



## Absolute Maximum Ratings

Stresses above the ratings listed below (Table 1 and Table 2) can cause permanent damage to the P9025AC. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

**Table 1: Absolute Maximum Ratings Summary**

Pins	Rating	Units
AC1, AC2, VRECT, ACM1, ACM2, CLAMP1, CLAMP2 to PGND_	-0.3 to 20	V
BST1, BST2 to PGND1	-0.3 to (AC1, AC2 + 6)	V
$\overline{\text{INT}}$ , $\overline{\text{EN}}$ , $\overline{\text{STAT}}$ , SCL, SDA, OUT, SNS, TEOP, RLIM, CHG_END/CS100, FOD1, FOD2, VDD to AGND	-0.3 to 6	V
PGND, PGND1, PGND2, to AGND	-0.3 to 0.3	V
Out Current	1.5	A
AC1, AC2 Current	2	A <sub>RMS</sub>

**Table 2: Package Thermal Information<sup>1,2,3,4</sup>**

Symbol	Description	Rating (VFQFPN)	Units
$\Theta_{JA}$	Thermal Resistance Junction to Ambient	35	°C/W
$\Theta_{JC}$	Thermal Resistance Junction to Case	29.6	°C/W
$\Theta_{JB}$	Thermal Resistance Junction to Board	2.4	°C/W
$T_J$	Operating Junction Temperature	0 to +125	°C
$T_A$	Ambient Operating Temperature	0 to +85	°C
$T_{STG}$	Storage Temperature	-55 to +150	°C
$T_{LEAD}$	Lead Temperature (soldering, 10s)	300	°C

**NOTES:**

1. The maximum power dissipation is  $P_D(\text{MAX}) = (T_J(\text{MAX}) - T_A) / \Theta_{JA}$  where  $T_J(\text{MAX})$  is 125°C. Exceeding the maximum allowable power dissipation will result in excessive die temperature, and the device will enter thermal shutdown.
2. This thermal rating was calculated on JEDEC 51 standard 4-layer board with dimensions 3" x 4.5" in still air conditions.
3. Actual thermal resistance is affected by PCB size, solder joint quality, layer count, copper thickness, air flow, altitude, and other unlisted variables.
4. For the NBG32 package, connecting the 5 mm X 5 mm EP to internal/external ground planes with a 5x5 matrix of PCB plated-through-hole (PTH) vias, from top to bottom sides of the PCB, is recommended for improving the overall thermal performance.

**Table 3: ESD Information**

Test Model	Pins	Ratings	Units
HBM	All pins	±1500	V
CDM	All pins	±500	V

## Electrical Specifications Table

**Table 4: Device Characteristics**
 $V_{RECT} = 6V$ ,  $C_{OUT} = 1\mu F$ ,  $C_{VRECT} = 20\mu F$ ,  $V_{\overline{EN}} = GND$ ,  $T_A = 0$  to  $+85^\circ C$ , unless otherwise noted. Typical values are at  $25^\circ C$ .

Symbol	Description	Conditions	Min	Typ	Max	Units
V <sub>RECT</sub> Under-Voltage Lock-out						
V <sub>UVLO</sub>	Under-voltage Lockout	Rising voltage on V <sub>RECT</sub>	2.3	2.5	2.7	V
V <sub>UVLO-HYS</sub>	UVLO Hysteresis			50		mV
V <sub>RECT</sub> Over-Voltage Protection						
V <sub>OVP</sub>	Over-Voltage V <sub>RECT</sub>	Rising voltage on V <sub>RECT</sub>		13.3		V
V <sub>OVP-HYS</sub>	Over-Voltage Hysteresis			1.5		V
Power Supply Current						
I <sub>RECT</sub>	Quiescent Current	I <sub>OUT</sub> = 0mA, with internal load	14	16	18	mA
		I <sub>OUT</sub> = 0mA, no internal load	2	3	4	mA
Low-drop-out Regulator						
I <sub>LIM</sub>	Output Current Limit	R <sub>LIM</sub> = 30kΩ	1.15	1.6	1.95	A
		R <sub>LIM</sub> < 25KΩ <sup>1</sup>			2.0	
V <sub>OUT</sub>	Regulated Output Voltage	I <sub>OUT</sub> = 0mA to 1000mA	5.04	5.3	5.56	V
V <sub>DD</sub> Voltage (For Internal Supply Use Only)						
V <sub>DD_INT</sub>	Internal Supply Voltage	I <sub>VDD</sub> = 100μA, maximum allowable load for test purposes	4.44	4.54	4.64	V
Thermal Shutdown						
T <sub>SHD</sub>	Thermal Shutdown Threshold	Temperature rising		150		°C
		Temperature falling		130		°C
Digital Input and Output Characteristics						
V <sub>IL</sub>	Logic Level Input Low	$\overline{EN}$ , TEOP			0.4	V
V <sub>IH</sub>	Logic level Input High	$\overline{EN}$ , TEOP	1.3			V
V <sub>OL</sub>	Open Drain; $\overline{STAT}$ , $\overline{INT}$	I <sub>STAT</sub> = 4mA			400	mV
R <sub>PD</sub>	Pull-down Resistance	EN		200		kΩ
		TEOP		1000		
Switch On-resistance						
R <sub>DSON</sub>	ACM1, ACM2 Switches	150mA		2500		mΩ
	CLAMP1, CLAMP2 Switches			600		mΩ
	Rectifier Bridge Switches			250		mΩ
SCL, SDA (I <sup>2</sup> C Interface)						
f <sub>SCL</sub>	Clock Frequency		0		400	kHz
t <sub>LOW</sub>	Clock Low Period		1.3			μs
t <sub>HIGH</sub>	Clock High Period		0.6			μs
t <sub>HD,STA</sub>	Hold Time (Repeated) for START Condition		0.6			μs

Symbol	Description	Conditions	Min	Typ	Max	Units
$t_{SU:STA}$	Set-up Time for Repeated START Condition		0.6			$\mu s$
$t_{SU:DAT}$	Data Setup Time		100			ns
$t_{HD:DAT}$	Data Hold Time				0.9	$\mu s$
$t_{SU:STO}$	Setup Time for STOP		0.6			$\mu s$
$t_{BUF}$	Bus Free Time between STOP & START		1.3			$\mu s$
$t_R$	Rise Time of both SDA and SCL Signals (Note 1,2)		$20 + 0.1 C_B$		300	ns
$t_F$	Fall Time of both SDA and SCL Signals <sup>1,2</sup>		$20 + 0.1 C_B$		300	ns
$T_{SP}$	Spike Pulse Widths Suppressed by Input Filter <sup>1,2</sup>		0		50	ns
$C_B$	Capacitive Load for each Bus Line <sup>1,2</sup>				400	pF
$C_{BIN}$	SCL, SDA Input Capacitance <sup>1,2</sup>				60	pF
$V_{IL}$	Input Threshold Low				0.4	V
$V_{IH}$	Input Threshold High		1.4			V
$I_I$	Input Leakage Current		-1.0		1.0	$\mu A$

