

SY26024 21µA Ultra-Low I_Q, 2.2MHz

Synchronous Step-Down Regulator

General Description

The SY26024 is a high-efficiency 2.2MHz synchronous step-down DC/DC regulator capable of delivering up to 4A output current. It operates over an input voltage range of 2.5V to 5.5V, and integrates very low $R_{DS (ON)}$ main and synchronous switches to minimize conduction loss.

The SY26024 is available in a space-saving, low-profile DFN1.5mm×1.5mm-6 package.

Applications

- Portable Electronics
- Industrial PC
- Smart Phone

Features

- 2.5V to 5.5V Input Voltage Range
- Fast Load-Transient Response
- Low R_{DS(ON)} for Internal Switches: 38mΩ Top, 30mΩ Bottom
- 2.2MHz Switching Frequency
- ±1% Output Voltage Accuracy (Full Temperature Range)
- PFM Mode for Light-Load Efficiency
- 21µA Operating Quiescent Current
- Internal Soft-Start Limits Inrush Current
- 100% Duty Cycle Enables Dropout
 Operation
- Output Auto-Discharge Function
- Power-Good Indicator
- Autorecovery for Short-Circuit, Overvoltage, and Overtemperature Protection
- RoHS-Compliant and Halogen-Free
- Compact Package: DFN1.5mm×1.5mm-6

Typical Applications



Figure 1. Schematic Diagram

Table 1. Inductor and COUT Selection

			C ουτ (μ F)		
Vout (V)	L(µH)	10	22	44	
1.2	0.33		*	\checkmark	
1.2	0.47		\checkmark	\checkmark	
1.0	0.33		*	\checkmark	
1.8	0.47		\checkmark	\checkmark	
0.5	0.47		*	\checkmark	
2.5	0.68		\checkmark	\checkmark	

Note: '*' indicates recommended for most applications.



Figure 2. Efficiency vs. Output Current



Ordering Information

Package type	Top Mark
DFN1.5×1.5-6	
RoHS-Compliant and Halogen-Free	f9 <i>xyz</i>
	DFN1.5×1.5-6 RoHS-Compliant and

x = year code, y = week code, z = lot number code

Pinout (top view)



Pin Description

Pin Name	Pin Number	Pin Description
EN	1	Enable control. Pull high to turn on. Do not leave floating.
PG	2	Power-good indicator. Power good indicator (open drain output). Low if the V_{FB} < 92% or the V_{FB} > 109% of V_{REF} , high otherwise. Connect a pullup resistor to the desired voltage level.
FB	3	Output feedback pin. Connect this pin to the center point of the output resistor divider (as shown in Figure 1) to program the output voltage: $V_{OUT} = 0.6 \times (1 + R_H/R_L)$.
GND	4	Power return path ground pin.
LX	5	Inductor pin. Connect this pin to the switching node of the inductor.
IN	6	Input pin. Decouple this pin to the GND pin with at least a $4.7\mu F$ ceramic capacitor.





Figure 3. Block Diagram

Absolute Maximum Ratings

Parameter (Note 1)	Min	Мах	Unit
IN	-0.3	6	
FB, EN, PG	-0.3	V _{IN} + 0.6	V
LX (tested down to -3V <20ns and up to +7V <20ns)	-0.3	6	
Junction Temperature, Operating	-40	150	
Lead Temperature (Soldering, 10s)		260	°C
Storage Temperature	-65	150	

Thermal Information

Parameter (Note 2)	Тур	Unit
θ _{JA} Junction-to-Ambient Thermal Resistance	62	°C/W
θ_{JC} Junction-to-Case Thermal Resistance	8	- C/vv
P_D Power Dissipation $T_A = 25^{\circ}C$	1.6	W

Recommended Operating Conditions

Parameter (Note 3)	Min	Max	Unit
Supply Input Voltage	2.5	5.5	V
Junction Temperature	-40	125	°C
Ambient Temperature	-40	85	C



Electrical Characteristics

 $(T_J = -40^{\circ}C - 125^{\circ}C)$, and $V_{IN} = 2.5V$ to 5.5V. Typical values are at $T_J = 25^{\circ}C$ and $V_{IN} = 5V$, unless otherwise specified.)

