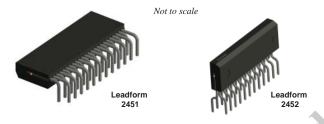


Features and Benefits

- Built-in pre-drive IC
- MOSFET power element
- Alleviate noise generation by adjusting an internal resistor
- CMOS compatible input (5 V)
- High-side gate driver using bootstrap circuit or floating power supply
- Built-in protection circuit for controlling power supply voltage drop (UVLO on VB and VCC)
- Overcurrent protection (OCP), overcurrent limiting (OCL), and thermal shutdown (TSD)
- Output of fault signal during operation of protection circuit
- Output current 1.5, 2, or 2.5 A
- Small SIP (SMA 24-pin)

Packages: Power SIP



Description

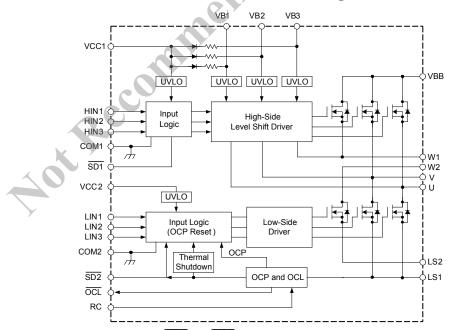
The SMA6860MZ inverter power module (IPM) series provides a robust, highly-integrated solution for optimally controlling 3-phase motor power inverter systems and variable speed control systems used in energy-conserving designs to drive motors of residential and commercial appliances. These ICs take 230 VAC input voltage, and up to 2.5 A (continuous) output current. They can withstand voltages of up to 500 V (MOSFET breakdown voltage).

The SMA6860MZ power package includes an IC with all of the necessary power elements (six MOSFETs), pre-driver ICs (two), and bootstrap diodes (three), needed to configure the main circuit of an inverter. This enables the main circuit of the inverter to be configured with fewer external components than traditional designs.

Applications include residential white goods (home applications) and commercial appliance motor control:

- · Air conditioner fan
- Small ventilation fan
- · Dishwasher pump

Functional Block Diagram



- A. SD1 and SD2 terminals are used for both input and output.
- B. SD1, SD2 and OCL terminals are open-collector output. RC terminal is open-drain output.
- C. Blanking Time (t_{blank}) is used in Overcurrent Limiting (OCL) and Overcurrent Protection (OCP). If the time exceeds the limit, the signal will be output (open-collector output turns on) on the $\overline{SD2}$ pin, and protection operation will start up.

Figure 1. Driver block diagram

High Voltage 3-Phase Motor Drivers

Selection Guide

	MOSFET Breakdown	Output Current				
Part Number	Voltage, V _{DSS} (min) (V)	Continuous, I _O (max) (A)	Pulsed, I _{OP} (max) (A)			
SMA6861MZ	250	2	3.0			
SMA6862MZ	500	1.5	2.25			
SMA6863MZ	500	2.5	3.75			
SMA6864MZ	250	2.5	3.75			
SMA6865MZ	500	2.5	3.75			

