STM32U5Axxx

Ultra-low-power Arm® Cortex®-M33 32-bit MCU+TrustZone®+FPU, 240 DMIPS, 4 MB Flash, 2.5 MB SRAM, LTDC, MIPI®DSI, crypto

Datasheet - production data

Features

Includes ST state-of-the-art patented technology

Ultra-low-power with FlexPowerControl

- 1.71 V to 3.6 V power supply
- - 40 °C to + 85/125 °C temperature range
- Low-power background autonomous mode (LPBAM): autonomous peripherals with DMA, functional down to Stop 2 mode
- V_{BAT} mode: supply for RTC, 32 x 32-bit backup registers and 2-Kbyte backup SRAM
- 150 nA Shutdown mode (24 wake-up pins)
- 195 nA Standby mode (24 wake-up pins)
- 480 nA Standby mode with RTC
- 2 µA Stop 3 mode with 40-Kbyte SRAM
- 8.2 µA Stop 3 mode with 2.5-Mbyte SRAM
- 4.65 µA Stop 2 mode with 40-Kbyte SRAM
- 17.5 µA Stop 2 mode with 2.5-Mbyte SRAM
- 18.5 µA/MHz Run mode at 3.3 V

Core

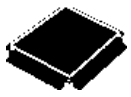
- Arm® 32-bit Cortex®-M33 CPU with TrustZone®, MPU, DSP, and FPU

ART Accelerator

- 32-Kbyte ICACHE allowing 0-wait-state execution from flash and external memories: frequency up to 160 MHz, 240 DMIPS
- 16-Kbyte DCACHE1 for external memories

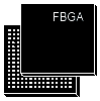
Power management

- Embedded regulator (LDO) and SMPS step-down converter supporting switch on-the-fly and voltage scaling



LQFP64 (10 x 10 mm)
LQFP100 (14 x 14 mm)
LQFP144 (20 x 20 mm)

WLCSP150
(5.38 x 5.47 mm)
WLCSP208
(5.38 x 5.47 mm)



UFBGA132 (7 x 7 mm)
TFBGA169 (7 x 7 mm)
TFBGA216 (13 x 13 mm)

Benchmarks

- 1.5 DMIPS/MHz (Dhrystone 2.1)
- 655 CoreMark® (4.09 CoreMark®/MHz)
- 369 ULPMark™-CP
- 89 ULPMark™-PP
- 47.2 ULPMark™-CM
- 120000 SecureMark™-TLS

Memories

- 4-Mbyte flash memory with ECC, 2 banks read-while-write, including 512 Kbytes with 100 kcycles
- With SRAM3 ECC off: 2514-Kbyte RAM including 66 Kbytes with ECC
- With SRAM3 ECC on: 2450-Kbyte RAM including 322 Kbytes with ECC
- External memory interface supporting SRAM, PSRAM, NOR, NAND, and FRAM memories
- 2 Octo-SPI memory interfaces
- 16-bit HSPI memory interface up to 160 MHz

Rich graphic features

- Neo-Chrom GPU (GPU2D) accelerating any angle rotation, scaling, and perspective correct texture mapping
- 16-Kbyte DCACHE2
- Chrom-ART Accelerator (DMA2D) for smooth motion and transparency effects

Product label

This is information on a product in full production. www.st.com

- Chrom-GRC (GFXMMU) allowing up to 20 % of graphic resources optimization
- MIPI® DSI host controller with two DSI lanes running at up to 500 Mbit/s each
- LCD-TFT controller (LTDC)
- Digital camera interface

General-purpose input/outputs

- Up to 156 fast I/Os with interrupt capability most 5V-tolerant and up to 14 I/Os with independent supply down to 1.08 V

Clock management

- 4 to 50 MHz crystal oscillator
- 32 kHz crystal oscillator for RTC (LSE)
- Internal 16 MHz factory-trimmed RC (± 1 %)
- Internal low-power 32 kHz RC (± 5 %)
- 2 internal multispeed 100 kHz to 48 MHz oscillators, including one autotrimmed by LSE (better than ±0.25 % accuracy)
- Internal 48 MHz
- 5 PLLs for system clock, USB, audio, ADC, DSI

Security and cryptography

- SESIP3 and PSA Level 3 Certified Assurance Target
- Arm® TrustZone® and securable I/Os, memories, and peripherals
- Flexible life cycle scheme with RDP and password-protected debug
- Root of trust thanks to unique boot entry and secure hide-protection area (HDP)
- Secure firmware installation (SFI) thanks to embedded root secure services (RSS)
- Secure data storage with hardware unique key (HUK)
- Secure firmware upgrade support with TF-M
- 2 AES coprocessors including one with DPA resistance
- Public key accelerator, DPA resistant
- On-the-fly decryption of Octo-SPI external memories
- HASH hardware accelerator
- True random number generator, NIST SP800-90B compliant
- 96-bit unique ID
- 512-byte OTP (one-time programmable)
- Active tampers

Up to 17 timers, 2 watchdogs and RTC

- 19 timers: 2 16-bit advanced motor-control, 4 32-bit, 3 16-bit general purpose, 2 16-bit basic, 4 low-power 16-bit (available in Stop mode), 2 SysTick timers, and 2 watchdogs
- RTC with hardware calendar, alarms, and calibration

Up to 25 communication peripherals

- 1 USB Type-C®/USB power delivery controller
- 1 USB OTG high-speed with embedded PHY
- 2 SAIs (serial audio interface)
- 6 I2C FM+(1 Mbit/s), SMBus/PMBus™
- 7 USARTs (ISO 7816, LIN, IrDA, modem)
- 3 SPIs (6x SPIs with OCTOSPI/HSPI)
- 1 CAN FD controller
- 2 SDMMC interfaces
- 1 multifunction digital filter (6 filters) + 1 audio digital filter with sound-activity detection
- Parallel synchronous slave interface

Mathematical coprocessor

- CORDIC for trigonometric functions acceleration
- FMAC (filter mathematical accelerator)

Rich analog peripherals (independent supply)

- 2 14-bit ADC 2.5-Msps with hardware oversampling
- 1 12-bit ADC 2.5-Msps, with hardware oversampling, autonomous in Stop 2 mode
- 12-bit DAC (2 channels), low-power sample, and hold, autonomous in Stop 2 mode
- 2 operational amplifiers with built-in PGA
- 2 ultra-low-power comparators

ECOPACK2 compliant packages

Table 1. Device summary

Reference	Part numbers
STM32U5Axxx	STM32U5A5AJ, STM32U5A5QI, STM32U5A5QJ, STM32U5A5RJ, STM32U5A5VJ, STM32U5A5ZJ, STM32U5A9BJ, STM32U5A9NJ, STM32U5A9VJ, STM32U5A9ZJ

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1 Introduction

This document provides the ordering information and mechanical device characteristics of the STM32U5Axxx microcontrollers.

For information on the Arm®(a) Cortex®-M33 core, refer to the Cortex®-M33 Technical Reference Manual, available from the www.arm.com website.

For information on the device errata with respect to the datasheet and reference manual, refer to the STM32U59xxx and STM32U5Axxx errata sheet (ES0553).

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2 Description

The STM32U5Axxx devices belong to an ultra-low-power microcontrollers family (STM32U5 series) based on the high-performance Arm® Cortex®-M33 32-bit RISC core. They operate at a frequency of up to 160 MHz.

The Cortex®-M33 core features a single-precision FPU (floating-point unit), that supports all the Arm® single-precision data-processing instructions and all the data types.

The Cortex®-M33 core also implements a full set of DSP (digital signal processing) instructions and a MPU (memory protection unit) that enhances the application security.

The devices embed high-speed memories (4 Mbytes of flash memory and 2.5 Mbytes of SRAM), a FSMC (flexible external memory controller) for static memories (for devices with packages of 100 pins and more), two Octo-SPI and one Hexadeca-SPI memory interfaces (at least one Quad-SPI available on all packages) and an extensive range of enhanced I/Os and peripherals connected to three APB buses, three AHB buses and a 32-bit multi-AHB bus matrix.

The devices offer security foundation compliant with the TBSA (trusted-based security architecture) requirements from Arm®. It embeds the necessary security features to implement a secure boot, secure data storage and secure firmware update. Besides these capabilities, the devices incorporate a secure firmware installation feature, that allows the customer to secure the provisioning of the code during its production. A flexible life cycle is managed thanks to multiple levels of readout protection and debug unlock with password. Firmware hardware isolation is supported thanks to securable peripherals, memories and I/Os, and privilege configuration of peripherals and memories.

The devices feature several protection mechanisms for embedded flash memory and SRAM: readout protection, write protection, secure and hide protection areas.

The devices embed several peripherals reinforcing security: a fast AES coprocessor, a secure AES coprocessor with DPA resistance and hardware unique key that can be shared by hardware with fast AES, a PKA (public key accelerator) with DPA resistance, an on-the-fly decryption engine for Octo-SPI external memories, a HASH hardware accelerator, and a true random number generator.

The devices offer active tamper detection and protection against transient and environmental perturbation attacks, thanks to several internal monitoring generating secret data erase in case of attack. This helps to fit the PCI requirements for point of sales applications.

The devices offer two fast 14-bit ADCs (2.5 Msps), one 12-bit ADC (2.5 Msps), two comparators, two operational amplifiers, two DAC channels, an internal voltage reference buffer, a low-power RTC, four 32-bit general-purpose timers, two 16-bit PWM timers dedicated to motor control, three 16-bit general-purpose timers, two 16-bit basic timers and four 16-bit low-power timers.

The devices offer a rich set of graphic features: Neo-Chrom GPU (GPU2D) for fast texture mapping, scaling and rotation, Chrom-ART (DMA2D) for smooth motion and transparency effects, Chrom-GRC (GFXMMU) for memory optimization, MIPI® DSI Host controller with two DSI lanes running at up to 500 Mbit/s each, and LCD-TFT controller (LTDC).

The devices support a MDF (multi-function digital filter) with six filters dedicated to the connection of external sigma-delta modulators. Another low-power digital filter dedicated to audio signals is embedded (ADF), with one filter supporting sound-activity detection.

The devices embed mathematical accelerators (a trigonometric functions accelerator plus a filter mathematical accelerator). In addition, up to 22 capacitive sensing channels are available.

The devices also feature standard and advanced communication interfaces such as: six I^2Cs, three SPIs, four USARTs, two UARTs and one low-power UART, two SAIs, one DCMI (digital camera interface), two SDMMCs, one FDCAN, one USB OTG high-speed, one USB Type-C™/USB Power Delivery controller, and one generic synchronous 8-/16-bit PSSI (parallel data input/output slave interface).

The devices operate in the –40 to +85 °C (+ 105 °C junction) and –40 to +125 °C (+130 °C junction) temperature ranges from a 1.71 to 3.6 V power supply.

A comprehensive set of power-saving modes allow the design of low-power applications. Many peripherals (including communication, analog, timers and audio peripherals) can be functional and autonomous down to Stop mode with direct memory access, thanks to LPBAM support (low-power background autonomous mode).

Some independent power supplies are supported like an analog independent supply input for ADC, DACs, OPAMPs and comparators, a 3.3 V dedicated supply input for USB and up to 14 I/Os, that can be supplied independently down to 1.08 V. A VBAT input is available for connecting a backup battery in order to preserve the RTC functionality and to backup 32 32-bit registers and 2-Kbyte SRAM.

The devices offer ten packages from 64 to 216 pins.

Table 2. STM32U5Axxx features and peripheral counts

Peripherals		STM32U5A5RJT	STM32U5A5VJT	STM32U5A9VJT	STM32U5A5QJ/II	STM32U5A5ZJT	STM32U5A9ZJT	STM32U5A5ZJY	STM32U5A9ZJY	STM32U5A5AJH	STM32U5A9BJY	STM32U5A9NJH
Flash memory (Mbytes)		4										
SRAM	System (Kbytes)	2512(768+64+832+16+832)										
	Backup (bytes)	2048 backup SRAM + 128 backup registers										
External memory controller for static memories (FSMC)		No	Yes[1]									
OCTOSPI		2[2]			2							
HSPI		No									Yes	

Table 2. STM32U5Axxx features and peripheral counts (continued)

Peripherals		STM32U5A5RJT	STM32U5A5VJT	STM32U5A9VJT	STM32U5A5QJ/II	STM32U5A5ZJT	STM32U5A9ZJT	STM32U5A5ZJY	STM32U5A9ZJY	STM32U5A5AJH	STM32U5A9BJY	STM32U5A9NJH
Graphic accelerators	Neo-Chrom (GPU2D)	No		Yes	No		Yes	No	Yes	No	Yes	
	Chrom-GRC (GFXMMU)	No		Yes	No		Yes	No	Yes	No	Yes	
	Chrom-ART (DMA2D)	Yes										
	DSI	No							Yes	No	Yes	
	LTDC	No		Yes	No		Yes	No	Yes	No	Yes	
Timers	Adv. control	2 (16 bits)										
	Gen. purpose	4 (32 bits) and 3 (16 bits)										
	Basic	2 (16 bits)										
	Low power	4 (16 bits)										
	SysTick timer	2										
	Watchdog timers (indep., window)	2										
Communication interfaces	SPI	3										
	I2C	6										
	USART	4										
	UART	2										
	LPUART	1										
	SAI	1	2									
	FDCAN	1										
	OTG_HS	Yes										
	UCPD	Yes										
	SDMMC	2(3)										
	Camera interface	Yes/ No(4)	Yes									
	PSSI	Yes/ No(4)	Yes									
MDF (multi-function digital filter)		Yes										
ADF (audio digital filter)		Yes										

Table 2. STM32U5Axxx features and peripheral counts (continued)

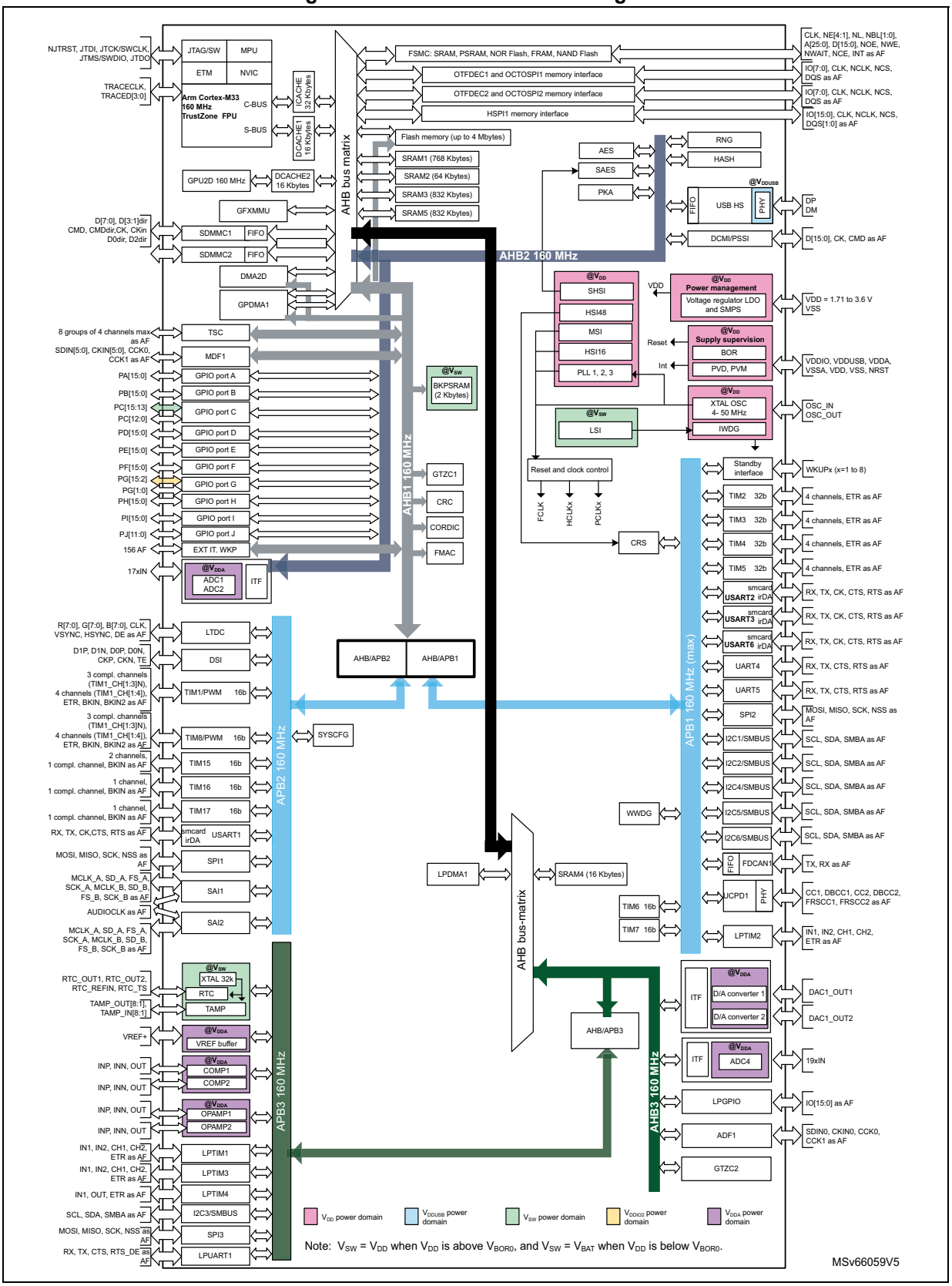
Peripherals		STM32U5A5RJT	STM32U5A5VJT	STM32U5A9VJT	STM32U5A5QJ/II	STM32U5A5ZJT	STM32U5A9ZJT	STM32U5A5ZJY	STM32U5A9ZJY	STM32U5A5AJH	STM32U5A9BJY	STM32U5A9NJH
CORDIC co-processor		Yes										
FMAC (filter mathematical accelerator)		Yes										
RTC (real-time clock)		Yes										
Tamper pins (without SMPS / with SMPS)		4/3	8/7		8/8	8/7	NA/7	NA/8		8/8	NA/8	
Active tampers (without SMPS / with SMPS)(5)		3/2	7/6		7/7	7/6	NA/6	NA/7		7/7	NA/7	
RNG (true random number generator)		Yes										
SAES, AES		Yes										
PKA (public key accelerator)		Yes										
HASH (SHA-256)		Yes										
OTFDEC (on-the-fly decryption for OCTOSPI)		Yes										
GPIOs (without SMPS / with SMPS)		51/47	82/79		110/106	114/111	NA/111	NA/115	NA/108	136/133	NA/145	NA/156
Wake-up pins (without SMPS / with SMPS)		18/17	23/22		24/24	24/23	NA/23	NA/24	NA/24	24/24	NA/24	NA/24
Number of I/Os down to 1.08 V (without SMPS / with SMPS)		0/0	0/0		13/10	14/13	NA/13	NA/14	NA/7	14/11	NA/14	NA/14
Capacitive sensing Number of channels (without SMPS / with SMPS)		10/9	19/18		22/22	22/21	NA/21	NA/22		22/22	NA/22	
ADC	12-bit ADC	1										
	14-bit ADC	2										
	Nb of channels (without SMPS / with SMPS)	17/15	20/18		24/24	24/22	NA/22	NA/24		24/24	NA/24	

Table 2. STM32U5Axxx features and peripheral counts (continued)

Peripherals		STM32U5A5RJT	STM32U5A5VJT	STM32U5A9VJT	STM32U5A5QJ/II	STM32U5A5ZJT	STM32U5A9ZJT	STM32U5A5ZJY	STM32U5A9ZJY	STM32U5A5AJH	STM32U5A9BJY	STM32U5A9NJH
DAC	12-bit DAC	1										
	Nb of 12-bit D-to-A conv.	2										
Internal voltage reference buffer		No	Yes									
Analog comparator		2										
Operational amplifiers		2										
Maximum CPU frequency		160 MHz										
Operating voltage		1.71 to 3.6 V										
Operating temperature		Ambient operating temperature: –40 to +85 °C / –40 to +125 °C Junction temperature: –40 to +105 °C / –40 to +130 °C										
Package		LQFP 64	LQFP 100		UFBGA 132	LQFP 144		WLCSP150		TFBGA 169	WLCSP 208	TFBGA 216

1. For the LQFP100 package, only FSMC bank1 is available. Bank1 can only support a multiplexed NOR/PSRAM memory using the NE1 chip select.
2. Two OCTOSPIs are available only in muxed mode.
3. When both are used simultaneously, one supports only SDIO interface.
4. Available on packages without SMPS, not available on packages with SMPS.
5. Active tampers in output sharing mode (one output shared by all inputs).

Figure 1. STM32U5Axxx block diagram



3 Functional overview

3.1 Arm Cortex-M33 core with TrustZone and FPU

The Cortex-M33 with TrustZone and FPU is a highly energy-efficient processor designed for microcontrollers and deeply embedded applications, especially those requiring efficient security.

The Cortex-M33 processor delivers a high computational performance with low-power consumption and an advanced response to interrupts. It features:

- Arm TrustZone technology, using the Armv8-M main extension supporting secure and nonsecure states
- MPUs (memory protection units), supporting up to 16 regions for secure and non-secure applications
- Configurable SAU (secure attribute unit) supporting up to eight memory regions as secure or nonsecure
- Floating-point arithmetic functionality with support for single precision arithmetic

The processor supports a set of DSP instructions that allows an efficient signal processing and a complex algorithm execution.

The Cortex-M33 processor supports the following bus interfaces:

- System AHB bus:

  The S-AHB (system AHB) bus interface is used for any instruction fetch and data access to the memory-mapped SRAM, peripheral, external RAM and external device, or Vendor_SYS regions of the Armv8-M memory map.
- Code AHB bus:

  The C-AHB (code AHB) bus interface is used for any instruction fetch and data access to the code region of the Armv8-M memory map.

Figure 1 shows the general block diagram of the STM32U5Axxx devices.

3.2 ART Accelerator (ICACHE and DCACHE)

3.2.1 Instruction cache (ICACHE)

The ICACHE is introduced on C-AHB code bus of Cortex-M33 processor to improve performance when fetching instruction (or data) from both internal and external memories.

ICACHE offers the following features:

- Multi-bus interface:
  - Slave port receiving the memory requests from the Cortex-M33 C-AHB code execution port
  - Master1 port performing refill requests to internal memories (flash memory and SRAMs)
  - Master2 port performing refill requests to external memories (external flash memory and RAMs through Octo-SPI and FMC interfaces)
  - Second slave port dedicated to ICACHE registers access

- Close to zero wait-states instructions/data access performance:
  - 0 wait-state on cache hit
  - Hit-under-miss capability, allowing to serve new processor requests while a line refill (due to a previous cache miss) is still ongoing
  - Critical-word-first refill policy, minimizing processor stalls on cache miss
  - Hit ratio improved by two-ways set-associative architecture and pLRU-t replacement policy (pseudo-least-recently-used, based on binary tree), algorithm with best complexity/performance balance
  - Dual master ports allowing to decouple internal and external memory traffics, on fast and slow buses, respectively; also minimizing impact on interrupt latency
  - Optimal cache line refill thanks to AHB burst transactions (of the cache line size)
  - Performance monitoring by means of a hit counter and a miss counter
- Extension of cacheable region beyond the code memory space, by means of address remapping logic that allows four cacheable external regions to be defined
- Power consumption reduced intrinsically (more accesses to cache memory rather to bigger main memories); even improved by configuring ICACHE as direct mapped (rather than the default two-ways set-associative mode)
- TrustZone security support
- Maintenance operation for software management of cache coherency
- Error management: detection of unexpected cacheable write access, with optional interrupt raising

3.2.2 Data cache (DCACHE)

The DCACHE is introduced on S-AHB system bus of Cortex-M33 processor to improve the performance of data traffic to/from external memories.

DCACHE offers the following features:

- Multi-bus interface:
  - Slave port receiving the memory requests from the Cortex-M33 S-AHB system port
  - Master port performing refill requests to external memories (external flash memory and RAMs through Octo-SPI and FMC interfaces)
  - Second slave port dedicated to DCACHE registers access
- Close to zero wait-states external data access performance:
  - Zero wait-states on cache hit
  - Hit-under-miss capability, allowing to serve new processor requests to cached data, while a line refill (due to a previous cache miss) is still ongoing
  - Critical-word-first refill policy for read transactions, minimizing processor stalls on cache miss
  - Hit ratio improved by two-ways set-associative architecture and pLRU-t replacement policy (pseudo-least-recently-used, based on binary tree), algorithm with best complexity/performance balance
  - Optimal cache line refill thanks to AHB burst transactions (of the cache line size)
  - Performance monitoring by means of two hit counters (for read and write) and two miss counters (for read and write)

- Supported cache accesses:
  - Both write-back and write-through policies supported (selectable with AHB bufferable attribute)
  - Read and write-back always allocated
  - Write-through always non-allocated (write-around)
  - Byte, half-word and word writes supported
- TrustZone security support
- Maintenance operations for software management of cache coherency:
  - Full cache invalidation (non interruptible)
  - Address range clean and/or invalidate operations (background task, interruptible)
- Error management: detection of error for master port request initiated by DCACHE (line eviction or clean operation), with optional interrupt raising

3.3 Memory protection unit

The MPU (memory protection unit) is used to manage the CPU accesses to the memory and to prevent one task to accidentally corrupt the memory or the resources used by any other active task. This memory area is organized into up to 16 protected areas.
The MPU regions and registers are banked across secure and nonsecure states.

The MPU is especially helpful for applications where some critical or certified code must be protected against the misbehavior of other tasks. It is usually managed by a RTOS (real-time operating system).

If a program accesses a memory location that is prohibited by the MPU, the RTOS can detect it and take action. In a RTOS environment, the kernel can dynamically update the MPU area setting based on the process to be executed.

The MPU is optional and can be bypassed for applications that do not need it.

3.4 Embedded flash memory

The devices feature 4 Mbytes of embedded flash memory that is available for storing programs and data. The flash memory supports 10 000 cycles and up to 100 000 cycles on 512 Kbytes. A 128-bit instruction prefetch is implemented and can optionally be enabled.

The flash memory interface features:

- Dual-bank operating modes
- Read-while-write (RWW)

This allows a read operation to be performed from one bank while an erase or program operation is performed to the other bank. The dual-bank boot is also supported. Each bank contains 256 pages of 8 Kbytes. The flash memory also embeds 512-byte OTP (one-time programmable) for user data.

The whole non-volatile memory embeds the ECC (error correction code) feature supporting:

- single-error detection and correction
- double-error detection
- ECC fail address report

3.4.1 Flash memory protection

The option bytes allow the configuration of flexible protections:

- write protection (WRP) to protect areas against erasing and programming. Two areas per bank can be selected with 8-Kbyte granularity.
- RDP (readout protection) to protect the whole memory, has four levels of protection available (see *Table 3* and *Table 4*):
  - Level 0: no readout protection
  - Level 0.5: available only when TrustZone is enabled

    All read/write operations (if no write protection is set) from/to the nonsecure flash memory are possible. The debug access to secure area is prohibited.
    Debug access to nonsecure area remains possible.
  - Level 1: memory readout protection

    The flash memory cannot be read from or written to if either the debug features are connected or the boot in RAM or bootloader are selected. If TrustZone is enabled, the nonsecure debug is possible and the boot in SRAM is not possible. Regressions from Level 1 to lower levels can be protected by password authentication.
  - Level 2: chip readout protection

    The debug features, the boot in RAM and the bootloader selection are disabled. A secure secret key can be configured in the secure options to allow the regression capability from Level 2 to Level 1. By default (key not configured), this Level 2 selection is irreversible and JTAG/SWD interfaces are disabled. If the secret key was previously configured in lower RDP levels, the device enables the RDP regression from Level 2 to Level 1 after password authentication through JTAG/SWD interface.

Note: In order to reach the best protection level, it is recommended to activate TrustZone and to set the RDP Level 2 with password authentication regression enabled.

Table 3. Access status versus protection level and execution modes when TZEN = 0

Area	RDP level	User execution (boot from flash memory)			Debug/boot from RAM/ bootloader(1)		
		Read	Write	Erase	Read	Write	Erase
Flash main memory	1	Yes	Yes	Yes	No	No	No(4)
	2	Yes	Yes	Yes	N/A	N/A	N/A
System memory (2)	1	Yes	No	No	Yes	No	No
	2	Yes	No	No	N/A	N/A	N/A
Option bytes(3)	1	Yes	Yes(4)	N/A	Yes	Yes(4)	N/A
	2	Yes	No(5)	N/A	N/A	N/A	N/A
OTP	1	Yes	Yes(6)	N/A	Yes	Yes(6)	N/A
	2	Yes	Yes(6)	N/A	N/A	N/A	N/A

Table 3. Access status versus protection level and execution modes when TZEN = 0 (continued)

Area	RDP level	User execution (boot from flash memory)			Debug/boot from RAM/ bootloader(1)		
		Read	Write	Erase	Read	Write	Erase
Backup registers	1	Yes	Yes	N/A	No	No	N/A(7)
	2	Yes	Yes	N/A	N/A	N/A	N/A
SRAM2/backup RAM	1	Yes	Yes	N/A	No	No	N/A(8)
	2	Yes	Yes	N/A	N/A	N/A	N/A
OTFDEC regions (Octo-SPI)	1	Yes	Yes	Yes	No(9)	Yes	Yes
	2	Yes	Yes	Yes	N/A	N/A	N/A

1. When the protection level 2 is active, the debug port, the boot from RAM and the boot from system memory are disabled.
2. The system memory is only read-accessible, whatever the protection level (0, 1 or 2) and execution mode.
3. Option bytes are only accessible through the flash memory registers and OPSTRT bit.
4. The Flash main memory is erased when the RDP option byte changes from level 1 to level 0.
5. SWAP_BANK option bit can be modified.
6. OTP can only be written once.
7. The backup registers are erased when RDP changes from level 1 to level 0.
8. All SRAMs are erased when RDP changes from level 1 to level 0.
9. The OTFDEC keys are erased when the RDP option byte changes from level 1 to level 0.

Table 4. Access status versus protection level and execution modes when TZEN = 1

Area	RDP level	User execution (boot from flash memory)			Debug/bootloader(1)		
		Read	Write	Erase	Read	Write	Erase
Flash main memory	0.5	Yes	Yes	Yes	Yes(2)	Yes(2)	Yes(2)
	1	Yes	Yes	Yes	No	No	No(5)
	2	Yes	Yes	Yes	N/A	N/A	N/A
System memory (3)	0.5	Yes	No	No	Yes	No	No
	1	Yes	No	No	Yes	No	No
	2	Yes	No	No	N/A	N/A	N/A
Option bytes(4)	0.5	Yes	Yes(5)	N/A	Yes	Yes (5)	N/A
	1	Yes	Yes(5)	N/A	Yes	Yes(5)	N/A
	2	Yes	No(6)	N/A	N/A	N/A	N/A

Table 4. Access status versus protection level and execution modes when TZEN = 1 (continued)

Area	RDP level	User execution (boot from flash memory)			Debug/bootloader(1)		
		Read	Write	Erase	Read	Write	Erase
OTP	0.5	Yes	Yes(7)	N/A	Yes	Yes(7)	N/A
	1	Yes	Yes(7)	N/A	Yes	Yes(7)	N/A
	2	Yes	Yes(7)	N/A	N/A	N/A	N/A
Backup registers	0.5	Yes	Yes	N/A	Yes(2)	Yes(2)	N/A(8)
	1	Yes	Yes	N/A	No	No	N/A(8)
	2	Yes	Yes	N/A	N/A	N/A	N/A
SRAM2/backup RAM	0.5	Yes	Yes	N/A	Yes(2)	Yes(2)	N/A(9)
	1	Yes	Yes	N/A	No	No	N/A(9)
	2	Yes	Yes	N/A	N/A	N/A	N/A
OTFDEC regions (Octo-SPI)	0.5	Yes	Yes	Yes	No(10)	Yes	Yes
	1	Yes	Yes	Yes	No(10)	Yes	Yes
	2	Yes	Yes	Yes	N/A	N/A	N/A

1. When the protection level 2 is active, the debug port and the bootloader mode are disabled.
2. Depends on TrustZone security access rights.
3. The system memory is only read-accessible, whatever the protection level (0, 1 or 2) and execution mode.
4. Option bytes are only accessible through the flash memory registers and OPSTRT bit.
5. The Flash main memory is erased when the RDP option byte regresses from level 1 to level 0.
6. SWAP_BANK option bit can be modified.
7. OTP can only be written once.
8. The backup registers are erased when RDP changes from level 1 to level 0.
9. All SRAMs are erased when RDP changes from level 1 to level 0.
10. The OTFDEC keys are erased when the RDP option byte changes from level 1 to level 0.

3.4.2 Additional flash memory protections when TrustZone activated

When the TrustZone security is enabled through option bytes, the whole flash memory is secure after reset and the following protections are available:

- non-volatile watermark-based secure flash memory area

  The secure area can be accessed only in Secure mode. One area per bank can be selected with a page granularity.
- secure HDP (hide protection area)

  It is part of the flash memory secure area and can be protected to deny an access to this area by any data read, write and instruction fetch. For example, a software code in the secure flash memory hide protection area can be executed only once and deny any

further access to this area until next system reset. One area per bank can be selected at the beginning of the secure area.

- volatile block-based secure flash memory area

  Each page can be programmed on-the-fly as secure or nonsecure.

3.4.3 FLASH privilege protection

Each flash memory page can be programmed on the fly as privileged or unprivileged.

3.5 Embedded SRAMs

Six SRAMs are embedded in the STM32U5Axxx devices, each with specific features. SRAM1, SRAM2, SRAM3 and SRAM5 are the main SRAMs. SRAM4 is in the SRAM used for peripherals LPBAM (low-power background autonomous mode) in Stop 2 mode.

These SRAMs are made of several blocks that can be powered down in Stop mode to reduce consumption:

- SRAM1: 12 64-Kbyte blocks (total 768 Kbytes)
- SRAM2: 8-Kbyte + 56-Kbyte blocks (total 64 Kbytes) with optional ECC. In addition SRAM2 blocks can be retained in Standby mode.
- SRAM3: 13 64-Kbyte blocks (total 832 Kbytes) with optional ECC. When ECC is enabled, 256 Kbytes support ECC and 512 Kbytes of SRAM3 can be accessed without ECC.
- SRAM4: 16 Kbytes
- SRAM5: 13 64-Kbyte blocks (total 832 Kbytes)
- BKPSRAM (backup SRAM): 2 Kbytes with optional ECC. The BKPSRAM can be retained in all low-power modes and when V_{DD} is off in V_{BAT} mode, but not in Shutdown mode.

3.5.1 SRAMs TrustZone security

When the TrustZone security is enabled, all SRAMs are secure after reset. The SRAM1, SRAM2, SRAM3, SRAM4 and SRAM5 can be programmed as secure or nonsecure by blocks, using the MPCBB (block-based memory protection controller).

The granularity of SRAM secure block based is a page of 512 bytes. Backup SRAM regions can be programmed as secure or nonsecure with watermark, using the TZSC (TrustZone security controller) in the GTZC (global TrustZone controller).

3.5.2 SRAMs privilege protection

The SRAM1, SRAM2, SRAM3, SRAM4 and SRAM5 can be programmed as privileged or unprivileged by blocks, using the MPCBB. The granularity of SRAM privilege block based is a page of 512 bytes. Backup SRAM regions can be programmed as privileged or unprivileged with watermark, using the TZSC (TrustZone security controller) in the GTZC (global TrustZone controller).

3.6 TrustZone security architecture

The security architecture is based on Arm TrustZone with the Armv8-M main extension.

The TrustZone security is activated by the TZEN option bit in the FLASH_OPTR register.

When the TrustZone is enabled, the SAU (security attribution unit) and IDAU (implementation defined attribution unit) define the access permissions based on secure and nonsecure state.

- SAU: up to eight SAU configurable regions are available for security attribution.
- IDAU: It provides a first memory partition as nonsecure or nonsecure callable attributes. It is then combined with the results from the SAU security attribution and the higher security state is selected.

Based on IDAU security attribution, the flash memory, system SRAM and peripheral memory space is aliased twice for secure and nonsecure states. However, the external memory space is not aliased.

The table below shows an example of typical SAU region configuration based on IDAU regions. The user can split and choose the secure, nonsecure or NSC regions for external memories as needed.

Table 5. Example of memory map security attribution versus SAU configuration regions

Region description	Address range	IDAU security attribution	SAU security attribution typical configuration	Final security attribution
Code - external memories	0x0000 0000 0x07FF FFFF	Nonsecure	Secure or nonsecure or NSC(1)	Secure or nonsecure or NSC
Code - Flash and SRAM	0x0800 0000 0x0BFF FFFF	Nonsecure	Nonsecure	Nonsecure
	0x0C00 0000 0x0FFF FFFF	NSC	Secure or NSC	Secure or NSC
Code - external memories	0x1000 0000 0x17FF FFFF	Nonsecure	Nonsecure	
	0x1800 0000 0x1FFF FFFF			
SRAM	0x2000 0000 0x2FFF FFFF	Nonsecure		
	0x3000 0000 0x3FFF FFFF	NSC	Secure or NSC	Secure or NSC
Peripherals	0x4000 0000 0x4FFF FFFF	Nonsecure	Nonsecure	Nonsecure
	0x5000 0000 0x5FFF FFFF	NSC	Secure or NSC	Secure or NSC
External memories	0x6000 0000 0xDFFF FFFF	Nonsecure	Secure or nonsecure or NSC	Secure or nonsecure or NSC

1. NSC = nonsecure callable.

3.6.1 TrustZone peripheral classification

When the TrustZone security is active, a peripheral can be either securable or TrustZone-aware type as follows:

- securable: peripheral protected by an AHB/APB firewall gate that is controlled from TZSC to define security properties
- TrustZone-aware: peripheral connected directly to AHB or APB bus and implementing a specific TrustZone behavior such as a subset of registers being secure

3.6.2 Default TrustZone security state

The default system security state is detailed below:

- CPU:
  - Cortex-M33 is in secure state after reset. The boot address must be in secure address.
- Memory map:
  - SAU is fully secure after reset. Consequently, all memory map is fully secure. Up to eight SAU configurable regions are available for security attribution.
- Flash memory:
  - Flash memory security area is defined by watermark user options.
  - Flash memory block based area is nonsecure after reset.
- SRAMs:
  - All SRAMs are secure after reset. MPCBB (memory protection block based controller) is secure.
- External memories:
  - FSMC, OCTOSPI banks are secure after reset. MPCWMx (memory protection watermark based controller) is secure.
- Peripherals
  - Securable peripherals are nonsecure after reset.
  - TrustZone-aware peripherals are nonsecure after reset. Their secure configuration registers are secure.
- All GPIOs are secure after reset.
- Interrupts:
  - NVIC: All interrupts are secure after reset. NVIC is banked for secure and nonsecure state.
- TZIC: All illegal access interrupts are disabled after reset.

3.7 Boot modes

At startup, a BOOT0 pin, nBOOT0, NSBOOTADDx[24:0] (x = 0,1) and SECBOOTADD0[24:0] option bytes are used to select the boot memory address that includes:

- Boot from any address in user flash memory.
- Boot from system memory bootloader.
- Boot from any address in embedded SRAM.
- Boot from RSS (root security services).

The BOOT0 value comes from the PH3-BOOT0 pin or from an option bit depending on the value of a user option bit to free the GPIO pad if needed.

The bootloader is located in the system memory, programmed by ST during production. The bootloader is used to reprogram the flash memory by using USART, I2C, SPI, FDCAN or USB OTG_HS in device mode through the DFU (device firmware upgrade).

The bootloader is available on all devices. Refer to the application note *STM32 microcontroller system memory boot mode* (AN2606) for more details.

The RSS are embedded in a flash memory area named secure information block, programmed during ST production.

For example, the RSS enable the SFI (secure firmware installation), thanks to the RSSe SFI (RSS extension firmware).

This feature allows customer to produce the confidentiality of the firmware to be provisioned into the STM32, when production is sub-contracted to untrusted third party.

The RSS are available on all devices, after enabling the TrustZone through the TZEN option bit. Refer to the application note *Overview secure firmware install* (SFI) (AN4992) for more details.

Refer to *Table 6* and *Table 7* for boot modes when TrustZone is disabled and enabled respectively.

Table 6. Boot modes when TrustZone is disabled (TZEN = 0)

nBOOT0 FLASH_ OPTR[27]	BOOT0 pin PH3	nSWBOOT0 FLASH_ OPTR[26]	Boot address option-byte selection	Boot area	ST programmed default value
-	0	1	NSBOOTADD0[24:0]	Boot address defined by user option bytes NSBOOTADD0[24:0]	Flash: 0x0800 0000
-	1	1	NSBOOTADD1[24:0]	Boot address defined by user option bytes NSBOOTADD1[24:0]	Bootloader: 0x0BF9 0000
1	-	0	NSBOOTADD0[24:0]	Boot address defined by user option bytes NSBOOTADD0[24:0]	Flash: 0x0800 0000
0	-	0	NSBOOTADD1[24:0]	Boot address defined by user option bytes NSBOOTADD1[24:0]	Bootloader: 0x0BF9 0000

When TrustZone is enabled by setting the TZEN option bit, the boot space must be in the secure area. The SECBOOTADD0[24:0] option bytes are used to select the boot secure memory address.

A unique boot entry option can be selected by setting the BOOT_LOCK option bit, allowing to boot always at the address selected by SECBOOTADD0[24:0] option bytes. All other boot options are ignored.

Table 7. Boot modes when TrustZone is enabled (TZEN = 1)

BOOT_ LOCK	nBOOT0 FLASH_ OPTR[27]	BOOT0 pin PH3	nSWBOOT0 FLASH_ OPTR[26]	RSS com-mand	Boot address option-byte selection	Boot area	ST programmed default value
0	-	0	1	0	SECBOOTADD0 [24:0]	Secure boot address defined by user option bytes SECBOOTADD0[24:0]	Flash: 0x0C00 0000
	-	1	1	0	N/A	RSS	RSS: 0x0FF8 0000
	1	-	0	0	SECBOOTADD0 [24:0]	Secure boot address defined by user option bytes SECBOOTADD0[24:0]	Flash: 0x0C00 0000
	0	-	0	0	N/A	RSS	RSS: 0x0FF8 0000
	-	-	-	≠0	N/A	RSS	RSS: 0x0FF8 0000
1	-	-	-	-	SECBOOTADD0 [24:0]	Secure boot address defined by user option bytes SECBOOTADD0[24:0]	Flash: 0x0C00 0000

The boot address option bytes allow any boot memory address to be programmed. However, the allowed address space depends on the flash memory RDP level.

If the programmed boot memory address is out of the allowed memory mapped area when RDP level is 0.5 or more, the default boot address is forced either in secure flash memory or nonsecure flash memory, depending on TrustZone security option as described in the table below.

Table 8. Boot space versus RDP protection

RDP	TZEN = 1	TZEN = 0
0	Any boot address	Any boot address
0.5	Boot address only in RSS or secure flash memory: 0x0C00 0000 - 0x0C3F FFFF Otherwise, forced boot address is 0x0FF8 0000.	N/A
1		Any boot address
2		Boot address only in flash memory: 0x0800 0000 - 0x083F FFFF Otherwise, forced boot address is 0x0800 0000.

3.8 Global TrustZone controller (GTZC)

GTZC is used to configure TrustZone and privileged attributes within the full system.

The GTZC includes three different sub-blocks:

- TZSC: TrustZone security controller

  This sub-block defines the secure/privilege state of slave/master peripherals. It also controls the nonsecure area size for the watermark memory peripheral controller (MPCWM). The TZSC block informs some peripherals (such as RCC or GPIOs) about the secure status of each securable peripheral, by sharing with RCC and I/O logic.
- TZIC: TrustZone illegal access controller

  This sub-block gathers all security illegal access events in the system and generates a secure interrupt towards NVIC.
- MPCBB: MPCBB: block-based memory protection controller

  This sub-block controls secure states of all memory blocks (512-byte pages) of the associated SRAM. This peripheral aims at configuring the internal RAM in a TrustZone system product having segmented SRAM with programmable-security and privileged attributes.

The GTZC main features are:

- Three independent 32-bit AHB interfaces for TZSC, TZIC and MPCBB
- Secure and nonsecure access supported for privileged/unprivileged part of TZSC
- Set of registers to define product security settings:
  - Secure/privilege regions for external memories
  - Secure/privilege access mode for securable peripherals
  - Secure/privilege access mode for securable legacy masters

3.9 Power supply management

The PWR (power controller) main features are:

- Power supplies and supply domains
  - Core domain (V_{CORE})
  - V_{DD} domain
  - Backup domain (V_{BAT})
  - Analog domain (V_{DDA})
  - SMPS power stage (V_{DDSMPS}, available only on SMPS packages)
  - V_{DDIO2} domain
  - V_{DDUSB} and optional $V_{DD11USB}$ for USB transceiver
  - V_{DDDSI} and $V_{DD11DSI}$ for DSI transceiver
- System supply voltage regulation
  - SMPS step down converter
  - Voltage regulator (LDO)

- Power supply supervision
  - BOR monitor
  - PVD monitor
  - PVM monitor (V_{DDA}, V_{DDUSB}, V_{DDIO2})
- Power management
  - Operating modes
  - Voltage scaling control
  - Low-power modes
- V_{BAT} battery charging
- TrustZone security and privileged protection

3.9.1 Power supply schemes

The devices require a 1.71 V to 3.6 V V_{DD} operating voltage supply. Several independent supplies can be provided for specific peripherals:

- V_{DD} = 1.71 V to 3.6 V (functionality guaranteed down to V_{BORx} min value)

  V_{DD} is the external power supply for the I/Os, the internal regulator and the system analog such as reset, power management and internal clocks. It is provided externally through the VDD pins.
- V_{DDA} = 1.58 V (COMPs) / 1.6 V (DACs, OPAMPs) / 1.62 V (ADCs) / 1.8 V (VREFBUF) to 3.6 V

  V_{DDA} is the external analog power supply for ADCs, DACs, voltage reference buffer, operational amplifiers and comparators. The V_{DDA} voltage level is independent from the V_{DD} voltage and must be connected to VDD or VSS pin (preferably to VDD) when these peripherals are not used.
- V_{DDSMPS} = 1.71 V to 3.6 V

  V_{DDSMPS} is the external power supply for the SMPS step-down converter. It is provided externally through VDDSMPS supply pin. It must be connected to the same supply as VDD pin when the SMPS is used in the application. When the SMPS is not used, it is recommended to connect both V_{DDSMPS} and V_{LXSMPS} to GND.
- V_{LXSMPS} is the switched SMPS step down converter output.

Note: The SMPS power supply pins are available only on a specific package with SMPS step down converter option.

- V_{DDUSB} = 3.0 V to 3.6 V

  V_{DDUSB} is the external independent power supply for USB transceivers. V_{DDUSB} voltage level is independent from the V_{DD} voltage and must be connected to VDD or VSS pin (preferably to VDD) when the USB is not used.
- $V_{DD11USB}$ = 1.0 V to 1.26 V

  $V_{DD11USB}$ is the external power supply for the USB transceiver. This supply is only available on specific packages and must be connected to VDD11.
- V_{DDIO2} = 1.08 V to 3.6 V

  V_{DDIO2} is the external power supply for 14 I/Os (port G[15:2]). The V_{DDIO2} voltage level is independent from the V_{DD} voltage and must be connected to VDD or VSS pin (preferably to VDD) when PG[15:2] are not used.
- V_{BAT} = 1.65 V to 3.6 V (functionality guaranteed down to V_{BOR_VBAT} min value)

  V_{BAT} is the power supply for RTC, TAMP, external and internal 32 kHz oscillators, and

backup registers (through power switch) when V_{DD} is not present.

- V_{DDDSI} = 1.71 V to 3.6 V

  V_{DDDSI} is the external power supply for the DSI controller. It is provided externally through VDDDSI supply pin, and must be connected to the same supply as VDD pin.

- $V_{DD11DSI}$ = 1.0 V to 1.26 V

  $V_{DD11DSI}$ is the external power supply for the DSI transceiver and must be connected to VDD11.

- V_{REF-}, V_{REF+}

  V_{REF+} is the input reference voltage for ADCs and DACs. It is also the output of the internal voltage reference buffer when enabled.

  V_{REF+} can be grounded when ADC and DAC are not active.

  The internal voltage reference buffer supports four outputs:

  – V_{REF+} around 1.5 V. This requires $V_{DDA} \geq 1.8$ V.
  – V_{REF+} around 1.8 V. This requires $V_{DDA} \geq 2.1$ V.
  – V_{REF+} around 2.048 V. This requires $V_{DDA} \geq 2.4$ V.
  – V_{REF+} around 2.5 V. This requires $V_{DDA} \geq 2.8$ V.

  VREF- and VREF+ pins are not available on all packages. When not available, they are bonded to VSSA and VDDA, respectively.

  When the VREF+ is double-bonded with VDDA in a package, the internal voltage reference buffer is not available and must be kept disabled.

  V_{REF-} must always be equal to V_{SSA}.

The STM32U5Axxx devices embed two regulators: one LDO and one SMPS in parallel to provide the V_{CORE} supply for digital peripherals, SRAM1, SRAM2, SRAM3, SRAM4, SRAM5 and embedded flash memory. The SMPS generates this voltage on VDD11 (two or three pins) with a total external capacitor of 4.7 µF typical. SMPS requires an external coil of 2.2 µH typical. The LDO generates this voltage on VCAP (one or two) pin(s) with a total external capacitor of 4.7 µF typical.

Both regulators can provide four different voltages (voltage scaling) and can operate in Stop modes. It is possible to switch from SMPS to LDO and from LDO to SMPS on-the-fly (refer to the product reference manual for more details).

Figure 2. STM32U5AxxxxxQ power supply overview (with SMPS)

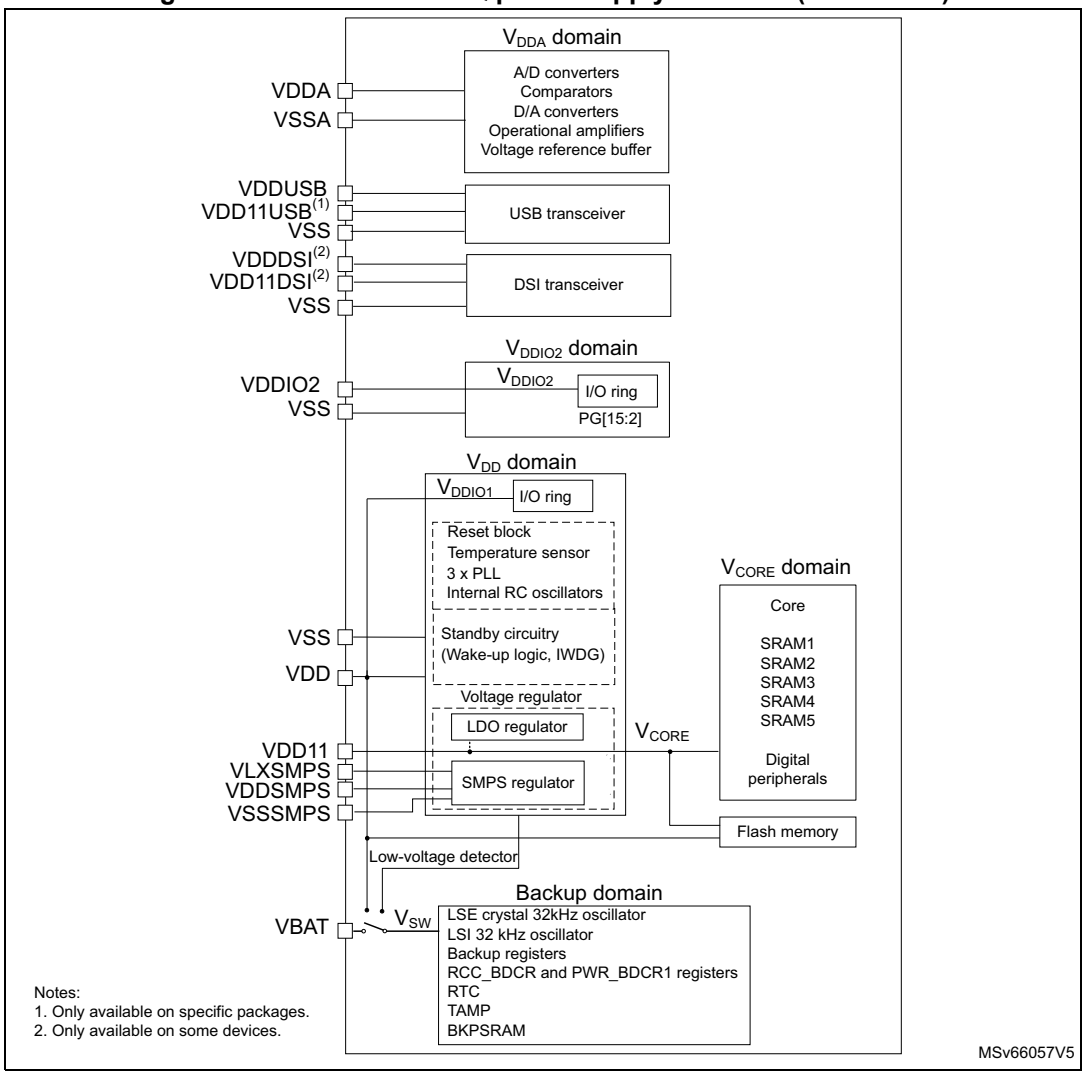
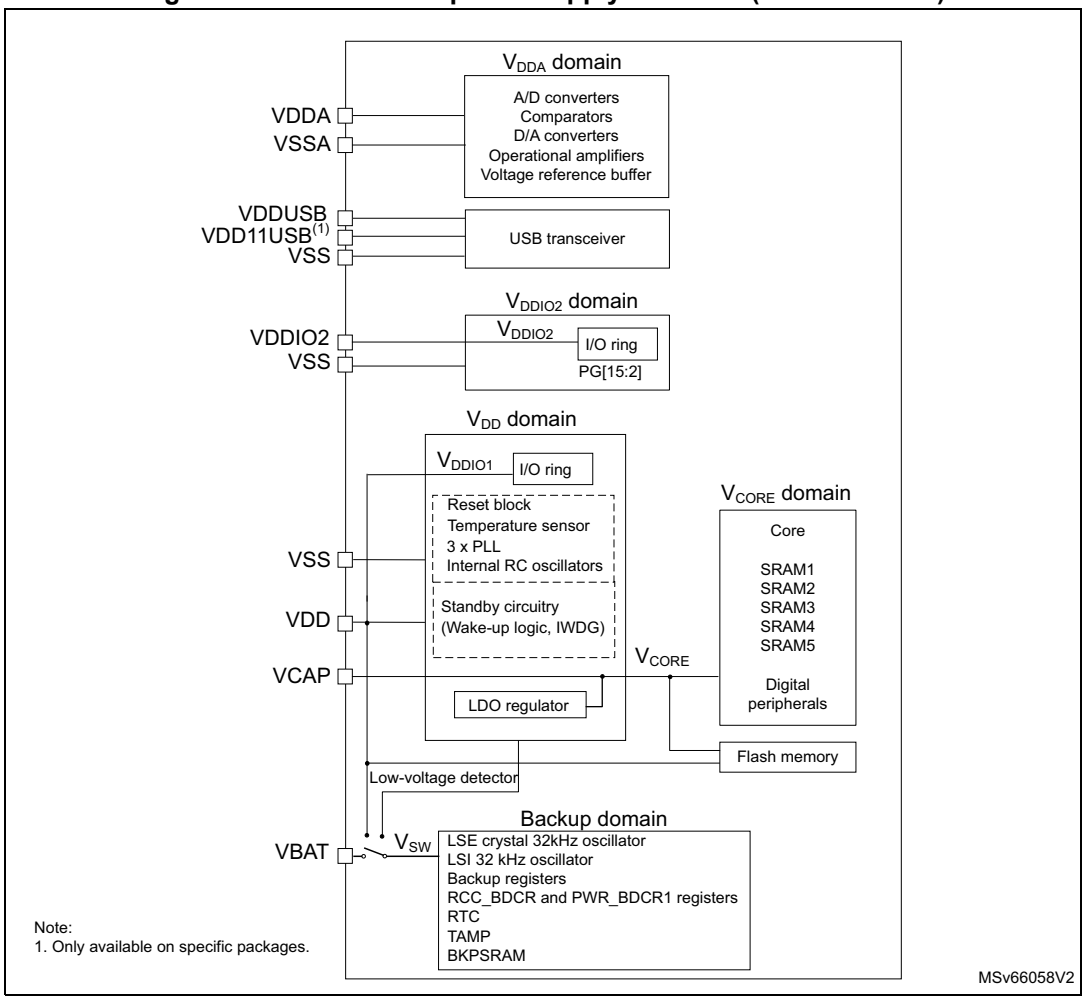


Figure 3. STM32U5Axxx power supply overview (without SMPS)



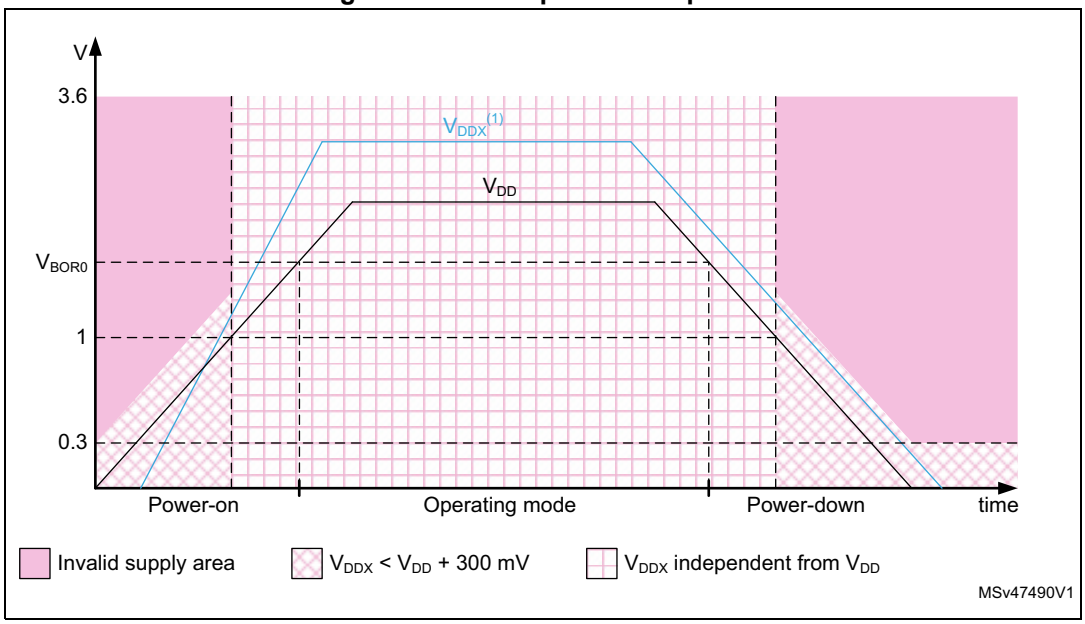
In this document, V_{DDIOx} refers to the I/O power supply. V_{DDIOx} can be V_{DDIO1} (which is supplied by V_{DD}), V_{DDIO2} (independent power supply for PG[15:2]), or V_{SW} (supplying PC13, PC14, PC15, and all FT_t I/Os in VBAT mode).

V_{SW} = V_{DD} when V_{DD} is above V_{BOR0}, and V_{SW} = V_{BAT} when V_{DD} is below V_{BOR0}.

During power-up and power-down phases, the following power sequence requirements must be respected:

- When V_{DD} is below 1 V, other power supplies (V_{DDA}, V_{DDIO2}, V_{DDUSB}) must remain below V_{DD} + 300 mV.
- When V_{DD} is above 1 V, all power supplies are independent.
- During the power-down phase, V_{DD} can temporarily become lower than other supplies only if the energy provided to the MCU remains below 1 mJ. This allows external decoupling capacitors to be discharged with different time constants during the power-down transient phase.

Figure 4. Power-up /down sequence



1. V_{DDX} refers to any power supply among V_{DDA}, V_{DDUSB}, and V_{DDIO2}.

3.9.2 Power supply supervisor

The devices have an integrated ultra-low-power BOR (Brownout reset) active in all modes (except for Shutdown mode). The BOR ensures proper operation of the device after power on and during power down. The device remains in reset mode when the monitored supply voltage V_{DD} is below a specified threshold, without the need for an external reset circuit.

The lowest BOR level is 1.71 V at power on, and other higher thresholds can be selected through option bytes.The devices feature an embedded PVD (programmable voltage detector) that monitors the V_{DD} power supply and compares it to the V_{PVD} threshold.

An interrupt can be generated when V_{DD} drops below and/or rises above the V_{PVD} threshold. The interrupt service routine can then generate a warning message and/or put the MCU into a safe state. The PVD is enabled by software.

In addition, the devices embed a peripheral voltage monitor that compares the independent supply voltages V_{DDA}, V_{DDUSB} and V_{DDIO2} to ensure that the peripheral is in its functional supply range.

The devices support dynamic voltage scaling to optimize its power consumption in Run mode. The voltage from the main regulator that supplies the logic (V_{CORE}) can be adjusted according to the system's maximum operating frequency.

The main regulator operates in the following ranges:

- Range 1 (V_{CORE} = 1.2 V) with CPU and peripherals running at up to 160 MHz
- Range 2 (V_{CORE} = 1.1 V) with CPU and peripherals running at up to 110 MHz
- Range 3 (V_{CORE} = 1.0 V) with CPU and peripherals running at up to 55 MHz
- Range 4 (V_{CORE} = 0.9 V) with CPU and peripherals running at up to 25 MHz

3.9.3 Low-power modes

The ultra-low-power STM32U5Axxx devices support seven low-power modes to achieve the best compromise between low-power consumption, short startup time, available peripherals and available wake-up sources.

The table below details the related low-power modes.

Table 9. STM32U5Axxx modes overview

Mode	Regulator (1)	CPU	Flash	SRAM	Clocks	DMA and peripherals(2)	Wake-up source
Run	Range 1	Yes	ON(3)	ON	Any	All	N/A
	Range 2						
	Range 3					All except DSI and OTG_HS	
	Range 4					All except DSI, LTDC, OTG_HS and UCPD	
Sleep	Range 1	No	ON	ON(4)	Any	All	Any interrupt or event
	Range 2						
	Range 3					All except DSI and OTG_HS	
	Range 4					All except DSI, LTDC, OTG_HS and UCPD	
Stop 0	Range 1	No	OFF	ON(5)	LSE LSI (6)	BOR, PVD, PVM, RTC, TAMP, IWDG, TEMP (temp. sensor), VREFBUF, ADC4(7), DAC1 (2 channels)(8), COMPx (x = 1, 2), OPAMPx (x = 1,2), USARTx (x = 1...6)(9), LPUART1, SPIx (x = 1...3)(10), I2Cx (x = 1...6)(11), LPTIMx (x = 1...4)(12), MDF1(13), ADF1, GPIO, LPGPIO, GPDMA1(14), LPDMA1 All other peripherals are frozen.	Reset pin, all I/Os BOR, PVD, PVM, RTC, TAMP, IWDG, TEMP, ADC4 DAC1 (2 channels), COMPx (x = 1, 2), USARTx (x = 1...6), LPUART1, SPIx (x = 1...3), I2Cx (x = 1...6), LPTIMx (x = 1...4), MDF1, ADF1, GPDMA1, LPDMA1, OTG_HS, UCPD
	Range 2						
	Range 3						
	Range 4						
Stop 1	LPR						

Table 9. STM32U5Axxx modes overview (continued)

Mode	Regulator (1)	CPU	Flash	SRAM	Clocks	DMA and peripherals(2)	Wake-up source
Stop 2	LPR	No	OFF	ON(5)	LSE LSI	BOR, PVD, PVM, RTC, TAMP, IWDG, TEMP, VREFBUF, ADC4, DAC1 (2 channels), COMPx (x = 1, 2) , OPAMPx (x = 1, 2), LPUART1, SPI3, I2C3, LPTIMx (x = 1,3,4), ADF1, LPGPIO, LPDMA1 All other peripherals are frozen.	Reset pin, all I/Os BOR, PVD, PVM, RTC, TAMP, IWDG, TEMP, ADC4, COMPx (x = 1, 2), LPUART1, SPI3, I2C3, LPTIMx (x = 1,3,4), ADF1, LPDMA1
Stop 3	LPR	No	OFF	ON(5)	LSE LSI	BOR, RTC, TAMP, IWDG, DAC1 (2 static channels), OPAMPx (x = 1, 2) All other peripherals are frozen. I/O configuration can be floating, pull-up or pull-down.	Reset pin, 24 I/Os (WKUPx), BOR, RTC, TAMP, IWDG
Standby	LPR	Powered off	OFF	64-, 56- or 8-Kbyte SRAM2 2-Kbyte BKPSRAM(5) all other SRAMs powered off	LSE LSI	BOR, RTC, TAMP, IWDG All other peripherals are powered off. I/O configuration can be floating, pull-up or pull-down.	Reset pin, 24 I/Os (WKUPx), BOR, RTC, TAMP, IWDG
	OFF			Powered off			
Shutdown	OFF	Powered off	OFF	Powered off	LSE	RTC, TAMP All other peripherals are powered off. I/O configuration can be floating, pull-up or pull-down(15).	Reset pin 24 I/Os (WKUPx) RTC, TAMP

1. LPR means that the main regulator is OFF and the low-power regulator is ON.
2. All peripherals can be active or clock gated to save power consumption.
3. The flash memory can be put in power-down and its clock can be gated off when executing from SRAM. One bank can also be put in power-down mode.
4. The SRAM1, SRAM2, SRAM3, SRAM4, SRAM5 and BKPSRAM clocks can be gated on or off independently.
5. The SRAM can be individually powered off to save power consumption.
6. MSI and HSI16 can be temporary enabled upon peripheral request, for autonomous functions with DMA or wake-up from Stop event detections.
7. The ADC4 conversion is functional and autonomous with DMA in Stop mode, and can generate a wake-up interrupt on conversion events.
8. DAC1 is the digital-to-analog (D/A) converter controller instance name. This instance controls two D/A converters also called "two channels". The DAC conversions are functional and autonomous with DMA in Stop mode.
9. U(S)ART and LPUART transmission and reception is functional and autonomous with DMA in Stop mode, and can generate a wake-up interrupt on transfer events.
10. SPI transmission and reception is functional and autonomous with DMA in Stop mode, and can generate a wake-up interrupt on transfer events.
11. I2C transmission and reception is functional and autonomous with DMA in Stop mode, and can generate a wake-up interrupt on transfer events.
12. LPTIM is functional and autonomous with DMA in Stop mode, and can generate a wake-up interrupt on all events.
13. MDF and ADF are functional and autonomous with DMA in Stop mode, and can generate a wake-up interrupt on events.
14. GPDMA and LPDMA are functional and autonomous in Stop mode, and can generate a wake-up interrupt on events.
15. I/Os can be configured with internal pull-up, pull-down or floating in Shutdown mode but the configuration is lost when exiting the Shutdown mode.

By default, the microcontroller is in Run mode after a system or a power reset. It is up to the user to select one of the low-power modes described below:

- **Sleep** mode

  In Sleep mode, only the CPU is stopped. All peripherals continue to operate and can wake up the CPU when an interrupt/event occurs.

- **Stop 0, Stop 1, Stop 2, and Stop 3** modes

  Stop mode achieves the lowest power consumption while retaining the content of SRAM and registers. The SRAMs can be totally or partially switched off to further reduce consumption. All clocks in the V_{CORE} domain are stopped, the PLL, the MSI, the HSI16, the HSI48 and the HSE crystal oscillators are disabled. The LSE or LSI is still running.

  The RTC can remain active (Stop mode with RTC, Stop mode without RTC).

  Some peripherals are autonomous and can operate in Stop mode by requesting their kernel clock and their bus (APB or AHB) when needed, in order to transfer data with DMA (GPDMA1 in Stop 0 and Stop 1 modes, LPDMA1 in Stop 0, Stop 1 and Stop 2 modes). Refer to *Low-power background autonomous mode (LPBAM)* for more details. LPBAM is not supported in Stop 3 mode.

  In Stop 2 and Stop 3 modes, most of the V_{CORE} domain is put in a lower leakage mode. Stop 0 and Stop 1 modes offer the largest number of active peripherals and wake-up sources, a smaller wake-up time but a higher consumption than Stop 2 mode.

  In Stop 0 mode, the main regulator remains ON, allowing a very fast wake-up time but with much higher consumption.

  Stop 3 is the lowest power mode with full retention, but the functional peripherals and sources of wake-up are reduced to the same ones than in Standby mode.

  The system clock when exiting from Stop 0, Stop 1 or Stop 2 mode can be either MSI up to 24 MHz or HSI16, depending on software configuration.

- **Standby** mode

  The Standby mode is used to achieve the lowest power consumption with BOR. The internal regulator is switched off so that the V_{CORE} domain is powered off. The PLL, the MSI, the HSI16, the HSI48 and the HSE crystal oscillators are also switched off.

  The RTC can remain active (Standby mode with RTC, Standby mode without RTC).

  The BOR always remains active in Standby mode.

  The state of each I/O during Standby mode can be selected by software: I/O with internal pull-up, internal pull-down or floating.

  After entering Standby mode, SRAMs and register contents are lost except for registers and backup SRAM in the Backup domain and Standby circuitry. Optionally, the full SRAM2 or 8 Kbytes or 56 Kbytes can be retained in Standby mode, supplied by the low-power regulator (Standby with SRAM2 retention mode).

  The BOR can be configured in ultra-low-power mode to further reduce power consumption during Standby mode.

  The device exits Standby mode when an external reset (NRST pin), an IWDG reset, WKUP pin event (configurable rising or falling edge), an RTC event occurs (alarm, periodic wake-up, timestamp), or a tamper detection. The tamper detection can be raised either due to external pins or due to an internal failure detection.

  The system clock after wake-up is MSI up to 4 MHz.

- **Shutdown** mode

  The lowest power consumption is achieved in Shutdown mode. The internal regulator is switched off so that the V_{CORE} domain is powered off. The PLL, the HSI16, the HSI48, the MSI, the LSI and the HSE oscillators are also switched off.

  The RTC can remain active (Shutdown mode with RTC, Shutdown mode without RTC). The BOR is not available in Shutdown mode. No power voltage monitoring is possible in this mode, therefore the switch to backup domain is not supported (V_{BAT} mode is not supported).

  SRAMs and register contents are lost except for registers in the backup domain as long as VDD is present.

  The device exits Shutdown mode when an external reset (NRST pin), a WKUP pin event (configurable rising or falling edge), or an RTC event occurs (alarm, periodic wake-up, timestamp), or a tamper detection.

  The system clock after wake-up is MSI at 4 MHz.

Low-power background autonomous mode (LPBAM)

The ultra-low-power STM32U5Axxx devices support LPBAM (low-power background autonomous mode) that allows peripherals to be functional and autonomous in Stop mode (Stop 0, Stop 1 and Stop 2 modes), so without any software running.

In Stop 0 and Stop 1 modes, the autonomous peripherals are the following: ADC4, DAC1, LPTIMx (x = 1 to 4), USARTx (x = 1 to 6), LPUART1, SPIx (x = 1 to 3), I2Cx (x = 1 to 6), MDF1, ADF1, GPDMA1 and LPDMA1. In these modes, SRAM1, SRAM2, SRAM3, SRAM4 and SRAM5 can be accessed by the GPDMA1, and SRAM4 can be accessed by the LPDMA1.

In Stop 2 mode, the autonomous peripherals are the following: ADC4, DAC1, LPTIM1, LPTIM3, LPTIM4, LPUART1, SPI3, I2C3, ADF1 and LPDMA1. In this mode, the SRAM4 can be accessed by the LPDMA1.

Those peripherals support the features detailed below:

- Functionality in Stop mode thanks to its own independent clock (named kernel clock) request capability: the peripheral kernel clock is automatically switched on when requested by a peripheral, and automatically switched off when no peripheral requests it.
- DMA transfers supported in Stop mode thanks to system clock request capability: the system clock (MSI or HSI16) automatically switched on when requested by a peripheral, and automatically switched off when no peripheral requests it. When the system clock is requested by an autonomous peripheral, the system clock is woken up and distributed to all peripherals enabled in the RCC. This allows the DMA to access the enabled SRAM, and any enabled peripheral register (for instance GPIO or LPGPIO registers).
- Automatic start of the peripheral thanks to hardware synchronous or asynchronous triggers (such as I/Os edge detection and low-power timer event).
- Wake-up from Stop mode with peripheral interrupt.

The GPDMA and LPDMA are fully functional and the linked-list is updated in Stop mode, allowing the different DMA transfers to be linked without any CPU wake-up. This can be used to chain different peripherals transfers, or to write peripherals registers in order to change their configuration while remaining in Stop mode.

The DMA transfers from memory to memory can be started by hardware synchronous or asynchronous triggers, and the DMA transfers between peripherals and memories can also be gated by those triggers.

Here below some use-cases that can be done while remaining in Stop mode:

- A/D or D/A conversion triggered by a low-power timer (or any other trigger)
  - wake-up from Stop mode on analog watchdog if the A/D conversion result is out of programmed thresholds
  - wake-up from Stop mode on DMA buffer event
- Audio digital filter data transfer into SRAM
  - wake-up from Stop on sound-activity detection
- I^2C slave reception or transmission, SPI reception, UART/LPUART reception
  - wake-up at the end of peripheral transfer or on DMA buffer event
- I^2C master transfer, SPI transmission, UART/LPUART transmission, triggered by a low-power timer (or any other trigger):
  - example: sensor periodic read
  - wake-up at the end of peripheral transfer or on DMA buffer event
- Bridges between peripherals
  - example: ADC converted data transferred by communication peripherals
- Data transfer from/to GPIO/LPGPIO to/from SRAM for:
  - controlling external components
  - implementing data transmission and reception protocols

Table 10. Functionalities depending on the working mode(1)

Peripheral	Run	Sleep	Stop 0/1		Stop 2		Stop 3		Standby		Shutdown		VBAT
			-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	
CPU	Y	-	-	-	-	-	-	-	-	-	-	-	-
Flash memory	O(2)	O(2)	-	-	-	-	-	-	-	-	-	-	-
SRAM1	Y(3)(4)	Y(3)(4)	O(7)	-	O(7)	-	O(7)	-	-	-	-	-	-
SRAM2	Y(3)(4)	Y(3)(4)	O(7)	O(5)	O(7)	-	O(7)	-	O(6)	-	-	-	-
SRAM3	Y(3)(4)	Y(3)(4)	O(7)	O(5)	O(7)	-	O(7)	-	-	-	-	-	-
SRAM4	Y(3)(4)	Y(3)(4)	O(7)	-	O(7)	-	O(7)	-	-	-	-	-	-
SRAM5	Y(3)(4)	Y(3)(4)	O(7)	-	O(7)	-	O(7)	-	-	-	-	-	-
BKPSRAM	O(4)	O(4)	O	O(5)	O		O		O				O
FSMC	O	O	-	-	-	-	-	-	-	-	-	-	-
OCTOSPIx (x =1,2)	O	O	-	-	-	-	-	-	-	-	-	-	-
HSPI1	O	O	-	-	-	-	-	-	-	-	-	-	-
Backup registers	Y	Y	Y	-	Y	-	Y	-	Y	-	Y	-	Y
BOR (Brownout reset)	Y	Y	Y	Y	Y	Y	Y	Y	Y	Y	-	-	-
PVD (programmable voltage detector)	O	O	O	O	O	O	-	-	-	-	-	-	-
Peripheral voltage monitor	O	O	O	O	O	O	-	-	-	-	-	-	-
GPDMA1	O	O	O	O(8)	-	-	-	-	-	-	-	-	-
LPDMA1	O	O	O	O(9)	O	O(9)	-	-	-	-	-	-	-
DMA2D	O	O											
HSI16 (high-speed internal)	O	O	(10)	-	(10)	-	-	-	-	-	-	-	-
HSI48 oscillator	O	O	-	-	-	-	-	-	-	-	-	-	-
HSE (high-speed external)	O	O	-	-	-	-	-	-	-	-	-	-	-
LSI (low-speed internal)	O	O	O	-	O	-	O	-	O	-	-	-	O
LSE (low-speed external)	O	O	O	-	O	-	O	-	O	-	O	-	O
MSIS and MSIK (multi-speed internal)	O	O	(10)	-	(10)	-	-	-	-	-	-	-	-
CSS (clock security system)	O	O	-	-	-	-	-	-	-	-	-	-	-

Table 10. Functionalities depending on the working mode[1] (continued)

Peripheral	Run	Sleep	Stop 0/1		Stop 2		Stop 3		Standby		Shutdown		VBAT
			-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	
Clock security system on LSE	O	O	O	O	O	O	O	O	O	O	O	O	O
Backup domain voltage and temperature monitoring	O	O	O	O	O	O	O	O	O	O	-	-	O
RTC/TAMP	O	O	O	O	O	O	O	O	O	O	O	O	O
Number of RTC tamper pins	8	8	8	O	8	O	8	O	8	O	8	O	8
OTG_HS, UCPD	O[11]	O[11]	-	O[12]	-	-	-	-	-	-	-	-	-
USARTx (x=1,2,3,4,5,6)	O	O	O[13]	O[13]	-	-	-	-	-	-	-	-	-
Low-power UART (LPUART1)	O	O	O[13]	O[13]	O[13]	O[13]	-	-	-	-	-	-	-
I2Cx (x = 1,2,4,5,6)	O	O	O[14]	O[14]	-	-	-	-	-	-	-	-	-
I2C3	O	O	O[14]	O [14]	O[14]	O[14]	-	-	-	-	-	-	-
SPIx (x = 1,2)	O	O	O[15]	O[15]	-	-	-	-	-	-	-	-	-
SPI3	O	O	O[15]	O[15]	O[15]	O[15]							
FDCAN1	O	O	-	-	-	-	-	-	-	-	-	-	-
SDMMCx (x = 1,2)	O	O	-	-	-	-	-	-	-	-	-	-	-
SAIx (x = 1,2)	O	O	-	-	-	-	-	-	-	-	-	-	-
ADCx (x = 1,2)	O	O	-	-	-	-	-	-	-	-	-	-	-
ADC4	O	O	O[16]	O[16]	O[16]	O[16]	-	-	-	-	-	-	-
DAC1 (2 converters)	O	O	O	-	O	-	-	-	-	-	-	-	-
VREFBUF	O	O	O	-	O	-	-	-	-	-	-	-	-
OPAMPx (x = 1,2)	O	O	O	-	O	-	-	-	-	-	-	-	-
COMPx (x = 1,2)	O	O	O	O	O	O	-	-	-	-	-	-	-
Temperature sensor	O	O	O	-	O	-	-	-	-	-	-	-	-
Timers (TIMx)	O	O	-	-	-	-	-	-	-	-	-	-	-
LPTIMx (x = 1,3,4)	O	O	O[17]	O[17]	O[17]	O[17]	-	-	-	-	-	-	-
LPTIM2	O	O	O[17]	O[17]	-	-	-	-	-	-	-	-	-
IWDG (independent watchdog)	O	O	O	O	O	O	O	O	O	O	-	-	-

Table 10. Functionalities depending on the working mode[1] (continued)

Peripheral	Run	Sleep	Stop 0/1		Stop 2		Stop 3		Standby		Shutdown		VBAT
			-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	-	Wake-up capability	
WWDG (window watchdog)	O	O	-	-	-	-	-	-	-	-	-	-	-
SysTick timer	O	O	-	-	-	-	-	-	-	-	-	-	-
MDF1 (multi-function digital filter)	O	O	O[18]	O[18]	-	-	-	-	-	-	-	-	-
ADF1 (audio digital filter)	O	O	O[18]	O[18]	O[18]	O[18]	-	-	-	-	-	-	-
LTDC	O	O	-	-	-	-	-	-	-	-	-	-	-
DSI	O	O	-	-	-	-	-	-	-	-	-	-	-
GFXMMU	O	O	-	-	-	-	-	-	-	-	-	-	-
GPU2D	O	O	-	-	-	-	-	-	-	-	-	-	-
DCMI (digital camera interface)	O	O	-	-	-	-	-	-	-	-	-	-	-
PSSI (parallel synchronous slave interface)	O	O											
CORDIC coprocessor	O	O	-	-	-	-	-	-	-	-	-	-	-
FMAC (filter mathematical accelerator)	O	O	-	-	-	-	-	-	-	-	-	-	-
TSC (touch sensing controller)	O	O	-	-	-	-	-	-	-	-	-	-	-
RNG (true random number generator)	O	O	-	-	-	-	-	-	-	-	-	-	-
AES and secure AES	O	O	-	-	-	-	-	-	-	-	-	-	-
PKA (public key accelerator)	O	O	-	-	-	-	-	-	-	-	-	-	-
OTFDEC (on-the-fly decryption)	O	O	-	-	-	-	-	-	-	-	-	-	-
HASH accelerator	O	O	-	-	-	-	-	-	-	-	-	-	-
CRC calculation unit	O	O	-	-	-	-	-	-	-	-	-	-	-
GPIOs	O	O	O	O	O	O	-[19]	24 pins	-[19]	24 pins	-[20]	24 pins	-

1. Y = yes (enabled). O = optional (disabled by default, can be enabled by software). - = not available. Gray cells highlight the wake-up capability in each mode.
2. The flash memory can be configured in power-down mode. By default, it is not in power-down mode.
3. The SRAMs can be powered on or off independently.
4. The SRAM clock can be gated on or off independently.
5. ECC error interrupt or NMI wake-up from Stop mode.

6. 8-Kbyte, 56-Kbyte or full SRAM2 content can be preserved.
7. Sub-blocks or full SRAM1, SRAM3, and SRAM5, full SRAM2 and SRAM4 can be powered-off to save power consumption. SRAM1, SRAM2, SRAM3, SRAM4, and SRAM5 can be accessed by GPDMA1 in Stop 0 and Stop 1 modes. SRAM4 can be accessed by LPDMA1 in Stop 0, Stop 1 and Stop 2 modes.
8. GPDMA transfers are functional and autonomous in Stop mode, and generates a wake-up interrupt on transfer events.
9. LPDMA transfers are functional and autonomous in Stop mode, and generates a wake-up interrupt on transfer events.
10. Some peripherals with autonomous mode and wake-up from Stop capability can request HSI16, MSIS or MSIK to be enabled. In this case, the oscillator is woken up by the peripheral, and is automatically put off when no peripheral needs it.
11. OTG_HS is functional in voltage scaling range 1 and 2.
12. OTG_HS cannot wake up from Stop mode 1.
13. USART and LPUART reception and transmission are functional and autonomous in Stop mode in asynchronous and in SPI master modes, and generate a wake-up interrupt on transfer events.
14. I2C reception and transmission are functional and autonomous in Stop mode, and generate a wake-up interrupt on transfer events.
15. SPI reception and transmission are functional and autonomous in Stop mode, and generate a wake-up interrupt on transfer events.
16. A/D conversion is functional and autonomous in Stop mode, and generates a wake-up interrupt on conversion events.
17. LPTIM is functional and autonomous in Stop mode, and generates a wake-up interrupt on events.
18. MDF and ADF are functional and autonomous in Stop mode, and generate a wake-up interrupt on events.
19. I/Os can be configured with internal pull-up, pull-down or floating in Stop 3 and Standby modes.
20. I/Os can be configured with internal pull-up, pull-down or floating in Shutdown mode but the configuration is lost when exiting the Shutdown mode.

3.9.4 Reset mode

In order to improve the consumption under reset, the I/O state under and after reset is “analog state” (the I/O Schmitt trigger is disabled). In addition, the internal reset pull-up is deactivated when the reset source is internal.

3.9.5 V_{BAT} operation

The VBAT pin allows the device V_{BAT} domain to be powered from an external battery or an external super-capacitor.

The VBAT pin supplies the RTC with LSE, anti-tamper detection (TAMP), backup registers and 2-Kbyte backup SRAM. Eight anti-tamper detection pins are available in V_{BAT} mode.

The V_{BAT} operation is automatically activated when V_{DD} is not present. An internal V_{BAT} battery charging circuit is embedded and can be activated when V_{DD} is present.

Note: When the microcontroller is supplied from V_{BAT}, neither external interrupts nor RTC/TAMP alarm/events exit the microcontroller from the V_{BAT} operation.

3.9.6 PWR TrustZone security

When the TrustZone security is activated by the TZEN option bit, the PWR is switched in TrustZone security mode.

The PWR TrustZone security secures the following configuration:

- low-power mode
- WKUP (wake-up) pins
- voltage detection and monitoring
- V_{BAT} mode

Some of the PWR configuration bits security is defined by the security of other peripherals:

- The VOS (voltage scaling) configuration is secure when the system clock selection is secure in RCC.
- The I/O pull-up/pull-down in Standby mode configuration is secure when the corresponding GPIO is secure.

3.10 Peripheral interconnect matrix

Several peripherals have direct connections between them, that allow autonomous communication between them and support the saving of CPU resources (thus power supply consumption). In addition, these hardware connections allow fast and predictable latency.

Depending on the peripherals, these interconnections can operate in Run, Sleep, Stop 0, Stop 1, and Stop 2 modes.

3.11 Reset and clock controller (RCC)

The RCC manages the different reset types, and generates all clocks for the bus and peripherals.

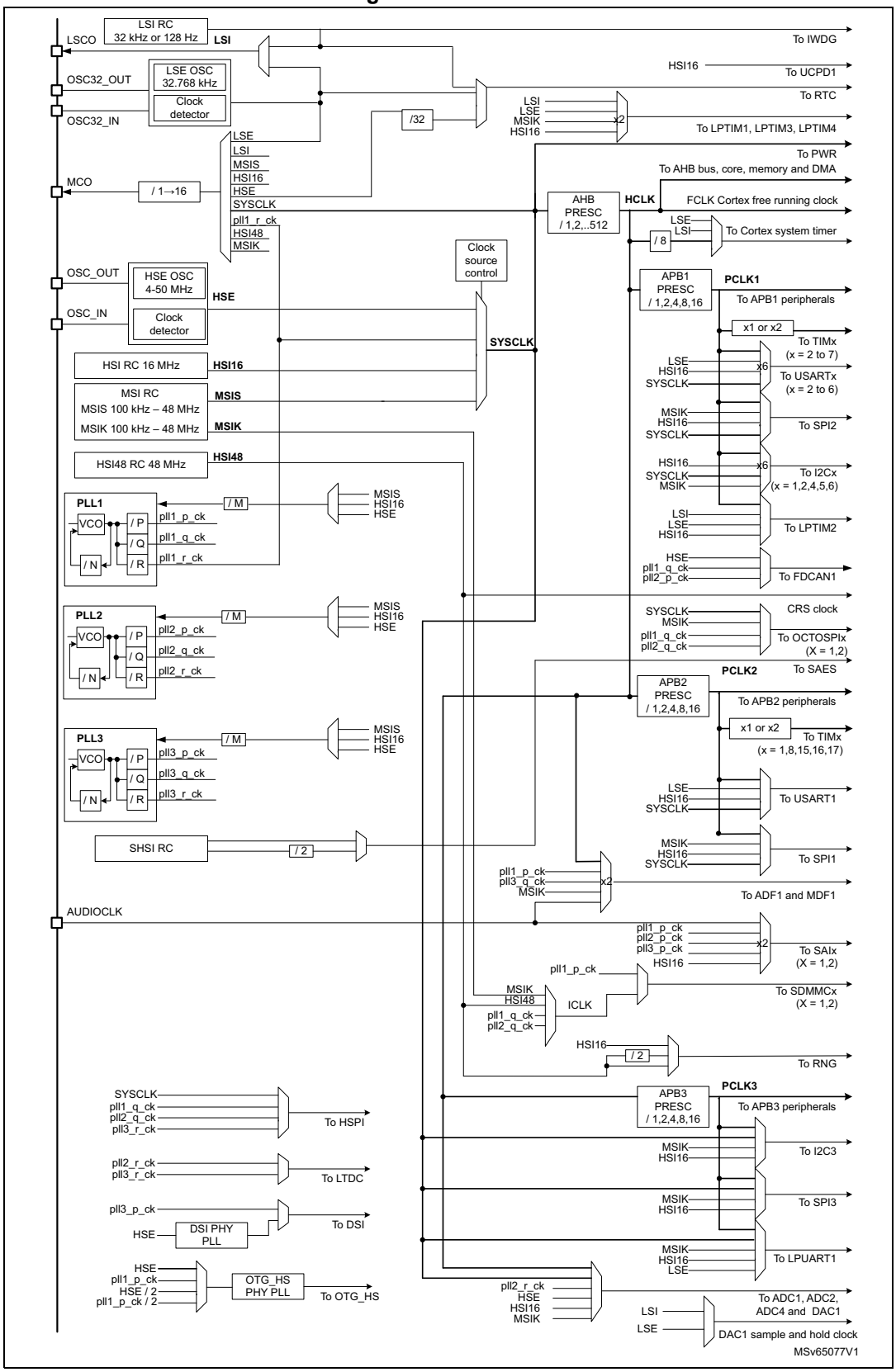
The RCC distributes the clocks coming from the different oscillators to the core and to the peripherals. It also manages the clock gating for low-power modes and ensures the clock robustness. It features:

- Clock prescaler: in order to get the best trade-off between speed and current consumption, the clock frequency to the CPU and peripherals can be adjusted by a programmable prescaler.
- Clock security system: clock sources can be changed safely on-the-fly in Run mode through a configuration register.
- Clock management: in order to reduce the power consumption, the clock controller can stop the clock to the core, individual peripherals or memory.
- System clock source: four different clock sources can be used to drive the master clock SYSCLK:
  - HSE (4 to 50 MHz high-speed external crystal or ceramic resonator) that can supply a PLL. The HSE can also be configured in bypass mode for an external clock.
  - HSI16 (16 MHz high-speed internal RC oscillator) trimmable by software, that can supply a PLL.
  - MSI (multispeed internal RC oscillator) trimmable by software, that can generate 16 frequencies from 100 kHz to 48 MHz. When a 32.768 kHz clock source is available in the system (LSE), the MSI frequency can be automatically trimmed by hardware to reach better than ±0.25% accuracy. The MSI can supply a PLL.
  - System PLL that can be fed by HSE, HSI16 or MSI, with a maximum frequency at 160 MHz.
- HSI48 (RC48 with clock recovery system) internal 48 MHz clock source that can be used to drive the USB, the SDMMC or the RNG peripherals. This clock can be output on the MCO.
- UCPD kernel clock, derived from HSI16 clock. The HSI16 RC oscillator must be enabled prior to the UCPD kernel clock use.

- Auxiliary clock source: two ultra-low-power clock sources that can be used to drive the real-time clock:
  - LSE (32.768 kHz low-speed external crystal), supporting three drive capability modes. The LSE can also be configured in bypass mode for an external clock.
  - LSI (32 kHz low-speed internal RC), also used to drive the independent watchdog. The LSI clock accuracy is ±5% accuracy. The LSI clock can be divided by 128 to output a 250 Hz as source clock.
- Peripheral clock sources: several peripherals have their own independent clock whatever the system clock. Three PLLs, each having three independent outputs allowing the highest flexibility, can generate independent clocks for the ADC, USB, SDMMC, RNG, MDF, ADF, FDCAN1, OCTOSPIs, HSPI, LTDC, DSI and SAIs.
- Startup clock: after reset, the microcontroller restarts by default with MSI. The prescaler ratio and clock source can be changed by the application program as soon as the code execution starts.
- CSS (clock security system): this feature can be enabled by software. If a HSE clock failure occurs, the master clock automatically switches to HSI16 and a software interrupt is generated if enabled. LSE failure can also be detected and generates an interrupt.
- Clock-out capability:
  - MCO (microcontroller clock output): it outputs one of the internal clocks for external use by the application.
  - LSCO (low-speed clock output): it outputs LSI or LSE in all low-power modes (except V_{BAT} mode).

Several prescalers allow AHB and APB frequencies configuration. The maximum frequency of the AHB and the APB clock domains is 160 MHz.

Figure 5. Clock tree



3.11.1 RCC TrustZone security

When the TrustZone security is activated by the TZEN option bit, the RCC is switched in TrustZone security mode.

The RCC TrustZone security secures some RCC system configuration and peripheral configuration clock from being read or modified by nonsecure accesses: when a peripheral is secure, the related peripheral clock, reset, clock source selection and clock enable during low-power modes control bits are secure.

A peripheral is in secure state:

- when its corresponding SEC security bit is set in the TZSC (TrustZone security controller), for securable peripherals.
- when a security feature of this peripheral is enabled through its dedicated bits, for TrustZone-aware peripherals.

3.12 Clock recovery system (CRS)

The devices embed a special block that allows automatic trimming of the internal 48 MHz oscillator to guarantee its optimal accuracy over the whole device operational range. This automatic trimming is based on the external synchronization signal, that is either derived from LSE oscillator, from an external signal on CRS_SYNC pin or generated by user software. For faster lock-in during startup, automatic trimming and manual trimming action can be combined.

3.13 General-purpose inputs/outputs (GPIOs)

Each of the GPIO pins can be configured by software as output (push-pull or open-drain), as input (with or without pull-up or pull-down) or as peripheral alternate function. Most of the GPIO pins are shared with digital or analog alternate functions.

After reset, all GPIOs are in analog mode to reduce power consumption.

The I/Os alternate function configuration can be locked if needed following a specific sequence in order to avoid spurious writing to the I/Os registers.

3.13.1 GPIOs TrustZone security

Each I/O pin of GPIO port can be individually configured as secure. When the selected I/O pin is configured as secure, its corresponding configuration bits for alternate function, mode selection, I/O data are secure against a nonsecure access. The associated registers bit access is restricted to a secure software only. After reset, all GPIO ports are secure.

3.14 Low-power general-purpose inputs/outputs (LPGPIO)

The LPGPIO allows dynamic I/O control in Stop 2 mode thanks to LPDMA1. Up to 16 I/Os can be configured and controlled as input or output (open-drain or push-pull depending on GPIO configuration).

3.14.1 LPGPIO TrustZone security

Each I/O pin registers bit of the LPGPIO is configured as secure if the corresponding I/O is configured as secure in the GPIO.

3.15 Multi-AHB bus matrix

A 32-bit multi-AHB bus matrix interconnects all the master (CPU, DMA2D, GFXMMU, GPDMA1, GPU2D, LTDC, OTG_HS, SDMMC1, SDMMC2) and the slave (flash memory, FMC, HSPI, OCTOSPIs, SRAMs, AHB and APB) peripherals. It also ensures a seamless and efficient operation even when several high-speed peripherals work simultaneously.

Another multi-AHB bus matrix interconnects two masters (previous AHB bus matrix slave port and LPDMA1) and all slaves that are functional in Stop 2 modes (SRAM4 and AHB/APB peripherals functional in Stop 2 mode).

3.16 System configuration controller (SYSCFG)

The STM32U5Axxx devices feature a set of configuration registers. The main purposes of the system configuration controller are the following:

- Managing robustness feature
- Configuring FPU interrupts
- Enabling/disabling the FMP high-drive mode of some I/Os and voltage booster for I/Os analog switches
- Managing the I/O compensation cell
- Configuring register security access
- Configuring the OTG_HS PHY
- Adjust the HSPI supply capacitance
- Disable internal SRAMs cacheability by DCACHE2

3.17 General purpose direct memory access controller (GPDMA)

The general purpose direct memory access (GPDMA) controller is a bus master and system peripheral.

The GPDMA is used to perform programmable data transfers between memory-mapped peripherals and/or memories via linked-lists, upon the control of an off-loaded CPU.

The GPDMA main features are:

- Dual bidirectional AHB master
- Memory-mapped data transfers from a source to a destination:
  - Peripheral-to-memory
  - Memory-to-peripheral
  - Memory-to-memory
  - Peripheral-to-peripheral
- Autonomous data transfers during Sleep and Stop modes

- Transfers arbitration based on a four-grade programmed priority at a channel level:
  - One high-priority traffic class, for time-sensitive channels (queue 3)
  - Three low-priority traffic classes, with a weighted round-robin allocation for non time-sensitive channels (queues 0, 1, 2)
- Per channel event generation, on any of the following events: transfer complete or half transfer complete or data transfer error or user setting error, and/or update linked-list item error or completed suspension
- Per channel interrupt generation, with separately programmed interrupt enable per event
- 16 concurrent DMA channels:
  - Per channel FIFO for queuing source and destination transfers
  - Intra-channel DMA transfers chaining via programmable linked-list into memory, supporting two execution modes: run-to-completion and link step mode
  - Intra-channel and inter-channel DMA transfers chaining via programmable DMA input triggers connection to DMA task completion events
- Per linked-list item within a channel:
  - Separately programmed source and destination transfers
  - Programmable data handling between source and destination: byte-based reordering, packing or unpacking, padding or truncation, sign extension and left/right realignment
  - Programmable number of data bytes to be transferred from the source, defining the block level
  - 12 channels with linear source and destination addressing: either fixed or contiguously incremented addressing, programmed at a block level, between successive single transfers
  - Four channels with 2D source and destination addressing: programmable signed address offsets between successive burst transfers (non-contiguous addressing within a block, combined with programmable signed address offsets between successive blocks, at a second 2D/repeated block level)
  - Support for scatter-gather (multi-buffer transfers), data interleaving and deinterleaving via 2D addressing
  - Programmable DMA request and trigger selection
  - Programmable DMA half-transfer and transfer complete events generation
  - Pointer to the next linked-list item and its data structure in memory, with automatic update of the DMA linked-list control registers
- Debug:
  - Channel suspend and resume support
  - Channel status reporting including FIFO level and event flags
- TrustZone support:
  - Support for secure and nonsecure DMA transfers, independently at a first channel level, and independently at a source/destination and link sub-levels
  - Secure and nonsecure interrupts reporting, resulting from any of the respectively secure and nonsecure channels
  - TrustZone-aware AHB slave port, protecting any DMA secure resource (register, register field) from a nonsecure access

- Privileged/unprivileged support:
  - Support for privileged and unprivileged DMA transfers, independently at channel level
  - Privileged-aware AHB slave port.

Table 11. GPDMA1 channels implementation and usage

Channel x	Hardware parameters		Features
	dma_fifo_ size[x]	dma_ addressing[x]	
x = 0 to 11	2	0	Channel x (x = 0 to 11) is implemented with: – a FIFO of 8 bytes, 2 words – fixed/contiguously incremented addressing These channels may be also used for GPDMA transfers, between an APB or AHB peripheral and SRAM.
x = 12 to 15	4	1	Channel x (x = 12 to 15) is implemented with: – a FIFO of 32 bytes, 8 words – 2D addressing These channels may be also used for GPDMA transfers, between a demanding AHB peripheral and SRAM, or for transfers from/to external memories.

Table 12. GPDMA1 autonomous mode and wake-up in low-power modes

Feature	Low-power modes
Autonomous mode and wake-up	GPDMA1 in Sleep, Stop 0 and Stop 1 modes

3.18 Low-power direct memory access controller (LPDMA)

The LPDMA controller is a bus master and system peripheral. The LPDMA is used to perform programmable data transfers between memory-mapped peripherals and/or memories via linked-lists, upon the control of an off-loaded CPU.

The LPDMA main features are:

- Single bidirectional AHB master
- Memory-mapped data transfers from a source to a destination:
  - Peripheral-to-memory
  - Memory-to-peripheral
  - Memory-to-memory
  - Peripheral-to-peripheral
- Autonomous data transfers during Sleep and Stop modes
- Transfers arbitration based on a 4-grade programmed priority at channel level:
  - One high-priority traffic class, for time-sensitive channels (queue 3)
  - Three low-priority traffic classes, with a weighted round-robin allocation for non time-sensitive channels (queues 0, 1, 2)

- Per channel event generation, on any of the following events: transfer complete, or half-transfer complete, or data transfer error, or user setting error, and/or update linked-list item error, or completed suspension
- Per channel interrupt generation, with separately programmed interrupt enable per event
- Four concurrent DMA channels:
  - Intra-channel DMA transfers chaining via programmable linked-list into memory, supporting two execution modes: run-to-completion and link step mode
  - Intra-channel and inter-channel DMA transfers chaining via programmable DMA input triggers connection to DMA task completion events
- Per linked-list item within a channel:
  - Separately programmed source and destination transfers
  - Programmable data handling between source and destination: byte-based padding or truncation, sign extension and left/right realignment
  - Programmable number of data bytes to be transferred from the source, defining the block level
  - Linear source and destination addressing: either fixed or contiguously incremented addressing, programmed at a block level, between successive single transfers
  - Programmable DMA request and trigger selection
  - Programmable DMA half-transfer and transfer complete events generation
  - Pointer to the next linked-list item and its data structure in memory, with automatic update of the DMA linked-list control registers
- Debug:
  - Channel suspend and resume support
  - Channel status reporting and event flags
- TrustZone support
  - Support for secure and nonsecure DMA transfers, independently at a first channel level, and independently at a source/destination and link sub-levels
  - Secure and nonsecure interrupts reporting, resulting from any of the respectively secure and nonsecure channels
  - TrustZone-aware AHB slave port, protecting any DMA secure resource (register, register field) from a nonsecure access
- Privileged/unprivileged support:
  - Support for privileged and unprivileged DMA transfers, independently at channel level
  - Privileged-aware AHB slave port.

Table 13.LPDMA1 channels implementation and usage

Channel x	Hardware parameters		Features
	dma_fifo_ size[x]	dma_ addressing[x]	
x = 0 to 3	0	0	Channel x (x = 0 to 3) is implemented with: – no FIFO. Only a single source transfer cell is internally registered. – fixed/contiguously incremented addressing

Table 14. LPDMA1 autonomous mode and wake-up in low-power modes

Feature	Low-power modes
Autonomous mode and wake-up	LPDMA1 in Sleep, Stop 0, Stop 1 and Stop 2 modes

3.19 Neo-Chrom GPU (GPU2D)

The Neo-Chrom GPU is accelerating operations for graphic effects like rotation, scaling, and perspective correct texture mapping (2.5D). It works together with an optimized software stack designed for state of the art graphic rendering.

The GPU2D main features are:

- Multi-threaded fragment (pixel) processing core with a VLIW (very-long instruction word) instruction set
- Fixed point functional units
- Command list based DMAs to minimize CPU overhead
- Two 32-bit AHB master interfaces for texture, command list and framebuffer access
- 32-bit AHB slave interface for register bank access
- Up to 4 general-purpose flags for system-level synchronization
- Texture decompression unit with TSC™4 and TSC™6/TSC™6a support

The GPU2D also features:

- 2D drawing
  - Pixel/line drawing
  - Filled rectangles
  - Triangles, quadrilateral drawing
  - Anti-aliasing 8xMSAA (multi-sample anti-aliasing)
- Image transformations
  - 3D perspective correct projections
  - Texture mapping with bilinear filtering or point sampling
- Blit support
  - Rotation, mirroring, stretching (independently on x and y axis)
  - Source and/or destination color keying
  - Pixel format conversions

- Text rendering support
  - A1, A2, A4 and A8 bitmap anti-aliased
  - Subsampled anti-aliased
- Color formats
  - RGB, grayscale
  - 32, 24, 16 and 8 bits with/without alpha
- Full alpha blending with hardware blender
  - Programmable blending modes
  - Source/destination color keying

3.20 Chrom-ART Accelerator controller (DMA2D)

The Chrom-ART Accelerator (DMA2D) is a specialized DMA dedicated to image manipulation. It can perform the following operations:

- Filling a part or the whole of a destination image with a specific color
- Copying a part or the whole of a source image into a part or the whole of a destination image
- Copying a part or the whole of a source image into a part or the whole of a destination image with a pixel format conversion
- Blending a part and/or two complete source images with different pixel format and copy the result into a part or the whole of a destination image with a different color format.

All the classical color coding schemes are supported from 4-bit up to 32-bit per pixel with indexed or direct color mode. The DMA2D has its own dedicated memories for CLUTs (color look-up tables).

The main DMA2D features are:

- Single AHB master bus architecture
- AHB slave programming interface supporting 8/16/32-bit accesses (except for CLUT accesses that are 32-bit)
- User programmable working area size
- User programmable offset for sources and destination areas expressed in pixels or bytes expressed in pixels or bytes
- User programmable sources and destination addresses on the whole memory space
- Up to two sources with blending operation
- Alpha value can be modified (source value, fixed value or modulated value)
- User programmable source and destination color format
- Up to 11 color formats supported from 4-bit up to 32-bit per pixel with indirect or direct color coding
- Two internal memories for CLUT storage in indirect color mode
- Automatic CLUT loading or CLUT programming via the CPU
- User programmable CLUT size
- Internal timer to control AHB bandwidth
- Six operating modes: register-to-memory, memory-to-memory, memory-to-memory with pixel format conversion, memory-to-memory with pixel format conversion and blending, memory-to memory with pixel format conversion, blending and fixed color

foreground, and memory-to memory with pixel format conversion, blending and fixed color background
- Area filling with a fixed color
- Copy from an area to another
- Copy with pixel format conversion between source and destination images
- Copy from two sources with independent color format and blending
- Output buffer byte swapping to support refresh of displays through parallel interface
- Abort and suspend of DMA2D operations
- Watermark interrupt on a user programmable destination line
- Interrupt generation on bus error or access conflict
- Interrupt generation on process completion

3.21 Chrom-GRC (GFXMMU)

The GFXMMU is a graphical oriented memory management unit aimed to:
- Optimize memory usage according to the display shape
- Cache linear accesses to the frame buffer
- Prefetch data

The GFXMMU main features are:
- Fully programmable display shape to physically store only the visible pixel
- Up to 4 virtual buffers
- Each virtual buffer have 3072 or 4096 bytes per line and 1024 lines
- Each virtual buffer can be physically mapped to any system memory
- Optional cache for linear accesses
- Cache can be locked to a virtual buffer
- Cache prefetch mechanism for linear accesses anticipation
- Interrupt in case of buffer overflow (1 per buffer)
- Interrupt in case of memory transfer error

3.22 Interrupts and events

3.22.1 Nested vectored interrupt controller (NVIC)

The devices embed a NVIC that is able to manage 16 priority levels and to handle up to 138 maskable interrupt channels plus the 16 interrupt lines of the Cortex-M33.

The NVIC benefits are the following:
- closely coupled NVIC giving low-latency interrupt processing
- interrupt entry vector table address passed directly to the core
- early processing of interrupts
- processing of late arriving higher priority interrupts
- support for tail chaining
- processor state automatically saved

- interrupt entry restored on interrupt exit with no instruction overhead
- TrustZone support: NVIC registers banked across secure and nonsecure states

The NVIC hardware block provides flexible interrupt management features with minimal interrupt latency.

3.22.2 Extended interrupt/event controller (EXTI)

The EXTI manages the individual CPU and system wake-up through configurable event inputs. It provides wake-up requests to the power control, and generates an interrupt request to the CPU NVIC and events to the CPU event input. For the CPU an additional event generation block (EVG) is needed to generate the CPU event signal.

The EXTI wake-up requests allow the system to be woken up from Stop modes.

The interrupt request and event request generation can also be used in Run modes. The EXTI also includes the EXTI multiplexer I/O port selection.

The EXTI main features are the following:

- All event inputs allowed to wake up the system
- Configurable events (signals from I/Os or peripherals able to generate a pulse)
  - Selectable active trigger edge
  - Interrupt pending status register bit independent for the rising and falling edge
  - Individual interrupt and event generation mask, used for conditioning the CPU wake-up, interrupt and event generation
  - Software trigger possibility
- TrustZone secure events
  - The access to control and configuration bits of secure input events can be made secure
- EXTI I/O port selection

3.23 Cyclic redundancy check calculation unit (CRC)

The CRC is used to get a CRC code using a configurable generator with polynomial value and size.

Among other applications, the CRC-based techniques are used to verify data transmission or storage integrity. In the scope of the EN/IEC 60335-1 standard, they offer a mean to verify the flash memory integrity.

The CRC calculation unit helps to compute a signature of the software during runtime, that can be ulteriorly compared with a reference signature generated at link-time and that can be stored at a given memory location.

3.24 CORDIC co-processor (CORDIC)

The CORDIC co-processor provides hardware acceleration of certain mathematical functions, notably trigonometric, commonly used in motor control, metering, signal processing and many other applications. It speeds up the calculation of these functions compared to a software implementation, allowing a lower operating frequency, or freeing up processor cycles in order to perform other tasks.

