

KH232

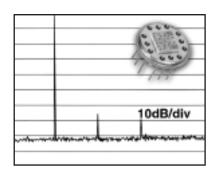
Low Distortion Wideband Op Amp

Features

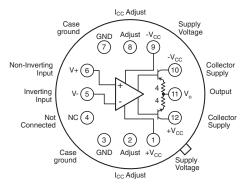
- -69dBc 2nd and 3rd harmonics at 20MHz
- -3dB bandwidth of 270MHz
- 0.05% settling in 15ns
- 3000V/µs slew rate
- 1mV input offset voltage, 10µV/°C drift
- ±10V, 100mA max output
- Direct replacement for CLC232

Applications

- Flash A/D drivers
- DAC current-to-voltage conversion
- Wide dynamic range IF amps
- VCO drivers
- DDS postamps
- Radar/communication receivers
- Precision line drivers



Bottom View



Pins 2 and 8 are used to adjust the supply current or to adjust the offset voltage (see text). These pins are normally left unconnected.

General Description

The KH232 is a wideband low distortion operational amplifier designed specifically for high speed, low gain applications requiring wide dynamic range. Utilizing a current feedback architecture, the KH232 offers high speed performance while maintaining DC precision.

The KH232 offers precise gains from ± 1 to ± 5 with a true 0.1% linearity and provides stable, oscillation-free operation across the entire gain range without external compensation. The KH232, a pin compatible enhanced version of the KH231, reduces 2nd and 3rd harmonic distortion to an extremely low -69dBc at 20MHz (2V_{pp}, R_L = 100 Ω). Additional features provided by the KH232 include a small signal bandwidth of 270MHz, a large signal bandwidth of 95MHz and a 3000V/ μ s slew rate. The input offset voltage is typically 1mV with an input offset drift of 10μ V/°C.

The KH232 combines these high performance features with its 0.05% settling time of 15ns and its 100mA drive capability to provide high speed, high resolution A/D and D/A converter systems with an attractive solution for driving and buffering. Wide dynamic range systems such as radar and communication receivers requiring low harmonic distortion and low noise will find the KH232 to be an excellent choice. As a line driver, the KH232 set at a gain of 2 cancels matched line losses.

The KH232 is constructed using thin film resistor/bipolar transistor technology, and is available in the following versions:

KH232AI	-25°C to +85°C	12-pin TO-8 can
KH232AK	-55°C to +125°C	12-pin TO-8 can, features burn-in & hermetic testing
KH232AM	-55°C to +125°C	12-pin TO-8 can, environmentally screened and electrically
		tested to MIL-STD-883
KH232HXC	-55°C to +125°C	SMD#: 5962-9166501HXC
KH232HXA	-55°C to +125°C	SMD#: 5962-9166501HXA

Typical Performance

	Gain Setting						
Parameter	1	2	5	-1	-2	-5	Units
-3dB bandwidth	430	270	135	220	175	110	MHz
rise time (2V)	1.8	2.0	2.5	2.0	2.2	2.9	ns
slew rate	2.5	3.0	3.0	3.0	3.0	3.0	V/ns
settling time (to 0.1%)	12	12	wiki	ri _{at}	a ¹² h	15t	41 from

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KH232 Electrical Characteristics ($T_A = +25$ °C, $A_V = +2V$, $V_{CC} = \pm 15V$, $R_L = 100\Omega$, $R_f = 250\Omega$; unless specified)