Absolute Maximum Ratings, valid at T_A = 25°C

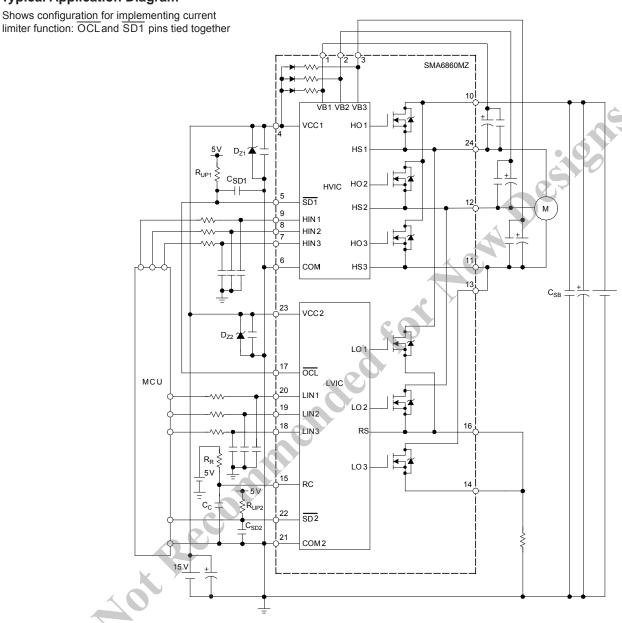
Characteristic	Symbol		Remarks	Rating	Unit
		SMA6861MZ		250	V
		SMA6862MZ	4 01	500	V
MOSFET Breakdown Voltage	V _{DSS}	SMA6863MZ	$V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	500	V
		SMA6864MZ		250	V
		SMA6865MZ		500	V
Logic Supply Voltage	V _{CC}	Between VCC a	nd COM	20	V
Bootstrap Voltage	V _{BS}	Between VB and	d HS (U,V, and W phases)	20	V
		SMA6861MZ		2	А
		SMA6862MZ		1.5	Α
Output Current, Continuous	Io	SMA6863MZ		2.5	Α
		SMA6864MZ		2.5	А
		SMA6865MZ		2.5	Α
	A	SMA6861MZ		3.0	Α
		SMA6862MZ		2.25	Α
Output Current, Pulsed	lop	SMA6863MZ	PW ≤ 100 μs, duty cycle = 1%	3.75	Α
		SMA6864MZ		3.75	Α
		SMA6865MZ		3.75	А
Input Voltage	V _{IN}	HINx and LINx p	pins	-0.5 to 7	V
Pull-up Voltage for Shutdown Pins	V _{SDX}	SDx pins		7	V
Pull-up Voltage for Overcurrent Limiting Pin	V _{OCL}			7	V
Allowable Power Dissipation	P _D	T _C = 25°C		28	W
Thermal Resistance (Junction to Case)	R _{eJC}	All elements ope	erating	4.46	°C/W
Thermal Resistance (Junction to Ambient)	R _{θJA}	All elements ope	erating	31.25	°C/W
Case Operating Temperature	T _{COP}			-20 to 100	°C
Storage Temperature	T _{stg}			-40 to 150	°C

All performance characteristics given are typical values for circuit or system baseline design only and are at the nominal operating voltage and an ambient temperature, T_A , of 25°C, unless otherwise stated.

Recommended Operating Conditions

Characteristic	Symbol		Remarks	Min.	Тур.	Max.	Units
		SMA6861MZ		_	-0	200	V
		SMA6862MZ		-		400	V
Main Supply Voltage	V_{BB}	SMA6863MZ	Between VBB and LS	- 2	1-0	400	V
		SMA6864MZ		-0	P '-	200	V
		SMA6865MZ	A	G	-	400	V
V _{BB} Snubber Capacitor	C _{SB}			0.01	_	0.1	μF
Logic Supply Voltage	V _{CC}	Between VCC and	ICOM	13.5	15	16.5	V
Zener Voltage for VCCx Pins	V_Z	Between VCC and	ICOM	18	_	20	V
Pull-up Voltage	V_{SDx} , V_{OCL}			4.5	5	5.5	V
Pull-up Resistor SD2 Pin	R _{UP2}		A Y	3.3	-	10	kΩ
Pull-up Resistor OCL Pin	R _{UP1}		co	1	-	10	kΩ
Pull-up Resistor RC Pin	R _R			33	-	390	kΩ
Capacitor SDx and OCL Pins	C _{SDX}		20	1	-	10	nF
Capacitor RC Pin	C _C	,		1	-	4.7	nF
Dead Time	t _{dead}	$T_{\rm J} = -20^{\circ}{\rm C} \text{ to } 150^{\circ}$	°C	1.5	_	_	μs
Minimum Input Pulse Width	I _{INMIN(on)}	$T_{\rm J} = -20^{\circ}{\rm C}$ to 150°	C	0.5	_	_	μs
Williman input i dise Width	I _{INMIN(off)}	$T_{\rm J} = -20^{\circ} {\rm C}$ to 150°	°C	0.5	_	_	μs
Switching Frequency	f _{PWM}			_	-	20	kHz
Switching Frequency T _{PWM} – – 20 KHz							

