EM78P131A

8-Bit Microcontroller with OTP ROM

Product Specification

Doc. Version 1.2

ELAN MICROELECTRONICS CORP.

September 2009



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Specification Revision History

Doc. Version	Revision Description	Date
1.0	Initial version	2008/06/30
1.1	Deleted the LVD function	2009/01/20
1.2	Added the LVD function	2009/09/16



1 General Description

The EM78P131A is an 8-bit microprocessor designed and developed with low-power and high-speed CMOS technology. It has an on-chip 1024×13-bit Electrical One Time Programmable Read Only Memory (OTP-ROM). It provides a protection bit to prevent intrusion of user's OTP memory code. Fifteen Code option bits are also available to meet user's requirements.

With its enhanced OTP-ROM feature, the EM78P131A provides a convenient way of developing and verifying user's programs. Moreover, this OTP device offers the advantages of easy and effective program updates, using development and programming tools. User can avail of the ELAN Writer to easily program his development code.

2 Features

- CPU Configuration
 - 1K×13 bits on-chip ROM
 - 32×8 bits on-chip registers (SRAM, general purpose)
 - 5 level stacks for subroutine nesting
 - Less than 1.5 mA at 5V/4MHz
 - Typically 15 μA, at 3V/32kHz
 - Typically 1 μA, during Sleep mode
- I/O Port Configuration
 - 1 bidirectional I/O ports : P6
 - 1 Input and 7 I/O pins
 - Wake-up port : P6
 - 3 Programmable pull-down I/O pins
 - 7 programmable pull-high I/O pins
 - 7 programmable open-drain I/O pins
 - External interrupt : P60
- Operating Voltage Range:
 - OTP version:
 Operating voltage range: 2.3V~5.5V
- Operating Temperature range: 0~70°C
- Operating Frequency range (base on 2 clocks):
 - Crystal Mode:

DC~20MHz/2clks @ 5V; DC~100ns inst. cycle @ 5V DC~8MHz/2clks @ 3V; DC~250ns inst. cycle @ 3V DC~4MHz/2clks @ 2.3V; DC~500ns inst. cycle @ 2.3V

ERC Mode:

DC~4MHz/2clks @ 5V; DC~500ns inst. cycle @ 5V DC~4MHz/2clks @ 3V; DC~500ns inst. cycle @ 3V DC~4MHz/2clks @ 2.3V; DC~500ns inst. cycle @ 2.3V

IRC Mode:

Oscillation mode : 4 MHz, 8 MHz, 1 MHz, 455kHz Process deviation : Typ. \pm 5.5%, Max. \pm 6% Temperature deviation : \pm 10% (0°C~70°C)

- Peripheral Configuration
 - 8-bit real time clock/counter (TCC) with selective signal sources, trigger edges, and overflow interrupt
- Three available Interrupts:
 - TCC overflow interrupt
 - Input-port status changed interrupt (wake-up from sleep mode)
 - External interrupt
- Special Features
 - Programmable free running watchdog timer
 - Power saving Sleep mode
 - Selectable Oscillation mode
- Other Features
 - Programmable prescaler of oscillator set-up time
 - One security register to prevent intrusion of user's OTP memory code
 - One configuration register to match user's requirement
 - · Two clocks per instruction cycle
 - Two LVD level selection / POR

(with \pm 0.3V allowance for error)

- Package Type:
 - 10-pin MSOP 118mil: EM78P131AMS10J

Note: Green products do not contain hazardous substances.



3 Pin Assignment

(1) 10-pin MSOP

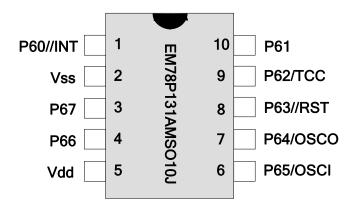


Figure 3-1 EM78P131AMS10J



Pin Description

4.1 EM78P131AMS10J

Symbol	Pin No.	Туре	Function		
P60//INT	1	I/O	General purpose input/output pin Pull-high/Pull-down/open-drain Wake up from sleep mode when the status of the pin changes. Schmitt Trigger input during programming mode. External interrupt pin triggered by a falling edge.		
P61	10	I/O	General purpose input/output pin Pull-high/Pull-down/open-drain Wake up from sleep mode when the status of the pin changes. Schmitt Trigger input during programming mode		
P62/TCC	9	I/O	General purpose input/output pin External Timer/Counter input Pull-high/Pull-down open-drain Wake up from sleep mode when the status of the pin changes.		
P63//RESET	8	I	P63 is input pin only Internal Pull-high is On if defined as /RESET. If set as /RESET and remains at logic low, the device will be reset. Wake-up from sleep mode when pin status changes. Voltage on /RESET must not exceed Vdd during normal mode.		
P64/OSCO	7	I/O	General purpose input/output pin External clock signal input Input pin of XT oscillator Pull-high/open-drain Wake up from sleep mode when the status of the pin changes.		
P65/OSCI	6 I/O		6 I/O		General purpose input/output pin External clock signal input Input pin of XT oscillator Pull-high/open-drain Wake up from sleep mode when the status of the pin changes.
P66, P67	4, 3	I/O	General purpose input/output pin Pull-high/open-drain Wake up from sleep mode when the status of the pin changes.		
VDD	5	_	Power supply		
VSS	2	ı	Ground		



5 Functional Description

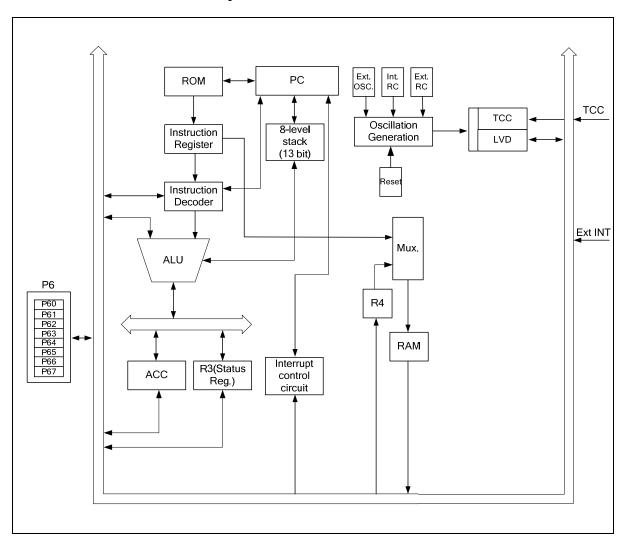


Figure 5-1 EM78P131A Functional Block Diagram

5.1 Operational Registers

5.1.1 R0 (Indirect Addressing Register)

R0 is not a physically implemented register. It is used as an indirect addressing pointer. Any instruction using R0 as a pointer actually accesses data pointed by the RAM Select Register (R4).

5.1.2 R1 (Timer Clock /Counter)

- Incremented by an external signal edge, which is defined by TE bit (CONT-4) through the TCC pin, or by the instruction cycle clock.
- Writable and readable as any other registers.
- Defined by resetting PAB (CONT-3).



