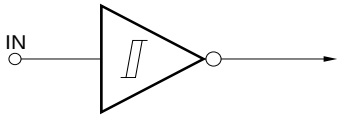
CMOS specification input buffer.

TYPE D



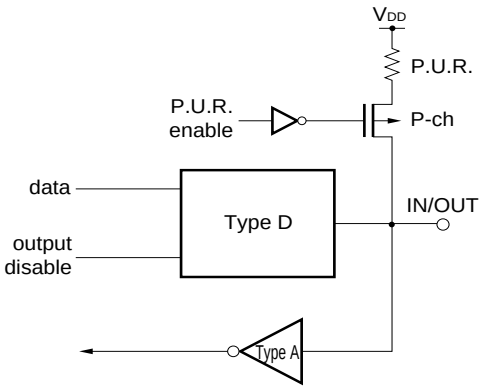
Push-pull output that can be placed in output high impedance (both P-ch, N-ch off).

TYPE B



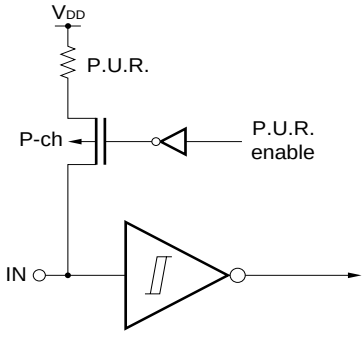
Schmitt trigger input having hysteresis characteristic.

TYPE E-B



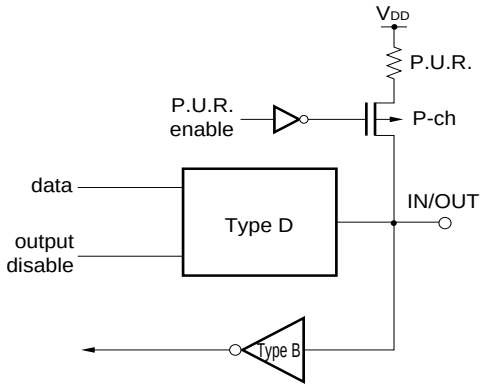
P.U.R. : Pull-Up Resistor

TYPE B-C



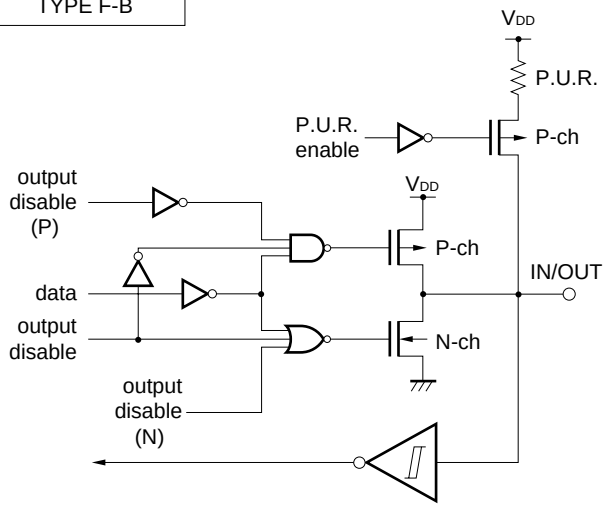
P.U.R. : Pull-Up Resistor

TYPE F-A



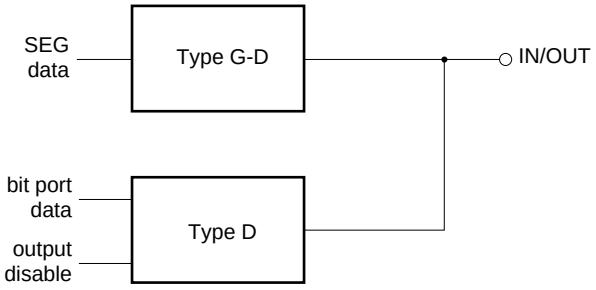
P.U.R. : Pull-Up Resistor

TYPE F-B

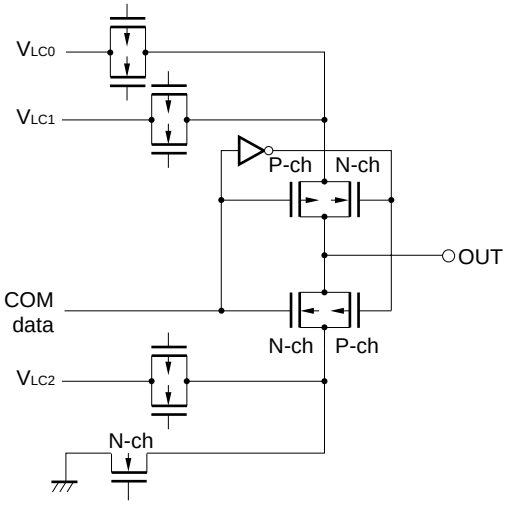


P.U.R. : Pull-Up Resistor

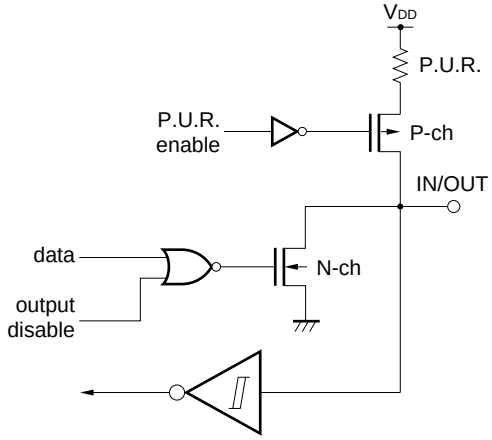
*TYPE H-A



*TYPE G-B

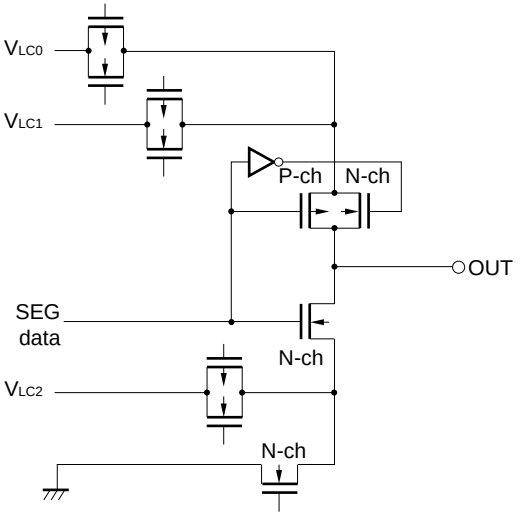


TYPE M-C

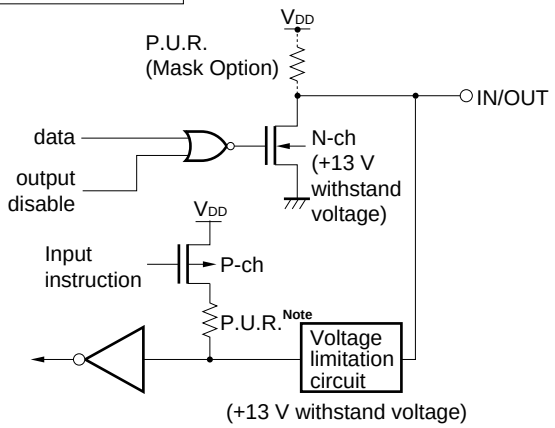


P.U.R. : Pull-Up Resistor

*TYPE G-D



*TYPE M-D



P.U.R. : Pull-Up Resistor

Note This pull-up resistor operates only when an input instruction is executed if the pull-up resistor is not connected by the mask option. (When the pin is at low level, current flows from V_{DD} to the pin.)

3.4 Recommended Connection for Unused Pins

★ **Table 3-1. List of Recommended Connection for Unused Pins**

Pin	Recommended Connection
P00/INT4	Connect to V_{SS} or V_{DD}.
P01/$\overline{SCK}$	Independently connect to V_{SS} or V_{DD} via resistor.
P02/SO/SB0	
P03/SI/SB1	Connected to V_{SS}.
P10/INT0, P11/INT1	Connect to V_{SS} or V_{DD}.
P12/TI1/TI2/INT2	
P13/TI0	
P20/PTO0	Input state : Individually connect to V_{SS} or V_{DD} via resistor. Output state: Leave unconnected.
P21/PTO1	
P22/PTO2/PCL	
P23/BUZ	
P30/LCDCL	
P31/SYNC	
P32	
P33	
P40-P43	Input state : Connect to V_{SS}.
P50-P53	Output state: Connected to V_{SS}. (Do not connect the pull-up resistor by mask option).
P60/KR0-P63/KR3	Input state : Individually connected to V_{SS} or V_{DD} via resistor.
P70/KR4-P73/KR7	Output state: Leave unconnected.
S0-S23	Leave unconnected.
S24/BP0-S31/BP7	
COM0-COM3	
V_{LC0}-V_{LC2}	Connect to V_{SS}.
BIAS	Only if all of V_{LC0}-V_{LC2} are unused, connect to V_{SS}. In other cases, leave unconnected.
XT1	Connect to V_{SS}.
XT2	Leave unconnected.
IC	Directly connect to V_{DD}.

4. SWITCHING FUNCTION BETWEEN MK I MODE AND MK II MODE

4.1 Differences between Mk I Mode and Mk II Mode

The CPU of μPD753017 has the following two modes: Mk I and Mk II, either of which can be selected. The mode can be switched by the bit 3 of the stack bank select register (SBS).

- Mk I mode: Upward compatible with μPD75316B.
  Can be used in the 75XL CPU with a ROM capacity of up to 16K bytes.
- Mk II mode: Incompatible with μPD75316B.
  Can be used in all the 75XL CPU's including those products whose ROM capacity is more than 16K bytes.

Table 4-1. Differences between Mk I Mode and Mk II Mode

	Mk I Mode	Mk II Mode
Program memory (bytes)	• μPD753012 : 12288 • μPD753016, 753017 : 16384	• μPD753012 : 12288 • μPD753016 : 16384 • μPD753017 : 24576
Number of stack bytes for subroutine instructions	2 bytes	3 bytes
BRA !addr1 instruction CALLA !addr1 instruction	Not available	Available
CALL !addr instruction	3-machine cycles	4-machine cycles
CALLF !faddr instruction	2-machine cycles	3-machine cycles

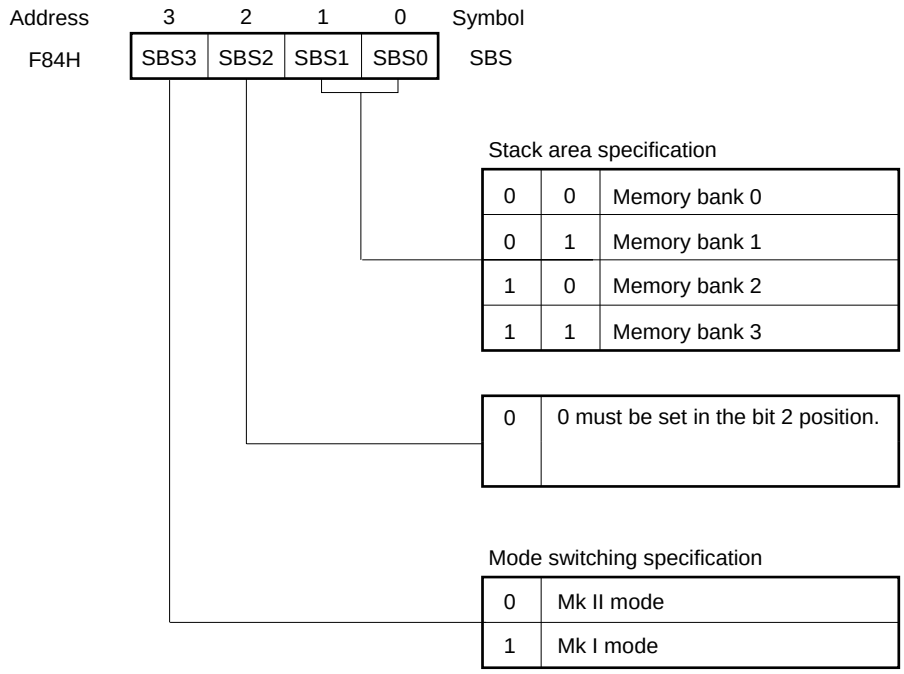
★ **Caution The Mk II mode supports a program area which exceeds 16K bytes in the 75X and 75XL series. This mode enhances the software compatibility with products which have more than 16K bytes.**
When Mk II mode is selected, the number of stack bytes (usable area) in the execution of a subroutine call instruction increases by 1 per stack compared to Mk I mode. Furthermore, when a CALL !addr, or CALLF !faddr instruction is used, each instruction takes another machine cycle. Therefore, when more importance is attached to RAM utilization or throughput than software compatibility, use the Mk I mode.

4.2 Setting Method of Stack Bank Select Register (SBS)

Switching between the Mk I mode and Mk II mode can be done by the SBS. Figure 4-1 shows the format.

The SBS is set by a 4-bit memory manipulation instruction. When using the Mk I mode, the SBS must be initialized to 10XXB[Note] at the beginning of a program. When using the Mk II mode, it must be initialized to 00XXB[Note].

Figure 4-1. Stack Bank Select Register Format



Note The desired numbers must be set in the XX positions.

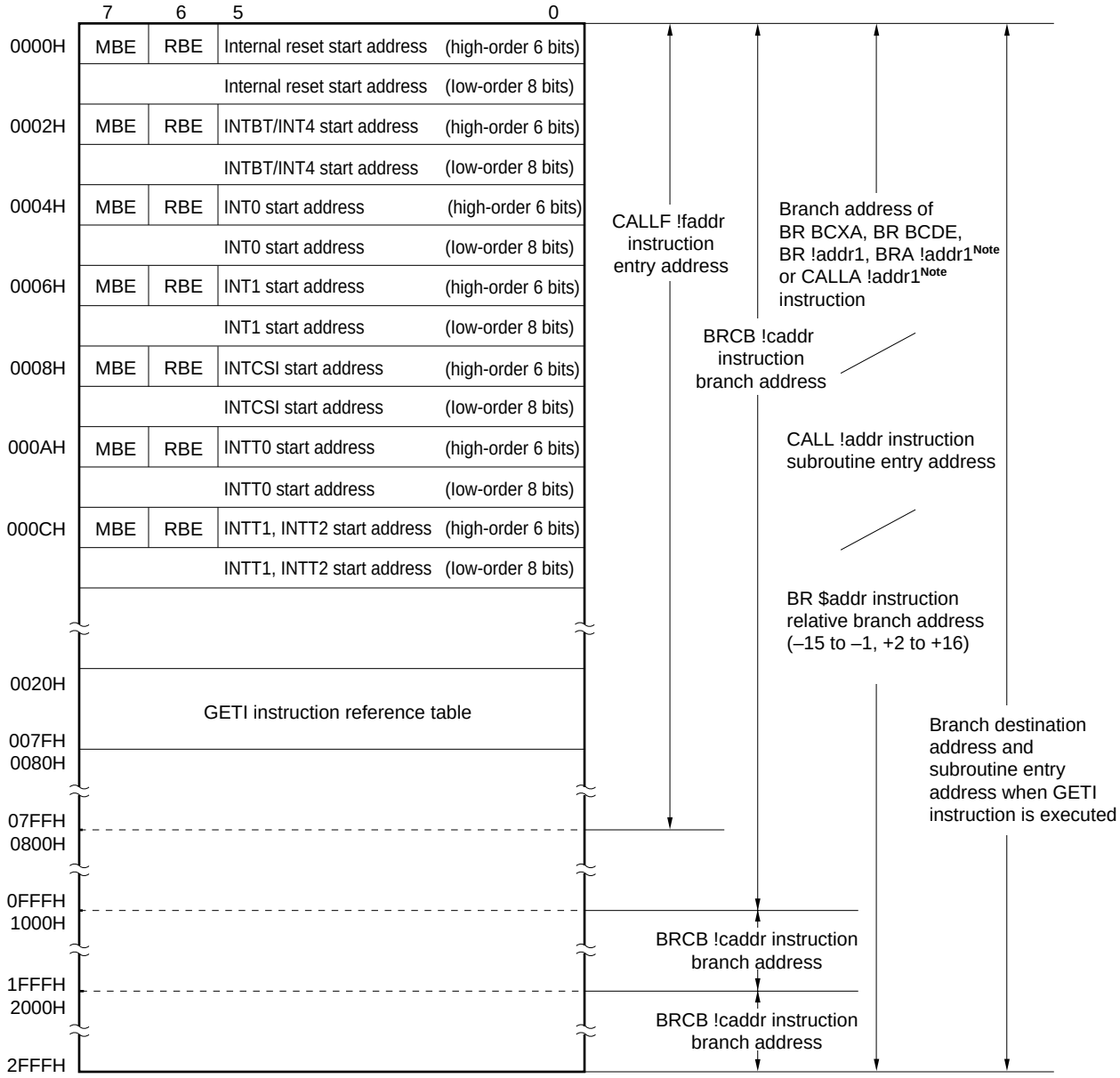
Caution Since SBS. 3 is set to "1" after a $\overline{\text{RESET}}$ signal is generated, the CPU operates in the Mk I mode. When executing an instruction in the Mk II mode, set SBS. 3 to "0" to select the Mk II mode.

5. MEMORY CONFIGURATION

- Program memory (ROM) ..... 12288 × 8 bits (μPD753012)
  ..... 16384 × 8 bits (μPD753016)
  ..... 24576 × 8 bits (μPD753017)
- Data memory (RAM)
  - Data area ...1024 words × 4 bits (000H to 3FFH)
  - Peripheral hardware area...128 × 4 bits (F80H to FFFH)

Figure 5-1. Program Memory Map (1/3)

(a) μPD753012

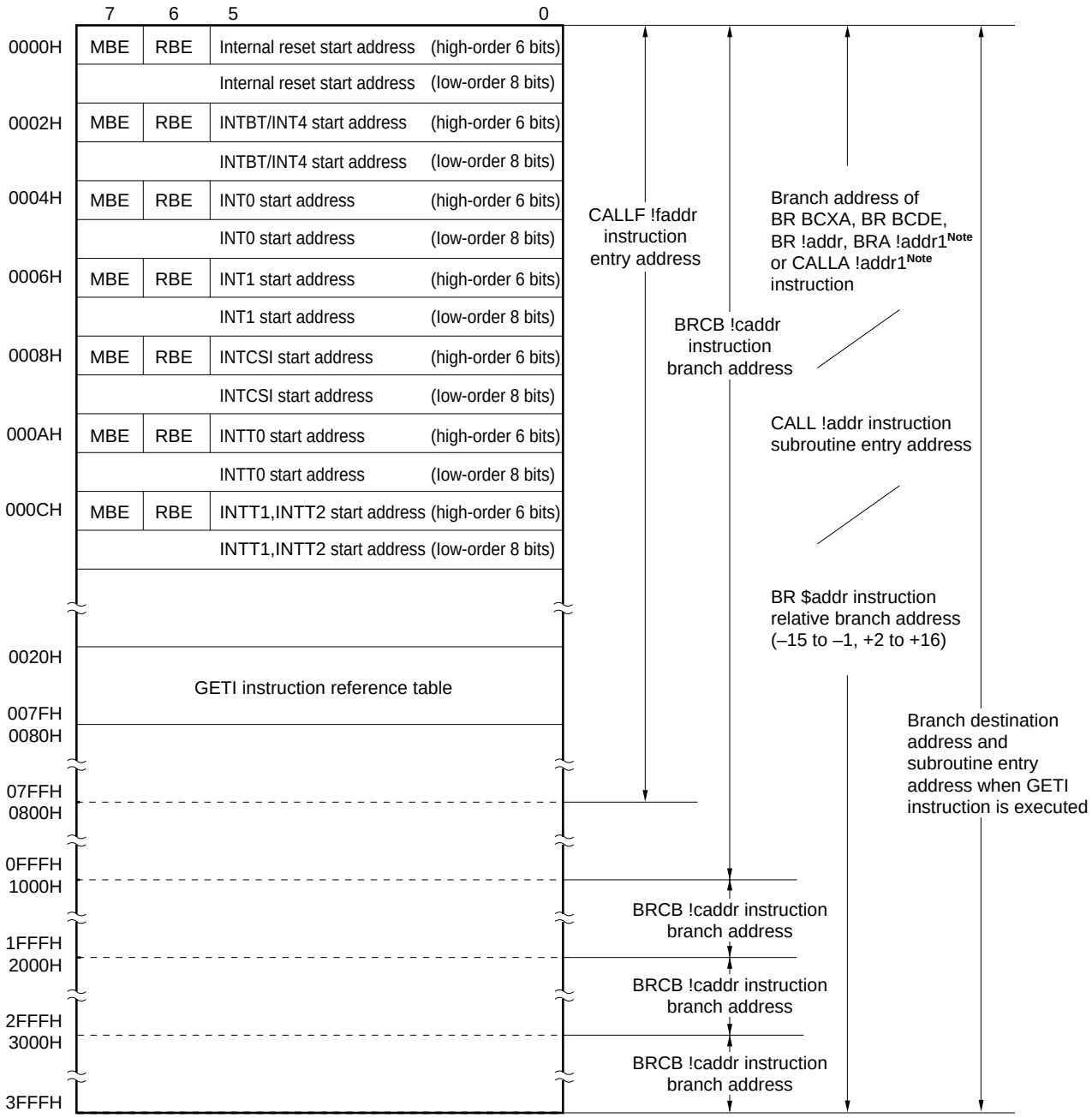


★ **Note** Can be used in Mk II mode only.

