



General Description

The MAX1219 dual, monolithic, 12-bit, 210Msps analogto-digital converter (ADC) provides outstanding dynamic performance up to a 250MHz input frequency. The device operates with conversion rates up to 210Msps while consuming only 800mW per channel.

At 210Msps and an input frequency of 200MHz, the MAX1219 achieves a 79dBc spurious-free dynamic range (SFDR) with excellent 65.5dB signal-to-noise ratio (SNR) at 200MHz. The SNR remains flat (within 3dB) for input tones up to 250MHz. This makes the MAX1219 ideal for wideband applications such as communications receivers, cable head-end receivers, and power-amplifier predistortion in cellular base-station transceivers.

The MAX1219 operates from a single 1.8V power supply. The analog inputs of each channel are designed for AC-coupled, differential or single-ended operation. The ADC also features a selectable on-chip divide-by-2 clock circuit that accepts clock frequencies as high as 420MHz and reduces the phase noise of the input clock source. A low-voltage differential signal (LVDS) sampling clock is recommended for best performance. The converter's digital outputs are LVDS compatible and the data format can be selected to be either two's complement or offset binary.

The MAX1219 is available in a 100-pin TQFP package with exposed paddle and is specified over the extended (-40°C to +85°C) temperature range. Refer to the MAX1218 (170Msps) and the MAX1217 (125Msps) data sheets for lower speed, pin-compatible devices.

Applications

Cable Modem Termination Systems (CMTS) Cable Digital Return Path Transmitters Cellular Base-Station Power-Amplifier Linearization IF and Baseband Digitization ATE and Instrumentation Radar Systems

Features

- **♦ 210Msps Conversion Rate**
- **♦ Excellent Low-Noise Characteristics** SNR = 66.6dB at $f_{IN} = 100MHz$ SNR = 65.5dB at $f_{IN} = 200MHz$
- **♦ Excellent Dynamic Range** SFDR = 81dBc at f_{IN} = 100MHz SFDR = 79dBc at f_{IN} = 200MHz
- ♦ Single 1.8V Supply
- **♦** 1.6W Power Dissipation at fSAMPLE = 210Msps and fin = 10MHz
- ♦ On-Chip Track-and-Hold Amplifier
- ♦ Internal 1.24V Bandgap Reference
- ♦ On-Chip Selectable Divide-by-2 Clock Input
- ♦ LVDS Digital Outputs with Data Clock Output
- **♦ EV Kit Available (Order MAX1219EVKIT)**

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE	PKG CODE
MAX1219ECQ	-40°C to +85°C	100 TQFP-EP*	C100E-6

^{*}EP = Exposed paddle.

Pin-Compatible Versions

PART	RESOLUTION (BITS)	SPEED GRADE (Msps)
MAX1219	12	210
MAX1218	12	170
MAX1217	12	125

Pin Configuration appears at end of data sheet.



ABSOLUTE MAXIMUM RATINGS

AVCC to AGND	0.3V to +2.1V
OV _{CC} to OGND	0.3V to +2.1V
OVCC to AVCC	0.3V to +0.3V
OGND to AGND	0.3V to +0.3V
CLKP, CLKN, INAP, INAN, INBP,	
INBN to AGND	0.3V to (AV _{CC} + 0.3V)
CLKDIV, T/BA, T/BB to AGND	0.3V to $(AV_{CC} + 0.3V)$
REFA, REFADJA, REFB, REFADJB	
to AGND	0.3V to (AV _{CC} + 0.3V)
DCOP, DCON, DA0P-DA11P, DA0N-DA	A11N,
DB0P-DB11P, DB0N-DB11N, ORAP,	ORAN,
ORBP, ORBN to OGND	$-0.3V$ to $(OV_{CC} + 0.3V)$

Current into any Pin50mA
ESD Voltage on INAP, INAN, INBP, INBN
(Human Body Model)±750V
ESD Voltage on All Other Pins (Human Body Model)±2000V
Continuous Power Dissipation $(T_A = +70^{\circ}C)$
100-Pin TQFP (derate 37mW/°C above +70°C)2963mW
Operating Temperature Range40°C to +85°C
Storage Temperature Range65°C to +150°C
Junction Temperature+150°C
Lead Temperature (soldering, 10s)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

DC ELECTRICAL CHARACTERISTICS

 $(AV_{CC}=OV_{CC}=+1.8V,\ AGND=OGND=0,\ f_{SAMPLE}=210MHz,\ differential\ input\ and\ differential\ sine-wave\ clock\ signal,\ 0.1 \mu F$ capacitors on REFA and REFB, internal reference, digital output differential $R_L=100\Omega$, $T_A=-40$ °C to +85°C, unless otherwise noted. Typical values are at $T_A=+25$ °C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DC ACCURACY						
Resolution	N		12			Bits
Integral Nonlinearity (Note 2)	INL	f _{IN} = 10MHz	-2.5	±1	+2.5	LSB
Differential Nonlinearity (Note 2)	DNL	$T_A = +25$ °C, no missing codes	-1	±0.3	+1	LSB
Transfer Curve Offset	Vos	$T_A = +25$ °C (Note 2)	-3		+3	mV
Offset Temperature Drift				10		μV/°C
ANALOG INPUTS (INAP, INAN, II	NBP, INBN)					
Full-Scale Input Voltage Range	V _{FSR}	$T_A = +25^{\circ}C \text{ (Note 2)}$	1375	1475	1625	mV _{P-P}
Full-Scale Range Temperature Drift				150		ppm/°C
Common-Mode Input Range	V _{CM}			0.8		V
Differential Input Capacitance	C _{IN}			3		pF
Differential Input Resistance	R _{IN}			1.8		kΩ
Full-Power Analog Bandwidth	FPBW			800		MHz
REFERENCE (REFA, REFB, REF	ADJA, REFAI	DJB)				
Reference Output Voltage	V _{REF} _	T _A = +25°C, REFADJ_ = AGND	1.18	1.24	1.30	V
Reference Temperature Drift				65		ppm/°C
REFADJ_ Input High Voltage	VREFADJ_	Used to disable the internal reference	AV _{CC} - 0.1			V
SAMPLING CHARACTERISTICS	•					
Maximum Sampling Rate	fSAMPLE		210			MHz
Minimum Sampling Rate	fSAMPLE			40		MHz

DC ELECTRICAL CHARACTERISTICS (continued)

