UNISONIC TECHNOLOGIES CO., LTD

RCR5 **Preliminary** *CMOS IC*

REMOTE CONTROLLER WITH NINE FUNCTIONS

DIP-22

■ DESCRIPTION

The UTC **RCR5** is a CMOS LSI and designed as receiver that complement to UTC **RCT5** for remote controlled car applications. It provide nine control keys controlling the motions, which are forward, backward, rightward, leftward, four function keys, and the turbo function, of the remote controlled car.

UTC **RCR5** have Forward (Backward) combined with the turbo application. During normal operation without Turbo, Forward (Backward) output from UTC **RCR5** sends a 60Hz signal. When Forward (Backward) and Turbo are both in effect, the output signal becomes completely high.
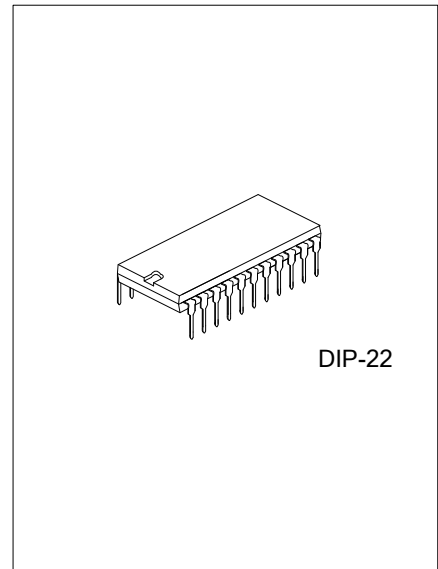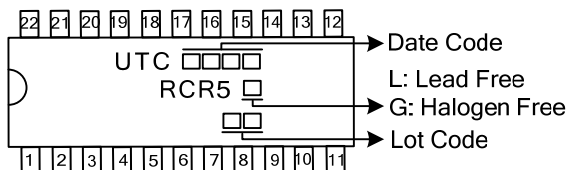
■ FEATURES

* Operating voltage range: 2.4V~4.0V
* Built-in 4.2V zener
* Few external components needed
* 9-function remote controller controlling Forward/ Backward/ Turbo/ Right-turn/ Left turn/ four function keys
* Complement to UTC **RCT5**.
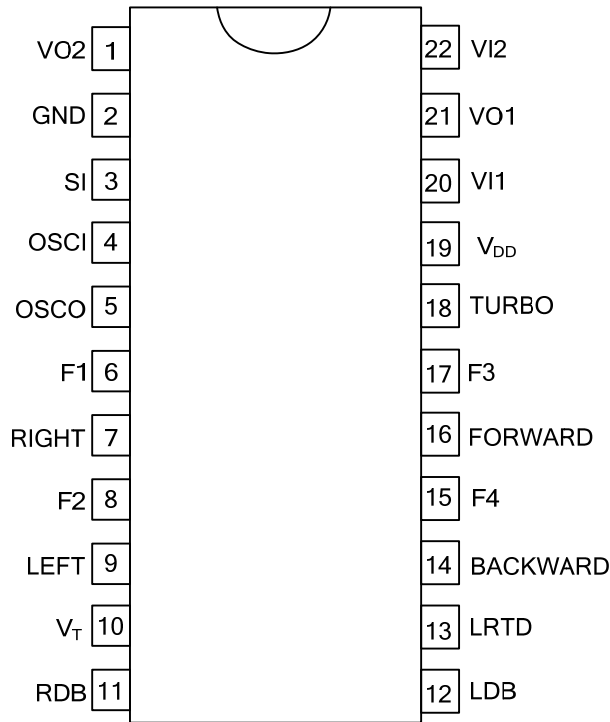
■ ORDERING INFORMATION

Ordering Number		Package	Packing
Lead Free	Halogen Free		
RCR5L-D22-T	RCR5G-D22-T	DIP-22	Tube

RCR5L-D22-T

(1) Packing Type
(2) Package Type
(3) Lead Free

(1) T: Tube

(2) D22: DIP-22

(5) L: Lead Free, G: Halogen Free

■ MARKING

UTC ☐☐☐☐
RCR5 ☐

22 21 20 19 18 17 16 15 14 13 12
1 2 3 4 5 6 7 8 9 10 11

→ Date Code
L: Lead Free
→ G: Halogen Free
→ Lot Code

RCR5 Preliminary CMOS IC

■ **PIN CONFIGURATIONS**


```
VO2  | 1        22 | VI2
GND  | 2        21 | VO1
SI   | 3        20 | VI1
OSCI | 4        19 | VDD
OSCO | 5        18 | TURBO
F1   | 6        17 | F3
RIGHT| 7        16 | FORWARD
F2   | 8        15 | F4
LEFT | 9        14 | BACKWARD
VT   | 10       13 | LRTD
RDB  | 11       12 | LDB
```

