# **NTBA104**

# Dual supply translating transceiver; auto direction sensing; 3-state

Rev. 2 — 22 May 2012

**Product data sheet** 

### 1. General description

The NTBA104 is a 4-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features two 4-bit input-output ports (An and Bn), one output enable input ( $\overline{\text{OE}}$ ) and two supply pins ( $V_{\text{CC}(A)}$ ) and  $V_{\text{CC}(B)}$ ).  $V_{\text{CC}(A)}$  can be supplied at any voltage between 1.2 V and 3.6 V and  $V_{\text{CC}(B)}$  can be supplied at any voltage between 1.65 V and 5.5 V, making the device suitable for translating between any of the low voltage nodes (1.2 V, 1.5 V, 1.8 V, 2.5 V, 3.3 V and 5.0 V).

Pins An and  $\overline{OE}$  are referenced to  $V_{CC(A)}$  and pins Bn are referenced to  $V_{CC(B)}$ . A HIGH level at pin  $\overline{OE}$  causes the outputs to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using  $I_{OFF}$ . The  $I_{OFF}$  circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

#### 2. Features and benefits

- Wide supply voltage range:
  - ◆ V<sub>CC(A)</sub>: 1.2 V to 3.6 V and V<sub>CC(B)</sub>: 1.65 V to 5.5 V
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
  - ◆ HBM JESD22-A114E Class 2 exceeds 2500 V for A port
  - ◆ HBM JESD22-A114E Class 3B exceeds 15000 V for B port
  - MM JESD22-A115-A exceeds 200 V
  - CDM JESD22-C101E exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C



#### Dual supply translating transceiver; auto direction sensing; 3-state

# 3. Ordering information

Table 1. Ordering information

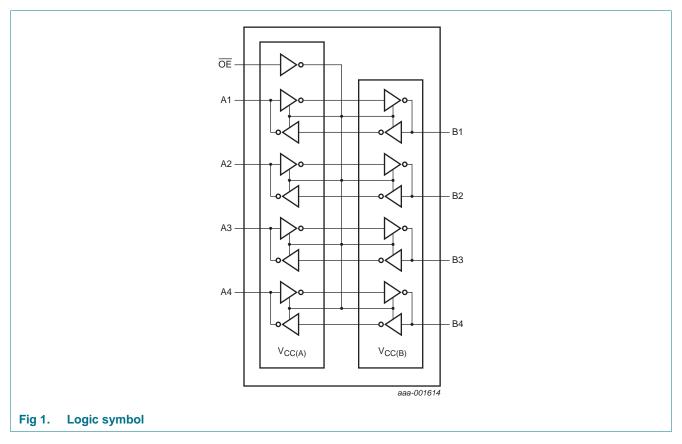
Type number	Package	Package							
	Temperature range	Name	Description	Version					
NTBA104BQ	–40 °C to +125 °C	DHVQFN14	plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 14 terminals; body $2.5\times3\times0.85$ mm	SOT762-1					
NTBA104GU16	–40 °C to +125 °C	XQFN16	plastic, extremely thin quad flat package; no leads; 16 terminals; body 1.80 x 2.60 x 0.50 mm	SOT1161-1					
NTBA104GU12	–40 °C to +125 °C	XQFN12	plastic, extremely thin quad flat package; no leads; 12 terminals; body 1.70 x 2.0 x 0.50 mm	SOT1174-1					

# 4. Marking

Table 2. Marking codes

Type number	Marking code
NTBA104BQ	BA104
NTBA104GU16	tA4
NTBA104GU12	tA

# 5. Functional diagram

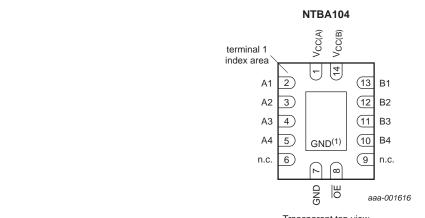


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# 6. Pinning information

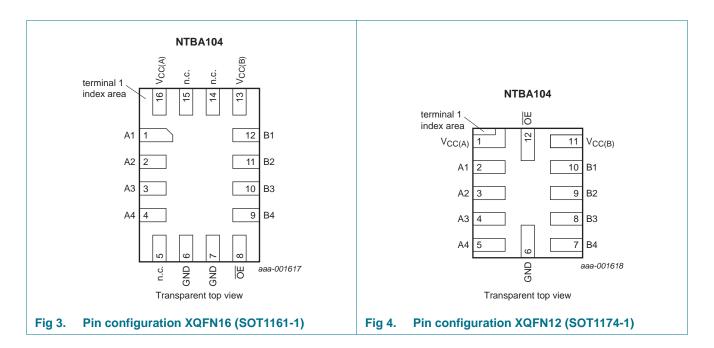
#### 6.1 Pinning



Transparent top view

(1) This is not a supply pin, the substrate is attached to this pad using conductive die attach material. There is no electrical or mechanical requirement to solder this pad however if it is soldered the solder land should remain floating or be connected to GND.

