

R2J25953

H-Bridge Control High Speed Power Switching with Built-in Driver IC and Power MOS FET

R07DS0044EJ0300

Rev.3.00

Sep 01, 2010

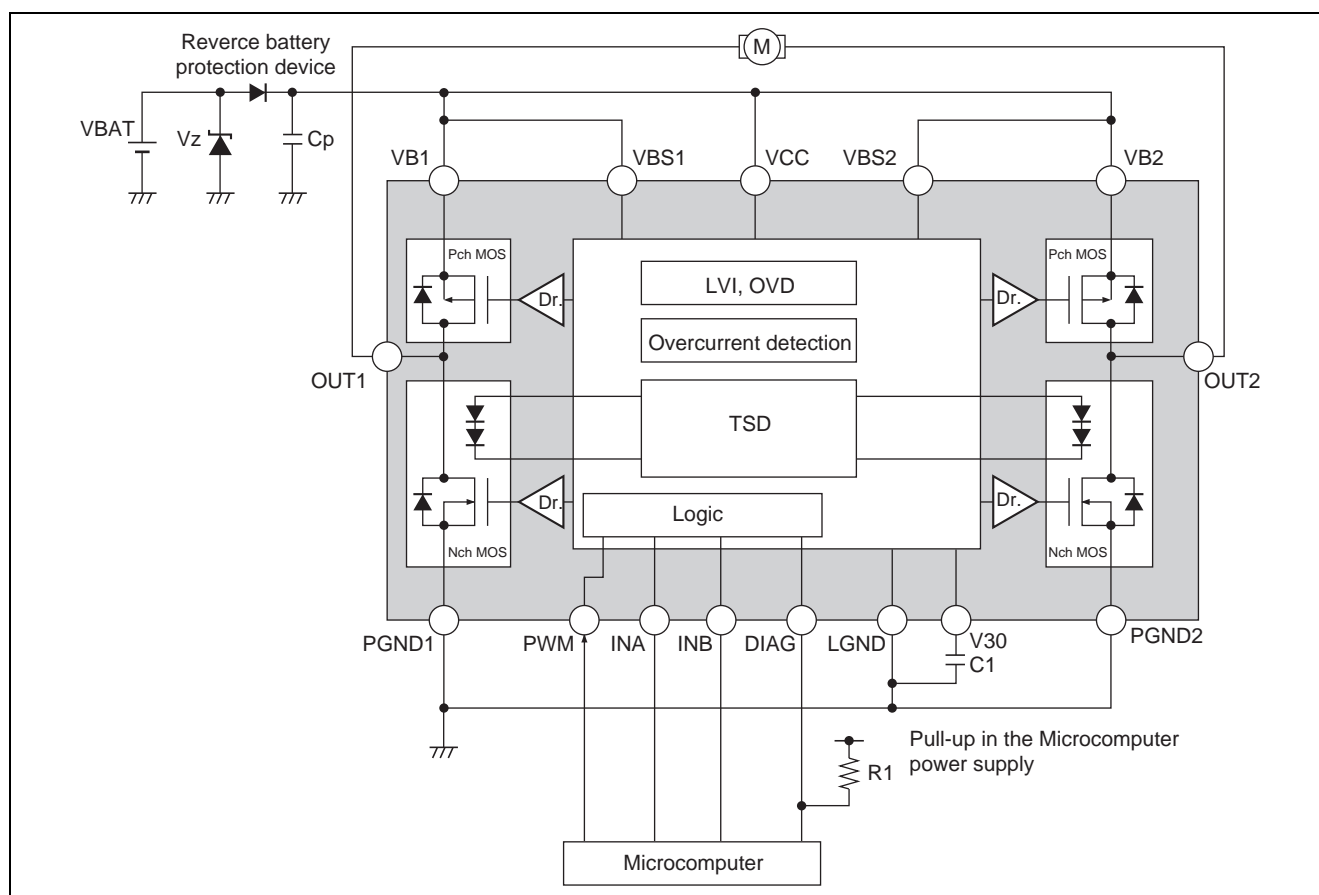
Description

The R2J25953 multi-chip module incorporates high-side Pch MOS FET, low-side Nch MOS FET, and Bi-CMOS driver in a single HSOP-36 package.

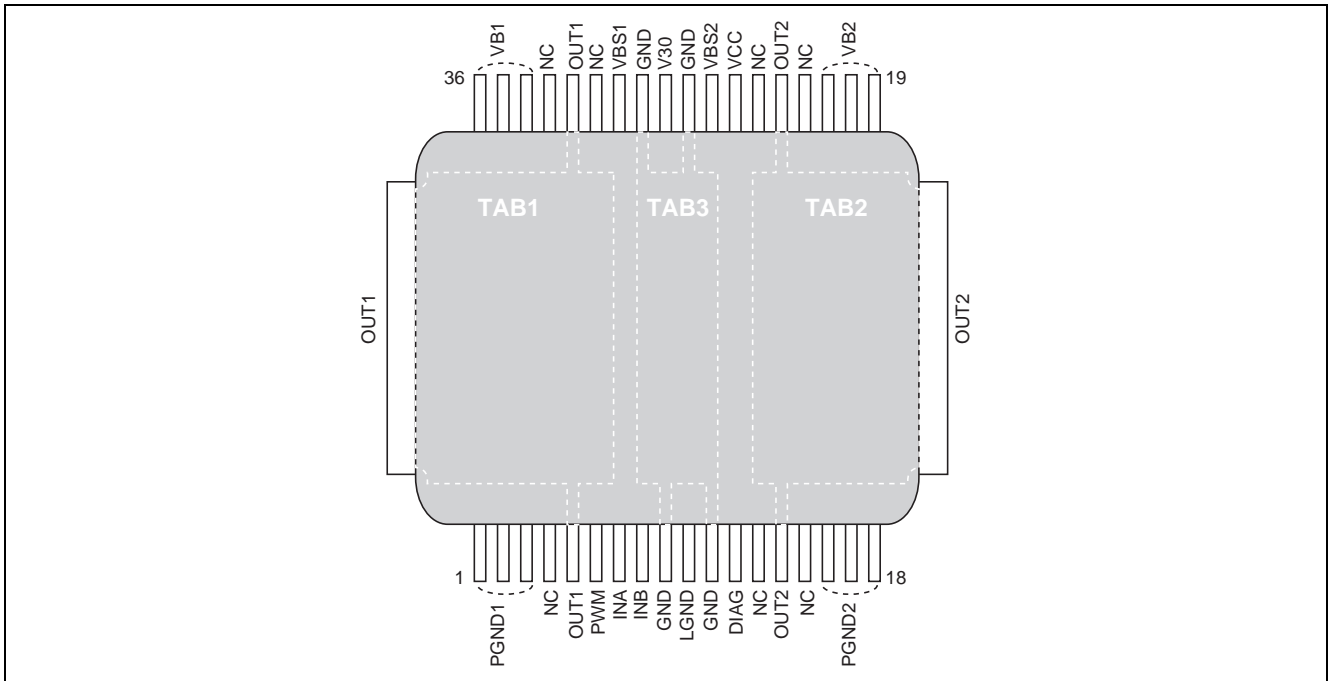
Features

- For Automotive application
- Built-in low on state resistance MOS FET.
(Pch: 16 mΩ Max., Nch: 11 mΩ Max.)
- Pch MOS FET is adopted on the high-side, and the charge pump noise was lost.
- Built-in protection circuit of Thermal shut-down (TSD), Low Voltage Inhibit (LVI), Overvoltage Detection (OVD) and Overcurrent Detection.
- Built-in diagnostic function.
- Built-in cross-conduction protection.
- Small Surface mounting package: HSOP-36