PARAMETERS	CONDITIONS	TYP	MIN & MAX RATINGS		UNITS	SYM	
Ambient Temperature	KH232AI	+25°C	-25°C	+25°C	+85°C		
Ambient Temperature	KH232AK/AM/HXC/HXA	+25°C	-55°C	+25°C	+125°C		
FREQUENCY DOMAIN RESPONSE							
† -3dB bandwidth (note 2) www.datasheet4u.com large-signal bandwidth	$V_{o} \le 0.63V_{pp}$ $V_{o} \le 2V_{pp}$ $V_{o} \le 10V_{pp}$	270 165 95	>200 >145 >80	>200 >145 >80	>200 >120 >60	MHz MHz MHz	SSBW SSBW FPBW
gain flatness (note 2) + peaking + peaking + rolloff group delay linear phase deviation reverse isolation	V_o ≤0.63 \tilde{V}_{pp} 0.1 to 50MHz >50MHz at 100MHz to 100MHz to 100MHz	0.1 0.1 0.4 3.5 ± 0.5 0.5	<0.6 <1.5 <0.6 - <2.0	<0.3 <0.3 <0.6 - <2.0	<0.6 <0.8 <1.0 - <2.0	dB dB dB ns	GFPL GFPH GFR GD LPD
non-inverting inverting		53 36	>43 >26	>43 >26	>43 >26	dB dB	RINI RIIN
TIME DOMAIN RESPONSE							
rise and fall time settling time to 0.05% to 0.1% overshoot slew rate (overdriven input)	2V step 10V step 5V step 2.5V step 5V step	2.0 5.0 15 12 5 3.0	<2.4 <7.0 - <22 <15 >2.5	<2.3 <6.5 - <17 <10 >2.5	<2.7 <6.5 - <22 <15 >1.8	ns ns ns ns % V/ns	TRS TRL TS TSP OS SR
overload recovery <50ns pulse, 200% overdrive	<1% error	120	_	_	_	ns	OR
NOISE AND DISTORTION RESPONSE + 2nd harmonic distortion + 3rd harmonic distortion equivalent input noise	2V _{pp} , 20MHz 2V _{pp} , 20MHz	-69 -69	<-64 <-64	<-64 <-64	<-56 <-64	dBc dBc	HD2 HD3
voltage inverting current non-inverting current noise floor integrated noise integrated noise	>100kHz >100kHz >100kHz >100kHz 1kHz to 200MHz 5MHz to 200MHz	2.8 20 2.3 -155 57 57	<3.2 <23 <2.6 <-154 <64 <64	<3.2 <23 <2.6 <-154 <64 <64	<3.5 <25 <2.9 <-153 <72 <72	nV/√Hz pA/√Hz pA/√Hz dBm(1Hz) μVrms μVrms	VN ICN NCN SNF INV INV
* input offset voltage average temperature coefficient * input bias current average temperature coefficient * input bias current average temperature coefficient * input bias current average temperature coefficient * power supply rejection ratio common mode rejection ratio * supply current	non-inverting inverting no load	1 10 5.0 50 10 125 50 46 25	<4.0 <25 <29 <125 <31 <200 >45 >40 <27	<2.0 <25 <21 <125 <15 <200 >45 >40 <27	<4.5 <25 <31 <125 < 35 <200 >45 >40 <29	mV μV/°C μA nA/°C μA nA/°C dB dB mA	VIO DVIO IBN DIBN IBI DIBI PSRR CMRR ICC
MISCELLANEOUS PERFORMANCE non-inverting input resistance non-inverting input capacitance output impedance output voltage range	DC @ 100MHz no load	400 1.3 5, 37 ±12	>100 <2.5 - >±11	>200 <2.5 - >±11	>400 <2.5 - >±11	kΩ pF Ω, nH V	RIN CIN RO VO

Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

Absolute Maximum Ratings

 V_{CC} ±20V I_0 ±100mA common mode input voltage, Vo $|V_{CC}| > 15V \pm (30-|V_{CC}|)V$ $|V_{CC}| \le 15V \pm |V_{CC}|V$ differential input voltage thermal resistance (see thermal model) +175°C junction temperature operating temperature AI: -25°C to +85°C AK/AM/HXC/HXA: -55°C to +125°C storage temperature -65°C to +150°C lead temperature (soldering 10s) +300°C

Recommended Operating Conditions

 V_{CC} ±5V to ±15V ±75mA common mode input voltage $\pm (|V_{CC}| - 5)V$ ±1 to ±5 gain range

AI/AK/AM/HXC/HXA 100% tested at +25°C note 1:

100% tested at +25°C and sample AK/AM/HXC/HXA + tested at -55°C and +125°C

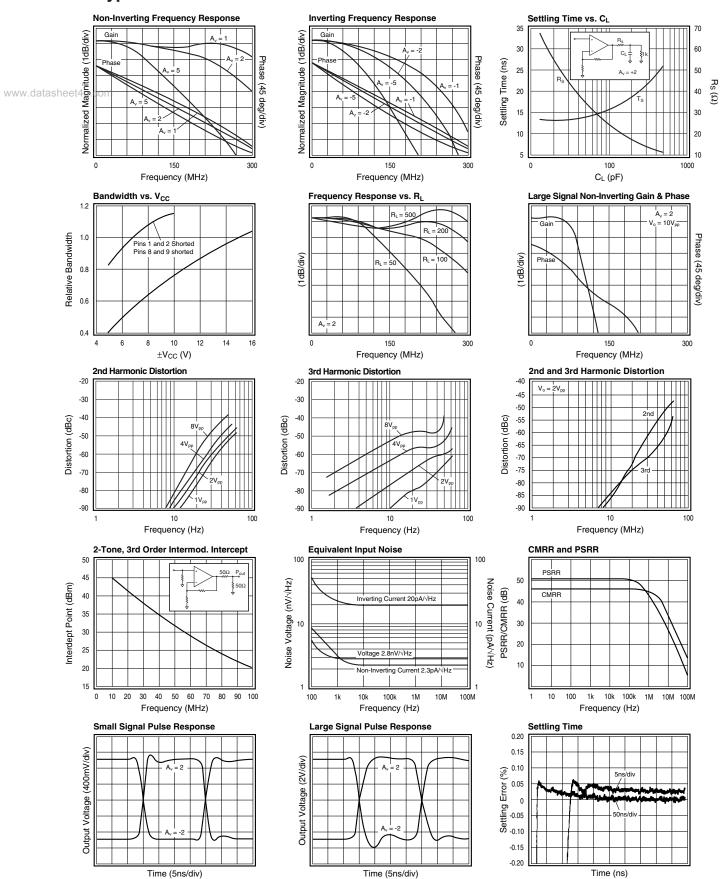
sample tested at +25°C

† Al note 2: The output amplitude used in testing is 0.63V_{pp}. Performance is guaranteed for conditions listed.

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KH232 Typical Performance Characteristics ($T_A = +25^{\circ}\text{C}$, $A_v = +2$, $V_{CC} = \pm 15\text{V}$, $R_L = 100\Omega$, $R_f = 250\Omega$; unless specified)



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Operation

The KH232 is based on the current feedback op amp topology, a design that uses current feedback instead of the usual voltage feedback.

The use of the KH232 is basically the same as that of the conventional op amp (see Figures 1 and 2). Since the wdevice is designed specifically for low gain applications, the best performance is obtained when the circuit is used at gains between ± 1 and ± 5 . Additionally, performance is optimum when a 250Ω feedback resistor is used.

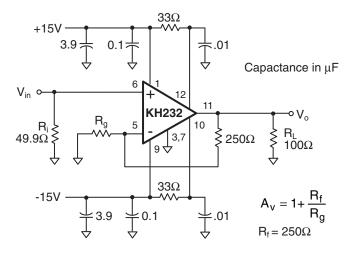


Figure 1: Recommended non-inverting gain circuit

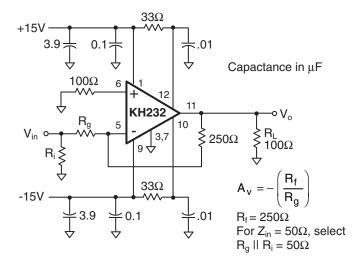


Figure 2: Recommended inverting gain circuit

Layout Considerations

To assure optimum performance the user should follow good layout practices which minimize the unwanted coupling of signals between nodes. During initial breadboarding of the circuit use direct point to point wiring, keeping the lead lengths to less than 0.25". The use of solid, unbroken ground plane is helpful. Avoid wire-wrap type pc boards and methods. Sockets with small, short pin receptacles may be used with minimal performance degradation although their use is not recommended.

During pc board layout keep all traces short and direct The resistive body of R_q should be as close as possible to pin 5 to minimize capacitance at that point. For the same reason, remove ground plane from the vicinity of pins 5 and 6. In other areas, use as much ground plane as possible on one side of the board. It is especially important to provide a ground return path for current from the load resistor to the power supply bypass capacitors. Ceramic capacitors of 0.01 to 0.1 \(\mu f \) (with short leads) should be less than 0.15 inches from pins 1 and 9. Larger tantalum capacitors should be placed within one inch of these pins. V_{CC} connections to pins 10 and 12 can be made directly from pins 9 and 1, but better supply rejection and settling time are obtained if they are separately bypassed as in figures 1 and 2. To prevent signal distortion caused by reflections from impedance mismatches, use terminated microstrip or coaxial cable when the signal must traverse more than a few inches.

Since the pc board forms such an important part of the circuit, much time can be saved if prototype boards of any high frequency sections are built and tested early in the design phase. Evaluation boards designed for either inverting or non-inverting gains are available.

Offset Voltage Adjustment

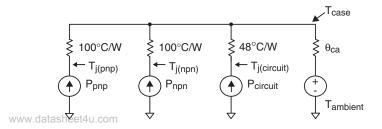
If trimming of the input offset voltage ($V_{os} = V_{ni} - V_{in}$) is desired, a resistor value of $10k\Omega$ to $1M\Omega$ placed between pins 8 and 9 will cause V_{os} to become more negative by 8mV to 0.2mV respectively. Similarly, a resistor placed between pins 1 and 2 will cause V_{os} , to become more positive.

Thermal Considerations

At high ambient temperatures or large internal power dissipations, heat sinking is required to maintain acceptable junction temperatures. Use the thermal model on the previous page to determine junction temperatures. Many styles of heat sinks are available for TO-8 packages; the Thermalloy 2240 and 2268 are good examples. Some heat sinks are the radial fin type which cover the pc board and may interfere with external components. An excellent solution to this problem is to use surface mounted resistors and capacitors. They have a very low profile and actually improve high frequency performance. For use of these heat sinks with conventional components, a 0.1" high spacer can be inserted under the TO-8 package to allow sufficient searches.

