

16-bit, 48 kHz, low-cost stereo current DAC

Rev. 02 — 20 February 2006

Product data sheet

1. General description

The UDA1431T is a 16-bit, 48 kHz, single-chip stereo DAC employing bitstream conversion techniques.

The UDA1431T supports the I^2S -bus data format with word lengths of up to 24 bits, MSB justified and can be operated with a 256f_s master clock mode.

The audio outputs meet the IEC 61938 specification.

2. Features

- Low power consumption
- Analog power supply voltage from 10.8 V to 13.2 V
- Digital power supply voltage from 3.1 V to 3.5 V
- Master clock frequencies of 256fs
- Supports sampling frequencies up to 48 kHz
- Integrated digital filter
- No analog post filtering required for DAC
- Slave mode only applications
- I²S-bus input interface: 16-bit, 18-bit, 20-bit and 24-bit format compatible
- CMOS levels compatible digital inputs and outputs
- Very easy application
- Advanced audio configuration:
 - Stereo line output
 - High linearity, wide dynamic range and low distortion
- Small package size (SO14)

3. Applications

- PC audio applications
- Car radio applications
- DVD players
- Digital set-top boxes



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4. Quick reference data

Table 1: Quick reference data

 V_{DDA} = 12.0 V; V_{DDD} = 3.3 V; T_{amb} = 25 °C; f_s = 48 kHz; f_i = 1 kHz; all voltages referenced to ground (pins V_{SSA} and V_{SSD}); unless otherwise specified.

	SSD), uniess ourierwise	-			-		
Symbol	Parameter	Conditions		Min	Тур	Max	Unit
Supplies							
V _{DDA}	analog supply voltage (for DAC)			10.8	12.0	13.2	V
V _{DDD}	digital supply voltage			3.1	3.3	3.5	V
I _{DDA}	analog supply current	$V_{DDA} = 12.0 V$					
	(for DAC)	operating	<u>[1]</u>	-	6.6	-	mA
		power-down		-	0.8	-	mA
I _{DDD}	digital supply current	$V_{DDD} = 3.3 V$					
		operating	<u>[1]</u>	-	7.0	-	mA
		power-down		-	6.8	-	mA
P _{tot}	total power dissipation	operating	<u>[1]</u>	-	102	-	mW
T _{amb}	ambient temperature			5	-	65	°C
Digital-to-ana	alog converter						
V _{o(rms)}	output voltage (RMS value)			1.575	1.880	1.925	V
(THD + N)/S	total harmonic	at 0 dB	[2] [3]	-62	-66	-	dB
	distortion-plus-noise to signal ratio	at –60 dB	[2] [4]	-	-32.5	-	dB
S/N	signal-to-noise ratio		[3] [5]	89	94	-	dB
α_{cs}	channel separation	at 0 dB; from 1 kHz to 20 kHz		85	98	-	dB

[1] A 1 kHz at 0 dB sine wave input is applied.

[2] (THD + N)/S is the power ratio between the sum of noise and distortion and the output signal.

[3] Measurement is performed with a 22 kHz low-pass filter and is unweighted.

[4] Measurement is performed with a ITU-R-2K filter and is unweighted.

[5] S/N is the power ratio between the output signal and the noise measured with no signal applied.

5. Ordering information

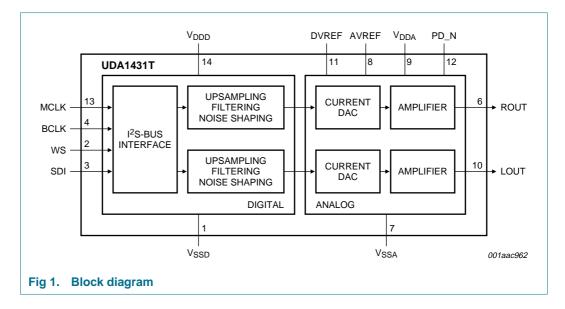
Table 2: C	Ordering info	ormation				
Type Package						
number	Name	Description	Version			
UDA1431T	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1			