Block Diagram



Outline



Pin Description

Pin No.	Pin name	Description	Pin No.	Pin name	Description
1 to 3	PGND1	Power GND1	22	NC	No connect
4	NC	No connect	23	OUT2	Internally corrected to TAB2
5	OUT1	Internally corrected to TAB1	24	NC	No connect
6	PWM	PWM input	25	VCC	IC power supply
7	INA	A input	26	VBS2	VB2 sense
8	INB	B input	27	GND	Internally corrected to TAB3
9	GND	Internally corrected to TAB3	28	V30	IC bias voltage (3.3 V)
10	LGND	IC GND	29	GND	Internally corrected to TAB3
11	GND	Internally corrected to TAB3	30	VBS1	VB1 sense
12	DIAG	Diagnostic output (open drain)	31	NC	No connect
13	NC	No connect	32	OUT1	Internally corrected to TAB1
14	OUT2	Internally corrected to TAB2	33	NC	No connect
15	NC	No connect	34 to 36	VB1	MOS FET power supply 1
16 to 18	PGND2	Power GND2	TAB1	OUT1	MOS FET output 1
19 to 21	VB2	MOS FET power supply 2	TAB2	OUT2	MOS FET output 2
			TAB3	GND	IC tab GND

Absolute Maximum Ratings

(Ta = 25°C)

Item	Symbol	Ratings	Unit	Note
Supply voltage	VB	18	V	1
Input voltage	Vin	−0.3 to VB	V	2
Diag voltage	Vdiag	−0.3 to VB	V	3
Output current	Iout	50	A	
Diag current	Idiag	5	mA	3
Junction temperature	Tj	−40 to +150	°C	
Storage temperature	Tstg	−55 to +150	°C	
Power temperature	Pt	40	W	4

- Notes: 1. 28 V at 25°C, 1 min.
40 V at 25°C, 1 sec.
2. Applies to INA, INB, and PWM. Clamps it with 19 V typ.
3. Applies to DIAG
4. One element operation: Tc = 25°C

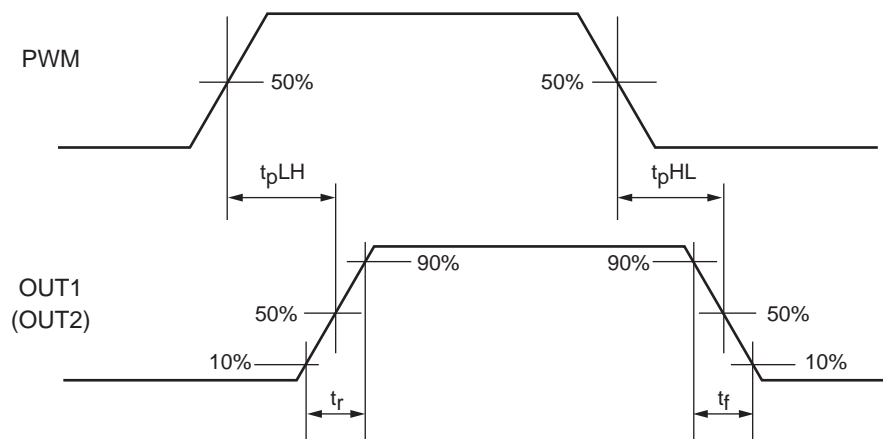
Electrical Characteristics

(Ta = 25°C, VB = VCC = 12 V)

Item		Symbol	Min	Typ	Max	Unit	Condition	Application terminal	Note
Supply current		Icc0	—	30	50	μA	Standby	VCC	1
		Icc	—	3.5	10	mA	ACTIVE		1
VB	Input current	IinVB	—	—	±1	μA	Standby	VB1/VB2	1
MOS	Static High-side resistance	RonH	—	9	16	mΩ	Iout = 15 A Pulse test		
	Static Low-side resistance	RonL	—	7	11	mΩ	Iout = 15 A Pulse test		
	Off state current	Ioff	—	10	20	μA			
IN	Input current	IinL	—	—	±10	μA	Vin = 0 V	INA/INB /PWM	
		IinH	—	—	±10	μA	Vin = VB		
	High threshold	Vthin	3.0	—	—	V			
	Low threshold	Vtlin	—	—	1.5	V			
Delay time		tpLH	—	1.5	4.0	μs	OUT/IN (PWM)	OUT, PWM	2
		tpHL	—	3.0	6.0	μs			
Rise time		tr	—	1.0	3.0	μs	OUT	OUT1/2	
Fall time		tf	—	1.0	3.0	μs			
DIAG	Output voltage	VDiag	—	0.4	0.6	V	I = 2 mA, DIAG = Low Vdiag = 0 V	DIAG	
	Leak current	IDiag	—	—	±10	μA			
TSD	Shut-down temperature	Tsd	150	175	—	°C			3
	Hysteresis	Thys	7	25	—	°C			
OVD	Shut-down voltage	VtvH	28.9	34	39.1	V		VCC	
	Return voltage	VtvL	21.3	25	28.7	V			
LVI	Return voltage	VRLVI	5.0	5.35	5.6	V		VCC	
	Hysteresis	VHLVI	0.3	0.5	0.7	V			
Overcurrent detection	Shut-down current	IcL	35	—	—	A		OUT1/2	
	Detection time	tcL	60	10	20	μs			
MOS FET Body-diode	Pch forward voltage	VDFp	—	1.0	1.3	V	IF = 50 A, Pulse test		
	Nch forward voltage	VDFn	—	1.0	1.3	V			

Notes: 1. Refer to truth table.

2. Refer to the input condition to the truth table.



3. It is a design guaranteed value, and it doesn't apply to the final test.

Truth table

The operation of OUT1, OUT2, and DIAG is shown in the following.

