

#### **Features**

Differential Inputs and Outputs
Internal Bias, Reference and Hysteresis Sources
Low Output Impedance
Useful for Single-Wire Input/Output Applications
MOS Compatible Inputs
Power Supply Range of 11V to 16V

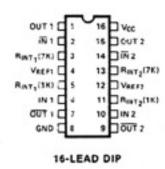
### Applications

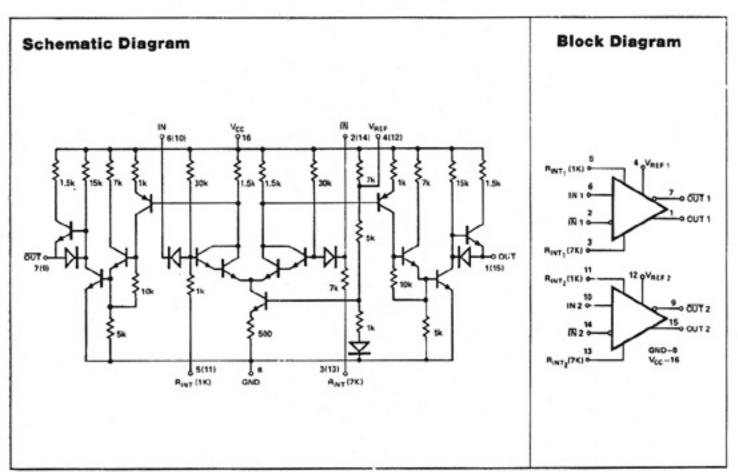
Differential Line Driver or Line Receiver Line Repeater Single-Ended Line Driver or Line Receiver Alternate to Motorola MC696

### **General Description**

The 396 dual differential line driver/receiver is designed for industrial logic applications requiring high immunity to electrical noise. The 396 has an extremely flexible hysteresis capability, allowing the user to adjust the switching threshold. Thus the 396 is also useful for single-wire input/output applications.

### **Connection Diagram**





# **Absolute Maximum Ratings**

| Continuous Supply Voltage                          | 16.5V<br>18V<br>-0.5 to +18V |  |  |
|--|------------------------------|--|--|
| Pulsed Supply Voltage (less than 100ms)            |                              |  |  |
| Input Voltage (any input)                          |                              |  |  |
| Storage Temperature                                | -65°C to +150°C              |  |  |
| Lead Temperature (1/16 inch from case 10 sec max.) | 300°C                        |  |  |

## **Recommended Operating Conditions**

(Normal operating range is 12 to 15 volts ±1 volt)

|            | Parameter                             | Min. | Typ. | Max. | Unit |
|------------|---------------------------------------|------|------|------|------|
| www.DataSh | Supply Voltage                        | 11   |      | 16   | ٧    |
|            | Operating Free-Air<br>Temperature, TA | -30  |      | 85   | °c   |

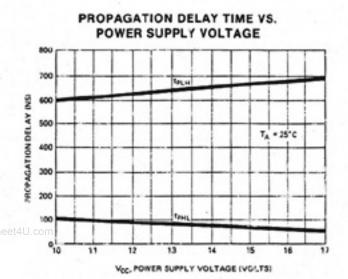
### **Electrical Characteristics**

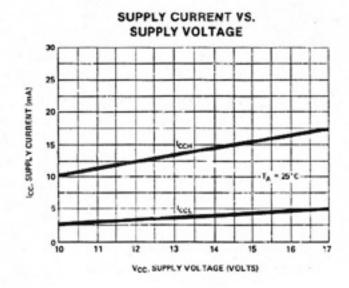
Over Recommended Operating Conditions Unless Otherwise Noted. (L and J package temperature range is -30 to +85°C)