Fig 2. Pin configuration DHVQFN14 (SOT762-1)



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### 6.2 Pin description

Table 3. Pin description

Symbol	Pin			Description
	SOT762-1	SOT1161-1	SOT1174-1	
V <sub>CC(A)</sub>	1	16	1	supply voltage A
A1, A2, A3, A4	2, 3, 4, 5	1, 2, 3, 4	2, 3, 4, 5	data input or output (referenced to $V_{\text{CC(A)}}$ )
n.c.	6, 9	5, 14, 15	-	not connected
GND	7	6, 7	6	ground (0 V)
ŌĒ	8	8	12	output enable input (active LOW; referenced to $V_{\text{CC(A)}}$ )
B4, B3, B2, B1	10, 11, 12, 13	9, 10, 11, 12	7, 8, 9, 10	data input or output (referenced to $V_{\text{CC(B)}}$ )
V <sub>CC(B)</sub>	14	13	11	supply voltage B

# 7. Functional description

Table 4. Function table[1]

Supply voltage		Input	Input/output	
$V_{CC(A)}$ $V_{CC(B)}$		OE	An	Bn
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	Н	Z	Z
1.2 V to V <sub>CC(B)</sub>	1.65 V to 5.5 V	L	input or output	output or input
GND[2]	GND[2]	Χ	Z	Z

<sup>[1]</sup> H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

# 8. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
$V_{CC(A)}$	supply voltage A		-0.5	+6.5	V
V <sub>CC(B)</sub>	supply voltage B		-0.5	+6.5	V
$V_{I}$	input voltage		<u>[1]</u> -0.5	+6.5	V
V <sub>O</sub>	output voltage	Active mode	[1][2][3] -0.5	$V_{CCO} + 0.5$	V
		Power-down or 3-state mode	<u>[1]</u> -0.5	+6.5	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V	-50	-	mA
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < 0 V	-50	-	mA
Io	output current	$V_O = 0 V \text{ to } V_{CCO}$	[2] _	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>	-	100	mA
$I_{GND}$	ground current		-100	-	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C

<sup>[2]</sup> When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into power-down mode.

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Table 5. Limiting values ...continued

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
P <sub>tot</sub>	total power dissipation	$T_{amb} = -40  ^{\circ}\text{C} \text{ to } +125  ^{\circ}\text{C}$	<u>[4]</u> _	250	mW

- [1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.
- [2]  $V_{\text{CCO}}$  is the supply voltage associated with the output.
- [3]  $V_{CCO} + 0.5 \text{ V}$  should not exceed 6.5 V.
- [4] For DHVQFN14 packages: above 60 °C the value of Ptot derates linearly at 4.5 mW/K.

### 9. Recommended operating conditions

Table 6. Recommended operating conditions [1][2]

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A		1.2	3.6	V
V <sub>CC(B)</sub>	supply voltage B		1.65	5.5	V
VI	input voltage		0	5.5	V
Vo	output voltage	Power-down or 3-state mode; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$			
		A port	0	3.6	V
		B port	0	5.5	V
T <sub>amb</sub>	ambient temperature		-40	+125	°C
Δt/ΔV	input transition rise and fall rate	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	40	ns/V

<sup>[1]</sup> The A and B sides of an unused I/O pair must be held in the same state, both at V<sub>CCI</sub> or both at GND.

#### 10. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
$V_{OH}$	HIGH-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = -20 \mu\text{A}$	-	1.1	-	V
V <sub>OL</sub>	LOW-level output voltage	A port; $V_{CC(A)} = 1.2 \text{ V}$ ; $I_O = 20 \mu\text{A}$	-	0.09	-	V
II	input leakage current	OE input; $V_I = 0 \text{ V to } 3.6 \text{ V}; V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	-	±1	μΑ
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V to $V_{CCO}$ ; $V_{CC(A)} = 1.2$ V to 3.6 V; $V_{CC(B)} = 1.65$ V to 5.5 V	<u>[1]</u> _	-	±1	μΑ
I <sub>OFF</sub>	power-off leakage current	A port; $V_1$ or $V_O = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V	-	-	±1	μΑ
		B port; $V_1$ or $V_0 = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V	-	-	±1	μА

<sup>[2]</sup>  $V_{CC(A)}$  must be less than or equal to  $V_{CC(B)}$ .

#### Dual supply translating transceiver; auto direction sensing; 3-state

 Table 7.
 Typical static characteristics ...continued

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T<sub>amb</sub> = 25 °C.

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
I <sub>CC</sub>	supply current	$V_1 = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	[2]			
		$I_{CC(A)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	0.05	-	μΑ
		$I_{CC(B)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	3.3	-	μΑ
		$I_{CC(A)} + I_{CC(B)}$ ; $V_{CC(A)} = 1.2 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V	-	3.5	-	μΑ
C <sub>I</sub>	input capacitance	$\overline{\text{OE}}$ input; $V_{\text{CC(A)}} = 1.2 \text{ V}$ to 3.6 V; $V_{\text{CC(B)}} = 1.65 \text{ V}$ to 5.5 V	-	2.0	-	pF
C <sub>I/O</sub>	input/output	A port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	4.0	-	pF
	capacitance	B port; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	-	7.5	-	рF

<sup>[1]</sup>  $V_{CCO}$  is the supply voltage associated with the output.