Typical Application Diagram

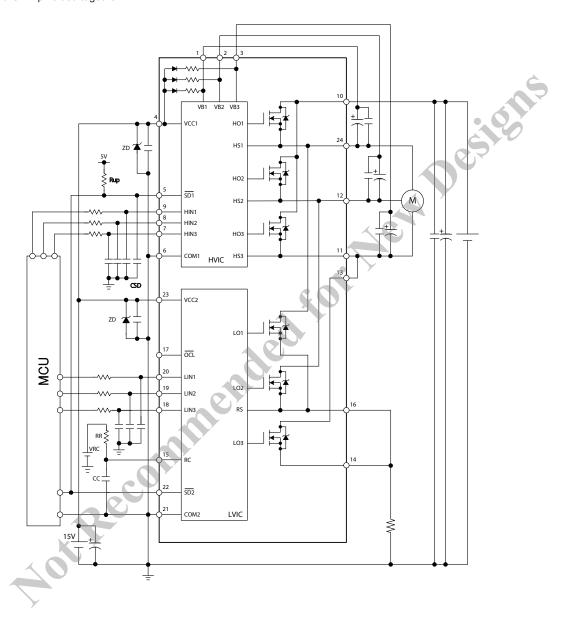


NOTE:

The external electrolytic capacitors should be placed as close to the IC as possible, in order to avoid malfunctions from external noise interference. Put a ceramic capacitor in parallel with the electrolytic capacitor if further reduction of noise susceptibility is necessary.

Typical Application Diagram

Shows configuration without current limiter function: SD1 and SD2 pins tied together



NOTE:

The external electrolytic capacitors should be placed as close to the IC as possible, in order to avoid malfunctions from external noise interference. Put a ceramic capacitor in parallel with the electrolytic capacitor if further reduction of noise susceptibility is necessary.

ELECTRICAL CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
Logic Supply Current	Icc	$V_{CC} = 15 \text{ V}, T_{C} = -20^{\circ}\text{C to } 125^{\circ}\text{C}$	_	2.7	5.0	mA
Bootstrap Supply Current	I _{BX}	V_{BX} = 15 V, V_{HIN} = 5 V, T_{C} = -20°C to 125°C	_	135	380	μΑ
Input Voltage	V _{IH}	V _{CC} = 15 V	_	2.9	3.4	V
Input Voltage	V _{IL}	V _{CC} = 15 V	1.6	2.1	-	V
Input Voltage Hysteresis	V _{Ihys}	V _{CC} = 15 V		0.8	_	V
Input Current	I _{IN}	V _{IN} = 5 V	1	230	500	μΑ
	V _{UVHL}	High eide hetween VDv and H. V. en W.	9.0	10.0	11.0	V
	V _{UVHH}	High side, between VBx and U, V, or W	9.5	10.5	11.5	V
Lindon voltage Look Out	V _{UVHhys}	High side, hysteresis		0.5	_	V
Undervoltage Lock Out	V _{UVLL}	Law side between VCC2 and COM2	10.0	11.0	12.0	V
	V _{UVLH}	Low side, between VCC2 and COM2	10.5	11.5	12.5	V
	V _{UVLhys}	Low side, hysteresis	_	0.5	_	V
SDx and OCL Output Voltage	V _{SDX(on)} ,	$V_{SDX} = V_{OCL} = 5 \text{ V}, R_{UPX} = 3.3 \text{ k}\Omega$	_	_	0.6	V
Overtemperature DetectionThreshold	T _{DH}	60	120	135	150	°C
Temperature (Activation and	T _{DL}	V _{CC} = 15 V, high-side and low side	100	115	130	°C
Deactivation)	T _{Dhys}		_	20	-	°C
Overcurrent Protection Trip Voltage	V _{TRIP}	V _{CC} = 15 V	0.9	1.0	1.1	V
Overcurrent Limit Reference Voltage	V _{LIM}	V _{CC} = 15 V	0.5035	0.53	0.5565	V
Overcurrent Protection Hold Time	tp	V_{RC} = 5 V, R_R = 360 k Ω , C_C = 0.0047 μ F	_	2.0	-	ms
Blanking Time	t _{blank}	V _{CC} = 15 V	-	2.0	-	μs
		SMA6861MZ V _R = 250 V	_	-	10	μΑ
		SMA6862MZ V _R = 500 V	_	_	10	μΑ
Bootstrap Diode Leakage Current	I _{LBD}	SMA6863MZ V _R = 500 V	_	_	10	μΑ
		SMA6864MZ V _R = 250 V	_	_	10	μA
		SMA6865MZ V _R = 500 V	_	_	10	μA
Bootstrap Diode Forward Voltage	V_{FBD}	I _F = 0.05 A	_	0.8	1.3	V
Bootstrap Diode Recovery Time	t _{rrb}	I _F / I _{RP} = 100 mA / 100 mA	_	70	_	ns
Bootstrap Diode Series Resistor	R _{BD}		168	210	252	Ω
		SMA6861MZ	250	_	_	V
		SMA6862MZ	500	_	_	V
MOSFET Breakdown Voltage	V _{DSS}	SMA6863MZ $V_{CC} = 15 \text{ V}, I_D = 100 \mu\text{A}, V_{IN} = 0 \text{ V}$	500	_	_	V
		SMA6864MZ	250	_	_	V
		SMA6865MZ	500	_	-	V
		SMA6861MZ V _{CC} = 15 V, V _{DS} = 250 V, V _{IN} = 0 V	-	-	100	μA
		SMA6862MZ V _{CC} = 15 V, V _{DS} = 500 V, V _{IN} = 0 V	_	_	100	μA
MOSFET Leakage Current	I _{DSS}	SMA6863MZ V _{CC} = 15 V, V _{DS} = 500 V, V _{IN} = 0 V	_	_	100	μΑ
		SMA6864MZ V _{CC} = 15 V, V _{DS} = 250 V, V _{IN} = 0 V	_	_	100	μΑ
		SMA6865MZ V _{CC} = 15 V, V _{DS} = 500 V, V _{IN} = 0 V	_	_	100	μΑ