- The prescaler is assigned to TCC, if the PAB bit (CONT-3) is reset.
- The contents of the prescaler counter will be cleared only when TCC register is written with a value.

5.1.3 R2 (Program Counter) and Stack

■ Depending on the device type, R2 and hardware stack are 10-bit wide. The structure is depicted in the following figure.

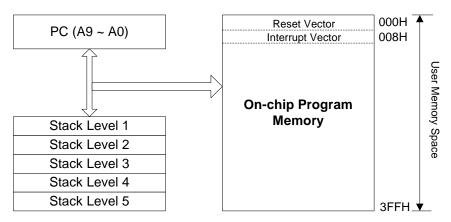


Fig 5-2 Program Counter Organization

- The configuration structure generates 1024×13 bits on-chip OTP ROM addresses to the relative programming instruction codes. One program page is 1024 words long.
- R2 is set as all "0" when under Reset condition.
- "JMP" instruction allows direct loading of the lower 10 program counter bits. Thus, "JMP" allows the PC to go to any location within a page.
- "CALL" instruction loads the lower 10 bits of the PC, and then PC+1 is pushed onto the stack. Thus, the subroutine entry address can be located anywhere within a page.
- "RET" ("RETLk", "RETI") instruction loads the program counter with the contents of the top-level stack.
- "ADD R2,A" allows the contents of 'A' to be added to the current PC, and the ninth and tenth bits of the PC will increase progressively.
- "MOV R2, A" allows loading of an address from the "A" register to the lower 8 bits of the PC, and the ninth and tenth bits of the PC will remain unchanged.
- Any instruction written to R2 (e.g. "MOV R2, A", "BC R2, 6", etc.) will cause the ninth bit and the tenth bit (A8 ~ A9) of the PC to remain unchanged.
- All instructions are single instruction cycle (fclk/2 or fclk/4) except for instructions that would change the contents of R2. Such instructions will need one more instruction cycle.



The Data Memory Configuration is as follows:

			· · · · · · · · · · · · · · · · · · ·	
Address	R	PAGE Registers		IOC PAGE Registers
00	R0			Reserve
01	R1	(TCC)	CONT	(Control Register)
02	R2	(PC)		Reserve
03	R3	(Status)		Reserve
04	R4	(RSR)		Reserve
05	R5	Reserve		Reserve
06	R6	(Port 6)	IOC6	(I/O Port Control Register)
07		Reserve		Reserve
08		Reserve		Reserve
09		Reserve		Reserve
0A		Reserve		Reserve
0B		Reserve	IOCB	(Pull-down Register)
0C		Reserve	IOCC	(Open-drain Control)
0D		Reserve	IOCD	(Pull-high Control Register)
0E		Reserve	IOCE	(WDT Control Register)
0F	RF	(Interrupt Status)	IOCF	(Interrupt Mask Register)
10 : 2F	G	eneral Registers		



5.1.4 R3 (Status Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RST	GP1	GP0	Т	Р	Z	DC	С

Bit 0 (C): Carry flag

Bit 1 (DC): Auxiliary carry flag

Bit 2 (Z): Zero flag

Set to "1" if the result of an arithmetic or logic operation is zero.

Bit 3 (P): Power down bit

Set to "1" during power on or by a "WDTC" command; and reset to "0" by a

"SLEP" command.

Bit 4 (T): Time-out bit

Set to "1" with the "SLEP" and "WDTC" commands, or during power up;

and reset to "0" by WDT time-out.

Bits 5 ~6 (GP0 ~ GP1): General-purpose read/write bits

Bit 7 (RST): Bit for reset type

0 : Set to 0 if the device wakes up from other reset type

1: Set to 1 if the device wakes up from sleep mode on a pin change

5.1.5 R4 (RAM Select Register)

Bits 0 ~ 5 are used to select registers (Address: 00~06, 0F~2F) in indirect addressing mode.

Bits 6 ~ 7 are general-purpose read bits.

See the Data Memory Configuration in Fig. 5-3.

5.1.6 R6 (Port 6)

R6 are I/O registers.

R5 are reserved.

P63 is input only.



5.1.7 RF (Interrupt Status Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	-	-	-	-	EXIF	ICIF	TCIF

Note: "1" means with interrupt request "0" means no interrupt occurs

Bit 0 (TCIF): TCC Overflow Interrupt Flag. Set when TCC overflows, reset by software.

Bit 1 (ICIF): Port 6 input status changed interrupt flag. Set when Port 6 input changes, reset by software.

Bit 2 (EXIF): External Interrupt Flag. Set by a falling edge on the /INT pin, reset by software.

Bits 3 ~ 7: Not used.

RF can be cleared by instruction but cannot be set.

IOCF is the interrupt mask register.

NOTE

The result of reading RF is the "logic AND" of RF and IOCF.

5.1.8 R10 ~ R2F

These are all 8-bit general-purpose registers.



5.2 Special Function Registers

5.2.1 A (Accumulator)

Internal data transfer operation, or instruction operand holding usually involves the temporary storage function of the Accumulator, which is not an addressable register.

5.2.2 CONT (Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	/INT	TS	TE	PAB	PSR2	PSR1	PSR0

Bit 0 ~ Bit 2 (PSR0 ~ PSR2): TCC/WDT prescaler bits

PSR2	PSR1	PSR0	TCC Rate	WDT Rate
0	0	0	1:2	1:1
0	0	1	1:4	1:2
0	1	0	1:8	1:4
0	1	1	1:16	1:8
1	0	0	1:32	1:16
1	0	1	1:64	1:32
1	1	0	1:128	1:64
1	1	1	1:256	1:128

Bit 3 (PAB): Prescaler Assigned Bit

0: TCC **1**: WDT

Bit 4 (TE): TCC signal edge

0 : increment if a transition from low to high takes place on the TCC pin1 : increment if a transition from high to low takes place on the TCC pin

Bit 5 (TS): TCC signal source

0: internal instruction cycle clock, P62 is a bidirectional I/O pin

1: transition on TCC pin

Bit 6 (/INT): Interrupt enable flag

0 : masked by DISI or hardware interrupt1 : enabled by ENI/RETI instructions

Bit 7: Not used

The CONT register is both readable and writable.

5.2.3 IOC6 (I/O Port Control Register)

0: defines the relative I/O pin as output

1 : sets the relative I/O pin into high impedance

IOC6 registers are both readable and writable.



5.2.4 IOCB (Pull-down Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	/PD6	/PD5	/PD4	-	-	-	-

Bit 0~3: Not used

Bit 4 (/PD4): Control bit used to enable pull-down of the 60 pin.

Bit 5 (/PD5): Control bit used to enable pull-down of the 61 pin.

Bit 6 (/PD6): Control bit used to enable pull-down of the 62 pin.

Bit 7: Not used

The IOCB Register is both readable and writable.

5.2.5 IOCC (Open-drain Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
OD7	OD6	OD5	OD4	-	OD2	OD1	OD0

Bit 0 (OD0): Control bit used to enable open-drain of the P60 pin.