Table 8. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C to	+85 °C	-40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
$V_{IH}$	HIGH-level	A or B port and OE input	<u>[1]</u>					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
$V_{IL}$	LOW-level	A or B port and OE input	[1]					
	input voltage	$V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
V <sub>OH</sub>	HIGH-level	$I_{O} = -20 \mu A$	[2]					
	output voltage	A port; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V}$		$V_{CCO}-0.4$	-	$V_{\text{CCO}}-0.4$	-	V
		B port; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V		$V_{CCO}-0.4$	-	$V_{\text{CCO}}-0.4$	-	V
V <sub>OL</sub>	LOW-level	I <sub>O</sub> = 20 μA	[2]					
	output voltage	A port; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V}$		-	0.4	-	0.4	V
		B port; $V_{CC(B)} = 1.65 \text{ V}$ to 5.5 V		-	0.4	-	0.4	V
I <sub>I</sub>	input leakage current	$\overline{\text{OE}}$ input; V <sub>I</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 1.2 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	±2	-	±5	μА
l <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0 \text{ V or } V_{CCO}$ ; $V_{CC(A)} = 1.2 \text{ V to } 3.6 \text{ V}$ ; $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$	[2]	-	±2	-	±10	μА
I <sub>OFF</sub>	power-off leakage	A port; $V_1$ or $V_0 = 0$ V to 3.6 V; $V_{CC(A)} = 0$ V; $V_{CC(B)} = 0$ V to 5.5 V		-	±2	-	±10	μА
	current	B port; $V_I$ or $V_O = 0$ V to 5.5 V; $V_{CC(B)} = 0$ V; $V_{CC(A)} = 0$ V to 3.6 V		-	±2	-	±10	μА

<sup>[2]</sup>  $V_{CCI}$  is the supply voltage associated with the input.

#### Dual supply translating transceiver; auto direction sensing; 3-state

**Table 8. Static characteristics** ...continued
At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		–40 °C t	o +85 °C	-40 °C to	+125 °C	Unit
				Min	Max	Min	Max	
I <sub>CC</sub>	supply current	$V_I = 0 \text{ V or } V_{CCI}; I_O = 0 \text{ A}$	<u>[1]</u>				'	
		I <sub>CC(A)</sub>						
	$\begin{aligned} &OE = HIGH; \\ &V_{CC(A)} = 1.4 \; V \; to \; 3.6 \; V; \\ &V_{CC(B)} = 1.65 \; V \; to \; 5.5 \; V \\ &OE = LOW; \\ &V_{CC(A)} = 1.4 \; V \; to \; 3.6 \; V; \\ &V_{CC(B)} = 1.65 \; V \; to \; 5.5 \; V \\ &V_{CC(A)} = 3.6 \; V; \; V_{CC(B)} = 0 \; V \\ &V_{CC(A)} = 0 \; V; \; V_{CC(B)} = 5.5 \; V \end{aligned}$	5	-	15	μΑ			
		$V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$		-	5	-	20	μА
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	2	-	15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-	-2	-	-15	μΑ
		I <sub>CC(B)</sub>						
		OE = HIGH; $V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	5	-	15	μΑ
		OE = LOW; V <sub>CC(A)</sub> = 1.4 V to 3.6 V; V <sub>CC(B)</sub> = 1.65 V to 5.5 V		-	5	-	20	μΑ
		$V_{CC(A)} = 3.6 \text{ V}; V_{CC(B)} = 0 \text{ V}$		-	-2	-	-15	μΑ
		$V_{CC(A)} = 0 \text{ V}; V_{CC(B)} = 5.5 \text{ V}$		-	2	-	15	μΑ
		$I_{CC(A)} + I_{CC(B)}$						
		$V_{CC(A)} = 1.4 \text{ V to } 3.6 \text{ V};$ $V_{CC(B)} = 1.65 \text{ V to } 5.5 \text{ V}$		-	10	-	40	μА

<sup>[1]</sup> V<sub>CCI</sub> is the supply voltage associated with the input.

# 11. Dynamic characteristics

Table 9. Typical dynamic characteristics for temperature 25 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for waveforms see Figure 5 and Figure 6.

Symbol	Parameter	Conditions	Conditions		V <sub>CC(B)</sub>				
				1.8 V	2.5 V	3.3 V	5.0 V		
$V_{CC(A)} = 1$	1.2 V; T <sub>amb</sub> = 25 °C								
$t_{pd}$	propagation delay	A to B		5.9	4.8	4.4	4.2	ns	
		B to A		5.6	4.8	4.5	4.4	ns	
t <sub>en</sub>	enable time	OE to A, B		0.5	0.5	0.5	0.5	μS	
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	9.3	9.3	9.3	9.3	ns	
		OE to B; no external load	[2]	8.7	7.7	7.6	7.1	ns	
		OE to A		81	69	83	68	ns	
		OE to B		81	69	83	68	ns	
t <sub>t</sub>	transition time	A port		4.0	4.0	4.1	4.1	ns	
		B port		2.6	2.0	1.7	1.4	ns	

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<sup>[2]</sup>  $V_{\text{CCO}}$  is the supply voltage associated with the output.

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Table 9. Typical dynamic characteristics for temperature 25 °C[1] ...continued

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for waveforms see Figure 5 and Figure 6.

Symbol	Parameter	Conditions		V <sub>CC(B)</sub>				Unit
				1.8 V	2.5 V	3.3 V	5.0 V	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	0.2	0.2	0.2	0.2	ns
t <sub>W</sub>	pulse width	data inputs		15	13	13	13	ns
f <sub>data</sub>	data rate			70	80	80	80	Mbps

 $<sup>\</sup>begin{aligned} \text{[1]} \quad & t_{pd} \text{ is the same as } t_{PLH} \text{ and } t_{PHL}. \\ & t_{en} \text{ is the same as } t_{PZL} \text{ and } t_{PZH}. \\ & t_{dis} \text{ is the same as } t_{PLZ} \text{ and } t_{PHZ}. \\ & t_{t} \text{ is the same as } t_{THL} \text{ and } t_{TLH} \end{aligned}$ 

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C[1]

Voltages are referenced to GND (ground = 0 V); for test circuit see Figure 7; for wave forms see Figure 5 and Figure 6.