Continued on the next page...

High Voltage 3-Phase Motor Drivers

ELECTRICAL CHARACTERISTICS (continued), valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol		Conditions	Min	Тур	Max	Units
		SMA6861MZ	V _{CC} = 15 V, I _D = 1.0 A, V _{IN} = 5 V	_	1.25	1.5	Ω
		SMA6862MZ	$V_{CC} = 15 \text{ V}, I_D = 0.75 \text{ A}, V_{IN} = 5 \text{ V}$	_	3.2	4.0	Ω
MOSFET On State Resistance	R _{DS(on)}	SMA6863MZ	$V_{CC} = 15 \text{ V}, I_D = 1.25 \text{ A}, V_{IN} = 5 \text{ V}$	-	2.0	2.4	Ω
		SMA6864MZ	V _{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	-2	0.35	0.5	Ω
		SMA6865MZ	V _{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V		1.4	1.7	Ω
		SMA6861MZ	V _{CC} = 15 V, I _D = 1.0 A, V _{IN} = 5 V	1	1.1	1.5	V
		SMA6862MZ	V _{CC} = 15 V, I _D = 0.75 A, V _{IN} = 5 V	_	1.1	1.5	V
MOSFET Diode Forward Voltage	V _{SDF}	SMA6863MZ	V _{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	_	1.1	1.5	V
		SMA6864MZ	V _{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V	_	0.8	1.2	V
		SMA6865MZ	$V_{CC} = 15 \text{ V}, I_D = 1.25 \text{ A}, V_{IN} = 5 \text{ V}$	_	1.0	1.5	V
	ecos		V _{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V V _{CC} = 15 V, I _D = 1.25 A, V _{IN} = 5 V				

High Voltage 3-Phase Motor Drivers

SMA6861MZ SWITCHING CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
	t _{dH(on)}		_	660	_	ns
	t _{rH}		_	25	_	ns
Switching Time, High Side	t _{rrH}	V_{BB} = 150 V, V_{CC} = 15 V, I_{D} = 2.0 A, 0 V \leq V_{IN} \leq 5 V, inductive load	1	50	1	ns
	t _{dH(off)}		-	560	-	ns
	t _{fH}			10	_	ns
	t _{dL(on)}		À	540	_	ns
	t _{rL}			25	-	ns
Switching Time, Low Side	t _{rrL}	$V_{BB} = 150 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 2.0 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	-	45	-	ns
	t _{dL(off)}		_	500	_	ns
	t _{fL}		_	15	_	ns

