MT8924

April 1994



PCM Conference Circuit (PCC)

Preliminary Information

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- Supports up to 10 independent conferences for up to 32 PCM Voice Channels
- ST-BUS compatible 2.048 Mb/s PCM Serial Interface (also supports 1.536 Mb/s and 1.544 Mb/s data rates)
- Per channel digital gain control (0/-3/-6 dB)
- Parallel microprocessor port for device control
- Programmable noise suppression
- External Tone Input
- Pin selectable A/µ-Law format
- Low power CMOS technology
- Available in 24 Pin PDIP and SOIC packages

Applications

- Digital PBX / KTS
- Conference bridges
- Digital C.O. switches

Ordering Information MT8924AE 24 Pin Plastic DIP MT8924AS 24 Pin SOIC 0°C to +70°C

ISSUE 1

Description

The MT8924 is designed to provide conference call capability in digital switching systems. It allows up to 10 independent conferences to be set for up to 32 PCM voice channels.

 A/μ -Law companded data from the PCM input port is converted to linear format, processed by a dedicated arithmetic unit, re-converted to companded format and then sent to the PCM output port.The PCM output signal contains all the information of each channel connected in conference except its own.

Programmable attenuation and noise suppression are provided for channels connected in conference or transparent mode. Additionally, an input for an external tone is featured that can be used as a signal to indicate to connected parties that they are on a conference call.



Figure 1 - Functional Block Diagram

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www.datasheet4u.com	TD 1 TF 2 RESET 3 OS 4 DST0 5 D7 6 D6 7 D5 8 D4 9 D3 10 D2 11 D1 12	24 □VSS 23 □A/µ 22 □DSTi 21 □Cko 20 □Cki 19 □F0i 18 □WR 17 □RD 16 □CS 15 □C/D 14 □VDD 13 □D0		
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Figure 2 - Pin Connections

Pin Description

Pin #	Name	Description
1	TD	Tone Duration (Input). When TD is High, a PCM-coded tone is sent out to <u>all</u> channels of the enabled conferences instead of PCM data. TD is latched by frame pulse F0i so that all channels have the same tone during the same frame number. When TD is Low, normal operation is enabled.
2	TF	Tone Frequency (Input). This input is connected to an external squarewave generator. TF is strobed by frame pulse F0i so that all channels have the same tone frequency during the same number of frames. The PCM-coded tone level corresponds to 1/10th of the full scale value, and is activated when TD is High.
3	RESET	Master RESET (Input). This input is used for system initialization after power up, or when the companding law format has been changed. The RESET pin is strobed by the rising edge of clock Cki. Complete circuit initialization takes two frame periods. Initialization disables the output drivers of the microprocessor interface and DSTo.
4	ŌS	Overflow Signalling (Output). When \overline{OS} is Low, a conference is in the overflow condition. This signal is delayed by half of a timeslot relative to the beginning of the output channel of the conference in overflow (see Figure 9).
5	DST _o	ST-BUS Serial Output. This pin is the output for the PCM signal. It is enabled upon channel selection, otherwise it is placed in a high impedance state. Maximum bit rate is 2.048 Mb/s.
6-13	D7 to D0	Data Bus I/O Port. These are bidirectional data pins over which data and instructions are transferred to and from the microprocessor (where D0 is the least significant bit). The bus is in a high impedance state when RESET is Low and/or CS is High.
14	V _{DD}	Positive Supply Voltage. Nominally 5 volts.
15	C/D	Control/Data Select (Input). The signal on this input defines whether the information on the data bus should be interpreted as opcode or data. During a write operation a Low signal defines the bus content as data, while a High signal defines it as opcode. During a read operation this input differentiates overflow status between the first eight channels for C/D being LOW, and the last two channels for C/D being HIGH (see Instruction 4). This input also allows status monitoring (see Instruction 6) during a read operation.
16	CS	Chip Select (Input). This active low input selects the device for microprocessor read/write operations. When CS is Low, data and instructions can be transferred to or from the microprocessor, and when CS is High, the data bus is in a high impedance state.
17	RD	Read (Input). This active low input is for the read signal on the microprocessor interface. The data bus is updated on the falling edge of RD.
18	WR	Write Input. This active low input is for the write signal on the microprocessor interface. The data bus is strobed on the rising edge of \overline{WR} .