Remark In addition to the above, a branch can be taken to the address indicated by changing only the low-order eight bits of PC by executing the BR PCDE, BR PCXA instruction.

Figure 5-1. Program Memory Map (2/3)

(b) μPD753016

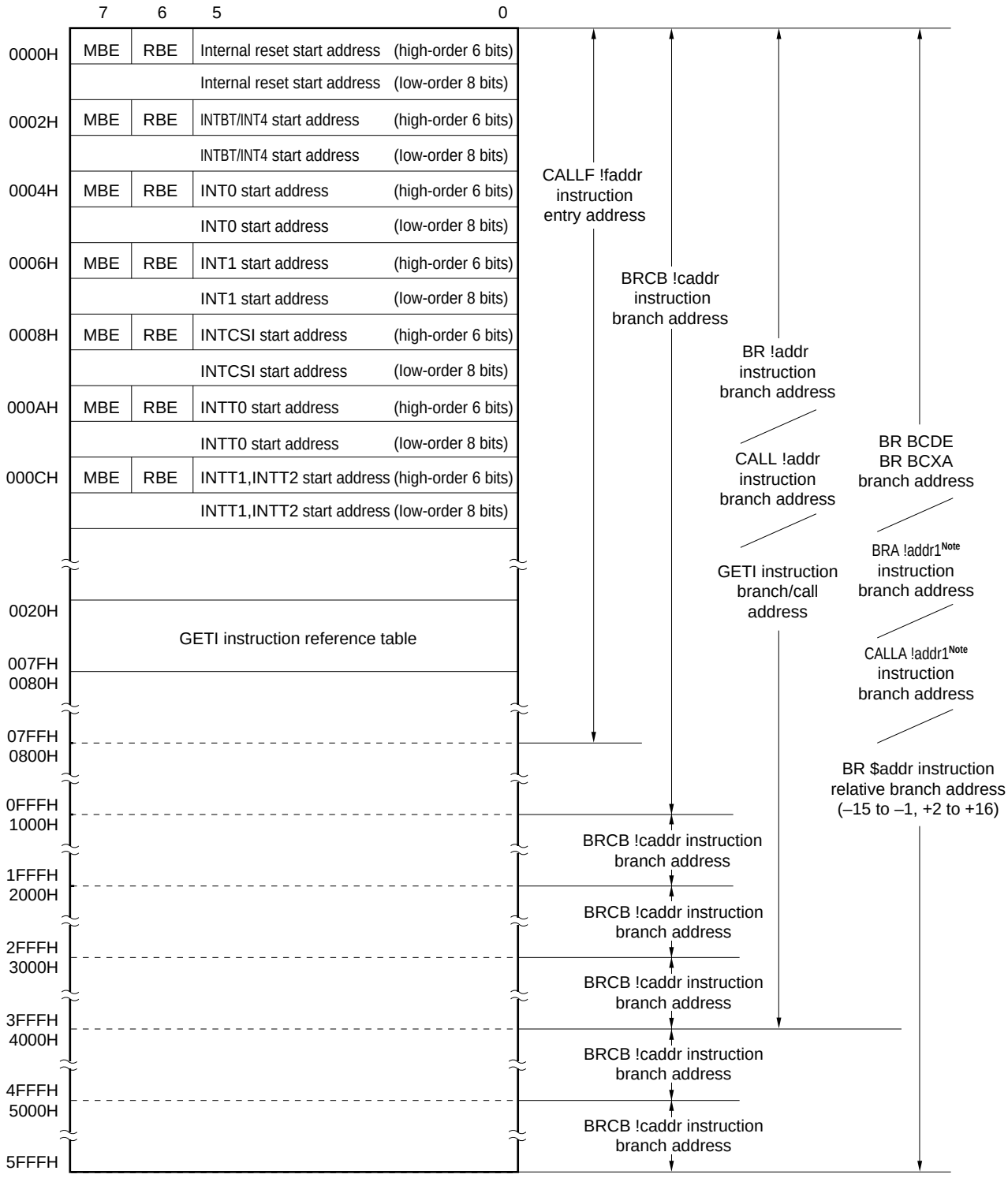


★ **Note** Can be used in Mk II mode only.

Remark In addition to the above, a branch can be taken to the address indicated by changing only the low-order eight bits of PC by executing the BR PCDE, BR PCXA instruction.

Figure 5-1. Program Memory Map (3/3)

(c) μPD753017

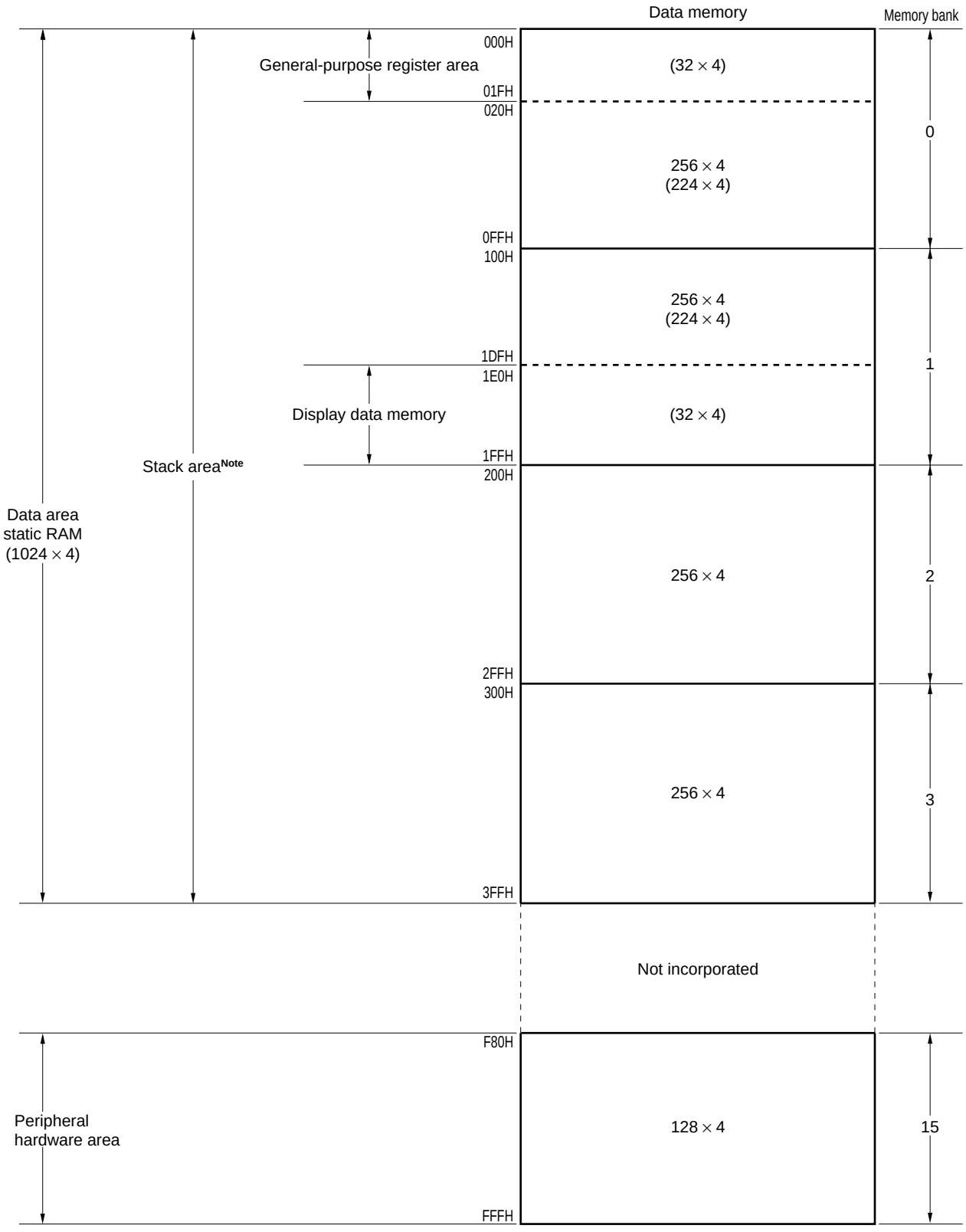


★ **Note** Can be used in Mk II mode only.

Caution The interrupt vector start address shown above consists of 14 bits. Set it in 16K space (0000H-3FFFH).

Remark In addition to the above, a branch can be taken to the address indicated by changing only the low-order eight bits of PC by executing the BR PCDE, BR PCXA instruction.

Figure 5-2. Data Memory Map



Note For stack area, one memory bank can be selected among memory bank 0-3.

6. PERIPHERAL HARDWARE FUNCTIONS

6.1 Digital Input/Output Ports

There are four types of I/O ports as follows.

- CMOS input (PORT0, 1) : 8
- CMOS input/output (PORT2, 3, 6, 7) : 16
- N-channel open-drain input/output (PORT4, 5) : 8
- Bit port output (BP0-BP7) : 8

Total 40

Table 6-1. Types and Features of Digital Ports

Port (Pin Name)	Function	Operation & Features		Remarks
PORT0 (P00-P03)	4-bit input	Dual function pins also function as output pins depending on the operation mode when the serial interface function is used.		Also used for the INT4, SCK, SO/SB0, SI/SB1 pins.
PORT1 (P10-P13)		Dedicated 4-bit I/O port		Also used for the INT0-INT2 and TI0-TI2 pins.
PORT2 (P20-P23)	4-bit I/O	Can be set to input mode or output mode in 4-bit units.		Also used for the PTO0-PTO2, PCL, BUZ pins.
PORT3 (P30-P33)		Can be set to input mode or output mode in 1/4 bit units.		Also used for the LCDCL, SYNC pins.
PORT4 (P40-P43)	4-bit I/O (N-channel open-drain, 13 V withstanding)	Can be set to input mode or output mode in 4-bit units.	Ports 4 and 5 are paired and data can be input/output in 8-bit units.	On-chip pull-up resistor can be specified bit-wise by mask option.
★ PORT5 (P50-P53)				
PORT6 (P60-P63)	4-bit I/O	Can be set to input mode or output mode in 1/4-bit units.	Ports 6 and 7 are paired and data can be input/output in 8-bit units.	Also used for the KR0-KR3 pins.
PORT7 (P70-P73)		Can be set to input mode or output mode in 4-bit units.		Also used for the KR4-KR7 pins.
BP0-BP7	1-bit output	Outputs data bit-wise. Can be switched to LCD drive segment output S24-S31 by software.		—

6.2 Clock Generator

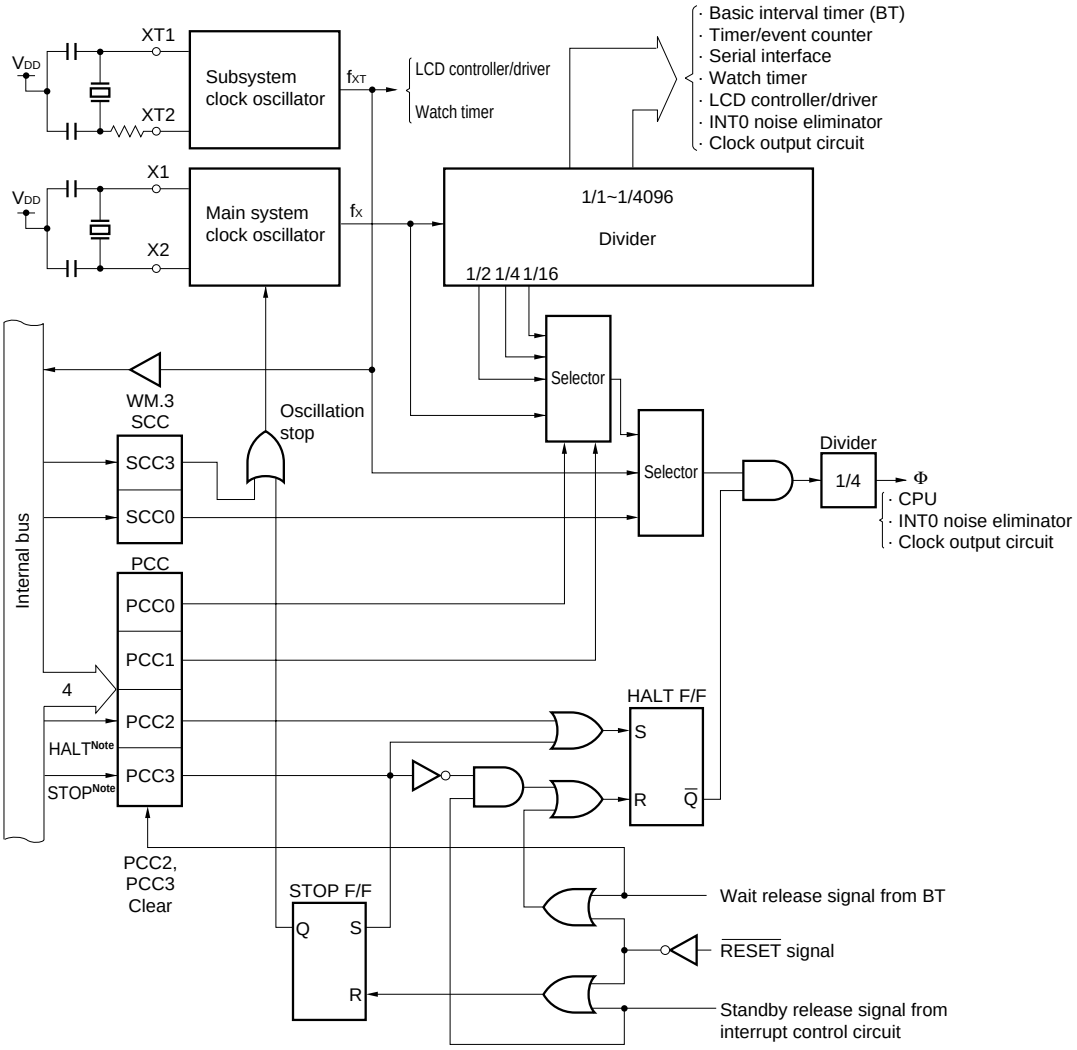
Operation of the clock generator is determined by the processor clock control register (PCC) and system clock control register (SCC).

The two clocks, the main system clock and subsystem clock, are available.

The instruction excution time can be altered.

- 0.95 μs, 1.91 μs, 3.81 μs, 15.3 μs (main system clock : at 4.19 MHz operation)
- 0.67 μs, 1.33 μs, 2.67 μs, 10.7 μs (main system clock : at 6.0 MHz operation)
- 122 μs (subsystem clock : at 32.768 kHz operation)

Figure 6-1. Clock Generator Block Diagram



Note Instruction execution

Remarks 1. f_X = Main system clock frequency

2. f_{XT} = Subsystem clock frequency

3. Φ = CPU clock

4. PCC: Processor Clock Control Register

5. SCC: System Clock Control Register

6. One clock cycle (t_{CY}) of Φ equal to one machine cycle of the instruction.

6.3 Subsystem Clock Oscillator Control Functions

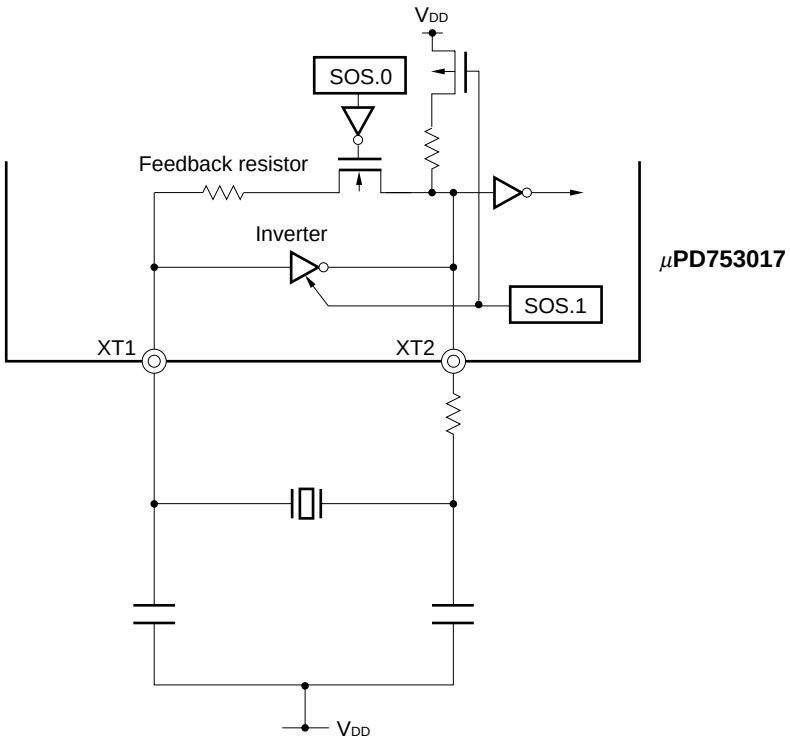
The μPD753017 subsystem clock oscillator has the following two control functions.

- Selects by software whether an on-chip feedback resistor is to be used or not[Note].
- Reduces current consumption by decreasing the drive current of the on-chip inverter when the supply current is high ($V_{DD} \geq 2.7$ V).

★ **Note** When not using the subsystem clock, set SOS.0 to 1 in software (on-chip feedback resistor is not used), connect XT1 to V_{SS}, and leave XT2 unconnected, so that the current consumption of the subsystem clock oscillator can be reduced.

The above functions can be used by switching the bits 0 and 1 of the sub-oscillator control register (SOS). (Refer to **Figure 6-2**.)

★ **Figure 6-2. Subsystem Clock Oscillator**

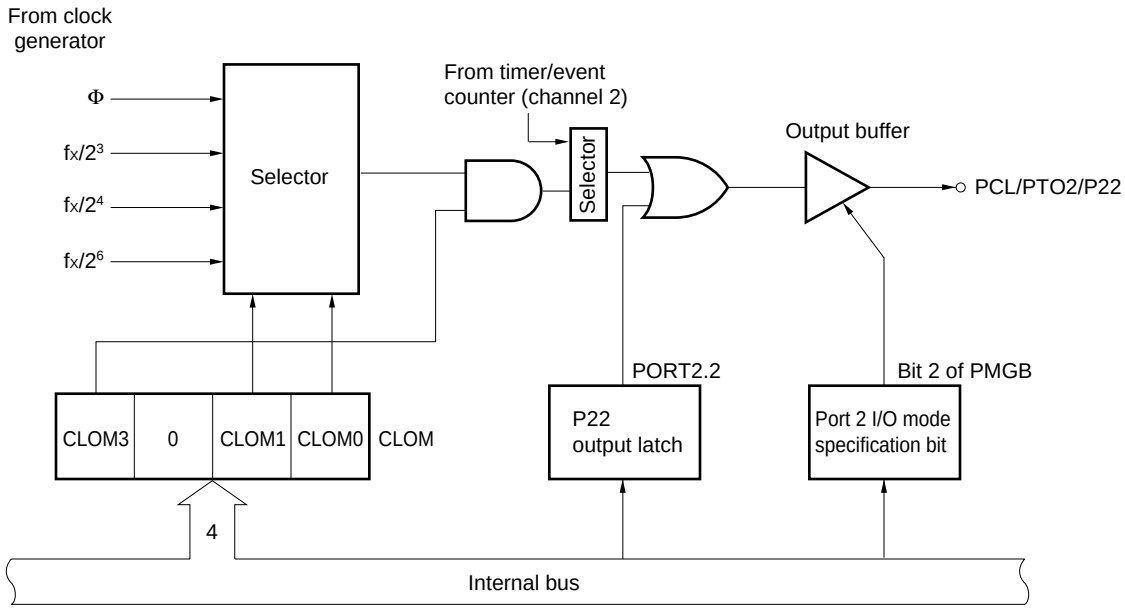


6.4 Clock Output Circuit

The clock output circuit is provided to output the clock pulses from the P22, PTO2, and PCL pins to the remote control waveform outputs and peripheral LSI's, etc.

- Clock output (PCL) : Φ, 524, 262, 65.5 kHz (at 4.19 MHz operation)
  Φ, 750, 375, 93.8 kHz (at 6.0 MHz operation)

Figure 6-3. Clock Output Circuit Block Diagram



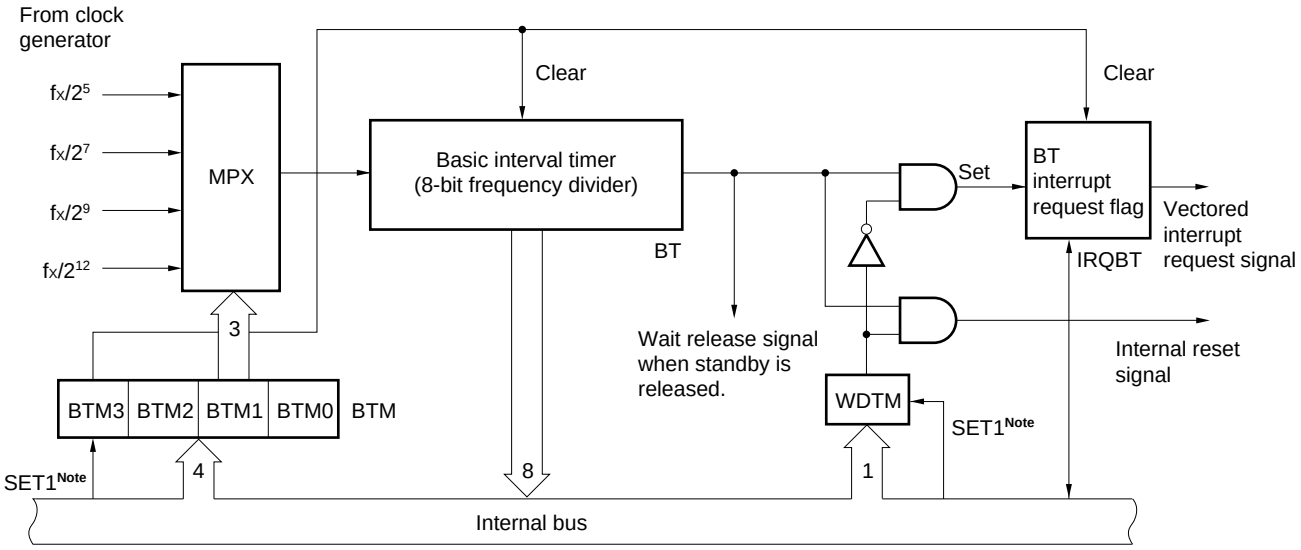
Remark Special care has been taken in designing the chip so that small-width pulses may not be output when switching clock output enable/disable.