SMA6862MZ SWITCHING CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
	t _{dH(on)}		1	720	_	ns
	t _{rH}		1	60	-	ns
Switching Time, High Side	t _{rrH}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 1.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	-	110	-	ns
	t _{dH(off)}	Industrio load	-	690	_	ns
	t _{fH}		-	30	_	ns
	t _{dL(on)}		1	670	_	ns
	t _{rL}		1	70	_	ns
Switching Time, Low Side	t _{rrL}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 1.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	1	120	_	ns
	t _{dL(off)}		1	590	-	ns
	t _{fL}		_	30	_	ns

SMA6863MZ SWITCHING CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

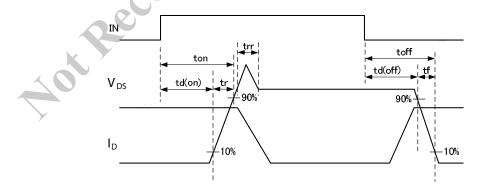
Characteristics	Symbol	Conditions	Min	Тур	Max	Units
	t _{dH(on)}		-	820	-	ns
	t _{rH}		_	100	_	ns
Switching Time, High Side	t _{rrH}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_D = 2.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	-	120	_	ns
<i>></i>	t _{dH(off)}		ı	740	_	ns
	t _{fH}			30	_	ns
	t _{dL(on)}		ı	790	_	ns
	t _{rL}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 2.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	-	110	-	ns
Switching Time, Low Side	t _{rrL}		-	130	-	ns
	t _{dL(off)}		_	700	-	ns
	t _{fL}		_	30	_	ns

SMA6864MZ SWITCHING CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
	t _{dH(on)}		-	730	_	ns
	t _{rH}		_	40	_	ns
Switching Time, High Side	t _{rrH}	$V_{BB} = 150 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 2.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	_	75	_	ns
	t _{dH(off)}	Inductive load		640	_	ns
	t _{fH}			20	_	ns
	t _{dL(on)}		Y	660	_	ns
	t _{rL}		N.	40	-	ns
Switching Time, Low Side	t _{rrL}	$V_{BB} = 150 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 2.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	-	55	-	ns
	t _{dL(off)}		_	600	_	ns
	t _{fL}		_	30	_	ns

SMA6865MZ SWITCHING CHARACTERISTICS, valid at T_A=25°C, unless otherwise noted

Characteristics	Symbol	Conditions	Min	Тур	Max	Units
	t _{dH(on)}		-	750	-	ns
	t _{rH}		-	60	-	ns
Switching Time, High Side	t _{rrH}	V_{BB} = 300 V, V_{CC} = 15 V, I_{D} = 2,5 A, 0 V ≤ V_{IN} ≤ 5 V, inductive load	-	100	-	ns
	t _{dH(off)}	Industrio load	-	680	-	ns
	t _{fH}		_	20	-	ns
	t _{dL(on)}		_	640	-	ns
	t _{rL}		-	65	-	ns
Switching Time, Low Side	t _{rrL}	$V_{BB} = 300 \text{ V}, V_{CC} = 15 \text{ V}, I_{D} = 2.5 \text{ A}, 0 \text{ V} \le V_{IN} \le 5 \text{ V},$ inductive load	-	100	-	ns
	t _{dL(off)}		-	560	-	ns
	t _{fL}		_	20	_	ns



Switching Characteristics Definitions

Truth Table

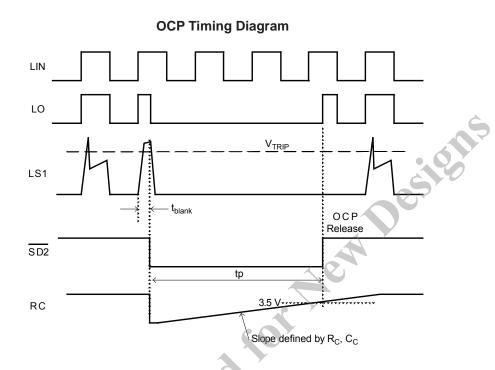
Mode	Hin	Lin	H-side MOSFET	L-side MOSFET
	L	L	Off	Off
Normal	Н	L	On	Off
Normai	L	Н	Off	On
	Н	Н	On	On
	L	L	Off	Off
TSD	Н	L	On	Off
190	L	Н	Off	Off
	Н	Н	On	Off
	L	L	Off	Off
OCP	Н	L	Oh	Off
UCP	L	Н	Off	Off
	Н	Н	On	Off
	L	L C	Off	Off
001 (-1)1	Н	L	Off	Off
OCL (= L) ¹	L	Н	Off	On
	Н	Н	Off	On
	L	L	Off	Off
11/11 0 (1/100)2	Н	L	Off	Off
UVLO (VCC) ²	L	Н	Off	Off
	Н	Н	Off	Off
	L	L	Off	Off
LIV/LO (V/D)3	H	L	Off	Off
UVLO (VB) ³	L	Н	Off	On
	Н	Н	Off	On
	L	L	Off	Off
SD2 (= L)	Н	L	On	Off
SD2 (= L)	L	Н	Off	Off
40	Н	Н	On	Off

