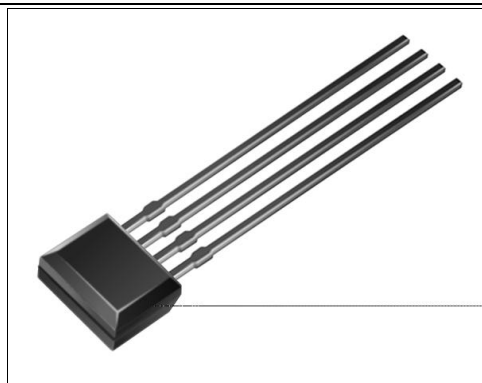


# HLC2701

## Encoder Detector

### FEATURES

- Side-looking plastic package
- TTL/LSTTL/CMOS compatible
- Inverting logic output
- Linear or rotary encoder applications
- Resolution to 0.009 in. (.229 mm)
- Sensitivity versus temperature compensation
- Mechanically and spectrally matched to SEP8506 and SEP8706 infrared emitting diodes



INFRA-74.TIF

### DESCRIPTION

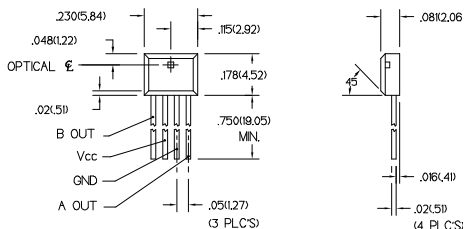
The HLC2701 detector is designed to sense speed and direction of mechanical motion. Applications include rotary and linear encoders; the device is especially well suited for the encoding function in an optical mouse. The detector is a monolithic IC, consisting of two narrow adjacent photodiodes, amplifiers, and Schmitt trigger output stages. The outputs are NPN collectors with internal 10 k $\Omega$  (nominal) pull-up resistors to V<sub>CC</sub> which can directly drive TTL loads. It incorporates circuitry to compensate the sensitivity for the output power versus temperature characteristics of an IRED. The IC is encapsulated in a molded, unlensed black plastic package which is transmissive to IR energy, yet provides shielding from visible light.

In a typical application, the HLC2701 is used in conjunction with an IRED and an encoder disk or linear encoder strip attached to an element for which speed and direction of movement is to be sensed. As the interruptive pattern moves, the sensor provides two phase shifted output signals (active low) which can be processed to provide the speed and direction information.

The sensing areas of the IC are each 0.008 in. (.203 mm) in width and in .015 in. (.381 mm) in height with a 0.001 in. (.0254 mm) separation, for center-to-center spacing of 0.009 in. (.203 mm), and outside edge to edge distance of 0.017 in. (.432 mm).

### OUTLINE DIMENSIONS in inches (mm)

Tolerance	3 plc decimals	$\pm 0.005(0.12)$
	2 plc decimals	$\pm 0.020(0.51)$



DIM\_030.cdr

# HLC2701

## Encoder Detector

### ELECTRICAL CHARACTERISTICS (-40°C to +85°C unless otherwise noted)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	TEST CONDITIONS
Operating Supply Voltage	V <sub>CC</sub>	4.5		5.5	V	
Turn-on Threshold Irradiance <sup>(2)</sup>	E <sub>ET(+)</sub>				mW/cm <sup>2</sup>	V <sub>CC</sub> =5 V
HLC2701-001		0.05		2.0		T <sub>A</sub> =25°C
Hysteresis <sup>(3)</sup>	HYST		28		%	
Supply Current	I <sub>CC</sub>			7.0	mA	V <sub>CC</sub> =5.25 V
High Level Output Voltage (A and B)	V <sub>OH</sub>	2.4			V	V <sub>CC</sub> =5 V I <sub>OH</sub> =0, E <sub>e</sub> =0
Low Level Output Voltage (A and B)	V <sub>OL</sub>			0.4	V	V <sub>CC</sub> =5 V, I <sub>OL</sub> =1.6 mA E <sub>e</sub> =2.0 mW/cm <sup>2</sup>
Internal Pull-Up Resistor	R <sub>INT</sub>	5.0	10.0	20.0	kΩ	
Operate Point Temperature Coefficient	O <sub>PTC</sub>		-0.76		%/°C	Emitter @ Constant Temperature
Output Rise Time, Output Fall Time	t <sub>r</sub> , t <sub>f</sub>		100		ns	V <sub>CC</sub> =5 V R <sub>L</sub> =1 kΩ T <sub>A</sub> =25°C
Propagation Delay, Low-High, High-Low	t <sub>PLH</sub> , t <sub>PHL</sub>		5.0		μs	V <sub>CE</sub> =5 V R <sub>L</sub> =1 kΩ T <sub>A</sub> =25°C

#### Notes

1. It is recommended that a bypass capacitor, 0.1 μF typical, be added between V<sub>CC</sub> and GND near the device in order to stabilize power supply line.
2. The radiation source is an IRED with a peak wavelength of 880 nm.
3. Hysteresis is defined as the difference between the operating and release threshold intensities, expressed as a percentage of the operate threshold intensity.