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Pin Description (continued)

	Pin #	Name	Description
/w.datashi	19 ₂et4u.com	F0i	Frame Pulse (Input). This is an 8 kHz active low input used for frame synchronization of the PCM bit stream. The first falling edge of Cki following the falling edge of frame pulse F0i determines the start of a new frame and must correspond to the first bit of the first channel. When PCM frames of 1544 kbit/s are used, the rising edge of F0i must correspond to the Extra (193rd) bit.
	20	Cki	Clock (Input). This signal is the timing reference used for all internal operations. The PCM bit cell boundaries lie on the alternate falling edges of this clock. The maximum allowable clock frequency is 4096 kHz.
	21	Cko	Clock (Output). This pin provides the master clock for a digital crosspoint switch (e.g., MT898x series, or the MT9080, MT9085 combination). Normally the signal on this pin is identical to Cki. When Extra bit operating mode is selected (see Instruction 5), the first two cycles of the master clock are suppressed (see Figure 10). This feature allows the MT8924 to operate in 1544 kbit/s systems.
	22	DST _i	ST-BUS Serial Input. This pin accepts the serial PCM input stream at a maximum allowable bit rate of 2048 kbit/s. In normal operation the first bit of the first channel is defined by the rising edge of Cki following the falling edge of frame pulse F0i. When Extra bit operating mode is selected, the first bit of the first channel defines the extra bit.
	23	A/µ	A/μ - Law Select Input. When A/μ is High, A-Law is selected, and when A/μ is Low, μ -Law is selected. The companding law selection must be done before initializing the device using the RESET pin.
	24	V _{SS}	Negative Power Supply Voltage. Nominally 0 Volts.

Functional Description

The MT8924 is a device designed to provide conferencing in a digital switching system in any combination for up to all 32 channels of a 2048 kbit/s ST-BUS stream (see Figure 3).

The information of channel N, frame M is first converted to Linear PCM and then added to the signal from other conferencees during the first half of



Figure 3 - Typical Conference Connection

channel N+1, frame M and subtracted during the second half of channel N-1, frame M+1. After Linear-to-PCM conversion the subtraction result goes to the parallel-to-serial converter, and appears at the output on the N+1 channel, M+1 frame with respect to the corresponding sending party information (see Figure 4).

To a microprocessor the MT8924 appears as a memory mapped peripheral device that can be controlled by a set of six instructions. These commands can be used to establish or cancel conferences between the PCM channels and also to transmit control messages on specific operating modes. The microprocessor can initiate and receive status messages or check conference connections that are currently in operation.



Figure 4 - Input/Output Channel Relationship www.DataSheet4U.com

	Noise	PCM Byte						
	Threshold	+ve input	-ve input					
		B7 - B0	B7 - B0					
A-Law	1/4096	1000 0000	0000 0000					
	9/4096	1000 0100	0000 0100					
	16/4096	1000 1000	0000 1000					
	32/4096	1000 1111	0000 1111					
μ-Law	1/8159	1111 1111	0111 1111					
	9/8159	1111 1011	0111 1011					
	16/8159	1111 0111	0111 0111					
	32/8159	1111 0000	0111 0000					

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Table 1 -	PCM N	oise Sunn	ression Th	reshold	l evels
		use supp		liesiioiu	

Overflow Detection / Input Channel Attenuation

If the sum of the channels involved in one conference exceeds the full scale value of the accumulator, an overflow condition is generated which can be monitored specifically by reading the status of the overflow register. If an overflow condition occurs, then each channel in a conference can be independently attenuated if desired. Alternatively, a conference in the overflow condition can be detected using the OS signal in conjunction with frame pulse F0i. OS will be low during the second half of a general output channel slot time N, if channel N belongs to a conference in overflow (see Figure 11). This information can be used to control input channel attenuation through software control.