**NOTES:**

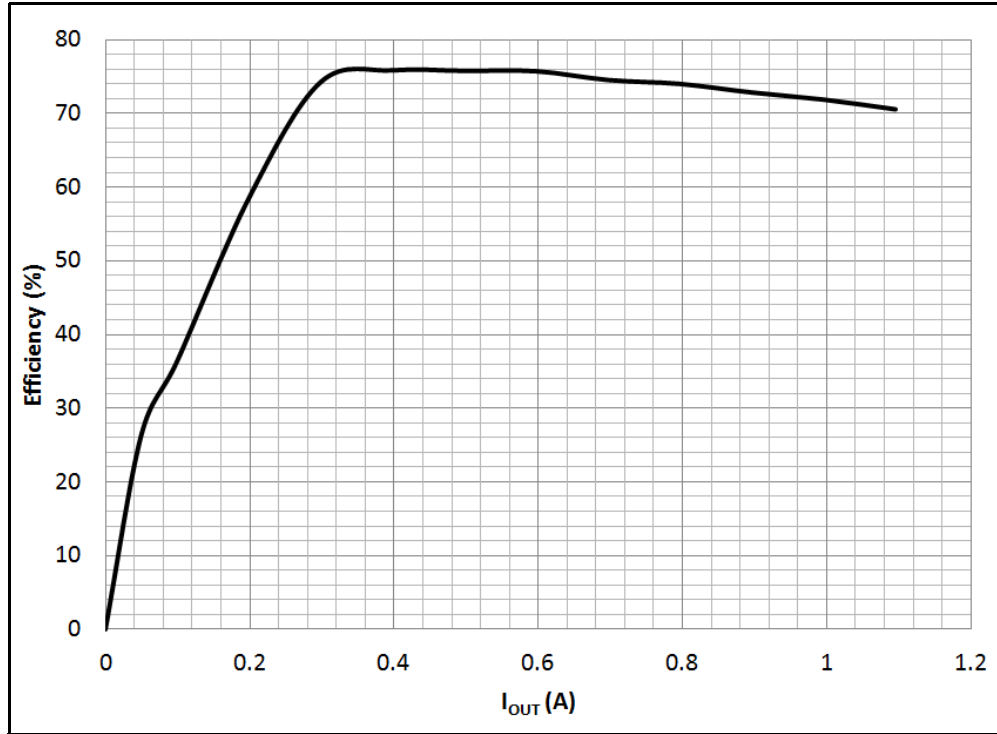
1. Guaranteed by design and not subject to 100% production testing.
2. Guaranteed by design and simulation.

## Typical Performance Characteristics

**Figure 1. System Efficiency vs. Load Current**

$V_{IN} = 5V$ ,  $V_{OUT} = 5.3V$ , Spacer = 3.7mm,  $C_s = 247nF$ ,  $T_A = 25^\circ C$

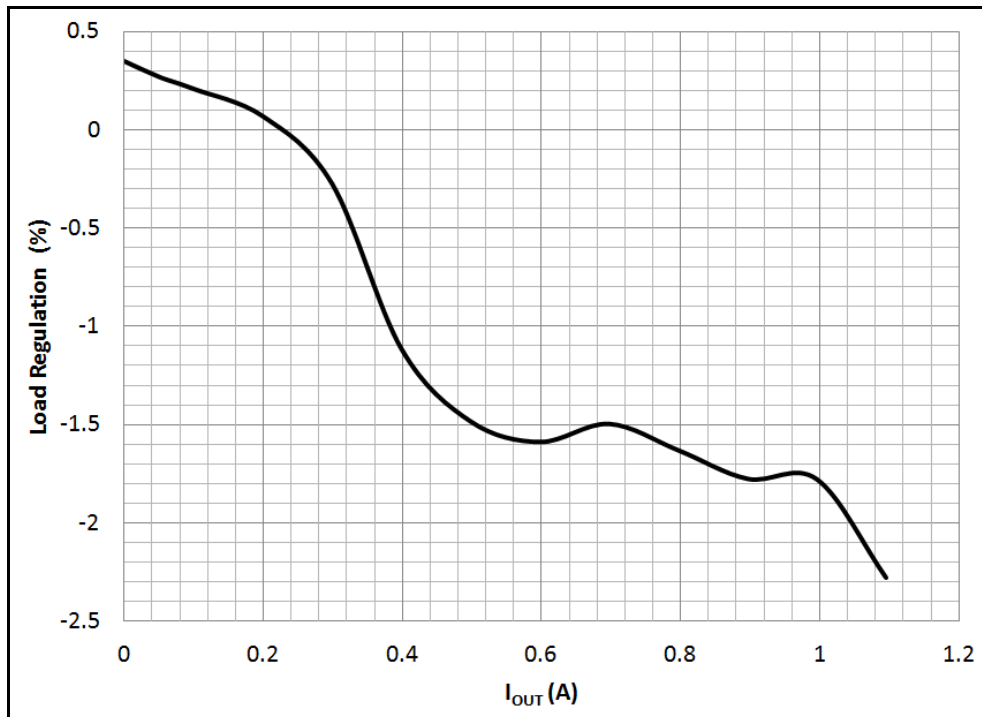
Measured using the P9025AC-R-EVK V1.0 (receiver) and P9038-R-EVK V1.0 (transmitter) reference boards.



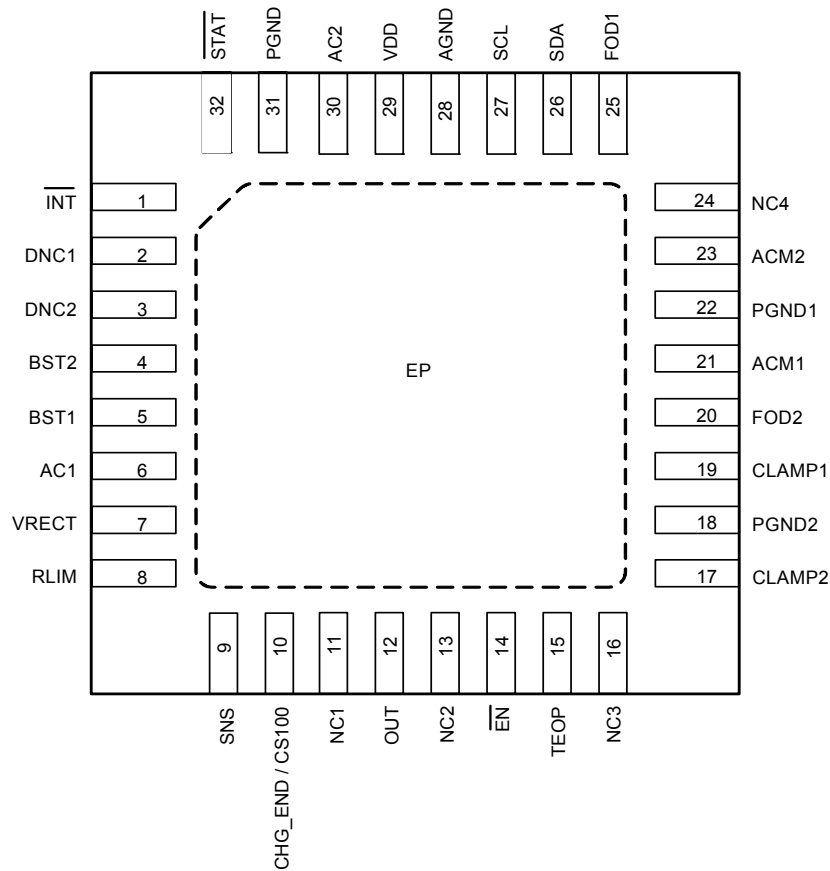
**Figure 2. Load Regulation vs. Load Current**

$V_{IN} = 5V$ ,  $V_{OUT} = 5.3V$ , Spacer = 3.7mm,  $C_s = 247nF$ ,  $T_A = 25^\circ C$

Measured using the P9025AC-R-EVK V1.0 (receiver) and P9038-R-EVK V1.0 (transmitter) reference boards.