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UDA1431T

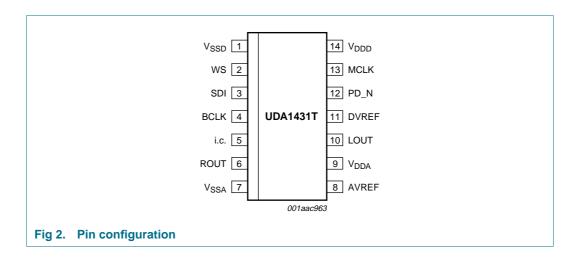
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6. Block diagram



7. Pinning information

7.1 Pinning



7.2 Pin description

Table 3:	Pin des	cription
Symbol	Pin	Description
V _{SSD}	1	digital ground
WS	2	word select input
SDI	3	serial audio data input
BCLK	4	bit clock input
i.c.	5	internally connected; do not connect or connect to V _{DDD}

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Table 3:	Pin desc	Pin description continued				
Symbol	Pin	Description				
ROUT	6	right channel output				
V _{SSA}	7	analog ground (for DAC)				
AVREF	8	regulator decoupling				
V _{DDA}	9	analog supply voltage (for DAC)				
LOUT	10	left channel output				
DVREF	11	internal reference voltage (digital part)				
PD_N	12	power-down input (active LOW)				
MCLK	13	master clock input (256fs)				
V _{DDD}	14	digital supply voltage				

8. Functional description

8.1 Master clock

The UDA1431T operates in slave mode only. Therefore, in all applications the system devices must provide a master clock (pin MCLK) at $256f_s$ for correct operation. The master clock must be locked in frequency to the digital interface input signals.

The UDA1431T supports sampling frequencies up to 48 kHz.

8.2 Data formats

The I^2S -bus formats are shown in Figure 3.

Left and right data channel words are time multiplexed.

The UDA1431T supports I²S-bus formats with data word length up to 24 bits.

The BCLK clock can be up to $48f_s$, or in other words the BCLK frequency is 48 times or less the word select frequency (pin WS): $f_{BCLK} \le 48 \times f_{WS}$.

Important: The WS edge MUST fall on the negative edge of the BCLK at all times for proper operation of the digital interface.

8.3 Noise shaper

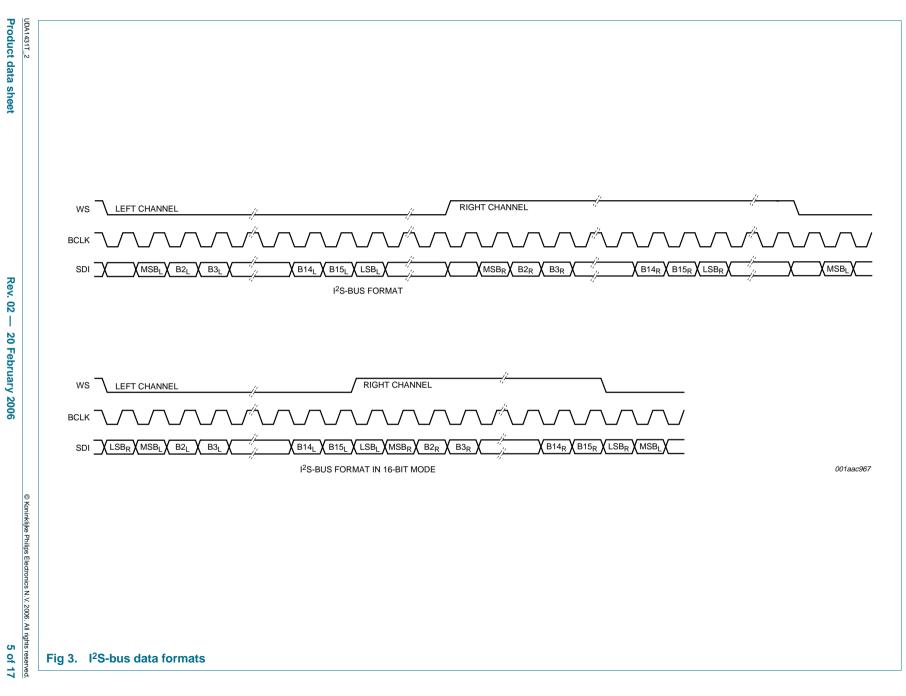
The 1st-order noise shaper operates at $32f_s$. It shifts in-band quantization noise to frequencies well above the audio band. This noise shaping technique enables high signal-to-noise ratios to be achieved. The noise shaper output is converted into an analog signal using a current DAC.