 $(AV_{CC}=OV_{CC}=+1.8V,\ AGND=OGND=0,\ f_{SAMPLE}=210MHz,\ differential\ input\ and\ differential\ sine-wave\ clock\ signal,\ 0.1 \mu F$ capacitors on REFA and REFB, internal reference, digital output differential $R_L=100\Omega$, $T_A=-40^{\circ}C$ to $+85^{\circ}C$, unless otherwise noted. Typical values are at $T_A=+25^{\circ}C$.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Clock Pulse-Width Low	t _{CL}	Figure 5 (Note 3)	1.2		20.0	ns
Clock Pulse-Width High	t _{CH}	Figure 5 (Note 3)	1.2		20.0	ns
Clock Duty Cycle		Set by clock-management circuit		25 to 75		%
Aperture Delay	t _{AD}	Figures 5, 11		310		ps
Aperture Jitter	taj	Figure 11		0.15		ps _{RMS}
CLOCK INPUTS (CLKP, CLKN)			•			
Differential Clock Input Amplitude		(Note 3)	200	500		mV _{P-P}
Clock Input Common-Mode Voltage	VCLKCM			1.15 ± 0.25		V
Clock Differential Input Resistance	R _{CLK}	T _A = +25°C (Note 3)		10 ±25%		kΩ
Clock Differential Input Capacitance	Cclk			3		pF
DYNAMIC CHARACTERISTICS (a	t -1dBFS) (N	ote 4)	•			
		f _{IN} = 10MHz	65	67.1		
Signal-to-Noise Ratio	SNR	$f_{IN} = 65MHz$	65	66.7		dB
		f _{IN} = 100MHz		66.6		
		$f_{IN} = 200MHz$		65.5		
		f _{IN} = 10MHz	10.5	10.9		
Effective Number of Dite	ENIOD	$f_{IN} = 65MHz$	10.5	10.8		Dite
Effective Number of Bits	ENOB	f _{IN} = 100MHz		10.8		Bits
		$f_{IN} = 200MHz$		10.5		
		f _{IN} = 10MHz	64.8	67		
Cismal to Naisa Diva Distantian	CINIAD	f _{IN} = 65MHz	64.8	66.6		٩D
Signal-to-Noise Plus Distortion	SINAD	f _{IN} = 100MHz		66.3		dB
		f _{IN} = 200MHz		65.2		
		f _{IN} = 10MHz	72	88		
0 : 5 0 : 5	OFDD	f _{IN} = 65MHz	72	83.5]
Spurious-Free Dynamic Range	SFDR	f _{IN} = 100MHz		81		dBc
		f _{IN} = 200MHz		79		
		f _{IN} = 10MHz		-88	-72	
Worst Harmonic		f _{IN} = 65MHz		-84	-72	1
(HD2 or HD3)		f _{IN} = 100MHz		-81		dBc
		f _{IN} = 200MHz		-79		
Two-Tone Intermodulation	TT11.45	$f_{\text{IN1}} = 29 \text{MHz}$ at -7dBFS $f_{\text{IN2}} = 31 \text{MHz}$ at -7dBFS		87		
Distortion	TTIMD	$f_{IN1} = 97MHz$ at -7dBFS $f_{IN2} = 100MHz$ at -7dBFS		83		dBc



DC ELECTRICAL CHARACTERISTICS (continued)

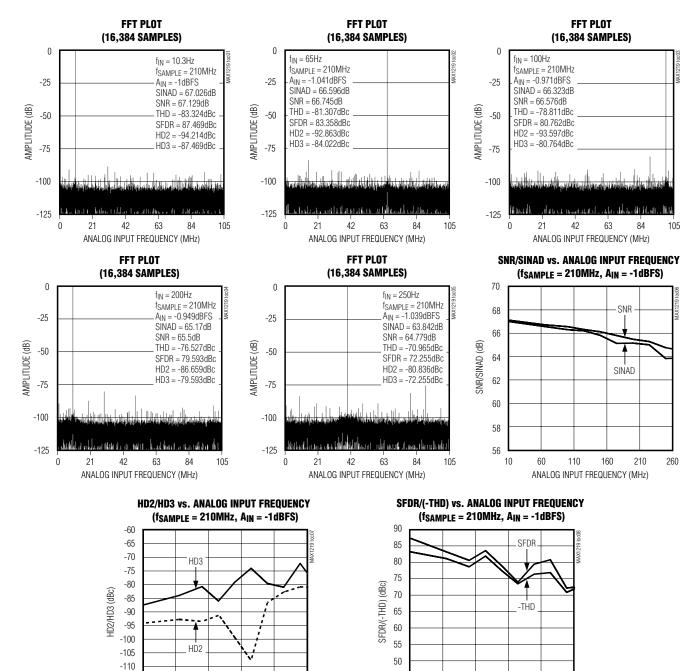
 $(AV_{CC} = OV_{CC} = +1.8V, AGND = OGND = 0, f_{SAMPLE} = 210MHz, differential input and differential sine-wave clock signal, 0.1<math>\mu$ F capacitors on REFA and REFB, internal reference, digital output differential $R_L = 100\Omega$, $T_A = -40$ °C to +85°C, unless otherwise noted. Typical values are at $T_A = +25$ °C.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
CHANNEL CROSSTALK AND C	HANNEL MAT	CHING SPECIFICATIONS	<u>.</u>			
Channel Isolation		f _{IN} = 200MHz, A _{IN} = -1dBFS		90		dB
LVCMOS LOGIC INPUTS (CLKD	IV, T/BA, T/BB	3)				
Input High Voltage	V _{IH}		0.8 x OVcc			V
Input Low Voltage	VIL				0.2 x OV _{CC}	V
Input Capacitance				2		pF
LVDS DIGITAL OUTPUTS (DA0F	P/N-DA11P/N,	DB0P/N-DB11P/N, ORAP/N, ORBP/N	, DCOP/N)			
Differential Output Voltage	IV _{OD} I		225		490	mV
Output Offset Voltage	Vos		1.125		1.310	V
OUTPUT TIMING CHARACTERIS	STICS					
CLK to Data Propagation Delay	tPDL	Figure 5 (Note 3)		1.7		ns
CLK to DCO Propagation Delay	tCPDL	Figure 5 (Note 3)		3.7		ns
DCO to Data Propagation Delay	tpdl - tcpdl	(Note 3)	2.3	2.7	3.1	ns
LVDS Output Rise Time	t _{RL}	20% to 80%, C _L = 5pF		350		ns
LVDS Output Fall Time	t _{FL}	20% to 80%, C _L = 5pF		350		ns
Output Data Pipeline Delay	tLATENCY	Figure 5		11		Clock Cycles
POWER REQUIREMENTS						
Analog Supply Voltage Range	AVCC		1.71	1.8	1.89	V
Output Supply Voltage Range	OVcc		1.71	1.8	1.89	V
Analog Supply Current	lavcc	f _{IN} = 10MHz		760	900	mA
Output Supply Current	lovcc	f _{IN} = 10MHz		120	160	mA
Analog Power Dissipation	P _{DISS}	f _{IN} = 10MHz		1.6	1.908	W
Power-Supply Rejection Ratio	PSRR	$T_A = +25$ °C (Note 5)		5		mV/V

- Note 1: Values at T_A = +25°C to +85°C are guaranteed by production test. Values at T_A < +25°C are guaranteed by design and characterization.
- **Note 2:** Static linearity and offset parameters are computed from a best-fit straight line through the code transition points. The full-scale range (FSR) is defined as 4095 x slope of the line.
- **Note 3:** Parameter guaranteed by design and characterization; $T_A = -40$ °C to +85°C.
- Note 4: ENOB and SINAD are computed from a curve fit.
- Note 5: PSRR is measured with the analog and output supplies connected to the same potential.

Typical Operating Characteristics

 $(AV_{CC} = OV_{CC} = 1.8V, f_{SAMPLE} = 210MHz, differential input and differential sine-wave clock signal, 0.1 \mu F capacitors on REFA and REFB, internal reference, digital output differential <math>R_L = 100\Omega$, $T_A = +25^{\circ}C$, unless otherwise noted.)



