

HEF4027B-Q100

Dual JK flip-flop

Rev. 3 — 8 August 2024

Product data sheet

1. General description

The HEF4027B-Q100 is a dual positive-edge triggered JK flip-flop featuring independent set direct (nSD), clear direct (nCD), clock inputs (nCP) and complementary outputs (nQ and nQ̄). Data is accepted when nCP is LOW, and transferred to the output on the positive-going edge of the clock. The asynchronous clear-direct (nCD) and set-direct (nSD) are independent and override the nJ, nK, and nCP inputs. Schmitt-trigger action in the clock input makes the circuit highly tolerant to slower clock rise and fall times. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of V_{DD} .

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 3) and is suitable for use in automotive applications.

2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 3)
 - Specified from -40 °C to +85 °C
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
 - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2000 V
 - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1000 V

3. Applications

- Registers
- Counters
- Control circuits

4. Ordering information

Table 1. Ordering information

| Type number | Package | | | |
|--------------------------------|-------------------|------|---|--------------------------|
| | Temperature range | Name | Description | Version |
| HEF4027BT-Q100 | -40 °C to +85 °C | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |

5. Functional diagram

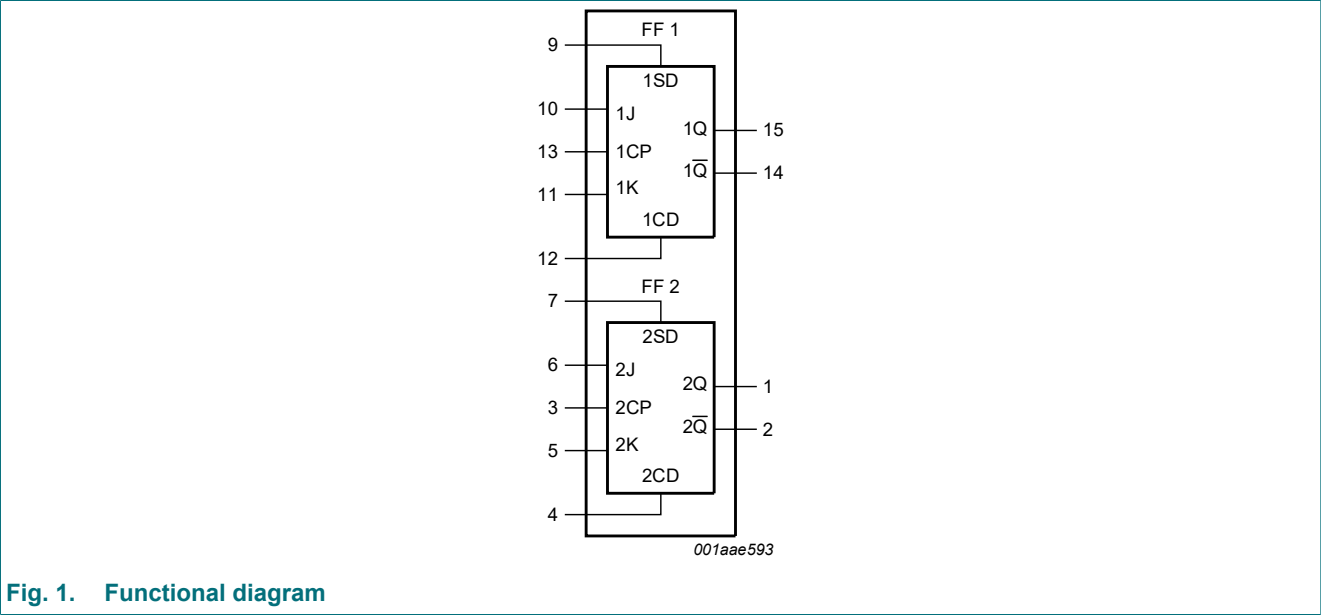


Fig. 1. Functional diagram

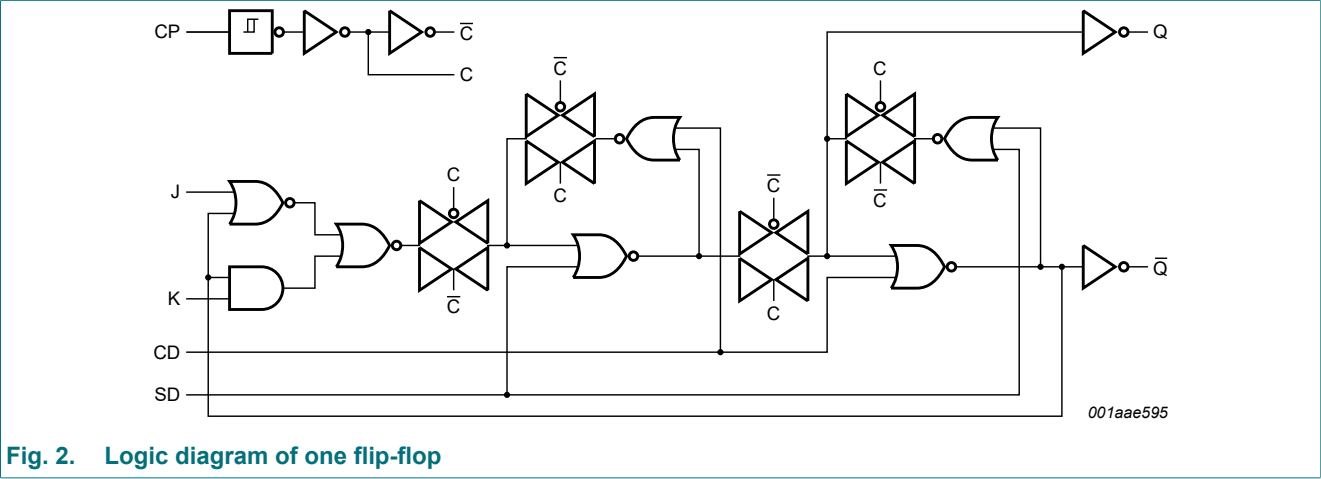
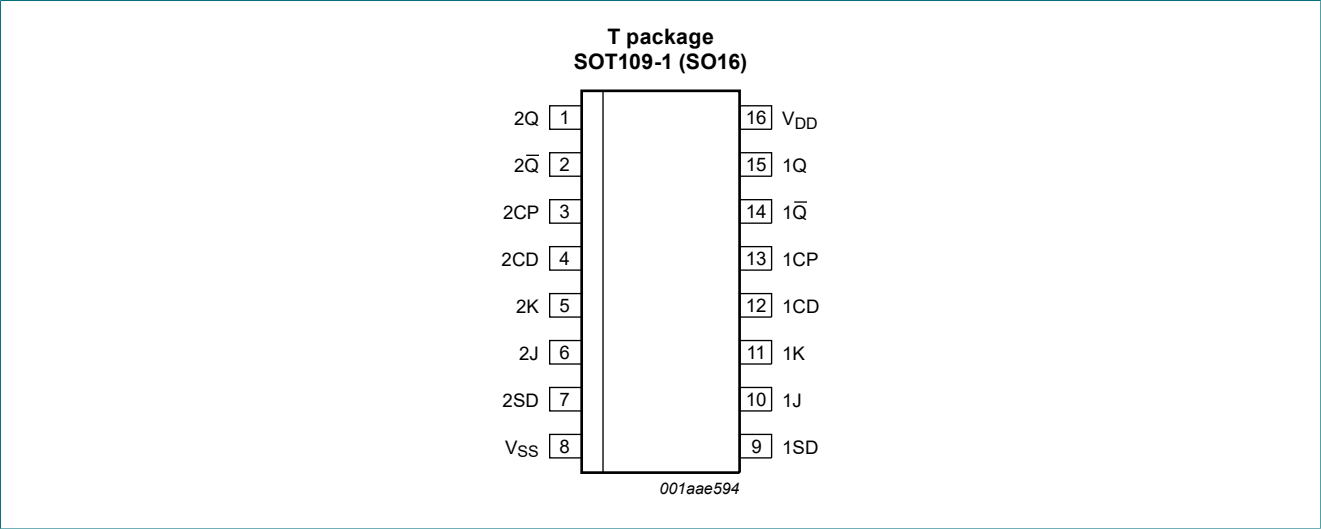