 $^{^{1}}$ The OCL feature is enabled when the $\overline{\text{OCL}}$ and $\overline{\text{SD1}}$ pins are tied together externally. If these pins are not tied when an OCL condition occurs, device operation continues in Normal mode.

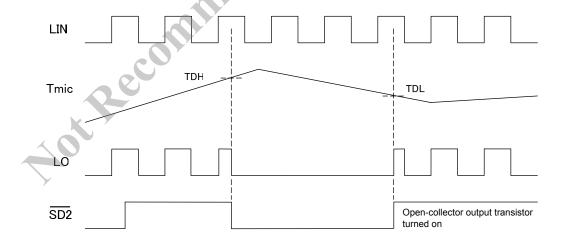
Note: To prevent a shoot-through condition, the external microcontroller should not drive HINx = LINx = H at the same time.

 $^{^2}$ Returning to the Normal mode of operation from a V_{CC} UVLO condition, a high-side MOSFET resumes switching on the rising edge of an HINx input. On the other hand, a low-side MOSFET resumes switching on the first logic high of a LINx input after release of the UVLO condition.

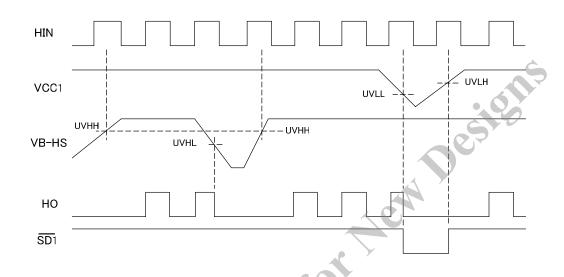
 $^{^3}$ Returning to the Normal mode of operation from a V_B UVLO condition, a high-side MOSFET resumes switching on the rising edge of an HINx input.



