



K51 Sub-Family Data Sheet

Supports the following:

MK51X256CLK100, MK51X256CMB100

Features

- Operating Characteristics
 - Voltage range: 1.71 to 3.6 V
 - Flash write voltage range: 1.71 to 3.6 V
 - Temperature range (ambient): -40 to 85°C
- Performance
 - Up to 100 MHz ARM Cortex-M4 core with DSP instructions delivering 1.25 Dhrystone MIPS per MHz
- Memories and memory interfaces
 - Up to 512 KB program flash memory on non-FlexMemory devices
 - Up to 256 KB program flash memory on FlexMemory devices
 - Up to 256 KB FlexNVM on FlexMemory devices
 - 4 KB FlexRAM on FlexMemory devices
 - Up to 128 KB RAM
 - Serial programming interface (EzPort)
- Clocks
 - 3 to 32 MHz crystal oscillator
 - 32 kHz crystal oscillator
 - Multi-purpose clock generator
- System peripherals
 - 10 low-power modes to provide power optimization based on application requirements
 - Memory protection unit with multi-master protection
 - 16-channel DMA controller, supporting up to 64 request sources
 - External watchdog monitor
 - Software watchdog
 - Low-leakage wakeup unit
- Security and integrity modules
 - Hardware CRC module to support fast cyclic redundancy checks
 - 128-bit unique identification (ID) number per chip
- Human-machine interface
 - Segment LCD controller supporting up to 40 frontplanes and 8 backplanes, or 44 frontplanes and 4 backplanes
 - Low-power hardware touch sensor interface (TSI)
 - General-purpose input/output
- Analog modules
 - Two 16-bit SAR ADCs
 - Programmable gain amplifier (up to x64) integrated into each ADC
 - Two 12-bit DACs
 - Two operational amplifiers
 - Two transimpedance amplifiers
 - Two analog comparators (CMP) containing a 6-bit DAC and programmable reference input
 - Voltage reference
- Timers
 - Programmable delay block
 - Eight-channel motor control/general purpose/PWM timer
 - Two 2-channel quadrature decoder/general purpose timers
 - Periodic interrupt timers
 - 16-bit low-power timer
 - Carrier modulator transmitter
 - Real-time clock
- Communication interfaces
 - USB full-/low-speed On-the-Go controller with on-chip transceiver
 - Two SPI modules
 - Two I2C modules
 - Four UART modules
 - I2S module

K51P81M100SF2



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Preliminary

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1 Ordering parts

1.1 Determining valid orderable parts

Valid orderable part numbers are provided on the web. To determine the orderable part numbers for this device, go to <http://www.freescale.com> and perform a part number search for the following device numbers: PK51 and MK51.

2 Part identification

2.1 Description

Part numbers for the chip have fields that identify the specific part. You can use the values of these fields to determine the specific part you have received.

2.2 Format

Part numbers for this device have the following format:

Q K## M FFF T PP CCC N

2.3 Fields

This table lists the possible values for each field in the part number (not all combinations are valid):

Field	Description	Values
Q	Qualification status	- M = Fully qualified, general market flow - P = Prequalification
K##	Kinetis family	K51
M	Flash memory type	- N = Program flash only - X = Program flash and FlexMemory

Table continues on the next page...

Field	Description	Values
FFF	Program flash memory size	• 32 = 32 KB • 64 = 64 KB • 128 = 128 KB • 256 = 256 KB • 512 = 512 KB • 1M0 = 1 MB
T	Temperature range (°C)	• V = -40 to 105 • C = -40 to 85
PP	Package identifier	• FM = 32 QFN (5 mm x 5 mm) • FT = 48 QFN (7 mm x 7 mm) • LF = 48 LQFP (7 mm x 7 mm) • EX = 64 QFN (9 mm x 9 mm) • LH = 64 LQFP (10 mm x 10 mm) • LK = 80 LQFP (12 mm x 12 mm) • MB = 81 MAPBGA (8 mm x 8 mm) • LL = 100 LQFP (14 mm x 14 mm) • MC = 121 MAPBGA (8 mm x 8 mm) • LQ = 144 LQFP (20 mm x 20 mm) • MD = 144 MAPBGA (13 mm x 13 mm) • MF = 196 MAPBGA (15 mm x 15 mm) • MJ = 256 MAPBGA (17 mm x 17 mm)
CCC	Maximum CPU frequency (MHz)	• 50 = 50 MHz • 72 = 72 MHz • 100 = 100 MHz • 120 = 120 MHz • 150 = 150 MHz
N	Packaging type	• R = Tape and reel • (Blank) = Trays

2.4 Example

This is an example part number:

MK51N512VMD100

3 Terminology and guidelines

3.1 Definition: Operating requirement

An *operating requirement* is a specified value or range of values for a technical characteristic that you must guarantee during operation to avoid incorrect operation and possibly decreasing the useful life of the chip.

3.1.1 Example

This is an example of an operating requirement, which you must meet for the accompanying operating behaviors to be guaranteed:

Symbol	Description	Min.	Max.	Unit
V _{DD}	1.0 V core supply voltage	0.9	1.1	V

3.2 Definition: Operating behavior

An *operating behavior* is a specified value or range of values for a technical characteristic that are guaranteed during operation if you meet the operating requirements and any other specified conditions.

3.2.1 Example

This is an example of an operating behavior, which is guaranteed if you meet the accompanying operating requirements:

Symbol	Description	Min.	Max.	Unit
I _{WP}	Digital I/O weak pullup/pulldown current	10	130	μA

3.3 Definition: Attribute

An *attribute* is a specified value or range of values for a technical characteristic that are guaranteed, regardless of whether you meet the operating requirements.

3.3.1 Example

This is an example of an attribute:

Symbol	Description	Min.	Max.	Unit
CIN_D	Input capacitance: digital pins	—	7	pF

3.4 Definition: Rating

A *rating* is a minimum or maximum value of a technical characteristic that, if exceeded, may cause permanent chip failure:

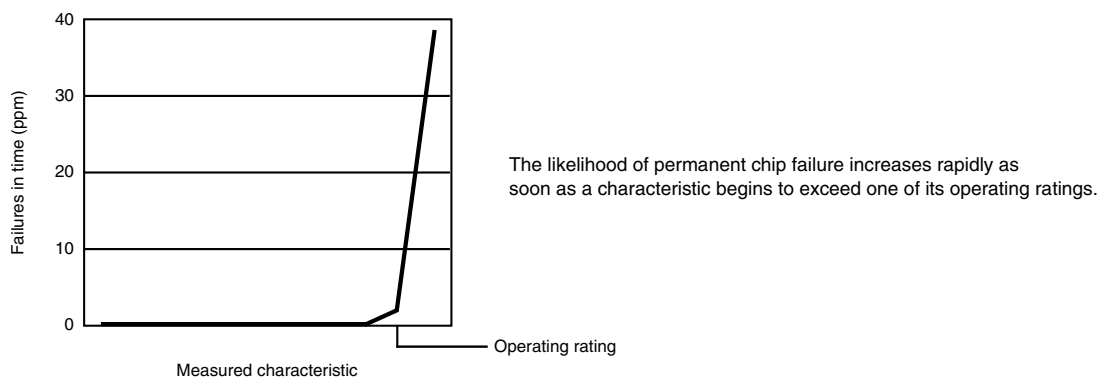
- *Operating ratings* apply during operation of the chip.
- *Handling ratings* apply when the chip is not powered.

3.4.1 Example

This is an example of an operating rating:

Symbol	Description	Min.	Max.	Unit
V _{DD}	1.0 V core supply voltage	−0.3	1.2	V

3.5 Result of exceeding a rating



3.6 Relationship between ratings and operating requirements

Operating or handling rating (min.)		Operating requirement (min.)		Operating requirement (max.)		Operating or handling rating (max.)	
Fatal range - Probable permanent failure	Limited operating range - No permanent failure - Possible decreased life - Possible incorrect operation	Normal operating range - No permanent failure - Correct operation	Limited operating range - No permanent failure - Possible decreased life - Possible incorrect operation	Handling range - No permanent failure		Fatal range - Probable permanent failure	

3.7 Guidelines for ratings and operating requirements

Follow these guidelines for ratings and operating requirements:

- Never exceed any of the chip's ratings.
- During normal operation, don't exceed any of the chip's operating requirements.
- If you must exceed an operating requirement at times other than during normal operation (for example, during power sequencing), limit the duration as much as possible.

3.8 Definition: Typical value

A *typical value* is a specified value for a technical characteristic that:

- Lies within the range of values specified by the operating behavior
- Given the typical manufacturing process, is representative of that characteristic during operation when you meet the typical-value conditions or other specified conditions

Typical values are provided as design guidelines and are neither tested nor guaranteed.

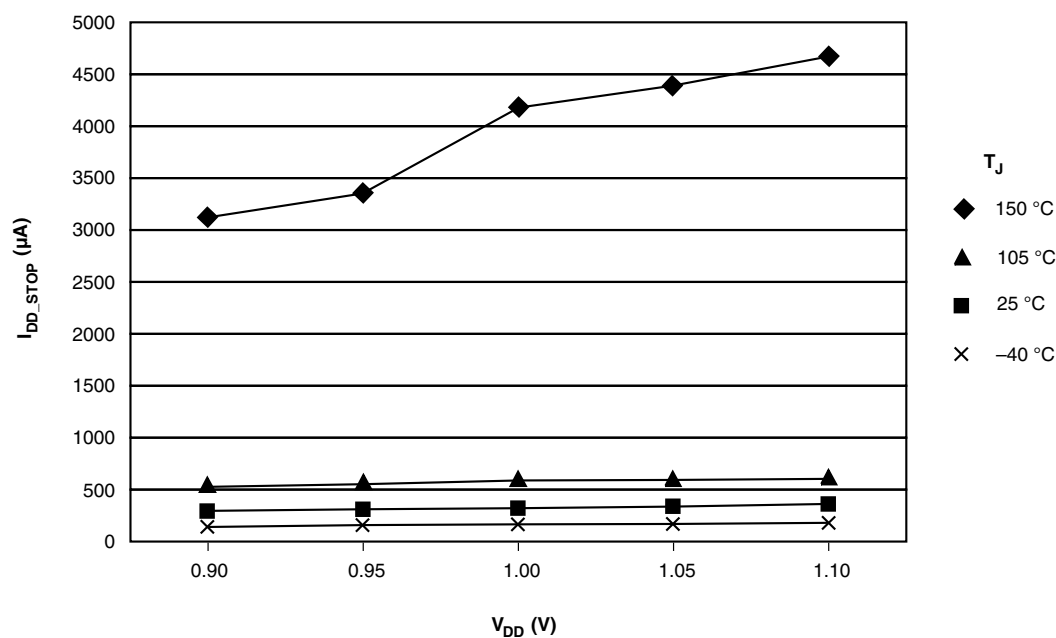
3.8.1 Example 1

This is an example of an operating behavior that includes a typical value:

Symbol	Description	Min.	Typ.	Max.	Unit
I_{WP}	Digital I/O weak pullup/pulldown current	10	70	130	μA

3.8.2 Example 2

This is an example of a chart that shows typical values for various voltage and temperature conditions:



3.9 Typical value conditions

Typical values assume you meet the following conditions (or other conditions as specified):

Symbol	Description	Value	Unit
T_A	Ambient temperature	25	°C
V_{DD}	3.3 V supply voltage	3.3	V

4 Ratings

4.1 Thermal handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
T _{STG}	Storage temperature	–55	150	°C	1
T _{SDR}	Solder temperature, lead-free	—	260	°C	2
	Solder temperature, leaded	—	245		

1. Determined according to JEDEC Standard JESD22-A103, *High Temperature Storage Life*.
2. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

4.2 Moisture handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
MSL	Moisture sensitivity level	—	3	—	1

1. Determined according to IPC/JEDEC Standard J-STD-020, *Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices*.

4.3 ESD handling ratings

Symbol	Description	Min.	Max.	Unit	Notes
V _{HBM}	Electrostatic discharge voltage, human body model	–2000	+2000	V	1
V _{CDM}	Electrostatic discharge voltage, charged-device model	–500	+500	V	2
I _{LAT}	Latch-up current at ambient temperature of 85°C	–100	+100	mA	

1. Determined according to JEDEC Standard JESD22-A114, *Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)*.
2. Determined according to JEDEC Standard JESD22-C101, *Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components*.

4.4 Voltage and current operating ratings

Symbol	Description	Min.	Max.	Unit
V _{DD}	Digital supply voltage	–0.3	3.8	V
I _{DD}	Digital supply current	—	185	mA
V _{DIO}	Digital input voltage (except RESET, EXTAL, and XTAL)	–0.3	5.5	V

Table continues on the next page...

Symbol	Description	Min.	Max.	Unit
V_{AIO}	Analog, RESET, EXTAL, and XTAL input voltage	-0.3	$V_{DD} + 0.3$	V
I_D	Instantaneous maximum current single pin limit (applies to all port pins)	-25	25	mA
V_{DDA}	Analog supply voltage	$V_{DD} - 0.3$	$V_{DD} + 0.3$	V
V_{USB_DP}	USB_DP input voltage	-0.3	3.63	V
V_{USB_DM}	USB_DM input voltage	-0.3	3.63	V
VREGIN	USB regulator input	-0.3	6.0	V
V_{BAT}	RTC battery supply voltage	-0.3	3.8	V

5 General

5.1 Nonswitching electrical specifications

5.1.1 Voltage and current operating requirements

Table 1. Voltage and current operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V_{DD}	Supply voltage	1.71	3.6	V	
V_{DDA}	Analog supply voltage	1.71	3.6	V	
$V_{DD} - V_{DDA}$	V_{DD} -to- V_{DDA} differential voltage	-0.1	0.1	V	
$V_{SS} - V_{SSA}$	V_{SS} -to- V_{SSA} differential voltage	-0.1	0.1	V	
V_{BAT}	RTC battery supply voltage	1.71	3.6	V	
V_{IH}	Input high voltage $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$ $1.7\text{ V} \leq V_{DD} \leq 2.7\text{ V}$	$0.7 \times V_{DD}$	—	V	
		$0.75 \times V_{DD}$	—	V	
V_{IL}	Input low voltage $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$ $1.7\text{ V} \leq V_{DD} \leq 2.7\text{ V}$	—	$0.35 \times V_{DD}$	V	
		—	$0.3 \times V_{DD}$	V	
V_{HYS}	Input hysteresis	$0.06 \times V_{DD}$	—	V	

Table continues on the next page...

Table 1. Voltage and current operating requirements (continued)

Symbol	Description	Min.	Max.	Unit	Notes
I_{IC}	DC injection current — single pin • $V_{IN} < V_{SS}$	0	-0.2	mA	1
	DC injection current — total MCU limit, includes sum of all stressed pins • $V_{IN} < V_{SS}$	0	-5	mA	1
V_{RAM}	V_{DD} voltage required to retain RAM	1.2	—	V	
V_{RFVBAT}	V_{BAT} voltage required to retain the VBAT register file	TBD	—	V	

1. All functional non-supply pins are internally clamped to V_{SS} , and induce an injection current when V_{IN} is less than V_{SS} . The I_{IC} maximum operating requirement should not be exceeded. If this requirement cannot be met, the input must be current limited to the value specified.

5.1.2 LVD and POR operating requirements

Table 2. V_{DD} supply LVD and POR operating requirements

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V_{POR}	Falling VDD POR detect voltage	TBD	1.1	TBD	V	
V_{LVDH}	Falling low-voltage detect threshold — high range (LVDV=01)	TBD	2.56	TBD	V	
V_{LW1H}	Low-voltage warning thresholds — high range • Level 1 falling (LVWV=00) • Level 2 falling (LVWV=01) • Level 3 falling (LVWV=10) • Level 4 falling (LVWV=11)	TBD	2.70	TBD	V	1
V_{LW2H}		TBD	2.80	TBD	V	
V_{LW3H}		TBD	2.90	TBD	V	
V_{LW4H}		TBD	3.00	TBD	V	
V_{HYSH}	Low-voltage inhibit reset/recover hysteresis — high range		60		mV	
V_{LVDL}	Falling low-voltage detect threshold — low range (LVDV=00)	TBD	1.60	TBD	V	
V_{LW1L}	Low-voltage warning thresholds — low range • Level 1 falling (LVWV=00) • Level 2 falling (LVWV=01) • Level 3 falling (LVWV=10) • Level 4 falling (LVWV=11)	TBD	1.80	TBD	V	1
V_{LW2L}		TBD	1.90	TBD	V	
V_{LW3L}		TBD	2.00	TBD	V	
V_{LW4L}		TBD	2.10	TBD	V	
V_{HYSL}	Low-voltage inhibit reset/recover hysteresis — low range		40		mV	
V_{BG}	Bandgap voltage reference	TBD	1.00	TBD	V	
t_{LPO}	Internal low power oscillator period factory trimmed	TBD	1000	TBD	μ s	

1. Rising thresholds are falling threshold + hysteresis voltage

Table 3. VBAT power operating requirements

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{POR_VBAT}	Falling VBAT supply POR detect voltage	TBD	1.1	TBD	V	

5.1.3 Voltage and current operating behaviors

Table 4. Voltage and current operating behaviors

Symbol	Description	Min.	Max.	Unit	Notes
V _{OH}	Output high voltage — high drive strength				
	• $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OH} = -10\text{mA}$	$V_{DD} - 0.5$	—	V	
	• $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OH} = -3\text{mA}$	$V_{DD} - 0.5$	—	V	
	Output high voltage — low drive strength				
	• $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OH} = -2\text{mA}$	$V_{DD} - 0.5$	—	V	
	• $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OH} = -0.6\text{mA}$	$V_{DD} - 0.5$	—	V	
I _{OHT}	Output high current total for all ports	—	100	mA	
V _{OL}	Output low voltage — high drive strength				
	• $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OL} = 10\text{mA}$	—	0.5	V	
	• $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OL} = 3\text{mA}$	—	0.5	V	
	Output low voltage — low drive strength				
	• $2.7\text{ V} \leq V_{DD} \leq 3.6\text{ V}$, $I_{OL} = 2\text{mA}$	—	0.5	V	
	• $1.71\text{ V} \leq V_{DD} \leq 2.7\text{ V}$, $I_{OL} = 0.6\text{mA}$	—	0.5	V	
I _{OLT}	Output low current total for all ports	—	100	mA	
I _{IN}	Input leakage current (per pin) except TRI0_DM, TRI0_DP, TRI1_DM, TRI1_DP	—	1	μA	1
I _{ILKG_A}	Input leakage current (per pin) for TRI0_DM, TRI0_DP, TRI1_DM, TRI1_DP	—	1	nA	1
I _{OZ}	Hi-Z (off-state) leakage current (per pin)	—	1	μA	
R _{PU}	Internal pullup resistors	30	50	kΩ	2
R _{PD}	Internal pulldown resistors	30	50	kΩ	3

1. Measured at V_{DD}=3.6V
2. Measured at V_{DD} supply voltage = V_{DD} min and V_{input} = V_{SS}
3. Measured at V_{DD} supply voltage = V_{DD} min and V_{input} = V_{DD}

5.1.4 Power mode transition operating behaviors

All specifications except t_{POR} , and VLLSx→RUN recovery times in the following table assume this clock configuration:

- CPU and system clocks = 100 MHz
- Bus clock = 50 MHz
- Flash clock = 25 MHz

Table 5. Power mode transition operating behaviors

Symbol	Description	Min.	Max.	Unit	Notes
t_{POR}	After a POR event, amount of time from the point V_{DD} reaches 1.8V to execution of the first instruction across the operating temperature range of the chip.	—	300	μs	1
	RUN → VLLS1 → RUN				
	• RUN → VLLS1	—	4.1	μs	
	• VLLS1 → RUN	—	123.8	μs	
	RUN → VLLS2 → RUN				
	• RUN → VLLS2	—	4.1	μs	
	• VLLS2 → RUN	—	49.3	μs	
	RUN → VLLS3 → RUN				
	• RUN → VLLS3	—	4.1	μs	
	• VLLS3 → RUN	—	49.2	μs	
	RUN → LLS → RUN				
	• RUN → LLS	—	4.1	μs	
	• LLS → RUN	—	5.9	μs	
	RUN → STOP → RUN				
	• RUN → STOP	—	4.1	μs	
	• STOP → RUN	—	4.2	μs	
	RUN → VLPS → RUN				
	• RUN → VLPS	—	4.1	μs	
	• VLPS → RUN	—	5.8	μs	

1. Normal boot (FTFL_OPT[LPBOOT]=1)

5.1.5 Power consumption operating behaviors

Table 6. Power consumption operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I _{DDA}	Analog supply current	—	—	TBD	mA	1
I _{DD_RUN}	Run mode current — all peripheral clocks disabled, code executing from flash	—	40	TBD	mA	2
		—	42	TBD	mA	
I _{DD_RUN}	Run mode current — all peripheral clocks enabled, code executing from flash	—	55	TBD	mA	3
		—	56	TBD	mA	
I _{DD_RUN_M AX}	Run mode current — all peripheral clocks enabled and peripherals active, code executing from flash	—	85	TBD	mA	4
		—	85	TBD	mA	
I _{DD_WAIT}	Wait mode high frequency current at 3.0 V — all peripheral clocks disabled	—	35	TBD	mA	2
I _{DD_WAIT}	Wait mode reduced frequency current at 3.0 V — all peripheral clocks disabled	—	15	TBD	mA	5
I _{DD_STOP}	Stop mode current at 3.0 V	—	0.4	TBD	mA	
I _{DD_VLPR}	Very-low-power run mode current at 3.0 V — all peripheral clocks disabled	—	1.25	TBD	mA	6
I _{DD_VLPR}	Very-low-power run mode current at 3.0 V — all peripheral clocks enabled	—	TBD	TBD	mA	7
I _{DD_VLPW}	Very-low-power wait mode current at 3.0 V	—	1.05	TBD	mA	8
I _{DD_VLPS}	Very-low-power stop mode current at 3.0 V	—	50	TBD	μA	
I _{DD_LLS}	Low leakage stop mode current at 3.0 V	—	12	TBD	μA	
I _{DD_VLLS3}	Very low-leakage stop mode 3 current at 3.0 V	—	6	TBD	μA	
		—	6	TBD	μA	
I _{DD_VLLS2}	Very low-leakage stop mode 2 current at 3.0 V	—	4	TBD	μA	
I _{DD_VLLS1}	Very low-leakage stop mode 1 current at 3.0 V	—	2	TBD	μA	
I _{DD_VBAT}	Average current when CPU is not accessing RTC registers at 3.0 V	—	550	TBD	nA	9

1. The analog supply current is the sum of the active or disabled current for each of the analog modules on the device. See each module's specification for its supply current.
2. 100MHz core and system clock, 50MHz bus clock, and 25MHz flash clock . MCG configured for FEI mode. All peripheral clocks disabled.
3. 100MHz core and system clock, 50MHz bus clock, and 25MHz flash clock. MCG configured for FEI mode. All peripheral clocks enabled, but peripherals are not in active operation.
4. 100MHz core and system clock, 50MHz bus clock, and 25MHz flash clock. MCG configured for FEI mode. All peripheral clocks enabled, and peripherals are in active operation.