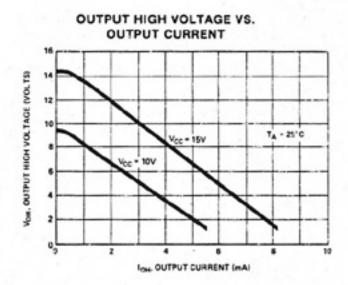
| Parameter                                       | Symbol      | Test Conditions  | Min. | Typ. | Max.     | Unit |
|---|-------------|--|------|------|----------|------|
| Output High Voltage                             | Vон         | IOH = -30µA, VIL = 4V<br>VCC = 11V                                       | 8.5  |      |          | v    |
|   |             | IOH = -30µA. VIL = €.5V<br>Voc = 16V                                     | 14.5 |      |          | v    |
| Output Low Voltage                              | VoL         | IOL = 12mA, V/L = 6.0V<br>VGC = 11V                                      |      |      | 1.5      | v    |
|   |             | IOL = 15mA; Vik = 8.5V<br>Vcc = 14V                                      |      |      | 1.5      | v    |
| Reference Voltage                               | VREF        | IREF = 0µA, Vcc = 12V  | 4.0  |      | 6.0      | V    |
|   |             | IREF = 0; A. VCC = 15V   | 6.5  |      | 8.5      | ٧    |
| Input High Current                              | lін         | VIH = 16V, VCC = 16V   |      |      | 10       | μА   |
| Input Low Current                               | lit.        | VIL = 0.4V, VCC = 11V  |      |      | -0.4     | mA   |
|   |             | VIL = 1.5V, VCC = 16V  |      |      | -1.0     | mA   |
| Output Leakage Current                          | ICEX        | VCEX = 16, VCC = 16V   |      |      | 25       | μΑ   |
| Output Short Circuit Current<br>High state only | Isc         | Vcc = 11V  | -3.9 |      | -10      | mA   |
|   |             | V <sub>CC</sub> = 16V  | -6.5 |      | -16      | mA   |
| Supply Current                                  | ICCL        | Vcc = 16V<br>All Inputs Grounded   |      |      | 12       | mA   |
| Supply Current                                  | Іссн        | Vcc = 16V Inverting<br>Inputs Tied to VREF                               |      |      | 25       | mA   |
| Common Mode Voltage Range                       |             |  | 1.5  |      | Vcc -1.5 | ٧    |
| Differential Voltage Range                      |             |  | ±12  |      |          | V    |
| Switching Characteristics                       | <b>TPHL</b> | T <sub>A</sub> = 25°C, R <sub>L</sub> ~ 1.5K,<br>C <sub>L</sub> = 100pf  |      | 80   |          | nsec |
|   | tpLH        | T <sub>A</sub> = 25° C, R <sub>L</sub> = 1.5K,<br>C <sub>L</sub> = 100pf |      | 650  |          | nsec |