Fig. 2. Logic diagram of one flip-flop

6. Pinning information

6.1. Pinning



6.2. Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|-------|---|
| V _{SS} | 8 | ground supply voltage |
| 1SD, 2SD | 9, 7 | asynchronous set-direct input (active HIGH) |
| 1J, 2J | 10, 6 | synchronous input |
| 1K, 2K | 11, 5 | synchronous input |
| 1CD, 2CD | 12, 4 | asynchronous clear-direct input (active HIGH) |
| 1CP, 2CP | 13, 3 | clock input (LOW-to-HIGH edge-triggered) |
| 1Q̄, 2Q̄ | 14, 2 | complement output |
| 1Q, 2Q | 15, 1 | true output |
| V _{DD} | 16 | supply voltage |

7. Functional description

Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care.; ↑ = positive-going transition.

| Inputs | | | | | Outputs | |
|--------|-----|-----|----|----|-----------|-----------|
| nSD | nCD | nCP | nJ | nK | nQ | nQ̄ |
| H | L | X | X | X | H | L |
| L | H | X | X | X | L | H |
| H | H | X | X | X | H | H |
| L | L | ↑ | L | L | no change | no change |
| L | L | ↑ | H | L | H | L |
| L | L | ↑ | L | H | L | H |
| L | L | ↑ | H | H | nQ̄ | nQ |

8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|------------------|-------------------------|---|------|-----------------------|------|
| V _{DD} | supply voltage | | -0.5 | +18 | V |
| I _{IK} | input clamping current | V _I < -0.5 V or V _I > V _{DD} + 0.5 V | - | ±10 | mA |
| V _I | input voltage | | -0.5 | V _{DD} + 0.5 | V |
| I _{OK} | output clamping current | V _O < -0.5 V or V _O > V _{DD} + 0.5 V | - | ±10 | mA |
| I _{I/O} | input/output current | | - | ±10 | mA |
| I _{DD} | supply current | | - | 50 | mA |
| T _{stg} | storage temperature | | -65 | +150 | °C |
| T _{amb} | ambient temperature | in free air | -40 | +85 | °C |
| P _{tot} | total power dissipation | T _{amb} -40 °C to +85 °C | - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

9. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|------------------|-------------------------------------|------------------------|-----|-----------------|------|
| V _{DD} | supply voltage | | 3 | 15 | V |
| V _I | input voltage | | 0 | V _{DD} | V |
| T _{amb} | ambient temperature | in free air | -40 | +85 | °C |
| Δt/ΔV | input transition rise and fall rate | V _{DD} = 5 V | - | 3.75 | μs/V |
| | | V _{DD} = 10 V | - | 0.5 | μs/V |
| | | V _{DD} = 15 V | - | 0.08 | μs/V |

10. Static characteristics

Table 6. Static characteristics

$V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ °C}$ | | $T_{amb} = +25\text{ °C}$ | | $T_{amb} = +85\text{ °C}$ | | Unit |
|----------|---------------------------|--------------------------------|----------|---------------------------|-----------|---------------------------|-----------|---------------------------|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I_I | input leakage current | | 15 V | - | ± 0.3 | - | ± 0.3 | - | ± 1.0 | μA |
| I_{DD} | supply current | $I_O = 0\text{ A}$ | 5 V | - | 4.0 | - | 4.0 | - | 30 | μA |
| | | | 10 V | - | 8.0 | - | 8.0 | - | 60 | μA |
| | | | 15 V | - | 16.0 | - | 16.0 | - | 120 | μA |
| C_I | input capacitance | | - | - | - | - | 7.5 | - | - | pF |

11. Dynamic characteristics

Table 7. Dynamic characteristics

$V_{SS} = 0\text{ V}$; $T_{amb} = 25\text{ °C}$ unless otherwise specified; for test circuit see Fig. 6.

| Symbol | Parameter | Conditions | V_{DD} | Extrapolation formula [1] | Min | Typ | Max | Unit |
|-----------|-------------------------------|--|----------|--|-----|-----|-----|------|
| t_{PHL} | HIGH to LOW propagation delay | CP \rightarrow Q, \bar{Q} ; see Fig. 3 | 5 V | $78\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 105 | 210 | ns |
| | | | 10 V | $29\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 40 | 80 | ns |
| | | | 15 V | $22\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 30 | 60 | ns |
| | | CD \rightarrow Q; see Fig. 3 | 5 V | $93\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 120 | 240 | ns |
| | | | 10 V | $33\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 45 | 90 | ns |
| | | | 15 V | $27\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 35 | 70 | ns |
| | | SD \rightarrow \bar{Q} ; see Fig. 3 | 5 V | $113\text{ ns} + (0.55\text{ ns/pF})C_L$ | - | 140 | 280 | ns |
| | | | 10 V | $44\text{ ns} + (0.23\text{ ns/pF})C_L$ | - | 55 | 110 | ns |
| | | | 15 V | $32\text{ ns} + (0.16\text{ ns/pF})C_L$ | - | 40 | 80 | ns |