General

- 25MHz core and system clock, 25MHz bus clock, and 12.5MHz flash clock. MCG configured for FEI mode.
- 2 MHz core, system, and bus clock and 1MHz flash clock. MCG configured for fast IRCLK mode. All peripheral clocks disabled. Code executing from flash.
- 2 MHz core, system, and bus clock and 1MHz flash clock. MCG configured for fast IRCLK mode. All peripheral clocks enabled but peripherals are not in active operation. Code executing from flash.
- 2 MHz core, system, and bus clock and 1MHz flash clock. MCG configured for fast IRCLK mode. All peripheral clocks disabled.
- Includes 32kHz oscillator current and RTC operation.

5.1.5.1 Diagram: Typical IDD_RUN operating behavior

The following data was measured under these conditions:

- MCG in FEI mode (39.0625 kHz IRC), except for 1 MHz core (FBE)
- All peripheral clocks disabled except FTFL
- LVD disabled, USB regulator disabled
- No GPIOs toggled
- Code execution from flash

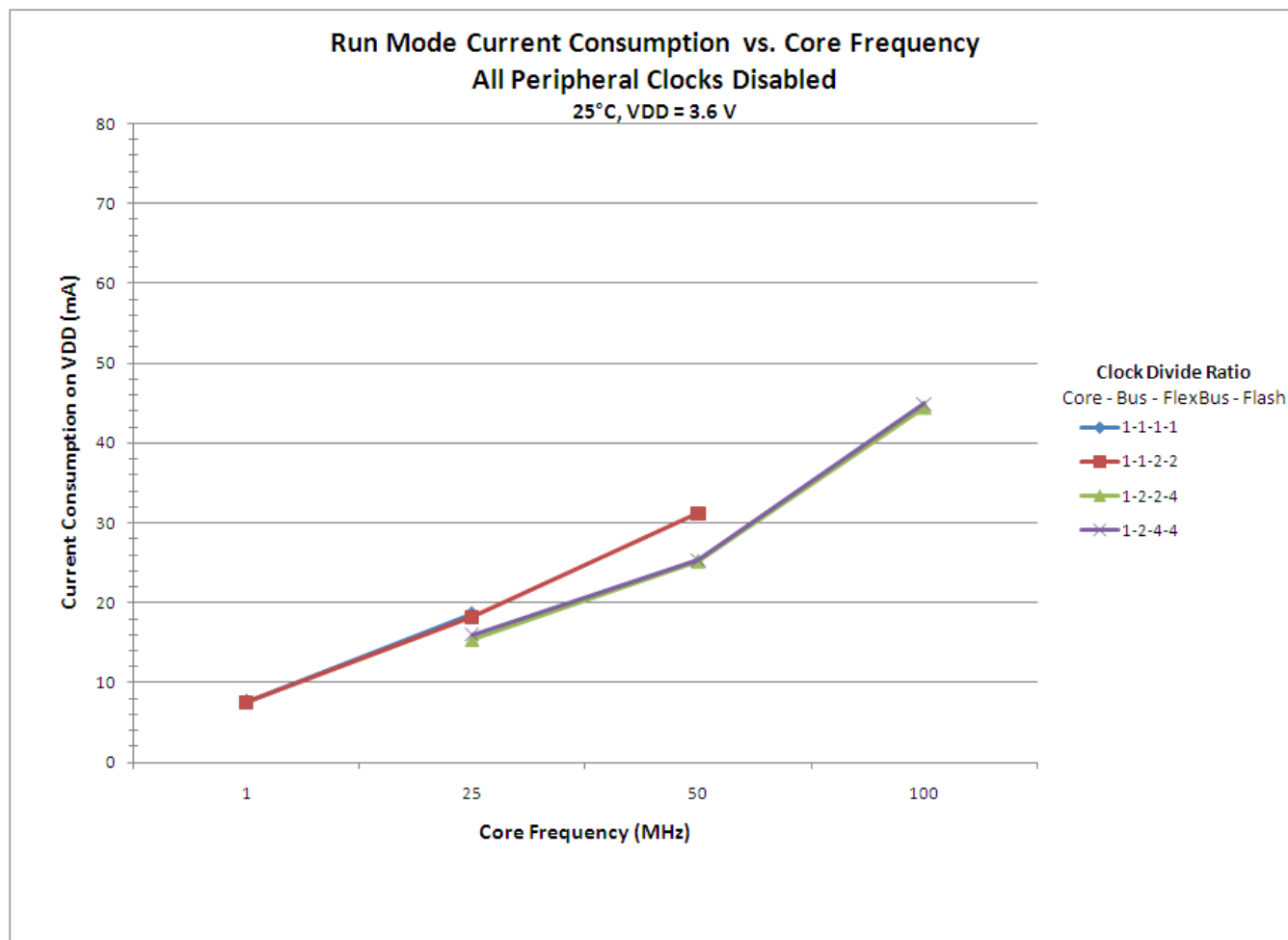


Figure 1. Run mode supply current vs. core frequency — all peripheral clocks disabled

The following data was measured under these conditions:

- MCG in FEI mode (39.0625 kHz IRC), except for 1 MHz core (FBE)
- All peripheral clocks enabled but peripherals are not in active operation
- LVD disabled, USB regulator disabled
- No GPIOs toggled
- Code execution from flash

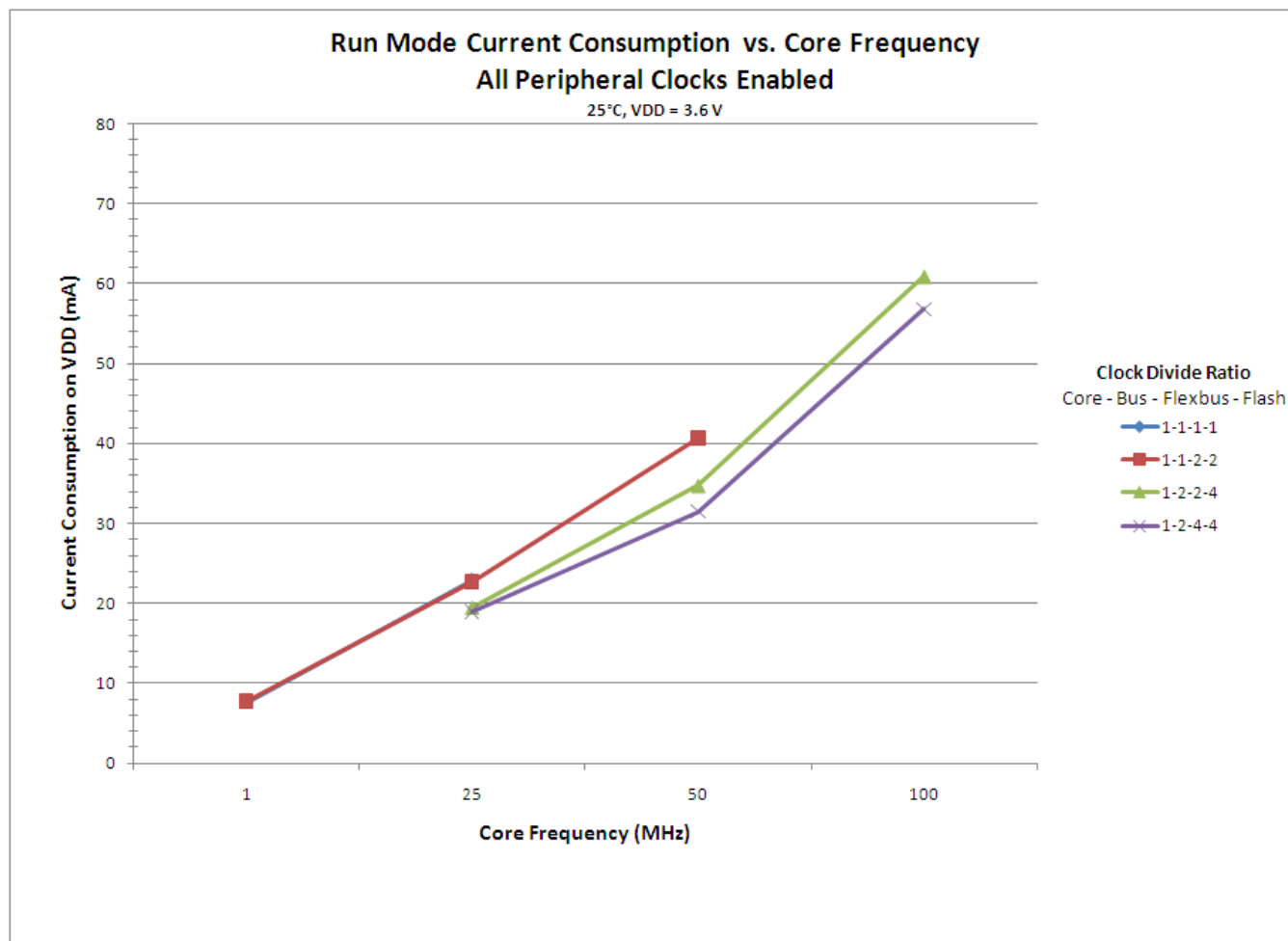


Figure 2. Run mode supply current vs. core frequency — all peripheral clocks enabled

5.1.6 EMC radiated emissions operating behaviors

Table 7. EMC radiated emissions operating behaviors

Symbol	Description	Frequency band (MHz)	Typ.	Unit	Notes
V _{RE1}	Radiated emissions voltage, band 1	0.15–50	TBD	dBμV	1, 2
V _{RE2}	Radiated emissions voltage, band 2	50–150	TBD		
V _{RE3}	Radiated emissions voltage, band 3	150–500	TBD		
V _{RE4}	Radiated emissions voltage, band 4	500–1000	TBD		
V _{RE_IEC_SAE}	IEC and SAE level	0.15–1000	TBD	—	2, 3

1. Determined according to IEC Standard 61967-1, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 1: General Conditions and Definitions*, IEC Standard 61967-2, *Integrated Circuits - Measurement of Electromagnetic Emissions, 150 kHz to 1 GHz Part 2: Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*, and SAE Standard J1752-3, *Measurement of Radiated Emissions from Integrated Circuits—TEM/ Wideband TEM (GTEM) Cell Method*.
2. V_{DD} = 3 V, T_A = 25 °C, f_{OSC} = 12 MHz (crystal), f_{SYS} = 96 MHz
3. Specified according to Annex D of IEC Standard 61967-2, *Measurement of Radiated Emissions—TEM Cell and Wideband TEM Cell Method*, and Appendix D of SAE Standard J1752-3, *Measurement of Radiated Emissions from Integrated Circuits—TEM/Wideband TEM (GTEM) Cell Method*.

5.1.7 Designing with radiated emissions in mind

To find application notes that provide guidance on designing your system to minimize interference from radiated emissions:

1. Go to <http://www.freescale.com>.
2. Perform a keyword search for “EMC design.”

5.1.8 Capacitance attributes

Table 8. Capacitance attributes

Symbol	Description	Min.	Max.	Unit
C _{IN_A}	Input capacitance: analog pins	—	7	pF
C _{IN_D}	Input capacitance: digital pins	—	7	pF

5.2 Switching specifications

5.2.1 Device clock specifications

Symbol	Description	Min.	Max.	Unit	Notes
Normal run mode					
f_{SYS}	System and core clock	—	100	MHz	
$f_{\text{SYS_USB}}$	System and core clock when USB in operation	20	—	MHz	
f_{BUS}	Bus clock	—	50	MHz	
f_{FLASH}	Flash clock	—	25	MHz	
VLPR mode					
f_{SYS}	System and core clock	—	2	MHz	
f_{BUS}	Bus clock	—	2	MHz	
f_{FLASH}	Flash clock	—	1	MHz	

5.2.2 General switching specifications

These general purpose specifications apply to all signals configured for GPIO, UART, CMT, and I²C signals.

Symbol	Description	Min.	Max.	Unit	Notes
	GPIO pin interrupt pulse width (digital glitch filter disabled) — Synchronous path	1.5	—	Bus clock cycles	1
	GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter enabled) — Asynchronous path	100	—	ns	2
	GPIO pin interrupt pulse width (digital glitch filter disabled, analog filter disabled) — Asynchronous path	16	—	ns	2
	External reset pulse width (digital glitch filter disabled)	TBD	—		
	Mode select (EZP_CS) hold time after reset deassertion	2	—	Bus clock cycles	
	Port rise and fall time (high drive strength) - Slew disabled - Slew enabled	— —	12 36	ns ns	3
	Port rise and fall time (low drive strength) - Slew disabled - Slew enabled	— —	32 36	ns ns	4

1. The greater synchronous and asynchronous timing must be met.
2. This is the shortest pulse that is guaranteed to be recognized.
3. 75pF load
4. 15pF load

5.3 Thermal specifications

5.3.1 Thermal operating requirements

Table 9. Thermal operating requirements

Symbol	Description	Min.	Max.	Unit
T_J	Die junction temperature	−40	125	°C
T_A	Ambient temperature	−40	85	°C

5.3.2 Thermal attributes

Board type	Symbol	Description	81 MAPBGA	80 LQFP	Unit	Notes
Single-layer (1s)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	TBD	TBD	°C/W	1
Four-layer (2s2p)	$R_{\theta JA}$	Thermal resistance, junction to ambient (natural convection)	TBD	TBD	°C/W	1
Single-layer (1s)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	TBD	TBD	°C/W	1
Four-layer (2s2p)	$R_{\theta JMA}$	Thermal resistance, junction to ambient (200 ft./min. air speed)	TBD	TBD	°C/W	1
—	$R_{\theta JB}$	Thermal resistance, junction to board	TBD	TBD	°C/W	2
—	$R_{\theta JC}$	Thermal resistance, junction to case	TBD	TBD	°C/W	3
—	Ψ_{JT}	Thermal characterization parameter, junction to package top outside center (natural convection)	TBD	TBD	°C/W	4

1. Determined according to JEDEC Standard JESD51-2, *Integrated Circuits Thermal Test Method Environmental Conditions—Natural Convection (Still Air)*, or EIA/JEDEC Standard JESD51-6, *Integrated Circuit Thermal Test Method Environmental Conditions—Forced Convection (Moving Air)*.

6 Peripheral operating requirements and behaviors

All digital I/O switching characteristics assume:

1. output pins
 - have $C_L=30\text{pF}$ loads,
 - are configured for fast slew rate ($\text{PORTx_PCRn[SRE]}=0$), and
 - are configured for high drive strength ($\text{PORTx_PCRn[DSE]}=1$)
2. input pins

- have their passive filter disabled (PORTx_PCRn[PFE]=0)

6.1 Core modules

6.1.1 Debug trace timing specifications

Table 10. Debug trace operating behaviors

Symbol	Description	Min.	Max.	Unit
T_{cyc}	Clock period	Frequency dependent		MHz
T_{wl}	Low pulse width	2	—	ns
T_{wh}	High pulse width	2	—	ns
T_r	Clock and data rise time	—	3	ns
T_f	Clock and data fall time	—	3	ns
T_s	Data setup	3	—	ns
T_h	Data hold	2	—	ns

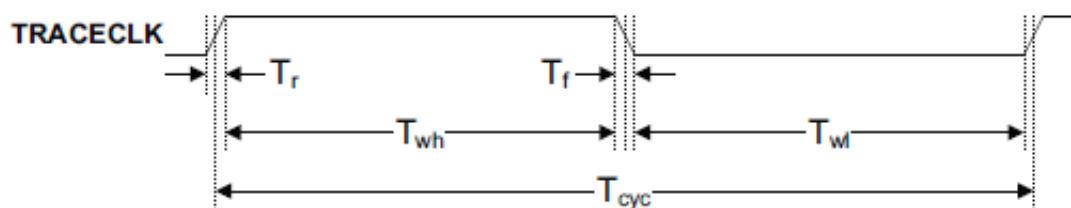


Figure 3. TRACE_CLKOUT specifications

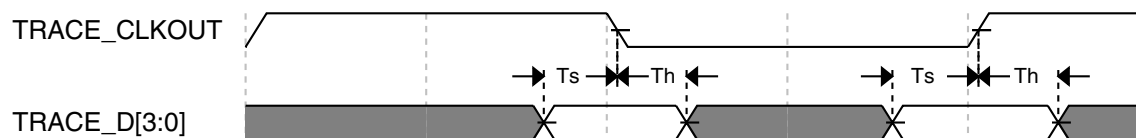


Figure 4. Trace data specifications

6.1.2 JTAG electricals

Table 11. JTAG limited voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
J1	TCLK frequency of operation - Boundary Scan - JTAG and CJTAG - Serial Wire Debug	0 0 0	10 25 50	MHz
J2	TCLK cycle period	1/J1	—	ns
J3	TCLK clock pulse width - Boundary Scan - JTAG and CJTAG - Serial Wire Debug	50 20 10	— — —	ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	0	—	ns
J7	TCLK low to boundary scan output data valid	—	25	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1	—	ns
J11	TCLK low to TDO data valid	—	17	ns
J12	TCLK low to TDO high-Z	—	17	ns
J13	$\overline{\text{TRST}}$ assert time	100	—	ns
J14	$\overline{\text{TRST}}$ setup time (negation) to TCLK high	8	—	ns

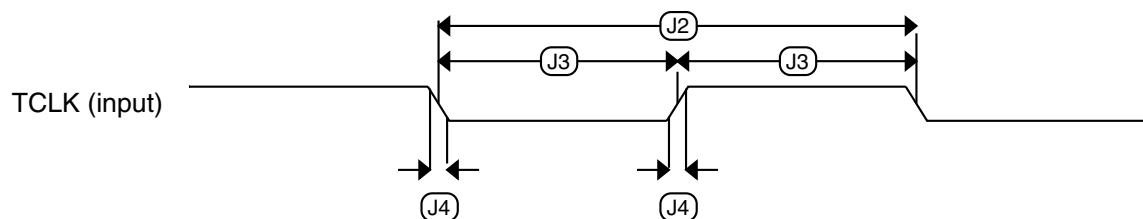
Table 12. JTAG full voltage range electricals

Symbol	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
J1	TCLK frequency of operation - Boundary Scan - JTAG and CJTAG - Serial Wire Debug	0 0 0	10 20 40	MHz
J2	TCLK cycle period	1/J1	—	ns

Table continues on the next page...