## Pin Configuration

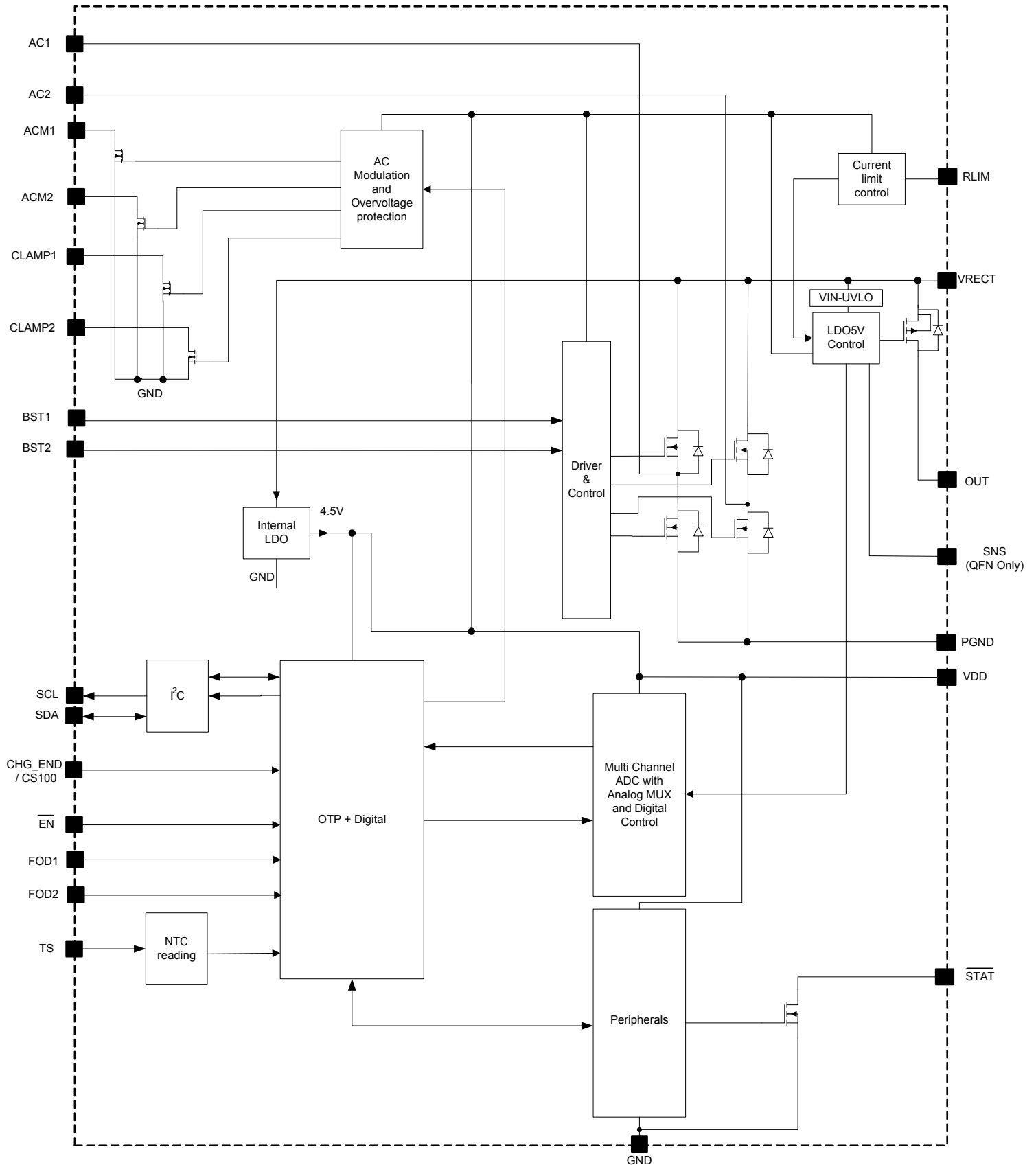


## Pin Descriptions

Pin #	Name	Type	Function
1	$\overline{\text{INT}}$	O	Interrupt output. Open drain output pin. A low state indicates that an over-current, over-voltage, or over-temperature condition has occurred. If used, connect a 100K $\Omega$ pullup resistor to the OUT pin or compatible system I/O voltage rail.
2	DNC1	DNC	DO NOT connect. It is internally connected. This pin must be left floating.
3	DNC2	DNC	DO NOT connect. It is internally connected. This pin must be left floating.
4	BST2	O	Bootstrap output for high-side rectifier FET 2. Connect a 0.01 $\mu\text{F}$ capacitor from AC2 pin to BST2.
5	BST1	O	Bootstrap output for high-side rectifier FET 1. Connect a 0.01 $\mu\text{F}$ capacitor from AC1 pin to BST1.
6	AC1	I	AC1 input to the Internal full-wave rectifier.
7	VRECT	O	Output of the full-wave rectifier. Bypass this pin with ceramic capacitors to power ground.
8	RLIM	I	Current-limit resistor. A resistor connected between this pin and ground sets the current limit of the 5V LDO output.
9	SNS	I	LDO output sense pin. Connect to the OUT pin.
10	CHG_END / CS100	I	Active-high input pin. Default setting is a Charge-End active-high input from an external battery charger to terminate power transfer. Alternatively, a Charge-Status active high input which will send a WPC Charge Status packet with value 100 (100% charge). This pin has an internal pull down resistor.

Pin #	Name	Type	Function
11	NC1	NC	Not internally connected. This pin may be connected to others to facilitate routing or to improve thermal performance.
12	OUT	O	Regulated 5.3V output voltage. Connect a 1μF in parallel with 4.7 μF capacitor between the pin and ground.
13	NC2	NC	Not internally connected. This pin may be connected to others to facilitate routing or to improve thermal performance.
14	$\overline{\text{EN}}$	I	Active-low enable pin. The chip is suspended and placed in low-current (sleep) mode when this pin is pulled high. This pin has internal pulldown resistor to Analog Ground (AGND).
15	TEOP	I	Active-high over-temperature input pin. When pulled high, the chip will disable the LDO output and send a WPC End-of-Power packet with code 0x03 (over-temperature code). This pin has an internal pull down resistor to ground.
16	NC3	NC	Not internally connected. This pin may be connected to others to facilitate routing or to improve thermal performance.
17	CLAMP2	I	AC clamp input 2. Connect a 0.47μF capacitor from this pin to AC2 pin.
18	PGND2	-	Power ground for the AC clamp FETs.
19	CLAMP1	I	AC clamp input 1. Connect a 0.47μF capacitor from this pin to AC1 pin.
20	FOD2	I	FOD2 adjustment. A resistor between this pin and AGND sets the FOD offset value used in the internal FOD calculation.
21	ACM1	I	AC Modulation input 1. Connect a 22nF capacitor from this pin to AC1 pin.
22	PGND1	-	Power ground for the full-wave rectifier.
23	ACM2	I	AC Modulation input 2. Connect a 22nF capacitor from this pin to AC2 pin.
24	NC4	NC	Not internally connected. This pin may be connected to others to facilitate routing or to improve thermal performance.
25	FOD1	I	A resistor between this pin and Analog Ground selects the FOD compensation curve that is used for the internal FOD calculation.
26	SDA	I/O	I <sup>2</sup> C data port. Connect a 2.2k pullup resistor from this pin to OUT (PIN) voltage or the system IO voltage rail. If not used, connect to ground.
27	SCL	I	I <sup>2</sup> C clock port. Connect a 2.2k pullup resistor from this pin to OUT voltage or the system IO voltage rail. If not used, connect to ground.
28	AGND	-	Analog Ground connection.
29	VDD	O	Internal voltage supply. Connect a 1uF capacitor between this pin and Analog Ground. Do not connect any external load to this pin.
30	AC2	I	AC2 input to the Internal full-wave rectifier.
31	PGND	-	Power ground for the full-wave rectifier.
32	$\overline{\text{STAT}}$	O	Status output. A logic low state indicates that power is being transferred.

## Block Diagram





## Description of the Wireless Power Charging System

A wireless power charging system has a base station with one or more transmitters that make power available via DC-to-AC inverter(s) and transmit the power over a strongly-coupled inductor pair to a receiver in a mobile device. The transmitter may be a *free-positioning* or *magnetically-guided* type. A *free-positioning* type of transmitter has one coil or an array of coils that offers limited spatial freedom to the end-user, whereas a *magnetically-guided* type of transmitter helps the end-user align the receiver to the transmitter with a magnetic attraction.

The amount of power transferred to the mobile device is controlled by the receiver. The receiver sends communication packets to the transmitter to increase power, decrease power, maintain the power level, or terminate power transfer. The bit rate for Rx-to-Tx communication link is 2kbps. The communication is digital and communication of 1's and 0's is achieved by the Rx modulating the amount of load on the receiver coil.