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Input Voltage Range	VIN		2.5		5.5	V
Input UVLO Threshold	Vuvlo	V _{IN} falling	2.1	2.2	2.3	V
Input UVLO Hysteresis	VHYS			160		mV
Quiescent Current	la	V _{FB} = 105% × V _{REF}		21		μA
Shutdown Current	I _{SHDN}	$V_{EN} = 0V, T_A = 25^{\circ}C$		0.05	0.5	μA
Feedback Reference Voltage	VREF	Iout = 1A, CCM	0.594	0.6	0.606	V
Output Voltage Load Regulation (Note 4)	ΔV_{LDR}	Iout = 0.5A to 4A, Vout = 1.8V		0.1		%/A
Output Discharge FET RON	RDIS	$V_{EN} = 0V$		8		Ω
Top FET R _{ON}	R _{DS(ON)1}			38		mΩ
Bottom FET R _{ON}	R _{DS(ON)2}			30		mΩ
EN Input Voltage High	Ven, h		1.0			V
EN Input Voltage Low	Ven, l				0.4	V
EN Leakage Current	IEN, LKG	EN = high		0.01		μA
		V _{FB} falling, PG from high to low		92		%
Power-Good Threshold	V	V _{FB} rising, PG from low to high		95.5		%
Power-Good Threshold	V _{PG}	VFB rising, PG from high to low		109		%
		V _{FB} falling, PG from low to high		105		%
Dower Cood Delay	t _{PG,R}	PG from low to high		100		μs
Power-Good Delay	t _{PG,F}	PG from high to low		20		μs
Power-Good Output Low	Vpg, l	I _{PG} = 1mA			0.4	V
Power-Good Leakage Current	IPG, LKG	$V_{PG} = 5V$		0.01		μA
Min ON Time (Note 4)	ton,min			50		ns
Maximum Duty Cycle (Note 4)	DMAX		100			%
Soft-Start Time	tss	From EN high to 95% of V_{OUT} nominal, $T_A = 25^{\circ}C$		1.75		ms
Switching Frequency	f _{S₩}	I _{OUT} = 1A, V _{OUT} = 1.8V		2.2		MHz
Top FET Current Limit	I _{LMT, TOP}		5			Α
Bottom FET Current Limit	I _{LMT, BOT}		4			А
Thermal Shutdown Temperature (Note 4)	Tsd			150		°C
Thermal Shutdown Hysteresis (Note 4)	T _{HYS}			20		°C

Note 1: Stresses beyond the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Note 2: Package thermal resistance is measured in the natural convection at TA = 25°C on a 6cm×6cm size 2-oz two-layer Silergy Evaluation Board.

Note 3: The device is not guaranteed to function outside its operating condition.

Note 4: Guaranteed by design.



Typical Performance Characteristics

 $(T_A = 25^{\circ}C, V_{IN} = 5V, L = 0.33 \mu H, C_{OUT} = 2 \times 10 \mu F$, unless otherwise specified.)





Time (4ms/div)



SY26024





Time (4ms/div)





Time (1µs/div)

Time (1µs/



SY26024



Time (100µs/div)



Time (100µs/div)



The SY26024 is a high-efficiency 2.2MHz synchronous step-down DC/DC regulator capable of delivering up to 4A output current. It operates over an input voltage range of 2.5V to 5.5V, and integrates very low $R_{DS\ (ON)}$ main and synchronous switches to minimize conduction loss.

The SY26024 uses instant-PWM architecture to achieve fast transient responses for step-down applications and high efficiency at light loads.

The SY26024 provides cycle-by-cycle current limiting and thermal shutdown protections.

The 2.2MHz switching frequency allows low-output voltage ripple and small external inductor and capacitor sizes.

Application Information

The following sections describe the selection process for the input capacitor C_{IN} , output capacitor C_{OUT} , output inductor L, and feedback resistors (R_H and R_L) for meeting the targeted application specifications.

Feedback Resistor Dividers $R_{\rm H}$ and $R_{\rm L}$

Choose R_H and R_L to program the proper output voltage. To minimize power consumption under light loads, choose large resistance values between $10k\Omega$ and $1M\Omega$ for both R_H and R_L . For $V_{OUT} = 1.8V$ and $R_H = 100k\Omega$, the calculated R_L value is $49.9k\Omega$, as shown in the following equation:



Input Capacitor C_{IN}

The ripple current through the input capacitor can be estimated using the following formula:

$$I_{CIN_RMS} = I_{OUT} \times \sqrt{D(1-D)}$$

For normal operation, a typical X5R or better grade ceramic capacitor with 6.3V rating should be placed close to the IN and GND pins. Care should be taken to minimize the loop area formed by C_{IN} and the IN/GND pins. A 4.7 μ F low-ESR ceramic capacitor is recommended for most applications.

Output Capacitor COUT

Select the output capacitor to handle the output ripple requirements, considering both steady-state ripple and transient requirements. For the best performance, it is recommended to use X5R or better grade ceramic capacitors with 6.3V rating and more than $2\times10\mu$ F capacitance.

Output Inductor L

Consider the following when choosing this inductor:

1) Choose the inductance to provide a ripple current that is approximately 40% of the maximum output current. The inductance is calculated as follows:

$$L = \frac{V_{OUT} (1 - V_{OUT} / V_{IN,MAX})}{f_{SW} \times I_{OUT,MAX} \times 40\%}$$

where f_{SW} is the switching frequency and $I_{\text{OUT,MAX}}$ is the maximum load current.