Table 12. JTAG full voltage range electricals (continued)

Symbol	Description	Min.	Max.	Unit
J3	TCLK clock pulse width - Boundary Scan - JTAG and CJTAG - Serial Wire Debug	50 25 12.5	—	ns
J4	TCLK rise and fall times	—	3	ns
J5	Boundary scan input data setup time to TCLK rise	20	—	ns
J6	Boundary scan input data hold time after TCLK rise	0	—	ns
J7	TCLK low to boundary scan output data valid	—	25	ns
J8	TCLK low to boundary scan output high-Z	—	25	ns
J9	TMS, TDI input data setup time to TCLK rise	8	—	ns
J10	TMS, TDI input data hold time after TCLK rise	1.4	—	ns
J11	TCLK low to TDO data valid	—	22.1	ns
J12	TCLK low to TDO high-Z	—	22.1	ns
J13	$\overline{\text{TRST}}$ assert time	100	—	ns
J14	$\overline{\text{TRST}}$ setup time (negation) to TCLK high	8	—	ns

**Figure 5. Test clock input timing**

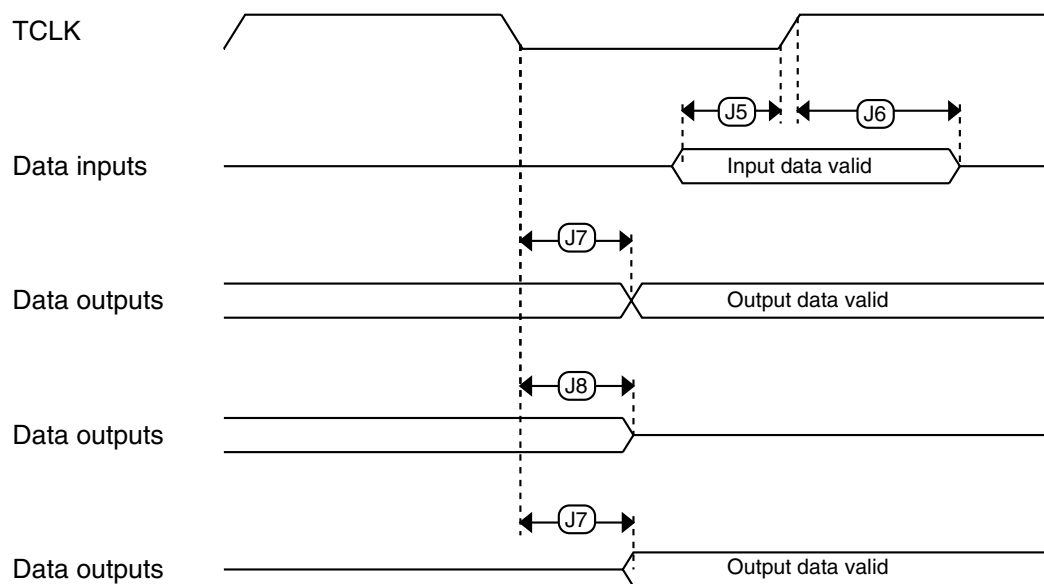


Figure 6. Boundary scan (JTAG) timing

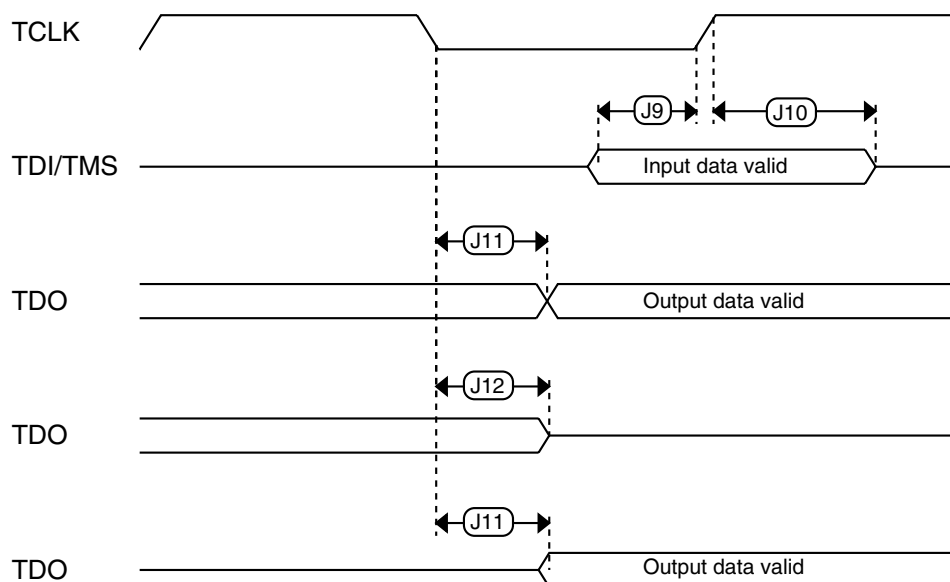


Figure 7. Test Access Port timing

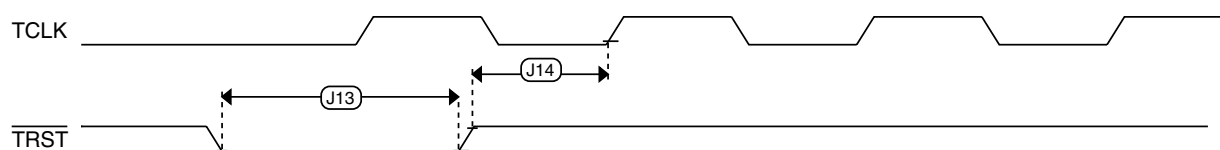


Figure 8. TRST timing

6.2 System modules

There are no specifications necessary for the device's system modules.

6.3 Clock modules

6.3.1 MCG specifications

Table 13. MCG specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$f_{\text{ints_ft}}$	Internal reference frequency (slow clock) — factory trimmed at nominal VDD and 25°C	—	32.768	—	kHz	
$f_{\text{ints_t}}$	Internal reference frequency (slow clock) — user trimmed	31.25	—	39.0625	kHz	
I_{ints}	Internal reference (slow clock) current	—	TBD	—	μA	
t_{refsts}	Internal reference (slow clock) startup time	—	TBD	4	μs	
$\Delta f_{\text{dco_res_t}}$	Resolution of trimmed DCO output frequency at fixed voltage and temperature — using SCTRIM and SCFTRIM	—	± 0.1	± 0.3	% f_{dco}	1
$\Delta f_{\text{dco_res_t}}$	Resolution of trimmed DCO output frequency at fixed voltage and temperature — using SCTRIM only	—	± 0.2	± 0.5	% f_{dco}	1
$\Delta f_{\text{dco_t}}$	Total deviation of trimmed average DCO output frequency over voltage and temperature	—	+ 0.5 - 1.0	± 3.5	% f_{dco}	1
$\Delta f_{\text{dco_t}}$	Total deviation of trimmed average DCO output frequency over fixed voltage and temperature range of 0–70°C	—	± 0.5	± TBD	% f_{dco}	1
$f_{\text{intf_ft}}$	Internal reference frequency (fast clock) — factory trimmed at nominal VDD and 25°C	3.4	—	4	MHz	
$f_{\text{intf_t}}$	Internal reference frequency (fast clock) — user trimmed	3	—	5	MHz	

Table continues on the next page...

Table 13. MCG specifications (continued)

Symbol	Description		Min.	Typ.	Max.	Unit	Notes
I _{intf}	Internal reference (fast clock) current		—	TBD	—	μA	
t _{irefstf}	Internal reference startup time (fast clock)		—	TBD	TBD	μs	
f _{loc_low}	Loss of external clock minimum frequency — RANGE = 00		(3/5) x f _{ints_t}	—	—	kHz	
f _{loc_high}	Loss of external clock minimum frequency — RANGE = 01, 10, or 11		(16/5) x f _{ints_t}	—	—	kHz	
FLL							
f _{fill_ref}	FLL reference frequency range		31.25	—	39.0625	kHz	
f _{dco}	DCO output frequency range	Low range (DRS=00) 640 × f _{fill_ref}	20	20.97	25	MHz	2, 3
		Mid range (DRS=01) 1280 × f _{fill_ref}	40	41.94	50	MHz	
		Mid-high range (DRS=10) 1920 × f _{fill_ref}	60	62.91	75	MHz	
		High range (DRS=11) 2560 × f _{fill_ref}	80	83.89	100	MHz	
f _{dco_t_DMX3} 2	DCO output frequency	Low range (DRS=00) 732 × f _{fill_ref}	—	23.99	—	MHz	4, 5
		Mid range (DRS=01) 1464 × f _{fill_ref}	—	47.97	—	MHz	
		Mid-high range (DRS=10) 2197 × f _{fill_ref}	—	71.99	—	MHz	
		High range (DRS=11) 2929 × f _{fill_ref}	—	95.98	—	MHz	
J _{cyc_fill}	FLL period jitter		—	TBD	TBD	ps	6
J _{acc_fill}	FLL accumulated jitter of DCO output over a 1μs time window		—	TBD	TBD	ps	6
t _{fill_acquire}	FLL target frequency acquisition time		—	—	1	ms	7
PLL							
f _{vco}	VCO operating frequency		48.0	—	100	MHz	
I _{pll}	PLL operating current PLL @ 96 MHz (f_{osc_hi_1}=8MHz, f_{pll_ref}=2MHz, VDIV multiplier=48)		—	950	—	μA	8
f _{pll_ref}	PLL reference frequency range		2.0	—	4.0	MHz	
J _{cyc_pll}	PLL period jitter		—	400	—	ps	9, 10
J _{acc_pll}	PLL accumulated jitter over 1μs window		—	TBD	—	ps	9, 10

Table continues on the next page...

Table 13. MCG specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
D _{lock}	Lock entry frequency tolerance	± 1.49	—	± 2.98	%	
D _{unl}	Lock exit frequency tolerance	± 4.47	—	± 5.97	%	
t _{pll_lock}	Lock detector detection time	—	—	0.15 + 1075(1/ f _{pll_ref})	ms	11

1. This parameter is measured with the internal reference (slow clock) being used as a reference to the FLL (FEI clock mode).
2. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32=0.
3. The resulting system clock frequencies should not exceed their maximum specified values. The DCO frequency deviation (Δf_{dco_t}) over voltage and temperature should be considered.
4. These typical values listed are with the slow internal reference clock (FEI) using factory trim and DMX32=1.
5. The resulting clock frequency must not exceed the maximum specified clock frequency of the device.
6. This specification was obtained at TBD frequency.
7. This specification applies to any time the FLL reference source or reference divider is changed, trim value is changed, DMX32 bit is changed, DRS bits are changed, or changing from FLL disabled (BLPE, BLPI) to FLL enabled (FEI, FEE, FBE, FBI). If a crystal/resonator is being used as the reference, this specification assumes it is already running.
8. Excludes any oscillator currents that are also consuming power while PLL is in operation.
9. This specification was obtained using a Freescale developed PCB. PLL jitter is dependent on the noise characteristics of each PCB and results will vary.
10. This specification was obtained at internal frequency of TBD.
11. This specification applies to any time the PLL VCO divider or reference divider is changed, or changing from PLL disabled (BLPE, BLPI) to PLL enabled (PBE, PEE). If a crystal/resonator is being used as the reference, this specification assumes it is already running.

6.3.2 Oscillator electrical specifications

This section provides the electrical characteristics of the module.

6.3.2.1 Oscillator DC electrical specifications

Table 14. Oscillator DC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{DD}	Supply voltage	1.71	—	3.6	V	
I _{DDOSC}	Supply current — low-power mode (HGO=0)					1
	• 32 kHz	—	500	—	nA	
	• 4 MHz	—	200	—	μA	
	• 8 MHz	—	300	—	μA	
	• 16 MHz	—	700	—	μA	
	• 24 MHz	—	1.2	—	mA	
	• 32 MHz	—	1.5	—	mA	

Table continues on the next page...

Table 14. Oscillator DC electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I _{DDOSC}	Supply current — high gain mode (HGO=1)					1
	• 32 kHz	—	25	—	μA	
	• 4 MHz	—	400	—	μA	
	• 8 MHz	—	800	—	μA	
	• 16 MHz	—	1.5	—	mA	
	• 24 MHz	—	3	—	mA	
	• 32 MHz	—	4	—	mA	
C _x	EXTAL load capacitance	—	—	—		2, 3
C _y	XTAL load capacitance	—	—	—		2, 3
R _F	Feedback resistor — low-frequency, low-power mode (HGO=0)	—	—	—	MΩ	2, 4
	Feedback resistor — low-frequency, high-gain mode (HGO=1)	—	10	—	MΩ	
	Feedback resistor — high-frequency, low-power mode (HGO=0)	—	—	—	MΩ	
	Feedback resistor — high-frequency, high-gain mode (HGO=1)	—	1	—	MΩ	
R _S	Series resistor — low-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — low-frequency, high-gain mode (HGO=1)	—	200	—	kΩ	
	Series resistor — high-frequency, low-power mode (HGO=0)	—	—	—	kΩ	
	Series resistor — high-frequency, high-gain mode (HGO=1)	—	0	—	kΩ	
V _{pp} ⁵	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — low-frequency, high-gain mode (HGO=1)	—	V _{DD}	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, low-power mode (HGO=0)	—	0.6	—	V	
	Peak-to-peak amplitude of oscillation (oscillator mode) — high-frequency, high-gain mode (HGO=1)	—	V _{DD}	—	V	

1. V_{DD}=3.3 V, Temperature =25 °C

2. See crystal or resonator manufacturer's recommendation

3. C_x, C_y can be provided by using either the integrated capacitors or by using external components.4. When low power mode is selected, R_F is integrated and must not be attached externally.

5. The EXTAL and XTAL pins should only be connected to required oscillator components and must not be connected to any other devices.

6.3.2.2 Oscillator frequency specifications

Table 15. Oscillator frequency specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f_{osc_lo}	Oscillator crystal or resonator frequency — low frequency mode (MCG_C2[RANGE]=00)	32	—	40	kHz	
$f_{osc_hi_1}$	Oscillator crystal or resonator frequency — high frequency mode (low range) (MCG_C2[RANGE]=01)	3	—	8	MHz	
$f_{osc_hi_2}$	Oscillator crystal or resonator frequency — high frequency mode (high range) (MCG_C2[RANGE]=1x)	8	—	32	MHz	
f_{ec_extal}	Input clock frequency (external clock mode)	—	—	50	MHz	1
t_{dc_extal}	Input clock duty cycle (external clock mode)	40	50	60	%	
t_{cst}	Crystal startup time — 32 kHz low-frequency, low-power mode (HGO=0)	—	TBD	—	ms	2, 3
	Crystal startup time — 32 kHz low-frequency, high-gain mode (HGO=1)	—	800	—	ms	
	Crystal startup time — 8 MHz high-frequency (MCG_C2[RANGE]=01), low-power mode (HGO=0)	—	4	—	ms	
	Crystal startup time — 8 MHz high-frequency (MCG_C2[RANGE]=01), high-gain mode (HGO=1)	—	3	—	ms	

1. Other frequency limits may apply when external clock is being used as a reference for the FLL or PLL.
2. Proper PC board layout procedures must be followed to achieve specifications.
3. Crystal startup time is defined as the time between the oscillator being enabled and the OSCINIT bit in the MCG_S register being set.

6.3.3 32kHz Oscillator Electrical Characteristics

This section describes the module electrical characteristics.

6.3.3.1 32kHz oscillator DC electrical specifications

Table 16. 32kHz oscillator DC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
V_{BAT}	Supply voltage	1.71	—	3.6	V
R_F	Internal feedback resistor	—	100	—	MΩ
C_{para}	Parasitical capacitance of EXTAL32 and XTAL32	—	2.5	—	pF

Table continues on the next page...

Table 16. 32kHz oscillator DC electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit
C_{load}	Internal load capacitance (programmable)	—	15	—	pF
V_{pp}	Peak-to-peak amplitude of oscillation	—	0.6	—	V

6.3.3.2 32kHz oscillator frequency specifications

Table 17. 32kHz oscillator frequency specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f_{osc_lo}	Oscillator crystal	—	32	—	kHz	
t_{start}	Crystal start-up time	—	1000	—	ms	1

1. Proper PC board layout procedures must be followed to achieve specifications.

6.4 Memories and memory interfaces

6.4.1 Flash (FTFL) electrical specifications

This section describes the electrical characteristics of the FTFL module.

6.4.1.1 Flash timing specifications — program and erase

The following specifications represent the amount of time the internal charge pumps are active and do not include command overhead.

Table 18. NVM program/erase timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{hvp\text{gm}4}$	Longword Program high-voltage time	—	20	TBD	μs	
$t_{hversscr}$	Sector Erase high-voltage time	—	20	100	ms	1
$t_{hversblk256k}$	Erase Block high-voltage time for 256 KB	—	160	800	ms	1

1. Maximum time based on expectations at cycling end-of-life.

6.4.1.2 Flash timing specifications — commands

Table 19. Flash command timing specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{rd1blk256k}$	Read 1s Block execution time • 256 KB data flash	—	—	1.4	ms	
$t_{rd1sec2k}$	Read 1s Section execution time (flash sector)	—	—	40	μ s	1
t_{pgmchk}	Program Check execution time	—	—	35	μ s	1
t_{rdsrc}	Read Resource execution time	—	—	35	μ s	1
t_{pgm4}	Program Longword execution time	—	50	TBD	μ s	
$t_{ersblk256k}$	Erase Flash Block execution time • 256 KB data flash	—	160	800	ms	2
t_{ersscr}	Erase Flash Sector execution time	—	20	100	ms	2
$t_{pgmsec512}$	Program Section execution time • 512 B flash	—	TBD	TBD	ms	
$t_{pgmsec1k}$	• 1 KB flash	—	TBD	TBD	ms	
$t_{pgmsec2k}$	• 2 KB flash	—	TBD	TBD	ms	
t_{rd1all}	Read 1s All Blocks execution time	—	—	2.8	ms	
t_{rdonce}	Read Once execution time	—	—	35	μ s	1
$t_{pgmonce}$	Program Once execution time	—	50	TBD	μ s	
t_{ersall}	Erase All Blocks execution time	—	320	1600	ms	2
t_{vfykey}	Verify Backdoor Access Key execution time	—	—	35	μ s	1
$t_{pgmpart256k}$	Program Partition for EEPROM execution time • 256 KB FlexNVM	—	175	TBD	ms	
$t_{setram32k}$	Set FlexRAM Function execution time: • 32 KB EEPROM backup	—	TBD	TBD	ms	
$t_{setram256k}$	• 256 KB EEPROM backup	—	TBD	TBD	ms	
Byte-write to FlexRAM for EEPROM operation						
$t_{eewr8bers}$	Byte-write to erased FlexRAM location execution time	—	100	TBD	μ s	3
$t_{eewr8b32k}$	Byte-write to FlexRAM execution time: • 32 KB EEPROM backup	—	TBD	TBD	ms	
$t_{eewr8b64k}$	• 64 KB EEPROM backup	—	TBD	1.5	ms	
$t_{eewr8b128k}$	• 128 KB EEPROM backup	—	TBD	TBD	ms	
$t_{eewr8b256k}$	• 256 KB EEPROM backup	—	TBD	2.5	ms	
Word-write to FlexRAM for EEPROM operation						

Table continues on the next page...