The CORDIC main features are:

- 24-bit CORDIC rotation engine
- Circular and hyperbolic modes
- Rotation and vectoring modes
- Functions: sine, cosine, sinh, cosh, atan, atan2, atanh, modulus, square root, natural logarithm
- Programmable precision
- Low-latency AHB slave interface
- Results can be read as soon as ready without polling or interrupt
- DMA read and write channels
- Multiple register read/write by DMA

3.25 Filter math accelerator (FMAC)

The FMAC performs arithmetic operations on vectors. It comprises a MAC (multiplier/accumulator) unit, together with address generation logic that allows it to index vector elements held in local memory.

The unit includes support for circular buffers on input and output, that allows digital filters to be implemented. Both finite and infinite impulse response filters can be done.

The unit allows frequent or lengthy filtering operations to be offloaded from the CPU, freeing up the processor for other tasks. In many cases it can accelerate such calculations compared to a software implementation, resulting in a speed-up of time critical tasks.

The FMAC main features are:

- 16 x 16-bit multiplier
- 24 + 2-bit accumulator with addition and subtraction
- 16-bit input and output data
- 256 x 16-bit local memory
- Up to three areas can be defined in memory for data buffers (two input, one output), defined by programmable base address pointers and associated size registers
- Input and output buffers can be circular
- Filter functions: FIR, IIR (direct form 1)
- Vector functions: dot product, convolution, correlation
- AHB slave interface
- DMA read and write data channels

3.26 Flexible static memory controller (FSMC)

The FSMC includes two memory controllers:

- NOR/PSRAM memory controller
- NAND/memory controller

The FSMC is also named flexible memory controller (FMC).

The main features of the FSMC are the following:

- Interface with static-memory mapped devices including:
  - Static random access memory (SRAM)
  - NOR flash memory/OneNAND flash memory
  - PSRAM (four memory banks)
  - NAND flash memory with ECC hardware to check up to 8 Kbytes of data
  - Ferroelectric RAM (FRAM)
- 8-,16- bit data bus width
- Independent chip select control for each memory bank
- Independent configuration for each memory bank
- Write FIFO

3.26.1 LCD parallel interface

The FSMC can be configured to interface seamlessly with most graphic LCD controllers. It supports the Intel® 8080 and Motorola® 6800 modes, and is flexible enough to adapt to specific LCD interfaces.

This LCD parallel interface capability makes it easy to build cost effective graphic applications using LCD modules with embedded controllers or high-performance solutions using external controllers with dedicated acceleration.

3.26.2 FSMC TrustZone security

When the TrustZone security is enabled, the whole FSMC banks are secure after reset. Nonsecure area can be configured using the TZSC MPCWMx controller:

- FSMC NOR/PSRAM bank:
  - Up to two nonsecure area can be configured thought the TZSC MPCWM2 controller with a 64-Kbyte granularity
- FSMC NAND bank:
  - Can be either configured as fully secure or fully nonsecure using the TZSC MPCWM3 controller

The FSMC registers can be configured as secure through the TZSC controller.

3.27 Octo-SPI interface (OCTOSPI)

The devices embed two OCTOSPIs. The OCTOSPI supports most external serial memories such as serial PSRAMs, serial NAND and serial NOR Flash memories, HyperRAMs™ and HyperFlash™ memories, with the following functional modes:

- Indirect mode: all the operations are performed using the OCTOSPI registers.
- Status-polling mode: the external memory status register is periodically read and an interrupt can be generated in case of flag setting.
- Memory-mapped mode: the external memory is memory mapped and is seen by the system as if it were an internal memory supporting read and write operation.

The OCTOSPI supports the following protocols with associated frame formats:

- the standard frame format with the command, address, alternate byte, dummy cycles and data phase
- the HyperBus™ frame format

The OCTOSPI offers the following features:

- Three functional modes: Indirect, Status-polling, and Memory-mapped
- Read and write support in Memory-mapped mode
- Supports for single, dual, quad and octal communication
- Dual-quad mode, where eight bits can be sent/received simultaneously by accessing two quad memories in parallel.
- SDR (single-data rate) and DTR (double-transfer rate) support
- Data strobe support
- Fully programmable opcode
- Fully programmable frame format
- HyperBus support
- Integrated FIFO for reception and transmission
- 8-, 16-, and 32-bit data accesses allowed
- DMA channel for Indirect mode operations
- Interrupt generation on FIFO threshold, timeout, operation complete, and access error

3.27.1 OCTOSPI TrustZone security

When the TrustZone security is enabled, the whole OCTOSPI bank is secure after reset.

Up to two nonsecure area can be configured thought the TZSC MPCWM1 and MPCWM5 controllers with a granularity of 64 Kbytes.

The OCTOSPI registers can be configured as secure through the TZSC controller.

3.28 OCTOSPI I/O manager (OCTOSPIM)

The OCTOSPI I/O manager is a low-level interface enabling:

- efficient OCTOSPI pin assignment with a full I/O matrix (before alternate function map)
- multiplex of Single-, Dual-, Quad-, Octal-SPI interfaces over the same bus and hence support memories embedded in a multichip package

The OCTOSPIM main features are:

- Supports up to two Single-, Dual-, Quad-, Octal-SPI interfaces
- Supports up to two ports for pin assignment
- Fully programmable I/O matrix for pin assignment by function (data/control/clock)

3.29 Delay block (DLYB)

The delay block (DLYB) is used to generate an output clock that is dephased from the input clock. The phase of the output clock must be programmed by the user application. The output clock is then used to clock the data received by another peripheral such as

a SDMMC or Octo-SPI interface. The delay is voltage and temperature dependent, that may require the application to re-configure and recenter the output clock phase with the received data.

The delay block main features are:

- Input clock frequency ranging from 25 to 160 MHz
- Up to 12 oversampling phases

3.30 Hexadeca-SPI interface (HSPI)

The HSPI supports most external serial memories such as serial PSRAMs, serial NAND and serial NOR Flash memories, HyperRAMs and HyperFlash memories, with the following functional modes:

- Indirect mode: all the operations are performed using the HSPI registers.
- Status polling mode: the external memory status register is periodically read and an interrupt can be generated in case of flag setting.
- Memory-mapped mode: the external memory is memory mapped and is seen by the system as if it were an internal memory supporting read and write operation.

The HSPI supports the following protocols with associated frame formats:

- the standard frame format with the command, address, alternate byte, dummy cycles and data phase
- the HyperBus frame format

The HSPI offers the following features:

- Three functional modes: Indirect, Status-polling, and Memory-mapped
- Read and write support in Memory-mapped mode
- Support for single, dual, quad, octal and hexadeca communication
- Dual-quad mode, where eight bits can be sent/received simultaneously by accessing two quad or two octal memories in parallel
- SDR (single-data rate) and DTR (double-transfer rate) support
- Data strobe support
- Fully programmable opcode
- Fully programmable frame format
- Support wrapped-type access to memory in read direction
- HyperBus support
- Integrated FIFO for reception and transmission
- 8-, 16-, and 32-bit data accesses allowed
- DMA channel for Indirect mode operations
- Interrupt generation on FIFO threshold, timeout, operation complete, and access error
- High-speed interface up to 160MHz

3.30.1 HSPI TrustZone security

When the TrustZone security is enabled, the whole HSPI bank is secure after reset.

Up to two nonsecure areas can be configured thought the TZSC MPCWM6 controller with a granularity of 64 Kbytes.

The HSPI registers can be configured as secure through the TZSC controller.

3.31 Analog-to-digital converters (ADC1, ADC2, and ADC4)

The devices embed three successive approximation analog-to-digital converters.

Table 15. ADC features

ADC modes/features[1]	ADC1	ADC2	ADC4
Resolution	14 bits		12 bits
Maximum sampling speed for maximum resolution	2.5 Msps		
Hardware offset calibration	X		
Hardware linearity calibration	X		-
Single-ended inputs	X		
Differential inputs	X		-
Injected channel conversion	X		-
Oversampling	up to x1024		up to x256
Data register	32 bits		16 bits
DMA support	X		
Parallel data output to MDF	X		-
Dual mode	X		-
Autonomous mode	-		X
Offset compensation	X		-
Gain compensation	X		-
Number of analog watchdogs	3		
Wake-up from Stop mode	-		X[2]

1. X = supported.
2. wake-up supported from Stop 0, Stop 1 and Stop 2 modes.

3.31.1 Analog-to-digital converters (ADC1/2)

The ADC1/2 are 14-bit ADC successive approximation analog-to-digital converters.

Each ADC has up to 20 multiplexed channels. A/D conversion of the various channels can be performed in Single, Continuous, Scan or Discontinuous mode. The result of the ADC is stored in a left-aligned or right-aligned 32-bit data register.

The ADC1/2 are mapped on the AHB bus to allow fast data handling. The analog watchdog features allow the application to detect if the input voltage goes outside the user-defined high or low thresholds.

A built-in hardware over sampler allows analog performances to be improved while off-loading the related computational burden from the CPU.

An efficient low-power mode is implemented to allow very low consumption at low frequency.
The ADC1/2 main features are:

- High-performance features
  - Dual mode operation
  - 14-, 12-, 10- or 8-bit configurable resolution
  - A/D conversion time independent from the AHB bus clock frequency
  - Faster conversion time by lowering resolution
  - Management of single-ended or differential inputs (programmable per channels)
  - Fast data handling thanks to the AHB slave bus interface
  - Self-calibration (both offset and linearity)
  - Channel-wise programmable sampling time
  - Flexible sampling time control
  - Up to four injected channels (analog inputs assignment to regular or injected channels is fully configurable)
  - Fast context switching thanks to the hardware assistant that prepares the context of the injected channels
  - Data alignment with in-built data coherency
  - Data can be managed by GPDMA for regular channel conversions with FIFO
  - Data can be routed to MDF for post processing
  - Four dedicated data registers for the injected channels
- Oversampler
  - 32-bit data register
  - Oversampling ratio adjustable from 2 to 1024
  - Programmable data right and left shift
- Data preconditioning
  - Gain compensation
  - Offset compensation
- Low-power features
  - Speed adaptive low-power mode to reduce ADC consumption when operating at low frequency
  - Slow bus frequency application while keeping optimum ADC performance
  - Automatic control to avoid ADC overrun in low AHB bus clock frequency application (auto-delayed mode)
- ADC features an external analog input channel:
  - Up to 17 channels from dedicated GPIO pads
- Three additional internal dedicated channels:
  - One channel for internal reference voltage (V_{REFINT})
  - One channel for internal temperature sensor (V_{SENSE})
  - One channel for V_{BAT} monitoring channel ($V_{BAT}/4$)
- Start-of-conversion can be initiated:
  - by software for both regular and injected conversions

  - by hardware triggers with configurable polarity (internal timers events or GPIO input events) for both regular and injected conversions
- Conversion modes
  - Single mode: the ADC converts a single channel. The conversion is triggered by a special event.
  - Scan mode: the ADC scans and converts a sequence of channels.
  - Continuous mode: the ADC converts continuously selected inputs.
  - Discontinuous mode: the ADC converts a subset of the conversion sequence.
- Interrupt generation when the ADC is ready, at end of sampling, end of conversion (regular or injected), end of sequence conversion (regular or injected), analog watchdog 1, 2 or 3 or when an overrun event occurs
- Three analog watchdogs
  - Filtering to ignore out-of-range data
- ADC input range: $V_{SSA} < V_{IN} < V_{REF+}$

Note: The ADC1/2 analog block clock frequency must be between 5 MHz and 55 MHz.

3.31.2 Analog-to-digital converter 4 (ADC4)

The 12-bit ADC4 is a successive approximation analog-to-digital converter. It has up to 25 multiplexed channels allowing it to measure signals from 19 external and six internal sources. A/D conversion of the various channels can be performed in Single, Continuous, Scan or Discontinuous mode. The result of the ADC is stored in a left-aligned or right-aligned 16-bit data register.

The analog watchdog feature allows the application to detect if the input voltage goes outside the user-defined higher or lower thresholds.

An efficient low-power mode is implemented to allow very low consumption at low frequency. The ADC4 is autonomous in low-power modes down to Stop 2 mode.

A built-in hardware oversampler allows analog performances to be improved while off-loading the related computational burden from the CPU.

The ADC4 main features are:

- High performance
  - 12-, 10-, 8- or 6-bit configurable resolution
  - A/D conversion time: 0.4 µs for 12-bit resolution (2.5 MHz), faster conversion times obtained by lowering resolution
  - Self-calibration
  - Programmable sampling time
  - Data alignment with built-in data coherency
  - DMA support
- Low-power
  - HCLK frequency reduced for low-power operation while still keeping optimum ADC performance
  - Wait mode: ADC overrun prevented in applications with low frequency HCLK
  - Auto-off mode: ADC automatically powered off except during the active conversion phase, dramatically reducing the ADC power consumption

  - Autonomous mode: In low-power modes down to Stop 2 mode, the ADC4 is automatically switched on when a trigger occurs to start conversion, and it is automatically switched off after conversion. Data are transfered in SRAM with DMA.
  - ADC4 interrupts wake up the device from Stop 0, Stop 1 and Stop 2 modes.
- Analog input channels
  - Up to 19 external analog inputs
  - One channel for the internal temperature sensor (VSENSE)
  - One channel for the internal reference voltage (VREFINT)
  - One channel for the internal digital core voltage (VCORE)
  - One channel for monitoring the external VBAT power supply pin
  - Connection to two DAC internal channels
- Start-of-conversion can be initiated:
  - By software
  - By hardware triggers with configurable polarity (timer events or GPIO input events)
- Conversion modes
  - Conversion of a single channel or scan of a sequence of channels
  - Selected inputs converted once per trigger in Single mode
  - Selected inputs converted continuously in Continuous mode
  - Discontinuous mode
- Interrupt generation at the end of sampling, end of conversion, end of sequence conversion, and in case of analog watchdog or overrun events, with wake-up from Stop capability
- Analog watchdog
- Oversampler
  - 16-bit data register
  - Oversampling ratio adjustable from 2 to 256
  - Programmable data shift up to 8 bits
- ADC supply requirements: 1.62 to 3.6 V
- ADC input range: $V_{SSA} < V_{IN} < V_{REF+}$

Note: The ADC4 analog block clock frequency must be between 140 kHz and 55 MHz.

3.31.3 Temperature sensor

The temperature sensor generates a voltage V_{SENSE} that varies linearly with temperature. The temperature sensor is internally connected to ADC1, ADC2 and ADC4 input channel that is used to convert the sensor output voltage into a digital value.

The sensor provides good linearity but it must be calibrated to obtain a good accuracy of the temperature measurement. As the offset of the temperature sensor varies from chip to chip due to process variation, the uncalibrated internal temperature sensor is suitable for applications that detect temperature changes only.

To improve the accuracy of the temperature sensor measurement, each device is individually factory-calibrated by ST. The temperature sensor factory calibration data are stored by STMicroelectronics in the system memory area, accessible in read-only mode.

Table 16. Temperature sensor calibration values

Calibration value name	Description	Memory address
TS_CAL1	Temperature sensor 14-bit raw data acquired by ADC1 at 30 °C (± 5 °C), $V_{DDA} = V_{REF+}$ = 3.0 V (± 10 mV)	0x0BFA 0710 - 0x0BFA 0711
TS_CAL2	Temperature sensor 14-bit raw data acquired by ADC1 at 130 °C (± 5 °C), $V_{DDA} = V_{REF+}$ = 3.0 V (± 10 mV)	0x0BFA 0742 - 0x0BFA 0743

3.31.4 Internal voltage reference (V_{REFINT})

The VREFINT provides a stable (bandgap) voltage output for the ADC and the comparators. The VREFINT is internally connected to ADC1, ADC2 and ADC4 input channels.

The precise voltage of VREFINT is individually measured for each part by STMicroelectronics during production test and stored in the system memory area. It is accessible in read-only mode.

Table 17. Internal voltage reference calibration values

Calibration value name	Description	Memory address
VREFINT_CAL	14-bit raw data acquired by ADC1 at 30 °C (± 5 °C), $V_{DDA} = V_{REF+}$ = 3.0 V (± 10 mV)	0x0BFA 07A5 - 0x0BFA 07A6

3.31.5 V_{BAT} battery voltage monitoring

This embedded hardware enables the application to measure the V_{BAT} battery voltage using ADC1, ADC2 or ADC4 input channel. As the V_{BAT} voltage may be higher than the V_{DDA}, and thus outside the ADC input range, the VBAT pin is internally connected to a bridge divider by four. As a consequence, the converted digital value is a quarter of the V_{BAT} voltage.

3.32 Digital to analog converter (DAC)

The DAC module is a 12-bit, voltage output digital-to-analog converter. The DAC can be configured in 8- or 12-bit mode and may be used in conjunction with the DMA controller. In 12-bit mode, the data may be left- or right-aligned.

The DAC features two output channels, each with its own converter. In dual DAC channel mode, conversions can be done independently or simultaneously when both channels are grouped together for synchronous update operations. An input reference pin, VREF+ (shared with others analog peripherals) is available for better resolution. An internal reference can also be set on the same input.

The DAC_OUTx pin can be used as general purpose input/output (GPIO) when the DAC output is disconnected from output pad and connected to on chip peripheral. The DAC output buffer can be optionally enabled to allow a high drive output current. An individual calibration can be applied on each DAC output channel. The DAC output channels support a low-power mode, the sample and hold mode.

The digital interface supports the following features:

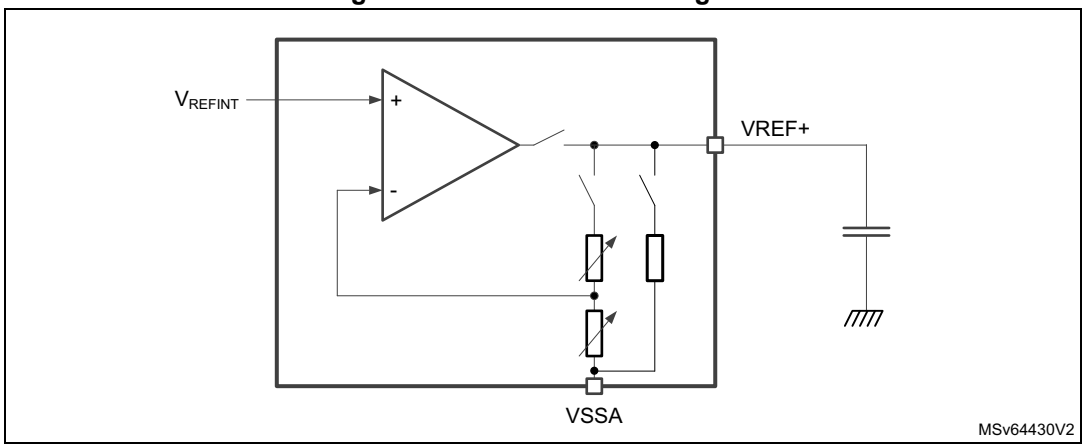
- One DAC interface, maximum two output channels

- Left or right data alignment in 12-bit mode
- Synchronized update capability
- Noise-wave and triangular-wave generation
- Sawtooth wave generation
- Dual DAC channel for independent or simultaneous conversions
- DMA capability for each channel including DMA underrun error detection
- Double data DMA capability to reduce the bus activity
- External triggers for conversion
- DAC output channel buffered/unbuffered modes
- Buffer offset calibration
- Each DAC output can be disconnected from the DAC_OUTx output pin
- DAC output connection to on chip peripherals
- Sample and hold mode for low-power operation in Stop mode. The DAC voltage can be changed autonomously with the DMA while the device is in Stop mode.
- Autonomous mode to reduce the power consumption for the system
- Voltage reference input

3.33 Voltage reference buffer (VREFBUF)

The devices embed a voltage reference buffer that can be used as voltage reference for ADCs, DACs and also as voltage reference for external components through the VREF+ pin.

Figure 6. VREFBUF block diagram



The internal voltage reference buffer supports four voltages: 1.5 V, 1.8 V, 2.048 V and 2.5 V.

An external voltage reference can be provided through the VREF+ pin when the internal voltage reference buffer is off.

The VREF+ pin is double-bonded with VDDA on some packages. In these packages the internal voltage reference buffer is not available.

3.34 Comparators (COMP)

The devices embed two rail-to-rail comparators with programmable reference voltage (internal or external), hysteresis and speed (low speed for low power) and with selectable output polarity.

The reference voltage can be one of the following:

- External I/O
- DAC output channels
- Internal reference voltage or submultiple (1/4, 1/2, 3/4)

All comparators can wake up from Stop 0, Stop 1 and Stop 2 modes, generate interrupts and breaks for the timers and can also be combined into a window comparator.

3.35 Operational amplifiers (OPAMP)

The devices embed two operational amplifiers with external or internal follower routing and PGA capability.

The operational amplifier features:

- Low-input bias current
- Low-offset voltage
- Low-power mode
- Rail-to-rail input

3.36 Multi-function digital filter (MDF) and audio digital filter (ADF)

The table below lists the set of features implemented into the MDF and the ADF.

Table 18. MDF features

MDF modes/features(1)	ADF1	MDF1
Number of filters (DFLTx) and serial interfaces (SITFx)	1	6
ADF_CKI0 / MDF_CKIy connected to pins	-	X
Sound activity detection (SAD)	X	-
RXFIFO depth (number of 24-bit words)	4	4
ADC connected to ADCITF1	-	ADC1
ADC connected to ADCITF2	-	ADC2
Motor dedicated features (SCD, OLD, OEC, INT, snapshot, break)	-	X
Main path with CIC4, CIC5	X	X
Main path with CIC1,2, 3 or FastSinc	-	X
RSFLT, HPF, SAT, SCALE, DLY, Discard functions	X	X
Autonomous in Stop mode	X(2)	X(3)

1. X = supported.
2. Stop 0, Stop 1 and Stop 2 modes only.
3. Stop 0 and Stop 1 modes only.

3.36.1 Multi-function digital filter (MDF)

The MDF is a high-performance module dedicated to the connection of external sigma-delta (ΣΔ) modulators. It is mainly targeted for the following applications:

- audio capture signals
- motor control
- metering

The MDF features six digital serial interfaces (SITFx) and digital filters (DFLTx) with flexible digital processing options to offer up to 24-bit final resolution.

The DFLTx of the MDF also include the filters of the ADF (audio digital filter).

The MDF can receive, via its serial interfaces, streams coming from various digital sensors.

The MDF supports the following standards allowing the connection of various ΣΔ modulator sensors:

- SPI interface
- Manchester coded 1-wire interface
- PDM interface

A flexible BSMX (bitstream matrix) allows the connection of any incoming bitstream to any filter.

The MDF converts an input data stream into clean decimated digital data words. This conversion is done thanks to low-pass digital filters and decimation blocks.In addition it is possible to insert a high-pass filter or DC offset correction block.

The conversion speed and resolution are adjustable according to configurable parameters for digital processing: filter type, filter order, decimation ratio, integrator length. The maximum output data resolution is up to 24 bits. There are two conversion modes: single conversion and continuous modes. The data can be automatically stored in a system RAM buffer through DMA, thus reducing the software overhead.

A flexible trigger interface can be used to control the conversion start. This timing control can trigger simultaneous conversions or insert a programmable delay between conversions.

The MDF features an OLD (out-off limit detectors) function. There is one OLD for each digital filter chain. Independent programmable thresholds are available for each OLD, making it very suitable for over-current detection.

A SCD (short circuit detector) is also available for every selected bitstream. The SCD is able to detect a short-circuit condition with a very short latency. Independent programmable thresholds are offered in order to define the short circuit condition.

All the digital processing is performed using only the kernel clock. The MDF requests the bus interface clock (AHB clock) only when data must be transfered or when a specific event requests the attention of the system processor.

The MDF main features are:

- AHB interface
- Six serial digital inputs:
  - configurable SPI interface to connect various digital sensors
  - configurable Manchester coded interface support
  - compatible with PDM interface to support digital microphones

- Two common clock input/output for ΣΔ modulators
- Flexible BSMX for connection between filters and digital inputs
- Two inputs to connect the internal ADCs
- Six flexible digital filter paths, including:
  - A configurable CIC filter:
    - Can be split into two CIC filters: high-resolution filter and out-off limit detector
    - Can be configured in Sinc^4 filter
    - Can be configured in Sinc^5 filter
    - Adjustable decimation ratio
  - A reshape filter to improve the out-off band rejection and in-band ripple
  - A high-pass filter to cancel the DC offset
  - An offset error cancellation
  - Gain control
  - Saturation blocks
  - An out-off limit detector
- Short-circuit detector
- Clock absence detector
- 16- or 24-bit signed output data resolution
- Continuous or single conversion
- Possibility to delay independently each bitstream
- Various trigger possibilities
- Break generation on out-of limit or short-circuit detector events
- Autonomous functionality in Stop modes
- DMA can be used to read the conversion data
- Interrupts services

3.36.2 Audio digital filter (ADF)

The ADF is a high-performance module dedicated to the connection of external ΣΔ modulators. It is mainly targeted for the following applications:

- audio capture signals
- metering

The ADF features one digital serial interface (SITF0) and one digital filter (DFLT0) with flexible digital processing options to offer up to 24-bit final resolution.

The DLFT0 of the ADF is a subset of the digital filters included into the MDF.

The ADF serial interface supports several standards allowing the connection of various ΣΔ modulator sensors:

- SPI interface
- Manchester coded 1-wire interface
- PDM interface

A flexible BSMX allows the connection of any incoming bitstream to any filter.

The ADF converts an input data stream into clean decimated digital data words. This conversion is done thanks to low-pass digital filters and decimation blocks. In addition it is possible to insert a high-pass filter or a DC offset correction block.

The conversion speed and resolution are adjustable according to configurable parameters for digital processing: filter type, filter order, decimation ratio. The maximum output data resolution is up to 24 bits. There are two conversion modes: single conversion and continuous modes. The data can be automatically stored in a system RAM buffer through DMA, thus reducing the software overhead.

A SAD (sound activity detector) is available for the detection of “speech-like” signals. The SAD is connected at the output of DFLT0. Several parameters can be programmed to adjust properly the SAD to the sound environment. The SAD can strongly reduce the power consumption by preventing the storage of samples into the system memory as long as the observed signal does not match the programmed criteria.

A flexible trigger interface can be used to control the start of conversion of the ADF.

All the digital processing is performed using only the kernel clock. The ADF requests the bus interface clock (AHB clock) only when data must be transfered or when a specific event requests the attention of the system processor.

The ADF main features are:

- AHB interface
- One serial digital input:
  - Configurable SPI interface to connect various digital sensors
  - Configurable Manchester coded interface support
  - Compatible with PDM interface to support digital microphones
- Two common clocks input/output for ΣΔ modulators
- Flexible BSMX for connection between filters and digital inputs
- One flexible digital filter path, including:
  - A configurable CIC filter:
    - Can be configured in $Sinc^4$ filter
    - Can be configured in $Sinc^5$ filter
    - Adjustable decimation ratio
  - A reshape filter to improve the out-off band rejection and in-band ripple
  - A high-pass filter to cancel the DC offset
  - Gain control
  - Saturation blocks
- Clock absence detector
- Sound activity detector
- 16- or 24-bit signed output data resolution
- Continuous or single conversion
- Possibility to delay independently each bitstream
- Various trigger possibilities
- Autonomous mode in Stop 0, Stop 1 and Stop 2 modes
- Wake-up from Stop with all interrupts
- DMA can be used to read the conversion data

- Interrupts services

3.37 Digital camera interface (DCMI)

The DCMI is a synchronous parallel interface able to receive a high-speed data flow from an external 8-, 10-, 12-, or 14-bit CMOS camera module. It supports different data formats: YCbCr4:2:2/RGB565 progressive video and compressed data (JPEG).

The DCMI features are:

- 8-, 10-, 12-, or 14-bit parallel interface
- Embedded/external line and frame synchronization
- Continuous or snapshot mode
- Crop feature
- Supports the following data formats:
  - 8/10/12/14-bit progressive video: either monochrome or raw Bayer
  - YCbCr 4:2:2 progressive video
  - RGB 565 progressive video
  - Compressed data: JPEG

3.38 Parallel synchronous slave interface (PSSI)

The PSSI and the DCMI use the same circuitry. As a result, these two peripherals cannot be used at the same time: when using the PSSI, the DCMI registers cannot be accessed, and vice versa. In addition, the PSSI and the DCMI share the same alternate functions and the same interrupt vector.

The PSSI is a generic synchronous 8-/16-bit parallel data input/output slave interface. It enables the transmitter to send a data valid signal that indicates when the data is valid, and the receiver to output a flow control signal that indicates when it is ready to sample the data.

The PSSI peripheral main features are the following:

- Slave mode operation
- 8-bit or 16-bit parallel data input or output
- 4-word (16-byte) FIFO
- Data enable (PSSI_DE) alternate function input and ready (PSSI_RDY) alternate function output

When selected, these inputs can either enable the transmitter to indicate when the data is valid, or allow the receiver to indicate when it is ready to sample the data, or both.

3.39 LCD-TFT display controller (LTDC)

The LCD-TFT (liquid crystal display - thin film transistor) display controller provides a parallel digital RGB (Red, Green, Blue) and signals for horizontal/vertical synchronization, pixel clock and data enable as output to interface directly to a variety of LCD and TFT panels.

The LTDC main features are:

- 24-bit RGB parallel pixel output; 8 bits-per-pixel (RGB888)
- 2 display layers with dedicated FIFO (64x32-bit)
- Color look-up table (CLUT) up to 256 color (256x24-bit) per layer
- Programmable timings for different display panels
- Programmable background color
- Programmable polarity for HSYNC, VSYNC and data enable
- Up to 8 input color formats selectable per layer:
  - ARGB8888
  - RGB888
  - RGB565
  - ARGB1555
  - ARGB4444
  - L8 (8-bit luminance or CLUT)
  - AL44 (4-bit alpha + 4-bit luminance)
  - AL88 (8-bit alpha + 8-bit luminance)
- Pseudo-random dithering output for low bits per channel
  - Dither width 2 bits for Red, Green, Blue
- Flexible blending between two layers using alpha value (per pixel or constant)
- Color keying (transparency color)
- Programmable window position and size
- Supports thin film transistor (TFT) color displays
- AHB master interface with burst of 16 words
- Up to 4 programmable interrupt events

3.40 DSI Host controller (DSI)

The display serial interface (DSI) is part of a group of communication protocols defined by the MIPI Alliance. The MIPI DSI Host controller is a digital core that implements all protocol functions defined in the MIPI DSI specification. It provides an interface between the system (LTDC and APB interface) and the MIPI D-PHY, allowing the user to communicate with a DSI-compliant display.

The DSI main features are:

- Compliant with MIPI Alliance standards
- Interface with internal MIPI D-PHY
- Supports all commands defined in the MIPI Alliance specification for DCS:
  - Transmission of all command mode packets through the APB interface
  - Transmission of commands in low-power and high-speed during video mode
- Support of up to 2 D-PHY data lanes
- Bidirectional communication and escape mode support through data lane 0
- Support of non-continuous clock in D-PHY clock lane for additional power saving
- Support of ultra low-power mode with PLL disabled
- ECC and checksum capabilities

- Support for end of transmission packet (EoTp)
- Fault recovery schemes
- Configurable selection of system interfaces:
  - AMBA® APB for control and optional support for generic and DCS commands
  - Video mode interface through LTDC
  - Adapted command mode interface through LTDC
  - Independently programmable virtual channel ID in video mode, adapted command mode and APB slave
- Video mode interfaces features:
  - LTDC interface color coding mappings into 24-bit interface:
    - 16-bit RGB, configurations 1, 2, and 3
    - 18-bit RGB, configurations 1 and 2
    - 24-bit RGB
  - Programmable polarity of all LTDC interface signals
  - Extended resolutions beyond the DPI standard maximum resolution of 800x480 pixels
  - Maximum resolution is limited by available DSI physical link bandwidth:
    - Number of lanes: 2
    - Maximum speed per lane: 500 Mbit/s
- Adapted interface features:
  - Support for sending large amounts of data through the memory_write_start (WMS) and memory_write_continue (WMC) DCS commands
  - LTDC interface color coding mappings into 24-bit interface:
    - 16-bit RGB, configurations 1, 2, and 3
    - 18-bit RGB, configurations 1 and 2
    - 24-bit RGB
- Video mode pattern generator:
  - Vertical and horizontal color bar generation without LTDC stimuli
  - BER pattern without LTDC stimuli

3.41 Touch sensing controller (TSC)

The TSC provides a simple solution to add capacitive sensing functionality to any application. A capacitive sensing technology is able to detect finger presence near an electrode that is protected from direct touch by a dielectric (such as glass or plastic). The capacitive variation introduced by the finger (or any conductive object) is measured using a proven implementation based on a surface charge transfer acquisition principle.

The TSC is fully supported by the STMTouch touch sensing firmware library that is free to use and allows touch sensing functionality to be implemented reliably in the end application.

The TSC main features are the following:

- Proven and robust surface charge transfer acquisition principle
- Supports up to 22 capacitive sensing channels

- Up to eight capacitive sensing channels can be acquired in parallel offering a very good response time
- Spread spectrum feature to improve system robustness in noisy environments
- Full hardware management of the charge transfer acquisition sequence
- Programmable charge transfer frequency
- Programmable sampling capacitor I/O pin
- Programmable channel I/O pin
- Programmable max count value to avoid long acquisition when a channel is faulty
- Dedicated end of acquisition and max count error flags with interrupt capability
- One sampling capacitor for up to three capacitive sensing channels to reduce the system components
- Compatible with proximity, touchkey, linear and rotary touch sensor implementation
- Designed to operate with STMTouch touch sensing firmware library

Note: The number of capacitive sensing channels is dependent on the size of the packages and subject to I/O availability.

3.42 True random number generator (RNG)

The RNG is a true random number generator that provides full entropy outputs to the application as 32-bit samples. It is composed of a live entropy source (analog) and an internal conditioning component.

The RNG is a NIST SP 800-90B compliant entropy source that can be used to construct a non-deterministic random bit generator (NDRBG).

The true random generator:

- delivers 32-bit true random numbers, produced by an analog entropy source conditioned by a NIST SP800-90B approved conditioning stage
- can be used as entropy source to construct a non-deterministic random bit generator (NDRBG)
- produces four 32-bit random samples every 412 AHB clock cycles if f_{AHB} < 77 MHz (256 RNG clock cycles otherwise)
- embeds startup and NIST SP800-90B approved continuous health tests (repetition count and adaptive proportion tests), associated with specific error management
- can be disabled to reduce power consumption, or enabled with an automatic low-power mode (default configuration)
- has an AMBA AHB slave peripheral, accessible through 32-bit word single accesses only (else an AHB bus error is generated, and the write accesses are ignored)

3.43 Secure advanced encryption standard hardware accelerator (SAES) and encryption standard hardware accelerator (AES)

The devices embed two AES accelerators: SAES and AES. The SAES with hardware unique key embeds protection against differential power analysis (DPA) and related side

channel attacks. The SAES can share its current key register information with the faster AES using a dedicated hardware bus.

The SAES and the AES can be used to both encrypt and decrypt data using the AES algorithm. It is a fully compliant implementation of the advanced encryption standard (AES) as defined by Federal Information Processing Standards Publication (FIPS PUB 197, Nov 2001).

Multiple chaining modes are supported for key sizes of 128 or 256 bits. ECB and CBC chaining is supported by both SAES and AES, while CTR, CCM, GCM and GMAC chaining is only supported by the AES.

SAES and AES support DMA single transfers for incoming and outgoing data (two DMA channels required).

The SAES supports the selection of all the following key sources, while the AES support only the first:

- 256-bit software key, written by the application in the key registers (write only)
- 256-bit derived hardware unique key (DHUK), computed inside the SAES engine from a non-volatile OTP based root hardware unique key (RHUK)
- 256-bit boot hardware key (BHK), stored in tamper-resistant secure backup registers, written by a secure code during boot. Once written, this key cannot be read or write by any application until the next product reset.
- XOR of DHUK (provisioned chip secret) and BHK (software secret)

DHUK, BHK and their XOR are not visible by any software (even secure).

Note: 128-bit key size can also be selected.

BHK key is cleared in case of tamper or RDP regression.

When the SAES is secure (respectively nonsecure), DHUK secure (respectively nonsecure) is used.

The SAES peripheral is connected by hardware to the true random number generator RNG (for side-channel resistance).

The SAES and AES peripherals support:

- Compliant implementation of standard NIST *Special Publication 197, Advanced Encryption Standard (AES)* and *Special Publication 800-38A, Recommendation for Block Cipher Modes of Operation*
- 128-bit data block processing
- Support for cipher keys length of 128-bit and 256-bit
- Encryption and decryption with multiple chaining modes:
  - Electronic codebook (ECB) mode
  - Cipher block chaining (CBC) mode
- Additional chaining modes supported by AES only:
  - Counter (CTR) mode
  - Galois counter mode (GCM)
  - Galois message authentication code (GMAC) mode
  - Counter with CBC-MAC (CCM) mode
- 528 or 743 clock cycle latency in ECB encryption mode for SAES processing one 128-bit block of data with, respectively, 128-bit or 256-bit key

- 51 or 75 clock cycle latency in ECB encryption mode for AES processing one 128-bit block of data with, respectively, 128-bit or 256-bit key
- Integrated round key scheduler to compute the last round key for AES ECB/CBC decryption
- 256-bit register for storing the cryptographic key (four 32-bit registers), with key atomicity enforcement
- 128-bit registers for storing initialization vectors (four 32-bit registers)
- One 32-bit input buffer and one 32-bit output buffer
- Automatic data flow control with support of single-transfer direct memory access (DMA) using two channels (one for incoming data, one for processed data)
- Data swapping logic to support 1-, 8-, 16- or 32-bit data
- Possibility for software to suspend a message if the SAES/AES needs to process another message with a higher priority (suspend/resume operation)
- SAES additional features:
  - Security context enforcement for keys
  - Hardware secret key encryption/ decryption (wrapped key mode) and sharing with faster AES peripheral (Shared key mode)
  - Protection against differential power analysis (DPA) and related side-channel attacks
  - Optional hardware loading of two hardware secret keys (BHK, DHUK) that can be XORed together

On top of standard AES encryption and decryption with a key loaded by software, SAES peripheral allows the following advanced use cases:

- Allow or deny the sharing of a key between a secure and a nonsecure application, enforced by hardware
- Encrypt once a key using side-channel resistant AES, then share it to a faster AES engine by decrypting it (Shared key mode)
- On-chip encrypted storage using chip-unique secret DHUK
- Transport key generation by encrypting the device public unique ID with the application secret BHK
- Binding of device secure storage keys, using the silicon unique secret key (DHUK) XORed with the boot secret key (BHK). If BHK is lost, the whole device secure storage is lost.

Note: Encrypted storage or derived keys that are using DHUK or BHK, cannot be used anymore when a security breach is detected.

Table 19. AES/SAES features

AES/SAES modes/features(1)	AES	SAES
ECB, CBC chaining	X	X
CTR, CCM, GCM chaining	X	-
AES 128-bit ECB encryption in cycles	51	528
DHUK and BHK key selection	-	X

Table 19. AES/SAES features (continued)

AES/SAES modes/features[1]	AES	SAES
Side-channel attacks resistance	-	X
Shared key between SAES and AES	X	

1. X = supported.

3.44 HASH hardware accelerator (HASH)

The HASH is a fully compliant implementation of the secure hash algorithm (SHA-1, SHA-224, SHA-256), the MD5 (message-digest algorithm 5) hash algorithm and the HMAC (keyed-hash message authentication code) algorithm. HMAC is suitable for applications requiring message authentication.

The HASH computes FIPS (Federal information processing standards) approved digests of length of 160, 224, 256 bits, for messages of up to (2^{64} – 1) bits. It also computes 128 bits digests for the MD5 algorithm.

The HASH main features are:

- Suitable for data authentication applications, compliant with:
  - Federal Information Processing Standards Publication FIPS PUB 180-4, *Secure Hash Standard* (SHA-1 and SHA-2 family)
  - Federal Information Processing Standards Publication FIPS PUB 186-4, *Digital* Signature Standard (DSS)
  - Internet Engineering Task Force (IETF) Request For Comments RFC 1321, *MD5* Message-Digest Algorithm
  - Internet Engineering Task Force (IETF) Request For Comments RFC 2104, *HMAC: Keyed-Hashing for Message Authentication* and Federal Information Processing Standards Publication FIPS PUB 198-1, *The Keyed-Hash Message* Authentication Code (HMAC)
- Fast computation of SHA-1, SHA-224, SHA-256, and MD5
  - 82 (respectively 66) clock cycles for processing one 512-bit block of data using SHA-1 (respectively SHA-256) algorithm
  - 66 clock cycles for processing one 512-bit block of data using MD5 algorithm
- Corresponding 32-bit words of the digest from consecutive message blocks are added to each other to form the digest of the whole message:
  - Automatic 32-bit words swapping to comply with the internal little-endian representation of the input bit string
  - Word swapping supported: bits, bytes, half-words and 32-bit words
- Automatic padding to complete the input bit string to fit digest minimum block size of 512 bits (16 × 32 bits)
- Single 32-bit input register associated to an internal input FIFO of sixteen 32-bit words, corresponding to one block size
- AHB slave peripheral, accessible through 32-bit word accesses only (else an AHB error is generated)
- 8 × 32-bit words (H0 to H7) for output message digest

- Automatic data flow control with support of direct memory access (DMA) using one channel. Single or fixed burst of 4 supported.
- Interruptible message digest computation, on a per-32-bit word basis
  - Re-loadable digest registers
  - Hashing computation suspend/resume mechanism, including using DMA

3.45 On-the-fly decryption engine (OTFDEC)

The OTFDEC allows the decryption of the on-the-fly AHB traffic based on the read request address information, for example execute-in-place of a code stored encrypted. Four independent and non-overlapping encrypted regions can be defined in OTFDEC.

OTFDEC uses AES-128 in counter mode to achieve the lowest possible latency.
As consequence, each time the content of one encrypted region is changed the entire region must be re-encrypted with a different cryptographic context (key or initialization vector). This constraint makes OTFDEC suitable to decrypt read-only data or code, stored in external NOR Flash.

Note: When OTFDEC is used in conjunction with OCTOSPI, it is mandatory to access the flash memory using the Memory-mapped mode of the flash memory controller.

When security is enabled in the product, OTFDEC can be programmed only by a secure host.

The OTFDEC main features are the following:

- On-the-fly 128-bit decryption during OCTOSPI memory-mapped read operations (single or multiple)
  - Use of AES in counter (CTR) mode, with two 128-bit keystream buffers
  - Support for any read size
  - Physical address of the reads is used for the encryption/decryption
- Up to 4 independent encrypted regions
  - Granularity of the region definition: 4096 bytes
  - Region configuration write locking mechanism
  - Each region has its own 128-bit key, two bytes firmware version, and eight bytes application-defined nonce. At least one of those must be changed each time an encryption is performed by the application.
- Encryption keys confidentiality and integrity protection
  - Write-only registers, with software locking mechanism
  - Availability of 8-bit CRC as public key information
- Support for OCTOSPI prefetching mechanism
- Possibility to select an enhanced encryption mode to add a proprietary layer of protection on top of AES stream cipher (execute only)
- AMBA® AHB slave peripheral, accessible through 32-bit word single accesses only (otherwise an AHB bus error is generated, and write accesses are ignored)
- Secure only programming if TrustZone security is enabled
- Encryption mode

3.46 Public key accelerator (PKA)

The PKA is intended for the computation of cryptographic public key primitives, specifically those related to RSA, Diffie-Hellmann or ECC (elliptic curve cryptography) over GF(p) (Galois fields). To achieve high performance at a reasonable cost, these operations are executed in the Montgomery domain.

All needed computations are performed within the accelerator, so no further hardware/software elaboration is needed to process the inputs or the outputs.

The PKA main features are:

- Acceleration of RSA, DH and ECC over GF(p) operations, based on the Montgomery method for fast modular multiplications. More specifically:
  - RSA modular exponentiation, RSA Chinese remainder theorem (CRT) exponentiation
  - ECC scalar multiplication, point on curve check, complete addition, double base ladder, projective to affine
  - ECDSA signature generation and verification
- Capability to handle operands up to 4160 bits for RSA/DH and 640 bits for ECC
- Arithmetic and modular operations such as addition, subtraction, multiplication, modular reduction, modular inversion, comparison, and Montgomery multiplication
- Built-in Montgomery domain inward and outward transformations
- Protection against differential power analysis (DPA) and related side-channel attacks.

3.47 Timers and watchdogs

The devices include two advanced control timers, up to seven general-purpose timers, two basic timers, four low-power timers, two watchdog timers and two SysTick timers.

The table below compares the features of the advanced control, general-purpose and basic timers.

Table 20. Timer feature comparison

Timer type	Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/ compare channels	Complementary outputs
Advanced control	TIM1, TIM8	16 bits	Up, down, Up/down	Any integer between 1 and 65536	Yes	4	3
General-purpose	TIM2, TIM3, TIM4, TIM5	32 bits	Up, down, Up/down	Any integer between 1 and 65536	Yes	4	No
General-purpose	TIM15	16 bits	Up	Any integer between 1 and 65536	Yes	2	1

Table 20. Timer feature comparison (continued)

Timer type	Timer	Counter resolution	Counter type	Prescaler factor	DMA request generation	Capture/ compare channels	Complementary outputs
General-purpose	TIM16, TIM17	16 bits	Up	Any integer between 1 and 65536	Yes	1	1
Basic	TIM6, TIM7	16 bits	Up	Any integer between 1 and 65536	Yes	0	No

3.47.1 Advanced-control timers (TIM1, TIM8)

The advanced-control timers can each be seen as a three-phase PWM multiplexed on six channels. They have complementary PWM outputs with programmable inserted dead-times. They can also be seen as complete general-purpose timers.

The four independent channels can be used for:

- Input capture
- Output compare
- PWM generation (edge or center-aligned modes) with full modulation capability (0 - 100 %)
- One-pulse mode output

In Debug mode, the advanced-control timer counter can be frozen and the PWM outputs disabled in order to turn off any power switches driven by these outputs.

Many features are shared with the general-purpose TIMx timers (described in the next section) using the same architecture, so the advanced-control timers can work together with the TIMx timers via the *Timer Link* feature for synchronization or event chaining.

3.47.2 General-purpose timers (TIM2, TIM3, TIM4, TIM5, TIM15, TIM16,TIM17)

There are up to seven synchronizable general-purpose timers embedded in the STM32U5Axxx devices (see *Table 20* for differences). Each general-purpose timer can be used to generate PWM outputs, or act as a simple time base.

- TIM2, TIM3, TIM4 and TIM5

  They are full-featured general-purpose timers with 32-bit auto-reload up/downcounter and 16-bit prescaler.

  These timers feature four independent channels for input capture/output compare, PWM or one-pulse mode output. They can work together, or with the other general-purpose timers via the *Timer Link* feature for synchronization or event chaining.

  The counters can be frozen in Debug mode.

  All have independent DMA request generation and support quadrature encoders.

- TIM15, 16 and 17

  They are general-purpose timers with mid-range features.

  They have 16-bit auto-reload upcounters and 16-bit prescalers.

  – TIM15 has two channels and one complementary channel

  – TIM16 and TIM17 have one channel and one complementary channel

  All channels can be used for input capture/output compare, PWM or one-pulse mode output.

  The timers can work together via the *Timer Link* feature for synchronization or event chaining. The timers have independent DMA request generation.

  The counters can be frozen in Debug mode.

3.47.3 Basic timers (TIM6 and TIM7)

The basic timers are mainly used for DAC trigger generation. They can also be used as generic 16-bit timebase.

3.47.4 Low-power timers (LPTIM1, LPTIM2, LPTIM3, LPTIM4)

The devices embed four low-power timers. These timers have an independent clock and are running in Stop mode if they are clocked by HSI16, MSI, LSE, LSI or an external clock. They are able to wake up the system from Stop mode.

LPTIM1, LPTIM3, and LPTIM4 are active in Stop 0, Stop 1 and Stop 2 modes.

LPTIM2 is active in Stop 0 and Stop 1 mode.

The low-power timer supports the following features:

- 16-bit up counter with 16-bit autoreload register
- 3-bit prescaler with eight possible dividing factors (1, 2, 4, 8, 16, 32, 64, 128)
- Selectable clock
  – Internal clock sources: LSE, LSI, HSI16, MSIK (LPTIM1, LPTIM3, LPTIM4 only) or APB clock (LPTIM2 only)
  – External clock source over LPTIM input (working with no LP oscillator running, used by *Pulse Counter* application)
- 16-bit ARR autoreload register
- 16-bit capture/compare register
- Continuous/One-shot mode
- Selectable software/hardware input trigger
- Programmable digital glitch filter
- Configurable output: pulse, PWM
- Configurable I/O polarity
- Encoder mode
- Repetition counter
- Up to 2 independent channels for:
  – Input capture
  – PWM generation (edge-aligned mode)
  – One-pulse mode output
- Interrupt generation on 10 events

- DMA request generation on the following events:
  - Update event
  - Input capture

3.47.5 Infrared interface (IRTIM)

An infrared interface (IRTIM) for remote control is available on the device. It can be used with an infrared LED to perform remote control functions. It uses internal connections with TIM16 and TIM17.

3.47.6 Independent watchdog (IWDG)

The independent watchdog is based on a 12-bit downcounter and a 8-bit prescaler. It is clocked from an independent 32 kHz internal RC (LSI) and, as it operates independently from the main clock, it can operate in Stop and Standby modes. It can be used either as a watchdog to reset the device when a problem occurs, or as a free running timer for application timeout management. It is hardware or software configurable through the option bytes. The counter can be frozen in Debug mode.

3.47.7 Window watchdog (WWDG)

The window watchdog is based on a 7-bit downcounter that can be set as free running. It can be used as a watchdog to reset the device when a problem occurs. It is clocked from the main clock. It has an early warning interrupt capability and the counter can be frozen in Debug mode.

3.47.8 SysTick timer

The Cortex-M33 with TrustZone embeds two SysTick timers.

When TrustZone is activated, two SysTick timer are available:

- SysTick, secure instance
- SysTick, nonsecure instance

When TrustZone is disabled, only one SysTick timer is available. This timer (secure or non-secure) is dedicated to real-time operating systems, but can also be used as a standard down counter. It features:

- A 24-bit down counter
- Autoreload capability
- Maskable system interrupt generation when the counter reaches 0
- Programmable clock source.

3.48 Real-time clock (RTC), tamper and backup registers

3.48.1 Real-time clock (RTC)

The RTC supports the following features:

- Calendar with subsecond, seconds, minutes, hours (12 or 24 format), weekday, date, month, year, in BCD (binary-coded decimal) format
- Binary mode with 32-bit free-running counter

- Automatic correction for 28, 29 (leap year), 30, and 31 days of the month
- Two programmable alarms
- On-the-fly correction from 1 to 32767 RTC clock pulses. This can be used to synchronize it with a master clock
- Reference clock detection: a more precise second source clock (50 or 60 Hz) can be used to enhance the calendar precision
- Digital calibration circuit with 0.95 ppm resolution, to compensate for quartz crystal inaccuracy
- Timestamp feature that can be used to save the calendar content. This function can be triggered by an event on the timestamp pin, or by a tamper event, or by a switch to V_{BAT} mode
- 17-bit auto-reload wake-up timer (WUT) for periodic events with programmable resolution and period
- TrustZone support:
  - RTC fully securable
  - Alarm A, alarm B, wake-up timer and timestamp individual secure or nonsecure configuration
  - Alarm A, alarm B, wake-up timer and timestamp individual privileged protection

The RTC is supplied through a switch that takes power either from the V_{DD} supply when present or from the VBAT pin.

The RTC clock sources can be one of the following:

- 32.768 kHz external crystal (LSE)
- external resonator or oscillator (LSE)
- internal low-power RC oscillator (LSI, with typical frequency of 32 kHz)
- high-speed external clock (HSE), divided by a prescaler in the RCC.

The RTC is functional in V_{BAT} mode and in all low-power modes when it is clocked by the LSE. When clocked by the LSI, the RTC is not functional in V_{BAT} mode, but is functional in all low-power modes except Shutdown mode.

All RTC events (alarm, wake-up timer, timestamp) can generate an interrupt and wake up the device from the low-power modes.

3.48.2 Tamper and backup registers (TAMP)

The anti-tamper detection circuit is used to protect sensitive data from external attacks. 32 32-bit backup registers are retained in all low-power modes and also in V_{BAT} mode. The backup registers, as well as other secrets in the device, are protected by this anti-tamper detection circuit with eight tamper pins and eleven internal tampers. The external tamper pins can be configured for edge detection, or level detection with or without filtering, or active tamper that increases the security level by auto checking that the tamper pins are not externally opened or shorted.

TAMP main features:

- A tamper detection can erase the backup registers, backup SRAM, SRAM2, caches, and cryptographic peripherals.
- 32 32-bit backup registers:
  - The backup registers (TAMP_BKPxR) are implemented in the Backup domain that remains powered-on by V_{BAT} when the V_{DD} power is switched off.

- Up to 8 tamper pins for 8 external tamper detection events:
  - Active tamper mode: continuous comparison between tamper output and input to protect from physical open-short attacks
  - Flexible active tamper I/O management: from 4 meshes (each input associated to its own exclusive output) to 7 meshes (single output shared for up to 7 tamper inputs)
  - Passive tampers: ultra-low power edge or level detection with internal pull-up hardware management
  - Configurable digital filter
- 11 internal tamper events to protect against transient or environmental perturbation attacks:
  - Backup domain voltage monitoring
  - Temperature monitoring
  - LSE monitoring
  - RTC calendar overflow
  - JTAG/SWD access if RDP different from 0
  - Monotonic counter overflow
  - Cryptographic peripherals fault (RNG, SAES, AES, PKA)
  - Independent watchdog reset when tamper flag is already set
  - 3 ADC4 watchdogs
- Each tamper can be configured in two modes:
  - Hardware mode: immediate erase of secrets on tamper detection, including backup registers erase
  - Software mode: erase of secrets following a tamper detection launched by software
- Any tamper detection can generate a RTC time stamp event.
- TrustZone support:
  - Tamper secure or nonsecure configuration
  - Backup registers configuration in 3 configurable-size areas:
    - 1 read/write secure area
    - 1 write secure/read nonsecure area
    - 1 read/write nonsecure area
  - Boot secret key (BHK) only usable by secure AES peripheral, stored in backup registers, protected against read and write access
- Tamper configuration and backup registers privilege protection
- Monotonic counter

3.49 Inter-integrated circuit interface (I2C)

The device embeds six I2C. Refer to *Table 21* for the features implementation.

The I^2C bus interface handles communications between the microcontroller and the serial I^2C bus. It controls all I^2C bus-specific sequencing, protocol, arbitration and timing.

The I2C peripheral supports:

- I²C-bus specification and user manual rev. 5 compatibility:
  - Slave and Master modes, multimaster capability
  - Standard-mode (Sm), with a bit rate up to 100 Kbit/s
  - Fast-mode (Fm), with a bit rate up to 400 Kbit/s
  - Fast-mode Plus (Fm+), with a bit rate up to 1 Mbit/s and 20 mA output drive I/Os
  - 7-bit and 10-bit addressing mode, multiple 7-bit slave addresses
  - Programmable setup and hold times
  - Optional clock stretching
- System management bus (SMBus) specification rev 3.0 compatibility:
  - Hardware PEC (packet error checking) generation and verification with ACK control
  - Address resolution protocol (ARP) support
  - SMBus alert
- Power system management protocol (PMBus) specification rev 1.3 compatibility
- Independent clock: a choice of independent clock sources allowing the I2C communication speed to be independent from the PCLK reprogramming
- Autonomous functionality in Stop modes with wake-up from Stop capability
- Programmable analog and digital noise filters
- 1-byte buffer with DMA capability

Table 21. I2C implementation

I2C features(1)	I2C1	I2C2	I2C3	I2C4	I2C5	I2C6
Standard-mode (up to 100 Kbit/s)	X	X	X	X	X	X
Fast-mode (up to 400 Kbit/s)	X	X	X	X	X	X
Fast-mode Plus with 20 mA output drive I/Os (up to 1 Mbit/s)	X	X	X	X	X	X
Programmable analog and digital noise filters	X	X	X	X	X	X
SMBus/PMBus hardware support	X	X	X	X	X	X
Independent clock	X	X	X	X	X	X
Autonomous in Stop 0, Stop 1 mode with wake-up capability	X	X	X	X	X	X
Autonomous in Stop 2 mode with wake-up capability	-	-	X	-	-	-

1. X: supported

3.50 Universal synchronous/asynchronous receiver transmitter (USART/UART) and low-power universal asynchronous receiver transmitter (LPUART)

The devices embed four universal synchronous receiver transmitters (USART1, USART2, USART3 and USART6), two universal asynchronous receiver transmitters (UART4, UART5) and one low-power universal asynchronous receiver transmitter (LPUART1).

Table 22. USART, UART and LPUART features

USART modes/features(1)	USART1/2/3/6	UART4/5	LPUART1
Hardware flow control for modem	X	X	X
Continuous communication using DMA	X	X	X
Multiprocessor communication	X	X	X
Synchronous mode (master/slave)	X	-	-
Smartcard mode	X	-	-
Single-wire half-duplex communication	X	X	X
IrDA SIR ENDEC block	X	X	-
LIN mode	X	X	-
Dual-clock domain and wake-up from Stop mode	X(2)	X(2)	X(3)
Receiver timeout interrupt	X	X	-
Modbus communication	X	X	-
Auto-baud rate detection	X	X	-
Driver enable	X	X	X
USART data length	7, 8 and 9 bits		
Tx/Rx FIFO	X	X	X
Tx/Rx FIFO size	8 bytes		
Autonomous mode	X	X	X

1. X = supported.
2. Wake-up supported from Stop 0 and Stop 1 modes.
3. Wake-up supported from Stop 0, Stop 1 and Stop 2 modes.

3.50.1 Universal synchronous/asynchronous receiver transmitter (USART/UART)

The USART offers a flexible means to perform full-duplex data exchange with external equipments requiring an industry standard NRZ asynchronous serial data format. A very wide range of baud rates can be achieved through a fractional baud rate generator.

The USART supports both synchronous one-way and half-duplex single-wire communications, as well as LIN (local interconnection network), Smartcard protocol, IrDA (infrared data association) SIR ENDEC specifications, and modem operations (CTS/RTS). Multiprocessor communications are also supported.

High-speed data communications up to 20 Mbauds are possible by using the DMA (direct memory access) for multibuffer configuration.

The USART main features are:

- Full-duplex asynchronous communication
- NRZ standard format (mark/space)
- Configurable oversampling method by 16 or 8 to achieve the best compromise between speed and clock tolerance
- Baud rate generator systems

- Two internal FIFOs for transmit and receive data
  Each FIFO can be enabled/disabled by software and come with a status flag.
- A common programmable transmit and receive baud rate
- Dual-clock domain with dedicated kernel clock for peripherals independent from PCLK
- Auto baud rate detection
- Programmable data word length (7, 8 or 9 bits)
- Programmable data order with MSB-first or LSB-first shifting
- Configurable stop bits (1 or 2 stop bits)
- Synchronous Master/Slave mode and clock output/input for synchronous communications
- SPI slave transmission underrun error flag
- Single-wire half-duplex communications
- Continuous communications using DMA
- Received/transmitted bytes are buffered in reserved SRAM using centralized DMA
- Separate enable bits for transmitter and receiver
- Separate signal polarity control for transmission and reception
- Swappable Tx/Rx pin configuration
- Hardware flow control for modem and RS-485 transceiver
- Communication control/error detection flags
- Parity control:
  – Transmits parity bit
  – Checks parity of received data byte
- Interrupt sources with flags
- Multiprocessor communications: wake-up from Mute mode by idle line detection or address mark detection
- Autonomous functionality in Stop mode with wake-up from stop capability
- LIN master synchronous break send capability and LIN slave break detection capability
  – 13-bit break generation and 10/11-bit break detection when USART is hardware configured for LIN
- IrDA SIR encoder decoder supporting 3/16-bit duration for Normal mode
- Smartcard mode
  – Supports the T=0 and T=1 asynchronous protocols for smartcards as defined in the ISO/IEC 7816-3 standard
  – 0.5 and 1.5 stop bits for Smartcard operation
- Support for Modbus communication
  – Timeout feature
  – CR/LF character recognition

3.50.2 Low-power universal asynchronous receiver transmitter (LPUART)

The LPUART supports bidirectional asynchronous serial communication with minimum power consumption. It also supports half-duplex single-wire communication and modem operations (CTS/RTS). It allows multiprocessor communication.

Only a 32.768 kHz clock (LSE) is needed to allow LPUART communication up to 9600 baud. Therefore, even in Stop mode, the LPUART can wait for an incoming frame while having an extremely low energy consumption. Higher-speed clock can be used to reach higher baudrates.

The LPUART interface can be served by the DMA controller.

The LPUART main features are:

- Full-duplex asynchronous communications
- NRZ standard format (mark/space)
- Programmable baud rate
- From 300 baud/s to 9600 baud/s using a 32.768 kHz clock source
- Higher baud rates can be achieved by using a higher frequency clock source
- Two internal FIFOs to transmit and receive data
  Each FIFO can be enabled/disabled by software and come with status flags for FIFO states.
- Dual-clock domain with dedicated kernel clock for peripherals independent from PCLK
- Programmable data word length (7 or 8 or 9 bits)
- Programmable data order with MSB-first or LSB-first shifting
- Configurable stop bits (1 or 2 stop bits)
- Single-wire half-duplex communications
- Continuous communications using DMA
- Received/transmitted bytes are buffered in reserved SRAM using centralized DMA
- Separate enable bits for transmitter and receiver
- Separate signal polarity control for transmission and reception
- Swappable Tx/Rx pin configuration
- Hardware flow control for modem and RS-485 transceiver
- Transfer detection flags:
  - Receive buffer full
  - Transmit buffer empty
  - Busy and end of transmission flags
- Parity control:
  - Transmits parity bit
  - Checks parity of received data byte
- Four error detection flags:
  - Overrun error
  - Noise detection
  - Frame error
  - Parity error
- Interrupt sources with flags
- Multiprocessor communications: wake-up from Mute mode by idle line detection or address mark detection
- Autonomous functionality in Stop mode with wake-up from Stop capability

3.51 Serial peripheral interfaces (SPI)

The devices embed three serial peripheral interfaces (SPI) that can be used to communicate with external devices while using the specific synchronous protocol. The SPI protocol supports half-duplex, full-duplex and simplex synchronous, serial communication with external devices.

The interface can be configured as master or slave and can operate in multi-slave or multi-master configurations. The device configured as master provides communication clock (SCK) to the slave device. The slave select (SS) and ready (RDY) signals can be applied optionally just to setup communication with concrete slave and to assure it handles the data flow properly. The Motorola® data format is used by default, but some other specific modes are supported as well.

The SPI main features are:

- Full-duplex synchronous transfers on three lines
- Half-duplex synchronous transfer on two lines (with bidirectional data line)
- Simplex synchronous transfers on two lines (with unidirectional data line)
- 4-bit to 32-bit data size selection or fixed to 8-bit and 16-bit only
- Multi master or multi slave mode capability
- Dual-clock domain, separated clock for the peripheral kernel that can be independent of PCLK
- Baud rate prescaler up to kernel frequency/2 or bypass from RCC in Master mode
- Protection of configuration and setting
- Hardware or software management of SS for both master and slave
- Adjustable minimum delays between data and between SS and data flow
- Configurable SS signal polarity and timing, MISO x MOSI swap capability
- Programmable clock polarity and phase
- Programmable data order with MSB-first or LSB-first shifting
- Programmable number of data within a transaction to control SS and CRC
- Dedicated transmission and reception flags with interrupt capability
- SPI Motorola® and Texas Instruments® formats support
- Hardware CRC feature can secure communication at the end of transaction by:
  - Adding CRC value in Tx mode
  - Automatic CRC error checking for Rx mode
- Error detection with interrupt capability in case of data overrun, CRC error, data underrun at slave, mode fault at master
- Two 16x or 8x 8-bit embedded Rx and TxFIFOs with DMA capability
- Programmable number of data in transaction
- Configurable FIFO thresholds (data packing)
- Configurable behavior at slave underrun condition (support of cascaded circular buffers)
- Autonomous functionality in Stop modes (handling of the transaction flow and required clock distribution) with wake-up from stop capability
- Optional status pin RDY signalizing the slave device ready to handle the data flow.

Table 23. SPI features

SPI feature	SPI1, SPI2 (full feature set instances)	SPI3 (limited feature set instance)
Data size	Configurable from 4 to 32-bit	8/16-bit
CRC computation	CRC polynomial length configurable from 5 to 33-bit	CRC polynomial length configurable from 9 to 17-bit
Size of FIFOs	16x 8-bit	8x 8-bit
Number of transfered data	Unlimited, expandable	Up to 1024, no data counter
Autonomous in Stop 0, Stop 1 mode with wake-up capability	Yes	Yes
Autonomous in Stop 2 mode with wake-up capability	No	Yes

3.52 Serial audio interfaces (SAI)

The devices embed two SAI. Refer to *Table 24: SAI implementation* for the features implementation. The SAI bus interface handles communications between the microcontroller and the serial audio protocol.

The SAI peripheral supports:

- Two independent audio sub-blocks that can be transmitters or receivers with their respective FIFO
- 8-word integrated FIFOs for each audio sub-block
- Synchronous or Asynchronous mode between the audio sub-blocks
- Master or slave configuration independent for both audio sub-blocks
- Clock generator for each audio block to target independent audio frequency sampling when both audio sub-blocks are configured in master mode
- Data size configurable: 8-, 10-, 16-, 20-, 24-, 32-bit
- Peripheral with large configurability and flexibility allowing to target as example the following audio protocol: I2S, LSB or MSB-justified, PCM/DSP, TDM, AC’97 and SPDIF out
- Up to 16 slots available with configurable size and with the possibility to select which ones are active in the audio frame
- Number of bits by frame may be configurable
- Frame synchronization active level configurable (offset, bit length, level)
- First active bit position in the slot is configurable
- LSB first or MSB first for data transfer
- Mute mode
- Stereo/mono audio frame capability
- Communication clock strobing edge configurable (SCK)
- Error flags with associated interrupts if enabled respectively
  - Overrun and underrun detection
  - Anticipated frame synchronization signal detection in Slave mode
  - Late frame synchronization signal detection in Slave mode

  - Codec not ready for the AC’97 mode in reception
- Interruption sources when enabled:
  - Errors
  - FIFO requests
- DMA interface with two dedicated channels to handle access to the dedicated integrated FIFO of each SAI audio sub-block.

Table 24. SAI implementation

SAI features(1)	SAI1	SAI2
I2S, LSB or MSB-justified, PCM/DSP, TDM, AC’97	X	X
Mute mode	X	X
Stereo/mono audio frame capability.	X	X
16 slots	X	X
Data size configurable: 8-, 10-, 16-, 20-, 24-, 32-bit	X	X
FIFO size	X (8 words)	X (8 words)
SPDIF	X	X
PDM	X	-

1. X: supported

3.53 Secure digital input/output and MultiMediaCards interface (SDMMC)

The SDMMC (SD/SDIO embedded MultiMediaCard *e*•MMC™ host interface) provides an interface between the AHB bus and SD memory cards, SDIO cards and *e*•MMC devices.

The MultiMediaCard system specifications are available through the MultiMediaCard association website at www.mmca.org, published by the MMCA technical committee.

SD memory card and SD I/O card system specifications are available through the SD card Association website at www.sdcard.org.

The SDMMC features include the following:

- Compliance with Embedded MultiMediaCard System Specification Version 5.1

  Card support for three different databus modes: 1-bit (default), 4-bit and 8-bit

  (HS200 SDMMC_CK speed limited to maximum allowed I/O speed) (HS400 is not supported).
- Full compatibility with previous versions of MultiMediaCards (backward compatibility).
- Full compliance with *SD memory card specifications version 6.0*

  (SDR104 SDMMC_CK speed limited to maximum allowed I/O speed, SPI mode and UHS-II mode not supported).
- Full compliance with *SDIO card specification version 4.0*

  Card support for two different databus modes: 1-bit (default) and 4-bit

  (SDR104 SDMMC_CK speed limited to maximum allowed I/O speed, SPI mode and UHS-II mode not supported).

- Data transfer up to 208 Mbyte/s for the 8-bit mode
  (Depending maximum allowed I/O speed).
- Data and command output enable signals to control external bidirectional drivers
- IDMA linked list support

The MultiMediaCard/SD bus connects cards to the host.

The current version of the SDMMC supports only one SD/SDIO/*e*•MMC card at any one time and a stack of *e*•MMC.

Table 25. SDMMC features

SDMMC modes/features(1)	SDMMC1	SDMMC2
Variable delay (SDR104, HS200)	X	X
SDMMC_CKIN	X	-
SDMMC_CDIR, SDMMC_D0DIR	X	-
SDMMC_D123DIR	X	-

1. X = supported.

When SDMMC peripherals are used simultaneously:

- Only one can be used in *e*•MMC with 8-bit bus width.
- The SDMMC1 SDIO voltage switch use is mutually exclusive with SDMMC2 interfacing *e*•MMC with 8-bit bus width, as follows:
  - If SDMMC1 has to support SDIO UHS-I modes (SDR12, SDR25, SDR50, SDR104 or DDR50), SDMMC2 cannot support *e*•MMC with 8-bit bus width.
  - if SDMMC2 has to support *e*•MMC with 8-bit bus width, SDMMC1 supports only SDIO default mode and high-speed mode.

3.54 Controller area network (FDCAN)

The controller area network (CAN) subsystem consists of one CAN module, a shared message RAM memory and a configuration block.

The modules (FDCAN) are compliant with ISO 11898-1: 2015 (CAN protocol specification version 2.0 part A, B) and CAN FD protocol specification version 1.0.

A 0.8-Kbyte message RAM implements filters, receives FIFOs, transmits event FIFOs and transmits FIFOs.

The FDCAN main features are:

- Conform with CAN protocol version 2.0 part A, B and ISO 11898-1: 2015, -4
- CAN FD with maximum 64 data bytes supported
- CAN error logging
- AUTOSAR and J1939 support
- Improved acceptance filtering
- 2 receive FIFOs of three payloads each (up to 64 bytes per payload)
- Separate signaling on reception of high priority messages
- Configurable transmit FIFO / queue of three payload (up to 64 bytes per payload)

- Configurable transmit Event FIFO
- Programmable loop-back test mode
- Maskable module interrupts
- Two clock domains: APB bus interface and CAN core kernel clock
- Power-down support

3.55 USB on-the-go high-speed (OTG_HS)

The devices embed an USB OTG high-speed device/host/OTG peripheral with integrated transceivers. The OTG_HS peripheral is compliant with the USB 2.0 specification and with the OTG 2.0 specification. It has software-configurable endpoint setting and supports suspend/resume.

This interface requires a precise 60 MHz clock that is generated from the internal USB PHY PLL (the clock source must use a HSE crystal oscillator).

The OTG_HS features are:

- USB-IF certified to the Universal Serial Bus Specification Rev 2.0
- On-chip high-speed PHY
- Full support (PHY) for the optional OTG (on-the-go) protocol detailed in the OTG Supplement Rev 2.0 specification
  - Integrated support for A-B device identification (ID line)
  - Supports OTG monitoring of V_{BUS} levels with internal comparators
  - Supports dynamic host-peripheral switch of role
- Software-configurable to operate as USB on-the-go high-speed dual role device
- Supports HS/FS SOF and LS keep-alives with
  - SOF pulse PAD connectivity
  - SOF pulse internal connection to timer (TIMx)
  - Configurable framing period
  - Configurable end of frame interrupt
- USB 2.0 link power management (LPM) support
- Internal DMA with thresholding support and software selectable AHB burst type in DMA mode
- Power saving features such as system stop during USB suspend, switch-off of clock domains internal to the digital core, PHY and DFIFO power management
- Dedicated RAM of 4 Kbytes with advanced FIFO control:
  - Configurable partitioning of RAM space into different FIFOs for flexible and efficient use of RAM
  - Each FIFO able to hold multiple packets
  - Dynamic memory allocation
  - Configurable FIFO sizes that are not powers of two to allow the use of contiguous memory locations
- Max guaranteed USB bandwidth for up to one frame (1 ms) without system intervention
- Support of charging port detection as described in *Battery Charging Specification* revision 1.2

Host-mode features:

- External charge pump for VBUS voltage generation
- Up to 16 host channels (pipes): each channel is dynamically reconfigurable to allocate any type of USB transfer
- Built-in hardware scheduler holding:
  - Up to 16 interrupt plus isochronous transfer requests in the periodic hardware queue
  - Up to 16 control plus bulk transfer requests in the non-periodic hardware queue
- Management of a shared Rx FIFO, a periodic Tx FIFO and a non periodic Tx FIFO for efficient usage of the USB data RAM

Peripheral-mode features:

- 1 bidirectional control endpoint0
- 8 IN endpoints (EPs) configurable to support bulk, interrupt or isochronous transfers
- 8 OUT endpoints configurable to support bulk, interrupt or isochronous transfers
- Management of a shared Rx FIFO and a Tx-OUT FIFO for efficient usage of the USB data RAM
- Management of up to 9 dedicated Tx-IN FIFOs (one for each active IN EP) to put less load on the application
- Support for the soft disconnect feature

3.56 USB Type-C /USB Power Delivery controller (UCPD)

The device embeds one controller (UCPD) compliant with USB Type-C Cable and Connector Specification release 2.0 and USB Power Delivery Rev. 3.0 specifications.

The controller uses specific I/Os supporting the USB Type-C and USB power delivery requirements, featuring:

- USB Type-C pull-up (Rp, all values) and pull-down (Rd) resistors
- “Dead battery” support
- USB power delivery message transmission and reception
- FRS (fast role swap) support

The digital controller handles notably:

- USB Type-C level detection with debounce, generating interrupts
- FRS detection, generating an interrupt
- Byte-level interface for USB power delivery payload, generating interrupts (DMA compatible)
- USB power delivery timing dividers (including a clock prescaler)
- CRC generation/checking
- 4b5b encode/decode
- Ordered sets (with a programmable ordered set mask at receive)
- Frequency recovery in receiver during preamble

The interface offers low-power operation compatible with Stop mode, maintaining the capacity to detect incoming USB power delivery messages and FRS signaling.

3.57 Development support

3.57.1 Serial-wire/JTAG debug port (SWJ-DP)

The Arm SWJ-DP interface is embedded and is a combined JTAG and serial-wire debug port that enables either a serial wire debug or a JTAG probe to be connected to the target.

Debug is performed using two pins only instead of five required by the JTAG (JTAG pins can be re-used as GPIO with alternate function): the JTAG TMS and TCK pins are shared with SWDIO and SWCLK, respectively, and a specific sequence on the TMS pin is used to switch between JTAG-DP and SW-DP.

3.57.2 Embedded Trace Macrocell

The Arm Embedded Trace Macrocell (ETM) provides a greater visibility of the instruction and data flow inside the CPU core by streaming compressed data at a very high rate from the devices through a small number of ETM pins to an external hardware trace port analyzer (TPA) device.

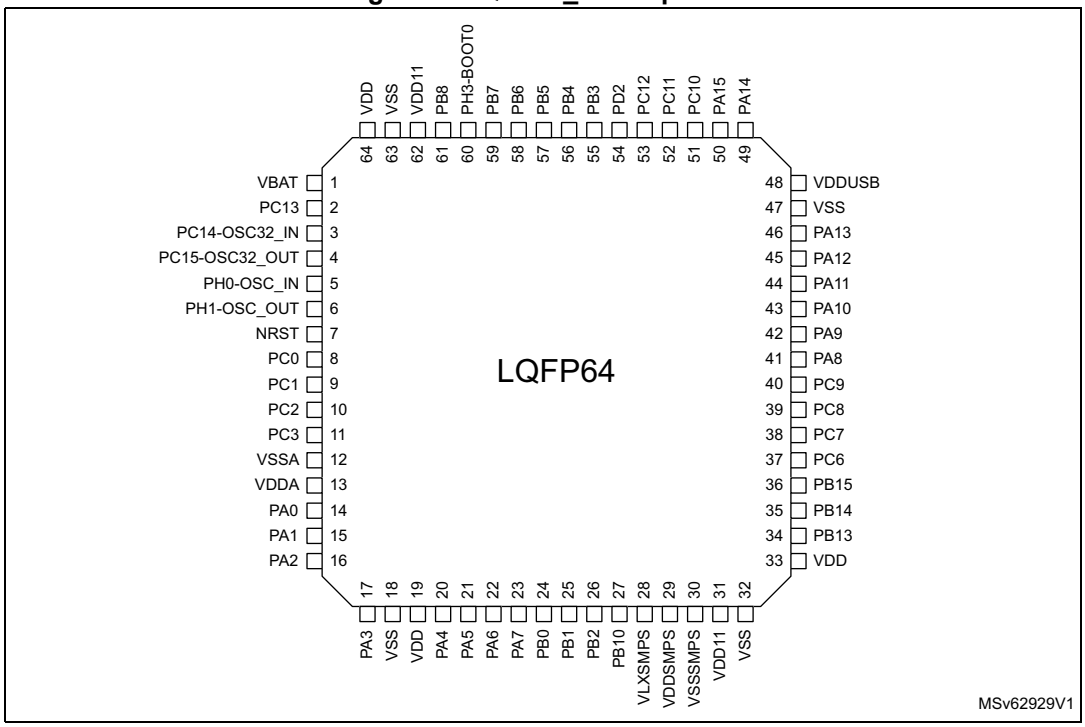
Real-time instruction and data flow activity be recorded and then formatted for display on the host computer that runs the debugger software. TPA hardware is commercially available from common development tool vendors.

The ETM operates with third party debugger software tools.

4 Pinout, pin description and alternate functions

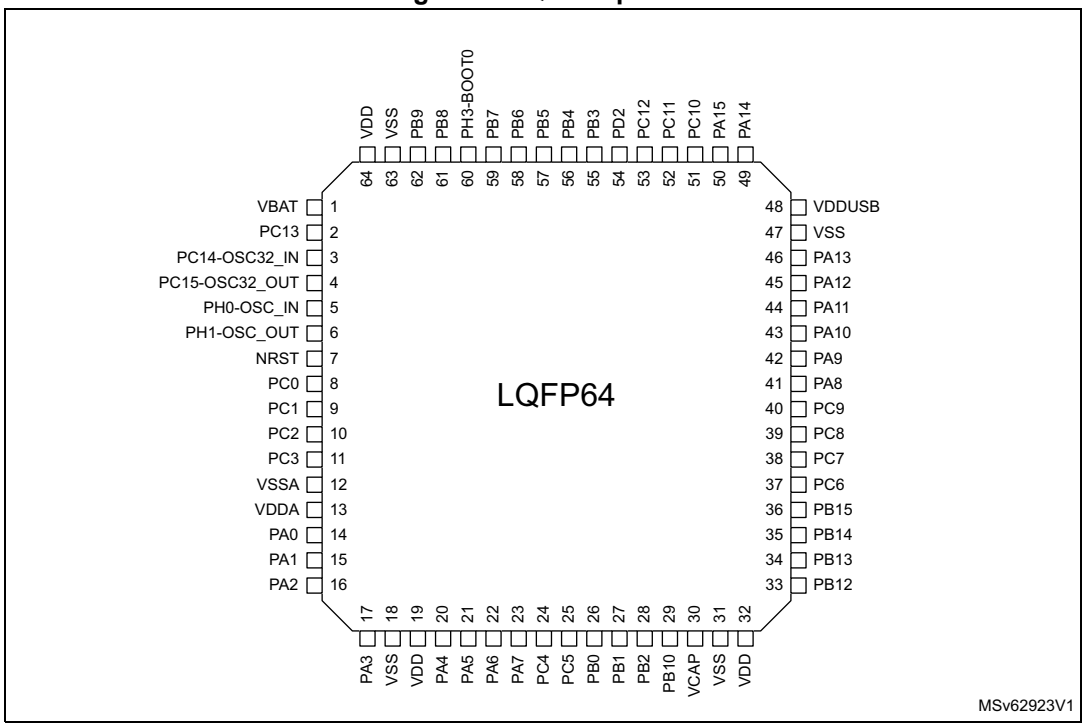
4.1 Pinout/ballout schematics

Figure 7. LQFP64_SMPS pinout



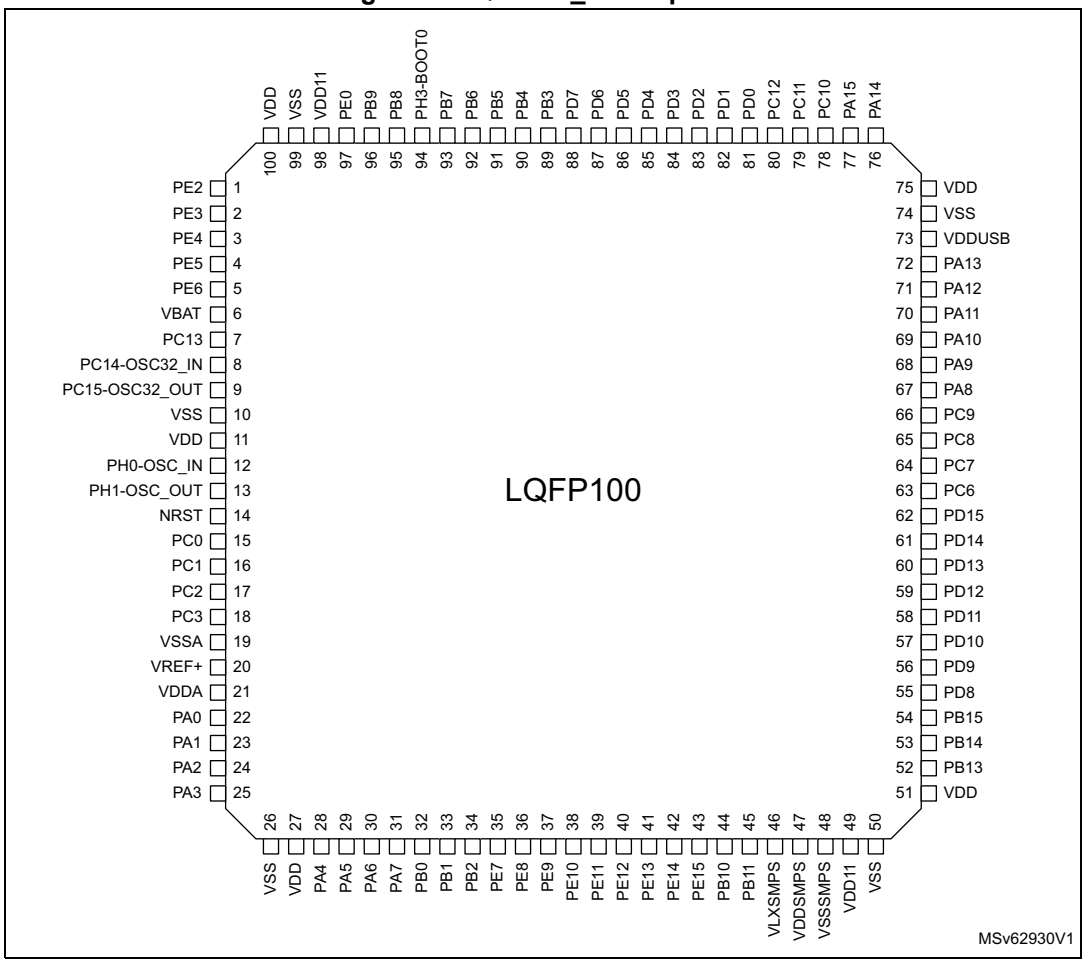
1. The above figure shows the package top view.

Figure 8. LQFP64 pinout



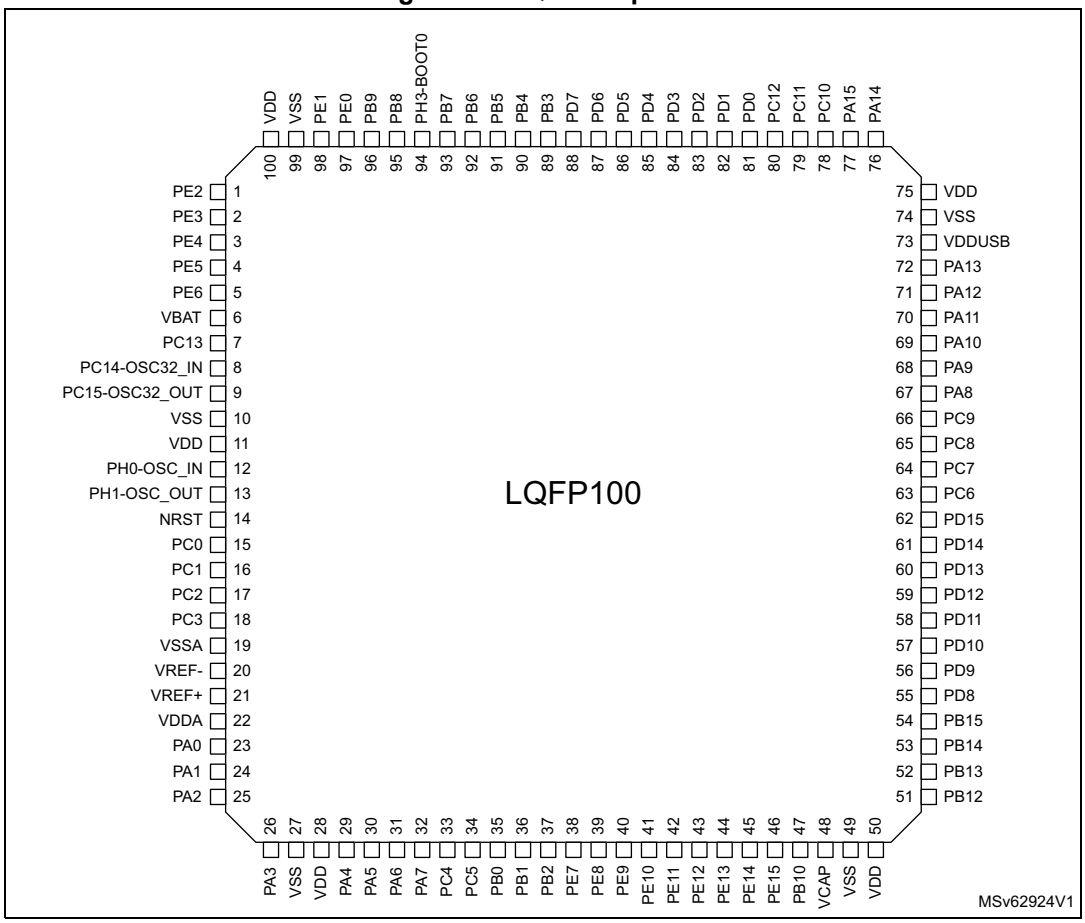
1. The above figure shows the package top view.

Figure 9. LQFP100_SMPS pinout



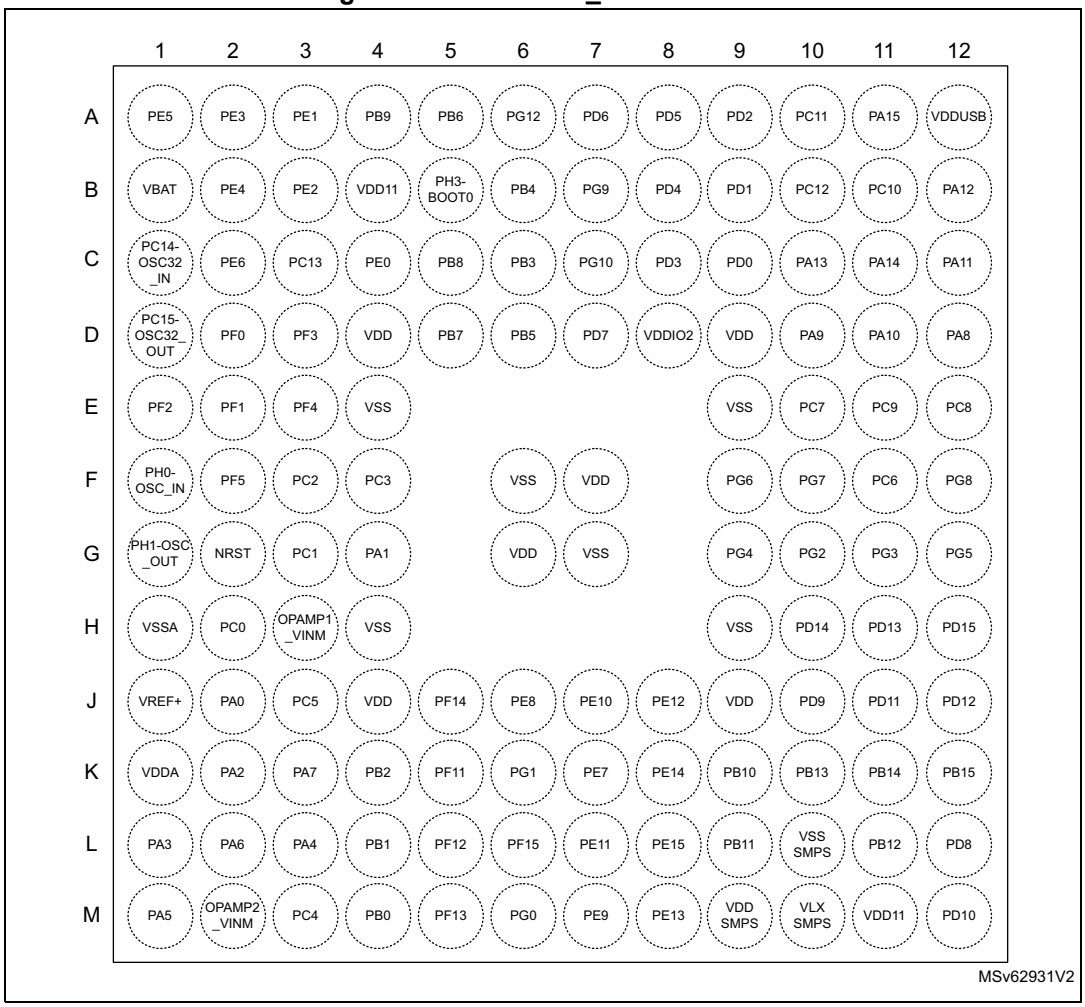
1. The above figure shows the package top view.

Figure 10. LQFP100 pinout



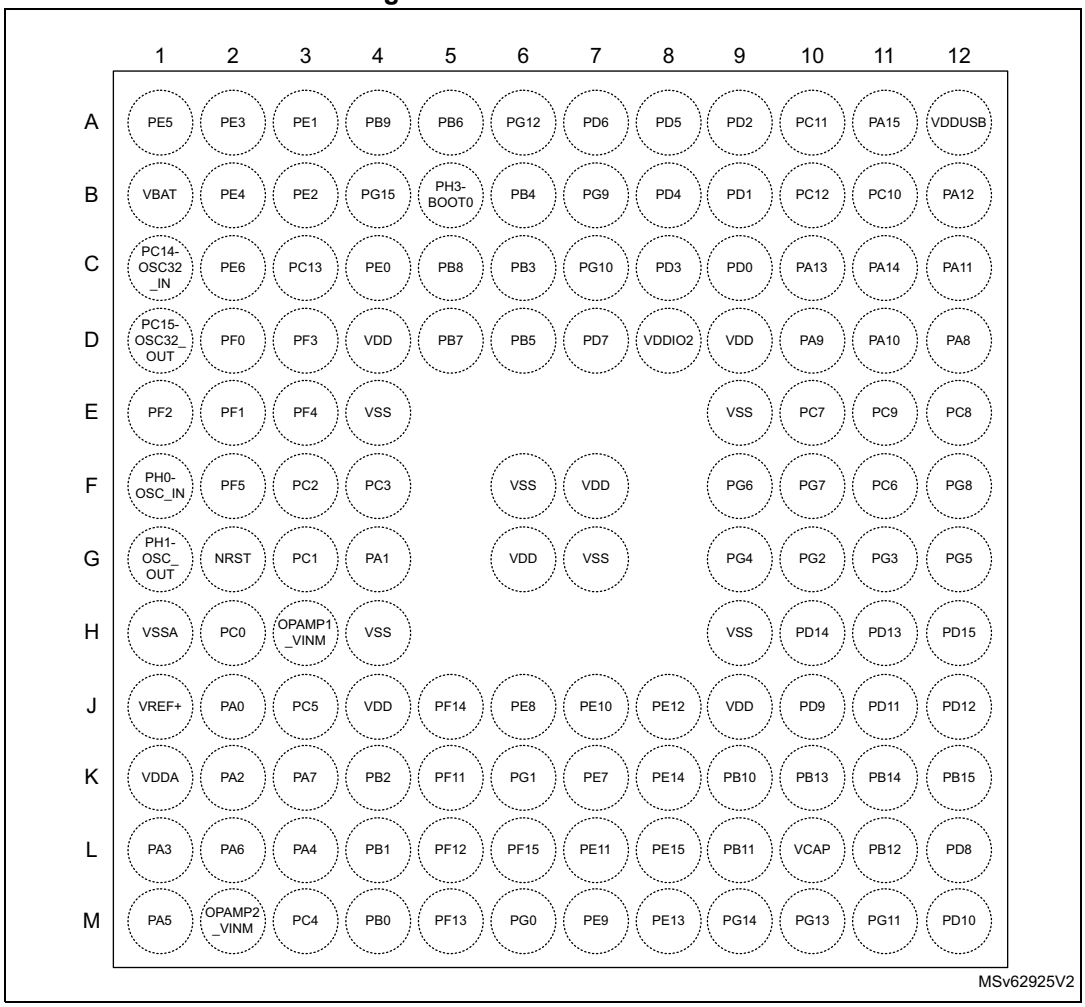
1. The above figure shows the package top view.

Figure 11. UFBGA132_SMPS ballout



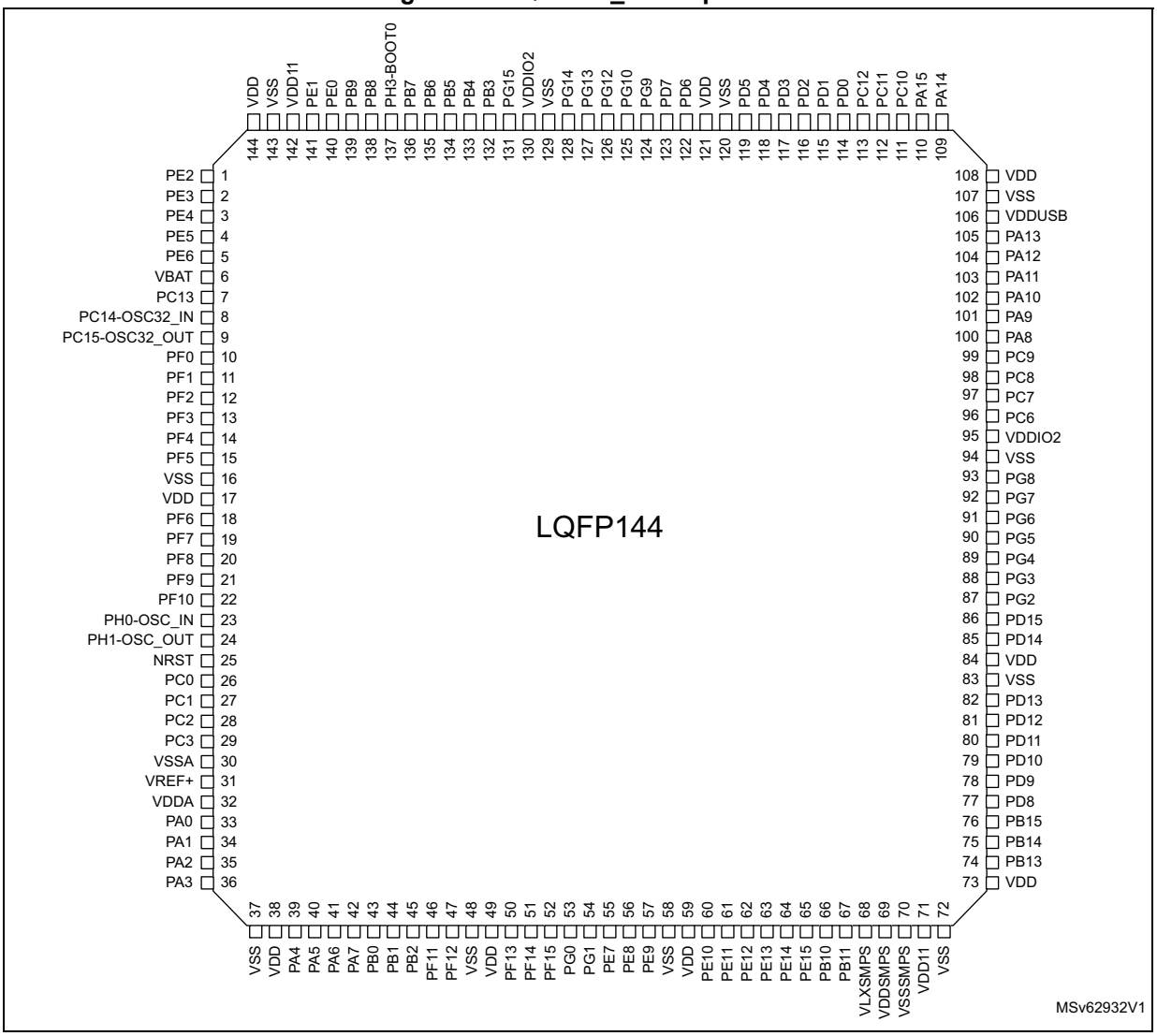
1. The above figure shows the package top view.

Figure 12. UFBGA132 ballout



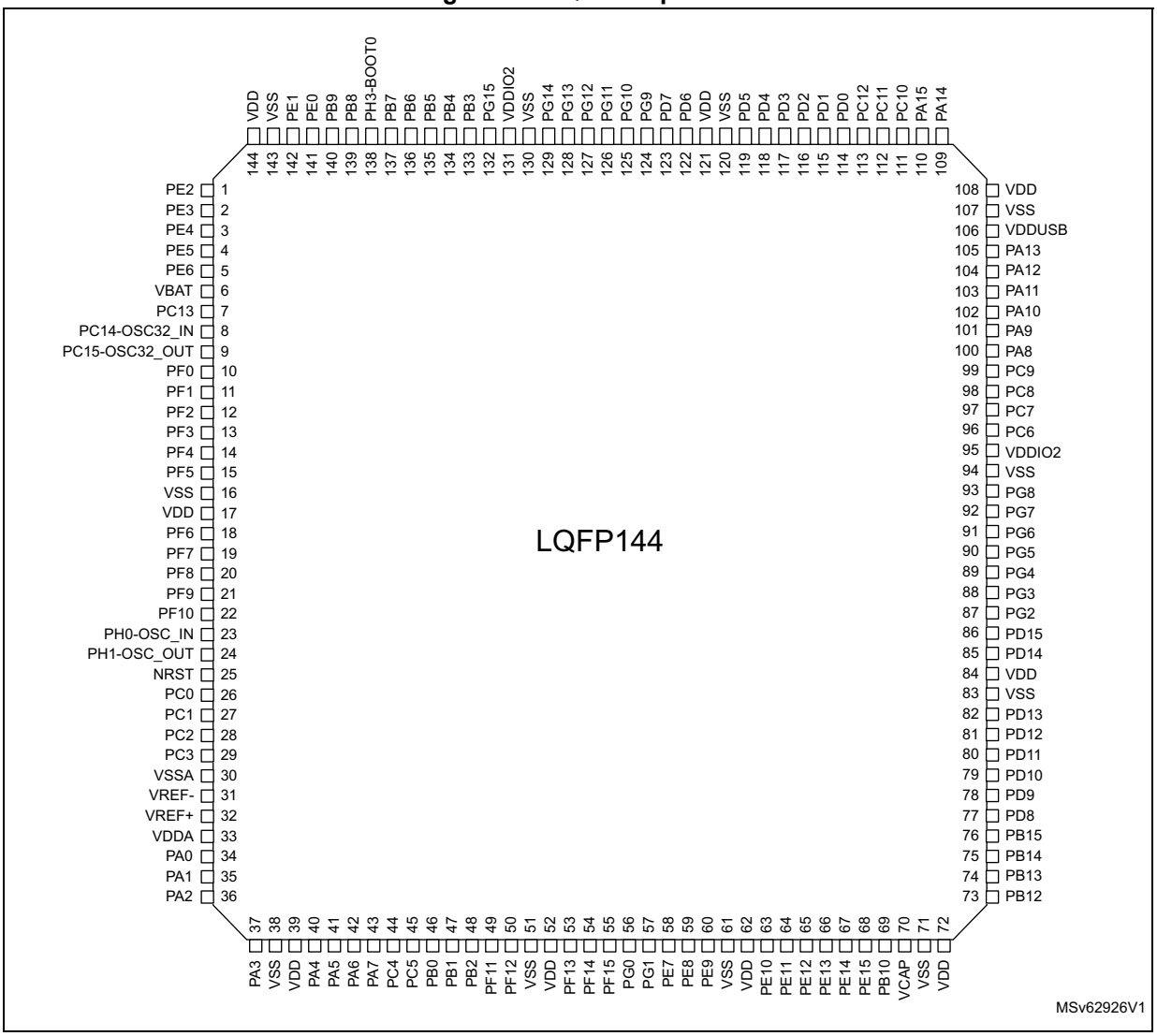
1. The above figure shows the package top view.

Figure 13. LQFP144_SMPS pinout



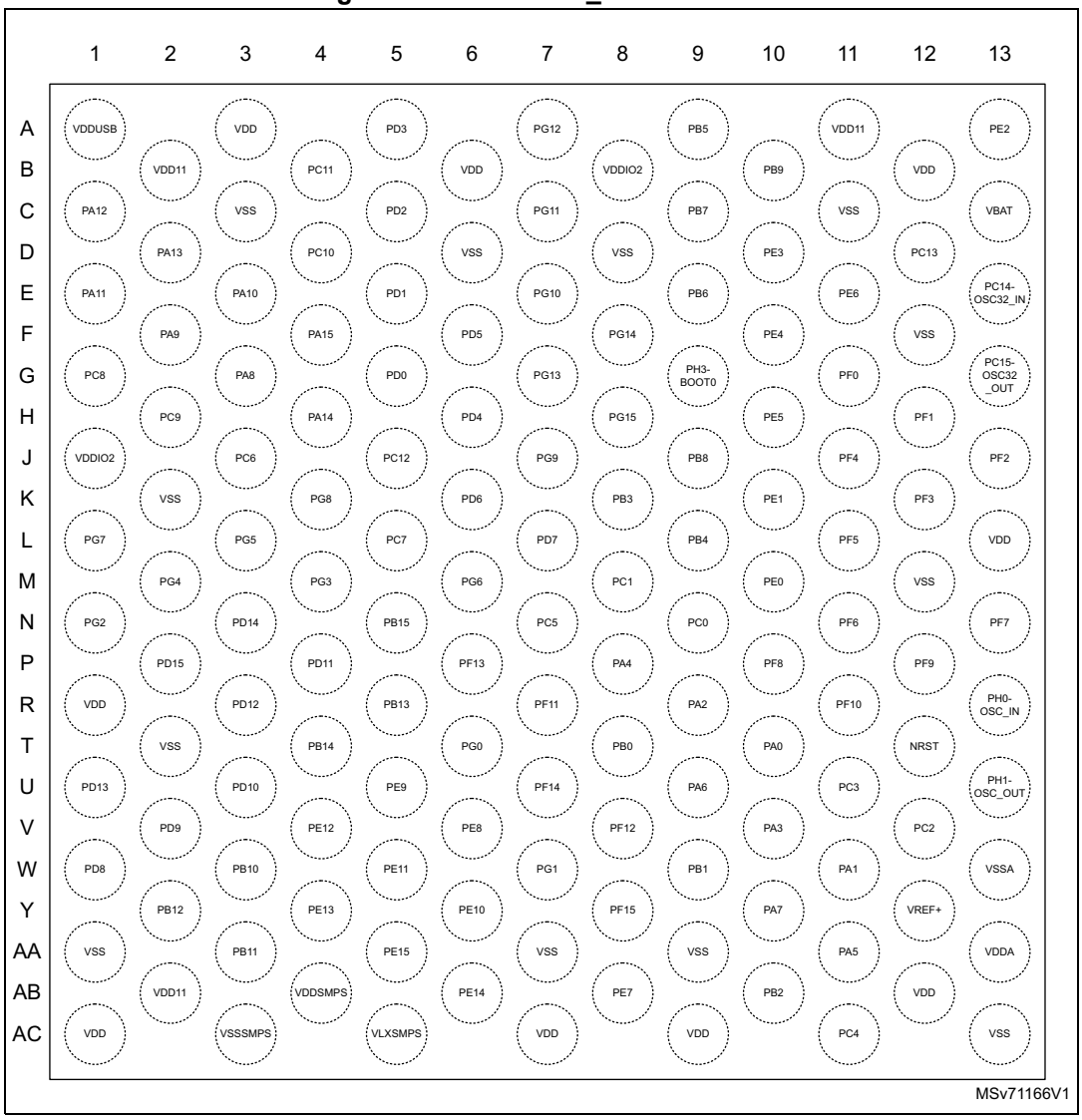
1. The above figure shows the package top view.

Figure 14. LQFP144 pinout



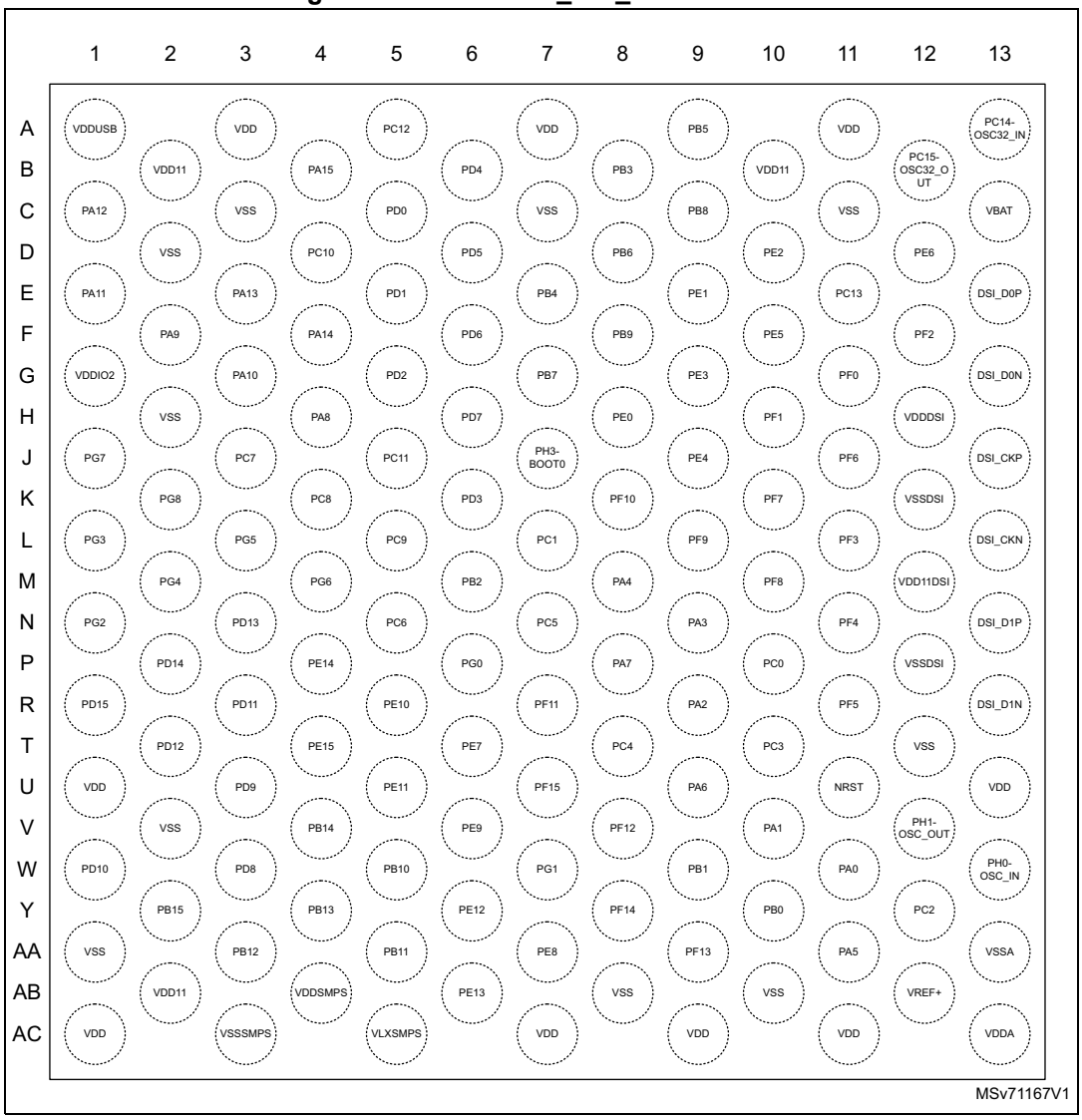
1. The above figure shows the package top view.