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula [1] | Min | Typ | Max | Unit |
|------------------|-------------------------------|--|-----------------|------------------------------------|-----|-----|-----|------|
| t _{PLH} | LOW to HIGH propagation delay | CP → Q, \overline{Q} ; see Fig. 3 | 5 V | 58 ns + (0.55 ns/pF)C _L | - | 85 | 170 | ns |
| | | | 10 V | 27 ns + (0.23 ns/pF)C _L | - | 35 | 70 | ns |
| | | | 15 V | 22 ns + (0.16 ns/pF)C _L | - | 30 | 60 | ns |
| | | CD → \overline{Q} ; see Fig. 3 | 5 V | 48 ns + (0.55 ns/pF)C _L | - | 75 | 150 | ns |
| | | | 10 V | 24 ns + (0.23 ns/pF)C _L | - | 35 | 70 | ns |
| | | | 15 V | 17 ns + (0.16 ns/pF)C _L | - | 25 | 50 | ns |
| | | SD → Q; see Fig. 3 | 5 V | 43 ns + (0.55 ns/pF)C _L | - | 70 | 140 | ns |
| | | | 10 V | 19 ns + (0.23 ns/pF)C _L | - | 30 | 60 | ns |
| | | | 15 V | 17 ns + (0.16 ns/pF)C _L | - | 25 | 50 | ns |
| t _t | transition time | see Fig. 3 | 5 V [2] | 10 ns + (1.00 ns/pF)C _L | - | 60 | 120 | ns |
| | | | 10 V | 9 ns + (0.42 ns/pF)C _L | - | 30 | 60 | ns |
| | | | 15 V | 6 ns + (0.28 ns/pF)C _L | - | 20 | 40 | ns |
| t _{su} | set-up time | J, K → CP; see Fig. 4 | 5 V | | 50 | 25 | - | ns |
| | | | 10 V | | 30 | 10 | - | ns |
| | | | 15 V | | 20 | 5 | - | ns |
| t _h | hold time | J, K → CP; see Fig. 4 | 5 V | | 25 | 0 | - | ns |
| | | | 10 V | | 20 | 0 | - | ns |
| | | | 15 V | | 15 | 5 | - | ns |
| t _w | pulse width | CP LOW; minimum width; see Fig. 4 | 5 V | | 80 | 40 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 24 | 12 | - | ns |
| | | SD, CD HIGH; minimum width; see Fig. 5 | 5 V | | 90 | 45 | - | ns |
| | | | 10 V | | 40 | 20 | - | ns |
| | | | 15 V | | 30 | 15 | - | ns |
| t _{rec} | recovery time | SD, CD inputs; see Fig. 5 | 5 V | | +20 | -15 | - | ns |
| | | | 10 V | | +15 | -10 | - | ns |
| | | | 15 V | | +10 | -5 | - | ns |
| f _{max} | maximum frequency | CP input; J = K = HIGH; see Fig. 4 | 5 V | | 4 | 8 | - | MHz |
| | | | 10 V | | 12 | 25 | - | MHz |
| | | | 15 V | | 15 | 30 | - | MHz |

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).
[2] t_t is the same as t_{TLH} and t_{THL}.

Table 8. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. V_{SS} = 0 V; t_r = t_f ≤ 20 ns; T_{amb} = 25 °C.

| Symbol | Parameter | V _{DD} | Typical formula for P _D (μW) | Where: |
|----------------|---------------------------|-----------------|---|--|
| P _D | dynamic power dissipation | 5 V | $P_D = 900 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f _i = input frequency in MHz f _o = output frequency in MHz C _L = output load capacitance in pF V _{DD} = supply voltage in V Σ(f _o × C _L) = sum of the outputs |
| | | 10 V | $P_D = 4500 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | |
| | | 15 V | $P_D = 13200 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | |

11.1. Waveforms and test circuit

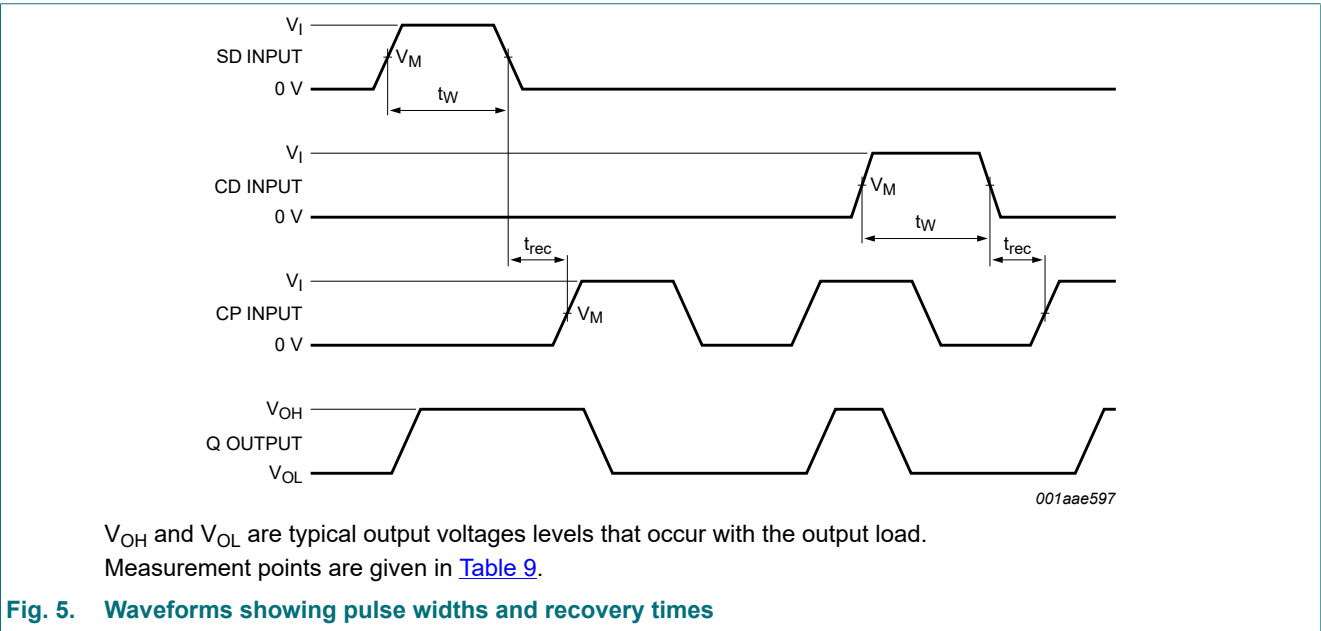
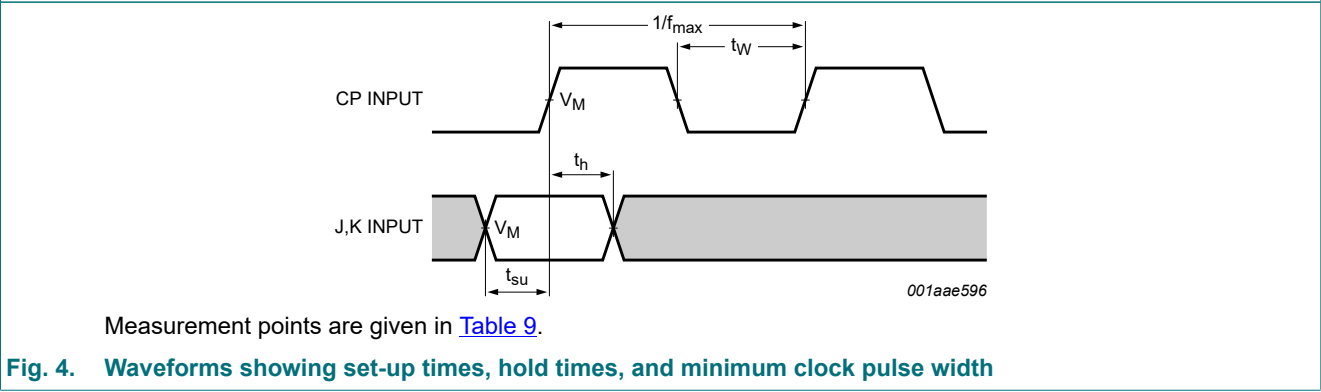