F1	F0		B7	B6	B5	B4	B3	B2	B1	B0	Comments
0	0	+ Full Scale	1	1	1	1	1	1	1	1	No Inversion
		+ 0 Level	1	0	0	0	0	0	0	0	
		- 0 Level	0	0	0	0	0	0	0	0	
		- Full Scale	0	1	1	1	1	1	1	1	
0	1	+ Full Scale	1	0	1	0	1	0	1	0	Even Bit Inversion
		+ 0 Level	1	1	0	1	0	1	0	1	
		- 0 Level	0	1	0	1	0	1	0	1	
		- Full Scale	0	0	1	0	1	0	1	0	
1	0	+ Full Scale	1	1	0	1	0	1	0	1	Odd Bit Inversion
		+ 0 Level	1	0	1	0	1	0	1	0	
		- 0 Level	0	0	1	0	1	0	1	0	
		- Full Scale	0	1	0	1	0	1	0	1	
1	1	+ Full Scale	1	0	0	0	0	0	0	0	Bit Inversion
		+ 0 Level	1	1	1	1	1	1	1	1	
		- 0 Level	0	1	1	1	1	1	1	1	
		- Full Scale	0	0	0	0	0	0	0	0	

Table 2 - PCM Byte Format

B7 (sign bit) is the MSB and B0 is the LSB F1-F0 corresponds to the D5-D4 bits of the control byte of Operating Mode Instruction 5

Noise Suppression

When noise suppression is enabled for a specific input channel then the PCM bytes for this channel, when below the selected threshold level, are converted to PCM bytes corresponding to the minimum PCM code level before being added to the www.datashconference sum.

The four threshold levels available correspond to the first, fifth, ninth and sixteenth step of the first segment. These are 1/4096, 9/4096, 16/4096, and 32/4096 with respect to full scale A-Law, and 1/8159, 9/8159, 16/8159, and 32/8159 with respect to full scale μ -Law (see Table 1).

PCM Format Selection

PCM digital code assignment is register programmable and achieved through the use of Instruction 5 (see Table 2). The available formats are CCITT G.711 A-Law or μ -Law, with true-sign Alternate Digit Inversion or true-sign/Inverted Magnitude coding.

Output clock Cko provides a reference time base for a digital time/space crosspoint switch. Normally this signal is identical to the master clock input Cki. When operating with the extra bit selection, through Instruction 5, Cko is low for two clock periods, which allows operation of the MT8924 with the 1.544 MHz PCM frame format (see Figure 10).

Transparent Mode

The MT8924 can operate in transparent mode. In this case the PCM input (DSTi) is passed unmodified through the MT8924 to the output (DSTo) with a delay of one frame and one channel. This feature allows attenuation of specific channels that are not connected to a conference.

Tone Insertion

The MT8924 provides for tone insertion into PCM output channels by using the two input pins TD and TF. An externally generated square wave tone applied to the TF input will generate a level corresponding to 1/10 of the full scale accumulator value when TD is High. Only channels connected in a conference with the insertion tone bit (IT) active will have the PCM coded tone at their output (see Instruction 1).

Testing and Diagnostic Feature

For testing and diagnostic purposes, a status instruction has been provided that indicates conference location and attenuation level for each channel requested. This data appears on the databus upon status request.

Programmable Control

Instruction 1 : Conference Mode Connection

This function connects a PCM channel to a conference. The control information from the microprocessor consists of two data bytes and one control byte. The first byte contains the conference number (bits D0-D3) and the Start bit S (D4). When S is High, the accumulator registers connected to a conference are initialized. S set to High is only required in Instruction 1 of the first channel connected to a new conference, otherwise S is set LOW to bring other channels into the conference. The second byte contains the number of the channel to be connected (D0-D4), and the Insert Tone Enable bit IT (D5). When IT and TD are both High all the channels belonging to that conference are enabled using the insert tone function. The third byte contains a four bit opcode (D0-D3) plus information about the attenuation level and noise suppression to be applied to the specific channel.