Figure 15. WLCSP150_SMPS ballout



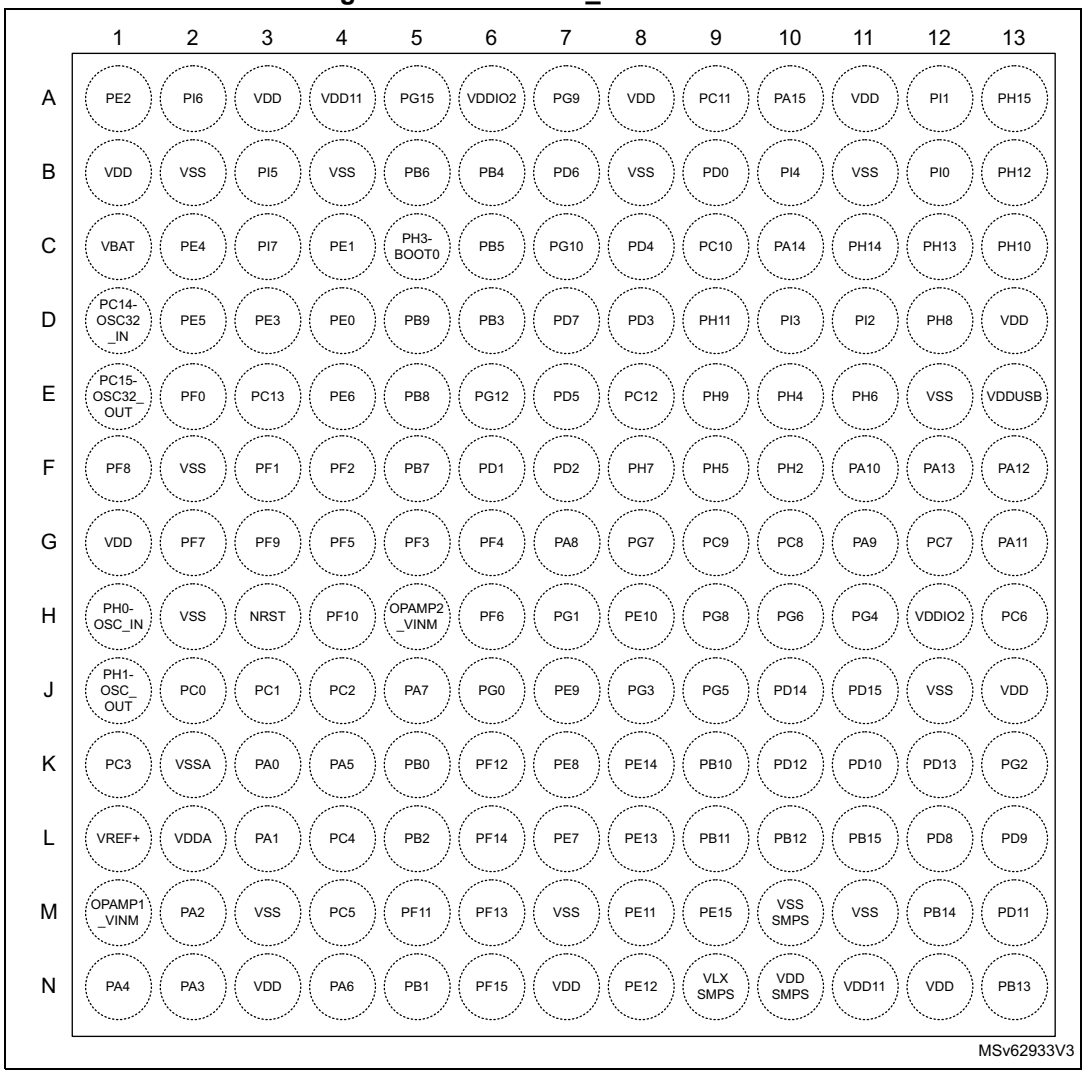
1. The above figure shows the package top view.

Figure 16. WLCSP150_DSI_SMPS ballout



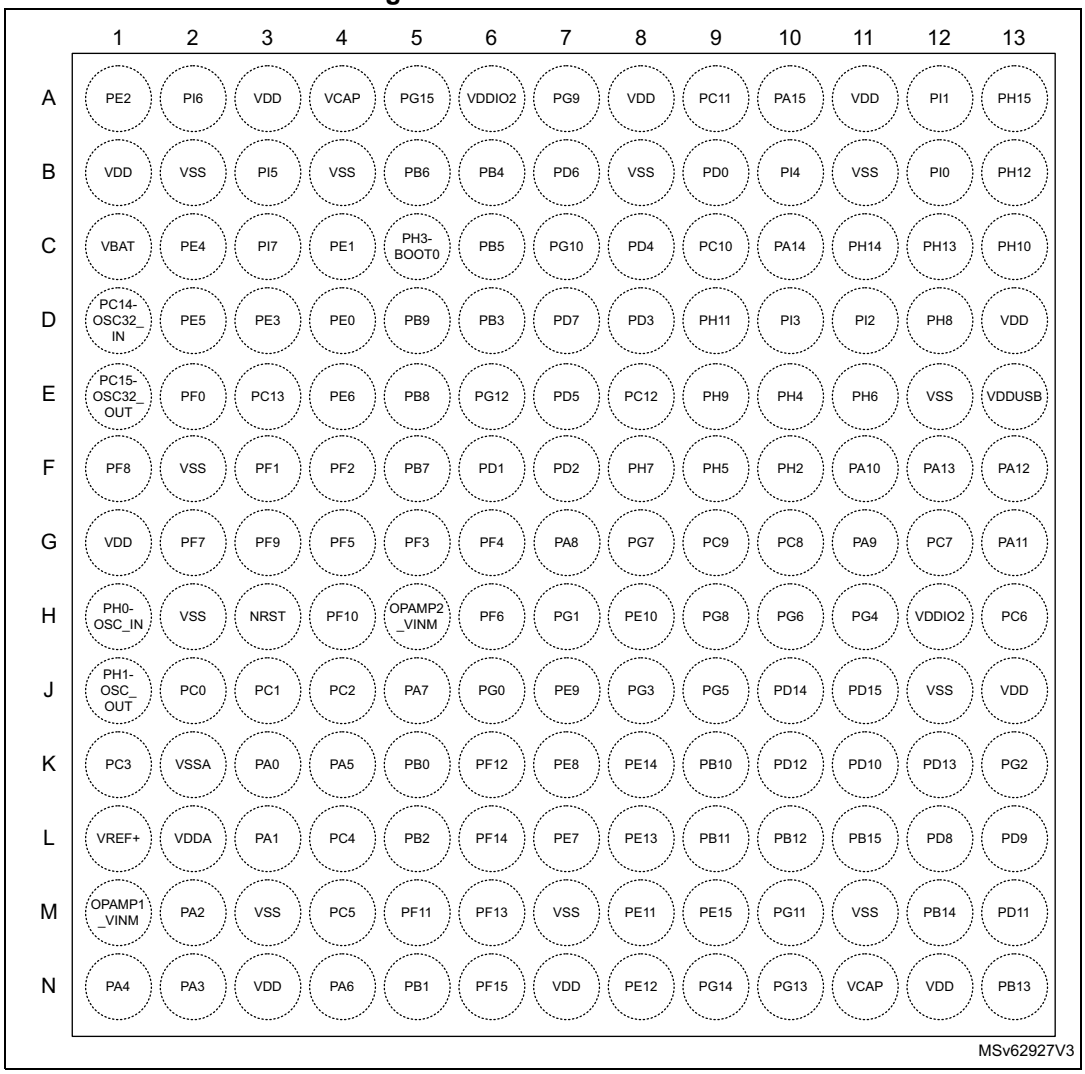
1. The above figure shows the package top view.

Figure 17. TFBGA169_SMPS ballout



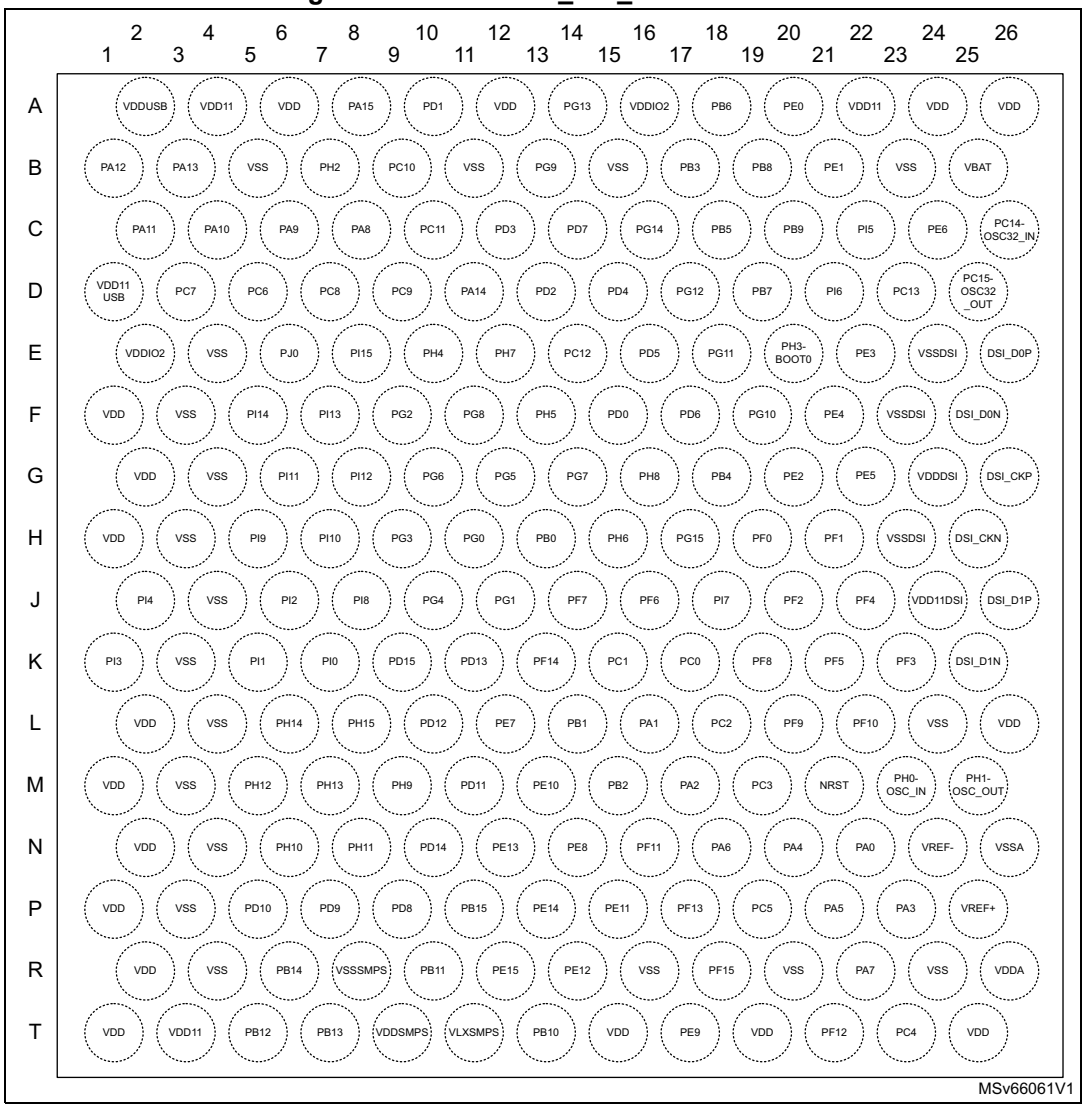
1. The above figure shows the package top view.

Figure 18. TFBGA169 ballout



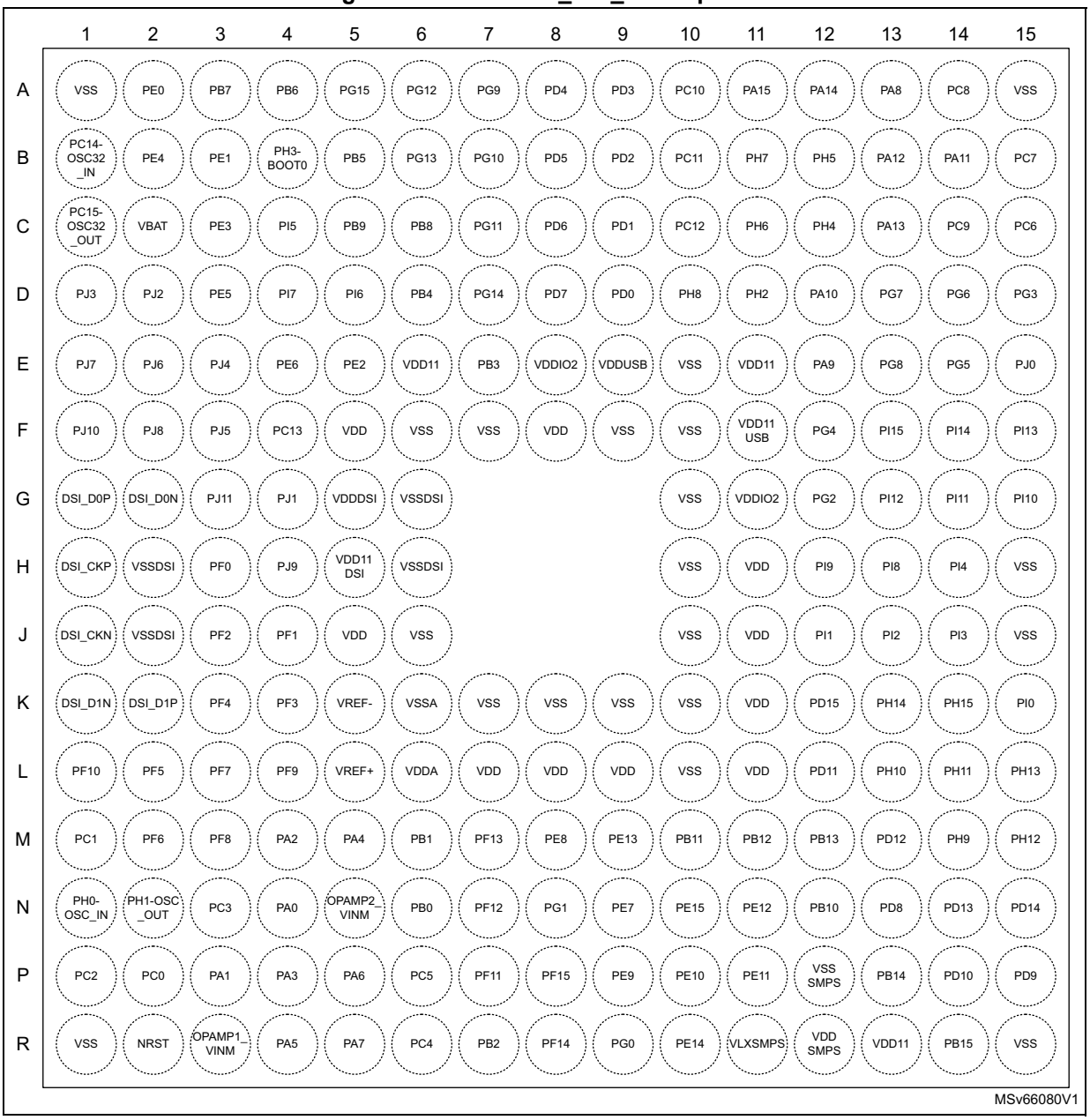
1. The above figure shows the package top view.

Figure 19. WLCSP208_DSI_SMPS ballout



1. The above figure shows the package top view.

Figure 20. TFBGA216_DSI_SMPS pinout



1. The above figure shows the package top view.

4.2 Pin description

Table 26. Legend/abbreviations used in the pinout table

Name		Abbreviation	Definition
Pin name		Unless otherwise specified in brackets below the pin name, the pin function during and after reset is the same as the actual pin name	
Pin type		S	Supply pin
		I	Input only pin
		I/O	Input/output pin
I/O structure		FT	5V-tolerant I/O
		TT	3.6V-tolerant I/O
		DSI	1.2 V I/O for DSI interface
		RST	Bidirectional reset pin with embedded weak pull-up resistor
		Option for TT or FT I/Os(1)	
		_a	I/O, with analog switch function supplied by V_{DDA}
		_c	I/O with USB Type-C power delivery function
		_d	I/O with USB Type-C power delivery dead battery function
		_f	I/O, Fm+ capable
		_h	I/O with high-speed low-voltage mode
		_o	I/O with OSC32_IN/OSC32_OUT capability
		_p	I/O with differential clock capability CLKP/CLKN
		_s	I/O supplied only by V_{DDIO2}
		_t	I/O with a function supplied by V_{SW}
		_u	I/O, with USB function supplied by V_{DDUSB}
		_v	I/O very high-speed capable
Notes		Unless otherwise specified by a note, all I/Os are set as analog inputs during and after reset.	
Pin functions	Alternate functions	Functions selected through GPIOx_AFR registers	
	Additional functions	Functions directly selected/enabled through peripheral registers	

1. The related I/O structures in the table below are a concatenation of various options. Examples: FT_hat, FT_fs, FT_u, TT_a.

Table 27. STM32U5Axxx pin/ball definitions(1)

| Pin number | | |

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	4	A1	4	H10	F10	D2	G22	D3	-	4	A1	4	D2	PE5	I/O	FT_hat	-	TRACED2, TIM3_CH3, SAI1_CK2, MDF1_CKI3, LCD_G0, TSC_G7_IO4, DCMI_D6/PSSI_D6, FMC_A21, SAI1_SCK_A, EVENTOUT	WKUP2, TAMP_IN8/ TAMP_OUT7
-	5	C2	5	E11	D12	E4	C24	E4	-	5	C2	5	E4	PE6	I/O	FT_ht	-	TRACED3, TIM3_CH4, SAI1_D1, LCD_G1, DCMI_D7/PSSI_D7, FMC_A22, SAI1_SD_A, EVENTOUT	WKUP3, TAMP_IN3/ TAMP_OUT6
1	6	B1	6	C13	C13	C1	B25	C2	1	6	B1	6	C1	VBAT	S	-	-	-	-
-	-	-	-	-	-	F2	B11	A1	-	-	-	-	F2	VSS	S	-	-	-	-
2	7	C3	7	D12	E11	E3	D23	F4	2	7	C3	7	E3	PC13	I/O	FT	(2) (3)	EVENTOUT	WKUP2, RTC_TS/ RTC_OUT1, TAMP_IN1/T AMP_OUT2
3	8	C1	8	E13	A13	D1	C26	B1	3	8	C1	8	D1	PC14-OSC32_IN (PC14)	I/O	FT_o	(2) (3)	EVENTOUT	OSC32_IN

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
4	9	D1	9	G13	B12	E1	D25	C1	4	9	D1	9	E1	PC15-OSC32_OUT (PC15)	I/O	FT_o	(2) (3)	EVENTOUT	OSC32_OUT
-	-	D2	10	G11	G11	E2	H19	H3	-	-	D2	10	E2	PF0	I/O	FT_fh	-	I2C6_SDA, I2C2_SDA, OCTOSPIM_P2_IO0, USART6_TX, FMC_A0, EVENTOUT	-
-	-	E2	11	H12	H10	F3	H21	J4	-	-	E2	11	F3	PF1	I/O	FT_fh	-	I2C6_SCL, I2C2_SCL, OCTOSPIM_P2_IO1, USART6_RX, FMC_A1, EVENTOUT	-
-	-	E1	12	J13	F12	F4	J20	J3	-	-	E1	12	F4	PF2	I/O	FT_h	-	LPTIM3_CH2, I2C2_SMBA, OCTOSPIM_P2_IO2, USART6_CK, FMC_A2, EVENTOUT	WKUP8
-	-	D3	13	K12	L11	G5	K23	K4	-	-	D3	13	G5	PF3	I/O	FT_h	-	LPTIM3_IN1, ADF1_CCK0, OCTOSPIM_P2_IO3, MDF1_CCK0, USART6_CTS, UART5_TX, FMC_A3, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	E3	14	J11	N11	G6	J22	K3	-	-	E3	14	G6	PF4	I/O	FT_hvp	-	LPTIM3_ETR, ADF1_SDI0, OCTOSPIM_P2_CLK, MDF1_SDI0, USART6_RTS_DE, UART5_RX, FMC_A4, EVENTOUT	-
-	-	F2	15	L11	R11	G4	K21	L2	-	-	F2	15	G4	PF5	I/O	FT_hvp	-	LPTIM3_CH1, OCTOSPIM_P2_NCLK, MDF1_CKI0, FMC_A5, EVENTOUT	-
-	10	F6	16	F12	-	H2	B15	A15	-	10	F6	16	H2	VSS	S	-	-	-	-
-	11	F7	17	L13	A11	G1	L26	F5	-	11	F7	17	G1	VDD	S	-	-	-	-
-	-	-	18	N11	J11	H6	J16	M2	-	-	-	18	H6	PF6	I/O	FT_h	-	TIM5_ETR, TIM5_CH1, DCMI_D12/PSSI_D12, OCTOSPIM_P2_NCS, OCTOSPIM_P1_IO3, SAI1_SD_B, EVENTOUT	-
-	-	-	19	N13	K10	G2	J14	L3	-	-	-	19	G2	PF7	I/O	FT_h	-	TIM5_CH2, FDCAN1_RX, OCTOSPIM_P1_IO2, SAI1_MCLK_B, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	20	P10	M10	F1	K19	M3	-	-	-	20	F1	PF8	I/O	FT_h	-	TIM5_CH3, PSSI_D14, FDCAN1_TX, OCTOSPIM_P1_IO0, SAI1_SCK_B, EVENTOUT	-
-	-	-	21	P12	L9	G3	L20	L4	-	-	-	21	G3	PF9	I/O	FT_h	-	TIM5_CH4, PSSI_D15, OCTOSPIM_P1_IO1, SAI1_FS_B, TIM15_CH1, EVENTOUT	-
-	-	-	22	R11	K8	H4	L22	L1	-	-	-	22	H4	PF10	I/O	FT_hv	-	OCTOSPIM_P1_CLK, PSSI_D15, MDF1_CCK1, DCMI_D11/PSSI_D11, DSI_TE, SAI1_D3, TIM15_CH2, EVENTOUT	-
5	12	F1	23	R13	W13	H1	M23	N1	5	12	F1	23	H1	PH0-OSC_IN (PH0)	I/O	FT	-	EVENTOUT	OSC_IN
6	13	G1	24	U13	V12	J1	M25	N2	6	13	G1	24	J1	PH1-OSC_OUT (PH1)	I/O	FT	-	EVENTOUT	OSC_OUT
7	14	G2	25	T12	U11	H3	M21	R2	7	14	G2	25	H3	NRST	I-O	RST	-	-	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
8	15	H2	26	N9	P10	J2	K17	P2	8	15	H2	26	J2	PC0	I/O	FT_fha	-	LPTIM1_IN1, OCTOSPIM_P1_IO7, I2C3_SCL(boot), SPI2_RDY, MDF1_SDI4, USART6_CTS, LPUART1_RX, SDMMC1_D5, SAI2_FS_A, LPTIM2_IN1, EVENTOUT	ADC1_IN1, ADC2_IN1, ADC4_IN1
9	16	G3	27	M8	L7	J3	K15	M1	9	16	G3	27	J3	PC1	I/O	FT_fhav	-	TRACED0, LPTIM1_CH1, SPI2_MOSI, I2C3_SDA(boot), MDF1_CKI4, USART6_CK, LPUART1_TX, OCTOSPIM_P1_IO4, SDMMC2_CK, SAI1_SD_A, EVENTOUT	ADC1_IN2, ADC2_IN2, ADC4_IN2

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
10	17	F3	28	V12	Y12	J4	L18	P1	10	17	F3	28	J4	PC2	I/O	FT_ha	-	LPTIM1_IN2, SPI2_MISO, MDF1_CCK1, USART6_RX, OCTOSPIM_P1_IO5, LPGPIO1_P5, EVENTOUT	ADC1_IN3, ADC2_IN3, ADC4_IN3
11	18	F4	29	U11	T10	K1	M19	N3	11	18	F4	29	K1	PC3	I/O	FT_ha	-	LPTIM1_ETR, LPTIM3_CH1, SAI1_D1, SPI2_MOSI, USART6_TX, OCTOSPIM_P1_IO6, SAI1_SD_A, LPTIM2_ETR, EVENTOUT	ADC1_IN4, ADC2_IN4, ADC4_IN4
12	19	H1	30	W13	AA13	K2	N26	K6	12	19	H1	30	K2	VSSA	S	-	-	-	-
-	-	-	-	-	-	-	N24	K5	-	20	-	31	-	VREF-	S	-	-	-	-
-	20	J1	31	Y12	AB12	L1	P25	L5	-	21	J1	32	L1	VREF+	S	-	-	-	VREFBUF_OUT
13	21	K1	32	AA13	AC13	L2	R26	L6	13	22	K1	33	L2	VDDA	S	-	-	-	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number				Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	14	-	PA0	I/O	FT_hat	-	TIM2_CH1, TIM5_CH1, TIM8_ETR, SPI3_RDY, USART2_CTS, UART4_TX, OCTOSPIM_P2_NCS, SDMMC2_CMD, AUDIOCLK, TIM2_ETR, EVENTOUT	OPAMP1_VINP, ADC1_IN5, ADC2_IN5, WKUP1, TAMP_IN2/TAMP_OUT1
LQFP100 SMPS	22	-							
UFBGA132 SMPS	J2	H3							
LQFP144 SMPS	33	-							
WLCSP150 SMPS	T10	-							
WLCSP150 DSI SMPS	W11	-							
TFBGA169 SMPS	K3	M1							
WLCSP208 DSI SMPS	N22	-							
TFBGA216 DSI SMPS	N4	R3							
LQFP64	14	-							
LQFP100	23	-							
UFBGA132	J2	H3							
LQFP144	34	-							
TFBGA169	K3	M1							
15	23	34	W11	V10	L3	L16	P3	15	24	G4	35	L3	PA1	I/O	FT_hat	-	LPTIM1_CH2, TIM2_CH2, TIM5_CH2, I2C1_SMBA, SPI1_SCK, USART2_RTS_DE, UART4_RX, OCTOSPIM_P1_DQS, LPGPIO1_P0, TIM15_CH1N, EVENTOUT	OPAMP1_VINM, ADC1_IN6, ADC2_IN6, WKUP3, TAMP_IN5/TAMP_OUT4

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
16	24	K2	35	R9	R9	M2	M17	M4	16	25	K2	36	M2	PA2	I/O	FT_ha	-	TIM2_CH3, TIM5_CH3, SPI1_RDY, USART2_TX(boot), LPUART1_TX, OCTOSPIM_P1_NCS, UCPD1_FRSTX1, TIM15_CH1, EVENTOUT	COMP1_INP3, ADC1_IN7, ADC2_IN7, WKUP4/ LSCO
17	25	L1	36	V10	N9	N2	P23	P4	17	26	L1	37	N2	PA3	I/O	TT_hav	-	TIM2_CH4, TIM5_CH4, SAI1_CK1, USART2_RX(boot), LPUART1_RX, OCTOSPIM_P1_CLK, LPGPIO1_P1, SAI1_MCLK_A, TIM15_CH2, EVENTOUT	OPAMP1_VOUT, ADC1_IN8, ADC2_IN8, WKUP5
18	26	G7	37	AC13	AB10	M3	B23	E10	18	27	G7	38	M3	VSS	S	-	-	-	-
19	27	G6	38	AB12	A3	N3	T25	F8	19	28	G6	39	N3	VDD	S	-	-	-	-
20	28	L3	39	P8	M8	N1	N20	M5	20	29	L3	40	N1	PA4	I/O	TT_ha	-	OCTOSPIM_P1_NCS, SPI1_NSS(boot), SPI3_NSS, USART2_CK, DCMI_HSYNC/PSSI_DE, SAI1_FS_B, LPTIM2_CH1, EVENTOUT	ADC1_IN9, ADC2_IN9, ADC4_IN9, DAC1_OUT1, WKUP2

Table 27. STM32U5Axxx pin/ball definitions(1) (continued)

| Pin number | | |

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
23	31	K3	42	Y10	P8	J5	R22	R5	23	32	K3	43	J5	PA7	I/O	FT_fha	-	SRDSTOP, TIM1_CH1N, TIM3_CH2, TIM8_CH1N, I2C3_SCL, SPI1_MOSI(boot), USART3_TX, OCTOSPIM_P1_IO2, LPTIM2_CH2, TIM17_CH1, EVENTOUT	OPAMP2_VINM, ADC1_IN12, ADC2_IN12, ADC4_IN20, WKUP8
-	-	M3	-	AC11	T8	L4	T23	R6	24	33	M3	44	L4	PC4	I/O	FT_ha	-	I2C6_SMBA, USART3_TX, OCTOSPIM_P1_IO7, EVENTOUT	COMP1_INM2, ADC1_IN13, ADC2_IN13, ADC4_IN22
-	-	J3	-	N7	N7	M4	P19	P6	25	34	J3	45	M4	PC5	I/O	FT_at	-	TIM1_CH4N, SAI1_D3, PSSI_D15, USART3_RX, EVENTOUT	COMP1_INP1, ADC1_IN14, ADC2_IN14, ADC4_IN23, WKUP5, TAMP_IN4/TAMP_OUT5

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
24	32	M4	43	T8	Y10	K5	H13	N6	26	35	M4	46	K5	PB0	I/O	TT_ha	-	TIM1_CH2N, TIM3_CH3, TIM8_CH2N, LPTIM3_CH1, SPI1_NSS, USART3_CK, OCTOSPIM_P1_IO1, LPGPIO1_P9, COMP1_OUT, AUDIOCLK, EVENTOUT	OPAMP2_VOUT, ADC1_IN15, ADC2_IN15, ADC4_IN18
25	33	L4	44	W9	W9	N5	L14	M6	27	36	L4	47	N5	PB1	I/O	FT_ha	-	TIM1_CH3N, TIM3_CH4, TIM8_CH3N, LPTIM3_CH2, MDF1_SDI0, USART3_RTS_DE, LPUART1_RTS_DE, OCTOSPIM_P1_IO0, LPGPIO1_P3, LPTIM2_IN1, EVENTOUT	COMP1_INM1, ADC1_IN16, ADC2_IN16, ADC4_IN19, WKUP4

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
26	34	K4	45	AB10	M6	L5	M15	R7	28	37	K4	48	L5	PB2	I/O	FT_hat	-	LPTIM1_CH1, TIM8_CH4N, I2C3_SMBA, SPI1_RDY, MDF1_CKI0, LCD_B1, OCTOSPIM_P1_DQS, UCPD1_FRSTX1, EVENTOUT	COMP1_INP2, ADC1_IN17, ADC2_IN17, WKUP1, RTC_OUT2
-	-	K5	46	R7	R7	M5	N16	P7	-	-	K5	49	M5	PF11	I/O	FT_hv	-	OCTOSPIM_P1_NCLK, LCD_DE, DCMI_D12/PSSI_D12, DSI_TE, LPTIM4_IN1, EVENTOUT	-
-	-	L5	47	V8	V8	K6	T21	N7	-	-	L5	50	K6	PF12	I/O	FT_h	-	OCTOSPIM_P2_DQS, LCD_B0, FMC_A6, LPTIM4_ETR, EVENTOUT	-
-	-	-	48	AA9	AB8	M7	B5	F10	-	-	-	51	M7	VSS	S	-	-	-	-
-	-	-	49	AC9	A7	N7	T19	J5	-	-	-	52	N7	VDD	S	-	-	-	-
-	-	M5	50	P6	AA9	M6	P17	M7	-	-	M5	53	M6	PF13	I/O	FT_h	-	I2C4_SMBA, LCD_B1, UCPD1_FRSTX2, FMC_A7, LPTIM4_OUT, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	J5	51	U7	Y8	L6	K13	R8	-	-	J5	54	L6	PF14	I/O	FT_fha	-	I2C4_SCL, LCD_G0, TSC_G8_IO1, FMC_A8, EVENTOUT	ADC4_IN5
-	-	L6	52	Y8	U7	N6	R18	P8	-	-	L6	55	N6	PF15	I/O	FT_fha	-	I2C4_SDA, LCD_G1, TSC_G8_IO2, FMC_A9, EVENTOUT	ADC4_IN6
-	-	M6	53	T6	P6	J6	H11	R9	-	-	M6	56	J6	PG0	I/O	FT_ha	-	OCTOSPIM_P2_IO4, TSC_G8_IO3, FMC_A10, EVENTOUT	ADC4_IN7
-	-	K6	54	W7	W7	H7	J12	N8	-	-	K6	57	H7	PG1	I/O	FT_ha	-	OCTOSPIM_P2_IO5, TSC_G8_IO4, FMC_A11, EVENTOUT	ADC4_IN8
-	35	K7	55	AB8	T6	L7	L12	N9	-	38	K7	58	L7	PE7	I/O	FT_h	-	TIM1_ETR, MDF1_SDI2, LCD_B6, FMC_D4, SAI1_SD_B, EVENTOUT	WKUP6
-	36	J6	56	V6	AA7	K7	N14	M8	-	39	J6	59	K7	PE8	I/O	FT_h	-	TIM1_CH1N, MDF1_CKI2, LCD_B7, FMC_D5, SAI1_SCK_B, EVENTOUT	WKUP7

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	37	M7	57	U5	V6	J7	T17	P9	-	40	M7	60	J7	PE9	I/O	FT_hv	-	TIM1_CH1, ADF1_CCK0, MDF1_CCK0, LCD_G2, OCTOSPIM_P1_NCLK, FMC_D6, SAI1_FS_B, EVENTOUT	-
-	-	-	58	AA7	C11	-	E4	F6	-	-	-	61	-	VSS	S	-	-	-	-
-	-	J4	59	AC7	AC1	-	T15	L7	-	-	J4	62	-	VDD	S	-	-	-	-
-	38	J7	60	Y6	R5	H8	M13	P10	-	41	J7	63	H8	PE10	I/O	FT_hav	-	TIM1_CH2N, ADF1_SDI0, MDF1_SDI4, LCD_G3, TSC_G5_IO1, OCTOSPIM_P1_CLK, FMC_D7, SAI1_MCLK_B, EVENTOUT	-
-	39	L7	61	W5	U5	M8	P15	P11	-	42	L7	64	M8	PE11	I/O	FT_ha	-	TIM1_CH2, SPI1_RDY, MDF1_CKI4, LCD_G4, TSC_G5_IO2, OCTOSPIM_P1_NCS, FMC_D8, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	40	J8	62	V4	Y6	N8	R14	N11	-	43	J8	65	N8	PE12	I/O	FT_ha	-	TIM1_CH3N, SPI1_NSS, MDF1_SDI5, LCD_G5, TSC_G5_IO3, OCTOSPIM_P1_IO0, FMC_D9, EVENTOUT	-
-	41	M8	63	Y4	AB6	L8	N12	M9	-	44	M8	66	L8	PE13	I/O	FT_ha	-	TIM1_CH3, SPI1_SCK, MDF1_CKI5, LCD_G6, TSC_G5_IO4, OCTOSPIM_P1_IO1, FMC_D10, EVENTOUT	-
-	42	K8	64	AB6	P4	K8	P13	R10	-	45	K8	67	K8	PE14	I/O	FT_h	-	TIM1_CH4, TIM1_BKIN2, SPI1_MISO, LCD_G7, OCTOSPIM_P1_IO2, FMC_D11, EVENTOUT	-
-	43	L8	65	AA5	T4	M9	R12	N10	-	46	L8	68	M9	PE15	I/O	FT_h	-	TIM1_BKIN, TIM1_CH4N, SPI1_MOSI, LCD_R2, OCTOSPIM_P1_IO3, FMC_D12, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
27	44	K9	66	W3	W5	K9	T13	N12	29	47	K9	69	K9	PB10	I/O	FT_fhv	-	TIM2_CH3, LPTIM3_CH1, I2C4_SCL, I2C2_SCL(boot), SPI2_SCK, USART3_TX, LPUART1_RX, TSC_SYNC, OCTOSPIM_P1_CLK, LPGPIO1_P4, COMP1_OUT, SAI1_SCK_A, EVENTOUT	WKUP8
-	45	L9	67	AA3	AA5	L9	R10	M10	-	-	L9	-	L9	PB11	I/O	FT_fh	-	TIM2_CH4, I2C4_SDA, I2C2_SDA(boot), SPI2_RDY, USART3_RX, LPUART1_TX, OCTOSPIM_P1_NCS, COMP2_OUT, EVENTOUT	-
28	46	M10	68	AC5	AC5	N9	T11	R11	-	-	-	-	-	VLXSMPS	S	-	-	-	-
29	47	M9	69	AB4	AB4	N10	T9	R12	-	-	-	-	-	VDDSMPS	S	-	-	-	-
30	48	L10	70	AC3	AC3	M10	R8	P12	-	-	-	-	-	VSSSMPS	S	-	-	-	-
-	-	-	-	-	-	-	-	-	30	48	L10	70	N11	VCAP	S	-	-	-	-
31	49	M11	71	AB2	AB2	N11	T3	R13	-	-	-	-	-	VDD11	S	-	-	-	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
32	50	E9	72	AA1	C3	M11	F3	F7	31	49	E9	71	M11	VSS	S	-	-	-	-
33	51	D4	73	AC1	AC11	N12	P1	L8	32	50	D4	72	N12	VDD	S	-	-	-	-
-	-	-	-	-	-	-	T1	-	-	-	-	-	-	VDD	S	-	-	-	-
-	-	L11	-	Y2	AA3	L10	T5	M11	33	51	L11	73	L10	PB12	I/O	FT_hav	-	TIM1_BKIN, I2C6_SMBA, I2C2_SMBA, SPI2_NSS(boot), MDF1_SDI1, USART3_CK, LPUART1_RTS_DE, TSC_G1_IO1, OCTOSPIM_P1_NCLK, SAI2_FS_A, TIM15_BKIN, EVENTOUT	-
34	52	K10	74	R5	Y4	N13	T7	M12	34	52	K10	74	N13	PB13	I/O	FT_fa	-	TIM1_CH1N, LPTIM3_IN1, I2C2_SCL, SPI2_SCK(boot), MDF1_CKI1, USART3_CTS, LPUART1_CTS, TSC_G1_IO2, SAI2_SCK_A, TIM15_CH1N, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
35	53	K11	75	T4	V4	M12	R6	P13	35	53	K11	75	M12	PB14	I/O	FT_fda	-	TIM1_CH2N, LPTIM3_ETR, TIM8_CH2N, I2C2_SDA, SPI2_MISO(boot), MDF1_SDI2, USART3_RTS_DE, TSC_G1_IO3, SDMMC2_D0, SAI2_MCLK_A, TIM15_CH1, EVENTOUT	UCPD1_DBCC2
36	54	K12	76	N5	Y2	L11	P11	R14	36	54	K12	76	L11	PB15	I/O	FT_c	(4)	RTC_REFIN, TIM1_CH3N, LPTIM2_IN2, TIM8_CH3N, SPI2_MOSI(boot), MDF1_CKI2, FMC_NBL1, SDMMC2_D1, SAI2_SD_A, TIM15_CH2, EVENTOUT	UCPD1_CC2, WKUP7
-	-	-	-	-	H12	-	G24	G5	-	-	-	-	-	VDDDSI	S	-	-	-	-
-	-	-	-	-	M12	-	J24	H5	-	-	-	-	-	VDD11DSI	S	-	-	-	-
-	-	-	-	-	E13	-	E26	G1	-	-	-	-	-	DSI_D0P	I/O	DSI	-	-	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	-	G13	-	F25	G2	-	-	-	-	-	DSI_D0N	I/O	DSI	-	-	-
-	-	-	-	-	K12	-	E24	G6	-	-	-	-	-	VSSDSI	S	-	-	-	-
-	-	-	-	-	-	-	H23	H6	-	-	-	-	-	VSSDSI	S	-	-	-	-
-	-	-	-	-	J13	-	G26	H1	-	-	-	-	-	DSI_CKP	I/O	DSI	-	-	-
-	-	-	-	-	L13	-	H25	J1	-	-	-	-	-	DSI_CKN	I/O	DSI	-	-	-
-	-	-	-	-	N13	-	J26	K2	-	-	-	-	-	DSI_D1P	I/O	DSI	-	-	-
-	-	-	-	-	R13	-	K25	K1	-	-	-	-	-	DSI_D1N	I/O	DSI	-	-	-
-	-	-	-	-	P12	-	F23	H2	-	-	-	-	-	VSSDSI	S	-	-	-	-
-	-	-	-	-	-	-	-	J2	-	-	-	-	-	VSSDSI	S	-	-	-	-
-	55	L12	77	W1	W3	L12	P9	N13	-	55	L12	77	L12	PD8	I/O	FT_h	-	USART3_TX, LCD_R3, DCMI_HSYNC/PSSI_DE, FMC_D13, EVENTOUT	-
-	56	J10	78	V2	U3	L13	P7	P15	-	56	J10	78	L13	PD9	I/O	FT_h	-	LPTIM2_IN2, USART3_RX, LCD_R4, DCMI_PIXCLK/PSSI_PDCK, FMC_D14, SAI2_MCLK_A, LPTIM3_IN1, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

| Pin number | | |

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	60	H11	82	U1	N3	K12	K11	N14	-	60	H11	82	K12	PD13	I/O	FT_fha	-	TIM4_CH2, I2C4_SDA, USART6_CTS, LCD_VSYNC, TSC_G6_IO4, LPGPIO1_P6, FMC_A18, LPTIM4_IN1, LPTIM2_CH1, EVENTOUT	ADC4_IN17
-	-	-	83	T2	C7	J12	G4	F9	-	-	-	83	J12	VSS	S	-	-	-	-
-	-	-	84	R1	AC9	A11	R2	L9	-	-	-	84	J13	VDD	S	-	-	-	-
-	61	H10	85	N3	P2	J10	N10	N15	-	61	H10	85	J10	PD14	I/O	FT_h	-	TIM4_CH3, USART6_CK, LCD_B2, FMC_D0, LPTIM3_CH1, EVENTOUT	-
-	62	H12	86	P2	R1	J11	K9	K12	-	62	H12	86	J11	PD15	I/O	FT_h	-	TIM4_CH4, USART6_RTS_DE, LCD_B3, FMC_D1, LPTIM3_CH2, EVENTOUT	-
-	-	G10	87	N1	N1	K13	F9	G12	-	-	G10	87	K13	PG2	I/O	FT_hs	-	SPI1_SCK, FMC_A12, SAI2_SCK_B, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	G11	88	M4	L1	J8	H9	D15	-	-	G11	88	J8	PG3	I/O	FT_hs	-	SPI1_MISO, FMC_A13, SAI2_FS_B, EVENTOUT	-
-	-	G9	89	M2	M2	H11	J10	F12	-	-	G9	89	H11	PG4	I/O	FT_hs	-	SPI1_MOSI, FMC_A14, SAI2_MCLK_B, EVENTOUT	-
-	-	G12	90	L3	L3	J9	G12	E14	-	-	G12	90	J9	PG5	I/O	FT_hs	-	SPI1_NSS, LPUART1_CTS, DSI_TE, FMC_A15, SAI2_SD_B, EVENTOUT	-
-	-	F9	91	M6	M4	H10	G10	D14	-	-	F9	91	H10	PG6	I/O	FT_hs	-	OCTOSPIM_P1_DQS, I2C3_SMBA, SPI1_RDY, LCD_R1, LPUART1_RTS_DE, UCPD1_FRSTX1, EVENTOUT	-
-	-	F10	92	L1	J1	G8	G14	D13	-	-	F10	92	G8	PG7	I/O	FT_fhs	-	SAI1_CK1, I2C3_SCL, OCTOSPIM_P2_DQS, MDF1_CCK0, LPUART1_TX, UCPD1_FRSTX2, FMC_INT, SAI1_MCLK_A, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	F12	93	K4	K2	H9	F11	E13	-	-	F12	93	H9	PG8	I/O	FT_fs	-	I2C3_SDA, LPUART1_RX, EVENTOUT	-
-	-	-	94	K2	-	-	N4	G10	-	-	-	94	-	VSS	S	-	-	-	-
-	-	-	95	J1	G1	H12	E2	G11	-	-	-	95	H12	VDDIO2	S	-	-	-	-
37	63	F11	96	J3	N5	H13	D5	C15	37	63	F11	96	H13	PC6	I/O	FT_a	-	CSLEEP, TIM3_CH1, TIM8_CH1, MDF1_CKI3, LCD_R0, SDMMC1_D0DIR, TSC_G4_IO1, DCMI_D0/PSSI_D0, SDMMC2_D6, SDMMC1_D6, SAI2_MCLK_A, EVENTOUT	-
38	64	E10	97	L5	J3	G12	D3	B15	38	64	E10	97	G12	PC7	I/O	FT_a	-	CDSTOP, TIM3_CH2, TIM8_CH2, MDF1_SDI3, LCD_R1, SDMMC1_D123DIR, TSC_G4_IO2, DCMI_D1/PSSI_D1, SDMMC2_D7, SDMMC1_D7, SAI2_MCLK_B, LPTIM2_CH2, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number													Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169					
39	65	E12	98	G1	K4	G10	D7	A14	39	65	E12	98	G10	PC8	I/O	FT_a	-	SRDSTOP, TIM3_CH3, TIM8_CH3, USART6_RX, TSC_G4_IO3, DCMI_D2/PSSI_D2, SDMMC1_D0, LPTIM3_CH1, EVENTOUT	-
40	66	E11	99	H2	L5	G9	D9	C14	40	66	E11	99	G9	PC9	I/O	FT_a	-	TRACED0, TIM8_BKIN2, TIM3_CH4, TIM8_CH4, DCMI_D3/PSSI_D3, USART6_TX, TSC_G4_IO4, SDMMC1_D1, LPTIM3_CH2, EVENTOUT	-
41	67	D12	100	G3	H4	G7	C8	A13	41	67	D12	100	G7	PA8	I/O	FT_hv	-	MCO, TIM1_CH1, SAI1_CK2, SPI1_RDY, USART1_CK, OTG_HS_SOF, TRACECLK, SAI1_SCK_A, LPTIM2_CH1, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
42	68	D10	101	F2	F2	G11	C6	E12	42	68	D10	101	G11	PA9	I/O	FT_u	-	TIM1_CH2, SPI2_SCK, DCMI_D0/PSSI_D0, USART1_TX(boot), SAI1_FS_A, TIM15_BKIN, EVENTOUT	OTG_HS _VBUS
43	69	D11	102	E3	G3	F11	C4	D12	43	69	D11	102	F11	PA10	I/O	FT_u	-	CRS_SYNC, TIM1_CH3, LPTIM2_IN2, SAI1_D1, DCMI_D1/PSSI_D1, USART1_RX(boot), OTG_HS_ID, SAI1_SD_A, TIM17_BKIN, EVENTOUT	-
-	-	-	-	-	-	-	D1	F11	-	-	-	-	-	VDD11USB	S	-	-	-	-
44	70	C12	103	E1	E1	G13	C2	B14	44	70	C12	103	G13	PA11	I/O	TT	(5)	TIM1_CH4, TIM1_BKIN2, SPI1_MISO, USART1_CTS, FDCAN1_RX, EVENTOUT	OTG_HS_ DM(boot)

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
45	71	B12	104	C1	C1	F13	B1	B13	45	71	B12	104	F13	PA12	I/O	TT	(5)	TIM1_ETR, SPI1_MOSI, OCTOSPIM_P2_NCS, USART1_RTS_DE, FDCAN1_TX, EVENTOUT	OTG_HS_ DP(boot)
46	72	C10	105	D2	E3	F12	B3	C13	46	72	C10	105	F12	PA13 (JTMS/ SWDIO)	I/O	FT	(6)	JTMS/SWDIO, IR_OUT, SAI1_SD_B, EVENTOUT	-
47	-	-	-	C3	AA1	-	P3	-	47	-	-	-	-	VSS	S	-	-	-	-
48	73	A12	106	A1	A1	E13	A2	E9	48	73	A12	106	E13	VDDUSB	S	-	-	-	-
-	74	H4	107	-	D2	E12	R16	H10	-	74	H4	107	E12	VSS	S	-	-	-	-
-	75	D9	108	-	U1	D13	A6	-	-	75	D9	108	D13	VDD	S	-	-	-	-
49	76	C11	109	H4	F4	C10	D11	A12	49	76	C11	109	C10	PA14 (JTCK/ SWCLK)	I/O	FT	(6)	JTCK/SWCLK, LPTIM1_CH1, I2C1_SMBA, I2C4_SMBA, OTG_HS_SOF, SAI1_FS_B, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

| Pin number | | |

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
52	79	A10	112	B4	J5	A9	C10	B10	52	79	A10	112	A9	PC11	I/O	FT_ha	-	LPTIM3_IN1, ADF1_SDI0, DCMI_D2/PSSI_D2, OCTOSPIM_P1_NCS, SPI3_MISO, USART3_RX(boot), UART4_RX, TSC_G3_IO3, DCMI_D4/PSSI_D4, UCPD1_FRSTX2, SDMMC1_D3, SAI2_MCLK_B, EVENTOUT	-
53	80	B10	113	J5	A5	E8	E14	C10	53	80	B10	113	E8	PC12	I/O	FT_hav	-	TRACED3, SPI3_MOSI, USART3_CK, UART5_TX, TSC_G3_IO4, DCMI_D9/PSSI_D9, LPGPIO1_P10, SDMMC1_CK, SAI2_SD_B, EVENTOUT	-
-	81	C9	114	G5	C5	B9	F15	D9	-	81	C9	114	B9	PD0	I/O	FT_fh	-	I2C6_SDA, TIM8_CH4N, I2C5_SDA, SPI2_NSS, LCD_B4, FDCAN1_RX, FMC_D2, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	82	B9	115	E5	E5	F6	A10	C9	-	82	B9	115	F6	PD1	I/O	FT_fh	-	I2C6_SCL, I2C5_SCL, SPI2_SCK, LCD_B5, FDCAN1_TX, FMC_D3, EVENTOUT	-
54	83	A9	116	C5	G5	F7	D13	B9	54	83	A9	116	F7	PD2	I/O	FT	-	TRACED2, TIM3_ETR, I2C5_SMBA, USART3_RTS_DE, UART5_RX, TSC_SYNC, DCMI_D11/PSSI_D11, LPGPIO1_P7, SDMMC1_CMD, LPTIM4_ETR, EVENTOUT	-
-	84	C8	117	A5	K6	D8	C12	A9	-	84	C8	117	D8	PD3	I/O	FT_hv	-	I2C6_SMBA, SPI2_SCK, DCMI_D5/PSSI_D5, SPI2_MISO, MDF1_SDI0, USART2_CTS, LCD_CLK, OCTOSPIM_P2_NCS, FMC_CLK, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	85	B8	118	H6	B6	C8	D15	A8	-	85	B8	118	C8	PD4	I/O	FT_h	-	SPI2_MOSI, MDF1_CKI0, USART2_RTS_DE, OCTOSPIM_P1_IO4, FMC_NOE, EVENTOUT	-
-	86	A8	119	F6	D6	E7	E16	B8	-	86	A8	119	E7	PD5	I/O	FT_h	-	SPI2_RDY, USART2_TX, OCTOSPIM_P1_IO5, FMC_NWE, EVENTOUT	-
-	-	-	120	D6	H2	B8	R20	H15	-	-	-	120	B8	VSS	S	-	-	-	-
-	-	-	121	B6	U13	A8	A12	-	-	-	-	121	A8	VDD	S	-	-	-	-
-	87	A7	122	K6	F6	B7	F17	C8	-	87	A7	122	B7	PD6	I/O	FT_hv	-	SAI1_D1, DCMI_D10/PSSI_D10, SPI3_MOSI, MDF1_SDI1, USART2_RX, LCD_DE, OCTOSPIM_P1_IO6, SDMMC2_CK, FMC_NWAIT, SAI1_SD_A, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	88	D7	123	L7	H6	D7	C14	D8	-	88	D7	123	D7	PD7	I/O	FT_h	-	MDF1_CKI1, USART2_CK, OCTOSPIM_P1_IO7, SDMMC2_CMD, FMC_NCE/FMC_NE1, LPTIM4_OUT, EVENTOUT	-
-	-	B7	124	J7	-	A7	B13	A7	-	-	B7	124	A7	PG9	I/O	FT_hs	-	OCTOSPIM_P2_IO6, SPI3_SCK(boot), USART1_TX, FMC_NCE/FMC_NE2, SAI2_SCK_A, TIM15_CH1N, EVENTOUT	-
-	-	C7	125	E7	-	C7	F19	B7	-	-	C7	125	C7	PG10	I/O	FT_hs	-	LPTIM1_IN1, OCTOSPIM_P2_IO7, SPI3_MISO(boot), USART1_RX, FMC_NE3, SAI2_FS_A, TIM15_CH1, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	C7	-	-	E18	C7	-	-	M11	126	M10	PG11	I/O	FT_hs	-	LPTIM1_IN2, OCTOSPIM_P1_IO5, SPI3_MOSI, USART1_CTS, SAI2_MCLK_A, TIM15_CH2, EVENTOUT	-
-	-	A6	126	A7	-	E6	D17	A6	-	-	A6	127	E6	PG12	I/O	FT_hs	-	LPTIM1_ETR, OCTOSPIM_P2_NCS, SPI3_NSS(boot), USART1_RTS_DE, FMC_NE4, SAI2_SD_A, EVENTOUT	-
-	-	-	127	G7	-	-	A14	B6	-	-	M10	128	N10	PG13	I/O	FT_fhs	-	I2C1_SDA, SPI3_RDY, USART1_CK, LCD_R0, FMC_A24, EVENTOUT	-
-	-	-	128	F8	-	-	C16	D7	-	-	M9	129	N9	PG14	I/O	FT_fhs	-	LPTIM1_CH2, I2C1_SCL, LCD_R1, FMC_A25, EVENTOUT	-
-	-	H9	129	D8	-	-	R24	J10	-	-	H9	130	-	VSS	S	-	-	-	-
-	-	D8	130	B8	-	A6	A16	E8	-	-	D8	131	A6	VDDIO2	S	-	-	-	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number													Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169					
-	-	-	131	H8	-	A5	H17	A5	-	-	B4	132	A5	PG15	I/O	FT_hs	-	LPTIM1_CH1, I2C1_SMBA, OCTOSPIM_P2_DQS, DCMI_D13/PSSI_D13, EVENTOUT	-
55	89	C6	132	K8	B8	D6	B17	E7	55	89	C6	133	D6	PB3 (JTDO/ TRACESWO)	I/O	FT_fa	-	JTDO/TRACESWO, TIM2_CH2, LPTIM1_CH1, ADF1_CCK0, I2C1_SDA, SPI1_SCK, SPI3_SCK, USART1_RTS_DE, CRS_SYNC, LPGPIO1_P11, SDMMC2_D2, SAI1_SCK_B, EVENTOUT	COMP2_ INM2

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number													Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169					
56	90	B6	133	L9	E7	B6	G18	D6	56	90	B6	134	B6	PB4 (NJTRST)	I/O	FT_fa	(6)	NJTRST, LPTIM1_CH2, TIM3_CH1, ADF1_SDI0, I2C3_SDA, SPI1_MISO, SPI3_MISO, USART1_CTS, UART5_RTS_DE, TSC_G2_IO1, DCMI_D12/PSSI_D12, LPGPIO1_P12, SDMMC2_D3, SAI1_MCLK_B, TIM17_BKIN, EVENTOUT	COMP2_INP1

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number				Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	57			PB5	I/O	FT_havc	-	LPTIM1_IN1, TIM3_CH2, OCTOSPIM_P1_NCLK, I2C1_SMBA, SPI1_MOSI, SPI3_MOSI(boot), USART1_CK, UART5_CTS, TSC_G2_IO2, DCMI_D10/PSSI_D10, COMP2_OUT, SAI1_SD_B, TIM16_BKIN, EVENTOUT	UCPD1_DBCC1, WKUP6
LQFP100 SMPS	91								
UFBGA132 SMPS	D6								
LQFP144 SMPS	134								
WLCSP150 SMPS	A9								
WLCSP150 DSI SMPS	A9								
TFBGA169 SMPS	C6								
WLCSP208 DSI SMPS	C18								
TFBGA216 DSI SMPS	B5								
LQFP64	57								
LQFP100	91								
UFBGA132	D6								
LQFP144	135								
TFBGA169	C6								
LQFP64 SMPS	58			PB6	I/O	FT_fa	-	LPTIM1_ETR, TIM4_CH1, TIM8_BKIN2, I2C1_SCL(boot), I2C4_SCL, MDF1_SDI5, USART1_TX, TSC_G2_IO3, DCMI_D5/PSSI_D5, SAI1_FS_B, TIM16_CH1N, EVENTOUT	COMP2_INP2, WKUP3
LQFP100 SMPS	92								
UFBGA132 SMPS	A5								
LQFP144 SMPS	135								
WLCSP150 SMPS	E9								
WLCSP150 DSI SMPS	D8								
TFBGA169 SMPS	B5								
WLCSP208 DSI SMPS	A18								
TFBGA216 DSI SMPS	A4								
LQFP64	58								
LQFP100	92								
UFBGA132	A5								
LQFP144	136								
TFBGA169	B5								

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
59	93	D5	136	C9	G7	F5	D19	A3	59	93	D5	137	F5	PB7	I/O	FT_fhav	-	LPTIM1_IN2, TIM4_CH2, TIM8_BKIN, I2C1_SDA(boot), I2C4_SDA, MDF1_CKI5, USART1_RX, UART4_CTS, TSC_G2_IO4, DCMI_VSYNC/PSSI_RDY, FMC_NL, TIM17_CH1N, EVENTOUT	COMP2_INM1, PVD_IN, WKUP4
60	94	B5	137	G9	J7	C5	E20	B4	60	94	B5	138	C5	PH3-BOOT0	I/O	FT	-	EVENTOUT	-
61	95	C5	138	J9	C9	E5	B19	C6	61	95	C5	139	E5	PB8	I/O	FT_f	-	TIM4_CH3, SAI1_CK1, I2C1_SCL, MDF1_CCK0, SPI3_RDY, LCD_B1, SDMMC1_CKIN, FDCAN1_RX(boot), DCMI_D6/PSSI_D6, SDMMC2_D4, SDMMC1_D4, SAI1_MCLK_A, TIM16_CH1, EVENTOUT	WKUP5

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	96	A4	139	B10	F8	D5	C20	C5	62	96	A4	140	D5	PB9	I/O	FT_f	-	IR_OUT, TIM4_CH4, SAI1_D2, I2C1_SDA, SPI2_NSS, SDMMC1_CDIR, FDCAN1_TX(boot), DCMI_D7/PSSI_D7, SDMMC2_D5, SDMMC1_D5, SAI1_FS_A, TIM17_CH1, EVENTOUT	-
-	97	C4	140	M10	H8	D4	A20	A2	-	97	C4	141	D4	PE0	I/O	FT_h	-	TIM4_ETR, USART6_RX, LCD_HSYNC, DCMI_D2/PSSI_D2, LPGPIO1_P13, FMC_NBL0, TIM16_CH1, EVENTOUT	-
-	-	A3	141	K10	E9	C4	B21	B3	-	98	A3	142	C4	PE1	I/O	FT_h	-	USART6_TX, LCD_VSYNC, DCMI_D3/PSSI_D3, FMC_NBL1, TIM17_CH1, EVENTOUT	-
-	-	-	-	-	-	-	-	-	-	-	-	-	A4	VCAP	S	-	-	-	-
62	98	B4	142	A11	B10	A4	A22	E6	-	-	-	-	-	VDD11	S	-	-	-	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
63	99	E4	143	C11	T12	B4	R4	J15	63	99	E4	143	B4	VSS	S	-	-	-	-
64	100	J9	144	B12	AC7	A3	A24	-	64	100	J9	144	A3	VDD	S	-	-	-	-
-	-	-	-	-	-	-	A26	-	-	-	-	-	-	VDD	S	-	-	-	-
-	-	-	-	B2	B2	-	A4	E11	-	-	-	-	-	VDD11	S	-	-	-	-
-	-	-	-	-	-	F10	B7	D11	-	-	-	-	F10	PH2	I/O	FT_h	-	OCTOSPIM_P1_IO4, EVENTOUT	-
-	-	-	-	-	-	E10	E10	C12	-	-	-	-	E10	PH4	I/O	FT_fh	-	I2C5_SDA, I2C2_SCL, OCTOSPIM_P2_DQS, PSSI_D14, EVENTOUT	-
-	-	-	-	-	-	F9	F13	B12	-	-	-	-	F9	PH5	I/O	FT_f	-	I2C5_SCL, I2C2_SDA, DCMI_PIXCLK/PSSI_PDCK, EVENTOUT	-
-	-	-	-	-	-	E11	H15	C11	-	-	-	-	E11	PH6	I/O	FT_hv	-	I2C5_SMBA, I2C2_SMBA, OCTOSPIM_P2_CLK, DCMI_D8/PSSI_D8, EVENTOUT	-
-	-	-	-	-	-	F8	E12	B11	-	-	-	-	F8	PH7	I/O	FT_fhv	-	I2C3_SCL, OCTOSPIM_P2_NCLK, DCMI_D9/PSSI_D9, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	-	-	D12	G16	D10	-	-	-	-	D12	PH8	I/O	FT_fh	-	I2C3_SDA, OCTOSPIM_P2_IO3, DCMI_HSYNC/PSSI_DE, EVENTOUT	-
-	-	-	-	-	-	E9	M9	M14	-	-	-	-	E9	PH9	I/O	FT_hv	-	I2C3_SMBA, OCTOSPIM_P2_IO4, HSPI1_NCS, DCMI_D0/PSSI_D0, EVENTOUT	-
-	-	-	-	-	-	-	H3	J6	-	-	-	-	-	VSS	S	-	-	-	-
-	-	-	-	-	-	J13	F1	H11	-	-	-	-	A11	VDD	S	-	-	-	-
-	-	-	-	-	-	C13	N6	L13	-	-	-	-	C13	PH10	I/O	FT_hv	-	TIM5_CH1, OCTOSPIM_P2_IO5, HSPI1_IO0, DCMI_D1/PSSI_D1, EVENTOUT	-
-	-	-	-	-	-	D9	N8	L14	-	-	-	-	D9	PH11	I/O	FT_hv	-	TIM5_CH2, OCTOSPIM_P2_IO6, HSPI1_IO1, DCMI_D2/PSSI_D2, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	-	-	B13	M5	M15	-	-	-	-	B13	PH12	I/O	FT_hv	-	TIM5_CH3, TIM8_CH4N, OCTOSPIM_P2_IO7, HSPI1_IO2, DCMI_D3/PSSI_D3, EVENTOUT	-
-	-	-	-	-	-	C12	M7	L15	-	-	-	-	C12	PH13	I/O	FT_hv	-	TIM8_CH1N, HSPI1_IO3, FDCAN1_TX, EVENTOUT	-
-	-	-	-	-	-	-	J4	K10	-	-	-	-	-	VSS	S	-	-	-	-
-	-	-	-	-	-	-	G2	J11	-	-	-	-	-	VDD	S	-	-	-	-
-	-	-	-	-	-	C11	L6	K13	-	-	-	-	C11	PH14	I/O	FT_hv	-	TIM8_CH2N, HSPI1_IO4, FDCAN1_RX, DCMI_D4/PSSI_D4, EVENTOUT	-
-	-	-	-	-	-	A13	L8	K14	-	-	-	-	A13	PH15	I/O	FT_hv	-	TIM8_CH3N, OCTOSPIM_P2_IO6, HSPI1_IO5, DCMI_D11/PSSI_D11, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	-	-	B12	K7	K15	-	-	-	-	B12	PI0	I/O	FT_hv	-	TIM5_CH4, OCTOSPIM_P1_IO5, SPI2_NSS, HSPI1_IO6, DCMI_D13/PSSI_D13, EVENTOUT	-
-	-	-	-	-	-	A12	K5	J12	-	-	-	-	A12	PI1	I/O	FT_hv	-	SPI2_SCK, OCTOSPIM_P2_IO2, HSPI1_IO7, DCMI_D8/PSSI_D8, EVENTOUT	-
-	-	-	-	-	-	-	K3	K7	-	-	-	-	-	VSS	S	-	-	-	-
-	-	-	-	-	-	-	H1	K11	-	-	-	-	-	VDD	S	-	-	-	-
-	-	-	-	-	-	D11	J6	J13	-	-	-	-	D11	PI2	I/O	FT_hv	-	TIM8_CH4, SPI2_MISO, OCTOSPIM_P2_IO1, HSPI1_DQS0, DCMI_D9/PSSI_D9, EVENTOUT	-
-	-	-	-	-	-	D10	K1	J14	-	-	-	-	D10	PI3	I/O	FT_hvp	-	TIM8_ETR, SPI2_MOSI, OCTOSPIM_P2_IO0, HSPI1_CLK, DCMI_D10/PSSI_D10, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	-	-	B10	J2	H14	-	-	-	-	B10	PI4	I/O	FT_hvp	-	TIM8_BKIN, SPI2_RDY, HSPI1_NCLK, DCMI_D5/PSSI_D5, EVENTOUT	-
-	-	-	-	-	-	B3	C22	C4	-	-	-	-	B3	PI5	I/O	FT_hv	-	TIM8_CH1, OCTOSPIM_P2_NCS, DCMI_VSYNC/PSSI_RDY, EVENTOUT	-
-	-	-	-	-	-	A2	D21	D5	-	-	-	-	A2	PI6	I/O	FT_hvp	-	TIM8_CH2, OCTOSPIM_P2_CLK, DCMI_D6/PSSI_D6, EVENTOUT	-
-	-	-	-	-	-	C3	J18	D4	-	-	-	-	C3	PI7	I/O	FT_hvp	-	TIM8_CH3, OCTOSPIM_P2_NCLK, DCMI_D7/PSSI_D7, EVENTOUT	-
-	-	-	-	-	-	-	J8	H13	-	-	-	-	-	PI8	I/O	FT_hv	-	HSPI1_DQS1, EVENTOUT	-
-	-	-	-	-	-	B2	L24	K8	-	-	-	-	B2	VSS	S	-	-	-	-
-	-	-	-	-	-	B1	L2	L11	-	-	-	-	B1	VDD	S	-	-	-	-
-	-	-	-	-	-	-	H5	H12	-	-	-	-	-	PI9	I/O	FT_hv	-	HSPI1_IO8, EVENTOUT	-
-	-	-	-	-	-	-	H7	G15	-	-	-	-	-	PI10	I/O	FT_hv	-	HSPI1_IO9, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	-	-	-	G6	G14	-	-	-	-	-	PI11	I/O	FT_hv	-	HSPI1_IO10, EVENTOUT	-
-	-	-	-	-	-	-	G8	G13	-	-	-	-	-	PI12	I/O	FT_hv	-	HSPI1_IO11, EVENTOUT	-
-	-	-	-	-	-	-	L4	K9	-	-	-	-	-	VSS	S	-	-	-	-
-	-	-	-	-	-	-	M1	-	-	-	-	-	-	VDD	S	-	-	-	-
-	-	-	-	-	-	-	F7	F15	-	-	-	-	-	PI13	I/O	FT_hv	-	HSPI1_IO12, EVENTOUT	-
-	-	-	-	-	-	-	F5	F14	-	-	-	-	-	PI14	I/O	FT_hv	-	HSPI1_IO13, EVENTOUT	-
-	-	-	-	-	-	-	E8	F13	-	-	-	-	-	PI15	I/O	FT_hv	-	HSPI1_IO14, EVENTOUT	-
-	-	-	-	-	-	-	E6	E15	-	-	-	-	-	PJ0	I/O	FT_hv	-	I2C5_SMBA, HSPI1_IO15, EVENTOUT	-
-	-	-	-	-	-	-	M3	L10	-	-	-	-	-	VSS	S	-	-	-	-
-	-	-	-	-	-	-	N2	-	-	-	-	-	-	VDD	S	-	-	-	-
-	-	-	-	-	-	-	-	G4	-	-	-	-	-	PJ1	I/O	FT_fhv	-	I2C5_SDA, EVENTOUT	-
-	-	-	-	-	-	-	-	D2	-	-	-	-	-	PJ2	I/O	FT_fhv	-	I2C5_SCL, EVENTOUT	-

Table 27. STM32U5Axxx pin/ball definitions[1] (continued)

Pin number														Pin name (function after reset)	Pin type	I/O structure	Notes	Alternate functions	Additional functions
LQFP64 SMPS	LQFP100 SMPS	UFBGA132 SMPS	LQFP144 SMPS	WLCSP150 SMPS	WLCSP150 DSI SMPS	TFBGA169 SMPS	WLCSP208 DSI SMPS	TFBGA216 DSI SMPS	LQFP64	LQFP100	UFBGA132	LQFP144	TFBGA169						
-	-	-	-	-	-	-	-	D1	-	-	-	-	-	PJ3	I/O	FT_hv	-	USART6_TX, EVENTOUT	-
-	-	-	-	-	-	-	-	E3	-	-	-	-	-	PJ4	I/O	FT_hv	-	USART6_RX, EVENTOUT	-
-	-	-	-	M12	V2	B11	-	R1	-	-	-	-	B11	VSS	S	-	-	-	-
-	-	-	-	-	-	-	-	F3	-	-	-	-	-	PJ5	I/O	FT_hv	-	USART6_RTS_DE, EVENTOUT	-
-	-	-	-	-	-	-	-	E2	-	-	-	-	-	PJ6	I/O	FT_hv	-	USART6_CK, EVENTOUT	-
-	-	-	-	-	-	-	-	E1	-	-	-	-	-	PJ7	I/O	FT_hv	-	USART6_CTS, EVENTOUT	-
-	-	-	-	-	-	-	-	F2	-	-	-	-	-	PJ8	I/O	FT_hv	-	I2C6_SMBA, EVENTOUT	-
-	-	-	-	-	-	-	-	H4	-	-	-	-	-	PJ9	I/O	FT_fhv	-	I2C6_SDA, EVENTOUT	-
-	-	-	-	-	-	-	-	F1	-	-	-	-	-	PJ10	I/O	FT_fhv	-	I2C6_SCL, EVENTOUT	-
-	-	-	-	-	-	-	-	G3	-	-	-	-	-	PJ11	I/O	FT_hv	-	EVENTOUT	-
-	-	-	-	-	-	-	-	R15	-	-	-	-	M7	VSS	S	-	-	-	-
-	-	-	-	A3	-	-	-	-	-	-	-	-	N7	VDD	S	-	-	-	-

1. Function availability depends on the chosen device.

2. PC13, PC14, and PC15 are supplied through the power switch (by V_{SW}). Since the switch only sinks a limited amount of current (3 mA), the use of PC13 to PC15 GPIOs in output mode is limited:
   - PC13 speed must not exceed 2 MHz with a maximum load of 30 pF. Refer to FT_o electrical characteristics for PC14, PC15.
   - These GPIOs must not be used as current sources (for example to drive a LED).
3. After a backup domain power-up, PC13, PC14, and PC15 operate as GPIOs. Their function depends then on the content of the RTC registers that are not reset by the system reset. For details on how to manage these GPIOs, refer to the backup domain and RTC register descriptions in the product reference manual.
4. After reset, a pull-down resistor (Rd = 5.1 kΩ from UCPD peripheral) can be activated on PA15 and PB15 (UCPD1_CC1, UCPD1_CC2). The pull-down on PA15 (UCPD1_CC1) is activated by high level on PB5 (UCPD1_DBCC1). The pull-down on PB15 (UCPD1_CC2) is activated by high level on PB14 (UCPD1_DBCC2). This pull-down control (dead battery support on UCPD) can be disabled by setting UCPD_DBDIS = 1 in the PWR_UCPDR register.
5. GPIO is 5V-tolerant when the USB PHY is powered on.
6. After reset, this pin is configured as JTAG/SWD alternate functions. The internal pull-up on PA15, PA13, PB4 pins and the internal pull-down on PA14 pin are activated.

4.3 Alternate functions

Table 28. Alternate function AF0 to AF7(1)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port A	PA0	-	TIM2_CH1	TIM5_CH1	TIM8_ETR	-	-	SPI3_RDY	USART2_CTS
	PA1	LPTIM1_CH2	TIM2_CH2	TIM5_CH2	-	I2C1_SMBA	SPI1_SCK	-	USART2_RTS_ DE
	PA2	-	TIM2_CH3	TIM5_CH3	-	-	SPI1_RDY	-	USART2_TX
	PA3	-	TIM2_CH4	TIM5_CH4	SAI1_CK1	-	-	-	USART2_RX
	PA4	-	-	-	OCTOSPIM_P1 _NCS	-	SPI1_NSS	SPI3_NSS	USART2_CK
	PA5	CSLEEP	TIM2_CH1	TIM2_ETR	TIM8_CH1N	PSSI_D14	SPI1_SCK	-	USART3_RX
	PA6	CDSTOP	TIM1_BKIN	TIM3_CH1	TIM8_BKIN	DCMI_ PIXCLK/ PSSI_PDCK	SPI1_MISO	-	USART3_CTS
	PA7	SRDSTOP	TIM1_CH1N	TIM3_CH2	TIM8_CH1N	I2C3_SCL	SPI1_MOSI	-	USART3_TX
	PA8	MCO	TIM1_CH1	-	SAI1_CK2	-	SPI1_RDY	-	USART1_CK
	PA9	-	TIM1_CH2	-	SPI2_SCK	-	DCMI_D0/PSSI_D0	-	USART1_TX
	PA10	CRS_SYNC	TIM1_CH3	LPTIM2_IN2	SAI1_D1	-	DCMI_D1/PSSI_D1	-	USART1_RX
	PA11	-	TIM1_CH4	TIM1_BKIN2	-	-	SPI1_MISO	-	USART1_CTS
	PA12	-	TIM1_ETR	-	-	-	SPI1_MOSI	OCTOSPIM_P2 _NCS	USART1_RTS_ DE
	PA13	JTMS/SWDIO	IR_OUT	-	-	-	-	-	-
	PA14	JTCK/SWCLK	LPTIM1_CH1	-	-	I2C1_SMBA	I2C4_SMBA	-	-
	PA15	JTDI	TIM2_CH1	TIM2_ETR	USART2_RX	-	SPI1_NSS	SPI3_NSS	USART3_RTS_ DE

Table 28. Alternate function AF0 to AF7(1) (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port B	PB0	-	TIM1_CH2N	TIM3_CH3	TIM8_CH2N	LPTIM3_CH1	SPI1_NSS	-	USART3_CK
	PB1	-	TIM1_CH3N	TIM3_CH4	TIM8_CH3N	LPTIM3_CH2	-	MDF1_SDI0	USART3_RTS_ DE
	PB2	-	LPTIM1_CH1	-	TIM8_CH4N	I2C3_SMBA	SPI1_RDY	MDF1_CKI0	-
	PB3	JTDO/ TRACESWO	TIM2_CH2	LPTIM1_CH1	ADF1_CCK0	I2C1_SDA	SPI1_SCK	SPI3_SCK	USART1_RTS_ DE
	PB4	NJTRST	LPTIM1_CH2	TIM3_CH1	ADF1_SDI0	I2C3_SDA	SPI1_MISO	SPI3_MISO	USART1_CTS
	PB5	-	LPTIM1_IN1	TIM3_CH2	OCTOSPIM_P1 _NCLK	I2C1_SMBA	SPI1_MOSI	SPI3_MOSI	USART1_CK
	PB6	-	LPTIM1_ETR	TIM4_CH1	TIM8_BKIN2	I2C1_SCL	I2C4_SCL	MDF1_SDI5	USART1_TX
	PB7	-	LPTIM1_IN2	TIM4_CH2	TIM8_BKIN	I2C1_SDA	I2C4_SDA	MDF1_CKI5	USART1_RX
	PB8	-	-	TIM4_CH3	SAI1_CK1	I2C1_SCL	MDF1_CCK0	SPI3_RDY	LCD_B1
	PB9	-	IR_OUT	TIM4_CH4	SAI1_D2	I2C1_SDA	SPI2_NSS	-	-
	PB10	-	TIM2_CH3	LPTIM3_CH1	I2C4_SCL	I2C2_SCL	SPI2_SCK	-	USART3_TX
	PB11	-	TIM2_CH4	-	I2C4_SDA	I2C2_SDA	SPI2_RDY	-	USART3_RX
	PB12	-	TIM1_BKIN	I2C6_SMBA	-	I2C2_SMBA	SPI2_NSS	MDF1_SDI1	USART3_CK
	PB13	-	TIM1_CH1N	LPTIM3_IN1	-	I2C2_SCL	SPI2_SCK	MDF1_CKI1	USART3_CTS
	PB14	-	TIM1_CH2N	LPTIM3_ETR	TIM8_CH2N	I2C2_SDA	SPI2_MISO	MDF1_SDI2	USART3_RTS_ DE
	PB15	RTC_REFIN	TIM1_CH3N	LPTIM2_IN2	TIM8_CH3N	-	SPI2_MOSI	MDF1_CKI2	-

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port C	PC0	-	LPTIM1_IN1	-	OCTOSPIM_P1 _IO7	I2C3_SCL	SPI2_RDY	MDF1_SDI4	USART6_CTS
	PC1	TRACED0	LPTIM1_CH1	-	SPI2_MOSI	I2C3_SDA	-	MDF1_CKI4	USART6_CK
	PC2	-	LPTIM1_IN2	-	-	-	SPI2_MISO	MDF1_CCK1	USART6_RX
	PC3	-	LPTIM1_ETR	LPTIM3_CH1	SAI1_D1	-	SPI2_MOSI	-	USART6_TX
	PC4	-	-	I2C6_SMBA	-	-	-	-	USART3_TX
	PC5	-	TIM1_CH4N		SAI1_D3	PSSI_D15	-	-	USART3_RX
	PC6	CSLEEP	-	TIM3_CH1	TIM8_CH1	-	-	MDF1_CKI3	LCD_R0
	PC7	CDSTOP	-	TIM3_CH2	TIM8_CH2	-	-	MDF1_SDI3	LCD_R1
	PC8	SRDSTOP	-	TIM3_CH3	TIM8_CH3	-	-	-	USART6_RX
	PC9	TRACED0	TIM8_BKIN2	TIM3_CH4	TIM8_CH4	DCMI_D3/ PSSI_D3	-	-	USART6_TX
	PC10	TRACED1	-	LPTIM3_ETR	ADF1_CCK1	-	-	SPI3_SCK	USART3_TX
	PC11	-	-	LPTIM3_IN1	ADF1_SDI0	DCMI_D2/ PSSI_D2	OCTOSPIM_P1_ NCS	SPI3_MISO	USART3_RX
	PC12	TRACED3	-	-	-	-	-	SPI3_MOSI	USART3_CK
	PC13	-	-	-	-	-	-	-	-
	PC14	-	-	-	-	-	-	-	-
	PC15	-	-	-	-	-	-	-	-

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port D	PD0	-	-	I2C6_SDA	TIM8_CH4N	I2C5_SDA	SPI2_NSS	-	-
	PD1	-	-	I2C6_SCL	-	I2C5_SCL	SPI2_SCK	-	-
	PD2	TRACED2	-	TIM3_ETR	-	I2C5_SMBA	-	-	USART3_RTS_ DE
	PD3	-	-	I2C6_SMBA	SPI2_SCK	DCMI_D5/ PSSI_D5	SPI2_MISO	MDF1_SDI0	USART2_CTS
	PD4	-	-	-	-	-	SPI2_MOSI	MDF1_CKI0	USART2_RTS_ DE
	PD5	-	-	-	-	-	SPI2_RDY	-	USART2_TX
	PD6	-	-	-	SAI1_D1	DCMI_D10/ PSSI_D10	SPI3_MOSI	MDF1_SDI1	USART2_RX
	PD7	-	-	-	-	-	-	MDF1_CKI1	USART2_CK
	PD8	-	-	-	-	-	-	-	USART3_TX
	PD9	-	-	LPTIM2_IN2	-	-	-	-	USART3_RX
	PD10	-	-	LPTIM2_CH2	-	I2C5_SMBA	-	-	USART3_CK
	PD11	-	-	-	-	I2C4_SMBA	-	-	USART3_CTS
	PD12	-	-	TIM4_CH1	-	I2C4_SCL	-	-	USART3_RTS_ DE
	PD13	-	-	TIM4_CH2	-	I2C4_SDA	-	-	USART6_CTS
	PD14	-	-	TIM4_CH3	-	-	-	-	USART6_CK
	PD15	-	-	TIM4_CH4	-	-	-	-	USART6_RTS_ DE

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port E	PE0	-	-	TIM4_ETR	-	-	-	-	USART6_RX
	PE1	-	-	-	-	-	-	-	USART6_TX
	PE2	TRACECLK	-	TIM3_ETR	SAI1_CK1	-	-	-	USART6_CK
	PE3	TRACED0	-	TIM3_CH1	OCTOSPIM_P1 _DQS	-	-	-	USART6_CTS
	PE4	TRACED1	-	TIM3_CH2	SAI1_D2	-	-	MDF1_SDI3	USART6_RTS_ DE
	PE5	TRACED2	-	TIM3_CH3	SAI1_CK2	-	-	MDF1_CKI3	-
	PE6	TRACED3	-	TIM3_CH4	SAI1_D1	-	-	-	-
	PE7	-	TIM1_ETR	-	-	-	-	MDF1_SDI2	-
	PE8	-	TIM1_CH1N	-	-	-	-	MDF1_CKI2	-
	PE9	-	TIM1_CH1	-	ADF1_CCK0	-	-	MDF1_CCK0	-
	PE10	-	TIM1_CH2N	-	ADF1_SDI0	-	-	MDF1_SDI4	-
	PE11	-	TIM1_CH2	-	-	-	SPI1_RDY	MDF1_CKI4	-
	PE12	-	TIM1_CH3N	-	-	-	SPI1_NSS	MDF1_SDI5	-
	PE13	-	TIM1_CH3	-	-	-	SPI1_SCK	MDF1_CKI5	-
	PE14	-	TIM1_CH4	TIM1_BKIN2	-	-	SPI1_MISO	-	-
	PE15	-	TIM1_BKIN	-	TIM1_CH4N	-	SPI1_MOSI	-	-

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port F	PF0	-	-	I2C6_SDA	-	I2C2_SDA	OCTOSPIM_P2_IO0	-	USART6_TX
	PF1	-	-	I2C6_SCL	-	I2C2_SCL	OCTOSPIM_P2_IO1	-	USART6_RX
	PF2	-	-	LPTIM3_CH2	-	I2C2_SMBA	OCTOSPIM_P2_IO2	-	USART6_CK
	PF3	-	-	LPTIM3_IN1	ADF1_CCK0	-	OCTOSPIM_P2_IO3	MDF1_CCK0	USART6_CTS
	PF4	-	-	LPTIM3_ETR	ADF1_SDI0	-	OCTOSPIM_P2_ CLK	MDF1_SDI0	USART6_RTS_ DE
	PF5	-	-	LPTIM3_CH1	-	-	OCTOSPIM_P2_ NCLK	MDF1_CKI0	-
	PF6	-	TIM5_ETR	TIM5_CH1	-	DCMI_D12/ PSSI_D12	OCTOSPIM_P2_ NCS	-	-
	PF7	-	-	TIM5_CH2	-	-	-	-	-
	PF8	-	-	TIM5_CH3	-	PSSI_D14	-	-	-
	PF9	-	-	TIM5_CH4	-	PSSI_D15	-	-	-
	PF10	-	-	-	OCTOSPIM_P1 _CLK	PSSI_D15	-	MDF1_CCK1	-
	PF11	-	-	-	OCTOSPIM_P1 _NCLK	-	-	-	-
	PF12	-	-	-	-	-	OCTOSPIM_P2_ DQS	-	-
	PF13	-	-	-	-	I2C4_SMBA	-	-	-
	PF14	-	-	-	-	I2C4_SCL	-	-	-
	PF15	-	-	-	-	I2C4_SDA	-	-	-

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port G	PG0	-	-	-	-	-	OCTOSPIM_P2_IO4	-	-
	PG1	-	-	-	-	-	OCTOSPIM_P2_IO5	-	-
	PG2	-	-	-	-	-	SPI1_SCK	-	-
	PG3	-	-	-	-	-	SPI1_MISO	-	-
	PG4	-	-	-	-	-	SPI1_MOSI	-	-
	PG5	-	-	-	-	-	SPI1_NSS	-	-
	PG6	-	-	-	OCTOSPIM_P1 _DQS	I2C3_SMBA	SPI1_RDY	-	LCD_R1
	PG7	-	-	-	SAI1_CK1	I2C3_SCL	OCTOSPIM_P2_ DQS	MDF1_CCK0	-
	PG8	-	-	-	-	I2C3_SDA	-	-	-
	PG9	-	-	-	-	-	OCTOSPIM_P2_IO6	SPI3_SCK	USART1_TX
	PG10	-	LPTIM1_IN1	-	-	-	OCTOSPIM_P2_IO7	SPI3_MISO	USART1_RX
	PG11	-	LPTIM1_IN2	-	OCTOSPIM_P1 _IO5	-	-	SPI3_MOSI	USART1_CTS
	PG12	-	LPTIM1_ETR	-	-	-	OCTOSPIM_P2_ NCS	SPI3_NSS	USART1_RTS_ DE
	PG13	-	-	-	-	I2C1_SDA	-	SPI3_RDY	USART1_CK
	PG14	-	LPTIM1_CH2	-	-	I2C1_SCL	-	-	-
	PG15	-	LPTIM1_CH1	-	-	I2C1_SMBA	OCTOSPIM_P2_ DQS	-	-

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port H	PH0	-	-	-	-	-	-	-	-
	PH1	-	-	-	-	-	-	-	-
	PH2	-	-	-	OCTOSPIM_P1 _IO4	-	-	-	-
	PH3	-	-	-	-	-	-	-	-
	PH4	-	-	I2C5_SDA	-	I2C2_SCL	OCTOSPIM_P2_ DQS	-	-
	PH5	-	-	I2C5_SCL	-	I2C2_SDA	-	-	-
	PH6	-	-	I2C5_SMBA	-	I2C2_SMBA	OCTOSPIM_P2_ CLK	-	-
	PH7	-	-	-	-	I2C3_SCL	OCTOSPIM_P2_ NCLK	-	-
	PH8	-	-	-	-	I2C3_SDA	OCTOSPIM_P2_IO3	-	-
	PH9	-	-	-	-	I2C3_SMBA	OCTOSPIM_P2_IO4	-	-
	PH10	-	-	TIM5_CH1	-	-	OCTOSPIM_P2_IO5	-	-
	PH11	-	-	TIM5_CH2	-	-	OCTOSPIM_P2_IO6	-	-
	PH12	-	-	TIM5_CH3	TIM8_CH4N	-	OCTOSPIM_P2_IO7	-	-
	PH13	-	-	-	TIM8_CH1N	-	-	-	-
	PH14	-	-	-	TIM8_CH2N	-	-	-	-
	PH15	-	-	-	TIM8_CH3N	-	OCTOSPIM_P2_IO6	-	-

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port I	PI0	-	-	TIM5_CH4	OCTOSPIM_P1_IO5	-	SPI2_NSS	-	-
	PI1	-	-	-	-	-	SPI2_SCK	OCTOSPIM_P2_IO2	-
	PI2	-	-	-	TIM8_CH4	-	SPI2_MISO	OCTOSPIM_P2_IO1	-
	PI3	-	-	-	TIM8_ETR	-	SPI2_MOSI	OCTOSPIM_P2_IO0	-
	PI4	-	-	-	TIM8_BKIN	-	SPI2_RDY	-	-
	PI5	-	-	-	TIM8_CH1	-	OCTOSPIM_P2_NCS	-	-
	PI6	-	-	-	TIM8_CH2	-	OCTOSPIM_P2_CLK	-	-
	PI7	-	-	-	TIM8_CH3	-	OCTOSPIM_P2_NCLK	-	-
	PI8	-	-	-	-	-	-	-	-
	PI9	-	-	-	-	-	-	-	-
	PI10	-	-	-	-	-	-	-	-
	PI11	-	-	-	-	-	-	-	-
	PI12	-	-	-	-	-	-	-	-
	PI13	-	-	-	-	-	-	-	-
	PI14	-	-	-	-	-	-	-	-
	PI15	-	-	-	-	-	-	-	-

Table 28. Alternate function AF0 to AF7[1] (continued)

Port		AF0	AF1	AF2	AF3	AF4	AF5	AF6	AF7
		CRS/LPTIM1/ SYS_AF	LPTIM1/ TIM1/2/5/8	I2C5/6/ LPTIM1/2/3/ TIM1/2/3/4/5	ADF1/I2C4/ OCTOSPIM_P1/ OTG_HS/SAI1/ SPI2/TIM1/8/ USART2	DCMI/ I2C1/2/3/4/5/ LPTIM3	DCMI/I2C4/MDF1/ OCTOSPIM_P1/2/ SPI1/2/3	I2C3/MDF1/ OCTOSPIM_P2/ SPI3	LCD/ USART1/2/3/6
Port J	PJ0	-	-	-	-	I2C5_SMBA	-	-	-
	PJ1	-	-	-	-	I2C5_SDA	-	-	-
	PJ2	-	-	-	-	I2C5_SCL	-	-	-
	PJ3	-	-	-	-	-	-	-	USART6_TX
	PJ4	-	-	-	-	-	-	-	USART6_RX
	PJ5	-	-	-	-	-	-	-	USART6_RTS_ DE
	PJ6	-	-	-	-	-	-	-	USART6_CK
	PJ7	-	-	-	-	-	-	-	USART6_CTS
	PJ8	-	-	I2C6_SMBA	-	-	-	-	-
	PJ9	-	-	I2C6_SDA	-	-	-	-	-
	PJ10	-	-	I2C6_SCL	-	-	-	-	-
	PJ11	-	-	-	-	-	-	-	-

1. Refer to the next table for AF8 to AF15.

Table 29. Alternate function AF8 to AF15(1)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
Port		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port A	PA0	UART4_TX	-	OCTOSPIM_P2_ NCS	-	SDMMC2_CMD	AUDIOCLK	TIM2_ETR	EVENTOUT
	PA1	UART4_RX	-	OCTOSPIM_P1_ DQS	LPGPIO1_P0	-	-	TIM15_CH1N	EVENTOUT
	PA2	LPUART1_TX	-	OCTOSPIM_P1_ NCS	UCPD1_ FRSTX1	-	-	TIM15_CH1	EVENTOUT
	PA3	LPUART1_RX	-	OCTOSPIM_P1_ CLK	LPGPIO1_P1	-	SAI1_MCLK_A	TIM15_CH2	EVENTOUT
	PA4	-	-	DCMI_HSYNC/ PSSI_DE	-	-	SAI1_FS_B	LPTIM2_CH1	EVENTOUT
	PA5	-	-	-	-	-	-	LPTIM2_ETR	EVENTOUT
	PA6	LPUART1_CTS	-	OCTOSPIM_P1_IO3	LPGPIO1_P2	-	-	TIM16_CH1	EVENTOUT
	PA7	-	-	OCTOSPIM_P1_IO2	-	-	LPTIM2_CH2	TIM17_CH1	EVENTOUT
	PA8	-	-	OTG_HS_SOF	-	TRACECLK	SAI1_SCK_A	LPTIM2_CH1	EVENTOUT
	PA9	-	-	-	-	-	SAI1_FS_A	TIM15_BKIN	EVENTOUT
	PA10	-	-	OTG_HS_ID	-	-	SAI1_SD_A	TIM17_BKIN	EVENTOUT
	PA11	-	FDCAN1_RX	-	-	-	-	-	EVENTOUT
	PA12	-	FDCAN1_TX	-	-	-	-	-	EVENTOUT
	PA13	-	-	-	-	-	SAI1_SD_B	-	EVENTOUT
	PA14	-	-	OTG_HS_SOF	-	-	SAI1_FS_B	-	EVENTOUT
	PA15	UART4_RTS_ DE	-	-	-	-	SAI2_FS_B	-	EVENTOUT

Table 29. Alternate function AF8 to AF15(1) (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port B	PB0	-	-	OCTOSPIM_P1_IO1	LPGPIO1_P9	COMP1_OUT	AUDIOCLK	-	EVENTOUT
	PB1	LPUART1_RTS_ DE	-	OCTOSPIM_P1_IO0	LPGPIO1_P3	-	-	LPTIM2_IN1	EVENTOUT
	PB2	LCD_B1	-	OCTOSPIM_P1_ DQS	UCPD1_ FRSTX1	-	-	-	EVENTOUT
	PB3	-	-	CRS_SYNC	LPGPIO1_P11	SDMMC2_D2	SAI1_SCK_B	-	EVENTOUT
	PB4	UART5_RTS_ DE	TSC_G2_IO1	DCMI_D12/ PSSI_D12	LPGPIO1_P12	SDMMC2_D3	SAI1_MCLK_B	TIM17_BKIN	EVENTOUT
	PB5	UART5_CTS	TSC_G2_IO2	DCMI_D10/ PSSI_D10	-	COMP2_OUT	SAI1_SD_B	TIM16_BKIN	EVENTOUT
	PB6	-	TSC_G2_IO3	DCMI_D5/PSSI_D5	-	-	SAI1_FS_B	TIM16_CH1N	EVENTOUT
	PB7	UART4_CTS	TSC_G2_IO4	DCMI_VSYNC/ PSSI_RDY	-	FMC_NL	-	TIM17_CH1N	EVENTOUT
	PB8	SDMMC1_CKIN	FDCAN1_RX	DCMI_D6/PSSI_D6	SDMMC2_D4	SDMMC1_D4	SAI1_MCLK_A	TIM16_CH1	EVENTOUT
	PB9	SDMMC1_CDIR	FDCAN1_TX	DCMI_D7/PSSI_D7	SDMMC2_D5	SDMMC1_D5	SAI1_FS_A	TIM17_CH1	EVENTOUT
	PB10	LPUART1_RX	TSC_SYNC	OCTOSPIM_P1_ CLK	LPGPIO1_P4	COMP1_OUT	SAI1_SCK_A	-	EVENTOUT
	PB11	LPUART1_TX	-	OCTOSPIM_P1_ NCS	-	COMP2_OUT	-	-	EVENTOUT
	PB12	LPUART1_RTS_ DE	TSC_G1_IO1	OCTOSPIM_P1_ NCLK	-	-	SAI2_FS_A	TIM15_BKIN	EVENTOUT
	PB13	LPUART1_CTS	TSC_G1_IO2	-	-	-	SAI2_SCK_A	TIM15_CH1N	EVENTOUT
	PB14	-	TSC_G1_IO3	-	-	SDMMC2_D0	SAI2_MCLK_A	TIM15_CH1	EVENTOUT
	PB15	-	-	-	FMC_NBL1	SDMMC2_D1	SAI2_SD_A	TIM15_CH2	EVENTOUT

Table 29. Alternate function AF8 to AF15[1] (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port C	PC0	LPUART1_RX	-	-	-	SDMMC1_D5	SAI2_FS_A	LPTIM2_IN1	EVENTOUT
	PC1	LPUART1_TX	-	OCTOSPIM_P1_IO4	-	SDMMC2_CK	SAI1_SD_A	-	EVENTOUT
	PC2	-	-	OCTOSPIM_P1_IO5	LPGPIO1_P5	-	-	-	EVENTOUT
	PC3	-	-	OCTOSPIM_P1_IO6	-	-	SAI1_SD_A	LPTIM2_ETR	EVENTOUT
	PC4	-	-	OCTOSPIM_P1_IO7	-	-	-	-	EVENTOUT
	PC5	-	-	-	-	-	-	-	EVENTOUT
	PC6	SDMMC1_ D0DIR	TSC_G4_IO1	DCMI_D0/PSSI_D0	SDMMC2_D6	SDMMC1_D6	SAI2_MCLK_A	-	EVENTOUT
	PC7	SDMMC1_ D123DIR	TSC_G4_IO2	DCMI_D1/PSSI_D1	SDMMC2_D7	SDMMC1_D7	SAI2_MCLK_B	LPTIM2_CH2	EVENTOUT
	PC8	-	TSC_G4_IO3	DCMI_D2/PSSI_D2	-	SDMMC1_D0	-	LPTIM3_CH1	EVENTOUT
	PC9	-	TSC_G4_IO4	-	-	SDMMC1_D1	-	LPTIM3_CH2	EVENTOUT
	PC10	UART4_TX	TSC_G3_IO2	DCMI_D8/PSSI_D8	LPGPIO1_P8	SDMMC1_D2	SAI2_SCK_B	-	EVENTOUT
	PC11	UART4_RX	TSC_G3_IO3	DCMI_D4/PSSI_D4	UCPD1_ FRSTX2	SDMMC1_D3	SAI2_MCLK_B	-	EVENTOUT
	PC12	UART5_TX	TSC_G3_IO4	DCMI_D9/PSSI_D9	LPGPIO1_P10	SDMMC1_CK	SAI2_SD_B	-	EVENTOUT
	PC13	-	-	-	-	-	-	-	EVENTOUT
	PC14	-	-	-	-	-	-	-	EVENTOUT
	PC15	-	-	-	-	-	-	-	EVENTOUT

Table 29. Alternate function AF8 to AF15(1) (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port D	PD0	LCD_B4	FDCAN1_RX	-	-	FMC_D2	-	-	EVENTOUT
	PD1	LCD_B5	FDCAN1_TX	-	-	FMC_D3	-	-	EVENTOUT
	PD2	UART5_RX	TSC_SYNC	DCMI_D11/ PSSI_D11	LPGPIO1_P7	SDMMC1_CMD	LPTIM4_ETR	-	EVENTOUT
	PD3	LCD_CLK	-	OCTOSPIM_P2_ NCS	-	FMC_CLK	-	-	EVENTOUT
	PD4	-	-	OCTOSPIM_P1_IO4	-	FMC_NOE	-	-	EVENTOUT
	PD5	-	-	OCTOSPIM_P1_IO5	-	FMC_NWE	-	-	EVENTOUT
	PD6	LCD_DE	-	OCTOSPIM_P1_IO6	SDMMC2_CK	FMC_NWAIT	SAI1_SD_A	-	EVENTOUT
	PD7	-	-	OCTOSPIM_P1_IO7	SDMMC2_CMD	FMC_NCE/ FMC_NE1	LPTIM4_OUT	-	EVENTOUT
	PD8	LCD_R3	-	DCMI_HSYNC/ PSSI_DE	-	FMC_D13	-	-	EVENTOUT
	PD9	LCD_R4	-	DCMI_PIXCLK/ PSSI_PDCK	-	FMC_D14	SAI2_MCLK_A	LPTIM3_IN1	EVENTOUT
	PD10	LCD_R5	TSC_G6_IO1	-	-	FMC_D15	SAI2_SCK_A	LPTIM3_ETR	EVENTOUT
	PD11	LCD_R6	TSC_G6_IO2	-	-	FMC_CLE/ FMC_A16	SAI2_SD_A	LPTIM2_ETR	EVENTOUT
	PD12	LCD_R7	TSC_G6_IO3	-	-	FMC_ALE/ FMC_A17	SAI2_FS_A	LPTIM2_IN1	EVENTOUT
	PD13	LCD_VSYNC	TSC_G6_IO4	-	LPGPIO1_P6	FMC_A18	LPTIM4_IN1	LPTIM2_CH1	EVENTOUT
	PD14	LCD_B2	-	-	-	FMC_D0	-	LPTIM3_CH1	EVENTOUT
	PD15	LCD_B3	-	-	-	FMC_D1	-	LPTIM3_CH2	EVENTOUT

Table 29. Alternate function AF8 to AF15[1] (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port E	PE0	LCD_HSYNC	-	DCMI_D2/PSSI_D2	LPGPIO1_P13	FMC_NBL0	-	TIM16_CH1	EVENTOUT
	PE1	LCD_VSYNC	-	DCMI_D3/PSSI_D3	-	FMC_NBL1	-	TIM17_CH1	EVENTOUT
	PE2	LCD_R0	TSC_G7_IO1	-	LPGPIO1_P14	FMC_A23	SAI1_MCLK_A	-	EVENTOUT
	PE3	LCD_R1	TSC_G7_IO2	-	LPGPIO1_P15	FMC_A19	SAI1_SD_B	-	EVENTOUT
	PE4	LCD_B0	TSC_G7_IO3	DCMI_D4/PSSI_D4	-	FMC_A20	SAI1_FS_A	-	EVENTOUT
	PE5	LCD_G0	TSC_G7_IO4	DCMI_D6/PSSI_D6	-	FMC_A21	SAI1_SCK_A	-	EVENTOUT
	PE6	LCD_G1	-	DCMI_D7/PSSI_D7	-	FMC_A22	SAI1_SD_A	-	EVENTOUT
	PE7	LCD_B6	-	-	-	FMC_D4	SAI1_SD_B	-	EVENTOUT
	PE8	LCD_B7	-	-	-	FMC_D5	SAI1_SCK_B	-	EVENTOUT
	PE9	LCD_G2	-	OCTOSPIM_P1_ NCLK	-	FMC_D6	SAI1_FS_B	-	EVENTOUT
	PE10	LCD_G3	TSC_G5_IO1	OCTOSPIM_P1_CL K	-	FMC_D7	SAI1_MCLK_B	-	EVENTOUT
	PE11	LCD_G4	TSC_G5_IO2	OCTOSPIM_P1_ NCS	-	FMC_D8	-	-	EVENTOUT
	PE12	LCD_G5	TSC_G5_IO3	OCTOSPIM_P1_IO0	-	FMC_D9	-	-	EVENTOUT
	PE13	LCD_G6	TSC_G5_IO4	OCTOSPIM_P1_IO1	-	FMC_D10	-	-	EVENTOUT
	PE14	LCD_G7	-	OCTOSPIM_P1_IO2	-	FMC_D11	-	-	EVENTOUT
	PE15	LCD_R2	-	OCTOSPIM_P1_IO3	-	FMC_D12	-	-	EVENTOUT

Table 29. Alternate function AF8 to AF15[1] (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port F	PF0	-	-	-	-	FMC_A0	-	-	EVENTOUT
	PF1	-	-	-	-	FMC_A1	-	-	EVENTOUT
	PF2	-	-	-	-	FMC_A2	-	-	EVENTOUT
	PF3	UART5_TX	-	-	-	FMC_A3	-	-	EVENTOUT
	PF4	UART5_RX	-	-	-	FMC_A4	-	-	EVENTOUT
	PF5	-	-	-	-	FMC_A5	-	-	EVENTOUT
	PF6	-	-	OCTOSPIM_P1_IO3	-	-	SAI1_SD_B	-	EVENTOUT
	PF7	-	FDCAN1_RX	OCTOSPIM_P1_IO2	-	-	SAI1_MCLK_B	-	EVENTOUT
	PF8	-	FDCAN1_TX	OCTOSPIM_P1_IO0	-	-	SAI1_SCK_B	-	EVENTOUT
	PF9	-	-	OCTOSPIM_P1_IO1	-	-	SAI1_FS_B	TIM15_CH1	EVENTOUT
	PF10	-	-	DCMI_D11/PSSI_ D11	DSI_TE	-	SAI1_D3	TIM15_CH2	EVENTOUT
	PF11	LCD_DE	-	DCMI_D12/PSSI_ D12	DSI_TE	-	LPTIM4_IN1	-	EVENTOUT
	PF12	LCD_B0	-	-	-	FMC_A6	LPTIM4_ETR	-	EVENTOUT
	PF13	LCD_B1	-	-	UCPD1_ FRSTX2	FMC_A7	LPTIM4_OUT	-	EVENTOUT
	PF14	LCD_G0	TSC_G8_IO1	-	-	FMC_A8	-	-	EVENTOUT
	PF15	LCD_G1	TSC_G8_IO2	-	-	FMC_A9	-	-	EVENTOUT

Table 29. Alternate function AF8 to AF15[1] (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port G	PG0	-	TSC_G8_IO3	-	-	FMC_A10	-	-	EVENTOUT
	PG1	-	TSC_G8_IO4	-	-	FMC_A11	-	-	EVENTOUT
	PG2	-	-	-	-	FMC_A12	SAI2_SCK_B	-	EVENTOUT
	PG3	-	-	-	-	FMC_A13	SAI2_FS_B	-	EVENTOUT
	PG4	-	-	-	-	FMC_A14	SAI2_MCLK_B	-	EVENTOUT
	PG5	LPUART1_CTS	-	-	DSI_TE	FMC_A15	SAI2_SD_B	-	EVENTOUT
	PG6	LPUART1_RTS_ DE	-	-	UCPD1_ FRSTX1	-	-	-	EVENTOUT
	PG7	LPUART1_TX	-	-	UCPD1_ FRSTX2	FMC_INT	SAI1_MCLK_A	-	EVENTOUT
	PG8	LPUART1_RX	-	-	-	-	-	-	EVENTOUT
	PG9	-	-	-	-	FMC_NCE/FMC _NE2	SAI2_SCK_A	TIM15_CH1N	EVENTOUT
	PG10	-	-	-	-	FMC_NE3	SAI2_FS_A	TIM15_CH1	EVENTOUT
	PG11	-	-	-	-	-	SAI2_MCLK_A	TIM15_CH2	EVENTOUT
	PG12	-	-	-	-	FMC_NE4	SAI2_SD_A	-	EVENTOUT
	PG13	LCD_R0	-	-	-	FMC_A24	-	-	EVENTOUT
	PG14	LCD_R1	-	-	-	FMC_A25	-	-	EVENTOUT
	PG15	-	-	DCMI_D13/PSSI_ D13	-	-	-	-	EVENTOUT

Table 29. Alternate function AF8 to AF15(1) (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port H	PH0	-	-	-	-	-	-	-	EVENTOUT
	PH1	-	-	-	-	-	-	-	EVENTOUT
	PH2	-	-	-	-	-	-	-	EVENTOUT
	PH3	-	-	-	-	-	-	-	EVENTOUT
	PH4	-	-	PSSI_D14	-	-	-	-	EVENTOUT
	PH5	-	-	DCMI_PIXCLK/PSSI _PDCK	-	-	-	-	EVENTOUT
	PH6	-	-	DCMI_D8/PSSI_D8	-	-	-	-	EVENTOUT
	PH7	-	-	DCMI_D9/PSSI_D9	-	-	-	-	EVENTOUT
	PH8	-	-	DCMI_HSYNC/PSSI _DE	-	-	-	-	EVENTOUT
	PH9	HSPI1_NCS	-	DCMI_D0/PSSI_D0	-	-	-	-	EVENTOUT
	PH10	HSPI1_IO0	-	DCMI_D1/PSSI_D1	-	-	-	-	EVENTOUT
	PH11	HSPI1_IO1	-	DCMI_D2/PSSI_D2	-	-	-	-	EVENTOUT
	PH12	HSPI1_IO2	-	DCMI_D3/PSSI_D3	-	-	-	-	EVENTOUT
	PH13	HSPI1_IO3	FDCAN1_TX	-	-	-	-	-	EVENTOUT
	PH14	HSPI1_IO4	FDCAN1_RX	DCMI_D4/PSSI_D4	-	-	-	-	EVENTOUT
	PH15	HSPI1_IO5	-	DCMI_D11/PSSI_ D11	-	-	-	-	EVENTOUT

Table 29. Alternate function AF8 to AF15[1] (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port I	PI0	HSPI1_IO6	-	DCMI_D13/PSSI_ D13	-	-	-	-	EVENTOUT
	PI1	HSPI1_IO7	-	DCMI_D8/PSSI_D8	-	-	-	-	EVENTOUT
	PI2	HSPI1_DQS0	-	DCMI_D9/PSSI_D9	-	-	-	-	EVENTOUT
	PI3	HSPI1_CLK	-	DCMI_D10/PSSI_ D10	-	-	-	-	EVENTOUT
	PI4	HSPI1_NCLK	-	DCMI_D5/PSSI_D5	-	-	-	-	EVENTOUT
	PI5	-	-	DCMI_VSYNC/PSSI _RDY	-	-	-	-	EVENTOUT
	PI6	-	-	DCMI_D6/PSSI_D6	-	-	-	-	EVENTOUT
	PI7	-	-	DCMI_D7/PSSI_D7	-	-	-	-	EVENTOUT
	PI8	HSPI1_DQS1	-	-	-	-	-	-	EVENTOUT
	PI9	HSPI1_IO8	-	-	-	-	-	-	EVENTOUT
	PI10	HSPI1_IO9	-	-	-	-	-	-	EVENTOUT
	PI11	HSPI1_IO10	-	-	-	-	-	-	EVENTOUT
	PI12	HSPI1_IO11	-	-	-	-	-	-	EVENTOUT
	PI13	HSPI1_IO12	-	-	-	-	-	-	EVENTOUT
	PI14	HSPI1_IO13	-	-	-	-	-	-	EVENTOUT
	PI15	HSPI1_IO14	-	-	-	-	-	-	EVENTOUT

Table 29. Alternate function AF8 to AF15(1) (continued)

Port		AF8	AF9	AF10	AF11	AF12	AF13	AF14	AF15
		HSPI1/LCD/ LPUART1/ SDMMC1/ UART4/5	CAN1/TSC	CRS/DCMI/ OCTOSPIM_P1/2/ OTG_HS	DSI/FMC/ LPGPIO1/ SDMMC2/ UCPD1	COMP1/2/FMC/ SDMMC1/2/ SYS_AF	LPTIM2/4/ SAI1/2	LPTIM2/3/ TIM2/15/16/17	EVENTOUT
Port J	PJ0	HSPI1_IO15	-	-	-	-	-	-	EVENTOUT
	PJ1	-	-	-	-	-	-	-	EVENTOUT
	PJ2	-	-	-	-	-	-	-	EVENTOUT
	PJ3	-	-	-	-	-	-	-	EVENTOUT
	PJ4	-	-	-	-	-	-	-	EVENTOUT
	PJ5	-	-	-	-	-	-	-	EVENTOUT
	PJ6	-	-	-	-	-	-	-	EVENTOUT
	PJ7	-	-	-	-	-	-	-	EVENTOUT
	PJ8	-	-	-	-	-	-	-	EVENTOUT
	PJ9	-	-	-	-	-	-	-	EVENTOUT
	PJ10	-	-	-	-	-	-	-	EVENTOUT
	PJ11	-	-	-	-	-	-	-	EVENTOUT

1. For AF0 to AF7 refer to the previous table.

5 Electrical characteristics

5.1 Parameter conditions

Unless otherwise specified, all voltages are referenced to V_{SS}.