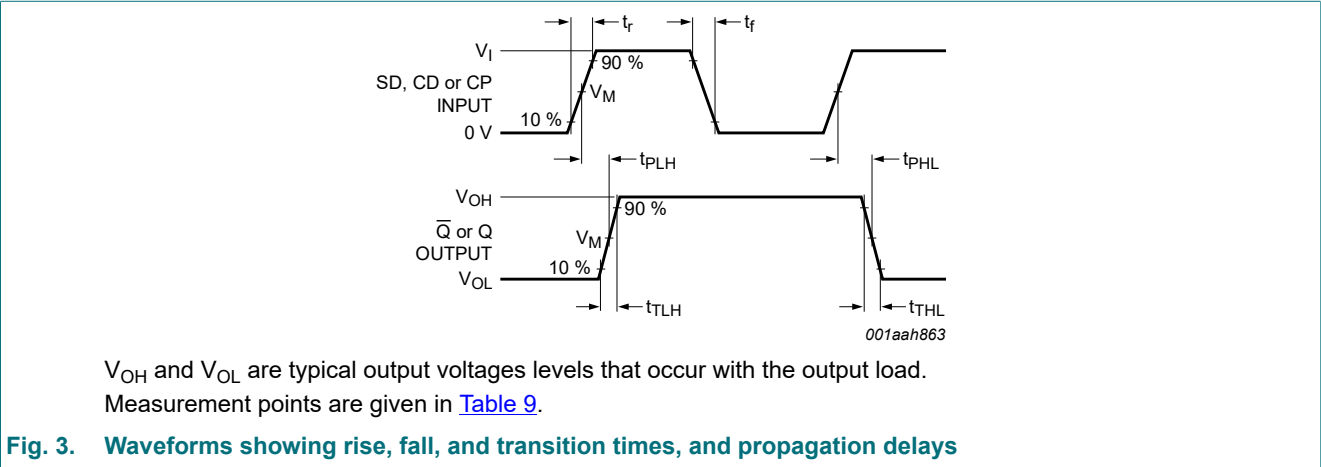
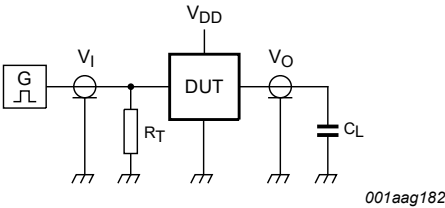