6.5 Basic Interval Timer/Watchdog Timer

The basic interval timer/watchdog timer has the following functions.

- Interval timer operation to generate a reference time interrupt
- Watchdog timer operation to detect a runaway of program and reset the CPU
- Selects and counts the wait time when the standby mode is released
- Reads the contents of counting

Figure 6-4. Basic Interval Timer/Watchdog Timer Block Diagram



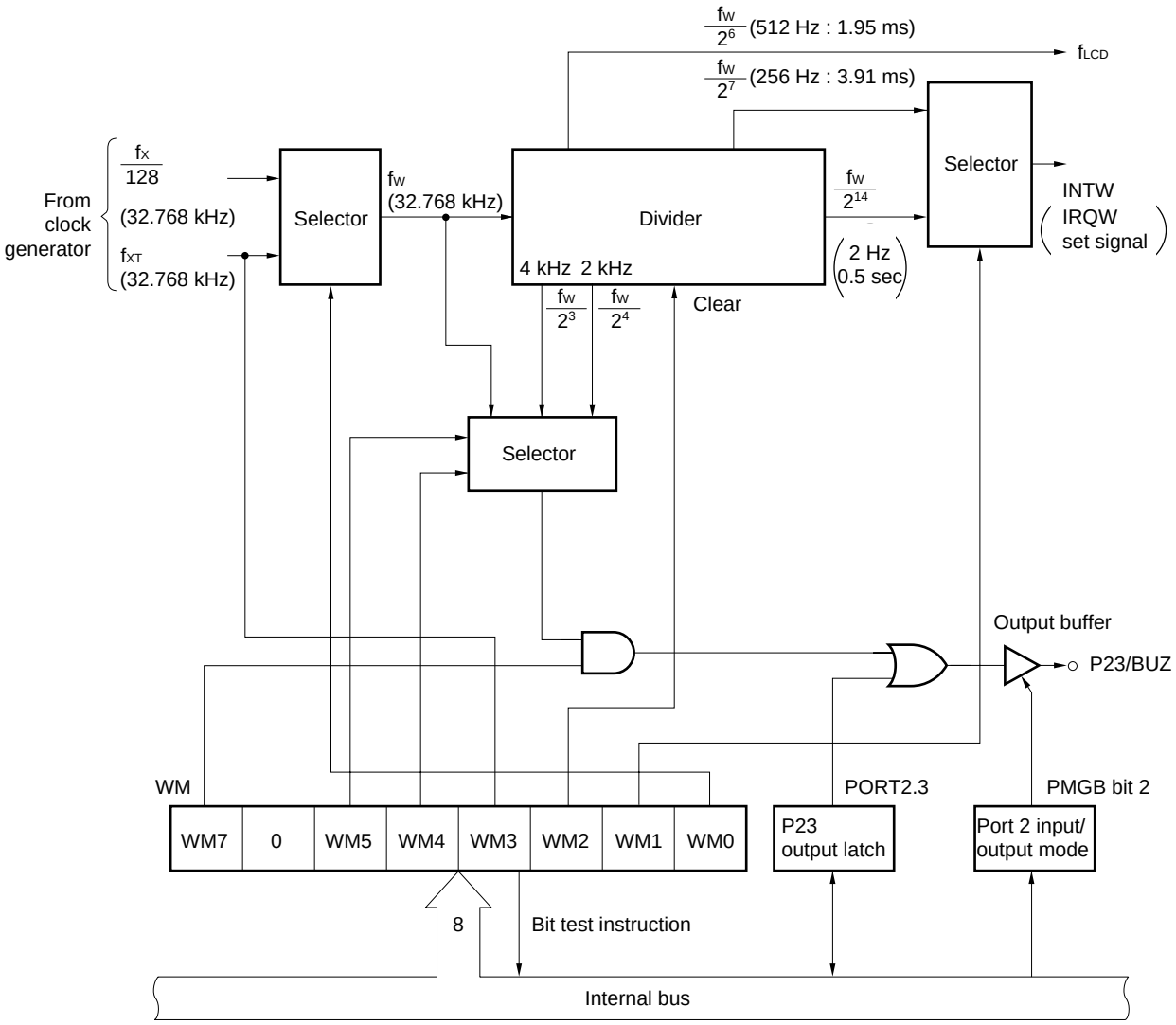
Note Instruction execution

6.6 Watch Timer

The μPD753017 has one channel of watch timer. The watch timer has the following functions.

- Sets the test flag (IRQW) with 0.5 sec interval.
  The standby mode can be released by the IRQW.
- 0.5 sec interval can be created by both the main system clock and subsystem clock. Take f_X = 4.194304 MHz for the main system clock frequency and f_{XT} = 32.768 kHz for the subsystem clock.
- Convenient for program debugging and checking as interval becomes 128 times longer (3.91 ms) with the fast feed mode.
- Outputs the frequencies (2.048, 4.096, 32.768 kHz) to the P23 and BUZ pins, usable for buzzer and trimming of system clock frequencies.
- Clears the frequency divider to make the clock start with zero seconds.

Figure 6-5. Watch Timer Block Diagram



The values enclosed in parentheses are applied when f_X = 4.194304 MHz and f_{XT} = 32.768 kHz.

6.7 Timer/Event Counter

The μPD753017 has three channels of timer/event counter. The timer/event counter has the following functions.

- Programmable interval timer operation
- Square wave output of any frequency to the PTOn pin
- Event counter operation
- Divides the frequency of signal input via the TIn pin to 1-Nth of the original signal and outputs the divided frequency to the PTOn pin (frequency divider operation).
- Supplies the serial shift clock to the serial interface circuit.
- Calls the counting status.

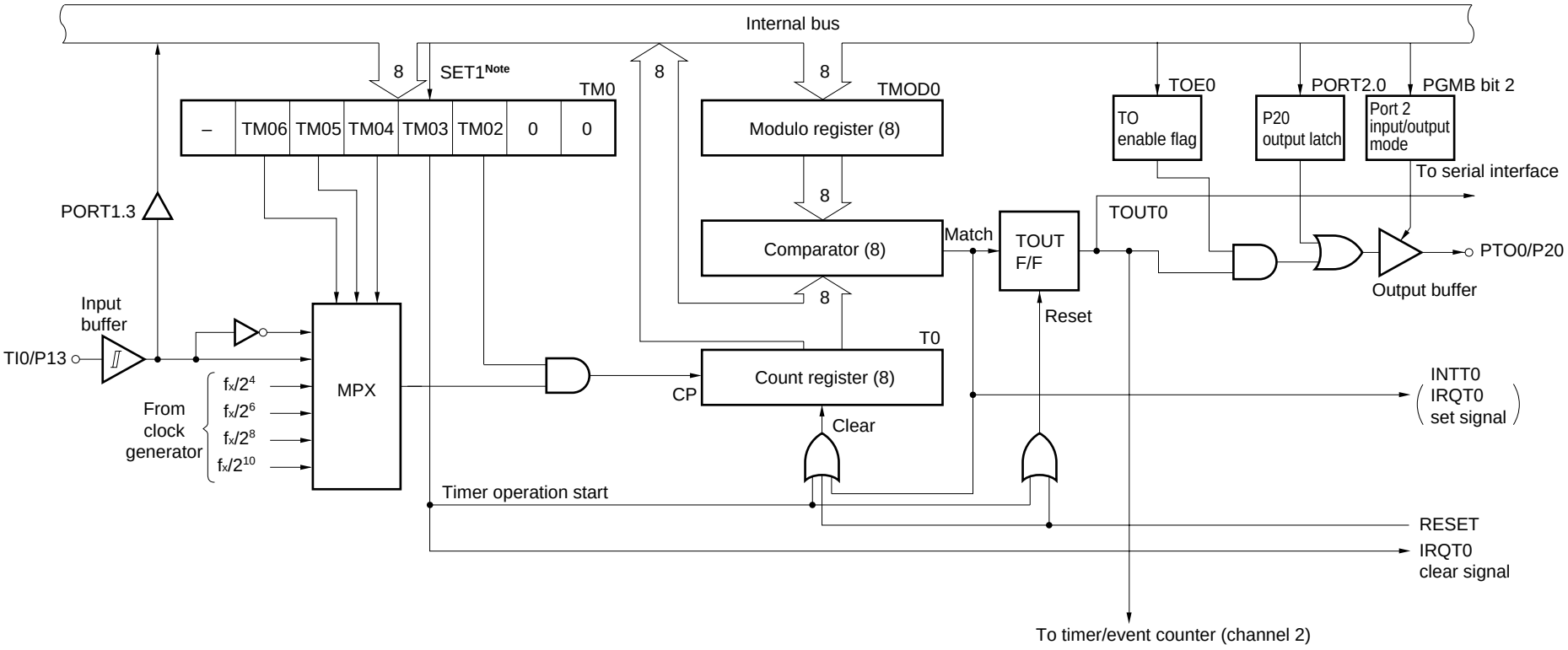
The timer/event counter operates in the following four modes as set by the mode register.

Table 6-2. Operation Modes of Timer/Event Counter

Mode \ Channel		Channel 0	Channel 1	Channel 2
8-bit timer/event counter mode		○	○	○
	Gate control function	× Note	×	○
PWM pulse generator mode		×	×	○
16-bit timer/event counter mode		×	○	
	Gate control function	× Note	○	
Carrier generator mode		×	○	

Note Used for gate control signal generation

Figure 6-6. Timer/Event Counter Block Diagram (channel 0)



Note Instruction execution

Caution When setting data to the TM0, be sure to set bits 0 and 1 to 0.

Figure 6-7. Timer/Event Counter Block Diagram (channel 1)

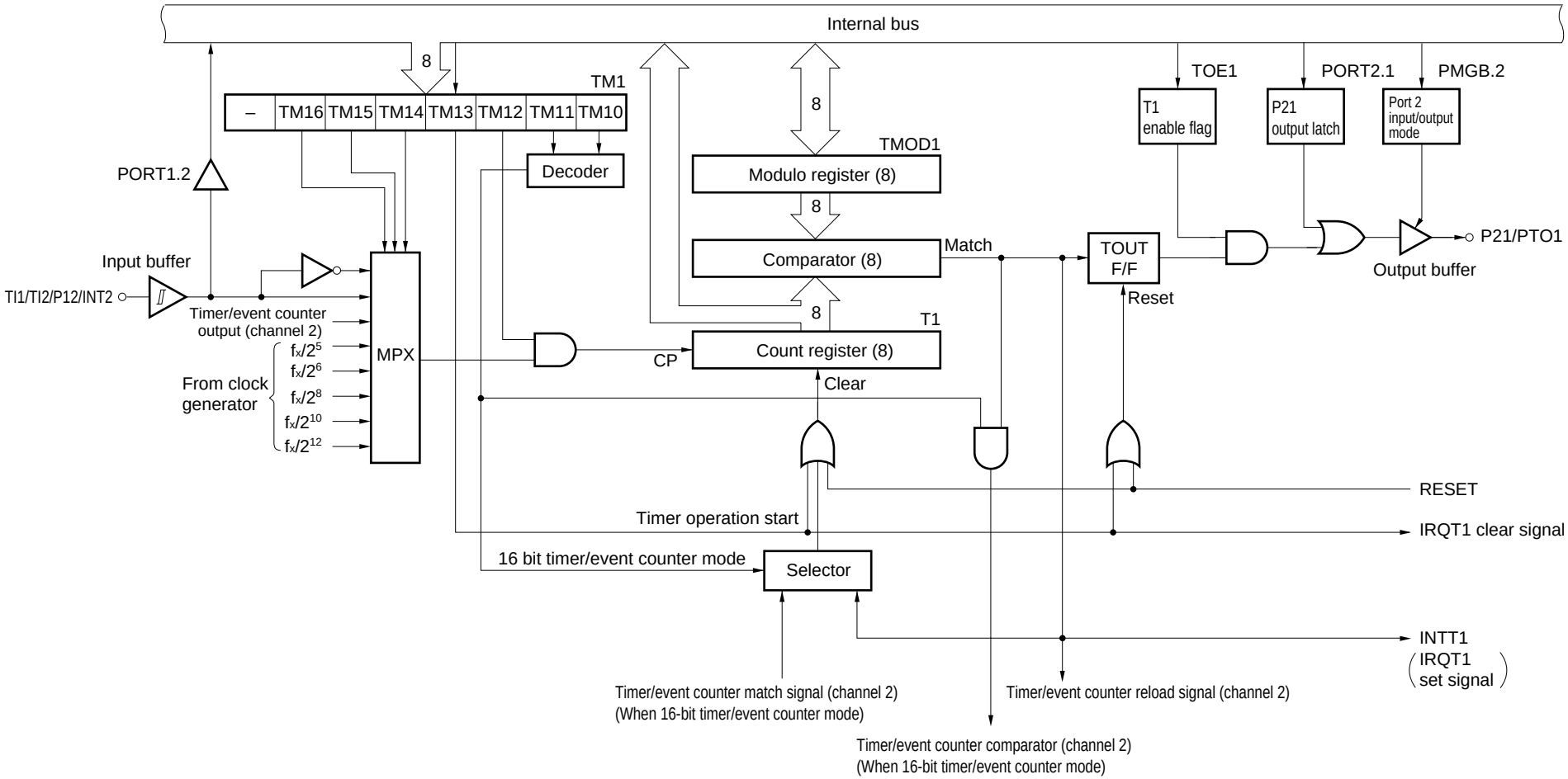
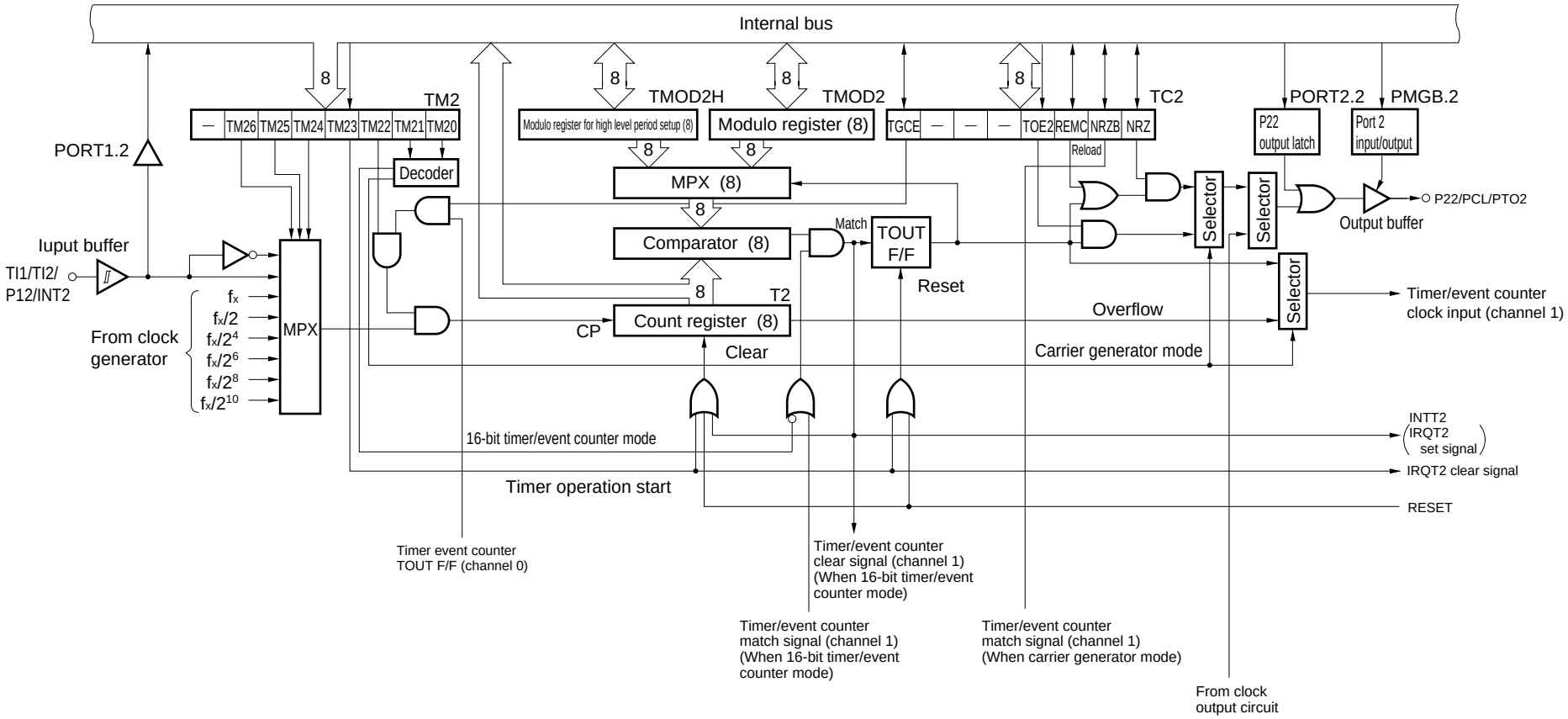


Figure 6-8. Timer/Event Counter Block Diagram (channel 2)

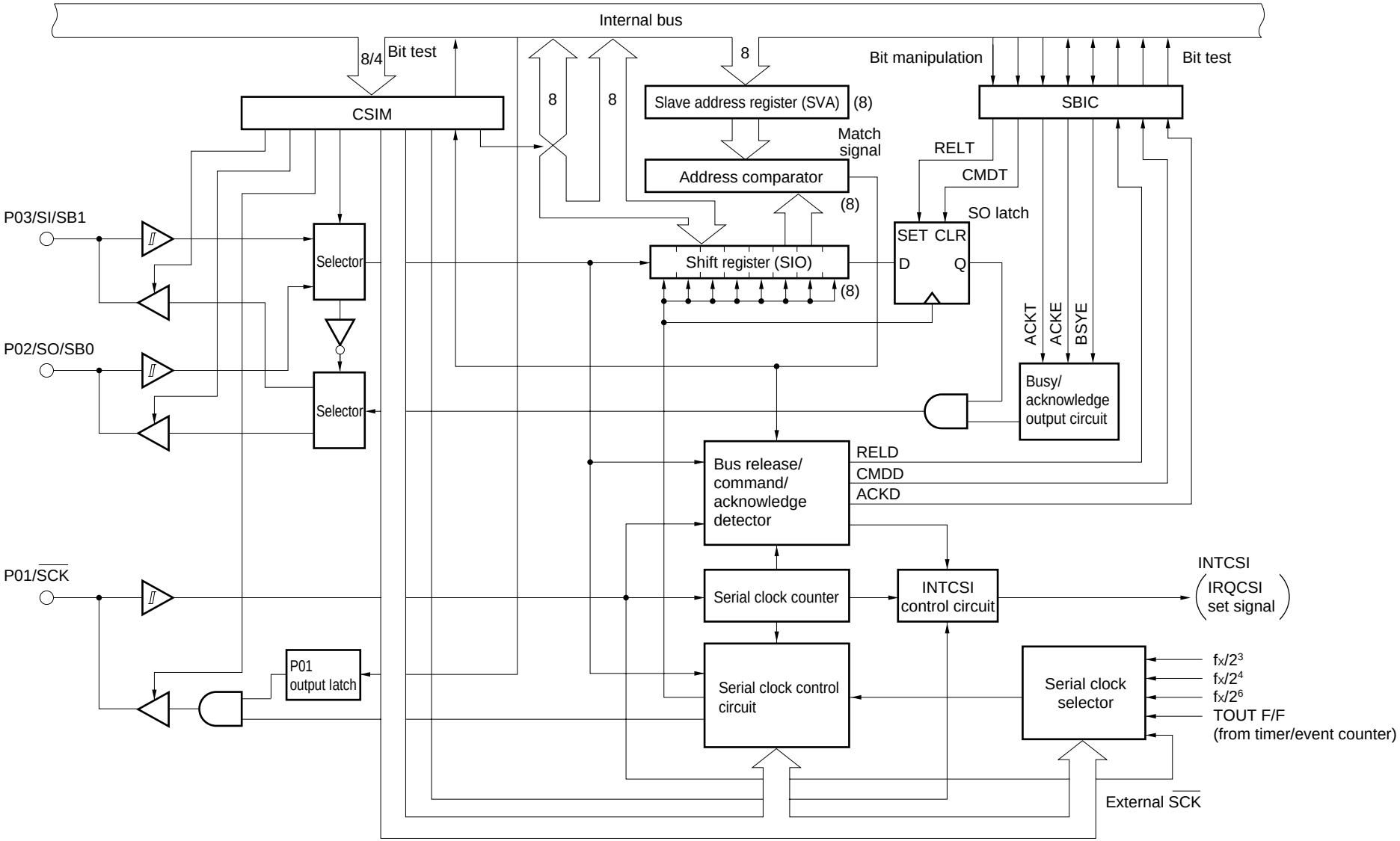


6.8 Serial Interface

The μPD753017 is provided with an 8-bit clocked serial interface. This serial interface operates in the following four modes:

- Operation stop mode
- 3-wire serial I/O mode
- 2-wire serial I/O mode
- SBI mode

Figure 6-9. Serial Interface Block Diagram



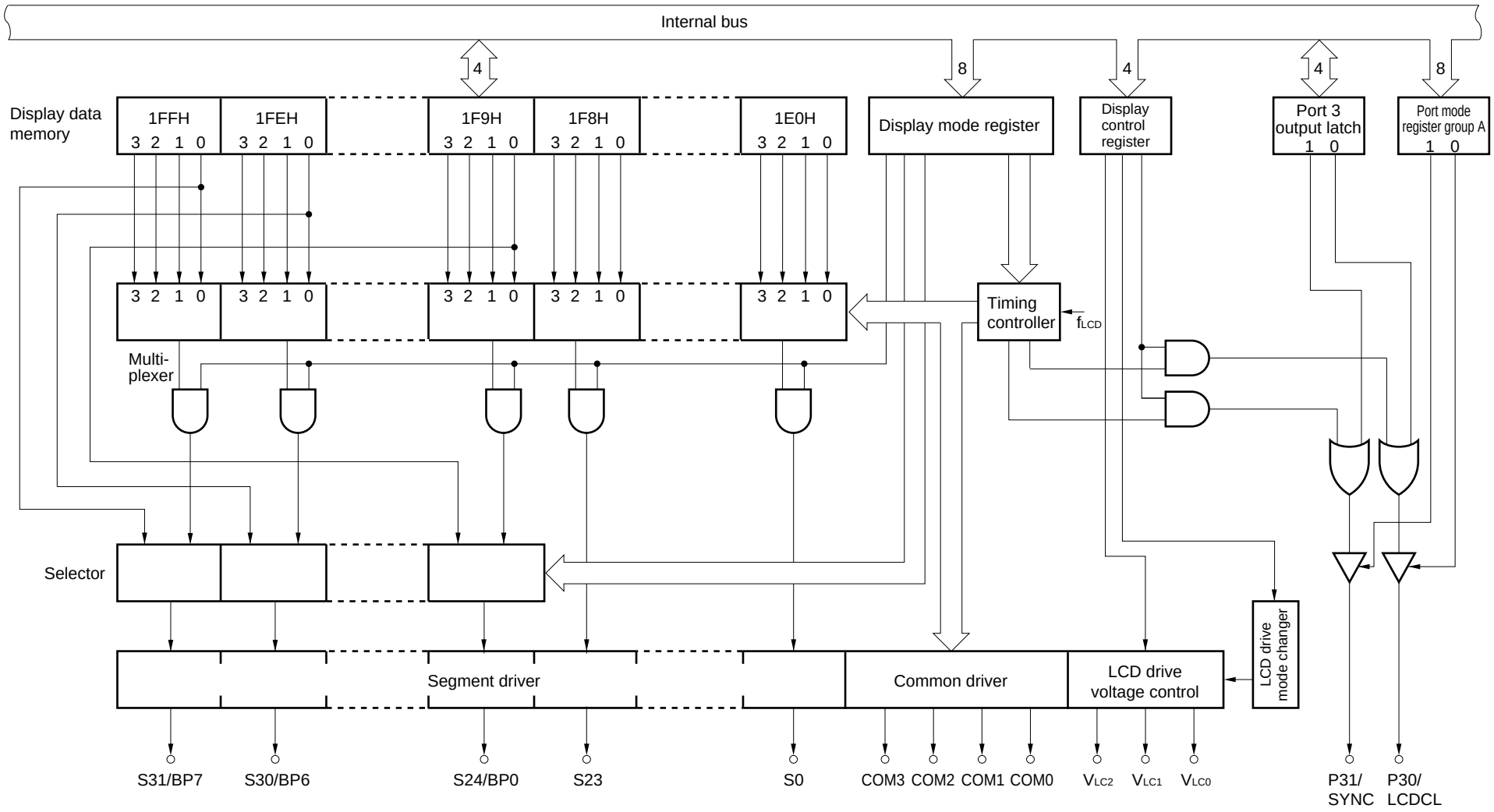
6.9 LCD Controller/Driver

The μPD753017 incorporates a display controller which generates segment and common signals according to the display data memory contents and incorporates segment and common drivers which can drive the LCD panel directly.

The μPD753017 LCD controller/driver functions are as follows:

- Display data memory is read automatically by DMA operation and segment and common signals are generated.
- Display mode can be selected from among the following five:
  <1> Static
  <2> 1/2 duty (time multiplexing by 2), 1/2 bias
  <3> 1/3 duty (time multiplexing by 3), 1/2 bias
  <4> 1/3 duty (time multiplexing by 3), 1/3 bias
  <5> 1/4 duty (time multiplexing by 4), 1/3 bias
- A frame frequency can be selected from among four in each display mode.
- A maximum of 32 segment signal output pins (S0-S31) and four common signal output pins (COM0-COM3).
- The segment signal output pins (S24-S27 and S28-S31) can be changed to the output ports in 4-pin units.
- Split-resistor can be incorporated to supply LCD drive power. (Mask option)
  · Various bias methods and LCD drive voltages can be applicable.
  · When display is off, current flow to the split resistor is cut.
- Display data memory not used for display can be used for normal data memory.
- It can also operate by using the subsystem clock.

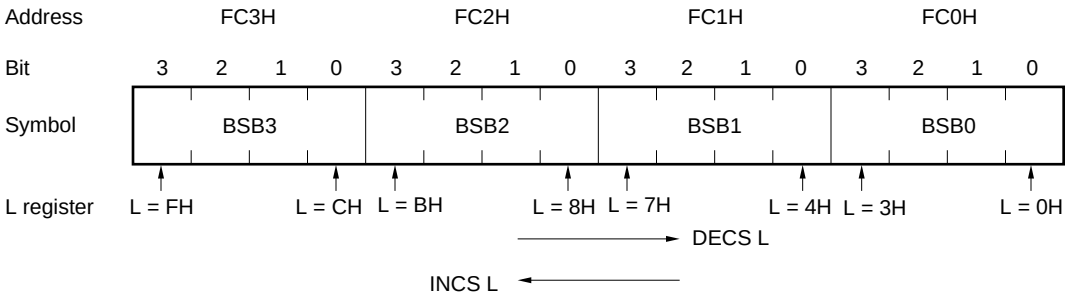
Figure 6-10. LCD Controller/Driver Block Diagram



6.10 Bit Sequential Buffer ... 16 Bits

The bit sequential buffer (BSB) is a special data memory for bit manipulation and the bit manipulation can be easily performed by changing the address specification and bit specification in sequence, therefore it is useful when processing a long data bit-wise.

Figure 6-11. Bit Sequential Buffer Format



Remarks 1. In the pmem.@L addressing, the specified bit moves corresponding to the L register.

2. In the pmem.@L addressing, the BSB can be manipulated regardless of MBE/MBS specification.

7. INTERRUPT FUNCTION AND TEST FUNCTION

μPD753017 has eight types of interrupt sources and two types of test sources. Among the test sources, INT2 is provided with two testable inputs for edge detection.

μPD753017 has the following functions in the interrupt controller.

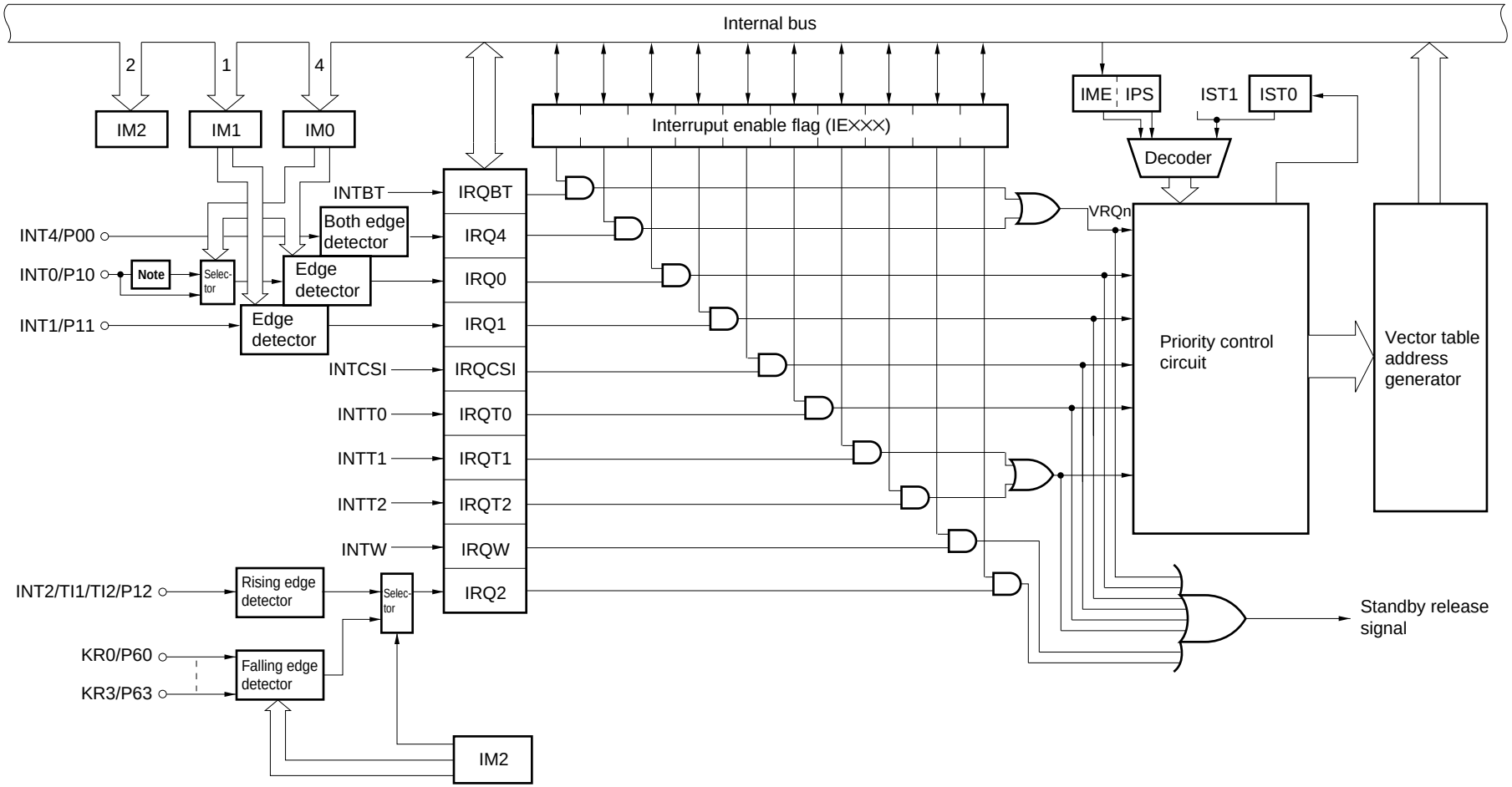
(1) Interrupt function

- Vectored interrupt function for hardware control, enabling/disabling the interrupt acceptance by the interrupt enable flag (IEXXX) and interrupt master enable flag (IME).
- Can set any interrupt start address.
- Multiple interrupts wherein the order of priority can be specified by the interrupt priority select register (IPS).
- Test function of interrupt request flag (IRQXXX). An interrupt generated can be checked by software.
- Release the standby mode. A release interrupt can be selected by the interrupt enable flag.

(2) Test function

- Test request flag (IRQXXX) generation can be checked by software.
- Release the standby mode. The test source to be released can be selected by the test enable flag.

Figure 7-1. Interrupt Control Circuit Block Diagram



Note Noise eliminator (Standby release is disabled when noise eliminator is selected.)

8. STANDBY FUNCTION

In order to save power consumption while a program is in a standby mode, two types of standby modes (STOP mode and HALT mode) are provided for the μPD753017.

Table 8-1. Operation Status in Standby Mode

		STOP Mode	HALT Mode
Set instruction		STOP instruction	HALT instruction
System clock when set		Settable only when the main system clock is used.	Settable both by the main system clock and subsystem clock.
Operation status	Clock generator	Only the main system clock stops oscillation.	Only the CPU Φ halts (oscillation continues).
★	Basic interval timer	Operation stops	Operation. Note 1 (BT mode : Sets IRQBT at reference time intervals. WT mode: Generates reset signal when BT overflows.)
	Serial interface	Operable only when an external $\overline{SCK}$ input is selected as the serial clock.	Operable Note 1
	Timer/event counter	Operable only when a signal input to the TI0-TI2 pins is specified as the count clock.	Operable Note 1
	Watch timer	Operable when f_{XT} is selected as the count clock.	Operable
	LCD controller/driver	Operable only when f_{XT} is selected as the LCDCL.	Operable
	External interrupt	The INT1, 2, and 4 are operable. Only the INT0 is not operated. Note 2	
	CPU	The operation stops.	
Release signal		Interrupt request signal sent from the operable hardware enabled by the interrupt enable flag or $\overline{RESET}$ signal input.	

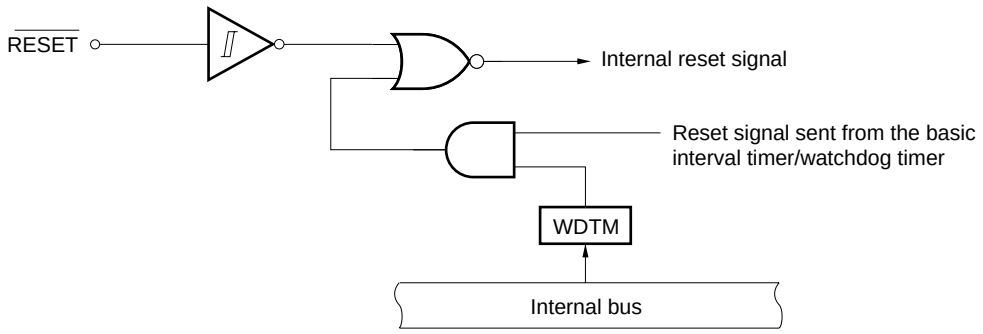
Notes 1. Cannot operate only when the main system clock stops.

2. Can operate only when the noise eliminator is not used (IM02 = 1) by bit 2 of the edge detection mode register(IM0).

9. RESET FUNCTION

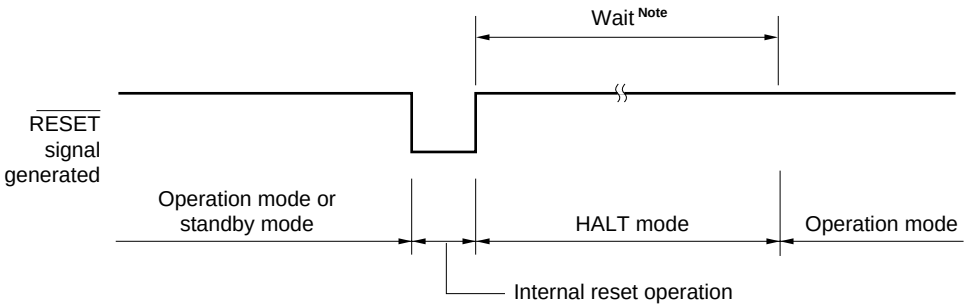
There are two reset inputs: external reset signal ($\overline{\text{RESET}}$) and reset signal sent from the basic interval timer/watchdog timer. When either one of the reset signals are input, an internal reset signal is generated. Figure 9-1 shows the circuit diagram of the above two inputs.

Figure 9-1. Configuration of Reset Function



The μPD753017 is set by the $\overline{\text{RESET}}$ signal generated and each device is initialized as listed in Table 9-1. Figure 9-2 shows the timing chart of the reset operation.

Figure 9-2. Reset Operation by $\overline{\text{RESET}}$ Signal Generation



Note The following two times can be selected by the mask option.

$2^{17}/f_X$ (21.8 ms : at 6.00 MHz operation, 31.3 ms : at 4.19 MHz operation)

$2^{15}/f_X$ (5.46 ms : at 6.00 MHz operation, 7.81 ms : at 4.19 MHz operation)

Table 9-1. Status of Each Device After Reset (1/2)

Hardware			$\overline{\text{RESET}}$ Signal Generation in Standby Mode	$\overline{\text{RESET}}$ Signal Generation in Operation
Program counter (PC)		μPD753012, 753016	Sets the low-order 6 bits of program memory's address 0000H to the PC13-PC8 and the contents of address 0001H to the PC7-PC0.	Sets the low-order 6 bits of program memory's address 0000H to the PC13-PC8 and the contents of address 0001H to the PC7-PC0.
		μPD753017	Sets the low-order 7 bits of program memory's address 0000H to the PC14-PC8 and the contents of address 0001H to the PC7-PC0.	Sets the low-order 7 bits of program memory's address 0000H to the PC14-PC8 and the contents of address 0001H to the PC7-PC0.
PSW	Carry flag (CY)		Held	Undefined
	Skip flag (SK0-SK2)		0	0
	Interrupt status flag (IST0)		0	0
	Bank enable flag (MBE, RBE)		Sets the bit 6 of program memory's address 0000H to the RBE and bit 7 to the MBE.	Sets the bit 6 of program memory's address 0000H to the RBE and bit 7 to the MBE.
Stack pointer (SP)			Undefined	Undefined
Stack bank select register (SBS)			1000B	1000B
Data memory (RAM)			Held	Undefined
General-purpose register (X, A, H, L, D, E, B, C)			Held	Undefined
Bank select register (MBS, RBS)			0, 0	0, 0
Basic interval/ watchdog timer	Counter (BT)		Undefined	Undefined
	Mode register (BTM)		0	0
	Watchdog timer enable flag (WDTM)		0	0
Timer/event counter (T0)	Counter (T0)		0	0
	Modulo register (TMOD0)		FFH	FFH
	Mode register (TM0)		0	0
	TOE0, TOUT F/F		0, 0	0, 0
Timer/event counter (T1)	Counter (T1)		0	0
	Modulo register (TMOD1)		FFH	FFH
	Mode register (TM1)		0	0
	TOE1, TOUT F/F		0, 0	0, 0
Timer/event counter (T2)	Counter (T2)		0	0
	Modulo register (TMOD2)		FFH	FFH
	High level period setting modulo register (TMOD2H)		FFH	FFH
	Mode register (TM2)		0	0
	TOE2, TOUT F/F		0, 0	0, 0
	REMC, NRZ, NRZB		0, 0, 0	0, 0, 0
	TGCE		0	0
Watch timer	Mode register (WM)		0	0

Table 9-1. Status of Each Device After Reset (2/2)

Hardware		$\overline{\text{RESET}}$ Signal Generation in Standby Mode	$\overline{\text{RESET}}$ Signal Generation in Operation
Serial interface	Shift register (SIO)	Held	Undefined
	Operating mode register (CSIM)	0	0
	SBI control register (SBIC)	0	0
	Slave address register (SVA)	Held	Undefined
Clock generator, clock output circuit	Processor clock control register (PCC)	0	0
	System clock control register (SCC)	0	0
	Clock output mode register (CLOM)	0	0
Sub-oscillator control register (SOS)		0	0
LCD controller /driver	Display mode register (LCDM)	0	0
	Display control register (LCDC)	0	0
Interrupt function	Interrupt request flag (IRQXXX)	Reset (0)	Reset (0)
	Interrupt enable flag (IEXXX)	0	0
	Interrupt master enable flag (IME)	0	0
	INT0, 1, 2 mode registers (IM0, IM1, IM2)	0, 0, 0	0, 0, 0
	Priority selection register (IPS)	0	0
Digital port	Output buffer	Off	Off
	Output latch	Cleared (0)	Cleared (0)
	I/O mode registers (PMGA, PMGB)	0	0
	Pull-up resistor setting register (POGA)	0	0
Bit sequential buffer (BSB0-BSB3)		Held	Undefined

★ 10. MASK OPTION

The μPD753017 has the following mask options.

- Mask option of P40 to P43 and P50 to P53
  An on-chip pull-up resistor can be selected.
  <1> Specifies an on-chip pull-up resistor in bit units.
  <2> Does not specify an on-chip pull-up resistor.

- Mask option of V_{LC0} to V_{LC2} and BIAS pins
  An on-chip split resistor for LDC driving can be selected.
  <1> Does not specify an on-chip divider resistor
  <2> Specifies four 10-kΩ (typ.) on-chip split resistors at the same time.
  <3> Specifies four 100-kΩ (typ.) on-chip split resistors at the same time.

- Standby function mask option
  Wait time can be selected by $\overline{\text{RESET}}$ signai input.
  <1> $2^{17}/f_X$ (21.8 ms: at f_X = 6.0 MHz, 31.3 ms: at f_X = 4.19 MHz)
  <2> $2^{15}/f_X$ (5.46 ms: at f_X = 6.0 MHz, 7.81 ms: at f_X = 4.19 MHz)

- Subsystem clock mask option
  Selectable an on-chip feedback resistor can be used/cannot be used
  <1> Make an on-chip feedback resistor usable
  (Switch on-chip feedback resistor ON/OFF in software)
  <2> Make an on-chip feedback resistor unusable
  (Disconnects on-chip feedback resistor in hardware)

11. INSTRUCTION SETS AND THEIR OPERATIONS

(1) Operand identifiers and methods of use

Operands are written in the operand column of each instruction in accordance with the method of use for the operand identifier of the instruction. For details, refer to **RA75X Assembler Package User's Manual—Language (U12385E)**. If there are several elements, one of them is selected. Capital letters and the + and – symbols are key words and are written as they are.