5.1.1 Minimum and maximum values

Unless otherwise specified, the minimum and maximum values are guaranteed in the worst conditions of ambient temperature, supply voltage and frequencies by tests in production on 100% of the devices with an ambient temperature at T_A = 25 °C and T_A = $T_A$max (given by the selected temperature range).

Data based on characterization results, design simulation and/or technology characteristics are indicated in the table footnotes, and are not tested in production. Based on characterization, the minimum and maximum values refer to sample tests and represent the mean value plus or minus three times the standard deviation (mean ±3σ).

5.1.2 Typical values

Unless otherwise specified, typical data are based on T_A = 25 °C, V_{DD} = V_{DDA} = 3 V. They are given only as design guidelines and are not tested.

Typical ADC accuracy values are determined by characterization of a batch of samples from a standard diffusion lot over the full temperature range and supply voltage range, where 95% of the devices have an error less than or equal to the value indicated (mean ±2σ).

5.1.3 Typical curves

Unless otherwise specified, all typical curves are given only as design guidelines and are not tested.

5.1.4 Loading capacitor

The loading conditions used for pin parameter measurement are shown in *Figure 21*.

5.1.5 Pin input voltage

The input voltage measurement on a pin of the device is described in *Figure 22*.

Figure 21. Pin loading conditions

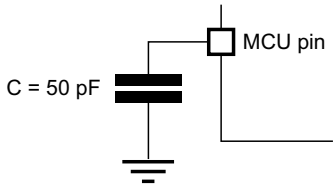
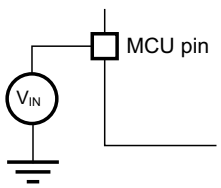


Figure 22. Pin input voltage

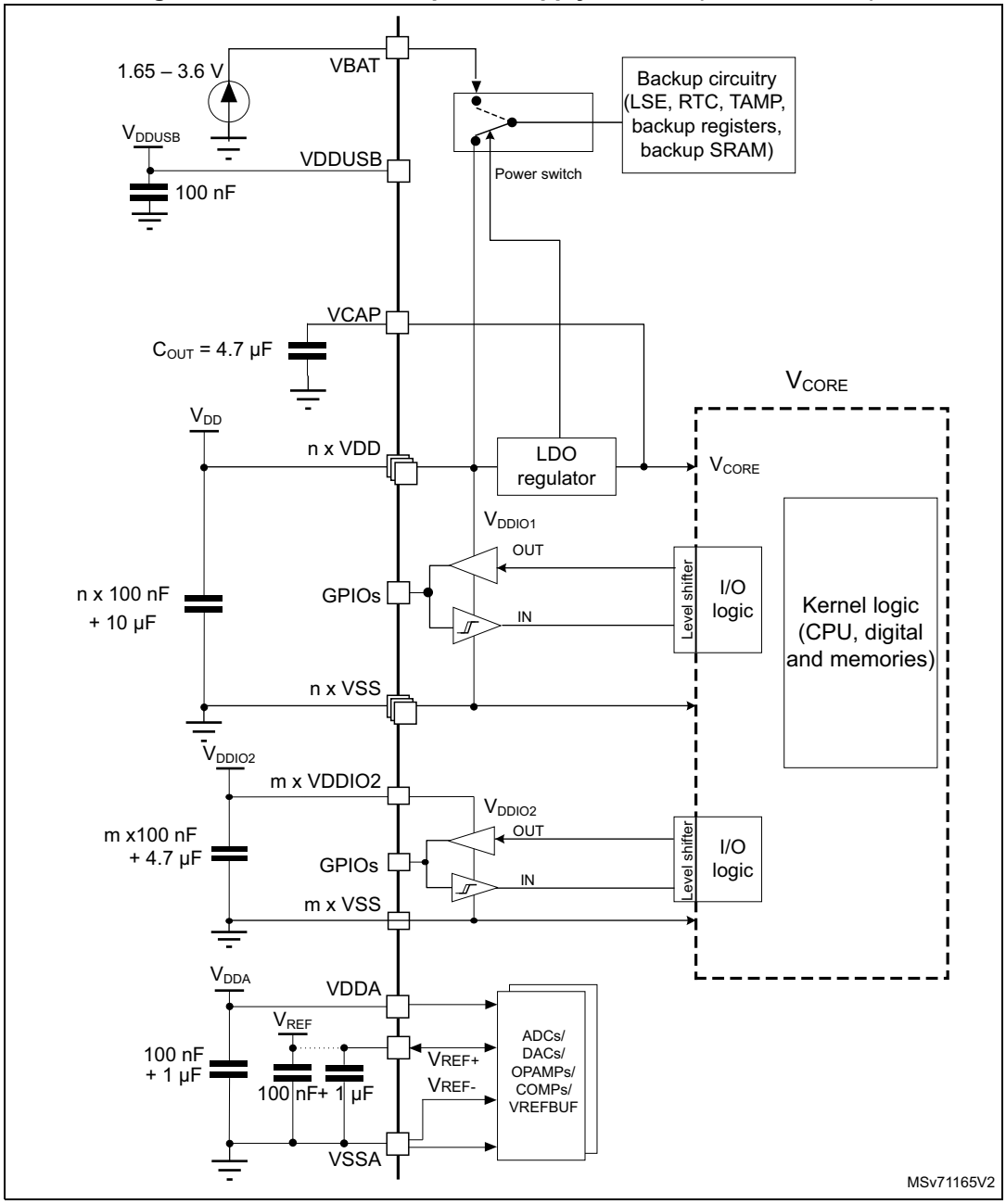


5.1.6 Power supply scheme

Each power supply pair (such as V_{DD}/V_{SS} or V_{DDA}/V_{SSA}) must be decoupled with filtering ceramic capacitors as shown in *Figure 23* and *Figure 24*. These capacitors must be placed

as close as possible to, or below, the appropriate pins on the underside of the PCB to ensure the proper functionality of the device.

Figure 23. STM32U5Axxx power supply scheme (without SMPS)

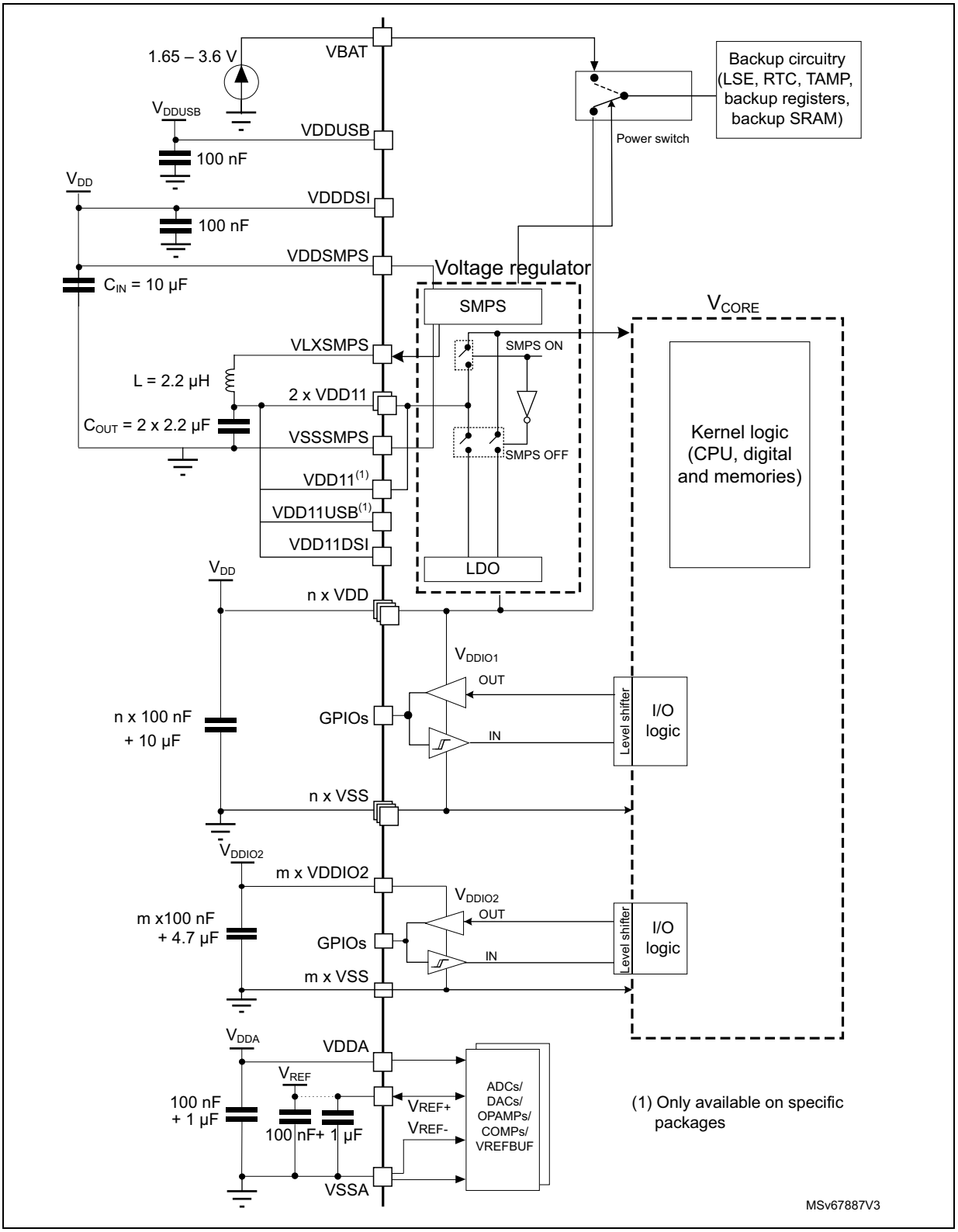


Caution: If there are two VCAP pins (TFBGA169 package), each pin must be connected to a 2.2 µF (typical) capacitor.

The external capacitor on VCAP pin requires the following characteristics:

- C_{OUT} = 4.7 µF or 2 × 2.2 µF ±20%
- C_{OUT} ESR < 20 mΩ at 3 MHz
- C_{OUT} rated voltage ≥ 10 V

Figure 24. STM32U5AxxxxxQ power supply scheme (with SMPS)



Note: SMPS and LDO regulators provide, in a concurrent way, the V_{CORE} supply depending on application requirements. However, only one of them is active at the same time. When SMPS is active, it feeds the V_{CORE} on the two VDD11 pins supplied by the filtered SMPS VLXSMPS output pin. When LDO is active, it supplies the V_{CORE} and regulates it using the same capacitors on VDD11 pins. It is recommended to add a decoupling capacitor of 100 nF near each VDD11 pin/ball, but it is not mandatory.

The external capacitors on VDD11 pins require the following characteristics:

- C_{OUT} = 2 × 2.2 µF ±20%
- C_{OUT} ESR < 20 mΩ at 3 MHz
- C_{OUT} rated voltage ≥ 10 V

The external capacitor on VDDSMPS pin requires the following characteristics:

- C_{IN} = 10 µF ±20%
- C_{IN} ESR < 10 mΩ at 3 MHz
- C_{IN} rated voltage ≥ 10 V

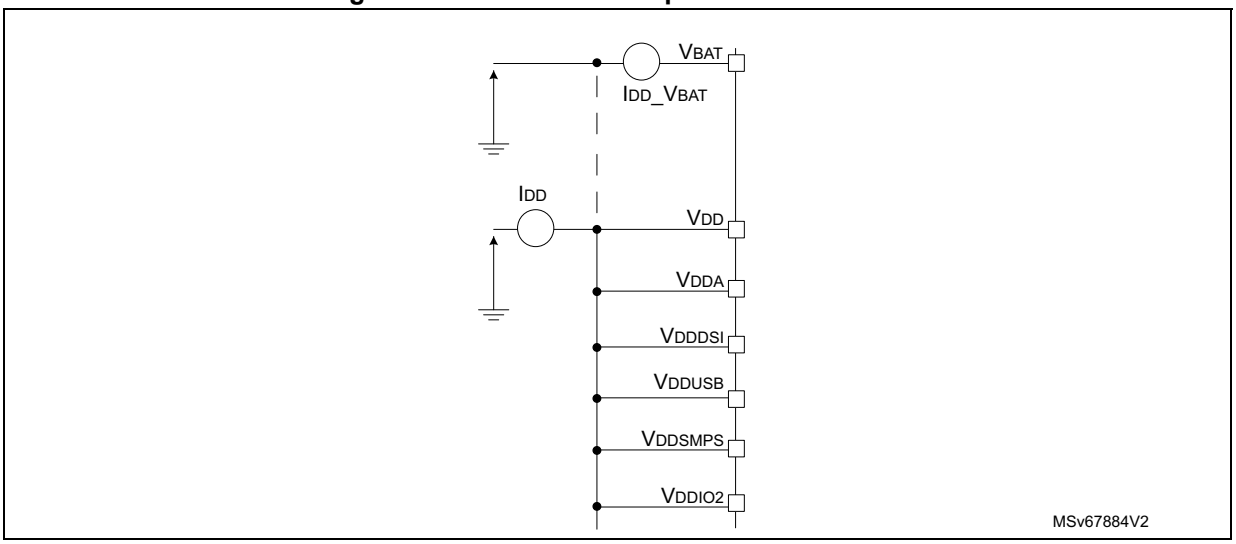
The external inductance between VLXSMPS and VDD11 requires the following characteristics:

- L = 2.2 µH ±20%
- L I_{SAT} > 0.5 A
- L DCR < 200 mΩ

5.1.7 Current consumption measurement

The I_{DD} parameters given in various tables in the next sections, represent the total MCU consumption including the current supplying V_{DD}, V_{DDIO2}, V_{DDA}, V_{DDUSB}, V_{DDDSI}, V_{BAT}, and V_{DDSMPS} (if the device embeds the SMPS).

Figure 25. Current consumption measurement



5.2 Absolute maximum ratings

Stresses above the absolute maximum ratings listed in *Table 30*, *Table 31*, and *Table 32* may cause permanent damage to the device. These are stress ratings only and the functional operation of the device at these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability. Device mission profile (application conditions) is compliant with JEDEC JESD47 qualification standard, extended mission profiles are available on demand.

Table 30. Voltage characteristics(1) (2)

Symbol	Ratings	Min	Max	Unit
V_{DDX} - V_{SS}	External main supply voltage (including V_{DDSMPS}, V_{DDA}, V_{DDUSB}, V_{DDDSI}, V_{BAT}, V_{REF+})	-0.3	4.0	V
V_{DDIOx}(3) - V_{SS}	I/O supply when HSLV = 0	-0.3	4.0	
	I/O supply when HSLV = 1	-0.3	2.75	
V_{IN}(4)	Input voltage on FT_xx pins except FT_c pins	V_{SS} - 0.3	Min (min (V_{DD}, V_{DDA}, V_{DDUSB}, V_{DDIO2}) + 4.0, 6.0)(5)(6)	
	Input voltage on FT_t pins in V_{BAT} mode	V_{SS} - 0.3	Min (min (V_{BAT}, V_{DDA}, V_{DDUSB}, V_{DDIO2}) + 4.0, 6.0)(5)(6)	
	Input voltage on FT_c pins	V_{SS} - 0.3	5.5	
	Input voltage on any other pins	V_{SS} - 0.3	4.0	
V_{REF+} - V_{DDA}	Allowed voltage difference for V_{REF+} > V_{DDA}	-	0.4	
$\lvert\Delta V_{DDx}\rvert$	Variations between different VDDx power pins of the same domain	-	50.0	mV
$\lvert V_{SSx}-V_{SS}\rvert$	Variations between all the different ground pins(7)	-	50.0	

1. All main power (VDD, VDDSMPS, VDDA, VDDUSB, VDDIO2, VDDDSI, VBAT) and ground (VSS, VSSA, VSSSMPS) pins must always be connected to the external power supply, in the permitted range.
2. The I/O structure options listed in this table can be a concatenation of options including the option explicitly listed. For instance TT_a refers to any TT I/O with _a option. TT_xx refers to any TT I/O and FT_xx refers to any FT I/O.
3. V_{DDIO1} or V_{DDIO2} or V_{SW}, V_{DDIO1} = V_{DD}.
4. V_{IN} maximum must always be respected. Refer to *Table 31* for the maximum allowed injected current values.
5. To sustain a voltage higher than 4 V, the internal pull-up/pull-down resistors must be disabled.
6. This formula has to be applied only on the power supplies related to the I/O structure described in the pin definition table.
7. Including VREF- pin.

Table 31. Current characteristics

Symbol	Ratings	Max	Unit
$\sum IV_{DD}$	Total current into sum of all V_{DD} power lines (source)(1)	200	mA
$\sum IV_{SS}$	Total current out of sum of all V_{SS} ground lines (sink)(1)	200	
IV_{DD}	Maximum current into each VDD power pin (source)(1)	100	
IV_{SS}	Maximum current out of each VSS ground pin (sink)(1)	100	
I_{IO}	Output current sunk by any I/O and control pin	20	
	Output current sourced by any I/O and control pin	20	
$\sum I_{(PIN)}$	Total output current sunk by sum of all I/Os and control pins(2)	120	
	Total output current sourced by sum of all I/Os and control pins(2)	120	
$I_{INJ(PIN)}$(3)(4)	Injected current on FT_xx, TT_xx, RST pins	-5/+0	
$\sum\lvert I_{INJ(PIN)}\rvert$	Total injected current (sum of all I/Os and control pins)(5)	±25	

1. All main power (VDD, VDDSMPS, VDDA, VDDUSB, VDDDSI, VDDIO2, VBAT) and ground (VSS, VSSA, VSSSMPS) pins must always be connected to the external power supplies, in the permitted range.
2. This current consumption must be correctly distributed over all I/Os and control pins. The total output current must not be sunk/sourced between two consecutive power supply pins, referring to high pin count QFP packages.
3. Positive injection (when $V_{IN} > V_{DDIOx}$) is not possible on these I/Os and does not occur for input voltages lower than the specified maximum value.
4. A negative injection is induced by $V_{IN} < V_{SS}$. $I_{INJ(PIN)}$ must never be exceeded. Refer also to *Table 30* for the minimum allowed input voltage values.
5. When several inputs are submitted to a current injection, the maximum $\sum\lvert I_{INJ(PIN)}\rvert$ is the absolute sum of the negative injected currents (instantaneous values).

Table 32. Thermal characteristics

Symbol	Ratings	Value	Unit
T_{STG}	Storage temperature range	–65 to +150	°C
T_J	Maximum junction temperature	140	

5.3 Operating conditions

5.3.1 General operating conditions

Table 33. General operating conditions

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DD}	Standard operating voltage	IO_VDD_HSLV(1) = 0	1.71(2)	-	3.6	V
		IO_VDD_HSLV = 1	1.71(2)	-	2.7	
V_{DDSMPS}	Supply voltage for the internal SMPS step-down converter	-	V_{DD}			
V_{DDIO2}	Supply voltage for PG[15:2] I/Os	At least one I/O in PG[15:2] used, IO_VDDIO2_HSLV = 0	1.08	-	3.6	
		At least one I/O in PG[15:2] used, IO_VDDIO2_HSLV = 1	1.08	-	2.7	
		PG[15:2] I/Os not used	0	-	3.6	
V_{DDUSB}	USB supply voltage	USB used	3.0	-	3.6	
		USB not used	0	-	3.6	
V_{DDA}	Analog supply voltage	COMP used	1.58	-	3.6	
		DAC or OPAMP used	1.60	-	3.6	
		ADC used	1.62	-	3.6	
		VREFBUF used (normal mode)	1.8	-	3.6	
		ADC, DAC, COMP, OPAMP, and VREFBUF not used	0	-	3.6	
V_{BAT}	Backup domain supply voltage	-	1.65(3)	-	3.6	
V_{IN}	I/O input voltage	All I/Os except FT_c and TT_xx pins	-0.3	-	Min(min(V_{DD}, V_{DDA}, V_{DDUSB}, V_{DDIO2}) +3.6, 5.5)(4)(5)	
		Input voltage on FT_t pins in V_{BAT} mode	-0.3	-	Min(min(V_{BAT}, V_{DDA}, V_{DDUSB}, V_{DDIO2}) + 3.6, 5.5)(4)(5)	
		FT_c I/Os	-0.3	-	5.0	
		TT_xx I/Os	-0.3	-	V_{DDIOx} + 0.3	
I_{IO_SW}	Sum of output current sourced by all I/Os powered by V_{SW}(6)	-	-	-	3	mA

Table 33. General operating conditions (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{CORE}	Internal regulator ON	Range 1	1.15	1.21	1.27	V
		Range 2	1.05	1.1	1.15	
		Range 3	0.95	1.0	1.05	
		Range 4	0.81	0.9	0.99	
f_{HCLK}	AHB clock frequency	Range 1	-	-	160	MHz
		Range 2	-	-	110	
		Range 3	-	-	55	
		Range 4	-	-	25	
f_{PCLKx} (x = 1, 2, 3)	APB1, APB2, APB3 clock frequency	Range 1	-	-	160	
		Range 2	-	-	110	
		Range 3	-	-	55	
		Range 4	-	-	25	
P_D	Power dissipation at T_A = 85 °C for suffix 6[7]	LQFP64	See *Section 6.9: Package thermal characteristics* for application appropriate thermal resistance and package. The power dissipation is then calculated according ambient temperature (T_A) and maximum junction temperature (T_J) and selected thermal resistance.			mW
		LPQF100				
		UFBGA132				
		LQFP144				
		WLCSP150				
		TFBGA169				
		WLCSP208				
		TFBGA216				
	Power dissipation at T_A = 125 °C for suffix 3[7]	LQFP64				
		LPQF100				
		UFBGA132				
		LQFP144				
		WLCSP150				
		TFBGA169				
		WLCSP208				
		TFBGA216				

Table 33. General operating conditions (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
T_A	Ambient temperature for suffix 6	Maximum power dissipation	–40		85	°C
		Low-power dissipation(8)	–40		105	
	Ambient temperature for suffix 3	Maximum power dissipation	–40		125	
		Low-power dissipation(8)	–40		130	
T_J	Junction temperature range	Suffix 6 version	–40		105	
		Suffix 3 version	–40		130	

1. HSLV means high-speed low-voltage mode (refer to the product reference manual).
2. When RESET is released, the functionality is guaranteed down to V_{BORx} min.
3. In V_{BAT} mode, the functionality is guaranteed down to V_{BOR_VBAT} min.
4. This formula has to be applied only on the power supplies related to the I/O structure described by the pin definition table. The maximum I/O input voltage is the smallest value between Min (V_{DD}, V_{DDA}, V_{DDUSB}, V_{DDIO2})+3.6 V, and 5.5V.
5. For operation with voltage higher than Min (V_{DD}, V_{DDA}, V_{DDUSB}, V_{DDIO2}) +0.3 V, the internal pull-up and pull-down resistors must be disabled.
6. The I/Os powered by V_{SW} are:

   - PC13, PC14, PC15 when V_{DD} is present,

   - PC13, PC14, PC15, and all FT_t I/Os in V_{BAT} mode.
7. If T_A is lower, higher P_D values are allowed as long as T_J does not exceed T_J max (see *Section 6.9: Package thermal characteristics*).
8. In low-power dissipation state, T_A can be extended to this range as long as T_J does not exceed T_J max (see *Section 6.9: Package thermal characteristics*).

5.3.2 Operating conditions at power-up/power-down

The parameters given in the table below are derived from tests performed under the ambient temperature condition summarized in *Table 33*.

Table 34. Operating conditions at power-up/power-down

Symbol	Parameter	Conditions	Min	Max	Unit
t_{VDD}	V_{DD} rise-time rate	-	0	∞	µs/V
	V_{DD} fall-time rate	ULPMEN = 0 (default value)	20	∞	
		Standby mode, BOR level 0 selected with ULPMEN = 1	250	∞	ms/V

5.3.3 Embedded reset and power control block characteristics

The parameters given in the table below are derived from tests performed under the ambient temperature conditions summarized in *Table 33*.

Table 35. Embedded reset and power control block characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{RSTTEMPO}$(2)	Reset temporization after BOR0 is detected	V_{DD} rising	-	-	900	µs
V_{BOR0}	Brownout reset threshold 0	Rising edge	1.6	1.66	1.71	V
		Falling edge, range 1, 2, 3	1.58	1.64	1.69	
		Falling edge, range 4 and low-power modes	1.58	1.64	1.69	
V_{BOR1}	Brownout reset threshold 1	Rising edge	1.98	2.08	2.17	
		Falling edge	1.9	2.00	2.1	
V_{BOR2}	Brownout reset threshold 2	Rising edge	2.18	2.29	2.39	
		Falling edge	2.08	2.18	2.25	
V_{BOR3}	Brownout reset threshold 3	Rising edge	2.48	2.59	2.7	
		Falling edge	2.39	2.5	2.61	
V_{BOR4}	Brownout reset threshold 4	Rising edge	2.76	2.88	3.0	
		Falling edge	2.67	2.79	2.9	
V_{PVD0}	Programmable voltage detector threshold 0	Rising edge	2.03	2.13	2.23	
		Falling edge	1.93	2.03	2.12	
V_{PVD1}	PVD threshold 1	Rising edge	2.18	2.29	2.39	
		Falling edge	2.08	2.18	2.28	
V_{PVD2}	PVD threshold 2	Rising edge	2.33	2.44	2.55	
		Falling edge	2.23	2.34	2.44	
V_{PVD3}	PVD threshold 3	Rising edge	2.47	2.59	2.7	
		Falling edge	2.39	2.50	2.61	
V_{PVD4}	PVD threshold 4	Rising edge	2.6	2.72	2.83	
		Falling edge	2.5	2.62	2.73	
V_{PVD5}	PVD threshold 5	Rising edge	2.76	2.88	3.0	
		Falling edge	2.66	2.78	2.9	
V_{PVD6}	PVD threshold 6	Rising edge	2.83	2.96	3.08	
		Falling edge	2.76	2.88	3.0	
V_{hyst_BOR0}	Hysteresis voltage of BOR0	-	-	20	-	mV
$V_{hyst_BOR_PVD}$	Hysteresis voltage of BOR (except BOR0) and PVD	-	-	80	-	
$t_{BOR0\ _sampling}$	BOR0 sampling period	ULPMEN = 1	-	30	55	ms

Table 35. Embedded reset and power control block characteristics(1) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I_{DD_BOR0}(2)	Additional BOR0 consumption if ULPMEN = 0 versus ULPMEN = 1	Standby mode	-	60	-	nA
$I_{DD_BOR_PVD}$(2)	BOR(3) (except BOR0) and PVD consumption from V_{DD}(4)	-	-	1	1.5	µA
V_{BOR_VBAT}	V_{BAT} brownout reset threshold	-	1.58	-	1.65	V
$t_{VBAT_BOR_sampling}$	V_{BAT} BOR sampling period in V_{BAT} mode	MONEN = 0(5)	-	0.5	2.5	s
V_{AVM1}	V_{DDA} voltage monitor 1 threshold	Rising edge	1.61	1.68	1.75	V
		Falling edge	1.58	1.65	1.71	
V_{AVM2}	V_{DDA} voltage monitor 2 threshold	Rising edge	1.77	1.86	1.95	
		Falling edge	1.73	1.82	1.9	
V_{IO2VM}	V_{DDIO2} voltage monitor threshold	-	0.96	1.01	1.05	
V_{UVM}	V_{DDUSB} voltage monitor threshold	-	1.15	1.22	1.28	
V_{hyst_AVM}	Hysteresis of V_{DDA} voltage monitor	-	-	40	-	mV
I_{DD_VM}(2)	Voltage monitor consumption from V_{DD} (AVM1, AVM2, IO2VM or UVM single instance)	-	-	0.4	0.6	µA
$I_{DD_AVM_A}$(2)	V_{DDA} voltage monitor consumption from V_{DDA} (resistor bridge)	-	-	1.25	1.85	

1. Evaluated by characterization and not tested in production, unless otherwise specified.
2. Specified by design. Not tested in production
3. BOR0 is enabled in all modes (except Shutdown), and its consumption is therefore included in the supply current characteristics tables.
4. This is also the consumption saved in Standby mode when ULPMEN = 1.
5. V_{BAT} brownout reset monitoring is discontinuous when MONEN = 0 in PWR_BDCR1, and is continuous when MONEN = 1.

5.3.4 SMPS characteristics

Table 36. SMPS characteristics

Symbol	Parameter	Conditions	Typ	Unit
Freq	Switching frequency (range 1, 2, 3)(1)	V_{DD} > 1.9 V	3	MHz
		V_{DD} < 1.9 V	1.5	

1. The SMPS is asynchronous in range 4 and low-power modes.

5.3.5 Embedded voltage reference

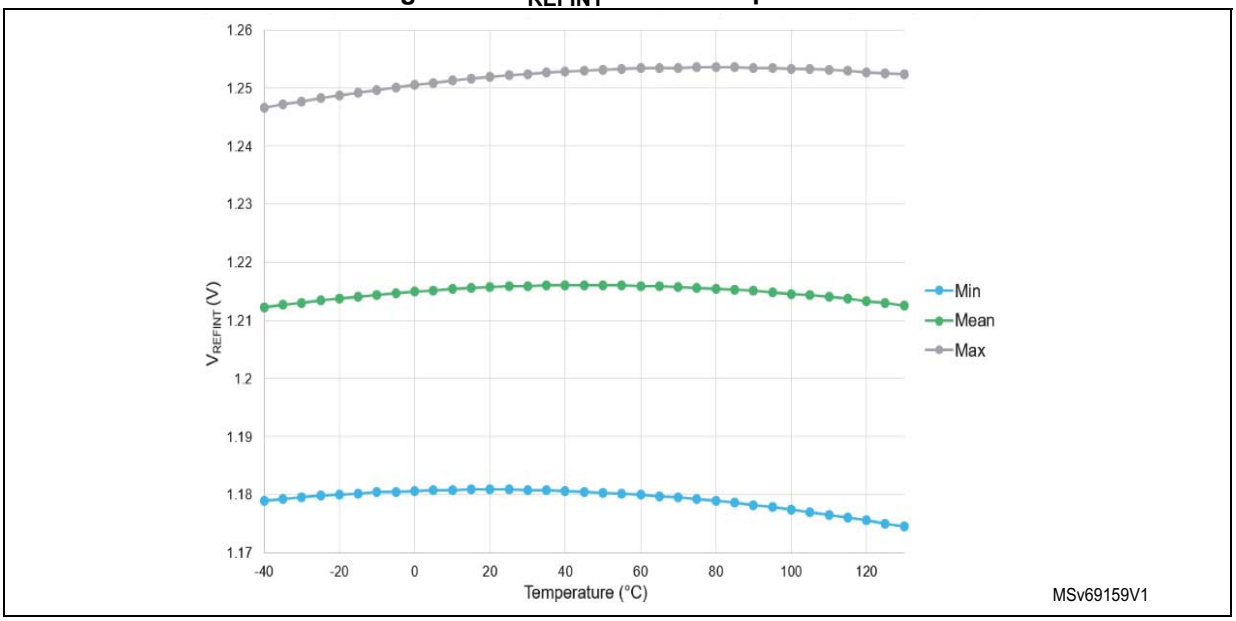
The parameters given in the table below are derived from tests performed under the ambient temperature and supply voltage conditions summarized in *Table 33*.

Table 37. Embedded internal voltage reference

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{REFINT}(1)	Internal reference voltage	Range 1, 2, 3	1.175	1.215	1.255	V
		Range 4 and low-power modes	1.170	1.215	1.260	
$t_{S_vrefint}$(2)(3)	ADC sampling time when reading the internal reference voltage	-	12.65	-	-	µs
$t_{start_vrefint}$(3)	Start time of reference voltage buffer when the ADC is enabled	-	-	4	6	
$I_{DD(VREFINTBUF)}$(3)	V_{REFINT} buffer consumption from V_{DD} when converted by the ADC	-	-	1.5	2.1	µA
ΔV_{REFINT}(4)	Internal reference voltage spread over the temperature range	V_{DD} = 3 V	-	6	11.5	mV
T_{Coeff}(4)	Average temperature coefficient	–40°C < T_J < +130 °C	-	40	125	ppm/°C
A_{Coeff}(3)	Long term stability	1000 hours, T_J = 25 °C	-	400	1000	ppm
$V_{DDCoeff}$(4)	Average voltage coefficient	3.0 V ≤ V_{DD} ≤ 3.6 V	-	500	2900	ppm/V
V_{REFINT_DIV1}(3)	1/4 reference voltage	-	24	25	26	% V_{REFINT}
V_{REFINT_DIV2}(3)	1/2 reference voltage		49	50	51	
V_{REFINT_DIV3}(3)	3/4 reference voltage		74	75	76	

1. V_{REFINT} does not take into account package and soldering effects.
2. The shortest sampling time for the application can be determined by multiple iterations.
3. Specified by design. Not tested in production
4. Evaluated by characterization. Not tested in production.

Figure 26. V_{REFINT} versus temperature



5.3.6 Supply current characteristics

The current consumption is a function of several parameters and factors such as the operating voltage, ambient temperature, I/O pin loading, device software configuration, operating frequencies, I/O pin switching rate, program location in memory and executed binary code.

The current consumption is measured as described in *Section 5.1.7: Current consumption measurement*.

Typical and maximum current consumption

The MCU is placed under the following conditions:

- All I/O pins are in analog input mode.
- All peripherals are disabled except when explicitly mentioned.
- The flash memory access time is adjusted with the minimum wait-state number, depending on the f_{HCLK} frequency (refer to the tables “Number of wait states according to CPU clock (HCLK) frequency” available in the product reference manual).
- When the peripherals are enabled, $f_{PCLK} = f_{HCLK}$.
- The voltage scaling range is adjusted to f_{HCLK} frequency as follows:
  - Voltage range 1 for 110 MHz < f_{HCLK} ≤ 160 MHz
  - Voltage range 2 for 55 MHz < f_{HCLK} ≤ 110 MHz
  - Voltage range 3 for 25 MHz < f_{HCLK} ≤ 55 MHz
  - Voltage range 4 for f_{HCLK} ≤ 25 MHz

The parameters given in the tables below are derived from tests performed under ambient temperature and supply voltage conditions summarized in *Table 33*. These parameters are evaluated by characterization, and not tested in production unless otherwise specified.

Table 38. Current consumption in Run mode on LDO, code with data processing running from flash memory, ICACHE ON in 1-way, prefetch ON(1)

Symbol	Parameter	Conditions			Typ					Max at 1.71 V ≤ V_{DD} ≤ 3.6 V(2)					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{MSI}$, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 4	24	1.85	2.50	4.45	7.4	13.0	3.1	4.8	11	20	37	mA
				16	1.45	2.10	4.05	7	12.5	2.7	4.4	11	19	36	
				12	1.20	1.80	3.80	6.7	12.0	2.4	4.0	9.9	19	36	
				4	0.65	1.30	3.25	6.15	11.5	1.8	3.5	9.3	18	35	
				2	0.53	1.15	3.10	6.05	11.5	1.6	3.3	9.2	18	35	
				1	0.47	1.10	3.05	6.0	11.5	1.6	3.3	9.1	18	35	
				0.4	0.43	1.05	3.00	5.95	11.5	1.5	3.2	9	18	35	
				0.1	0.41	1.05	3.00	5.9	11.5	1.5	3.2	9	18	35	
		f_{HCLK} = PLL on HSE 16 MHz in bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 1	160	14.0	15.5	18.5	23.5	31.5	19	23	36	56	93	
				140	12.5	14.0	17.0	22	30.0	17	21	34	54	91	
				120	11.0	12.0	15.5	20	28.5	15	19	33	52	90	
			Range 2	110	9.15	10.0	13.0	17	24.0	12	15	26	41	68	
				72	6.35	7.35	10.0	14	21.0	9	12	22	37	65	
				64	5.80	6.75	9.50	13.5	20.5	8.4	12	22	37	65	
		$f_{HCLK} = f_{HSE}$ bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 3	55	4.60	5.40	7.70	11	17.5	6.5	8.7	17	28	50	
				32	2.95	3.75	6.05	9.5	15.5	4.7	6.9	15	26	48	

1. The current consumption from SRAM is similar.
2. Evaluated by characterization. Not tested in production.

Table 39. Current consumption in Run mode on SMPS, code with data processing running from flash memory, ICACHE ON in 1-way, prefetch ON(1)

Symbol	Parameter	Conditions			Typ at V_{DD} = 1.8 V					Max at 1.71 V ≤ V_{DD} ≤ 3.6 V(2)(3)					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{MSI}$, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 4	24	1.20	1.50	2.65	4.40	7.60	2.1	2.9	7	13	23	mA
				16	0.93	1.25	2.40	4.15	7.35	1.8	2.6	6	12	23	
				12	0.80	1.10	2.25	4.00	7.20	1.6	2.5	6.3	12	22	
				4	0.43	0.79	1.95	3.70	6.90	1.2	2.1	5.9	12	22	
				2	0.31	0.65	1.85	3.60	6.80	1.0	2	5.8	12	22	
				1	0.27	0.60	1.85	3.55	6.80	1.0	1.9	5.8	12	22	
				0.4	0.25	0.58	1.80	3.55	6.75	0.9	1.8	6	12	22	
				0.1	0.24	0.57	1.80	3.55	6.75	0.9	1.8	6	12	22	
		f_{HCLK} = PLL on HSE 16 MHz in bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 1	160	11.5	12.0	14.5	18.0	24.0	15	17	27	40	64	
				140	10.0	10.5	13.0	16.5	22.5	14	16	25	38	62	
				120	8.75	9.35	12.0	15.5	21.5	12	14	24	37	61	
			Range 2	110	6.75	7.15	9.05	12.0	16.5	9	11	18	28	45	
				72	4.75	5.20	7.10	9.80	14.5	7	9	16	25	43	
				64	4.30	4.80	6.70	9.40	14.0	6.2	8	15	25	42	
		$f_{HCLK} = f_{HSE}$ bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 3	55	3.15	3.55	5.00	7.15	11.0	4.5	6	11	19	32	
				32	2.10	2.50	4.00	6.15	10.0	3.3	4.5	10	17	31	

1. The current consumption from SRAM is similar.
2. Evaluated by characterization. Not tested in production.
3. The maximum value is at V_{DD} = 1.71 V in Run mode on SMPS.

Table 40. Current consumption in Run mode on SMPS, code with data processing running from flash memory, ICACHE ON in 1-way, prefetch ON, V_{DD} = 3.0 V(1)

Symbol	Parameter	Conditions			Typ at V_{DD} = 3.0 V					Max at V_{DD} = 3.0 V(2)					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{MSI}$, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 4	24	0.77	0.95	1.65	2.75	4.75	1.3	1.9	4.0	7	14	mA
				16	0.61	0.80	1.50	2.60	4.60	1.2	1.7	3.9	7	14	
				12	0.50	0.70	1.40	2.50	4.50	1.0	1.6	3.8	7	13	
				4	0.28	0.49	1.20	2.30	4.30	0.8	1.4	3.6	7	13	
				2	0.23	0.45	1.20	2.25	4.25	0.7	1.3	3.6	7	13	
				1	0.21	0.43	1.15	2.25	4.25	0.7	1.3	3.5	7	13	
				0.4	0.19	0.42	1.15	2.25	4.25	0.7	1.3	3.5	7	13	
				0.1	0.18	0.41	1.15	2.20	4.20	0.7	1.3	3.5	7	13	
		f_{HCLK} = PLL on HSE 16 MHz in bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 1	160	7.60	8.00	9.70	12.0	16.0	10	11	17	25	39	
				140	6.80	7.20	8.90	11.5	15.5	9	10	16	24	39	
				120	5.95	6.40	8.05	10.5	14.5	8	9	15	23	38	
			Range 2	110	4.65	5.00	6.25	8.05	11.5	6	7	12	17	28	
				72	3.30	3.70	4.95	6.75	10.0	4.5	5.6	10	16	27	
				64	3.05	3.45	4.70	6.50	9.75	4.3	5.3	9	16	26	
		$f_{HCLK} = f_{HSE}$ bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 3	55	2.30	2.60	3.60	5.05	7.70	3.2	4.0	7	12	20	
				32	1.55	1.90	2.85	4.30	6.95	2.4	3.2	6	11	19	

1. The current consumption from SRAM is similar.
2. Evaluated by characterization. Not tested in production.

Table 41. Typical current consumption in Run mode on LDO, with different codes running from flash memory, ICACHE ON (1-way), prefetch ON(1)

Symbol	Parameter	Conditions			Typ			Unit	Typ			Unit
		-	Voltage scaling	Code	1.8 V	3 V	3.3 V		1.8 V	3 V	3.3 V	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{MSI}$ = 24 MHz, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 4	Reduced Code	1.85	1.85	1.85	mA	77	77	77	µA/MHz
				CoreMark	1.85	1.85	1.85		77	77	77	
				SecureMark	2	2	2		83	83	83	
				Dhrystone 2.1	1.95	1.95	1.95		81	81	81	
				Fibonacci	1.6	1.6	1.6		67	67	67	
				While(1)	1.4	1.4	1.4		58	58	58	
		$f_{HCLK} = f_{PLL}$ = 160 MHz, PLL on HSE 16 MHz in bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 1	Reduced Code	14	14	14		88	88	88	
				CoreMark	14.5	14.5	14.5		91	91	91	
				SecureMark	16	16	16		100	100	100	
				Dhrystone 2.1	15	15	15		94	94	94	
				Fibonacci	11.5	11.5	11.5		72	72	72	
				While(1)	10.5	10.5	10.5		66	66	66	
		$f_{HCLK} = f_{PLL}$ = 110 MHz, PLL on HSE 16 MHz in bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 2	Reduced Code	9.15	9.15	9.15		83	83	83	
				CoreMark	9.2	9.25	9.25		84	84	84	
				SecureMark	10	10	10		91	91	91	
				Dhrystone 2.1	9.75	9.8	9.8		89	89	89	
				Fibonacci	7.55	7.6	7.6		69	69	69	
				While(1)	6.7	6.75	6.75		61	61	61	

Table 41. Typical current consumption in Run mode on LDO, with different codes running from flash memory, ICACHE ON (1-way), prefetch ON(1) (continued)

Symbol	Parameter	Conditions			Typ			Unit	Typ			Unit
		-	Voltage scaling	Code	1.8 V	3 V	3.3 V		1.8 V	3 V	3.3 V	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{HSE}$ = 55 MHz, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 3	Reduced Code	4.5	4.6	4.6	mA	82	84	84	µA/MHz
				CoreMark	4.6	4.65	4.7		84	85	85	
				SecureMark	5	5.05	5.1		91	92	93	
				Dhrystone 2.1	4.85	4.9	4.9		88	89	89	
				Fibonacci	3.7	3.8	3.8		67	69	69	
				While(1)	3.25	3.35	3.35		59	61	61	

1. The current consumption from SRAM is similar.

Table 42. Typical current consumption in Run mode on SMPS, with different codes running from flash memory, ICACHE ON (1-way), prefetch ON(1)

Symbol	Parameter	Conditions			Typ			Unit	Typ			Unit
		-	Voltage scaling	Code	1.8 V	3 V	3.3 V		1.8 V	3 V	3.3 V	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{MSI}$ = 24 MHz, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 4	Reduced Code	1.2	0.77	0.7	mA	50	32	29	µA/MHz
				CoreMark	1.2	0.77	0.7		50	32	29	
				SecureMark	1.3	0.83	0.76		54	35	31	
				Dhrystone 2.1	1.25	0.81	0.74		52	34	31	
				Fibonacci	1.05	0.66	0.61		44	27	25	
				While(1)	0.94	0.61	0.54		39	25	22	
		$f_{HCLK} = f_{PLL}$ = 160 MHz, PLL on HSE 16 MHz in bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 1	Reduced Code	11.5	7.6	7.1		72	48	44	
				CoreMark	11.5	7.65	7.15		72	48	45	
				SecureMark	12.5	8.4	7.85		78	53	49	
				Dhrystone 2.1	12.0	8.1	7.55		75	51	47	
				Fibonacci	9.35	6.35	5.9		58	40	37	
				While(1)	8.3	5.65	5.3		52	35	33	
		$f_{HCLK} = f_{PLL}$ = 110 MHz, PLL on HSE 16 MHz in bypass mode, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 2	Reduced Code	6.75	4.65	4.35		61	42	40	
				CoreMark	6.8	4.7	4.4		62	43	40	
				SecureMark	7.45	5.1	4.8		68	46	44	
				Dhrystone 2.1	7.2	4.95	4.6		65	45	42	
				Fibonacci	5.6	3.9	3.7		51	35	34	
				While(1)	5.0	3.5	3.3		45	32	30	

Table 42. Typical current consumption in Run mode on SMPS, with different codes running from flash memory, ICACHE ON (1-way), prefetch ON(1) (continued)

Symbol	Parameter	Conditions			Typ			Unit	Typ			Unit
		-	Voltage scaling	Code	1.8 V	3 V	3.3 V		1.8 V	3 V	3.3 V	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{HSE}$ = 55 MHz, all peripherals disabled, Flash bank 2 in power down, all SRAMs enabled	Range 3	Reduced Code	3.15	2.3	2.2	mA	57	42	40	µA/MHz
				CoreMark	3.2	2.35	2.2		58	43	40	
				SecureMark	3.5	2.5	2.4		64	45	44	
				Dhrystone 2.1	3.35	2.45	2.3		61	45	42	
				Fibonacci	2.65	1.95	1.85		48	35	34	
				While(1)	2.35	1.75	1.7		43	32	31	

1. The current consumption from SRAM is similar.

Table 43. Typical current consumption in Run mode on LDO, with different codes running from flash memory in low-power mode, ICACHE ON (1-way), prefetch ON

Symbol	Parameter	Conditions			Typ			Unit	Typ			Unit
		-	Voltage scaling	Code	1.8 V	3 V	3.3 V		1.8 V	3 V	3.3 V	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{MSI}$ = 24 MHz, all peripherals disabled, Flash bank 1 in low power, Flash bank 2 in power down, SRAM2 enabled, SRAM1/3/4/5 in power down	Range 4	Reduced Code	1.65	1.65	1.65	mA	68.8	68.8	68.8	µA/MHz
				CoreMark	1.65	1.65	1.65		68.8	68.8	68.8	
				SecureMark	1.8	1.8	1.8		75	75	75	
				Dhrystone 2.1	1.75	1.75	1.75		72.9	72.9	72.9	
				Fibonacci	1.4	1.4	1.4		58.3	58.3	58.3	
				While(1)	1.2	1.2	1.2		50	50	50	

Table 44. Typical current consumption in Run mode on SMPS, with different codes running from flash memory in low-power mode, ICACHE ON (1-way), prefetch ON

Symbol	Parameter	Conditions			Typ			Unit	Typ			Unit
		-	Voltage scaling	Code	1.8 V	3 V	3.3 V		1.8 V	3 V	3.3 V	
I_{DD} (Run)	Supply current in Run mode	$f_{HCLK} = f_{MSI}$ = 24 MHz, all peripherals disabled, Flash bank 1 in low power, Flash bank 2 in power down, SRAM2 enabled, SRAM1/3/4/5 in power down	Range 4	Reduced Code	1.05	0.66	0.61	mA	43.8	27.5	25.4	µA/MHz
				CoreMark	1.05	0.66	0.61		43.8	27.5	25.4	
				SecureMark	1.15	0.73	0.67		47.9	30.4	27.7	
				Dhrystone 2.1	1.10	0.70	0.65		45.8	29.2	26.9	
				Fibonacci	0.94	0.56	0.52		39	23.3	21.5	
				While(1)	0.80	0.49	0.45		33.3	20.2	18.5	

Table 45. Current consumption in Sleep mode on LDO, flash memory in power down

Symbol	Parameter	Conditions			Typ					Max at 1.71 V ≤ V_{DD} ≤ 3.6 V(1)					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (Sleep)	Supply current in Sleep mode	$f_{HCLK} = f_{MSI}$, all peripherals disabled	Range 4	24	0.75	1.35	3.30	6.25	11.5	1.8	3.4	9.2	18	34	mA
				16	0.63	1.25	3.20	6.10	11.5	1.6	3.3	9.1	18	34	
				12	0.57	1.20	3.15	6.05	11.5	1.6	3.2	9.0	18	34	
				4	0.42	1.05	3.00	5.90	11.5	1.4	3.1	8.9	18	34	
				2	0.39	1.00	2.95	5.85	11.0	1.4	3.0	8.8	18	33	
				1	0.37	1.00	2.95	5.85	11.0	1.3	3.0	8.8	18	33	
				0.4	0.36	0.99	2.90	5.85	11.0	1.3	3.0	8.7	18	33	
				0.1	0.36	0.98	2.90	5.85	11.0	1.3	3.0	8.7	18	33	
		f_{HCLK} = PLL on HSE 16 MHz in bypass mode, all peripherals disabled	Range 1	160	4.80	6.00	9.15	14.0	22.0	7.7	11	21	37	64	
				140	4.40	5.55	8.70	13.5	21.5	7.2	9.7	21	36	64	
				120	3.95	5.10	8.25	13.0	21.0	6.7	9.2	20	36	63	
			Range 2	110	3.25	4.20	6.90	11.0	18.0	5.3	8.2	19	34	60	
				72	2.50	3.45	6.15	10.0	17.0	4.5	7.4	18	33	59	
				64	2.35	3.30	5.95	9.90	17.0	4.3	7.2	18	33	59	
		$f_{HCLK} = f_{HSE}$ bypass mode, all peripherals disabled	Range 3	55	1.75	2.55	4.80	8.20	14.5	3.2	5.4	13	25	45	
				32	1.30	2.05	4.35	7.75	14.0	2.7	4.9	13	24	45	

1. Evaluated by characterization. Not tested in production.

Table 46. Current consumption in Sleep mode on SMPS, flash memory in power down

Symbol	Parameter	Conditions			Typ at V_{DD} = 1.8 V					Max at 1.71 V ≤ V_{DD} ≤ 3.6 V(1)(2)					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (Sleep)	Supply current in Sleep mode	$f_{HCLK} = f_{MSI}$, all peripherals disabled	Range 4	24	0.47	0.86	1.95	3.7	6.85	1.1	2.1	5.8	12	22	mA
				16	0.39	0.75	1.90	3.6	6.80	1.0	1.9	5.7	12	22	
				12	0.36	0.69	1.85	3.6	6.75	0.9	1.9	5.7	12	22	
				4	0.22	0.55	1.75	3.5	6.65	0.8	1.7	5.6	11	21	
				2	0.21	0.53	1.75	3.45	6.65	0.7	1.7	5.6	11	21	
				1	0.20	0.52	1.75	3.45	6.65	0.7	1.7	5.6	11	21	
				0.4	0.19	0.52	1.75	3.45	6.65	0.7	1.7	5.6	11	21	
				0.1	0.19	0.51	1.75	3.45	6.65	0.7	1.7	5.6	11	21	
		f_{HCLK} = PLL on HSE 16 MHz in bypass mode, all peripherals disabled	Range 1	160	3.95	4.70	7.10	10.5	16.5	5.9	8	18	31	55	
				140	3.60	4.35	6.75	10.0	16.5	5.5	8	18	30	55	
				120	3.25	4.00	6.40	9.85	16.0	5.1	7	17	30	54	
			Range 2	110	2.50	3.05	4.90	7.6	12.5	3.9	5.5	13	22	40	
				72	1.95	2.50	4.35	7.05	12.0	3.3	4.9	12	22	40	
				64	1.80	2.40	4.25	6.95	11.5	3.1	4.8	12	22	39	
		$f_{HCLK} = f_{HSE}$ bypass mode, all peripherals disabled	Range 3	55	1.25	1.70	3.15	5.3	9.15	2.2	3.4	9	16	29	
				32	0.98	1.45	2.90	5.0	8.85	1.9	3.1	8	16	29	

1. Evaluated by characterization. Not tested in production.
2. The maximum value is at V_{DD} = 1.71 V in Sleep mode on SMPS.

Table 47. Current consumption in Sleep mode on SMPS, flash memory in power down, V_{DD} = 3.0 V

Symbol	Parameter	Conditions			Typ at V_{DD} = 3.0 V					Max at V_{DD} = 3.0 V(1)					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (Sleep)	Supply current in Sleep mode	$f_{HCLK} = f_{MSI}$, all peripherals disabled	Range 4	24	0.29	0.50	1.20	2.30	4.25	0.7	1.3	3.4	7	13	mA
				16	0.25	0.46	1.15	2.25	4.20	0.6	1.2	3.3	7	13	
				12	0.22	0.44	1.15	2.20	4.20	0.6	1.2	3.3	7	13	
				4	0.16	0.38	1.10	2.15	4.15	0.5	1.1	3.3	7	13	
				2	0.15	0.37	1.10	2.15	4.10	0.5	1.1	3.3	7	13	
				1	0.14	0.36	1.05	2.15	4.10	0.5	1.1	3.2	7	13	
				0.4	0.14	0.36	1.05	2.15	4.10	0.5	1.1	3.2	7	13	
				0.1	0.14	0.36	1.05	2.15	4.10	0.5	1.1	3.2	7	13	
		f_{HCLK} = PLL on HSE 16 MHz in bypass mode, all peripherals disabled	Range 1	160	2.80	3.35	4.95	7.20	11.5	4.0	5.5	11	19	34	
				140	2.55	3.10	4.70	7.00	11.0	3.8	5.2	11	19	33	
				120	2.35	2.85	4.45	6.75	11.0	3.5	5.0	11	19	33	
			Range 2	110	1.85	2.25	3.50	5.30	8.50	2.7	3.8	8	14	25	
				72	1.50	1.90	3.15	4.90	8.10	2.3	3.4	7	14	24	
				64	1.40	1.85	3.05	4.85	8.05	2.2	3.4	7	14	24	
		$f_{HCLK} = f_{HSE}$ bypass mode, all peripherals disabled	Range 3	55	1.05	1.35	2.35	3.75	6.35	1.7	2.5	5.4	10	18	
				32	0.82	1.15	2.10	3.55	6.10	1.4	2.2	5.1	10	18	

1. Evaluated by characterization. Not tested in production.

Table 48. SRAM1/SRAM3/SRAM5 current consumption in Run/Sleep mode with LDO and SMPS

Symbol	Parameter	Conditions			Typ					Max					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (SRAM1)	LDO	SRAM1 supply current in Run/Sleep mode (SRAM1PD = 1 versus SRAM1PD = 0)	Range 4	24	0.05	0.16	0.50	1.00	2.00	0.20	0.48	1.5	3.0	6.0	mA
			Range 1	160	0.15	0.32	0.85	1.65	3.10	0.53	0.96	2.6	5.0	9.3	
			Range 2	110	0.11	0.25	0.71	1.40	2.65	0.38	0.75	2.2	4.2	8.0	
			Range 3	55	0.08	0.20	0.59	1.20	2.30	0.28	0.60	1.8	3.6	6.9	
I_{DD} (SRAM3)		SRAM3 supply current in Run/Sleep mode (SRAM3PD = 1 versus SRAM3PD = 0)	Range 4	24	0.06	0.17	0.53	1.10	2.10	0.22	0.51	1.6	3.3	6.3	
			Range 1	160	0.16	0.35	0.91	1.75	3.30	0.56	1.1	2.8	5.3	9.9	
			Range 2	110	0.12	0.27	0.75	1.50	2.80	0.42	0.81	2.3	4.5	8.4	
			Range 3	55	0.08	0.21	0.63	1.25	2.45	0.30	0.63	1.9	3.8	7.4	
I_{DD} (SRAM5)		SRAM5 supply current in Run/Sleep mode (SRAM5PD = 1 versus SRAM5PD = 0)	Range 4	24	0.06	0.17	0.53	1.10	2.15	0.22	0.51	1.6	3.3	6.5	
			Range 1	160	0.16	0.35	0.92	1.75	3.30	0.58	1.1	2.8	5.3	9.9	
			Range 2	110	0.12	0.27	0.76	1.50	2.85	0.42	0.81	2.3	4.5	8.6	
			Range 3	55	0.08	0.22	0.64	1.25	2.45	0.30	0.65	2.0	3.8	7.4	

Table 48. SRAM1/SRAM3/SRAM5 current consumption in Run/Sleep mode with LDO and SMPS (continued)

Symbol	Parameter	Conditions			Typ					Max					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (SRAM1)	SMPS(1)	SRAM1 supply current in Run/Sleep mode (SRAM1PD = 1 versus SRAM1PD = 0)	Range 4	24	0.04	0.10	0.29	0.63	1.21	0.14	0.32	0.93	2.0	3.9	mA
			Range 1	160	0.12	0.27	0.70	1.35	2.50	0.48	0.85	2.3	4.3	7.9	
			Range 2	110	0.08	0.18	0.53	1.04	2.00	0.31	0.58	1.7	3.3	6.4	
			Range 3	55	0.05	0.14	0.41	0.83	1.60	0.21	0.44	1.3	2.7	5.1	
I_{DD} (SRAM3)		SRAM3 supply current in Run/Sleep mode (SRAM3PD = 1 versus SRAM3PD = 0)	Range 4	24	0.04	0.11	0.31	0.66	1.29	0.15	0.34	0.98	2.1	4.1	
			Range 1	160	0.12	0.28	0.75	1.44	2.67	0.47	0.90	2.4	4.6	8.5	
			Range 2	110	0.09	0.20	0.57	1.12	2.08	0.33	0.64	1.8	3.6	6.6	
			Range 3	55	0.06	0.15	0.44	0.88	1.67	0.23	0.47	1.4	2.8	5.3	
I_{DD} (SRAM5)		SRAM5 supply current in Run/Sleep mode (SRAM5PD = 1 versus SRAM5PD = 0)	Range 4	24	0.04	0.11	0.32	0.67	1.30	0.15	0.34	1.0	2.2	4.2	
			Range 1	160	0.13	0.28	0.76	1.46	2.75	0.51	0.90	2.4	4.7	8.7	
			Range 2	110	0.09	0.20	0.58	1.13	2.17	0.34	0.64	1.9	3.6	6.9	
			Range 3	55	0.06	0.15	0.44	0.89	1.75	0.23	0.48	1.4	2.9	5.6	

Table 48. SRAM1/SRAM3/SRAM5 current consumption in Run/Sleep mode with LDO and SMPS (continued)

Symbol	Parameter	Conditions			Typ					Max					Unit
		-	Voltage scaling	f_{HCLK} (MHz)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
I_{DD} (SRAM1)	SMPS (V_{DD} = 3.0V)	SRAM1 supply current in Run/Sleep mode (SRAM1PD = 1 versus SRAM1PD = 0)	Range 4	24	0.02	0.06	0.18	0.38	0.73	0.08	0.18	0.53	1.2	2.2	mA
			Range 1	160	0.07	0.16	0.42	0.81	1.50	0.27	0.48	1.3	2.5	4.5	
			Range 2	110	0.05	0.11	0.32	0.63	1.20	0.18	0.33	0.96	1.9	3.6	
			Range 3	55	0.03	0.08	0.25	0.50	0.96	0.12	0.25	0.74	1.5	2.9	
I_{DD} (SRAM3)		SRAM3 supply current in Run/Sleep mode (SRAM3PD = 1 versus SRAM3PD = 0)	Range 4	24	0.02	0.06	0.19	0.40	0.78	0.09	0.19	0.56	1.2	2.4	
			Range 1	160	0.07	0.17	0.45	0.87	1.60	0.27	0.51	1.4	2.6	4.8	
			Range 2	110	0.05	0.12	0.34	0.67	1.25	0.19	0.36	1.1	2.1	3.8	
			Range 3	55	0.04	0.09	0.27	0.53	1.00	0.13	0.27	0.80	1.6	3.0	
I_{DD} (SRAM5)		SRAM5 supply current in Run/Sleep mode (SRAM5PD = 1 versus SRAM5PD = 0)	Range 4	24	0.02	0.06	0.19	0.40	0.78	0.09	0.20	0.57	1.2	2.4	
			Range 1	160	0.08	0.17	0.46	0.88	1.65	0.29	0.51	1.4	2.7	5.0	
			Range 2	110	0.05	0.12	0.35	0.68	1.30	0.19	0.36	1.1	2.1	3.9	
			Range 3	55	0.04	0.09	0.27	0.54	1.05	0.13	0.27	0.80	1.7	3.2	

1. The typical value is measured at V_{DD} = 1.8 V. The maximum value is for 1.71 ≤ V_{DD} ≤ 3.6V and is at V_{DD} = 1.71 V in Run/Sleep mode on SMPS.

Table 49. Static power consumption of flash memory banks when supplied by LDO or SMPS

Symbol	Parameter	Typ					Max					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Flash_Bank1)}$ (1)	Flash bank 1 static consumption in normal mode (PD1 = 1 versus PD1 = 0)	46	50	60	75	105	63	74	93	114	160	µA
$I_{DD(Flash_Bank2)}$ (1)	Flash bank 2 static consumption in normal mode (PD2 = 1 versus PD2 = 0)	47	51	61	75	105	64	75	94	114	160	
$I_{DD(Flash_Bank_LPM)}$ (2)	One Flash bank additional static consumption in normal mode versus low-power mode (LPM = 0 versus. LPM = 1)	25	25	26	27	30	34	37	41	45	50	

1. When the flash memory is in power down in Sleep mode (SLEEP_PD = 1), Bank 1 and Bank 2 are in power down.
2. If no bank is in power down, the additional static consumption of the flash memory in normal mode versus low-power mode is 2 × $I_{DD(Flash_Bank_LPM)}$.

Table 50. Current consumption in Stop 0 mode on LDO

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 0)}$	Supply current in Stop 0 mode, regulator in range 4, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	150	390	1100	2150	4000	550	1200	3300	6500	12000	µA
		2.4	150	390	1100	2150	4000	550	1200	3300	6500	12000	
		3	150	390	1100	2150	4050	550	1200	3300	6500	13000	
		3.3	150	390	1100	2150	4050	550	1200	3300	6500	13000	
		3.6	155	390	1100	2150	4050	560	1200	3300	6500	13000	
	Supply current in Stop 0 mode, regulator in range 4, RTC disabled, all SRAMs retained	1.8	190	465	1300	2600	4950	690	1400	3900	7800	15000	
		2.4	190	465	1300	2600	5000	690	1400	3900	7800	15000	
		3	190	465	1300	2600	5000	690	1400	3900	7800	15000	
		3.3	190	465	1300	2600	5000	690	1400	3900	7800	15000	
		3.6	190	470	1300	2600	5000	690	1500	3900	7800	15000	

1. Evaluated by characterization. Not tested in production.

Table 51. Current consumption in Stop 0 mode on SMPS

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	25°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 0)}$	Supply current in Stop 0 mode, regulator in range 4, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	71	195	580	1250	2400	260	590	1800	3800	7200	µA
		2.4	57	155	465	965	1850	210	470	1400	2900	5600	
		3	50	135	400	790	1500	190	410	1200	2400	4500	
		3.3	47	125	370	730	1400	170	380	1200	2200	4200	
		3.6	45	120	345	680	1300	170	360	1100	2100	3900	
	Supply current in Stop 0 mode, regulator in range 4, RTC disabled, all SRAMs retained	1.8	92	230	815	1550	2950	330	690	2500	4700	8900	
		2.4	74	185	575	1150	2250	270	560	1800	3500	6800	
		3	64	165	480	965	1850	240	500	1500	2900	5600	
		3.3	60	150	445	880	1700	220	450	1400	2700	5100	
		3.6	57	145	415	825	1600	210	440	1300	2500	4800	

1. Evaluated by characterization. Not tested in production.

Table 52. Current consumption in Stop 1 mode on LDO

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 1)}$	Supply current in Stop 1 mode, regulator in range 4, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	115	340	1000	2000	3800	420	1100	3000	6000	12000	µA
		2.4	125	345	1000	2000	3800	460	1100	3000	6000	12000	
		3	125	345	1050	2000	3850	460	1100	3200	6000	12000	
		3.3	130	345	1050	2000	3850	470	1100	3200	6000	12000	
		3.6	120	345	1050	2050	3850	440	1100	3200	6200	12000	
	Supply current in Stop 1 mode, RTC disabled, all SRAMs retained	1.8	145	415	1250	2450	4750	530	1300	3800	7400	15000	
		2.4	155	410	1250	2450	4750	560	1300	3800	7400	15000	
		3	160	415	1250	2450	4800	580	1300	3800	7400	15000	
		3.3	160	415	1250	2450	4750	580	1300	3800	7400	15000	
		3.6	150	405	1250	2450	4800	550	1300	3800	7400	15000	
$I_{DD(Stop\ 1\ with\ RTC)}$	Supply current in Stop 1 mode, RTC(2) clocked by LSI 32 kHz, 8-Kbyte SRAM2 + ICACHE retained	1.8	115	345	1000	2000	3800	420	1100	3000	6000	12000	
		2.4	125	345	1000	2000	3800	460	1100	3000	6000	12000	
		3	125	345	1050	2000	3850	460	1100	3200	6000	12000	
		3.3	130	350	1050	2000	3850	470	1100	3200	6000	12000	
		3.6	120	345	1050	2050	3850	440	1100	3200	6200	12000	
	Supply current in Stop 1 mode, RTC(2) clocked by LSE bypassed at 32768 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	115	350	1000	2000	3750	420	1100	3000	6000	12000	
		2.4	125	350	1000	2000	3750	460	1100	3000	6000	12000	
		3	120	340	1000	2000	3750	460	1100	3200	6000	12000	
		3.3	130	345	1000	2000	3800	470	1100	3200	6000	12000	
		3.6	120	350	1050	2000	3800	440	1100	3200	6200	12000	

Table 52. Current consumption in Stop 1 mode on LDO (continued)

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 1\ with\ RTC)}$	Supply current in Stop 1 mode, RTC(2) clocked by LSE quartz in low-drive mode, RCC_BDCR.LSESYSEN = 0, 8-Kbyte SRAM2 + ICACHE retained	1.8	135	340	1000	2000	3700	-	-	-	-	-	µA
		2.4	140	340	1000	2000	3750	-	-	-	-	-	
		3	135	340	1000	2000	3750	-	-	-	-	-	
		3.3	135	345	1000	2000	3750	-	-	-	-	-	
		3.6	135	340	1050	2000	3800	-	-	-	-	-	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.

Table 53. Current consumption in Stop 1 mode on SMPS

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 1)}$	Supply current in Stop 1 mode, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	71	195	580	1250	2400	260	590	1800	3800	7200	µA
		2.4	57	155	465	965	1800	210	470	1400	2900	5400	
		3	50	135	400	790	1500	180	410	1200	2400	4500	
		3.3	46	125	370	725	1400	170	380	1200	2200	4200	
		3.6	44	120	345	680	1300	160	360	1100	2100	3900	
	Supply current in Stop 1 mode, RTC disabled, all SRAMs retained	1.8	91	230	815	1550	2950	330	690	2500	4700	8900	
		2.4	74	185	575	1150	2250	270	560	1800	3500	6800	
		3	64	165	480	965	1850	240	500	1500	2900	5600	
		3.3	60	150	445	880	1700	220	450	1400	2700	5100	
		3.6	57	145	415	820	1600	210	440	1300	2500	4800	
$I_{DD(Stop\ 1\ with\ RTC)}$	Supply current in Stop 1 mode, RTC(2) clocked by LSI 32 kHz, 8-Kbyte SRAM2 + ICACHE retained	1.8	71	195	580	1250	2400	260	590	1800	3800	7200	
		2.4	57	155	465	965	1800	210	470	1400	2900	5400	
		3	50	135	400	790	1500	190	410	1200	2400	4500	
		3.3	47	125	370	725	1400	170	380	1200	2200	4200	
		3.6	45	120	350	680	1300	170	360	1100	2100	3900	
	Supply current in Stop 1 mode, RTC(2) clocked by LSE bypassed at 32768 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	71	195	585	1250	2400	260	590	1800	3800	7200	
		2.4	57	160	470	970	1800	210	480	1500	3000	5400	
		3	50	135	400	785	1500	190	410	1200	2400	4500	
		3.3	47	125	370	725	1400	170	380	1200	2200	4200	
		3.6	45	120	345	680	1300	170	360	1100	2100	3900	

Table 53. Current consumption in Stop 1 mode on SMPS (continued)

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 1\ with\ RTC)}$	Supply current in Stop 1 mode, RTC(2) clocked by LSE quartz in low-drive mode, RCC_BDCR.LSESYSEN = 0, 8-Kbyte SRAM2 + ICACHE retained	1.8	79	190	575	1250	2350	-	-	-	-	-	µA
		2.4	62	155	450	975	1800	-	-	-	-	-	
		3	56	135	400	780	1450	-	-	-	-	-	
		3.3	52	125	370	720	1350	-	-	-	-	-	
		3.6	50	120	345	675	1250	-	-	-	-	-	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.

Table 54. Current consumption in Stop 2 mode on LDO

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 2)}$	Supply current in Stop 2 mode, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	12.5	30	85.5	175	355	46	90	260	530	1100	µA
		2.4	12.5	26.5	85.5	175	355	46	80	260	530	1100	
		3	11.5	29	87	180	360	42	87	270	540	1100	
		3.3	13	28.5	88.5	180	365	47	86	270	540	1100	
		3.6	12	32	91.5	185	375	44	96	280	560	1200	
	Supply current in Stop 2 mode, RTC disabled, all SRAMs retained	1.8	48	110	310	650	1350	180	330	930	2000	4100	
		2.4	47	105	310	650	1350	170	320	930	2000	4100	
		3	50	105	310	655	1350	190	320	930	2000	4100	
		3.3	49.5	110	310	660	1350	180	330	930	2000	4100	
		3.6	55	110	315	665	1350	200	330	950	2000	4100	
$I_{DD(Stop\ 2\ with\ RTC)}$	Supply current in Stop 2 mode, RTC(2) clocked by LSI 32 kHz, 8-Kbyte SRAM2 + ICACHE retained	1.8	12.5	30.5	86	175	355	46	92	260	530	1100	
		2.4	13	27	86	175	355	47	81	260	530	1100	
		3	12	29.5	87.5	180	360	44	89	270	540	1100	
		3.3	13.5	29	89.5	180	365	49	87	270	540	1100	
		3.6	12.5	32.5	92	185	375	46	98	280	560	1200	
	Supply current in Stop 2 mode, RTC(2) clocked by LSI 250 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	12.5	30	85.5	175	355	46	90	260	530	1100	
		2.4	12.5	27	86	175	355	46	81	260	530	1100	
		3	11	29	87	180	360	40	87	270	540	1100	
		3.3	13	29	89	180	365	47	87	270	540	1100	
		3.6	12.5	32	91.5	185	375	46	96	280	560	1200	

Table 54. Current consumption in Stop 2 mode on LDO (continued)

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 2\ with\ RTC)}$	Supply current in Stop 2 mode, RTC(2) clocked by LSE bypassed at 32768 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	12.5	28.5	85	175	345	46	86	260	530	1100	µA
		2.4	12.5	29.5	85.5	175	350	46	89	260	530	1100	
		3	12	29.5	87	175	355	44	89	270	530	1100	
		3.3	13.5	29	88	180	360	49	87	270	540	1100	
		3.6	12	32	91	185	365	44	96	280	560	1100	
	Supply current in Stop 2 mode, RTC(2) clocked by LSE quartz in low-drive mode, 8-Kbyte SRAM2 + ICACHE retained	1.8	14.5	29.5	85.5	175	345	-	-	-	-	-	
		2.4	14.5	27.5	86	175	345	-	-	-	-	-	
		3	12.5	28.5	87	175	350	-	-	-	-	-	
		3.3	14.5	29	88.5	180	355	-	-	-	-	-	
		3.6	13.5	32	91.5	185	365	-	-	-	-	-	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.

Table 55. SRAM static power consumption in Stop 2 when supplied by LDO

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM1_64kB)}$(2)	SRAM1 64 KB page x static consumption (SRAM1PDSx = 1 versus SRAM1PDSx = 0)	0.7	1.7	5.7	11.5	25.0	2.70	5.10	17.0	35.0	75.0	µA
$I_{DD(SRAM2_8kB)}$(3)	SRAM2 8KB page 1 static consumption (SRAM2PDS1 = 1 versus SRAM2PDS1 = 0)	0.1	0.3	1.5	2.7	6.1	0.46	0.81	4.4	8.0	19.0	
$I_{DD(SRAM2_56kB)}$(3)	SRAM2 56 KB page 2 static consumption (SRAM2PDS2 = 1 versus SRAM2PDS2 = 0)	1.0	2.4	7.8	16.5	32.5	3.40	7.10	24.0	50.0	98.0	

Table 55. SRAM static power consumption in Stop 2 when supplied by LDO (continued)

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM3_64kB)}$(4)	SRAM3 64 KB page x static consumption (SRAM3PDSx = 1 versus SRAM3PDSx = 0)	0.8	1.8	5.8	12.0	25.0	2.80	5.30	18.0	36.0	75.0	µA
$I_{DD(SRAM4)}$	SRAM4 static consumption (SRAM4PDS = 1 versus SRAM4PDS = 0)	0.1	0.4	1.8	3.5	7.5	0.37	1.20	5.3	11.0	23.0	
$I_{DD(SRAM5_64kB)}$(5)	SRAM5 64 KB page x static consumption (SRAM5PDSx = 1 versus SRAM5PDSx = 0)	0.8	1.7	5.6	11.5	25.0	2.80	5.10	17.0	35.0	75.0	
$I_{DD(ICRAM)}$	ICACHE SRAM static consumption (ICRAMPDS = 1 versus ICRAMPDS = 0)	0.5	1.4	5.2	10.5	22.5	1.90	4.20	16.0	32.0	68.0	
$I_{DD(DC1RAM)}$	DCACHE1 SRAM static consumption (DC1RAMPDS = 1 versus DC1RAMPDS = 0)	0.3	0.5	2.7	5.3	11.0	1.10	1.60	8.0	16.0	33.0	
$I_{DD(DC2RAM)}$	DCACHE2 SRAM static consumption (DC2RAMPDS = 1 versus DC2RAMPDS = 0)	0.3	0.5	2.7	5.3	11.0	1.10	1.60	8.0	16.0	33.0	
$I_{DD(DMA2DRAM)}$	DMA2D SRAM static consumption (DMA2DRAMPDS = 1 versus DMA2DRAMPDS = 0)	0.0	0.1	0.4	0.4	1.3	0.07	0.36	1.1	1.2	3.8	
$I_{DD(PRAM)}$	FMAC, FDCAN and USB peripherals SRAM static consumption (PRAMPDS = 1 versus PRAMPDS = 0)	0.1	0.2	0.8	1.3	3.0	0.37	0.69	2.4	3.8	9.0	
$I_{DD(GPRAM)}$	Graphic peripherals (LTDC, GFXMMU) SRAM static consumption (GPRAMPDS = 1 versus GPRAMPDS = 0)	0.0	0.2	0.7	1.3	2.0	0.00	0.59	2.2	3.8	5.9	
$I_{DD(PKARAM)}$	PKA SRAM static consumption (PKARAMPDS = 1 versus PKARAMPDS = 0)	0.1	0.2	0.7	1.3	2.7	0.37	0.48	2.1	3.9	8.0	

1. Evaluated by characterization. Not tested in production.
2. SRAM1 total consumption is 12 x $I_{DD(SRAM1_64KB)}$.
3. SRAM2 total consumption is $I_{DD(SRAM2_8KB)}$ + $I_{DD(SRAM2_56KB)}$.
4. SRAM3 total consumption is 13 x $I_{DD(SRAM3_64KB)}$.
5. SRAM5 total consumption is 13 x $I_{DD(SRAM5_64KB)}$.

Table 56. Current consumption in Stop 2 mode on SMPS

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 2)}$	Supply current in Stop 2 mode, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	6.35	15.5	47	97.5	200	23	47	140	290	590	µA
		2.4	5.1	12.5	39	82	170	19	38	120	250	500	
		3	4.65	11.5	35.5	75	155	17	34	110	220	460	
		3.3	4.65	11.5	34.5	72	150	17	34	110	210	440	
		3.6	5.25	12	35	72	150	18	35	110	210	440	
	Supply current in Stop 2 mode, RTC disabled, all SRAMs retained	1.8	27.5	57.5	165	400	885	99	180	500	1200	2700	
		2.4	22	46.5	140	285	690	80	140	420	860	2100	
		3	19	41	120	255	535	69	130	360	760	1600	
		3.3	18	38.5	115	235	495	65	120	350	700	1500	
		3.6	17.5	37.5	105	225	470	62	120	320	670	1400	
$I_{DD(Stop\ 2\ with\ RTC)}$	Supply current in Stop 2 mode, RTC(2) clocked by LSI 32 kHz, 8-Kbyte SRAM2 + ICACHE retained	1.8	6.65	15.5	47	97.5	200	24	47	140	290	590	
		2.4	5.45	13	39.5	82.5	170	20	39	120	250	500	
		3	5.10	12	36	75.5	155	19	36	110	230	460	
		3.3	5.15	12	35	72.5	150	19	36	110	220	440	
		3.6	5.85	12.5	35.5	72.5	150	21	36	110	210	440	
	Supply current in Stop 2 mode, RTC(2) clocked by LSI 250 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	6.5	15.5	47	97.5	200	24	47	140	290	590	
		2.4	5.2	12.5	39.5	82	170	19	38	120	250	500	
		3	4.75	11.5	36	75	155	17	34	110	220	460	
		3.3	4.8	11.5	34.5	72.5	150	17	34	110	220	440	
		3.6	5.4	12.5	35	72	150	19	36	110	210	440	

Table 56. Current consumption in Stop 2 mode on SMPS (continued)

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 2\ with\ RTC)}$	Supply current in Stop 2 mode, RTC(2) clocked by LSE bypassed at 32768 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	6.6	15.5	47	97	195	24	47	140	290	580	µA
		2.4	5.35	13	40	83	170	20	39	120	250	500	
		3	5	12	36	75	155	18	36	110	220	460	
		3.3	5.1	11.5	35	72.5	150	18	34	110	220	440	
		3.6	5.75	12.5	35.5	72	145	20	36	110	210	420	
	Supply current in Stop 2 mode, RTC(2) clocked by LSE quartz in low-drive mode, 8-Kbyte SRAM2 + ICACHE retained	1.8	7.3	15.5	47	97	195	-	-	-	-	-	
		2.4	5.7	13	39	81.5	165	-	-	-	-	-	
		3	5.4	12	36	74.5	150	-	-	-	-	-	
		3.3	5.4	11.5	35	72	145	-	-	-	-	-	
		3.6	6.1	12.5	35.5	71.5	145	-	-	-	-	-	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.

Table 57. SRAM static power consumption in Stop 2 when supplied by SMPS

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM1_64kB)}$(2)	SRAM1 64 KB page x static consumption (SRAM1PDSx = 1 versus SRAM1PDSx = 0)	0.4	0.7	2.1	4.5	9.4	1.30	2.10	6.30	14.0	29.0	µA
$I_{DD(SRAM2_8kB)}$(3)	SRAM2 8KB page 1 static consumption (SRAM2PDS1 = 1 versus SRAM2PDS1 = 0)	0.1	0.2	0.5	1.3	2.4	0.28	0.51	1.60	3.80	7.2	
$I_{DD(SRAM2_56kB)}$(3)	SRAM2 56 KB page 2 static consumption (SRAM2PDS2 = 1 versus SRAM2PDS2 = 0)	0.4	0.9	2.9	6.2	13.0	1.50	2.90	8.60	19.0	39.0	
$I_{DD(SRAM3_64kB)}$(4)	SRAM3 64 KB page x static consumption (SRAM3PDSx = 1 versus SRAM3PDSx = 0)	0.4	0.7	2.2	4.7	9.7	1.30	2.20	6.50	14.0	30.0	

Table 57. SRAM static power consumption in Stop 2 when supplied by SMPS (continued)

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM4)}$	SRAM4 static consumption (SRAM4PDS = 1 versus SRAM4PDS = 0)	0.1	0.2	0.6	1.5	2.8	0.38	0.62	1.90	4.40	8.4	µA
$I_{DD(SRAM5_64kB)}$(5)	SRAM5 64 KB page x static consumption (SRAM5PDSx = 1 versus SRAM5PDSx = 0)	0.4	0.7	2.1	4.4	9.4	1.30	2.20	6.30	14.0	29.0	
$I_{DD(ICRAM)}$	ICACHE SRAM static consumption (ICRAMPDS = 1 versus ICRAMPDS = 0)	0.3	0.6	1.9	4.1	8.4	1.10	1.90	5.60	13.0	26.0	
$I_{DD(DC1RAM)}$	DCACHE1 SRAM static consumption (DC1RAMPDS = 1 versus DC1RAMPDS = 0)	0.1	0.3	0.9	2.1	4.3	0.47	0.86	2.80	6.30	13.0	
$I_{DD(DC2RAM)}$	DCACHE2 SRAM static consumption (DC2RAMPDS = 1 versus DC2RAMPDS = 0)	0.1	0.3	0.9	2.1	4.2	0.47	0.86	2.80	6.30	13.0	
$I_{DD(DMA2DRAM)}$	DMA2D SRAM static consumption (DMA2DRAMPDS = 1 versus DMA2DRAMPDS = 0)	0.01	0.02	0.09	0.31	0.41	0.04	0.07	0.27	0.93	1.3	
$I_{DD(PRAM)}$	FMAC, FDCAN and USB peripherals SRAM static consumption (PRAMPDS = 1 versus PRAMPDS = 0)	0.05	0.09	0.26	0.67	1.15	0.18	0.27	0.78	2.00	3.5	
$I_{DD(GPRAM)}$	Graphic peripherals (LTDC, GFXMMU) SRAM static consumption (GPRAMPDS = 1 versus GPRAMPDS = 0)	0.04	0.08	0.28	0.61	1.15	0.14	0.25	0.83	1.90	3.5	
$I_{DD(PKARAM)}$	PKA SRAM static consumption (PKARAMPDS = 1 versus PKARAMPDS = 0)	0.03	0.07	0.24	0.60	1.05	0.11	0.23	0.72	1.80	3.2	

1. Evaluated by characterization. Not tested in production.
2. SRAM1 total consumption is 12 x $I_{DD(SRAM1_64KB)}$.
3. SRAM2 total consumption is $I_{DD(SRAM2_8KB)}$ + $I_{DD(SRAM2_56KB)}$.
4. SRAM3 total consumption is 13 x $I_{DD(SRAM3_64KB)}$.
5. SRAM5 total consumption is 13 x $I_{DD(SRAM5_64KB)}$.

Table 58. Current consumption in Stop 3 mode on LDO

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 3)}$	Supply current in Stop 3 mode, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	5.55	18.5	60.5	130	270	20	56	190	390	800	µA
		2.4	6.1	16.5	60.5	130	270	22	50	180	390	800	
		3	5.7	17	62	135	280	21	51	190	400	830	
		3.3	7.15	19	63.5	135	285	26	57	190	400	840	
		3.6	7.55	19.5	66	140	290	27	57	200	420	860	
	Supply current in Stop 3 mode, RTC disabled, all SRAMs retained	1.8	27.5	82	300	680	1500	99	250	900	2100	4500	
		2.4	29	79.5	300	685	1500	110	240	900	2100	4500	
		3	28.5	81	300	685	1500	110	250	900	2100	4500	
		3.3	28.5	83	300	690	1500	110	250	900	2100	4500	
		3.6	27	84.5	305	695	1550	96	260	920	2100	4700	
$I_{DD(Stop\ 3\ with\ RTC)}$	Supply current in Stop 3 mode, RTC(2) clocked by LSI 32 kHz, 8-Kbyte SRAM2 + ICACHE retained	1.8	5.75	18.5	61	130	270	21	56	190	390	800	
		2.4	6.45	17	61	130	275	24	51	190	390	820	
		3	6.25	17.5	62.5	135	280	23	52	210	400	830	
		3.3	7.7	19.5	64	135	285	28	58	190	400	840	
		3.6	8.15	20.5	66.5	140	290	29	60	200	420	860	
	Supply current in Stop 3 mode, RTC(2) clocked by LSI 250 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	5.55	18.5	60.5	130	270	20	56	180	390	800	
		2.4	6.2	17	61	130	275	23	51	190	390	820	
		3	5.95	17	62	135	280	22	51	210	400	830	
		3.3	7.35	19	63.5	135	285	26	57	190	400	840	
		3.6	7.3	20	66	140	290	26	59	200	420	860	

Table 58. Current consumption in Stop 3 mode on LDO (continued)

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 3\ with\ RTC)}$	Supply current in Stop 3 mode, RTC(2) clocked by LSE bypassed at 32768 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	5.7	18	60	130	265	21	54	180	390	790	µA
		2.4	6.4	17.5	60.5	130	270	23	53	190	390	800	
		3	6.05	17.5	61.5	130	275	22	52	200	390	820	
		3.3	7.45	19	63	135	280	27	57	190	400	830	
		3.6	8.1	20	66	140	285	29	59	200	420	840	
	Supply current in Stop 3 mode, RTC(2) clocked by LSE quartz in low-drive mode, 8-Kbyte SRAM2 + ICACHE retained	1.8	7.15	18.5	60.5	130	265	-	-	-	-	-	
		2.4	6.95	17	60.5	130	265	-	-	-	-	-	
		3	7.1	17	62	130	270	-	-	-	-	-	
		3.3	8.35	19	63.5	135	275	-	-	-	-	-	
		3.6	9.05	20	66	140	285	-	-	-	-	-	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.

Table 59. SRAM static power consumption in Stop 3 when supplied by LDO

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM1_64kB)}$(2)	SRAM1 64 KB page x static consumption (SRAM1PDSx = 1 versus SRAM1PDSx = 0)	0.9	1.4	6.0	14.0	30.5	3.40	4.20	18.0	42.0	92.0	µA
$I_{DD(SRAM2_8kB)}$(3)	SRAM2 8KB page 1 static consumption (SRAM2PDS1 = 1 versus SRAM2PDS1 = 0)	0.1	0.3	1.1	3.1	5.3	0.47	0.86	3.30	9.2	16.0	
$I_{DD(SRAM2_56kB)}$(3)	SRAM2 56 KB page 2 static consumption (SRAM2PDS2 = 1 versus SRAM2PDS2 = 0)	1.1	1.8	7.5	17.0	36.5	4.00	5.40	23.0	51.0	110	
$I_{DD(SRAM3_64kB)}$(4)	SRAM3 64 KB page x static consumption (SRAM3PDSx = 1 versus SRAM3PDSx = 0)	1.0	1.5	6.3	14.5	31.0	3.50	4.40	19.0	44.0	93.0	
$I_{DD(SRAM4)}$	SRAM4 static consumption (SRAM4PDS = 1 versus SRAM4PDS = 0)	0.2	0.4	1.7	3.6	7.1	0.55	1.20	5.00	11.0	22.0	
$I_{DD(SRAM5_64kB)}$(5)	SRAM5 64 KB page x static consumption (SRAM5PDSx = 1 versus SRAM5PDSx = 0)	1.0	1.4	6.1	14.0	30.0	3.50	4.20	19.0	42.0	90.0	
$I_{DD(ICRAM)}$	ICACHE SRAM static consumption (ICRAMPDS = 1 versus ICRAMPDS = 0)	0.7	1.1	4.4	9.9	20.5	2.60	3.20	14.0	30.0	62.0	
$I_{DD(DC1RAM)}$	DCACHE1 SRAM static consumption (DC1RAMPDS = 1 versus DC1RAMPDS = 0)	0.3	0.5	2.2	5.0	10.0	0.94	1.60	6.60	15.0	30.0	
$I_{DD(DC2RAM)}$	DCACHE2 SRAM static consumption (DC2RAMPDS = 1 versus DC2RAMPDS = 0)	0.3	0.5	2.2	4.9	10.0	0.94	1.50	6.60	15.0	30.0	
$I_{DD(DMA2DRAM)}$	DMA2D SRAM static consumption (DMA2DRAMPDS = 1 versus DMA2DRAMPDS = 0)	0.02	0.06	0.25	0.50	1.10	0.08	0.19	0.75	1.5	3.3	

Table 59. SRAM static power consumption in Stop 3 when supplied by LDO (continued)

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(PRAM)}$	FMAC, FDCAN and USB peripherals SRAM static consumption (PRAMPDS = 1 versus PRAMPDS = 0)	0.09	0.13	0.59	1.35	2.70	0.33	0.39	1.80	4.1	8.1	µA
$I_{DD(GPRAM)}$	Graphic peripherals (LTDC, GFXMMU) SRAM static consumption (GPRAMPDS = 1 versus GPRAMPDS = 0)	0.09	0.14	0.72	1.65	3.20	0.33	0.41	2.20	5.0	9.6	
$I_{DD(PKARAM)}$	PKA SRAM static consumption (PKARAMPDS = 1 versus PKARAMPDS = 0)	0.07	0.14	0.62	1.55	2.75	0.26	0.41	1.90	4.7	8.3	

1. Evaluated by characterization. Not tested in production.
2. SRAM1 total consumption is 12 x $I_{DD(SRAM1_64KB)}$.
3. SRAM2 total consumption is $I_{DD(SRAM2_8KB)}$ + $I_{DD(SRAM2_56KB)}$.
4. SRAM3 total consumption is 13 x $I_{DD(SRAM3_64KB)}$.
5. SRAM5 total consumption is 13 x $I_{DD(SRAM5_64KB)}$.

Table 60. Current consumption in Stop 3 mode on SMPS

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 3)}$	Supply current in Stop 3 mode, RTC disabled, 8-Kbyte SRAM2 + ICACHE retained	1.8	2.75	8.5	29.5	65	140	9.8	26	87	200	410	µA
		2.4	2.15	6.7	23.5	52	110	7.6	20	69	160	320	
		3	2	6.05	21	47	100	7	18	61	140	290	
		3.3	2.2	6.25	21	46	100	7.5	18	60	140	290	
		3.6	2.95	7.35	22.5	47.5	100	9.7	21	64	140	290	
	Supply current in Stop 3 mode, RTC disabled, all SRAMs retained	1.8	13	38.5	140	305	730	47	120	420	920	2200	
		2.4	10	29.5	110	250	550	36	89	330	750	1700	
		3	8.45	24.5	91	210	465	30	73	280	630	1400	
		3.3	8.2	23.5	85.5	195	435	29	70	260	580	1300	
		3.6	8.55	23.5	82	185	410	30	69	250	550	1300	
$I_{DD(Stop\ 3\ with\ RTC)}$	Supply current in Stop 3 mode, RTC(2) clocked by LSI 32 kHz, 8-Kbyte SRAM2 + ICACHE retained	1.8	3	8.8	30	65.5	140	11	26	89	200	410	
		2.4	2.55	7.05	24	52.5	110	9.1	21	71	160	320	
		3	2.45	6.5	21.5	47.5	100	8.6	19	63	140	290	
		3.3	2.7	6.75	21.5	46.5	100	9.3	20	62	140	290	
		3.6	3.5	7.9	23	48	100	12	22	65	140	290	
	Supply current in Stop 3 mode, RTC(2) clocked by LSI 250 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	2.85	8.6	29.5	65	140	11	26	87	200	410	
		2.4	2.3	6.8	23.5	52	110	8.2	20	69	160	320	
		3	2.1	6.15	21.5	47	100	7.3	18	63	140	290	
		3.3	2.35	6.4	21.5	46.5	100	8	19	62	140	290	
		3.6	3.1	7.5	22.5	47.5	100	11	21	64	140	290	

Table 60. Current consumption in Stop 3 mode on SMPS (continued)

Symbol	Parameter	Conditions	Typ					Max(1)					Unit
		V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Stop\ 3\ with\ RTC)}$	Supply current in Stop 3 mode, RTC(2) clocked by LSE bypassed at 32768 Hz, 8-Kbyte SRAM2 + ICACHE retained	1.8	2.95	8.75	29.5	65	140	11	26	87	200	410	µA
		2.4	2.45	7	23.5	52	110	8.7	21	69	160	320	
		3	2.35	6.4	21.5	47	100	8.2	19	63	140	290	
		3.3	2.6	6.6	21.5	46.5	99	8.9	19	62	140	290	
		3.6	3.45	7.75	22.5	48	100	12	22	64	140	290	
	Supply current in Stop 3 mode, RTC(2) clocked by LSE quartz in low-drive mode, 8-Kbyte SRAM2 + ICACHE retained	1.8	3.4	8.8	30	65	135	-	-	-	-	-	
		2.4	2.8	7	24	52	110	-	-	-	-	-	
		3	2.6	6.4	21.5	46.5	99.5	-	-	-	-	-	
		3.3	2.85	6.65	21.5	46	97.5	-	-	-	-	-	
		3.6	3.65	7.75	23	47.5	98.5	-	-	-	-	-	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.

Table 61. SRAM static power consumption in Stop 3 when supplied by SMPS

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM1_64kB)}$(2)	SRAM1 64 KB page x static consumption (SRAM1PDSx = 1 versus SRAM1PDSx = 0)	0.2	0.5	1.7	4.0	9.1	0.56	1.40	5.10	12.0	28.0	µA
$I_{DD(SRAM2_8kB)}$(3)	SRAM2 8KB page 1 static consumption (SRAM2PDS1 = 1 versus SRAM2PDS1 = 0)	0.0	0.1	0.4	0.7	1.8	0.12	0.30	1.20	2.30	5.4	
$I_{DD(SRAM2_56kB)}$(2)	SRAM2 56 KB page 2 static consumption (SRAM2PDS2 = 1 versus SRAM2PDS2 = 0)	0.2	0.6	2.2	4.9	11.0	0.69	1.80	6.60	15.0	33.0	
$I_{DD(SRAM3_64kB)}$(4)	SRAM3 64 KB page x static consumption (SRAM3PDSx = 1 versus SRAM3PDSx = 0)	0.2	0.5	1.8	4.1	9.4	0.60	1.50	5.40	13.0	29.0	

Table 61. SRAM static power consumption in Stop 3 when supplied by SMPS (continued)

Symbol	Parameter	Typ					Max(1)					Unit
		25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM4)}$	SRAM4 static consumption (SRAM4PDS = 1 versus SRAM4PDS = 0)	0.0	0.1	0.5	1.0	2.5	0.15	0.38	1.50	3.00	7.4	µA
$I_{DD(SRAM5_64kB)}$(5)	SRAM5 64 KB page x static consumption (SRAM5PDSx = 1 versus SRAM5PDSx = 0)	0.2	0.5	1.8	3.9	9.2	0.58	1.40	5.30	12.0	28.0	
$I_{DD(ICRAM)}$	ICACHE SRAM static consumption (ICRAMPDS = 1 versus ICRAMPDS = 0)	0.1	0.3	1.3	2.8	6.5	0.42	1.10	3.80	8.40	20.0	
$I_{DD(DC1RAM)}$	DCACHE1 SRAM static consumption (DC1RAMPDS = 1 versus DC1RAMPDS = 0)	0.1	0.2	0.6	1.4	3.4	0.21	0.51	2.00	4.20	11.0	
$I_{DD(DC2RAM)}$	DCACHE2 SRAM static consumption (DC2RAMPDS = 1 versus DC2RAMPDS = 0)	0.1	0.2	0.6	1.4	3.5	0.22	0.51	2.00	4.10	11.0	
$I_{DD(DMA2DRAM)}$	DMA2D SRAM static consumption (DMA2DRAMPDS = 1 versus DMA2DRAMPDS = 0)	0.01	0.02	0.08	0.13	0.70	0.03	0.06	0.25	0.39	2.1	
$I_{DD(PRAM)}$	FMAC, FDCAN and USB peripherals SRAM static consumption (PRAMPDS = 1 versus PRAMPDS = 0)	0.02	0.05	0.20	0.40	1.30	0.07	0.14	0.59	1.20	3.9	
$I_{DD(GPRAM)}$	Graphic peripherals (LTDC, GFXMMU) SRAM static consumption (GPRAMPDS = 1 versus GPRAMPDS = 0)	0.02	0.05	0.22	0.38	1.35	0.06	0.17	0.65	1.20	4.1	
$I_{DD(PKARAM)}$	PKA SRAM static consumption (PKARAMPDS = 1 versus PKARAMPDS = 0)	0.02	0.05	0.21	0.39	1.25	0.06	0.15	0.63	1.20	3.8	

1. Evaluated by characterization. Not tested in production.
2. SRAM1 total consumption is 12 x $I_{DD(SRAM1_64KB)}$.
3. SRAM2 total consumption is $I_{DD(SRAM2_8KB)}$ + $I_{DD(SRAM2_56KB)}$.
4. SRAM3 total consumption is 13 x $I_{DD(SRAM3_64KB)}$.
5. SRAM5 total consumption is 13 x $I_{DD(SRAM5_64KB)}$.

Table 62. Current consumption in Standby mode

Symbol	Parameter	Conditions		Typ					Max(1)					Unit
		-	V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Standby)}$	Supply current in Standby mode (backup registers retained), RTC disabled	No independent watchdog ULPMEN = 1	1.8	0.195	0.765	3.45	8.9	23	0.52	1.9	8.3	22	54	µA
			2.4	0.22	0.815	3.65	9.4	24	0.61	2.0	8.8	23	56	
			3	0.38	1.2	4.85	12	29.5	1.10	3.0	12	29	69	
			3.3	0.735	1.85	6.2	14	33.5	2.20	4.6	16	34	80	
			3.6	1.65	3.4	8.85	18	40	5.10	8.5	22	44	96	
		No independent watchdog	1.8	0.255	0.84	3.5	8.9	22.5	0.59	2.0	8.4	22	53	
			2.4	0.285	0.89	3.7	9.35	23.5	0.68	2.1	8.9	23	56	
			3	0.445	1.3	4.85	12	29	1.20	3.2	12	29	70	
			3.3	0.795	1.95	6.2	14	33	2.30	4.7	16	34	79	
			3.6	1.7	3.5	8.85	18	39	5.10	8.6	22	44	94	
		With independent watchdog clocked by LSI 32 kHz	1.8	0.54	1.1	3.8	9.25	23	0.76	2.2	8.7	22	53	
			2.4	0.69	1.25	4.1	9.8	24	0.95	2.4	9.3	23	56	
			3	0.955	1.75	5.35	12.5	29	1.60	3.5	13	29	69	
			3.3	1.4	2.45	6.75	14.5	33.5	2.70	5.2	16	35	80	
			3.6	2.4	4.05	9.45	18.5	39.5	5.60	9.1	23	45	95	
		With independent watchdog clocked by LSI 250 Hz	1.8	0.355	0.94	3.65	9	23	0.70	2.2	8.5	22	53	
			2.4	0.39	1	3.85	9.45	23.5	0.80	2.3	9.0	23	56	
			3	0.565	1.4	5	12	29	1.30	3.3	12	29	69	
			3.3	0.92	2.05	6.35	14	33	2.40	4.9	16	34	80	
			3.6	1.85	3.6	9	18	39	5.20	8.8	22	44	95	

Table 62. Current consumption in Standby mode (continued)

Symbol	Parameter	Conditions		Typ					Max[1]					Unit
		-	V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Standby with RTC)}$	Supply current in Standby mode (backup registers retained), RTC enabled	RTC[2] clocked by LSI 32 kHz, no independent watchdog[3]	1.8	0.54	1.1	3.8	9.25	23	0.76	2.2	8.7	22	53	µA
			2.4	0.65	1.25	4.1	9.7	24	0.95	2.4	9.2	23	56	
			3	0.9	1.75	5.3	12	29	1.60	3.5	12	29	69	
			3.3	1.3	2.45	6.75	14.5	33.5	2.70	5.2	16	35	80	
			3.6	2.3	4.05	9.45	18.5	39.5	5.60	9.1	23	45	95	
		RTC[2] clocked by LSI 250 Hz, no independent watchdog	1.8	0.355	0.94	3.65	9.05	23	0.70	2.2	8.5	22	53	
			2.4	0.395	1	3.85	9.45	23.5	0.80	2.3	9.0	23	56	
			3	0.565	1.4	5	12	29	1.30	3.3	12	29	69	
			3.3	0.93	2.05	6.35	14	33	2.40	4.9	16	34	80	
			3.6	1.85	3.65	9.05	18	39	5.30	8.8	22	44	95	
		RTC[2] clocked by LSE bypassed at 32768 Hz	1.8	0.48	1.05	3.75	9.1	22.5	0.87	2.3	8.8	22	54	
			2.4	0.555	1.15	4	9.6	23.5	1.10	2.6	9.3	23	56	
			3	0.785	1.6	5.2	12	29	1.70	3.7	12	29	69	
			3.3	1.2	2.3	6.55	14.5	33	2.80	5.3	16	35	80	
			3.6	2.2	3.9	9.25	18.5	39	5.70	9.2	23	45	95	
		RTC[2] clocked by LSE quartz in low-drive mode	1.8	0.65	1.2	3.9	9.25	22.5	-	-	-	-	-	
			2.4	0.69	1.3	4.1	9.7	23.5	-	-	-	-	-	
			3	0.885	1.7	5.3	12	28.5	-	-	-	-	-	
			3.3	1.25	2.35	6.65	14.5	32.5	-	-	-	-	-	
			3.6	2.25	3.9	9.3	18.5	38.5	-	-	-	-	-	

Table 62. Current consumption in Standby mode (continued)

Symbol	Parameter	Conditions		Typ					Max(1)					Unit
		-	V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(BKPSRAM)}$	Supply current to be added in Standby mode when backup SRAM is retained	-	1.8	0.14	0.26	0.5	0.95	2	0.5	0.8	1.5	2.9	6.0	µA
			2.4	0.135	0.26	0.5	0.65	2	0.5	0.8	1.5	2.0	6.0	
			3	0.13	0.25	0.5	0.5	1.5	0.5	0.8	1.5	1.5	4.5	
			3.3	0.135	0.2	0.5	1	2	0.5	0.6	1.5	3.0	6.0	
			3.6	0.15	0.25	0.5	1	2	0.6	0.8	1.5	3.0	6.0	
$I_{DD(SRAM2)}$	Supply current to be added in Standby mode when full SRAM2 is retained	LDO	1.8	1.695	5.36	15.5	32.1	65.5	6.2	17	47	97	200	
			2.4	1.715	5.41	15.3	32.15	65	6.2	17	46	97	200	
			3	1.755	5.45	15.65	32	65.5	6.4	17	47	96	200	
			3.3	1.755	6.25	15.3	32.5	66	6.4	19	46	98	200	
			3.6	1.85	5.95	15.65	32.5	66	6.7	18	47	98	200	
I_{DD} (SRAM2_8K)	Supply current to be added in Standby mode when SRAM2 8KB page 1 is retained		1.8	0.645	2.71	7.5	15.6	31.5	2.4	8.2	23	47	95	
			2.4	0.665	2.66	7.3	15.65	31.5	2.4	8.0	22	47	95	
			3	0.705	2.65	7.65	15.5	31.5	2.6	8.0	23	47	95	
			3.3	0.705	2.3	7.8	15.5	32	2.6	6.9	24	47	96	
			3.6	0.75	3	7.65	15.5	31.5	2.8	9.0	23	47	95	

Table 62. Current consumption in Standby mode (continued)

Symbol	Parameter	Conditions		Typ					Max(1)					Unit
		-	V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(SRAM2)}$	Supply current to be added in Standby mode when full SRAM2 is retained	SMPS	1.8	0.945	2.66	8	16.6	34	3.5	8.0	24	50	110	µA
			2.4	0.715	2.16	6.3	13.65	27.5	2.6	6.5	19	41	83	
			3	0.705	1.85	5.65	11.5	24	2.6	5.6	17	35	72	
			3.3	0.655	1.6	4.8	10.5	22	2.4	4.8	15	32	66	
			3.6	0.55	1.35	4.15	9.5	20	2.0	4.1	13	29	60	
I_{DD} (SRAM2_8K)	Supply current to be added in Standby mode when SRAM2 8KB page 1 is retained		1.8	0.39	1.31	3.8	8.1	16.5	1.5	4.0	12	25	50	
			2.4	0.315	1.06	3.1	6.65	13	1.2	3.2	9.3	20	39	
			3	0.205	0.9	2.65	5	11	0.7	2.7	8.0	15	33	
			3.3	0.255	0.75	2.35	5	10	0.9	2.3	7.1	15	30	
			3.6	0.25	0.55	1.65	4	9	0.9	1.7	5.0	12	27	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.
3. Current consumption with IWDG enabled is similar.

Table 63. Current consumption in Shutdown mode

Symbol	Parameter	Conditions		Typ					Max(1)					Unit
		-	V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(Shutdown)}$	Supply current in Shutdown mode (backup registers retained), RTC disabled	-	1.8	0.15	0.73	3.20	8.10	20.0	0.47	1.9	8.0	21	50	µA
			2.4	0.18	0.78	3.40	8.55	21.0	0.56	2.0	8.5	22	53	
			3	0.34	1.20	4.55	11.00	26.0	1.10	3.0	12.0	28	65	
			3.3	0.68	1.80	5.90	13.00	30.5	2.20	4.5	15.0	33	77	
			3.6	1.60	3.35	8.55	17.00	36.5	5.00	8.4	22.0	43	92	
$I_{DD(Shutdown with RTC)}$	Supply current in Shutdown mode (backup registers retained), RTC enabled	RTC(2) clocked by LSE bypassed at 32768 Hz	1.8	0.37	0.95	3.45	8.30	20.0	0.86	2.1	8.3	21	50	
			2.4	0.45	1.05	3.65	8.80	21.0	1.10	2.3	8.8	22	53	
			3	0.67	1.50	4.85	11.00	26.0	1.60	3.4	12.0	28	65	
			3.3	1.10	2.15	6.20	13.50	30.0	2.70	4.9	16.0	34	76	
			3.6	2.05	3.75	8.90	17.50	36.5	5.00	8.9	22.0	44	92	
		RTC(2) clocked by LSE quartz in low-drive mode	1.8	0.55	1.10	3.60	8.45	20.0	-	-	-	-	-	
			2.4	0.59	1.15	3.80	8.90	21.0	-	-	-	-	-	
			3	0.78	1.60	4.95	11.50	26.0	-	-	-	-	-	
			3.3	1.15	2.20	6.30	13.50	30.0	-	-	-	-	-	
			3.6	2.15	3.80	8.95	17.50	36.0	-	-	-	-	-	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration but RTC_CALR.LPCAL = 1.