Input			Status				Output			State
PWM	INA	INB	LVI	TSD	Overcurrent detection	OVD	OUT1	OUT2	DIAG	
High	High	High	off				High	High	High	ACTIVE
		Low	off				High	Low	High	
	Low	High	off				Low	High	High	
		Low	off				Low	Low	High	
Low	High	High	off				Hi-z	Hi-z	High	
		Low	off				Hi-z	Low	High	
	Low	High	off				Low	Hi-z	High	
		Low	Protection circuit doesn't operate				Low	Low	High	STANDBY
Excluding All = Low At least one of PWM, INA, and INB is high.			on	x	x	x	Hi-z	Hi-z	High	LVI
			off	on	x	x	Hi-z	Hi-z	Low	TSD
			off	x	on	x	Hi-z (Latch)	Hi-z (Latch)	Low (Latch)	Overcurrent detection
			off	x	x	on	Hi-z	Hi-z	Low	OVD

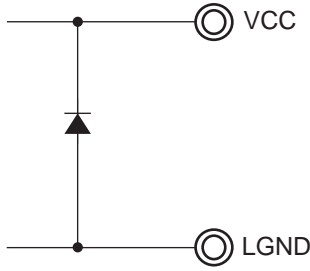
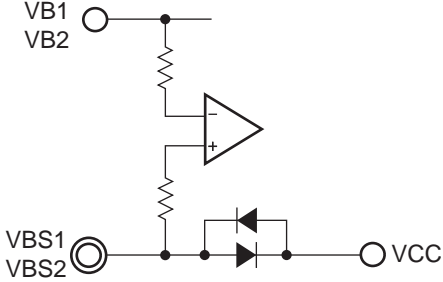
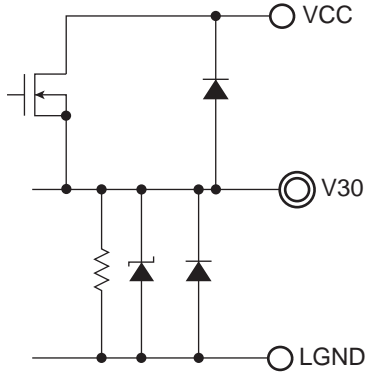
- Notes
1. x: Regardless of High, Low, on and off.
 2. Protect circuit
off = undetection
on = detection
 3. State of pin OUT
Low: Nch MOS FET ON, High: Pch MOS FET ON, Hi-z: Nch and Pch MOS FET OFF
 4. The latch of overcurrent detection is released when LVI = on or INA = INB = Low.

External Parts List

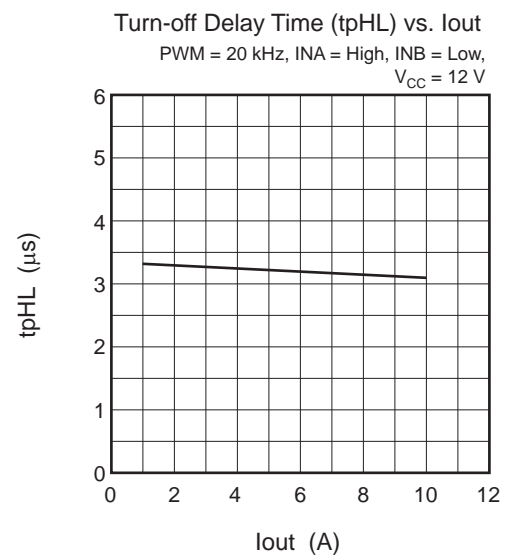
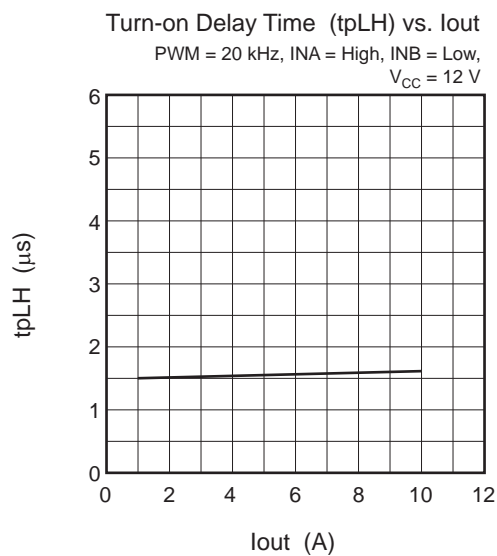
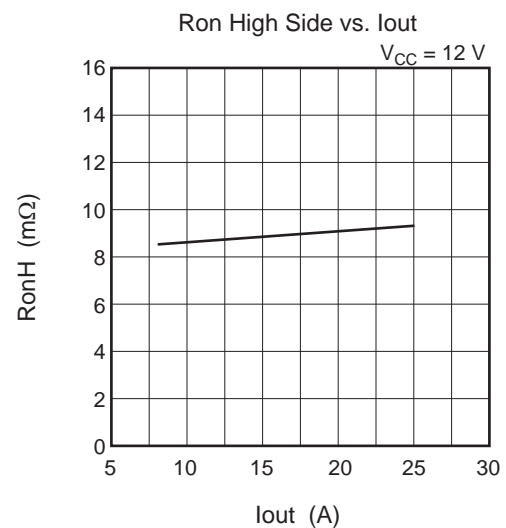
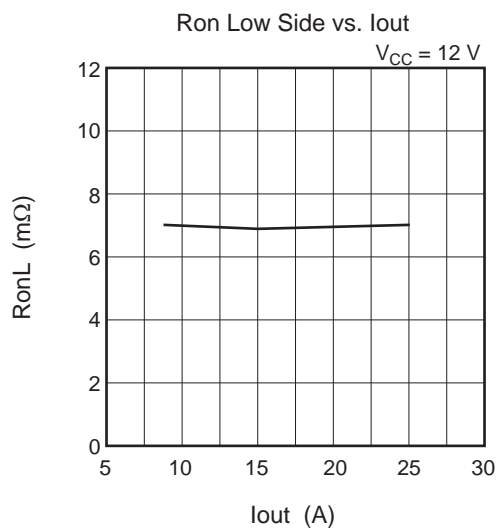
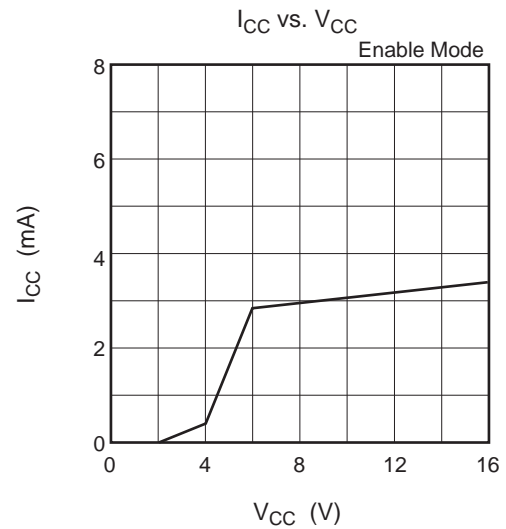
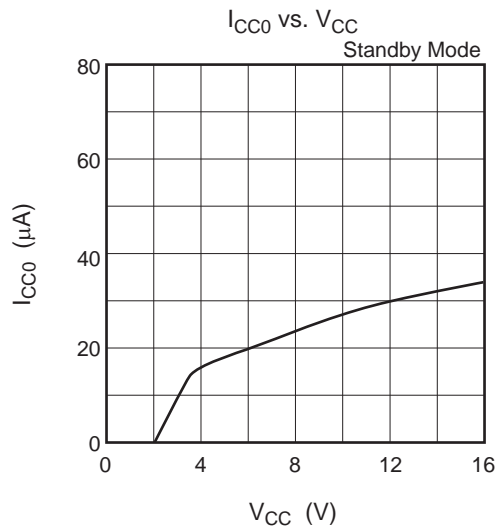
Parts No.	Recommended value	Purpose
Cp	10 μ F	Power supply bypass capacitor
R1	> 10 k Ω	Pull up Pin DIAG
C1	0.033 μ F	Pin V30 bypass capacitor