0 : Disable open-drain output

1: Enable open-drain output

Bit 1 (OD1): Control bit used to enable open-drain of the P61 pin.

Bit 2 (OD2): Control bit used to enable open-drain of the P62 pin.

Bit 3: Not used

Bit 4 (OD4): Control bit used to enable open-drain of the P64 pin.

Bit 5 (OD5): Control bit used to enable open-drain of the P65 pin.

Bit 6 (OD6): Control bit used to enable open-drain of the P66 pin.

Bit 7 (OD7): Control bit used to enable open-drain of the P67 pin.

The IOCC Register is both readable and writable.

5.2.6 IOCD (Pull-high Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
/PH7	/PH6	/PH5	/PH4	-	/PH2	/PH1	/PH0

Bit 0 (/PH0): Control bit used to enable pull-high of the P60 pin.

0: Enable internal pull-high

1 : Disable internal pull-high

Bit 1 (/PH1): Control bit used to enable pull-high of the P61 pin.



Bit 2 (/PH2): Control bit is used to enable pull-high of the P62 pin.

Bit 3: Not used

Bit 4 (/PH4): Control bit used to enable pull-high of the P64 pin.

Bit 5 (/PH5): Control bit used to enable pull-high of the P65 pin.

Bit 6 (/PH6): Control bit used to enable pull-high of the P66 pin.

Bit 7 (/PH7): Control bit used to enable pull-high of the P67 pin.

The IOCD Register is both readable and writable.

5.2.7 IOCE (WDT Control Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
WDTE	EIS	-	-	-	LVDF	LVDSEL	LVDEN

Bit 0 (LVDEN): LVD function enable bit

0: disable

1: enable

Bit 1 (LVDSEL): LVD level select bit

0: set LVD level to 2.4V (with \pm 0.3V allowance for error).

1: set LVD level to 3.6V (with \pm 0.3V allowance for error).

Bit 2 (LVDF): Low voltage detector flag

Bits 3~ 5: Not used

Bit 6 (EIS): Control bit is used to define the function of the P60 (/INT) pin.

0: P60, bidirectional I/O pin.

1: /INT, external interrupt pin. In this case, the I/O control bit of P60 (Bit 0 of IOC6) must be set to "1."

When EIS is "0," the path of /INT is masked. When EIS is "1," the status of /INT pin can also be read by way of reading Port 6 (R6). See Figure 5-6 under Section 5.4 for reference.

EIS is both readable and writable.

Bit 7 (WDTE): Control bit used to enable the Watchdog timer.

0: Disable WDT

1: Enable WDT

WDTE is both readable and writable.



5.2.8 IOCF (Interrupt Mask Register)

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
-	-	-	-	-	EXIE	ICIE	TCIE

Bit 0 (TCIE): TCIF interrupt enable bit

0: disable TCIF interrupt

1 : enable TCIF interrupt

The IOCF register is both readable and writable.

Bit 1 (ICIE): ICIF interrupt enable bit

0 : disable ICIF interrupt

1 : enable ICIF interrupt

Bit 2 (EXIE): EXIF interrupt enable bit

0: disable EXIF interrupt

1 : enable EXIF interrupt

Bits 3~7: Not used

Individual interrupt is enabled by setting its associated control bit in the

IOCF to "1".

Global interrupt is enabled by the ENI instruction and is disabled by the DISI instruction. Refer to Figure 5-8.



5.3 TCC/WDT and Prescaler

There is an 8-bit counter available as prescaler for the TCC or WDT. The prescaler is available for the TCC only or WDT only, one at a time and the PAB bit of the CONT register is used to determine the prescaler assignment. The PSR0~PSR2 bits determine the ratio. The prescaler is cleared each time an instruction is written to TCC in TCC mode. The WDT and prescaler, when assigned to WDT mode, are cleared by the "WDTC" or "SLEP" instructions. If the prescaler is earlier assigned to TCC and later assigned to WDT, or vice versa, the contents of the prescaler counter would be cleared automatically. Figure 5-4 depicts the circuit diagram of TCC/WDT.

- R1 (TCC) is an 8-bit timer/counter. The clock source of TCC can be internal or external clock input (edge selectable from TCC pin). If the TCC signal source is from an internal clock, TCC will increase by 1 at every instruction cycle (without prescaler). Referring to Figure 5-4, CLK=Fosc/2 or CLK=Fosc/4, depends on the Code Option bit CLK. CLK=Fosc/2 is used if CLK bit is "0", and CLK=Fosc/4 is used if CLK bit is "1". If the TCC signal source is from an external clock input, TCC is incremented by 1 at every falling edge or rising edge of the TCC pin.
- The watchdog timer is a free running on-chip RC oscillator. The WDT will keep running even when the oscillator driver has been turned off (i.e. in sleep mode). During normal operation or sleep mode, a WDT time-out (if enabled) will cause the device to reset. The WDT can be enabled or disabled any time during normal mode by software programming. Refer to WDTE bit of the IOCE register. Without prescaler, the WDT time-out period is approximately 18 ms (default).

5.4 I/O Ports

The I/O registers, Port 6, are bidirectional tri-state I/O ports. Port 6 can be pulled-high internally by software except P63. In addition, Port 6 can also have open-drain output by software except P63. Input status changed interrupt (or wake-up) function is available from Port 6. P60 ~ P62 pins can be pulled-down by software. Each I/O pin can be defined as "input" or "output" pin by the I/O control register (IOC6) except P63. The I/O registers and I/O control registers are both readable and writable. The I/O interface circuits for Port 6 are shown in Figures 5-5, 5-6 and 5-7 respectively.

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Note: Vdd = 5V, set up time period = 16.5ms ± 30% Vdd = 3V, set up time period = 18ms ± 30%



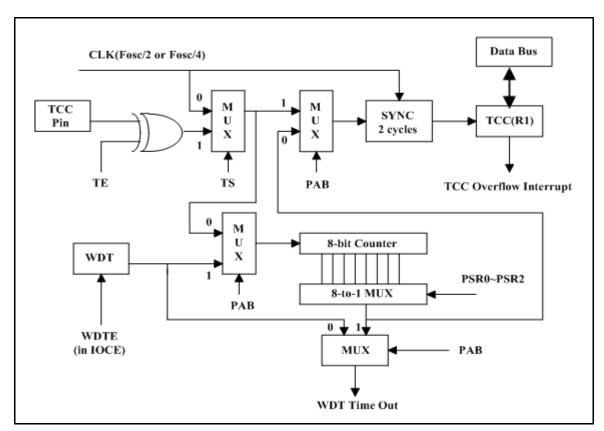
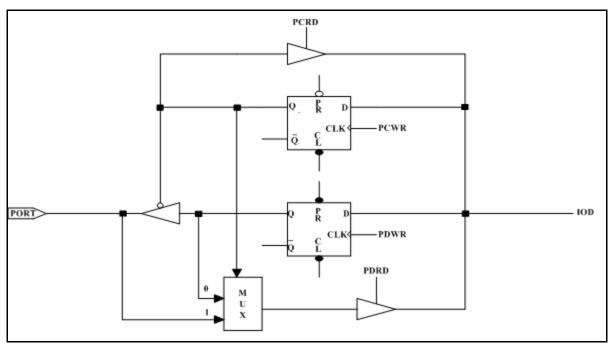


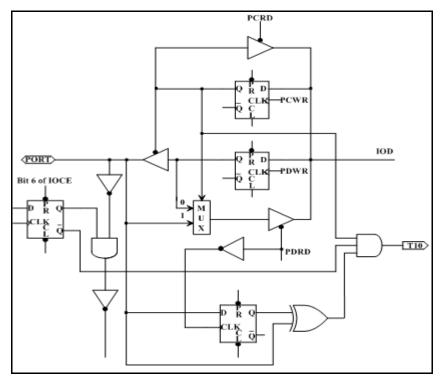
Figure 5-4 TCC and WDT Block Diagram



Note: Pull-down is not shown in the figure.