Instruction 2 : Transparent Mode Connection

This function sets up a PCM channel for transparent mode operation. The control information from the microprocessor consists of one data byte and one control byte.

The first byte contains the channel number, and the second byte contains a four bit opcode (D0-D3) and information about attenuation and noise suppression levels to be applied to the specific channel. PCM data on this channel is not added to any conference, but is transferred to the PCM output after a full frame pulse plus one channel delay. It is not affected by the tone control pins (TF, TD).

Instruction 3 : Disconnection

This function disconnects a PCM channel from a conference. The control information from the microprocessor consists of one data byte and one

control byte. The data byte contains the number of the channel to be disconnected. The second byte contains the opcode (D0-D3). One frame pulse must pass between disconnection and reconnection of the same channel.

Instruction 4 : Overflow Status Monitoring

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This function extracts overflow status information on all existing conferences and transfers it to the microprocessor data bus. This instruction consists of two control bytes which are differentiated by the C/\overline{D} control signal. C/\overline{D} set Low reads the status of the first eight conferences, while C/\overline{D} set High reads the status of the remaining two conferences. A conference is in overflow when the corresponding status bit is high.

Instruction 5 : PCM Mode Select

This function is used to set the PCM format. The control byte from the microprocessor consists of one data byte. It contains the Extra Bit E (D6), the Format Bits F1-F0 (D5, D4), and the opcode (D0-D3). The E bit must be high when the PCM frame contains an extra bit (i.e. 1.544 Mb/s). Normally E is Low. Bits F1-F0 are used to select the PCM byte format, according to Table 2. After RESET the default values correspond to F1 at Low and F0 at High if A-Law is selected, and F1 at High and F0 at High if µ-Law is selected. All channels must be disconnected when the PCM mode select instruction is sent. They must remain disconnected for at least two frame pulses after the instruction is sent. It is recommended that this instruction be used immediately following a system reset (see RESET pin description).

Instruction 6 : Status Monitoring

This function is a read operation which consists of a data byte, a control byte, and a status byte. It extracts information for test and diagnostic purposes and transfers it to the microprocessor bus. The first byte contains the channel number, while the second byte contains the opcode (D0-D3). The third byte contains the status information about the operating mode of the channel (D4-D7); the attenuation level (D2-D3); and the noise suppression level (D0-D1).

	С	ontrol	Signa	ls				Data	Bus				Comments
	CS	RD	C/D	WR	D7	D6	D5	D4	D3	D2	D1	D0	
	0	1	0	0	Х	Х	Х	S	P3	P2	P1	P0	Conference Number
www.datash	eet4µ.co 0	^m 1	0	0	Х	Х	IT	C4	C3	C2	C1	C0	PCM Channel Number and Insertion Tone control
	0	1	1	0	A1	A0	T1	Т0	0	1	1	1	Opcode, Attenuation, and Noise Suppression control
	S: P3-P0 IT: C4-C0 A1-A0	: :	Confe Confe Inser Chan Chan	erence S erence N tion Ton- inel Num inel Atte 00 = -0d 01 = -3d 10 = -6d	Start Bit Number e Function bber (0-3 nuation B B B B	(1-10) on Enab 31)	le (IT=1)	T,	1-T0: <u>T1/T(</u> 00 01 10 11	<u>2</u>	Channel <u>A-La</u> no r 9/40 16/4 32/4	Noise Suppression <u>aw µ-Law</u> loise suppression 196 9/8159 1096 16/8159 1096 32/8159

Instruction 1 : Channel Connection in Conference Mode

Instruction 2 : Channel Connection in Transparent Mode

Control Signals Data Bus										Comments		
CS	RD	C/D	WR	D7	D6	D5	D4	D3	D2	D1	D0	
0	1	0	0	Х	Х	Х	C4	C3	C2	C1	C0	PCM Channel Number
0	1	1	0	A1	A0	T1	Т0	0	0	1	1	Opcode and Attenuation