Equivalent Circuit

Pin name	Pin No.	Equivalent circuit
PGND1 PGND2	1, 2, 3, 16, 17, 18	
OUT1 OUT2	5, 32, TAB1 14, 23, TAB2	
PWM INA INB	6 7 8	
DIAG	12	
VB1 VB2	34, 35, 36 19, 20, 21	

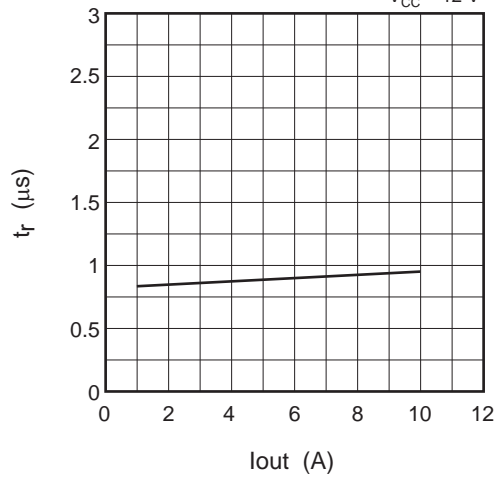
Pin name	Pin No.	Equivalent circuit
VCC LGND	25 10	
VBS1 VBS2	30 26	
V30	28	

Main Characteristics

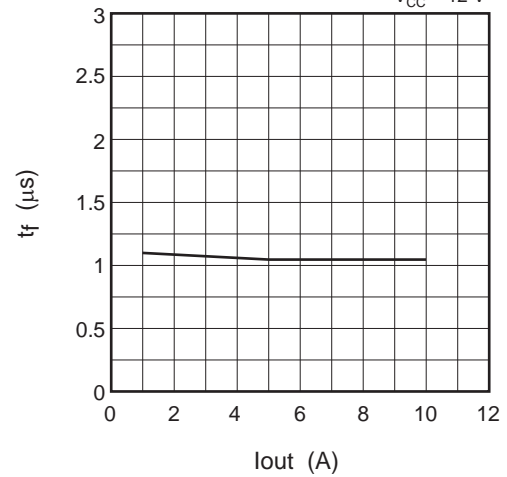


Rise Time vs. I_{out}

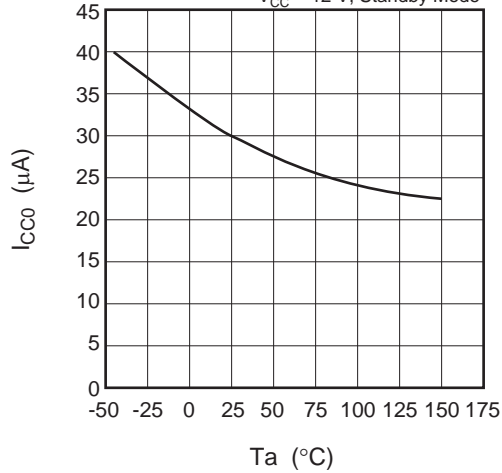
PWM = 20 kHz, INA = High, INB = Low,
 $V_{CC} = 12\text{ V}$

Fall Time vs. I_{out}

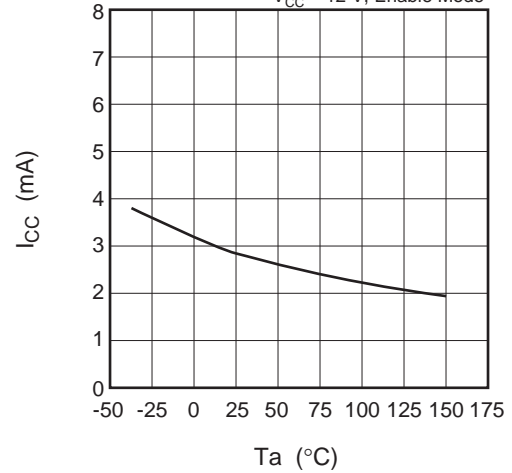
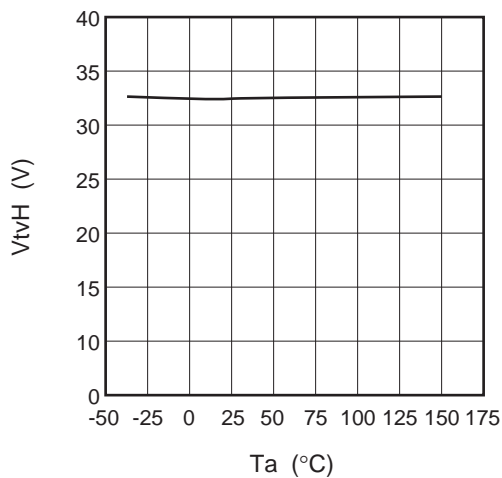
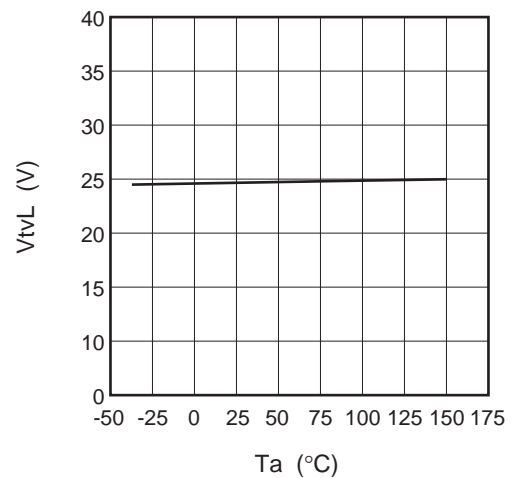
PWM = 20 kHz, INA = High, INB = Low,
 $V_{CC} = 12\text{ V}$