For immediate data, appropriate numbers and labels are written.

Instead of the labels such as mem, fmem, pmem, and bit, the symbols of the registers can be written. However, there are restrictions in the labels that can be written for fmem and pmem. For details, refer to **User's Manual**.

Identifier	Format
reg reg1	X, A, B, C, D, E, H, L X, B, C, D, E, H, L
rp rp1 rp2 rp' rp'1	XA, BC, DE, HL BC, DE, HL BC, DE XA, BC, DE, HL, XA', BC', DE', HL' BC, DE, HL, XA', BC', DE', HL'
rpa rpa1	HL, HL+, HL–, DE, DL DE, DL
n4 n8	4-bit immediate data or label 8-bit immediate data or label
mem bit	8-bit immediate data or label Note 2-bit immediate data or label
fmem pmem	FB0H-FBFH, FF0H-FFFH immediate data or label FC0H-FFFH immediate data or label
addr addr1 caddr faddr	0000H-2FFFH immediate data or label (μPD753012) 0000H-3FFFH immediate data or label (μPD753016, 753017) 0000H-5FFFH immediate data or label 12-bit immediate data or label 11-bit immediate data or label
taddr	20H-7FH immediate data (where bit 0 = 0) or label
PORTn IEXXX RBn MBn	PORT0-PORT7 IEBT, IET0-IET2, IE0-IE2, IE4, IECSI, IEW RB0-RB3 MB0, MB1, MB2, MB3, MB15

Note mem can be only used even address in 8-bit data processing.

(2) Legend in explanation of operation

A	: A register, 4-bit accumulator
B	: B register
C	: C register
D	: D register
E	: E register
H	: H register
L	: L register
X	: X register
XA	: XA register pair; 8-bit accumulator
BC	: BC register pair
DE	: DE register pair
HL	: HL register pair
XA'	: XA' expanded register pair
BC'	: BC' expanded register pair
DE'	: DE' expanded register pair
HL'	: HL' expanded register pair
PC	: Program counter
SP	: Stack pointer
CY	: Carry flag, bit accumulator
PSW	: Program status word
MBE	: Memory bank enable flag
RBE	: Register bank enable flag
PORTn	: Port n (n = 0-7)
IME	: Interrupt master enable flag
IPS	: Interrupt priority selection register
IEXXX	: Interrupt enable flag
RBS	: Register bank selection register
MBS	: Memory bank selection register
PCC	: Processor clock control register
.	: Separation between address and bit
(XX)	: The contents addressed by XX
XXH	: Hexadecimal data

(3) Explanation of symbols under addressing area column

*1	MB = MBE•MBS (MBS = 0-3, 15)		Data memory addressing
*2	MB = 0		
*3	MBE = 0 : MB = 0 (00H-7FH) MB = 15 (F80H-FFFH) MBE = 1 : MB = MBS (MBS = 0-3, 15)		
*4	MB = 15, fmem = FB0H-FBFH, FF0H-FFFH		
*5	MB = 15, pmem = FC0H-FFFH		
*6	μPD753012	addr = 0000H-2FFFH	Program memory addressing
	μPD753016 753017	addr = 0000H-3FFFH	
*7	μPD753012 753016 753017 (In Mk I mode)	addr = (Current PC) – 15 to (Current PC) – 1 (Current PC) + 2 to (Current PC) + 16	
	μPD753017 (In Mk II mode)	addr1 = (Current PC) – 15 to (Current PC) – 1 (Current PC) + 2 to (Current PC) + 16	
*8	μPD753012	caddr = 0000H-0FFFH($PC_{13, 12}$ = 00B) or 1000H-1FFFH($PC_{13, 12}$ = 01B) or 2000H-2FFFH($PC_{13, 12}$ = 10B)	
	μPD753016	caddr = 0000H-0FFFH($PC_{13, 12}$ = 00B) or 1000H-1FFFH($PC_{13, 12}$ = 01B) or 2000H-2FFFH($PC_{13, 12}$ = 10B) or 3000H-3FFFH($PC_{13, 12}$ = 11B)	
	μPD753017	caddr = 0000H-0FFFH($PC_{14, 13, 12}$ = 000B) or 1000H-1FFFH($PC_{14, 13, 12}$ = 001B) or 2000H-2FFFH($PC_{14, 13, 12}$ = 010B) or 3000H-3FFFH($PC_{14, 13, 12}$ = 011B) or 4000H-4FFFH($PC_{14, 13, 12}$ = 100B) or 5000H-5FFFH($PC_{14, 13, 12}$ = 101B)	
*9	faddr = 0000H-07FFH		
*10	taddr = 0020H-007FH		
*11	μPD753012	addr1 = 0000H-2FFFH	
	μPD753016	addr1 = 0000H-3FFFH	
	μPD753017	addr1 = 0000H-5FFFH	

Remarks 1. MB indicates memory bank that can be accessed.

2. In *2, MB = 0 independently of how MBE and MBS are set.

3. In *4 and *5, MB = 15 independently of how MBE and MBS are set.

4. *6 to *11 indicate the areas that can be addressed.

(4) Explanation of number of machine cycles column

S denotes the number of machine cycles required by skip operation when a skip instruction is executed. The value of S varies as follows.

- When no skip is made: S = 0
- When the skipped instruction is a 1- or 2-byte instruction: S = 1
- When the skipped instruction is a 3-byte instruction[Note]: S = 2

Note 3-byte instruction: BR !addr, BRA !addr1, CALL !addr or CALLA !addr1 instruction

Caution The GETI instruction is skipped in one machine cycle.

One machine cycle is equal to one cycle of CPU clock Φ (= t_{CY}); time can be selected from among four types by setting PCC.

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Transfer instruction	MOV	A, #n4	1	1	A ← n4		String effect A
		reg1, #n4	2	2	reg1 ← n4		
		XA, #n8	2	2	XA ← n8		String effect A
		HL, #n8	2	2	HL ← n8		String effect B
		rp2, #n8	2	2	rp2 ← n8		
		A, @HL	1	1	A ← (HL)	*1	
		A, @HL+	1	2+S	A ← (HL), then L ← L+1	*1	L = 0
		A, @HL–	1	2+S	A ← (HL), then L ← L–1	*1	L = FH
		A, @rpa1	1	1	A ← (rpa1)	*2	
		XA, @HL	2	2	XA ← (HL)	*1	
		@HL, A	1	1	(HL) ← A	*1	
		@HL, XA	2	2	(HL) ← XA	*1	
		A, mem	2	2	A ← (mem)	*3	
		XA, mem	2	2	XA ← (mem)	*3	
		mem, A	2	2	(mem) ← A	*3	
		mem, XA	2	2	(mem) ← XA	*3	
		A, reg	2	2	A ← reg		
		XA, rp’	2	2	XA ← rp’		
		reg1, A	2	2	reg1 ← A		
		rp’1, XA	2	2	rp’1 ← XA		
	XCH	A, @HL	1	1	A ↔ (HL)	*1	
		A, @HL+	1	2+S	A ↔ (HL), then L ← L+1	*1	L = 0
		A, @HL–	1	2+S	A ↔ (HL), then L ← L–1	*1	L = FH
		A, @rpa1	1	1	A ↔ (rpa1)	*2	
		XA, @HL	2	2	XA ↔ (HL)	*1	
		A, mem	2	2	A ↔ (mem)	*3	
		XA, mem	2	2	XA ↔ (mem)	*3	
		A, reg1	1	1	A ↔ reg1		
		XA, rp’	2	2	XA ↔ rp’		

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Table	MOVT[Note 1]	XA, @PCDE	1	3	XA ← $(PC_{13-8}+DE)_{ROM}$		
					• μPD753017 XA ← $(PC_{14-8}+DE)_{ROM}$		
		XA, @PCXA	1	3	XA ← $(PC_{13-8}+XA)_{ROM}$		
					• μPD753017 XA ← $(PC_{14-8}+XA)_{ROM}$		
		XA, @BCDE[Note 2]	1	3	XA ← $(B_{1,0}+CDE)_{ROM}$	*6	
					• μPD753017 XA ← $(B_{2-0}+CDE)_{ROM}$	*11	
		XA, @BCXA[Note 2]	1	3	XA ← $(B_{1,0}+CXA)_{ROM}$	*6	
					• μPD753017 XA ← $(B_{2-0}+CXA)_{ROM}$	*11	
Bit transfer	MOV1	CY, fmem.bit	2	2	CY ← (fmem.bit)	*4	
		CY, pmem.@L	2	2	CY ← $(pmem_{7-2}+L_{3-2}.bit(L_{1-0}))$	*5	
		CY, @H+mem.bit	2	2	CY ← $(H+mem_{3-0}.bit)$	*1	
		fmem.bit, CY	2	2	(fmem.bit) ← CY	*4	
		pmem.@L, CY	2	2	$(pmem_{7-2}+L_{3-2}.bit(L_{1-0}))$ ← CY	*5	
		@H+mem.bit, CY	2	2	$(H+mem_{3-0}.bit)$ ← CY	*1	
Operation	ADDS	A, #n4	1	1+S	A ← A+n4		carry
		XA, #n8	2	2+S	XA ← XA+n8		carry
		A, @HL	1	1+S	A ← A+(HL)	*1	carry
		XA, rp'	2	2+S	XA ← XA+rp'		carry
		rp'1, XA	2	2+S	rp'1 ← rp'1+XA		carry
	ADDC	A, @HL	1	1	A, CY ← A+(HL)+CY	*1	
		XA, rp'	2	2	XA, CY ← XA+rp'+CY		
		rp'1, XA	2	2	rp'1, CY ← rp'1+XA+CY		
	SUBS	A, @HL	1	1+S	A ← A–(HL)	*1	borrow
		XA, rp'	2	2+S	XA ← XA–rp'		borrow
		rp'1, XA	2	2+S	rp'1 ← rp'1–XA		borrow
	SUBC	A, @HL	1	1	A, CY ← A–(HL)–CY	*1	
		XA, rp'	2	2	XA, CY ← XA–rp'–CY		
		rp'1, XA	2	2	rp'1, CY ← rp'1–XA–CY		

Notes 1. The above operations in the shaded boxes can be performed only in the Mk II mode. The other operations can be performed only in the Mk I mode.

2. Only the following bits are valid for the B register.
μPD753012, 753016 : low-order 2 bits
μPD753017 : low-order 3 bits

★ **Remark** PC_{14} is fixed to 0 when the μPD753017 is set in the Mk I mode.

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Operating instructions	AND	A, #n4	2	2	A ← A ∧ n4		
		A, @HL	1	1	A ← A ∧ (HL)	*1	
		XA, rp'	2	2	XA ← XA ∧ rp'		
		rp'1, XA	2	2	rp'1 ← rp'1 ∧ XA		
	OR	A, #n4	2	2	A ← A ∨ n4		
		A, @HL	1	1	A ← A ∨ (HL)	*1	
		XA, rp'	2	2	XA ← XA ∨ rp'		
		rp'1, XA	2	2	rp'1 ← rp'1 ∨ XA		
	XOR	A, #n4	2	2	A ← A ⊻ n4		
		A, @HL	1	1	A ← A ⊻ (HL)	*1	
		XA, rp'	2	2	XA ← XA ⊻ rp'		
		rp'1, XA	2	2	rp'1 ← rp'1 ⊻ XA		
Accumulator manipulation instructions	RORC	A	1	1	CY ← A_0, A_3 ← CY, A_{n-1} ← A_n		
	NOT	A	2	2	A ← $\overline{A}$		
Increment and Decrement instructions	INCS	reg	1	1+S	reg ← reg+1		reg=0
		rp1	1	1+S	rp1 ← rp1+1		rp1=00H
		@HL	2	2+S	(HL) ← (HL)+1	*1	(HL)=0
		mem	2	2+S	(mem) ← (mem)+1	*3	(mem)=0
	DECS	reg	1	1+S	reg ← reg–1		reg=FH
		rp'	2	2+S	rp' ← rp'–1		rp'=FFH
Comparison instruction	SKE	reg, #n4	2	2+S	Skip if reg = n4		reg=n4
		@HL, #n4	2	2+S	Skip if (HL) = n4	*1	(HL) = n4
		A, @HL	1	1+S	Skip if A = (HL)	*1	A = (HL)
		XA, @HL	2	2+S	Skip if XA = (HL)	*1	XA = (HL)
		A, reg	2	2+S	Skip if A = reg		A=reg
		XA, rp'	2	2+S	Skip if XA = rp'		XA=rp'
Carry flag manipulation instruction	SET1	CY	1	1	CY ← 1		
	CLR1	CY	1	1	CY ← 0		
	SKT	CY	1	1+S	Skip if CY = 1		CY=1
	NOT1	CY	1	1	CY ← $\overline{CY}$		

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Memory bit manipulation instructions	SET1	mem.bit	2	2	(mem.bit) ←1	*3	
		fmem.bit	2	2	(fmem.bit) ←1	*4	
		pmem.@L	2	2	($pmem_{7-2}$+L_{3-2}.bit(L_{1-0})) ←1	*5	
		@H+mem.bit	2	2	(H+mem_{3-0}.bit) ←1	*1	
	CLR1	mem.bit	2	2	(mem.bit) ←0	*3	
		fmem.bit	2	2	(fmem.bit) ←0	*4	
		pmem.@L	2	2	($pmem_{7-2}$+L_{3-2}.bit(L_{1-0})) ←0	*5	
		@H+mem.bit	2	2	(H+mem_{3-0}.bit) ←0	*1	
	SKT	mem.bit	2	2+S	Skip if (mem.bit)=1	*3	(mem.bit)=1
		fmem.bit	2	2+S	Skip if (fmem.bit)=1	*4	(fmem.bit)=1
		pmem.@L	2	2+S	Skip if ($pmem_{7-2}$+L_{3-2}.bit(L_{1-0}))=1	*5	(pmem.@L)=1
		@H+mem.bit	2	2+S	Skip if (H+mem_{3-0}.bit)=1	*1	(@H+mem.bit)=1
	SKF	mem.bit	2	2+S	Skip if (mem.bit)=0	*3	(mem.bit)=0
		fmem.bit	2	2+S	Skip if (fmem.bit)=0	*4	(fmem.bit)=0
		pmem.@L	2	2+S	Skip if ($pmem_{7-2}$+L_{3-2}.bit(L_{1-0}))=0	*5	(pmem.@L)=0
		@H+mem.bit	2	2+S	Skip if (H+mem_{3-0}.bit)=0	*1	(@H+mem.bit)=0
	SKTCLR	fmem.bit	2	2+S	Skip if (fmem.bit)=1 and clear	*4	(fmem.bit)=1
		pmem.@L	2	2+S	Skip if ($pmem_{7-2}$+L_{3-2}.bit(L_{1-0}))=1 and clear	*5	(pmem.@L)=1
		@H+mem.bit	2	2+S	Skip if (H+mem_{3-0}.bit)=1 and clear	*1	(@H+mem.bit)=1
	AND1	CY, fmem.bit	2	2	CY ← CY ∧ (fmem.bit)	*4	
		CY, pmem.@L	2	2	CY ← CY ∧ ($pmem_{7-2}$+L_{3-2}.bit(L_{1-0}))	*5	
		CY, @H+mem.bit	2	2	CY ← CY ∧ (H+mem_{3-0}.bit)	*1	
	OR1	CY, fmem.bit	2	2	CY ← CY ∨ (fmem.bit)	*4	
		CY, pmem.@L	2	2	CY ← CY ∨ ($pmem_{7-2}$+L_{3-2}.bit(L_{1-0}))	*5	
		CY, @H+mem.bit	2	2	CY ← CY ∨ (H+mem_{3-0}.bit)	*1	
	XOR1	CY, fmem.bit	2	2	CY ← CY ∨̄ (fmem.bit)	*4	
		CY, pmem.@L	2	2	CY ← CY ∨̄ ($pmem_{7-2}$+L_{3-2}.bit(L_{1-0}))	*5	
		CY, @H+mem.bit	2	2	CY ← CY ∨̄ (H+mem_{3-0}.bit)	*1	

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Branch instructions	BR[Note 1]	addr	–	–	$PC_{13-0} \leftarrow$ addr Select appropriate instruction from among BR !addr, BRCB !caddr, and BR $addr according to the assembler being used. BR !addr BRCB !caddr BR $addr	*6	
		addr1	–	–	• μPD753017 $PC_{14-0} \leftarrow$ addr1 Select appropriate instruction from among BR !addr, BRA !caddr1 BRCB !caddr, and BR $addr according to the assembler being used. BR !addr BRA !addr1 BRCB !caddr BR $addr	*11	
		!addr	3	3	$PC_{13-0} \leftarrow$ addr	*6	
					• μPD753017 $PC_{14} \leftarrow 0$, $PC_{13-0} \leftarrow$ addr		
		$addr	1	2	$PC_{13-0} \leftarrow$ addr	*7	
		$addr1	1	2	• μPD753017 $PC_{14-0} \leftarrow$ addr1		
		PCDE	2	3	$PC_{13-0} \leftarrow PC_{13-8}$+DE		
					• μPD753017 $PC_{14-0} \leftarrow PC_{14-8}$+DE		
		PCXA	2	3	$PC_{13-0} \leftarrow PC_{13-8}$+XA		
					• μPD753017 $PC_{14-0} \leftarrow PC_{14-8}$+XA		
		BCDE[Note 2]	2	3	$PC_{13-0} \leftarrow B_{1,0}$+CDE	*6	
					• μPD753017 $PC_{14-0} \leftarrow B_{2-0}$+CDE	*11	
		BCXA[Note2]	2	3	$PC_{13-0} \leftarrow B_{1,0}$+CXA	*6	
					• μPD753017 $PC_{14-0} \leftarrow B_{2-0}$+CXA	*11	
	BRA[Note1]	!addr	3	3	• μPD753012, 753016 $PC_{13-0} \leftarrow$ addr	*6	
		!addr1	3	3	• μPD753017 $PC_{14-0} \leftarrow$ addr1	*11	

Notes 1. The above operations in the shaded boxes can be performed only in the Mk II mode. The other operations can be performed only in the Mk I mode.

2. Only the following bits are valid for the B register.

μPD753012, 753016 : low-order 2 bits

μPD753017 : low-order 3 bits

★ **Remark** PC_{14} is fixed to 0 when the μPD753017 is set in the Mk I mode.

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Branch instructions	BRCB[Note]	!caddr	2	2	$PC_{13-0} \leftarrow PC_{13,12}+caddr_{11-0}$	*8	
					• μPD753017 $PC_{14-0} \leftarrow PC_{14,13,12}+caddr_{11-0}$		
Subroutine stack control instructions	CALLA[Note]	!addr	3	3	• μPD753012, 753016 (SP–5)(SP–6)(SP–3)(SP–4) ← 0, 0, PC_{13-0} (SP–2) ← ×, ×, MBE, RBE PC_{13-0} ← addr, SP ← SP–6	*6	
		!addr1	3	3	• μPD753017 (SP–5)(SP–6)(SP–3)(SP–4) ← 0, PC_{14-0} (SP–2) ← ×, ×, MBE, RBE PC_{14-0} ← addr1, SP ← SP–6	*11	
	CALL[Note]	!addr	3	3	(SP–4)(SP–1)(SP–2) ← PC_{11-0} (SP–3) ← MBE, RBE, PC_{13}, PC_{12} PC_{13-0} ← addr, SP ← SP–4	*6	
				4	• μPD753012, 753016 (SP–5)(SP–6)(SP–3)(SP–4) ← 0, 0, PC_{13-0} (SP–2) ← ×, ×, MBE, RBE PC_{13-0} ← addr, SP ← SP–6		
				4	• μPD753017 (SP–5)(SP–6)(SP–3)(SP–4) ← 0, PC_{14-0} (SP–2) ← ×, ×, MBE, RBE PC14 ← 0, PC_{13-0} ← addr, SP ← SP–6		
	CALLF[Note]	!faddr	2	2	(SP–4)(SP–1)(SP–2) ← PC_{11-0} (SP–3) ← MBE, RBE, PC_{13}, PC_{12} PC_{13-0} ← 000+faddr, SP ← SP–4	*9	
				3	• μPD753012, 753016 (SP–5)(SP–6)(SP–3)(SP–4) ← 0, 0, PC_{13-0} (SP–2) ← ×, ×, MBE, RBE PC_{13-0} ← 000+faddr, SP ← SP–6		
				3	• μPD753017 (SP–5)(SP–6)(SP–3)(SP–4) ← 0, PC_{14-0} (SP–2) ← ×, ×, MBE, RBE PC_{14-0} ← 0000+faddr, SP ← SP–6		

Note The above operations in the shaded boxes can be performed only in the Mk II mode. The other operations can be performed only in the Mk I mode.

★ **Remark** PC_{14} is fixed to 0 when the μPD753017 is set in the Mk I mode.