Table 19. Flash command timing specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
$t_{\text{eewr16bers}}$	Word-write to erased FlexRAM location execution time	—	100	TBD	μs	
$t_{\text{eewr16b32k}}$	Word-write to FlexRAM execution time: • 32 KB EEPROM backup	—	TBD	TBD	ms	
$t_{\text{eewr16b64k}}$	• 64 KB EEPROM backup	—	TBD	1.5	ms	
$t_{\text{eewr16b128k}}$	• 128 KB EEPROM backup	—	TBD	TBD	ms	
$t_{\text{eewr16b256k}}$	• 256 KB EEPROM backup	—	TBD	2.5	ms	
Longword-write to FlexRAM for EEPROM operation						
$t_{\text{eewr32bers}}$	Longword-write to erased FlexRAM location execution time	—	200	TBD	μs	
$t_{\text{eewr32b32k}}$	Longword-write to FlexRAM execution time: • 32 KB EEPROM backup	—	TBD	TBD	ms	
$t_{\text{eewr32b64k}}$	• 64 KB EEPROM backup	—	TBD	2.7	ms	
$t_{\text{eewr32b128k}}$	• 128 KB EEPROM backup	—	TBD	TBD	ms	
$t_{\text{eewr32b256k}}$	• 256 KB EEPROM backup	—	TBD	3.7	ms	

1. Assumes 25MHz flash clock frequency.
2. Maximum times for erase parameters based on expectations at cycling end-of-life.
3. For byte-writes to an erased FlexRAM location, the aligned word containing the byte must be erased.

6.4.1.3 Flash (FTFL) current and power specifications

Table 20. Flash (FTFL) current and power specifications

Symbol	Description	Typ.	Unit
$I_{\text{DD_PGM}}$	Worst case programming current in program flash	10	mA

6.4.1.4 Reliability specifications

Table 21. NVM reliability specifications

Symbol	Description	Min.	Typ. ¹	Max.	Unit	Notes
Program Flash						
$t_{\text{nvmretp10k}}$	Data retention after up to 10 K cycles	5	TBD	—	years	2
$t_{\text{nvmretp1k}}$	Data retention after up to 1 K cycles	10	TBD	—	years	2
$t_{\text{nvmretp100}}$	Data retention after up to 100 cycles	15	TBD	—	years	2
n_{nvmcycp}	Cycling endurance	10 K	TBD	—	cycles	3
Data Flash						
$t_{\text{nvmretd10k}}$	Data retention after up to 10 K cycles	5	TBD	—	years	2

Table continues on the next page...

Table 21. NVM reliability specifications (continued)

Symbol	Description	Min.	Typ. ¹	Max.	Unit	Notes
$t_{\text{nvmretd1k}}$	Data retention after up to 1 K cycles	10	TBD	—	years	2
$t_{\text{nvmretd100}}$	Data retention after up to 100 cycles	15	TBD	—	years	2
n_{nvmcyed}	Cycling endurance	10 K	TBD	—	cycles	3
FlexRAM as EEPROM						
$t_{\text{nvmretee100}}$	Data retention up to 100% of write endurance	5	TBD	—	years	2
$t_{\text{nvmretee10}}$	Data retention up to 10% of write endurance	10	TBD	—	years	2
$t_{\text{nvmretee1}}$	Data retention up to 1% of write endurance	15	TBD	—	years	2
	Write endurance					4
$n_{\text{nvmwree16}}$	• EEPROM backup to FlexRAM ratio = 16	35 K	TBD	—	writes	
$n_{\text{nvmwree128}}$	• EEPROM backup to FlexRAM ratio = 128	315 K	TBD	—	writes	
$n_{\text{nvmwree512}}$	• EEPROM backup to FlexRAM ratio = 512	1.27 M	TBD	—	writes	
$n_{\text{nvmwree4k}}$	• EEPROM backup to FlexRAM ratio = 4096	10 M	TBD	—	writes	
$n_{\text{nvmwree32k}}$	• EEPROM backup to FlexRAM ratio = 32,768	80 M	TBD	—	writes	

1. Typical data retention values are based on intrinsic capability of the technology measured at high temperature derated to 25°C. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618.
2. Data retention is based on $T_{\text{javg}} = 55^{\circ}\text{C}$ (temperature profile over the lifetime of the application).
3. Cycling endurance represents number of program/erase cycles at $-40^{\circ}\text{C} \leq T_j \leq 125^{\circ}\text{C}$.
4. Write endurance represents the number of writes to each FlexRAM location at $-40^{\circ}\text{C} \leq T_j \leq 125^{\circ}\text{C}$ influenced by the cycling endurance of the FlexNVM (same value as data flash) and the allocated EEPROM backup per subsystem. Minimum value assumes all byte-writes to FlexRAM.

6.4.1.5 Write endurance to FlexRAM for EEPROM

When the FlexNVM partition code is not set to full data flash, the EEPROM data set size can be set to any of several non-zero values.

The bytes not assigned to data flash via the FlexNVM partition code are used by the FTFL to obtain an effective endurance increase for the EEPROM data. The built-in EEPROM record management system raises the number of program/erase cycles that can be attained prior to device wear-out by cycling the EEPROM data through a larger EEPROM NVM storage space.

While different partitions of the FlexNVM are available, the intention is that a single choice for the FlexNVM partition code and EEPROM data set size is used throughout the entire lifetime of a given application. The EEPROM endurance equation and graph shown below assume that only one configuration is ever used.

$$\text{Writes}_{\text{subsystem}} = \frac{\text{EEPROM} - 2 \times \text{EEESPLIT} \times \text{EEESIZE}}{\text{EEESPLIT} \times \text{EEESIZE}} \times \text{Write_efficiency} \times n_{\text{nvmcyed}}$$

where

- Writes_subsystem — minimum number of writes to each FlexRAM location for subsystem (each subsystem can have different endurance)
- EEPROM — allocated FlexNVM for each EEPROM subsystem based on DEPART; entered with Program Partition command
- EEESPLIT — FlexRAM split factor for subsystem; entered with the Program Partition command
- EEESIZE — allocated FlexRAM based on DEPART; entered with Program Partition command
- Write_efficiency —
 - 0.25 for 8-bit writes to FlexRAM
 - 0.50 for 16-bit or 32-bit writes to FlexRAM
- n_{nvmcyd} — data flash cycling endurance

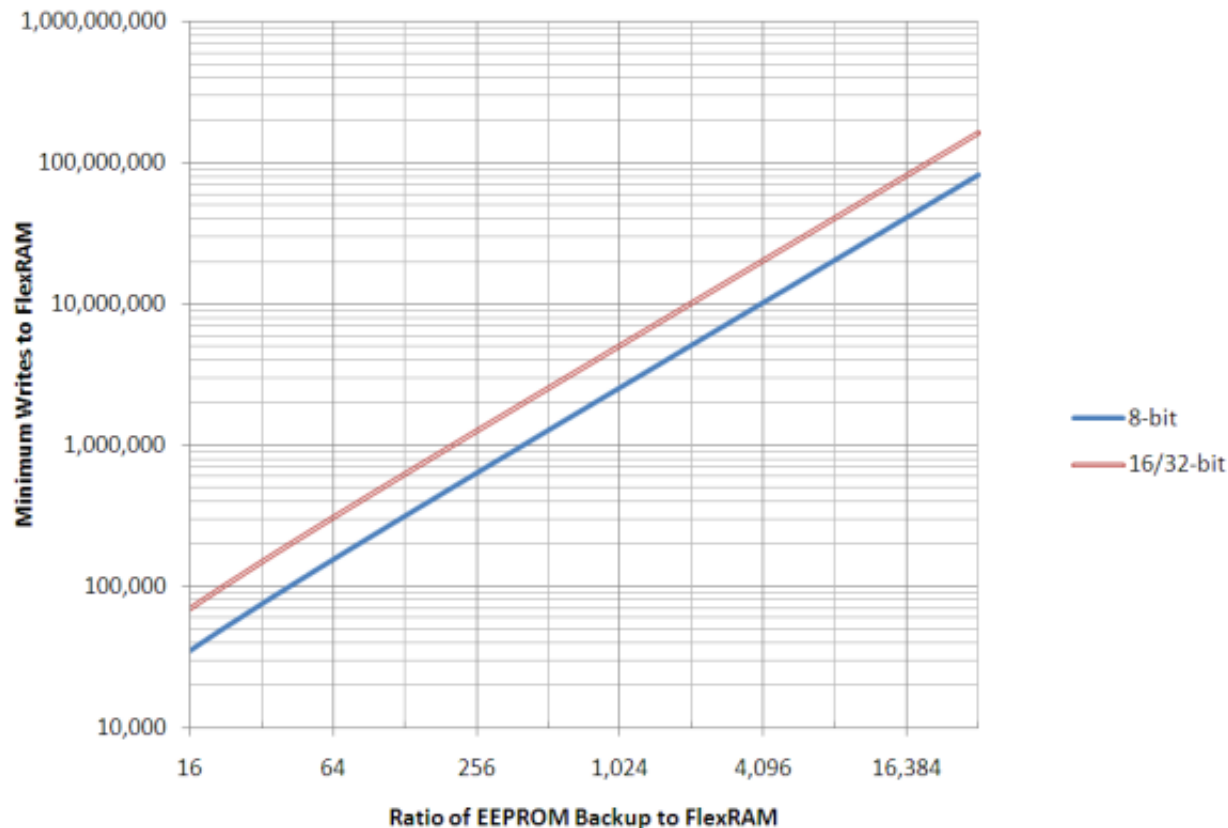


Figure 9. EEPROM backup writes to FlexRAM

6.4.2 EzPort Switching Specifications

Table 22. EzPort switching specifications

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
EP1	EZP_CK frequency of operation (all commands except READ)	—	$f_{SYS}/2$	MHz
EP1a	EZP_CK frequency of operation (READ command)	—	$f_{SYS}/8$	MHz
EP2	$\overline{\text{EZP_CS}}$ negation to next $\overline{\text{EZP_CS}}$ assertion	$2 \times t_{\text{EZP_CK}}$	—	ns
EP3	$\overline{\text{EZP_CS}}$ input valid to EZP_CK high (setup)	5	—	ns
EP4	EZP_CK high to $\overline{\text{EZP_CS}}$ input invalid (hold)	5	—	ns
EP5	EZP_D input valid to EZP_CK high (setup)	2	—	ns
EP6	EZP_CK high to EZP_D input invalid (hold)	5	—	ns
EP7	EZP_CK low to EZP_Q output valid (setup)	—	12	ns
EP8	EZP_CK low to EZP_Q output invalid (hold)	0	—	ns
EP9	$\overline{\text{EZP_CS}}$ negation to EZP_Q tri-state	—	12	ns

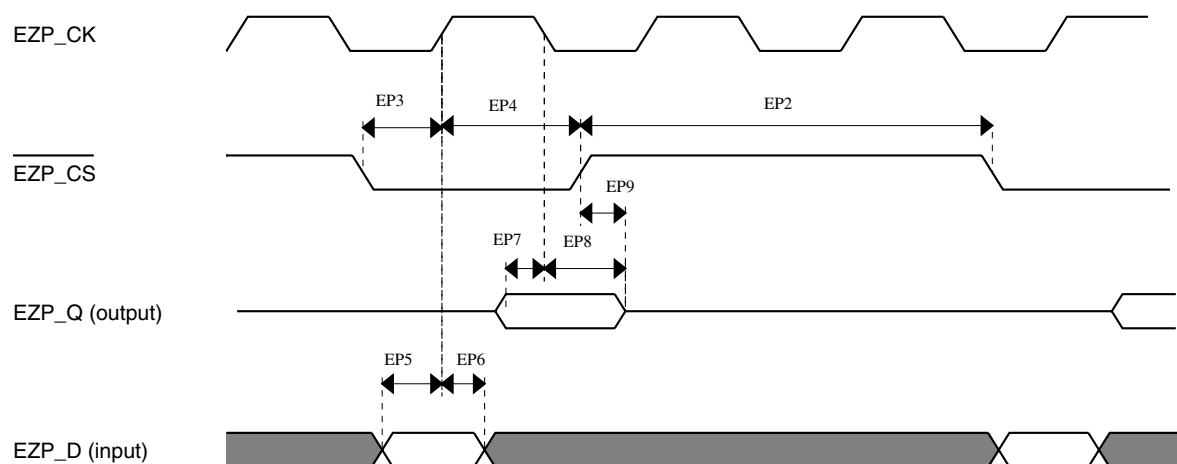


Figure 10. EzPort Timing Diagram

6.5 Security and integrity modules

There are no specifications necessary for the device's security and integrity modules.

6.6 Analog

6.6.1 ADC electrical specifications

The 16-bit accuracy specifications listed in [Table 23](#) and [Table 24](#) are achievable on the differential pins ADCx_DP0, ADCx_DM0, ADCx_DP1, ADCx_DM1, ADCx_DP3, and ADCx_DM3.

The ADCx_DP2 and ADCx_DM2 ADC inputs are used as the PGA inputs and are not direct device pins. Accuracy specifications for these pins are defined in [Table 25](#) and [Table 26](#).

All other ADC channels meet the 13-bit differential/12-bit single-ended accuracy specifications.

6.6.1.1 16-bit ADC operating conditions

Table 23. 16-bit ADC operating conditions

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
V _{DDA}	Supply voltage	Absolute	1.71	—	3.6	V	
ΔV _{DDA}	Supply voltage	Delta to V _{DD} (V _{DD} - V _{DDA})	-100	0	+100	mV	2
ΔV _{SSA}	Ground voltage	Delta to V _{SS} (V _{SS} - V _{SSA})	-100	0	+100	mV	2
V _{REFH}	ADC reference voltage high		1.13	V _{DDA}	V _{DDA}	V	
V _{REFL}	Reference voltage low		V _{SSA}	V _{SSA}	V _{SSA}	V	
V _{ADIN}	Input voltage		V _{REFL}	—	V _{REFH}	V	
C _{ADIN}	Input capacitance	• 16 bit modes	—	8	10	pF	
		• 8/10/12 bit modes	—	4	5		
R _{ADIN}	Input resistance		—	2	5	kΩ	
R _{AS}	Analog source resistance	13/12 bit modes	—	—	5	kΩ	3
		f _{ADCK} < 4MHz					
f _{ADCK}	ADC conversion clock frequency	≤13 bit modes	1.0	—	18.0	MHz	4
f _{ADCK}	ADC conversion clock frequency	16 bit modes	2.0	—	12.0	MHz	5

Table continues on the next page...

Table 23. 16-bit ADC operating conditions (continued)

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
C_{rate}	ADC conversion rate	≤ 13 bit modes No ADC hardware averaging Continuous conversions enabled Peripheral clock = 50MHz	18.484	—	818.330	Ksps	6
C_{rate}	ADC conversion rate	16 bit modes No ADC hardware averaging Continuous conversions enabled Peripheral clock = 50MHz	37.037	—	361.402	Ksps	7

1. Typical values assume $V_{DDA} = 3.0\text{ V}$, $\text{Temp} = 25^{\circ}\text{C}$, $f_{ADCK} = 1.0\text{ MHz}$ unless otherwise stated. Typical values are for reference only and are not tested in production.
2. DC potential difference.
3. This resistance is external to MCU. The analog source resistance should be kept as low as possible in order to achieve the best results. The results in this datasheet were derived from a system which has $<8\ \Omega$ analog source resistance. The R_{AS}/C_{AS} time constant should be kept to $<1\text{ ns}$.
4. In order to use the maximum ADC conversion clock frequency ADHSC bit should be set and the ADLPC should be clear.
5. In order to use the maximum ADC conversion clock frequency ADHSC bit should be set and the ADLPC should be clear.
6. For guidelines and examples of conversion rate calculation please download the ADC calculator tool http://cache.freescale.com/files/soft_dev_tools/software/app_software/converters/ADC_CALCULATOR_CNV.zip?fpsp=1
7. For guidelines and examples of conversion rate calculation please download the ADC calculator tool http://cache.freescale.com/files/soft_dev_tools/software/app_software/converters/ADC_CALCULATOR_CNV.zip?fpsp=1

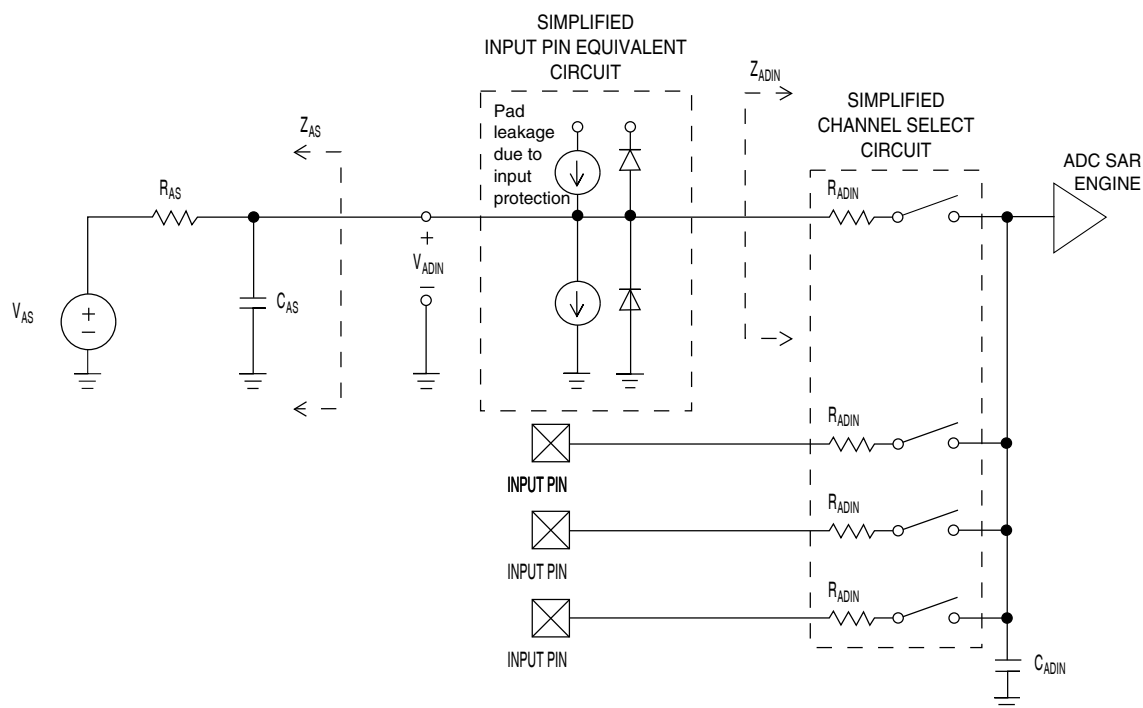


Figure 11. ADC input impedance equivalency diagram

6.6.1.2 16-bit ADC electrical characteristics

Table 24. 16-bit ADC characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$)

Symbol	Description	Conditions ¹	Min.	Typ. ²	Max.	Unit	Notes
I _{DDA}	Supply current		0.215	—	1.7	mA	3
f _{ADACK}	ADC asynchronous clock source	• ADLPC=1, ADHSC=0 • ADLPC=1, ADHSC=1 • ADLPC=0, ADHSC=0 • ADLPC=0, ADHSC=1	— — — —	2.4 4.0 5.2 6.2	— — — —	MHz MHz MHz MHz	t _{ADACK} = 1/f _{ADACK}
	Sample Time	See Reference Manual chapter for sample times					
	Conversion Time	The ADC calculator tool can be used to determine ADC conversion times for different ADC configurations: http://cache.freescale.com/files/soft_dev_tools/software/app_software/converters/ADC_CALCULATOR_CNV.zip?fp=1					
TUE	Total unadjusted error	• ≤13 bit modes • <12 bit modes		±0.8 ±0.5	±TBD ±1	LSB ⁴	ADC conversion clock <12MHz, Max hardware averaging (AVGE = %1, AVGS = %11)

Table continues on the next page...

Table 24. 16-bit ADC characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$) (continued)

Symbol	Description	Conditions ¹	Min.	Typ. ²	Max.	Unit	Notes
DNL	Differential non-linearity	• ≤ 13 bit modes • < 12 bit modes		± 0.7 ± 0.2	$\pm \text{TBD}$ ± 0.5	LSB ⁴	ADC conversion clock $< 12\text{MHz}$, Max hardware averaging (AVGE = %1, AVGS = %11)
INL	Integral non-linearity	• ≤ 13 bit modes • < 12 bit modes	— —	± 1.0 ± 0.5	$\pm \text{TBD}$ $\pm \text{TBD}$	LSB ⁴	Max averaging
E_{FS}	Full-scale error	• ≤ 13 bit modes • < 12 bit modes	— —	± 0.4 ± 1.0	$\pm \text{TBD}$ $\pm \text{TBD}$	LSB ⁴	$V_{ADIN} = V_{DDA}$
E_Q	Quantization error	• 16 bit modes • ≤ 13 bit modes	— —	-1 to 0 —	— ± 0.5	LSB ⁴	
ENOB	Effective number of bits	16 bit differential mode • Avg=32 • Avg=1 16 bit single-ended mode • Avg=32 • Avg=1	TBD TBD TBD TBD	13.6 13.2 TBD TBD	TBD TBD TBD TBD	bits bits bits bits	5
SINAD	Signal-to-noise plus distortion	See ENOB	$6.02 \times \text{ENOB} + 1.76$			dB	
THD	Total harmonic distortion	16 bit differential mode • Avg=32 16 bit single-ended mode • Avg=32	— —	-94 TBD	TBD TBD	dB dB	5
SFDR	Spurious free dynamic range	16 bit differential mode • Avg=32 16 bit single-ended mode • Avg=32	TBD TBD	95 TBD	— —	dB dB	5

Table continues on the next page...