45

40

10

110

160

ANALOG INPUT FREQUENCY (MHz)

210

260

-115 -120

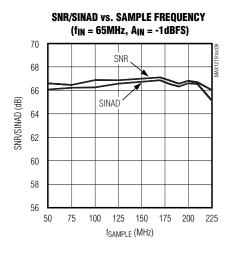
10

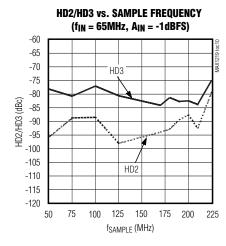
160

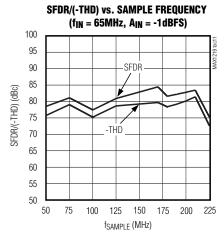
ANALOG INPUT FREQUENCY (MHz)

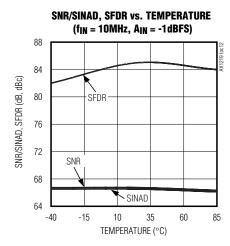
Typical Operating Characteristics (continued)

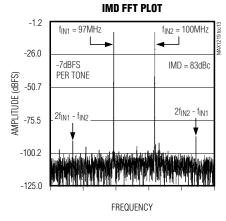
 $(AV_{CC} = OV_{CC} = 1.8V, f_{SAMPLE} = 210MHz, differential input and differential sine-wave clock signal, 0.1 \mu capacitors on REFA and REFB, internal reference, digital output differential <math>R_L = 100\Omega, T_A = +25^{\circ}C$, unless otherwise noted.)

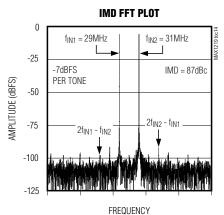






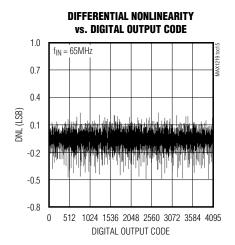


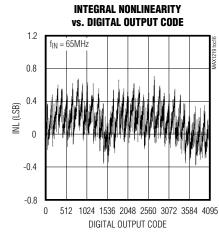


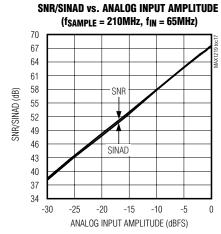


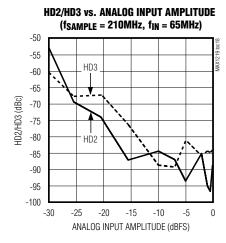
Typical Operating Characteristics (continued)

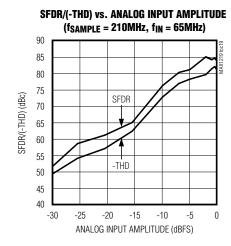
(AVCC = OVCC = 1.8V, fSAMPLE = 210MHz, differential input and differential sine-wave clock signal, $0.1\mu F$ capacitors on REFA and REFB, internal reference, digital output differential R_L = 100Ω , T_A = $+25^{\circ}C$, unless otherwise noted.)

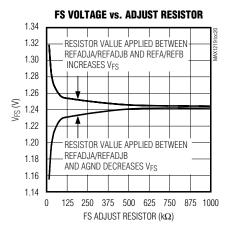












Pin Description

PIN	NAME	FUNCTION
1	REFA	Channel A Reference Input/Output. Channel A 1.23V reference output when REFADJA is driven low. Channel A external reference input when REFADJA is driven high. Connect a 0.1µF capacitor from REFA to AGND with both internal and external reference.
2	REFADJA	Channel A Reference Adjust Input. REFADJA allows for full-scale range adjustments by placing a resistor or trim potentiometer between REFADJA and AGND (decreases FS range) or REFADJA and REFA (increases FS range). Connect REFADJA to AVCC to overdrive the internal reference with an external reference. Connect REFADJA to AGND to allow the internal reference to determine the full-scale range of the data converter. See the FSR Adjustments Using the Internal Bandgap Reference section.
3, 5, 8, 11, 14, 18, 21, 23, 26, 28, 30, 33, 93, 96, 99, 100	AGND	Analog Converter Ground
4, 9, 10, 15, 16, 17, 22, 27, 29, 31, 94, 95	AVCC	Analog Supply Voltage. Bypass AV _{CC} to AGND with a 0.1µF capacitor for best decoupling results. Use additional board decoupling. See the <i>Grounding, Bypassing, and Layout Considerations</i> section.
6	INAP	Positive Analog Input A. Positive analog input to channel A.
7	INAN	Negative Analog Input A. Negative analog input to channel A.
12	CLKP	True Clock Input. Apply an LVDS-compatible input level to CLKP.
13	CLKN	Complementary Clock Input. Apply an LVDS-compatible input level to CLKN.
19	INBN	Negative Analog Input B. Negative analog input to channel B.
20	INBP	Positive Analog Input B. Positive analog input to channel B.
24	REFADJB	Channel B Reference Adjust Input. REFADJB allows for full-scale range adjustments by placing a resistor or trim potentiometer between REFADJB and AGND (decreases FS range) or REFADJB and REFA (increases FS range). Connect REFADJB to AVCC to overdrive the internal reference with an external reference. Connect REFADJB to AGND to allow the internal reference to determine the full-scale range of the data converter. See the FSR Adjustments Using the Internal Bandgap Reference section.
25	REFB	Channel B Reference Input/Output. Channel B 1.23V reference output when REFADJB is driven low. Channel B external reference input when REFADJB is driven high. Connect a 0.1µF capacitor from REFB to AGND with both internal and external reference.
32	CLKDIV	Clock-Divider Input. CLKDIV controls the sampling frequency relative to the input clock frequency. CLKDIV has an internal pulldown resistor. CLKDIV = 0: Sampling frequency is one-half the input clock frequency. CLKDIV = 1: Sampling frequency is equal to the input clock frequency.
34, 62, 92	OVCC	Output Stage Supply Voltage. Bypass OV _{CC} with a 0.1µF capacitor to AGND. Use additional board decoupling. See the <i>Grounding</i> , <i>Bypassing</i> , and <i>Layout Considerations</i> section.
35	ORBP	Channel B True Differential Over-Range Output
36	ORBN	Channel B Complementary Differential Over-Range Output
37	DB11P	Channel B True Differential Digital Output Bit 11 (MSB)
38	DB11N	Channel B Complementary Differential Digital Output Bit 11 (MSB)
39	DB10P	Channel B True Differential Digital Output Bit 10
40	DB10N	Channel B Complementary Differential Digital Output Bit 10
41	DB9P	Channel B True Differential Digital Output Bit 9
42	DB9N	Channel B Complementary Differential Digital Output Bit 9

Pin Description (continued)