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Subroutine stack control instructions	RET[Note]		1	3	MBE, RBE, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2), SP ← SP+4		
					• μPD753012, 753016 ×, ×, MBE, RBE ← (SP+4) 0, 0, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2), SP ← SP+6		
					• μPD753017 ×, ×, MBE, RBE ← (SP+4) 0, PC_{14}, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2), SP ← SP+6		
	RETS[Note]		1	3+S	MBE, RBE, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2), SP ← SP+4 then skip unconditionally		Unconditional
					• μPD753012, 753016 ×, ×, MBE, RBE ← (SP+4) 0, 0, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2), SP ← SP+6 then skip unconditionally		
					• μPD753017 ×, ×, MBE, RBE ← (SP+4) 0, PC_{14}, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2), SP ← SP+6 then skip unconditionally		
	RETI[Note]		1	3	MBE, RBE, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2) PSW ← (SP+4)(SP+5), SP ← SP+6		
					• μPD753012, 753016 0, 0, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2) PSW ← (SP+4)(SP+5), SP ← SP+6		
					• μPD753017 0, PC_{14}, PC_{13}, PC_{12} ← (SP+1) PC_{11-0} ← (SP)(SP+3)(SP+2) PSW ← (SP+4)(SP+5), SP ← SP+6		

Note The above operations in the shaded boxes can be performed only in the Mk II mode. The other operations can be performed only in the Mk I mode.

★ **Remark** PC_{14} is fixed to 0 when the μPD753017 is set in the Mk I mode.

Instruction Group	Mnemonic	Operand	Number of Bytes	Number of Machine Cycles	Operation	Addressing Area	Skip Condition
Subroutine stack control instructions	PUSH	rp	1	1	(SP–1)(SP–2) ← rp, SP ← SP–2		
		BS	2	2	(SP–1) ← MBS, (SP–2) ← RBS, SP ← SP–2		
	POP	rp	1	1	rp ← (SP+1)(SP), SP ← SP+2		
		BS	2	2	MBS ← (SP+1), RBS ← (SP), SP ← SP+2		
Interrupt control instructions	EI		2	2	IME(IPS.3) ← 1		
		IEXXX	2	2	IEXXX ← 1		
	DI		2	2	IME(IPS.3) ← 0		
		IEXXX	2	2	IEXXX ← 0		
Input/output instructions	IN[Note 1]	A, PORTn	2	2	A ← PORTn (n = 0-7)		
		XA, PORTn	2	2	XA ← PORTn+1, PORTn (n = 4, 6)		
	OUT[Note 1]	PORTn, A	2	2	PORTn ← A (n = 2-7)		
		PORTn, XA	2	2	PORTn+1, PORTn ← XA (n = 4, 6)		
CPU control instruction	HALT		2	2	Set HALT mode (PCC.2 ← 1)		
	STOP		2	2	Set STOP mode (PCC.3 ← 1)		
	NOP		1	1	No operation		
Special instruction	SEL	RBn	2	2	RBS ← n (n = 0-3)		
		MBn	2	2	MBS ← n (n = 0-3, 15)		
	GETI[Notes 2, 3]	taddr	1	3	• When TBR instruction PC_{13-0} ← $(taddr)_{5-0}$+(taddr+1)	*10	
					• When TCALL instruction (SP–4)(SP–1)(SP–2) ← PC_{11-0} (SP–3) ← MBE, RBE, PC_{13}, PC_{12} PC_{13-0} ← $(taddr)_{5-0}$+(taddr+1) SP ← SP–4		
					• When instruction other than TBR and TCALL instructions (taddr) (taddr+1) instruction is executed		Depending on the reference instruction
			1	3	• μPD753017 • When TBR instruction PC_{13-0} ← $(taddr)_{5-0}$+(taddr+1) PC_{14} ← 0		
				4	• When TCALL instruction (SP–5)(SP–6)(SP–3)(SP–4) ← 0, PC_{14-0} (SP–2) ← ×, ×, MBE, RBE PC_{13-0} ← $(taddr)_{5-0}$+(taddr+1) SP ← SP–6, PC_{14} ← 0		
				3	• When instruction other than TBR and TCALL instructions (taddr) (taddr+1) instruction is executed		Depending on the reference instruction

Notes 1. While the IN instruction and OUT instruction are being executed, the MBE must be set to 0 or 1 and MBS must be set to 15.

2. The shaded area is applicable only to the Mk II mode. The other area is applicable only to Mk I mode.

3. The TBR and TCALL instructions are the table definition assembler pseudo instructions of the GETI instruction.

★ **Remark** PC_{14} is fixed to 0 when the μPD753017 is set in the Mk I mode.

12. ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings (T_A = 25 °C)

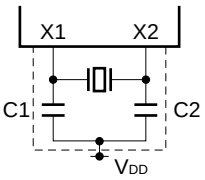
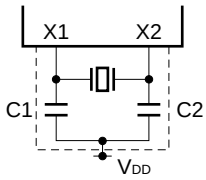
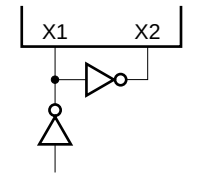
Parameter	Symbol	Conditions		Ratings	Unit
Supply voltage	V_{DD}			–0.3 to +7.0	V
Input voltage	V_{I1}	Other than ports 4 and 5		–0.3 to V_{DD} +0.3	V
	V_{I2}	Ports 4 and 5	Pull-up resistor provided	–0.3 to V_{DD} +0.3	V
			N-ch open drain	–0.3 to +14	V
Output voltage	V_O			–0.3 to V_{DD} +0.3	V
High-level output current	I_{OH}	Per pin		–10	mA
		Total of all pins		–30	mA
Low-level output current	I_{OL}	Per pin		30	mA
		Total of all pins		200	mA
Operating ambient temperature	T_A			–40 to +85	°C
Storage temperature	T_{stg}			–65 to +150	°C

Caution If any of the parameters exceeds the absolute maximum ratings, even momentarily, the quality of the product may be impaired. The absolute maximum ratings are values that may physically damage the product(s). Be sure to use the product(s) within the ratings.

Capacitance (T_A = 25 °C, V_{DD} = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Input capacitance	C_{IN}	f = 1 MHz			15	pF
Output capacitance	C_{OUT}	Pins other than tested pins: 0 V			15	pF
I/O capacitance	C_{IO}				15	pF

Main System Clock Oscillator Characteristics (T_A = –40 to +85 °C)

Oscillator	Recommended Constants	Parameter	Conditions	MIN.	TYP.	MAX.	Unit
Ceramic oscillator		Oscillation frequency (f_X)Note 1	V_{DD} = 2.2 to 5.5 V	1.0		6.0Note 2	MHz
		Oscillation stabilization timeNote 3	After V_{DD} has reached MIN. value of oscillation voltage range			4	ms
Crystal oscillator		Oscillation frequency (f_X)Note 1	V_{DD} = 2.2 to 5.5 V	1.0		6.0Note 2	MHz
		Oscillation stabilization timeNote 3	V_{DD} = 4.5 to 5.5 V			10	ms
			V_{DD} = 2.2 to 5.5 V			30	
External clock		X1 input frequency (f_X)Note 1	V_{DD} = 1.8 to 5.5 V	1.0		6.0Note 4	MHz
		X1 input high-, low-level widths (t_{XH}, t_{XL})	V_{DD} = 1.8 to 5.5 V	83.3		500	ns

Notes 1. The oscillation frequency and X1 input frequency shown above indicate characteristics of the oscillator only. For the instruction execution time, refer to **AC Characteristics**.

★ **2.** When the oscillation frequency is 4.7 MHz < f_X ≤ 6.0 MHz at 2.2 V ≤ V_{DD} < 2.7 V, assign a value other than 0011 to the processor clock control register (PCC). If 0011 is assigned to PCC, one machine cycle falls short of the rated value of 0.85 μs.

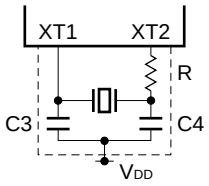
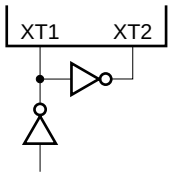
3. The oscillation stabilization time is the time required for oscillation to stabilize after V_{DD} has been applied or STOP mode has been released.

★ **4.** When the X1 input frequency is 4.19 MHz < f_X ≤ 6.0 MHz at 1.8 V ≤ V_{DD} < 2.7 V, assign a value other than 0011 to the processor clock control register (PCC). If 0011 is assigned to PCC, one machine cycle falls short of the rated value of 0.95 μs.

Caution When using the main system clock oscillator, wire the portion enclosed by the dotted line in the above figure as follows to prevent adverse influence from wiring capacitance:

- **Keep the wiring length as short as possible.**
- **Do not cross the wiring with any other signal lines.**
- **Do not route the wiring in the vicinity of a line through which a high alternating current flows.**
- **Always keep the ground point of the capacitor of the oscillator at the same potential as V_{DD}.**
- **Do not ground to a power supply pattern through which a high current flows.**
- **Do not extract any signal from the oscillator.**

Subsystem Clock Oscillator Characteristics (T_A = –40 to +85 °C)

Oscillator	Recommended Constants	Parameter	Conditions	MIN.	TYP.	MAX.	Unit
Crystal oscillator		Oscillation frequency (f_{XT})Note 1	V_{DD} = 2.2 to 5.5 V	32	32.768	35	kHz
		Oscillation stabilization timeNote 2	V_{DD} = 4.5 to 5.5 V		1.0	2	s
			V_{DD} = 2.2 to 5.5 V			10	
External clock		XT1 input frequency (f_{XT})Note 1	V_{DD} = 1.8 to 5.5 V	32		100	kHz
		XT1 input high-, low-level widths (t_{XTH}, t_{XTL})	V_{DD} = 1.8 to 5.5 V	5		15	μs

Notes 1. The oscillation frequency shown above indicate characteristics of the oscillator only. For the instruction execution time, refer to **AC Characteristics**.

2. The oscillation stabilization time is the time required for oscillation to be stabilized after V_{DD} has been applied.

Caution When using the subsystem clock oscillator, wire the portion enclosed by the dotted line in the above figure as follows to prevent adverse influence from to wiring capacitance:

- **Keep the wiring length as short as possible.**
- **Do not cross the wiring with any other signal lines.**
- **Do not route the wiring in the vicinity of a line through which a high alternating current flows.**
- **Always keep the ground point of the capacitor of the oscillator at the same potential as V_{DD}.**
- **Do not ground to a power supply pattern through which a high current flows.**
- **Do not extract any signal from the oscillator.**

The subsystem clock oscillator has a low amplification factor to reduce current dissipation and is more susceptible to noise than the main system clock oscillator. Therefore, exercise utmost care in wiring the subsystem clock oscillator.

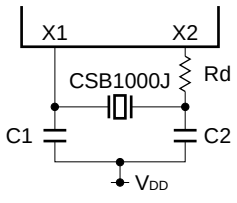
Recommended Oscillator Constants

Ceramic oscillator (T_A = –40 to +85 ˚C)

Manufacturer	Part Number	Frequency (MHz)	Recommended Circuit Constant (pF)		Oscillation Voltage Range (V_{DD})		Remark
			C1	C2	MIN.	MAX.	
Murata Mfg. Co., Ltd.	CSB1000J[Note]	1.0	100	100	2.7	5.5	Rd = 5.6 kΩ
	CSA2.00MG040	2.0	100	100			
	CST2.00MG040		–	–			Capacitor-contained model
	CSA4.19MG	4.19	30	30	2.5	5.5	
	CST4.19MGW		–	–			Capacitor-contained model
	CSA4.19MGU		30	30	2.2	5.5	
	CST4.19MGWU		–	–			Capacitor-contained model
	CSA6.00MG	6.0	30	30	2.7	5.5	
	CST6.00MGW		–	–			Capacitor-contained model
	CSA6.00MGU		30	30	2.5	5.5	
	CST6.00MGWU		–	–			Capacitor-contained model
Kyocera Corp.	KBR-1000F/Y	1.0	220	220	2.9	5.5	–20 to +85 ˚C
	KBR-2.0MS	2.0	82	82	3.1	5.5	
	KBR-4.19MSA	4.19	33	33	2.7	5.5	
	KBR-4.19MKS						
	PBRC 4.19A		–	–			Capacitor-contained model
	PBRC 4.19B		–	–			–20 to +85 ˚C
	KBR-6.0MSA	6.0	33	33	2.8	5.5	–20 to +85 ˚C
	KBR-6.0MKS						
	PBRC 6.00A		–	–			Capacitor-contained model
	PBRC 6.00B		–	–			–20 to +85 ˚C
TDK Corp.	FCR2.0MC3	2.0	30	30	2.0	5.5	
	FCR4.19MC5	4.19			2.5	5.5	
	FCR6.0MC5	6.0			2.7	5.5	

Note When using the CSB1000J (1.00 MHz) by Murata Mfg. Co., Ltd. as a ceramic oscillator, a limiting resistor (Rd = 5.6 kΩ) is necessary (refer to the figure below). The resistor is not necessary when using the other recommended oscillators.

Example of recommended main system clock oscillator (when using CSB1000J by Murata Mfg. Co., Ltd.)



DC Characteristics (T_A = –40 to +85 °C, V_{DD} = 2.2 to 5.5 V)

Parameter	Symbol	Conditions			MIN.	TYP.	MAX.	Unit
★ Low-level output current	I_{OL}	Per pin					15	mA
		Total of all pins					120	mA
High-level input voltage	V_{IH1}	Ports 2, 3		2.7 V ≤ V_{DD} ≤ 5.5 V	0.7 V_{DD}		V_{DD}	V
				2.2 V ≤ V_{DD} < 2.7 V	0.9 V_{DD}		V_{DD}	V
	V_{IH2}	Ports 0, 1, 6, 7, $\overline{\text{RESET}}$		2.7 V ≤ V_{DD} ≤ 5.5 V	0.8 V_{DD}		V_{DD}	V
				2.2 V ≤ V_{DD} < 2.7 V	0.9 V_{DD}		V_{DD}	V
	V_{IH3}	Ports 4, 5	Pull-up resistor provided	2.7 V ≤ V_{DD} ≤ 5.5 V	0.7 V_{DD}		V_{DD}	V
				2.2 V ≤ V_{DD} < 2.7 V	0.9 V_{DD}		V_{DD}	V
			N-ch open drain	2.7 V ≤ V_{DD} ≤ 5.5 V	0.7 V_{DD}		13	V
				2.2 V ≤ V_{DD} < 2.7 V	0.9 V_{DD}		13	V
	V_{IH4}	X1, XT1			V_{DD} – 0.1		V_{DD}	V
Low-level input voltage	V_{IL1}	Ports 2, 3, 4, 5		2.7 V ≤ V_{DD} ≤ 5.5 V	0		0.3 V_{DD}	V
				2.2 V ≤ V_{DD} < 2.7 V	0		0.1 V_{DD}	V
	V_{IL2}	Ports 0, 1, 6, 7, $\overline{\text{RESET}}$		2.7 V ≤ V_{DD} ≤ 5.5 V	0		0.2 V_{DD}	V
				2.2 V ≤ V_{DD} < 2.7 V	0		0.1 V_{DD}	V
	V_{IL3}	X1, XT1			0		0.1	V
High-level output voltage	V_{OH}	$\overline{\text{SCK}}$, SO, ports 0, 2, 3, 6, 7, BP0 to 7 I_{OH} = –1 mA			V_{DD} – 0.5			V
Low-level output voltage	V_{OL1}	$\overline{\text{SCK}}$, SO, ports 0, 2, 3, 4, 5, 6, 7, BP0 to 7		I_{OL} = 15 mA V_{DD} = 4.5 to 5.5 V		0.2	2.0	V
				I_{OL} = 1.6 mA			0.4	V
	V_{OL2}	SB0, 1	N-ch open drain Pull-up resistor ≥ 1 kΩ				0.2 V_{DD}	V
High-level input leakage current	I_{LIH1}	V_{IN} = V_{DD}	Pins other than X1, XT1				3	μA
	I_{LIH2}		X1, XT1				20	μA
	I_{LIH3}	V_{IN} = 13 V	Ports 4, 5 (N-ch open drain)				20	μA
Low-level input leakage current	I_{LIL1}	V_{IN} = 0 V	Pins other than X1, XT1, ports 4 and 5				–3	μA
	I_{LIL2}		X1, XT1				–20	μA
	I_{LIL3}		Ports 4, 5 (N-ch open drain) When input instruction is not executed				–3	μA
★			Ports 4, 5 (N-ch open drain) When input instruction is executed				–30	μA
				V_{DD} = 5 V		–10	–27	μA
				V_{DD} = 3 V		–3	–8	μA
High-level output leakage current	I_{LOH1}	V_{OUT} = V_{DD}	SCK, SO/SB0, SB1, ports 2, 3, 6, 7, ports 4, 5 (with on-chip pull-up resistor), BP0 to 7				3	μA
	I_{LOH2}	V_{OUT} = 13 V	Ports 4, 5 (N-ch open drain)				20	μA
Low-level output leakage current	I_{LOL}	V_{OUT} = 0 V					–3	μA
Internal pull-up resistor	R_{L1}	V_{IN} = 0 V	Ports 0, 1, 2, 3, 6, 7 (except P00 pin)		50	100	200	kΩ
	R_{L2}		Ports 4, 5 (mask option)		15	30	60	kΩ

DC Characteristics (T_A = –40 to +85 °C, V_{DD} = 2.2 to 5.5 V)

Parameter	Symbol	Conditions			MIN.	TYP.	MAX.	Unit
LCD drive voltage	V_{LCD}				2.2		V_{DD}	V
LCD divider resistor[Note 1]	R_{LCD1}				50	100	200	kΩ
	R_{LCD2}				5	10	20	kΩ
LCD output voltage deviation[Note 2] (common)	V_{ODC}	I_O = ±5μA	$V_{LCD0} = V_{LCD}$ $V_{LCD1} = V_{LCD} \times 2/3$ $V_{LCD2} = V_{LCD} \times 1/3$		0		±0.2	V
LCD output voltage deviation[Note 2] (segment)	V_{ODS}	I_O = ±1μA	2.2 V ≤ V_{LCD} ≤ V_{DD}		0		±0.2	V
Supply current[Note 3]	I_{DD1}	6.00 MHz[Note 4] crystal oscillation C1 = C2 = 22 pF	V_{DD} = 5.0 V ± 10 %[Note 5]			1.9	6.0	mA
			V_{DD} = 3.0 V ± 10 %[Note 6]			0.4	1.3	mA
	I_{DD2}		HALT mode	V_{DD} = 5.0 V ± 10 %		0.72	2.1	mA
				V_{DD} = 3.0 V ± 10 %		0.27	0.8	mA
	I_{DD1}	4.19 MHz[Note 4] crystal oscillation C1 = C2 = 22 pF	V_{DD} = 5.0 V ± 10 %[Note 5]			1.5	4.0	mA
			V_{DD} = 3.0 V ± 10 %[Note 6]			0.25	0.75	mA
	I_{DD2}		HALT mode	V_{DD} = 5.0 V ± 10 %		0.7	2.0	mA
				V_{DD} = 3.0 V ± 10 %		0.23	0.7	mA
	I_{DD3}	32.768 kHz[Note 7] crystal oscillation	Low-voltage mode[Note 8]	V_{DD} = 3.0 V ± 10 %		12	35	μA
				V_{DD} = 2.5 V ± 10 %		4.5	12	μA
				V_{DD} = 3.0 V, T_A = 25 °C		12	24	μA
			Low current dissipation mode[Note 9]	V_{DD} = 3.0 V ± 10 %		6	18	μA
				V_{DD} = 3.0 V, T_A = 25 °C		6	12	μA
	I_{DD4}		HALT mode	Low-voltage mode[Note 8]	V_{DD} = 3.0 V ± 10 %	8.5	25	μA
					V_{DD} = 2.5 V ± 10 %	3	9	μA
					V_{DD} = 3.0 V, T_A = 25 °C	8.5	17	μA
				Low power dissipation mode[Note 9]	V_{DD} = 3.0 V ± 10 %	3.5	12	μA
					V_{DD} = 3.0 V, T_A = 25 °C	3.5	7	μA
	I_{DD5}	XT1 = 0 V STOP mode[Note 10]	V_{DD} = 5.0 V ± 10 %			0.05	10	μA
			V_{DD} = 3.0 V ± 10 %			0.02	5	μA
					T_A = 25 °C	0.02	3	μA

Notes 1. Either R_{LCD1} or R_{LCD2} can be selected by mask option.

2. Voltage deviation is the difference between the ideal values (V_{LCDn}; n = 0, 1, 2) of the segment and common outputs and the output voltage.

3. The current flowing through the internal pull-up resistor and the LCD split resistor is not included.

4. Including the case when the subsystem clock oscillates.

5. When the device operates in high-speed mode with the processor clock control register (PCC) set to 0011.

6. When the device operates in low-speed mode with PCC set to 0000.

7. When the device operates on the subsystem clock, with the system clock control register (SCC) set to 1001 and oscillation of the main system clock stopped.

★ **8.** When 0000 is assigned to the sub-oscillator control register (SOS).

★ **9.** When 0010 is assigned to the SOS.

★ **10.** When the sub-oscillator feedback resistor is not used with the SOS set to 00X1 (X: don't care).