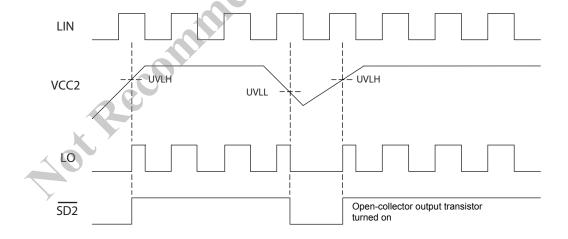
Low-Side Logic TSD Timing Diagram



High-Side UVLO Timing Diagram

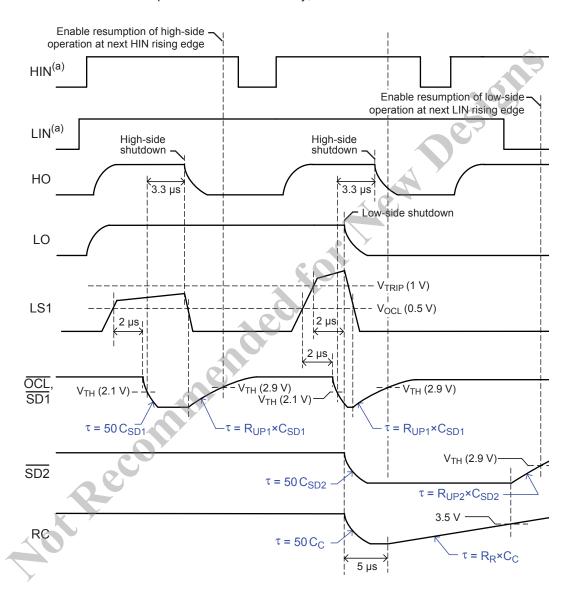


Low-Side UVLO Timing Diagram



OCL Timing Diagram

OCL and SD1 pins connected externally; current-limiter function in use



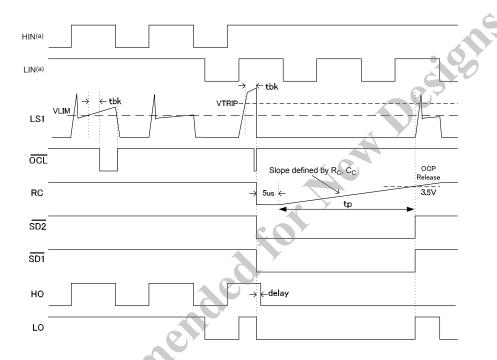
(a) Each HINx or LINx pin drives a independent side of a phase, that is, the high-side and the low-side swtiching devices of a U, V, or W motor coil phase are each driven separately, by the corresponding dedicated HINx or LINx

Aot Rec

High Voltage 3-Phase Motor Drivers

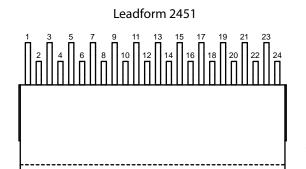
Shut Down Timing Diagram

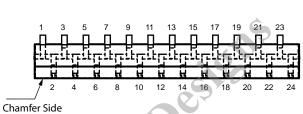
SD1 and SD2 pins connected externally; current-limiter function not in use



(a) Each HINx or LINx pin drives a independent side of a phase, that is, the high-side and the low-side swtiching devices of a U, V, or W motor coil phase are each driven separately, by the corresponding dedicated HINx or LINx input

Pin-out Diagrams





Leadform 2452

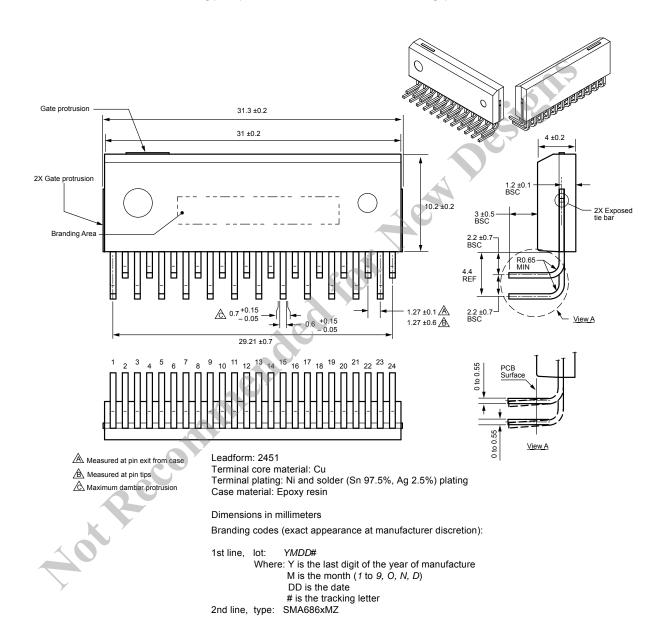
Chamfer on Opposite Side

Terminal List Table

Number	Name	Function
1	VB1	High side bootstrap terminal (U phase)
2	VB2	High side bootstrap terminal (V phase)
3	VB3	High side bootstrap terminal (W phase)
4	VCC1	High side logic supply voltage
5	SD1	High side shutdown input and UVLO fault signal output
6	COM1	High side logic GND terminal
7	HIN3	High side input terminal (W phase)
8	HIN2	High side input terminal (V phase)
9	HIN1	High side input terminal (U phase)
10	VBB	Main supply voltage
11	W1	Output of W phase (connect to W2 externally)
12	V	Output of V phase
13	W2	Output of W phase (connect to W1 externally)
14	LS2	Low side source terminal (connect to LS1 externally)
45	RC	Overcurrent protection hold time adjustment input terminal
16	LS1	Low side source terminal (connect to LS2 externally)
17	OCL	Output for overcurrent limiting
18	LIN3	Low side input terminal (W phase)
19	LIN2	Low side input terminal (V phase)
20	LIN1	Low side input terminal (U phase)
21	COM2	Low side GND terminal
22	SD2	Low side shutdown input and overtemperature, overcurrent, and UVLO fault signals output
23	VCC2	Low side logic supply voltage
24	U	Output of U phase