Symbol	Parameter	Conditions					Vcc	C(B)				Unit
				1.8 V ±	0.15 V	2.5 V	± 0.2 V	3.3 V	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{CC(A)} =$	1.5 V ± 0.1 V											
t <sub>pd</sub>	propagation	A to B		1.4	12.9	1.2	10.1	1.1	10.0	8.0	9.9	ns
	delay	B to A		0.9	14.2	0.7	12.0	0.4	11.7	0.3	13.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.9	1.0	12.9	1.0	12.9	1.0	12.9	ns
		OE to B; no external load	[2]	1.0	18.7	1.0	15.8	1.0	15.1	1.0	14.4	ns
		OE to A		-	320	-	260	-	260	-	280	ns
		OE to B		-	-	200	-	200	-	200	-	ns
t <sub>t</sub> transition	A port		0.9	5.1	0.9	5.1	0.9	5.1	0.9	5.1	ns	
	time	B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
$t_{W}$	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbps
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V											
t <sub>pd</sub>	propagation	A to B		1.6	11.0	1.4	7.7	1.3	6.8	1.2	6.5	ns
	delay	B to A		1.5	12.0	1.3	8.4	1.0	7.6	0.9	7.1	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	11.7	1.0	11.7	1.0	11.7	1.0	11.7	ns
		OE to B; no external load	[2]	1.0	16.9	1.0	14.5	1.0	13.7	1.0	12.7	ns
		OE to A		-	260	-	230	-	230	-	230	ns
		OE to B		-	200	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		8.0	4.1	8.0	4.1	0.8	4.1	8.0	4.1	ns
time		B port		0.9	4.7	0.6	3.2	0.5	2.5	0.4	2.7	ns

<sup>[2]</sup> Delay between  $\overline{\text{OE}}$  going HIGH and when the outputs are actually disabled.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

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Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C[1] ...continued Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 7</u>; for wave forms see <u>Figure 5</u> and <u>Figure 6</u>.

Symbol	Parameter	Conditions		V <sub>CC(B)</sub>								Unit
				1.8 V ±	0.15 V	2.5 V ±	± 0.2 V	3.3 V :	± 0.3 V	5.0 V	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
$t_{W}$	pulse width	data inputs		20	-	17	-	17	-	17	-	ns
f <sub>data</sub>	data rate			-	49	-	60	-	60	-	60	Mbps
	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	6.3	1.0	5.2	0.9	4.7	ns
	delay	B to A		-	-	1.2	6.6	1.1	5.1	0.9	4.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	9.7	1.0	9.7	1.0	9.7	ns
		OE to B; no external load	[2]	-	-	1.0	12.9	1.0	12.0	1.0	11.0	ns
		OE to A		-	-	-	200	-	200	-	200	ns
		OE to B		-	-	-	200	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	0.7	3.0	0.7	3.0	0.7	3.0	ns
	time	B port		-	-	0.7	3.2	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	12	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	85	-	100	-	100	Mbps
	3.3 V ± 0.3 V											
t <sub>pd</sub>	propagation	A to B		-	-	-	-	0.9	4.7	0.8	4.0	ns
	delay	B to A		-	-	-	-	1.0	4.9	0.9	3.8	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.4	1.0	9.4	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	11.3	1.0	10.4	ns
		OE to A		-	-	-	-	-	260	-	260	ns
		OE to B		-	-	-	-	-	200	-	200	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	2.5	0.7	2.5	ns
	time	B port		-	-	-	-	0.5	2.5	0.4	2.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .  $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .

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NTBA104

 $t_{\mbox{\scriptsize dis}}$  is the same as  $t_{\mbox{\scriptsize PLZ}}$  and  $t_{\mbox{\scriptsize PHZ}}.$ 

 $t_{t}$  is the same as  $t_{\text{THL}}$  and  $t_{\text{TLH}}$ 

<sup>[2]</sup> Delay between  $\overline{\text{OE}}$  going HIGH and when the outputs are actually disabled.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 11. Dynamic characteristics for temperature range –40 °C to +125 °C[1] Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 7</u>; for wave forms see <u>Figure 5</u> and <u>Figure 6</u>.