### ABSOLUTE MAXIMUM RATINGS

(25°C Free-Air Temperature unless otherwise noted)

#### Duration of Output

Short to V <sub>CC</sub> or Ground	1.0 sec.
Operating Temperature Range	-40°C to 85°C
Storage Temperature Range	-40°C to 85°C
Soldering Temperature (5 sec)	240°C

Honeywell reserves the right to make changes in order to improve design and supply the best products possible.

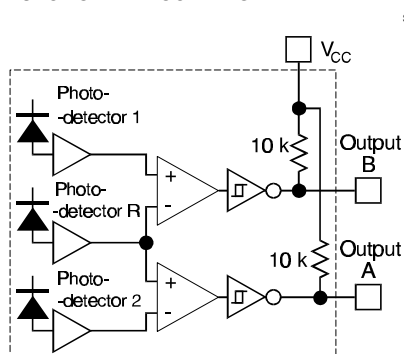
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## Encoder Detector

### FUNCTIONAL BLOCK DIAGRAM



### SWITCHING WAVEFORM

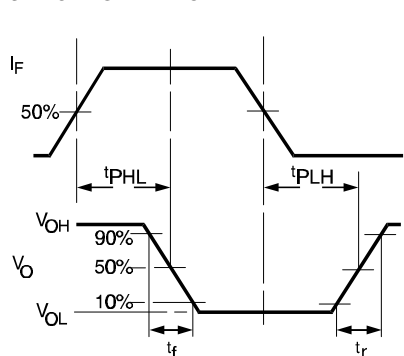
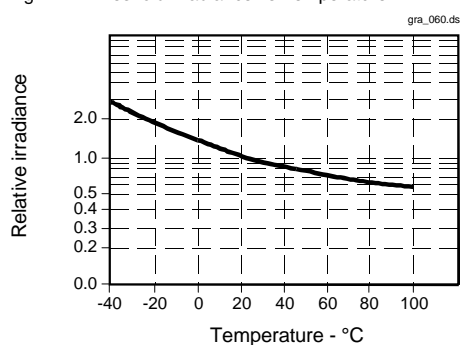


Fig. 2 Threshold Irradiance vs Temperature



### SWITCHING TIME TEST CIRCUIT

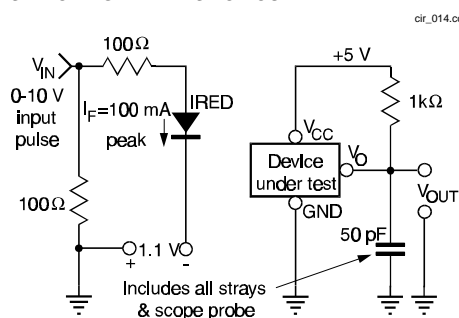


Fig. 1 Responsivity vs Angular Displacement

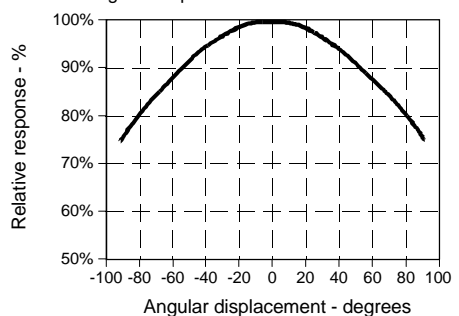
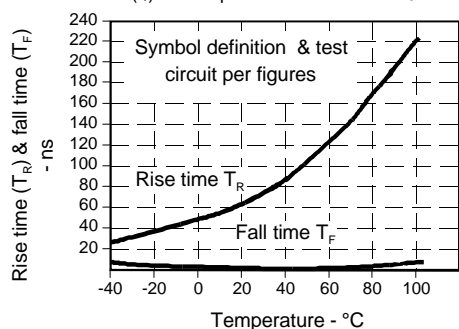


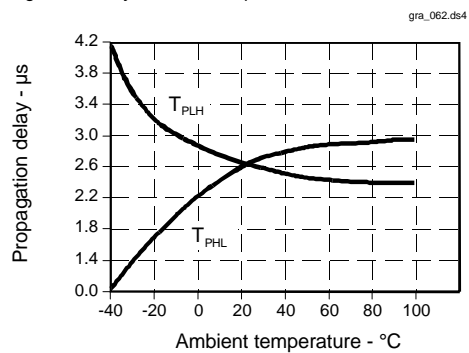
Fig. 3 Output Rise Time ( $t_r$ ) and Output Fall Time ( $t_f$ ) vs Temperature



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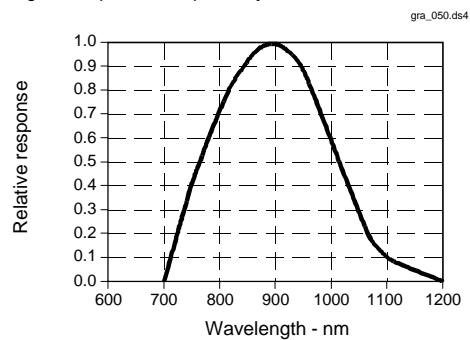
## Encoder Detector

Fig. 4 Delay Time vs Temperature



All Performance Curves Show Typical Values

Fig. 5 Spectral Responsivity



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