To conserve power, the transmitter places itself in a very-low-power sleep mode unless it detects the presence of a receiver. Once a receiver is detected, the transmitter exits sleep mode and begins the power transfer per the WPC specification.

### Theory of Operation

The P9025AC is a highly-integrated WPC (Wireless Power Consortium)-compliant wireless power receiver IC for mobile devices. It can transfer 5W of power from a wireless transmitter to a load (ex. a battery charger) in WPC "Qi" mode using near-field magnetic induction. For complete details of the WPC wireless power systems, refer to the WPC specifications and other materials at <http://www.wirelesspowerconsortium.com>.

### Overview

The simplified internal block diagram of the P9025AC is shown on [page 8](#). An external inductor and capacitor transfers energy from the transmitter's coil through the P9025AC's AC1 and AC2 pins to be full-wave-rectified and stored on a capacitor connected to  $V_{RECT}$ . Until the voltage across the capacitor exceeds the threshold of the VIN\_UVLO block, the rectification is performed by the body diodes of the Synchronous Full Bridge Rectifier FETs. After the internal biasing circuit is enabled, the Driver and Control block operates the MOSFET switches in the rectifier synchronously with the applied AC signal for increased efficiency. An internal ADC monitors the voltage at  $V_{RECT}$  and the load current.

Using this information, the P9025AC sends instructions to the wireless power transmitter to increase, maintain, or decrease the amount of power transferred. The P9025AC may also instruct the transmitter to terminate power transmission based on various conditions and other inputs.

### Power Control

The voltage at  $V_{RECT}$  and the current through the rectifier are sampled periodically and digitized by the ADC. The digital equivalents of the voltage and current are supplied to the internal control logic, which decides whether the loading conditions on  $V_{RECT}$  indicate that a change in the operating point is required. If the load is heavy enough to bring the voltage at  $V_{RECT}$  below its target, the transmitter is instructed to move its frequency lower, closer to resonance. If the voltage at  $V_{RECT}$  is higher than its target, the transmitter is instructed to increase its frequency. To maximize efficiency, the voltage at  $V_{RECT}$  is programmed to decrease and become closer to the LDO output voltage as the LDO's load current increases. When the load current is small, a higher  $V_{RECT}$  is desirable so that the system can better handle a sudden load increase.

### WPC Characteristics

#### Startup and Power Transfer

When a mobile device containing the P9025AC is placed on a WPC "Qi" charging pad, it responds to the transmitter's "ping" signal by rectifying the AC power from the transmitter and storing it on a capacitor connected to  $V_{RECT}$ . During the "ping" phase, the rectifier provides about 5V at the  $V_{RECT}$  pin. An internal linear voltage regulator provides the supply voltage for the digital section to enable WPC communication. To increase the reliability of the communication, an internal load of about 15mA is connected to  $V_{RECT}$  until the external load is large enough to support communication.

The P9025AC then communicates its Identification and Configuration information to the transmitter. After this, the system is in the Power Transfer state. The control loop of the P9025AC then adjusts the rectifier voltage to 7V by sending Control Error Packets instruction to the transmitter. The LDO output is enabled and power is delivered to the load after  $V_{RECT}$  initially reaches 7V.

During power delivery to the load, the P9025AC control circuit continues to send Control Error Packets to the transmitter to adjust the rectifier voltage to the level required to maximize the efficiency of the linear regulator.

## Advanced Foreign Object Detection (FOD)

When metallic objects are exposed to an alternating magnetic field, eddy currents cause such objects to heat up. Examples of parasitic metal objects as such are coins, keys, paper clips, etc. The amount of heating depends on the strength of coupled magnetic field, as well as on the characteristics of the object, such as its resistivity, size, and shape. In a wireless power transfer system, the heating manifests itself as a power loss, and therefore a reduced power transfer efficiency. Moreover, if no appropriate measures are taken, the heating could be sufficient that the foreign objects may become heated to an undesirable temperature.

During Power Transfer state, the receiver periodically will communicate to the transmitter the amount of power received by means of a Received Power packet. The transmitter will compare this power with the amount of power transmitted during the same time period. If there is a significant unexplained loss of power, then the transmitter will shut off power delivery, because a possible foreign object may be absorbing too much energy.

For a WPC system to perform this function with sufficient accuracy, both the transmitter and receiver need each to account for and compensate for all of their known losses. Such losses could be to resistive losses, nearby metals that are part of the transmitter or receiver, etc. Because the system accurately measures its power and accounts for all known losses, it can thereby detect foreign objects owing to their creation of an unknown loss.

The P9025AC employs advanced FOD techniques to both accurately measure its received power, and to accurately compensate all of its known losses. This compensation is implemented by means of a curve fitting table. This table supports up to 10 different curves stored in OTP (One Time Programmable) memory. The 10 programmed OTP settings are externally selected by means of the FOD1 selection resistor value (see [page 14](#)) which selects the settings that best match a particular system characteristic. Additionally, the I<sup>2</sup>C interface supports 1 volatile FOD compensation setting that can be selected that will override the OTP memory settings. A further enhancement is selected by the FOD2 offset resistor which adds a -300 to +300mW power offset to the values selected by the FOD1 resistor. This is useful to tune the selected compensation curve up or down to optimally match the actual known receiver system losses.

For more information about how to determine and program the FOD settings, refer to application note [AN-886 P9025AC FOD Tuning Guide](#).

## Over-Voltage Protection

In the event that the input voltage increases above 15V, the control loop disables the LDO, and sends error packets to the transmitter in an attempt to bring the rectifier voltage below 7V. If the voltage at  $V_{RECT}$  exceeds VOVP, two internal FETs turn on to clamp the AC inputs to quickly reduce the  $V_{RECT}$  voltage. This is accomplished through loading the receiver resonant tank with extra capacitance shorted to ground through the above mentioned internal FETs. This changes the parallel resonance of the tank circuit which causes the Tx to Rx gain to decrease dramatically. The clamp is released when the  $V_{RECT}$  voltage falls below the VOVP hysteresis level.  $V_{RECT}$  must not be directly loaded.

## Over-Current Protection and Thermal Shutdown

The P9025AC employs over-current and thermal protection by sending an End of Power packet to the transmitter when the output current reaches the current limit level or the die temperature exceeds the thermal shutdown level. The LDO output is also disabled during these conditions.

The current limit level is programmable with an external resistor:

$$I_{LIM} = \frac{45000}{R_{LIM}}$$

For any value of  $R_{LIM}$  below 25k $\Omega$ , the output current is limited to 2-Amps. However,  $R_{LIM}$  is not recommended to be set higher than 60 k $\Omega$ .

## Rectifier and $V_{RECT}$ Level

Once  $V_{RECT}$  powers up to greater than 7V, the full-bridge rectifier switches to half synchronous or full synchronous mode (depending on the loading conditions) to efficiently transfer energy from the transmitter to  $V_{RECT}$ . The control loop of the P9025AC maintains the rectifier voltage between 5.45V and 7V, depending upon the output current ( $I_{OUT}$ ). The  $R_{LIM}$  resistor sets both the current limit ( $I_{LIM}$ ) and the  $V_{RECT}$  steps based on  $I_{SET}$  which is a reference current used to partition the  $I_{OUT}$  load range into 4 regions, each with a  $V_{RECT}$  target for efficiency and transient optimization.  $I_{SET}$  is equal to:

$$I_{SET} = \frac{38000}{R_{LIM}}$$

The recommended value of  $R_{LIM}$  for a 1A output is 30 k $\Omega$ .

**Table 5:  $V_{RECT}$  Target Range**

$V_{RECT}$	$I_{OUT}$
7V	$I_{OUT} < 10\% \text{ of } I_{SET}$
6.3V	$10\% \text{ of } I_{SET} < I_{OUT} < 20\% \text{ of } I_{SET}$
5.5V	$20\% \text{ of } I_{SET} < I_{OUT} < 40\% \text{ of } I_{SET}$
5.45V	$40\% \text{ of } I_{SET} < I_{OUT}$

**Status Output**

The  $\overline{STAT}$  output goes low when the LDO output is enabled.