$V_{CC(A)} = t_{pd}$	1.5 V ± 0.1 V			1 8 V +	0.45.1/			2 2 1/		E 0 1/		
	1.5 V ± 0.1 V			1.0 1	U.15 V	2.5 V	± U.2 V	3.3 V :	± 0.3 V	5.U V :	± 0.5 V	
	1.5 V ± 0.1 V			Min	Max	Min	Max	Min	Max	Min	Max	
t <sub>pd</sub>				1	•							
	propagation	A to B		1.4	15.9	1.2	13.1	1.1	13.0	8.0	12.9	ns
	delay	B to A		0.9	17.2	0.7	15.0	0.4	14.7	0.3	16.7	ns
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	13.5	1.0	13.5	1.0	13.5	1.0	13.5	ns
		OE to B; no external load	[2]	1.0	19.9	1.0	16.8	1.0	16.1	1.0	15.2	ns
		OE to A		-	340	-	280	-	280	-	300	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.9	7.1	0.9	7.1	0.9	7.1	0.9	7.1	ns
	time	B port		0.9	6.5	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	<u>[3]</u>	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		25	-	25	-	25	-	25	-	ns
f <sub>data</sub>	data rate			-	40	-	40	-	40	-	40	Mbp
V <sub>CC(A)</sub> =	1.8 V ± 0.15 V											
t <sub>pd</sub> propagation delay	A to B		1.6	14.0	1.4	10.7	1.3	9.8	1.2	9.5	ns	
	B to A		1.5	15.0	1.3	11.4	1.0	10.6	0.9	10.1	ns	
t <sub>en</sub>	enable time	OE to A, B		-	1.0	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	1.0	12.3	1.0	12.3	1.0	12.3	1.0	12.3	ns
		OE to B; no external load	[2]	1.0	18.1	1.0	15.3	1.0	14.5	1.0	13.5	ns
		OE to A		-	280	-	250	-	250	-	250	ns
		OE to B		-	220	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		0.8	6.2	0.8	6.1	0.8	6.1	0.8	6.1	ns
	time	B port		0.9	5.8	0.6	5.2	0.5	4.8	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	0.5	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		22	-	19	-	19	-	19	-	ns
f <sub>data</sub>	data rate			-	45	-	55	-	55	-	55	Mbp
V <sub>CC(A)</sub> =	2.5 V ± 0.2 V											
t <sub>pd</sub>	propagation	A to B		-	-	1.1	9.3	1.0	8.2	0.9	7.7	ns
	delay	B to A		-	-	1.2	9.6	1.1	8.1	0.9	7.4	ns
t <sub>en</sub>	enable time	OE to A, B		-	-	-	1.0	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	1.0	10.1	1.0	10.1	1.0	10.1	ns
		OE to B; no external load	[2]	-	-	1.0	13.5	1.0	12.7	1.0	11.7	ns
		OE to A		-	-	-	220	-	220	-	220	ns
		OE to B		-	-	-	220	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	0.7	5.0	0.7	5.0	0.7	5.0	ns
	time	B port		-	-	0.7	4.6	0.5	4.8	0.4	4.7	ns

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C[1] Voltages are referenced to GND (ground = 0 V); for test circuit see <u>Figure 7</u>; for wave forms see <u>Figure 5</u> and <u>Figure 6</u>.

		, , , , , , , , , , , , , , , , , , , ,										
Symbol	Parameter	Conditions		V <sub>CC(B)</sub>								Unit
				1.8 V ±	0.15 V	2.5 V ±	± 0.2 V	3.3 V =	Ŀ 0.3 V	5.0 V :	± 0.5 V	
				Min	Max	Min	Max	Min	Max	Min	Max	
$t_{sk(o)}$	output skew time	between channels	[3]	-	-	-	0.5	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs;		-	-	14	-	13	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	75	-	80	-	100	Mbps
V <sub>CC(A)</sub> =	3.3 V ± 0.3 V											
t <sub>pd</sub> propagation delay		A to B		-	-	-	-	0.9	7.7	8.0	7.0	ns
	B to A		-	-	-	-	1.0	7.9	0.9	6.8	ns	
t <sub>en</sub>	enable time	OE to A, B		-	-	-	-	-	1.0	-	1.0	μS
t <sub>dis</sub>	disable time	OE to A; no external load	[2]	-	-	-	-	1.0	9.9	1.0	9.9	ns
		OE to B; no external load	[2]	-	-	-	-	1.0	12.1	1.0	10.9	ns
		OE to A		-	-	-	-	-	280	-	280	ns
		OE to B		-	-	-	-	-	220	-	220	ns
t <sub>t</sub>	transition	A port		-	-	-	-	0.7	4.5	0.7	4.5	ns
	time	B port		-	-	-	-	0.5	4.1	0.4	4.7	ns
t <sub>sk(o)</sub>	output skew time	between channels	[3]	-	-	-	-	-	0.5	-	0.5	ns
t <sub>W</sub>	pulse width	data inputs		-	-	-	-	10	-	10	-	ns
f <sub>data</sub>	data rate			-	-	-	-	-	100	-	100	Mbps

<sup>[1]</sup>  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ .

 $t_{\text{en}}$  is the same as  $t_{\text{PZL}}$  and  $t_{\text{PZH}}.$ 

 $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ .

 $t_{t}$  is the same as  $t_{THL}$  and  $t_{TLH}$ 

<sup>[2]</sup> Delay between  $\overline{\text{OE}}$  going HIGH and when the outputs are actually disabled.

<sup>[3]</sup> Skew between any two outputs of the same package switching in the same direction.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

Table 12. Typical power dissipation capacitance

Voltages are referenced to GND (ground = 0 V).[1][2]

Symbol	Parameter	Conditions				V <sub>CC(A)</sub>				Unit
			1.2 V	1.2 V	1.5 V	1.8 V	2.5 V	2.5 V	3.3 V	
			V <sub>CC(B)</sub>							
		1.8 V	5.0 V	1.8 V	1.8 V	2.5 V	5.0 V	3.3 V to 5.0 V		
$T_{amb} = 2$	5 °C									
diss	power dissipation capacitance	outputs enabled; OE = GND								
		A port: (direction A to B)	5	5	5	5	5	5	5	pF
	capacitarice	A port: (direction B to A)	8	8	8	8	8	8	8	pF
		B port: (direction A to B)	18	18	18	18	18	18	18	pF
		B port: (direction B to A)	13	16	12	12	12	12	13	pF
		outputs disabled; $OE = V_{CC(A)}$								
		A port: (direction A to B)	0.12	0.12	0.04	0.05	0.08	0.08	0.07	pF
		A port: (direction B to A)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction A to B)	0.01	0.01	0.01	0.01	0.01	0.01	0.01	pF
		B port: (direction B to A)	0.07	0.09	0.07	0.07	0.05	0.09	0.09	pF

[1]  $C_{PD}$  is used to determine the dynamic power dissipation ( $P_D$  in  $\mu W$ ).