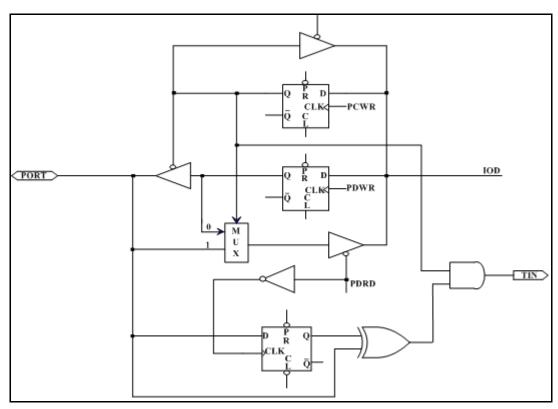
Figure 5-5 I/O Port and I/O Control Register Circuit for Port 5





Note: Pull-high (down) and open-drain are not shown in the figure.

Figure 5-6 I/O Port and I/O Control Register Circuit for P60 (/INT)



Note: Pull-high (down) and open-drain are not shown in the figure.

Figure 5-7 I/O Port and I/O Control Register Circuit for P61~P67



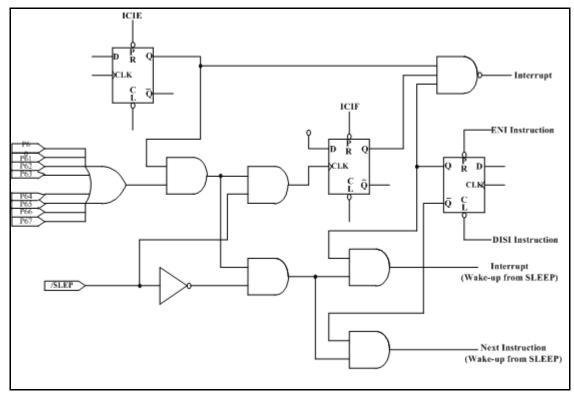


Fig. 5-8 Block Diagram of I/O Port 6 with input change interrupt/wake-up

Table 1 Usage of Port 6 Input Change Wake-up/Interrupt Function

rabio i Goago di Forto input Ghango Wake aprinteri apri Fanotion							
Usage of Port 6 Input Status Change Wake-up/Interrupt							
(I) Wake-up from Port 6 Input Status Change	(II) Port 6 Input Status Change Interrupt						
(a) Before Sleep	1. Read I/O Port 6 (MOV R6,R6)						
1. Disable WDT	2. Execute "ENI"						
2. Read I/O Port 6 (MOV R6,R6)	3. Enable interrupt (Set IOCF.1)						
3. Execute "ENI" or "DISI"	4. IF Port 6 change (interrupt)						
4. Enable interrupt (Set IOCF.1)	→ Interrupt vector (008H)						
5. Execute "SLEP" instruction							
(b) After Wake-up							
1. IF "ENI" \rightarrow Interrupt vector (008H)							
2. IF "DISI" \rightarrow Next instruction							



5.5 Reset and Wake-up

5.5.1 Reset

A Reset is initiated by one of the following events:

- 1) Power-on reset
- 2) /RESET pin input "low"
- 3) WDT time-out (if enabled)

The device is kept under reset condition for a period of approximately 18ms² (one oscillator start-up timer period) after a reset is detected. Once a Reset occurs, the following functions are performed:

- The oscillator is running, or will be started.
- The Program Counter (R2) is set to all "0."
- All I/O port pins are configured as input mode (high-impedance state)
- The Watchdog timer and prescaler are cleared.
- When power is switched on, the upper 3 bits of R3 are cleared.
- The bits of the CONT register are set to all "1" except for Bit 6 (INT flag).
- The bits of the IOCB register are set to all "1."
- The IOCC register is cleared.
- The bits of the IOCD register are set to all "1."
- Bit 7 of the IOCE register is set to "1," and Bits 4 and 6 are cleared.
- Bits 0 ~ 2 of RF and Bits 0 ~ 2 of IOCF registers are cleared.

Sleep (power down) mode is asserted by executing the "SLEP" instruction. While entering Sleep mode, WDT (if enabled) is cleared but keeps on running. The controller can be awakened by:

- 1) External reset input on /RESET pin,
- 2) WDT time-out (if enabled)
- 3) Port 6 input status change (if enabled)

The first two cases will cause the EM78P131A to reset. The T and P flags of R3 are used to determine the source of the reset (wake-up). The last case is considered the continuation of program execution and the global interrupt ("ENI" or "DISI" being executed) determines whether or not the controller branches to the interrupt vector

_

 $^{^2}$ Vdd = 5V, set up time period = 16.8ms \pm 30% Vdd = 3V, set up time period = 18ms \pm 30%



following a wake-up. If ENI is executed before SLEP, the instruction will begin to execute from Address 008H after a wake-up. If DISI is executed before SLEP, the operation will restart from the succeeding instruction right next to SLEP after a wake-up.

Only one of Cases 2 and 3 can be enabled before going into Sleep mode. That is,

- [a] if Port 6 Input Status Change Interrupt is enabled before SLEP, WDT must be disabled by software. However, the WDT bit in the option register remains enabled. Hence, the EM78P131A can be awakened only by Case 1 or Case 3.
- **[b]** if WDT is enabled before SLEP, Port 6 Input Status Change Interrupt must be disabled. Hence, the EM78P131A can be awakened only by Case 1 or Case 2. Refer to Section 5.6, *Interrupt* for further details.

If Port 6 Input Status Change Interrupt is used to wake-up the EM78P131A (Case [a] above), the following instructions must be executed before SLEP:

```
MOV A, @xxxx1110b
                      ; Select the WDT prescaler, it must be
                      ; set over 1:1
CONTW
WDTC
                      ; Clear WDT and prescaler
MOV A, @0xxxxxxxb
                      ; Disable WDT
IOW RE
MOV R6, R6
                      ; Read Port 6
MOV A, @00000x1xb
                      ; Enable Port 6 input change interrupt
IOW RF
ENI (or DISI)
                     ; Enable (or disable) global interrupt
SLEP
                      ; Sleep
```

NOTE

- 1. After waking up from sleep mode, WDT is automatically enabled. The WDT enable/disable operation after waking up from sleep mode should be appropriately defined in the software.
- 2. To avoid a reset from occurring when the Port 6 Input Status Changed Interrupt enters into an interrupt vector or is used to wake-up the MCU, the WDT prescaler must be set above 1:1 ratio.