■ **PIN DESCRIPTION**

PIN NO.	PIN NAME	DESCRIPTION
1	VO2	Inverter 2 output pin for signal amplify
2	GND	Ground
3	SI	Input pin of the encoding signal
4	OSCI	Oscillator input pin
5	OSCO	Oscillator output pin
6	F1	F1 function output pin
7	RIGHT	Rightward output pin
8	F2	F2 function output pin
9	LEFT	Leftward output pin
10	V_T	Auto Shut-OFF input pin. If V_T voltage exceeds 1.4V, all outputs shut off automatically.
11	RDB	Right disable pin.
12	LDB	Left disable pin.
13	LRTD	Left/right turbo disable pin
14	BACKWARD	Backward output pin
15	F4	F4 function output pin
16	FORWARD	Forward output pin
17	F3	F3 function output pin
18	TURBO	TURBO output pin
19	V_{DD}	Power supply
20	VI1	Inverter 1 input pin for signal amplify
21	VO1	Inverter 1 output pin for signal amplify
22	VI2	Inverter 2 input pin for signal amplify

■ **BLOCK DIAGRAM**
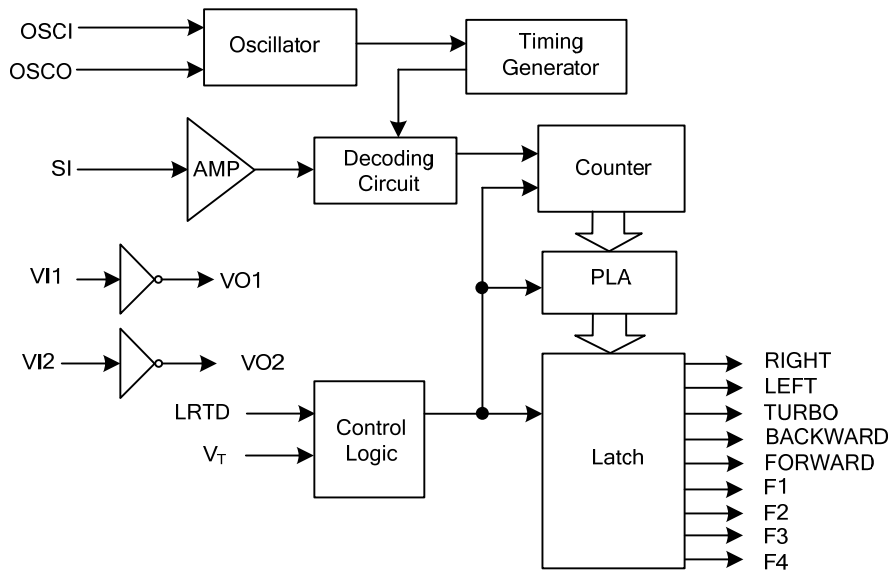
Input Condition	O/P Condition		
	Forward	Backward	Turbo
Forward	⊔⊔⊔⊔=60Hz	Low	Low
Backward	Low	⊓⊓⊓⊓=60Hz	Low
Forward + turbo	⌐=high	Low	⌐=high
Backward + turbo	Low	⌐=high	⌐=high

An Auto Shut-Off mechanism is built-in according to Toy Safety Requirement and effective during over-current situation in motor driver. The active high input applying to this Auto Shut-Off pin will turn off the motor. (V_T pin, when unused, has to be connected to ground. The transfer point =1.4V)