 $P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \Sigma (C_L \times V_{CC}^2 \times f_o)$  where:

 $f_i$  = input frequency in MHz;

 $f_o$  = output frequency in MHz;

C<sub>L</sub> = load capacitance in pF;

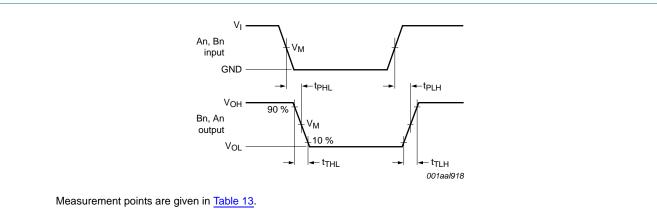
V<sub>CC</sub> = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_o)$  = sum of the outputs.

[2]  $f_i$  = 10 MHz;  $V_I$  = GND to  $V_{CC}$ ;  $t_f$  =  $t_f$  = 1 ns;  $C_L$  = 0 pF;  $R_L$  =  $\infty$   $\Omega$ .

#### 12. Waveforms



 $V_{\text{OL}}$  and  $V_{\text{OH}}$  are typical output voltage levels that occur with the output load.

Fig 5. The data input (An, Bn) to data output (Bn, An) propagation delay times

#### Dual supply translating transceiver; auto direction sensing; 3-state

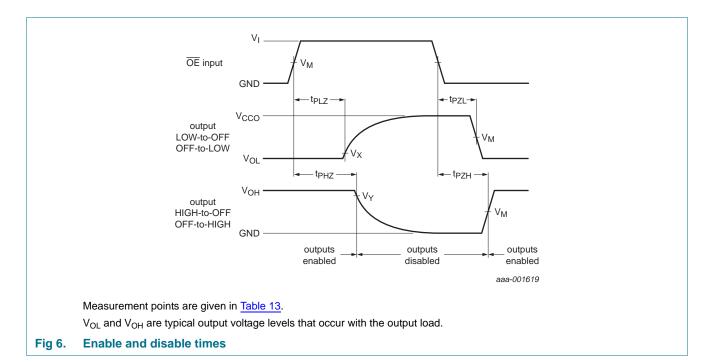
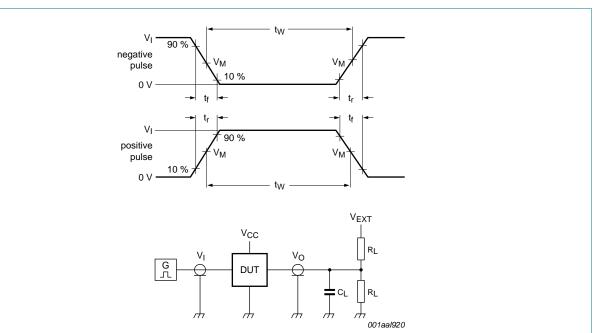


Table 13. Measurement points[1]

Supply voltage	Input	Output		
V <sub>CCO</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>
1.2 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	$V_{OH} - 0.1 V$
1.5 V $\pm$ 0.1 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> – 0.1 V
1.8 V $\pm$ 0.15 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
$2.5~\text{V} \pm 0.2~\text{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> – 0.15 V
3.3 V $\pm$ 0.3 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$
$5.0~\textrm{V} \pm 0.5~\textrm{V}$	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	$V_{OL} + 0.3 V$	$V_{OH} - 0.3 V$

<sup>[1]</sup>  $V_{CCI}$  is the supply voltage associated with the input and  $V_{CCO}$  is the supply voltage associated with the output.

#### Dual supply translating transceiver; auto direction sensing; 3-state



Test data is given in Table 14.

All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  10 MHz;  $Z_0$  = 50  $\Omega$ ;  $dV/dt \geq$  1.0 V/ns.

R<sub>L</sub> = Load resistance.

 $C_L$  = Load capacitance including jig and probe capacitance.

 $V_{\mathsf{EXT}}$  = External voltage for measuring switching times.

Fig 7. Test circuit for measuring switching times

Table 14. Test data

Supply voltage		Input		Load		V <sub>EXT</sub>			
V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	۷ <sub>ا</sub> [1]	Δt/ΔV	CL	R <sub>L</sub> [2]	$t_{PLH}$ , $t_{PHL}$	$t_{PZH}, t_{PHZ}$	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]	
1.2 V to 3.6 V	1.65 V to 5.5 V	$V_{\text{CCI}}$	$\leq$ 1.0 ns/V	15 pF	50 kΩ, 1 MΩ	open	open	2V <sub>CCO</sub>	

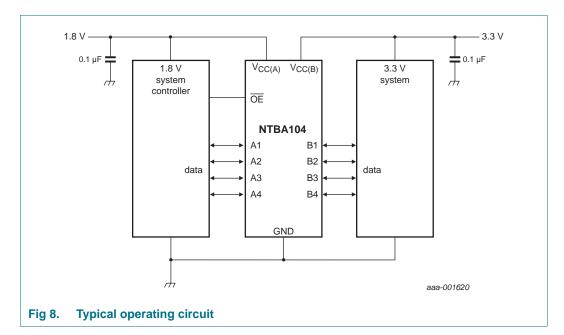
- [1]  $V_{CCI}$  is the supply voltage associated with the input.
- [2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements,  $R_L = 1 \text{ M}\Omega$ ; for measuring enable and disable times,  $R_L = 50 \text{ K}\Omega$ .
- [3]  $V_{CCO}$  is the supply voltage associated with the output.