PIN	NAME	FUNCTION
43	DB8P	Channel B True Differential Digital Output Bit 8
44	DB8N	Channel B Complementary Differential Digital Output Bit 8
45	DB7P	Channel B True Differential Digital Output Bit 7
46	DB7N	Channel B Complementary Differential Digital Output Bit 7
47	DB6P	Channel B True Differential Digital Output Bit 6
48	DB6N	Channel B Complementary Differential Digital Output Bit 6
49	DB5P	Channel B True Differential Digital Output Bit 5
50	DB5N	Channel B Complementary Differential Digital Output Bit 5
51	DB4P	Channel B True Differential Digital Output Bit 4
52	DB4N	Channel B Complementary Differential Digital Output Bit 4
53	DB3P	Channel B True Differential Digital Output Bit 3
54	DB3N	Channel B Complementary Differential Digital Output Bit 3
55	DB2P	Channel B True Differential Digital Output Bit 2
56	DB2N	Channel B Complementary Differential Digital Output Bit 2
57	DB1P	Channel B True Differential Digital Output Bit 1
58	DB1N	Channel B Complementary Differential Digital Output Bit 1
59	DB0P	Channel B True Differential Digital Output Bit 0 (LSB)
60	DB0N	Channel B Complementary Differential Digital Output Bit 0 (LSB)
61, 63	OGND	Output Stage Ground. Ground connection for output circuitry.
64	DCON	Complementary LVDS Digital Clock Output. Outputs same frequency as ADC sampling frequency.
65	DCOP	True LVDS Digital Clock Output. Outputs same frequency as ADC sampling frequency.
66	DAON	Channel A Complementary Differential Digital Output Bit 0 (LSB)
67	DA0P	Channel A True Differential Digital Output Bit 0 (LSB)
68	DA1N	Channel A Complementary Differential Digital Output Bit 1
69	DA1P	Channel A True Differential Digital Output Bit 1
70	DA2N	Channel A Complementary Differential Digital Output Bit 2
71	DA2P	Channel A True Differential Digital Output Bit 2
72	DA3N	Channel A Complementary Differential Digital Output Bit 3
73	DA3P	Channel A True Differential Digital Output Bit 3
74	DA4N	Channel A Complementary Differential Digital Output Bit 4
75	DA4P	Channel A True Differential Digital Output Bit 4
76	DA5N	Channel A Complementary Differential Digital Output Bit 5
77	DA5P	Channel A True Differential Digital Output Bit 5
78	DA6N	Channel A Complementary Differential Digital Output Bit 6
79	DA6P	Channel A True Differential Digital Output Bit 6
80	DA7N	Channel A Complementary Differential Digital Output Bit 7
81	DA7P	Channel A True Differential Digital Output Bit 7
82	DA8N	Channel A Complementary Differential Digital Output Bit 8
83	DA8P	Channel A True Differential Digital Output Bit 8
84	DA9N	Channel A Complementary Differential Digital Output Bit 9



Pin Description (continued)

PIN	NAME	FUNCTION
85	DA9P	Channel A True Differential Digital Output Bit 9
86	DA10N	Channel A Complementary Differential Digital Output Bit 10
87	DA10P	Channel A True Differential Digital Output Bit 10
88	DA11N	Channel A Complementary Differential Digital Output Bit 11 (MSB)
89	DA11P	Channel A True Differential Digital Output Bit 11 (MSB)
90	ORAN	Channel B Complementary Differential Over-Range Output
91	ORAP	Channel B True Differential Over-Range Output
97	T/BB	Output Format Select Input for Channel B. T/BB controls the digital output format of channel B of the MAX1219. T/BB has an internal pulldown resistor. T/BB = 1: Binary output format. T/BB = 0: Two's-complement output format.
98	T/BA	Output Format Select Input for Channel A. \overline{T}/BA controls the digital output format of channel A of the MAX1219. \overline{T}/BA has an internal pulldown resistor. $\overline{T}/BA = 1$: Binary output format. $\overline{T}/BA = 0$: Two's-complement output format.
_	EP	Exposed Paddle. The exposed paddle is located on the backside of the device and must be connected to AGND.

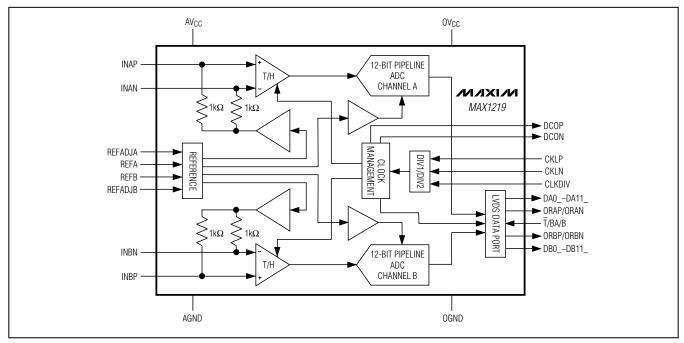


Figure 1. Functional Diagram

10 ______ 10 _____ 10 ____ 10 ____ 10 ____ 10 ____ 10 ____ 10 ____ 10 ___ 10 ___

Detailed Description

Theory of Operation

The MAX1219 uses a fully differential pipelined architecture that allows for high-speed conversion, optimized accuracy, and linearity while minimizing power consumption.

Both positive inputs (INAP, INBP) and negative/complementary analog inputs (INAN, INBN) are centered around a 0.8V common-mode voltage, and each accept a ±VFS / 4 differential analog input voltage swing, providing a 1.475VP-P typical differential full-scale signal swing. Each set of inputs (INAP, INAN and INBP, INBN) is sampled when the differential sampling clock signal transitions high. When using the clock-divide mode, the analog inputs are sampled at every other high transition of the differential sampling clock.

Each pipeline converter stage converts its input voltage to a digital output code. At every stage, except the last, the error between the input voltage and the digital output code is multiplied and passed along to the next pipeline stage. Digital error correction compensates for ADC comparator offsets in each pipeline stage and ensures no missing codes. The result is a 12-bit parallel digital output word in selectable two's-complement or offset binary output formats with LVDS-compatible output levels (Figure 1).

Analog Inputs

The MAX1219 features two sets of fully differential inputs (INAP, INAN and INBP, INBN) for each input channel. Differential inputs feature good rejection of even-order harmonics, which allows for enhanced AC performance as the signals are progressing through the analog stages. The MAX1219 analog inputs are self-biased at a 0.8V common-mode voltage and allow a 1.475Vp-p differential input voltage swing (Figure 2). Both sets of inputs are self-biased through $1k\Omega$ resistors, resulting in a typical $2k\Omega$ differential input resistance. Drive the analog inputs of the MAX1219 in AC-coupled configuration to achieve best dynamic performance. See the *Transformer-Coupled*, *Differential Analog Input Drive* section.

On-Chip Reference Circuit

The MAX1219 features an internal 1.24V bandgap reference circuit (Figure 3), which, in combination with two internal reference-scaling amplifiers, determines the FSR of each channel. Bypass REFA and REFB with a 0.1µF capacitor to AGND. Adjust the voltage of the

bandgap reference for each channel independently by adding an external resistor (e.g., $100k\Omega$ trim potentiometer) between REFADJA/REFADJB and AGND or REFADJA/REFADJB and REFA/REFB to compensate for gain errors or increase the FSR of each channel. See the *Applications Information* section for a detailed description of this process.

To disable the internal reference for each channel, connect the reference adjust input (REFADJA, REFADJB) to AVCC. Apply an external, stable reference to the channel's reference input/output (REFA, REFB) to set the converter's full scale. To enable the internal reference for a channel, connect the appropriate reference adjust input (REFADJA, REFADJB) to AGND.

Clock Inputs (CLKP, CLKN)

Drive the clock inputs of the MAX1219 with an LVDS-compatible clock to achieve the best dynamic performance. The clock signal source must be a high-quality, low phase noise to avoid any degradation in the noise performance of the ADC. The clock inputs (CLKP, CLKN) are internally biased to 1.15V to accept a typical 0.5VP-P differential signal swing (Figure 4). See the Differential, AC-Coupled PECL-Compatible Clock Input section for more circuit details on how to drive CLKP and CLKN appropriately. Although not recommended, the clock inputs also accept a single-ended input signal.

