Toshiba Bi-CD Integrated Circuit Silicon Monolithic

TB6552FN,TB6552FL

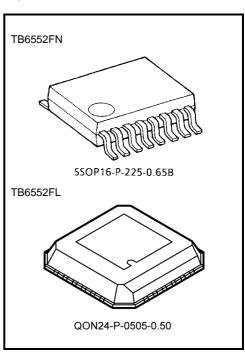
Dual-Bridge Driver IC for DC motor

TB6552FN/FL is a dual-bridge driver IC for DC motor with output transistor in LD MOS structure with low ON-resistor. Two input signals, IN1 and IN2, can chose one of four modes such as CW, CCW, short brake, and stop mode. Efficient driven at high temperature is possible by PWM drive system.

Features

- Power supply voltage for motor: VM ≤ 15 V (max)
- Power supply voltage for control: $V_{CC} = 2.7 \text{ V to } 6.0 \text{ V}$
- Output current: 1 A (max)
- Low ON resistor: 1.5 Ω (typ.) (Upper side + Lower side combined @VM = 5 V)
- Direct PWM control
- Standby system (Power save)
- CW/CCW/short brake/stop function modes.
- Built-in thermal shutdown circuit
- Package: SSOP16 for TB6552FN /QON24 for TB6552FL

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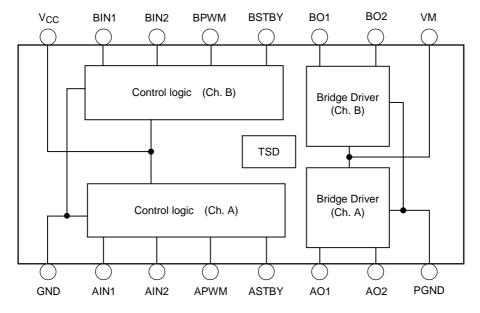
Weight

SSOP16-P-225-0.65B : 0.07 g (typ.) QON24-P-0505-0.50 : 0.05 g (typ.) DataShe

* This product has a MOS structure and is sensitive to electrostatic discharge. When handling this product, ensure that the environment is protected against electrostatic discharge by using an earth strap, a conductive mat and an ionizer. Ensure also that the ambient temperature and relative humidity are maintained at reasonable levels.

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Block Diagram



Pin Functions

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Pin.Name	Pin No		Eurotional Description	Demerica			
Pin.iname	FN FL		Functional Description	Remarks			
GND	1	21	Small-signal GND pin	GND for small-signal power supply (V_{CC})			
AIN1	2	18	Control signal input 1 (Ch. A)				
AIN2	3	17	Control signal input 2 (Ch. A)				
APWM	4	16	PWM control signal input pin (Ch. A)	Input PWM signal			
ASTBY	5	15	Standby control input pin (Ch. A)	Ch. A circuit is in standby (power save) state while this signal is Low.			
AO1	7	13	Output pin 1 (Ch. A)	Ch. A connect to motor coil pin			
AO2	8	11	Output pin 2 (Ch. A)	Ch. A connect to motor coil pin			
PGND	9	10	GND pin for motor	GND for motor power supply (VM)			
VM	6	14	Motor power supply pin	VM (ope) = 2.5 V to 13.5 V			
BO2	10	8	Output pin 2 (Ch. B)	Ch. B connect to motor coil pin			
BO1	11	5	Output pin 1 (Ch. B)	Ch. B connect to motor coil pin			
BSTBY	12	4	Standby control input pin (Ch. B)	Ch. B circuit is in standby (power save) state while this signal is Low.			
BPWM	13	3	PWM control signal input pin (Ch. B)	Input PWM signal			
BIN2	14	2	Control signal input 2 (Ch. B)				
BIN1	15	1	Control signal input 1 (Ch. B)				
V _{CC}	16	22	Small-signal power supply pin	V _{CC (ope)} = 2.7 V to 5.5 V			

Note: Pins 6, 7, 9, 12, 19, 20, 23 and 24 on the FL are NC (not connected) pins.