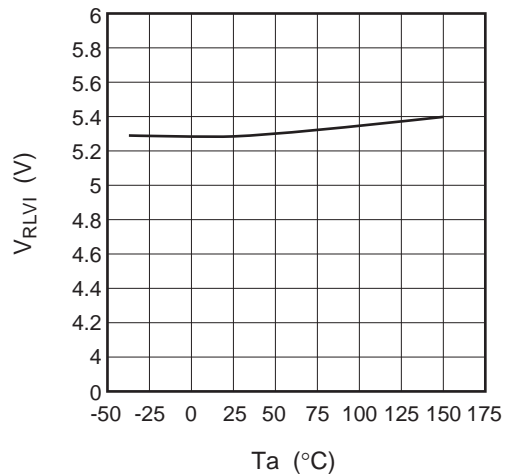
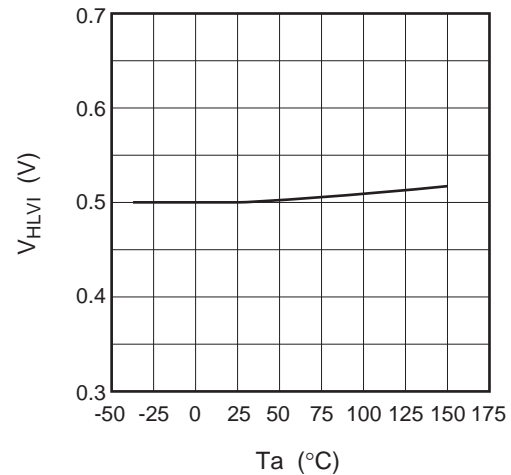
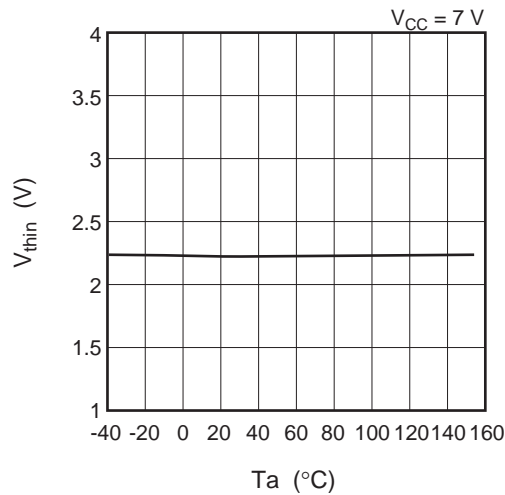
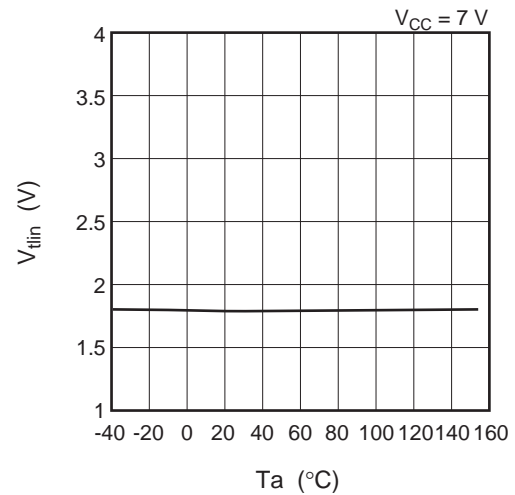
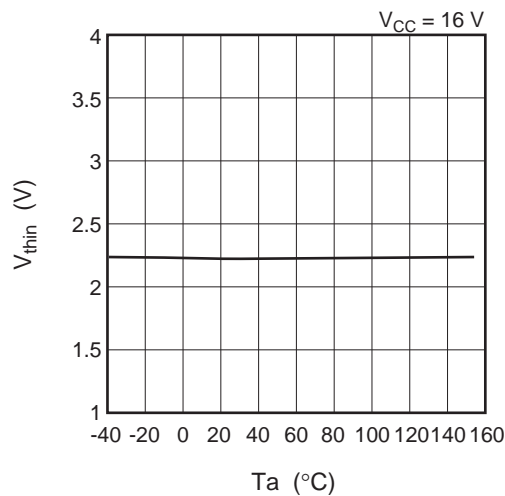
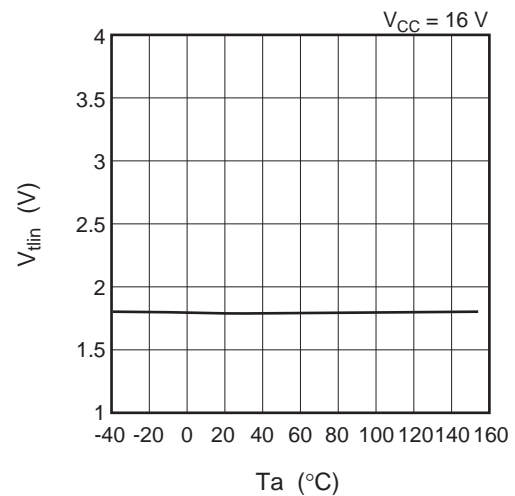
 I_{CC0} vs. T_a

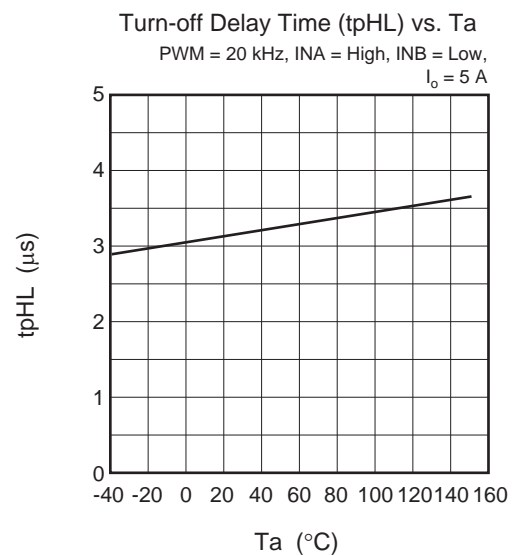
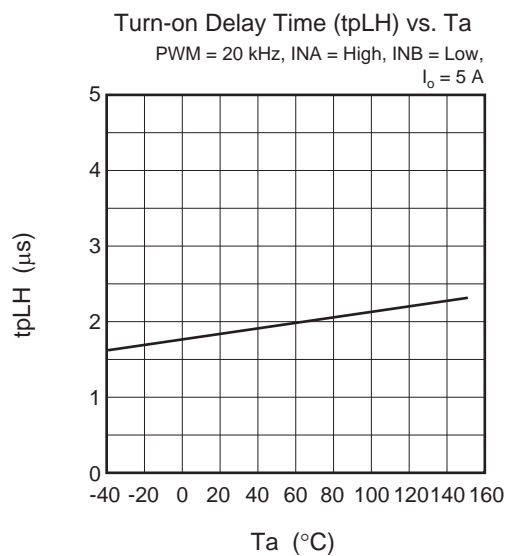
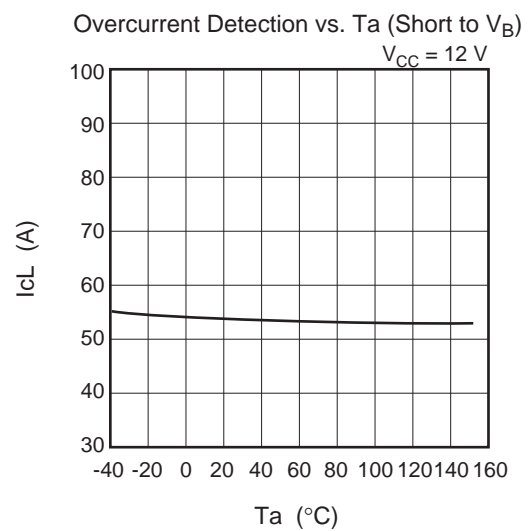
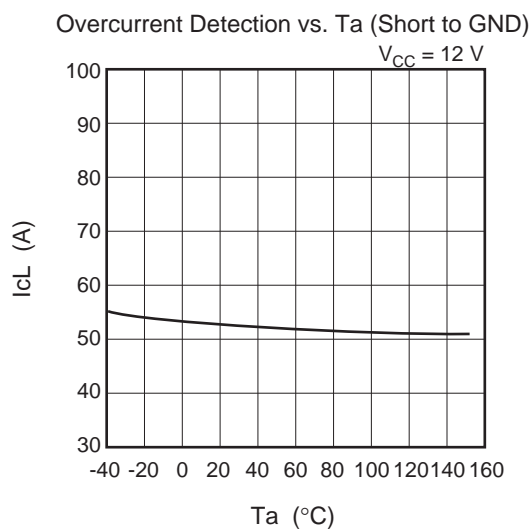
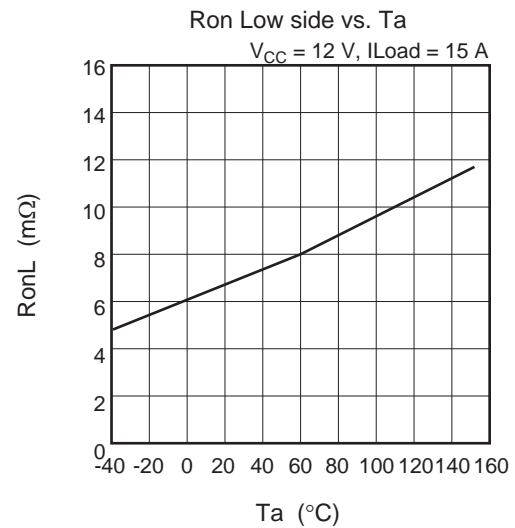
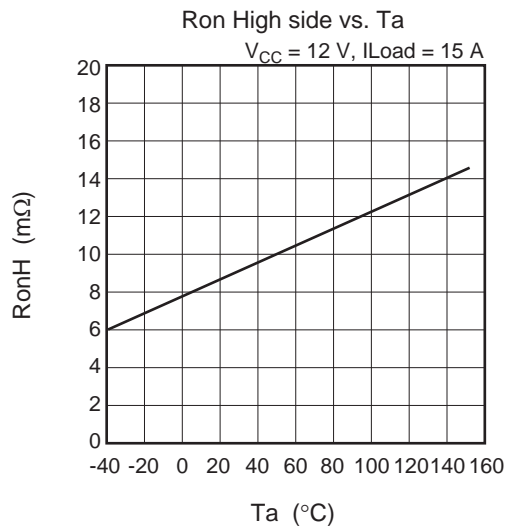
$V_{CC} = 12\text{ V}$, Standby Mode