The MAX1219 also features an internal clock-management circuit (duty-cycle equalizer) to ensure that the clock signal applied to inputs CLKP and CLKN is processed to provide a 50% duty-cycle clock signal that desensitizes the performance of the converter to variations in the duty cycle of the input clock source. The clock duty-cycle equalizer cannot be turned off externally and requires a minimum 40MHz clock frequency to allow the device to meet data sheet specifications.

If the MAX1219 is not clocked, the digital outputs begin to change state randomly, resulting in a supply current increase of up to 40mA.

Clock Outputs (DCON, DCOP)

The MAX1219 features a differential clock output, which can be used to latch the digital output data with an external latch or receiver. Additionally, the clock output can be used to synchronize external devices (e.g., FPGAs) to the ADC. DCOP and DCON are differential outputs with LVDS-compatible voltage levels. There is a 3.7ns (typ) delay between the rising (falling) edge of CLKP (CLKN) and the rising (falling) edge of DCOP (DCON). See Figure 5 for timing details.

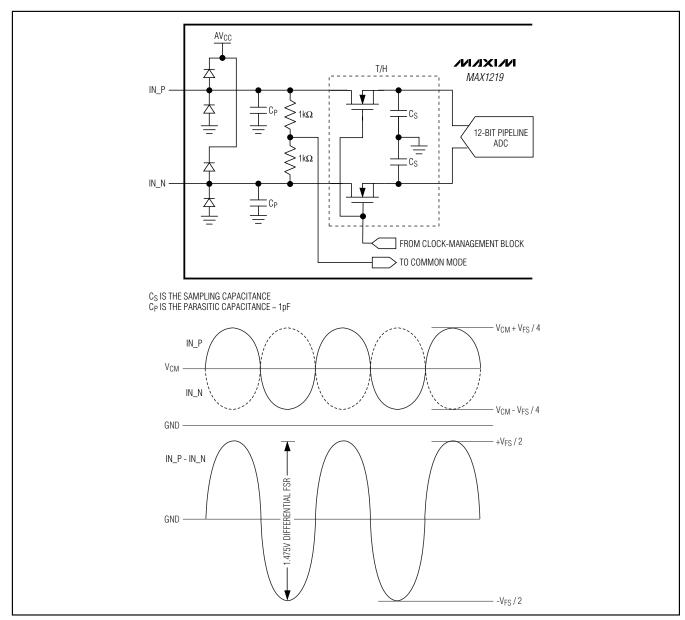


Figure 2. Simplified Analog Input Architecture and Allowable Input Voltage Range

Divide-by-2 Clock Control

The MAX1219 offers a clock control line (CLKDIV) that supports the reduction of clock jitter in a system. Connect CLKDIV to OGND to enable the ADC's internal divide-by-2 clock divider. Data is now updated at one-half the ADC's input clock rate. CLKDIV has an internal pulldown resistor and can be left open for applications that require this divide-by-2 mode. Connecting CLKDIV to OVCC disables the divide-by-2 mode.

System Timing Requirements

Figure 5 depicts the relationship between the clock input and output, analog input, sampling event, and data output. The MAX1219 samples on the rising (falling) edge of CLKP (CLKN). Output data is valid on the next rising (falling) edge of DCOP (DCON), with an internal latency of 11 clock cycles.

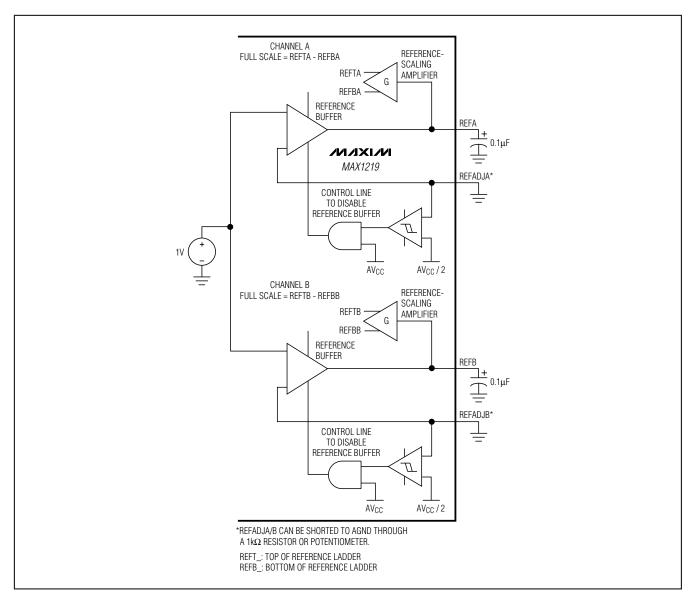


Figure 3. Simplified Reference Architecture

Digital Outputs (DA0P/N-DA11P/N, DB0P/N-DB11P/N, ORAP/N, ORBP/N, DCOP/N) and Control Inputs T/BA, T/BB

Digital outputs DA0P/N-DA11P/N, DB0P/N-DB11P/N, ORAP/N, ORBP/N, and DCOP/N are LVDS compatible, and data on DA0P/N-DA11P/N and DB0P/N-DB11P/N are presented in either binary or two's-complement format (Table 1). The T/BA, T/BB control lines are LVCMOS-compatible inputs that allow a selectable output format for each channel. Pulling T/BA, T/BB low outputs data in

two's complement and pulling it high presents data in offset binary format on each of the channels' 12-bit parallel buses. \overline{T}/BA , \overline{T}/BB have an internal pulldown resistor and can be left unconnected in applications using only two's-complement output format. All LVDS outputs provide a typical 0.371V voltage swing around roughly a 1.2V common-mode voltage, and must be terminated at the far end of each transmission line pair (true and complementary) with 100Ω . Apply a 1.71V to 1.89V voltage supply at OVCC to power the LVDS outputs.

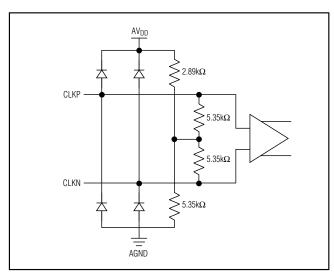


Figure 4. Simplified Clock Input Architecture

The MAX1219 offers an additional set of differential output pairs (ORAP/N and ORBP/N) to flag out-of-range conditions for each channel, where out-of-range is above positive or below negative full scale. An out-of-range condition on each channel is identified with ORAP or ORBP (ORAN or ORBN) transitioning high (low).

Note: Although a differential LVDS output architecture reduces single-ended transients to the supply and ground planes, capacitive loading on the digital outputs should still be kept as low as possible. Using LVDS buffers on the digital outputs of the ADC when driving larger loads improves overall performance and reduces system-timing constraints.

Applications Information

FSR Adjustments Using the Internal Bandgap Reference

The MAX1219 supports a 10% (±5%) full-scale adjustment range on each channel. Add an external resistor ranging from $13k\Omega$ to $1M\Omega$ between the reference adjust input of the channel (REFADJA, REFADJB) and AGND to decrease the full-scale range of the channel. Adding a variable resistor, potentiometer, or predetermined resistor value between the reference adjust input of a channel (REFADJA, REFADJB) and its respective reference input/output (REFA, REFB) increases the FSR of the channel. Figure 6a shows the two possible configurations and their impact on the overall full-scale range adjustment of the MAX1219. The FSR for each channel can be set to any value in the allowed range independent of the FSR of the other channel. Do not use resistor values of less than $13k\Omega$ to avoid instability of the internal gain regulation loop for the bandgap reference. See Figure 6b for the resulting FSR for a series of resistor values.