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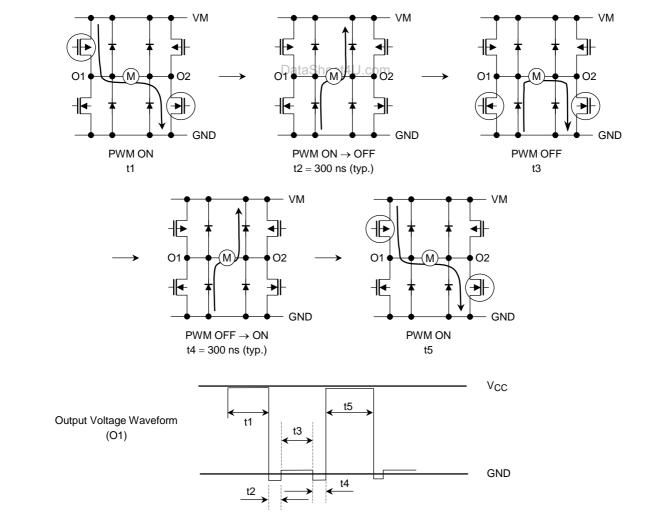
Input/Output Function (common for channel A and B)

Input			Output													
IN1	IN2	STBY	PWM	O1 O2		Mode										
н	н	Н	H	L	L	Short brake										
	ь н н	ц	H	L	Н	CW/CCW										
L										11		L	L	L	Short brake	
н	H L	н	н	н	н	н	н	н	н	н	Н	н	Н	Н	L	CCW/CW
		L	L	L	Short brake											
		L H				FF	Stop									
	L		L (high impedance)		360											
H/I	H/L H/L		Н		FF	Standby										
11/		L	L	(high impedance)		Stanuby										

Operating Description

• PWM control function

Speed can be controlled by inputting the high-level or low-level PWM signal to the pin PWM. When PWM control is provided, normal operation and short brake operation are repeated. To prevent penetrating current, dead time t2 and t4 is provided in the IC.



Note: Please set the pin PWM to High when PWM control functionn is not used.

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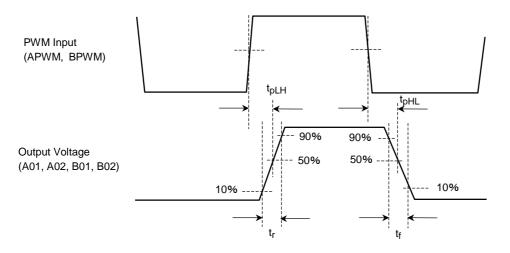
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• Switching characteristics of output transistors

The switching characteristics between PWM input and the output transistors are shown below.



<Typical Value>

Item	Typical Value	Unit	
t _{pLH}	1000		
t _{pHL}	1000	ns	
t _r	100	115	
t _f	100		

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• Input pin

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Input pins (AIN1, AIN2, APWM, ASTBY, BIN1, BIN2, BPWM and BSTBY) have internal pull-down resistors that are connected to ground.

Maximum Ratings (Ta = 25°C)

Characteristics	Symbol	Rating	Unit	Remarks
Supply voltage	VM	15	V	
Supply voltage	V _{CC}	6	v	
Input voltage	V _{IN}	-0.2 to 6	V	IN1, 2, STBY and PWM pins
Output current	IOUT	1	А	
Power dissipation	PD	0.78	W	
	. D	(Note 1)		
Operating temperature	T _{opr}	-20 to 85	°C	
Storage temperature	T _{stg}	-55 to 150	°C	

Note 1: This value is obtained by $50 \times 30 \times 1.6$ mm glass-epoxy PCB mounting occupied 40% of copper area.