Table 9. Measurement points

| Supply voltage | Input | Output |
|----------------|-------------|-------------|
| V_{DD} | V_M | V_M |
| 5 V to 15 V | $0.5V_{DD}$ | $0.5V_{DD}$ |



Test data is given in [Table 10](#).
Definitions test circuit:
 C_L = load capacitance including jig and probe capacitance;
 R_T = termination resistance should be equal to the output impedance Z_o of the pulse generator.

Fig. 6. Test circuit

Table 10. Test data

| Supply voltage | Input | | Load |
|----------------|----------------------|--------------|-------|
| V_{DD} | V_I | t_r, t_f | C_L |
| 5 V to 15 V | V_{SS} or V_{DD} | ≤ 20 ns | 50 pF |

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

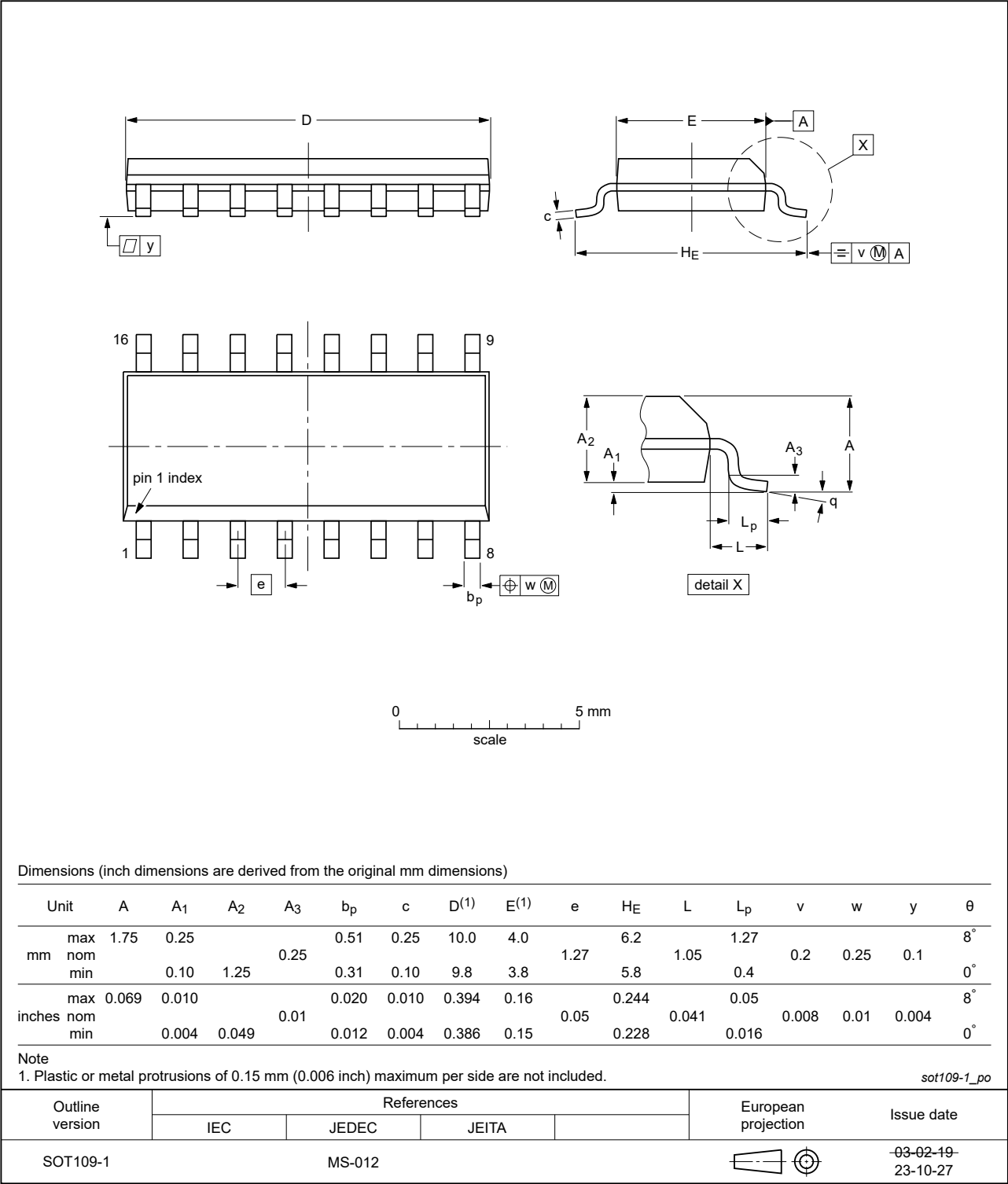


Fig. 7. Package outline SOT109-1 (SO16)

13. Abbreviations

Table 11. Abbreviations

| Acronym | Description |
|---------|---|
| ANSI | American National Standards Institute |
| CDM | Charged Device Model |
| CMOS | Complementary Metal-Oxide Semiconductor |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| ESDA | ElectroStatic Discharge Association |
| HBM | Human Body Model |
| JEDEC | Joint Electron Device Engineering Council |

14. Revision history

Table 12. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|-------------------|---|--------------------|---------------|-------------------|
| HEF4027B_Q100 v.3 | 20240808 | Product data sheet | - | HEF4027B_Q100 v.2 |
| Modifications: | <ul style="list-style-type: none">Section 2: ESD specification updated according to the latest JEDEC standard.Fig. 7: Aligned SO package outline drawing to JEDEC MS-012 | | | |
| HEF4027B_Q100 v.2 | 20211207 | Product data sheet | - | HEF4027B_Q100 v.1 |
| Modifications: | <ul style="list-style-type: none">The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.Legal texts have been adapted to the new company name where appropriate.Section 1 and Section 2 updated. | | | |
| HEF4027B_Q100 v.1 | 20130626 | Product data sheet | - | - |

15. Legal information

Data sheet status

| Document status [1][2] | Product status [3] | Definition |
|--------------------------------|--------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
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