Package Outline Drawing Leadform 2451

Dual rows, 24 alternating pins; pins bent 90° for horizontal case mounting; pin #1 in outer row



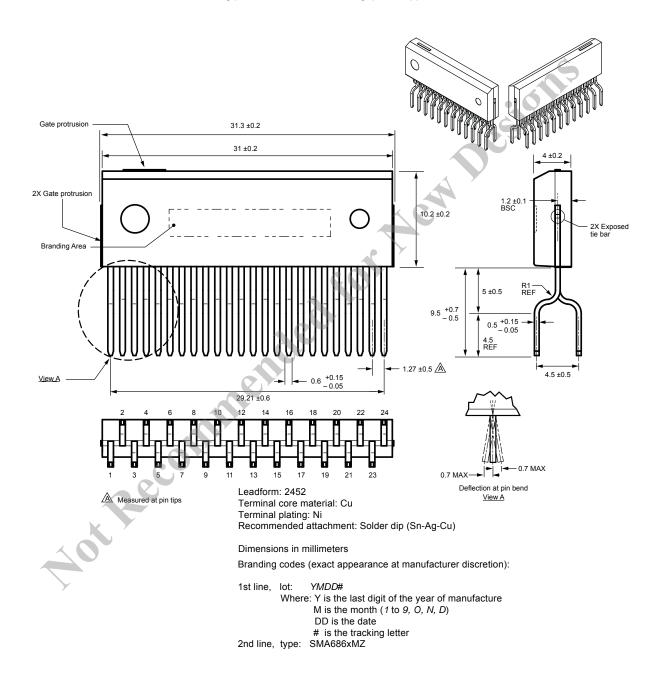


Leadframe plating Pb-free. Device composition complies with the RoHS directive.

Package Outline Drawing

Leadform 2452

Dual rows, 24 alternating pins; vertical case mounting; pin #1 opposite chamfer side





Leadframe plating Pb-free. Device composition complies with the RoHS directive.

High Voltage 3-Phase Motor Drivers

Because reliability can be affected adversely by improper storage environments and handling methods, please observe the following cautions.

Cautions for Storage

- Ensure that storage conditions comply with the standard temperature (5°C to 35°C) and the standard relative humidity (around 40 to 75%); avoid storage locations that experience extreme changes in temperature or humidity.
- Avoid locations where dust or harmful gases are present and avoid direct sunlight.
- Reinspect for rust on leads and solderability of products that have been stored for a long time.

Cautions for Testing and Handling

When tests are carried out during inspection testing and other standard test periods, protect the products from power surges from the testing device, shorts between adjacent products, and shorts to the heatsink.

Remarks About Using Silicone Grease with a Heatsink

- When silicone grease is used in mounting this product on a heatsink, it shall be applied evenly and thinly. If more silicone grease than required is applied, it may produce stress.
- Volatile-type silicone greases may permeate the product and produce cracks after long periods of time, resulting in reduced heat radiation effect, and possibly shortening the lifetime of the product.
- Our recommended silicone greases for heat radiation purposes, which will not cause any adverse effect on the product life, are indicated below:

Type	Suppliers
G746	Shin-Etsu Chemical Co., Ltd.
YG6260	Momentive Performance Materials
SC102	Dow Corning Toray Silicone Co., Ltd.

Soldering

 When soldering the products, please be sure to minimize the working time, within the following limits: 260±5°C 10 s

380±5°C 5 s

 Soldering iron should be at a distance of at least 1.5 mm from the body of the products

Electrostatic Discharge

- When handling the products, operator must be grounded. Grounded wrist straps worn should have at least 1 MΩ of resistance to ground to prevent shock hazard.
- Workbenches where the products are handled should be grounded and be provided with conductive table and floor mats.
- When using measuring equipment such as a curve tracer, the equipment should be grounded.
- When soldering the products, the head of soldering irons or the solder bath must be grounded in other to prevent leak voltages generated by them from being applied to the products.
- The products should always be stored and transported in our shipping containers or conductive containers, or be wrapped in aluminum foil.

High Voltage 3-Phase Motor Drivers

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