**Interrupt Output**

The  $\overline{INT}$  output goes low to indicate that an Over-Current, Over-Voltage or Over-Temperature event has occurred. See the Electrical Specifications for threshold levels.

**Enable Input**

If the particular application requires the P9025AC to be disabled, this can be accomplished with the  $\overline{EN}$  pin. When the  $\overline{EN}$  pin is pulled high, the device is suspended and placed in low current (sleep) mode. If the  $\overline{EN}$  pin is pulled low or floating, the device is active.

**TEOP Input**

The P9025AC can optionally be shut down with the TEOP pin. This pin is typically used to shut down the P9025AC if the battery charger or host system determines an over-limit high temperature condition. When the TEOP pin is pulled high, the P9025AC will disable its LDO output, and also send an End-of-Power packet to the transmitter with code 0x03 (Over-Temperature code). In response to the End-of-Power packet, the transmitter will immediately stop power transfer and go into a sleeping (no power offered) condition for some period of time. The amount of sleep time is not prescribed by WPC and varies among different transmitters. A common value used for this over-temperature sleep time is approximately 5-minutes.

**CHG\_END / CS100**

This pin has two functions. The Charge-End default function can be used to terminate power transfer with the transmitter. When CHG\_END is pulled high, the P9025AC will send a WPC End-of-Charge packet with a code value of 0x01 (Charge Complete code). In response to this, the transmitter should immediately stop power transfer and go into a sleeping (no power offered) condition for some period of time. The amount of sleep time is not prescribed by WPC and varies from 5-seconds to much longer, depending on the transmitter design.

If the pin is set in Charge-Status mode, the device will send a WPC Charge Status packet with value 100 (100% charge) indicating a fully charged battery.

**LDO**

The primary output of the P9025AC device is a linear regulator that receives its input from  $V_{RECT}$ . The LDO supplies power to the system and/or charging circuitry. The output provides a nominal 5.3V with 1 A output current capability. The voltage is intentionally set 0.3V higher than the standard 5V rail to provide extra headroom for voltage drops that may be encountered in the system under heavy loads.

**Modulation/Communication**

Receiver-to-transmitter communication is accomplished by modulating the load seen by the receiver's inductor. To the transmitter, this appears as an impedance change, which results in measurable variations of the transmitter's output waveform. Modulation is done with AC Modulation, using internal switches to connect external capacitors from AC1 and AC2 to ground. The communication protocol is covered in the next section.

**WPC Communication**

The P9025AC communicates with the base via communication packets. Each communication packet has the following structure:

**Figure 3. Communication Packet Structure**

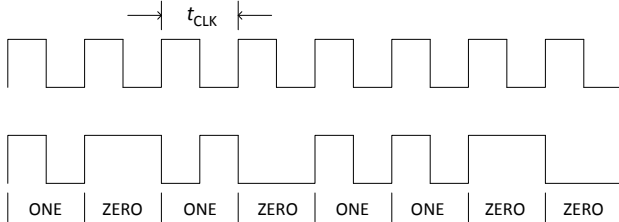
Preamble	Header	Message	Checksum
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In accordance with the WPC specification, the power receiver communicates with the power transmitter using load modulation. The load seen by the power transmitter's inductor is modulated on the receiver side in a periodic fashion to send packets. The power transmitter detects this as a modulation of coil current/voltage to receive the packet information.

## Bit Encoding Scheme

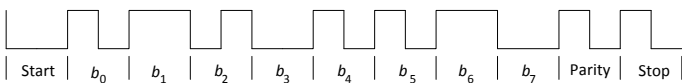
As required by the WPC, the P9025AC uses a differential bi-phase encoding scheme to modulate data bits onto the Power Signal. A clock frequency of 2kHz is used for this purpose. A logic ONE bit is encoded by generating two transitions per clock period, whereas a logic ZERO bit is encoded using only one transition per clock period as shown below:

**Figure 4. Bit Encoding Scheme**



Each byte in the communication packet comprises 11bits in an asynchronous serial format, as shown below:

**Figure 5. Byte Encoding Scheme**



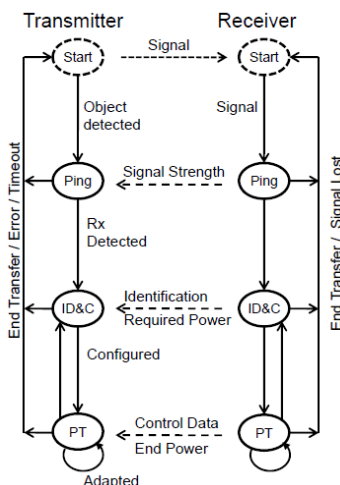
Each byte has a start bit, 8 data bits, a parity bit, and a single stop bit.

## System Feedback Control

The P9025AC is fully compatible with WPC specification Rev. 1.1.2 and has all necessary circuitry to communicate with the base station via WPC-compliant communication packets.

The overall WPC-compliant system behavior between the transmitter and receiver follows the state machine below:

**Figure 6. WPC System Feedback Control**



The P9025AC goes through four phases: Start/Selection, Ping, Identification & Configuration, and Power Transfer.

### Start/Selection

In this phase, the P9025AC senses the incoming power from the base station transmitter and proceeds to the PING state. It monitors the rectified voltage, and when the voltage is above the  $V_{RECT}$ , UVLO threshold, the P9025AC wakes up its digital electronics and prepares to communicate with the base station. If the P9025AC does not proceed to PING, then it does not transmit any communication packets.

### Ping

In this phase, the P9025AC transmits a Signal Strength Packet as the first communication packet to instruct the base to keep the power signal ON. After sending the Signal Strength Packet, the P9025AC proceeds to the Identification and Configuration phase. If, instead, the P9025AC sends End of Power Packets, then it remains in the PING phase.

In this phase, the P9025AC sends the following packets:

- Signal Strength Packet
- End of Power Packet

### Identification and Configuration (ID & Config)

In this phase, the P9025AC may send the following packets:

- Identification Packet
- Configuration Packet

After sending the Configuration Packet, the P9025AC proceeds to the power transfer phase.

### Power Transfer

In this phase, the P9025AC controls the power transfer from the Power Transmitter by means of the following Control Data Packets:

- Control Error Packets
- Rectified Power Packet
- End Power Transfer Packet

### Modulation

The P9025AC is compatible with WPC V1.1.2 transmitter coils. Each receiver coil type has a unique inductance value and various physical properties as are best for a given application. As such, the resonant capacitor (CS) that is used with a given receiver coil should be optimized for the overall application. The WPC guidance for Cs is that the resonant frequency of the receiver coil and Cs capacitor should be 100kHz while placed on the surface of a transmitter with the normal spacing.



## Application Information

### External Components

The P9025AC requires a minimum number of external components for proper operation, as indicated in the Reference schematic.

### LDO

#### Input Capacitor ( $V_{RECT}$ Capacitors)

The LDO input capacitors ( $V_{RECT}$  capacitors) should be located as close as possible to the  $V_{RECT}$  pins, and ground (PGND). Ceramic capacitors are recommended for their lower ESR and small profile.

#### $V_{DD}$ Capacitor

The P9025AC has an internal LDO regulator that must be bypassed with a  $1\mu\text{F}$  capacitor connected from the  $V_{DD}$  pin to GND. This capacitor should be as close as possible to the  $V_{DD}$  pin with a close GND connection.

#### Output Capacitor

A  $0.1\mu\text{F}$  and a  $4.7\mu\text{F}$  capacitors in parallel must be connected from this pin to ground (PGND). The trace should be made as short as practical for maximum device performance. Since the LDO has been designed to function with very low ESR capacitors, a ceramic capacitor is recommended for best performance. For better transient response increase the total amount of output capacitance. For 1-Amp load steps, an output capacitance of at least  $10\mu\text{F}$  is recommended.