Differential, AC-Coupled, LVPECL-Compatible Clock Input

The MAX1219 dynamic performance depends on the use of a very clean clock source. The phase noise floor of the clock source has a negative impact on the SNR performance. Spurious signals on the clock signal source also affect the ADC's dynamic range. The preferred method of clocking the MAX1219 is differentially with LVDS- or LVPECL-compatible input levels. The fast data transition rates of these logic families minimize the clock input circuitry's transition uncertainty improving

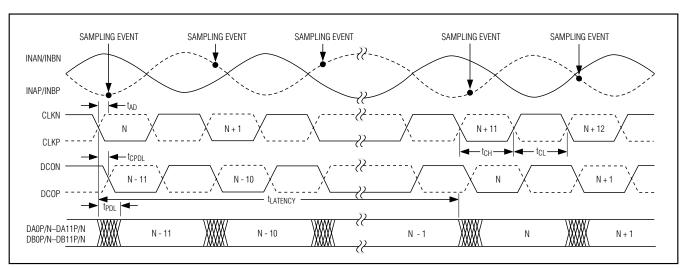


Figure 5. System and Output Timing Diagram

14 ______**/N/1X1/V**

Table 1. MAX1219 Digital Output Coding

INAP/INBP ANALOG INPUT VOLTAGE LEVEL	INAN/INBN ANALOG INPUT VOLTAGE LEVEL	OUT-OF-RANGE ORAP/ORBP (ORAN/ORBN)	BINARY DIGITAL OUTPUT CODE (DA11P/N-DA0P/N; DB11P/N-DB0P/N)	TWO'S-COMPLEMENT DIGITAL OUTPUT CODE (DA11P/N-DA0P/N; DB11P/N-DB0P/N)
> V _{CM} + V _{FS} / 4	< V _{CM} - V _{FS} / 4	1 (0)	1111 1111 1111 (exceeds +FS, OR set)	0111 1111 1111 (exceeds +FS, OR set)
V _{CM} + V _{FS} / 4	V _{CM} - V _{FS} / 4	0 (1)	1111 1111 1111 (+FS)	0111 1111 1111 (+FS)
V _{CM}	V _{CM}	0 (1)	1000 0000 0000 or 0111 1111 1111 (FS / 2)	0000 0000 0000 or 1111 1111 1111 (FS / 2)
V _{CM} - V _{FS} / 4	V _{CM} + V _{FS} / 4	0 (1)	0000 0000 0000 (-FS)	1000 0000 0000 (-FS)
< V _{CM} + V _{FS} / 4	> V _{CM} - V _{FS} / 4	1 (0)	0000 0000 0000 (exceeds -FS, OR set)	1000 0000 0000 (exceeds -FS, OR set)

the SNR performance. To accomplish this, AC-couple a 50Ω reverse-terminated clock signal source with low phase noise into a fast differential receiver, such as the MAX9388 (Figure 7). The receiver produces the necessary LVPECL output levels to drive the clock inputs of the data converter.

Transformer-Coupled, Differential Analog Input Drive

The MAX1219 provides the best SFDR and THD performance with fully differential input signals. In differential input mode, even-order harmonics are lower since the inputs to each channel (INAP/N and INBP/N) are balanced, and each of the channel's inputs only requires half the signal swing compared to a single-ended configuration.

Wideband RF transformers provide an excellent solution to convert a single-ended signal to a fully differential signal. Apply a secondary-side termination to a 1:1 transformer (e.g., Mini-Circuit's ADT1-1WT) by two separate 24.9 Ω resistors. Higher source impedance values can be used at the expense of a degradation in dynamic performance. Use resistors with tight tolerance (0.5%) to minimize effects of imbalance, maximizing the ADC's dynamic range. This configuration optimizes THD and SFDR performance of the ADC by reducing the effects of transformer parasitics. However, the source impedance combined with the shunt capacitance provided by a PC board and the ADC's parasitic capacitance limit the ADC's full-power input bandwidth.

To further enhance THD and SFDR performance at high input frequencies (> 100MHz) place a second transformer (Figure 8) in series with the single-ended-to-differential conversion transformer. The second transformer reduces the increase of even-order harmonics at high frequencies.

Single-Ended, AC-Coupled Analog Inputs

Although not recommended, the MAX1219 can be used in single-ended mode (Figure 9). AC-couple the analog signals to the positive input of each channel (INAP, INBP) through a 0.1µF capacitor terminated with a 49.9 Ω resistor to AGND. Terminate the negative input of each channel (INAN, INBN) with a 24.9 Ω resistor in series with a 0.1µF capacitor to AGND. In single-ended mode the input range is limited to approximately half of the FSR of the device, and dynamic performance usually degrades.

Grounding, Bypassing, and Board Layout

The MAX1219 requires board layout design techniques suitable for high-speed data converters. This ADC accepts separate analog and output power supplies. The analog and output power-supply inputs accept 1.71V to 1.89V input voltage ranges. Although both AV_{CC} and OV_{CC} can be supplied from one source, use separate sources to reduce performance degradation caused by output switching currents, which can couple into the analog supply network. Isolate analog and output supplies (AV_{CC} and OV_{CC}) where they enter the PC board with separate networks of ferrite beads and capacitors to their corresponding grounds (AGND, OGND).

To achieve optimum performance, provide each supply with a separate network of 47µF tantalum capacitor and parallel combination of 10µF and 1µF ceramic capacitors. Additionally, the ADC requires each supply input to be bypassed with a separate 0.1µF ceramic capacitor (Figure 10). Locate these capacitors directly at the ADC supply inputs or as close as possible to the MAX1219. Choose surface-mount capacitors, whose preferred location is on the same side as the converter

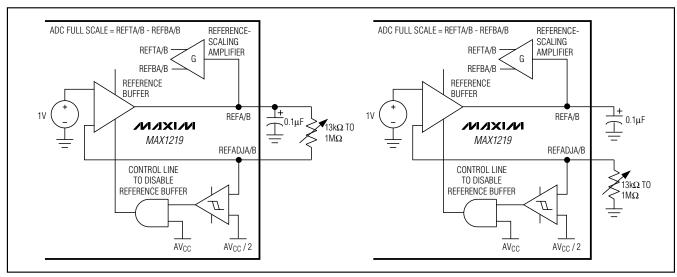


Figure 6a. Circuit Suggestions to Adjust the ADC's Full-Scale Range

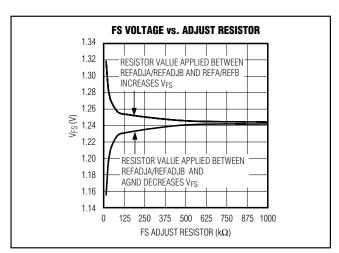


Figure 6b. FS Adjustment Range vs. FS Adjustment Resistor

to save space and minimize inductance. If close placement on the same side is not possible, route these bypassing capacitors through vias to the bottom side of the PC board.

Multilayer boards with separate ground and power planes produce the highest level of signal integrity. Use a split ground plane arranged to match the physical location of the analog and output grounds on the ADC's package. Join the two ground planes at a single point so the noisy output ground currents do not interfere with the analog ground plane. Dynamic currents traveling long distances before reaching ground cause large and undesirable ground loops. Ground loops can degrade the

input noise by coupling back to the analog front-end of the converter, resulting in increased spurious activity, leading to decreased noise performance.