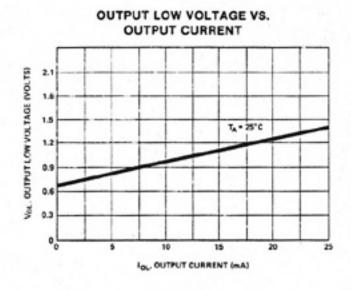
# Line Driver/Receiver 396

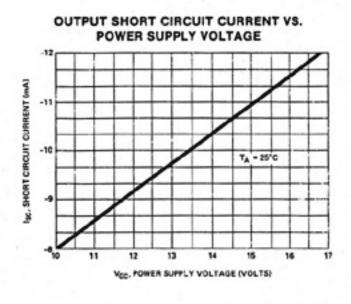
### **Typical Performance Curves**

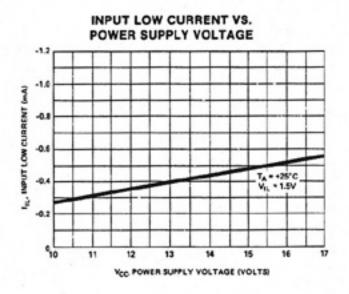






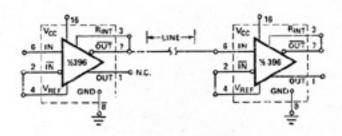




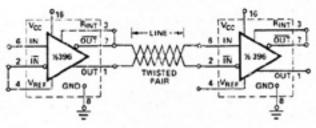


### **Applications Information**

#### CONNECTION DIAGRAMS



Single Ended



Differential

### Hysteresis Modes of the 396

The 396 has very flexible hysteresis capability, enabling the designer to adjust the switching thresholds (and thus the noise immunity) of the device to suit his needs. The hysteresis thresholds (V<sub>IL</sub>, V<sub>IH</sub>) and widths (V<sub>HW</sub>) for various feedback resistor values of the test circuit shown in Figure 1 are plotted in Figure 2. The power supply is set at 15V, so that with the inverting input tied to the internal reference voltage of the circuit (approximately 1/2 V<sub>CC</sub>), the high level and low level switching points of the device are centered about the 7.5 volt level.

Note that both switching points change symmetrically about that reference level until the feedback resistor is decreased below 5.5K ohm, giving a very wide range of widths. The variation of hysteresis width with changes in the power supply voltage is quite linear over the operating range as shown in Figure 3; the internal 7.0K resistor is used in that test for the hysteresis feedback.

The hysteresis center point level  $(V_L)$  can be changed by varying the reference voltage level as shown in Figure 4, giving complete control over the setting of the hysteresis levels. The only limitation is that the levels must remain within the common-mode range (CMR) of the device (1.5V above ground to 1.5V less than  $V_{CC}$ ).

The hysteresis widths for the test circuit shown in Figure 4 are plotted in Figure 4A.

# Line Driver/Receiver 396

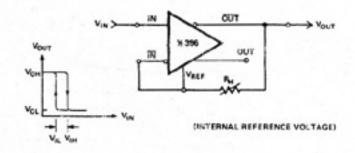


Figure 1. Variable Hysteresis Width Circuit

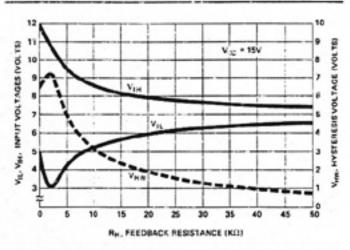


Figure 2. Typical Hysteresis Voltage (V<sub>IL</sub>, V<sub>IH</sub>) vs. Feedback Resistance (R<sub>H</sub>)

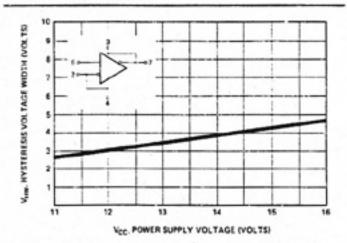


Figure 3. Hysteresis Width vs. Power Supply Voltage (Using Internal 7.0kΩ Resistor)

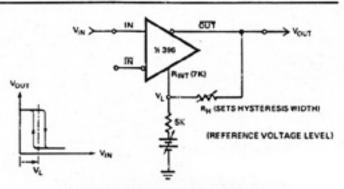


Figure 4. Hysteresis Level Variable

## **Applications Information**

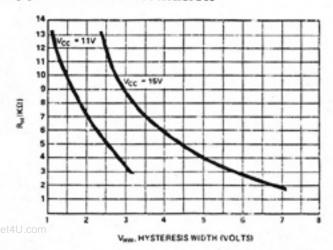
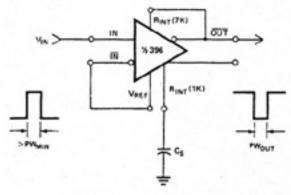


Figure 4A. Feedback Resistances vs. Hysteresis Widths

#### 396 Slow-Down Receiver

The 396 can be used as a single-ended slow-down receiver as shown in Figure 5. By connecting a capacitor to the internal 1.0K resistor, the device can be made insensitive to pulses with widths shorter than a predetermined value. The graph in Figure 6 shows the minimum input signal pulse width necessary to trigger the circuit versus capacitance.