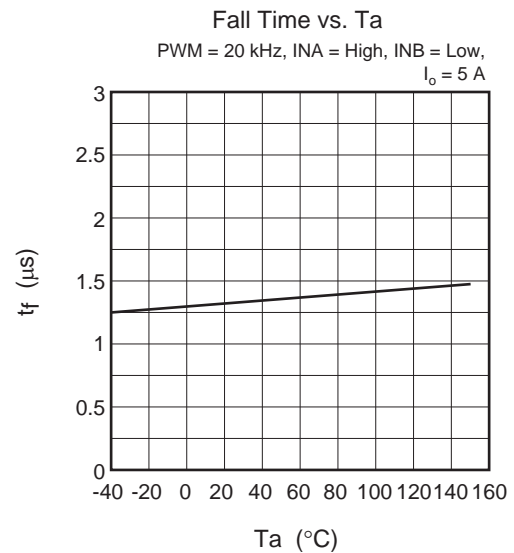
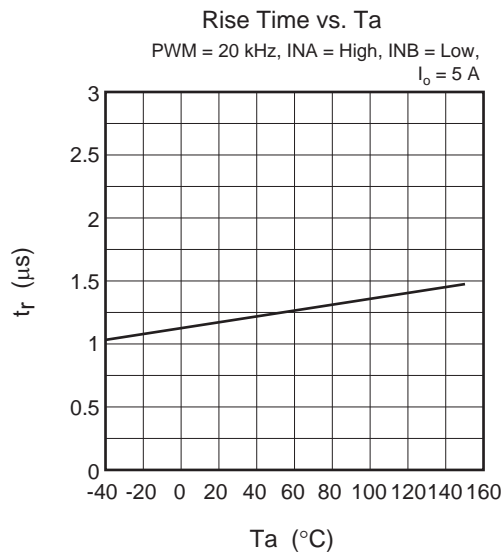
 I_{CC} vs. T_a

$V_{CC} = 12\text{ V}$, Enable Mode

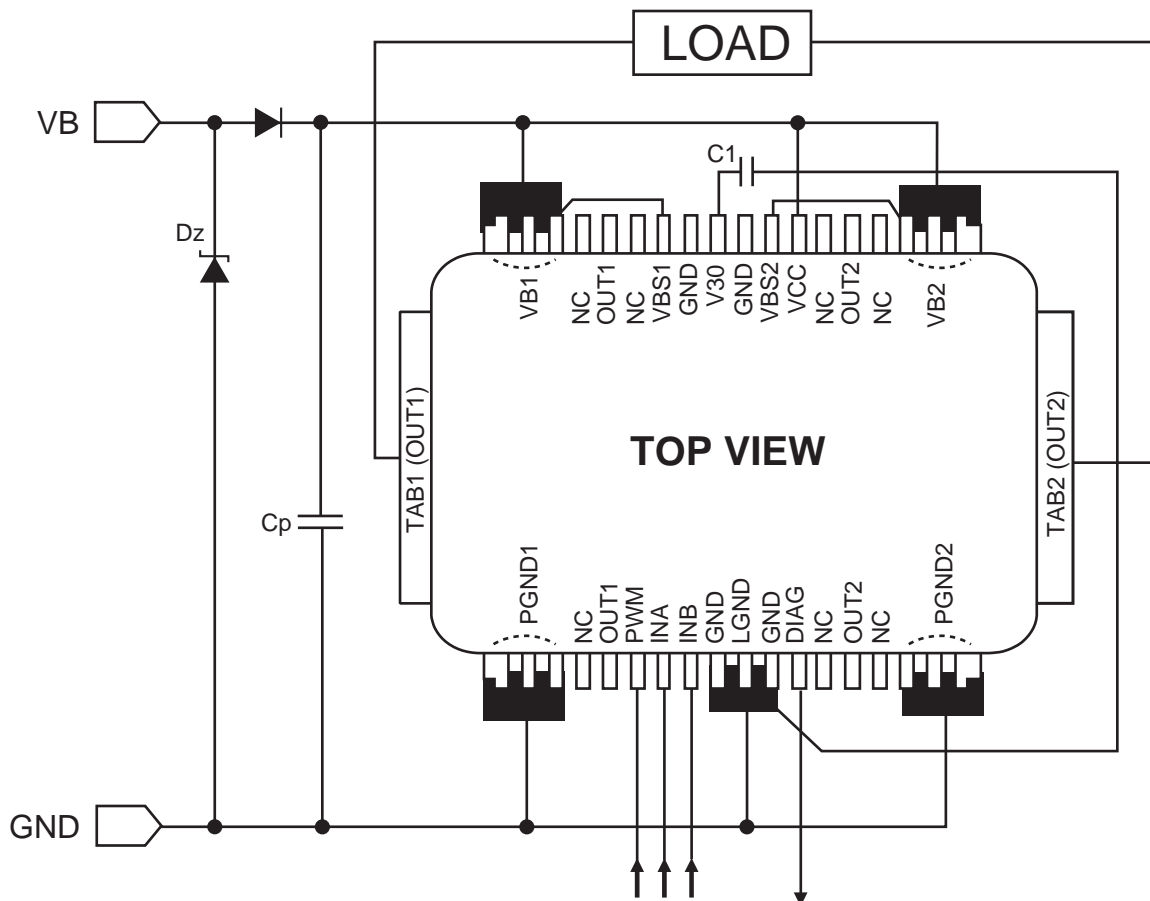
Over-Voltage Detection vs. T_a Over-Voltage Return vs. T_a 