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9. Limiting values

Table 4:Limiting valuesIn accordance with the Absolute Maximum Rating System (IEC 60134).							
Symbol	Parameter	Conditions	Min	Max	Unit		
V _{DDA}	analog supply voltage (for DAC)		<u>[1]</u> -	15.2	V		
V _{DDD}	digital supply voltage		<u>[1]</u> _	5.5	V		
T _{xtal}	crystal temperature		-	125	°C		
T _{stg}	storage temperature		-65	+125	°C		

[1] All supply connections must be made to the same power supply.

10. Thermal characteristics

Table 5:	Thermal characteristics			
Symbol	Parameter	Conditions	Тур	Unit
R _{th(j-a)}	thermal resistance from junction to ambient	in free air	115	K/W

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11. Static characteristics

Table 6: Static characteristics

 V_{DDA} = 12.0 V; V_{DDD} = 3.3 V; T_{amb} = 25 °C; all voltages referenced to ground (pins V_{SSA} and V_{SSD}); unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
Supplies	5						
V _{DDA}	analog supply voltage (for DAC)			10.8	12.0	13.2	V
V _{DDD}	digital supply voltage			3.1	3.3	3.5	V
I _{DDA}	analog supply current	V _{DDA} = 12.0 V					
	(for DAC)	operating	[1]	-	6.6	-	mA
		power-down		-	0.8	-	mA
I _{DDD}	digital supply current	$V_{DDD} = 3.3 V$					
		operating	[1]	-	7.0	-	mA
		power-down		-	6.8	-	mA
P _{tot}	total power dissipation	operating	[1]	-	102	-	mW
T _{amb}	ambient temperature			5	-	65	°C
Digital in	nputs: pins BCLK, WS, S	DI, PD_N and MCLK					
V _{IL}	LOW-level input voltage			0	-	$0.3V_{DDD}$	V
V _{IH}	HIGH-level input voltage			$0.7V_{DDD}$	-	V _{DDD}	V
llul	input leakage current (absolute value)			-	-	1	μA
Ci	input capacitance			-	-	2.5	pF
Digital-to	o-analog converter						
V _{O(DC)}	channel DC output voltage	with respect to pin V _{SSA}		-	4.9	-	V

[1] A 1 kHz at 0 dB sine wave input is applied.

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12. Dynamic characteristics

Table 7: Dynamic characteristics

 $V_{DDA} = 12.0 V$; $V_{DDD} = 3.3 V$; $T_{amb} = 25 °C$; $f_s = 48 \text{ kHz}$; $f_i = 1 \text{ kHz}$; all voltages referenced to ground (pins V_{SSA} and V_{SSD}); unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Мах	Unit	
Digital-to-analog converter								
V _{o(rms)}	output voltage (RMS value)			1.575	1.880	1.925	V	
ΔV_0	unbalance between channels	at –20 dB on both channels		-	-	0.5	dB	
(THD + N)/S	total harmonic	at 0 dB	[1] [2]	-62	-66	-	dB	
	distortion-plus-noise to signal ratio	at -60 dB	<u>[1] [3]</u>	-	-32.5	-	dB	
DNR	dynamic range	at –60 dB	<u>[3] [4]</u>	89	92.5	-	dB	
S/N	signal-to-noise ratio		[2] [5]	89	94	-	dB	
G _{pb}	pass-band gain	at –20 dB; over the band 20 Hz to 20 kHz		-1.0	-	+0.5	dB	
В	bandwidth	at –3 dB cut-off frequency		-	22	-	kHz	
φmis	phase mismatch	at –20 dB; over the band 20 Hz to 20 kHz		-	0.2	1.5	deg	
α_{cs}	channel separation	at 0 dB; from 1 kHz to 20 kHz		85	98	-	dB	