Dual supply translating transceiver; auto direction sensing; 3-state

# 13. Application information

### 13.1 Applications

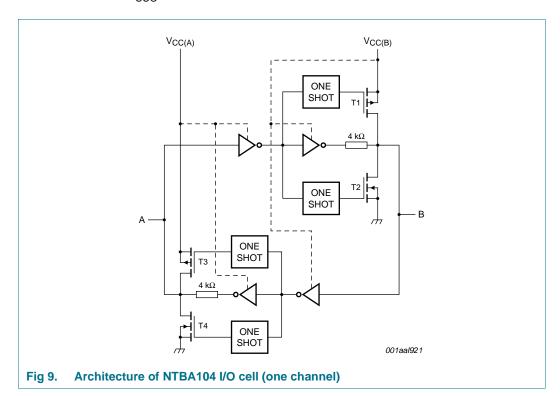
Voltage level-translation applications. The NTBA104 can be used to interface between devices or systems operating at different supply voltages. See <u>Figure 8</u> for a typical operating circuit using the NTBA104.



#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 13.2 Architecture

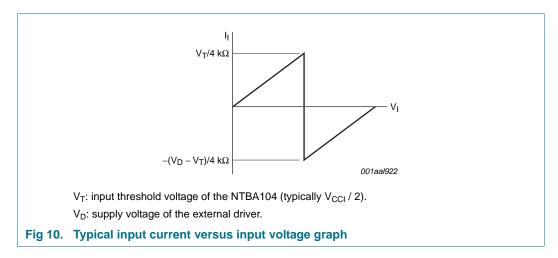
The architecture of the NTBA104 is shown in Figure 9. The device does not require an extra input signal to control the direction of data flow from A to B or from B to A. In a static state, the output drivers of the NTBA104 can maintain a defined output level, but the output architecture is designed to be weak, so that they can be overdriven by an external driver when data on the bus starts flowing in the opposite direction. The output one shots detect rising or falling edges on the A or B ports. During a rising edge, the one shots turn on the PMOS transistors (T1, T3) for a short duration, accelerating the low-to-high transition. Similarly, during a falling edge, the one shots turn on the NMOS transistors (T2, T4) for a short duration, accelerating the high-to-low transition. During output transitions the typical output impedance is 70  $\Omega$  at  $V_{\rm CCO}$  = 1.2 V to 1.8 V, 50  $\Omega$  at  $V_{\rm CCO}$  = 1.8 V to 3.3 V and 40  $\Omega$  at  $V_{\rm CCO}$  = 3.3 V to 5.0 V.



#### Dual supply translating transceiver; auto direction sensing; 3-state

#### 13.3 Input driver requirements

For correct operation, the device driving the data I/Os of the NTBA104 must have a minimum drive capability of  $\pm 2$  mA See Figure 10 for a plot of typical input current versus input voltage.



#### 13.4 Power up

During operation  $V_{CC(A)}$  must never be higher than  $V_{CC(B)}$ , however during power-up  $V_{CC(A)} \ge V_{CC(B)}$  does not damage the device, so either power supply can be ramped up first. There is no special power-up sequencing required. The NTBA104 includes circuitry that disables all output ports when either  $V_{CC(A)}$  or  $V_{CC(B)}$  is switched off.

#### 13.5 Enable and disable

An output enable input (OE) is used to disable the device. Setting OE = HIGH causes all I/Os to assume the high-impedance OFF-state. The disable time ( $t_{dis}$  with no external load) indicates the delay between when OE goes HIGH and when outputs actually become disabled. The enable time ( $t_{en}$ ) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken LOW. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to  $V_{CC(A)}$  through a pull-up resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

#### 13.6 Pull-up or pull-down resistors on I/O lines

As mentioned previously the NTBA104 is designed with low static drive strength to drive capacitive loads of up to 70 pF. To avoid output contention issues, any pull-up or pull-down resistors used must be kept higher than 50 k $\Omega$ . For this reason the NTBA104 is not recommended for use in open drain driver applications such as 1-Wire or I<sup>2</sup>C. For these applications, the NTSA104 level translator is recommended.

#### Dual supply translating transceiver; auto direction sensing; 3-state

# 14. Package outline

DHVQFN14: plastic dual in-line compatible thermal enhanced very thin quad flat package; no leads; 14 terminals; body 2.5 x 3 x 0.85 mm SOT762-1

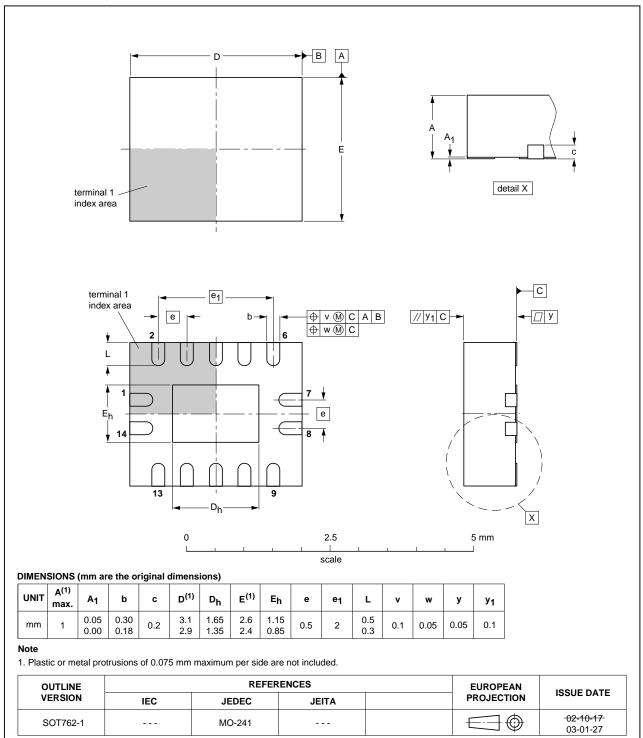


Fig 11. Package outline SOT762-1 (DHVQFN14)