Low-Voltage Inhibit Return vs. T_a Low-Voltage Inhibit Hysteresis vs. T_a High Level Input Voltage vs. T_a
(PWM/INA/INB)Low Level Input Voltage vs. T_a
(PWM/INA/INB)High Level Input Voltage vs. T_a
(PWM/INA/INB)Low Level Input Voltage vs. T_a
(PWM/INA/INB)





Recommended Wiring Pattern



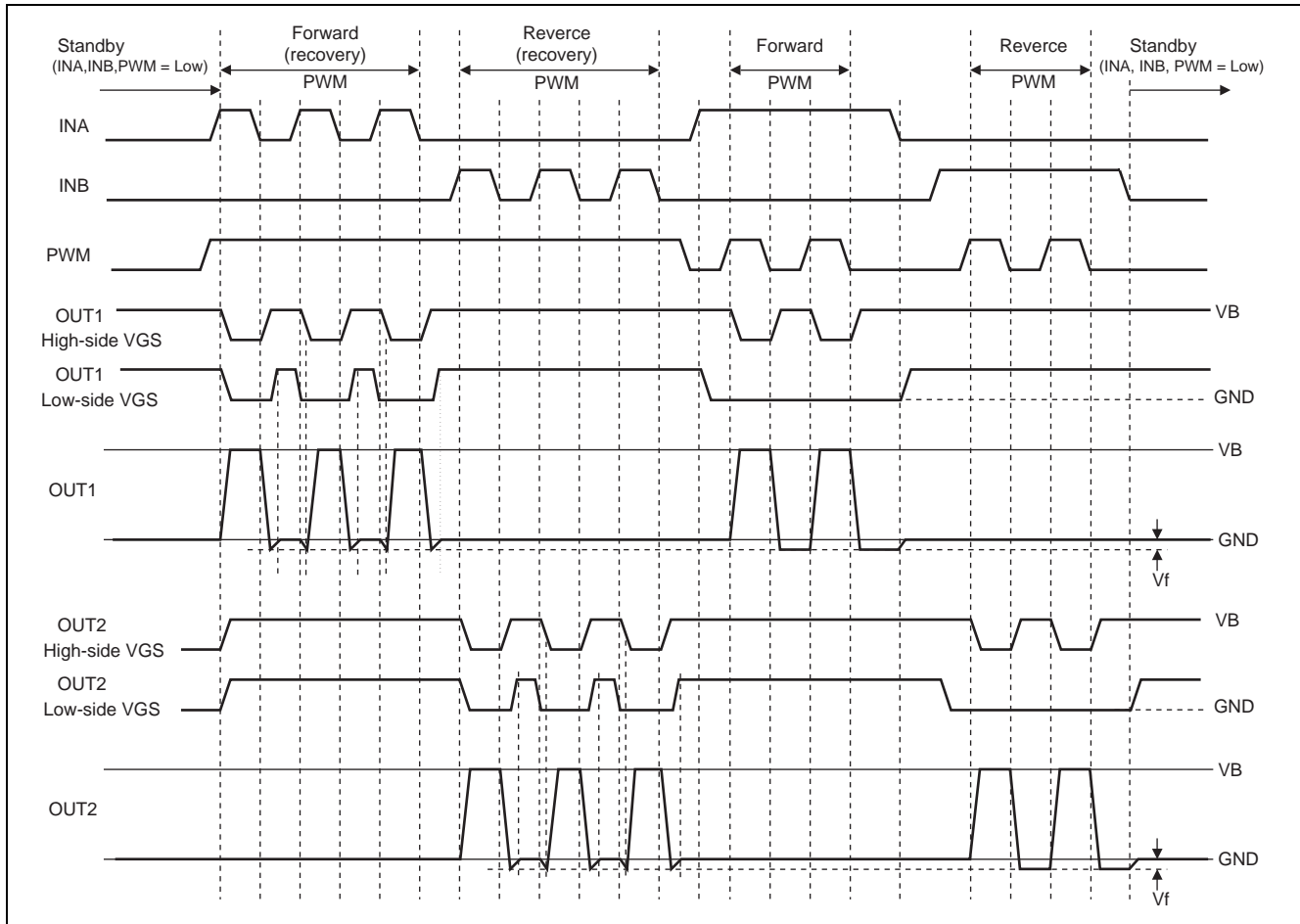
- Notes
1. VB1 and VB2 will diverge soon because of the voltage sensing terminal and it wires for VBS1 and VBS2.
 2. GND side wiring of C1 must diverge from the LGND side.
 3. Insertion examination of use conditions about the reverse battery protection device and Dz.
 4. The reverse battery protection please choose the parts such as MOSFET or Schottky diode by use.