[1] (THD + N)/S is the power ratio between the sum of noise and distortion, and the output signal.

[2] Measurement is performed with a 22 kHz low-pass filter and is unweighted.

[3] Measurement is performed with a ITU-R-2K filter and is unweighted.

 $\label{eq:constraint} [4] \quad \text{DNR is the result of (THD + N)/S corrected with the full-scale ratio (60 dB in this case).}$

[5] S/N is the power ratio between the output signal and the noise measured with no signal applied.

Table 8: Timing characteristics

 V_{DDA} = 12.0 V; V_{DDD} = 3.3 V; T_{amb} = 5 °C to 65 °C; f_s = 48 kHz; all voltages referenced to ground (pins V_{SSA} and V_{SSD}); unless otherwise specified.

	000,					
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
t _{d(po-so)}	delay time from power on to stable output	MCLK active	-	-	500	ms
Master cl	ock (see <u>Figure 4</u>)					
Master clo	ock input: pin MCLK					
T _{cy(MCLK)}	master clock cycle time		-	81.4	-	ns
t _{WL}	pulse width LOW		28	-	53	ns
t _{WH}	pulse width HIGH		28	-	53	ns
Digital int	terface (see Figure 5)					
Bit clock in	nput: pin BCLK					
T _{cy(BCLK)}	bit clock cycle time		20.83	-	-	μs
t _{WL}	pulse width LOW		7.29	-	-	μs

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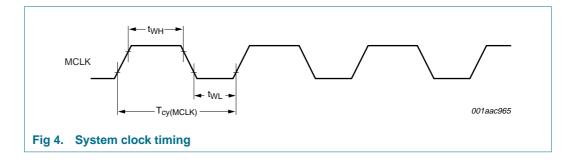
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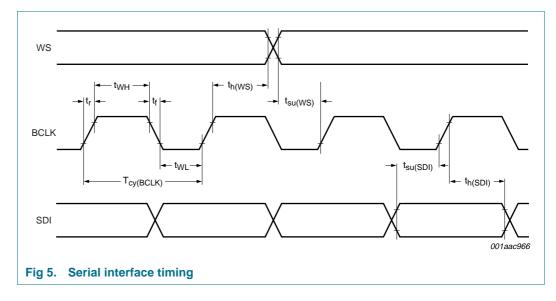
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Table 8: Timing characteristics ... continued

 $V_{DDA} = 12.0 V$; $V_{DDD} = 3.3 V$; $T_{amb} = 5 \circ C$ to $65 \circ C$; $f_s = 48 \text{ kHz}$; all voltages referenced to ground (pins V_{SSA} and V_{SSD}); unless otherwise specified.

• • •		A 1 1/1		-		
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
t _{WH}	pulse width HIGH		7.29	-	-	μs
t _r	rise time		-	-	3.12	μs
t _f	fall time		-	-	3.12	μs
Data inpu	t: pin SDI					
t _{su(SDI)}	data input set-up time		4.16	-	-	μs
t _{h(SDI)}	data input hold time		0	-	-	μs
Word sele	ect input: pin WS					
t _{su(WS)}	word select set-up time		4.16	-	-	μs
t _{h(WS)}	word select hold time		0	-	-	μs