T1-T0: see noise suppression description given for Instruction 1

Instruction 3 : Channel Disconnection

С	Control Signals Data Bus										Comments	
CS	RD	C/D	WR	D7	D6	D5	D4	D3	D2	D1	D0	
0	1	0	0	Х	Х	Х	C4	C3	C2	C1	C0	PCM Channel Number
0	1	1	0	Х	Х	Х	Х	1	1	1	1	Opcode

Instruction 4: Overflow Status Monitoring

Control Signals Dat												Comments
CS	RD	C/D	WR	D7	D6	D5	D4	D3	D2	D1	D0	
0	0	0	1	CF 8	CF 7	CF 6	CF 5	CF 4	CF 3	CF 2	CF 1	Conferences 1 to 8
0	0	1	1	Х	Х	Х	Х	Х	Х	CF 10	CF 9	Conferences 9 to 10

CF10 - CF1 : Conference is in overflow when bit is HIGH

Note : as long as RD remains LOW, the overflow status of the conference selected by C/D can be monitored in real time

Instruction 5 : PCM Operating Mode Selection

	Control Signals Data Bus										Comments	
CS	RD	C/D	WR	D7	D6	D5	D4					
0	1	1	0	Х	Е	F1	F0	0	1	0	1	see Table 1

www.et. datas Extra bit insertion (active when E=1)

F1 - F0: PCM byte format selection (see Table 1)

00 = no bit inverted

01 = even bit (B0, B2, B4, B6) inverted

10 = odd bit (B1, B3, B5) inverted

11 = all bits (B0, B1, B2, B3, B4, B5, B6) inverted

Instruction 6 : Status Monitoring

Control Signals Data												Comments
CS	RD	C/D	WR	D7	D6	D5	D4	D3	D2	D1	D0	
0	1	0	0	Х	Х	Х	C4	C3	C2	C1	C0	
0	1	1	0	Х	Х	Х	Х	0	1	1	0	
0	0	1	1	P3	P2	P1	P0	A1	A0	T1	Т0	
P3 - P0: channel mode operation information 0000 = no connection 1111 = transparent mode 1010 - 0001 = conference mode										:	see char for Instru see noise for Instru	nel attenuation description ction 1 e suppression description ction 1

P3 - P0 provides conference number

Note: Instruction 6 enables the data bus to read the status until reset by $C/\overline{D}=0$, $\overline{WR}=1$, and $\overline{CS}=0$

Absolute Maximum Ratings*

		Parameter	Symbol	Min	Max	Units
	1	Supply Voltage	V_{DD} - V_{SS}	- 0.3	7	V
	2	Voltage on any I/O pin	V _{I/O}	V _{SS} - 0.3	V _{DD} + 0.3	V
www.datash	eet 3 u.co	Current on any I/O pin	I _{I/O}		± 10	mA
	4	Storage Temperature	T _{ST}	- 65	+ 150	°C
	5	Power Dissipation (plastic package)	P _D		500	mW

* Exceeding these figures may cause permanent damage. Functional operation under these conditions is not guaranteed.

Recommended Operating Conditions

	Characteristics	Sym	Min	Тур*	Max	Units	Test Conditions
1	Supply Voltage	V_{DD}	4.75	5	5.25	V	
2	Ambient Operating Temp. Range	T _{OP}	0		+70	°C	
3	Input Voltage High	V _{IH}	2.4		V _{DD}	V	for 400mv noise margin
4	Input Voltage Low	V _{IL}	V_{SS}		0.8	V	

* Typical figures are at 25°C and are for design aid only; not guaranteed and not subject to production testing.