Operational Mode

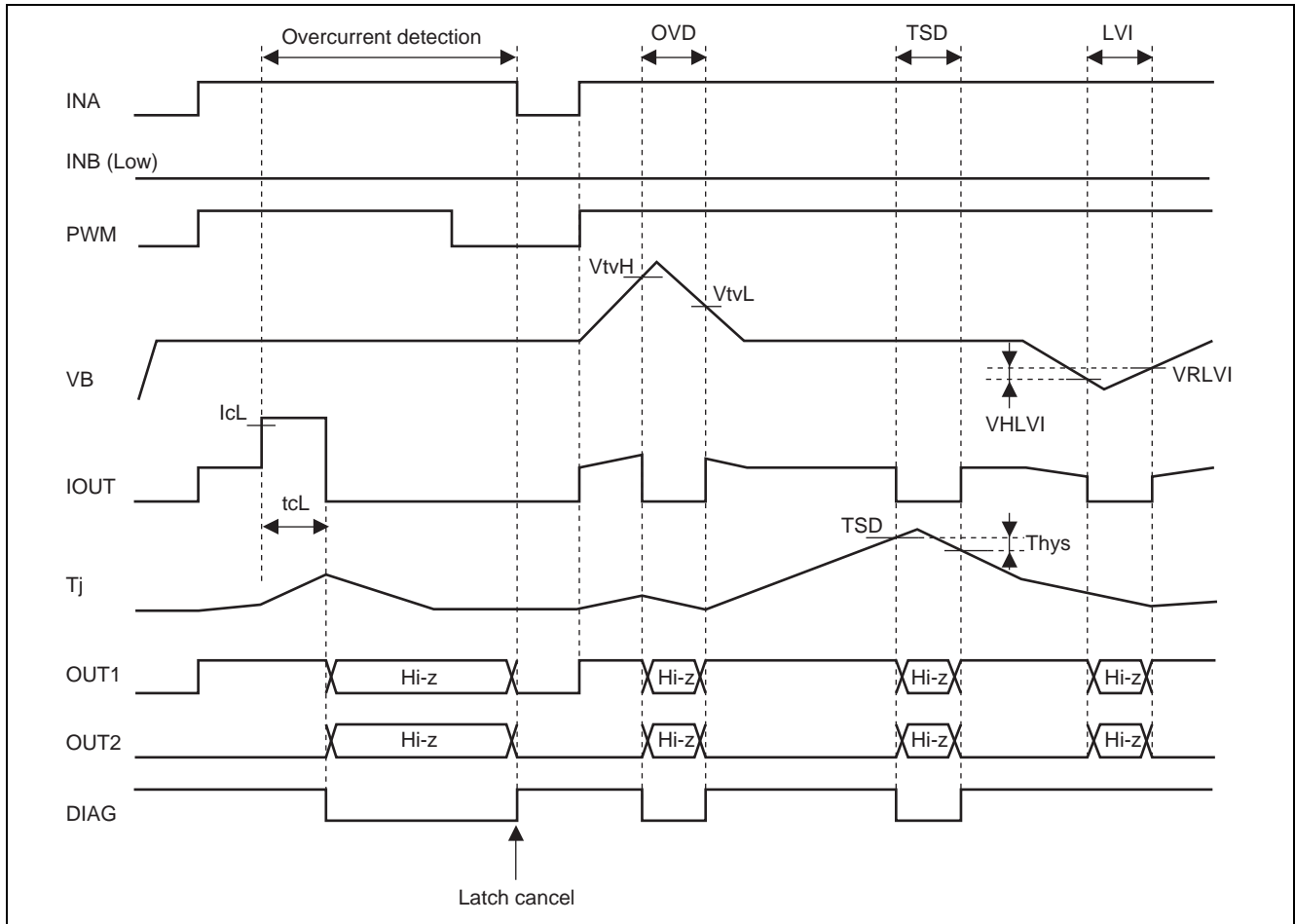
When PWM is controlled, recovery control can be selected because of the low loss. However, please note that reverse-brake hangs at acceleration of the motor.

Operational mode	Circuit operational
<p>Example 1. Forward mode (Recovery control)</p> <p>INA = PWM on/off</p> <p>INB = Low</p> <p>PWM = High</p>	
<p>Example 2. Reverse mode (Recovery control)</p> <p>INA = Low</p> <p>INB = PWM on/off</p> <p>PWM = High</p>	
<p>Example 3. Forward mode (No recovery control)</p> <p>INA = High</p> <p>INB = Low</p> <p>PWM = PWM on/off</p>	
<p>Example 4. Reverse mode (No recovery control)</p> <p>INA = Low</p> <p>INB = High</p> <p>PWM = PWM on/off</p>	

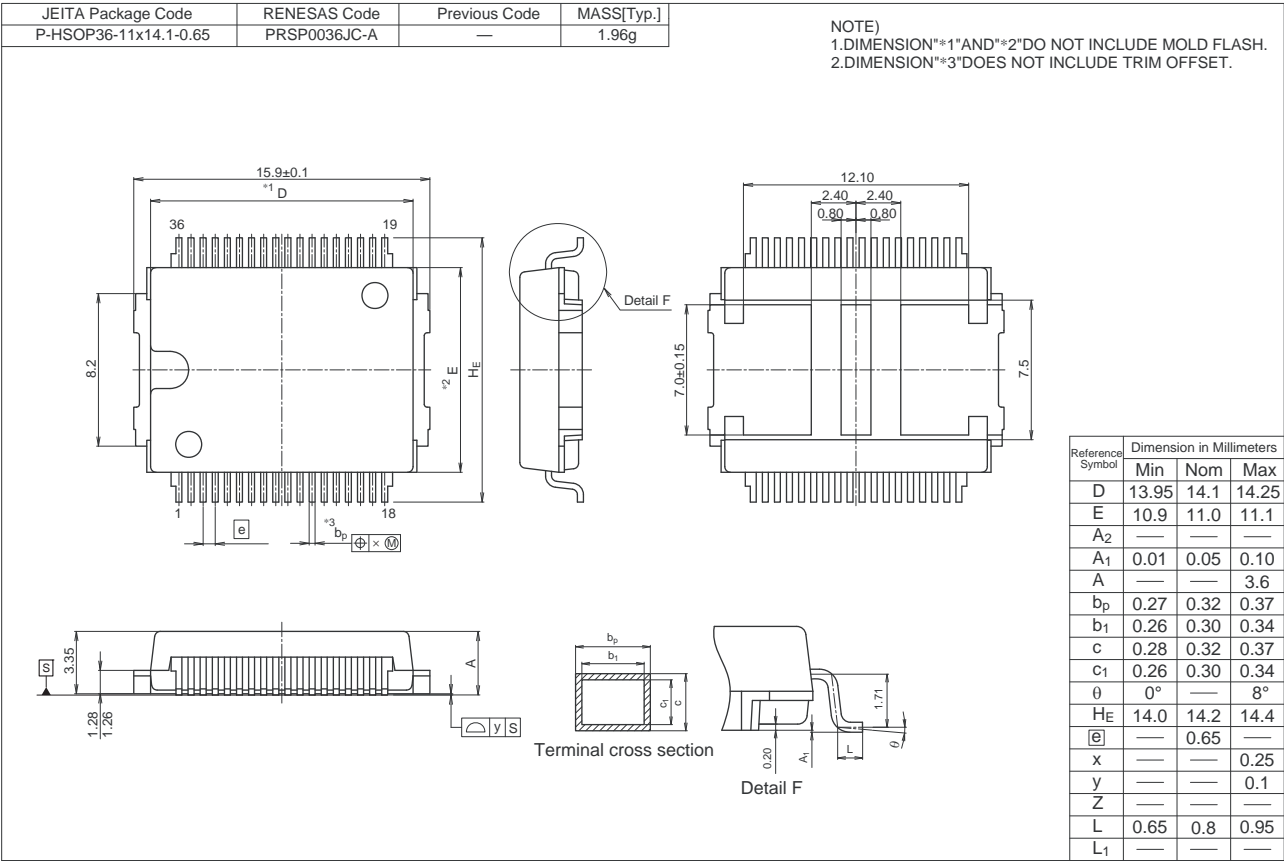
Timing Chart (Normal operation)



Timing Chart (Protection operation)



Package Dimensions



Ordering Information

Part No.	Quantity	Shipping Container
R2J25953-00	700 pcs/ box	Tray

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