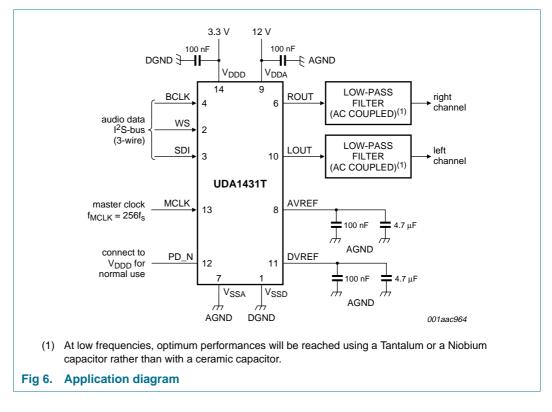


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13. Application information



14. Test information

14.1 Quality information

The General Quality Specification for Integrated Circuits, SNW-FQ-611 is applicable.

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15. Package outline

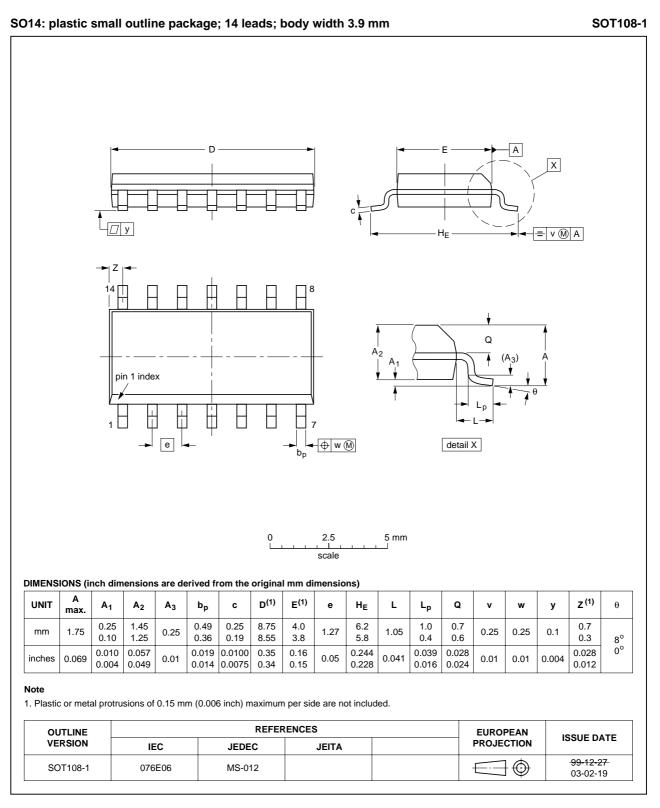


Fig 7. Package outline SOT108-1 (SO14)

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16. Handling information

Inputs and outputs are protected against electrostatic discharge in normal handling. However, to be completely safe you must take normal precautions appropriate to handling integrated circuits.

17. Soldering

17.1 Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *Data Handbook IC26; Integrated Circuit Packages* (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

17.2 Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement. Driven by legislation and environmental forces the worldwide use of lead-free solder pastes is increasing.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 seconds and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 °C to 270 °C depending on solder paste material. The top-surface temperature of the packages should preferably be kept:

- below 225 °C (SnPb process) or below 245 °C (Pb-free process)
 - for all BGA, HTSSON..T and SSOP..T packages
 - for packages with a thickness \geq 2.5 mm
 - for packages with a thickness < 2.5 mm and a volume ≥ 350 mm³ so called thick/large packages.
- below 240 °C (SnPb process) or below 260 °C (Pb-free process) for packages with a thickness < 2.5 mm and a volume < 350 mm³ so called small/thin packages.

Moisture sensitivity precautions, as indicated on packing, must be respected at all times.

