

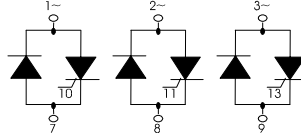
Three Phase AC Controller Modules

PSUH 36

I_{RMS} = 3 x 39A
 V_{RRM} = 400-1600 V

V_{RSM} V_{DSM}	V_{RRM} V_{DRM}	Type
500	400	PSUH 36/04
900	800	PSUH 36/08
1300	1200	PSUH 36/12
1500	1400	PSUH 36/14
*1700	*1600	PSUH 36/16

* Delivery on request



Symbol	Test Conditions	Maximum Ratings
I_{RMS}	$T_C = 85^\circ\text{C}$, 50-400 Hz (per phase)	39 A
I_{TRMS}	$T_{VJ} = T_{VJM}$	28 A
I_{TAVM}	$T_C = 85^\circ\text{C}$ 180° sine	18 A
I_{TSM}	$T_{VJ} = 45^\circ\text{C}$ $t = 10\text{ ms}$ (50 Hz), sine	320 A
	$V_R = 0$ $t = 8.3\text{ ms}$ (60 Hz), sine	350 A
	$T_{VJ} = T_{VJM}$ $t = 10\text{ ms}$ (50 Hz), sine	280 A
	$V_R = 0$ $t = 8.3\text{ ms}$ (60 Hz), sine	310 A
$\int i^2 dt$	$T_{VJ} = 45^\circ\text{C}$ $t = 10\text{ ms}$ (50 Hz), sine	500 A^2s
	$V_R = 0$ $t = 8.3\text{ ms}$ (60 Hz), sine	520 A^2s
	$T_{VJ} = T_{VJM}$ $t = 10\text{ ms}$ (50 Hz), sine	390 A^2s
	$V_R = 0$ $t = 8.3\text{ ms}$ (60 Hz), sine	400 A^2s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ repetitive, $I_T = 20\text{ A}$	150 $\text{A}/\mu\text{s}$
	$f = 50\text{ Hz}$, $t_p = 200\mu\text{s}$	
	$V_D = 2/3 V_{DRM}$	
$(dv/dt)_{cr}$	$I_G = 0.3\text{ A}$ non repetitive, $I_T = I_{TAVM}$	500 $\text{A}/\mu\text{s}$
	$di_G/dt = 0.3\text{ A}/\mu\text{s}$	
	$T_{VJ} = T_{VJM}$ $V_{DR} = 2/3 V_{DRM}$	1000 $\text{V}/\mu\text{s}$
P_{GM}	$R_{GK} = \infty$, method 1 (linear voltage rise)	
	$T_{VJ} = T_{VJM}$ $t_p = 30\mu\text{s}$	10 W
P_{GAVM}	$I_T = I_{TAVM}$ $t_p = 300\mu\text{s}$	5 W
		0.5 W
V_{RGM}		10 V
T_{VJ}		-40 ... + 125 $^\circ\text{C}$
T_{VJM}		125 $^\circ\text{C}$
T_{stg}		-40 ... + 125 $^\circ\text{C}$
V_{ISOL}	50/60 HZ, RMS $t = 1\text{ min}$	2500 V ~
	$I_{ISOL} \leq 1\text{ mA}$ $t = 1\text{ s}$	3000 V ~
M_d	Mounting torque (M5)	2-2.5 Nm
Weight	typ.	100 g

Features

- Thyristor controller for AC (circuit W3C acc. to IEC) for mains frequency
- Isolation voltage 3000 V~
- Planar glasspassivated chips
- Package with metal base plate
- UL registered E 148688

Applications

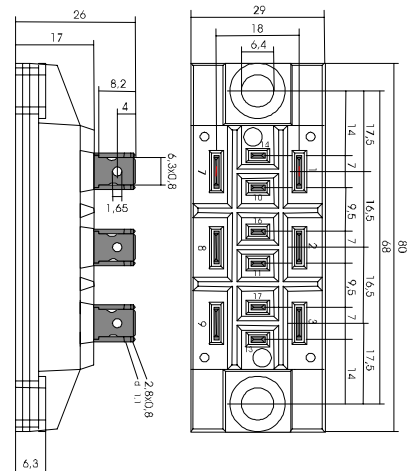
- Switching and control of three phase AC circuits
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling capability
- High power density

Package, stil and outline

Dimensions in mm (1mm = 0.0394")



Symbol	Test Conditions	Characteristic Value
I_D, I_R	$T_{VJ} = T_{VJM}, V_R = V_{RRM}, V_D = V_{DRM}$	≤ 5 mA
V_T	$I_T = 45A, T_{VJ} = 25^\circ C$	≤ 1.45 V
V_{TO}	For power-loss calculations only ($T_{VJ} = T_{VJM}$)	0.85 V
r_T		13 m Ω
V_{GT}	$V_D = 6V, T_{VJ} = 25^\circ C$	≤ 1.0 V
	$T_{VJ} = -40^\circ C$	≤ 1.2 V
I_{GT}	$V_D = 6V, T_{VJ} = 25^\circ C$	≤ 65 mA
	$T_{VJ} = -40^\circ C$	≤ 80 mA
V_{GD}	$T_{VJ} = T_{VJM}, V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}	$T_{VJ} = T_{VJM}, V_D = 2/3 V_{DRM}$	≤ 5 mA
I_L	$T_{VJ} = 25^\circ C, t_p = 10\mu s$ $I_G = 0.3A, di_G/dt = 0.3A/\mu s$	≤ 150 mA
I_H	$T_{VJ} = 25^\circ C, V_D = 6V, R_{GK} = \infty$	≤ 100 mA
t_{gd}	$T_{VJ} = 25^\circ C, V_D = 1/2 V_{DRM}$ $I_G = 0.3A, di_G/dt = 0.3A/\mu s$	≤ 2 μs
t_q	$T_{VJ} = T_{VJM}, I_T = 20A, t_p = 200\mu s, V_R = 100V$ $-di/dt = 10A/\mu s, dv/dt = 15V/\mu s, V_D = 2/3 V_{DRM}$	150 μs
R_{thJC}	per thyristor; sine 180° el	1.3 K/W
	per module	0.22 K/W
R_{thJK}	per thyristor; sine 180° el	1.5 K/W
	per module	0.25 K/W
d_s	Creeping distance on surface	16.1 mm
d_A	Creeping distance in air	6.0 mm
a	Max. allowable acceleration	50 m/s ²