DC Characteristics: Clocked operation (T_{OP}=0 to 70°C; V_{DD}=5V±5%)

	Characteristics	Sym	Min	Тур	Max	Units	Test Conditions
1	Input Low Level	V _{IL}			0.8	V	Pins 1-3, 6-13, 15-20, 22-23
2	Input High Level	V _{IH}	2.0			V	Pins 1-3, 6-13, 15-20, 22-23
3	Output Low Level	V _{OL}			0.4	V	Pins 4, 6-13; I _{OL} =4 mA
4	Output High Level	V _{OH}	2.4			V	Pins 4, 6-13; I _{OL} =4 mA
5	Output Low Level	V _{OL}			0.4	V	Pins 5, 21; I _{OL} =8 mA
6	Input Leakage Current	I			10	μA	Pins 1-3, 6-13, 15-20, 22-23; V _{IN} =0 to V _{DD}
7	Data Bus Leakage Current	I _{OL}			±10	μA	$\frac{\text{Pins 6-13; V}_{\text{IN}}=0 \text{ to V}_{\text{DD}};}{\text{CS}=\text{V}_{\text{DD}}}$
8	Supply Current	I _{DD}			10	mA	Pin 14; Cki=4.096 MHz

All DC characterisitics are valid 250 μs after V_{DD} and C4i have been applied.

AC Electrical Characteristics - Capacitances

	Characteristics	Sym	Min	Тур	Max	Units	Test Conditions
1	Input Capacitance	CI			5	pF	frequency=1MHz; T _{OP} =0
2	I/O Capacitance (Bidirectional)	C _{I/O}			15	pF	to 70°C; unused pins tied to Vas:
3	Output Capacitance	Co			10	pF	V_{DD} =5V±5%

AC Electrical Characteristics - Clocke	J Timing* (T _{OP} =0 to 70°C; V _{DD} =5V±5%)
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]		Characteristics	Sym	Min	Тур	Max	Units	Test Conditions
	1	Clock period	t _{CK}	230			ns	
	2	Clock low level width	t _{WLCK}	100			ns	
	3	Clock high level width	t _{WHCK}	100			ns	
WV	4	Clock rise time	t _{RCK}			25	ns	
	5	Clock fall time	t _{FCK}			25	ns	
	6	Sync. low setup time	t _{SLSY}	50			ns	**
	7	Sync. low level hold time	t _{HLSY}	40			ns	
	8	Sync. high setup time	t _{SHSY}	80			ns	
	9	Sync. high width	t _{WHSY}	t _{CK}			ns	
	10	OS propagation delay from rising edge of Clock	t _{PDOS}			100	ns	C _L =50pF
	11	Cko propagation delay to Clock edges	t _{PDEC}			80	ns	C _L =50pF
	12	TD setup time	t _{STD}	80			ns	
	13	TD hold time	t _{HTD}	40			ns	
1	14	TD setup time	t _{STF}	80			ns	
	15	TD hold time	t _{HTD}	40			ns	

* All AC characteristics are valid 250μs after V_{DD} and the clock have been applied. C_L is the max. capacitive load and R_L is the test pull up resistor. With Extra Bit Insert operating mode these times are 80ns longer.

** With Extra Bit Insert operating mode this time becomes $\mbox{3t}_{\mbox{CK}}$



Figure 5 - Clock Timing

				U V OF		, 00	,	
		Characteristics	Sym	Min	Тур	Max	Units	Test Conditions
	1	Input PCM setup time	t _{SPCM}	80			ns	
	2	Input PCM hold time	t _{HPCM}	35			ns	
www.datash	eet 4 u.c	Output PCM propagation delay	t _{PD}	25		125	ns	C_L =150pF, R _L =1K Ω in 2.048MHz mode **

AC Electrical Characteristics - PCM Timing* (T_{OP}=0 to 70°C; V_{DD}=5V±5%)

*All AC characteristics are valid 250 μ s after V_{DD} and the clock have been applied. C_L is the max. capacitive load and R_L is the test pull up resistor.