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#### Dual supply translating transceiver; auto direction sensing; 3-state

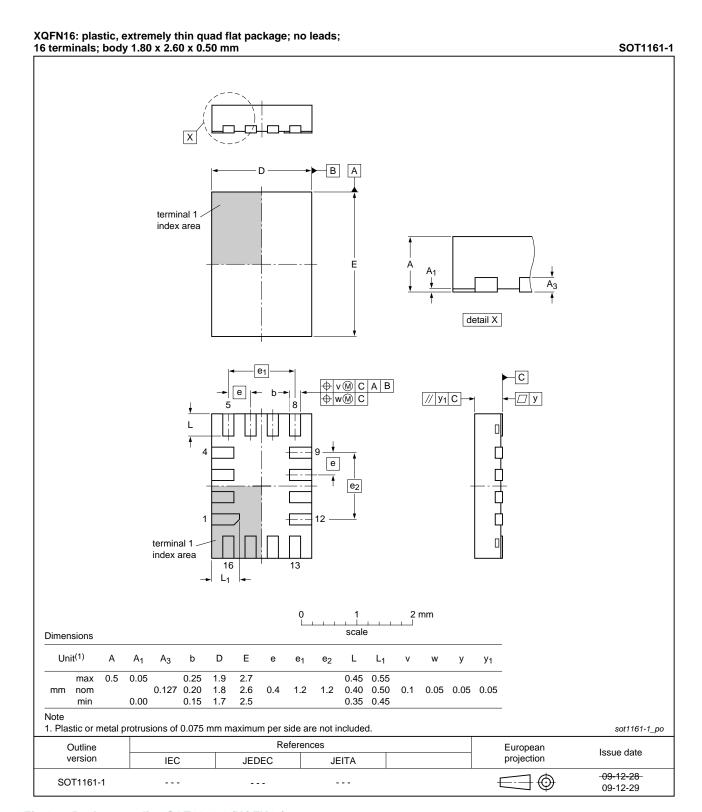


Fig 12. Package outline SOT1161-1 (XQFN16)

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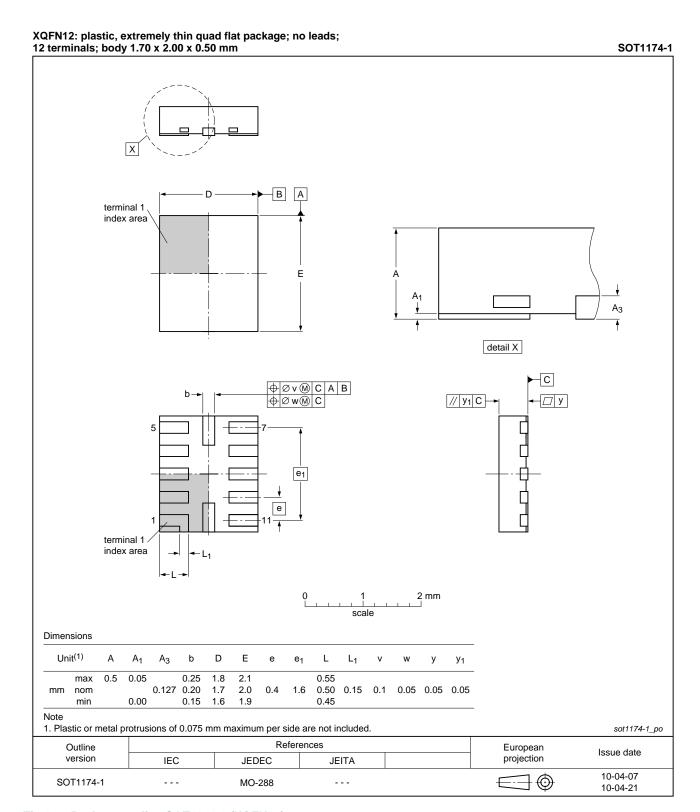


Fig 13. Package outline SOT1174-1 (XQFN12)

NTBA104

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### Dual supply translating transceiver; auto direction sensing; 3-state

# 15. Abbreviations

#### Table 15. Abbreviations

Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

# 16. Revision history

#### Table 16. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
NTBA104 v.2	20120522	Product data sheet	-	NTBA104 v.1
Modifications:	<ul> <li>Typical operation</li> </ul>	ating circuit ( <u>Figure 8</u> ) modifie	d (errata).	
NTBA104 v.1	20111206	Product data sheet	-	-

#### Dual supply translating transceiver; auto direction sensing; 3-state

### 17. Legal information

#### 17.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions"
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <a href="http://www.nxp.com">http://www.nxp.com</a>.

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#### Dual supply translating transceiver; auto direction sensing; 3-state

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#### Dual supply translating transceiver; auto direction sensing; 3-state

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