■ **ABSOLUTE MAXIMUM RATINGS**

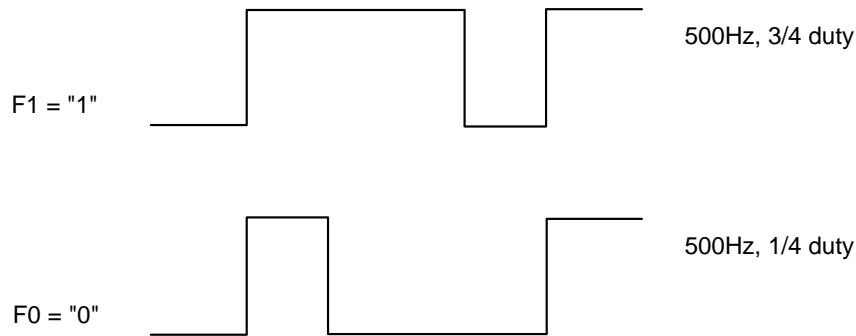| PARAMETER	SYMBOL	RATINGS	UNIT
DC Supply Voltage	V_{DD}	2.4~4.0	V
Input/Output Voltage		GND-0.2~ V_{DD}+0.2	V
Operating Temperature	T_{OPR}	-10~+60	°C
Storage Temperature	T_{STG}	-25~+125	°C

Note: Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

■ **ELECTRICAL CHARACTERISTICS** (T_A=25℃, V_{DD}=3.0V, Fosc=128KHz, unless otherwise specified.)

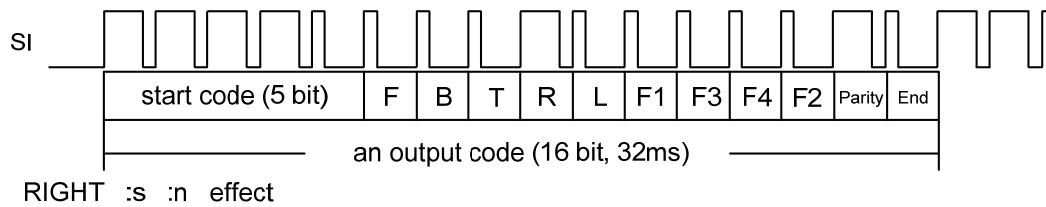Direct Driving: No connect a resistance between POWER and IC's V_{DD} pin.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Operating Voltage	V_{OPR}		2.4	3.0	4.0	V
Operating Current	I_{OPR}	Unload	0.2	0.4	1.0	mA
O/P Driving Current	I_{DRIVE}	V_{OH}=0.7V	5.0			mA
O/P Driving Current (F1, F2)	I_{DRIVE}	V_{OH}=0.7V	5.0			mA
Effect Decoding (Frequency Variation)	$F_{TOLERANCE}$		-50		50	%
Oscillator Frequency	F_{OSC}			128		KHz
Oscillator Frequency Tolerance	Ftolerance	UTC RCT5 FOSC=128KHz	-20		+20	%

■ DATA FORMAT

F1 = "1"   500Hz, 3/4 duty

F0 = "0"   500Hz, 1/4 duty

■ CODING METHOD

The data string that UTC **RCR5** receiver is below:

SI

| start code (5 bit) | F | B | T | R | L | F1 | F3 | F4 | F2 | Parity | End |

an output code (16 bit, 32ms)

RIGHT :s :n effect

Data string: start code + data code + parity code + end code

- start code = F1 F1 F1 F1 F0

- data code =

| F | B | T | R | L | F1 | F3 | F4 | F2 |

F = Forward   B = Backward   T = Turbo
R = Right   L = Left   F1 = Function 1
F2 = Function 2   F3 = Function 3   F4 = Function 3

F、B、T、R、L、F1、F3、F4、F2 all can have two date format, "F1" or "F0",
"F1" means the function is in effect, and "F0" means not.

- parity code = for parity check
- end code = for (latch data)

* Data code can be any combination of F, B, T, R, L, F1, F2, F3, F4 except for F & B, and R & L