Table 24. 16-bit ADC characteristics ($V_{REFH} = V_{DDA}$, $V_{REFL} = V_{SSA}$) (continued)

Symbol	Description	Conditions ¹	Min.	Typ. ²	Max.	Unit	Notes
E_{IL}	Input leakage error		$I_{in} \times R_{AS}$			mV	I_{in} = leakage current (refer to the MCU's voltage and current operating ratings)
	Temp sensor slope	• -40°C to 25°C • 25°C to 105°C	—	TBD	—	mV/ $^{\circ}\text{C}$	
V_{TEMP25}	Temp sensor voltage	25°C	—	TBD	—	mV	

1. All accuracy numbers assume the ADC is calibrated with $V_{REFH} = V_{DDA}$
2. Typical values assume $V_{DDA} = 3.0\text{ V}$, Temp = 25°C , $f_{ADCK} = 2.0\text{ MHz}$ unless otherwise stated. Typical values are for reference only and are not tested in production.
3. The ADC supply current depends on the ADC conversion clock speed, conversion rate and the ADLPC bit (low power). For lowest power operation the ADLPC bit should be set, the HSC bit should be clear with 1MHz ADC conversion clock speed.
4. $1\text{ LSB} = (V_{REFH} - V_{REFL})/2^N$
5. Input data is 1 kHz sine wave.

FIGURE TBD

Figure 12. Typical TUE vs. ADC conversion rate 12-bit single-ended mode

FIGURE TBD

Figure 13. Typical ENOB vs. Averaging for 16-bit differential and 16-bit single-ended modes

6.6.1.3 16-bit ADC with PGA operating conditions

Table 25. 16-bit ADC with PGA operating conditions

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
V_{DDA}	Supply voltage	Absolute	1.71	—	3.6	V	
V_{REFPGA}	PGA ref voltage		V_{REFOUT}	V_{REFOUT}	V_{REFOUT}	V	2, 3
V_{ADIN}	Input voltage		V_{SSA}	—	V_{DDA}	V	
V_{CM}	Input Common Mode range		V_{SSA}	—	V_{DDA}	V	

Table continues on the next page...

Table 25. 16-bit ADC with PGA operating conditions (continued)

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
R _{PGAD}	Differential input impedance	Gain = 1, 2, 4, 8 Gain = 16, 32 Gain = 64	— — —	128 64 32	— — —	kΩ	IN+ to IN- ⁴
R _{AS}	Analog source resistance		—	100	—	Ω	5
T _S	ADC sampling time		1.25	—	—	μs	6

1. Typical values assume V_{DDA} = 3.0 V, Temp = 25°C, f_{ADCK} = 6 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.
2. ADC must be configured to use the internal voltage reference (VREFOUT)
3. PGA reference connected to the VREFOUT pin. If the user wishes to drive VREFOUT with a voltage other than the output of the VREF module, the VREF module must be disabled.
4. For single ended configurations the input impedance of the driven input is 1/2.
5. The analog source resistance (R_{AS}), external to MCU, should be kept as minimum as possible. Increased R_{AS} causes drop in PGA gain without affecting other performances. This is not dependent on ADC clock frequency.
6. The minimum sampling time is dependent on input signal frequency and ADC mode of operation. A minimum of 1.25μs time should be allowed for F_{in}=4 kHz at 16-bit differential mode. Recommended ADC setting is: ADLSMP=1, ADLSTS=2 at 8 MHz ADC clock.

6.6.1.4 16-bit ADC with PGA characteristics

Table 26. 16-bit ADC with PGA characteristics

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
I _{DDA_PGA}	Supply current		—	590	TBD	μA	
I _{DC_PGA}	Input DC current		$\frac{2}{R_{PGAD}} \left(\frac{(V_{REFPGA} \times 0.583) - V_{CM}}{(Gain+1)} \right)$			A	2
I _{ILKG}	Input Leakage current	PGA disabled	—	TBD	TBD	μA	3
G	Gain ⁴	• PGAG=0 • PGAG=1 • PGAG=2 • PGAG=3 • PGAG=4 • PGAG=5 • PGAG=6	TBD TBD TBD TBD TBD TBD TBD	0.98 1.99 3.97 7.95 15.8 31.4 61.2	TBD TBD TBD TBD TBD TBD TBD		R _{AS} < 100Ω
BW	Input signal bandwidth	• 16-bit modes • < 16-bit modes	— —	— —	4 40	kHz kHz	
PSRR	Power supply rejection ration	Gain=1	TBD	TBD	—	dB	V _{DDA} = 3V ±100mV, f _{VDDA} = 50Hz, 60Hz

Table continues on the next page...

Table 26. 16-bit ADC with PGA characteristics (continued)

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
CMRR	Common mode rejection ratio	- Gain=1 - Gain=64	TBD TBD	TBD TBD	— —	dB dB	V _{CM} = 500mVpp, f _{VCM} = 50Hz, 100Hz
V _{OFS}	Input offset voltage		—	0.2	TBD	mV	Gain=1, ADC Averaging=32
T _{GSW}	Gain switching settling time		—	—	10	μs	5
dG/dT	Gain drift over temperature	- Gain=1 - Gain=64	— —	TBD TBD	TBD TBD	ppm/°C ppm/°C	0 to 50°C
dV _{OFS} /dT	Offset drift over temperature	Gain=1	—	TBD	TBD	ppm/°C	0 to 50°C, ADC Averaging=32
dG/dV _{DDA}	Gain drift over supply voltage	- Gain=1 - Gain=64	— —	TBD TBD	TBD TBD	%/V %/V	V _{DDA} from 1.71 to 3.6V
E _{IL}	Input leakage error	All modes	I _{in} × R _{AS}			mV	I _{in} = leakage current (refer to the MCU's voltage and current operating ratings)
V _{PP,DIFF}	Maximum differential input signal swing		$\left(\frac{(\min(V_X V_{DDA} - V_X) - 0.2) \times 4}{\text{Gain}} \right)$ where V _X = V _{REFPGA} × 0.583			V	6
SNR	Signal-to-noise ratio	- Gain=1 - Gain=64	TBD TBD	83.0 57.5	— —	dB dB	16-bit differential mode, Average=32
THD	Total harmonic distortion	- Gain=1 - Gain=64	TBD TBD	89.4 90.0	— —	dB dB	16-bit differential mode, Average=32, f _{in} =500Hz
SFDR	Spurious free dynamic range	- Gain=1 - Gain=64	TBD TBD	90.9 77.0	— —	dB dB	16-bit differential mode, Average=32, f _{in} =500Hz

Table continues on the next page...

Table 26. 16-bit ADC with PGA characteristics (continued)

Symbol	Description	Conditions	Min.	Typ. ¹	Max.	Unit	Notes
ENOB	Effective number of bits	• Gain=1, Average=4	TBD	12.3	—	bits	16-bit differential mode, $f_{in}=500\text{Hz}$
		• Gain=1, Average=8	TBD	12.7	—	bits	
		• Gain=64, Average=4	TBD	8.4	—	bits	
		• Gain=64, Average=8	TBD	8.7	—	bits	
		• Gain=1, Average=32	TBD	13.3	—	bits	
		• Gain=2, Average=32	TBD	13.1	—	bits	
		• Gain=4, Average=32	TBD	12.5	—	bits	
		• Gain=8, Average=32	TBD	11.8	—	bits	
		• Gain=16, Average=32	TBD	11.1	—	bits	
		• Gain=32, Average=32	TBD	10.2	—	bits	
		• Gain=64, Average=32	TBD	9.3	—	bits	
SINAD	Signal-to-noise plus distortion ratio	See ENOB	$6.02 \times \text{ENOB} + 1.76$			dB	

1. Typical values assume $V_{DDA}=3.0\text{V}$, $\text{Temp}=25^{\circ}\text{C}$, $f_{ADCK}=6\text{MHz}$ unless otherwise stated.
2. Between IN+ and IN-. The PGA draws a DC current from the input terminals. The magnitude of the DC current is a strong function of input common mode voltage (V_{CM}) and the PGA gain.
3. This is the input leakage current of the module in addition to the PAD leakage current.
4. $\text{Gain} = 2^{\text{PGAG}}$
5. When the PGA gain is changed, it takes some time to settle the output for the ADC to work properly. During a gain switching, a few ADC outputs should be discarded (minimum two data samples, may be more depending on ADC sampling rate and time of the switching).
6. Limit the input signal swing so that the PGA does not saturate during operation. Input signal swing is dependent on the PGA reference voltage and gain setting.

6.6.2 CMP and 6-bit DAC electrical specifications

Table 27. Comparator and 6-bit DAC electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
V_{DD}	Supply voltage	1.71	—	3.6	V
I_{DDHS}	Supply current, High-speed mode (EN=1, PMODE=1)	—	—	200	μA
$I_{DDL S}$	Supply current, low-speed mode (EN=1, PMODE=0)	—	—	20	μA
V_{AIN}	Analog input voltage	$V_{SS} - 0.3$	—	V_{DD}	V
V_{AIO}	Analog input offset voltage	—	—	20	mV

Table continues on the next page...

Table 27. Comparator and 6-bit DAC electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit
V_H	Analog comparator hysteresis ¹				
	• CR0[HYSTCTR] = 00	—	5	—	mV
	• CR0[HYSTCTR] = 01	—	10	—	mV
	• CR0[HYSTCTR] = 10	—	20	—	mV
	• CR0[HYSTCTR] = 11	—	30	—	mV
V_{CMPOH}	Output high	$V_{DD} - 0.5$	—	—	V
V_{CMPOI}	Output low	—	—	0.5	V
t_{DHS}	Propagation delay, high-speed mode (EN=1, PMODE=1)	20	50	200	ns
t_{DLS}	Propagation delay, low-speed mode (EN=1, PMODE=0)	120	250	600	ns
	Analog comparator initialization delay ²	—	—	TBD	ns
I_{DAC6b}	6-bit DAC current adder (enabled)	—	7	—	μA
INL	6-bit DAC integral non-linearity	-0.5	—	0.5	LSB ³
DNL	6-bit DAC differential non-linearity	-0.3	—	0.3	LSB

1. Typical hysteresis is measured with input voltage range limited to 0.6 to $V_{DD}-0.6V$.

2. Comparator initialization delay is defined as the time between software writes to change control inputs (Writes to DACEN, VRSEL, PSEL, MSEL, VOSEL) and the comparator output settling to a stable level.

3. 1 LSB = $V_{reference}/64$

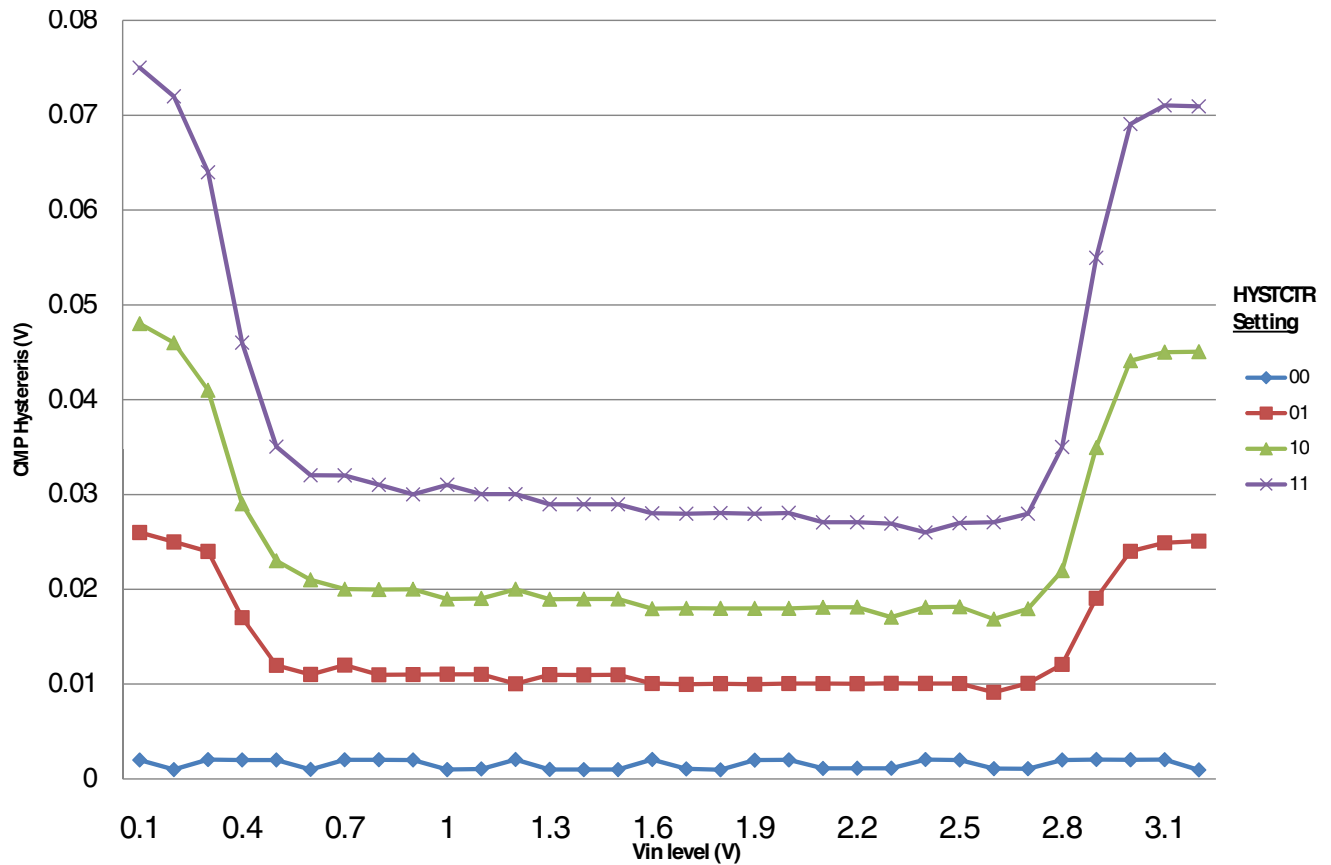


Figure 14. Typical hysteresis vs. Vin level (VDD=3.3V, PMODE=0)

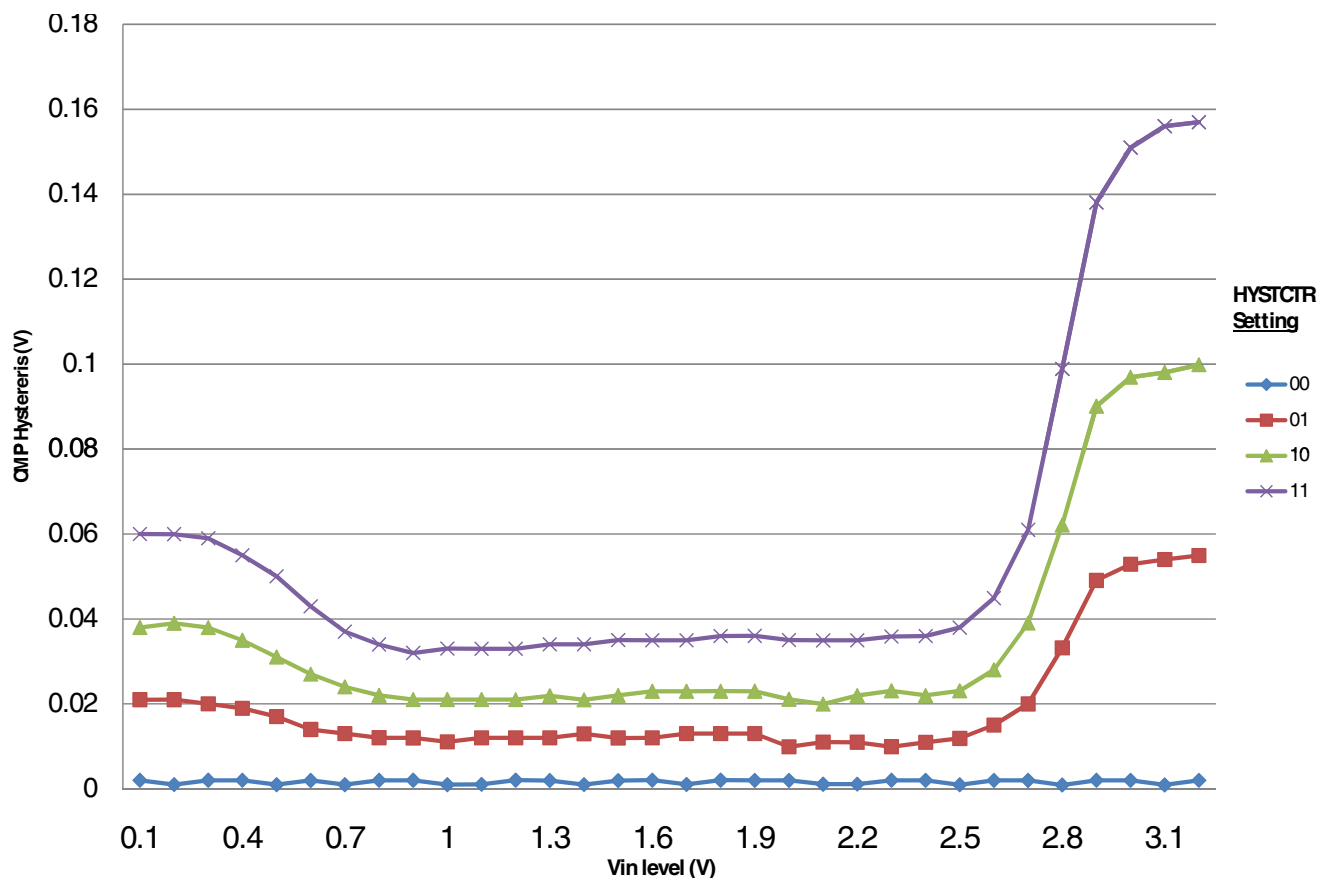


Figure 15. Typical hysteresis vs. Vin level (VDD=3.3V, PMODE=1)

6.6.3 12-bit DAC electrical characteristics

6.6.3.1 12-bit DAC operating requirements

Table 28. 12-bit DAC operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V_{DDA}	Supply voltage	1.71	3.6	V	
V_{DACR}	Reference voltage	1.13	3.6	V	1
T_A	Temperature	-40	105	°C	
C_L	Output load capacitance	—	100	pF	2
I_L	Output load current	—	1	mA	

1. The DAC reference can be selected to be VDDA or the voltage output of the VREF module (VREFO)
2. A small load capacitance (47 pF) can improve the bandwidth performance of the DAC

6.6.3.2 12-bit DAC operating behaviors

Table 29. 12-bit DAC operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I_{DDA_DACLP}	Supply current — low-power mode	—	—	150	μA	
I_{DDA_DACHP}	Supply current — high-speed mode	—	—	700	μA	
t_{DACLP}	Full-scale settling time (0x080 to 0xF7F) — low-power mode	—	100	200	μs	1
t_{DACHP}	Full-scale settling time (0x080 to 0xF7F) — high-power mode	—	15	30	μs	1
$t_{CCDACLP}$	Code-to-code settling time (0xBF8 to 0xC08) — low-power mode	—	—	5	μs	1
$t_{CCDACHP}$	Code-to-code settling time (0xBF8 to 0xC08) — high-speed mode	1	TBD	—	μs	1
$V_{dacoutl}$	DAC output voltage range low — high-speed mode, no load, DAC set to 0x000	—	100	TBD	mV	
$V_{dacouth}$	DAC output voltage range high — high-speed mode, no load, DAC set to 0xFFF	$V_{DACR} - 100$	—	V_{DACR}	mV	
INL	Integral non-linearity error — high speed mode	—	—	± 8	LSB	2
DNL	Differential non-linearity error — $V_{DACR} > 2 V$	—	—	± 1	LSB	3
DNL	Differential non-linearity error — $V_{DACR} = V_{REFO}$ (1.15 V)	—	—	± 1	LSB	4
V_{OFFSET}	Offset error	± 0.4	—	± 0.8	%FSR	5
E_G	Gain error	± 0.1	—	± 0.6	%FSR	5
PSRR	Power supply rejection ratio, $V_{DDA} \geq 2.4 V$	60	—	90	dB	
T_{CO}	Temperature coefficient offset voltage	—	TBD	—	$\mu V/C$	
T_{GE}	Temperature coefficient gain error	—	TBD	—	ppm of FSR/C	
A_C	Offset aging coefficient	—	—	TBD	$\mu V/yr$	
R_{op}	Output resistance load = 3 k Ω	—	—	250	Ω	
SR	Slew rate -80h $\rightarrow$ F7Fh $\rightarrow$ 80h - High power (SP_{HP}) - Low power (SP_{LP})	1.2 0.05	1.7 0.12	— —	V/ μs	
CT	Channel to channel cross talk	—	—	-80	dB	
BW	3dB bandwidth - High power (SP_{HP}) - Low power (SP_{LP})	550 40	— —	— —	kHz	