AC Characteristics (T_A = –40 to +85 °C, V_{DD} = 2.2 to 5.5 V)

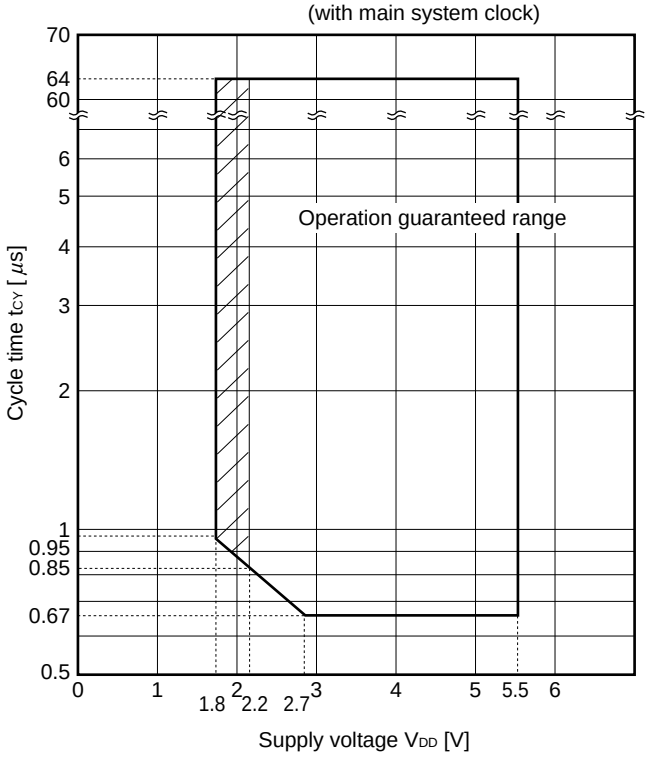
Parameter	Symbol	Conditions			MIN.	TYP.	MAX.	Unit
★ CPU clock cycle time[Note 1] (minimum instruction execution time = 1 machine cycle)	t_{CY}	Operates with main system clock	When using ceramic or crystal	V_{DD} = 2.7 to 5.5 V	0.67		64	μs
					0.85		64	μs
			When using external clock	V_{DD} = 2.7 to 5.5 V	0.67		64	μs
				V_{DD} = 1.8 to 5.5 V	0.95		64	μs
		Operates with subsystem clock			114	122	125	μs
TI0, TI1, TI2 input frequency	f_{TI}	V_{DD} = 2.7 to 5.5 V			0		1	MHz
					0		275	kHz
TI0, TI1, TI2 high-, low-level widths	t_{TIH}, t_{TIL}	V_{DD} = 2.7 to 5.5 V			0.48			μs
					1.8			μs
Interrupt input high-, low-level widths	t_{INTH}, t_{INTL}	INT0		IM02 = 0	**Note 2**			μs
				IM02 = 1	10			μs
		INT1, 2, 4			10			μs
		KR0-7			10			μs
$\overline{\text{RESET}}$ low-level width	t_{RSL}				10			μs

Notes 1. The cycle time of the CPU clock (Φ) is determined by the oscillation frequency of the connected oscillator (and external clock), the system clock control register (SCC), and processor clock control register (PCC).

The figure on the right shows the supply voltage V_{DD} vs. cycle time t_{CY} characteristics when the device operates with the main system clock.

2. $2t_{CY}$ or $128/f_X$ depending on the setting of the interrupt mode register (IM0).

t_{CY} vs V_{DD}
(with main system clock)



Remark The shaded portion is guaranteed only when using the external clock.

Serial transfer operation

2-wire and 3-wire serial I/O modes ($\overline{SCK}$ ··· internal clock output): (T_A = –40 to +85 °C, V_{DD} = 2.2 to 5.5 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
$\overline{SCK}$ cycle time	t_{KCY1}	V_{DD} = 2.7 to 5.5 V		1300			ns
				3800			ns
$\overline{SCK}$ high-, low-level widths	t_{KL1},	V_{DD} = 2.7 to 5.5 V		t_{KCY1}/2–50			ns
	t_{KH1}			t_{KCY1}/2–150			ns
SI[Note 1] setup time (vs. $\overline{SCK}$ ↑)	t_{SIK1}	V_{DD} = 2.7 to 5.5 V		150			ns
				500			ns
SI[Note 1] hold time (vs. $\overline{SCK}$ ↑)	t_{KSI1}	V_{DD} = 2.7 to 5.5 V		400			ns
				600			ns
$\overline{SCK}$ ↓ → SO[Note 1] output	t_{KSO1}	R_L = 1 kΩ[Note 2]	V_{DD} = 2.7 to 5.5 V	0		250	ns
delay time		C_L = 100 pF		0		1000	ns

Notes 1. Replace the parameter with SB0 or SB1 in the 2-wire serial I/O mode.

2. R_L and C_L respectively indicate the load resistance and load capacitance of the SO output line.

2-wire and 3-wire serial I/O modes ($\overline{SCK}$ ··· external clock input): (T_A = –40 to +85 °C, V_{DD} = 2.2 to 5.5 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
$\overline{SCK}$ cycle time	t_{KCY2}	V_{DD} = 2.7 to 5.5 V		800			ns
				3200			ns
$\overline{SCK}$ high-, low-level widths	t_{KL2},	V_{DD} = 2.7 to 5.5 V		400			ns
	t_{KH2}			1600			ns
SI[Note 1] setup time (vs. $\overline{SCK}$ ↑)	t_{SIK2}	V_{DD} = 2.7 to 5.5 V		100			ns
				150			ns
SI[Note 1] hold time (vs. $\overline{SCK}$ ↑)	t_{KSI2}	V_{DD} = 2.7 to 5.5 V		400			ns
				600			ns
$\overline{SCK}$ ↓ → SO[Note 1] output	t_{KSO2}	R_L = 1 kΩ[Note 2]	V_{DD} = 2.7 to 5.5 V	0		300	ns
delay time		C_L = 100 pF		0		1000	ns

Notes 1. Replace the parameter with SB0 or SB1 in the 2-wire serial I/O mode.

2. R_L and C_L respectively indicate the load resistance and load capacitance of the SO output line.

SBI mode ($\overline{SCK}$ ··· internal clock output (master)): (T_A = –40 to +85 °C, V_{DD} = 2.2 to 5.5 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
$\overline{SCK}$ cycle time	t_{KCY3}	V_{DD} = 2.7 to 5.5 V		1300			ns
				3800			ns
$\overline{SCK}$ high-, low-level widths	t_{KL3},	V_{DD} = 2.7 to 5.5 V		t_{KCY3}/2–50			ns
	t_{KH3}			t_{KCY3}/2–150			ns
SB0, 1 setup time	t_{SIK3}	V_{DD} = 2.7 to 5.5 V		150			ns
(vs. $\overline{SCK}$ ↑)				500			ns
SB0, 1 hold time (vs. $\overline{SCK}$ ↑)	t_{KSI3}			t_{KCY3}/2			ns
$\overline{SCK}$ ↓ → SB0, 1 output	t_{KSO3}	R_L = 1 kΩ[Note]	V_{DD} = 2.7 to 5.5 V	0		250	ns
delay time		C_L = 100 pF		0		1000	ns
$\overline{SCK}$ ↑ → SB0, 1 ↓	t_{KSB}			t_{KCY3}			ns
SB0, 1 ↓ → $\overline{SCK}$ ↓	t_{SBK}			t_{KCY3}			ns
SB0, 1 low-level width	t_{SBL}			t_{KCY3}			ns
SB0, 1 high-level width	t_{SBH}			t_{KCY3}			ns

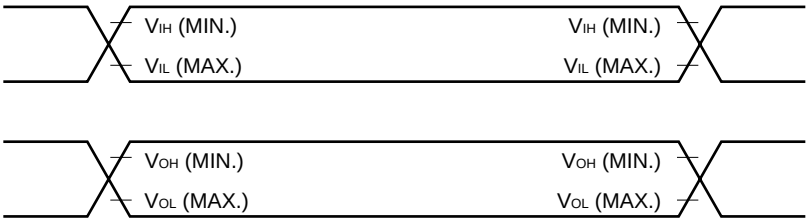
Note R_L and C_L respectively indicate the load resistance and load capacitance of the SB0 and 1 output lines.

SBI mode ($\overline{SCK}$ ··· external clock input (slave)): (T_A = –40 to +85 °C, V_{DD} = 2.2 to 5.5 V)

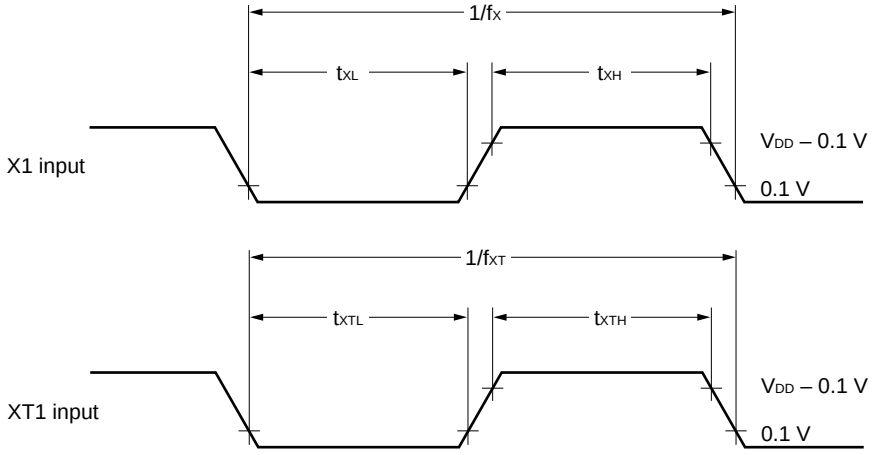
Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
$\overline{SCK}$ cycle time	t_{KCY4}	V_{DD} = 2.7 to 5.5 V		800			ns
				3200			ns
$\overline{SCK}$ high-, low-level widths	t_{KL4},	V_{DD} = 2.7 to 5.5 V		400			ns
	t_{KH4}			1600			ns
SB0, 1 setup time	t_{SIK4}	V_{DD} = 2.7 to 5.5 V		100			ns
(vs. $\overline{SCK}$ ↑)				150			ns
SB0, 1 hold time (vs. $\overline{SCK}$ ↑)	t_{KSI4}			t_{KCY4}/2			ns
$\overline{SCK}$ ↓ → SB0, 1 output	t_{KSO4}	R_L = 1 kΩ[Note]	V_{DD} = 2.7 to 5.5 V	0		300	ns
delay time		C_L = 100 pF		0		1000	ns
$\overline{SCK}$ ↑ → SB0, 1 ↓	t_{KSB}			t_{KCY4}			ns
SB0, 1 ↓ → $\overline{SCK}$ ↓	t_{SBK}			t_{KCY4}			ns
SB0, 1 low-level width	t_{SBL}			t_{KCY4}			ns
SB0, 1 high-level width	t_{SBH}			t_{KCY4}			ns

Note R_L and C_L respectively indicate the load resistance and load capacitance of the SB0 and 1 output lines.

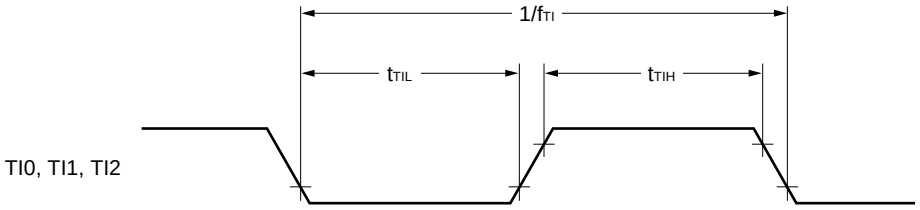
★ **AC timing test points (except X1 and XT1 inputs)**



Clock timing

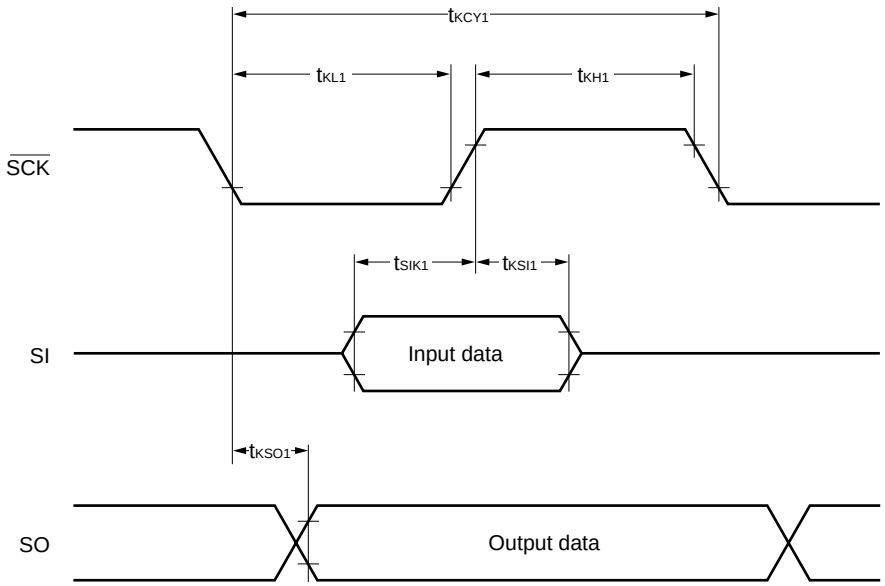


TI0, TI1, TI2 timing

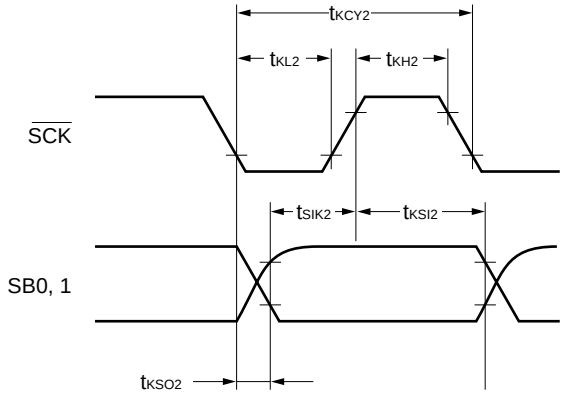


Serial transfer timing

3-wire serial I/O mode

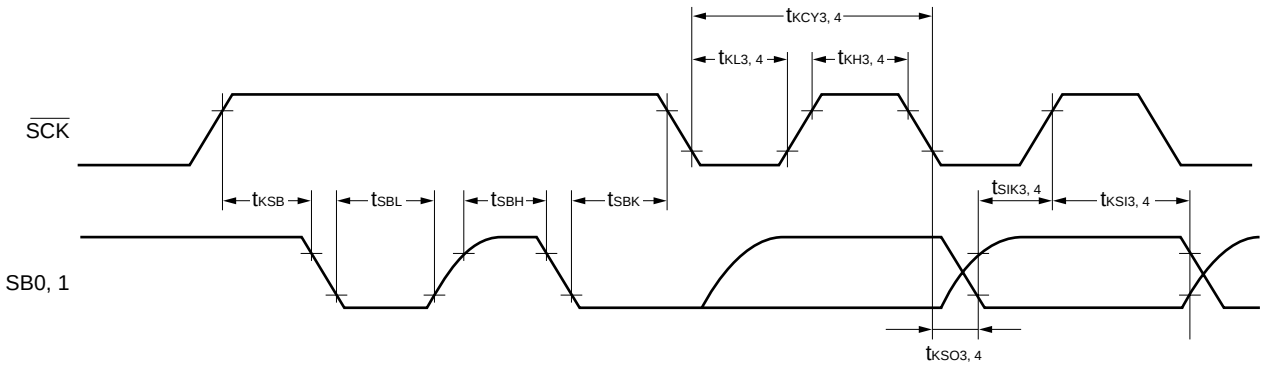


2-wire serial I/O mode

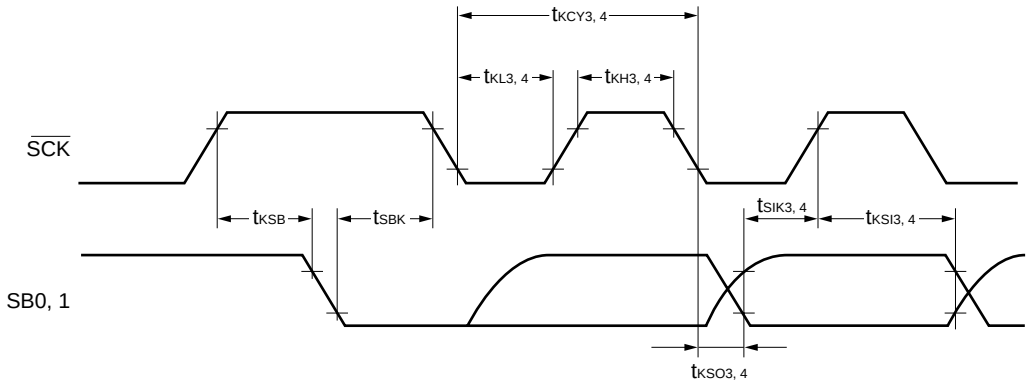


Serial transfer timing

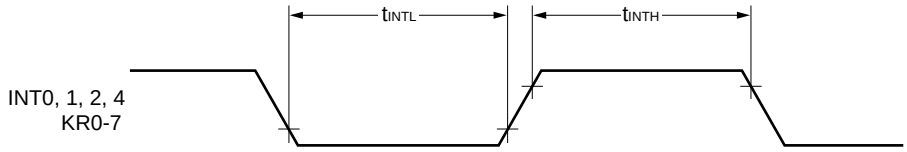
Bus release signal transfer



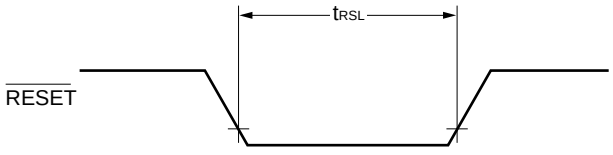
Command signal transfer



Interrupt input timing



$\overline{\text{RESET}}$ input timing



Data retention characteristics of data memory in STOP mode and at low supply voltage (T_A = –40 to +85 °C)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Release signal setup time	t_{SREL}		0			μs
Oscillation stabilization wait time[Note 1]	t_{WAIT}	Released by $\overline{RESET}$		**Note 2**		ms
		Released by interrupt request		**Note 3**		ms

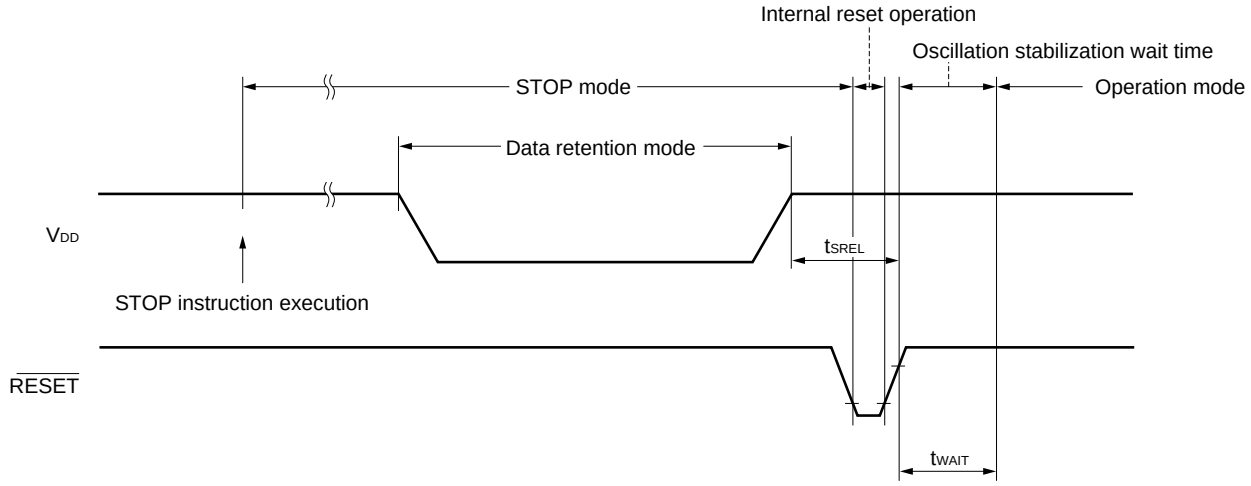
Notes 1. The oscillation stabilization wait time is the time during which the CPU stops operating to prevent unstable operation when oscillation is started.

2. Either $2^{17}/f_X$ or $2^{15}/f_X$ can be selected by mask option.

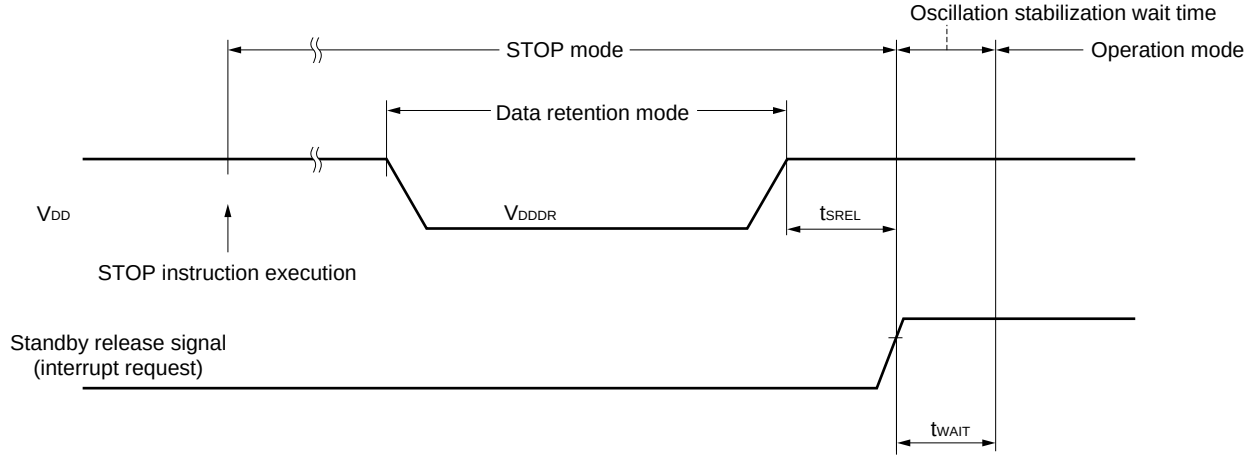
3. Set by the basic interval timer mode register (BTM). (Refer to the table below.)