### NC and DNC Pins

NC pins that are indicated as “Not Internally Connected” should be soldered to the PCB ground plane to improve thermal performance with multiple vias exiting the bottom side of the PCB. This improves heat flow away from the package and minimizes package thermal gradients.

DNC pins that are indicated as “Internally connected” must be left floating.

### PCB Layout Considerations

For optimum device performance and lowest output phase noise, IDT recommends that customers copy the reference layout used in the P9025AC-R-EVK reference kit. More information and layout files can be found at <http://www.idt.com/P9025AC-R-EVK>.

Additional layout guidelines can be found in application note [AN-889 P9025AC Layout Guidelines](#). Users are encouraged to read this document prior to starting a board design.

### Power Dissipation and Thermal Requirements

The P9025AC is offered in a VFQFPN-32 package which has a maximum power dissipation capability of about 1.9W. The maximum power dissipation is determined by the number of thermal vias between the package and the printed circuit board, combined with the ability of the board to ultimately transfer the thermal energy into the ambient environment. The maximum power dissipation is defined by the dies specified maximum operating junction temperature,  $T_J$ , of  $125^\circ\text{C}$ . The junction temperature rises when the heat generated by the device's power dissipation goes through the package thermal resistance. The VFQFPN package offers a typical thermal resistance, junction to ambient ( $\theta_{JA}$ ), of  $35^\circ\text{C/W}$  when the PCB layout and surrounding devices are optimized as described in application note [AN-889 P9025AC Layout Guidelines](#).

### Thermal Overload Protection

The P9025AC integrates thermal overload shutdown circuitry to prevent damage resulting from excessive thermal stress that may be encountered under fault conditions. This circuitry will shut down and reset the device if the die temperature exceeds  $150^\circ\text{C}$ . To allow the maximum load current on each regulator and the synchronous rectifier, and to prevent thermal overload, it is important to ensure that the heat generated by the P9025AC is dissipated efficiently into the PCB and environment.

### End of Charge (EOC)

In the event of thermal shutdown ( $150^\circ\text{C}$ ), EN, CHG\_END or TEOP pins assertion the device turns off the LDO and continually sends End Of Power (EOP) packets until the transmitter removes the power and the rectifier voltage on the receiver side drops below the UVLO threshold.

### Special Notes

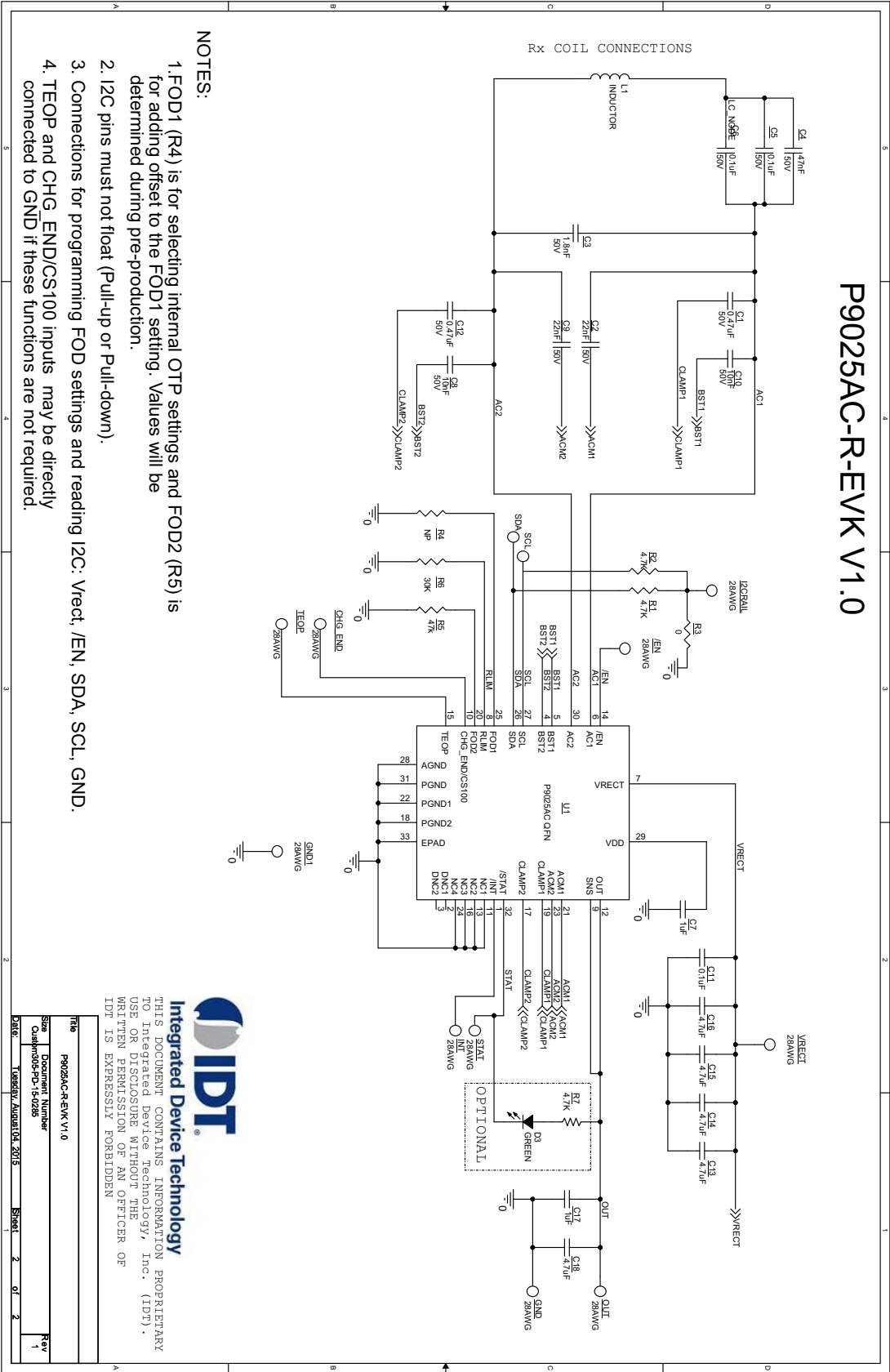
#### 32-VFQFPN Package Assembly

**Note 1:** Unopened Dry Packaged Parts have a one year shelf life.

**Note 2:** The HIC indicator card for newly-opened Dry Packaged Parts should be checked. If there is any moisture content, the parts must be baked for a minimum of 8 hours at  $125^\circ\text{C}$  within 24 hours of the assembly reflow process.

Reference Schematic (P9025AC-R-EVK V1.0)

The reference schematic bill-of-materials can be found in the P9025AC-R-EVK reference board manual.



## I<sup>2</sup>C Register Map

The P9025AC has a one-time programmable I<sup>2</sup>C address that is set to default 0X25h.