Operating Range (Ta = -20 to 85° C)

Characteristics	Symbol	Min	Тур.	Max	Unit
Supply voltage (V _{CC})	V _{CC}	2.7	3.0	5.5	V
Supply voltage (VM)	VM	2.5	5.0	13.5	V
Output current	lout	_	_	0.8	А
PWM frequency	fPWM			100	kHz

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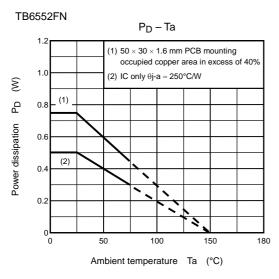
Electrical Characteristics (unless otherwise specified, $V_{CC} = 3 V$, VM = 12 V, $Ta = 25^{\circ}C$)

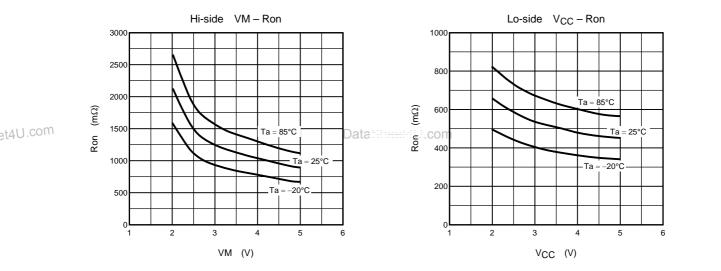
Characteristics		Symbol	Test Circuit	Test Condition	Min	Тур.	Max	Unit
Supply current		I _{CC (STP)}	_	Stop mode	_	0.9	1.2	
		I _{CC (W)}	_	CW/CCW mode		0.9	1.2	mA
		I _{CC (SB)}	_	Short break mode	_	0.9	1.2	
		I _{CC (STB)}	_	(Oten allow as a da)			10	μA
		I _{M (STB)}	_	(Standby mode)			1	
	Input voltage	V _{INH}	_		2	_	V _{CC} + 0.2	
		V _{INL}	_		-0.2	—	0.8	V
Control circuit	Hysteresis voltage	V _{IN (HIS)}	_	(Not tested)	_	0.2	_	
	Input current	I _{INH}	_		5	15	25	μA
	input current	I _{INL}	_		_	—	1	
	Input voltage	VINSH			2		V _{CC} + 0.2	V
Standby circuit		VINSL	_		-0.2	_	0.8	
	Input current	IINSH	_		5	10	20	μA
		I _{INSL}	_			_	1	
Output saturating	Output saturating voltage			I ₀ = 0.2 A		0.3	0.4	V
Output saturating	voltage	V _{sat (U + L)}		I ₀ = 0.8 A		1.2	1.5	v
Output leakage cu	irrent	I _{L (U)}		VM = 15 V		_	1	μΑ
Output leakage et	anent	I _{L (L)}				_	1	
Diode forward vol	tana	V _{F (U)} D	ataShe	f ^t d 0.8 A ^m		1	1.2	V
Didde forward vor	lage	V _{F (L)}		I ₀ = 0.8 A		1	1.2	v
PWM control	PWM frequency	fpwm				_	100	kHz
circuit	Minimum clock pulse width	t _{w (PWM)}			_	—	10	μs
Output transistor switching		Tr				100	_	
		Tf		Not tested		100	_	ns
		t _{pLH} (PWM)]			1000	_	
		t _{pHL} (PWM)				1000		
Thermal shutdown circuit operating temperature		T _{SD}		(Not tested)	_	170	_	°C
Thermal shutdown hysteriesis		ΔT_{SD}		(Not tested)		20		°C

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Characteristic Wave Form

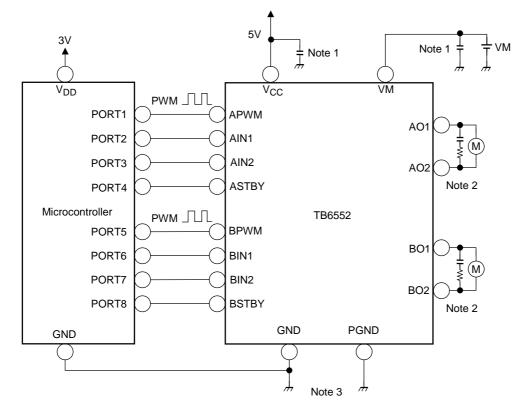




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Typical Application Diagram



Note 1: The power supply capacitor should be connected as close as possible to the IC.