**With Extra Bit Insert operating mode these times are 80ns longer.



Figure 6 - PCM Timing

AC Electrical Characteristics - RESET Timing* (T_{OP}=0 to 70°C; V_{DD}=5V±5%)

	Characteristics	Sym	Min	Тур	Max	Units	Test Conditions
1	RESET low setup time	t _{SLRES}	100			ns	
2	RESET low hold time	t _{HLRES}	50			ns	
3	RESET high setup time	t _{SHRES}	90			ns	
4	RESET high level width	t _{WHRES}	t _{CK}			ns	

* All AC characteristics are valid 250 μ s after V_{DD} and the clock have been applied. C_L is the max. capacitive load and R_L is the test pull up resistor.



Figure 7 - Reset Timing

		Characteristics	Sym	Min	Тур	Max	Units	Test Conditions
	1	Write Pulse low width	t _{WLWR}	150			ns	
	2	Write Pulse high width	t _{WHWR}	200			ns	
VV V	w. 3 ata	Repetition Interval between active Write Pulses	t _{REPWR}	500			ns	
	4	Read high setup time to active Write Pulse	t _{SHRD}	0			ns	
ſ	5	Read high hold time from active Write Pulse	t _{HHRD}	20			ns	
	6	Write Pulse rise time	t _{RWR}	60			ns	
	7	Write Pulse fall time	t _{FWR}	60			ns	
	8	$\overline{\text{CS}}$ low setup time to $\overline{\text{WR}}$ falling edge	t _{SLCSWR}	0			ns	Active case
	9	$\overline{\text{CS}}$ low hold time from $\overline{\text{WR}}$ falling edge	t _{HLCSWR}	0			ns	Active case
	10	$\overline{\text{CS}}$ high setup time to $\overline{\text{WR}}$ rising edge	t _{SHCSWR}	0			ns	
	11	$\overline{\text{CS}}$ high hold time from $\overline{\text{WR}}$ rising edge	t _{HHCSWR}	0			ns	
	12	C/\overline{D} setup time to Write Pulse end	t _{SC/DWR}	130			ns	
	13	C/\overline{D} hold time from Write Pulse end	t _{HCDWR}	25			ns	
	14	Input setup time to Write Pulse end	t _{SDWR}	130			ns	
	15	Input hold time from Bus Write Pulse end	t _{HDWR}	25			ns	

AC Electrical Characteristics - Write Timing (T_{OP}=0 to 70°C; V_{DD}=5V±5%)



Figure 8 - Write Timing Characteristics

		Characteristics	Sym	Min	Тур	Max	Units	Test Conditions
Γ	1	Read Pulse low width	t _{WLRD}	180			ns	
Γ	2	Read Pulse high width	t _{WHRD}	200			ns	
www.datashee	et431.co	Repetition Interval between active Read Pulses	t _{REPRD}	500			ns	
	4	Write high setup time to active Read Pulse	t _{SHWR}	0			ns	
	5	Write high hold time from active Read Pulse	t _{HHWR}	20			ns	
	6	Read Pulse rise time	t _{RRD}			60	ns	
	7	Read Pulse fall time	t _{FRD}			60	ns	
	8	Low setup time to \overline{RD} falling edge	t _{SLCSRD}	0			ns	Active case
	9	Low hold time from \overline{RD} falling edge	t _{HLCSRD}	0			ns	Active case
	10	High setup time to \overline{RD} falling edge	t _{SHCSRD}	0			ns	Active case
	11	High hold time from \overline{RD} rising edge	t _{HHCSRD}	0			ns	Active case
	12	C/\overline{D} setup time to \overline{RD} Pulse start	t _{SCDRD}	20			ns	
	13	Hold time from Read Pulse end	t _{HCDRD}	25			ns	
	14	Propagation delay from falling edge of Read Pulse	t _{PDD}			120	ns	Read; C _L =200pF
	15	Propagation delay from rising edge of Read Pulse to high impedance state	t _{HZ}			80	ns	Write; C _L =200pF

AC Electrical Characteristics - Read Timin	ng (T _{OP} =0 to 70°C; V _{DD} =5V±5%)
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Figure 10 - CKo Timing with Extra Bit Insertion Mode



Figure 11 - OS Timing with Output PCM Channel belonging to a Conference in Overflow