17.3 Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

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- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
 - larger than or equal to 1.27 mm, the footprint longitudinal axis is preferred to be parallel to the transport direction of the printed-circuit board;
 - smaller than 1.27 mm, the footprint longitudinal axis **must** be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

• For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time of the leads in the wave ranges from 3 seconds to 4 seconds at 250 °C or 265 °C, depending on solder material applied, SnPb or Pb-free respectively.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

17.4 Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 $^{\circ}$ C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 seconds to 5 seconds between 270 $^{\circ}$ C and 320 $^{\circ}$ C.

17.5 Package related soldering information

Table 9: Suitability of surface mount IC packages for wave and reflow soldering methods

Package [1]	Soldering method				
	Wave	Reflow ^[2]			
BGA, HTSSONT 🕄, LBGA, LFBGA, SQFP, SSOPT 🕄, TFBGA, VFBGA, XSON	not suitable	suitable			
DHVQFN, HBCC, HBGA, HLQFP, HSO, HSOP, HSQFP, HSSON, HTQFP, HTSSOP, HVQFN, HVSON, SMS	not suitable 4	suitable			
PLCC 5, SO, SOJ	suitable	suitable			
LQFP, QFP, TQFP	not recommended [5] [6]	suitable			
SSOP, TSSOP, VSO, VSSOP	not recommended [7]	suitable			
CWQCCNL ^[8] , PMFP ^[9] , WQCCNL ^[8]	not suitable	not suitable			

 For more detailed information on the BGA packages refer to the (LF)BGA Application Note (AN01026); order a copy from your Philips Semiconductors sales office.

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- [2] All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods.
- [3] These transparent plastic packages are extremely sensitive to reflow soldering conditions and must on no account be processed through more than one soldering cycle or subjected to infrared reflow soldering with peak temperature exceeding 217 °C ± 10 °C measured in the atmosphere of the reflow oven. The package body peak temperature must be kept as low as possible.
- [4] These packages are not suitable for wave soldering. On versions with the heatsink on the bottom side, the solder cannot penetrate between the printed-circuit board and the heatsink. On versions with the heatsink on the top side, the solder might be deposited on the heatsink surface.
- [5] If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- [6] Wave soldering is suitable for LQFP, QFP and TQFP packages with a pitch (e) larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- [7] Wave soldering is suitable for SSOP, TSSOP, VSO and VSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.
- [8] Image sensor packages in principle should not be soldered. They are mounted in sockets or delivered pre-mounted on flex foil. However, the image sensor package can be mounted by the client on a flex foil by using a hot bar soldering process. The appropriate soldering profile can be provided on request.
- [9] Hot bar soldering or manual soldering is suitable for PMFP packages.

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18. Revision history

Document ID Release date Data sheet status Change notice Doc. number Supersedes UDA1431T_2 20060220 Product data sheet - - UDA1431T_1 Modifications: • Note added to Figure 6 • - - UDA1431T_1	Table 10: F	Revision history						
Modifications: • Note added to Figure 6	Document I	D Release date	Data sheet status	Change notice	Doc. number	Supersedes		
	UDA1431T_:	2 20060220	Product data sheet	-	-	UDA1431T_1		
In Table 8: 'MCLK active' moved to conditions column	Modifications: • Note added to Figure 6							
	 In <u>Table 8</u>; 'MCLK active' moved to conditions column 							
UDA1431T_1 20060206 Product data sheet - 9397 750 14957 -	UDA1431T_	1 20060206	Product data sheet	-	9397 750 14957	-		

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19. Data sheet status

Level	Data sheet status [1]	Product status [2] [3]	Definition
I	Objective data	Development	This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice.
II	Preliminary data	Qualification	This data sheet contains data from the preliminary specification. Supplementary data will be published at a later date. Philips Semiconductors reserves the right to change the specification without notice, in order to improve the design and supply the best possible product.
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[2] The product status of the device(s) described in this data sheet may have changed since this data sheet was published. The latest information is available on the Internet at URL http://www.semiconductors.philips.com.

[3] For data sheets describing multiple type numbers, the highest-level product status determines the data sheet status.

20. Definitions

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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