**Table 6: READ Registers – V<sub>RECT</sub> Voltage:**  $V_{RECT} = 5 \times \text{ADC1}<12:1> = [\text{ADC1}<12:1>] \times 5 \times [1.8\text{V}/2^{12}]$

Byte Address	Byte Name	Bit Field	Field Name	Type	Default Value	Description
0x40	REG0	7	ADC1<12>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x40	REG0	6	ADC1<11>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x40	REG0	5	ADC1<10>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x40	REG0	4	ADC1<9>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x40	REG0	3	ADC1<8>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x40	REG0	2	ADC1<7>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x40	REG0	1	ADC1<6>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x40	REG0	0	ADC1<5>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x41	REG1	7	ADC1<4>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x41	REG1	6	ADC1<3>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x41	REG1	5	ADC1<2>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x41	REG1	4	ADC1<1>	R		V <sub>RECT</sub> ADC code (average of 8 consecutive measurements)
0x41	REG1	3	Reserved	R		Reserved
0x41	REG1	2	Reserved	R		Reserved
0x41	REG1	1	Reserved	R		Reserved
0x41	REG1	0	Reserved	R		Reserved

**Table 7: Read Registers – I<sub>OUT</sub> Current:**

I<sub>OUT</sub> is read directly from I<sub>OUT</sub> = ADC2<12:1> = [ADC1<12:1>] X [1.8A/2<sup>12</sup>]

Byte Address	Byte Name	Bit Field	Field Name	Type	Default Value	Description
0x42	REG2	7	ADC2<12>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0x42	REG2	6	ADC2<11>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0x42	REG2	5	ADC2<10>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0x42	REG2	4	ADC2<9>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0x42	REG2	3	ADC2<8>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0x42	REG2	2	ADC2<7>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0x42	REG2	1	ADC2<6>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0x42	REG2	0	ADC2<5>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0X43	REG3	7	ADC2<4>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0X43	REG3	6	ADC2<3>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0X43	REG3	5	ADC2<2>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0X43	REG3	4	ADC2<1>	R		I <sub>OUT</sub> ADC code (average of 8 consecutive measurements)
0X43	REG3	3	Reserved	R		Reserved
0X43	REG3	2	Reserved.	R		Reserved
0X43	REG3	1	Reserved.	R		Reserved
0x43	REG3	0	Reserved.	R		Reserved

**Table 8: READ Registers - Frequency:**

$$f_{CLK} = \frac{65536}{COUNT} \quad \text{where COUNT is the decimal number represented by } \text{FREQ}\langle 10:1 \rangle.$$

Byte Address	Byte Name	Bit Field	Field Name	Type	Default Value	Description
0X44	REG4	7	FREQ<10>	R		Frequency value (10 bits)
0X44	REG4	6	FREQ<9>	R		Frequency value (10 bits)
0X44	REG4	5	FREQ<8>	R		Frequency value (10 bits)
0X44	REG4	4	FREQ<7>	R		Frequency value (10 bits)
0X44	REG4	3	FREQ<6>	R		Frequency value (10 bits)
0X44	REG4	2	FREQ<5>	R		Frequency value (10 bits)
0X44	REG4	1	FREQ<4>	R		Frequency value (10 bits)
0X44	REG4	0	FREQ<3>	R		Frequency value (10 bits)
0X45	REG5	7	FREQ<2>	R		Frequency value (10 bits)
0X45	REG5	6	FREQ<1>	R		Frequency value (10 bits)
0X45	REG5	5	Reserved	R		Reserved
0X45	REG5	4	Reserved	R		Reserved
0X45	REG5	3	Reserved	R		Reserved
0X45	REG5	2	Reserved	R		Reserved
0X45	REG5	1	Reserved	R		Reserved
0X45	REG5	0	Reserved	R		Reserved

**Table 9: READ Registers – Miscellaneous Functions**

Byte Address	Byte Name	Bit Field	Field Name	Type	Default Value	Description
0X47	REG7	3	UVLO	R		1: V <sub>RECT</sub> is higher than UVLO threshold 0: No meaning.
0X47	REG7	2	CLAMP_ON	R		0: VRECT is lower than AC clamp threshold 1: VRECT is higher than AC clamp threshold
0X47	REG7	1	LDO_CL	R		0: Normal Operation 1: LDO current limit exceeded.
0X47	REG7	0	Reserved	R		Reserved
0X48	REG8	7	CHARGE_COMPLETE	R		0: No meaning 1: Charge Complete
0X48	REG8	6	Reserved	R		Reserved
0X48	REG8	5	Reserved	R		Reserved
0X48	REG8	4	Reserved	R		Reserved
0X48	REG8	3	Reserved	R		Reserved
0X48	REG8	2	Reserved	R		Reserved
0X48	REG8	1	DIE_TEMP	R		0: Die Temperature < 150C 1: Die Temperature >150C
0x48	REG8	0	TX_TYPE	R		0: TX is WPC
0x54	REG20	[7:0]	WPC_ID_B0	R		Unique IC identifier per WPC specification
0x55	REG21	[7:0]	WPC_ID_B1	R		Unique IC identifier per WPC specification