1. Settling within ± 1 LSB
2. The INL is measured for 0+100mV to $V_{DACR} - 100$ mV
3. The DNL is measured for 0+100 mV to $V_{DACR} - 100$ mV
4. The DNL is measured for 0+100mV to $V_{DACR} - 100$ mV with $V_{DDA} > 2.4V$

5. Calculated by a best fit curve from $V_{SS}+100\text{ mV}$ to $V_{REF}-100\text{ mV}$

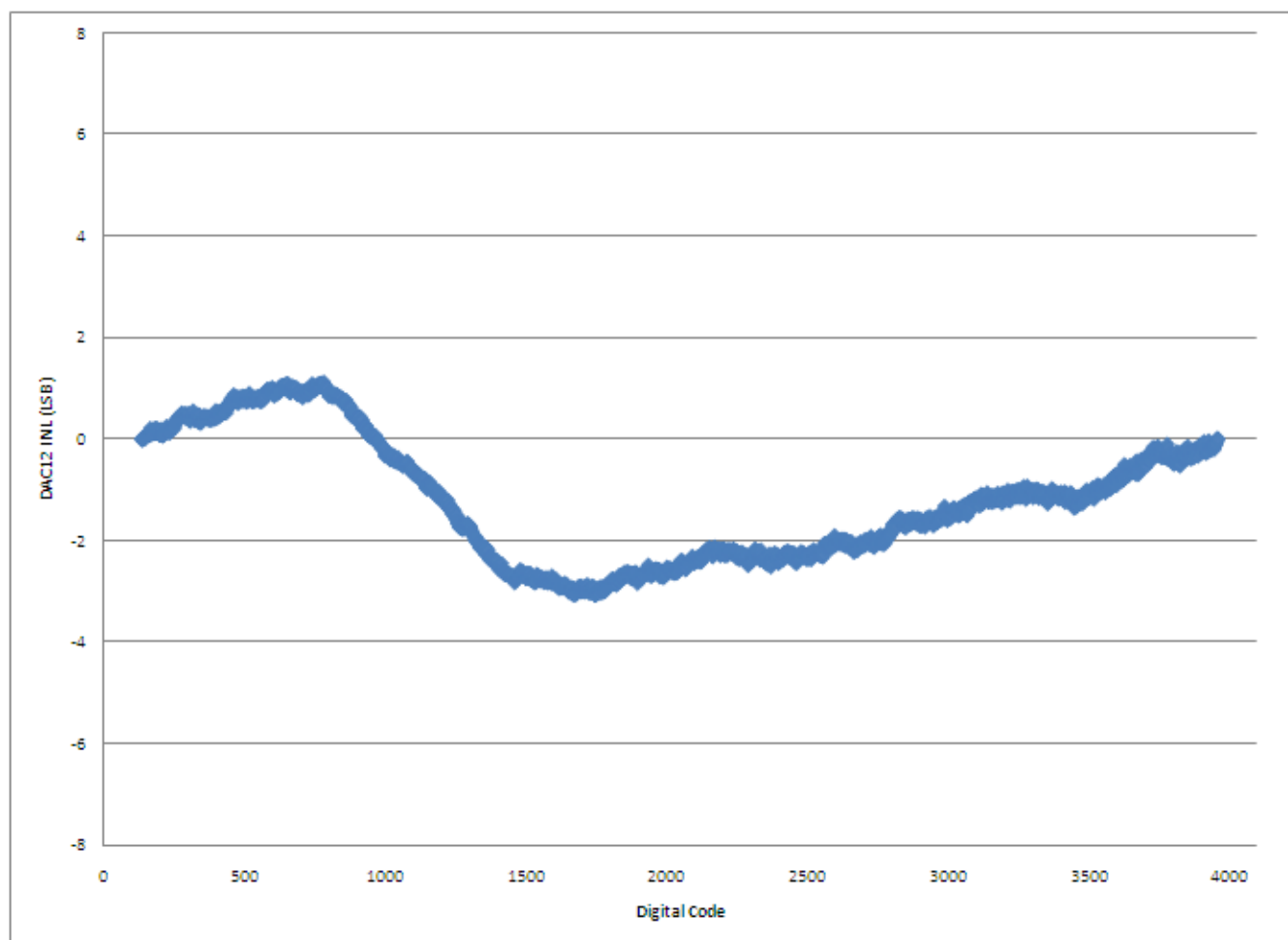


Figure 16. Typical INL error vs. digital code

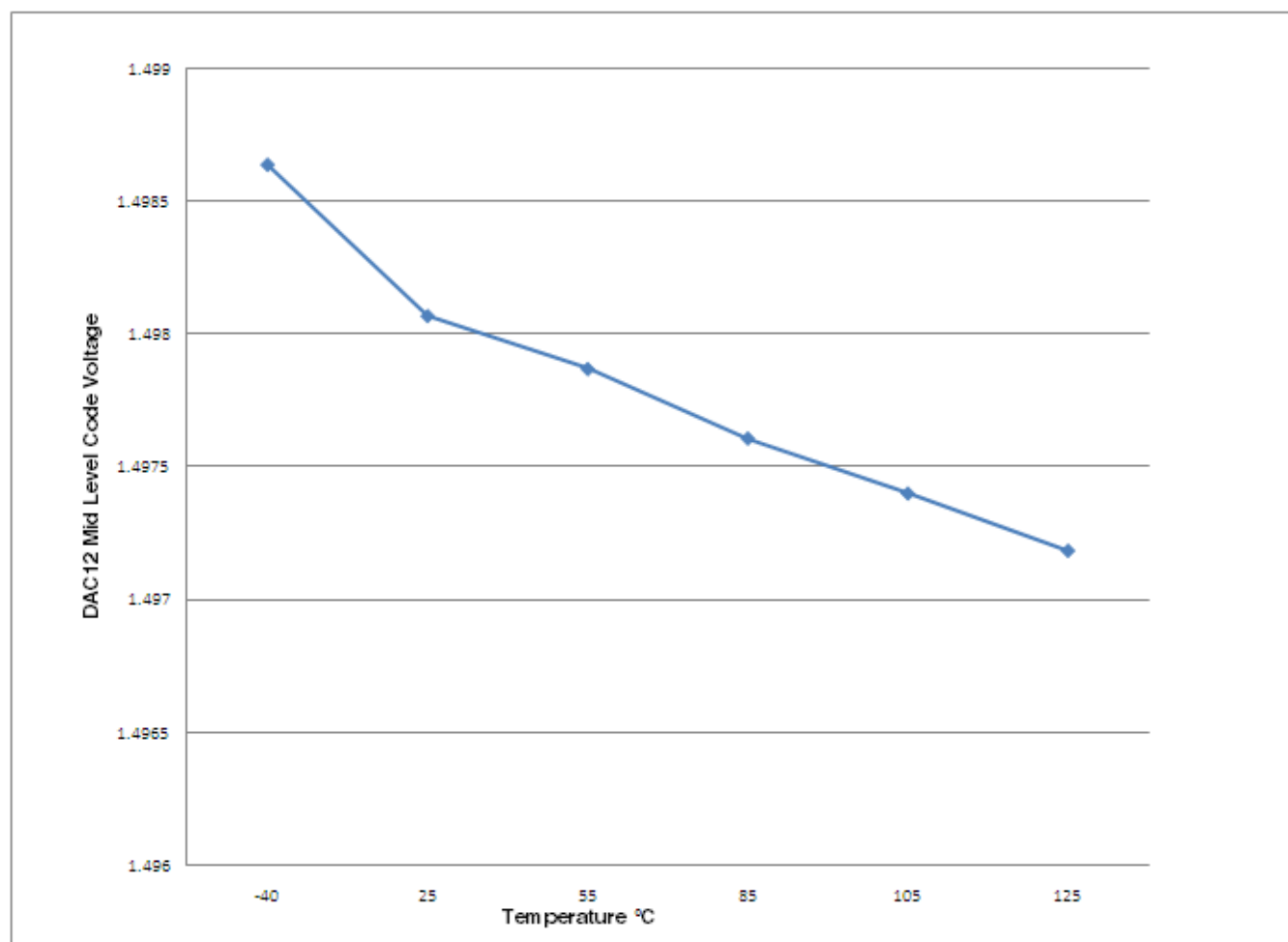


Figure 17. Offset at half scale vs. temperature

6.6.4 Op-amp electrical specifications

Table 30. Op-amp electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
V_{DD}	Operating voltage	1.71	—	3.6	V
I_{SUPPLY}	Supply current ($I_{OUT}=0mA$, $CL=0$), low-power mode	—	70	TBD	μA
I_{SUPPLY}	Supply current ($I_{OUT}=0mA$, $CL=0$), high-speed mode	—	500	TBD	μA
V_{OS}	Input offset voltage	—	± 3	TBD	mV
α_{VOS}	Input offset voltage temperature coefficient	—	10	—	$\mu V/C$
I_{OS}	Input offset current (0~50°C)	—	± 300	—	pA
I_{OS}	Input offset current (-40~105°C)	—	TBD	—	pA
I_{BIAS}	Input bias current (0~50°C)	—	± 300	—	pA

Table continues on the next page...

Table 30. Op-amp electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit
I_{BIAS}	Input bias current (0~105°C)	—	TBD	—	pA
V_{CML}	Input common mode voltage low	0	—	—	V
V_{CMH}	Input common mode voltage high	—	—	VDD	V
R_{IN}	Input resistance	500	—	—	MΩ
C_{IN}	Input capacitance	—	—	TBD	pF
$ X_{IN} $	AC input impedance ($f_{IN}=100\text{kHz}$)	—	50	—	MΩ
CMRR	Input common mode rejection ratio	60	—	—	dB
PSRR	Power supply rejection ratio	60	—	—	dB
SR	Slew rate ($\Delta V_{IN}=100\text{mV}$), low-power mode	0.1	—	—	V/μs
SR	Slew rate ($\Delta V_{IN}=100\text{mV}$), high-speed mode	1	—	—	V/μs
GBW	Unity gain bandwidth, low-power mode	0.15	—	—	MHz
GBW	Unity gain bandwidth, high-speed mode	1	—	—	MHz
A_V	DC open-loop voltage gain	80	90	—	dB
CL(max)	Load capacitance driving capability	—	—	TBD	pF
R_{OUT}	Output resistance	—	—	TBD	Ω
V_{OUT}	Output voltage range	0.1	—	TBD	V
I_{OUT}	Output load current	—	±0.5	—	mA
GM	Gain margin	—	20	—	dB
PM	Phase margin	45	56	—	deg
T_{settle}	Settling time (Buffer mode, low-power mode) ($T_o < 0.1\%$, $V_{in}=2V_{p-p}$, $C_L=25\text{pF}$, $R_L=100\text{k}$)	—	TBD	—	μs
T_{settle}	Settling time (Buffer mode, high-speed mode) ($T_o < 0.1\%$, $V_{in}=2V_{p-p}$, $C_L=25\text{pF}$, $R_L=100\text{k}$)	—	TBD	—	μs
V_n	Voltage noise density (noise floor) 1kHz	—	350	TBD	nV/√Hz
V_n	Voltage noise density (noise floor) 10kHz	—	90	TBD	nV/√Hz

6.6.5 Transimpedance amplifier electrical specifications — full range

Table 31. TRIAMP full range operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V_{DDA}	Supply voltage	1.71	3.6	V	
V_{IN}	Input voltage range	-0.2	$V_{DDA}-1.4$	V	
C_L	Output load capacitance		100	pf	
R_{OUT}	Output resistance		1500	Ω	

Table 32. TRIAMP full range operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I_{SUPPLY}	Supply current ($I_{OUT}=0mA$, $CL=0$) — Low-power mode	—	60	—	μA	
I_{SUPPLY}	Supply current ($I_{OUT}=0mA$, $CL=0$) — High-speed mode	—	280	—	μA	
V_{OS}	Input offset voltage	—	± 3	TBD	mV	
α_{VOS}	Input offset voltage temperature coefficient	—	10	TBD	$\mu V/C$	
I_{OS}	Input offset current	—	± 200	TBD	pA	
I_{BIAS}	Input bias current	—	± 300	TBD	pA	
R_{IN}	Input resistance	500	—	—	$M\Omega$	
C_{IN}	Input capacitance	—	17	—	pF	
$ X_{IN} $	AC input impedance ($f_{IN}=100kHz$)	—	TBD	—	$M\Omega$	
CMRR	Input common mode rejection ratio	60	—	—	dB	
PSRR	Power supply rejection ratio	60	—	—	dB	
SR	Slew rate ($\Delta V_{IN}=100mV$) — Low-power mode	0.1	—	—	$V/\mu s$	
SR	Slew rate ($\Delta V_{IN}=100mV$) — High speed mode	1	—	—	$V/\mu s$	
GBW	Unity gain bandwidth — Low-power mode 50pF	0.15	—	—	MHz	
GBW	Unity gain bandwidth — High speed mode 50pF	1	—	—	MHz	
A_v	DC open-loop voltage gain	80	—	—	dB	
V_{OUT}	Output voltage range	0.15	—	$V_{DD}-0.15$	V	
I_{OUT}	Output load current	—	± 0.5	—	mA	
GM	Gain margin	—	20	—	dB	
PM	Phase margin	50	60	—	deg	
V_n	Voltage noise density (noise floor) 1kHz	—	280	—	$nV/\sqrt{Hz}$	
V_n	Voltage noise density (noise floor) 10kHz	—	100	—	$nV/\sqrt{Hz}$	

Figure 18. Typical Open Loop Gain vs. Frequency [TBD]**Figure 19. Typical Phase vs. Frequency [TBD]**

6.6.6 Transimpedance amplifier electrical specifications — limited range

Table 33. TRIAMP limited range operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V _{DDA}	Supply voltage	2.4	3.3	V	
V _{IN}	Input voltage range	0.1	V _{DDA} -1.4	V	
T _A	Temperature	0	50	°C	
C _L	Output load capacitance		100	pf	
R _{OUT}	Output resistance		1500	Ω	

Table 34. TRIAMP limited range operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{OS}	Input offset voltage	—	±3	TBD	mV	
α _{VOS}	Input offset voltage temperature coefficient	—	4	TBD	μV/°C	
I _{OS}	Input offset current	—	±300	TBD	pA	
I _{BIAS}	Input bias current	—	±300	TBD	pA	
X _{IN}	AC input impedance (f _{IN} =100kHz)	500	—	—	MΩ	
CMRR	Input common mode rejection ratio	—	70	—	dB	
PSRR	Power supply rejection ratio	—	70	—	dB	
SR	Slew rate (ΔV _{IN} =100mV) — Low-power mode	0.1	—	—	V/μs	
SR	Slew rate (ΔV _{IN} =100mV) — High speed mode	1	—	—	V/μs	
GBW	Unity gain bandwidth — Low-power mode 50pF	0.15	—	—	MHz	
GBW	Unity gain bandwidth — High speed mode 50pF	1	—	—	MHz	
A _V	DC open-loop voltage gain	80	—	—	dB	
GM	Gain margin	30	—	—	dB	
PM	Phase margin	60	69	—	deg	

6.6.7 Voltage reference electrical specifications

Table 35. VREF full-range operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
V _{DDA}	Supply voltage	1.71	3.6	V	
T _A	Temperature	−40	105	°C	
C _L	Output load capacitance	—	100	nF	

Table 36. VREF full-range operating behaviors

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{out}	Voltage reference output with factory trim at nominal V _{DDA} and temperature=25C	TBD	1.2	TBD	V	
V _{out}	Voltage reference output with factory trim	TBD	—	TBD	V	
V _{out}	Voltage reference output user trim	1.198	—	1.202	V	
V _{step}	Voltage reference trim step	—	0.5	—	mV	
V _{drift}	Temperature drift (V _{max} -V _{min} across the full temperature range)	—	—	20	mV	See Figure 20
A _c	Aging coefficient	—	—	TBD	ppm/year	
I _{bg}	Bandgap only (MODE_LV = 00) current	—	—	TBD	μA	
I _{tr}	Tight-regulation buffer (MODE_LV =10) current	—	—	1.1	mA	
	Load regulation (MODE_LV = 10) current = ±1.0mA	—	—	TBD	V	
T _{stup}	Buffer startup time	—	—	100	μs	
DC	Line regulation (power supply rejection)	—	—	TBD	mV	
		-60	—	TBD	dB	

Table 37. VREF limited-range operating requirements

Symbol	Description	Min.	Max.	Unit	Notes
T _A	Temperature	0	50	°C	

Table 38. VREF limited-range operating behaviors

Symbol	Description	Min.	Max.	Unit	Notes
V _{out}	Voltage reference output with factory trim	TBD	TBD	V	

TBD

Figure 20. Typical output vs.temperature

TBD

Figure 21. Typical output vs. VDD

6.7 Timers

See [General switching specifications](#).

6.8 Communication interfaces

6.8.1 USB electrical specifications

The USB electricals for the USB On-the-Go module conform to the standards documented by the Universal Serial Bus Implementers Forum. For the most up-to-date standards, visit <http://www.usb.org>.

6.8.2 USB DCD electrical specifications

Table 39. USB DCD electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit
V _{DP_SRC}	USB_DP source voltage (up to 250 μ A)	TBD	TBD	TBD	V
V _{LGC}	Threshold voltage for logic high	0.8	—	2.0	V
I _{DP_SRC}	USB_DP source current	7	10	13	μ A
I _{DM_SINK}	USB_DM sink current	50	100	150	μ A
R _{DM_DWN}	D- pulldown resistance for data pin contact detect	14.25	—	24.8	k Ω
V _{DAT_REF}	Data detect voltage	0.25	TBD	0.4	V

6.8.3 USB VREG electrical specifications

Table 40. USB VREG electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{REGIN}	Input supply voltage	2.7	—	5.5	V	
I _{DDon}	Quiescent current — Run mode, load current equal zero, input supply (V _{REGIN}) > 3.6 V	—	120	TBD	μ A	
I _{DDstby}	Quiescent current — Standby mode, load current equal zero	—	1	TBD	μ A	
I _{DDoff}	Quiescent current — Shutdown mode - V_{REGIN} = 5.0 V and temperature=25C - Across operating voltage and temperature	—	500	—	nA	
		—	—	TBD	μ A	
I _{LOADrun}	Maximum load current — Run mode	—	—	120	mA	
I _{LOADstby}	Maximum load current — Standby mode	—	—	1	mA	

Table continues on the next page...

**Table 40. USB VREG electrical specifications
(continued)**

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V_{Reg33out}	Regulator output voltage — Input supply (VREGIN) > 3.6 V - Run mode - Standby mode	3	3.3	3.6	V	
		2.5	2.8	3.6	V	
V_{Reg33out}	Regulator output voltage — Input supply (VREGIN) < 3.6 V, pass-through mode	2.3	—	3.6	V	1
C_{OUT}	External output capacitor	1.76	2.2	8.16	μF	
ESR	External output capacitor equivalent series resistance	1	—	100	m Ω	
I_{LIM}	Current limitation threshold	185	290	395	mA	

1. Operating in pass-through mode: regulator output voltage equal to the input voltage minus a drop proportional to I_{Load} .