BTM3	BTM2	BTM1	BTM0	Wait Time	
				f_x = 4.19 MHz	f_x = 6.0 MHz
–	0	0	0	$2^{20}/f_x$ (approx. 250 ms)	$2^{20}/f_x$ (approx. 175 ms)
–	0	1	1	$2^{17}/f_x$ (approx. 31.3 ms)	$2^{17}/f_x$ (approx. 21.8 ms)
–	1	0	1	$2^{15}/f_x$ (approx. 7.82 ms)	$2^{15}/f_x$ (approx. 5.46 ms)
–	1	1	1	$2^{13}/f_x$ (approx. 1.95 ms)	$2^{13}/f_x$ (approx. 1.37 ms)

Data retention timing (when STOP mode released by $\overline{RESET}$)

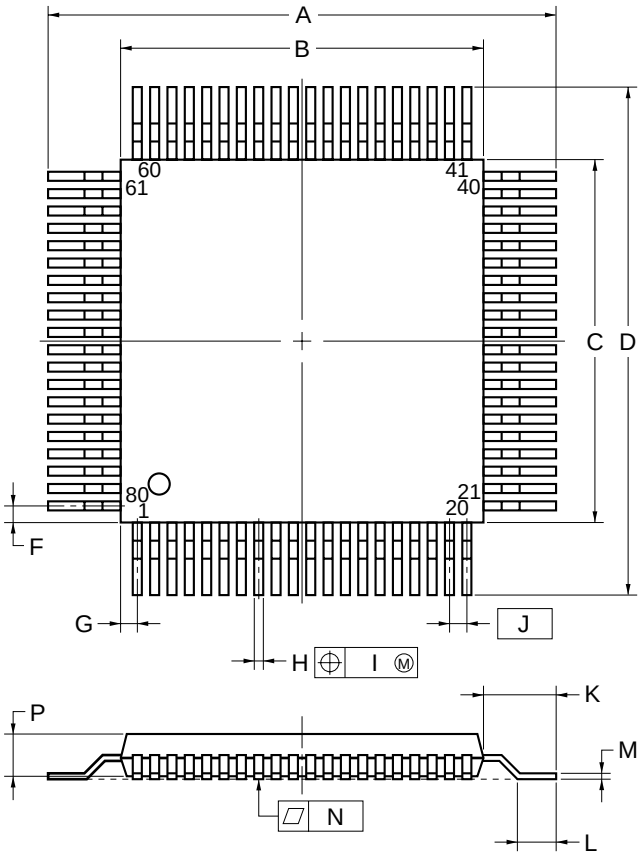


Data retention timing (standby release signal: when STOP mode released by interrupt signal)

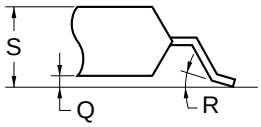


13 . PACKAGE DRAWINGS

80 PIN PLASTIC QFP (14x14)



detail of lead end



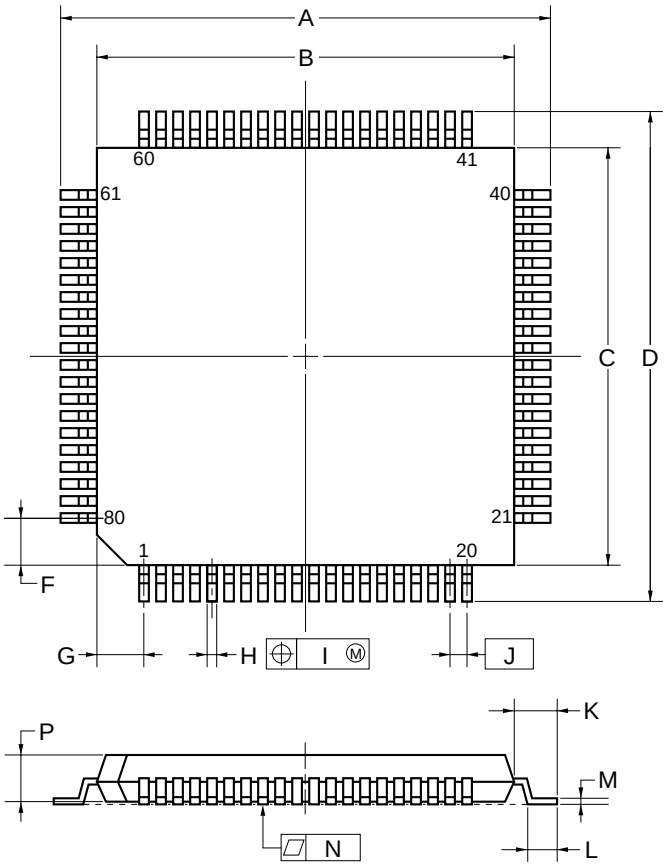
NOTE

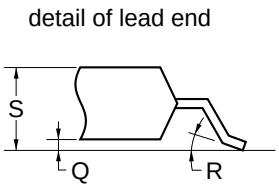
Each lead centerline is located within 0.13 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
A	17.2±0.4	0.677±0.016
B	14.0±0.2	$0.551^{+0.009}_{-0.008}$
C	14.0±0.2	$0.551^{+0.009}_{-0.008}$
D	17.2±0.4	0.677±0.016
F	0.825	0.032
G	0.825	0.032
H	0.30±0.10	$0.012^{+0.004}_{-0.005}$
I	0.13	0.005
J	0.65 (T.P.)	0.026 (T.P.)
K	1.6±0.2	0.063±0.008
L	0.8±0.2	$0.031^{+0.009}_{-0.008}$
M	$0.15^{+0.10}_{-0.05}$	$0.006^{+0.004}_{-0.003}$
N	0.10	0.004
P	2.7±0.1	$0.106^{+0.005}_{-0.004}$
Q	0.1±0.1	0.004±0.004
R	5°±5°	5°±5°
S	3.0 MAX.	0.119 MAX.

S80GC-65-3B9-5

80 PIN PLASTIC TQFP (FINE PITCH) (12×12)





NOTE

Each lead centerline is located within 0.10 mm (0.004 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES
A	14.00±0.20	0.551±0.008
B	12.00±0.20	$0.472^{+0.009}_{-0.008}$
C	12.00±0.20	$0.472^{+0.009}_{-0.008}$
D	14.00±0.20	0.551±0.008
F	1.25	0.049
G	1.25	0.049
H	$0.22^{+0.05}_{-0.04}$	0.009±0.002
I	0.10	0.004
J	0.50 (T.P.)	0.020 (T.P.)
K	1.00±0.20	$0.039^{+0.009}_{-0.008}$
L	0.50±0.20	$0.020^{+0.008}_{-0.009}$
M	$0.145^{+0.055}_{-0.045}$	0.006±0.002
N	0.10	0.004
P	1.05	0.041
Q	0.10±0.05	0.004±0.002
R	5°±5°	5°±5°
S	1.27 MAX.	0.050 MAX.

P80GK-50-BE9-5

14. RECOMMENDED SOLDERING CONDITIONS

Solder the μPD753017 under the following recommended conditions.

For the details on the recommended soldering conditions, refer to Information Document **Semiconductor Device Mounting Technology Manual (C10535E)**.

For the soldering methods and conditions other than those recommended, consult NEC.

Table 14-1. Soldering Conditions of Surface Mount Type

(1) μPD753012GC-XXX-3B9: 80-pin plastic QFP (14 × 14 mm)
μPD753016GC-XXX-3B9: 80-pin plastic QFP (14 × 14 mm)
μPD753017GC-XXX-3B9: 80-pin plastic QFP (14 × 14 mm)

Soldering Method	Soldering Conditions	Symbol of Recommended Condition
★ Infrared reflow	Package peak temperature: 235 °C, Time: 30 seconds max. (210 °C min.), Number of times: 3 max.	IR35-00-3
★ VPS	Package peak temperature: 215 °C, Time: 40 seconds max. (200 °C min.), Number of times: 3 max.	VP15-00-3
Wave soldering	Solder bath temperature: 260 °C max., Time: 10 seconds max., Number of times: 1 Preheating temperature: 120 °C max. (package surface temperature)	WS60-00-1
Partial heating	Pin temperature: 300 °C max., Time: 3 seconds max. (per side of device)	–

Caution Do not use two or more soldering methods in combination (except partial heating).

(2) μPD753012GK-XXX-BE9: 80-pin plastic TQFP (fine pitch) (12 × 12 mm)
μPD753016GK-XXX-BE9: 80-pin plastic TQFP (fine pitch) (12 × 12 mm)
μPD753017GK-XXX-BE9: 80-pin plastic TQFP (fine pitch) (12 × 12 mm)

Soldering Method	Soldering Conditions	Symbol of Recommended Condition
Infrared reflow	Package peak temperature: 235 °C, Time: 30 seconds max. (210 °C min.), Number of times: 2 max., Number of days: 7[Note] (After that, prebaking is necessary at 125 °C for 10 hours.) **<Precaution>** Products other than those packed in heat-resistant trays (such as those packed in a magazine, taping, or non-heat-resistant tray) cannot be baked while they are in their packaging.	IR35-107-2
VPS	Package peak temperature: 215 °C, Time: 40 seconds max. (200 °C min.), Number of times: 2 max., Number of days: 7[Note] (After that, prebaking is necessary at 125 °C for 10 hours.) **<Precaution>** Products other than those packed in heat-resistant trays (such as those packed in a magazine, taping, or non-heat-resistant tray) cannot be baked while they are in their packaging.	VP15-107-2
Pin partial heating	Pin temperature: 300 °C max., Time: 3 seconds max. (per side of device)	–

Note The number of days for storage after the dry pack has been opened. The storing conditions are 25 °C, 65% RH max.

Caution Do not use two or more soldering methods in combination (except partial heating).

APPENDIX A μPD75316B, 753017 AND 75P3018 FUNCTION LIST

Parameter		μPD75316B	μPD753017	μPD75P3018
Program memory		Mask ROM 0000H-3F7FH (16256 × 8 bits)	Mask ROM 0000H-5FFFH (24576 × 8 bits)	One-time PROM 0000H-7FFFH (32768 × 8 bits)
Data memory		000H-3FFH (1024 × 4 bits)		
CPU		Standard CPU	75XL CPU	
Instruction execution time	When main system clock is selected	0.95, 1.91, 15.3 μs (at 4.19 MHz operation)	• 0.95, 1.91, 3.81, 15.3 μs (at 4.19 MHz operation) • 0.67, 1.33, 2.67, 10.7 μs (at 6.0 MHz operation)	
	When subsystem clock is selected	122 μs (32.768 kHz operation)		
Pin connection	44	P12/INT2	P12/INT2/TI1/TI2	
	47	P21	P21/PTO1	
	48	P22/PCL	P22/PCL/PTO2	
	50-53	P30-P33		P30/MD0-P33/MD3
	57	IC		V_{PP}
Stack	SBS register	None	SBS.3 = 1: Mk I mode selection SBS.3 = 0: Mk II mode selection	
	Stack area	000H-0FFH	n00H-nFFH (n = 0-3)	
	Subroutine call instruction stack operation	2-byte stack	Mk I mode: 2-byte stack Mk II mode: 3-byte stack	
Instruction	BRA !addr1 CALLA !addr1	Unavailable	Mk I mode: unavailable Mk II mode: available	

	MOVT XA, @BCDE
	MOVT XA, @BCXA
	BR BCDE
	BR BCXA
			Available	

	CALL !addr	3 machine cycles	Mk I mode: 3 machine cycles, Mk II mode: 4 machine cycles	
	CALLF !faddr	2 machine cycles	Mk I mode: 2 machine cycles, Mk II mode: 3 machine cycles	
Timer		3 channels • Basic interval timer: 1 channel • 8-bit timer/event counter: 1 channel • Watch timer: 1 channel	5 channels • Basic interval timer/watchdog timer: 1 channel • 8-bit timer/event counter: 3 channels (can be used as 16-bit timer/event counter, carrier generator, or timer with gate) • Watch timer: 1 channel	

Parameter		μPD75316B	μPD753017	μPD75P3018
Clock output (PCL)		Φ, 524, 262, 65.5 kHz (Main system clock: at 4.19 MHz operation)	• Φ, 524, 262, 65.5 kHz (Main system clock: at 4.19 MHz operation) • Φ, 750, 375, 93.8 kHz (Main system clock: at 6.0 MHz operation)	
BUZ output		2 kHz (Main system clock: at 4.19 MHz operation)	• 2, 4, 32 kHz (Main system clock: at 4.19 MHz operation or subsystem clock: at 32.768 kHz operation) • 2.93, 5.86, 46.9 kHz (Main system clock: at 6.0 MHz operation)	
Serial interface		3 modes are available • 3-wire serial I/O mode ... MSB/LSB can be selected for transfer top bit • 2-wire serial I/O mode • SBI mode		
SOS register	Feedback resistor cut flag (SOS.0)	None	Provided	
	Sub-oscillator current cut flag (SOS.1)	None	Provided	
Register bank selection register (RBS)		None	Yes	
Standby release by INT0		No	Yes	
Vectored interrupt		External: 3, internal: 3	External: 3, internal: 5	
★ Supply voltage		V_{DD} = 2.0 to 6.0 V	V_{DD} = 2.2 to 5.5 V	
Operation ambient temperature		T_A = –40 to +85°C		
Package		• 80-pin plastic TQFP (fine pitch) (12 × 12 mm) • 80-pin plastic QFP (14 × 14 mm)		

APPENDIX B DEVELOPMENT TOOLS

The following development tools are provided for system development using the μPD753017. The 75XL series uses a common relocatable assembler, in combination with a device file matching each machine.

Language processor

RA75X relocatable assembler	Host Machine	OS	Distribution media	Part Number (product name)
★	PC-9800 series	MS-DOS™ (Ver. 3.30 to Ver. 6.2[Note])	3.5-inch 2HD	μS5A13RA75X
			5-inch 2HD	μS5A10RA75X
	IBM PC/AT™ and compatible machines	Refer to **OS for IBM PC**	3.5-inch 2HC	μS7B13RA75X
			5-inch 2HC	μS7B10RA75X

Device file	Host Machine	OS	Distribution media	Part Number (product name)
★	PC-9800 series	MS-DOS™ (Ver. 3.30 to Ver. 6.2[Note])	3.5-inch 2HD	μS5A13DF753017
			5-inch 2HD	μS5A10DF753017
	IBM PC/AT and compatible machines	Refer to **OS for IBM PC**	3.5-inch 2HC	μS7B13DF753017
			5-inch 2HC	μS7B10DF753017

Note Ver. 5.00 and later have the task swap function, but cannot be used for this software.

Remark The operation of the assembler and device file is guaranteed only on the above host machines and OSs.

PROM write tools

<table>
<tr><td rowspan="4">Hardware</td><td>PG-1500</td><td colspan="4">PG-1500 is a PROM programmer which enables you to program single chip microcomputers containing PROM by stand-alone or host machine operation by connecting an attached board and optional programmer adapter to PG-1500.
It also enables you to program typical PROM devices of 256K bits to 4M bits.</td></tr>
<tr><td>PA-75P316BGC</td><td colspan="4">PROM programmer adapter for μPD75P3018GC. Connect the programmer adapter to PG-1500 for use.</td></tr>
<tr><td>PA-75P316BGK</td><td colspan="4">PROM programmer adapter for μPD75P3018GK. Connect the programmer adapter to PG-1500 for use.</td></tr>
<tr><td rowspan="5">Software</td><td rowspan="5">PG-1500 controller</td><td colspan="4">PG-1500 and a host machine are connected by serial and parallel interfaces and PG-1500 is controlled on the host machine.</td></tr>
<tr><td rowspan="2">Host machine</td><td colspan="2" rowspan="2"></td><td rowspan="2">Part number (product name)</td></tr>
<tr></tr>
<tr><td>PC-9800 series</td><td>MS-DOS
(Ver. 3.30 to Ver. 6.2^{Note})</td><td>3.5-inch 2HD</td><td>μS5A13PG1500</td></tr>
<tr><td>IBM PC/AT and compatible machines</td><td>Refer to OS for IBM PC</td><td>5-inch 2HD</td><td>μS5A10PG1500</td></tr>
<tr><td></td><td></td><td>3.5-inch 2HC</td><td>μS7B13PG1500</td></tr>
<tr><td></td><td></td><td>5-inch 2HC</td><td>μS7B10PG1500</td></tr>
</table>

★

Note Ver.5.00 and later have the task swap function, but it cannot be used for this software.

Remark The operation of the PG-1500 controller is guaranteed only on the above host machines and OSs.

Debugging tool

The in-circuit emulators (IE-75000-R and IE-75001-R) are available as the program debugging tool for the μPD753017.

The system configurations are described as follows.

Hardware	IE-75000-R**Note1**	In-circuit emulator for debugging the hardware and software when developing the application systems that use the 75X series and 75XL series. When developing a μPD753017 subseries, the emulation board IE-75300-R-EM and emulation probe that are sold separately must be used with the IE-75000-R. By connecting with the host machine and the PROM programmer, efficient debugging can be made. It contains the emulation board IE-75000-R-EM which is connected.
	IE-75001-R	In-circuit emulator for debugging the hardware and software when developing the application systems that use the 75X series and 75XL series. When developing a μPD753017 sub-series, the emulation board IE-75300-R-EM and emulation probe which are sold separately must be used with the IE-75001-R. It can debug the system efficiently by connecting the host machine and PROM programmer.
	IE-75300-R-EM	Emulation board for evaluating the application systems that use the μPD753017 subseries. It must be used with the IE-75000-R or IE-75001-R.
	EP-753017GC-R EV-9200GC-80	Emulation probe for the μPD753017GC. It must be connected to IE-75000-R (or IE-75001-R) and IE-75300-R-EM. It is supplied with the 80-pin conversion socket EV-9200GC-80 which facilitates connection to a target system.
	EP-753017GK-R ★ TGK-080SDW**Note 2**	Emulation probe for the μPD753017GK. It must be connected to the IE-75000-R (or IE-75001-R) and IE-75300-R-EM. It is supplied with the 80-pin conversion adapter TGK-080SDW which facilitates connection to a target system.
Software	IE control program	Connects the IE-75000-R or IE-75001-R to a host machine via RS-232-C and Centronix I/F and controls the above hardware on a host machine.

Host machine	OS	Distribution media	Part number (product name)
PC-9800 series	MS-DOS Ver. 3.30 to ★ Ver. 6.2**Note 3**	3.5-inch 2HD	μS5A13IE75X
		5-inch 2HD	μS5A10IE75X
IBM PC/AT and its compatible machines	Refer to **OS for IBM PC**	3.5-inch 2HC	μS7B13IE75X
		5-inch 2HC	μS7B10IE75X

Notes 1. Maintenance parts

★ **2.** This is a product of Tokyo Eletech Corp. (Tokyo 03-5295-1661)
When purchasing this product, consult your NEC distributor.

3. Ver.5.00 and later have the task swap function, but it cannot be used for this software.

Remark The operation of the IE control program is guaranteed only on the above host machines and OSs.

OS for IBM PC

The following IBM PC OS's are supported.

OS	Version
PC DOS™	Ver. 3.1 to Ver. 6.3 J6.1/V Note to J6.3/V Note
MS-DOS	Ver. 5.0 to Ver. 6.22 5.0/V Note to 6.2/V Note
IBM DOS™	J5.02/V Note

Note Only English version is supported.

Caution Ver. 5.0 and later have the task swap function, but it cannot be used for this software.

APPENDIX C RELATED DOCUMENTS

Some of the following related documents are preliminary.

Device Related Documents

Document Name	Document No.	
	Japanese	English
μPD753012, 753016, 753017 Data Sheet	U10140J	U10140E (This manual)
μPD75P3018 Data Sheet	U10956J	U10956E
μPD753017 User's Manual	U11282J	U11282E
μPD753017 Instruction	IEM-5598	–
75XL Series Selection Guide	U10453J	U10453E

Development Tool Related Documents

Document Name			Document No.	
			Japanese	English
Hardware	IE-75000 R/IE-75001-R User's Manual		EEU-846	EEU-1416
	IE-75300-R-EM User's Manual		U11354J	U11354E
	EP-753017GC/GK-R User's Manual		EEU-967	EEU-1494
	PG-1500 User's Manual		U11940J	U11940E
Software	RA75X Assembler Package	Operation	U12622J	EEU-1346
	User's Manual	Language	U12385J	EEU-1363
	PG-1500 Controller User's Manual	PC-9800 Series (MS-DOS) Base	EEU-704	EEU-1291
		IBM PC Series (PC DOS) Base	EEU-5008	U10540E

Other Documents

Document Name	Document No.	
	Japanese	English
IC Package Manual	C10943X	
Semiconductor Device Mounting Technology Manual	C10535J	C10535E
Quality Grades on NEC Semiconductor Devices	C11531J	C11531E
NEC Semiconductor Device Reliability/Quality Control System	C10983J	C10983E
Guide to Prevent Damage for Semiconductor Devices by Electrostatic Discharge (ESD)	C11892J	C11892E
Semiconductor Devices Quality Guarantee Guide	C11893J	MEI-1202
Guide for Products Related to Microcomputer : Other Companies	U11416J	–

Caution The above related documents are subject to change without notice. For design purpose, etc., be sure to use the latest documents.

NOTES FOR CMOS DEVICES

① PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note: Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

② HANDLING OF UNUSED INPUT PINS FOR CMOS

Note: No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS device behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to V_{DD} or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

③ STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note: Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

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