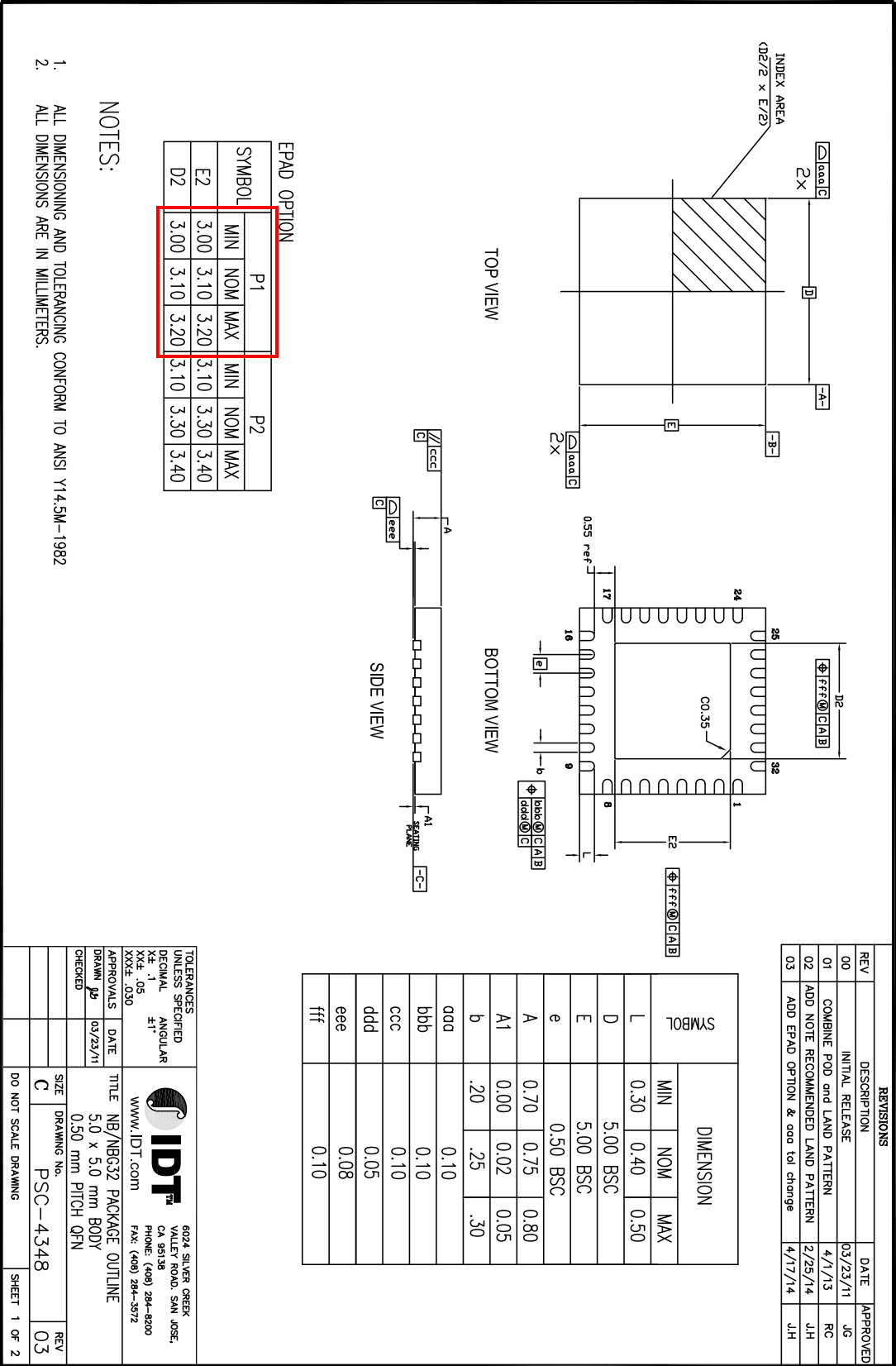


Byte Address	Byte Name	Bit Field	Field Name	Type	Default Value	Description
0x56	REG22	[7:0]	WPC_ID_B2	R		Unique IC identifier per WPC specification
0x57	REG23	[7:0]	WPC_ID_B3	R		Unique IC identifier per WPC specification
0x58	REG24	[7:0]	WPC_ID_B4	R		Unique IC identifier per WPC specification
0x59	REG25	[7:0]	WPC_ID_B5	R		Unique IC identifier per WPC specification
0x5A	REG26	[7:0]	WPC_ID_B6	R		Unique IC identifier per WPC specification
0x5B	REG27	[7:0]	Reserved	R		Reserved
0x5C	REG28	[7:0]	Reserved	R		Reserved
0x5D	REG29	[7:0]	Reserved	R		Reserved
0x5E	REG30	[7:0]	Reserved	R		Reserved
0x5F	REG31	[7:0]	Reserved	R		Reserved
0x60	REG32	[7:0]	Reserved	R		Reserved
0x61	REG33	[7:0]	Reserved	R		Reserved
0x62	REG34	[7:0]	Reserved	R		Reserved
0x63	REG35	[7:0]	Reserved	R		Reserved
0x64	REG36	[7:0]	Reserved	R		Reserved
0x65	REG37	[7:0]	Reserved	R		Reserved

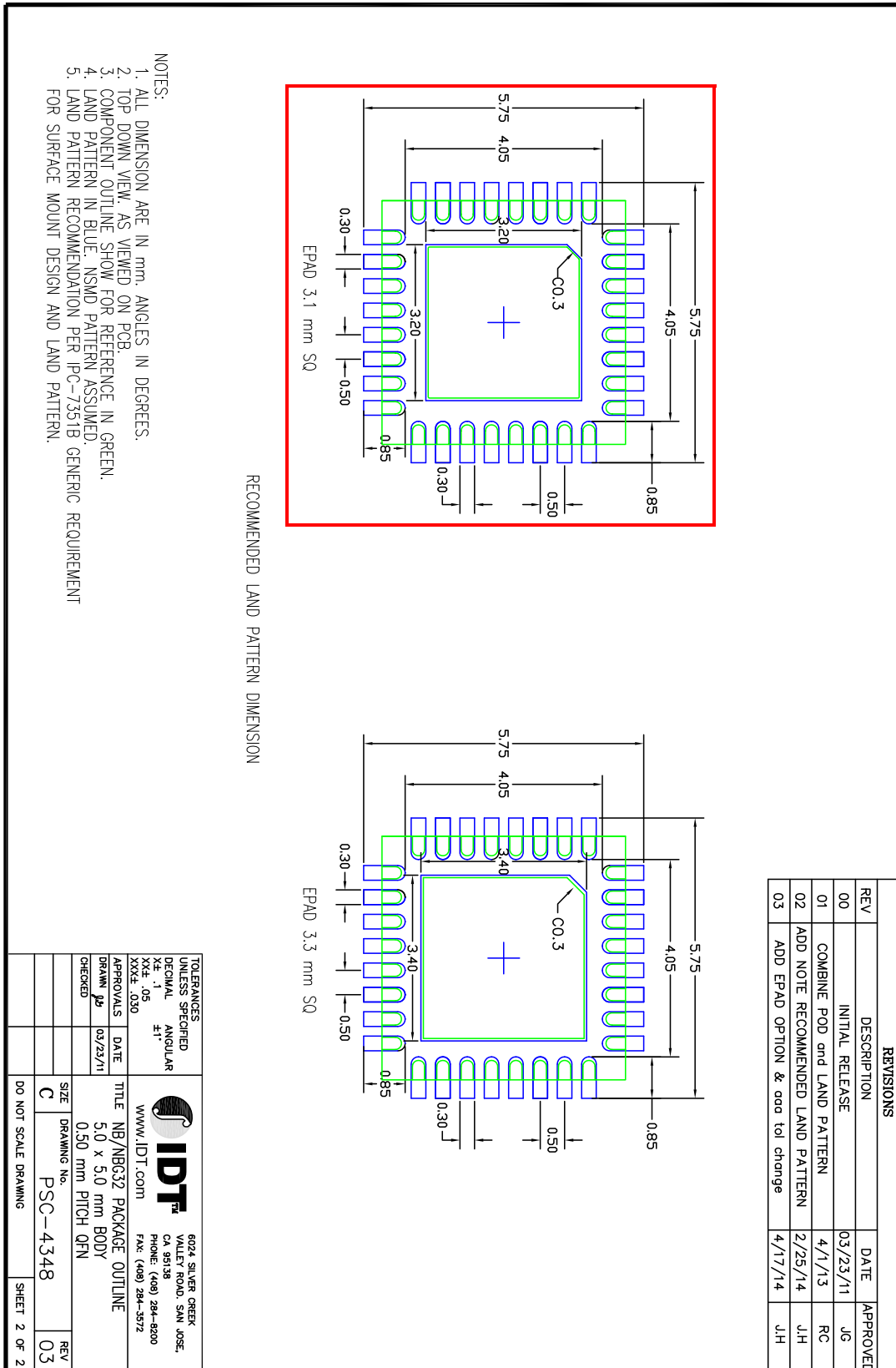
**Table 10: Read-Write physical FOD registers:**

Byte Address	Byte Name	Bit Field	Field Name	Type	Default Value	Description
0x49	REG9	0-7	FOD9<0-7>	R/W	0	mcf correction for Region 1 IO1, IO2, IO3 = 000
0x4A	REG10	0-7	FOD10<0-7>	R/W	0	bcf correction for Region 1 IO1, IO2, IO3 = 000
0x4B	REG11	0-7	FOD11<0-7>	R/W	0	mcf correction for Region 2 IO1, IO2, IO3 = 010
0x4C	REG12	0-7	FOD12<0-7>	R/W	0	bcf correction for Region 2 IO1, IO2, IO3 = 010
0x4D	REG13	0-7	FOD13<0-7>	R/W	0	mcf correction for Region 3 IO1, IO2, IO3 = 100
0x4E	REG14	0-7	FOD14<0-7>	R/W	0	bcf correction for Region 3 IO1, IO2, IO3 = 100
0x4F	REG15	0-7	FOD15<0-7>	R/W	0	mcf correction for Region 4 IO1,IO2,IO3 = 110
0x50	REG16	0-7	FOD16<0-7>	R/W	0	bcf correction for Region 4 IO1, IO2, IO3 = 110
0x51	REG17	0-7	FOD17<0-7>	R/W	0	mcf correction for Region 5 IO1, IO2, IO3 = 111
0x52	REG18	0-7	FOD18<0-7>	R/W	0	bcf correction for Region 5 IO1, IO2, IO3 = 111
0x53	REG19	0-7	FOD19<0-7>	R/W	0	bcf correction for start-up phase

Package Outline and Package Dimensions (NBG32) – use EPAD option P1



# Package Outline and Package Dimensions (NBG32), cont. Use Epad 3.1mm Sq.



## Ordering Information

Part/Order Number	Marking	Package	Shipping Packaging	Ambient Temperature
P9025AC-RNBGI	P9025AC-RNBGI	5 x 5 x 0.75 mm 32-VFQFPN	Tray	0 to +85°C
P9025AC-RNBGI8	P9025AC-RNBGI	5 x 5 x 0.75 mm 32-VFQFPN	Tape and Reel	0 to +85°C

Note 1: Custom configurations and a compact CSP package is available for qualified customers. Contact your IDT Sales Representative for more information

Note 2: Factory-customized versions are available for qualified customers. Contact your IDT Sales Representative for more information.

## Revision History

Date	Originator	Description of Change
08/19/15	A.L.	Initial release.
09/01/15	A.L.	1. Updated Block Diagram. 2. Updated T <sub>J</sub> from "0 to 150°C" to "0 to 125°C". 3. Corrected minor textual typos.



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