

BI-DIRECTIONAL MOTOR DRIVER**DESCRIPTION**

The M54540AL, BI-DIRECTIONAL MOTOR DRIVER, consists of a full bridge power driver designed for a low power D-C motor control.

FEATURES

- Small single-in-line package
- Integral diodes for transient suppression
- PMOS compatible input

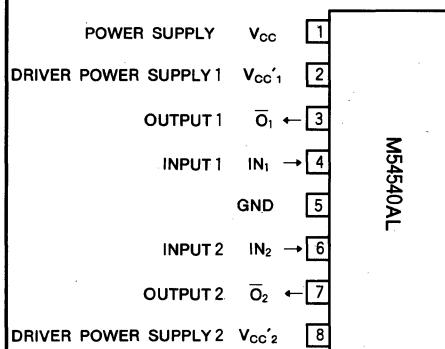
APPLICATION

Audio cassette tape recorder

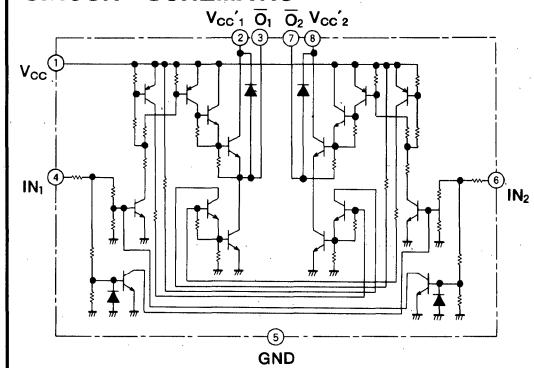
FUNCTION

The M54540AL, full bridge motor driver, has the logic circuitry and non-darlington power drivers for bidirection control of D-C motors operating at currents of up to 600mA.

The power supplies for the logic circuitry and the drivers are separated so that the applied voltage to the motor can be controlled by the V_{CC}' of the driver supply voltage.

PIN CONFIGURATION (TOP VIEW)

Outline 8P5

CIRCUIT SCHEMATIC**LOGIC TRUTH TABLE**

Input		Output		Note
IN1	IN2	O1	O2	
L	L	"OFF" state	"OFF" state	Open
H	L	H	L	Q
L	H	L	H	Q
H	H	"OFF" state	"OFF" state	Open

ABSOLUTE MAXIMUM RATINGS ($T_a=25^\circ\text{C}$, unless otherwise noted)

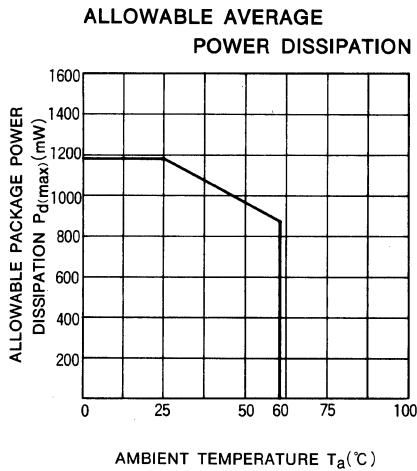
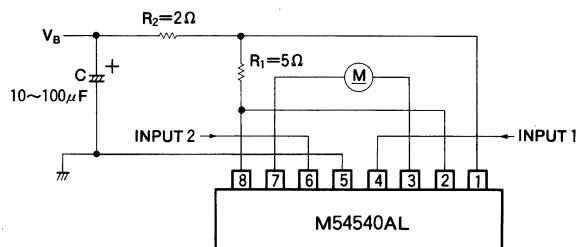
Symbol	Parameter	Conditions	Ratings	Unit
V_{CC}	Supply voltage		-0.3~+12	V
V_{CC}'	Driver supply voltage		-0.3~ V_{CC}	V
V_i	Input voltage		-0.3~ V_{CC}	V
V_o	Output voltage		-0.3~ $V_{CC}+2.5$	V
$I_{O(\max)}$	Peak output current	$t_{op}=10\text{ms}$, Repetitive cycle 0.2Hz max	± 600	mA
I_o	Continuous output current		± 120	mA
P_d	Power dissipation	$T_a=60^\circ\text{C}$	850	mW
T_{opr}	Operating ambient temperature range		-10~+60	°C
T_{stg}	Storage temperature range		-55~+125	°C

BI-DIRECTIONAL MOTOR DRIVER**RECOMMENDED OPERATING CONDITIONS** ($T_a=25^\circ\text{C}$, unless otherwise noted)

Symbol	Parameter	Conditions	Limits			Unit
			Min	Typ	Max	
V_{CC}	Supply voltage		6	10	11	v
I_O	Continuous output current				± 100	mA
V_{IH}	"H" Input voltage		3	5	V_{CC}	v
V_{IL}	"L" Input voltage			0	0.4	v
T_{off}	Input switching interval	It is prohibited to switch the inputs at the same time.	10	300		ms

ELECTRICAL CHARACTERISTICS ($T_a=25^\circ\text{C}$, unless otherwise noted)

Symbol	Parameter	Test conditions	Limits			Unit
			Min	Typ	Max	
$I_{O(\text{leak})}$	Output leakage current	$V_{CC}=V_{CC'}=20\text{V}$	$V_O=12\text{V}$		100	μA
		$V_1=V_2=3\text{V}$	$V_O=0\text{V}$		-100	
V_{OH}	"H" Output saturation voltage	$V_{CC}=V_{CC'}=10\text{V}$	$V_{11}=3\text{V}, V_{12}=0\text{V}$	8		v
		$I_{OH}=-100\text{mA}$	$V_{11}=0\text{V}, V_{12}=3\text{V}$			
V_{OL}	"L" Output saturation voltage	$V_{CC}=V_{CC'}=10\text{V}$	$V_{11}=3\text{V}, V_{12}=0\text{V}$		0.6	v
		$I_{OL}=100\text{mA}$	$V_{11}=0\text{V}, V_{12}=3\text{V}$			
I_{IH}	"H" Input current	$V_{CC}=V_{CC'}=10\text{V}$	$V_{11}=3\text{V}$		500	μA
			$V_{12}=3\text{V}$			
I_{CC}	Supply current	$V_{CC}=V_{CC'}=12\text{V}$	$V_{11}=3\text{V}, V_{12}=0\text{V}$	28	40	mA
			$V_{11}=0\text{V}, V_{12}=3\text{V}$			
			$V_{11}=0\text{V}, V_{12}=0\text{V}$	0		mA
			$V_{11}=3\text{V}, V_{12}=3\text{V}$			

TYPICAL CHARACTERISTICS**TYPICAL APPLICATION**

Note

1. It is prohibited to switch the both inputs simultaneously. The inputs should be driven separately to avoid high crossover current.
2. The pins 1, 2 and 8 are separated and shall be connected externally.