■ **OUTPUT TABLES**

FUNCTION	OUTPUT STATUS								
	F	B	T	R	L	F1	F2	F3	F4
FORWARD	H								
LEFT + FORWARD	H				H				
RIGHT + FORWARD	H			H					
TURBO			H						
TURBO + FORWARD	H		H						
TURBO + LEFT + FORWARD	H		H		H				
TURBO + RIGHT + FORWARD	H		H	H					
BACKWARD		H							
BACKWARD + RIGHT		H		H					
BACKWARD + LEFT		H			H				
TURBO + BACKWARD		H	H						
TURBO + BACKWARD + RIGHT		H	H	H					
TRUBO + BACKWARD + LEFT		H	H		H				
LEFT					H				
RIGHT				H					
FUNCTION1						H			
FORWARD + FUNCTION1	H					H			
FORWARD + TURBO + FUNCTION1	H		H			H			
TURBO + FUNCTION1			H			H			
BACKWARD + FUNCTION1		H				H			
BACKWARD + TURBO + FUNCTION1		H	H			H			
LEFT + FORWARD + FUNCTION1	H				H	H			
RIGHT + FORWARD + FUNCTION1	H			H		H			
LEFT + BACKWARD + FUNCTION1		H			H	H			
RIGHT + BACKWARD + FUNCTION1		H		H		H			
LEFT + FUNCTION1					H	H			
RIGHT + FUNCTION1				H		H			
FUNCTION2							H		
FORWARD + FUNCTION2	H						H		
FORWARD + TURBO + FUNCTION2	H		H				H		
TURBO+ FUNCTION2			H				H		
BACKWARD + FUNCTION2		H					H		
BACKWARD + TURBO + FUNCTION2		H	H				H		
LEFT + FORWARD + FUNCTION2	H				H		H		
RIGHT + FORWARD + FUNCTION2	H			H			H		
LEFT + BACKWARD + FUNCTION2		H			H		H		
RIGHT + BACKWARD + FUNCTION2		H		H			H		
LEFT + FUNCTION2					H		H		
RIGHT + FUNCTION2				H			H		
FUNCTION3								H	
FORWARD + FUNCTION3	H							H	
FORWARD + TURBO + FUNCTION3	H		H					H	
TURBO+ FUNCTION3			H					H	
BACKWARD + FUNCTION3		H						H	
BACKWARD + TURBO + FUNCTION3		H	H					H	
LEFT + FORWARD + FUNCTION3	H				H			H	
RIGHT + FORWARD + FUNCTION3	H			H				H	
LEFT + BACKWARD + FUNCTION3		H			H			H	
RIGHT + BACKWARD + FUNCTION3		H		H				H	

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■ OUTPUT TABLES(Cont.)

FUNCTION	OUTPUT STATUS								
	F	B	T	R	L	F1	F2	F3	F4
LEFT + FUNCTION3					H			H	
RIGHT + FUNCTION3				H				H	
FUNCTION4									H
FORWARD + FUNCTION4	H								H
FORWARD + TURBO + FUNCTION4	H		H						H
TURBO+ FUNCTION4			H						H
BACKWARD + FUNCTION4		H							H
BACKWARD + TURBO + FUNCTION4		H	H						H
LEFT + FORWARD + FUNCTION4	H				H				H
RIGHT + FORWARD + FUNCTION4	H			H					H
LEFT + BACKWARD + FUNCTION4		H			H				H
RIGHT + BACKWARD + FUNCTION4		H		H					H
LEFT +FUNCTION4					H				H
RIGHT + FUNCTION4				H					H

H = high level, Z = 60Hz flash, Blank=L
Thus, from the table, we can see that there are more than 50 states of function combinations from 7 control keys.

Notes: 1. LRTD pin functions as an option pin for LEFT/RIGHT turbo disable.

"LRTD"	Key selected	Output Function
HIGH (OPEN)	FORWARD + LEFT (RIGHT) + TURBO	FORWARD + LEFT (RIGHT) + TURBO
LOW	FORWARD + LETT (RIGHT) + TURBO	FORWARD + LEFT (RIGHT)