Table 64. Current consumption in V_{BAT} mode

Symbol	Parameter	Conditions		Typ					Max(1)					Unit
		-	V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(VBAT)}$	Supply current in V_{BAT} mode (backup registers retained), RTC disabled	-	1.8	0.08	0.23	0.93	2.30	5.65	0.24	0.68	2.6	5.8	15	µA
			2.4	0.08	0.24	0.97	2.35	5.80	0.24	0.70	2.6	5.9	15	
			3	0.12	0.33	1.25	2.90	6.90	0.36	0.83	3.2	7.3	18	
			3.3	0.20	0.51	1.80	4.25	10	0.61	1.30	4.5	11	25	
			3.6	0.40	0.82	2.35	4.95	11	1.30	2.10	5.9	13	28	
$I_{DD(VBAT}$ with RTC)	Supply current in V_{BAT} mode (backup registers retained), RTC enabled	RTC(2) clocked by LSE bypassed at 32768 Hz	1.8	0.39	0.55	1.25	2.65	5.95	0.58	1.10	2.9	6.2	15	
			2.4	0.47	0.63	1.40	2.80	6.20	0.67	1.30	3.1	6.4	15	
			3	0.62	0.82	1.75	3.45	7.40	0.91	1.40	3.7	7.9	18	
			3.3	0.78	1.05	2.35	4.80	10.50	1.30	1.90	5.2	12	26	
			3.6	1.05	1.40	2.95	5.60	11.50	2.00	2.70	6.6	14	29	
		RTC(2) clocked by LSE bypassed at 32768 Hz, RTC_CALR.LPCAL = 1	1.8	0.30	0.46	1.20	2.55	5.85	0.49	1.10	2.8	6.1	15	
			2.4	0.34	0.51	1.25	2.70	6.10	0.53	1.10	3.0	6.3	15	
			3	0.46	0.65	1.60	3.30	7.20	0.74	1.30	3.6	7.7	18	
			3.3	0.60	0.87	2.20	4.65	10.5	1.10	1.70	5.0	12	26	
			3.6	0.87	1.20	2.75	5.40	11.5	1.80	2.50	6.4	13	29	

Table 64. Current consumption in V_{BAT} mode (continued)

Symbol	Parameter	Conditions		Typ					Max(1)					Unit
		-	V_{DD} (V)	25°C	55°C	85°C	105°C	125°C	30°C	55°C	85°C	105°C	125°C	
$I_{DD(VBAT with RTC)}$	Supply current in V_{BAT} mode (backup registers retained), RTC enabled	RTC(2) clocked by LSE quartz in low-drive mode	1.8	0.53	0.69	1.40	2.75	6.00	-	-	-	-	-	µA
			2.4	0.58	0.74	1.50	2.90	6.20	-	-	-	-	-	
			3	0.68	0.89	1.85	3.50	7.35	-	-	-	-	-	
			3.3	0.79	1.10	2.45	4.85	10.5	-	-	-	-	-	
			3.6	1.05	1.45	3.00	5.60	11.5	-	-	-	-	-	
		RTC(2) clocked by LSE quartz in low-drive mode, RTC_CALR.LPCAL =1	1.8	0.44	0.61	1.35	2.70	5.95	-	-	-	-	-	
			2.4	0.46	0.63	1.40	2.80	6.10	-	-	-	-	-	
			3	0.52	0.74	1.65	3.35	7.20	-	-	-	-	-	
			3.3	0.62	0.93	2.25	4.70	10.5	-	-	-	-	-	
			3.6	0.86	1.25	2.80	5.45	11.5	-	-	-	-	-	
I_{DD} (BKPSRAM)	Supply current to add in V_{BAT} mode when the backup SRAM is retained	-	1.8	0.14	0.22	0.48	0.90	1.90	0.29	0.49	1.3	2.6	5.6	
			2.4	0.14	0.22	0.48	0.95	1.90	0.30	0.49	1.3	2.7	5.6	
			3	0.14	0.21	0.45	0.95	1.85	0.31	0.48	1.2	2.7	5.4	
			3.3	0.14	0.21	0.50	0.95	2.00	0.31	0.48	1.4	2.7	5.9	
			3.6	0.15	0.24	0.45	0.95	2.00	0.33	0.56	1.2	2.7	5.9	

1. Evaluated by characterization. Not tested in production.
2. RTC with default configuration except otherwise specified.

I/O system current consumption

The current consumption of the I/O system has two components: static and dynamic.

I/O static current consumption

All the I/Os used as inputs with pull-up or pull-down generate current consumption when the pin is externally held to the opposite level. The value of this current consumption can be simply computed by using the pull-up/pull-down resistors values given in *Section 5.3.15: I/O port characteristics*.

For the output pins, any internal or external pull-up or pull-down or external load must also be considered to estimate the current consumption.

Additional I/O current consumption is due to I/Os configured as inputs if an intermediate voltage level is externally applied. This current consumption is caused by the input Schmitt trigger circuits used to discriminate the input value. Unless this specific configuration is required by the application, this supply current consumption can be avoided by configuring these I/Os in analog mode. This is notably the case of the ADC input pins, that must be configured as analog inputs.

Caution: Any floating input pin can also settle to an intermediate voltage level or switch inadvertently, as a result of external electromagnetic noise. To avoid current consumption related to floating pins, they must either be configured in analog mode, or forced internally to a definite digital value. This can be done either by using pull-up/down resistors or by configuring the pins in output mode.

I/O dynamic current consumption

In addition to the on-chip peripheral current consumption (see *Table 65*), the I/Os used by an application also contribute to the current consumption. When an I/O pin switches, it uses the current from the I/O supply voltage to supply the I/O pin circuitry and to charge/discharge the capacitive load (internal and external) connected to the pin:

$$I_{SW} = V_{DDIOx} \times f_{SW} \times C$$

where:

- I_{SW} is the current sunk by a switching I/O to charge/discharge the capacitive load.
- V_{DDIOx} is the I/O supply voltage.
- f_{SW} is the I/O switching frequency.
- C is the total capacitance seen by the I/O pin: $C = C_{INT} + C_{EXT} + C_S$.
- C_S is the PCB board capacitance including the pad pin.

The test pin is configured in push-pull output mode and is toggled by software at a fixed frequency.

On-chip peripheral current consumption

The current consumption of the on-chip peripherals is given in the table below. The MCU is placed under the following conditions:

- All I/O pins are in analog mode.
- The given value is calculated by measuring the difference of the current consumptions:
  - when the peripheral is clocked on
  - when the peripheral is clocked off

- The ambient operating temperature and supply voltage conditions are summarized in *Table 33: General operating conditions*.
- The power consumption of the digital part of the on-chip peripherals is given in the table below. The power consumption of the analog part of the peripherals (where applicable) is indicated in each related section of the datasheet.

Table 65. Typical dynamic current consumption of peripherals

Bus	Peripheral	LDO					SMPS					Unit
		Range 1	Range 2	Range 3	Range 4	Stop 1/2	Range 1	Range 2	Range 3	Range 4	Stop 1/2	
AHB1	AHB1	0.48	0.39	0.35	0.32	-	0.21	0.18	0.15	0.11	-	µA/MHz
	BKPSRAM	1.24	1.06	0.96	0.85	-	0.57	0.47	0.39	0.31	-	
	CORDIC	0.67	0.60	0.54	0.48	-	0.32	0.26	0.22	0.18	-	
	CRC	1.02	0.88	0.80	0.70	-	0.47	0.40	0.33	0.25	-	
	DCACHE1	0.39	0.28	0.26	0.21	-	0.15	0.12	0.10	0.08	-	
	DCACHE2	1.10	0.93	0.83	0.74	-	0.50	0.41	0.34	0.27	-	
	DMA2D	2.51	2.23	2.02	1.79	-	1.20	1.00	0.84	0.66	-	
	FLASH	2.08	1.86	1.68	1.49	-	1.00	0.83	0.70	0.55	-	
	FMAC	2.36	2.09	1.90	1.69	-	1.17	0.94	0.78	0.63	-	
	GFXMMU	3.73	3.32	3.00	2.67	-	1.80	1.48	1.24	0.99	-	
	GPDMA1	3.16	2.87	2.58	2.32	-	1.55	1.29	1.08	0.84	-	
	GPU	11.83	10.68	9.68	8.61	-	5.79	4.81	4.02	3.18	-	
	GTZC1	0.96	0.81	0.73	0.64	-	0.47	0.35	0.30	0.23	-	
	ICACHE	0.94	0.79	0.72	0.63	-	0.42	0.35	0.29	0.23	-	
	MDF1	8.05	7.29	6.62	5.89	-	3.99	3.28	2.75	2.19	-	
	MDF1 indep(1)	0.92	0.87	0.79	0.69	-	0.47	0.39	0.33	0.26	-	
	RAMCFG	2.26	2.00	1.81	1.60	-	1.07	0.90	0.75	0.59	-	
	SRAM1	1.20	1.02	0.92	0.80	-	0.55	0.45	0.38	0.29	-	
	TSC	1.37	1.20	1.08	0.95	-	0.64	0.54	0.45	0.35	-	
AHB2-1	AHB2_1	1.02	0.78	0.71	0.62	-	0.42	0.34	0.29	0.24	-	
	ADC12	4.53	4.13	3.71	3.38	-	2.22	1.85	1.56	1.22	-	
	ADC12 indep(1)	0.85	0.81	0.73	0.66	-	0.44	0.36	0.30	0.25	-	
	AES	2.95	2.67	2.39	2.20	-	1.44	1.20	1.00	0.77	-	
	DCMI	5.10	4.66	4.20	3.82	-	2.55	2.09	1.76	1.38	-	
	GPIOA	0.07	0.07	0.06	0.05	-	0.03	0.03	0.03	0.02	-	
	GPIOB	0.08	0.07	0.05	0.04	-	0.04	0.03	0.03	0.02	-	
	GPIOC	0.11	0.09	0.07	0.06	-	0.05	0.05	0.04	0.02	-	
	GPIOD	0.25	0.22	0.18	0.15	-	0.12	0.10	0.09	0.06	-	

Table 65. Typical dynamic current consumption of peripherals (continued)

Bus	Peripheral	LDO					SMPS					Unit
		Range 1	Range 2	Range 3	Range 4	Stop 1/2	Range 1	Range 2	Range 3	Range 4	Stop 1/2	
AHB2-1	GPIOE	0.14	0.12	0.09	0.09	-	0.06	0.05	0.05	0.03	-	µA/MHz
	GPIOF	0.14	0.13	0.09	0.08	-	0.06	0.05	0.05	0.03	-	
	GPIOG	0.20	0.18	0.15	0.13	-	0.10	0.08	0.07	0.04	-	
	GPIOH	0.27	0.24	0.20	0.18	-	0.13	0.11	0.09	0.06	-	
	GPIOI	0.30	0.26	0.22	0.20	-	0.14	0.12	0.10	0.07	-	
	GPIOJ	0.28	0.25	0.19	0.17	-	0.13	0.10	0.09	0.06	-	
	HASH1	2.00	1.82	1.61	1.48	-	0.97	0.81	0.68	0.52	-	
	OCTOSPIM	0.54	0.49	0.41	0.36	-	0.27	0.21	0.18	0.13	-	
	OTFDEC1	2.09	1.89	1.68	1.55	-	1.06	0.85	0.70	0.53	-	
	OTFDEC2	2.05	1.85	1.64	1.53	-	1.04	0.83	0.69	0.52	-	
	OTG_HS	27.98	25.52	23.12	20.71	-	13.76	11.49	9.68	9.56	-	
	PKA	7.04	6.44	5.80	5.22	-	3.46	2.88	2.42	1.91	-	
	RNG	1.43	1.28	1.13	1.05	-	0.68	0.56	0.48	0.36	-	
	RNG indep(1)	0.07	0.07	0.07	0.06	-	0.05	0.05	0.03	0.02	-	
	SAES	3.38	3.07	2.75	2.50	-	1.65	1.37	1.15	0.89	-	
	SDMMC1	13.80	12.58	11.37	10.22	-	6.80	5.66	4.74	3.74	-	
	SDMMC1 indep(1)	1.67	1.53	1.38	1.30	-	0.82	0.69	0.58	0.52	-	
	SDMMC2	12.82	11.68	10.56	9.50	-	6.31	5.26	4.41	3.48	-	
	SDMMC2 indep(1)	1.63	1.49	1.36	1.26	-	0.81	0.67	0.57	0.51	-	
	SRAM2	1.22	1.10	0.97	0.94	-	0.59	0.49	0.42	0.30	-	
	SRAM3	2.31	2.10	1.86	1.74	-	1.13	0.93	0.79	0.60	-	
AHB2-2	AHB2_2	0.18	0.12	0.10	0.09	-	0.10	0.05	0.04	0.02	-	
	FMC	6.71	6.13	5.52	5.00	-	3.30	2.74	2.30	1.82	-	
	HSPI1	3.36	3.05	2.72	2.51	-	1.65	1.36	1.14	0.88	-	
	HSPI1 indep(1)	2.37	2.12	1.91	1.71	-	1.15	0.95	0.80	0.62	-	
	OCTOSPI1	1.44	1.30	1.15	1.07	-	0.70	0.58	0.48	0.36	-	
	OCTOSPI1 indep(1)	1.10	1.00	0.90	0.81	-	0.54	0.45	0.38	0.29	-	
	OCTOSPI2	1.47	1.33	1.17	1.12	-	0.72	0.59	0.49	0.37	-	
	OCTOSPI2 indep(1)	1.28	1.16	1.05	0.94	-	0.63	0.53	0.44	0.34	-	
	SRAM5	2.16	1.96	1.74	1.62	-	1.06	0.87	0.73	0.56	-	

Table 65. Typical dynamic current consumption of peripherals (continued)

Bus	Peripheral	LDO					SMPS					Unit
		Range 1	Range 2	Range 3	Range 4	Stop 1/2	Range 1	Range 2	Range 3	Range 4	Stop 1/2	
AHB3	AHB3	0.16	0.13	0.11	0.10	-	0.07	0.05	0.05	0.04	-	µA/MHz
	ADC4	1.42	1.31	1.18	1.05	1.17	0.67	0.58	0.49	0.38	0.43	
	ADC4 indep(1)	1.78	1.66	1.50	1.33	1.34	0.90	0.75	0.62	0.49	0.49	
	ADF1	1.08	1.00	0.90	0.79	0.91	0.49	0.44	0.37	0.28	0.33	
	ADF1 indep(1)	0.55	0.50	0.45	0.41	0.40	0.31	0.23	0.19	0.15	0.15	
	DAC1	1.63	1.51	1.35	1.20	1.33	0.77	0.66	0.56	0.44	0.49	
	DAC1 indep(1)	1.00	0.92	0.83	0.75	0.75	0.50	0.42	0.35	0.27	0.27	
	GTZC2	1.31	1.20	1.09	0.96	-	0.60	0.53	0.45	0.34	-	
	LPDMA1	0.40	0.38	0.34	0.29	0.41	0.16	0.16	0.14	0.11	0.15	
	LPGPIO1	0.09	0.08	0.07	0.06	0.18	0.04	0.03	0.03	0.02	0.06	
	PWR	0.18	0.17	0.15	0.13	-	0.09	0.07	0.06	0.05	-	
	SRAM4	1.00	0.92	0.84	0.74	-	0.49	0.40	0.35	0.26	-	
APB1	APB1	1.16	0.90	0.79	0.76	-	0.48	0.38	0.33	0.24	-	
	CRS	0.36	0.34	0.31	0.30	-	0.22	0.15	0.13	0.11	-	
	FDCAN1	4.88	4.46	4.06	3.64	-	2.41	2.01	1.69	1.36	-	
	FDCAN1 indep(1)	2.33	2.21	2.12	1.89	-	1.28	1.07	0.88	0.71	-	
	I2C1	0.87	0.81	0.74	0.67	-	0.43	0.36	0.30	0.25	-	
	I2C1 indep(1)	2.10	1.91	1.73	1.55	-	1.03	0.86	0.72	0.56	-	
	I2C2	3.04	2.78	2.53	2.28	-	1.50	1.24	1.05	0.85	-	
	I2C2 indep(1)	2.13	1.98	1.80	1.61	-	1.12	0.89	0.75	0.59	-	
	I2C4	0.92	0.85	0.77	0.71	-	0.46	0.38	0.32	0.26	-	
	I2C4 indep(1)	2.21	2.02	1.83	1.64	-	1.09	0.91	0.76	0.60	-	
	I2C5	3.15	2.88	2.61	2.33	-	1.56	1.29	1.09	0.88	-	
	I2C5 indep(1)	2.31	2.12	1.92	1.72	-	1.14	0.95	0.80	0.63	-	
	I2C6	3.02	2.77	2.50	2.23	-	1.53	1.23	1.04	0.84	-	
	I2C6 indep(1)	2.19	2.00	1.81	1.61	-	1.08	0.90	0.75	0.59	-	
	LPTIM2	1.36	1.23	1.12	1.02	-	0.66	0.55	0.46	0.38	-	
	LPTIM2 Indep(1)	4.01	3.66	3.32	2.97	-	1.98	1.64	1.38	1.10	-	
	LTDC	10.29	9.38	8.49	7.59	-	5.07	4.22	3.54	2.80	-	
	SPI2	1.89	1.71	1.54	1.42	-	0.91	0.76	0.64	0.53	-	
	SPI2 indep(1)	0.71	0.64	0.58	0.51	-	0.35	0.29	0.24	0.19	-	

Table 65. Typical dynamic current consumption of peripherals (continued)

Bus	Peripheral	LDO					SMPS					Unit
		Range 1	Range 2	Range 3	Range 4	Stop 1/2	Range 1	Range 2	Range 3	Range 4	Stop 1/2	
APB1	TIM2	4.75	4.30	3.91	3.50	-	2.33	1.93	1.63	1.30	-	µA/MHz
	TIM3	4.74	4.30	3.91	3.50	-	2.32	1.93	1.62	1.30	-	
	TIM4	4.73	4.32	3.93	3.53	-	2.34	1.94	1.63	1.31	-	
	TIM5	4.82	4.41	4.01	3.60	-	2.38	1.98	1.66	1.34	-	
	TIM6	0.92	0.86	0.77	0.71	-	0.50	0.38	0.32	0.26	-	
	TIM7	0.92	0.86	0.77	0.71	-	0.45	0.39	0.32	0.26	-	
	UART4	2.04	1.89	1.71	1.57	-	1.05	0.84	0.71	0.58	-	
	UART4 indep(1)	3.88	3.55	3.23	2.88	-	1.91	1.59	1.34	1.07	-	
	UART5	2.07	1.91	1.73	1.58	-	1.02	0.85	0.72	0.58	-	
	UART5 indep(1)	3.70	3.38	3.07	2.73	-	1.82	1.52	1.28	1.02	-	
	UCPD1	1.73	1.60	1.45	1.31	-	0.86	0.71	0.60	0.49	-	
	USART2	7.03	6.44	5.84	5.26	-	3.47	2.90	2.43	1.95	-	
	USART2 indep(1)	4.97	4.55	4.14	3.69	-	2.45	2.05	1.72	1.38	-	
	USART3	2.34	2.16	1.95	1.79	-	1.15	0.96	0.81	0.66	-	
	USART3 indep(1)	4.64	4.24	3.86	3.43	-	2.29	1.91	1.61	1.29	-	
	USART6	6.61	6.03	5.48	4.89	-	3.25	2.71	2.29	1.82	-	
	USART6 indep(1)	4.49	4.11	3.73	3.32	-	2.21	1.85	1.55	1.24	-	
	WWDG	0.47	0.45	0.39	0.34	-	0.23	0.19	0.17	0.14	-	
APB2	APB2	0.83	0.59	0.51	0.47	-	0.31	0.24	0.22	0.16	-	
	DSI	13.76	12.53	11.33	10.14	-	6.78	5.65	4.74	3.86	-	
	SAI1	1.68	1.51	1.36	1.22	-	0.81	0.68	0.56	0.45	-	
	SAI1 indep(1)	1.30	1.18	1.08	0.95	-	0.64	0.53	0.45	0.34	-	
	SAI2	1.77	1.57	1.42	1.29	-	0.85	0.71	0.59	0.47	-	
	SAI2 indep(1)	1.40	1.29	1.17	1.00	-	0.69	0.58	0.49	0.38	-	
	SPI1	1.71	1.55	1.41	1.26	-	0.83	0.70	0.59	0.47	-	
	SPI1 indep(1)	0.83	0.76	0.69	0.62	-	0.41	0.34	0.29	0.23	-	
	TIM1	7.25	6.61	6.00	5.34	-	3.56	2.97	2.50	1.99	-	
	TIM15	3.74	3.41	3.10	2.78	-	1.88	1.54	1.29	1.03	-	
	TIM16	2.61	2.38	2.17	1.94	-	1.29	1.07	0.90	0.72	-	
	TIM17	2.71	2.47	2.24	2.01	-	1.34	1.11	0.93	0.74	-	
	TIM8	7.26	6.63	5.99	5.38	-	3.57	3.00	2.50	1.98	-	

Table 65. Typical dynamic current consumption of peripherals (continued)

Bus	Peripheral	LDO					SMPS					Unit
		Range 1	Range 2	Range 3	Range 4	Stop 1/2	Range 1	Range 2	Range 3	Range 4	Stop 1/2	
APB2	USART1	2.09	1.92	1.75	1.55	-	1.03	0.87	0.73	0.58	-	µA/MHz
	USART1 indep(1)	3.97	3.63	3.31	2.94	-	1.96	1.63	1.37	1.10	-	
APB3	APB3	0.34	0.21	0.17	0.16	-	0.11	0.08	0.07	0.06	-	
	COMP	0.23	0.21	0.19	0.17	0.14	0.11	0.09	0.08	0.06	0.05	
	I2C3	0.64	0.59	0.52	0.47	0.48	0.32	0.26	0.22	0.17	0.17	
	I2C3 indep(1)	1.73	1.59	1.42	1.27	1.28	0.90	0.71	0.60	0.45	0.47	
	LPTIM1	1.08	0.98	0.89	0.78	0.81	0.57	0.44	0.37	0.29	0.29	
	LPTIM1 indep(1)	3.03	2.74	2.47	2.20	2.24	1.48	1.21	1.03	0.81	0.82	
	LPTIM3	1.03	0.95	0.85	0.76	0.77	0.51	0.43	0.35	0.28	0.28	
	LPTIM3 indep(1)	2.87	2.54	2.32	2.06	2.13	1.41	1.15	0.98	0.77	0.78	
	LPTIM4	0.65	0.60	0.54	0.48	0.49	0.33	0.27	0.22	0.18	0.18	
	LPTIM4 indep(1)	1.69	1.54	1.46	1.28	1.34	0.88	0.72	0.63	0.47	0.49	
	LPUART1	1.27	1.16	1.04	0.93	0.95	0.67	0.52	0.44	0.34	0.35	
	LPUART1 indep(1)	2.12	1.94	1.76	1.58	1.58	1.05	0.87	0.73	0.57	0.58	
	OPAMP	0.24	0.22	0.18	0.17	0.18	0.11	0.10	0.08	0.07	0.06	
	RTC	1.87	1.70	1.52	1.38	1.39	0.93	0.77	0.64	0.50	0.51	
	SPI3	1.13	1.01	0.90	0.80	0.81	0.54	0.45	0.37	0.30	0.30	
	SPI3 indep(1)	0.48	0.44	0.40	0.35	0.35	0.23	0.20	0.16	0.12	0.13	
	SYSCFG	0.37	0.30	0.27	0.24	-	0.17	0.14	0.11	0.09	-	
	VREFBUF	0.14	0.12	0.11	0.10	0.11	0.07	0.06	0.05	0.04	0.04	

1. Indep stands for independent clock domain.

5.3.7 Wake-up time from low-power modes and voltage scaling transition times

The wake-up times given in the table below are the latency between the event and the execution of the first user instruction (FSTEN = 1 in PWR_CR3 if not mentioned).

The device goes in low-power mode after the WFE (wait for event) instruction.

Table 66. Low-power mode wake-up timings on LDO(1)

Mode	Parameter	Conditions		Typ (3V, 25°C)	Max (3V)	Unit
$t_{wu(Sleep)}$	Wake-up time from Sleep to Run mode	SLEEP_PD = 0		14	17	Nb of CPU cycles
		SLEEP_PD = 1 with MSI = 24 MHz		8.1	9	µs
$t_{wu(Stop\ 0)}$	Wake-up time from Stop 0 to Run mode All SRAMs retained	Wake-up in FLASH, range 4, FLASHFWU = 1 and SRAM4FWU = 1 in PWR_CR2 ICACHE OFF	MSI 24 MHz	2.6	3	
		Wake-up in FLASH, range 4, FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2 ICACHE OFF	MSI 24 MHz	11.0	12	
			HSI 16 MHz	10.7	12	
			MSI 1 MHz	38.1	40	
		Wake-up in SRAM2, range 4, FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2	MSI 24 MHz	5.0	6	
			HSI 16 MHz	6.9	8	
			MSI 1 MHz	34.1	36	
$t_{wu(Stop\ 1)}$	Wake-up time from Stop 1 to Run mode All SRAMs retained	Wake-up in FLASH, FLASHFWU = 1 and SRAM4FWU = 1 in PWR_CR2 ICACHE OFF	MSI 24 MHz	13.4	17	
		Wake-up in FLASH, FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2 ICACHE OFF	MSI 24 MHz	21.9	25	
			HSI 16 MHz	21.6	25	
			MSI 1 MHz	48.9	53	
		Wake-up in SRAM2, range 4, FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2	MSI 24 MHz	15.8	19	
			HSI 16 MHz	17.7	21	
			MSI 1 MHz	44.9	49	
$t_{wu(Stop\ 2)}$	Wake-up time from Stop 2 to Run mode All SRAMs retained	Wake-up in FLASH, SRAM4FWU = 1 in PWR_CR2 ICACHE OFF	MSI 24 MHz	20.3	24	
		Wake-up in FLASH, SRAM4FWU = 0 in PWR_CR2 ICACHE OFF	MSI 24 MHz	22.9	26	
			HSI 16 MHz	22.7	27	
			MSI 1 MHz	58.0	63	
		Wake-up in SRAM2, range 4, SRAM4FWU = 0 in PWR_CR2	MSI 24 MHz	16.9	20	
			HSI 16 MHz	19.0	23	
			MSI 1 MHz	54.0	59	
$t_{wu(Stop\ 3)}$	Wake-up time from Stop 3 to Run mode All SRAMs retained	Wake-up in FLASH, FSTEN = 0 in PWR_CR3 ICACHE OFF	MSI 24 MHz	55.3	132	

Table 66. Low-power mode wake-up timings on LDO(1) (continued)

Mode	Parameter	Conditions		Typ (3V, 25°C)	Max (3V)	Unit
$t_{wu(Stop\ 3)}$	Wake-up time from Stop 3 to Run mode All SRAMs retained	Wake-up in FLASH, FSTEN = 1 in PWR_CR3 ICACHE OFF	MSI 24 MHz	28.9	38	µs
			HSI 16 MHz	28.7	37	
			MSI 1 MHz	63.0	98	
		Wake-up in SRAM2, range 4	MSI 24 MHz	20.2	32	
			HSI 16 MHz	22.3	32	
			MSI 1 MHz	58.3	91	
$t_{wu(Standby\ with\ SRAM2)}$	Wake-up time from Standby with SRAM2 to Run mode	Wake-up in FLASH, FSTEN = 0 in PWR_CR3	MSI 4 MHz	60.5	90	
		Wake-up in FLASH, FSTEN = 1 in PWR_CR3	MSI 4 MHz	59.7	89	
			MSI 1 MHz	168.1	248	
$t_{wu(Standby)}$	Wake-up time from Standby to Run mode	Wake-up in FLASH, FSTEN = 0 in PWR_CR3	MSI 4 MHz	327.3	416	
		Wake-up in FLASH, FSTEN = 1 in PWR_CR3	MSI 4 MHz	95.5	127	
			MSI 1 MHz	199.5	283	
$t_{wu(Shutdown)}$	Wake-up time from Shutdown to Run mode	-	MSI 4 MHz	683.3	718	

1. Evaluated by characterization. Not tested in production.

Table 67. Low-power mode wake-up timings on SMPS(1)

Mode	Parameter	Conditions		Typ (3 V, 25 °C)	Max (3 V)	Unit
$t_{wu(Sleep)}$	Wake-up time from Sleep to Run mode	SLEEP_PD = 0		14	17	Nb of CPU cycles
		SLEEP_PD = 1 with MSI = 24 MHz		8.0	9	µs
$t_{wu(Stop\ 0)}$	Wake-up time from Stop 0 to Run mode All SRAMs retained	Wake-up in FLASH, range 4, FLASHFWU = 1 and SRAM4FWU = 1 in PWR_CR2 ICACHE OFF	MSI 24 MHz	2.6	3	
		Wake-up in FLASH, range 4, FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2 ICACHE OFF	MSI 24 MHz	11.0	12	
			HSI 16 MHz	10.7	12	
			MSI 1 MHz	38.1	40	
		Wake-up in SRAM2, range 4, FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2	MSI 24 MHz	5.0	6	
			HSI 16 MHz	6.8	8	
			MSI 1 MHz	34.1	36	

Table 67. Low-power mode wake-up timings on SMPS(1) (continued)

Mode	Parameter	Conditions		Typ (3 V, 25 °C)	Max (3 V)	Unit
$t_{wu(Stop\ 1)}$	Wake-up time from Stop 1 to Run mode All SRAMs retained	Wake-up in FLASH, FLASHFWU = 1 and SRAM4FWU = 1 in PWR_CR2 ICACHE OFF	MSI 24 MHz	7.8	9	µs
		Wake-up in FLASH FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2 ICACHE OFF	MSI 24 MHz	16.2	18	
			HSI 16 MHz	15.9	17	
			MSI 1 MHz	43.2	46	
		Wake-up in SRAM2, range 4, FLASHFWU = 0 and SRAM4FWU = 0 in PWR_CR2	MSI 24 MHz	10.1	12	
			HSI 16 MHz	12.0	14	
			MSI 1 MHz	39.3	42	
$t_{wu(Stop\ 2)}$	Wake-up time from Stop 2 to Run mode All SRAMs retained	Wake-up in FLASH SRAM4FWU = 1 in PWR_CR2 ICACHE OFF	MSI 24 MHz	17.6	20	
		Wake-up in FLASH SRAM4FWU = 0 in PWR_CR2 ICACHE OFF	MSI 24 MHz	20.2	22	
			HSI 16 MHz	20.0	22	
			MSI 1 MHz	55.1	59	
		Wake-up in SRAM2, range 4, SRAM4FWU = 0 in PWR_CR2	MSI 24 MHz	14.2	16	
			HSI 16 MHz	16.2	18	
			MSI 1 MHz	51.1	55	
$t_{wu(Stop\ 3)}$	Wake-up time from Stop 3 to Run mode All SRAMs retained	Wake-up in FLASH, FSTEN = 0 in PWR_CR3 ICACHE OFF	MSI 24 MHz	131.4	164	
		Wake-up in FLASH, FSTEN = 1 in PWR_CR3 ICACHE OFF	MSI 24 MHz	30.9	36	
			HSI 16 MHz	30.6	35	
			MSI 1 MHz	67.3	101	
		Wake-up in SRAM2, range 4	MSI 24 MHz	25.0	31	
			HSI 16 MHz	26.8	32	
			MSI 1 MHz	62.8	94	
$t_{wu(Standby\ with\ SRAM2)}$	Wake-up time from Standby with SRAM2 to Run mode	Wake-up in FLASH, FSTEN = 0 in PWR_CR3	MSI 4 MHz	57.3	88	
		Wake-up in FLASH, FSTEN = 1 in PWR_CR3	MSI 4 MHz	57.9	87	
			MSI 1 MHz	165.2	246	
$t_{wu(Standby)}$	Wake-up time from Standby to Run mode	Wake-up in FLASH, FSTEN = 0 in PWR_CR3	MSI 4 MHz	329.2	417	
		Wake-up in FLASH, FSTEN = 1 in PWR_CR3	MSI 4 MHz	94.8	125	
			MSI 1 MHz	200.5	282	
$t_{wu(Shutdown)}$	Wake-up time from Shutdown to Run mode	-	MSI 4 MHz	683.2	718	

1. Evaluated by characterization. Not tested in production.

Table 68. Regulator mode transition times(1)

Symbol	Parameter	Conditions	Typ (3 V, 25 °C)	Max (3 V)	Unit
t_{LDO}(2)	SMPS to LDO transition time	Range 4	15.6	19	µs
		Range 3	14.5	18	
		Range 2	14	18	
		Range 1	13.9	17	
t_{SMPS}(2)	LDO to SMPS transition time	Range 4	13.1	16	
		Range 3	16.5	19	
		Range 2	16.1	19	
		Range 1	15.9	19	
t_{VOST}(3)	Range 4 to range 3	LDO	18	21	
		SMPS	24.3	28	
	Range 3 to range 2	LDO	12.2	15	
		SMPS	12.2	15	
	Range 2 to range 1	LDO	11.8	14	
		SMPS	11.8	14	
	Range 4 to range 1	LDO	40.9	43	
		SMPS	47	55	

1. Evaluated by characterization. Not tested in production.
2. Time to REGS change in PWR_SVMSR.
3. Time to VOSRDY = 1 in PWR_VOSR.

Table 69. Wake-up time using USART/LPUART(1)

Symbol	Parameter	Typ	Max	Unit
$t_{WUUSART}$ $t_{WULPUART}$	Wake-up time needed to calculate the maximum USART/LPUART baudrate that is needed to wake up from Stop mode when the USART/LPUART kernel clock source is HSI16/MSI.	-	(2)	µs

1. Specified by design. Not tested in production.
2. This wake-up time is the HSI16 (see *Table 74*) or the MSI (see *Table 75*) oscillator maximum startup time.

5.3.8 External clock timing characteristics

High-speed external user clock generated from an external source

In bypass mode, the HSE oscillator is switched off and the input pin is a standard GPIO.

The external clock signal has to respect the I/O characteristics in *Section 5.3.15: I/O port characteristics*. The recommended clock input waveform is shown in *Figure 27*.

Table 70. High-speed external user clock characteristics(1)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
f_{HSE_ext}	User external clock source frequency	Digital mode (HSEBYP = 1, HSEEXT = 1)	Voltage scaling range 1, 2, 3	4(2)	-	50	MHz
		Analog mode (HSEBYP = 1, HSEEXT = 0)					
		-	Voltage scaling range 4	4(2)	-	25	
V_{HSEH}	OSC_IN input pin high-level voltage	Digital mode (HSEBYP = 1, HSEEXT = 1)	-	0.7 × V_{DD}	-	V_{DD}	V
V_{HSEL}	OSC_IN input pin low-level voltage		-	V_{SS}	-	0.3 × V_{DD}	
$t_{w(HSEH)}$ $t_{w(HSEL)}$	OSC_IN high or low time		Voltage scaling range 1, 2, 3	7	-	-	ns
			Voltage scaling range 4	18	-	-	
$DuCy_{HSE}$	OSC_IN duty cycle		-	45	-	55	%
$V_{HSE_ext_PP}$	OSC_IN peak-to-peak amplitude	Analog mode (HSEBYP = 1, HSEEXT = 0)	-	0.2	-	2/3 V_{DD}	V
V_{HSE_ext}	OSC_IN input range		-	0	-	V_{DD}	
$t_{r(HSE)}$, $t_{f(HSE)}$	OSC_IN rise and fall time		-	0.05 / f_{HSE_ext}	-	0.3 / f_{HSE_ext}	ns

1. Specified by design. Not tested in production.
2. Only for Analog mode. No minimum value in digital mode.

Figure 27. AC timing diagram for high-speed external clock source (digital mode)

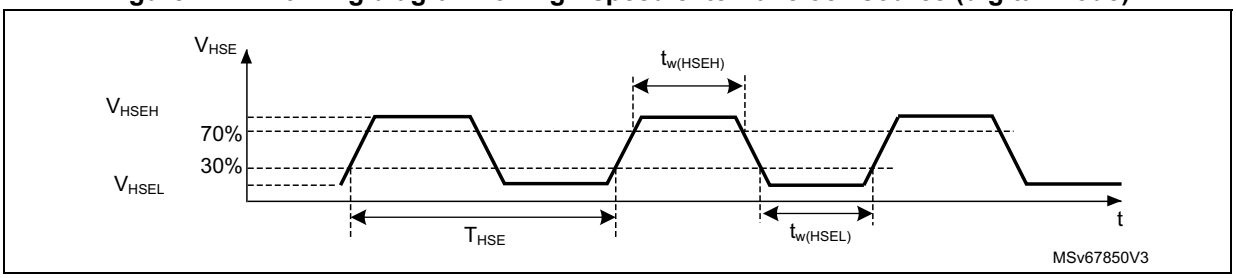
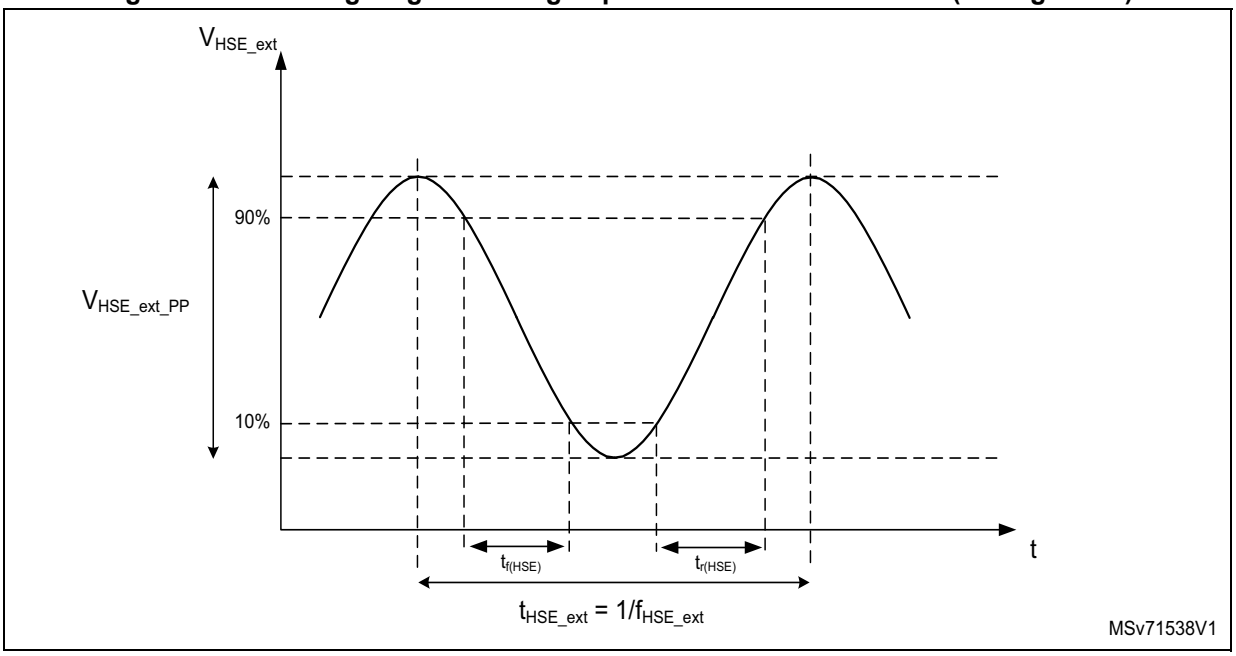


Figure 28. AC timing diagram for high-speed external clock source (analog mode)



Low-speed external user clock generated from an external source

In bypass mode, the LSE oscillator is switched off and the input pin is a standard GPIO.

The external clock signal has to respect the I/O characteristics in *Section 5.3.15: I/O port characteristics*. The recommended clock input waveform is shown in *Figure 29* and *Figure 30*.

Table 71. Low-speed external user clock characteristics(1)

Symbol	Parameter	Min	Typ	Max	Unit
f_{LSE_ext}	User external clock source frequency	5	32.768	40	kHz
$V_{LSE_ext_PP}$	OSC32_IN peak-to-peak amplitude	0.3	-	V_{SW}	V
V_{LSE_ext}	OSC32_IN input range	0	-	V_{SW}	
$t_{w(LSEH)}$ $t_{w(LSEL)}$	OSC32_IN high or low time for square signal input	10	-	-	µs

1. Specified by design. Not tested in production.

Figure 29. AC timing diagram for low-speed external square clock source

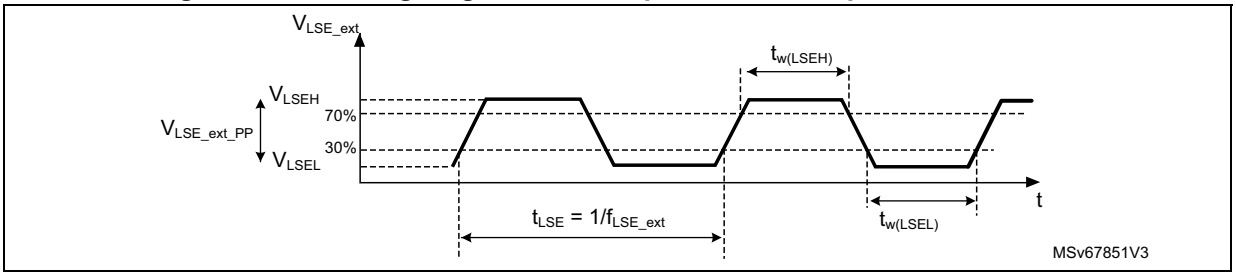
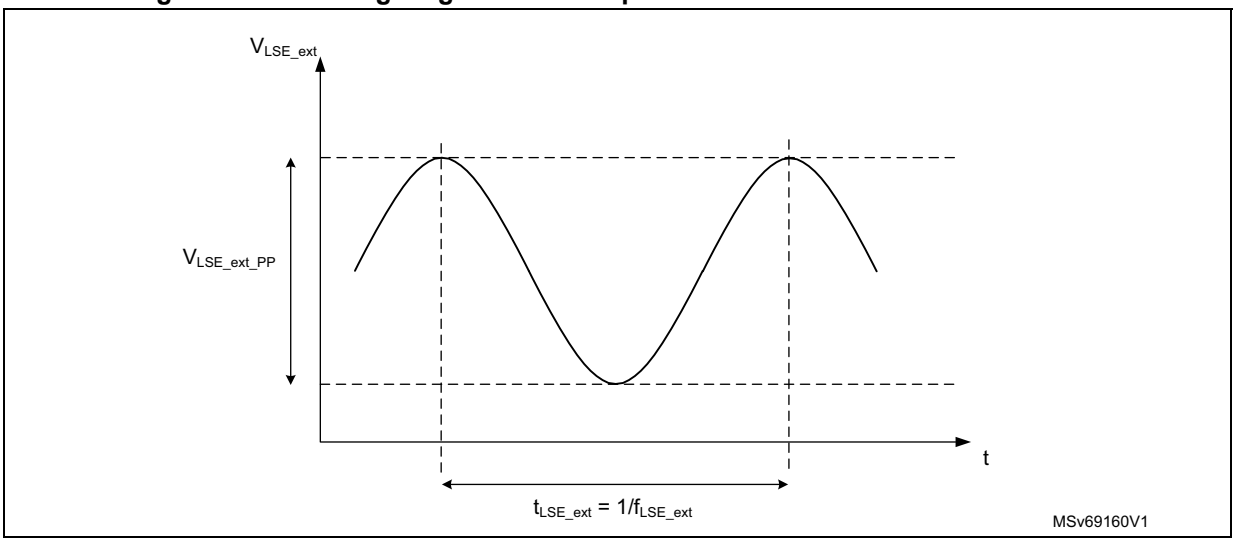


Figure 30. AC timing diagram for low-speed external sinusoidal clock source



High-speed external clock generated from a crystal/ceramic resonator

The high-speed external (HSE) clock can be supplied with a 4 to 48 MHz crystal/ceramic resonator oscillator. All the information given in this paragraph are based on design simulation results obtained with typical external components specified in the table below.

In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins, in order to minimize the output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Table 72. HSE oscillator characteristics(1)

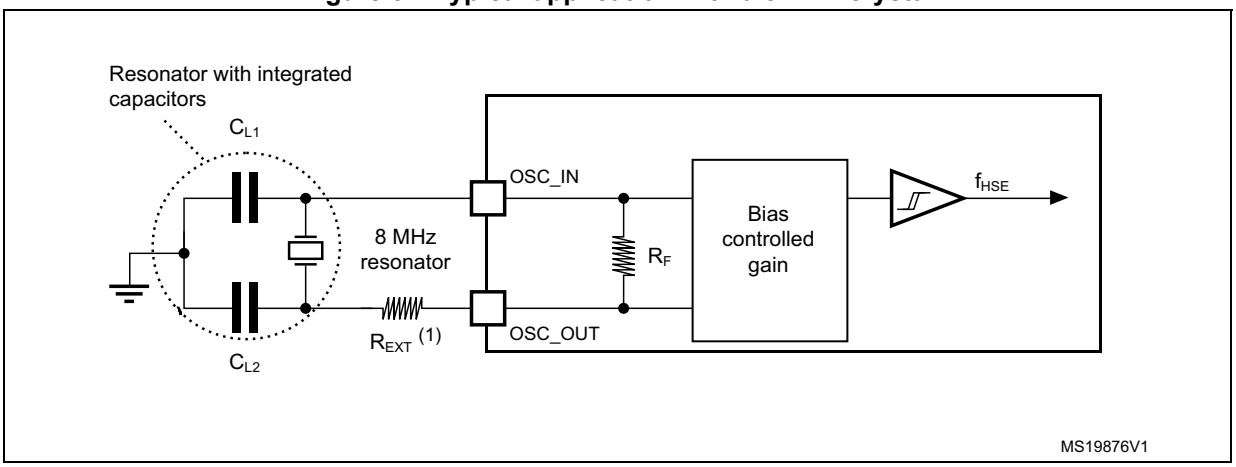
Symbol	Parameter	Conditions(2)	Min	Typ	Max	Unit
f_{OSC_IN}	Oscillator frequency	-	4	-	50	MHz
R_F	Feedback resistor	-	-	200	-	kΩ
$I_{DD(HSE)}$	HSE current consumption	During startup(3)	-	-	8	mA
		V_{DD} = 3 V, Rm = 30 Ω, CL = 10 pF @ 4 MHz	-	790	-	µA
		V_{DD} = 3 V, Rm = 30 Ω, CL = 10 pF @ 8 MHz	-	910	-	
		V_{DD} = 3 V, Rm = 45 Ω, CL = 10 pF @ 8 MHz	-	930	-	
		V_{DD} = 3 V, Rm = 30 Ω, CL = 5 pF @ 48 MHz	-	1430	-	
		V_{DD} = 3 V, Rm = 30 Ω, CL = 10 pF @ 48 MHz	-	1960	-	
		V_{DD} = 3 V, Rm = 30 Ω, CL = 20 pF @ 48 MHz	-	3000	-	
$Gm_{critmax}$	Maximum critical crystal transconductance G_m	Startup	-	-	1.5	mA/V
$t_{su(HSE)}$ (4)	Startup time	V_{DD} stabilized	-	2	-	ms

1. Specified by design. Not tested in production.

2. Resonator characteristics given by the crystal/ceramic resonator manufacturer.
3. This consumption level occurs during the first 2/3 of the $t_{SU(HSE)}$ startup time.
4. $t_{SU(HSE)}$ is the startup time measured from the moment it is enabled (by software) to a stabilized 8 MHz oscillation is reached. This value is measured for a standard crystal resonator and it can vary significantly with the crystal manufacturer.

Note: For information on selecting the crystal, refer to the application note 'Oscillator design guide for STM8AF/AL/S, STM32 MCUs and MPUs' (AN2867).

Figure 31. Typical application with a 8 MHz crystal



1. R_{EXT} value depends on the crystal characteristics.

Low-speed external clock generated from a crystal resonator

The low-speed external (LSE) clock can be supplied with a 32.768 kHz crystal resonator oscillator. All the information given in this paragraph are based on design simulation results obtained with typical external components specified in the table below. In the application, the resonator and the load capacitors have to be placed as close as possible to the oscillator pins in order to minimize output distortion and startup stabilization time. Refer to the crystal resonator manufacturer for more details on the resonator characteristics (frequency, package, accuracy).

Table 73. LSE oscillator characteristics (f_{LSE} = 32.768 kHz)(1)

Symbol	Parameter	Conditions(2)	Min	Typ	Max	Unit
$I_{DD(LSE)}$	LSE current consumption	LSEDRV[1:0] = 00, low-drive capability	-	410	-	nA
		LSEDRV[1:0] = 01, medium low-drive capability	-	450	-	
		LSEDRV[1:0] = 10, medium high-drive capability	-	590	-	
		LSEDRV[1:0] = 11, high-drive capability	-	700	-	
$Gm_{critmax}$	Maximum critical crystal Gm	LSEDRV[1:0] = 00, low-drive capability	-	-	0.5	µA/V
		LSEDRV[1:0] = 01, medium low-drive capability	-	-	0.75	
		LSEDRV[1:0] = 10, medium high-drive capability	-	-	1.7	
		LSEDRV[1:0] = 11, high-drive capability	-	-	2.7	

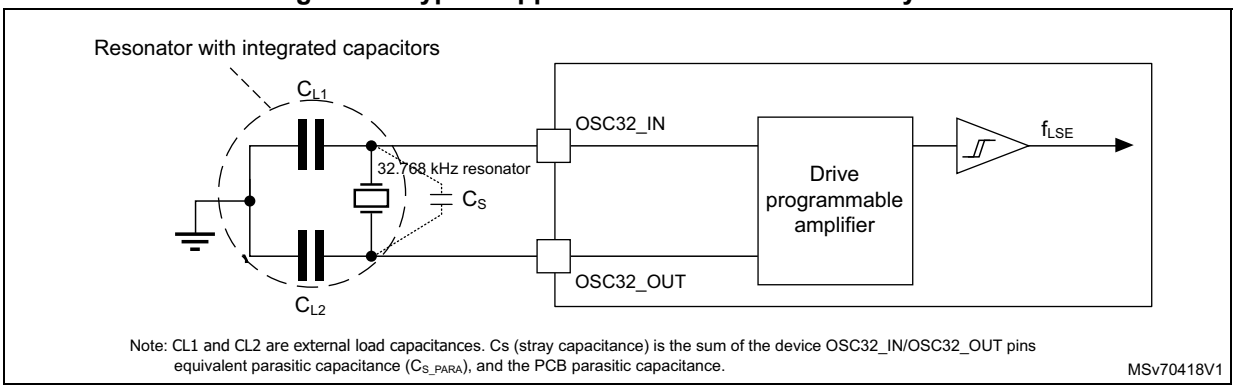
Table 73. LSE oscillator characteristics (f_{LSE} = 32.768 kHz)(1) (continued)

Symbol	Parameter	Conditions(2)	Min	Typ	Max	Unit
C_{S_PARA}	Internal stray parasitic capacitance(3)	-	-	3	-	pF
$t_{SU(LSE)}$(4)	Startup time	V_{DD} is stabilized	-	2	-	s

1. Specified by design. Not tested in production.
2. Refer to the note below this table.
3. C_{S_PARA} is the equivalent capacitance seen by the crystal due to OSC32_IN and OSC32_OUT internal parasitic capacitances.
4. $t_{SU(LSE)}$ is the startup time measured from the moment it is enabled (by software) to a stabilized 32.768 kHz oscillation is reached. This value is measured for a standard crystal and it can vary significantly with the crystal manufacturer

Note: For information on selecting the crystal, refer to the application note 'Oscillator design guide for STM8AF/AL/S, STM32 MCUs and MPUs' (AN2867).

Figure 32. Typical application with a 32.768 kHz crystal



Note: An external resistor is not required between OSC32_IN and OSC32_OUT and it is forbidden to add one.

5.3.9 Internal clock timing characteristics

The parameters given in the table below are derived from tests performed under ambient temperature and supply voltage conditions summarized in *Table 33*. The provided curves are characterization results, not tested in production.

High-speed internal (HSI16) RC oscillator

Table 74. HSI16 oscillator characteristics

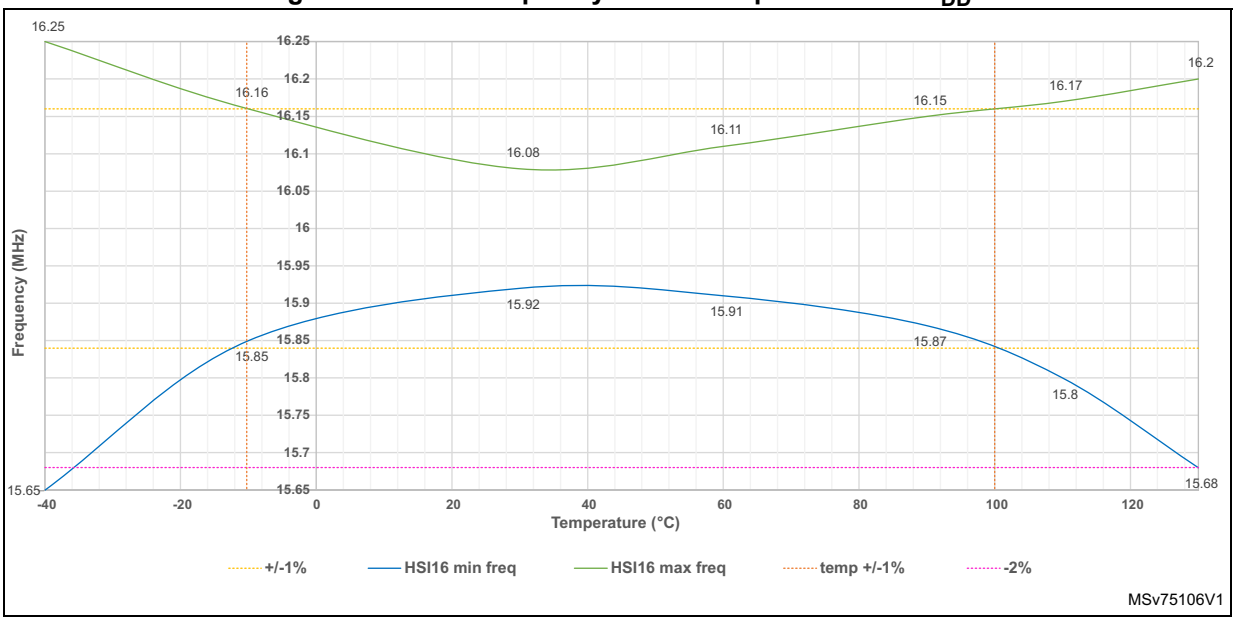
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI16}	HSI16 frequency after factory calibration	V_{DD} = 3.0 V, T_J = 30 °C	15.92	16	16.08	MHz
f_{HSI16}(1)		T_J = –10 °C to 100 °C, 1.58 ≤ V_{DD} ≤ 3.6 V	15.84	-	16.16	
		T_J = –40 °C to 130 °C, 1.58 ≤ V_{DD} ≤ 3.6 V	15.65	-	16.25	
$TRIM_{HSI16}$(2)	HSI16 user trimming step	-	18	29	40	kHz

Table 74. HSI16 oscillator characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$DuCy_{HSI16}$ (2)	Duty cycle	-	45	-	55	%
$t_{su(HSI16)}$ (2)	HSI16 oscillator startup time	-	-	2.5	3.6	µs
$t_{stab(HSI16)}$ (2)	HSI16 oscillator stabilization time	At 1% of target frequency	-	4	6	
$I_{DD(HSI16)}$ (2)	HSI16 oscillator power consumption	-	-	150	210	µA

1. Evaluated by characterization. Not tested in production. It does not take into account package and soldering effects.
2. Specified by design. Not tested in production.

Figure 33. HSI16 frequency versus temperature and V_{DD}



Multi-speed internal (MSI) RC oscillator

Table 75. MSI oscillator characteristics(1)

Symbol	Parameter	Conditions			Min	Typ	Max	Unit
f_{MSI}	MSI frequency after factory calibration	V_{DD} = 3 V T_J = 30 °C	MSI mode	MSI range 0 (MSIRC0)	47.74	48	48.70	MHz
				MSI range 1	23.87	24	24.35	
				MSI range 2	15.91	16	16.23	
				MSI range 3	11.93	12	12.17	
				MSI range 4 (MSIRC1)	3.98	4	4.06	
				MSI range 5	1.99	2	2.03	
				MSI range 6	1.33	1.33	1.35	
				MSI range 7	0.99	1	1.01	
				MSI range 8 (MSIRC2)	3.05	3.08	3.12	
				MSI range 9	1.53	1.54	1.56	
				MSI range 10	1.02	1.03	1.04	
				MSI range 11	0.76	0.77	0.78	
				MSI range 12 (MSIRC3)	397.68	400	405.71	kHz
				MSI range 13	198.84	200	202.86	
				MSI range 14	132.56	133	135.24	
				MSI range 15	99.42	100	101.43	
			PLL mode(2) XTAL = 32.768 kHz	MSI range 0 (MSIRC0)	-	48.005	-	MHz
				MSI range 1	-	24.003	-	
				MSI range 2	-	16.002	-	
				MSI range 3	-	12.001	-	
				MSI range 4 (MSIRC1)	-	3.998	-	
				MSI range 5	-	1.999	-	
				MSI range 6	-	1.333	-	
				MSI range 7	-	0.999	-	
				MSI range 8 (MSIRC2)	-	3.08	-	
				MSI range 9	-	1.54	-	
				MSI range 10	-	1.027	-	
				MSI range 11	-	0.77	-	

Table 75. MSI oscillator characteristics(1) (continued)

Symbol	Parameter	Conditions			Min	Typ	Max	Unit
$f_{MSI\ (cont'd)}$	MSI frequency after factory calibration	V_{DD} = 3 V T_J = 30 °C	PLL mode XTAL = 32.768 kHz	MSI range 12 (MSIRC3)	-	393	-	kHz
				MSI range 13	-	196.6	-	
				MSI range 14	-	131	-	
				MSI range 15	-	98.3	-	
$DuCy_{MSI}$(3)	Duty cycle	MSI range 0, 4, 8, or 12			38	-	62	%
		MSI range 2, 6, 10, or 14			31	-	69	
		Other MSI ranges			48	-	52	
$TRIM_{MSI}$	User trimming step	-			-	0.4	-	
$\Delta_{TEMP(MSI)}$(4)	MSI oscillator frequency drift over temperature (reference is 30 °C)	MSI mode	T_J = –40 to 130 °C		-4	-	2	
$\Delta_{VDD(MSI)}$(4)	MSI oscillator frequency drift over V_{DD} (reference is 3V)	MSI mode	MSI range 0 to 3	1.58 ≤ V_{DD} ≤ 3.6 V	-4	-	1	
				2.4 ≤ V_{DD} ≤ 3.6 V	-1	-	1	
			MSI range 4 to 7	1.58 ≤ V_{DD} ≤ 3.6 V	-3	-	1	
				2.4 ≤ V_{DD} ≤ 3.6 V	-1	-	1	
			MSI range 8 to 11	1.58 ≤ V_{DD} ≤ 3.6 V	-3	-	1	
				2.4 ≤ V_{DD} ≤ 3.6 V	-1	-	1	
			MSI range 12 to 15	1.58 ≤ V_{DD} ≤ 3.6 V	-3	-	1	
				2.4 ≤ V_{DD} ≤ 3.6 V	-1	-	1	
$\Delta_{FSAMPLING(MSI)}$(3)(4)	MSI frequency variation in sampling mode (MSIBIAS = 1)	MSI mode	T_J = –40 to 130 °C		-	-	0.2	
CC jitter(MSI)(3)	RMS cycle-to-cycle jitter	PLL mode	MSI range 0		-	60	-	ps
			MSI range 4		-	160	-	
			MSI range 8		-	200	-	
			MSI range 12		-	1100	-	
P jitter(MSI)(3)	RMS period jitter	PLL mode	MSI range 0		-	40	-	
			MSI range 4		-	130	-	
			MSI range 8		-	170	-	
			MSI range 12		-	800	-	

Table 75. MSI oscillator characteristics(1) (continued)

Symbol	Parameter	Conditions			Min	Typ	Max	Unit
$t_{su(MSI)}$(3)	MSI oscillator startup time(5)	MSI range 0 to 3			-	-	13 MSIRC0 cycles + 11 MSI cycles	cycles
		MSI range 4 to 7			-	-	4 MSIRC1 cycles + 11 MSI cycles	
		MSI range 8 to 11			-	-	4 MSIRC2 cycles + 11 MSI cycles	
		MSI range 12 to 15			-	-	4 MSIRC3 cycles + 11 MSI cycles	
$t_{switch(MSI)}$(3)	MSI oscillator transition time(6)	-			-	-	3 destination MSI cycles	
$t_{stab(MSI)}$(3)	MSI oscillator stabilization time	Normal mode	Continuous mode(7)	Final frequency	-	-	10	µs
			Sampling mode(8)		-	-	200	
		PLL mode, MSIPLL FAST = 0	All MSI ranges	1% of final frequency	-	-	0.8	ms
		PLL mode, MSIPLL FAST = 1	All MSI ranges		2			cycles
$I_{DD(MSI_OFF_PLLFAST)}$(3)	MSI PLL-mode oscillator power consumption when MSI is disabled with PLL accuracy retention	MSIPLL EN = 1 and MSIPLL FAST = 1	LDO	MSI range 0 to 3	-	6.6	-	µA
				MSI range 4 to 7	-	1.6	-	
				MSI range 8 to 11	-	1.4	-	
				MSI range 12 to 15	-	0.8	-	
			SMPS	MSI range 0 to 3	-	4.7	-	
				MSI range 4 to 7	-	1.4	-	
				MSI range 8 to 11	-	1.3	-	
				MSI range 12 to 15	-	0.8	-	

Table 75. MSI oscillator characteristics(1) (continued)

Symbol	Parameter	Conditions			Min	Typ	Max	Unit
$I_{DD(MSI)}$(3)	MSI oscillator power consumption	Continuous mode(7)	LDO	MSI range 0 to 3	-	21 + 2.5 µA/MHz	-	µA
				MSI range 4 to 15	-	19 + 2.5 µA/MHz	-	
			SMPS(9)	MSI range 0 to 3	-	21 + 1,3 µA/MHz	-	
				MSI range 4 to 15	-	19 + 1,3 µA/MHz	-	
		Sampling mode(8)	LDO	Range 0 to 3	-	3 + 2.5 µA/MHz	-	
				Range 4 to 15	-	1 + 2.5µA/ MHz	-	
			SMPS	Range 0 to 3	-	3 + 1 µA/MHz	-	
				Range 4 to 15	-	1 + 1 µA/MHz	-	

1. Evaluated by characterization and not tested in production, unless otherwise specified.
2. In PLL mode, the MSI accuracy is the LSE crystal accuracy.
3. Specified by design. Not tested in production.
4. This is a deviation for an individual part once the initial frequency has been measured.
5. The MSI startup time is the time when the four MSIRCs are in power down.
6. This delay is the time to switch from one MSIRC to another one. In case the destination MSIRC is in power down, the total delay is $t_{su(MSI)} + t_{switch(MSI)}$.
7. The MSI is in continuous mode when the internal regulator is in voltage range 1, 2 or 3.
8. The MSI is in sampling mode when MSIBIAS = 1 in RCC_ICSCR1, and the regulator is in voltage range 4, or when the device is in Stop 1 or Stop 2 mode.
9. SMPS efficiency in range 1, based on V_{CORE} current = 19.4 mA.

High-speed internal 48 MHz (HSI48) RC oscillator

Table 76. HSI48 oscillator characteristics

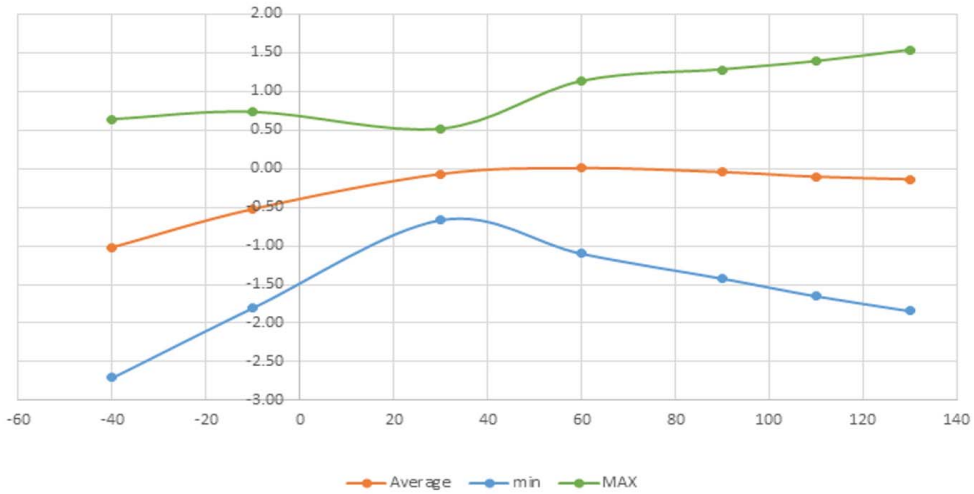
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{HSI48}	HSI48 frequency after factory calibration	V_{DD} = 3.0 V, T_J = 30 °C	47.5	48	48.5	MHz

Table 76. HSI48 oscillator characteristics (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$TRIM_{HSI48}$(1)	User trimming step	-	-	0.12	0.18	%
USER TRIM COVERAGE(2)	User trimming coverage	±63 steps	±4.5	±7.56	-	
$DuCy_{HSI48}$(1)	Duty cycle	-	45	-	55	
ACC_{HSI48_REL}(2)	Accuracy of the HSI48 oscillator over temperature (factory calibrated) Reference is 3 V and 30 °C(3).	1.58 V ≤ V_{DD} ≤ 3.6 V, T_J = –40 to 125 °C	-3	-	2	
$\Delta_{VDD(HSI48)}$(1)	HSI48 frequency drift with V_{DD}(4)	3.0 V ≤ V_{DD} ≤ 3.6 V	-	0.025	0.05	
		1.58 V ≤ V_{DD} ≤ 3.6 V	-	0.05	0.1	
N_T jitter(1)	Next transition jitter Accumulated jitter on 28 cycles(5)	-	-	±0.15	-	ns
P_T jitter(1)	Paired transition jitter Accumulated jitter on 56 cycles(5)	-	-	±0.25	-	
$t_{su(HSI48)}$(1)	HSI48 oscillator startup time	-	-	2.5	6	µs
$I_{DD(HSI48)}$(1)	HSI48 oscillator power consumption	-	-	350	400	µA

1. Specified by design. Not tested in production.
2. Evaluated by characterization. Not tested in production.
3. $\Delta f_{HSI} = ACC_{HSI48_REL} + \Delta V_{DD}$.
4. These values are obtained with one of the following formula: (Freq(3.6 V) - Freq(3.0 V)) / Freq(3.0 V) or (Freq(3.6 V) - Freq(1.58 V)) / Freq(1.58 V).
5. Jitter measurements are performed without clock source activated in parallel.

Figure 34. HSI48 frequency versus temperature



Secure high-speed internal (SHSI) RC oscillator

Table 77. SHSI oscillator characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{SHSI}	SHSI frequency	-	-	48	-	MHz
$t_{SU(SHSI)}$	SHSI oscillator startup time	-	-	2.5	6	µs
$I_{DD(SHSI)}$	SHSI oscillator power consumption	-	-	350	400	µA

1. Specified by design. Not tested in production.

Low-speed internal (LSI) RC oscillator

Table 78. LSI oscillator characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{LSI}	LSI frequency	V_{DD} = 3.0 V, T_J = 30 °C, LSIPREDIV = 0	31.4	-	32.6	kHz
		V_{DD} = 3.0 V, T_J = 30 °C, LSIPREDIV = 1	0.245	-	0.255	
		1.58 V≤ V_{DD} ≤ 3.6 V, T_J = –40 to 125 °C	30.4(1)	-	33.6(1)	
$DuCy_{LSI}$	LSI duty cycle	LSIPREDIV = 1	-	50	-	%
$t_{SU(LSI)}$(2)	LSI oscillator startup time	-	-	230	260	µs
$t_{STAB(LSI)}$(2)	LSI oscillator stabilization time	5% of final frequency	-	230	260	
$I_{DD(LSI)}$(2)	LSI oscillator power consumption	LSIPREDIV = 0	-	140	255	nA
		LSIPREDIV = 1	-	130	240	

1. Evaluated by characterization. Not tested in production.
2. Specified by design. Not tested in production.

5.3.10 PLL characteristics

The parameters given in the table below are derived from tests performed under temperature and V_{DD} supply voltage conditions summarized in *Table 33*.

Table 79. PLL characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{PLL_IN}	PLL input clock	-	4	-	16	MHz
	PLL input clock duty cycle	-	10	-	90	%
f_{PLL_OUT}	PLL P, Q, R output clock	Voltage scaling range 1	1	-	160(2)	MHz
		Voltage scaling range 2	1	-	110	
		Voltage scaling range 3	1	-	55	
f_{VCO_OUT}	PLL VCO output	Voltage scaling range 1, 2	128	-	544	
		Voltage scaling range 3	128	-	330	
		Duty cycle with division 1	40	-	60	%

Table 79. PLL characteristics(1) (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
t_{LOCK}(3)(4)	PLL lock time	Integer mode		-	25	50	µs
		Fractional mode		-	40	65	
Jitter	RMS cycle-to-cycle jitter	Integer mode, VCO = 544 MHz		-	20	-	±ps
		Fractional mode, VCO = 544 MHz		-	70	-	
	RMS period jitter	Integer mode, VCO = 544 MHz		-	35	-	
		Fractional mode, VCO = 544 MHz		-	45	-	
	Long-term jitter(5), f_{PLL_IN} = 8 MHz	Integer mode, VCO = 544 MHz		-	160	-	
		Fractional mode, VCO = 544 MHz		-	170	-	
$I_{DD(PLL)}$	PLL power consumption on V_{DD} with LDO	VCO freq = 160 MHz, 1 clock output	Range 1	-	370	-	µA
		VCO freq = 160 MHz, 3 clock outputs	Range 1	-	390	-	
		VCO freq = 200 MHz, 1 clock output	Range 1	-	460	-	
			Range 2	-	435	-	
			Range 3	-	410	-	
		VCO freq = 336 MHz, 1 clock output	Range 1	-	710	-	
		VCO freq = 544 MHz, 1 clock output	Range 1	-	1100	-	
$I_{DD(PLL)}$	PLL power consumption on V_{DD} with SMPS	VCO freq = 160 MHz, 1 clock output	Range 1, I_{VCORE}(6) = 19.4 mA	-	260	-	
		VCO freq = 160 MHz, 3 clock outputs	Range 1, I_{VCORE}(6) = 19.4 mA	-	270	-	
		VCO freq = 200 MHz, 1 clock output	Range 1, I_{VCORE}(6) = 19.4 mA	-	320	-	
			Range 2, I_{VCORE}(6) = 11.7 mA	-	300	-	
			Range 3, I_{VCORE}(6) = 5.74 mA	-	290	-	
		VCO freq = 336 MHz, 1 clock output	Range 1, I_{VCORE}(6) = 19.4 mA	-	470	-	
		VCO freq = 544 MHz, 1 clock output	Range 1, I_{VCORE}(6) = 19.4 mA	-	730	-	

1. Specified by design and not tested in production, unless otherwise specified.
2. PLL1 output Q and PLL2 output Q can be up to 200 MHz only when selected as OCTOSPI clock.
3. Evaluated by characterization. Not tested in production.
4. Lock time is the duration until PLLxRDY flag (2% of final frequency).
5. Measured on 5000 cycles.
6. SMPS efficiency based on CoreMark RUN current on V_{CORE} at max frequency of each voltage range.

5.3.11 Flash memory characteristics

Table 80. Flash memory characteristics(1)

Symbol	Parameter	Conditions	Typ	Max(2)	Unit
t_{prog}	128-bit programming time	Normal mode	118	119	µs
		Burst mode	47	48	
t_{prog_page}	One 8-Kbyte page programming time	f_{AHB} = 160 MHz, normal mode	60.2	-	ms
		f_{AHB} = 160 MHz, burst mode	24.5	-	
t_{prog_bank}	One 2-Mbyte bank programming time	f_{AHB} = 160 MHz, normal mode	15420	-	
		f_{AHB} = 160 MHz, burst mode	6280	-	
t_{ERASE}	One 8-Kbyte page erase time	10 k endurance cycles	1.5	2.4	
		100 k endurance cycles	1.7	3.4	
t_{ME}	Mass erase time (one bank)	10 k endurance cycles	220	616	
	Mass erase time (two banks)		440	1230	
I_{DD}(3)	Average consumption from V_{DD}	Write mode	2.1	-	mA
		Erase mode	1.3	-	
	Maximum current (peak)	Write mode	2.6	-	
		Erase mode	3.0	-	

1. Specified by design. Not tested in production.
2. Evaluated by characterization after cycling. Not tested in production.
3. Evaluated by characterization. Not tested in production.

Table 81. Flash memory endurance and data retention

Symbol	Parameter	Conditions		Min(1)	Unit
N_{END}	Endurance	Whole bank	T_A = –40 to 125 °C	10	kcycles
		Limited to 256 Kbytes per bank		100	
t_{RET}	Data retention	Whole bank	T_A = 85 °C after 1 kcycle(2)	30	Years
			T_A = 105 °C after 1 kcycle(2)	15	
			T_A = 125 °C after 1 kcycle(2)	10	
			T_A = 55 °C after 10 kcycle(2)	30	
			T_A = 85 °C after 10 kcycle(2)	15	
			T_A = 105 °C after 10 kcycle(2)	10	
		Limited to 256 Kbytes per bank	T_A = 55 °C after 100 kcycle(2)	30	
			T_A = 85 °C after 100 kcycle(2)	15	
			T_A = 105 °C after 100 kcycle(2)	10	

1. Evaluated by characterization. Not tested in production.
2. Cycling performed over the whole temperature range.

5.3.12 EMC characteristics

Susceptibility tests are performed on a sample basis during device characterization.

Functional EMS (electromagnetic susceptibility)

While a simple application is executed on the device (toggling two LEDs through the I/O ports), the device is stressed by two electromagnetic events until a failure occurs. The failure is indicated by the LEDs as follows:

- Electrostatic discharge (ESD) (positive and negative): applied to all device pins until a functional disturbance occurs. This test is compliant with the IEC 61000-4-2 standard.
- FTB (fast transient voltage burst) (positive and negative): applied to VDD and VSS pins through a 100 pF capacitor, until a functional disturbance occurs. This test is compliant with the IEC 61000-4-4 standard.

A device reset allows normal operations to be resumed.

The test results are given in the table below. They are based on the EMS levels and classes defined in application note *EMC design guide for STM8, STM32 and Legacy MCUs (*AN1709).

Table 82. EMS characteristics

Symbol	Parameter	Conditions	Level/ Class
V_{FESD}	Voltage limits to be applied on any I/O pin to induce a functional disturbance	V_{DD} = 3.3 V, T_A = +25 °C, f_{HCLK} = 160 MHz, TFBGA216 conforming to IEC 61000-4-2	3B
V_{EFTB}	Fast transient voltage burst limits to be applied through 100 pF on V_{DD} and V_{SS} pins to induce a functional disturbance	V_{DD} = 3.3 V, T_A = +25 °C, f_{HCLK} = 160 MHz, TFBGA216 conforming to IEC 61000-4-4	5A

Designing hardened software to avoid noise problems

The EMC characterization and optimization are performed at component level with a typical application environment and simplified MCU software. Note that good EMC performance is highly dependent on the user application and the software in particular.

Therefore it is recommended that the user applies EMC software optimization and prequalification tests in relation with the EMC level requested for the application.

Software recommendations

The software flowchart must include the management of runaway conditions such as:

- Corrupted program counter
- Unexpected reset
- Critical data corruption (control registers)

Prequalification trials

Most of the common failures (unexpected reset and program counter corruption) can be reproduced by manually forcing a low state on the NRST pin or the oscillator pins for 1 second.

To complete these trials, ESD stress can be applied directly on the device, over the range of specification values. When unexpected behavior is detected, the software can be hardened

to prevent unrecoverable errors occurring. See application note *Software techniques for improving microcontrollers EMC performance* (AN1015) for more details.

Electromagnetic Interference (EMI)

The electromagnetic field emitted by the device is monitored while a simple application is executed (toggling two LEDs through the I/O ports). This emission test is compliant with IEC 61967-2 standard that specifies the test board and the pin loading.

Table 83. EMI characteristics (for f_{HSE} = 8 MHz, f_{HCLK} = 160 MHz)

Symbol	Parameter	Conditions	Monitored frequency band	Value	Unit
S_{EMI}	Peak(1)	V_{DD} = 3.6 V, T_A = 25 °C, TFBGA216 package compliant with IEC 61967-2	0.1 MHz to 30 MHz	4	dBµV
			30 MHz to 130 MHz	11	
			130 MHz to 1 GHz	13	
			1 GHz to 2 GHz	9	
	Level(2)		0.1 MHz to 2 GHz	2.5	-

1. Refer to the ‘EMI radiated test’ section of the application note *EMC design guide for STM8, STM32 and legacy MCUs* (AN1709).
2. Refer to the ‘EMI level classification’ section of the same application note AN1709.

5.3.13 Electrical sensitivity characteristics

Based on three different tests (ESD, latch-up) using specific measurement methods, the device is stressed in order to determine its performance in terms of electrical sensitivity.

Electrostatic discharge (ESD)

Electrostatic discharges (a positive then a negative pulse separated by 1 second) are applied to the pins of each sample according to each pin combination. The sample size depends on the number of supply pins in the device (3 parts × (n+1) supply pins). This test conforms to the ANSI/JEDEC standard.

Table 84. ESD absolute maximum ratings

Symbol	Ratings	Conditions	Packages	Class	Max. value(1)	Unit
$V_{ESD(HBM)}$	Electrostatic discharge voltage (human body model)	T_A = +25 °C, conforming to ANSI/ESDA/JEDEC JS-001	All	2	2000	V
$V_{ESD(CDM)}$	Electrostatic discharge voltage (charge device model)	T_A = +25 °C, conforming to ANSI/ESDA/JEDEC JS-002	LQFP64	C2a	500	
			LPQF100	C1	250	
			LQFP144	C1	250	
			UFBGA132	C2b	750	
			WLCSP150	C1	250	
			TFBGA169	C2b	750	
			WLCSP208	C1	250	
			TFBGA216	C2a	500	

1. Evaluated by characterization. Not tested in production.

Static latch-up

The following complementary static tests are required on three parts to assess the latch-up performance:

- A supply overvoltage is applied to each power supply pin.
- A current injection is applied to each input, output and configurable I/O pin.

These tests are compliant with EIA/JESD 78E IC latch-up standard.

Table 85. Electrical sensitivities(1)

Symbol	Parameter	Conditions	Class
LU	Static latch-up class	T_J = 130 °C conforming to JESD78E	Class II level A

1. Evaluated by characterization. Not tested in production.

5.3.14 I/O current injection characteristics

As a general rule, the current injection to the I/O pins, due to external voltage below V_{SS} or above V_{DDIOx} (for standard, 3.3 V-capable I/O pins) must be avoided during normal product operation. However, in order to give an indication of the robustness of the microcontroller if abnormal injection accidentally happens, some susceptibility tests are performed on a sample basis during the device characterization.

Functional susceptibility to I/O current injection

While a simple application is executed on the device, the device is stressed by injecting current into the I/O pins programmed in floating-input mode. While this current is injected into the I/O pin, one at a time, the device is checked for functional failures.

The failure is indicated by an out-of-range parameter, such as an ADC error above a certain limit (higher than 5 LSB TUE), out of conventional limits of induced leakage current on adjacent pins (out of the -5 µA/+0 µA range), or other functional failure (for example reset occurrence or oscillator frequency deviation).

The characterization results are given in the table below. The negative induced leakage current is caused by the negative injection.The positive induced leakage current is caused by the positive injection.

Table 86. I/O current injection susceptibility(1)(2)

Symbol	Description	Functional susceptibility		Unit
		Negative injection	Positive injection	
I_{INJ}	Injected current on all pins except TT_a, PA4, PA5, DSI_DN_DL1, DSI_DP_DL1, DSI_DN_CL1, DSI_DP_CL1, DSI_DN_DL2, DSI_DP_DL2, OPAMP1_VINM, OPAMP2_VINM, PA11, PA12, PE11, PE12, PE7,PB14, PB5, PA1	5	NA	mA
	Injected current on TT_a, PA4, PA5, DSI_DN_DL1, DSI_DP_DL1, DSI_DN_CL1, DSI_DP_CL1, DSI_DN_DL2, DSI_DP_DL2, OPAMP1_VINM, OPAMP2_VINM, PA11, PA12 pins	0	0	
	Injected current on PE11, PE12, PE7 pins	0	NA	
	Injected current on PB14, PB5, PA1 pins	5	0	

1. Evaluated by characterization. Not tested in production.
2. The I/O structure options listed in this table can be a concatenation of options including the option explicitly listed. For instance TT_a refers to any TT I/O with _a option. TT_xx refers to any TT I/O and FT_xx refers to any FT I/O.

5.3.15 I/O port characteristics

General input/output characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the conditions summarized in *Table 33*. All I/Os are designed as CMOS -and TTL-compliant.

Note: For information on GPIO configuration, refer to the application note 'STM32 GPIO configuration for hardware settings and low-power consumption' (AN4899).

Table 87. I/O static characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{IL}(2)	I/O input low-level voltage	1.08 V ≤ V_{DDIOx} ≤ 3.6 V	-	-	0.3 V_{DDIOx}	V
		All I/Os except FT_c	-	-	0.38 V_{DDIOx}(3)	
		FT_c I/Os	-	-	0.3 V_{DDIOx}	
V_{IH} (2)	I/O input high-level voltage	1.08 V ≤ V_{DDIOx} ≤ 3.6 V	0.7 V_{DDIOx}	-	-	
		All I/Os except FT_c	0.5 V_{DDIOx} + 0.2(3)	-	-	
		FT_c I/Os	0.7 V_{DDIOx}	-	-	
V_{hys} (3)	Input hysteresis	TT_xx, FT_xx I/Os	-	250	-	mV

Table 87. I/O static characteristics(1) (continued)

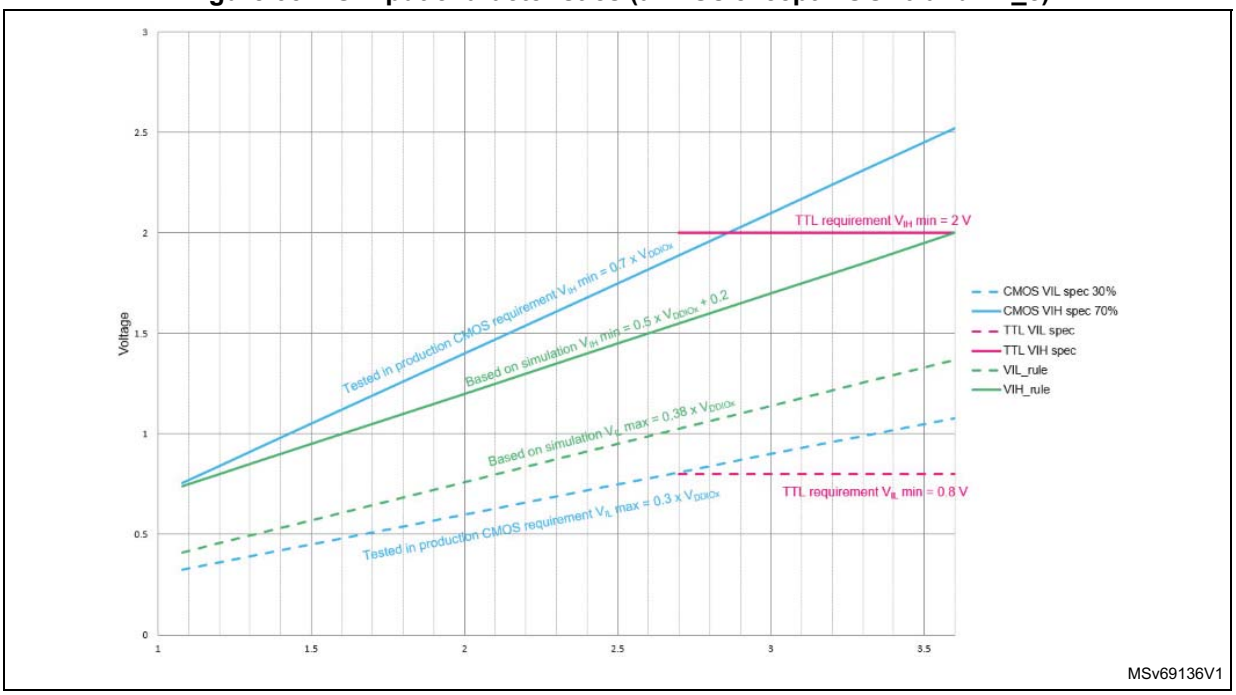
Symbol	Parameter	Conditions		Min	Typ	Max	Unit
I_{lkg} (3)(4)	Input leakage current	All I/Os except FT_c, FT_d, FT_o, FT_t, FT_u,TT_xx	$V_{IN} \le$ Max (V_{DDXXX})(5)	-	-	150	nA
			Max (V_{DDXXX}) < V_{IN} ≤ Max (V_{DDXXX}) + 1 V(6)	-	-	2000	
			Max (V_{DDXXX}) + 1 V < V_{IN} ≤ 5.5 V(6)	-	-	500	
		FT_c I/Os	$V_{IN} \le$ Max (V_{DDXXX})(5)	-	-	1500	
			Max (V_{DDXXX}) < $V_{IN} \le$ 5 V(6)	-	-	2000	
		FT_d I/Os	$V_{IN} \le$ Max (V_{DDXXX})(5)	-	-	1500	
			Max (V_{DDXXX}) < $V_{IN} \le$ 5.5 V(6)	-	-	5000	
		FT_o I/Os	$V_{IN} \le$ Max (V_{DDXXX})(5)	-	-	50	
			Max (V_{DDXXX}) < V_{IN} ≤ Max (V_{DDXXX}) + 1 V(6)	-	-	500	
			Max (V_{DDXXX}) + 1 V < V_{IN} ≤ 5.5 V(6)	-	-	200	
		FT_u I/Os	$V_{IN} \le$ Max (V_{DDXXX})(5)	-	-	200	
			Max (V_{DDXXX}) < V_{IN} ≤ Max (V_{DDXXX}) + 1 V(6)	-	-	2500	
			Max (V_{DDXXX}) + 1 V < V_{IN} ≤ 5.5 V(6)	-	-	500	
		FT_t I/Os	$V_{IN} \le$ Max (V_{DDXXX})(5)	-	-	300	
			Max (V_{DDXXX}) < V_{IN} ≤ Max (V_{DDXXX}) + 1 V(6)	-	-	3000	
			Max (V_{DDXXX}) + 1 V < V_{IN} ≤ 5.5 V(6)	-	-	600	
I_{lkg} (3)(4)	Input leakage current	TT_xx I/Os except OPAMPx_VINM (x = 1, 2)	$V_{IN} \le$ Max (V_{DDXXX})(5)	-	-	500	
		OPAMPx_VINM (x = 1, 2) dedicated input leakage current		-	-	(7)	
R_{PU}	Weak pull-up equivalent	-		30	40	50	kΩ
R_{PD}	Weak pull-down equivalent resistor(8)	-		30	40	50	
C_{IO}	I/O pin capacitance	-		-	5	-	pF

1. The I/O structure options listed in this table can be a concatenation of options including the option explicitly listed. For instance TT_a refers to any TT I/O with _a option. TT_xx refers to any TT I/O and FT_xx refers to any FT I/O.

2. Refer to *Figure 35: I/O input characteristics (all I/Os except BOOT0 and FT_c)*.
3. Specified by design. Not tested in production.
4. This parameter represents the pad leakage of the I/O itself. The total product pad leakage is provided by the following formula: $I_{Total_Ileak_max}$ = 10 µA + [number of I/Os where VIN is applied on the pad] x I_{lkg} max.
5. Max (V_{DDXXX}) is the maximum value of all the I/O supplies. The I/O supplies depend on the I/O structure options, as described in *Table 26: Legend/abbreviations used in the pinout table*.
6. To sustain a voltage higher than Min (V_{DD}, V_{DDA}, V_{DDUSB}, V_{DDIO2}) +0.3 V, the internal pull-up and pull-down resistors must be disabled.
7. Refer to I_{bias} in the OPAMP characteristics table for the values of the OPAMP dedicated input leakage current.
8. The pull-up and pull-down resistors are designed with a true resistance in series with a switchable PMOS/NMOS. This PMOS/NMOS contribution to the series resistance is minimal (~10% order).

All I/Os are CMOS- and TTL-compliant (no software configuration required). Their characteristics cover more than the strict CMOS-technology or TTL parameters. The coverage of these requirements is shown in the figure below.

Figure 35. I/O input characteristics (all I/Os except BOOT0 and FT_c)



Output driving current

The GPIOs (except PC13, PC14, PC15) can sink or source up to ±8 mA, and sink or source up to ± 20 mA (with a relaxed V_{OL}/V_{OH}). PC13, PC14, PC15 are limited in source capability: +3 mA shared between the three I/Os. These GPIOs have the same sink capability than other GPIOs.

In the user application, the number of I/O pins tat can drive current must be limited to respect the absolute maximum rating specified in *Section 5.2: Absolute maximum ratings*:

- The sum of the currents sourced by all the I/Os on $V_{DDIOx,}$ plus the maximum consumption of the MCU sourced on $V_{DD,}$ cannot exceed the absolute maximum rating ΣI_{VDD} (see *Table 31: Current characteristics*).
- The sum of the currents sunk by all the I/Os on V_{SS}, plus the maximum consumption of the MCU sunk on V_{SS}, cannot exceed the absolute maximum rating ΣI_{VSS} (see *Table 31: Current characteristics*).

Output voltage levels

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature and supply voltage conditions summarized in *Table 33*. All I/Os are CMOS- and TTL-compliant (FT OR TT unless otherwise specified).

Table 88. Output voltage characteristics (all I/Os except FT_t I/Os in V_{BAT} mode(1), and FT_o I/Os)(2)(3)

Symbol	Parameter	Conditions	Min	Max	Unit
V_{OL}	Output low-level voltage	CMOS port(4), $\|I_{IO}\|$ = 8 mA, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	0.4	V
V_{OH}	Output high-level voltage		V_{DDIOx} - 0.4	-	
V_{OL}(5)	Output low-level voltage	TTL port(4),$\|I_{IO}\|$ = 8 mA, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	0.4	
V_{OH}(5)	Output high-level voltage		2.4	-	
V_{OL}(5)	Output low-level voltage	All I/Os, $\|I_{IO}\|$ = 20 mA, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	1.3	
V_{OH}(5)	Output high-level voltage		V_{DDIOx} - 1.3	-	
V_{OL}(5)	Output low-level voltage	$\|I_{IO}\|$ = 4 mA, 1.58 V ≤ V_{DDIOx} ≤ 3.6 V	-	0.4	
V_{OH}(5)	Output high-level voltage		V_{DDIOx} - 0.4	-	
V_{OL}(5)	Output low-level voltage	$\|I_{IO}\|$ = 1 mA, 1.08 V ≤ V_{DDIOx} <3.6 V	-	0.4	
V_{OH}(5)	Output high-level voltage		V_{DDIOx} - 0.4	-	
V_{OLFM+}(5)	Output low-level voltage for a FT_f I/O pin in FM+ mode	$\|I_{IO}\|$ = 20 mA, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	0.4	
		$\|I_{IO}\|$ = 10 mA, 1.58 V ≤ V_{DDIOx} ≤ 3.6 V	-	0.4	
		$\|I_{IO}\|$ = 2 mA, 1.08 V ≤ V_{DDIOx} < 3.6 V	-	0.4	

1. FT_t I/O characteristics are degraded only in V_{BAT} mode (refer to *Table 89*).
2. The I/O structure options listed in this table can be a concatenation of options including the option explicitly listed. For instance TT_a refers to any TT I/O with _a option. TT_xx refers to any TT I/O and FT_xx refers to any FT I/O.
3. The I_{IO} current sourced or sunk by the device must always respect the absolute maximum rating specified in *Table 31: Current characteristics*, and the sum of the currents sourced or sunk by all the I/Os (I/O ports and control pins) must always respect the absolute maximum ratings ΣI_{IO}.
4. TTL and CMOS outputs are compatible with JEDEC standards JESD36 and JESD52.
5. Specified by design. Not tested in production.

Table 89. Output voltage characteristics for FT_t I/Os in V_{BAT} mode, and for FT_o I/Os(1)

Symbol	Parameter	Conditions	Min	Max	Unit
V_{OL}	Output low-level voltage	$\|I_{IO}\|$ = 0.5 mA, 2.7 V ≤ V_{SW} ≤ 3.6 V	-	0.4	V
V_{OH}	Output high-level voltage		V_{SW} - 0.4	-	
V_{OL}	Output low-level voltage	$\|I_{IO}\|$ = 0.25 mA, 1.58 V ≤ V_{SW}≤ 3.6 V	-	0.4	
V_{OH}	Output high-level voltage		V_{SW} - 0.4	-	

1. Specified by design. Not tested in production.

Output AC characteristics

The definition and values of output AC characteristics are given in *Figure 36: Output AC characteristics definition* and in the table below respectively.

Unless otherwise specified, the parameters given are derived from tests performed under the ambient temperature and supply voltage conditions summarized in *Table 33*.

Table 90. Output AC characteristics, HSLV OFF (all I/Os except FT_c, FT_t in V_{BAT} mode(1), and FT_o I/Os)(2)(3)(4)

Speed	Symbol	Parameter	Conditions	Min	Max	Unit
00	Fmax	Maximum frequency all I/Os	C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	12.5	MHz
			C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	5	
			C_L = 50 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	1	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	12.5	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	5	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	1	
	t_r/t_f	Output rise and fall time all I/Os	C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	17	ns
			C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	33	
			C_L = 50 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	85	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	12.5	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	25	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	50	

Table 90. Output AC characteristics, HSLV OFF (all I/Os except FT_c, FT_t in V_{BAT} mode[1], and FT_o I/Os)[2][3][4] (continued)

Speed	Symbol	Parameter	Conditions	Min	Max	Unit
01	Fmax	Maximum frequency all I/Os	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	55	MHz
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	12.5	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	2.5	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	55	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	12.5	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} ≤<1.58 V	-	2.5	
	t_r/t_f	Output rise and fall time all I/Os	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	5.8	ns
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	10	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	18	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	4.2	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	7.5	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	12	
10	Fmax	Maximum frequency all I/Os	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	100[5]	MHz
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	33[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	5	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	133[5]	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	40[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	5	
	t_r/t_f	Output rise and fall time all I/Os	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	3.3[5]	ns
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	6.0[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	13.3	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	2[5]	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	4.1[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	9.2	
11	Fmax	Maximum frequency All I/Os except FT_c, FT_v, and TT_v	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	100[5]	MHz
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	33[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	5	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	133[5]	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	40[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	5	

Table 90. Output AC characteristics, HSLV OFF (all I/Os except FT_c, FT_t in V_{BAT} mode[1], and FT_o I/Os)[2][3][4] (continued)

Speed	Symbol	Parameter	Conditions	Min	Max	Unit
11 (cont'd)	Fmax	Maximum frequency FT_v and TT_v I/Os	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	140[5]	MHz
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	40[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	5	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	166[5]	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	50[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	5	
	t_r/t_f	Output rise and fall time All I/Os except FT_c, FT_v, and TT_v	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	3.3[5]	ns
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	6.0[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	13.3	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	2.0[5]	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	4.1[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	9.2	
	t_r/t_f	Output rise and fall time FT_v and TT_v I/Os	C_L = 30 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	2.5[5]	
			C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	5.0[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	11	
			C_L = 10 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	1.66[5]	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	3.1[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	7	
Fm+	Fmax	Maximum frequency	C_L = 550 pF, 1.08 V ≤ V_{DDIOx} < 3.6 V	-	1	MHz
	t_f	Output fall time[6]	C_L = 100 pF, 1.58 V ≤ V_{DDIOx} < 3.6 V	-	50	ns
			C_L = 100 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	80	
			C_L = 550 pF, 1.58 V ≤ V_{DDIOx} < 3.6 V	-	100	
			C_L = 550 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	220	

1. FT_t I/O characteristics are degraded only in V_{BAT} mode (refer to *Table 93*).
2. The I/O structure options listed in this table can be a concatenation of options including the option explicitly listed. For instance TT_a refers to any TT I/O with _a option. TT_xx refers to any TT I/O and FT_xx refers to any FT I/O.
3. The I/O speed is configured using the OSPEEDRy[1:0] bits. Refer to the product reference manual for a description of GPIO port configuration register.
4. Specified by design. Not tested in production.
5. Compensation system enabled.
6. The fall time is defined between 70% and 30% of the output waveform accordingly to I^2C specification.

Table 91. Output AC characteristics, HSLV ON (all I/Os except FT_c, FT_t in V_{BAT} mode[1], and FT_o I/Os)[2][3][4]

Speed	Symbol	Parameter	Conditions	Min	Max	Unit
00	Fmax	Maximum frequency	C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	10	MHz
			C_L = 50 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	4	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	15	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	4	
	t_r/t_f	Output rise and fall time	C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	18	ns
			C_L = 50 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	32	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	12	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	21	
01	Fmax	Maximum frequency	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	50	MHz
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	10	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	67	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	10	
	t_r/t_f	Output rise and fall time	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	5.3	ns
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	10.6	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	3.1	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	5.6	
10	Fmax	Maximum frequency	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	75[5]	MHz
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	15	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	100[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	15	
	t_r/t_f	Output rise and fall time	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	4.4[5]	ns
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	9.6	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	2.2[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	4.7	

Table 91. Output AC characteristics, HSLV ON (all I/Os except FT_c, FT_t in V_{BAT} mode[1], and FT_o I/Os)[2][3][4] (continued)

Speed	Symbol	Parameter	Conditions	Min	Max	Unit
11	Fmax	Maximum frequency All I/Os except FT_c, FT_v, and TT_v	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	75[5]	MHz
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	15	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	100[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	15	
		Maximum frequency FT_v and TT_v I/Os	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	110[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	25	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	150[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	25	
	t_r/t_f	Output rise and fall time All I/Os except FT_c, FT_v, and TT_v	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	4.4[5]	ns
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	9.6	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V		2.2[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V		4.7	
		Output rise and fall time FT_v and TT_v I/Os	C_L = 30 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	3.0[5]	
			C_L = 30 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	6.6	
			C_L = 10 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V		1.6[5]	
			C_L = 10 pF, 1.08 V ≤ V_{DDIOx} < 1.58 V	-	3.4	

1. FT_t I/O characteristics are degraded only in V_{BAT} mode (refer to *Table 93*).
2. The I/O structure options listed in this table can be a concatenation of options including the option explicitly listed. For instance TT_a refers to any TT I/O with _a option. TT_xx refers to any TT I/O and FT_xx refers to any FT I/O.
3. The I/O speed is configured using the OSPEEDRy[1:0] bits. Refer to the product reference manual for a description of GPIO port configuration register.
4. Specified by design. Not tested in production.
5. Compensation system enabled.

Table 92. Output AC characteristics for FT_c I/Os[1][2]

Speed	Symbol	Parameter	Conditions	Min	Max	Unit
00	Fmax	Maximum frequency	All I/Os, C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	10	MHz
			All I/Os, C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	5	
	t_r/t_f	Output rise and fall time	All I/Os, C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	33	ns
			All I/Os, C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	66	
01	Fmax	Maximum frequency	All I/Os, C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	25	MHz
			All I/Os, C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	10	
	t_r/t_f	Output rise and fall time	All I/Os, C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	13	ns
			All I/Os, C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	33	

Table 92. Output AC characteristics for FT_c I/Os(1)(2) (continued)

Speed	Symbol	Parameter	Conditions	Min	Max	Unit
1x	Fmax	Maximum frequency	All I/Os, C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	40	MHz
			All I/Os, C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	20	
	t_r/t_f	Output rise and fall time	All I/Os, C_L = 50 pF, 2.7 V ≤ V_{DDIOx} ≤ 3.6 V	-	8	ns
			All I/Os, C_L = 50 pF, 1.58 V ≤ V_{DDIOx} < 2.7 V	-	17	

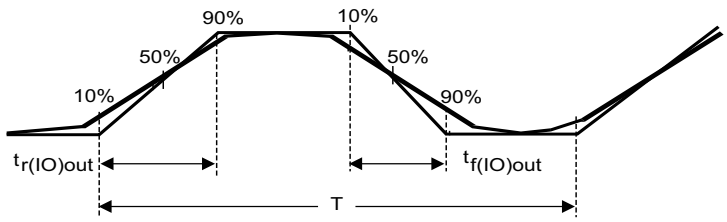
1. Specified by design. Not tested in production.
2. The I/O speed is configured using the OSPEEDRy[1:0] bits. Refer to the product reference manual for a description of GPIO port configuration register.

Table 93. Output AC characteristics for FT_t I/Os in V_{BAT} mode, and for FT_o I/Os(1)

Symbol	Parameter	Conditions	Min	Max	Unit
Fmax	Maximum frequency	C_L = 50 pF, 2.7 V ≤ V_{SW} ≤ 3.6 V	-	0.5	MHz
		C_L = 50 pF, 1.58 V ≤ V_{SW} < 2.7 V	-	0.25	
t_r/t_f	Output rise and fall time	C_L = 50 pF, 2.7 V ≤ V_{SW} ≤ 3.6 V	-	400	ns
		C_L = 50 pF, 1.58 V ≤ V_{SW} < 2.7 V	-	900	

1. Specified by design. Not tested in production.

Figure 36. Output AC characteristics definition



Maximum frequency is achieved with a duty cycle at (45 - 55%) when loaded by the specified capacitance.

MS32132V4

5.3.16 NRST pin characteristics

The NRST pin input driver uses the CMOS technology. It is connected to a permanent pull-up resistor, R_{PU}.

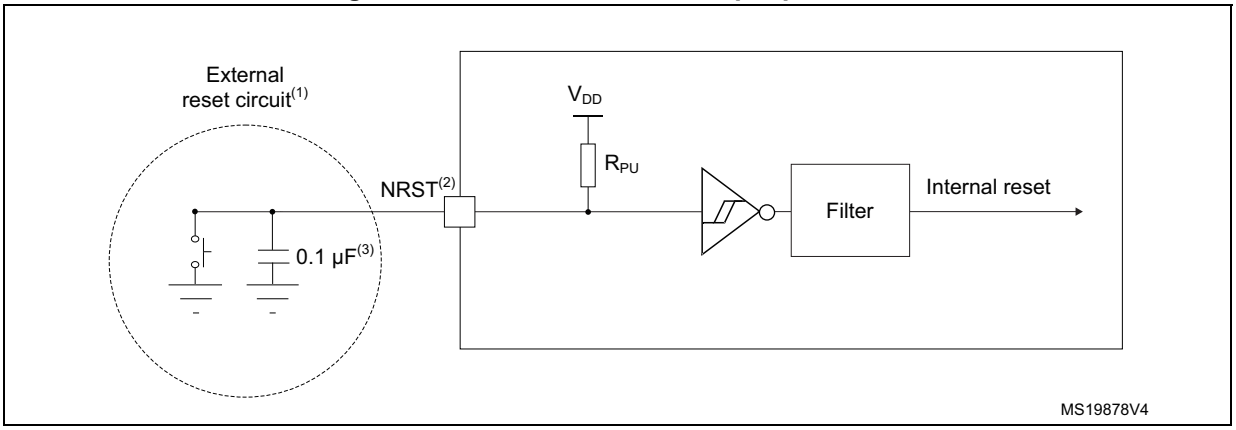
Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature and supply voltage conditions summarized in *Table 33*.

Table 94. NRST pin characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IL(NRST)}$	NRST input low-level voltage	-	-	-	$0.3 \times V_{DDIOx}$	V
$V_{IH(NRST)}$	NRST input high-level voltage	-	$0.7 \times V_{DDIOx}$	-	-	
$V_{hys(NRST)}$	NRST Schmitt trigger voltage hysteresis	-	-	200	-	mV
R_{PU}	Weak pull-up equivalent resistor(2)	$V_{IN} = V_{SS}$	30	40	50	kΩ
$t_{F(NRST)}$	NRST input filtered pulse	-	-	-	50	ns
$t_{NF(NRST)}$	NRST input not-filtered pulse	$1.71\ V \le V_{DD} \le 3.6\ V$	330	-	-	
		$1.58\ V \le V_{DD} \le 3.6\ V$	1000	-	-	

1. Specified by design. Not tested in production.
2. The pull-up is designed with a true resistance in series with a switchable PMOS. This PMOS contribution to the series resistance is minimal (~10% order).

Figure 37. Recommended NRST pin protection



1. The reset network protects the device against parasitic resets.
2. The user must ensure that the level on the NRST pin can go below the $V_{IL(NRST)}$ max level specified in the above table. Otherwise the reset is not taken into account by the device.
3. The external capacitor on NRST must be placed as close as possible to the device.

5.3.17 Extended interrupt and event controller input (EXTI) characteristics

The pulse on the interrupt input must have a minimal length in order to guarantee that it is detected by the event controller.

Table 95. EXTI input characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
PLEC	Pulse length to event controller	-	20	-	-	ns

1. Specified by design. Not tested in production.

5.3.18 Analog switches booster

Table 96. Analog switches booster characteristics(1)

Symbol	Parameter	Min	Typ	Max	Unit
V_{DD}	Supply voltage	1.6	1.8	3.6	V
$t_{SU(BOOST)}$	Booster startup time	-	-	50	µs
$I_{DD(BOOST)}$	Booster consumption	-	-	125	µA

1. Specified by design. Not tested in production.

5.3.19 14-bit analog-to-digital converter (ADC12) characteristics

Unless otherwise specified, the parameters given in the table below are values derived from tests performed under ambient temperature, f_{HCLK} frequency and V_{DDA} supply voltage conditions summarized in *Table 33*.

Note: It is recommended to perform a calibration after each power-up.

