



28 mm sq.

1.8°/step

Bipolar winding, Lead wire type
Unipolar winding, Lead wire type ▶ p. 39

Customizing

Hollow Shaft modification
Decelerator Encoder

Varies depending on the model number
and quantity. Contact us for details.

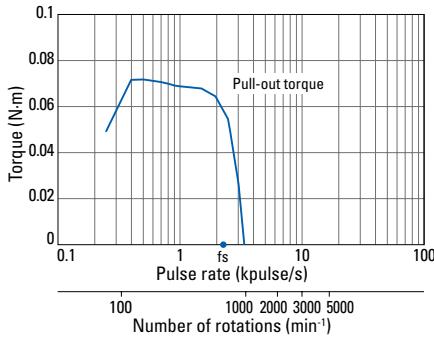
Bipolar winding, Lead wire type

| Model no. | | Holding torque at 2-phase energization | Rated current | Wiring resistance | Winding inductance | Rotor inertia | Mass | Motor length (L) |
|--------------------|--------------------|--|---------------|-------------------|--------------------|-------------------------------------|------|------------------|
| Single shaft | Dual shaft | N·m min. | A/phase | Ω/phase | mH/phase | x10 ⁻⁴ kg·m ² | kg | mm |
| SH2281-5671 | SH2281-5631 | 0.07 | 0.5 | 10.5 | 7.2 | 0.01 | 0.11 | 32 |
| SH2281-5771 | SH2281-5731 | 0.07 | 1 | 2.6 | 1.85 | 0.01 | 0.11 | 32 |
| SH2285-5671 | SH2285-5631 | 0.145 | 0.5 | 15 | 13.5 | 0.022 | 0.2 | 51.5 |
| SH2285-5771 | SH2285-5731 | 0.145 | 1 | 3.75 | 3.4 | 0.022 | 0.2 | 51.5 |

■ Characteristics diagram

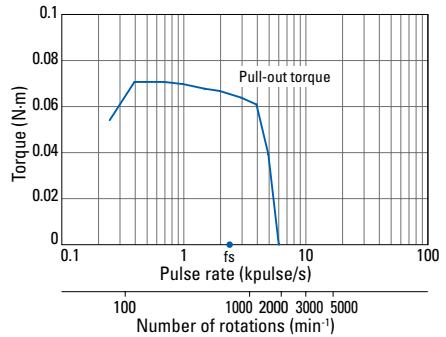
SH2281-5671
SH2281-5631

Constant current circuit
 Source voltage: 24 VDC
 Operating current:
 0.5 A/phase, 2-phase
 energization (full-step)
 Pull-out torque:
 $J=0.01 \times 10^{-4} \text{ kg-m}^2$ (pulley
 balancer method)
 fs: Maximum self-start
 frequency when not
 loaded



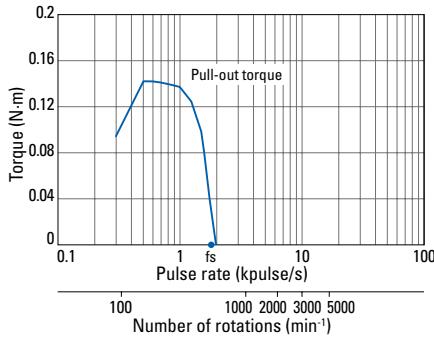
SH2281-5771
SH2281-5731

Constant current circuit
 Source voltage: 24 VDC
 Operating current:
 1 A/phase, 2-phase
 energization (full-step)
 Pull-out torque:
 $J_t = 0.01 \times 10^{-4} kg \cdot m^2$ (pulley
 balancer method)
 f_s : Maximum self-start
 frequency when not
 loaded



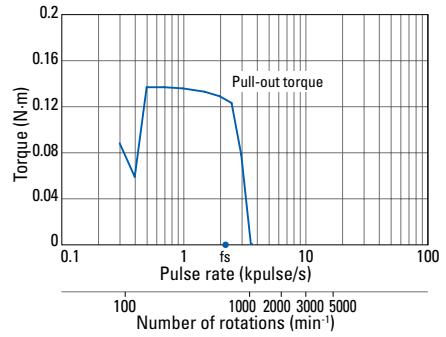
SH2285-5671
SH2285-5631

Constant current circuit
 Source voltage: 24 VDC
 Operating current:
 0.5 A/phase, 2-phase
 energization (full-step)
Pull-out torque:
 $J_0=0.01 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (pulley
 balancer method)
f_s: Maximum self-start
 frequency when not
 loaded

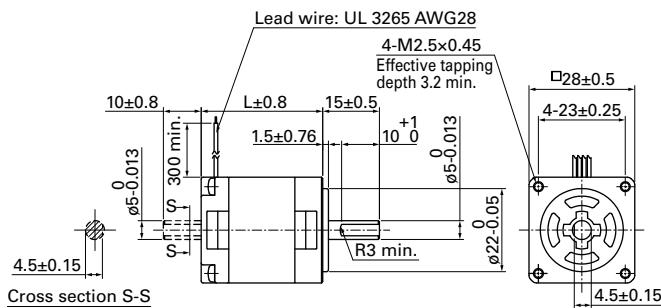


SH2285-5771
SH2285-5731

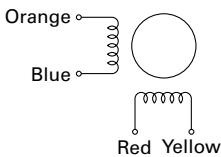
Constant current circuit
 Source voltage: 24 VDC
 Operating current:
 1 A/phase, 2-phase
 energization (full-step)
 Pull-out torque:
 $J_1 = 0.01 \times 10^{-4} \text{ kg-m}^2$ (pulley
 balancer method)
 f_s : Maximum self-start
 frequency when not
 loaded



■ Dimensions (Unit: mm)



Internal wiring



■ Compatible drivers

- For motor model no. SH228 □ -56 □ 1 (0.5 A/phase)
Driver is not included.
If you require assistance finding a driver, contact us for details.
 - For model no. SH228 □ -57 □ 1 (1 A/phase)
Model no.: BS1D200P10 (DC input)
Operating current select switch setting: A
The characteristics diagram shown above is from our experimental circuit.