2. The UTC **RCR5** have built in a zener diode, so you must add a resistance between POWER and IC's V_{DD} pin, like the R6 of UTC **RCR5** application circuit.
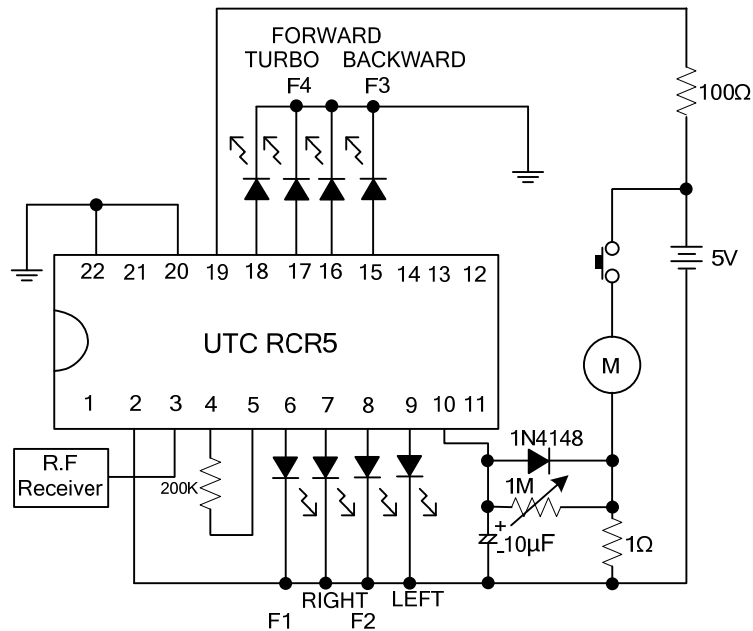
■ TYPICAL APPLICATION CIRCUIT (FOR REFERENCE ONLY)
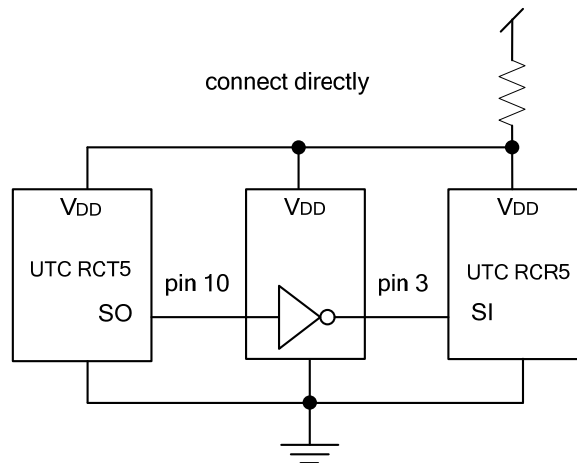
Receiver (UTC **RCR5** Fosc ≌ 128KHz)
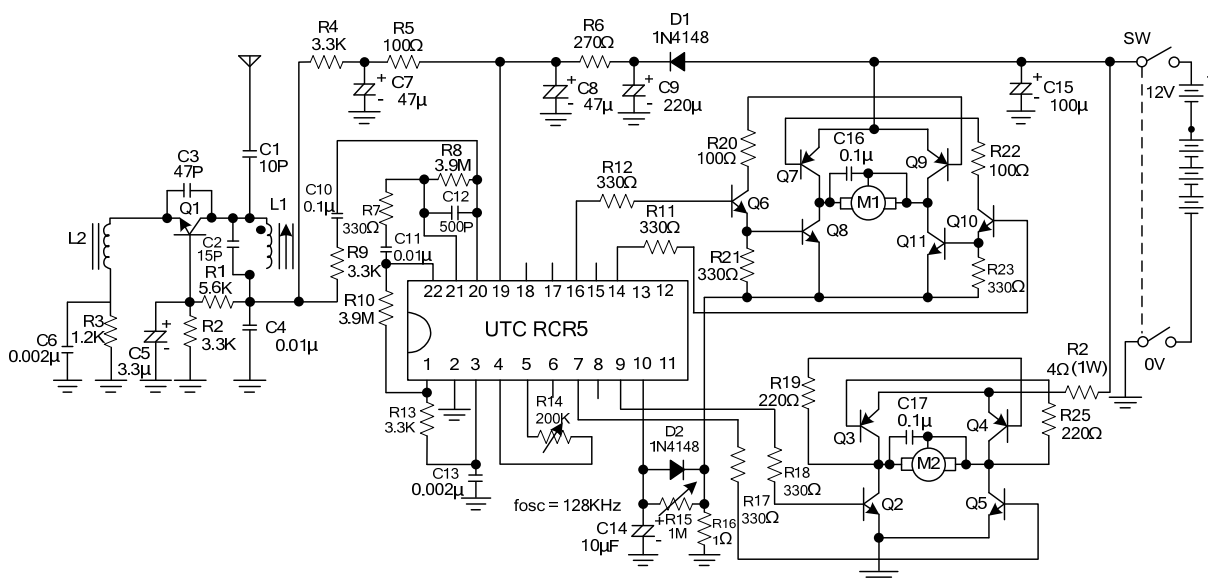
■ **TEST CIRCUIT**

Fosc for UTC **RCR5** ≌ 128KHz

UTC **RCT5** output pin (SO) has an inverted phase with UTC **RCR5** input (SI). If UTC **RCT5** is connected without using a R$_F$ module, an inverter has to be inserted between this 2 pins.