NOTE: PWOUT < PWIN - DELAY TIME DUE TOCS

Figure 5. 396 as Single-Ended Slow-Down Receiver

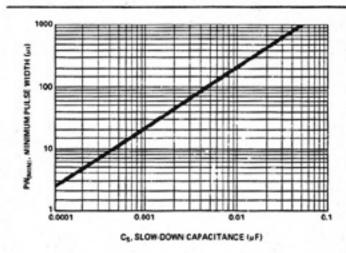


Figure 6. Minimum Pulse Width vs. Slow-Down Capacitance

# Line Driver/Receiver 396

### 396 as Line Driver/Receiver/Repeater

One of the best applications of the 396 is, of course, as a line driver/receiver/repeater, and because of its low frequency operation, (<500 kHz), many of the complicated effects associated with line driving and receiving can be ignored and calculations become straight-forward.

In Figure 7, one device is used as a twisted-pair line driver and another as a line receiver. The balanced series resistance, Rs, adds some series damping and limits the current through the line at high power supply levels while setting the voltage levels at the input of the receiver for maximum common-mode noise rejection (i.e., bias the input differential voltage in the middle of the common-mode range). Ro merely terminates the line in its characteristics impedance (~ 100 ohm for 30 turns/ft, AWG24-2B; twisted pair) so that capacitive effects on the line may effectively be ignored.

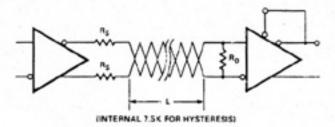


Figure 7. Using 396 as Differential Line Driver/Receiver

The worst-case limits of the series resistor can be calculated roughly by looking at the dc equivalent circuit shown in Figure 8. The three major constraints are:

- V<sub>diff</sub> < V<sub>diff</sub> min. ≈ 50mV (For safety margin use V<sub>diff</sub> = 150mV)
- 2. IL < Isc max.
- Receiver input common-mode voltage centered in common-mode range (1.5V < CMR < Vcc — 1.5V)</li>

For V<sub>CC</sub> = 15V, these constraints require R<sub>S</sub> to be about 5.0K.

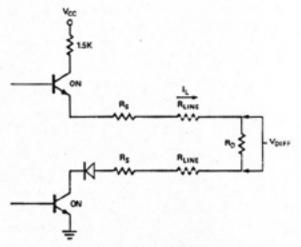


Figure 8. DC Equivalent Circuit

# Line Driver/Receiver 396

### **Applications Information**

If necessary, hysteresis can be added to the receiver to improve switching characteristics, and for upgrading the signal along extremely long lines, the 396 can be used in a repeater configuration as shown in Figure 9.

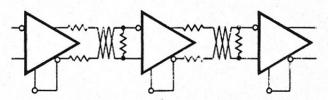


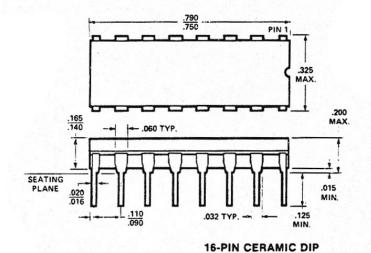
Figure 9. Using 396 as Line Repeaters

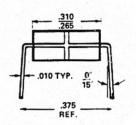
# **Ordering Information**

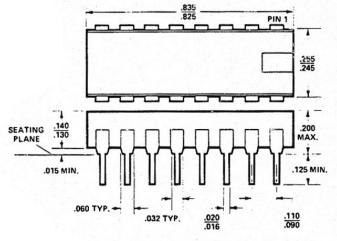
Order Part Numbers:

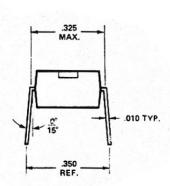
- L Package 16-Pin Ceramic DIP (-30°C ≥ T<sub>A</sub> ≤ 85°C) 396AL/CL
- J Package 16-Pin Plastic DIP (-30°C ≥ T<sub>A</sub> ≤ 85°C) 396AJ/CJ

# **Physical Dimensions**









16-LEAD PLASTIC DIP