5.5.2 Summary of Registers Initialized Values

Address	Name	Reset Type	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Bit Name	×	×	×	×	×	×	×	×
NI/A	1005	Power-on	0	0	0	0	1	1	1	1
N/A	IOC5	/RESET and WDT	0	0	0	0	1	1	1	1
		Wake-up from Pin Change	0	0	0	0	Р	Р	Р	Р
		Bit Name	C67	C66	C65	C64	C63	C62	C61	C60
N/A	IOC6	Power-on	1	1	1	1	1	1	1	1
IN/A	1006	/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р
		Bit Name	×	×	×	×	×	×	×	×
005	P5	Power-on	1	1	1	1	1	1	1	1
0×05	F5	/RESET and WDT	Р	Р	Р	Р	Р	Р	Р	Р
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р
		Bit Name	P67	P66	P65	P64	P63	P62	P61	P60
000	P6	Power-on	1	1	1	1	1	1	1	1
0×06	P0	/RESET and WDT	Р	Р	Р	Р	Р	Р	Р	Р
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р
		Bit Name	×	/INT	TS	TE	PAB	PSR2	PSR1	PSR0
N/A	CONT	Power-on	1	0	1	1	1	1	1	1
IN/A	CONT	/RESET and WDT	1	0	1	1	1	1	1	1
		Wake-up from Pin Change	Р	0	Р	Р	Р	Р	Р	Р
		Bit Name	•	•	-	•	•	-	ı	ı
0,,00	R0 (IAR)	Power-on	J	J	U	J	U	U	J	J
0×00	NO (IAN)	/RESET and WDT	Р	Р	Р	Р	Р	Р	Р	Р
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р
		Bit Name	-	-	-	-	-	-	-	-
0×01	R1 (TCC)	Power-on	0	0	0	0	0	0	0	0
UXUI	IX1 (100)	/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р
		Bit Name	-	-	-	-	-	-	-	-
0×02	R2 (PC)	Power-on	0	0	0	0	0	0	0	0
UXU2	112 (1 0)	/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-up from Pin Change	Р	Р	Р	Р	N	Р	Р	Р
		Bit Name	RST	GP1	GP0	Т	Р	Z	DC	С
0×03	R3 (SR)	Power-on	0	0	0	1	1	U	U	U
0.03	133 (313)	/RESET and WDT	0	0	0	*	*	Р	Р	Р
		Wake-up from Pin Change	1	Р	Р	*	*	Р	Р	Р
		Bit Name	GP1	GP0	-	-	-	-	-	-
0×04	R4 (RSR)	Power-on	U	U	U	U	U	U	U	U
UXU4	114 (11311)	/RESET and WDT	Р	Р	Р	Р	Р	Р	Р	Р
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р



Address	Name	Reset Type	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
		Bit Name	×	×	×	×	×	EXIF	ICIF	TCIF
005	DE(ICD)	Power-on	0	0	0	0	0	0	0	0
0×0F	RF(ISR)	/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-up from Pin Change	0	0	0	0	0	Р	N	Р
		Bit Name	×	/PD6	/PD5	/PD4	×	×	×	×
0×0B	IOCB	Power-on	1	1	1	1	1	1	1	1
UXUB	ЮСВ	/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р
		Bit Name	OD7	OD6	OD5	OD4	×	OD2	OD1	OD0
0×0C	IOCC	Power-on	0	0	0	0	0	0	0	0
UXUC		/RESET and WDT	0	0	0	0	0	0	0	0
		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р
	IOCD	Bit Name	/PH7	/PH6	/PH5	/PH4	×	/PH2	/PH1	/PH0
0×0D		Power-on	1	1	1	1	1	1	1	1
UXUD		/RESET and WDT	1	1	1	1	1	1	1	1
		Wake-up from Pin Change	Р	Ρ	Р	Р	Р	Р	Р	Р
		Bit Name	WDTE	EIS	×	×	×	LVDF	LVD SEL	LVD EN
0×0E	IOCE	Power-on	1	0	1	1	1	0	0	0
		/RESET and WDT	1	0	1	1	1	0	0	0
		Wake-up from Pin Change	1	Ρ	1	1	1	Р	Р	Р
		Bit Name	×	×	×	×	×	EXIE	ICIE	TCIE
0×0F	IOCF	Power-on	1	1	1	1	1	0	0	0
UXUF	1001	/RESET and WDT	1	1	1	1	1	0	0	0
		Wake-up from Pin Change	1	1	1	1	1	Р	Р	Р
		Bit Name	-	•	-	•		-	-	-
0×10	R10~R2F	Power-on	U	U	U	U	U	U	U	U
0×2F	N IU~NZF	/RESET and WDT	Р	Р	Р	Р	Р	Р	Р	Р
0//21		Wake-up from Pin Change	Р	Р	Р	Р	Р	Р	Р	Р

Legend: X: Not used U: Unknown or don't care P: Previous value before reset

^{*}Refer to tables provided in the next section (Section 5.5.3), particularly Table 4.



5.5.3 Status of RST, T, and P of the Status Register

A Reset condition is initiated by the following events

- 1) A power-on condition
- 2) A high-low-high pulse on /RESET pin
- 3) Watchdog timer time-out

The values of T and P listed in the table below are used to check how the processor wakes up.

Table 2 Values of RST, T, and P after a Reset

Reset Type	RST	Т	Р
Power on	0	1	1
/RESET during Operating mode	0	*P	*P
/RESET wake-up during Sleep mode	0	1	0
WDT during Operating mode	0	0	*P
WDT wake-up during Sleep mode	0	0	0
Wake-up on pin change during Sleep mode	1	1	0

^{*} P: Previous status before reset

The following table shows the events that may affect the status of T and P.

Table 3 Status of T and P Being Affected by Events

Event	RST	Т	Р
Power on	0	1	1
WDTC instruction	*P	1	1
WDT time-out	0	0	*P
SLEP instruction	*P	1	0
Wake-up on pin change during Sleep mode	1	1	0

* P: Previous status before reset

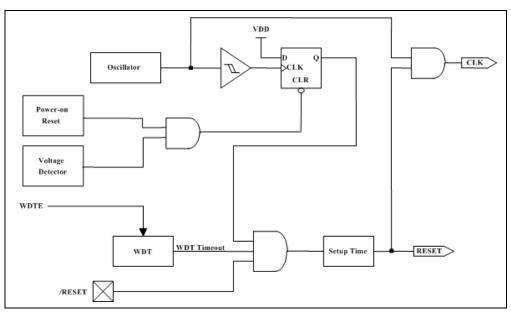


Figure 5-9 Controller Reset Block Diagram



5.6 Interrupt

The EM78P131A has three falling-edge interrupts as listed herewith:

- 1) TCC overflow interrupt
- 2) Port 6 Input Status Change Interrupt
- 3) External interrupt [(P60, /INT) pin]

Before the Port 6 Input Status Changed Interrupt is enabled, reading Port 6 (e.g. "MOV R6,R6") is necessary. Each pin of Port 6 will have this feature if its status changes. Any pin configured as output or P60 pin configured as /INT, is excluded from this function. The Port 6 Input Status Changed Interrupt can wake up the EM78P131A from Sleep mode if Port 6 is enabled prior to going into Sleep mode by executing SLEP instruction. When the chip wakes-up, the controller will continue to execute the program in-line if the global interrupt is disabled. If the global interrupt is enabled, it will branch to the interrupt Vector 008H.