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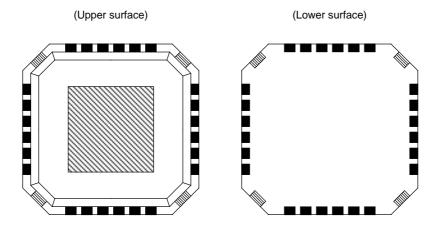
 Note 2: When connecting the motor pins through the capacitor for reducing noise, connect a resistor to the capacitor for limiting the charge current.
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- Note 3: Avoid using common impedance for GND and PGND.

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Requests Concerning Use of QON

Outline Drawing of Package



When using QON, please take into account the following items.

Caution

- (1)Do not carry out soldering on the island section in the four corners of the package (the section shown on the lower surface drawing with diagonal lines) with the aim of increasing mechanical strength.
- (2)The island section exposed on the package surface (the section shown on the upper surface drawing with diagonal lines) must be used as (Note 6) below while electrically insulated from outside.
 - Note 6: Ensure that the island section (the section shown on the lower surface drawing with diagonal lines) does not come into contact with solder from through-holes on the board layout.
 - DataSheet4U.com When mounting or soldering, take care to ensure that neither static electricity nor electrical overstress is applied to the IC (measures to prevent anti-static, leaks, etc.).
 - When incorporating into a set, adopt a set design that does not apply voltage directly to the island section.

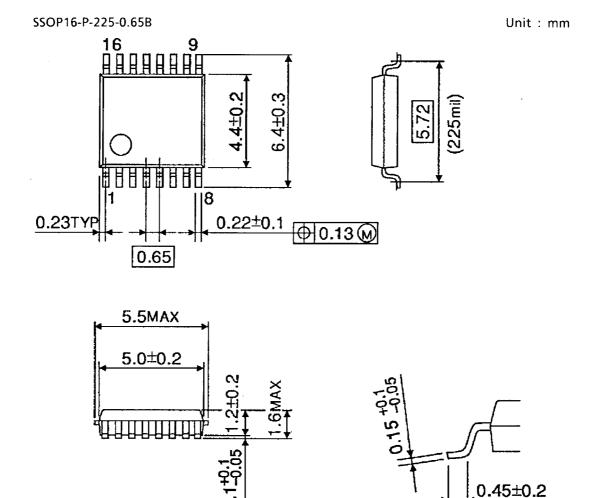
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TB6552FN/FL

Package Dimensions



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Weight: 0.07 g (typ.)

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Package Dimensions

QON24-P-0505-0.50

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0.8±0.05 0.9MAX $0.145^{+0.055}_{-0.045}$ ∠70.05 0.3±0.1 4 F <u>a ka ka ka k</u> 0.3 0.25 (0.3) 0,5 Note 1) The solder plating portion in four corners of the package shall not be treated as an external terminal. Note 2) Don't carry out soldering to four corners of the package.

4.91±0.04 4.7±0.1

13

6

12

0.2^{+0.05} 0.2^{-0.04} 0.05

4.91±0.04 4.7±0.1

18

19

24

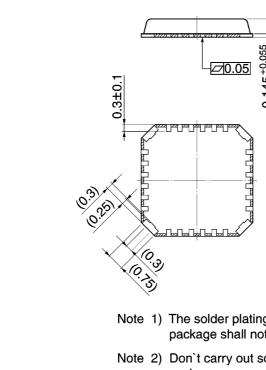
0.5

.1 TYP.

4-C0.61

Note 3) area : Resin surface

Weight: 0.05 g (typ.)



Unit: mm

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