Table 97. 14-bit ADC12 characteristics(1)(2)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog power supply for ADC ON	-	1.62	-	3.6	V
V_{REF+}	Positive reference voltage	$V_{DDA} \geq 2$ V	2	-	V_{DDA}	
		$V_{DDA} < 2$ V	V_{DDA}			
V_{REF-}	Negative reference voltage	-	V_{SSA}			
f_{ADC}	ADC clock frequency	1.62 V ≤ V_{DDA} ≤ 3.6 V	5(3)	-	55	MHz
	ADC clock ratio	-	45	-	55	%
f_s	Sampling rate	Resolution = 14 bits	0.23	-	2.5	Msps
		Resolution = 12 bits	0.25	-	2.75	
		Resolution = 10 bits	0.28	-	3.05	
		Resolution = 8 bits	0.31	-	3.44	
t_{TRIG}	External trigger period	Resolution = 14 bits	26	-	-	$1/f_{ADC}$
V_{AIN}(4)	Conversion voltage range	-	0	-	V_{REF+}	V

Table 97. 14-bit ADC12 characteristics(1)(2) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{CIMV}	Common mode input voltage	-	V_{REF+}/2 - 10%	V_{REF+}/2	V_{REF+}/2 + 10%	V
R_{AIN}(5)	External input impedance	Resolution = 14 bits T_j = 130 °C	-	-	1000	Ω
		Resolution = 12 bits T_j = 130 °C	-	-	1000	
		Resolution = 10 bits T_j = 130 °C	-	-	4700	
		Resolution = 8 bits T_j = 130 °C	-	-	22000	
C_{ADC}	Internal sample-and-hold capacitor	-	-	5	-	pF
$t_{ADCVREG_STUP}$	ADC LDO startup time	-	-	-	17	µs
t_{STAB}	ADC power-up time	LDO already started	(3 × 1/f_{ADC}) + 1 conversion			Cycle
t_{CAL}	Offset and linearity calibration time	-	31849			1/f_{ADC}
t_{OFF_CAL}	Offset calibration time	-	885			
t_{LATR}	Trigger conversion latency for regular and injected channels, without aborting the conversion	PRESC = 0	3			
		PRESC = 1	7			
		PRESC = 2	13			
$t_{LATRINJ}$	Trigger conversion latency Injected channels aborting a regular conversion	PRESC = 0	4			
		PRESC = 1	9			
		PRESC = 2	17			
t_s	Sampling time	-	5	-	814	
t_{CONV}	Total conversion time (including sampling time)	Resolution = N bits	t_s + N + 3			

Table 97. 14-bit ADC12 characteristics(1)(2) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DDA_D(ADC)}$	ADC consumption on V_{DDA} Differential mode	f_s = 2.5 Msps, resolution = 14 bits	-	970	-	µA
		f_s = 1 Msps, resolution = 14 bits	-	550	-	
		f_s = 10 ksps, resolution = 14 bits	-	130	-	
		f_s = 2.5 Msps, resolution = 12 bits	-	940	-	
		f_s = 2.5 Msps, resolution = 10 bits	-	840	-	
		f_s = 2.5 Msps, resolution = 8bits	-	730	-	
$I_{DDV_D(ADC)}$	ADC consumption on V_{REF+} Differential mode	f_s = 2.5 Msps, resolution = 14 bits	-	140	-	
		f_s = 1 Msps, resolution = 14 bits	-	80	-	
		f_s = 10 ksps, resolution = 14 bits	-	13	-	
		f_s = 2.5 Msps, resolution = 12 bits	-	140	-	
		f_s = 2.5 Msps, resolution = 10 bits	-	140	-	
		f_s = 2.5 Msps, resolution = 8bits	-	120	-	
$I_{DDA_s(ADC)}$	ADC consumption on V_{DDA} Singe-ended mode	f_s = 2.5 Msps, resolution = 14 bits	-	980	-	
		f_s = 1 Msps, resolution = 14 bits	-	550	-	
		f_s = 10 ksps, resolution = 14 bits	-	130	-	
		f_s = 2.5 Msps, resolution = 12 bits	-	900	-	
		f_s = 2.5 Msps, resolution = 10 bits	-	840	-	
		f_s = 2.5 Msps, resolution = 8bits	-	770	-	

Table 97. 14-bit ADC12 characteristics(1)(2) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DDV_s(ADC)}$	ADC consumption on V_{REF+} Single-ended mode	f_s = 2.5 Msps, resolution = 14 bits	-	160	-	µA
		f_s = 1 Msps, resolution = 14 bits	-	90	-	
		f_s = 10 ksps, resolution = 14 bits	-	15	-	
		f_s = 2.5 Msps, resolution = 12 bits	-	150	-	
		f_s = 2.5 Msps, resolution = 10 bits	-	150	-	
		f_s = 2.5 Msps, resolution = 8bits	-	150	-	

1. Specified by design. Not tested in production.
2. The voltage booster on the ADC switches must be used when V_{DDA} < 2.4 V (embedded I/O switches).
3. Degraded differential linearity error below 10 MHz.
4. Depending on the package, V_{REF+} can be internally connected to V_{DDA} and V_{REF-} can be internally connected to V_{SSA}.
5. The maximum value of R_{ain} is specified to keep leakage induced offset within the specified tolerance. The tolerance is 4 LSBs for 14-bit resolution and 2 LSBs for 12-bit, 10-bit, and 8-bit resolutions.

The maximum value of R_{AIN} can be found in the table below.

Table 98. Maximum R_{AIN} for 14-bit ADC12(1)(2) (3)

Resolution(4)	R_{AIN} max (Ω)(5)	Sampling time [ns]	Sampling cycle at 5 MHz	Sampling cycle at 55 MHz
14 bits	47	142	5	12
	68	145		
	100	170		
12 bits	47	135		
	68	135		
	100	140		
	150	145		
	220	150		
	330	155		
	470	180		
10 bits	47	128		
	68	130		
	100	132		
	150	134		
	220	140		
	330	146		
	470	160		
	680	176		
	1000	200		
	1500	240		20
	2200	320		

Table 98. Maximum R_{AIN} for 14-bit ADC12(1)(2) (3) (continued)

Resolution(4)	R_{AIN} max (Ω)(5)	Sampling time [ns]	Sampling cycle at 5 MHz	Sampling cycle at 55 MHz
8 bits	47	123	5	12
	68	124		
	100	125		
	150	128		
	220	130		
	330	137		
	470	140		
	680	157		
	1000	178		
	1500	204		
	2200	250		20
	3300	313		
	4700	400		36
	6800	546		
	10000	830		68

1. Specified by design. Not tested in production.
2. BOOSTEN and ANASWVDD configured properly according to V_{DD} and V_{DDA} values.
3. Values without external capacitor.
4. The tolerance is 2 LSBs for 14 bits and 1 LSB for other resolutions.
5. The maximum value of R_{AIN} is obtained in a worst-case scenario: channel conversion in scan mode with channel i connected to V_{REF+} and channel i + 1 connected to V_{REF-}.

Table 99. 14-bit ADC12 accuracy(1)(2)(3)

Symbol	Parameter	Conditions(4)		Min	Typ	Max	Unit
ET	Total unadjusted error	Single ended		-	±6	±12	LSB
		Differential		-	±3	±6	
EO	Offset error	Single ended		-	±6	±12(5)	
		Differential		-	±2	±6(5)	
EG	Gain error	Single ended		-	±5	±10	
		Differential		-	±2.5	±5	
ED	Differential linearity error	Single ended	f_{ADC} ≥ 10 MHz	-	-0.9/+1.5	-0.9/+2.5	
		Differential		-			
		Single ended	f_{ADC} < 10 MHz	-	-0.9/+1.5	-1/+3	
		Differential		-			
EL	Integral linearity error	Single ended		-	±3	±7	
		Differential		-	±2	±5	

Table 99. 14-bit ADC12 accuracy(1)(2)(3) (continued)

Symbol	Parameter	Conditions(4)	Min	Typ	Max	Unit
ENOB	Effective number of bits	Single ended	11	12	-	bits
		Differential	11.8	12.8	-	
SINAD	Signal-to-noise and distortion ratio	Single ended	68	74	-	dB
		Differential	73	78	-	
SNR	Signal-to-noise ratio	Single ended	68	74	-	
		Differential	73	78	-	
THD	Total harmonic distortion	Single ended	-	-84	-80	
		Differential	-	-95	-89	

1. Evaluated by characterization for BGA packages. Not tested in production. The values for LQFP packages may differ.
2. ADC DC accuracy values are measured after the internal calibration.
3. Extended calibration mode activated.
4. The I/O analog switch voltage booster is enable when V_{DDA} < 2.4 V (BOOSTEN = 1 in SYSCFG_CFGR1 when V_{DDA} < 2.4 V). The booster is disabled when V_{DDA} ≥ 2.4 V. Resolution = 14 bits, no oversampling.
5. This parameter may degrade in case of digital activity on adjacent I/Os.

Figure 38. ADC accuracy characteristics

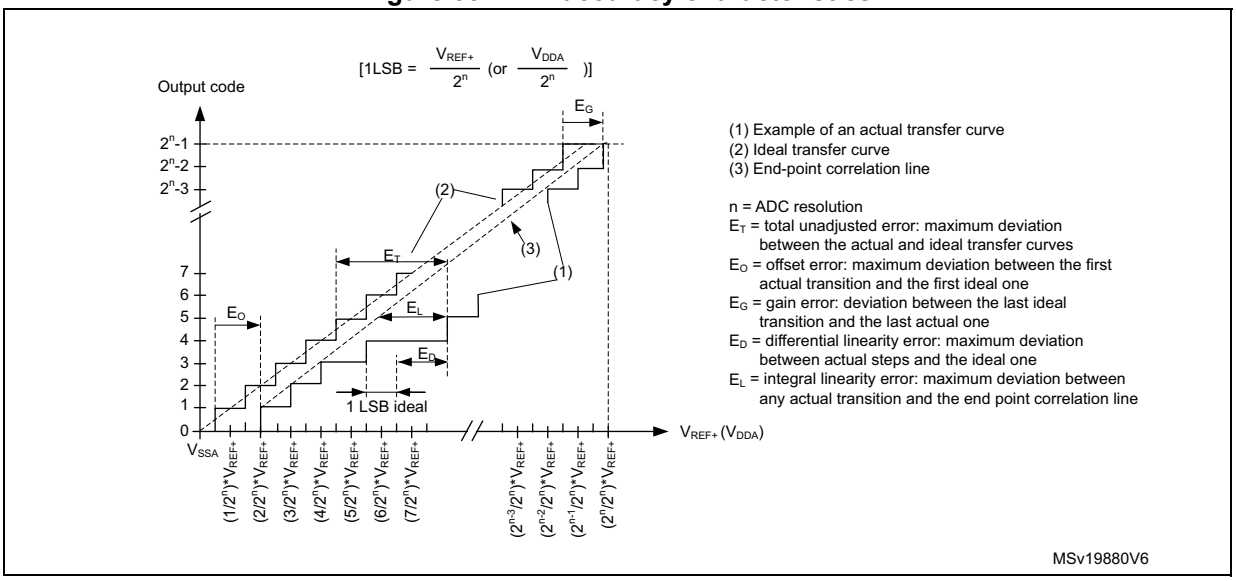
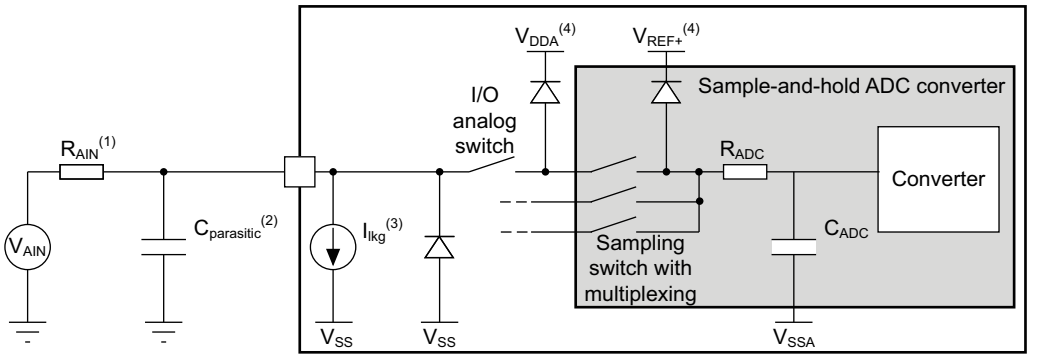


Figure 39. Typical connection diagram when using the ADC with FT/TT pins featuring analog switch function



1. Refer to the ADCx characteristic table for the values of R_{AIN} and C_{ADC}.
2. $C_{parasitic}$ represents the capacitance of the PCB (dependent on soldering and PCB layout quality) plus the pad capacitance (refer to *Table 87: I/O static characteristics* for the value of the pad capacitance). A high $C_{parasitic}$ value downgrades the conversion accuracy. To remedy this, f_{ADC} must be reduced.
3. Refer to *Table 87: I/O static characteristics* for the values of I_{lkg}.
4. Refer to *Section 5.1.6: Power supply scheme*.

General PCB design guidelines

The power-supply decoupling must be performed as shown in the corresponding power-supply scheme. The 100 nF capacitor must be ceramic (good quality) and must be placed as close as possible to the chip.

5.3.20 12-bit analog-to-digital converter (ADC4) characteristics

Unless otherwise specified, the parameters given in the table below are values derived from tests performed under ambient temperature, f_{HCLK} frequency and V_{DDA} supply voltage conditions summarized in *Table 33*.

Note: It is recommended to perform a calibration after each power-up.

Table 100. 12-bit ADC4 characteristics(1)(2)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog power supply for ADC ON	-	1.62	-	3.6	V
V_{REF+}	Positive reference voltage	-	1	-	V_{DDA}	
V_{REF-}	Negative reference voltage	-	V_{SSA}			
f_{ADC}	ADC clock frequency	1.62 V ≤ V_{DDA} ≤ 3.6 V	0.14	-	55	MHz
	ADC clock duty cycle	-	45	-	55	%
f_s	Sampling rate	Resolution = 12 bits	0.01	-	2.75	Msps
		Resolution = 10 bits	0.012	-	3.05	
		Resolution = 8 bits	0.014	-	3.43	
		Resolution = 6bits	0.0175	-	3.92	

Table 100. 12-bit ADC4 characteristics(1)(2) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t_{TRIG}	External trigger period	Resolution = 12 bits	16	-	-	$1/f_{ADC}$
V_{AIN}(3)	Conversion voltage range	-	0	-	V_{REF+}	V
R_{AIN}(4)	External input impedance T_j = 130 °C	Resolution = 12 bits	-	-	2.2	kΩ
		Resolution = 10 bits	-	-	6.8	
		Resolution = 8 bits	-	-	33.0	
		Resolution = 6 bits	-	-	47.0	
C_{ADC}	Internal sample and hold capacitor	-	-	5	-	pF
$t_{ADCVREG_STUP}$	ADC LDO startup ready flag time	-	-	-	25	µs
t_{STAB}	ADC power-up time	LDO already started	(3 × 1/f_{ADC}) + 1 conversion			Cycle
t_{OFF_CAL}	Offset calibration time	-	-	123	-	$1/f_{ADC}$
t_{LATR}	Trigger conversion latency	WAIT = 0, AUTOFF = 0, DPD = 0, f_{ADC} = HCLK	4			
		WAIT = 0, AUTOFF = 0, DPD = 0, f_{ADC} = HCLK/2	4			
		WAIT = 0, AUTOFF = 0, DPD = 0, f_{ADC} = HCLK/4	3.75			
t_s	Sampling time	-	1.5	-	814.5	
t_{CONV}	Total conversion time (including sampling time)	Resolution = N bits, VREFPROTEN = 0	t_s + N + 0.5			
		Resolution = N bits, VREFPROTEN = 1 VREFSECSMP = 0	t_s + N + 0.5	-	t_s + N + 1.5	
		Resolution = N bits, VREFPROTEN = 1 VREFSECSMP = 1	t_s + N + 0.5	-	t_s + N + 2.5	

Table 100. 12-bit ADC4 characteristics(1)(2) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DDA(ADC)}$	ADC consumption on V_{DDA}	f_s = 2.5 Msps	-	360	-	µA
		f_s = 1 Msps	-	180	-	
		f_s = 10 ksps	-	10	-	
		AUTOFF = 1, DPD = 0, no conversion	-	9	-	
		AUTOFF = 1, DPD = 1, no conversion	-	0.1	-	
$I_{DDV(ADC)}$	ADC consumption on V_{REF+}	f_s = 2.5 Msps	-	18	-	
		f_s = 1 Msps	-	10.2	-	
		f_s = 10 ksps	-	0.12	-	
		AUTOFF = 1, DPD = 0, no conversion	-	0.01	-	
		AUTOFF = 1, DPD = 1, no conversion	-	0.01	-	

1. Specified by design. Not tested in production.
2. The voltage booster on the ADC switches must be used when V_{DDA} < 2.4 V (embedded I/O switches).
3. Depending on the package, V_{REF+} can be internally connected to V_{DDA} and V_{REF-} can be internally connected to V_{SSA}.
4. The maximum value of R_{ain} is specified to keep leakage induced offset within the specified tolerance. The tolerance is 2 LSBs.

The maximum value of R_{AIN} can be found in the table below.

Table 101. Maximum R_{AIN} for 12-bit ADC4(1)(2)(3)

Resolution(4)	R_{AIN} max (Ω)(5)	Sampling time [ns]	Sampling cycle at 35 MHz	Sampling cycle at 55 MHz
12 bits	47	276	12.5	19.5
	68	288		
	100	306		
	150	336		
	220	377	19.5	39.5
	330	442		
	470	526		
	680	650	39.5	
	1000	840		79.5
	1500	1134		
	2200	1643	79.5	814.5
	3300	2395	814.5	
	4700	3342		
	6800	4754		
	10000	6840		
	15000	9967		
	22000	14068		
	33000	19933		N/A
10 bits	47	86	3.5	7.5
	68	90		
	100	95		
	150	108	7.5	
	220	116		
	330	136		
	470	161		12.5
	680	212		
	1000	276	12.5	19.5
	1500	376	19.5	39.5
	2200	516		79.5
	3300	735	39.5	
	4700	1012		
	6800	1423	79.5	814.5

Table 101. Maximum R_{AIN} for 12-bit ADC4[(1)(2)(3)] (continued)

Resolution[(4)]	R_{AIN} max (Ω)[(5)]	Sampling time [ns]	Sampling cycle at 35 MHz	Sampling cycle at 55 MHz
10 bits (cont'd)	10000	2040	814.5	814.5
	15000	2978		
	22000	4356		
	33000	6443		
	47000	8925		
8 bits	47	45	3.5	3.5
	68	46		
	100	48		
	150	53		
	220	59		
	330	69		7.5
	470	81		
	680	101	7.5	
	1000	130		
	1500	177		12.5
	2200	242	12.5	19.5
	3300	345		
	4700	475	19.5	39.5
	6800	670	39.5	
	10000	963		79.5
	15000	1417	79.5	
	22000	2040		814.5
	33000	2995	814.5	
	47000	4158		
6 bits	47	32	1.5	3.5
	68	32		
	100	33		
	150	35		
	220	37		
	330	41		
	470	49	3.5	
	680	61		
	1000	79		7.5
	1500	106	7.5	

Table 101. Maximum R_{AIN} for 12-bit ADC4(1)(2)(3) (continued)

Resolution(4)	R_{AIN} max (Ω)(5)	Sampling time [ns]	Sampling cycle at 35 MHz	Sampling cycle at 55 MHz
6 bits (cont'd)	2200	146	7.5	12.5
	3300	207		
	4700	286	12.5	19.5
	6800	404	19.5	39.5
	10000	584	39.5	
	22000	1250	79.5	79.5
	33000	1853		814.5
	47000	2607	814.5	

1. Specified by design. Not tested in production.
2. BOOSTEN and ANASWVDD configured properly according to V_{DD} and V_{DDA} values.
3. Values without external capacitor.
4. The tolerance is 1 LSB.
5. The maximum value of RAIN is obtained in a worst-case scenario: channel conversion in scan mode with channel i connected to VREF+ and channel i + 1 connected to VREF-.

Table 102. 12-bit ADC4 accuracy(1)(2) (3)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
ET	Total unadjusted error	-	-	±3	±7.5	LSB
EO	Offset error	-	-	±2	±5.5	
EG	Gain error	-	-	±2	±6.5	
ED	Differential linearity error	-	-	-0.9/+1	-0.9/+1.5	
EL	Integral linearity error	-	-	±2	±3.5	
ENOB	Effective number of bits	-	9.9	10.9	-	bits
SINAD	Signal-to-noise and distortion ratio	-	61.4	67.4	-	dB
SNR	Signal-to-noise ratio	-	61.6	67.5	-	
THD	Total harmonic distortion	-	-	-74	-70	

1. Evaluated by characterization for BGA packages. Not tested in production. The values for LQFP packages may differ.
2. ADC DC accuracy values are measured after the internal calibration.
3. The I/O analog switch voltage booster is enabled when V_{DDA} < 2.4 V (BOOSTEN = 1 in SYSCFG_CFGR1 when V_{DDA} < 2.4 V). This switch is disabled when V_{DDA} ≥ 2.4 V. Resolution = 12 bits, no oversampling.

See *Figure 38: ADC accuracy characteristics*, *Figure 39: Typical connection diagram when using the ADC with FT/TT pins featuring analog switch function*, and *General PCB design guidelines*.

5.3.21 Temperature sensor characteristics

Table 103. Temperature sensor characteristics

Symbol	Parameter	Min	Typ	Max	Unit
T_L[1]	V_{SENSE} linearity with temperature	-	-	1.3	°C
Avg_Slope[1]	Average slope	2	2.5	3.0	mV/°C
V_{30}[2]	Voltage at 30°C (±5 °C)	700	752	800	mV
$\Delta(V_{continuous} - V_{sampling})$[3]	Difference of voltage between continuous and sampling modes[4]	-	-	-10/+4	
$t_{START_(TS_BUF)}$[3]	Sensor buffer startup time	-	1	10	µs
t_{S_temp}[3]	ADC sampling time when reading the temperature	13	-	-	
$I_{DD(TS)}$[3]	Temperature sensor consumption from V_{DD}, when selected by ADC	-	14	20	µA

1. Evaluated by characterization. Not tested in production.
2. Measured at $V_{REF+} = V_{DDA}$ = 3.0 V ±10 mV. The V_{30} A/D conversion result is stored in the TS_CAL1 byte. Refer to *Table 16: Temperature sensor calibration values*.
3. Specified by design. Not tested in production.
4. The temperature sensor is in continuous mode when the regulator is in range 1, 2 or 3. The temperature sensor is in sampling mode when the regulator is in range 4, or when the device is in Stop 1 or Stop 2 mode.

5.3.22 V_{CORE} monitoring characteristics

Table 104. V_{CORE} monitoring characteristics[1]

Symbol	Parameter	Min	Typ	Max	Unit
t_{S_VCORE}	ADC sampling time when reading the V_{CORE} voltage	1	-	-	µs

1. Specified by design. Not tested in production.

5.3.23 V_{BAT} monitoring characteristics

Table 105. V_{BAT} monitoring characteristics[1]

Symbol	Parameter	Min	Typ	Max	Unit
R	Resistor bridge for V_{BAT}	-	4 × 25.6	-	kΩ
Q	Ratio on V_{BAT} measurement	-	4	-	-
Er[2]	Error on Q	-5	-	5	%
t_{S_VBAT}[2]	ADC sampling time when reading the VBAT	5	-	-	µs

1. 1.58 V ≤ V_{BAT} ≤ 3.6 V
2. Specified by design. Not tested in production.

Table 106. V_{BAT} charging characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
R_{BC}	Battery charging resistor	VBRS = 0	-	5	-	kΩ
		VBRS = 1	-	1.5	-	

5.3.24 Digital-to-analog converter characteristics

Table 107. DAC characteristics(1)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage for DAC ON	-		1.6	-	3.6	V
V_{REF+}	Positive reference voltage	-		1.6	-	V_{DDA}	
V_{REF-}	Negative reference voltage	-		-	V_{SSA}	-	
R_L	Resistive load	DAC output buffer ON	connected to V_{SSA}	5	-	-	kΩ
			connected to V_{DDA}	25	-	-	
R_O	Output impedance	DAC output buffer OFF		10	13	16	
R_{BON}	Output impedance sample and hold mode, output buffer ON	V_{DDA} = 2.7 V		-	-	1.5	
		V_{DDA} = 2.0 V		-	-	2.5	
R_{BOFF}	Output impedance sample and hold mode, output buffer OFF	V_{DDA} = 2.7 V		-	-	16.5	
		V_{DDA} = 2.0 V		-	-	17.5	
C_L	Capacitive load	DAC output buffer OFF		-	-	50	pF
C_{SH}		Sample and hold mode		-	0.1	1	µF
V_{DAC_OUT}	Voltage on DAC_OUT output	DAC output buffer ON		0.2	-	V_{DDA} - 0.2	V
		DAC output buffer OFF		0	-	V_{REF+}	
$t_{SETTLING}$	Settling time (full scale: for a 12-bit code transition between the lowest and the highest input codes when DAC_OUT reaches the final value of ±0.5 LSB, ±1 LSB, ±2 LSB, ±4 LSB, or ±8 LSB)	Normal mode DAC output buffer ON C_L ≤ 50 pF, R_L ≥ 5 kΩ	±0.5 LSB	-	2.05	3.05	µs
			±1 LSB	-	1.90	3	
			±2 LSB	-	1.85	2.85	
			±4 LSB	-	1.80	2.8	
			±8 LSB	-	1.75	2.65	
		Normal mode DAC output buffer OFF, ±1 LSB, C_L = 10 pF		-	1.7	3	
t_{WAKEUP} (2)	Wake-up time from off state (setting the ENx bit in the DAC control register) until the final value ±1 LSB	Normal mode DAC output buffer ON, C_L ≤ 50 pF, R_L = 5 kΩ		-	4.2	7.5	
		Normal mode DAC output buffer OFF, C_L ≤ 10 pF		-	2	5	
PSRR	DC V_{DDA} supply rejection ratio	Normal mode DAC output buffer ON, C_L ≤ 50 pF, R_L = 5 kΩ		35	-80	-28	dB

Table 107. DAC characteristics(1) (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
t_{SAMP}	Sampling time in sample and hold mode, C_{SH} = 100 nF (code transition between the lowest input code and the highest input code when DACOUT reaches the final value ±1 LSB)	DAC_OUT pin connected	DAC output buffer ON, C_{SH} = 100 nF	-	0.7	1.9	ms
			DAC output buffer OFF, C_{SH} = 100 nF	-	10.5	15	
		DAC_OUT pin not connected (internal connection only)	DAC output buffer OFF	-	2	8	µs
I_{leak}	Output leakage current	-		-	-	(3)	nA
CI_{int}	Internal sample and hold capacitor	-		7	9.2	11	pF
t_{TRIM}	Middle code offset trim time	DAC output buffer ON		50	-	-	µs
V_{offset}	Middle code offset for 1 trim code step	V_{REF+} = 3.6 V		-	1520	-	µV
		V_{REF+} = 1.6 V		-	680	-	
$I_{DDA(DAC)}$	DAC consumption from V_{DDA}	DAC output buffer ON	No load, middle code (0x800)	-	330	510	µA
			No load, worst code (0xF1C)	-	470	680	
		DAC output buffer OFF	No load, middle/worst code (0x800)	-	-	0.3	
		Sample and hold mode, C_{SH} = 100 nF		-	330 × T_{ON} /(T_{ON} + T_{OFF}) (4)	680 × T_{ON} /(T_{ON} + T_{OFF}) (4)	
$I_{DDV(DAC)}$	DAC consumption from V_{REF+}	DAC output buffer ON	No load, middle code (0x800)	-	170	240	
			No load, worst code (0x0E4)	-	300	400	
		DAC output buffer OFF	No load, middle/worst code (0x800)	-	145	180	
		Sample and hold mode, buffer ON, C_{SH} = 100 nF (worst code)		-	170 × T_{ON} /(T_{ON} + T_{OFF}) (4)	400 × T_{ON} /(T_{ON} + T_{OFF}) (4)	
		Sample and hold mode, buffer OFF, C_{SH} = 100 nF (worst code)		-	145 × T_{ON} /(T_{ON} + T_{OFF}) (4)	180 × T_{ON} /(T_{ON} + T_{OFF}) (4)	

1. Specified by design. Not tested in production.

2. In buffered mode, the output can overshoot above the final value for low input code (starting from the minimum value).
3. Refer to *Table 87: I/O static characteristics*.
4. T_{ON} is the refresh phase duration. T_{OFF} is the hold phase duration (see the product reference manual for more details).

Figure 40. 12-bit buffered/non-buffered DAC

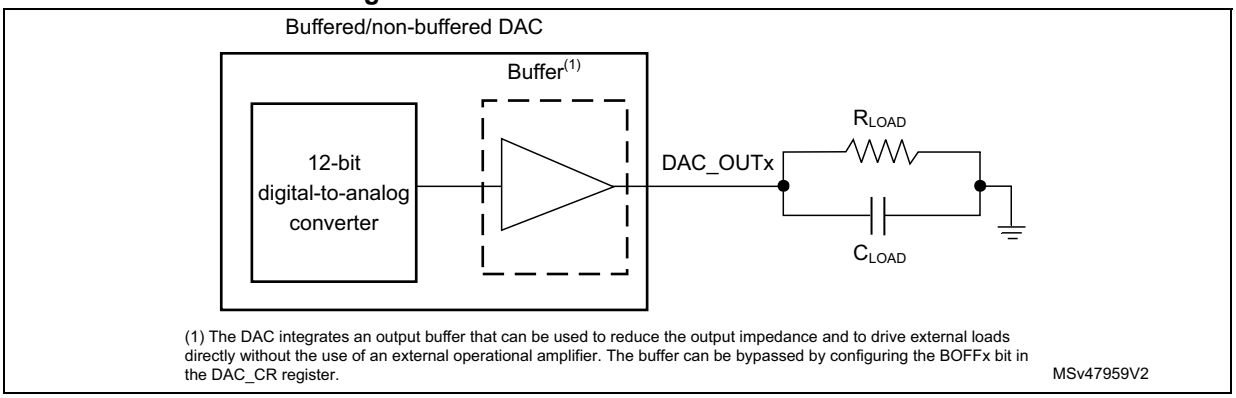


Table 108. DAC accuracy(1)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
DNL	Differential non-linearity(2)	DAC output buffer ON		-	-	±2	LSB
		DAC output buffer OFF		-	-	±2	
-	Monotonicity	10 bits		guaranteed			-
INL	Integral non-linearity(3)	DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ		-	-	±4	LSB
		DAC output buffer OFF, $C_L \le 50$ pF, no R_L		-	-	±4	
Offset	Offset error at code 0x800(3)	DAC output buffer OFF, $C_L \le 50$ pF, no R_L		-	-	±8	
Offset1	Offset error at code 0x001(4)	DAC output buffer OFF, $C_L \le 50$ pF, no R_L		-	-	±5	
OffsetCal	Offset error at code 0x800(3) after calibration	DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ	V_{REF+} = 3.6 V	-	-	±5	
			V_{REF+} = 1.6 V	-	-	±5	
Gain	Gain error(5)	DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ		-	-	±0.5	%
		DAC output buffer OFF, $C_L \le 50$ pF, no R_L		-	-	±0.5	
TUE	Total unadjusted error	DAC output buffer OFF, $C_L \le 50$ pF, no R_L		-	-	±10	LSB
		DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ, after calibration		-	-	±14	

Table 108. DAC accuracy(1) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
SNR	Signal-to-noise ratio(6)	DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ, 1 kHz, BW = 500 kHz	-	70.6	-	dB
		DAC output buffer OFF, $C_L \le 50$ pF, no R_L, 1 kHz, BW = 500 kHz	-	72	-	
THD	Total harmonic distortion(6)	DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ, 1 kHz	-	-79	-	
		DAC output buffer OFF, $C_L \le 50$ pF, no R_L, 1 kHz	-	-81	-	
SINAD	Signal-to-noise and distortion ratio(6)	DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ, 1 kHz	-	70.1	-	
		DAC output buffer OFF, $C_L \le 50$ pF, no R_L, 1 kHz	-	71.5	-	
ENOB	Effective number of bits	DAC output buffer ON, $C_L \le 50$ pF, $R_L \ge 5$ kΩ, 1 kHz	-	11.3	-	bits
		DAC output buffer OFF, $C_L \le 50$ pF, no R_L, 1 kHz	-	11.6	-	

1. Specified by design. Not tested in production.
2. Difference between two consecutive codes minus 1 LSB.
3. Difference between the value measured at code i and the value measured at code i on a line drawn between code 0 and last code 4095.
4. Difference between the value measured at code (0x001) and the ideal value.
5. Difference between the ideal transfer-function slope and the measured slope computed from code 0x000 and 0xFFF when the buffer is OFF, and from code giving 0.2 V and (VREF+ - 0.2 V) when the buffer is ON.
6. Signal is -0.5 dBFS with Fsampling = 1 MHz.

5.3.25 Voltage reference buffer characteristics

Table 109. VREFBUF characteristics(1)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage	Normal mode	VRS = 000	1.8	-	3.6	V
			VRS = 001	2.1	-		
			VRS = 010	2.4	-		
			VRS = 011	2.8	-		
		Degraded mode(2)	VRS = 000	1.62	-	1.8	
			VRS = 001		-	2.1	
			VRS = 010		-	2.4	
			VRS = 011		-	2.8	
V_{REFBUF_OUT} (3)	Voltage reference buffer output	Normal mode at V_{DDA} = 3 V, T_J = 30 °C, I_{load} = 10 µA	VRS = 000	1.496	1.5	1.504	
			VRS = 001	1.795	1.8	1.805	
			VRS = 010	2.042	2.048	2.054	
			VRS = 011	2.493	2.5	2.507	

Table 109. VREFBUF characteristics(1) (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
V_{REFBUF_OUT} (3) (cont'd)	Voltage reference buffer output	Degraded mode(2)	VRS = 000	Min (V_{DDA} - 0.15 ;1.496)	-	1.504	V
			VRS = 001	Min (V_{DDA} - 0.15 ;1.795)	-	1.805	
			VRS = 010	Min (V_{DDA} - 0.15 ;2.042)	-	2.054	
			VRS = 011	Min (V_{DDA} - 0.15 ;2.493)	-	2.507	
TRIM	Trim step	-		0.1	0.175	0.25	%
C_L	Load capacitor(4)	-		0.5	1.10	1.50	µF
esr	C_L equivalent serial resistor	-		-	-	2	Ω
I_{load}	Static load current	-		-	-	4	mA
R_{PD}	Pull-down resistance	-		-	-	400	Ω
I_{line_reg}	Line regulation	$V_{DDAmin} \leq V_{DDA} \leq 3.6$ V, Normal mode, 500 µA ≤ I_{load} ≤ 4 mA		±0.016	±0.033	±0.053	%
I_{load_reg}	Load regulation(5)	Normal mode, 500 µA ≤ I_{load} ≤ 4 mA		-	50	400	ppm/ mA
T_{Coeff}	Temperature coefficient	–40 °C < T_J < +130 °C		-	-	$T_{coeff_vrefint}$ + 50	ppm/ °C
PSRR	Power supply rejection	DC		-	65	-	dB
		100 kHz		-	30	-	
t_{START}	Startup time	C_L = 0.5 µF		-	110	200	µs
		C_L = 1.1 µF		-	240	350	
		C_L = 1.5 µF		-	320	500	
I_{INRUSH}	Control of DC current drive on V_{REFBUF_OUT} during startup phase (6)	-		-	8	11	mA
I_{DDA} (VREFBUF)	VREFBUF consumption from V_{DDA}	I_{load} = 0 µA		-	14	18	µA
		I_{load} = 500 µA		-	16	20	
		I_{load} = 4 mA		-	42	50	

1. Specified by design and not tested in production, unless otherwise specified.
2. In degraded mode, the voltage reference buffer can not accurately maintain the output voltage (V_{DDA} - drop voltage).
3. Evaluated by characterization. Not tested in production.
4. The capacitive load must include a 100 nF capacitor in order to cut off the high-frequency noise.
5. The load regulation value only takes into account the die and package resistance. The parasitic resistance on PCB degrades this value.
6. To correctly control the VREFBUF inrush current during startup phase and scaling change, the V_{DDA} voltage must be in the range of [1.8 V-3.6 V], [2.1 V-3.6 V], [2.4 V-3.6 V] and [2.8 V-3.6 V] for VRS = 000, 001, 010 and 011 respectively.

Figure 41. V_{REFBUF_OUT} versus temperature (VRS = 000)

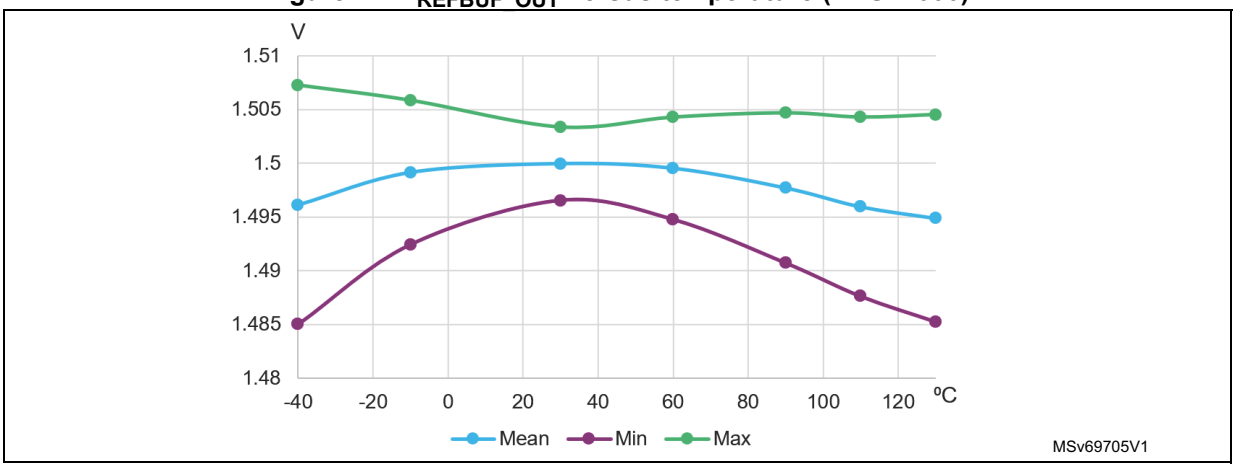


Figure 42. V_{REFBUF_OUT} versus temperature (VRS = 001)

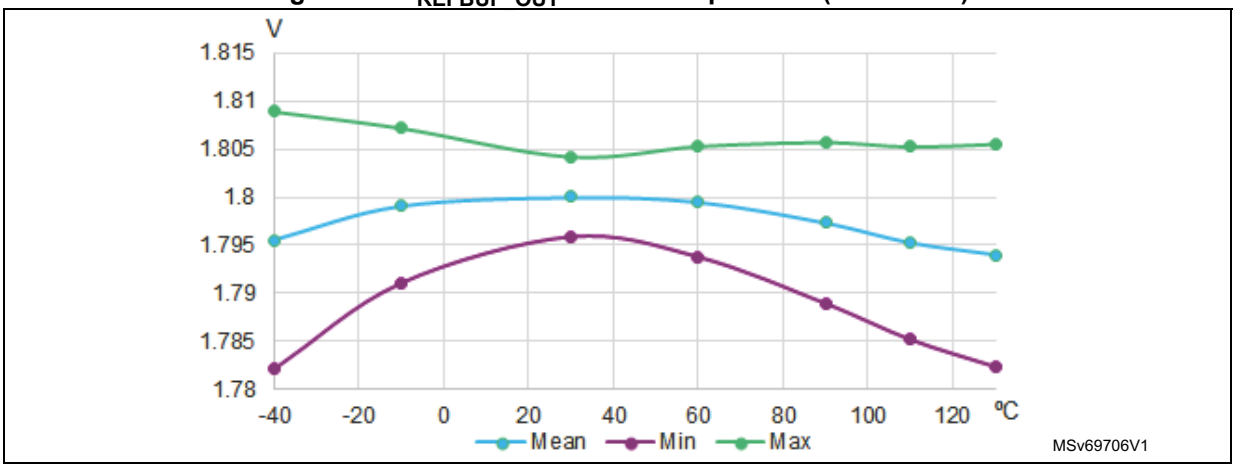


Figure 43. V_{REFBUF_OUT} versus temperature (VRS = 010)

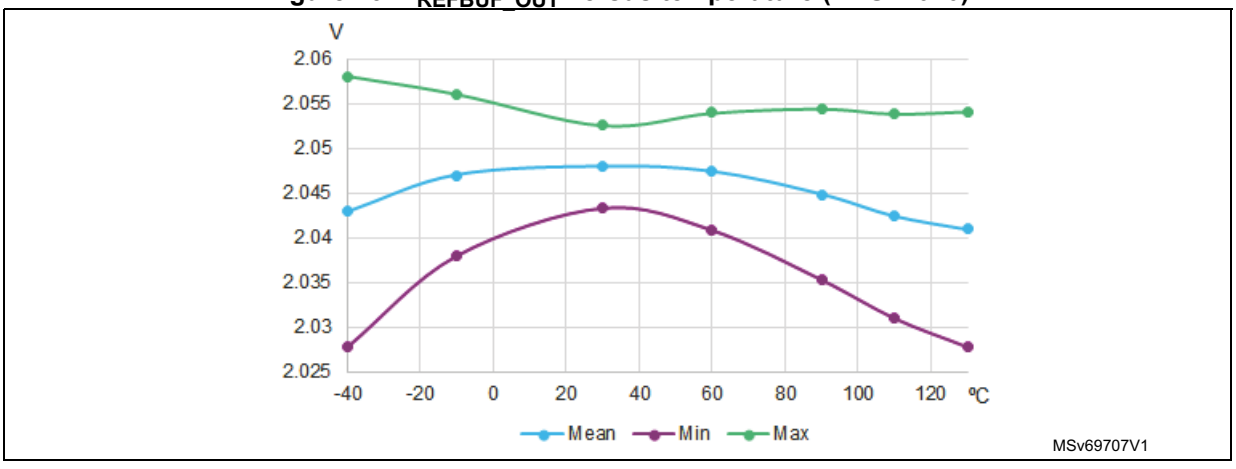
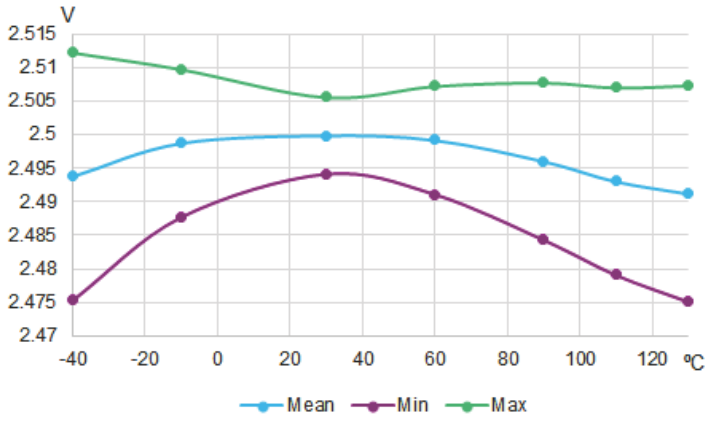


Figure 44. V_{REFBUF_OUT} versus temperature (VRS = 011)



5.3.26 Comparator characteristics

Table 110. COMP characteristics(1)(2)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage for COMP ON	-	1.58	-	3.6	V
V_{IN}	Comparator input voltage range	-	0	-	V_{DDA}	V
V_{REFINT}(3)	Scaler input voltage	-	(3)			V
V_{SC}	Scaler offset voltage	-	-	±5	±10	mV
$I_{DDA(SCALER)}$	Scaler static consumption from V_{DDA}	Scaler bridge disabled(4)	-	0.20	0.25	µA
		Scaler bridge enabled(5)	-	0.7	1	
t_{START_SCALER}	Scaler startup time	-	-	130	220	µs
t_{START}	Comparator startup time to reach propagation delay specification	High-speed mode	-	-	5	
		Medium mode	-	-	25	
		Ultra-low-power mode	-	-	80	
t_D(6)	Propagation delay for 200 mV step with 100 mV overdrive	High-speed mode	-	40	100	ns
		Medium mode	-	0.5	1	µs
		Ultra-low-power mode	-	2	7	
V_{offset}	Comparator offset error	Full common mode range	-	±5	±20	mV
V_{hys}	Comparator hysteresis	No hysteresis	-	0	-	
		Low hysteresis	-	15	-	
		Medium hysteresis	-	30	-	
		High hysteresis	-	45	-	
I_{bias}	Comparator input bias current	-	(7)			nA

Table 110. COMP characteristics(1)(2) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DDA(COMP)}$	Comparator consumption from V_{DDA}	High-speed mode, static	-	48	90	µA
		High-speed mode, with 50 kHz, ±100 mV overdrive square signal	-	50	-	
		Medium mode, static	-	3	6	
		Medium mode, with 50 kHz, ±100 mV overdrive square signal	-	3.75	-	
		Ultra-low-power mode, static	-	0.3	1	
		Ultra-low-power mode, with 50 kHz, ±100 mV overdrive square signal	-	0.65		

1. Specified by design and not tested in production, unless otherwise specified.
2. The input capacitance is negligible compared to the I/O capacitance.
3. Refer to *Table 37: Embedded internal voltage reference*.
4. No V_{REFINT} division, includes only buffer consumption.
5. V_{REFINT} division, includes resistor bridge and buffer consumption.
6. Evaluated by characterization. Not tested in production.
7. Mostly I/O leakage when used in analog mode. Refer to I_{lkg} parameter in *Table 87: I/O static characteristics*.

5.3.27 Operational amplifiers characteristics

Table 111. OPAMP characteristics(1)(2)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DDA}	Analog supply voltage range for OPAMP ON	-	1.60	-	3.6	V
CMIR	Common mode input range	-	0	-	V_{DDA}	
VI_{OFFSET}	Input offset voltage	T_J = 30 °C, no load on output, Normal mode	-	-	±3	mV
		T_J= 30 °C, no load on output, Low-power mode	-	-	±3	
		All voltages and temperature, Normal mode	-	-	±7	
		All voltages and temperature, Low-power mode	-	-	±11.5	
ΔVI_{OFFSET}	Input offset voltage drift over temperature	Normal mode	-	±7	-	µV/°C
		Low-power mode	-	±15	-	
TRIMOFFSETP TRIMLPOFFSETP	Offset trim step at low common input voltage (0.1 × V_{DDA})	-	-	1.05	1.25	mV
TRIMOFFSETN TRIMLPOFFSETN	Offset trim step at high common input voltage (0.9 × V_{DDA})	-	-	1.05	1.25	

Table 111. OPAMP characteristics(1)(2) (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
I_{LOAD}	Drive current	Normal mode		-	-	500	µA
		Low-power mode		-	-	100	
I_{LOAD_PGA}	Drive current in PGA mode	Normal mode		-	-	450	
		Low-power mode		-	-	50	
R_{LOAD}	Resistive load (connected to VSSA or VDDA)	Normal mode		3.9	-	-	kΩ
		Low-power mode		20	-	-	
C_{LOAD}	Capacitive load	-		-	-	50	pF
CMRR	Common mode rejection ratio	Normal mode		-	79	-	dB
		Low-power mode		-	69	-	
PSRR	Power supply rejection ratio	Normal mode	C_{LOAD} ≤ 50 pF, R_{LOAD} ≥ 3.9 kΩ(3), DC	35	75	-	
		Low-power mode	C_{LOAD} ≤ 50 pF, R_{LOAD} ≥ 20 kΩ(3), DC	32	69	-	
GBW	Gain bandwidth product	Normal mode		0.4	2	3.1	MHz
		Low-power mode		0.23	0.5	0.76	
SR(3)	Slew rate (from 10% and 90% of output voltage)	Normal mode	Standard speed mode (OPAHSM = 0)	0.5	1	3.2	V/µs
		Low-power mode		0.14	0.25	0.75	
		Normal mode	High speed mode (OPAHSM = 1)	1.4	3.2	5.6	
		Low-power mode		0.38	0.82	1.5	
AO	Open loop gain	Normal mode		72	105	-	dB
		Low-power mode		77	106	-	
φm	Phase margin	Normal mode		54	67	-	°
		Low-power mode		54	65	-	
GM	Gain margin	Normal mode		-	9	-	dB
		Low-power mode		-	17	-	
V_{OHSAT}(3)	High saturation voltage	Normal mode	I_{LOAD} max or R_{LOAD} min, Input at V_{DDA}	V_{DDA} - 100	-	-	mV
		Low-power mode		V_{DDA} - 50	-	-	
V_{OLSAT}(3)	Low saturation voltage	Normal mode	I_{LOAD} max or R_{LOAD} min, Input at 0 V	-	-	100	
		Low-power mode		-	-	50	

Table 111. OPAMP characteristics(1)(2) (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
t_{WAKEUP}	Wake-up time from OFF state	Normal mode	C_{LOAD} ≤ 50 pF, R_{LOAD} ≥ 3.9 kΩ, follower config.	-	4	10	µs
		Low-power mode	C_{LOAD} ≤ 50 pF, R_{LOAD} ≥ 20kΩ, follower config.	-	20	40	
I_{bias}	OPAMP input bias current	General purpose input (all packages except UFBGA)		-	-	(4)	nA
		Dedicated input (UFBGA and TFBGA)	T_J ≤ 75 °C	-	-	7	
			T_J ≤ 85 °C	-	-	9	
			T_J ≤ 105 °C	-	-	18	
			T_J ≤ 125 °C	-	-	25	
PGA gain(3)	Non-inverting gain value	PGA_GAIN[1:0] = 00		-	2	-	-
		PGA_GAIN[1:0] = 01		-	4	-	
		PGA_GAIN[1:0] = 10		-	8	-	
		PGA_GAIN[1:0] = 11		-	16	-	
Rnetwork	R2/R1 internal resistance values in non-inverting PGA mode(5)	PGA gain = 2		-	80/80	-	kΩ/ kΩ
		PGA gain = 4		-	120/40	-	
		PGA gain = 8		-	140/20	-	
		PGA gain = 16		-	150/10	-	
Delta R	Resistance variation (R1 or R2)	-		-18	-	18	%
PGA gain error	PGA gain error	-		-1	-	1	
PGA BW	PGA bandwidth for different non inverting gain	PGA gain = 2		-	GBW/2	-	MHz
		PGA gain = 4		-	GBW/4	-	
		PGA gain = 8		-	GBW/8	-	
		PGA gain = 16		-	GBW/16	-	
en	Voltage noise density	Normal mode	At 1 kHz, output loaded with 3.9 kΩ	-	220	-	nV /√Hz
		Low-power mode	At 1 kHz, output loaded with 20 kΩ	-	350	-	
		Normal mode	At 10 kHz, output loaded with 3.9 kΩ	-	190	-	
		Low-power mode	at 10 kHz, output loaded with 20 kΩ	-	210	-	

Table 111. OPAMP characteristics(1)(2) (continued)

Symbol	Parameter	Conditions		Min	Typ	Max	Unit
$I_{DDA(OPAMP)}$	OPAMP consumption from V_{DDA}	Normal mode	no load, quiescent mode, standard speed	-	130	190	µA
		Low-power mode		-	40	58	
		Normal mode	no load, quiescent mode, high-speed mode	-	138	205	
		Low-power mode		-	42	60	

1. Specified by design and not tested in production, unless otherwise specified.
2. OPA_RANGE must be set to 1 in OPAMP1_CSR.
3. Evaluated by characterization. Not tested in production.
4. Mostly I/O leakage when used in analog mode. Refer to I_{lkg} parameter in *Table 87: I/O static characteristics*.
5. R2 is the internal resistance between the OPAMP output and the OPAMP inverting input. R1 is the internal resistance between the OPAMP inverting input and ground. PGA gain = 1 + R2/R1.

Figure 45. OPAMP voltage noise density, normal mode, R_{LOAD} = 3.9 kΩ

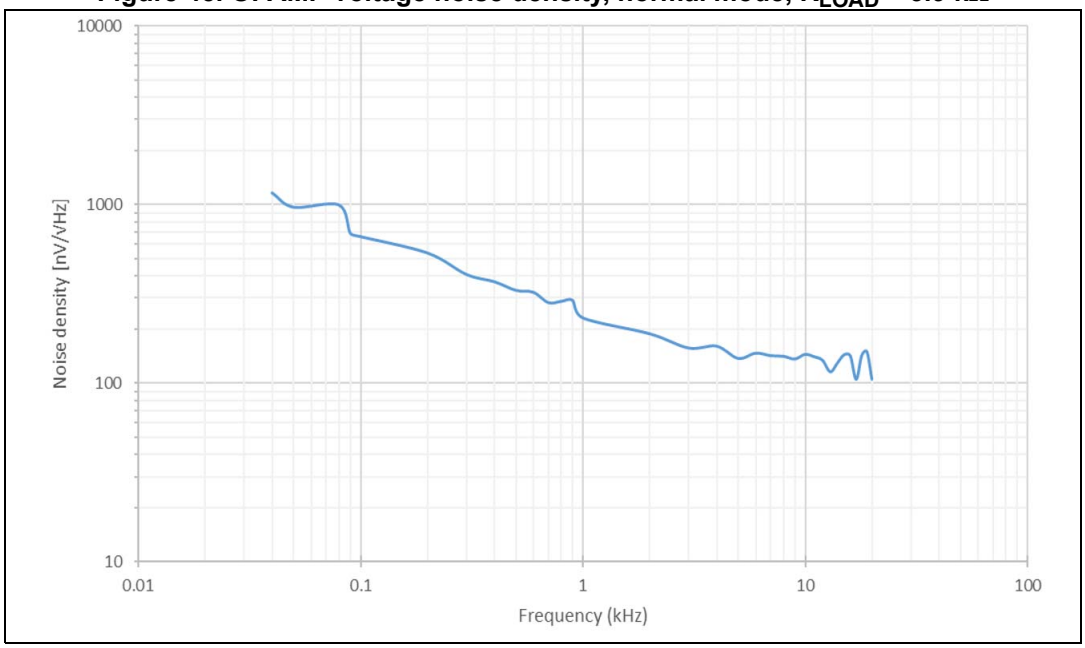
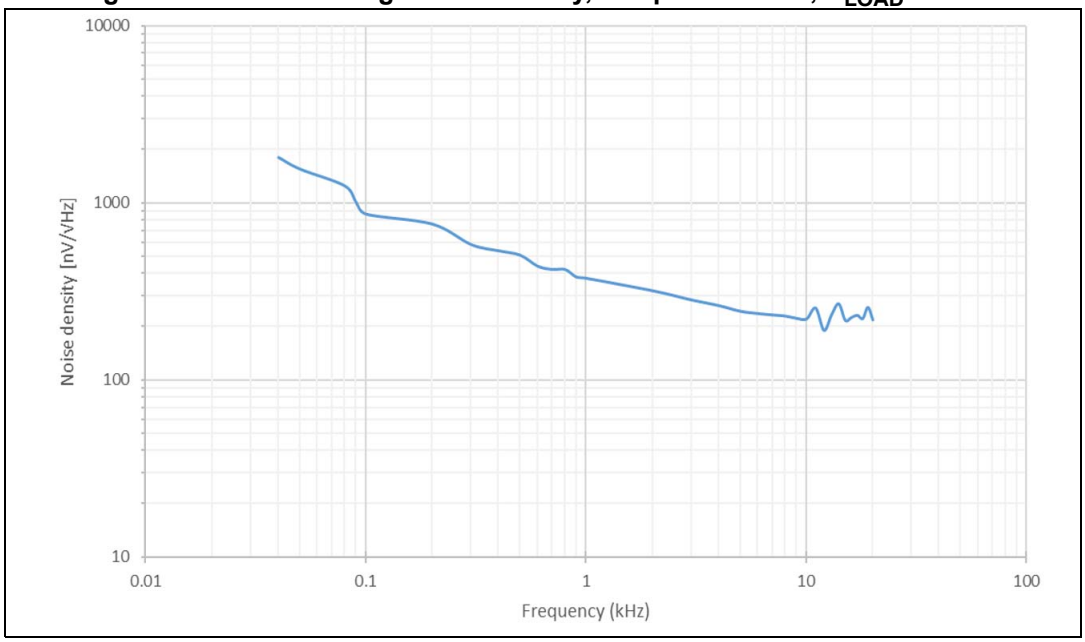


Figure 46. OPAMP voltage noise density, low-power mode, R_{LOAD} = 20 kΩ



5.3.28 Temperature and backup domain supply thresholds monitoring

The temperature and backup domain supply monitoring characteristics are provided in the technical note STM32U54xxx/STM32U58xxx/STM32U5Axxx/STM32U5Gxxx MCUs for PCI products (TN1333) (NDA required).

5.3.29 ADF/MDF characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{AHB} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30 pF
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output alternate function characteristics.

Table 112. ADF characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{CCKI}	Input clock frequency via ADF_CCK[1:0] pin, in SLAVE SPI mode	1.71 ≤ V_{DD} ≤ 3.6 V	-	-	25	MHz
f_{CCKO}	Output clock frequency in MASTER SPI mode		-	-	25	
f_{CCKOLF}	Output clock frequency in LF_MASTER SPI mode		-	-	5	
f_{SYMB}	Input symbol rate in Manchester mode		-	-	20	
t_{HCCKI} t_{LCCKI}	ADF_CCK[1:0] input clock high and low time	In SLAVE SPI mode	2 × Tadf_proc_ck(2)	-	-	ns
t_{HCCKO} t_{LCCKO}	ADF_CCK[1:0] output clock high and low time	In MASTER SPI mode	2 × Tadf_proc_ck	-	-	
$t_{HCCKOLF}$ $t_{LCCKOLF}$	ADF_CCK[1:0] output clock high and low time	In LF_MASTER SPI mode	Tadf_proc_ck	-	-	
t_{SUCCKI}	Data setup time with respect to ADF_CCK[1:0] input	In SLAVE SPI mode: ADF_CCK[1:0] configured in input, measured on rising and falling edge	4.5	-	-	
t_{HDCCKI}	Data hold time with respect to ADF_CCK[1:0] input		0	-	-	
t_{SUCCKO}	Data setup time with respect to ADF_CCK[1:0] output	In MASTER SPI mode: ADF_CCK[1:0] configured in output, measured on rising and falling edge	5.5	-	-	
t_{HDCCKO}	Data hold time with respect to ADF_CCK[1:0] output		0	-	-	
$t_{SUCCKOLF}$	Data setup time with respect to ADF_CCK[1:0] output	In LF_MASTER SPI mode: ADF_CCK[1:0] configured in output, measured on rising and falling edge	19.5	-	-	
$t_{HDCCKOLF}$	Data hold time with respect to ADF_CCK[1:0] output		0	-	-	

1. Evaluated by characterization. Not tested in production.
2. Tadf_proc_ck is the period of the ADF processing clock.

Figure 47. ADF timing diagram

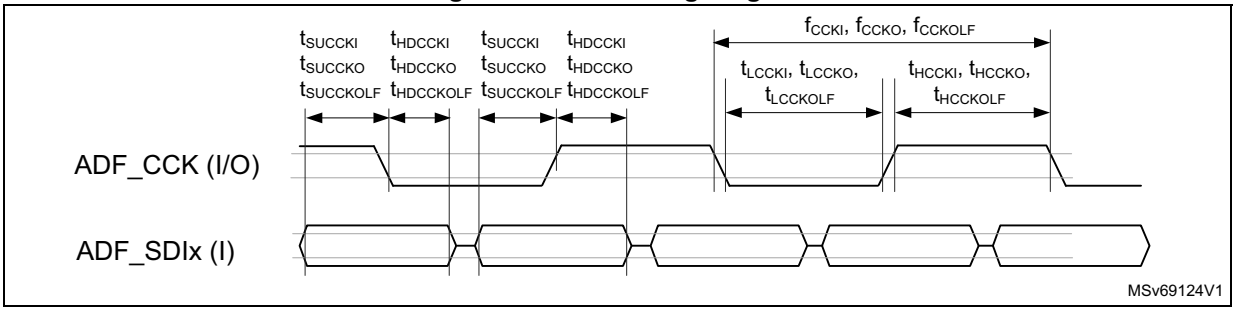
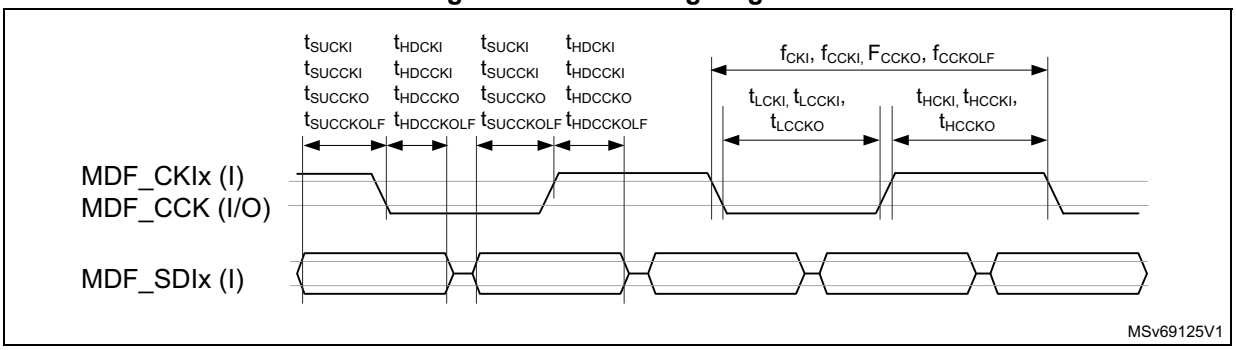


Table 113. MDF characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{CKI}	Input clock frequency via MDF_CKIx pin, in SLAVE SPI mode	1.71 ≤ V_{DD} ≤ 3.6 V	-	-	25	MHz
f_{CCKI}	Input clock frequency via MDF_CCK[1:0] pin, in SLAVE SPI mode		-	-	25	
f_{CCKO}	Output clock frequency in MASTER SPI mode		-	-	25	
f_{CCKOLF}	Output clock frequency in LF_MASTER SPI mode		-	-	5	
f_{SYMB}	Input symbol rate in Manchester mode		-	-	20	
t_{HCKI} t_{LCKI}	MDF_CKIx input clock high and low time	In SLAVE SPI mode	2 × Tmdf_proc_ck(2)	-	-	ns
t_{HCCKI} t_{LCCKI}	MDF_CCK[1:0] input clock high and low time	In SLAVE SPI mode	2 × Tmdf_proc_ck	-	-	
t_{HCCKO} t_{LCCKO}	MDF_CCK[1:0] output clock high and low time	In MASTER SPI mode	2 × Tmdf_proc_ck	-	-	
$t_{HCCKOLF}$ $t_{LCCKOLF}$	MDF_CCK[1:0] output clock high and low time	In LF_MASTER SPI mode	Tmdf_proc_ck	-	-	
t_{SUCKI}	Data setup time with respect to MDF_CKIx input	In SLAVE SPI mode, measured on rising and falling edge	1.5	-	-	
t_{HDCKI}	Data hold time with respect to MDF_CKIx input		0	-	-	
t_{SUCCKI}	Data setup time with respect to MDF_CCK[1:0] input	In SLAVE SPI mode: MDF_CCK[1:0] configured in input, measured on rising and falling edge	1.5	-	-	
t_{HDCCKI}	Data hold time with respect to MDF_CCK[1:0] input		0.5	-	-	
t_{SUCCKO}	Data setup time with respect to MDF_CCK[1:0] output	In MASTER SPI mode: MDF_CCK[1:0] configured in output, measured on rising and falling edge	3.5	-	-	
t_{HDCCKO}	Data hold time with respect to MDF_CCK[1:0] output		1.5	-	-	
$t_{SUCCKOLF}$	Data setup time with respect to MDF_CCK[1:0] output	In LF_MASTER SPI mode, MDF_CCK[1:0] configured in output, measured on rising and falling edge	19.5	-	-	
$t_{HDCCKOLF}$	Data hold time with respect to MDF_CCK[1:0] output		0	-	-	

1. Evaluated by characterization. Not tested in production.
2. Tmdf_proc_ck is the period of the MDF processing clock.

Figure 48. MDF timing diagram



5.3.30 DCMI characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage summarized in *Table 33*, with the following configuration:

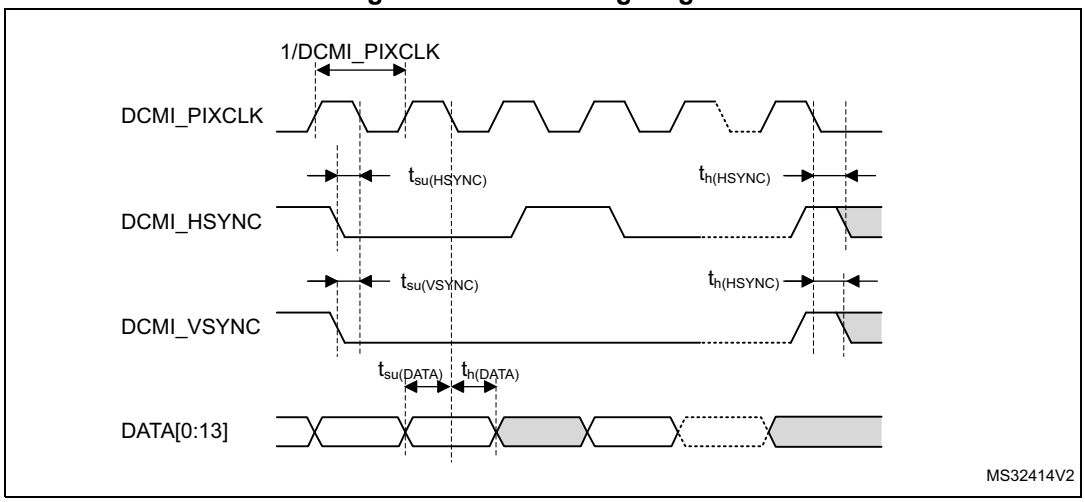
- Output speed set to OSPEEDRy[1:0] = 10
- DCMI_PIXCLK polarity: falling
- DCMI_VSYNC and DCMI_HSYNC polarity: high
- Data formats: 14 bits
- Capacitive load C_L = 30 pF
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Table 114. DCMI characteristics(1)

Symbol	Parameter	Min	Max	Unit
-	Frequency ratio DCMI_PIXCLK/f_{HCLK}	-	0.4	-
DCMI_PIXCLK	Pixel clock input	-	64	MHz
D_{PIXEL}	Pixel clock input duty cycle	30	70	%
$t_{su(DATA)}$	Data input setup time	2.5	-	ns
$t_{h(DATA)}$	Data hold time	1	-	
$t_{su(HSYNC)}$ $t_{su(VSYNC)}$	DCMI_HSYNC and DCMI_VSYNC input setup times	2	-	
$t_{h(HSYNC)}$ $t_{h(VSYNC)}$	DCMI_HSYNC and DCMI_VSYNC input hold times	1	-	

1. Evaluated by characterization. Not tested in production.

Figure 49. DCMI timing diagram



5.3.31 PSSI characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- PSSI_PDCK polarity: falling
- PSSI_RDY and PSSI_DE polarity: low
- Bus width: 16 lines
- Data width: 32 bits
- Capacitive load C_L = 30 pF
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Table 115. PSSI transmit characteristics(1)

Symbol	Parameter	Conditions	Min	Max	Unit
-	Frequency ratio DCMI_PDCK/f_{HCLK}	-	-	0.4	-
PSSI_PDCK	PSSI clock input	2.7 V ≤ V_{DD} ≤ 3.6 V	-	64(2)	MHz
		1.71 V ≤ V_{DD} ≤ 3.6 V	-	47(2)	
D_{PIXEL}	PSSI clock input duty cycle	-	30	70	%

Table 115. PSSI transmit characteristics(1) (continued)

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{OV(DATA)}$	Data output valid time	2.7 V ≤ V_{DD} ≤ 3.6 V	-	14	ns
		1.71 V ≤ V_{DD} ≤ 3.6 V	-	21	
$t_{OH(DATA)}$	Data output hold time	1.71 V ≤ V_{DD} ≤ 3.6 V	7	-	
$t_{OV(DE)}$	DE output valid time		-	13.5	
$t_{OH(DE)}$	DE output hold time		6	-	
$t_{SU(RDY)}$	RDY input setup time		0	-	
$t_{H(RDY)}$	RDY input hold time		0	-	

1. Evaluated by characterization. Not tested in production.
2. This maximal frequency does not consider receiver setup and hold timings.

Figure 50. PSSI transmit timing diagram

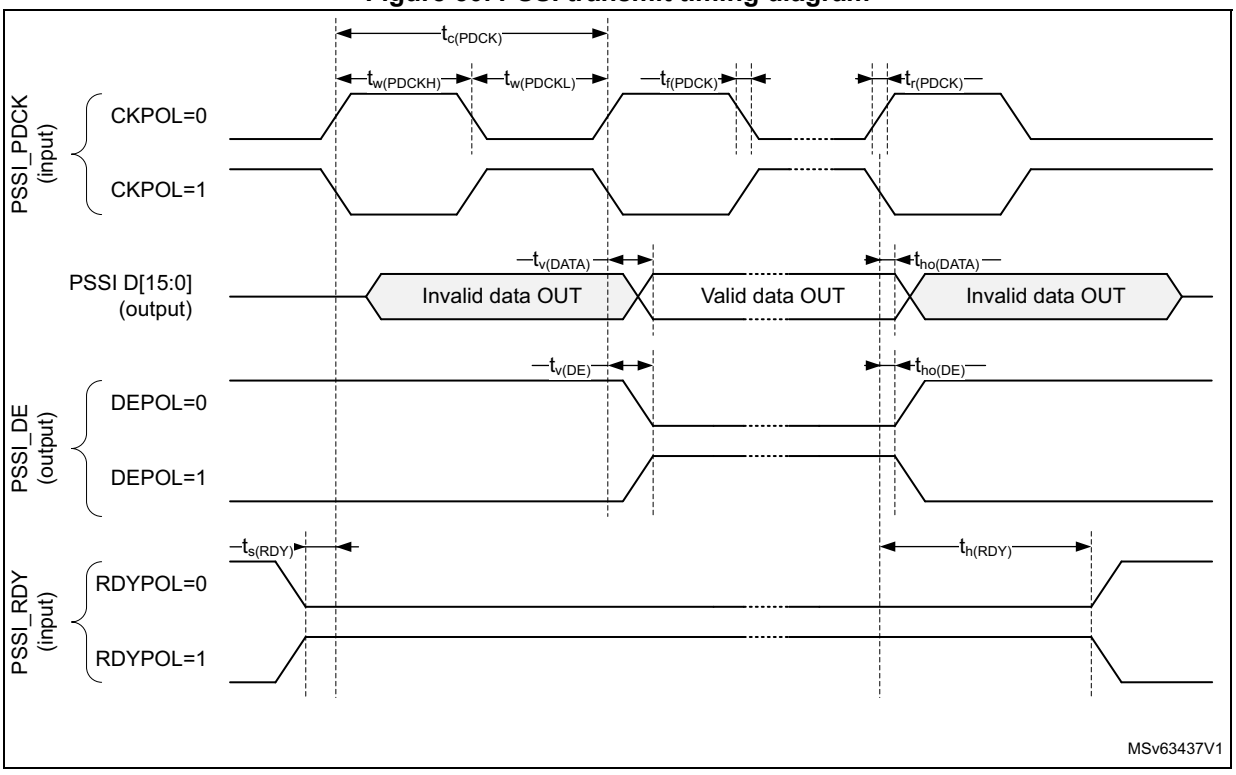


Table 116. PSSI receive characteristics(1)

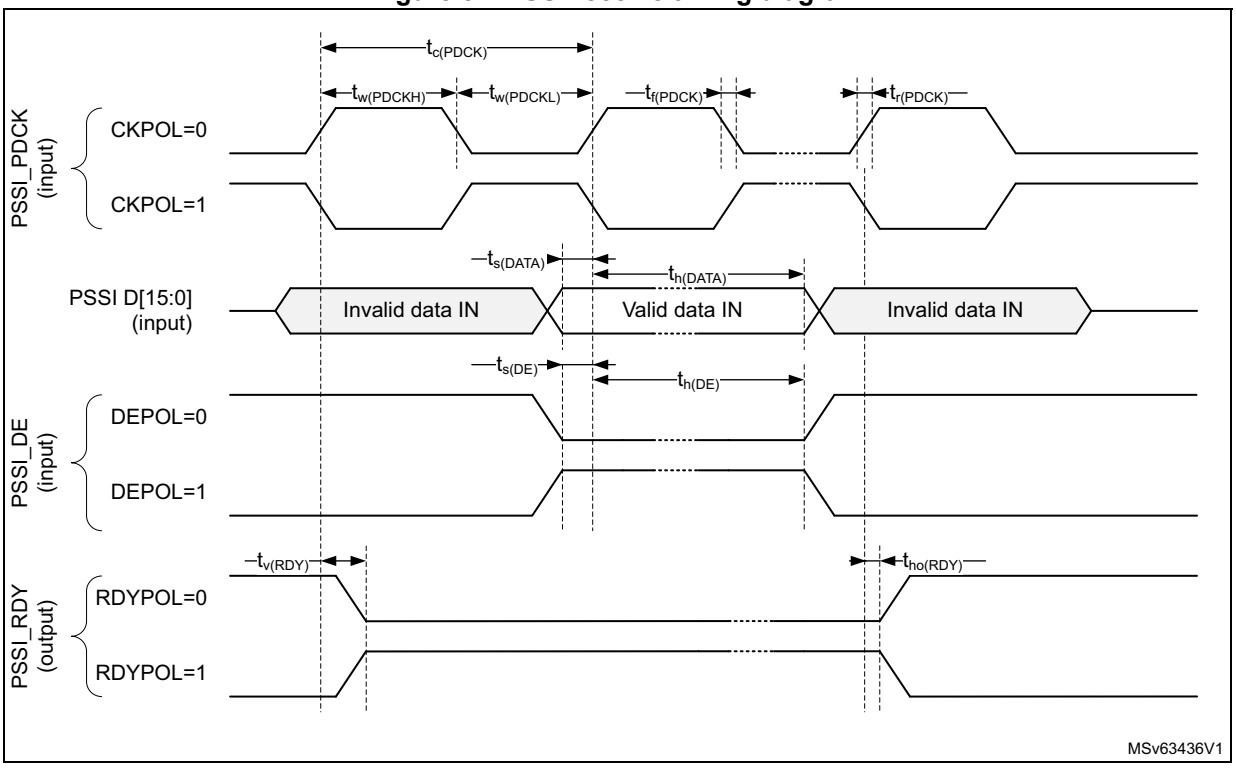
Symbol	Parameter	Conditions	Min	Max	Unit
-	Frequency ratio DCMI_PDCK/f_{HCLK}	-	-	0.4	-
PSSI_PDCK	PSSI clock input	1.71 V ≤ V_{DD} ≤ 3.6 V	-	64	MHz
D_{PIXEL}	PSSI clock input duty cycle	-	30	70	%

Table 116. PSSI receive characteristics(1) (continued)

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{SU(DATA)}$	Data input setup time	1.71 V ≤ V_{DD} ≤ 3.6 V	2	-	ns
$t_{H(DATA)}$	Data input hold time		1.5	-	
$t_{SU(DE)}$	DE input setup time		1	-	
$t_{H(DE)}$	DE input hold time		2	-	
$t_{OV(RDY)}$	RDY output valid time		-	13	
$t_{OH(RDY)}$	RDY output hold time		6	-	

1. Evaluated by characterization. Not tested in production.

Figure 51. PSSI receive timing diagram



5.3.32 LCD-TFT controller (LTDC) characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage summarized in *Table 33*, with the following configuration:

- LCD_CLK polarity: high
- LCD_DE polarity: low
- LCD_VSYNC and LCD_HSYNC polarity: high
- Pixel formats: 24 bits
- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30 pF
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Table 117. LTDC characteristics(1)

Symbol	Parameter	Conditions	Min	Max	Unit
f_{CLK}	LTDC clock output frequency	2.7 V ≤ V_{DD} ≤ 3.6 V, C_L = 20 pF	-	116	MHz
		2.7 V ≤ V_{DD} ≤ 3.6 V		100	
		1.71 V ≤ V_{DD} ≤ 3.6 V		66.5	
D_{CLK}	LTDC clock output duty cycle		45	55	%
$t_{W(CLKH)}$ $t_{W(CLKL)}$	Clock High time, low time		$t_{W(CLK)}/2$ - 0.5	$t_{W(CLK)}/2$ + 0.5	ns
$t_{V(DATA)}$	Data output valid time	2.7 V ≤ V_{DD} ≤ 3.6 V	-	2.5	
		1.71 V ≤ V_{DD} ≤ 3.6 V		7.5	
$t_{H(DATA)}$	Data output hold time		0.5	-	
$t_{V(HSYNC)}$ $t_{V(VSYNC)}$ $t_{V(DE)}$	HSYNC/VSYNC/DE output valid time		-	3	
$t_{H(HSYNC)}$ $t_{H(VSYNC)}$ $t_{H(DE)}$	HSYNC/VSYNC/DE output hold time		1.5	-	

1. Evaluated by characterization. Not tested in production.

Figure 52. LTDC horizontal timing diagram

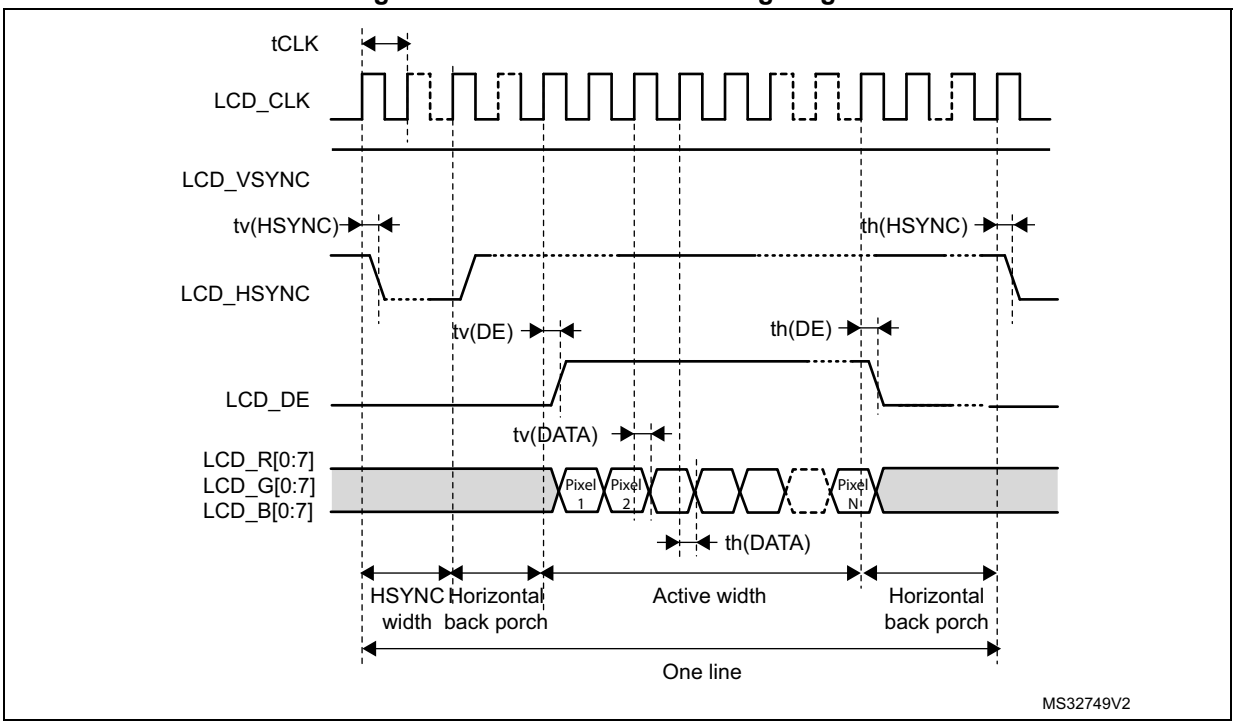
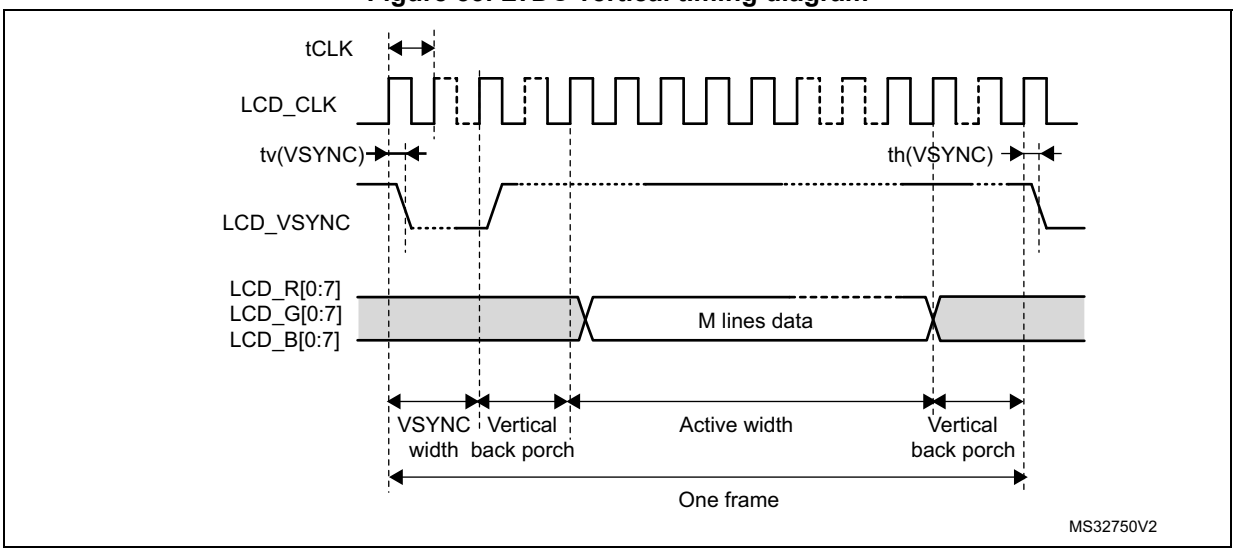


Figure 53. LTDC vertical timing diagram



5.3.33 MIPI D-PHY characteristics

The parameters given in the table below are derived from tests performed under temperature and V_{DD} supply voltage conditions summarized in *Table 33*.

Table 118. MIPI D-PHY characteristics(1)

Symbol	Parameter	Min	Typ	Max	Unit
High-speed input/output characteristics					
U_{INST}(2)	UI instantaneous	2	-	12.5	ns
V_{CMTX}	High-speed transmit common mode voltage	150	200	250	mV
$\|\Delta V_{CMTX}\|$	V_{CMTX} mismatch when output is Differential-1 or Differential-0	-	-	5	
$\|V_{OD}\|$	High-speed transmit differential voltage	140	200	270	
$\|\Delta V_{OD}\|$	V_{OD} mismatch when output is Differential-1 or Differential-0	-	-	14	
V_{OHHS}	High-speed output high voltage	-	-	360	
Z_{OS}	Single-ended output impedance	40	50	62.5	Ω
ΔZ_{OS}	Single-ended output impedance mismatch	-	-	10	%
t_{HSr}, t_{HSf}(2)	20%-80% rise and fall time	100	-	0.3 × UI(3)	ps
Low-power receiver input characteristics					
V_{IL}	Logic 0 input voltage (not in ULP state)	-	-	550	mV
$V_{IL-ULPS}$	Logic 0 input voltage in ULP state	-	-	300	
V_{IH}	Input high-level voltage	880	-	-	
V_{hys}(2)	Voltage hysteresis	25	-	-	
Low-power emitter output characteristics					
V_{OL}	Output low level voltage	-50	-	50	mV
V_{OH}	Output high level voltage	1.1	1.2	1.2	V
Z_{OLP}	Output impedance of LP transmitter	110	-	-	Ω
t_{LPr}, t_{LPf}(2)	15%-85% rise and fall time	-	-	25	ns
Low-power contention detector characteristics					
V_{ILCD}	Logic 0 contention threshold	-	-	200	mV
V_{IHCD}	Logic 1 contention threshold	450	-	-	

1. Evaluated by characterization, not tested in production unless otherwise specified.
2. Specified by design. Not tested in production.
3. UI (unit interval) equals to the duration of any HS state on the clock lane.

Table 119. MIPI D-PHY AC characteristics LP mode and HS/LP transitions(1)

Symbol	Parameter	Min	Typ	Max	Unit
T_{LPX}	Transmitted length of any LP state period	50	-	-	ns
$T_{CLK-PREPARE}$	Time that the transmitter drives the clock lane LP-00 line state immediately before the HS-0 line state, starting the HS transmission	38	-	95	
$T_{CLK-PREPARE}$ + $T_{CLK-ZERO}$	$T_{CLK-PREPARE}$ + time that the transmitter drives the HS-0 state prior to starting the clock	300	-	-	
$T_{CLK-PRE}$	Time that the HS clock must be driven by the transmitter prior to any associated data lane beginning the transition from LP to HS mode	8	-	-	UI(2)
$T_{CLK-POST}$	Time that the transmitter continues to send HS clock after the last associated data lane transitioned to LP mode	62 + 52 × UI	-	-	ns
$T_{CLK-TRAIL}$	Time that the transmitter drives the HS-0 state after the last payload clock bit of an HS transmission burst	60	-	-	
$T_{HS-PREPARE}$	Time that the transmitter drives the data lane LP-00 line state immediately before the HS-0 line state starting the HS transmission	40 + 4 × UI	-	85 + 6 × UI	
$T_{HS-PREPARE}$ + $T_{HS-ZERO}$	$T_{HS-PREPARE}$ + time that the transmitter drives the HS-0 state prior to transmitting the sync sequence	145 + 10 × UI	-	-	
$T_{HS-TRAIL}$	Time that the transmitter drives the flipped differential state after last payload data bit of a HS transmission burst	Max (n × 8 × UI, 60 + n × 4 × UI)	-	-	
$T_{HS-EXIT}$	Time that the transmitter drives LP-11 following a HS burst	100	-	-	
T_{REOT}	30%-85% rise and fall time	-	-	35(3)	
T_{EOT}	Transmitted time interval from the start of $T_{HS-TRAIL}$ or $T_{CLK-TRAIL}$, to the start of the LP-11 state following a HS burst	-	-	105 + n × 12 × UI	

1. Evaluated by characterization. Not tested in production.
2. UI (unit interval) equals to the duration of any HS state on the clock lane.
3. For V_{DD} above 3 V, this parameter may be degraded in the 55°C to 125°C range. For V_{DD} = 1.8 V, this parameter may be degraded in the 25°C to 125°C range.

Figure 54. MIPI D-PHY HS/LP clock lane transition

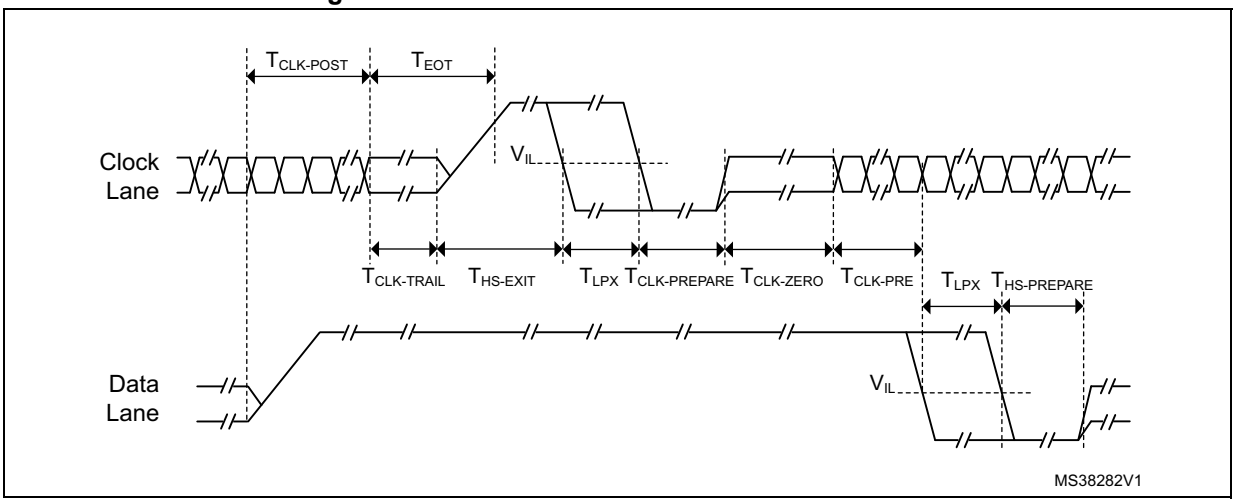


Figure 55. MIPI D-PHY HS/LP data lane transition

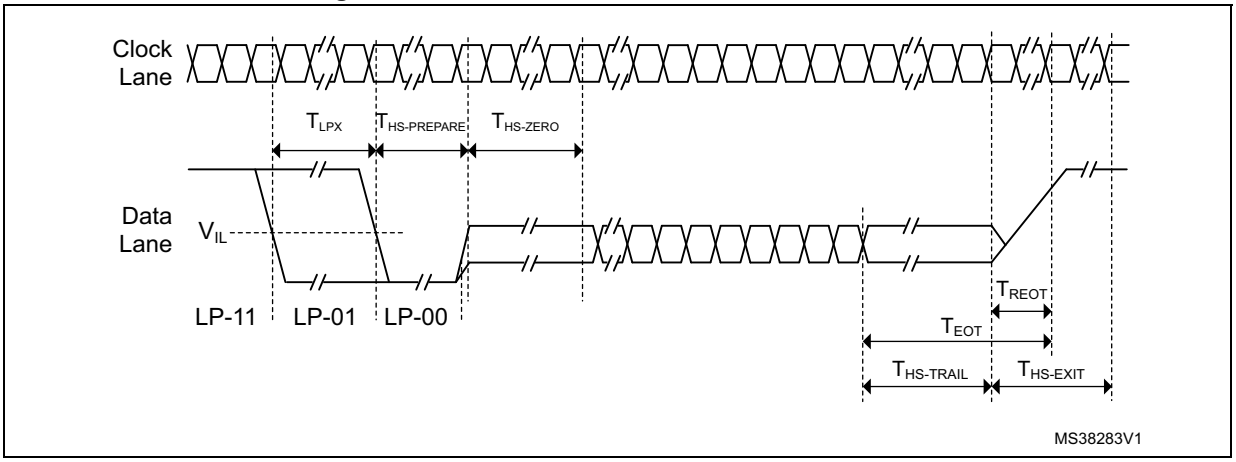


Table 120. DSI-PLL characteristics(1)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
f_{PLL_IN}	PLL input clock	-	4	-	48	MHz
f_{PLL_INFIN}	PFD input clock	-	2	-	48	
f_{PLL_OUT}	PLL multiplier output clock	-	0.976	-	1000	
f_{VCO_OUT}	PLL VCO output	-	500	-	1000	
t_{LOCK}	PLL lock time	-	-	-	400	µs
I_{DD_PLL}	PLL power consumption on VDD11DSI, for PFD input clock = 2 MHz	f_{VCO_OUT} = 500 MHz	-	0.25	0.27	mA
		f_{VCO_OUT} = 600 MHz	-	0.29	0.31	
		f_{VCO_OUT} = 1000 MHz	-	0.51	0.53	
I_{DD_PLL}	PLL power consumption on VDD11DSI, for PFD input clock = 48 MHz	f_{VCO_OUT} = 500 MHz	-	0.7	0.95	
		f_{VCO_OUT} = 600 MHz	-	0.76	1.01	
		f_{VCO_OUT} = 1000 MHz	-	1	1.22	

1. Evaluated by characterization. Not tested in production.

Table 121. DSI current consumption characteristics on V_{DDDSI}(1)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
I_{DD_DSI}	DSI system (Host, PLL and D-PHY) current consumption on V_{DDDSI}	Ultra-low-power mode (PLL OFF)	-	194	208	µA
		Stop state - 1 data lane (PLL OFF)	-	2.74	3.2	mA
		Stop state - 2 data lanes (PLL OFF)	-	4.08	4.8	
I_{DD_DSILP}	DSI system current consumption on V_{DDDSI} in LP mode communication(2)	10 MHz escape clock - 1 data lane (PLL OFF)	-	4.32	4.8	
		10 MHz escape clock - 2 data lanes (PLL OFF)	-	5.65	6.4	
		20 MHz escape clock - 1 data lane (PLL OFF)	-	5.94	6.6	
		20 MHz escape clock - 2 data lanes (PLL OFF)	-	7.27	8.2	
I_{DD_DSIHS}	DSI system (Host, PLL and D-PHY) current consumption on V_{DDDSI} in HS mode communication(3)	300 Mbit/s - 1 data lane (PLL ON)	-	2.98	3.1	
		300 Mbit/s - 2 data lanes (PLL ON)	-	4.33	4.5	
		500 Mbit/s - 1 data lane (PLL ON)	-	3.21	3.4	
		500 Mbit/s - 2 data lanes (PLL ON)	-	4.54	4.8	
	DSI system (Host, PLL and D-PHY) current consumption on V_{DDDSI} in HS mode with CLK like payload	500 Mbit/s - 2 data lanes (PLL ON)	-	4.56	4.8	

1. Evaluated by characterization. Not tested in production.
2. Values based on an average traffic in LP command mode.
3. Values based on an average traffic (3/4 HS traffic and 1/4 LP) in Video mode.

Table 122. DSI current consumption characteristics on $V_{DD11DSI}$(1)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
I_{DD11_DSI}	DSI system (Host, PLL and D-PHY) current consumption on $V_{DD11DSI}$	Ultra-low--power mode (PLL OFF)	-	7.7	48	µA
		Stop state - 1 data lane (PLL OFF)	-	0.56	1.1	mA
		Stop state - 2 data lanes (PLL OFF)	-	0.83	1.7	

Table 122. DSI current consumption characteristics on $V_{DD11DSI}$(1) (continued)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
I_{DD11_DSILP}	DSI system current consumption on $V_{DD11DSI}$ in LP mode communication(2)	10 MHz escape clock - 1 data lane (PLL OFF)	-	0.56	1.2	mA
		10 MHz escape clock - 2 data lanes (PLL OFF)	-	0.83	1.7	
		20 MHz escape clock - 1 data lane (PLL OFF)	-	0.56	1.2	
		20 MHz escape clock - 2 lanes (PLL OFF)	-	0.83	1.7	
I_{DD11_DSIHS}	DSI system (Host, PLL and D-PHY) current consumption on $V_{DD11DSI}$ in HS mode communication(3)	300 Mbit/s - 1 data lane (PLL ON)	-	6.45	8.5	
		300 Mbit/s - 2 data lanes (PLL ON)	-	7.8	10.3	
		500 Mbit/s - 1 data lane (PLL ON)	-	7.4	9.7	
		500 Mbit/s - 2 data lanes (PLL ON)	-	8.8	11.5	
	DSI system (Host, PLL and D-PHY) current consumption on $V_{DD11DSI}$ in HS mode with CLK like payload	500 Mbit/s - 2 data lanes (PLL ON)	-	10.1	13.3	

1. Evaluated by characterization. Not tested in production.
2. Values based on an average traffic in LP command mode.
3. Values based on an average traffic (3/4 HS traffic and 1/4 LP) in video mode.

5.3.34 Timer characteristics

The parameters given in the following tables are specified by design, not tested in production.

Refer to *Section 5.3.15: I/O port characteristics* for details on the input/output alternate function characteristics (output compare, input capture, external clock, PWM output).

Table 123. TIMx(1) characteristics

Symbol	Parameter	Conditions	Min	Max	Unit
$t_{res(TIM)}$	Timer resolution time	-	1	-	$t_{TIMxCLK}$
		$f_{TIMxCLK}$ = 160 MHz	6.25	-	ns
f_{EXT}	Timer external clock frequency on CH1 to CH4	-	0	$f_{TIMxCLK}/2$	MHz
		$f_{TIMxCLK}$ = 160 MHz	0	80	
Res_{TIM}	Timer resolution	TIMx (except TIM2/3/4/5)	-	16	bit
		TIM2/3/4/5	-	32	
$t_{COUNTER}$	16-bit counter clock period	-	1	65536	$t_{TIMxCLK}$
		$f_{TIMxCLK}$ = 160 MHz	0.007	409.6	µs

Table 123. TIMx(1) characteristics (continued)

Symbol	Parameter	Conditions	Min	Max	Unit
t_{MAX_COUNT}	Maximum possible count with 32-bit counter	-	-	65536 × 65536	$t_{TIMxCLK}$
		$f_{TIMxCLK}$ = 160 MHz	-	26.843	s

1. TIMx, is used as a general term in which x stands for 1,2,3,4,5,6,7,8,15,16 or 17.

Table 124. IWDG min/max timeout period at 32 kHz (LSI)(1)

Prescaler divider	PR[2:0] bits	Min timeout RL[11:0] = 0x000	Max timeout RL[11:0] = 0xFFF	Unit
/4	0	0.125	512	ms
/8	1	0.250	1024	
/16	2	0.500	2048	
/32	3	1.0	4096	
/64	4	2.0	8192	
/128	5	4.0	16384	
/256	6 or 7	8.0	32768	

1. The exact timings still depend on the phasing of the APB interface clock versus the LSI clock, so that there is always a full RC period of uncertainty.

Table 125. WWDG min/max timeout value at 160 MHz (PCLK)

Prescaler	WDGTB	Min timeout value	Max timeout value	Unit
1	0	0.025	1.638	ms
2	1	0.051	3.276	
4	2	0.102	6.553	
8	3	0.204	13.107	
16	4	0.409	26.214	
32	5	0.819	52.428	
64	6	1.638	104.858	
128	7	3.276	209.715	

5.3.35 FSMC characteristics

Unless otherwise specified, the parameters given in the tables below are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30 pF, unless otherwise specified
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output characteristics.

Asynchronous waveforms and timings

Figure 56 to *Figure 59* represent asynchronous waveforms and *Table 126* to *Table 133* provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- AddressSetupTime (ADDSET) = 0x1
- AddressHoldTime (ADDHLD) = 0x1
- ByteLaneSetup (NBLSET) = 0x1
- DataSetupTime (DATAST) = 0x1 (except for asynchronous NWAIT mode, DataSetupTime = 0x5)
- DataHoldTime (DATAHLD) = 0x1 (0x0 for write operation)
- BusTurnAroundDuration = 0x0
- Capacitive load C_L = 30 pF

In all timing tables, the T_{HCLK} is the HCLK clock period.

Figure 56. Asynchronous non-multiplexed SRAM/PSRAM/NOR read waveforms

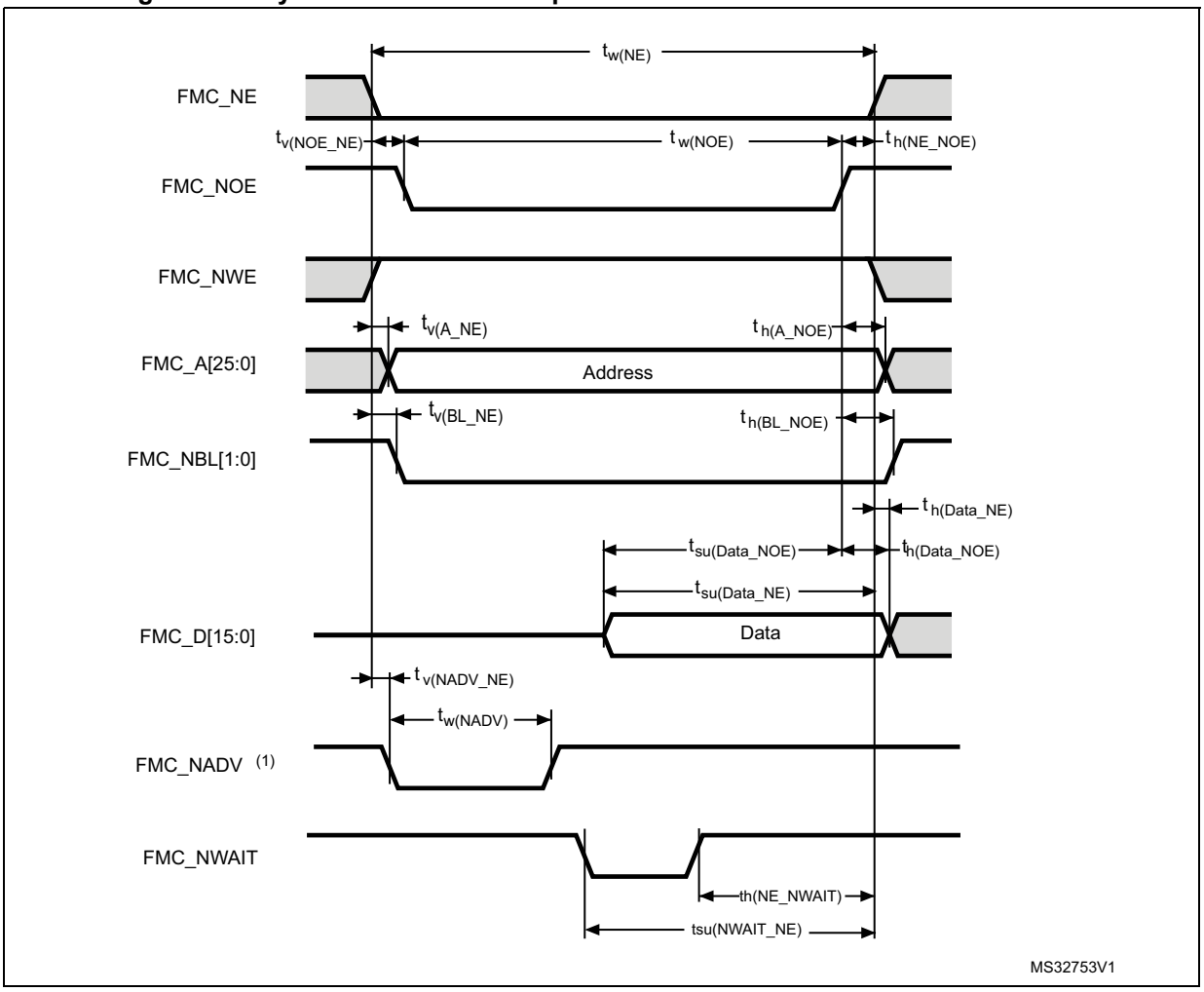


Table 126. Asynchronous non-multiplexed SRAM/PSRAM/NOR read timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$3 \times t_{HCLK} - 1$	$3 \times t_{HCLK} + 1$	ns
$t_{v(NOE_NE)}$	FMC_NEx low to FMC_NOE low	0	5	
$t_{w(NOE)}$	FMC_NOE low time	$2 \times t_{HCLK} - 1$	$2 \times t_{HCLK} + 1$	
$t_{h(NE_NOE)}$	FMC_NOE high to FMC_NE high hold time	T_{HCLK}	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	2	
$t_{h(A_NOE)}$	Address hold time after FMC_NOE high	$2 \times t_{HCLK} - 1$	-	
$t_{su(Data_NE)}$	Data to FMC_NEx high setup time	$t_{HCLK} + 15$	-	
$t_{su(Data_NOE)}$	Data to FMC_NOEx high setup time	15	-	
$t_{h(Data_NOE)}$	Data hold time after FMC_NOE high	0	-	
$t_{h(Data_NE)}$	Data hold time after FMC_NEx high	0	-	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	-	1.5	
$t_{w(NADV)}$	FMC_NADV low time	-	$T_{HCLK} + 1$	

1. Evaluated by characterization. Not tested in production.

Table 127. Asynchronous non-multiplexed SRAM/PSRAM/NOR read-NWAIT timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$8 \times t_{HCLK} - 1$	$8 \times t_{HCLK} + 1$	ns
$t_{w(NOE)}$	FMC_NWE low time	$7 \times t_{HCLK} - 1$	$7 \times t_{HCLK} + 1$	
$t_{w(NWAIT)}$	FMC_NWAIT(2) low time	t_{HCLK}	-	
$t_{su(NWAIT_NE)}$	FMC_NWAIT valid before FMC_NEx high	$5 \times t_{HCLK} + 9.5$	-	
$t_{h(NE_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$4 \times t_{HCLK} + 10$	-	

1. Evaluated by characterization. Not tested in production.
2. NWAIT pulse is equal to one HCLK cycle.

Figure 57. Asynchronous non-multiplexed SRAM/PSRAM/NOR write waveforms

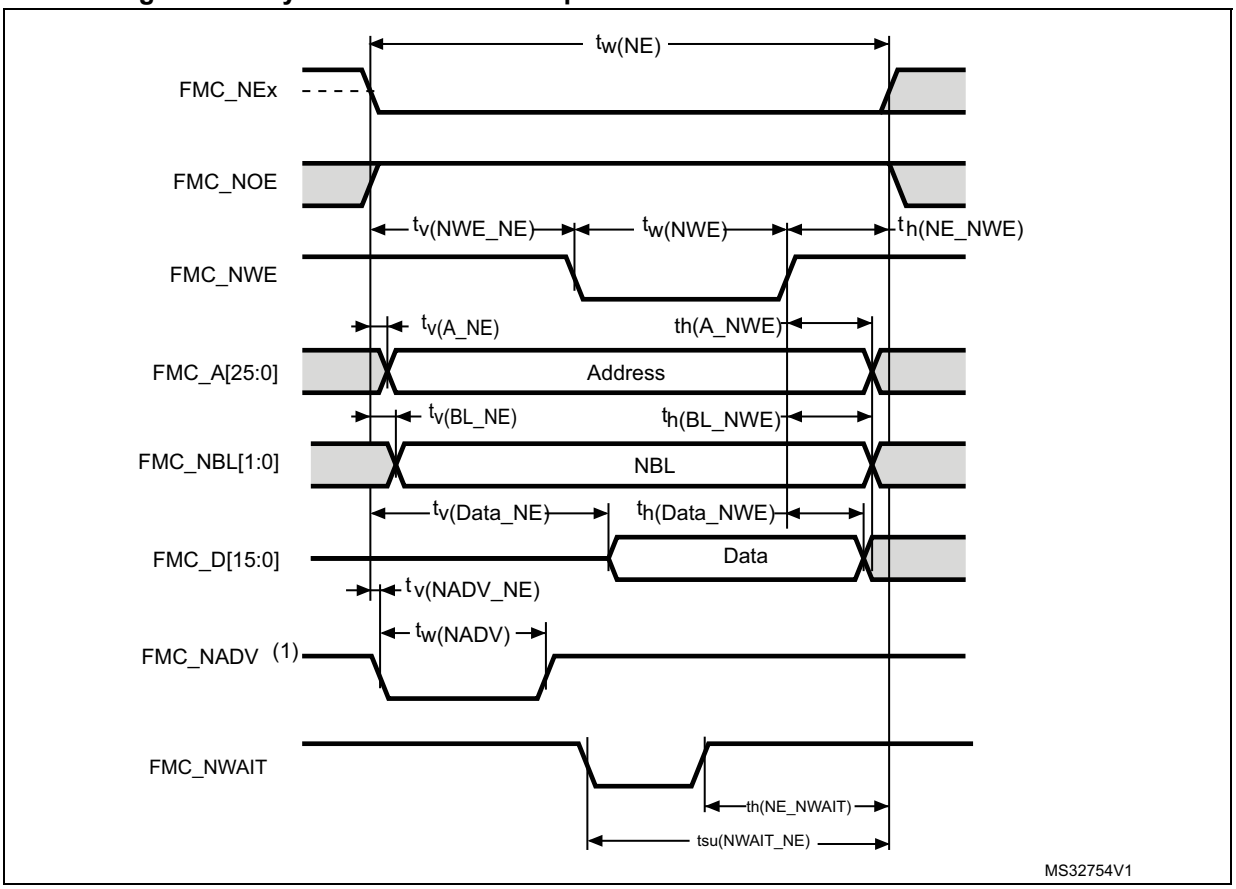


Table 128. Asynchronous non-multiplexed SRAM/PSRAM/NOR write timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$3 \times t_{HCLK} - 1$	$3 \times t_{HCLK} + 1$	ns
$t_{v(NWE_NE)}$	FMC_NEx low to FMC_NWE low	$t_{HCLK} - 1$	t_{HCLK}	
$t_{w(NWE)}$	FMC_NWE low time	$t_{HCLK} - 0.5$	$t_{HCLK} + 0.5$	
$t_{h(NE_NWE)}$	FMC_NWE high to FMC_NE high hold time	t_{HCLK}	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	1	
$t_{h(A_NWE)}$	Address hold time after FMC_NWE high	$t_{HCLK} - 0.5$	-	
$t_{v(BL_NE)}$	FMC_NEx low to FMC_BL valid	-	0.5	
$t_{h(BL_NWE)}$	FMC_BL hold time after FMC_NWE high	$t_{HCLK} - 0.5$	-	
$t_{v(Data_NE)}$	FMC_NEx low to Data valid	-	$t_{HCLK} + 2$	
$t_{h(Data_NWE)}$	Data hold time after FMC_NWE high	t_{HCLK}	-	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	-	2	
$t_{w(NADV)}$	FMC_NADV low time	-	$t_{HCLK} + 1$	

1. Evaluated by characterization. Not tested in production.

Table 129. Asynchronous non-multiplexed SRAM/PSRAM/NOR write-NWAIT timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$8 \times t_{HCLK} - 1$	$8 \times t_{HCLK} + 1$	ns
$t_{w(NWE)}$	FMC_NWE low time	$6 \times t_{HCLK} - 1$	$6 \times t_{HCLK} + 1$	
$t_{su(NWAIT_NE)}$	FMC_NWAIT(2) valid before FMC_NEx high	$5 \times t_{HCLK} + 13$	-	
$t_{h(NE_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$4 \times t_{HCLK} + 12$	-	

1. Evaluated by characterization. Not tested in production.
2. NWAIT pulse is equal to one HCLK cycle.

Figure 58. Asynchronous multiplexed PSRAM/NOR read waveforms

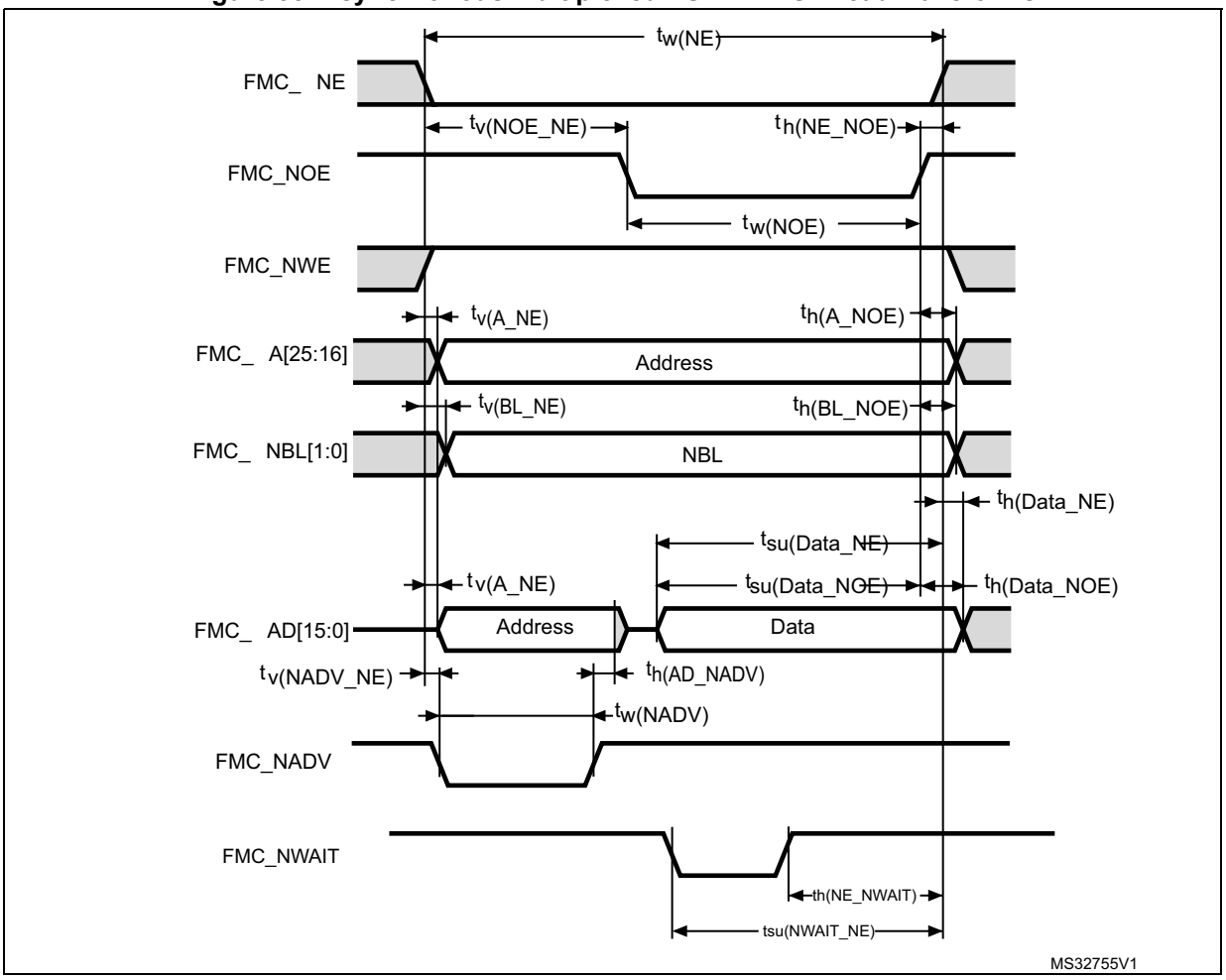


Table 130. Asynchronous multiplexed PSRAM/NOR read timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$3 \times t_{HCLK} - 1$	$3 \times t_{HCLK} + 1$	ns
$t_{v(NOE_NE)}$	FMC_NEx low to FMC_NOE low	0	5	
$t_{w(NOE)}$	FMC_NOE low time	$2 \times t_{HCLK} - 0.5$	$2 \times t_{HCLK} + 0.5$	
$t_{h(NE_NOE)}$	FMC_NOE high to FMC_NE high hold time	t_{HCLK}	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	1.5	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	0	1.5	
$t_{w(NADV)}$	FMC_NADV low time	$t_{HCLK} - 0.5$	$t_{HCLK} + 1$	
$t_{h(AD_NADV)}$	FMC_AD(address) valid hold time after FMC_NADV high)	$t_{HCLK} - 4$	-	
$t_{h(A_NOE)}$	Address hold time after FMC_NOE high	$t_{HCLK} - 1$	-	
$t_{su(Data_NE)}$	Data to FMC_NEx high setup time	$t_{HCLK} + 15$	-	
$t_{su(Data_NOE)}$	Data to FMC_NOE high setup time	15	-	
$t_{h(Data_NE)}$	Data hold time after FMC_NEx high	0	-	
$t_{h(Data_NOE)}$	Data hold time after FMC_NOE high	0	-	

1. Evaluated by characterization. Not tested in production.

Table 131. Asynchronous multiplexed PSRAM/NOR read-NWAIT timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$8 \times t_{HCLK} - 1$	$8 \times t_{HCLK} + 1$	ns
$t_{w(NOE)}$	FMC_NOE low time	$7 \times t_{HCLK} - 1$	$7 \times t_{HCLK} + 1$	
$t_{su(NWAIT_NE)}$	FMC_NWAIT(2) valid before FMC_NEx high	$4 \times t_{HCLK} + 9.5$	-	
$t_{h(NE_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$3 \times t_{HCLK} + 10$	-	

1. Evaluated by characterization. Not tested in production.
2. NWAIT pulse is equal to one HCLK cycle.

Figure 59. Asynchronous multiplexed PSRAM/NOR write waveforms

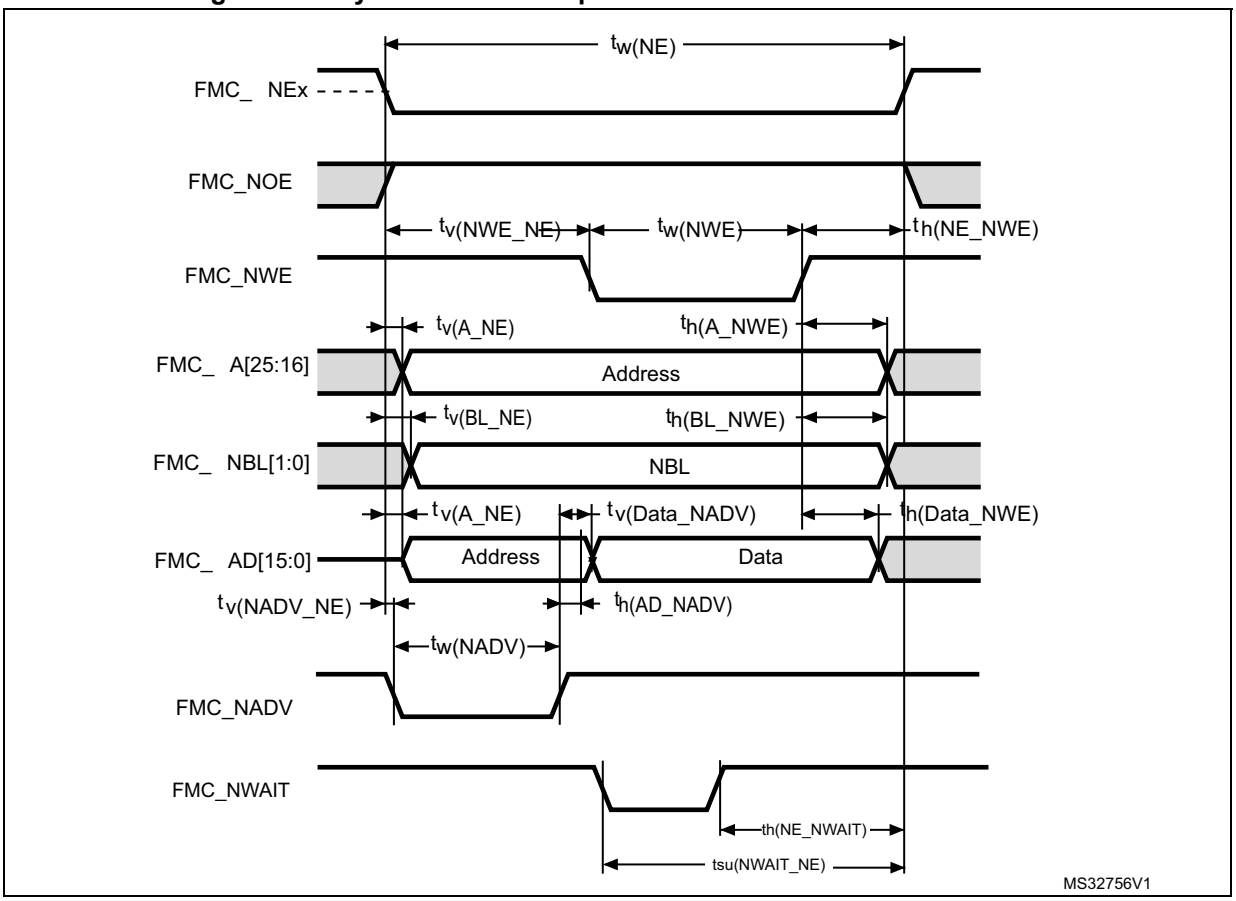


Table 132. Asynchronous multiplexed PSRAM/NOR write timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$3 \times t_{HCLK} - 1$	$3 \times t_{HCLK}$	ns
$t_{v(NWE_NE)}$	FMC_NEx low to FMC_NWE low	$t_{HCLK} - 1$	t_{HCLK}	
$t_{w(NWE)}$	FMC_NWE low time	$2 \times t_{HCLK} - 0.5$	$2 \times t_{HCLK} + 1$	
$t_{h(NE_NWE)}$	FMC_NWE high to FMC_NE high hold time	t_{HCLK}	-	
$t_{v(A_NE)}$	FMC_NEx low to FMC_A valid	-	1	
$t_{v(NADV_NE)}$	FMC_NEx low to FMC_NADV low	0	2	
$t_{w(NADV)}$	FMC_NADV low time	$t_{HCLK} - 0.5$	$t_{HCLK} + 1$	
$t_{h(AD_NADV)}$	FMC_AD(adress) valid hold time after FMC_NADV high)	$t_{HCLK} - 4.5$	-	
$t_{h(A_NWE)}$	Address hold time after FMC_NWE high	$t_{HCLK} - 0.5$	-	
$t_{h(BL_NWE)}$	FMC_BL hold time after FMC_NWE high	$t_{HCLK} - 0.5$	-	
$t_{v(BL_NE)}$	FMC_NEx low to FMC_BL valid	-	0.5	
$t_{v(Data_NADV)}$	FMC_NADV high to Data valid	-	$t_{HCLK} + 2$	
$t_{h(Data_NWE)}$	Data hold time after FMC_NWE high	t_{HCLK}	-	

1. Evaluated by characterization. Not tested in production.

Table 133. Asynchronous multiplexed PSRAM/NOR write-NWAIT timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NE)}$	FMC_NE low time	$8 \times t_{HCLK} - 1$	$8 \times t_{HCLK} + 1$	ns
$t_{w(NWE)}$	FMC_NWE low time	$6 \times t_{HCLK} - 1$	$6 \times t_{HCLK} + 1$	
$t_{su(NWAIT_NE)}$	FMC_NWAIT(2) valid before FMC_NEx high	$5 \times t_{HCLK} + 13$	-	
$t_{h(NE_NWAIT)}$	FMC_NEx hold time after FMC_NWAIT invalid	$4 \times t_{HCLK} + 12$	-	

1. Evaluated by characterization. Not tested in production.
2. NWAIT pulse is equal to one HCLK cycle.

Synchronous waveforms and timings

Figure 60 to *Figure 63* represent synchronous waveforms and *Table 134* to *Table 137* provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- BurstAccessMode = FMC_BurstAccessMode_Enable
- MemoryType = FMC_MemoryType_CRAM
- WriteBurst = FMC_WriteBurst_Enable
- CLKDivision = 1
- DataLatency = 1 for NOR Flash; DataLatency = 0 for PSRAM

In all timing tables, the T_{HCLK} is the HCLK clock period.