RF is the interrupt status register that records the interrupt requests in the relative flags/bits. IOCF is an interrupt mask register. The global interrupt is enabled by the ENI instruction and is disabled by the DISI instruction. When one of the interrupts (enabled) occurs, the next instruction will be fetched from Address 008H. Once in the interrupt service routine, the source of an interrupt can be determined by polling the flag bits in RF. The interrupt flag bit must be cleared by instructions before leaving the interrupt service routine before interrupts are enabled to avoid recursive interrupts.

The flag (except ICIF bit) in the Interrupt Status Register (RF) is set regardless of the status of its mask bit or the execution of ENI. Note that the outcome of RF will be the logic AND of RF and IOCF (refer to Fig. 5-10). The RETI instruction ends the interrupt routine and enables the global interrupt (the execution of ENI).

When an interrupt is generated by the INT instruction (enabled), the next instruction will be fetched from Address 001H.

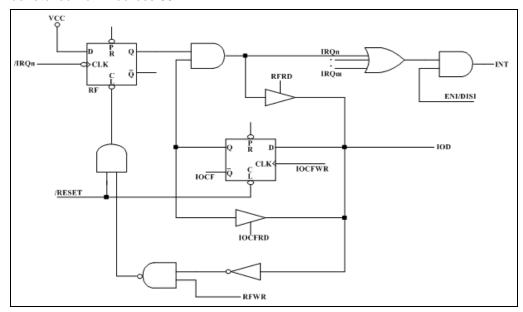


Figure 5-10 Interrupt Input Circuit



5.7 Oscillator

5.7.1 Oscillator Modes

The EM78P131A can be operated in four different oscillator modes, such as External RC oscillator mode (ERC), Internal RC oscillator mode (IRC), High Crystal oscillator mode (HXT), and Low Crystal oscillator mode (LXT). The desired mode can be selected by programming OSC1 and OSC2 in the Code Option register. The Table below describes how these four oscillator modes are defined.

Table 4 Oscillator Modes Defined by OSC

Mode	OSC1	OSC2
IRC (Internal RC oscillator mode)	1	1
ERC (External RC oscillator mode)	1	0
HXT (High Crystal oscillator mode)	0	1
LXT (Low Crystal oscillator mode)	0	0

Note: The transient point of system frequency between HXT and LXY is 400kHz.

The maximum operational frequency of the crystal/resonator under different VDDs is as listed below.

Table 5 Summary of Maximum Operating Speeds

Conditions	VDD	Max Freq. (MHz)
	2.3	4.0
Two cycles with two clocks	3.0	8.0
	5.0	20.0

5.7.2 Crystal Oscillator/Ceramic Resonators (Crystal)

The EM78P131A can be driven by an external clock signal through the OSCI pin as shown in the following figure.

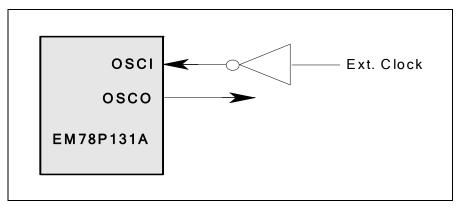


Fig. 5-11 Circuit for External Clock Input



In most applications, pin OSCI and pin OSCO can be connected with a crystal or ceramic resonator to generate oscillation. Fig. 5-12 depicts such circuit. The same thing applies whether it is in the HXT mode or in the LXT mode.

In Fig. 5-12-1, when the connected resonator in OSCI and OSCO is used in applications, R1 that is 1 $M\Omega$ needs to be shunted with resonator.

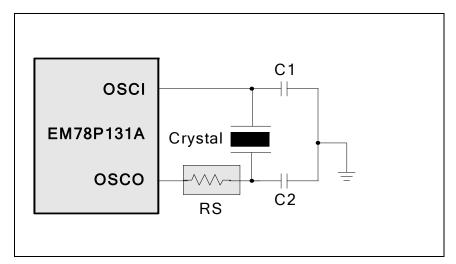


Fig. 5-12 Circuit for Crystal/Resonator

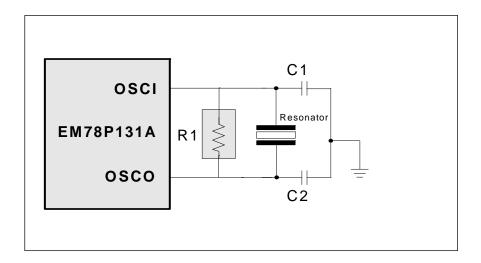


Fig. 5-12-1 Circuit for Crystal/Resonator



The following table provides the recommended values of C1 and C2. Since each resonator has its own attribute, refer to its specification for appropriate values of C1 and C2. RS, a serial resistor, may be necessary for AT strip cut crystal or low frequency mode.

Table 6 Capacitor Selection Guide for Crystal Oscillator or Ceramic Resonator

Oscillator Type	Frequency Mode	Frequency	C1 (pF)	C2 (pF)
		455kHz	100~150	100~150
Ceramic Resonators	HXT	2.0 MHz	20~40	20~40
		4.0 MHz	10~30	10~30
		32.768kHz	25	15
	LXT	100kHz	25	25
		200kHz	25	25
Crystal Oscillator		455kHz	20~40	20~150
	LIVT	1.0 MHz	15~30	15~30
	HXT	2.0 MHz	15	15
		4.0 MHz	15	15

Note: The values of Capacitors C1 and C2 are for reference only

5.7.3 External RC Oscillator Mode

For some applications that do not require a very precise timing calculation, the RC oscillator (Fig 5-13) offers a cost-effective oscillator configuration. Nevertheless, it should be noted that the frequency of the RC oscillator is influenced by the supply voltage, the values of the resistor (Rext), the capacitor (Cext), and even by the operation temperature. Moreover, the frequency also changes slightly from one chip to another due to manufacturing process variations.

In order to maintain a stable system frequency, the values of the Cext should not be less than 20pF, and the value of Rext should not be greater than 1 M Ω . If they cannot be kept in this range, the frequency can be easily affected by noise, humidity, and leakage.

The smaller the Rext in the RC oscillator is, the faster its frequency will be. On the contrary, for very low Rext values, for instance, 1 $K\Omega$, the oscillator becomes unstable because the NMOS cannot discharge the current of the capacitance correctly.