The SY26024 is tolerant of different ripple current amplitude. Consequently, the final choice of inductance can be slightly off the calculation value without significantly impacting the performance.

2) The inductor's saturation current rating must be greater than the peak inductor current under full load:

Isat, min > Iout, max + $\frac{V_{OUT}(1-V_{OUT}/V_{IN,MAX})}{2 \times f_{SW} \times L}$

3) The DCR of the inductor and the core loss at the switching frequency must be low enough to achieve the desired efficiency requirement. Choose an inductor with DCR less than $25m\Omega$ to achieve good overall efficiency.

Inductor vs. Output Capacitor

The ripple base control strategy needs very little C_{OUT} for stable operation. An inductor that is too large and C_{OUT} capacitance can lead to unstable operation. The



recommended inductance and output capacitance are shown in the table below.

Table 2. Inductance vs. Output CapacitanceSelection Table (Note 5)

L	Соит (µF)					
(µH)	22	44	88	120	180	220
0.33	Note 6	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
0.47	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
0.68	\checkmark	\checkmark	\checkmark	\checkmark	×	×

Note 5: Tested with 120pF feed-forward capacitor.

Note 6: Only suitable for $V_{OUT} < 2.0V$ application.

Minimum Duty Cycle and Maximum Duty Cycle

In the COT architecture, there is no limitation for low duty cycles, since even at very low duty cycles, the switching frequency can be reduced as needed as long as the on-time is close to the minimum, to ensure proper operation.

The device will enter 100% dropout mode if the output voltage is very close to the input voltage, In this mode of operation the top FET is constantly turned on, and the bottom FET is turned off.

Power-Good Indicator

The power-good indicator is an open-drain output controlled by a window comparator connected to the feedback signal. If V_{FB} is greater than V_{PG, R} and less than V_{OVP} for at least the power-good delay time (low to high), PG will be high-impedance. Otherwise, it is pulled low. PG should be connected to V_{IN} or another voltage source through a resistor (e.g., $10k\Omega$ – $100k\Omega$).

Load-Transient Considerations

The SY26024 integrates the compensation components to achieve good stability and fast transient responses. Adding a small feed-forward ceramic capacitor with more than 120pF capacitance in parallel with R_H helps improve the load-transient response and is therefore highly recommended.



Overcurrent and Undervoltage Protection

The SY26024 uses cycle-by-cycle current limiting for both the high-side and low-side MOSFETs. If the highside power FET current exceeds the peak current-limit threshold, the high-side power FET will turn off and the low-side power FET will turn on. If the low-side FET current exceeds the valley current-limit threshold, the low-side FET will stay on until the current decreases below the valley current-limit threshold. If the load current continues to increase in these conditions, the output voltage will drop. When the output voltage falls below 33% of the regulation level, the undervoltage protection (UVP) will be triggered, and the IC will start operating in hiccup mode. The hiccup on-time and hiccup off time ratio is 1:1. If the hard short is removed, the IC will return to normal operation.





Layout Design

To achieve optimal design, follow these PCB layout considerations:

- For maximum efficiency and stable operation, the following components should be placed close to the device: C_{IN}, L, R_H, R_L, and C_{FF}.
- Maximize the PCB copper area connecting to the GND pin to achieve the best thermal and noise performance. Using a ground plane is highly recommended. Place an adequate number of vias on the GND copper to improve heat distribution.
- Place C_{IN} close to IN and GND pins. Minimize the loop area formed by C_{IN} and GND.

- Minimize the PCB copper area associated with the LX pin.
- The components R_H and R_L, and the trace connecting to the FB pin must not be adjacent to the LX net on the PCB layout to avoid noise coupling.
- The feedback sampling point should be connected at the C_{OUT} terminal rather than the inductor output terminal.
- If the system chip interfacing with the EN pin has a high impedance state during shutdown mode, and the IN pin is connected directly to a power source such as a Li-ion battery, add a $1M\Omega$ pulldown resistor between the EN and GND pins to prevent noise from falsely turning on while the regulator is in shutdown mode.



Figure 4. PCB Layout Suggestion







Note: All dimensions are in millimeters and exclude mold flash and metal burr.



Taping and Reel Specification

DFN1.5×1.5 taping orientation



Feeding direction

Carrier tape and reel specification for packages



Package types	Tape width (mm)	Pocket pitch(mm)	Reel size (Inch)	Trailer length(mm)	Leader length (mm)	Qty per reel
DFN1.5×1.5	8	4	7"	400	160	3000

Others: NA



Revision History

The revision history provided is for informational purposes only and is believed to be accurate, however, not warrantied. Please make sure that you have the latest revision.

Date	Revision	Change
Dec.14, 2022	Revision 1.0	Language improvements for clarity.
Nov.17, 2022	Revision 0.9A	Update the Package outline (page 11)
Dec.14, 2021	Revision 0.9	Initial Release



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