- Maximum FMC_CLK = 80 MHz for 2.7 V ≤ V_{DD} ≤ 3.6 V, with C_L = 15pF and with C_L = 20 pF
- Maximum FMC_CLK = 80 MHz for 1.71 V ≤ V_{DD} ≤ 1.9 V with C_L = 15pF and with C_L = 20 pF

Figure 60. Synchronous multiplexed NOR/PSRAM read timings

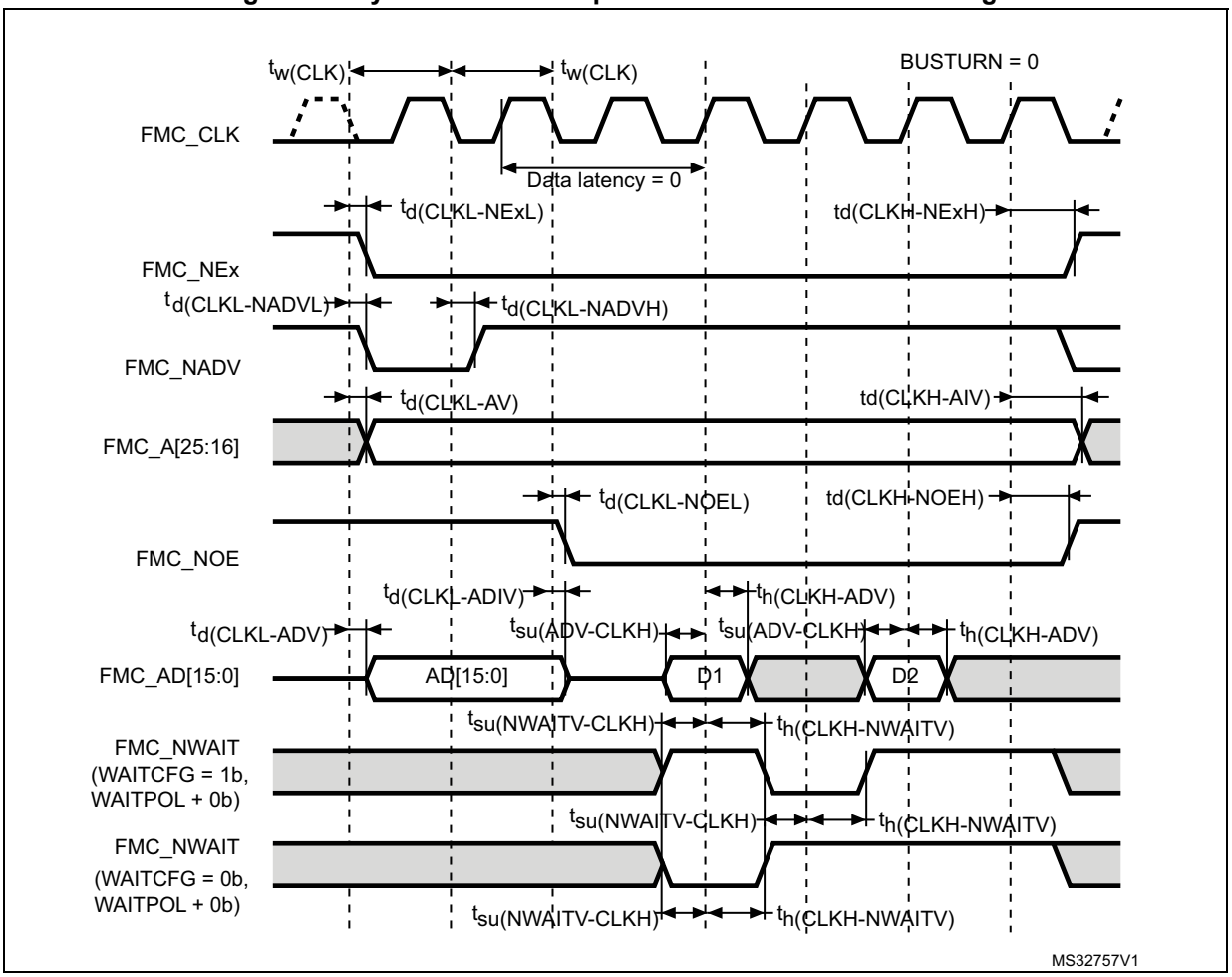


Table 134. Synchronous multiplexed NOR/PSRAM read timings(1)(2)

Symbol	Parameter	Min	Max	Unit
$t_{w(CLK)}$	FMC_CLK period	2 × t_{HCLK} - 0.5	-	ns
$t_{d(CLKL-NExL)}$	FMC_CLK low to FMC_NEx low (x = 0..2)	-	3	
$t_{d(CLKH_NExH)}$	FMC_CLK high to FMC_NEx high (x = 0..2)	t_{HCLK} - 0.5	-	
$t_{d(CLKL-NADVL)}$	FMC_CLK low to FMC_NADV low	-	2.5	
$t_{d(CLKL-NADVH)}$	FMC_CLK low to FMC_NADV high	2	-	
$t_{d(CLKL-AV)}$	FMC_CLK low to FMC_Ax valid (x = 16..25)	-	2.5	
$t_{d(CLKH-AIV)}$	FMC_CLK high to FMC_Ax invalid (x = 16..25)	t_{HCLK} - 0.5	-	

Table 134. Synchronous multiplexed NOR/PSRAM read timings(1)(2) (continued)

Symbol	Parameter	Min	Max	Unit
$t_{d(CLKL-NOEL)}$	FMC_CLK low to FMC_NOE low	-	1.5	ns
$t_{d(CLKH-NOEH)}$	FMC_CLK high to FMC_NOE high	t_{HCLK} + 1	-	
$t_{d(CLKL-ADV)}$	FMC_CLK low to FMC_AD[15:0] valid	-	2	
$t_{d(CLKL-ADIV)}$	FMC_CLK low to FMC_AD[15:0] invalid	0	-	
$t_{su(ADV-CLKH)}$	FMC_A/D[15:0] valid data before FMC_CLK high	3	-	
$t_{h(CLKH-ADV)}$	FMC_A/D[15:0] valid data after FMC_CLK high	4	-	
$t_{su(NWAIT-CLKH)}$	FMC_NWAIT valid before FMC_CLK high	1	-	
$t_{h(CLKH-NWAIT)}$	FMC_NWAIT valid after FMC_CLK high	2.5	-	

1. Evaluated by characterization. Not tested in production.
2. Clock ratio R = (HCLK period /FMC_CLK period).

Figure 61. Synchronous multiplexed PSRAM write timings

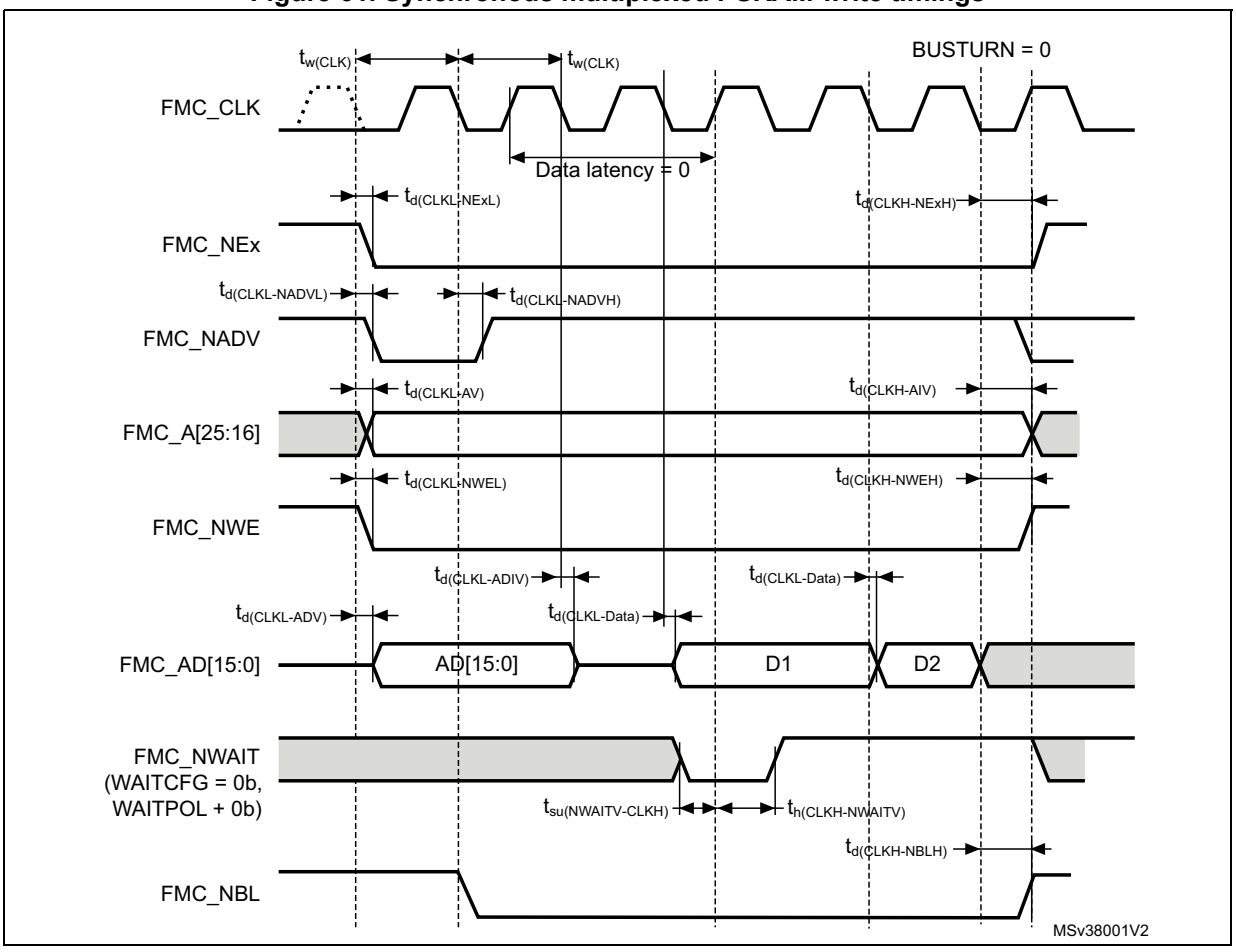


Table 135. Synchronous multiplexed PSRAM write timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(CLK)}$	FMC_CLK period, 2.7 V ≤ VDD ≤ 3.6 V	2 × t_{HCLK} - 0.5	-	ns
$t_{d(CLKL-NExL)}$	FMC_CLK low to FMC_NEx low (x = 0..2)	-	2	
$t_{d(CLKH-NExH)}$	FMC_CLK high to FMC_NEx high (x= 0..2)	t_{HCLK} + 1.5	-	
$t_{d(CLKL-NADVL)}$	FMC_CLK low to FMC_NADV low	-	2	
$t_{d(CLKL-NADVH)}$	FMC_CLK low to FMC_NADV high	2	-	
$t_{d(CLKL-AV)}$	FMC_CLK low to FMC_Ax valid (x = 16..25)	-	3	
$t_{d(CLKH-AIV)}$	FMC_CLK high to FMC_Ax invalid (x = 16..25)	t_{HCLK}	-	
$t_{d(CLKL-NWEL)}$	FMC_CLK low to FMC_NWE low	-	2.5	
$t_{d(CLKH-NWEH)}$	FMC_CLK high to FMC_NWE high	t_{HCLK} + 1	-	
$t_{d(CLKL-ADV)}$	FMC_CLK low to FMC_AD[15:0] valid	-	2	
$t_{d(CLKL-ADIV)}$	FMC_CLK low to FMC_AD[15:0] invalid	0	-	
$t_{d(CLKL-DATA)}$	FMC_A/D[15:0] valid data after FMC_CLK low	-	3	
$t_{d(CLKL-NBLL)}$	FMC_CLK low to FMC_NBL low	-	2	
$t_{d(CLKH-NBLH)}$	FMC_CLK high to FMC_NBL high	t_{HCLK} + 0.5	-	
$t_{su(NWAIT-CLKH)}$	FMC_NWAIT valid before FMC_CLK high	3	-	
$t_{h(CLKH-NWAIT)}$	FMC_NWAIT valid after FMC_CLK high	2.5	-	

1. Evaluated by characterization. Not tested in production.

Figure 62. Synchronous non-multiplexed NOR/PSRAM read timings

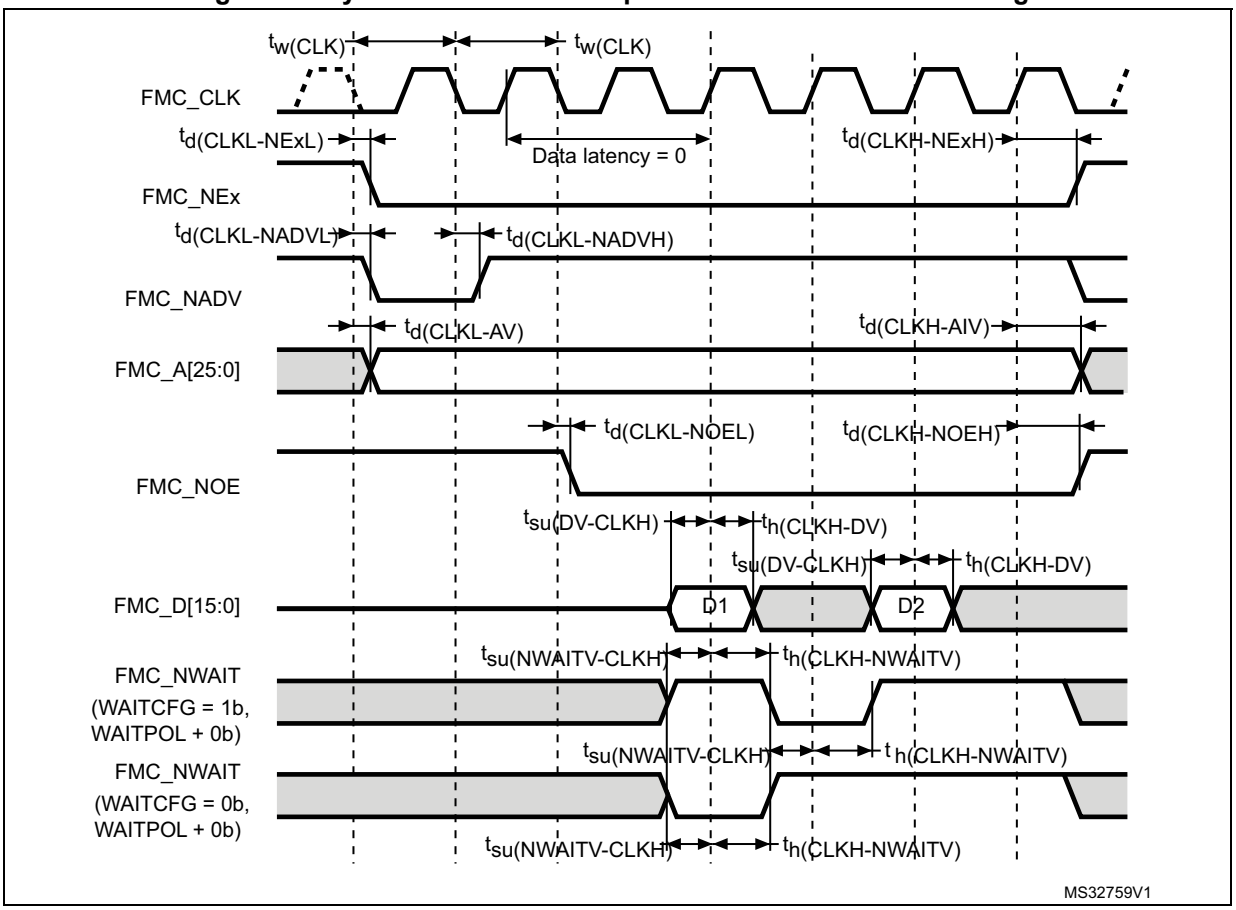


Table 136. Synchronous non-multiplexed NOR/PSRAM read timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(CLK)}$	FMC_CLK period	$2 \times t_{HCLK}$ - 0.5	-	ns
$t_{d(CLKL-NExL)}$	FMC_CLK low to FMC_NEx low (x=0..2)	-	3	
$t_{d(CLKH-NExH)}$	FMC_CLK high to FMC_NEx high (x= 0…2)	t_{HCLK} - 0.5	-	
$t_{d(CLKL-NADVL)}$	FMC_CLK low to FMC_NADV low	-	2.5	
$t_{d(CLKL-NADVH)}$	FMC_CLK low to FMC_NADV high	2	-	
$t_{d(CLKL-AV)}$	FMC_CLK low to FMC_Ax valid (x=0…25)	-	2.5	
$t_{d(CLKH-AIV)}$	FMC_CLK high to FMC_Ax invalid (x=0…25)	t_{HCLK} - 0.5	-	
$t_{d(CLKL-NOEL)}$	FMC_CLK low to FMC_NOE low	-	1.5	
$t_{d(CLKH-NOEH)}$	FMC_CLK high to FMC_NOE high	t_{HCLK} + 1	-	
$t_{su(DV-CLKH)}$	FMC_D[15:0] valid data before FMC_CLK high	4	-	
$t_{h(CLKH-DV)}$	FMC_D[15:0] valid data after FMC_CLK high	4	-	
$t_{su(NWAIT-CLKH)}$	FMC_NWAIT valid before FMC_CLK high	1	-	
$t_{h(CLKH-NWAIT)}$	FMC_NWAIT valid after FMC_CLK high	2.5	-	

1. Evaluated by characterization. Not tested in production.

Figure 63. Synchronous non-multiplexed PSRAM write timings

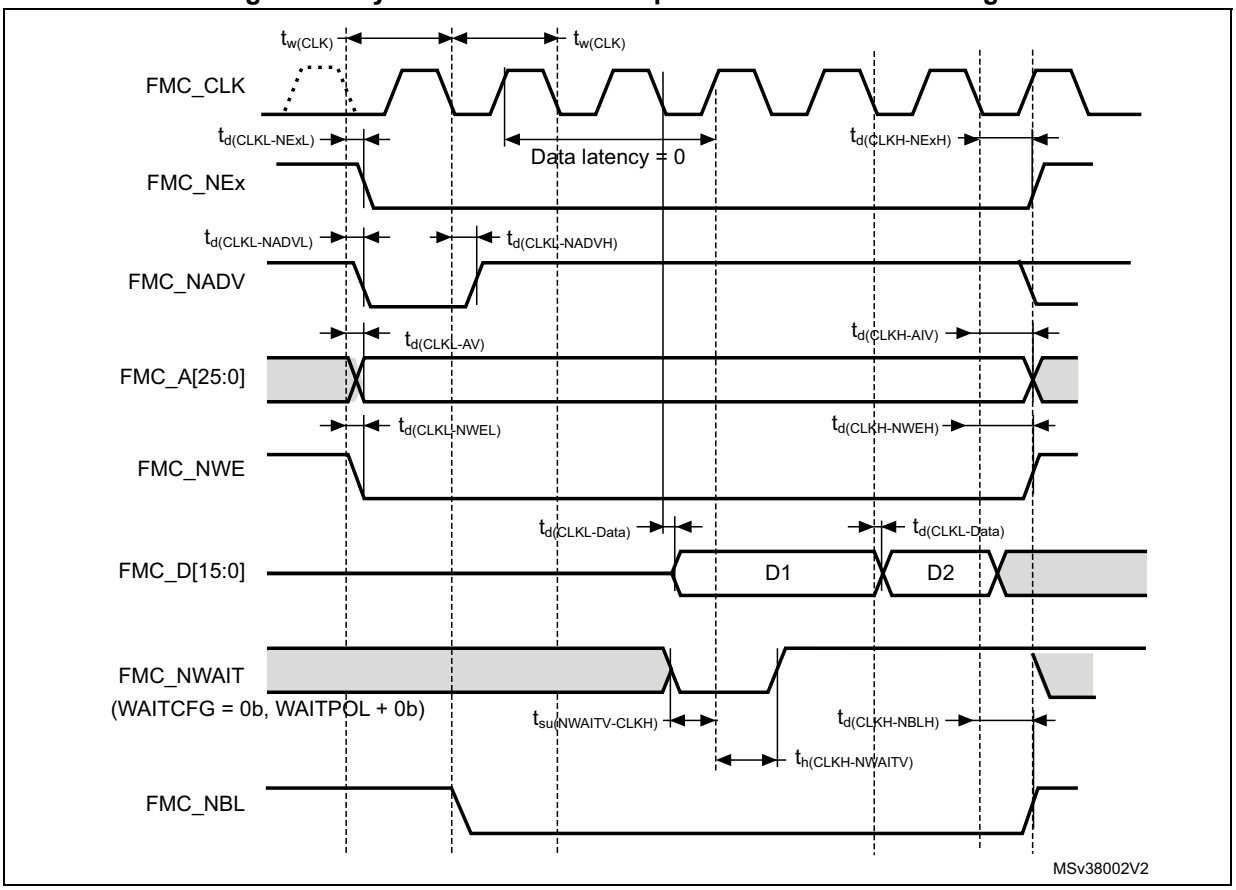


Table 137. Synchronous non-multiplexed PSRAM write timings(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(CLK)}$	FMC_CLK period	$2 \times t_{HCLK} - 0.5$	-	ns
$t_{d(CLKL-NExL)}$	FMC_CLK low to FMC_NEx low (x = 0..2)	-	3	
$t_{d(CLKH-NExH)}$	FMC_CLK high to FMC_NEx high (x = 0..2)	$t_{HCLK} + 1.5$	-	
$t_{d(CLKL-NADVL)}$	FMC_CLK low to FMC_NADV low	-	2	
$t_{d(CLKL-NADVH)}$	FMC_CLK low to FMC_NADV high	2	-	
$t_{d(CLKL-AV)}$	FMC_CLK low to FMC_Ax valid (x = 16..25)	-	3	
$t_{d(CLKH-AIV)}$	FMC_CLK high to FMC_Ax invalid (x = 16..25)	t_{HCLK}	-	
$t_{d(CLKL-NWEL)}$	FMC_CLK low to FMC_NWE low	-	2.5	
$t_{d(CLKH-NWEH)}$	FMC_CLK high to FMC_NWE high	$t_{HCLK} + 1$	-	
$t_{d(CLKL-Data)}$	FMC_D[15:0] valid data after FMC_CLK low	-	3	
$t_{d(CLKL-NBLL)}$	FMC_CLK low to FMC_NBL low	-	2	
$t_{d(CLKH-NBLH)}$	FMC_CLK high to FMC_NBL high	$t_{HCLK} + 0.5$	-	

Table 137. Synchronous non-multiplexed PSRAM write timings(1) (continued)

Symbol	Parameter	Min	Max	Unit
$t_{su(NWAIT-CLKH)}$	FMC_NWAIT valid before FMC_CLK high	3	-	ns
$t_{h(CLKH-NWAIT)}$	FMC_NWAIT valid after FMC_CLK high	2.5	-	

1. Evaluated by characterization. Not tested in production.

NAND controller waveforms and timings

Figure 64 to *Figure 67* represent synchronous waveforms, and *Table 138*/*Table 139* provide the corresponding timings. The results shown in these tables are obtained with the following FMC configuration:

- COM.FMC_SetupTime = 0x01
- COM.FMC_WaitSetupTime = 0x03
- COM.FMC_HoldSetupTime = 0x02
- COM.FMC_HiZSetupTime = 0x01
- ATT.FMC_SetupTime = 0x01
- ATT.FMC_WaitSetupTime = 0x03
- ATT.FMC_HoldSetupTime = 0x02
- ATT.FMC_HiZSetupTime = 0x01
- Bank = FMC_Bank_NAND
- MemoryDataWidth = FMC_MemoryDataWidth_16b
- ECC = FMC_ECC_Enable
- ECCPageSize = FMC_ECCPageSize_512Bytes
- TCLRSetupTime = 0
- TARSetupTime = 0

In all timing tables, the T_{HCLK} is the HCLK clock period.

Figure 64. NAND controller waveforms for read access

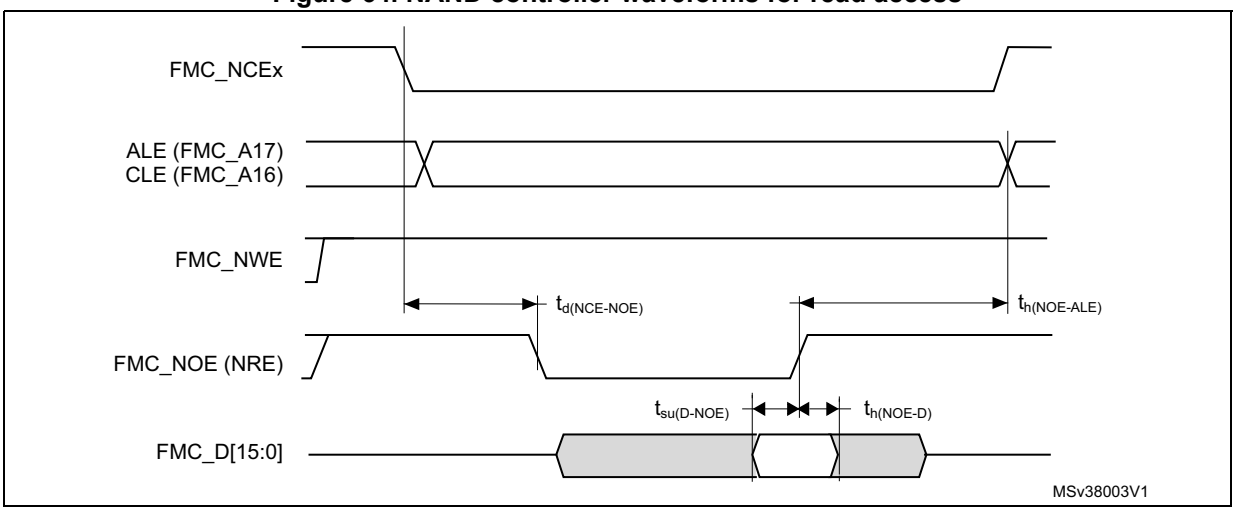


Figure 65. NAND controller waveforms for write access

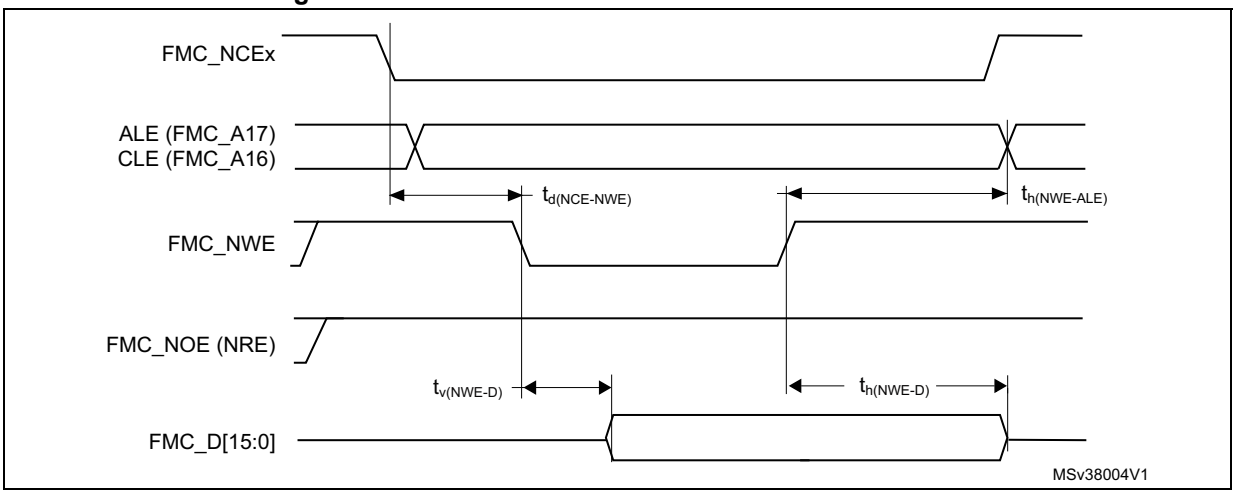


Figure 66. NAND controller waveforms for common memory read access

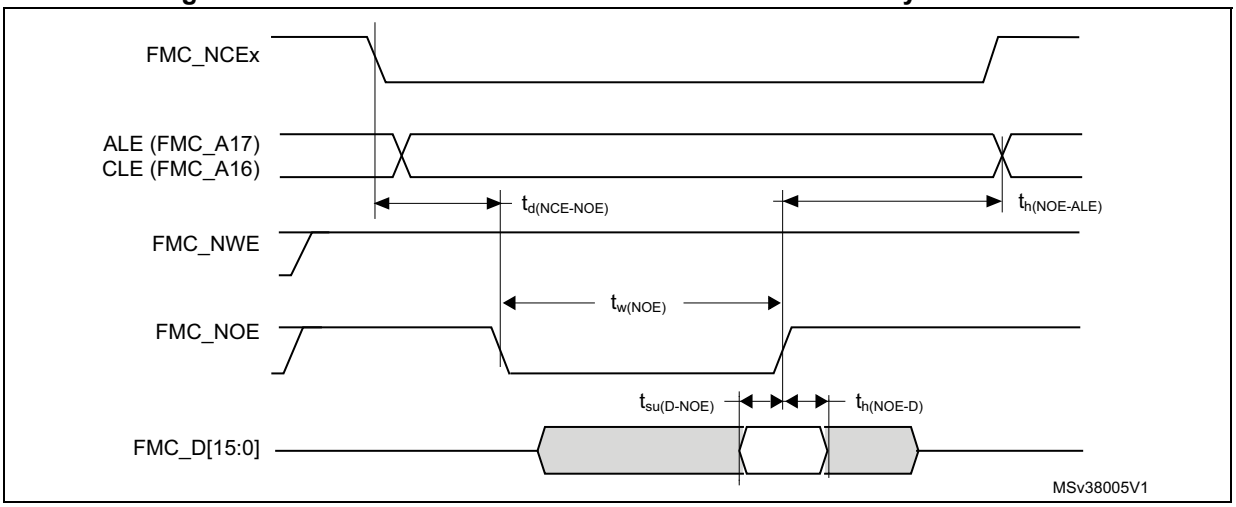


Figure 67. NAND controller waveforms for common memory write access

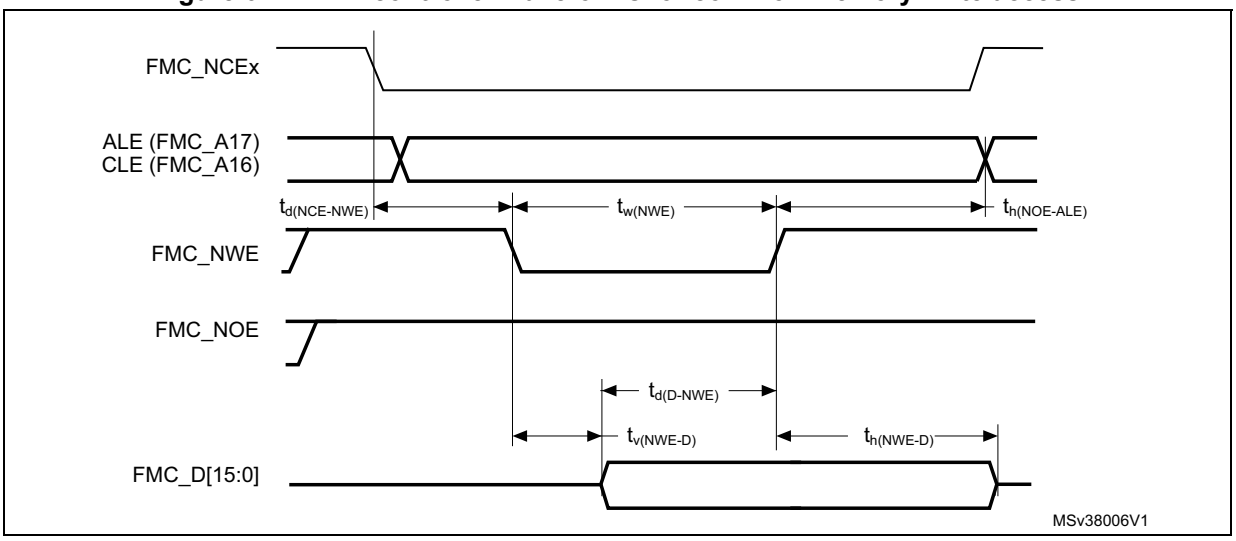


Table 138. Switching characteristics for NAND Flash read cycles(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(N0E)}$	FMC_NOE low width	$4 \times t_{HCLK} - 0.5$	$4 \times t_{HCLK} + 0.5$	ns
$t_{su(D-NOE)}$	FMC_D[15-0] valid data before FMC_NOE high	13	-	
$t_{h(NOE-D)}$	FMC_D[15-0] valid data after FMC_NOE high	0	-	
$t_{d(ALE-NOE)}$	FMC_ALE valid before FMC_NOE low	-	$3 \times t_{HCLK} + 0.5$	
$t_{h(NOE-ALE)}$	FMC_NWE high to FMC_ALE invalid	$4 \times t_{HCLK} - 1$	-	

1. Evaluated by characterization. Not tested in production.

Table 139. Switching characteristics for NAND Flash write cycles(1)

Symbol	Parameter	Min	Max	Unit
$t_{w(NWE)}$	FMC_NWE low width	$4 \times t_{HCLK} - 0.5$	$4 \times t_{HCLK} + 0.5$	ns
$t_{v(NWE-D)}$	FMC_NWE low to FMC_D[15-0] valid	0	-	
$t_{h(NWE-D)}$	FMC_NWE high to FMC_D[15-0] invalid	$2 \times t_{HCLK} + 1$	-	
$t_{d(D-NWE)}$	FMC_D[15-0] valid before FMC_NWE high	$5 \times t_{HCLK} - 5$	-	
$t_{d(ALE_NWE)}$	FMC_ALE valid before FMC_NWE low	-	$3 \times t_{HCLK} + 0.5$	
$t_{h(NWE-ALE)}$	FMC_NWE high to FMC_ALE invalid	$2 \times t_{HCLK} - 0.5$	-	

1. Evaluated by characterization. Not tested in production.

5.3.36 OCTOSPI characteristics

Unless otherwise specified, the parameters given in *Table 140* to *Table 142* are derived from tests performed under the ambient temperature, f_{AHB} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- Delay block enabled for DTR (with DQS)/HyperBus
- Measurement points done at $0.5 \times V_{DD}$ level
- I/O compensation cell activated
- HSLV activated when $V_{DD} \leq 2.7$ V
- Voltage scaling range 1 unless otherwise specified

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output alternate function characteristics.

Table 140. OCTOSPI characteristics in SDR mode(1)(2)(3)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{(CLK)}$	OCTOSPI clock frequency	1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	93	MHz
		2.7 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	100	
		1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 4 C_L = 15 pF	-	-	25	
$t_{w(CLKH)}$	OCTOSPI clock high and low time (even division)	PRESCALER[7:0] = n (n = 0, 1, 3, 5,..255)	$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$	ns
$t_{w(CLKL)}$			$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$	
$t_{w(CLKH)}$	OCTOSPI clock high and low time (odd division)	PRESCALER[7:0] = n (n = 2, 4, 6,..254)	(n/2) × $t_{(CLK)}$ /(n+1) - 0.5	-	(n/2) × $t_{(CLK)}$ /(n+1)	
$t_{w(CLKL)}$			((n/2)+1) × $t_{(CLK)}$ /(n+1) - 0.5	-	((n/2)+1) × $t_{(CLK)}$ /(n+1)	
$t_{s(IN)}$	Data input setup time	Voltage range 1	2.5	-	-	
		Voltage range 4	6	-	-	
$t_{h(IN)}$	Data input hold time	Voltage range 1	0.5	-	-	
		Voltage range 4	1	-	-	
$t_{v(OUT)}$	Data output valid time	Voltage range 1	-	0.5	1	
		Voltage range 4	-	1.5	2.5	
$t_{h(OUT)}$	Data output hold time	Voltage range 1	-0.5	-	-	
		Voltage range 4	-0.25	-	-	

1. Evaluated by characterization. Not tested in production.
2. Measured values in this table apply to Octo- and Quad-SPI data modes.
3. Delay block bypassed.

Table 141. OCTOSPI characteristics in DTR mode (no DQS)(1)(2)(3)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{(CLK)}$	OCTOSPI clock frequency	1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	93(4)	MHz
		2.7 V ≤ V_{DD} ≤ 3.6 V Voltage range1 C_L = 15 pF	-	-	100(4)	
		1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 4, C_L = 15 pF	-	-	25(4)	

Table 141. OCTOSPI characteristics in DTR mode (no DQS)(1)(2)(3) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{w(CLKH)}$	OCTOSPI clock high and low time (even division)	PRESCALER[7:0] = n (n = 0, 1, 3, 5,..255)	$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	ns
$t_{w(CLKL)}$			$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	
$t_{w(CLKH)}$	OCTOSPI clock high and low time (odd division)	PRESCALER[7:0] = n (n = 2, 4, 6,..254)	(n/2) × $t_{(CLK)}$ /(n+1) - 0.5	-	(n/2) × $t_{(CLK)}$ /(n+1) + 0.5	
$t_{w(CLKL)}$			((n/2)+1) × $t_{(CLK)}$ /(n+1) - 0.5	-	((n/2)+1) × $t_{(CLK)}$ /(n+1) + 0.5	
$t_{sr(IN)}$ $t_{sf(IN)}$	Data input setup time	Voltage range 1	3.25	-	-	
		Voltage range 4	3.75	-	-	
$t_{hr(IN)}$ $t_{hf(IN)}$	Data input hold time	Voltage range 1	1	-	-	
		Voltage range 4	1.5	-	-	
$t_{vr(OUT)}$ $t_{vf(OUT)}$	Data output valid time, DHQC = 0	Voltage range 1	-	6	9.25	
		Voltage range 4	-	13.25	19.75	
	Data output valid time, DHQC = 1	Voltage range 1 All prescaler values (except 0)	-	$t_{(CLK)}/4$ + 0.75	$t_{(CLK)}/4$ + 1.5	
$t_{hr(OUT)}$ $t_{hf(OUT)}$	Data output hold time DHQC = 0	Voltage range 1	4	-	-	
		Voltage range 4	8	-	-	
	Data output hold time DHQC = 1	Voltage range 1 All prescaler values (except 0)	$t_{(CLK)}/4$ - 0.5	-	-	

1. Evaluated by characterization. Not tested in production.
2. Measured values in this table apply to Octo- and Quad-SPI data modes.
3. Delay block bypassed.
4. Activating DHQC is mandatory to reach this frequency.

Table 142. OCTOSPI characteristics in DTR mode (with DQS)/HyperBus(1)(2)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{(CLK)}$	OCTOSPI clock frequency	1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	93(3)(4)	MHz
		2.7 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	100(3)(4)	
		1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 4 C_L = 15 pF	-	-	25(4)	
$t_{w(CLKH)}$	OCTOSPI clock high and low time (even division)	PRESCALER[7:0] = n (n = 0, 1, 3, 5,..255)	$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	ns
$t_{w(CLKL)}$			$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	

Table 142. OCTOSPI characteristics in DTR mode (with DQS)/HyperBus(1)(2) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{w(CLKH)}$	OCTOSPI clock high and low time (odd division)	PRESCALER[7:0] = n (n = 2, 4, 6,..254)	(n/2) × $t_{(CLK)}$ /(n+1) - 0.5	-	(n/2) × $t_{(CLK)}$ /(n+1) + 0.5	ns
$t_{w(CLKL)}$			((n/2)+1) × $t_{(CLK)}$ /(n+1) - 0.5	-	((n/2)+1) × $t_{(CLK)}$ /(n+1) + 0.5	
$t_{v(CLK)}$	Clock valid time	-	-	-	$t_{(CLK)}$ + 2	
$t_{h(CLK)}$	Clock hold time	-	$t_{(CLK)}$/2 - 0.5	-	-	
$V_{ODr(CLK)}$ (5)	CLK, NCLK crossing level on CLK rising edge	V_{DD} = 1.8 V	925	-	1040	mV
$V_{ODf(CLK)}$ (5)	CLK, NCLK crossing level on CLK falling edge	V_{DD} = 1.8 V	870	-	1105	
$t_{w(CS)}$	Chip select high time	-	3 × $t_{(CLK)}$	-	-	ns
$t_{v(DQ)}$	Data input valid time	-	0	-	-	
$t_{v(DS)}$	Data strobe input valid time	-	0	-	-	
$t_{h(DS)}$	Data strobe input hold time	-	0	-	-	
$t_{v(RWDS)}$	Data strobe output valid time	-	-	-	3 × $t_{(CLK)}$	
$t_{sr(DQ)}$ $t_{sf(DQ)}$	Data input setup time	Voltage range 1	-0.25	-	-	
		Voltage range 4	0	-	-	
$t_{hr(DQ)}$ $t_{hf(DQ)}$	Data input hold time	Voltage range 1	1.25	-	-	
		Voltage range 4	1.75	-	-	
$t_{vr(OUT)}$ $t_{vf(OUT)}$	Data output valid time DHQC = 0	Voltage range 1	-	6	9.5	
		Voltage range 4	-	13	19.5	
	Data output valid time DHQC = 1	Voltage range 1 All prescaler values (except 0)	-	$t_{(CLK)}$/4 + 0.5	$t_{(CLK)}$/4 + 1.25	
$t_{hr(OUT)}$ $t_{hf(OUT)}$	Data output hold time DHQC = 0	Voltage range 1	4	-	-	
		Voltage range 4	7.75	-	-	
$t_{hr(OUT)}$	Data output hold time DHQC = 1	Voltage range 1 All prescaler values (except 0)	$t_{(CLK)}$/4 - 0.5	-	-	

1. Evaluated by characterization. Not tested in production.
2. Delay block activated.
3. Maximum frequency values are given for a RWDS to DQ skew of maximum ±1.0 ns.
4. Activating DHQC is mandatory to reach this frequency.
5. Crossing results are in line with specification, except for PA3/PB5 CLK that exceed slightly the specification.

Figure 68. OCTOSPI timing diagram - SDR mode

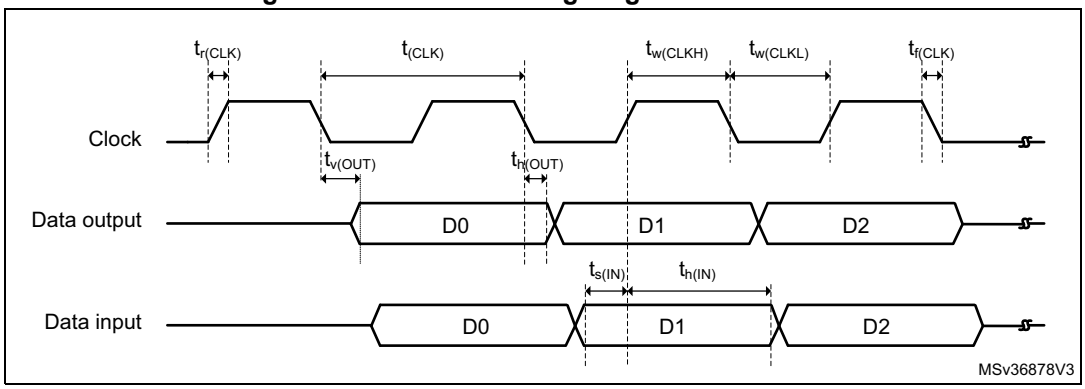


Figure 69. OCTOSPI timing diagram - DTR mode

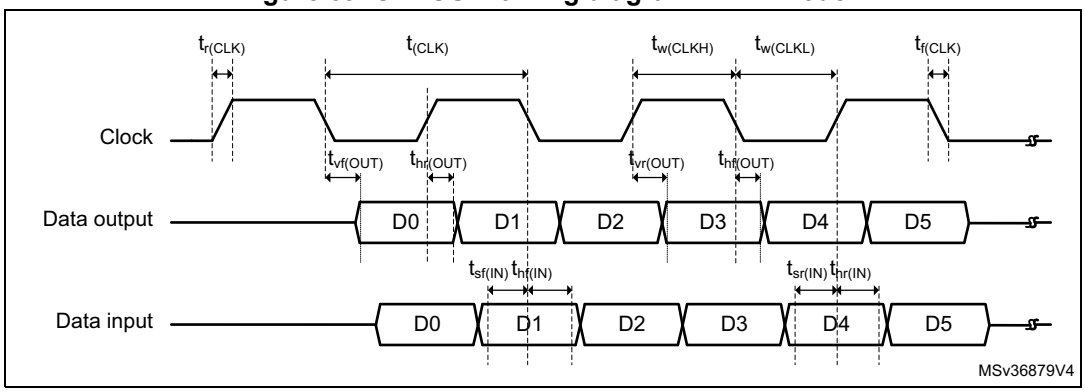


Figure 70. OCTOSPI HyperBus clock

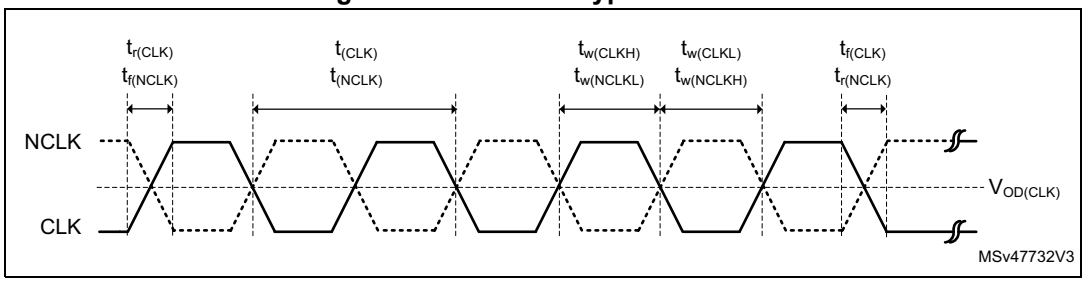


Figure 71. OCTOSPI HyperBus read

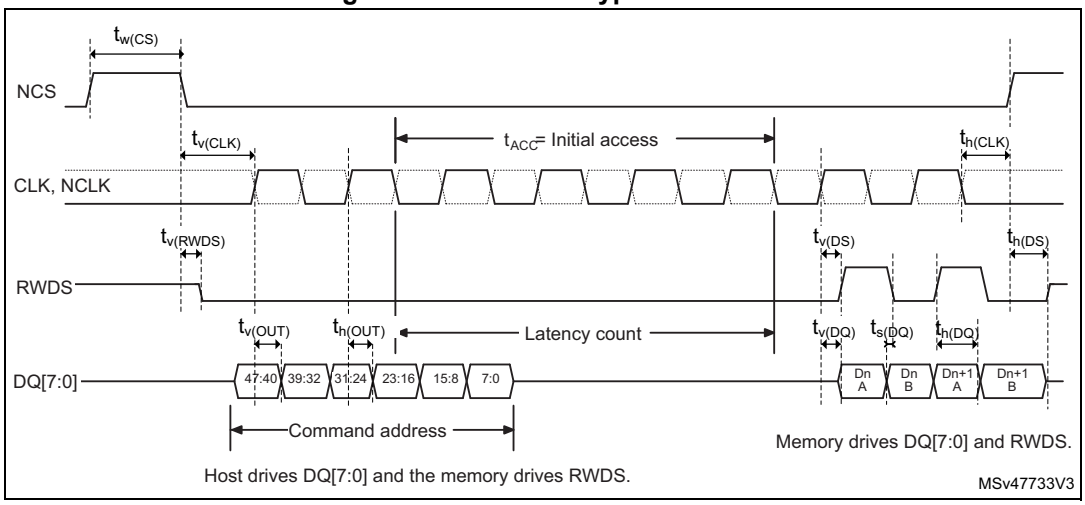


Figure 72. OCTOSPI HyperBus read with double latency

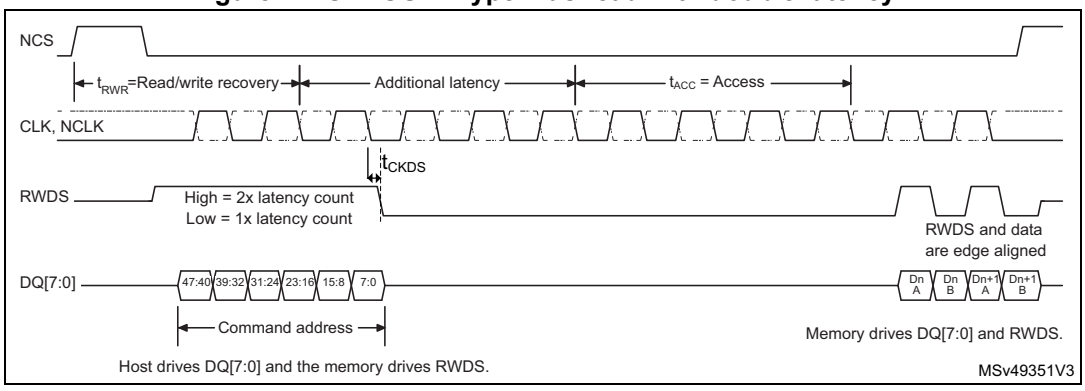
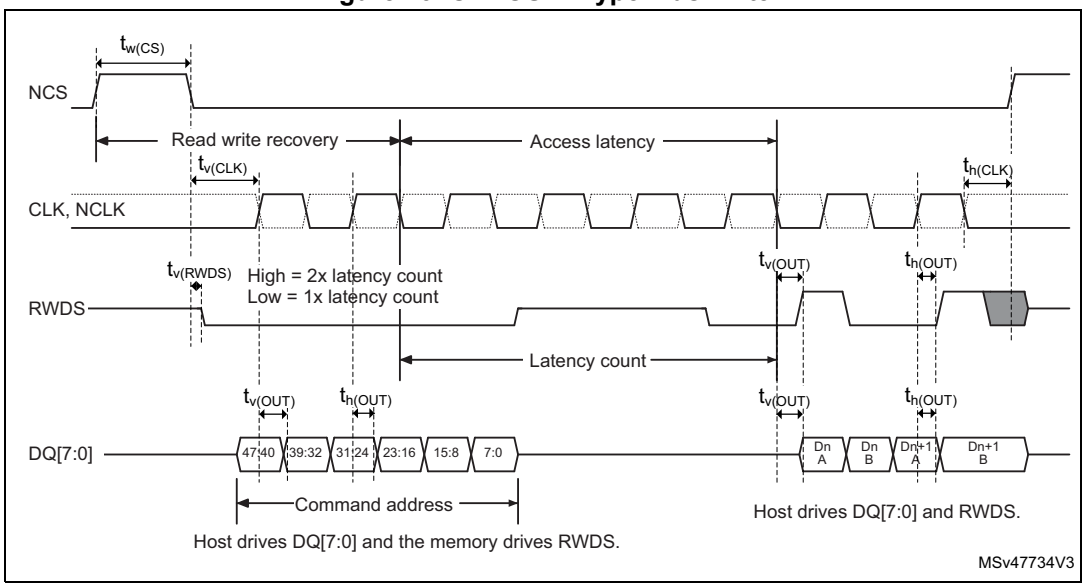


Figure 73. OCTOSPI HyperBus write



5.3.37 HSPI characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{AHB} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 11
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1 unless otherwise specified

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output alternate function characteristics.

Table 143. HSPI characteristics in SDR mode(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{(CLK)}$	HSPI clock frequency	1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	160	MHz
		1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 4 C_L = 15 pF	-	-	25	
$t_{w(CLKH)}$	HSPI clock high and low time (even division)	PRESCALER[7:0] = n (n = 0, 1, 3, 5,..255)	$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$	ns
$t_{w(CLKL)}$			$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$	
$t_{w(CLKH)}$	HSPI clock high and low time (odd division)	PRESCALER[7:0] = n (n = 2, 4, 6,..254)	(n/2) × $t_{(CLK)}$ /(n+1) - 0.5	-	(n/2) × $t_{(CLK)}$ /(n+1)	
$t_{w(CLKL)}$			((n/2)+1) × $t_{(CLK)}$ /(n+1) - 0.5	-	((n/2)+1) × $t_{(CLK)}$ /(n+1)	
$t_{s(IN)}$	Data input setup time	Voltage range 1	2	-	-	
		Voltage range 4	2.5	-	-	
$t_{h(IN)}$	Data input hold time	Voltage range 1	0	-	-	
		Voltage range 4	0.5	-	-	
$t_{v(OUT)}$	Data output valid time	Voltage range 1	-	0.5	1	
		Voltage range 4	-	1.5	2.5	
$t_{h(OUT)}$	Data output hold time	Voltage range 1	0	-	-	
		Voltage range 4	1	-	-	

1. Evaluated by characterization. Not tested in production.

Table 144. HSPI characteristics in DTR mode (no DQS)(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{(CLK)}$	HSPI clock frequency	1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	160	MHz
		1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 4, C_L = 15 pF	-	-	25	
$t_{w(CLKH)}$	HSPI clock high and low time (even division)	PRESCALER[7:0] = n (n = 0, 1, 3, 5,..255)	$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	ns
$t_{w(CLKL)}$			$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	
$t_{w(CLKH)}$	HSPI clock high and low time (odd division)	PRESCALER[7:0] = n (n = 2, 4, 6,..254)	(n/2) × $t_{(CLK)}$ /(n+1) - 0.5	-	(n/2) × $t_{(CLK)}$ /(n+1) + 0.5	
$t_{w(CLKL)}$			((n/2)+1) × $t_{(CLK)}$ /(n+1) - 0.5	-	((n/2)+1) × $t_{(CLK)}$ /(n+1) + 0.5	
$t_{sr(IN)}$ $t_{sf(IN)}$	Data input setup time	Voltage range 1	2	-	-	
		Voltage range 4	3	-	-	
$t_{hr(IN)}$ $t_{hf(IN)}$	Data input hold time	Voltage range 1	0.5	-	-	
		Voltage range 4	1	-	-	
$t_{vr(OUT)}$ $t_{vf(OUT)}$	Data output valid time	Voltage range 1	-	$t_{(CLK)}/4$ + 0.5	$t_{(CLK)}/4$ + 1.5	
		Voltage range 1 (prescaler = 0) with F(CLK) < 50 MHz	-	5.5	6.5	
		Voltage range 4	-	$t_{(CLK)}/4$ + 0.75	$t_{(CLK)}/4$ + 3	
$t_{hr(OUT)}$ $t_{hf(OUT)}$	Data output hold time	Voltage range 1	$t_{(CLK)}/4$ - 1	-	-	
		Voltage range 1 (prescaler = 0) with F(CLK) < 50 MHz	4.75	-	-	
		Voltage range 4	$t_{(CLK)}/4$ - 2	-	-	

1. Evaluated by characterization. Not tested in production.

Table 145. HSPI characteristics in DTR mode (with DQS)/HyperBus(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{(CLK)}$	HSPI clock frequency	1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 1 C_L = 15 pF	-	-	160	MHz
		1.71 V ≤ V_{DD} ≤ 3.6 V Voltage range 4 C_L = 15 pF	-	-	25	
$t_{w(CLKH)}$	HSPI clock high and low time (even division)	PRESCALER[7:0] = n (n = 0, 1, 3, 5,..255)	$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	ns
$t_{w(CLKL)}$			$t_{(CLK)}/2$ - 0.5	-	$t_{(CLK)}/2$ + 0.5	

Table 145. HSPI characteristics in DTR mode (with DQS)/HyperBus(1) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{w(CLKH)}$	HSPI clock high and low time (odd division)	PRESCALER[7:0] = n (n = 2, 4, 6,..254)	(n/2) × $t_{(CLK)}$ /(n+1) - 0.5	-	(n/2) × $t_{(CLK)}$ /(n+1) + 0.5	ns
$t_{w(CLKL)}$			((n/2)+1) × $t_{(CLK)}$ /(n+1) - 0.5	-	((n/2)+1) × $t_{(CLK)}$ /(n+1) + 0.5	
$t_{v(CLK)}$	Clock valid time	-	-	-	$t_{(CLK)}$ - 1.5	
$t_{h(CLK)}$	Clock hold time	-	$t_{(CLK)}/2$ + 1	-	-	
$V_{ODr(CLK)}$	CLK, NCLK crossing level on CLK rising edge	V_{DD} = 1.8 V	860	-	890	mV
$V_{ODf(CLK)}$	CLK, NCLK crossing level on CLK falling edge	V_{DD} = 1.8 V	720	-	740	
$t_{v(DQ)}$	Data input valid time	-	0	-	-	ns
$t_{v(DS)}$	Data strobe input valid time	-	0	-	-	
$t_{h(DS)}$	Data strobe input hold time	-	0	-	-	
$t_{v(RWDS)}$	Data strobe output valid time	-	-	-	$t_{(CLK)}$	
$t_{sr(DQ)}$ $t_{sf(DQ)}$	Data input setup time	Voltage range 1	1 - $t_{(CLK)}/4$	-	-	
		Voltage Range 1, (prescaler = 0) with F(CLK) < 50 MHz	- 6.5	-	-	
		Voltage range 4	0	-	-	
$t_{hr(DQ)}$ $t_{hf(DQ)}$	Data input hold time	Voltage range 1	0.5 + $t_{(CLK)}/4$	-	-	
		Voltage Range 1, (prescaler = 0) with F(CLK) < 50 MHz	6	-	-	
		Voltage range 4	11.5	-	-	
$t_{vr(OUT)}$ $t_{vf(OUT)}$	Data output valid time	Voltage range 1	-	$t_{(CLK)}/4$ + 0.5	$t_{(CLK)}/4$ + 1.5	
		Voltage Range 1, (prescaler = 0) with F(CLK) < 50 MHz	-	5	6.5	
		Voltage range 4	-	$t_{(CLK)}/4$ + 0.75	$t_{(CLK)}/4$ + 3	
$t_{hr(OUT)}$ $t_{hf(OUT)}$	Data output hold time	Voltage range 1	$t_{(CLK)}/4$ - 1	-	-	
		Voltage Range 1, (prescaler = 0) with F(CLK) < 50 MHz	4.75	-	-	
		Voltage range 4	$t_{(CLK)}/4$ - 2	-	-	

1. Evaluated by characterization. Not tested in production.

Figure 74. HSPI timing diagram - SDR mode

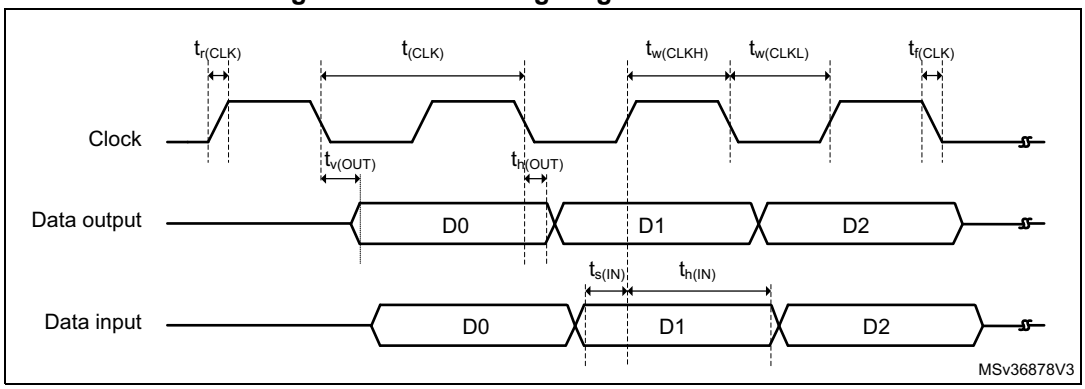


Figure 75. HSPI timing diagram - DTR mode

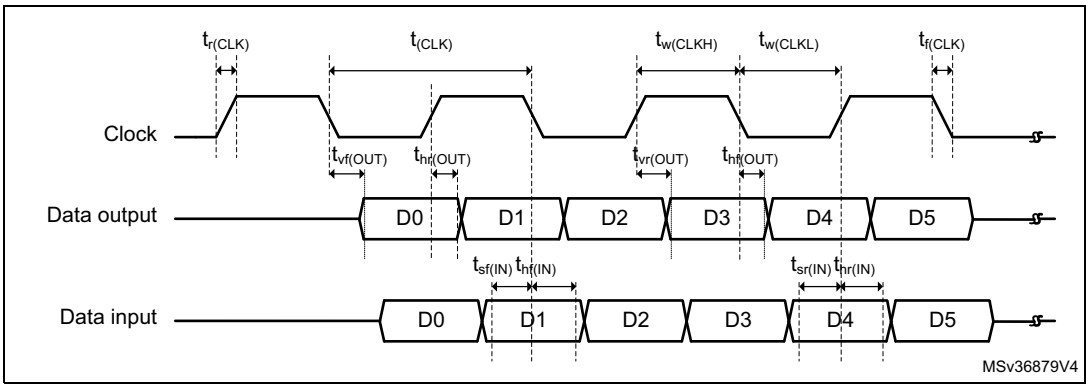


Figure 76. HSPI HyperBus clock

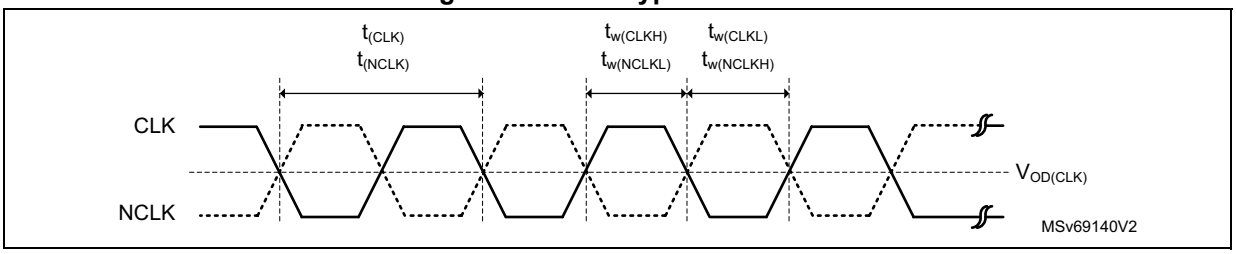


Figure 77. HSPI HyperBus read

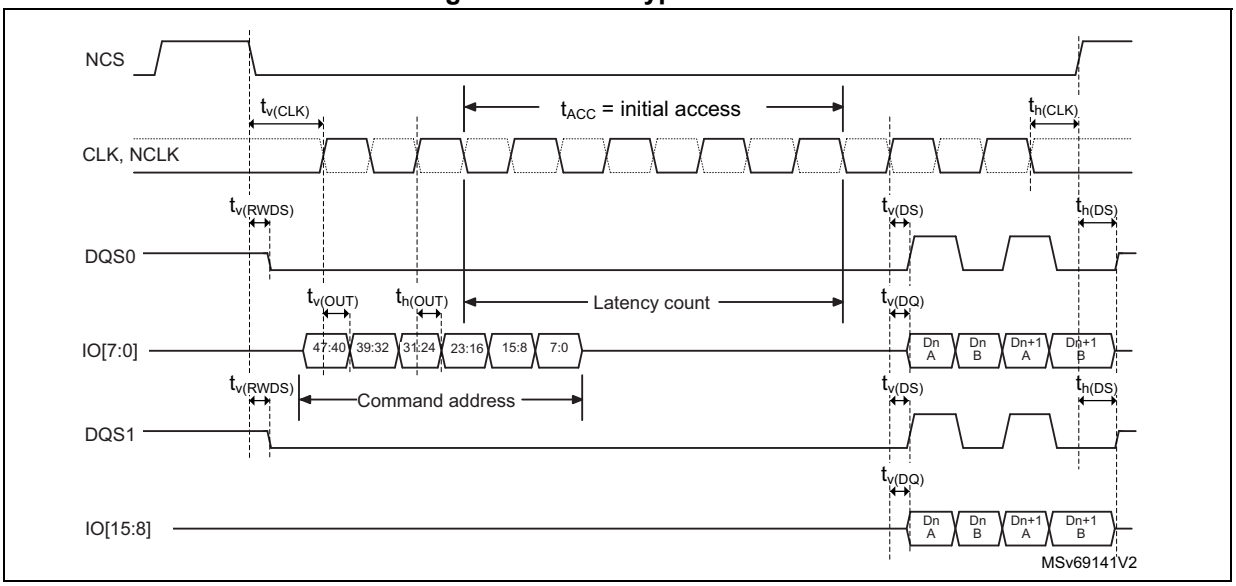
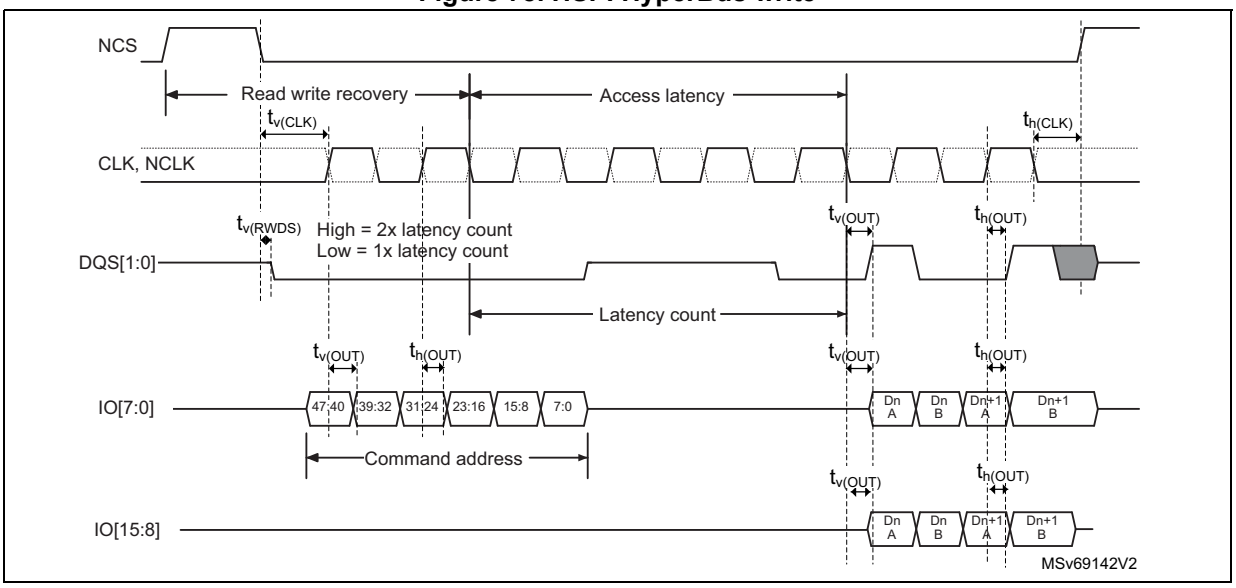


Figure 78. HSPI HyperBus write



5.3.38 SD/SDIO/e•MMC card host interfaces (SDMMC) characteristics

Unless otherwise specified, the parameters given in *Table 146* and *Table 147* are derived from tests performed under the ambient temperature, f_{AHB} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30 pF, unless otherwise specified
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output characteristics.

Table 146. SD/*e*•MMC characteristics (V_{DD} = 2.7 V to 3.6 V)(1)(2)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{PP}	Clock frequency in data transfer mode	-	0	-	100(3)	MHz
$t_{W(CKL)}$	Clock low time	f_{PP} = 52 MHz	8.5	9.5	-	ns
$t_{W(CKH)}$	Clock high time	f_{PP} = 52 MHz	8.5	9.5	-	
CMD, D inputs (referenced to CK) in *e*•MMC legacy/SDR/DDR and SD HS/SDR(4)/DDR(4) modes						
t_{ISU}	Input setup time HS	-	3.5	-	-	ns
t_{IH}	Input hold time HS	-	1.5	-	-	
t_{IDW}(5)	Input valid window (variable window)	-	4.5	-	-	
CMD, D outputs (referenced to CK) in *e*•MMC legacy/SDR/DDR and SD HS/SDR(4)/DDR(4) modes						
t_{OV}	Output valid time HS	-	-	6.5	7.5/8.5 (6)	ns
t_{OH}	Output hold time HS	-	3	-	-	
CMD, D inputs (referenced to CK) in SD default mode						
t_{ISU}	Input setup time SD	-	3.5	-	-	ns
t_{IH}	Input hold time SD	-	1.5	-	-	
CMD, D outputs (referenced to CK) in SD default mode						
t_{OV}	Output valid default time SD	-	-	1.5	3	ns
t_{OH}	Output hold default time SD	-	0.5	-	-	

1. Evaluated by characterization. Not tested in production.
2. In SD/*e*.MMC DDR mode, the clock OSPEEDRy[1:0] is set to 01 while data OSPEEDRy[1:0] remains at 10.
3. With capacitive load C_L = 20 pF.
4. For SD 1.8 V support, an external voltage converter is needed.
5. Minimum window of time where the data needs to be stable for proper sampling in tuning mode.
6. t_{OV} = 7.5 ns for SDMMC1 and t_{OV} = 8.5 ns for SDMMC2.

Table 147. *e*•MMC characteristics (V_{DD} = 1.71 V to 1.9 V)(1)(2)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{PP}	Clock frequency in data transfer mode	All modes except DDR	-	-	84	MHz
		DDR mode	-	-	40(3)	
$t_{W(CKL)}$	Clock low time	f_{PP} = 52 MHz	8.5	9.5	-	ns
$t_{W(CKH)}$	Clock high time	f_{PP} = 52 MHz	8.5	9.5	-	
CMD, D inputs (referenced to CK) in *e*•MMC mode						
t_{ISU}	Input setup time HS	-	3	-	-	ns
t_{IH}	Input hold time HS	-	2	-	-	
t_{IDW}(4)	Input valid window (variable window)	-	4	-	-	
CMD, D outputs (referenced to CK) in *e*•MMC mode						
t_{OV}	Output valid time HS	-	-	12	14/16(5)	ns
t_{OH}	Output hold time HS	-	6	-	-	

1. Evaluated by characterization. Not tested in production.
2. With capacitive load C_L = 20 pF.
3. For DDR mode, the maximum frequency is 40 MHz and HSLV must be OFF.
4. Minimum window of time where the data needs to be stable for proper sampling in tuning mode.
5. t_{OV} = 14 ns for SDMMC1 and t_{OV} = 16 ns for SDMMC2.

Figure 79. SD high-speed mode

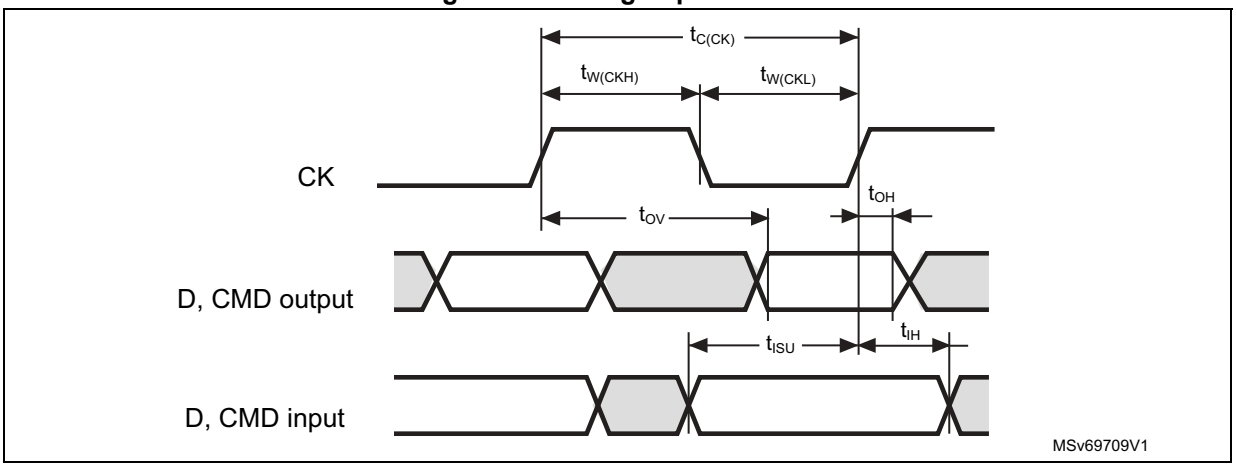


Figure 80. SD default mode

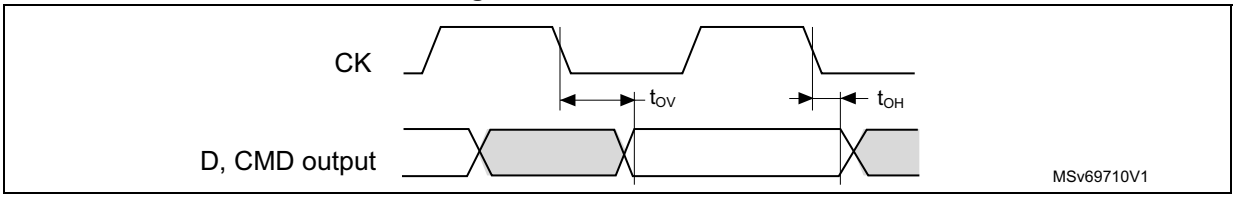
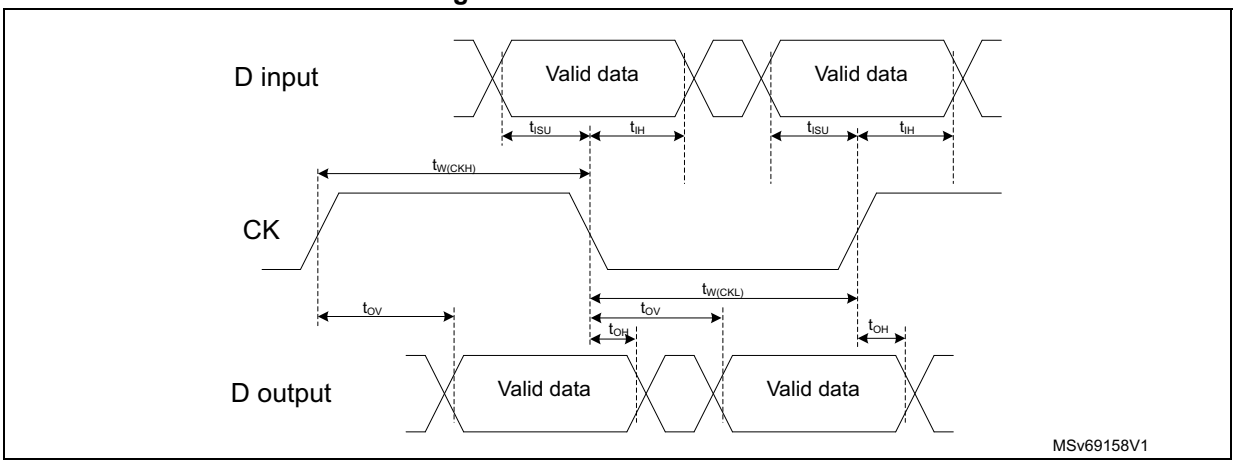


Figure 81. SDMMC DDR mode



5.3.39 Delay block characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{HCLK} frequency and V_{DD} supply voltage conditions summarized in *Table 33*.

Table 148. Delay block characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
t_{init}	Initial delay	-	900	1300	2100	ps
t_{Δ}	Unit delay	-	34	41	51	

1. Evaluated by characterization. Not tested in production.

5.3.40 I²C interface characteristics

The I²C interface meets the timings requirements of the I²C-bus specification and user manual rev. 03 for:

- Standard-mode (Sm): with a bitrate up to 100 Kbit/s
- Fast-mode (Fm): with a bitrate up to 400 Kbit/s
- Fast-mode Plus (Fm+): with a bitrate up to 1 Mbit/s

The I2C timings requirements are specified by design, not tested in production, when the I2C peripheral is properly configured (refer to the product reference manual).

The SDA and SCL I/O requirements are met with the following restrictions: the SDA and SCL I/O pins are not “true” open-drain. When configured as open-drain, the PMOS connected between the I/O pin and V_{DDIOx} is disabled, but is still present. Only FT_f I/O pins support Fm+ low-level output-current maximum requirement. Refer to *Section 5.3.15: I/O port characteristics* for the I2C I/Os characteristics.

All I2C SDA and SCL I/Os embed an analog filter. Refer to the table below for the analog filter characteristics.

Table 149. I2C analog filter characteristics(1)

Symbol	Parameter	Min	Max	Unit
t_{AF}	Maximum pulse width of spikes that are suppressed by the analog filter	50(2)	115(3)	ns

1. Specified by design. Not tested in production.
2. Spikes with widths below t_{AF} min are filtered.
3. Spikes with width above t_{AF} max are not filtered.

5.3.41 USART characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30pF
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output alternate function characteristics (NSS, CK, TX, RX for USART).

Table 150. USART characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{CK}	USART clock frequency	Master mode, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	-	20	MHz
		Slave receiver, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	-	53	
		Slave transmitter, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	-	27	
		Slave transmitter, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V	-	-	30	
$t_{su(NSS)}$	NSS setup time	Slave mode	T_{ker}(2) + 2	-	-	ns
$t_{h(NSS)}$	NSS hold time	Slave mode	2	-	-	
$t_{w(CKH)}$ $t_{w(CKL)}$	CK high and low time	Master mode	$1/f_{CK}$ / 2 - 1	$1/f_{CK}$ / 2	$1/f_{CK}$ / 2 + 1	
$t_{su(RX)}$	Data input setup time	Master mode	15	-	-	
$t_{su(TX)}$		Slave mode	2.5	-	-	
$t_{h(RX)}$	Data input hold time	Master mode	4	-	-	
$t_{h(RX)}$		Slave mode	1	-	-	
$t_{v(TX)}$	Data output valid time	Slave mode, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V	-	13	16.5	
		Slave mode, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	13	18.5	
$t_{v(TX)}$		Master mode	-	2.5	6.5	
$t_{h(TX)}$	Data output hold time	Slave mode	8.5	-	-	
$t_{h(TX)}$		Master mode	0.5	-	-	

1. Evaluated by characterization. Not tested in production.

2. T_{ker} is the usart_ker_ck_pres clock period.

Figure 82. USART timing diagram in master mode

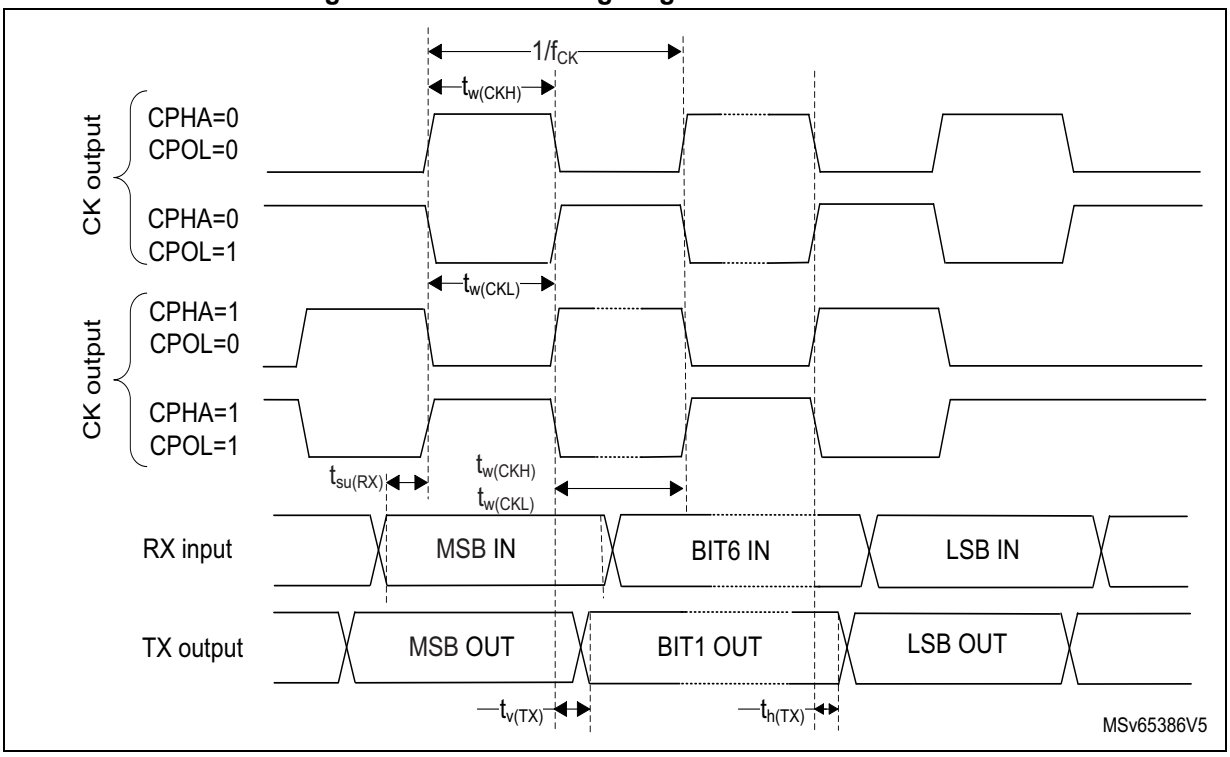
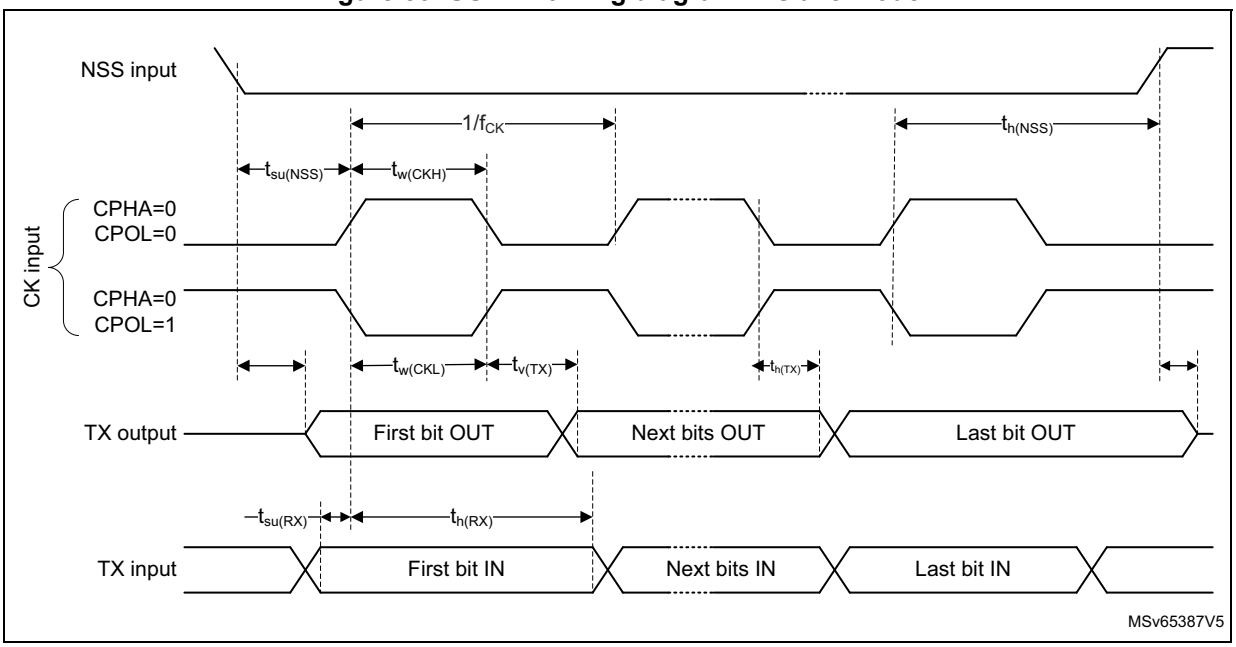


Figure 83. USART timing diagram in slave mode



5.3.42 SPI characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and supply voltage conditions summarized in *Table 33*.

- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30 pF
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output alternate function characteristics (NSS, SCK, MOSI, MISO for SPI).

Table 151. SPI characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f_{SCK} $1/t_{c(SCK)}$	SPI clock frequency	Master mode, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V, voltage range 1	-	-	80	MHz
		Master mode, 1.71 V ≤ V_{DDIOX} < 2.7 V voltage range 1	-	-	75 or 50(2)	
		Master transmitter mode, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V, voltage range 1	-	-	80	
		Master transmitter mode, 1.71 V ≤ V_{DDIOX} ≤ 2.7 V, voltage range 1	-	-	75 or 50(2)	
		Slave receiver mode, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V, voltage range 1	-	-	100	
		Slave mode transmitter/full duplex(3), 1.71 V ≤ V_{DDIOX} < 2.7 V, voltage range 1	-	-	37 or 25(4)	
		Slave mode transmitter/full duplex(3), 2.7 V ≤ V_{DDIOX} ≤ 3.6 V, voltage range 1	-	-	35.5	
		Master or slave mode, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V, voltage range 4	-	-	12.5	
		Master or slave mode, 1.08 V ≤ V_{DDIO2} ≤ 1.32 V(5)	-	-	15	

Table 151. SPI characteristics(1) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{su(NSS)}$	NSS setup time	Slave mode	4	-	-	ns
$t_{h(NSS)}$	NSS hold time	Slave mode	3	-	-	
$t_{w(SCKH)}$ $t_{w(SCKL)}$	SCK high and low time	Master mode	t_{SCK}(6)/2 - 1	$t_{SCK}/2$	$t_{SCK}/2$ + 1	
$t_{su(MI)}$	Data input setup time	Master mode	4.5	-	-	
$t_{su(SI)}$		Slave mode	2.5	-	-	
$t_{h(MI)}$	Data input hold time	Master mode	3	-	-	
$t_{h(SI)}$		Slave mode	1	-	-	
$t_{a(SO)}$	Data output access time	Slave mode	9	12	34	
$t_{dis(SO)}$	Data output disable time	Slave mode	9	10	16	
$t_{v(SO)}$	Data output valid time	Slave mode, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V, voltage range 1	-	11.5	14	
		Slave mode, 1.71 V ≤ V_{DDIOX} < 2.7 V, voltage range 1	-	11.5	13.5 or 20(4)	
		Slave mode, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V, voltage range 4	-	17	19.5 or 27(4)	
		Slave mode, 1.08 V ≤ V_{DDIO2} ≤ 1.32 V(5)	-	23	25	
$t_{v(MO)}$	Data output valid time	Master mode	-	2.5	3 or 9.5(7) or 12.5(8)	
$t_{h(SO)}$	Data output hold time	Slave mode, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	7	-	-	
		Slave mode, 1.08 V ≤ V_{DDIO2} ≤ 1.32 V(5)	15	-	-	
$t_{h(MO)}$		Master mode	0.5	-	-	

1. Evaluated by characterization. Not tested in production.
2. When using PA5, PA9, PC10, PB3, PB13.
3. The maximum frequency in slave transmitter mode is determined by the sum of $t_{v(SO)}$ and $t_{su(MI)}$ that has to fit into SCK low or high phase preceding the SCK sampling edge. This value can be achieved when the SPI communicates with a master having $t_{su(MI)}$ = 0 while Duty(SCK) = 50%.
4. When using PA11, PB4, PB14.
5. The SPI is mapped on port G I/Os, that is supplied by VDDIO2 specified down to 1.08V. The SPI is tested at this value.
6. t_{SCK} = tspi_ker_ck × baudrate prescaler.
7. When using PA12.
8. When using PB15.

Figure 84. SPI timing diagram - slave mode and CPHA = 0

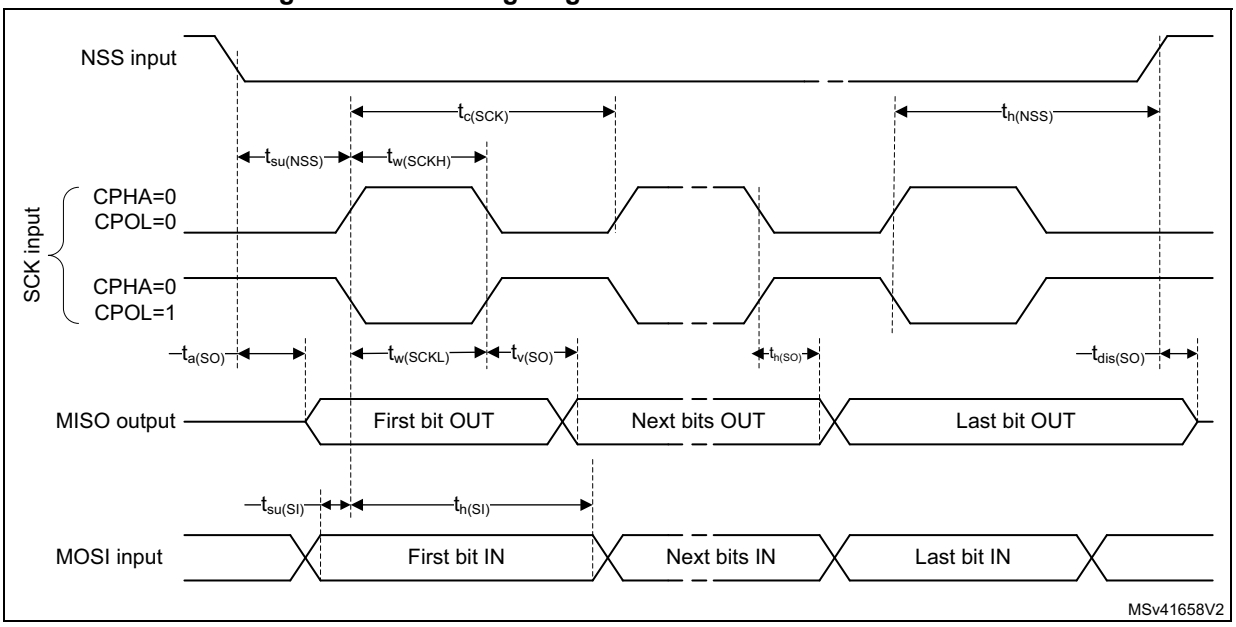


Figure 85. SPI timing diagram - slave mode and CPHA = 1

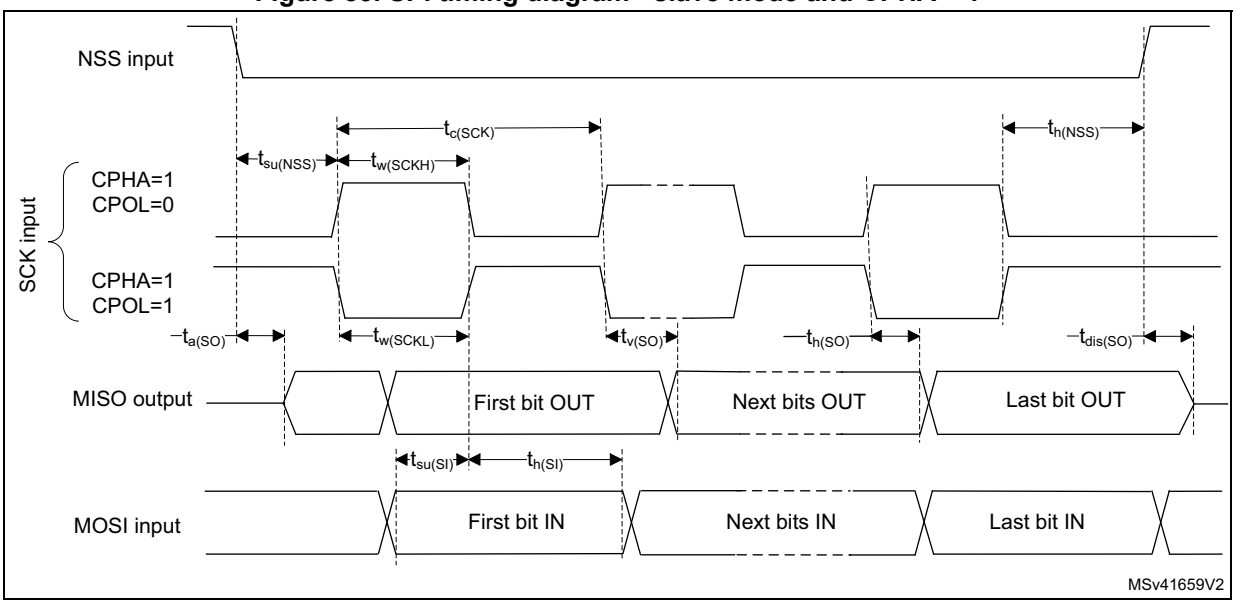
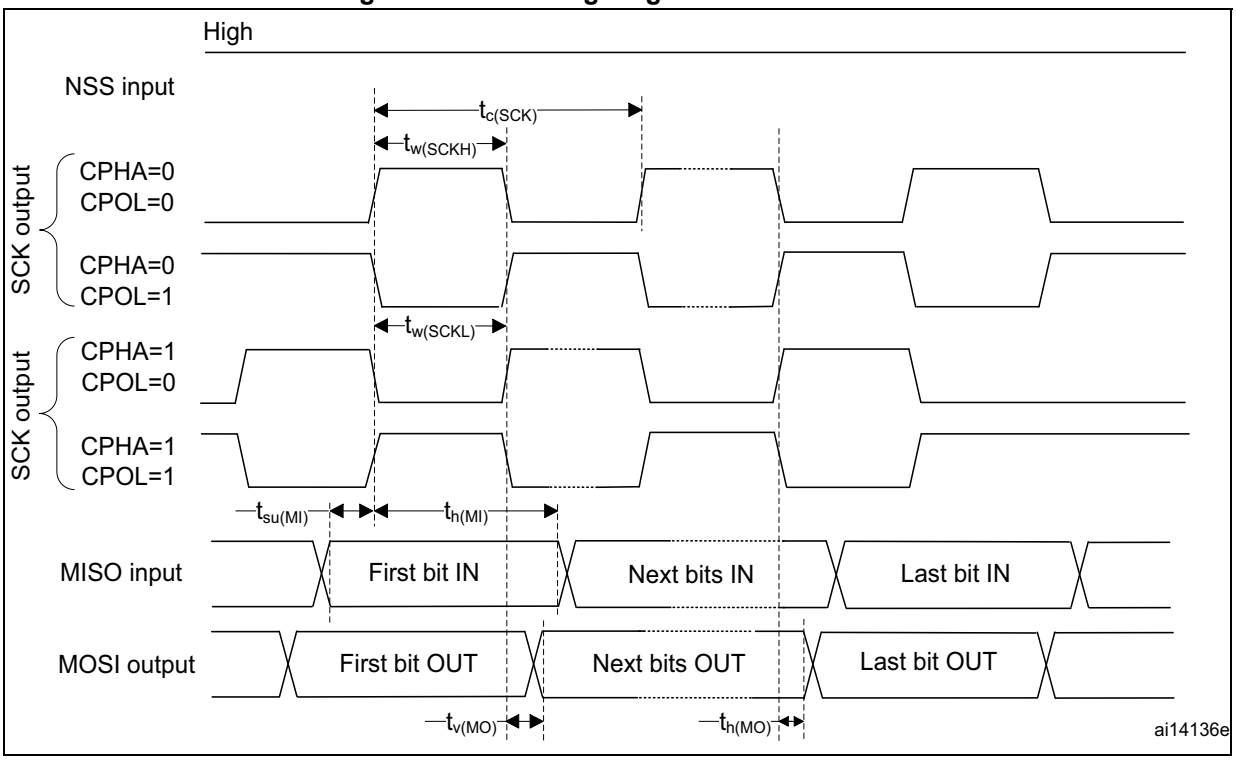


Figure 86. SPI timing diagram - master mode



5.3.43 SAI characteristics

Unless otherwise specified, the parameters given in the table below are derived from tests performed under the ambient temperature, f_{PCLKx} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30 pF
- Measurement points done at 0.5 × V_{DD} level
- I/O compensation cell activated
- HSLV activated when V_{DD} ≤ 2.7 V
- Voltage scaling range 1

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output alternate function characteristics (SCK, SD, FS).

Table 152. SAI characteristics(1)

Symbol	Parameter	Conditions	Min	Max	Unit
f_{MCK}	SAI main clock output	-	-	50	MHz
f_{SCK}	SAI clock frequency(2)	Master transmitter, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V	-	26	
		Master transmitter, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	18	
		Master receiver, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	21.5	
		Slave transmitter, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V	-	27.5	
		Slave transmitter, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	18	
		Slave receiver, 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	50	
$t_{v(FS)}$	FS valid time	Master mode, 2.7 V ≤ V_{DDIOX} ≤ 3.6 V	-	16	ns
		Master mode 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	23	
$t_{h(FS)}$	FS hold time	Master mode	7	-	
$t_{su(FS)}$	FS setup time	Slave mode	2.5	-	
$t_{h(FS)}$	FS hold time	Slave mode	1	-	
$t_{su(SD_A_MR)}$	Data input setup time	Master receiver	4	-	
$t_{su(SD_B_SR)}$		Slave receiver	3	-	
$t_{h(SD_A_MR)}$	Data input hold time	Master receiver	2	-	
$t_{h(SD_B_SR)}$		Slave receiver	1	-	
$t_{v(SD_B_ST)}$	Data output valid time	Slave transmitter (after enable edge), 2.7 V ≤ V_{DDIOX} ≤ 3.6 V	-	18	
		Slave transmitter (after enable edge), 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	27.5	
$t_{h(SD_B_ST)}$	Data output hold time	Slave transmitter (after enable edge)	8	-	
$t_{v(SD_A_MT)}$	Data output valid time	Master transmitter (after enable edge), 2.7 V ≤ V_{DDIOX} ≤ 3.6 V	-	19	
		Master transmitter (after enable edge), 1.71 V ≤ V_{DDIOX} ≤ 3.6 V	-	27.5	
$t_{h(SD_A_MT)}$	Data output hold time	Master transmitter (after enable edge)	8	-	

1. Evaluated by characterization. Not tested in production.
2. APB clock frequency that must be at least twice SAI clock frequency.