6.8.4 DSPI switching specifications (low-speed mode)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provides DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

Table 41. Master mode DSPI timing (low-speed mode)

Num	Description	Min.	Max.	Unit	Notes
	Operating voltage	1.71	3.6	V	1
	Frequency of operation	—	12.5	MHz	
DS1	DSPI_SCK output cycle time	$4 \times t_{\text{BCLK}}$	—	ns	
DS2	DSPI_SCK output high/low time	$(t_{\text{SCK}}/2) - 4$	$(t_{\text{SCK}}/2) + 4$	ns	
DS3	DSPI_PCS n to DSPI_SCK output valid	$(t_{\text{SCK}}/2) - 4$	—	ns	
DS4	DSPI_SCK to DSPI_PCS n output hold	$(t_{\text{SCK}}/2) - 4$	—	ns	
DS5	DSPI_SCK to DSPI_SOUT valid	—	10	ns	
DS6	DSPI_SCK to DSPI_SOUT invalid	-2	—	ns	
DS7	DSPI_SIN to DSPI_SCK input setup	15	—	ns	
DS8	DSPI_SCK to DSPI_SIN input hold	0	—	ns	

1. The DSPI module can operate across the entire operating voltage for the processor, but to run across the full voltage range the maximum frequency of operation is reduced.

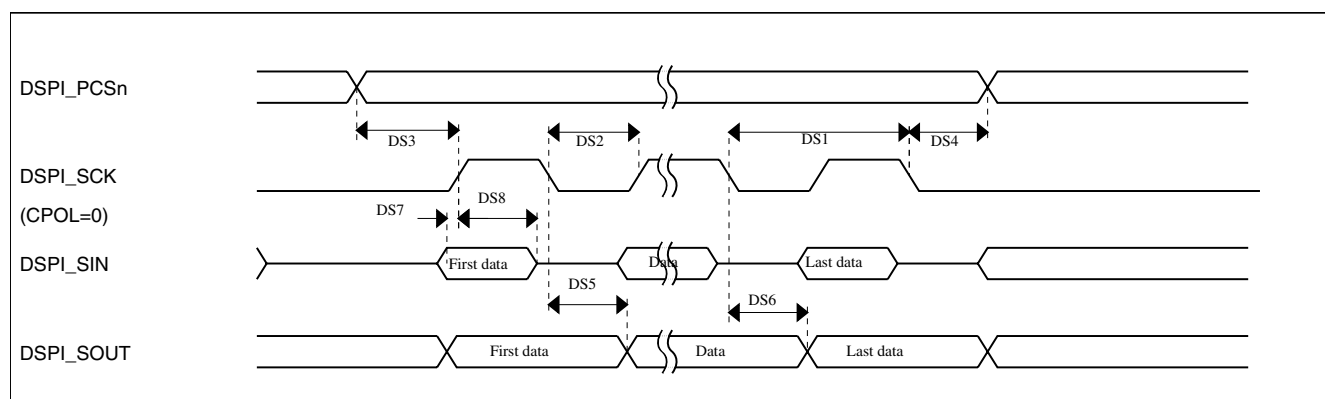


Figure 22. DSPI classic SPI timing — master mode

Table 42. Slave mode DSPI timing (low-speed mode)

Num	Description	Min.	Max.	Unit
	Operating voltage	1.71	3.6	V
	Frequency of operation	—	6.25	MHz
DS9	DSPI_SCK input cycle time	$8 \times t_{BCLK}$	—	ns
DS10	DSPI_SCK input high/low time	$(t_{SCK}/2) - 4$	$(t_{SCK}/2) + 4$	ns
DS11	DSPI_SCK to DSPI_SOUT valid	—	20	ns
DS12	DSPI_SCK to DSPI_SOUT invalid	0	—	ns
DS13	DSPI_SS to DSPI_SCK input setup	5	—	ns
DS14	DSPI_SCK to DSPI_SIN input hold	15	—	ns
DS15	$\overline{\text{DSPI_SS}}$ active to DSPI_SOUT driven	—	15	ns
DS16	$\overline{\text{DSPI_SS}}$ inactive to DSPI_SOUT not driven	—	15	ns

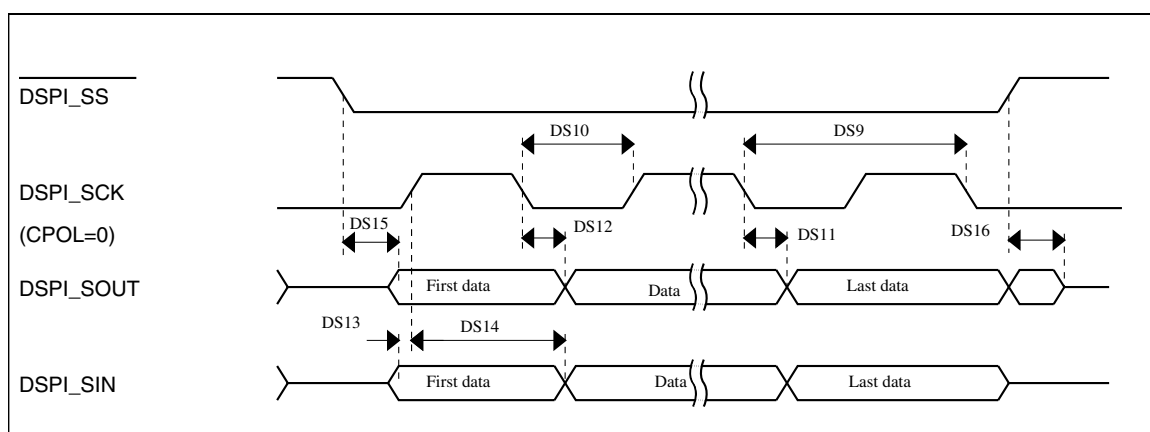


Figure 23. DSPI classic SPI timing — slave mode

6.8.5 DSPI switching specifications (high-speed mode)

The DMA Serial Peripheral Interface (DSPI) provides a synchronous serial bus with master and slave operations. Many of the transfer attributes are programmable. The tables below provide DSPI timing characteristics for classic SPI timing modes. Refer to the DSPI chapter of the Reference Manual for information on the modified transfer formats used for communicating with slower peripheral devices.

Table 43. Master mode DSPI timing (high-speed mode)

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
	Frequency of operation	—	25	MHz
DS1	DSPI_SCK output cycle time	$2 \times t_{BCLK}$	—	ns
DS2	DSPI_SCK output high/low time	$(t_{SCK}/2) - 2$	$(t_{SCK}/2) + 2$	ns
DS3	DSPI_PCSn to DSPI_SCK output valid	$(t_{SCK}/2) - 2$	—	ns
DS4	DSPI_SCK to DSPI_PCSn output hold	$(t_{SCK}/2) - 2$	—	ns
DS5	DSPI_SCK to DSPI_SOUT valid	—	8.5	ns
DS6	DSPI_SCK to DSPI_SOUT invalid	-2	—	ns
DS7	DSPI_SIN to DSPI_SCK input setup	TBD	—	ns
DS8	DSPI_SCK to DSPI_SIN input hold	0	—	ns

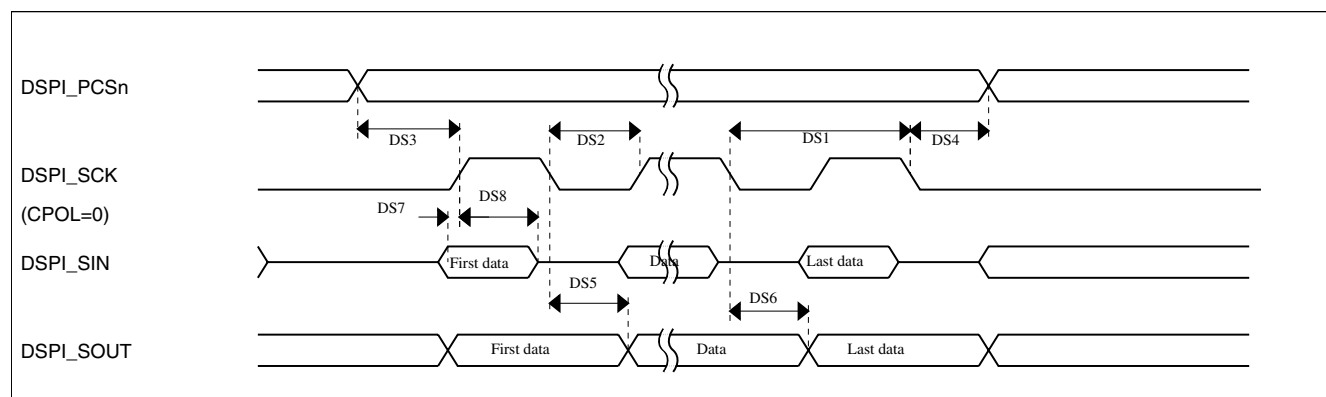


Figure 24. DSPI classic SPI timing — master mode

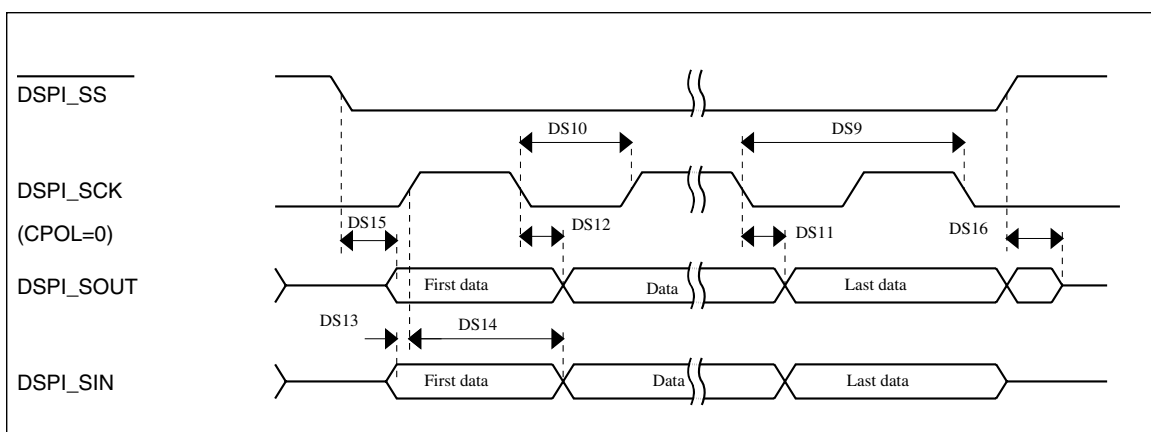
Table 44. Slave mode DSPI timing (high-speed mode)

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
	Frequency of operation		12.5	MHz
DS9	DSPI_SCK input cycle time	$4 \times t_{BCLK}$	—	ns
DS10	DSPI_SCK input high/low time	$(t_{SCK}/2) - 2$	$(t_{SCK}/2) + 2$	ns

Table continues on the next page...

Table 44. Slave mode DSPI timing (high-speed mode) (continued)

Num	Description	Min.	Max.	Unit
DS11	DSPI_SCK to DSPI_SOUT valid	—	TBD	ns
DS12	DSPI_SCK to DSPI_SOUT invalid	0	—	ns
DS13	DSPI_SIN to DSPI_SCK input setup	2	—	ns
DS14	DSPI_SCK to DSPI_SIN input hold	7	—	ns
DS15	$\overline{\text{DSPI_SS}}$ active to DSPI_SOUT driven	—	14	ns
DS16	$\overline{\text{DSPI_SS}}$ inactive to DSPI_SOUT not driven	—	14	ns

**Figure 25. DSPI classic SPI timing — slave mode**

6.8.6 I²C switching specifications

See [General switching specifications](#).

6.8.7 UART switching specifications

See [General switching specifications](#).

6.8.8 I²S switching specifications

This section provides the AC timings for the I²S in master (clocks driven) and slave modes (clocks input). All timings are given for non-inverted serial clock polarity (TCR[TSCKP] = 0, RCR[RSCKP] = 0) and a non-inverted frame sync (TCR[TFSI] = 0,

RCR[RFSI] = 0). If the polarity of the clock and/or the frame sync have been inverted, all the timings remain valid by inverting the clock signal (I2S_BCLK) and/or the frame sync (I2S_FS) shown in the figures below.

Table 45. I²S master mode timing

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
S1	I2S_MCLK cycle time	$2 \times t_{SYS}$		ns
S2	I2S_MCLK pulse width high/low	45%	55%	MCLK period
S3	I2S_BCLK cycle time	$5 \times t_{SYS}$	—	ns
S4	I2S_BCLK pulse width high/low	45%	55%	BCLK period
S5	I2S_BCLK to I2S_FS output valid	—	15	ns
S6	I2S_BCLK to I2S_FS output invalid	-2.5	—	ns
S7	I2S_BCLK to I2S_TXD valid	—	15	ns
S8	I2S_BCLK to I2S_TXD invalid	-3	—	ns
S9	I2S_RXD/I2S_FS input setup before I2S_BCLK	20	—	ns
S10	I2S_RXD/I2S_FS input hold after I2S_BCLK	0	—	ns

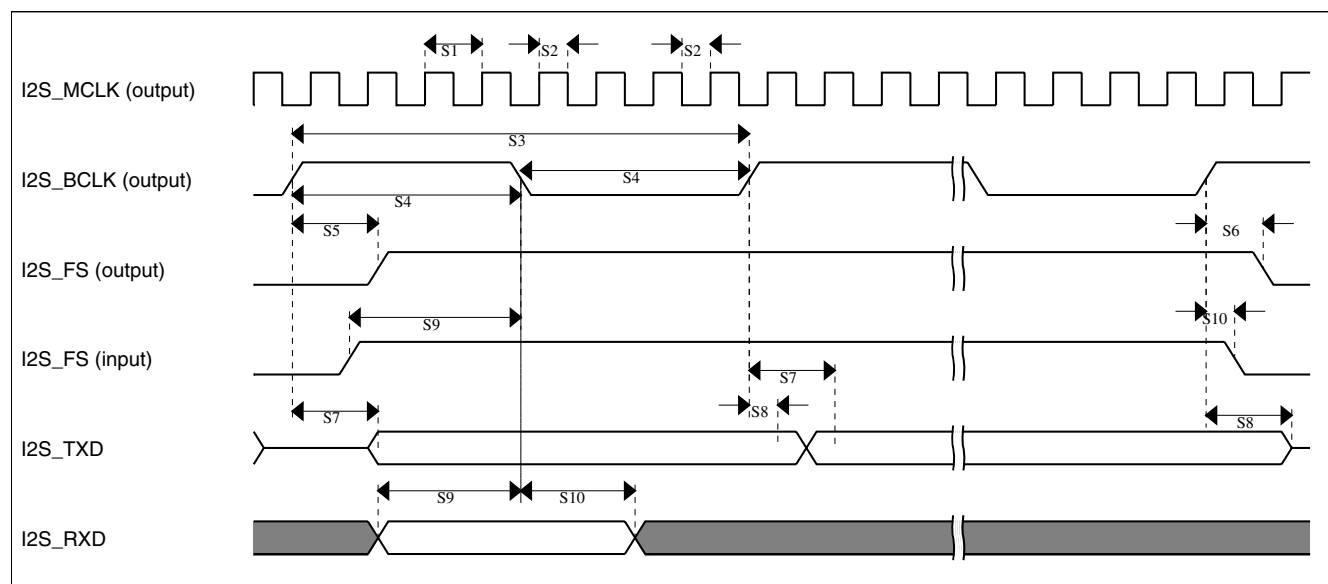


Figure 26. I²S timing — master mode

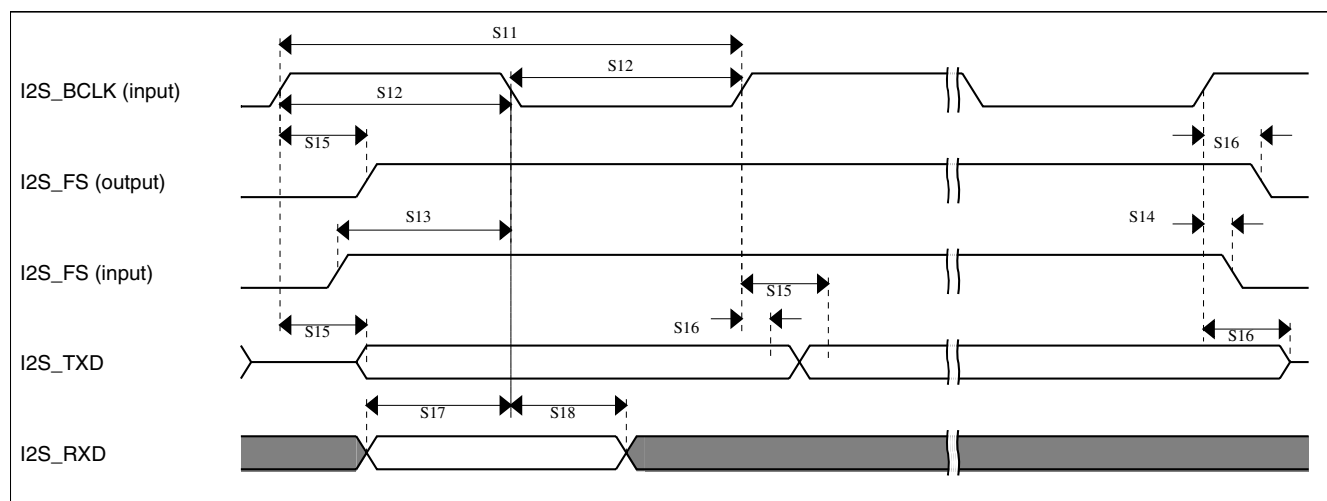
Table 46. I²S slave mode timing

Num	Description	Min.	Max.	Unit
	Operating voltage	2.7	3.6	V
S11	I2S_BCLK cycle time (input)	$8 \times t_{SYS}$	—	ns

Table continues on the next page...

Table 46. I²S slave mode timing (continued)

Num	Description	Min.	Max.	Unit
S12	I2S_BCLK pulse width high/low (input)	45%	55%	MCLK period
S13	I2S_FS input setup before I2S_BCLK	10	—	ns
S14	I2S_FS input hold after I2S_BCLK	3	—	ns
S15	I2S_BCLK to I2S_TXD/I2S_FS output valid	—	20	ns
S16	I2S_BCLK to I2S_TXD/I2S_FS output invalid	0	—	ns
S17	I2S_RXD setup before I2S_BCLK	10	—	ns
S18	I2S_RXD hold after I2S_BCLK	2	—	ns

**Figure 27. I²S timing — slave modes**

6.9 Human-machine interfaces (HMI)

6.9.1 TSI electrical specifications

Table 47. TSI electrical specifications

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
V _{DDTSI}	Operating voltage	1.71	—	3.6	V	
C _{ELE}	Target electrode capacitance range	1	20	500	pF	1
f _{REFmax}	Reference oscillator frequency	—	5.5	TBD	MHz	
f _{ELEmax}	Electrode oscillator frequency	—	0.5	TBD	MHz	
C _{REF}	Internal reference capacitor	TBD	1	TBD	pF	
V _{DELTA}	Oscillator delta voltage	TBD	600	TBD	mV	

Table continues on the next page...

Table 47. TSI electrical specifications (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
I_{REF}	Reference oscillator current source base current	TBD	1	TBD	μA	2
I_{ELE}	Electrode oscillator current source base current	TBD	1	TBD	μA	2
Pres5	Electrode capacitance measurement precision	—	TBD	TBD	%	3
Pres20	Electrode capacitance measurement precision	—	TBD	TBD	%	4
Pres100	Electrode capacitance measurement precision	—	TBD	TBD	%	5
MaxSens20	Maximum sensitivity @ 20 pF electrode	0.003	0.25	—	fF/count	6
MaxSens	Maximum sensitivity	0.003	—	—	fF/count	7
Res	Resolution	—	—	16	bits	
T_{Con20}	Response time @ 20 pF	8	15	25	μs	8
I_{TSI_RUN}	Current added in run mode	—	TBD	—	μA	
I_{TSI_LP}	Low power mode current adder	—	1	TBD	μA	

1. The TSI module is functional with capacitance values outside this range. However, optimal performance is not guaranteed.
2. The programmable current source value is generated by multiplying the SCANC[REFCHRG] value and the base current.
3. Measured with a 5 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 8; lext = 16.
4. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 128, NSCN = 2; lext = 16.
5. Measured with a 20 pF electrode, reference oscillator frequency of 10 MHz, PS = 16, NSCN = 3; lext = 16.
6. Measured with a 20 pF electrode, reference oscillator frequency of ~5 MHz ($I_{REF} = 5 \mu A$, REFCHRG = 4), PS = 128, NSCN = 2; lext = 16 (EXTCHRG = 15).
7. Typical value depends on the configuration used.
8. Time to do one complete measurement of the electrode. Sensitivity resolution of 0.0133 pF, PS = 0, NSCN = 0, 1 electrode, DELVOL = 2, EXTCHRG = 15.