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$$P_{(circuit)} = (I_{CC})((+V_{CC}) - (V_{CC}))$$
 where $I_{CC} = 14mA$ at ±15V

$$P_{(xxx)} = [(\pm V_{CC}) - V_{out} - (I_{col}) (R_{col} + 4)] (I_{col}) (\%Duty)$$

For positive V_o and V_{CC} , this is the power in the npn device. For negative V_o and V_{CC} , this is the power in the pnp device.

 $I_{col} = V_o/R_L$ or 12mA, whichever is greater. (Include feedback R in R_I .)

 $\rm R_{col}$ is a resistor (33 $\!\Omega$ recommended) between the xxx collector and $\pm \rm V_{CC}.$

The limiting factor for output current and voltage is junction temperature. Of secondary importance is $I_{(out)}$, which should not exceed 150mA.

$$T_{j(pnp)} = P_{(pnp)} (100 + \theta_{ca}) + (P_{(cir)} + P_{(npn)})(\theta_{ca}) + T_a,$$
 similar for $T_{i(npn)}$.

$$T_{i(cir)} = P_{(cir)}(48 + \theta_{ca}) + (P_{(pnp)} + P_{(npn)})(\theta_{ca}) + T_a.$$

 θ_{ca} = 65°C/W for the KH232 without heat sink in still air. 35°C/W for the KH232 with a Thermalloy 2268A heat sink in still air.

15°C/W for the KH232 with a Thermalloy 2268A heat sink at 300 ft/min air.

(Thermalloy 2240A works equally as well.)

For example, with the KH232 operating at $\pm 15V$ while driving a 100Ω load at $15V_{pp}$ output (50% duty cycle pulse waveform, DC = 0), $P_{(npn)} = P_{(pnp)} = 190$ mW ($R_{col} = 33$) and $P_{(cir)} = 0.42$ W. Then with the Thermalloy 2268 heat sink and air flow of 300 ft/min the output transistors' T_j is 31°C above ambient and worst case T_j in the rest of the circuit is 32°C above ambient. In still air, however, the rise in T_j is 47°C and 48°C, respectively. With no heat sink, the rise in T_j is 71°C and 72°C, respectively! Under most conditions, **HEAT SINKING IS REQUIRED**.

Other methods of heat sinking may be used, but for best results, make contact with the base of the KH232 package, use a large thermal capacity heat sink and use forced air convection.

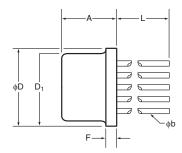
Low V_{CC} Operation: Supply Current Adjustment

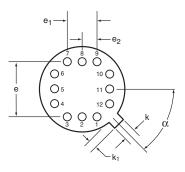
The KH232 is designed to operate on supplies as low as $\pm 5V$. In order to improve full bandwidth at reduced supply voltages, the supply current (I_{CC}) must be increased. The plot of Bandwidth vs. V_{CC}, shows the effect of shorting pins 1 and 2 and pins 8 and 9; this will increase both bandwidth and supply current. Care should be taken to not exceed the maximum junction temperatures; for this reason this technique should not be used with supplies exceeding $\pm 10V$. For intermediate values of V_{CC}, external resistors between pins 1 and 2 and pins 8 and 9 can be used.

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KH232 Package Dimensions

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TO-8							
SYMBOL	INC	HES	MILIMETERS				
STWDOL	Minimun	Maximum	Minimum	Maximum			
А	0.142	0.181	3.61	4.60			
φb	0.016	0.019	0.41	0.48			
φD	0.595	0.605	15.11	15.37			
φD ₁	0.543	0.555	13.79	14.10			
е	0.400	BSC	10.16 BSC				
e ₁	0.200) BSC	5.08 BSC				
e ₂	0.100 BSC		2.54 BSC				
F	0.016	0.030	0.41	0.76			
k	0.026	0.036	0.66	0.91			
k ₁	0.026	0.036	0.66	0.91			
L	0.310	0.340	7.87	8.64			
α	45° BSC		45° BSC				

NOTES:

Seal: cap weld Lead finish: gold per MIL-M-38510 Package composition: Package: metal

Lid: Type A per MIL-M-38510

Life Support Policy

Cadeka's products are not authorized for use as critical components in life support devices or systems without the express written approval of the president of Cadeka Microcircuits, Inc. As used herein:

1. Life support devices or systems are devices or systems which, a) are intended for surgical implant into the body, or b) support or sustain life, and whose failure to perform, when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.

2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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