Figure 87. SAI master timing diagram

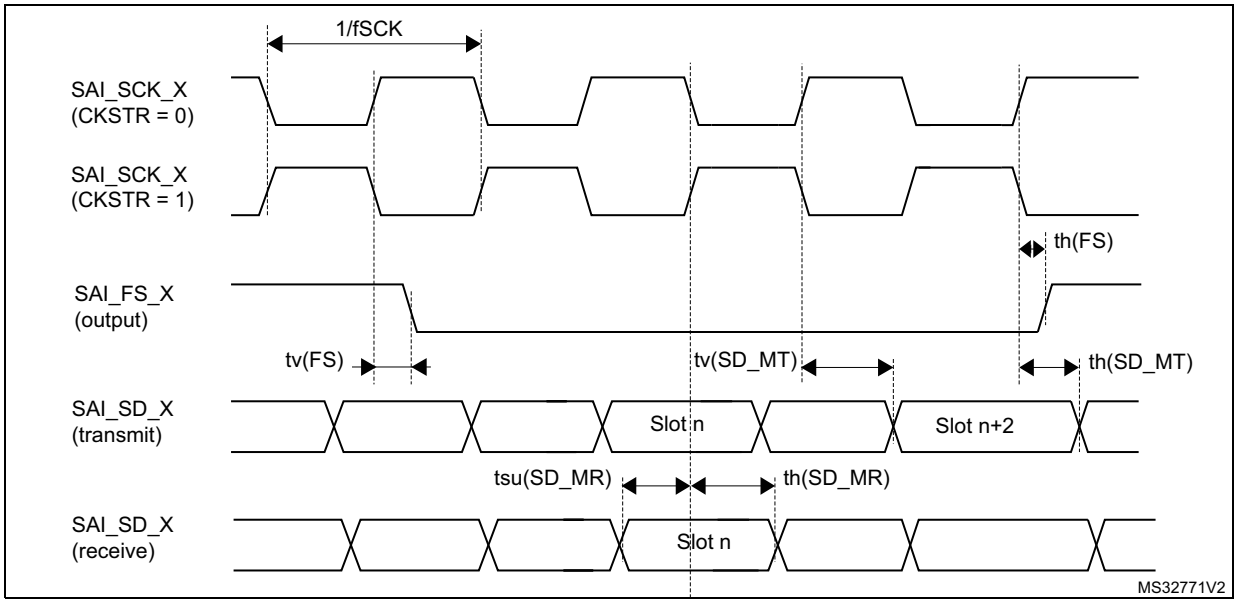
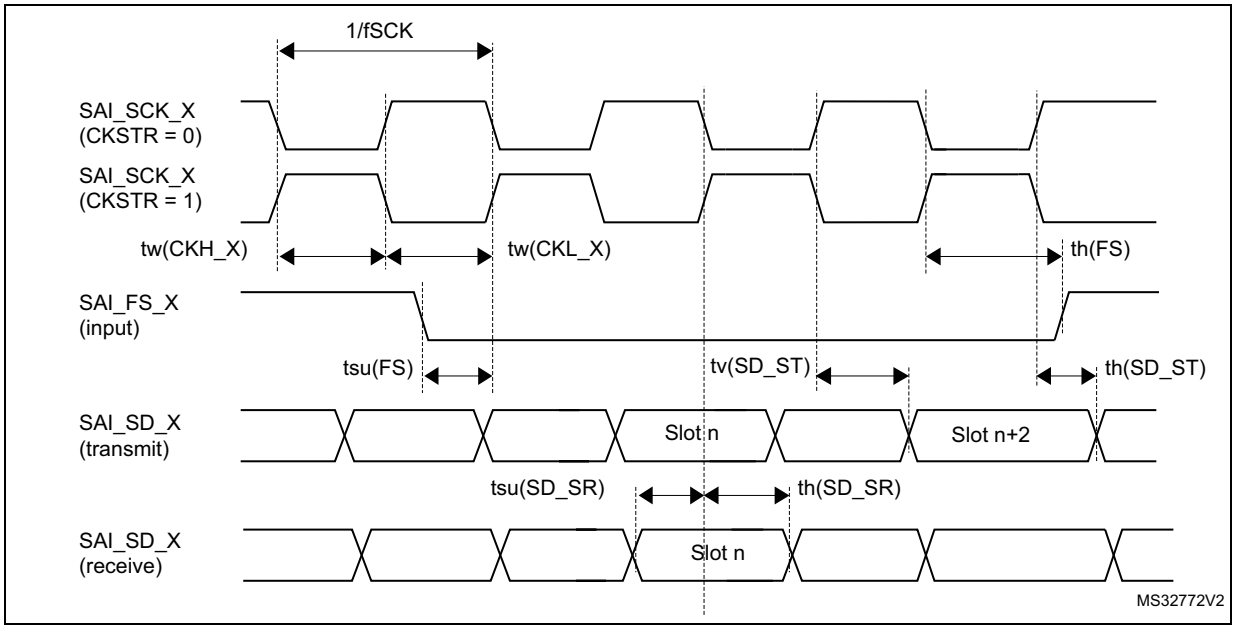


Figure 88. SAI slave timing diagram



5.3.44 OTG_HS characteristics

The OTG_HS controller complies with the following specifications:

- USB On-The-Go supplement, revision 2.0
- Universal Serial Bus revision 2.0 specification
- Battery charging specification, revision 1.2

The parameters given in tables below are derived from tests performed under temperature and V_{DD} supply voltage conditions summarized in *Table 33: General operating conditions*.

Table 153. OTG_HS electrical characteristics(1)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
V_{DDUSB}	USB transceiver operating voltage	-	3.12(2)	-	3.6	V
f_{HCLK}	f_{HCLK} value to guarantee proper operation of the OTG_HS interface	-	30(3)	-	-	MHz
R_{PUI}	Embedded OTG_HS_DP pull-up value during idle	-	900	1250	1575	Ω
R_{PUR}	Embedded OTG_HS_DP pull-up value during reception	-	1425(3)	2250	3090(3)	
R_{PD}	Embedded OTG_HS_DP and OTG_HS_DM pull-down value	-	14250	-	24800	
Z_{DRV}	Output driver impedance(4)	Driving high or low	40.5(3)	45	49.5(3)	
t_{lr}	Rise time	CL < 5 pF	0.5(3)	-	-	ns
t_{lf}	Fall time	CL < 5 pF	0.5(3)	-	-	
t_{lrfm}	Rise/fall time matching	-	80(3)	-	125(3)	%

1. Evaluated by characterization. Not tested in production, unless otherwise specified.
2. The USB functionality is ensured down to 3 V but not the full USB electrical characteristics which are degraded in 3.0 to 3.12 V voltage range.
3. Specified by design. Not tested in production.
4. No external termination series resistors are required on OTG_HS_DP (D+) and OTG_HS_DM (D-). The matching impedance is already included in the embedded driver.

Table 154. OTG_HS DC electrical characteristics(1)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
V_{hssq}	High-speed squelch detection threshold	-	100(2)	-	150	mV
V_{hsdsc}	High-speed disconnect detection threshold	-	525	-	625	
V_{hsdif}	High-speed differential detection threshold	-	100	-	-	
V_{hscm}	High-speed data signaling common mode voltage range	-	-50	-	500	
V_{hsoi}	High-speed idle level	-	-10	-	10	
V_{hsoh}	High-speed data signaling high	-	360	-	440	
V_{hsol}	High-speed data signaling low	-	-10	-	10	
$V_{hchirpj}$	Chirp J level	-	700	-	1100	
$V_{hchirpk}$	Chirp K level	-	-900	-	-500	

1. Evaluated by characterization. Not tested in production.
2. 50 mV test waivers from usb.org have been applied.

Table 155. OTG_HS PHY BCD electrical characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{DD(USBBCD)}$	Primary detection mode consumption on V_{DDUSB}	-	-	4.9	5.7	mA
	Secondary detection mode consumption on V_{DDUSB}	-	-	4.8		
$I_{DD11(USBBCD)}$	Primary detection mode consumption on $V_{DD11USB}$	-	-	5.2	7.4	
	Secondary detection mode consumption on $V_{DD11USB}$	-	-	5.3		
R_{DAT_LKG}	Data line leakage resistance	-	300(2)	-	-	kΩ
V_{DAT_LKG}	Data line leakage voltage	-	0.0	-	3.6(2)	V
R_{DCP_DAT}	Dedicated charging port resistance across D+/D-	-	-	-	200(2)	Ω
V_{LGC_HI}	Logic high	-	2.0		3.6	V
V_{LGC_LOW}	Logic low	-	-	-	0.8	
V_{LGC}	Logic threshold	-	0.8	-	2.0	
V_{DAT_REF}	Data detect voltage	-	0.25(2)	-	0.4(2)	
V_{DP_SRC}	D+ source voltage	-	0.5	-	0.7	
V_{DM_SRC}	D- source voltage	-	0.5	-	0.7	
I_{DM_SINK}	D- sink current	-	25	-	175	µA
I_{DP_SINK}	D+ sink current	-	25	-	175	
I_{DP_SRC}	Data contact detect current source	-	7.0	-	13	

1. Evaluated by characterization. Not tested in production, unless otherwise specified.
2. Specified by design. Not tested in production.

Table 156. OTG_HS current consumption characteristics(1)

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$I_{IDD(OTG_HS)}$	USB (PLL and PHY) current consumption on VDDUSB	Suspend mode(2)	-	53	173	µA
		Full-speed transmit(3)	-	9.9	12.2	mA
		High-speed idle	-	5.8	6.4	
		High-speed transmit(3)	-	13.5	16.0	
$I_{IDD11(OTG_HS)}$	USB (PLL and PHY) current consumption on VDD11USB	Suspend mode(2)	-	86	1570	µA
		Full-speed transmit(3)	-	7.5	10.3	mA
		High-speed idle	-	7.7	10.5	
		High-speed transmit(3)	-	9	12.2	

1. Evaluated by characterization. Not tested in production.
2. Suspend when operating in device mode with no far-side host termination on DP/DM during measurements.
3. Transfers include 70% transmit activity and 30% interpacket delay.

5.3.45 UCPD characteristics

UCPD controller complies with USB Type-C Rev 1.2 and USB Power Delivery Rev 3.0 specifications.

Table 157. UCPD characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{DD}	UCPD operating supply voltage	Sink mode only	3.0	3.3	3.6	V
		Sink and source mode	3.135	3.3	3.465	

5.3.46 JTAG/SWD interface characteristics

Unless otherwise specified, the parameters given in the tables below are derived from tests performed under the ambient temperature, f_{HCLKx} frequency and V_{DD} supply voltage conditions summarized in *Table 33*, with the following configuration:

- Output speed set to OSPEEDRy[1:0] = 10
- Capacitive load C_L = 30 pF
- Measurement points done at 0.5 × V_{DD} level

Refer to *Section 5.3.15: I/O port characteristics* for more details on the input/output characteristics.

Table 158. JTAG characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F_{TCK}	TCK clock frequency	2.7 V ≤ V_{DD} ≤ 3.6 V	-	-	27.5	MHz
		1.71 V ≤ V_{DD} ≤ 3.6 V	-	-	20.5	
$ti_{su(TMS)}$	TMS input setup time	-	2	-	-	ns
$ti_{h(TMS)}$	TMS input hold time	-	3	-	-	
$ti_{su(TDI)}$	TDI input setup time	-	3	-	-	
$ti_{h(TDI)}$	TDI input hold time	-	1	-	-	
$t_{ov(TDO)}$	TDO output valid time	2.7 V ≤ V_{DD} ≤ 3.6 V	-	14	18	
		1.71 V ≤ V_{DD} ≤ 3.6 V	-	14	24	
$t_{oh(TDO)}$	TDO output hold time	-	10	-	-	

1. Evaluated by characterization. Not tested in production.

Table 159. SWD characteristics(1)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
F_{SWCLK}	SWCLK clock frequency	2.7 V ≤ V_{DD} ≤ 3.6 V	-	-	60.5	MHz
		1.71 V ≤ V_{DD} ≤ 3.6 V	-	-	43	
$ti_{su(SWDIO)}$	SWDIO input setup time	-	1	-	-	ns
$ti_{h(SWDIO)}$	SWDIO input hold time	-	2.5	-	-	

Table 159. SWD characteristics(1) (continued)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{ov(SWDIO)}$	SWDIO output valid time	2.7 V ≤ V_{DD} ≤ 3.6 V	-	10.5	16.5	ns
		1.71 V ≤ V_{DD} ≤ 3.6 V	-	10.5	23	
$t_{oh(SWDIO)}$	SWDIO output hold time	-	7.5	-	-	

1. Evaluated by characterization. Not tested in production.

Figure 89. JTAG timing diagram

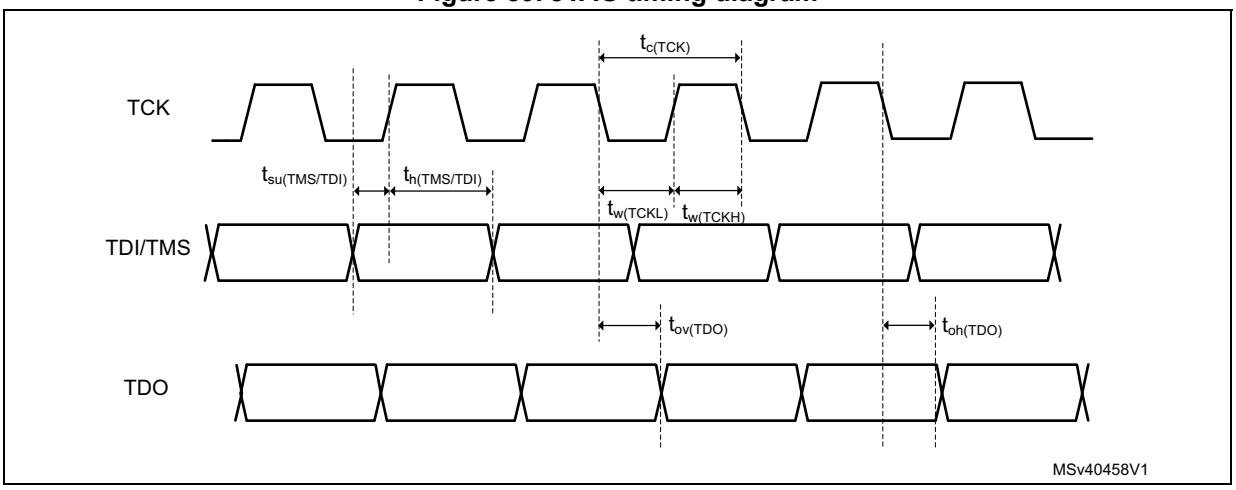
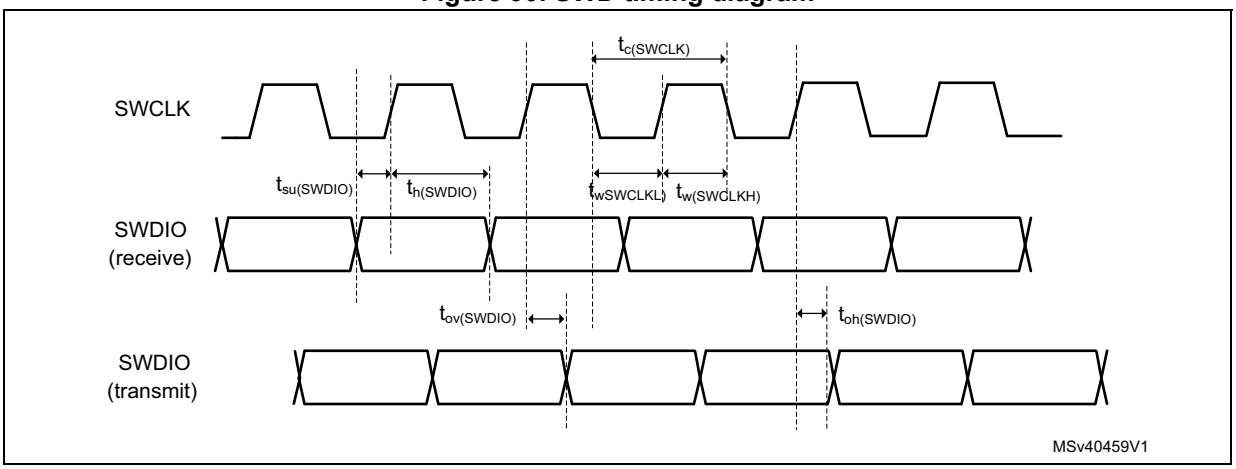


Figure 90. SWD timing diagram



6 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK packages, depending on their level of environmental compliance. ECOPACK specifications, grade definitions and product status are available at: *www.st.com*. ECOPACK is an ST trademark.

6.1 LQFP64 package information (5W)

This LQFP is 64-pin, 10 x 10 mm low-profile quad flat package.

Note: See list of notes in the notes section.

Figure 91. LQFP64 - Outline(15)

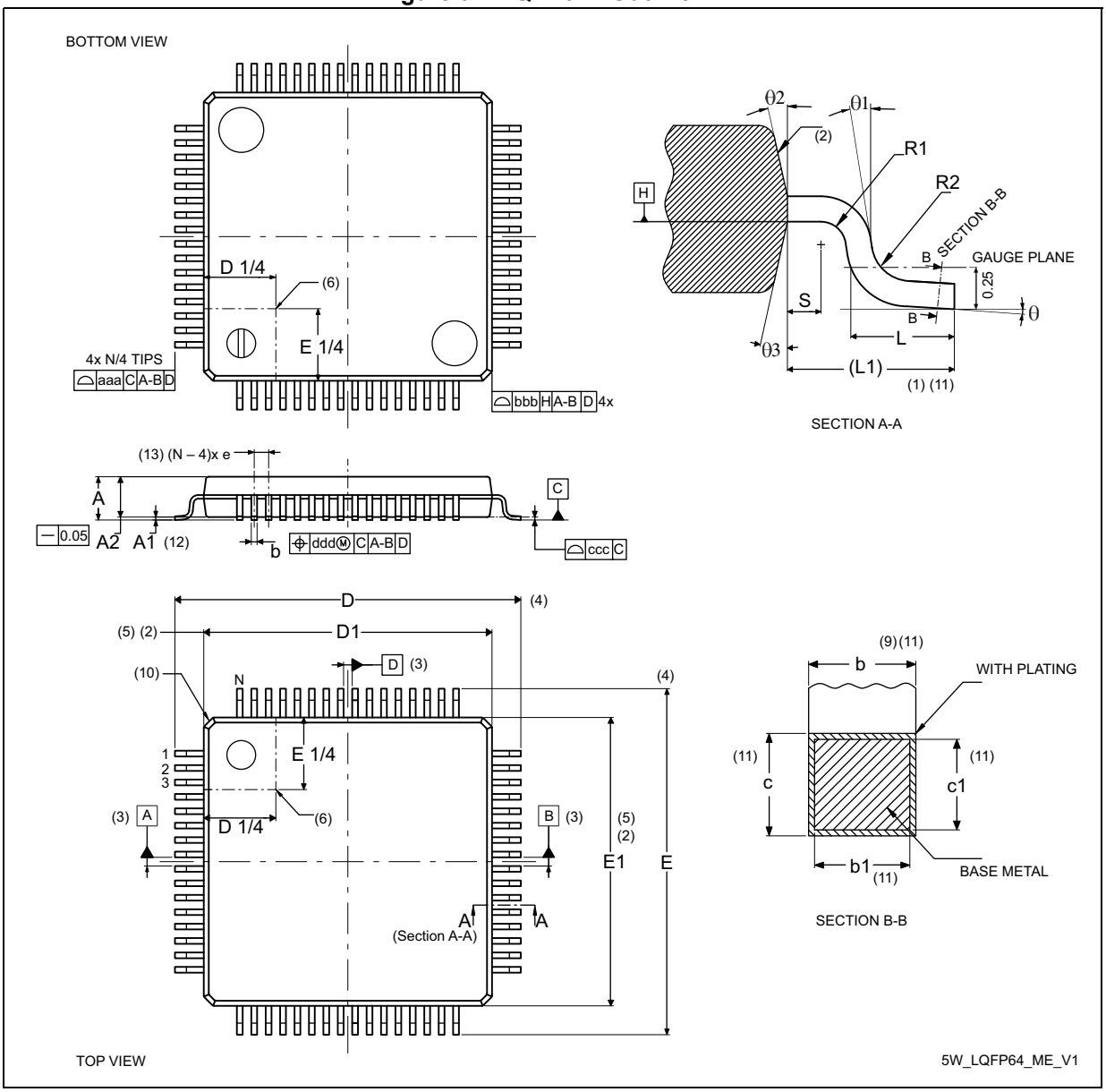


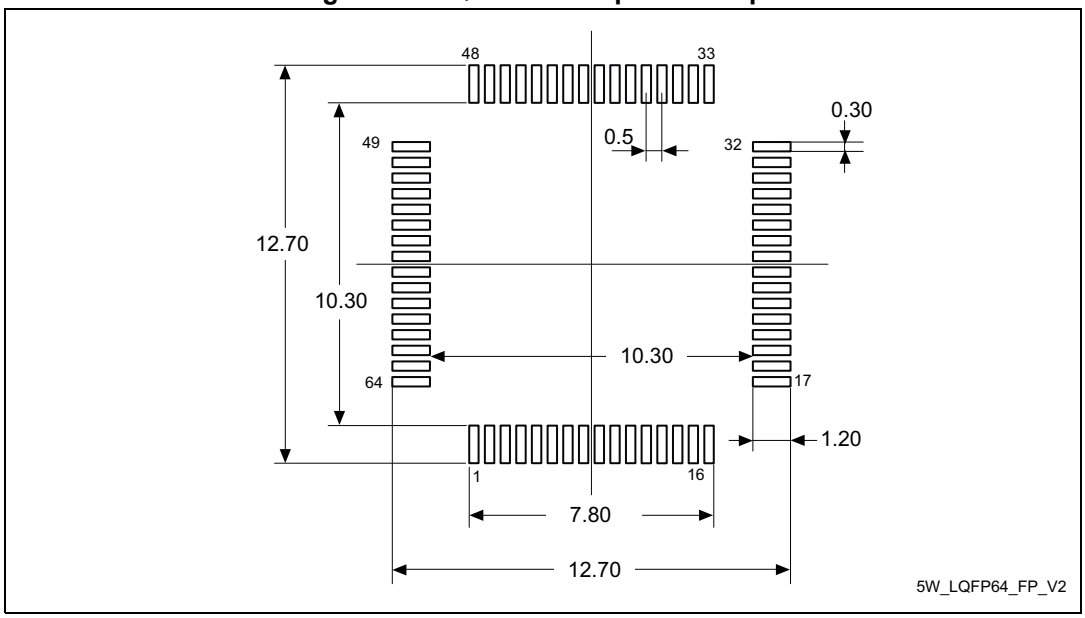
Table 160. LQFP64 - Mechanical data

Symbol	millimeters			inches[14]		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.60	-	-	0.0630
A1[12]	0.05	-	0.15	0.0020	-	0.0059
A2	1.35	1.40	1.45	0.0531	0.0551	0.0570
b[9][11]	0.17	0.22	0.27	0.0067	0.0087	0.0106
b1[11]	0.17	0.20	0.23	0.0067	0.0079	0.0091
c[11]	0.09	-	0.20	0.0035	-	0.0079
c1[11]	0.09	-	0.16	0.0035	-	0.0063
D[4]	12.00 BSC			0.4724 BSC		
D1[2][5]	10.00 BSC			0.3937 BSC		
E[4]	12.00 BSC			0.4724 BSC		
E1[2][5]	10.00 BSC			0.3937 BSC		
e	0.50 BSC			0.1970 BSC		
L	0.45	0.60	0.75	0.0177	0.0236	0.0295
L1	1.00 REF			0.0394 REF		
N[13]	64					
θ	0°	3.5°	7°	0°	3.5°	7°
θ1	0°	-	-	0°	-	-
θ2	10°	12°	14°	10°	12°	14°
θ3	10°	12°	14°	10°	12°	14°
R1	0.08	-	-	0.0031	-	-
R2	0.08	-	0.20	0.0031	-	0.0079
S	0.20	-	-	0.0079	-	-
aaa[1]	0.20			0.0079		
bbb[1]	0.20			0.0079		
ccc[1]	0.08			0.0031		
ddd[1]	0.08			0.0031		

Notes:

1. Dimensioning and tolerancing schemes conform to ASME Y14.5M-1994.
2. The Top package body size may be smaller than the bottom package size by as much as 0.15 mm.
3. Datums A-B and D to be determined at datum plane H.
4. To be determined at seating datum plane C.
5. Dimensions D1 and E1 do not include mold flash or protrusions. Allowable mold flash or protrusions is “0.25 mm” per side. D1 and E1 are Maximum plastic body size dimensions including mold mismatch.
6. Details of pin 1 identifier are optional but must be located within the zone indicated.
7. All Dimensions are in millimeters.
8. No intrusion allowed inwards the leads.
9. Dimension “b” does not include dambar protrusion. Allowable dambar protrusion shall not cause the lead width to exceed the maximum “b” dimension by more than 0.08 mm. Dambar cannot be located on the lower radius or the foot. Minimum space between protrusion and an adjacent lead is 0.07 mm for 0.4 mm and 0.5 mm pitch packages.
10. Exact shape of each corner is optional.
11. These dimensions apply to the flat section of the lead between 0.10 mm and 0.25 mm from the lead tip.
12. A1 is defined as the distance from the seating plane to the lowest point on the package body.
13. “N” is the number of terminal positions for the specified body size.
14. Values in inches are converted from mm and rounded to 4 decimal digits.
15. Drawing is not to scale.

Figure 92. LQFP64 - Footprint example



1. Dimensions are expressed in millimeters.

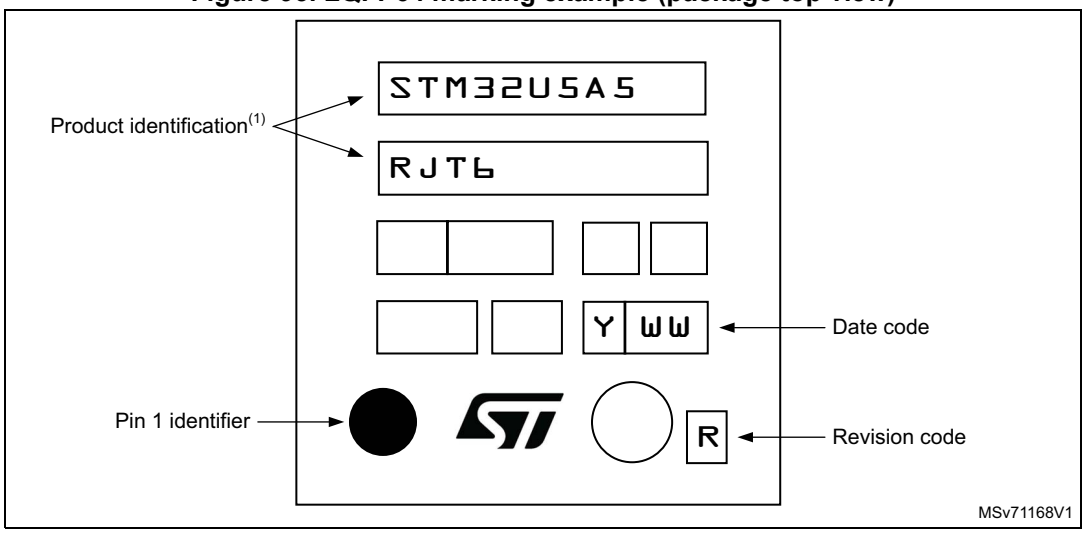
Device marking for LQFP64

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

Figure 93. LQFP64 marking example (package top view)



1. Parts marked as ES or E or accompanied by an Engineering Sample notification letter are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

6.2 LQFP100 package information (1L)

This LQFP is 100 lead, 14 x 14 mm low-profile quad flat package.

Note: See list of notes in the notes section.

Figure 94. LQFP100 - Outline(15)

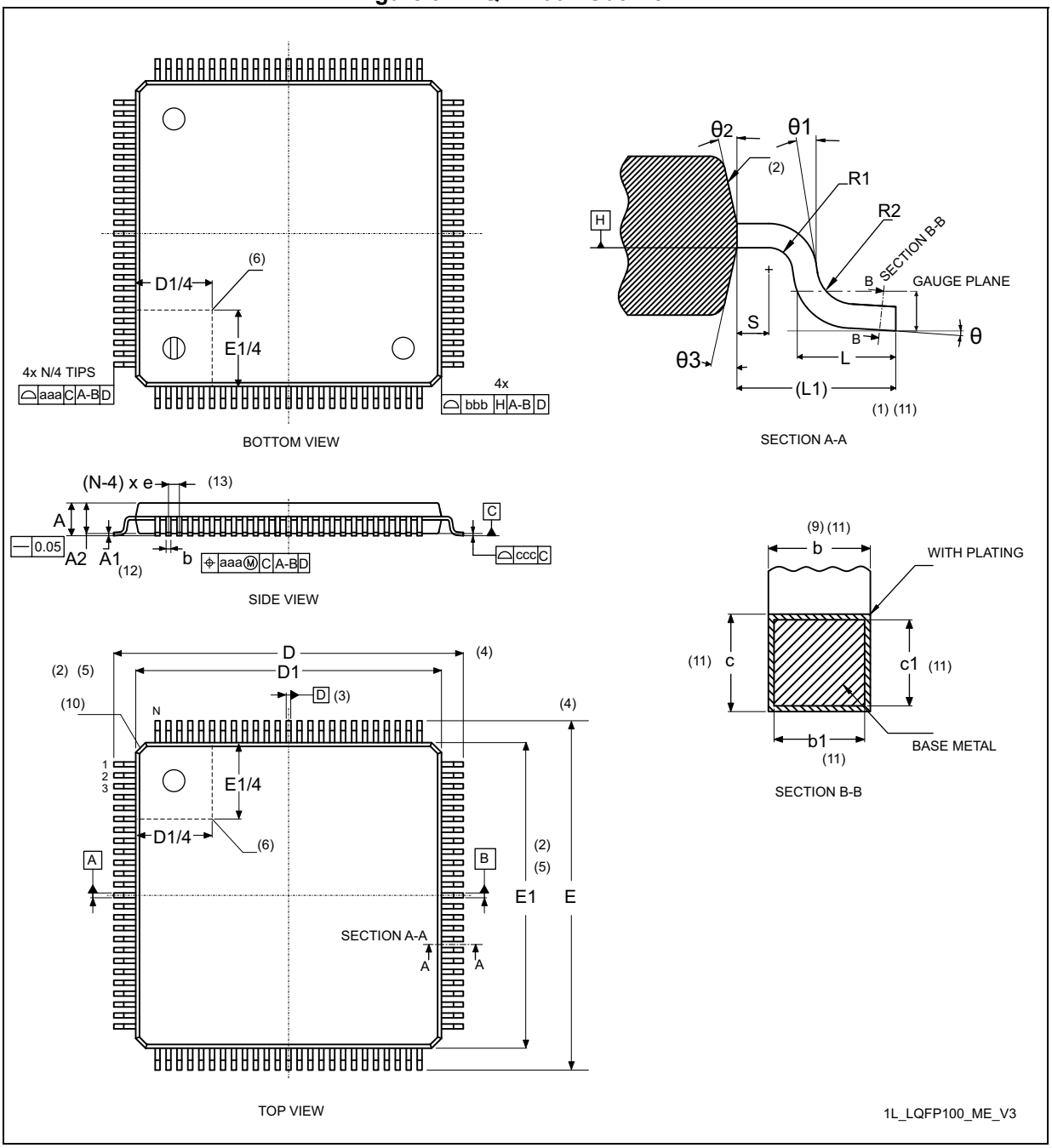


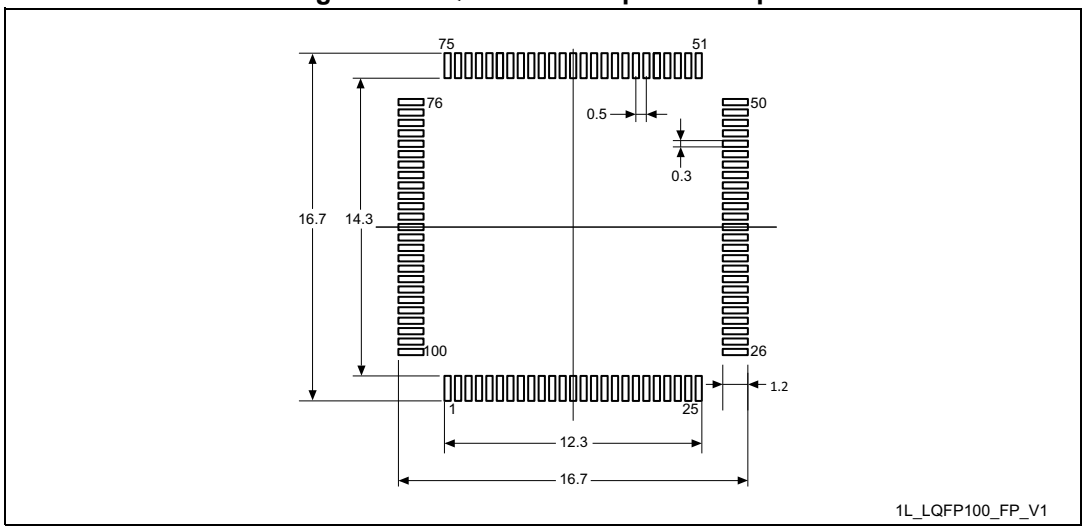
Table 161. LQFP100 - Mechanical data

Symbol	millimeters			inches[14]		
	Min	Typ	Max	Min	Typ	Max
A	-	1.50	1.60	-	0.0590	0.0630
A1[12]	0.05	-	0.15	0.0019	-	0.0059
A2	1.35	1.40	1.45	0.0531	0.0551	0.0570
b[9][11]	0.17	0.22	0.27	0.0067	0.0087	0.0106
b1[11]	0.17	0.20	0.23	0.0067	0.0079	0.0090
c[11]	0.09	-	0.20	0.0035	-	0.0079
c1[11]	0.09	-	0.16	0.0035	-	0.0063
D[4]	16.00 BSC			0.6299 BSC		
D1[2][5]	14.00 BSC			0.5512 BSC		
E[4]	16.00 BSC			0.6299 BSC		
E1[2][5]	14.00 BSC			0.5512 BSC		
e	0.50 BSC			0.0197 BSC		
L	0.45	0.60	0.75	0.177	0.0236	0.0295
L1[1][11]	1.00			-	0.0394	-
N[13]	100					
θ	0°	3.5°	7°	0°	3.5°	7°
θ1	0°	-	-	0°	-	-
θ2	10°	12°	14°	10°	12°	14°
θ3	10°	12°	14°	10°	12°	14°
R1	0.08	-	-	0.0031	-	-
R2	0.08	-	0.20	0.0031	-	0.0079
S	0.20	-	-	0.0079	-	-
aaa[1]	0.20			0.0079		
bbb[1]	0.20			0.0079		
ccc[1]	0.08			0.0031		
ddd[1]	0.08			0.0031		

Notes:

1. Dimensioning and tolerancing schemes conform to ASME Y14.5M-1994.
2. The Top package body size may be smaller than the bottom package size by as much as 0.15 mm.
3. Datums A-B and D to be determined at datum plane H.
4. To be determined at seating datum plane C.
5. Dimensions D1 and E1 do not include mold flash or protrusions. Allowable mold flash or protrusions is “0.25 mm” per side. D1 and E1 are Maximum plastic body size dimensions including mold mismatch.
6. Details of pin 1 identifier are optional but must be located within the zone indicated.
7. All Dimensions are in millimeters.
8. No intrusion allowed inwards the leads.
9. Dimension “b” does not include dambar protrusion. Allowable dambar protrusion shall not cause the lead width to exceed the maximum “b” dimension by more than 0.08 mm. Dambar cannot be located on the lower radius or the foot. Minimum space between protrusion and an adjacent lead is 0.07 mm for 0.4 mm and 0.5 mm pitch packages.
10. Exact shape of each corner is optional.
11. These dimensions apply to the flat section of the lead between 0.10 mm and 0.25 mm from the lead tip.
12. A1 is defined as the distance from the seating plane to the lowest point on the package body.
13. “N” is the number of terminal positions for the specified body size.
14. Values in inches are converted from mm and rounded to 4 decimal digits.
15. Drawing is not to scale.

Figure 95. LQFP100 - Footprint example



1. Dimensions are expressed in millimeters.

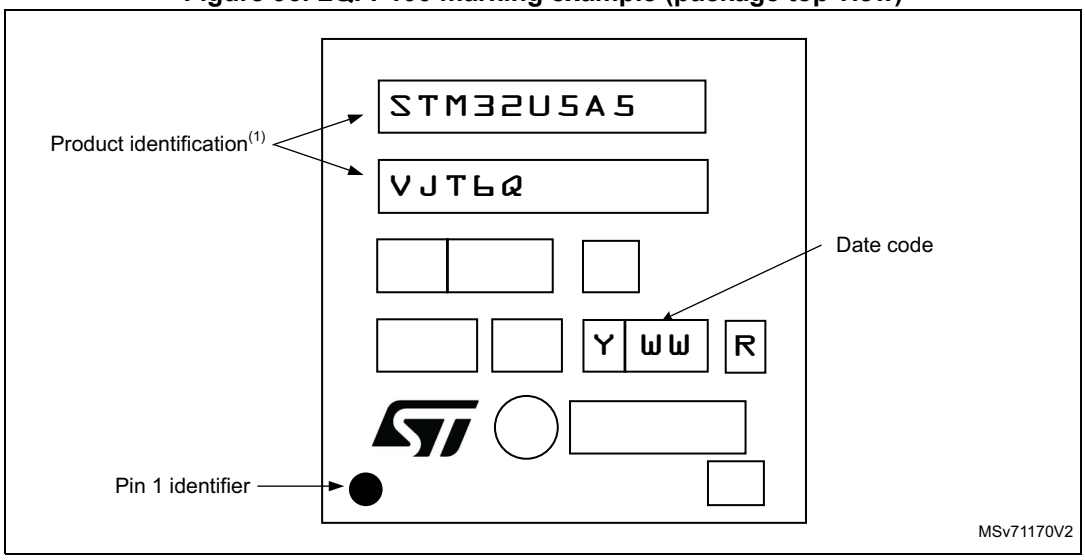
Device marking for LQFP100

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

Figure 96. LQFP100 marking example (package top view)

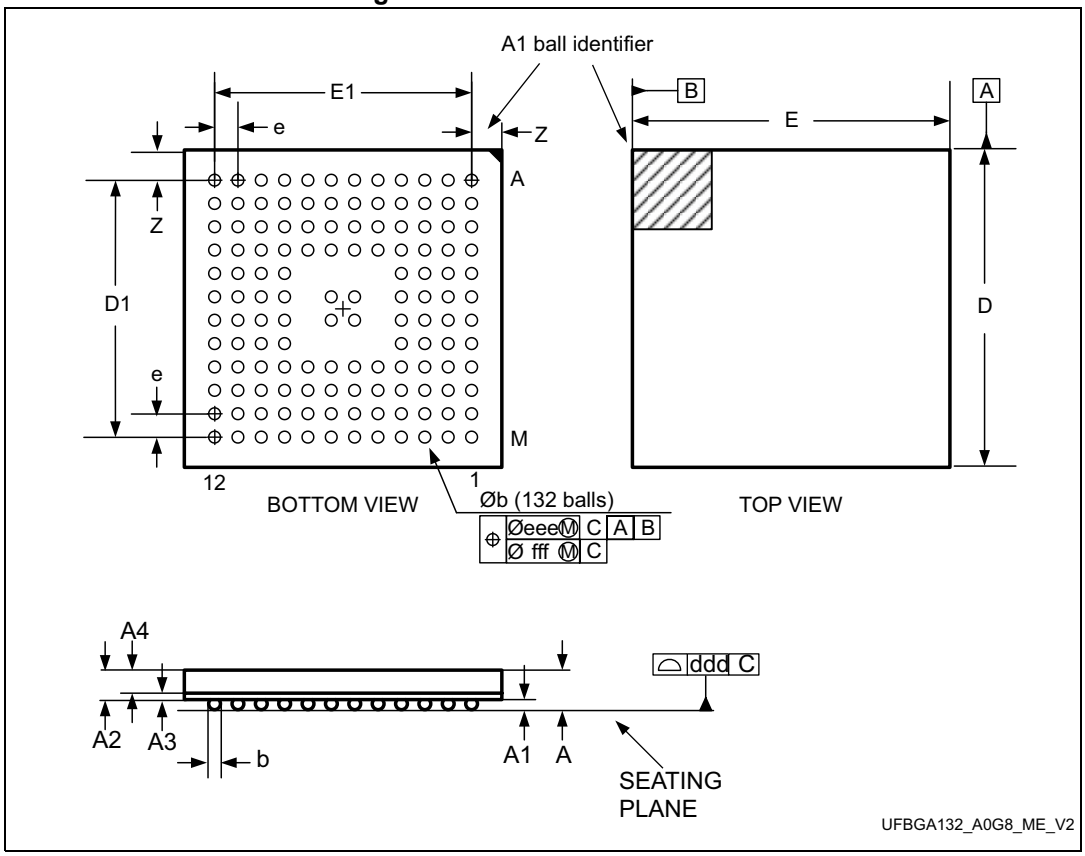


1. Parts marked as ES or E or accompanied by an Engineering Sample notification letter are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

6.3 UFBGA132 package information (A0G8)

This UFBGA is a 132-ball, 7 x 7 mm ultra thin fine pitch ball grid array package.

Figure 97. UFBGA132 - Outline



1. Drawing is not to scale.

Table 162. UFBGA132 - Mechanical data

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
A	-	-	0.600	-	-	0.0236
A1	-	-	0.110	-	-	0.0043
A2	-	0.450	-	-	0.0177	-
A3	-	0.130	-	-	0.0051	-
A4	-	0.320	-	-	0.0126	-
b	0.240	0.290	0.340	0.0094	0.0114	0.0134
D	6.850	7.000	7.150	0.2697	0.2756	0.2815
D1	-	5.500	-	-	0.2165	-
E	6.850	7.000	7.150	0.2697	0.2756	0.2815
E1	-	5.500	-	-	0.2165	-

Table 162. UFBGA132 - Mechanical data (continued)

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
e	-	0.500	-	-	0.0197	-
Z	-	0.750	-	-	0.0295	-
ddd	-	0.080	-	-	0.0031	-
eee	-	0.150	-	-	0.0059	-
fff	-	0.050	-	-	0.0020	-

1. Values in inches are converted from mm and rounded to 4 decimal digits.

Figure 98. UFBGA132 - Footprint example

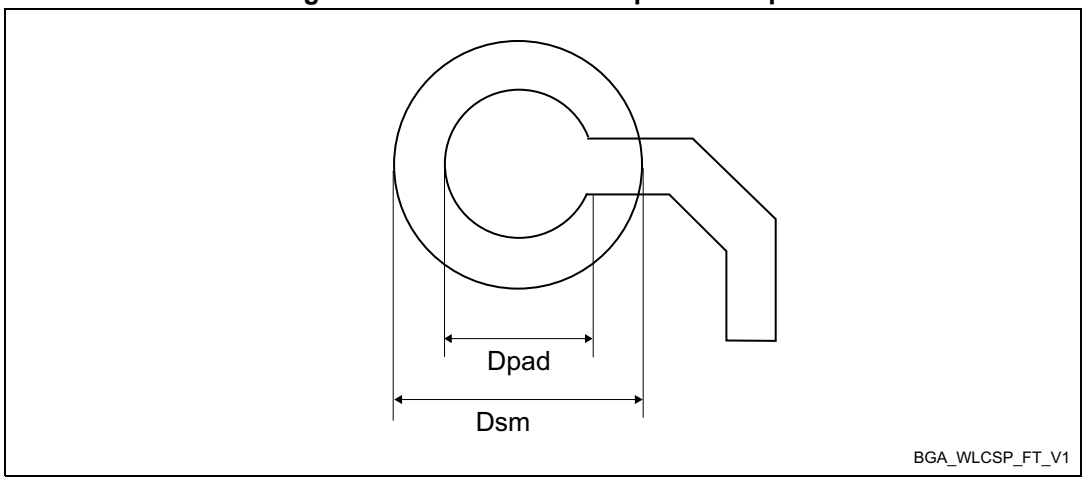


Table 163. UFBGA132 - Example of PCB design rules (0.5 mm pitch BGA)

Dimension	Values
Pitch	0.5 mm
Dpad	0.280 mm
Dsm	0.370 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.280 mm
Stencil thickness	Between 0.100 mm and 0.125 mm
Pad trace width	0.100 mm
Ball diameter	0.280 mm

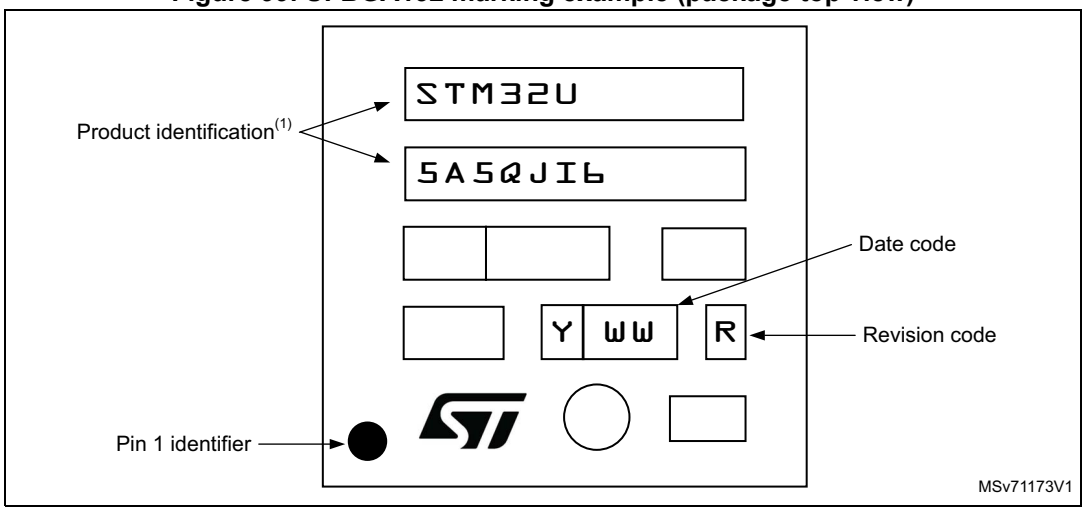
Device marking for UFBGA132

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

Figure 99. UFBGA132 marking example (package top view)



1. Parts marked as ES or E or accompanied by an Engineering Sample notification letter are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

6.4 LQFP144 package information (1A)

This LQFP is a 144-pin, 20 x 20 mm low-profile quad flat package.

Note: See list of notes in the notes section.

Figure 100. LQFP144 - Outline(15)

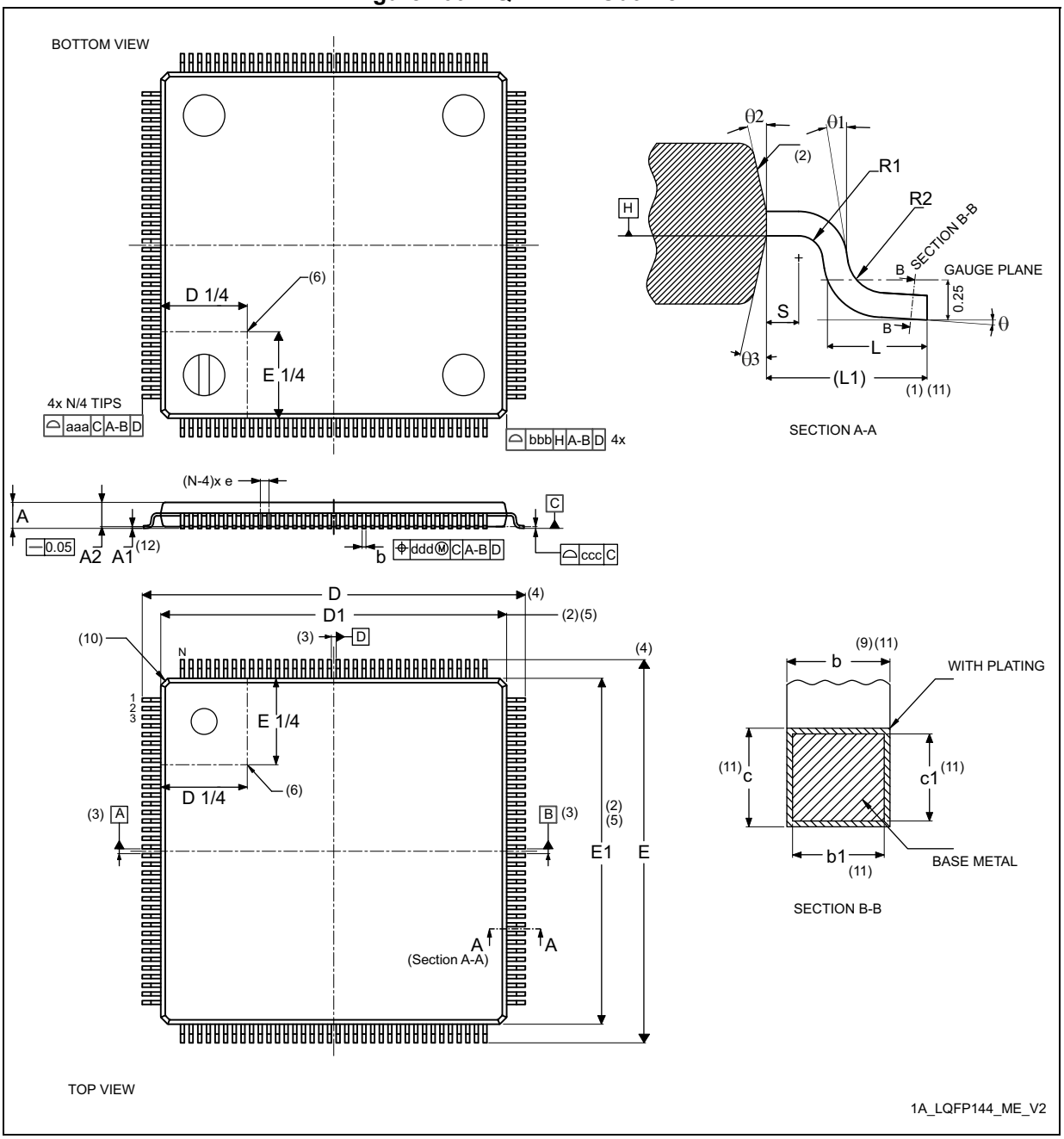


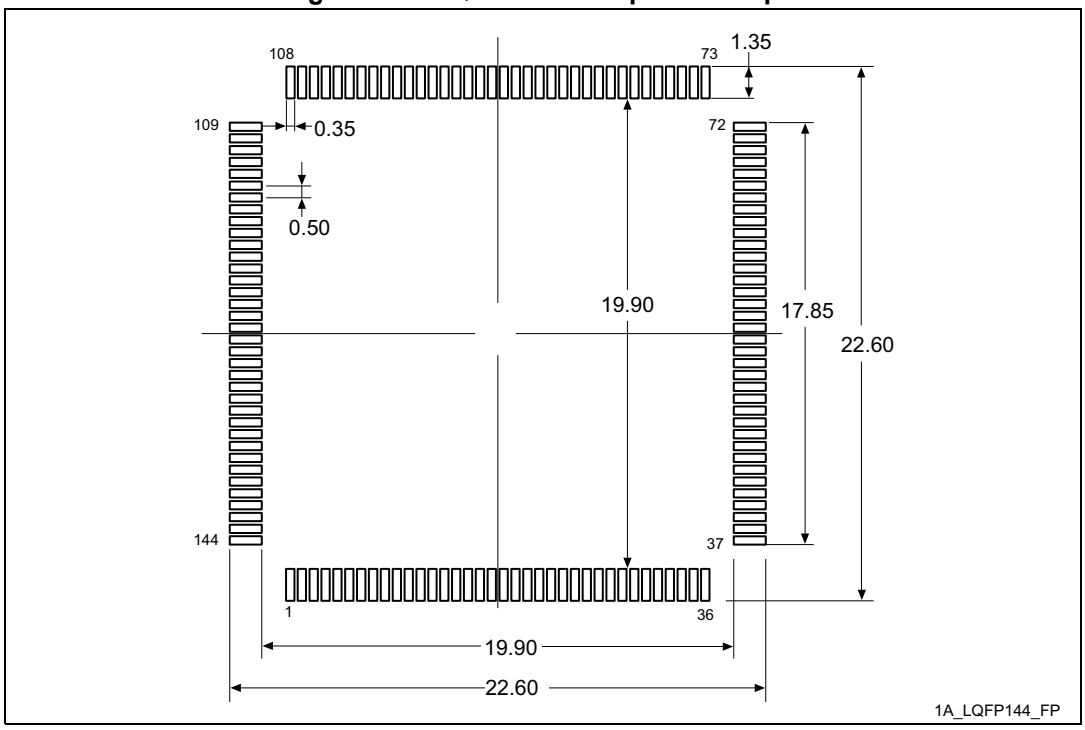
Table 164. LQFP144 - Mechanical data

Symbol	millimeters			inches[14]		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.60	-	-	0.0630
A1[12]	0.05	-	0.15	0.0020	-	0.0059
A2	1.35	1.40	1.45	0.0531	0.0551	0.0571
b[9][11]	0.17	0.22	0.27	0.0067	0.0087	0.0106
b1[11]	0.17	0.20	0.23	0.0067	0.0079	0.0090
c[11]	0.09	-	0.20	0.0035	-	0.0079
c1[11]	0.09	-	0.16	0.0035	-	0.0063
D[4]	22.00 BSC			0.8661 BSC		
D1[2][5]	20.00 BSC			0.7874 BSC		
E[4]	22.00 BSC			0.8661 BSC		
E1[2][5]	20.00 BSC			0.7874 BSC		
e	0.50 BSC			0.0197 BSC		
L	0.45	0.60	0.75	0.0177	0.0236	0.0295
L1	1.00 REF			0.0394 REF		
N[13]	144					
θ	0°	3.5°	7°	0°	3.5°	7°
θ1	0°	-	-	0°	-	-
θ2	10°	12°	14°	10°	12°	14°
θ3	10°	12°	14°	10°	12°	14°
R1	0.08	-	-	0.0031	-	-
R2	0.08	-	0.20	0.0031	-	0.0079
S	0.20	-	-	0.0079	-	-
aaa	0.20			0.0079		
bbb	0.20			0.0079		
ccc	0.08			0.0031		
ddd	0.08			0.0031		

Notes:

1. Dimensioning and tolerancing schemes conform to ASME Y14.5M-1994.
2. The Top package body size may be smaller than the bottom package size by as much as 0.15 mm.
3. Datums A-B and D to be determined at datum plane H.
4. To be determined at seating datum plane C.
5. Dimensions D1 and E1 do not include mold flash or protrusions. Allowable mold flash or protrusions is “0.25 mm” per side. D1 and E1 are Maximum plastic body size dimensions including mold mismatch.
6. Details of pin 1 identifier are optional but must be located within the zone indicated.
7. All Dimensions are in millimeters.
8. No intrusion allowed inwards the leads.
9. Dimension “b” does not include dambar protrusion. Allowable dambar protrusion shall not cause the lead width to exceed the maximum “b” dimension by more than 0.08 mm. Dambar cannot be located on the lower radius or the foot. Minimum space between protrusion and an adjacent lead is 0.07 mm for 0.4 mm and 0.5 mm pitch packages.
10. Exact shape of each corner is optional.
11. These dimensions apply to the flat section of the lead between 0.10 mm and 0.25 mm from the lead tip.
12. A1 is defined as the distance from the seating plane to the lowest point on the package body.
13. “N” is the number of terminal positions for the specified body size.
14. Values in inches are converted from mm and rounded to 4 decimal digits.
15. Drawing is not to scale.

Figure 101. LQFP144 - Footprint example



1. Dimensions are expressed in millimeters.

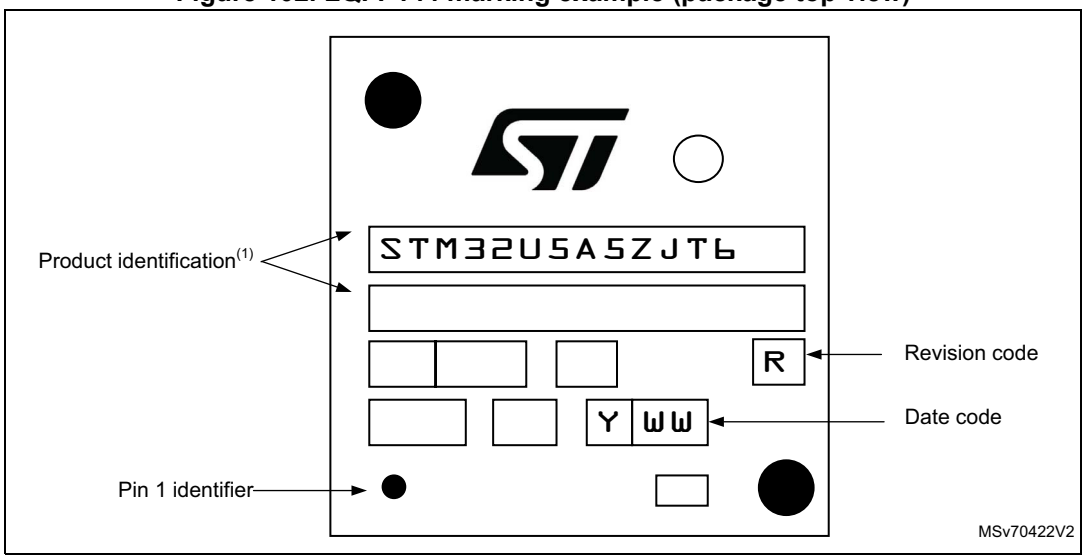
Device marking for LQFP144

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

Figure 102. LQFP144 marking example (package top view)

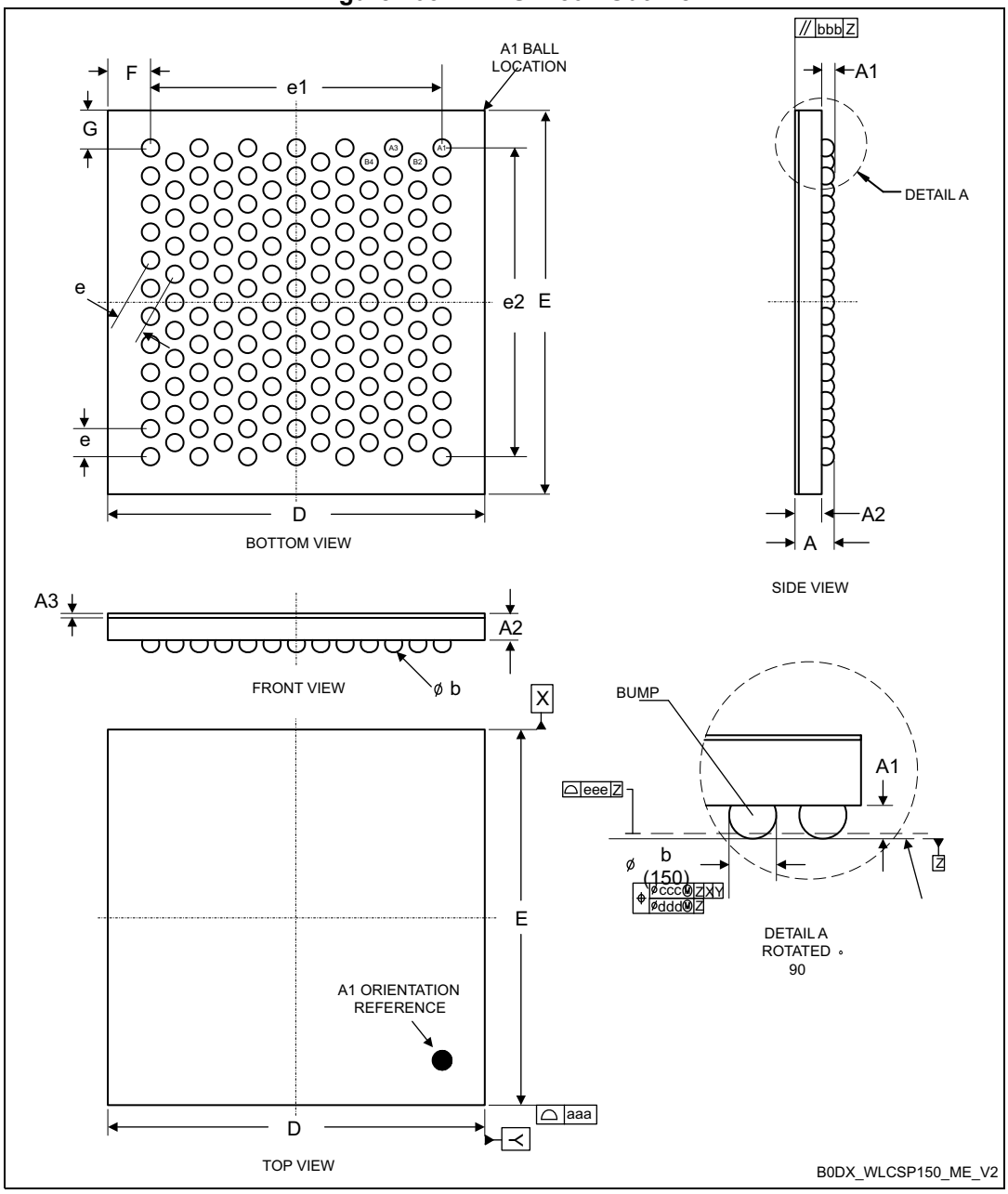


1. Parts marked as ES or E or accompanied by an Engineering Sample notification letter are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

6.5 WLCSP150 package information (B0DX)

This WLCSP is a 150-ball, 5.38 x 5.47 mm, 0.4 mm pitch, wafer level chip scale array package.

Figure 103. WLCSP150 - Outline



1. Drawing is not to scale.
2. Dimension is measured at the maximum bump diameter parallel to primary datum Z.
3. Primary datum Z and seating plane are defined by the spherical crowns of the bump.
4. Bump position designation per JESD 95-1, SPP-010. The tolerance of position that controls the location of the pattern of balls with respect to datums X and Y. For each ball, there is a cylindrical tolerance zone ccc perpendicular to datum Z and located on true position with respect to datums X and Y as defined by e. The axis perpendicular to datum Z of each ball must lie within this tolerance zone.

Table 165. WLCSP150 - Mechanical data

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
A	-	-	0.58	-	-	0.0228
A1[2]	-	0.17	-	-	0.0067	-
A2[2]	-	0.38	-	-	0.0150	-
A3[3]	-	0.025	-	-	0.0010	-
b[4]	0.23	0.26	0.28	0.0090	0.0102	0.0110
D	5.36	5.38	5.40	0.2110	0.2118	0.2126
E	5.45	5.47	5.49	0.2146	0.2153	0.2161
e	-	0.40	-	-	0.0157	-
e1	-	4.16	-	-	0.1638	-
e2	-	4.40	-	-	0.1732	-
F[5]	-	0.612	-	-	0.0241	-
G[5]	-	0.535	-	-	0.0212	-
N	150					
aaa	-	0.10	-	-	0.0043	-
bbb	-	0.10	-	-	0.0043	-
ccc[6]	-	0.10	-	-	0.0043	-
ddd[7]	-	0.05	-	-	0.0020	-
eee	-	0.05	-	-	0.0020	-

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. The maximum total package height is calculated by the RSS method (root sum square) using nominal and tolerances values of A1 and A2.
3. Back side coating. Nominal dimension is rounded to the third decimal place resulting from process capability.
4. Dimension is measured at the maximum bump diameter parallel to primary datum Z.
5. Calculated dimensions are rounded to the third decimal place.
6. Bump position designation per JESD 95-1, SPP-010. The tolerance of position that controls the location of the pattern of balls with respect to datums X and Y. For each ball, there is a cylindrical tolerance zone ccc perpendicular to datum Z and located on true position with respect to datums X and Y as defined by e. The axis perpendicular to datum Z of each ball must lie within this tolerance zone.
7. The tolerance of position that controls the location of the balls within the matrix with respect to each other. For each ball, there is a cylindrical tolerance zone ddd perpendicular to datum Z and located on true position as defined by e. The axis perpendicular to datum Z of each ball must lie within this tolerance zone. Each tolerance zone ddd in the array is contained entirely in the respective zone ccc above. The axis of each ball must lie simultaneously in both tolerance zones.

Figure 104. WLCSP150 - Recommended footprint

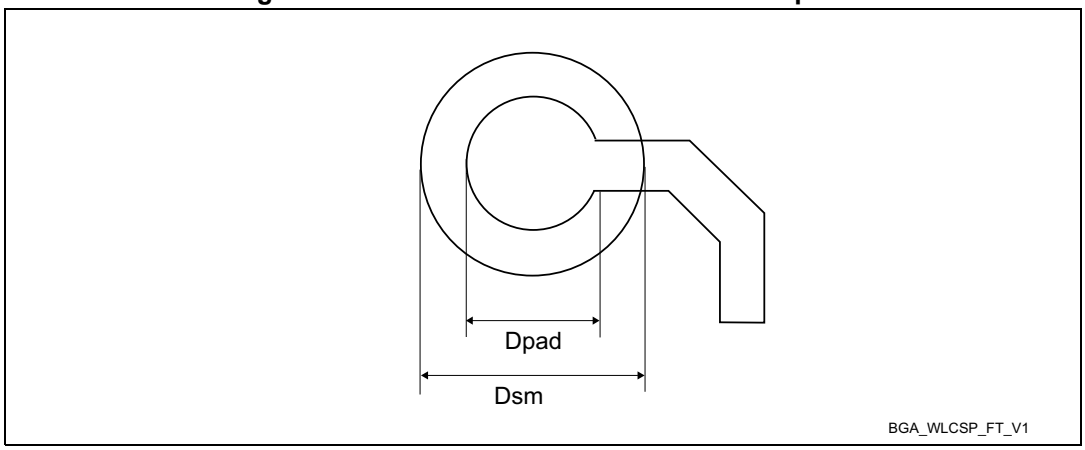


Table 166. WLCSP150 - Recommended PCB design rules

Dimension	Recommended values
Pitch	0.4 mm
Dpad	0,250 mm
Dsm	0.325 mm typ. (depends on soldermask registration tolerance)
Stencil opening	0.325 mm
Stencil thickness	0.080 to 0.100 mm

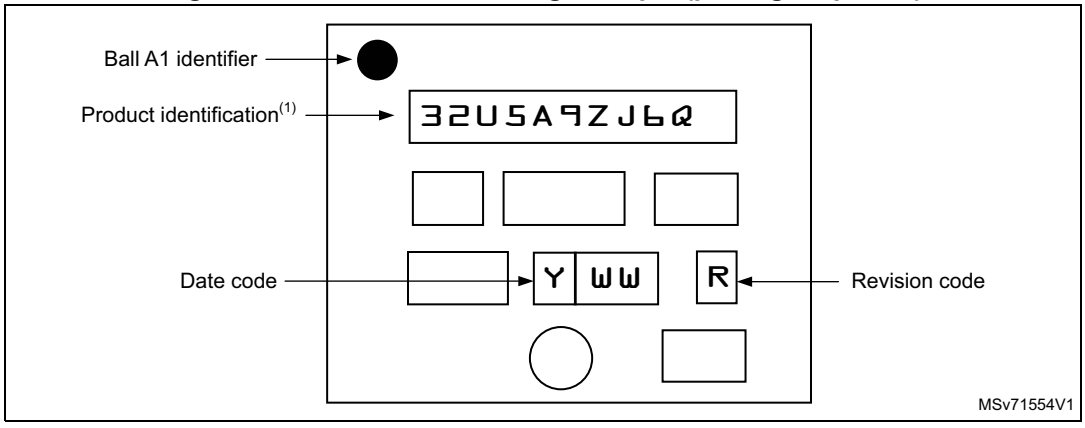
Device marking for WLCSP150

The following figure gives an example of topside marking orientation versus ball 1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

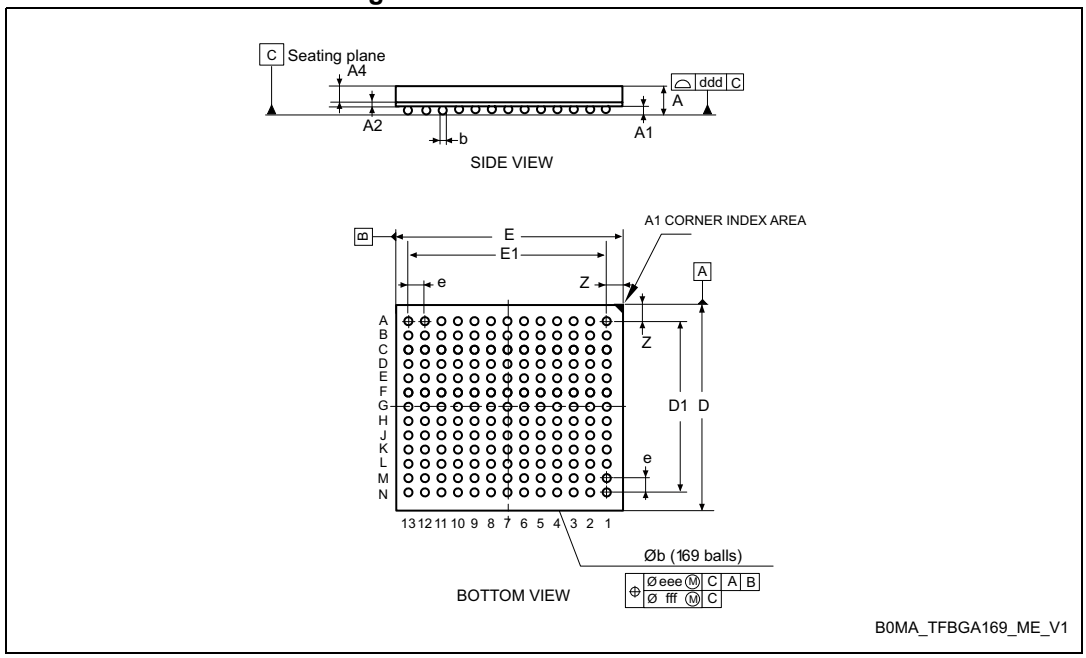
Figure 105. WLCSP150 marking example (package top view)



6.6 TFBGA169 package information (B0MA)

This TFBGA is a 169-ball, 7 x 7 mm, 0.50 mm pitch, thin fine pitch ball grid array package.

Figure 106. TFBGA169 - Outline



1. Drawing is not to scale.
2. - The terminal A1 corner must be identified on the top surface by using a corner chamfer, ink or metallized markings, or other feature of package body or integral heat-slug.
   - A distinguishing feature is allowable on the bottom surface of the package to identify the terminal A1 corner. Exact shape of each corner is optional.

Table 167. TFBGA169 - Mechanical data

Symbol	millimeters			inches(1)		
	Min.	Typ.	Max.	Min.	Typ.	Max.
A (2)	-	-	1.137	-	-	0.0448
A1	0.125	-	-	0.0049	-	-
A2	-	0.29	-	-	0.0114	-
A4	-	0.62	-	-	0.0244	-
b(3)	0.25	0.30	0.35	0.0098	0.0118	0.0138
D	6.95	7.000	7.05	0.2736	0.2756	0.2776
D1	-	6.00	-	0.2343	0.2362	0.2382
E	6.95	7.000	7.05	0.2736	0.2756	0.2776
E1	-	6.00	-	0.2343	0.2362	0.2382
e	-	0.50	-	-	0.0197	-
Z	-	0.50	-	0.0177	0.0197	0.0217
ddd	-	-	0.08	-	-	0.0031

Table 167. TFBGA169 - Mechanical data (continued)

Symbol	millimeters			inches[1]		
	Min.	Typ.	Max.	Min.	Typ.	Max.
eee[4]	-	-	0.09	-	-	0.0035
fff[5]	-	-	0.05	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. - Thin profile: 1.00mm < A ≤ 1.20mm / Fine pitch: e < 1.00 mm pitch.
   - The total profile height (Dim A) is measured from the seating plane to the top of the component
   - The maximum total package height is calculated by the following methodology:
   A Max = A1 Typ + A2 Typ + A4 Typ +√ (A1² + A2² + A4² tolerance values)
3. The typical ball diameter before mounting is 0.25 mm.
4. The tolerance of position that controls the location of the pattern of balls with respect to datums A and B. For each ball there is a cylindrical tolerance zone eee perpendicular to datum C and located on true position with respect to datums A and B as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone.
5. The tolerance of position that controls the location of the balls within the matrix with respect to each other. For each ball there is a cylindrical tolerance zone fff perpendicular to datum C and located on true position as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone. Each tolerance zone fff in the array is contained entirely in the respective zone eee above The axis of each ball must lie simultaneously in both tolerance zones.

Figure 107. TFBGA169 - Footprint example

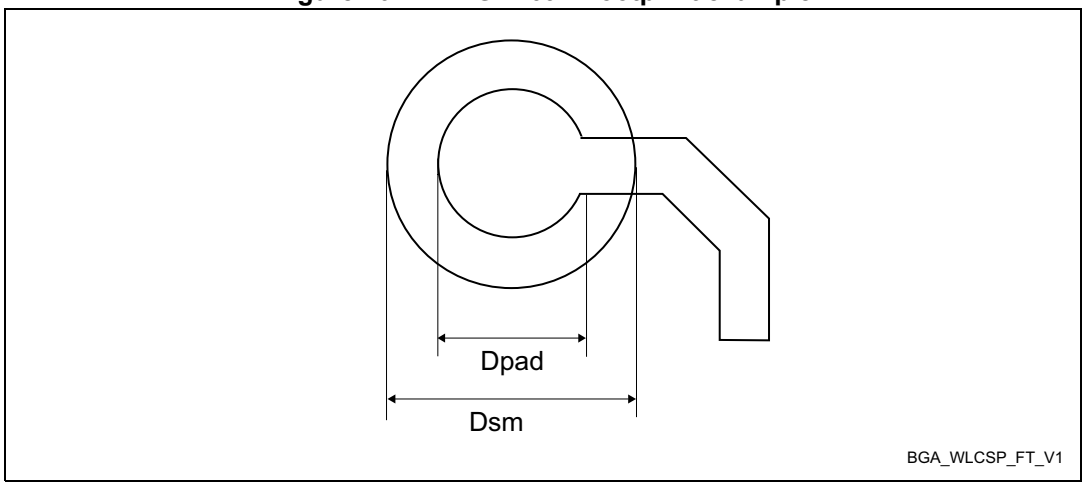


Table 168. TFBGA169 - Example of PCB design rules (0.5 mm pitch BGA)

Dimension	Values
Pitch	0.5 mm
Dpad	0.30 mm
Dsm	0.376 mm (pad + 2 x 0.038)
Board metal pad diameter	0.25 mm to 0.30 mm
Trace width top view	0.14 mm aperture diameter.

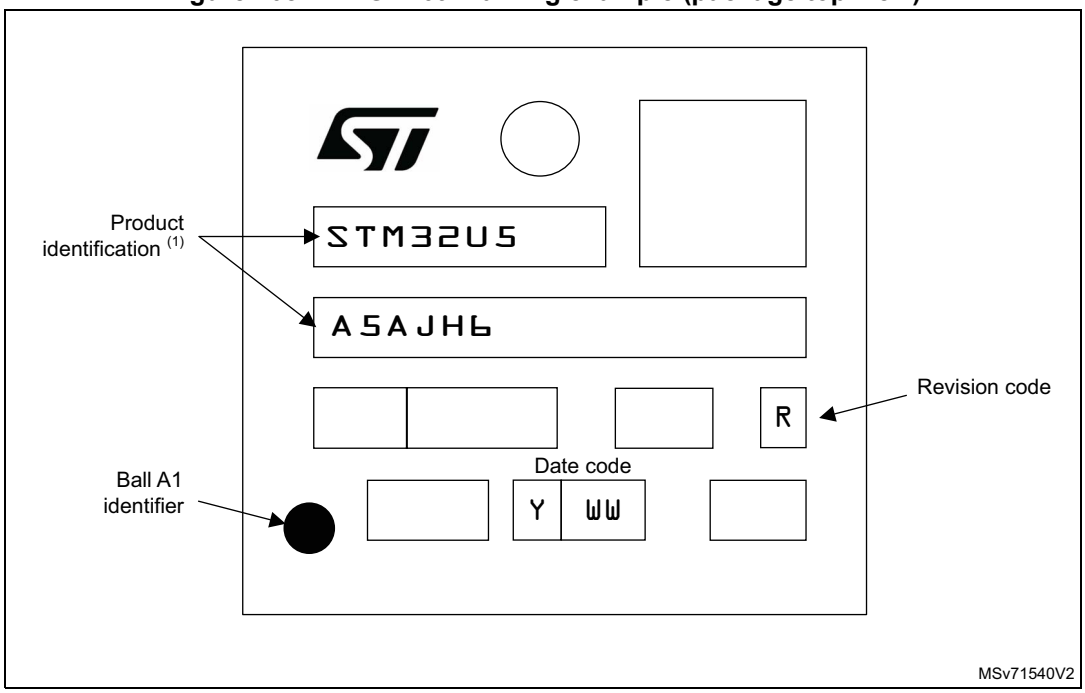
Device marking for TFBGA169

The following figure gives an example of topside marking orientation versus ball A1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

Figure 108. TFBGA169 marking example (package top view)

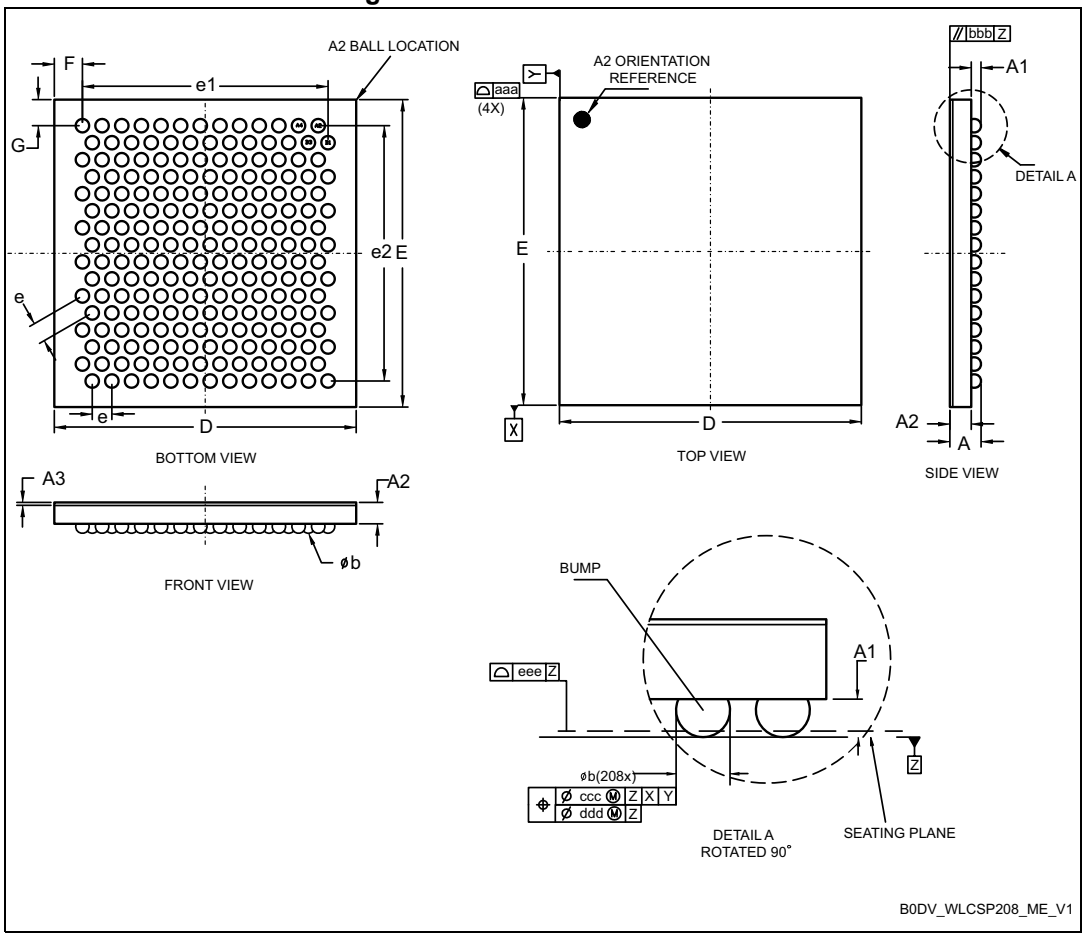


1. Parts marked as ES or E or accompanied by an Engineering Sample notification letter are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

6.7 WLCSP208 package information (B0DV)

This WLCSP is a 208-ball, 5.38 x 5.47 mm, 0.35 mm pitch, wafer level chip scale package.

Figure 109. WLCSP208 - Outline



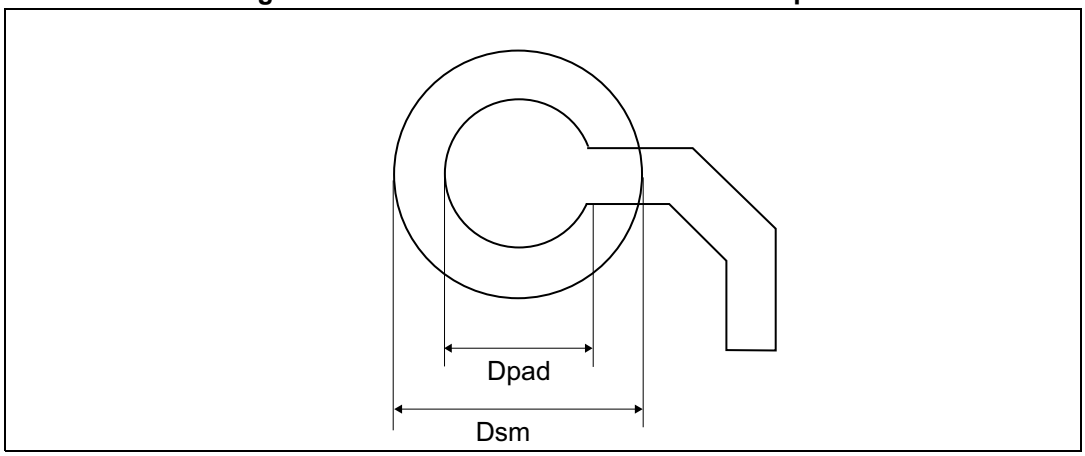
1. Drawing is not to scale.
2. Dimension is measured at the maximum bump diameter parallel to primary datum Z.
3. Primary datum Z and seating plane are defined by the spherical crowns of the bump.
4. Bump position designation per JESD 95-1, SPP-010. The tolerance of position that controls the location of the pattern of balls with respect to datums X and Y. For each ball there is a cylindrical tolerance zone ccc perpendicular to datum Z and located on true position with respect to datums X and Y as defined by e. The axis perpendicular to datum Z of each ball must lie within this tolerance zone.

Table 169. WLCSP208 - Mechanical data

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
A[2]	-	-	0.58	-	-	0.0228
A1	-	0.17	-	-	0.0067	-
A2	-	0.38	-	-	0.0150	-
A3[3]	-	0.025	-	-	0.0010	-
b[4]	0.22	0.24	0.27	0.0087	0.0094	0.0106
D	5.37	5.38	5.39	0.2114	0.2118	0.2122
E	5.45	5.47	5.49	0.2146	0.2154	0.2161
e	-	0.35	-	-	0.0138	-
e1	-	4.38	-	-	0.1724	-
e2	-	4.55	-	-	0.1791	-
F[5]	-	0.503	-	-	0.0198	-
G[5]	-	0.462	-	-	0.0182	-
N	208					
aaa	-	-	0.10	-	-	0.0039
bbb	-	-	0.10	-	-	0.0039
ccc[6]	-	-	0.10	-	-	0.0039
ddd[7]	-	-	0.05	-	-	0.0020
eee	-	-	0.05	-	-	0.0020

1. Values in inches are converted from mm and rounded to 4decimal digits.
2. The maximum total package height is calculated by the RSS method (Root Sum Square) using nominal and tolerances values of A1 and A2.
3. Back side coating. Nominal dimension is rounded to the 3rd decimal place resulting from process capability.
4. Dimension is measured at the maximum bump diameter parallel to primary datum Z.
5. Calculated dimensions are rounded to the 3rd decimal place
6. Bump position designation per JESD 95-1, SPP-010. The tolerance of position that controls the location of the pattern of balls with respect to datums X and Y. For each ball there is a cylindrical tolerance zone ccc perpendicular to datum Z and located on true position with respect to datums X and Y as defined by e. The axis perpendicular to datum Z of each ball must lie within this tolerance zone.
7. The tolerance of position that controls the location of the balls within the matrix with respect to each other. For each ball there is a cylindrical tolerance zone ddd perpendicular to datum Z and located on true position as defined by e. The axis perpendicular to datum Z of each ball must lie within this tolerance zone. Each tolerance zone ddd in the array is contained entirely in the respective zone ccc above. The axis of each ball must lie simultaneously in both tolerance zones.

Figure 110. WLCSP208 - Recommended footprint



1. Dimensions are expressed in millimeters.

Table 170. WLCSP208 - Recommended PCB design rules

Dimension	Recommended values
Pitch	0.35 mm
Dpad	0,210 mm
Dsm	0.275 mm typ. (depends on soldermask registration tolerance)
Stencil opening	0.235 mm
Stencil thickness	0.100 mm

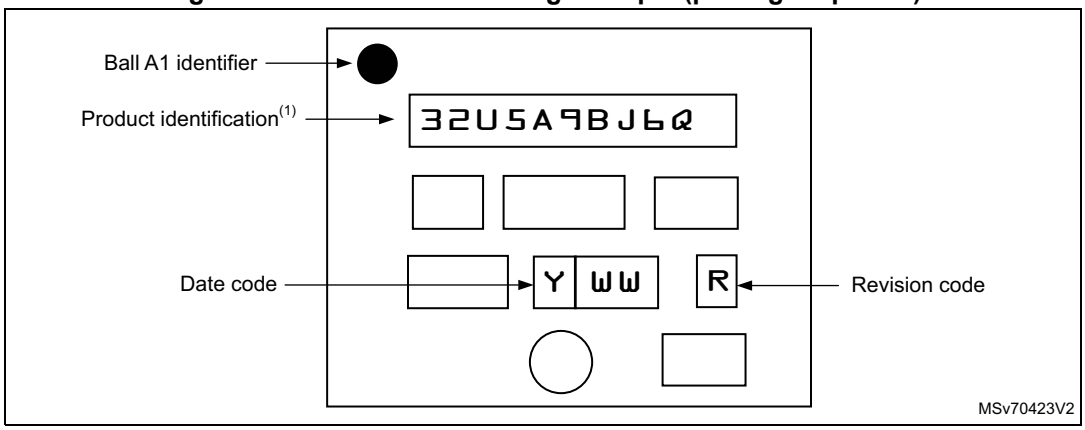
Device marking for WLCSP208

The following figure gives an example of topside marking orientation versus pin 1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

Figure 111. WLCSP208 marking example (package top view)

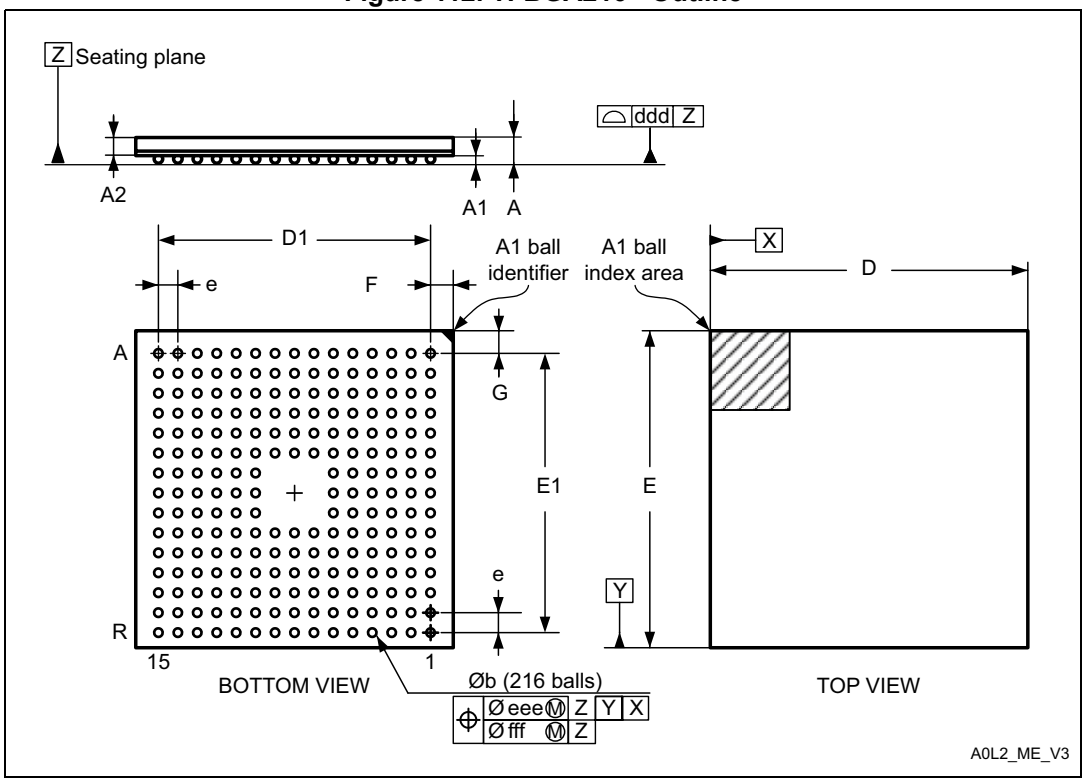


1. Parts marked as ES or E or accompanied by an Engineering Sample notification letter are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

6.8 TFBGA216 package information (A0L2)

This TFBGA is a 216-ball, 13 x 13 mm, 0.8 mm pitch, fine pitch ball grid array package.

Figure 112. TFBGA216 - Outline



1. Drawing is not to scale.
2. • The terminal A1 corner must be identified on the top surface by using a corner chamfer, ink or metalized markings, or other feature of package body or integral heat slug.
   • A distinguishing feature is allowable on the bottom surface of the package to identify the terminal A1 corner. Exact shape of each corner is optional

Table 171. TFBGA216 - Mechanical data

Symbol	millimeters			inches[1]		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.200	-	-	0.0472
A1[2]	0.150	-	-	0.0059	-	-
A2	-	0.760	-	-	0.0299	-
b[3]	0.350	0.400	0.450	0.0138	0.0157	0.0177
D	12.850	13.000	13.150	0.5059	0.5118	0.5177
D1	-	11.200	-	-	0.4409	-
E	12.850	13.000	13.150	0.5059	0.5118	0.5177
E1	-	11.200	-	-	0.4409	-
e	-	0.800	-	-	0.0315	-
F	-	0.900	-	-	0.0354	-
G	-	0.900	-	-	0.0354	-
ddd	-	-	0.100	-	-	0.0039
eee[4]	-	-	0.150	-	-	0.0059
fff[5]	-	-	0.080	-	-	0.0031

1. Values in inches are converted from mm and rounded to four decimal digits.
2. • The terminal A1 corner must be identified on the top surface by using a corner chamfer, ink or metallized markings, or other feature of package body or integral heat slug.
   • A distinguishing feature is allowable on the bottom surface of the package to identify the terminal A1 corner. Exact shape of each corner is optional.
3. Initial ball equal 0.350 mm.
4. The tolerance of position that controls the location of the pattern of balls with respect to datums A and B. For each ball there is a cylindrical tolerance zone eee perpendicular to datum C and located on true position with respect to datums A and B as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone.
5. The tolerance of position that controls the location of the balls within the matrix with respect to each other. For each ball there is a cylindrical tolerance zone fff perpendicular to datum C and located on true position as defined by e. The axis perpendicular to datum C of each ball must lie within this tolerance zone. Each tolerance zone fff in the array is contained entirely in the respective zone eee above The axis of each ball must lie simultaneously in both tolerance zones.

Figure 113. TFBGA216 - Footprint example

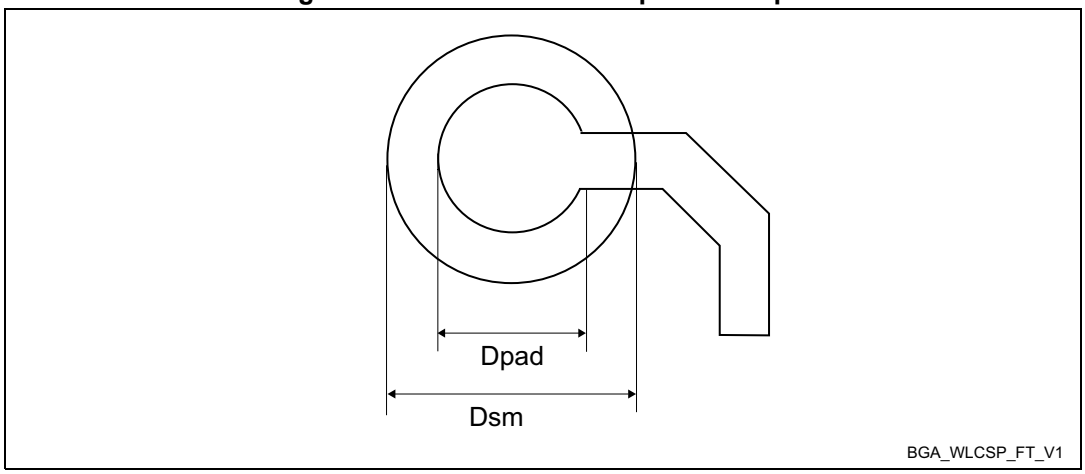


Table 172. TFBGA216 - Example of PCB design rules (0.8 mm pitch)

Dimension	Values
Pitch	0.8 mm
Dpad	0.400 mm
Dsm	0.470 mm typ. (depends on the soldermask registration tolerance)
Stencil opening	0.400 mm
Stencil thickness	Between 0.100 mm and 0.125 mm
Pad trace width	0.120 mm

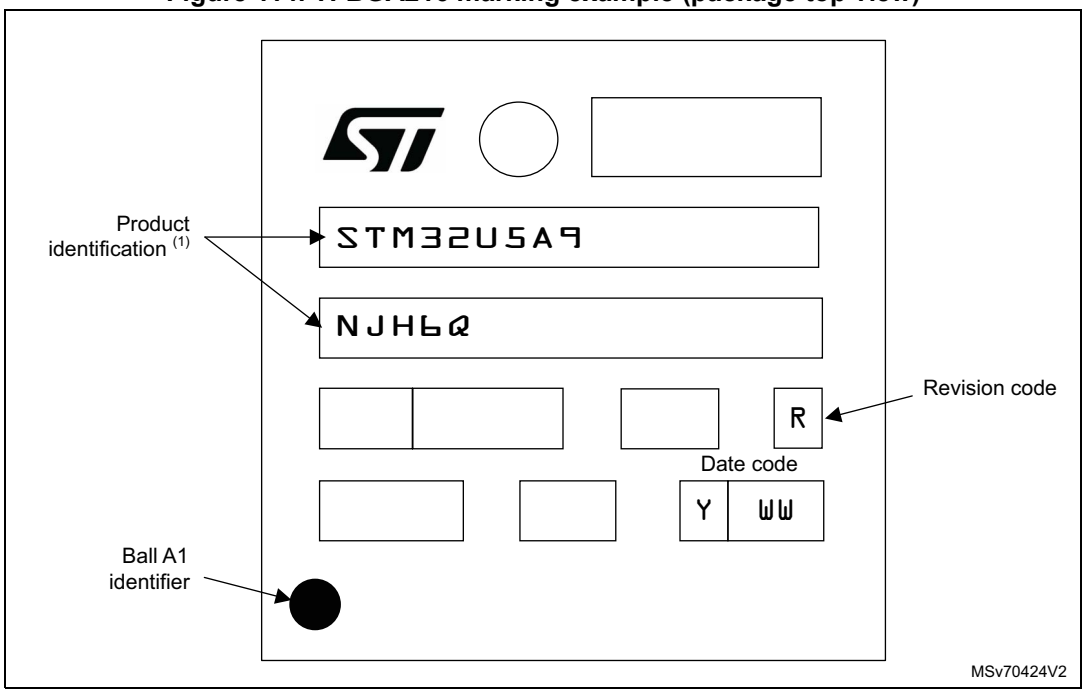
Device marking for TFBGA216

The following figure gives an example of topside marking orientation versus ball A1 identifier location.

The printed markings may differ depending on the supply chain.

Other optional marking or inset/upset marks, which also depend on supply chain operations, are not indicated below.

Figure 114. TFBGA216 marking example (package top view)



1. Parts marked as ES or E or accompanied by an Engineering Sample notification letter are not yet qualified and therefore not approved for use in production. ST is not responsible for any consequences resulting from such use. In no event will ST be liable for the customer using any of these engineering samples in production. ST's Quality department must be contacted prior to any decision to use these engineering samples to run a qualification activity.

6.9 Package thermal characteristics

The maximum chip-junction temperature, T_J max, in degrees Celsius, can be calculated using the following equation:

T_J max = T_A max + (P_D max * Θ_{JA})

where:

- T_A max is the maximum ambient temperature in °C.
- Θ_{JA} is the package junction-to-ambient thermal resistance in °C/W.
- P_D max is the sum of P_{INT} max and $P_{I/O}$ max (P_D max = P_{INT} max + $P_{I/O}$ max).
- P_{INT} max is the product of I_{DD} and V_{DD}, expressed in Watts. This is the maximum chip internal power.

$P_{I/O}$ max represents the maximum power dissipation on output pins:

$P_{I/O}$ max = $\sum(V_{OL} * I_{OL}) + \sum((V_{DDIOx} - V_{OH}) * I_{OH})$

taking into account the actual V_{OL}/I_{OL} and V_{OH}/I_{OH} of the I/Os at low and high level in the application.

Table 173. Package thermal characteristics

Symbol	Parameter	Package	Value	Unit
Θ_{JA}	Thermal resistance junction-ambient	LQFP64 (10 x10 mm)	36.0	°C/W
		LQFP100 (14 x 14 mm)	32.2	
		UFBGA132 (7 x 7 mm)	30.9	
		LQFP144 (20 x 20 mm)	34.1	
		WLCSP150 (5.38 x 5.47 mm)	31.7	
		TFBGA169 (7 x 7 mm)	32.2	
		WLCSP208 (5.38 x 5.47 mm)	35.4	
		TFBGA216 (13 x 13 mm)	26.5	
Θ_{JB}	Thermal resistance junction-board	LQFP64 (10 x10 mm)	18.3	
		LQFP100 (14 x14 mm)	18.0	
		UFBGA132 (7 x 7 mm)	15.9	
		LQFP144 (20 x 20 mm)	22.9	
		WLCSP150 (5.38 x 5.47 mm)	13.5	
		TFBGA169 (7 x 7 mm)	17.7	
		WLCSP208 (5.38 x 5.47 mm)	12.5	
		TFBGA216 (13 x 13 mm)	16.0	
Θ_{JC}	Thermal resistance junction-case	LQFP64 (10 x 10 mm)	6.8	
		LQFP100 (14 x 14 mm)	5.9	
		UFBGA132 (7 x 7 mm)	6.0	
		LQFP144 (20 x 20 mm)	6.0	
		WLCSP150 (5.38 x 5.47 mm)	0.9	
		TFBGA169 (7 x 7 mm)	9.0	
		WLCSP208 (5.38 x 5.47 mm)	1.0	
		TFBGA216 (13 x 13 mm)	7.7	

6.9.1 Reference documents

- JESD51-2 Integrated Circuits Thermal Test Method Environment Conditions - Natural Convection (Still Air) available on www.jedec.org.
- For information on thermal management, refer to application note “Guidelines for thermal management on STM32 applications” (AN5036) available on www.st.com.

7 Ordering information

Example: STM32 U 5A9 B J Y 6 Q TR

Device family

STM32 = Arm® based 32-bit microcontroller

Product type

U = ultra-low-power

Device subfamily

5A9 = STM32U5A9xx with GFX accelerators and interfaces, OTG_HS, and hardware encryption accelerators
5A5 = STM32U5A5xx with OTG_HS and hardware encryption accelerators

Pin/ball count

R = 64 pins
V = 100 pins
Q = 132 balls
Z = 144 pins or 150 balls
A = 169 balls
B = 208 balls
N= 216 balls

Flash memory size

I = 2 Mbytes
J = 4 Mbytes

Package

T = LQFP
H = TFBGA
I = UFBGA
Y = WLCSP

Temperature range

6 = Industrial temperature range, –40 to 85 °C (105 °C junction)

3 = Industrial temperature range, -40 to 125°C (130°C junction)

Dedicated pinout

Q = Dedicated pinout supporting internal SMPS step-down converter

Packing

TR = tape and reel

xxx = programmed parts

For a list of available options (such as speed or package) or for further information on any aspect of this device, contact the nearest ST sales office.

8 Important security notice

The STMicroelectronics group of companies (ST) places a high value on product security, which is why the ST product(s) identified in this documentation may be certified by various security certification bodies and/or may implement our own security measures as set forth herein. However, no level of security certification and/or built-in security measures can guarantee that ST products are resistant to all forms of attacks. As such, it is the responsibility of each of ST's customers to determine if the level of security provided in an ST product meets the customer needs both in relation to the ST product alone, as well as when combined with other components and/or software for the customer end product or application. In particular, take note that:

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- Certification bodies have the right to evaluate, grant and revoke security certification in relation to ST products. These certification bodies are therefore independently responsible for granting or revoking security certification for an ST product, and ST does not take any responsibility for mistakes, evaluations, assessments, testing, or other activity carried out by the certification body with respect to any ST product.
- Industry-based cryptographic algorithms (such as AES, DES, or MD5) and other open standard technologies which may be used in conjunction with an ST product are based on standards which were not developed by ST. ST does not take responsibility for any flaws in such cryptographic algorithms or open technologies or for any methods which have been or may be developed to bypass, decrypt or crack such algorithms or technologies.
- While robust security testing may be done, no level of certification can absolutely guarantee protections against all attacks, including, for example, against advanced attacks which have not been tested for, against new or unidentified forms of attack, or against any form of attack when using an ST product outside of its specification or intended use, or in conjunction with other components or software which are used by customer to create their end product or application. ST is not responsible for resistance against such attacks. As such, regardless of the incorporated security features and/or any information or support that may be provided by ST, each customer is solely responsible for determining if the level of attacks tested for meets their needs, both in relation to the ST product alone and when incorporated into a customer end product or application.
- All security features of ST products (inclusive of any hardware, software, documentation, and the like), including but not limited to any enhanced security features added by ST, are provided on an "AS IS" BASIS. AS SUCH, TO THE EXTENT PERMITTED BY APPLICABLE LAW, ST DISCLAIMS ALL WARRANTIES, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, unless the applicable written and signed contract terms specifically provide otherwise.

9 Revision history

Table 174. Document revision history

Date	Revision	Changes
16-Feb-2023	1	Initial release.
18-Jul-2023	2	Updated: – CoreMark® value changed in *Features* – *Table 2: STM32U5Axxx features and peripheral counts* – *Figure 2: STM32U5AxxxxxQ power supply overview (with SMPS)* – *Figure 3: STM32U5Axxx power supply overview (without SMPS)* – *Section 3.9.1: Power supply schemes* – *Section 3.9.3: Low-power modes* – *Table 10: Functionalities depending on the working mode* – *Table 15: ADC features* – *Figure 23: STM32U5Axxx power supply scheme (without SMPS)* – *Figure 24: STM32U5AxxxxxQ power supply scheme (with SMPS)* – Typical values for temperatures between 55 °C and 125 °C in *Section 5.3.6: Supply current characteristics* – *Table 79: Low-speed external user clock characteristics* – Increased HSE consumption during startup from 8 µA to 8 mA *in Table 80: HSE oscillator characteristics* – *Table 92: ESD absolute maximum ratings* – *Table 97: Output voltage characteristics for FT_t I/Os in V_{BAT} mode, and for FT_o I/Os* – *Table 101: Output AC characteristics for FT_t I/Os in V_{BAT} mode, and for FT_o I/Os* – *t_{CAL} and t_{OFF_CAL} values in Table 105: 14-bit ADC12 characteristics* – *Table 107: 14-bit ADC12 accuracy* – *t_{OFF_CAL} values in Table 108: 12-bit ADC4 characteristics* – *Section 5.3.28: Temperature and backup domain supply thresholds monitoring* – *Table 124: PSSI receive characteristics* – *Table 127: MIPI D-PHY AC characteristics LP mode and HS/LP transitions* – *Table 134: Asynchronous non-multiplexed SRAM/PSRAM/NOR read timings* – *Table 148: OCTOSPI characteristics in SDR mode* – *Table 152: HSPI characteristics in DTR mode (no DQS)* – *Table 150: OCTOSPI characteristics in DTR mode (with DQS)/HyperBus* – HSPI characteristics tables and figures in *Section 5.3.37: HSPI characteristics* – *Figure 82: USART timing diagram in master mode* – *Figure 83: USART timing diagram in slave mode*

Table 174. Document revision history (continued)

Date	Revision	Changes
18-Jul-2023	2 (cont'd)	– *Figure 84: SPI timing diagram - slave mode and CPHA = 0* – *Figure 85: SPI timing diagram - slave mode and CPHA = 1* – *Figure 86: SPI timing diagram - master mode* – *Figure 87: SAI master timing diagram* – *Figure 88: SAI slave timing diagram* – *Section 6.1: LQFP64 package information (5W)* – *Section 6.2: LQFP100 package information (1L)* – *Section 6.3: UFBGA132 package information (A0G8)* – *Section 6.4: LQFP144 package information (1A)* – *Section 6.5: WLCSP150 package information (B0DX)* – *Section 6.6: TFBGA169 package information (B0MA)* – *Section 6.7: WLCSP208 package information (B0DV)* – *Section 6.8: TFBGA216 package information (A0L2)* – *Figure 95: LQFP100 marking example (package top view)* – *Figure 101: LQFP144 marking example (package top view)* – *Figure 107: TFBGA169 marking example (package top view)* – *Figure 110: WLCSP208 marking example (package top view)* Added: – SESIP3 and PSA Level 3 Certified Assurance Target in *Security and cryptography* – STM32U5A5QI in *Table 1: Device summary*, *Table 2: STM32U5Axxx features and peripheral counts*, and *Section 7: Ordering information* – *Section 5.3.4: SMPS characteristics* – Maximum values for each temperature in *Section 5.3.6: Supply current characteristics* – Maximum values added in *Table 74: Low-power mode wake-up timings on LDO*, *Table 75: Low-power mode wake-up timings on SMPS*, and *Table 76: Regulator mode transition times* – Current consumption during wake-up tables – *Figure 104: WLCSP150 marking example (package top view)*
5-May-2025	3	Updated: – *Replaced "o" by "-" for Backup domain voltage and temperature monitoring in Table 10: Functionalities depending on the working mode* – *Section 3.9.1: Power supply schemes* – *Section 3.37: Digital camera interface (DCMI)* – Notes in *Section 5.2: Absolute maximum ratings* – *Table 27: STM32U5Axxx pin/ball definitions* – *Table 70: High-speed external user clock characteristics* – *Table 125: WWDG min/max timeout value at 160 MHz (PCLK)* Added: – *Sustainable technology logo in Features* – *Figure 33: HSI16 frequency versus temperature and V_{DD}*

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