6.9.2 LCD electrical characteristics

Table 48. LCD electricals

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
f_{Frame}	LCD frame frequency	28	30	58	Hz	
C_{LCD}	LCD charge pump capacitance — nominal value	—	100	—	nF	1
C_{BYLCD}	LCD bypass capacitance — nominal value	—	100	—	nF	1
C_{Glass}	LCD glass capacitance	—	2000	8000	pF	
V_{IREG}	V_{IREG} — HREFSEL = 0 • HREFSEL = 0 • HREFSEL = 1	0.89 1.49	1.00 1.67	1.15 1.85	V V	2
Δ_{RTRIM}	V_{IREG} TRIM resolution	3.0	—	—	% V_{IREG}	

Table continues on the next page...

Table 48. LCD electricals (continued)

Symbol	Description	Min.	Typ.	Max.	Unit	Notes
—	V _{I_{REG}} ripple - HREFSEL = 0 - HREFSEL = 1	— —	— —	30 50	mV mV	
I _{V_{REG}}	V _{I_{REG}} current adder — RVEN = 1	—	1	—	μA	3
I _{RBIAS}	RBIAS current adder - HREFSEL = 0 - HREFSEL = 1	— —	10 1	— —	μA μA	3
R _{RBIAS}	RBIAS resistor values - LADJ = 00 or 01 — Low load (LCD glass capacitance ≤ 2000 pF) - LADJ = 10 or 11 — High load (LCD glass capacitance ≤ 8000 pF)	— —	0.28 2.98	— —	MΩ MΩ	
VLL2	VLL2 voltage - HREFSEL = 0 - HREFSEL = 1	2.0 – 5% 3.3 – 5%	2.0 3.3	— —	V V	
VLL3	VLL3 voltage - HREFSEL = 0 - HREFSEL = 1	3.0 – 5% 5 – 5%	3.0 5	— —	V V	

1. The actual value used could vary with tolerance.
2. V_{I_{REG}} maximum should never be externally driven to any level other than V_{DD} - 0.15 V
3. 2000 pF load LCD, 32 Hz frame frequency

7 Dimensions

7.1 Obtaining package dimensions

Package dimensions are provided in package drawings.

To find a package drawing, go to <http://www.freescale.com> and perform a keyword search for the drawing's document number:

If you want the drawing for this package	Then use this document number
80-pin LQFP	98ASS23174W
81-pin MAPBGA	98ASA10631D

8 Pinout

8.1 K51 Signal Multiplexing and Pin Assignments

The following table shows the signals available on each pin and the locations of these pins on the devices supported by this document. The Port Control Module is responsible for selecting which ALT functionality is available on each pin.

NOTE

The 81-pin ballmap assignments are currently being developed.
The • in the entries in this package column indicate which signals are present on the package.

81 MAP BGA	80 LQF P	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
•	1	VDD	VDD	VDD								
•	2	VSS	VSS	VSS								
•	3	USB0_DP	USB0_DP	USB0_DP								
•	4	USB0_DM	USB0_DM	USB0_DM								
•	5	VOUT33	VOUT33	VOUT33								
•	6	VREGIN	VREGIN	VREGIN								
•	7	ADC0_DP1/ OP0_DP0	ADC0_DP1/ OP0_DP0	ADC0_DP1/ OP0_DP0								
•	8	ADC0_DM1/ OP0_DM0	ADC0_DM1/ OP0_DM0	ADC0_DM1/ OP0_DM0								
•	9	ADC1_DP1/ OP1_DP0/ OP1_DM1	ADC1_DP1/ OP1_DP0/ OP1_DM1	ADC1_DP1/ OP1_DP0/ OP1_DM1								
•	10	ADC1_DM1/ OP1_DM0	ADC1_DM1/ OP1_DM0	ADC1_DM1/ OP1_DM0								
•	11	PGA0_DP/ ADC0_DP0/ ADC1_DP3	PGA0_DP/ ADC0_DP0/ ADC1_DP3	PGA0_DP/ ADC0_DP0/ ADC1_DP3								
•	12	PGA0_DM/ ADC0_DM0/ ADC1_DM3	PGA0_DM/ ADC0_DM0/ ADC1_DM3	PGA0_DM/ ADC0_DM0/ ADC1_DM3								
•	13	PGA1_DP/ ADC1_DP0/ ADC0_DP3	PGA1_DP/ ADC1_DP0/ ADC0_DP3	PGA1_DP/ ADC1_DP0/ ADC0_DP3								
•	14	PGA1_DM/ ADC1_DM0/ ADC0_DM3	PGA1_DM/ ADC1_DM0/ ADC0_DM3	PGA1_DM/ ADC1_DM0/ ADC0_DM3								
•	15	VDDA	VDDA	VDDA								
•	16	VREFH	VREFH	VREFH								

Pinout

81 MAP BGA	80 LQF P	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
•	17	VREFL	VREFL	VREFL								
•	18	VSSA	VSSA	VSSA								
•	19	ADC1_SE1 6/ OP1_OUT/ ADC0_SE2 2/OP0_DP2/ OP1_DP2	ADC1_SE1 6/ OP1_OUT/ ADC0_SE2 2/OP0_DP2/ OP1_DP2	ADC1_SE1 6/ OP1_OUT/ ADC0_SE2 2/OP0_DP2/ OP1_DP2								
•	20	ADC0_SE1 6/ OP0_OUT/ CMP1_IN2/ ADC0_SE2 1/OP0_DP1/ OP1_DP1	ADC0_SE1 6/ OP0_OUT/ CMP1_IN2/ ADC0_SE2 1/OP0_DP1/ OP1_DP1	ADC0_SE1 6/ OP0_OUT/ CMP1_IN2/ ADC0_SE2 1/OP0_DP1/ OP1_DP1								
•	21	VREF_OUT/ CMP1_IN5/ CMP0_IN5/ ADC1_SE1 8	VREF_OUT	VREF_OUT/ CMP1_IN5/ CMP0_IN5/ ADC1_SE1 8								
•	22	TRIO_OUT/ OP1_DM2	TRIO_OUT/ OP1_DM2	TRIO_OUT/ OP1_DM2								
•	23	TRIO_DM	TRIO_DM	TRIO_DM								
•	24	TRIO_DP	TRIO_DP	TRIO_DP								
•	25	TRI1_DM	TRI1_DM	TRI1_DM								
•	26	TRI1_DP	TRI1_DP	TRI1_DP								
•	27	TRI1_OUT/ ADC1_SE2 2	TRI1_OUT	TRI1_OUT/ ADC1_SE2 2								
•	28	DAC0_OUT/ CMP1_IN3/ ADC0_SE2 3/OP0_DP4/ OP1_DP4	DAC0_OUT	DAC0_OUT/ CMP1_IN3/ ADC0_SE2 3/OP0_DP4/ OP1_DP4								
•	29	DAC1_OUT/ ADC1_SE2 3/OP0_DP5/ OP1_DP5	DAC1_OUT	DAC1_OUT/ ADC1_SE2 3/OP0_DP5/ OP1_DP5								
•	30	XTAL32	XTAL32	XTAL32								
•	31	EXTAL32	EXTAL32	EXTAL32								
•	32	VBAT	VBAT	VBAT								
•	33	PTA0	JTAG_TCLK/ SWD_CLK/ EZP_CLK	TSIO_CH1	PTA0	UART0_CTS_b	FTM0_CH5				JTAG_TCLK/ SWD_CLK	EZP_CLK
•	34	PTA1	JTAG_TDI/ EZP_DI	TSIO_CH2	PTA1	UART0_RX	FTM0_CH6				JTAG_TDI	EZP_DI

81 MAP BGA	80 LQF P	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
•	35	PTA2	JTAG_TDO/ TRACE_SW O/EZP_DO	TSIO_CH3	PTA2	UART0_TX	FTM0_CH7				JTAG_TDO/ TRACE_SW O	EZP_DO
•	36	PTA3	JTAG_TMS/ SWD_DIO	TSIO_CH4	PTA3	UART0_RT S_b	FTM0_CH0				JTAG_TMS/ SWD_DIO	
•	37	PTA4	NMI_b/ EZP_CS_b	TSIO_CH5	PTA4		FTM0_CH1				NMI_b	EZP_CS_b
•	38	VDD	VDD	VDD								
•	39	VSS	VSS	VSS								
•	40	PTA18	EXTAL	EXTAL	PTA18		FTM0_FLT2	FTM_CLKIN 0				
•	41	PTA19	XTAL	XTAL	PTA19		FTM1_FLT0	FTM_CLKIN 1		LPT0_ALT1		
•	42	RESET_b	RESET_b	RESET_b								
•	43	PTB0	LCD_P0/ ADC0_SE8/ ADC1_SE8/ TSIO_CH0	LCD_P0/ ADC0_SE8/ ADC1_SE8/ TSIO_CH0	PTB0	I2C0_SCL	FTM1_CH0			FTM1_QD_ PHA	LCD_P0	
•	44	PTB1	LCD_P1/ ADC0_SE9/ ADC1_SE9/ TSIO_CH6	LCD_P1/ ADC0_SE9/ ADC1_SE9/ TSIO_CH6	PTB1	I2C0_SDA	FTM1_CH1			FTM1_QD_ PHB	LCD_P1	
•	45	PTB2	LCD_P2/ ADC0_SE1 2/TSIO_CH7	LCD_P2/ ADC0_SE1 2/TSIO_CH7	PTB2	I2C0_SCL	UART0_RT S_b			FTM0_FLT3	LCD_P2	
•	46	PTB3	LCD_P3/ ADC0_SE1 3/TSIO_CH8	LCD_P3/ ADC0_SE1 3/TSIO_CH8	PTB3	I2C0_SDA	UART0_CT S_b			FTM0_FLT0	LCD_P3	
•	47	PTB8	LCD_P8	LCD_P8	PTB8		UART3_RT S_b				LCD_P8	
•	48	PTB9	LCD_P9	LCD_P9	PTB9	SPI1_PCS1	UART3_CT S_b				LCD_P9	
•	49	PTB10	LCD_P10/ ADC1_SE1 4	LCD_P10/ ADC1_SE1 4	PTB10	SPI1_PCS0	UART3_RX			FTM0_FLT1	LCD_P10	
•	50	PTB11	LCD_P11/ ADC1_SE1 5	LCD_P11/ ADC1_SE1 5	PTB11	SPI1_SCK	UART3_TX			FTM0_FLT2	LCD_P11	
•	51	PTB16	LCD_P12/ TSIO_CH9	LCD_P12/ TSIO_CH9	PTB16	SPI1_SOUT	UART0_RX			EWM_IN	LCD_P12	
•	52	PTB17	LCD_P13/ TSIO_CH10	LCD_P13/ TSIO_CH10	PTB17	SPI1_SIN	UART0_TX			EWM_OUT _b	LCD_P13	
•	53	PTB18	LCD_P14/ TSIO_CH11	LCD_P14/ TSIO_CH11	PTB18		FTM2_CH0	I2S0_TX_B CLK		FTM2_QD_ PHA	LCD_P14	
•	54	PTB19	LCD_P15/ TSIO_CH12	LCD_P15/ TSIO_CH12	PTB19		FTM2_CH1	I2S0_TX_F S		FTM2_QD_ PHB	LCD_P15	
•	55	PTC0	LCD_P20/ ADC0_SE1	LCD_P20/ ADC0_SE1	PTC0	SPI0_PCS4	PDB0_EXT RG	I2S0_TXD			LCD_P20	

Pinout

81 MAP BGA	80 LQF P	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
			4/ TSI0_CH13	4/ TSI0_CH13								
•	56	PTC1	LCD_P21/ ADC0_SE1 5/ TSI0_CH14	LCD_P21/ ADC0_SE1 5/ TSI0_CH14	PTC1	SPI0_PCS3	UART1_RT S_b	FTM0_CH0			LCD_P21	
•	57	PTC2	LCD_P22/ ADC0_SE4 b/ CMP1_IN0/ TSI0_CH15	LCD_P22/ ADC0_SE4 b/ CMP1_IN0/ TSI0_CH15	PTC2	SPI0_PCS2	UART1_CT S_b	FTM0_CH1			LCD_P22	
•	58	PTC3	LCD_P23/ CMP1_IN1	LCD_P23/ CMP1_IN1	PTC3	SPI0_PCS1	UART1_RX	FTM0_CH2			LCD_P23	
•	59	VSS	VSS	VSS								
•	60	VLL3	VLL3	VLL3								
•	61	VLL2	VLL2	VLL2								
•	62	VLL1	VLL1	VLL1								
•	63	VCAP2	VCAP2	VCAP2								
•	64	VCAP1	VCAP1	VCAP1								
•	65	PTC4	LCD_P24	LCD_P24	PTC4	SPI0_PCS0	UART1_TX	FTM0_CH3		CMP1_OUT	LCD_P24	
•	66	PTC5	LCD_P25	LCD_P25	PTC5	SPI0_SCK		LPT0_ALT2		CMP0_OUT	LCD_P25	
•	67	PTC6	LCD_P26/ CMP0_IN0	LCD_P26/ CMP0_IN0	PTC6	SPI0_SOUT	PDB0_EXT RG				LCD_P26	
•	68	PTC7	LCD_P27/ CMP0_IN1	LCD_P27/ CMP0_IN1	PTC7	SPI0_SIN					LCD_P27	
•	69	PTC8	LCD_P28/ ADC1_SE4 b/ CMP0_IN2	LCD_P28/ ADC1_SE4 b/ CMP0_IN2	PTC8		I2S0_MCLK	I2S0_CLKIN			LCD_P28	
•	70	PTC9	LCD_P29/ ADC1_SE5 b/ CMP0_IN3	LCD_P29/ ADC1_SE5 b/ CMP0_IN3	PTC9			I2S0_RX_B CLK		FTM2_FLT0	LCD_P29	
•	71	PTC10	LCD_P30/ ADC1_SE6 b/ CMP0_IN4	LCD_P30/ ADC1_SE6 b/ CMP0_IN4	PTC10	I2C1_SCL		I2S0_RX_F S			LCD_P30	
•	72	PTC11	LCD_P31/ ADC1_SE7 b	LCD_P31/ ADC1_SE7 b	PTC11	I2C1_SDA		I2S0_RXD			LCD_P31	
•	73	PTD0	LCD_P40	LCD_P40	PTD0	SPI0_PCS0	UART2_RT S_b				LCD_P40	
•	74	PTD1	LCD_P41/ ADC0_SE5 b	LCD_P41/ ADC0_SE5 b	PTD1	SPI0_SCK	UART2_CT S_b				LCD_P41	
•	75	PTD2	LCD_P42	LCD_P42	PTD2	SPI0_SOUT	UART2_RX				LCD_P42	
•	76	PTD3	LCD_P43	LCD_P43	PTD3	SPI0_SIN	UART2_TX				LCD_P43	

81 MAP BGA	80 LQF P	Pin Name	Default	ALT0	ALT1	ALT2	ALT3	ALT4	ALT5	ALT6	ALT7	EzPort
•	77	PTD4	LCD_P44	LCD_P44	PTD4	SPI0_PCS1	UART0_RT S_b	FTM0_CH4		EWM_IN	LCD_P44	
•	78	PTD5	LCD_P45/ ADC0_SE6 b	LCD_P45/ ADC0_SE6 b	PTD5	SPI0_PCS2	UART0_CT S_b	FTM0_CH5		EWM_OUT _b	LCD_P45	
•	79	PTD6	LCD_P46/ ADC0_SE7 b	LCD_P46/ ADC0_SE7 b	PTD6	SPI0_PCS3	UART0_RX	FTM0_CH6		FTM0_FLT0	LCD_P46	
•	—	VSS	VSS	VSS								
•	80	PTD7	LCD_P47	LCD_P47	PTD7	CMT_IRO	UART0_TX	FTM0_CH7		FTM0_FLT1	LCD_P47	

8.2 K51 Pinouts

The below figure shows the pinout diagram for the devices supported by this document. Many signals may be multiplexed onto a single pin. To determine what signals can be used on which pin, see the previous section.

NOTE

The 81 MAPBGA ballmap assignments are currently being developed.

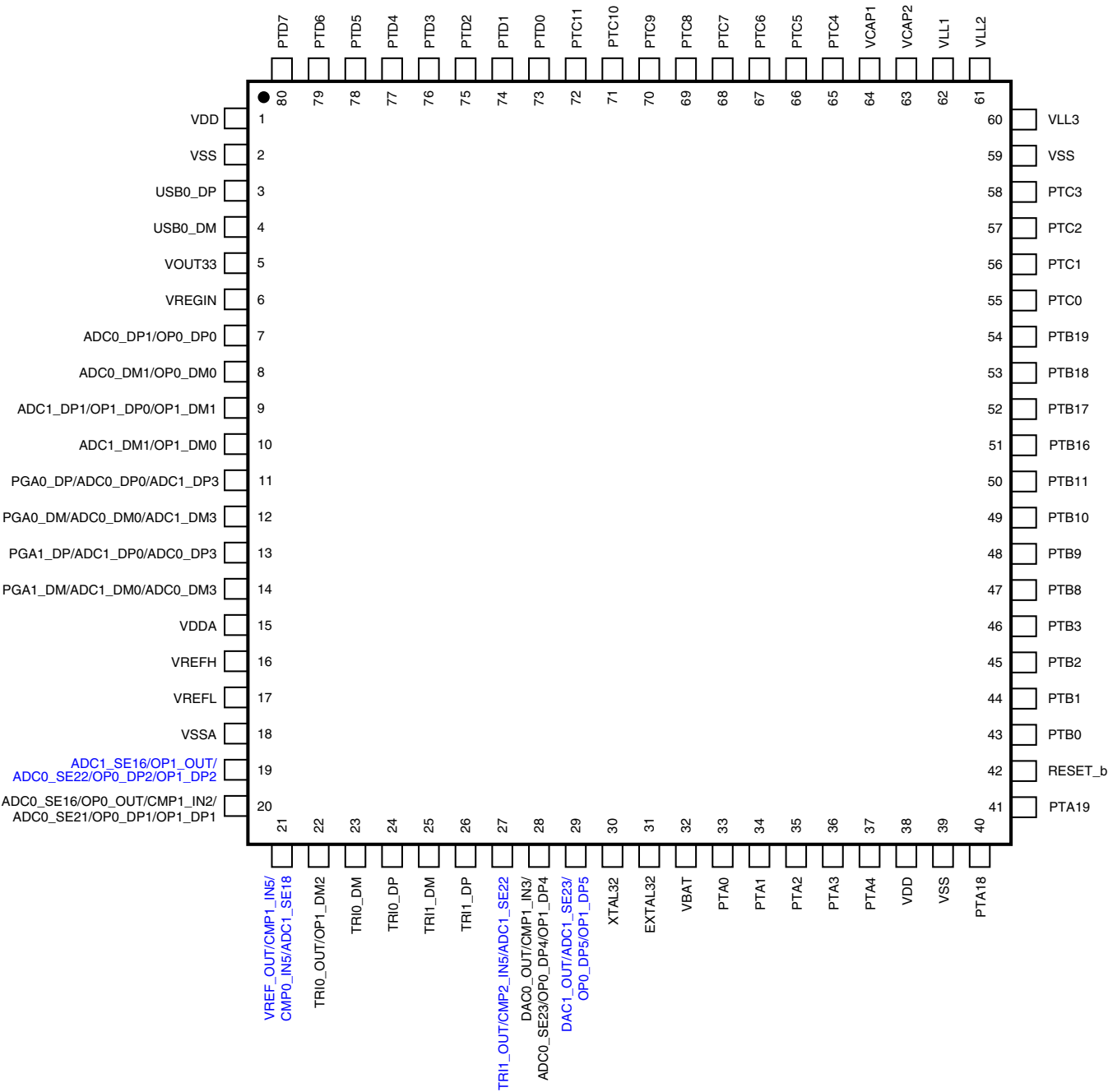


Figure 28. K51 80 LQFP Pinout Diagram

9 Revision History

The following table provides a revision history for this document.

Table 49. Revision History

Rev. No.	Date	Substantial Changes
2	3/2011	Initial public revision
3	3/2011	Added sections that were inadvertently removed in previous revision
4	3/2011	Reworded I_{IC} footnote in "Voltage and Current Operating Requirements" table. Added paragraph to "Peripheral operating requirements and behaviors" section. Added "JTAG full voltage range electricals" table to the "JTAG electricals" section.

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