Based on the above reasons, it must be kept in mind that all of the supply voltage, the operation temperature, the components of the RC oscillator, the package types, the way the PCB is layout, will affect the system frequency.



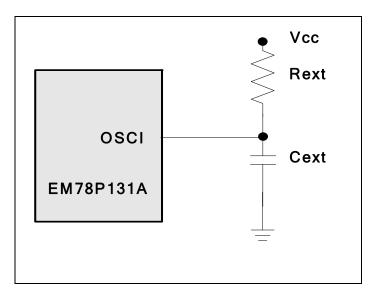


Figure 5-13 External RC Oscillator Mode Circuit

Table 7 RC Oscillator Frequencies

Cext	Rext	Average Fosc 5V, 25°C	Average Fosc 3V, 25°C
	3.3k	3.92 MHz	3.65 MHz
20pF	5.1k	2.67 MHz	2.60 MHz
20ρΓ	10k	1.4 MHz	1.40 MHz
	100k	150kHz	156 kHz
	3.3k	1.4 MHz	1.33 MHz
100pF	5.1k	940kHz	917kHz
ΤοορΓ	10k	476kHz	480kHz
	100k	50kHz	52kHz
	3.3k	595kHz	570kHz
300pF	5.1k	400kHz	384kHz
300pr	10k	200kHz	203kHz
	100k	20.9kHz	20kHz

Note: 1: Measured based on DIP packages.

5.7.4 Internal RC Oscillator Mode

EM78P131A offers a versatile internal RC mode with default frequency value of 4MHz. The Internal RC oscillator mode has other frequencies (1MHz, 8MHz, and 455kHz) that can be set by Code Option (Word 1), RCM1, and RCM0. All these four main frequencies can be calibrated by programming the Option Bits CAL0 ~ CAL2. The table below describes the EM78P131A internal RC drift with variation of voltage, temperature, and process.

^{2:} The values are for design reference only.

³: The frequency drift is \pm 30%.



Table 8 Internal RC Drift Rate (Ta=25°C, VDD=5V ± 5%, VSS=0V)

	Drift Rate						
Internal RC	Temperature (0°C~70°C)	Voltage (2.3V~5.5V)	Process	Total			
8 MHz	± 3%	± 5%	± 10%	± 18%			
4 MHz	± 3%	± 5%	± 5%	± 13%			
1 MHz	± 3%	± 5%	± 10%	± 18%			
455kHz	± 3%	± 5%	± 10%	± 18%			

Note: These are theoretical values provided for reference only. Actual values may vary depending on the actual process.

5.8 Code Option Register

The EM78P131A has a Code Option word that is not a part of the normal program memory. The option bits cannot be accessed during normal program execution.

Code Option Register and Customer ID Register Arrangement Distribution:

Word 0	Word 1	Word 2
Bit 12 ~ Bit 0	Bit 12 ~ Bit 0	Bit 12 ~ Bit 0

5.8.1 Code Option Register (Word 0)

Word 0												
Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
/RESET	/ENWDT	CLKS	OSC1	OCS0	CS	SUT1	SUT0	TYPE	RCOUT	C2	C1	C0

Bit 12 (/RESET): Define Pin 6.3 as a reset pin

0:/RESET enable

1:/RESET disable

Bit 11 (/ENWTD): Watchdog timer enable bit

0: Enable

1: Disable

Note

This bit must be enabled and the WDTE register (IOCE reg. Bit 6) must be disabled when Port 6 pin change wake-up function is used.

Bit 10 (CLKS): Instruction period option bit

0: Two oscillator periods

1: Four oscillator periods

Refer to the Instruction Set section.



Bit 9 and Bit 8 (OSC1 and OSC0): Oscillator Modes Selection bits.

Table 9 Oscillator Modes defined by OSC1 and OSC0

Mode	OSC1	OSC0
IRC (Internal RC oscillator mode)	1	1
ERC (External RC oscillator mode)	1	0
HXT (High Crystal oscillator mode)	0	1
LXT (Low Crystal oscillator mode)	0	0

Note: The transient point of system frequency between HXT and LXY is 400kHz.

Bit 7 (CS): Code Security Bit

0 : Security On1 : Security Off

Bit 6 and Bit 5 (SUT1 and SUT0): Set-up Time of device bits.

Table 10 Set-up Time of Device Programming

SUT1	SUT0	*Set-up Time
1	1	18 ms
1	0	4.5 ms
0	1	288 ms
0	0	72 ms

^{*} Theoretical values, for reference only

Bit 4 (Type): Type selection for EM78P131A

TYPE	Series
0	EM78P131A
1	×

Bit 3 (RCOUT): Selection bit of Oscillator output or I/O port

RCOUT	Pin Function
0	P64
1	OSCO

Bits 2~ 0 (C2~C 0): Calibrator of internal RC mode Bit 3 C2, C1, C0 must be set to "1" only.

■ Code Option Register (Word 1)

Word 1				
Bit 2	Bit 1	Bit 0		
HLP	RCM1	RCM0		

Bit 2 (HLP): Power Consumption Selection Bit

0 : Low power consumption1 : High power consumption



RCM 1	RCM 0	*Frequency (MHz)
1	1	4
1	0	8
_	_	

Bit 1 and Bit 0 (RCM1, RCM0): RC mode select bits

■ Customer ID Register (Word 2)

Bit 12~Bit 0
XXXXXXXXXXX

Bits 12~ 0: Customer's ID code

5.9 Power-on Considerations

Any microcontroller is not guaranteed to start to operate properly before the power supply stabilizes at its steady state. Under customer application, when power is OFF, Vdd must drop to below 1.8V and remains OFF for 10µs before power can be switched ON again. This way, the EM78P131A will reset and operate normally. The extra external reset circuit will work well if Vdd can rise at a very fast speed (50 ms or less). However, under most cases where critical applications are involved, extra devices are required to assist in solving the power-up problems.

455kHz

5.10 Programmable Oscillator Set-up Time

The Option word contains SUT0 and SUT1 which can be used to define the oscillator set-up time. Theoretically, the range is from 4.5 ms to 72 ms. For most of crystal or ceramic resonators, the lower the operation frequency is, the longer the Set-up time may be required. Table 12 describes the values of the Oscillator Set-up Time.

5.11 External Power-on Reset Circuit

The circuit shown in Figure 5-14 implements an external RC to produce the reset pulse. The pulse width (time constant) should be kept long enough for Vdd to reach minimum operation voltage. This circuit is used when the power supply has a slow rise time.

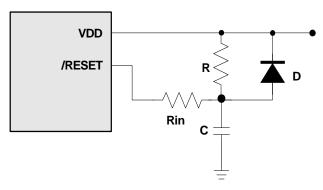


Fig 5-14 External Power-up Reset Circuit

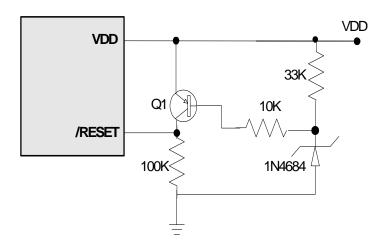
Since the current leakage from the /RESET pin is \pm 5 μ A, it is recommended that R should not be greater than 40K. In this way, the /RESET pin voltage is held below 0.2V. The diode (D) acts as a short circuit at the moment of power down.