All AGND connections could share the same ground plane, if the ground plane is sufficiently isolated from any noisy, output systems ground. To minimize the coupling of the output signals from the analog input, segregate the output bus carefully from the analog input circuitry. To further minimize the effects of noise coupling, position ground return vias throughout the layout to divert output switching currents away from the sensitive analog sections of the ADC. This approach does not require split ground planes, but can be accomplished by placing substantial ground connections between the analog front-end and the digital outputs.

The MAX1219 is packaged in a 100-pin TQFP-EP package (package code: C100E-6), providing greater design flexibility, increased thermal dissipation, and optimized AC performance of the ADC. The exposed paddle (EP) must be soldered to AGND.

The data converter die is attached to an EP lead frame with the back of this frame exposed to the package bottom surface, facing the PC board side of the package. This allows a solid attachment of the package to the board with standard infrared (IR) flow soldering techniques.

Thermal efficiency is one of the factors for selecting a package with an exposed paddle for the MAX1219. The exposed paddle improves thermal efficiency and ensures a solid ground connection between the ADC and the PC board's analog ground layer.

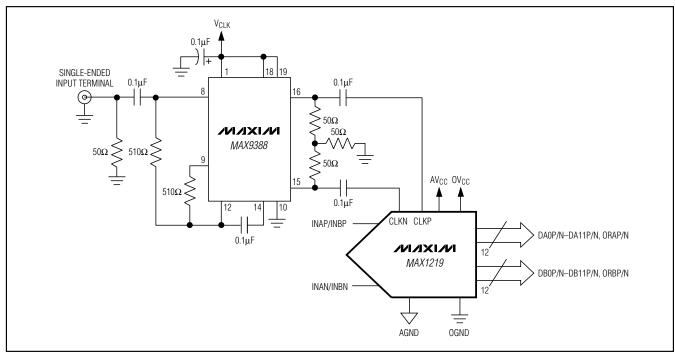


Figure 7. Differential, AC-Coupled, PECL-Compatible Clock Input Configuration

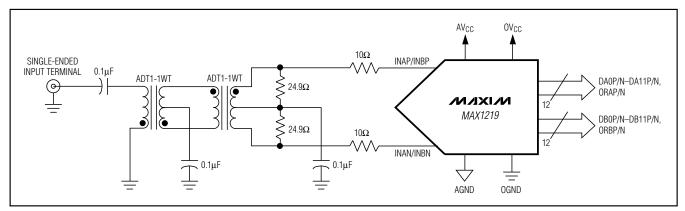


Figure 8. Analog Input Configuration with Back-to-Back Transformers and Secondary-Side Termination

Route the digital output traces for a high-speed, high-resolution data converter with care. Keep trace lengths at a minimum and place minimal capacitive loading, less than 5pF, on any digital trace to prevent coupling to sensitive analog sections of the ADC. Run the LVDS output traces as differential lines with 100Ω characteristic impedance from the ADC to the LVDS load device.

Static Parameter Definitions

Integral Nonlinearity (INL)

Integral nonlinearity is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit or a line drawn between the end points of the transfer function, once offset and gain errors have been nullified. However, the static linearity parameters for the MAX1219 are measured using the histogram method with a 65MHz input frequency.

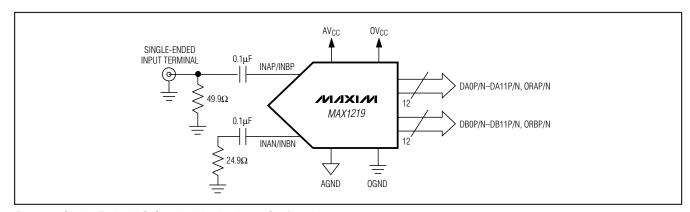


Figure 9. Single-Ended AC-Coupled Analog Input Configuration

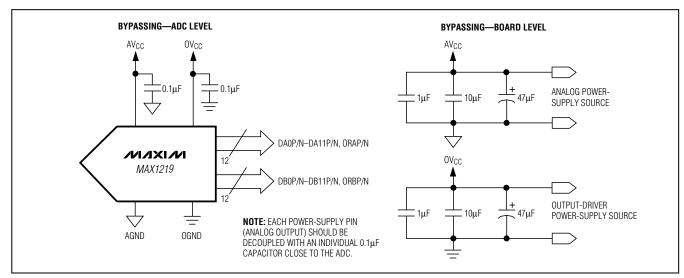


Figure 10. Grounding, Bypassing, and Decoupling Recommendations for the MAX1219

Differential Nonlinearity (DNL)

Differential nonlinearity is the difference between an actual step width and the ideal value of 1 LSB. A DNL error specification greater than -1 LSB guarantees no missing codes and a monotonic transfer function. The MAX1219's DNL specification is measured with the histogram method based on a 65MHz input tone.

_Dynamic Parameter Definitions

Aperture Jitter

Figure 11 depicts the aperture jitter (t_{AJ}), which is the sample-to-sample variation in the aperture delay.

Aperture Delay

Aperture delay (t_{AD}) is the time defined between the rising edge of the sampling clock and the instant when an actual sample is taken (Figure 11).

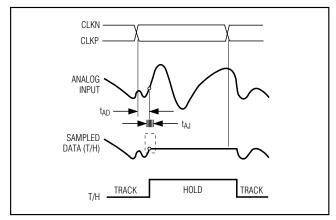


Figure 11. Aperture Jitter/Delay Specifications

N/IXI/N

Signal-to-Noise Ratio (SNR)

For a waveform perfectly reconstructed from digital samples, the theoretical maximum SNR is the ratio of the full-scale analog input (RMS value) to the RMS quantization error (residual error). The ideal, theoretical minimum analog-to-digital noise is caused by quantization error only and results directly from the ADC's resolution (N bits):

$$SNR_{dB}[max] = 6.02dB \times N + 1.76dB$$

In reality, there are other noise sources besides quantization noise: thermal noise, reference noise, clock jitter, etc. SNR is computed by taking the ratio of the RMS signal to the RMS noise. RMS noise includes all spectral components to the Nyquist frequency excluding the fundamental, the first six harmonics (HD2–HD7), and the DC offset.

Signal-to-Noise Plus Distortion (SINAD)

SINAD is computed by taking the ratio of the RMS signal to all spectral components excluding the fundamental and the DC offset. In the case of the MAX1219, SINAD is computed from a curve fit.

Spurious-Free Dynamic Range (SFDR)

SFDR is the ratio of the RMS amplitude of the fundamental (maximum signal component) to the RMS value of the next-largest noise or harmonic distortion component, excluding DC offset. SFDR is usually measured in dBc with respect to the fundamental (carrier) frequency amplitude or in dBFS with respect to the ADC's full-scale range.

Intermodulation Distortion (IMD)

IMD is the ratio of the RMS sum of the intermodulation products to the RMS sum of the two fundamental input tones. This is expressed as:

IMD =
$$20 \times log \left(\frac{\sqrt{V^2_{IM1} + V^2_{IM2} + ... + V^2_{IMn}}}{\sqrt{V_1^2 + V_2^2}} \right)$$

The fundamental input tone amplitudes (V_1 and V_2) are at -7dBFS. The intermodulation products are the amplitudes of the output spectrum at the following frequencies:

- 2nd-order intermodulation products (IM2): f_{IN1} + f_{IN2}, f_{IN2} - f_{IN1}
- 3rd-order intermodulation products (IM3): 2f_{IN1} f_{IN2}, 2f_{IN2} - f_{IN1}, 2f_{IN1} + f_{IN2}, 2f_{IN2} + f_{IN1}

- 4th-order intermodulation products (IM4): 3f_{IN1} f_{IN2}, 3f_{IN2} - f_{IN1}, 3f_{IN1} + f_{IN2}, 3f_{IN2} + f_{IN1}
- 5th-order intermodulation products (IM5): 3f_{IN1} 2f_{IN2}, 3f_{IN2} - 2f_{IN1}, 3f_{IN1} + 2f_{IN2}, 3f_{IN2} + 2f_{IN1}

Full-Power Bandwidth

A large -1dBFS analog input signal is applied to an ADC, and the input frequency is swept up to the point where the amplitude of the digitized conversion result has decreased by 3dB. The -3dB point is defined as the full-power input bandwidth frequency of the ADC.

Offset Error

Ideally, the midscale MAX1219 transition occurs at 0.5 LSB above midscale. The offset error is the amount of deviation between the measured transition point and the ideal transition point.

Gain Error

Ideally, the positive full-scale MAX1219 transition occurs at 1.5 LSB below positive full scale, and the negative full-scale transition occurs at 0.5 LSB above negative full scale. The gain error is the difference of the measured transition points minus the difference of the ideal transition points.

Effective Number of Bits (ENOB)

ENOB specifies the dynamic performance of an ADC at a specific input frequency and sampling rate. An ideal ADC's error consists of quantization noise only. ENOB for a full-scale sinusoidal input waveform is computed from:

$$ENOB = \left(\frac{SINAD - 1.76}{6.02}\right)$$

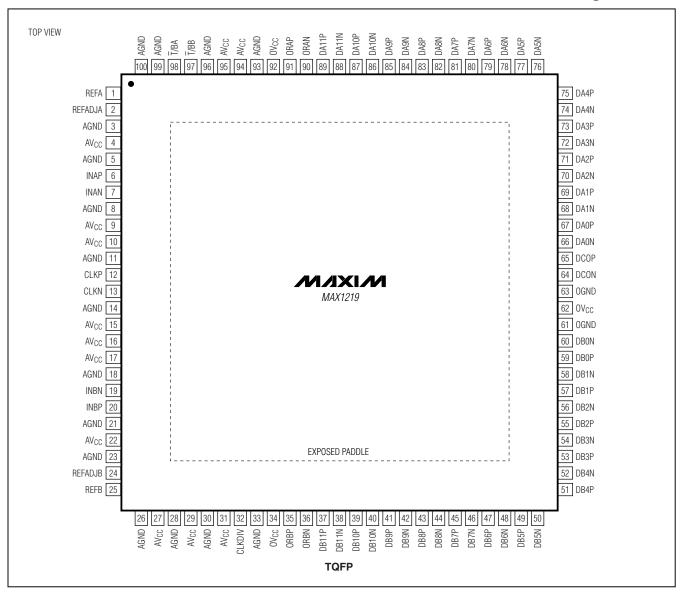
Total Harmonic Distortion (THD)

THD is the ratio of the RMS sum of the first six harmonics of the input signal to the fundamental itself. This is expressed as:

THD =
$$20 \times log \left[\frac{\sqrt{(V_2^2 + V_3^2 + V_4^2 + V_5^2 + V_6^2 + V_7^2)}}{V_1} \right]$$

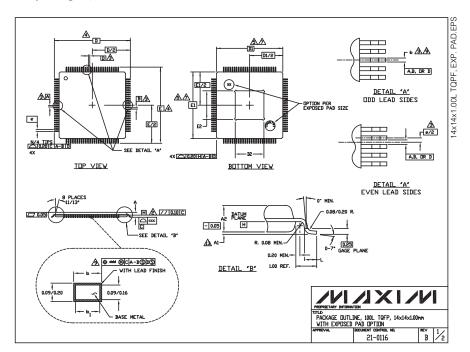
where V_1 is the fundamental amplitude, and V_2 through V_7 are the amplitudes of the 2nd- through 7th-order harmonics (HD2–HD7).

Pin Configuration



Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)



NOTES:

- ALL DIMENSIONING AND TOLERANCING CONFORM TO ASME Y14.5M-1994.
- 2. DATUM PLANE H LOCATED AT MOLD PARTING LINE AND COINCIDENT WITH LEAD, WHERE LEAD EXITS PLASTIC BODY AT BOTTOM OF PARTING LINE.
- DATUM A-B AND D TO BE DETERMINED AT CENTERLINE BETWEEN LEADS WHERE LEADS EXITS PLASTIC BODY AT DATUM PLANE H.
- 4. TO BE DETERMINED AT SEATING PLANE C
- 5. DIMENSIONS D1 AND E1 DO NOT INCLUDE MOLD PROTRUSION. ALLOWABLE MOLD PROTRUSION IS 0.254mm ON D1 AND E1 DIMENSIONS.
- 6. "N" IS THE TOTAL NUMBER OF TERMINALS.
- THESE DIMENSIONS TO BE DETERMINED AT DATUM PLANE
- THE TOP OF PACKAGE IS SMALLER THAN THE BOTTOM OF PACKAGE BY 0.15mm.
- MENSIONS & DOES NOT INCLUDE DAMBAR PROTRUSION.
 ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.08mm
 TOTAL IN EXCESS OF THE & DIMENSION AT MAXIMUM
 MATERIAL CONDITION. DAMBAR CANNOT BE LOCATED ON
 THE LOWER RADIUS OR THE FOOT.
- 10. CONTROLLING DIMENSION: MILLIMETER
- MAXIMUM ALLOWABLE DIE THICKNESS TO BE ASSEMBLED IN THIS PACKAGE FAMILY IS 0.50mm.
- 12. THIS OUTLINE IS NOT YET JEDEC REGISTERED.
- PLANE TO THE LOWEST POINT OF THE PACKAGE BOD
- EXPOSED DIE PAD SHALL BE COPLANAR WITH BOTTOM OF PACKAGE WITHIN 0.05mm.

- METAL AREA OF EXPOSED DIE PAD SHALL BE WITHIN 0.30mm OF THE NOMINAL DIE PAD SIZE.
- 16. COUNTRY OF ORIGIN MUST BE MARKED ON THE PACKAGE.

S _Y H BOL	ALL DIMENSIONS ARE IN MILLIMETERS					
[*] 0_	MIN.	N□M.	MAX.	NOTES		
Α	7se	me.	1.20			
Aı	0.05	- Me	0.15	13		
Ag	0.95	1.00	1.05			
D		16.00 BSC.		4		
D ₁		14.00 BSC.		7,8		
E			4			
E ₁		14.00 BSC.		7,8		
L	0.45	0.60	0.75			
N		100				
e		0.50 BSC.				
b	0.17	0.17 0.22 0.27				
b1	0.17	0.17 0.20 0.23				
ccc	74c	ne ne 0.08				
ddd	75e	- Me	0.08			

EXPOSED PAD VARIATIONS						
	D2			E2		
PKG, CODE	MIN.	NDM.	MAX.	MIN.	NDM.	MAX.
C100E-2	7.7	8.0	8.3	7.7	8.0	8.3
C100E-3	6.2	6.5	6.8	6.2	6.5	6.8
C100E-6	4.7	5.0	5.3	4.7	5.0	5.3

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

Maxim Integrated Products, 120 San Gabriel Drive, Sunnyvale, CA 94086 408-737-7600

_21