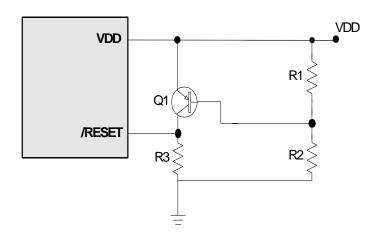
The capacitor C will discharge rapidly and fully. Rin, the current-limited resistor, will prevent high current or ESD (electrostatic discharge) from flowing to pin /RESET.

5.12 Residue-Voltage Protection

When the battery is replaced, the device power (Vdd) is cut off but residue-voltage remains. The residue-voltage may trip below the minimum Vdd, but not to zero. This condition may cause a poor power-on reset. The following figures illustrate two recommended methods on how to build a residue-voltage protection circuit for EM78P131A.



* Figure 5-15 Residue Voltage Protection Circuit 1



* Figure 5-16 Residue Voltage Protection Circuit 2

Note: * Figure 5-15 and Figure 5-16 should be designed with their /RESET pin voltage larger than VIH(min).



5.13 Instruction Set

Each instruction in the instruction set is a 13-bit word divided into an OP code and one or more operands. Normally, all instructions are executed within one single instruction cycle (one instruction consists of two oscillator periods), unless the program counter is changed by instruction "MOV R2,A", "ADD R2,A", or by instructions of arithmetic or logic operation on R2 (e.g., "SUB R2,A", "BS(C) R2,6", "CLR R2", etc.). In this case, the execution takes two instruction cycles.

If for some reasons, the specification of the instruction cycle is not suitable for certain applications, try modifying the instruction as follows:

- A) Modify one instruction cycle to consist of four oscillator periods.
- **B)** "JMP," "CALL," "RET," "RETL," "RETI," or the conditional skip ("JBS," "JBC," "JZ," "JZA," "DJZ," "DJZA") commands which were tested to be true, are executed within two instruction cycles. The instructions that are written to the program counter also take two instruction cycles.

Case (A) is selected by the Code Option bit, called CLK. One instruction cycle consists of two oscillator clocks if CLK is low; and four oscillator clocks if CLK is high.

Note that once the four oscillator periods within one instruction cycle is selected as in Case (A), the internal clock source to TCC should be CLK=Fosc/4, instead of Fosc/2.

Moreover, the instruction set has the following features:

- 1) Every bit of any register can be set, cleared, or tested directly.
- 2) The I/O register can be regarded as general register. That is, the same instruction can operate on I/O register.

The following symbols are used in the Instruction Set table:

Convention:

- **R** = Register designator that specifies which one of the registers (including operation and general purpose registers) is to be utilized by the instruction.
 - Bits 6 and 7 in R4 determine the selected register bank.
- **b** = Bit field designator that selects the value for the bit located in the register R and which affects the operation.
- **k** = 8 or 10-bit constant or literal value

Binary Instruction	Hex	Mnemonic	Operation	Status Affected
0 0000 0000 0000	0000	NOP	No Operation	None
0 0000 0000 0001	0001	DAA	Decimal Adjust A	С
0 0000 0000 0010	0002	CONTW	$A \to CONT$	None
0 0000 0000 0011	0003	SLEP	$0 \rightarrow WDT$, Stop oscillator	T, P
0 0000 0000 0100	0004	WDTC	$0 \rightarrow WDT$	T, P
0 0000 0000 rrrr	000r	IOW R	$A \rightarrow IOCR$	None ¹



Binary Instruction	Hex	Mnemonic	Operation	Status Affected
0 0000 0001 0000	0010	ENI	Enable Interrupt	None
0 0000 0001 0001	0011	DISI	Disable Interrupt	None
0 0000 0001 0010	0012	RET	[Top of Stack] → PC	None
0 0000 0001 0011	0013	RETI	[Top of Stack] → PC, Enable Interrupt	None
0 0000 0001 0100	0014	CONTR	$CONT \rightarrow A$	None
0 0000 0001 rrrr	001r	IOR R	$IOCR \rightarrow A$	None ¹
0 0000 01rr rrrr	00rr	MOV R,A	$A \rightarrow R$	None
0 0000 1000 0000	0800	CLRA	$0 \rightarrow A$	Z
0 0000 11rr rrrr	00rr	CLR R	$0 \rightarrow R$	Z
0 0001 00rr rrrr	01rr	SUB A,R	$R-A \rightarrow A$	Z, C, DC
0 0001 01rr rrrr	01rr	SUB R,A	$R-A \rightarrow R$	Z, C, DC
0 0001 10rr rrrr	01rr	DECA R	R-1 → A	Z
0 0001 11rr rrrr	01rr	DEC R	$R-1 \rightarrow R$	Z
0 0010 00rr rrrr	02rr	OR A,R	$A \lor R \to A$	Z
0 0010 01rr rrrr	02rr	OR R,A	$A \lor R \to R$	Z
0 0010 10rr rrrr	02rr	AND A,R	$A \& R \rightarrow A$	Z
0 0010 11rr rrrr	02rr	AND R,A	$A \& R \rightarrow R$	Z
0 0011 00rr rrrr	03rr	XOR A,R	$A \oplus R \to A$	Z
0 0011 01rr rrrr	03rr	XOR R,A	$A \oplus R \to R$	Z
0 0011 10rr rrrr	03rr	ADD A,R	$A + R \rightarrow A$	Z, C, DC
0 0011 11rr rrrr	03rr	ADD R,A	$A + R \rightarrow R$	Z, C, DC
0 0100 00rr rrrr	04rr	MOV A,R	$R \rightarrow A$	Z
0 0100 01rr rrrr	04rr	MOV R,R	$R \rightarrow R$	Z
0 0100 10rr rrrr	04rr	COMA R	$/R \rightarrow A$	Z
0 0100 11rr rrrr	04rr	COM R	$/R \rightarrow R$	Z
0 0101 00rr rrrr	05rr	INCA R	$R+1 \rightarrow A$	Z
0 0101 01rr rrrr	05rr	INC R	$R+1 \rightarrow R$	Z
0 0101 10rr rrrr	05rr	DJZA R	$R-1 \rightarrow A$, skip if zero	None
0 0101 11rr rrrr	05rr	DJZ R	$R-1 \rightarrow R$, skip if zero	None
0 0110 00rr rrrr	06rr	RRCA R	$R(n) \rightarrow A(n-1),$ $R(0) \rightarrow C, C \rightarrow A(7)$	С
0 0110 01rr rrrr	06rr	RRC R	$R(n) \rightarrow R(n-1),$ $R(0) \rightarrow C, C \rightarrow R(7)$	С
0 0110 10rr rrrr	06rr	RLCA R	$R(n) \rightarrow A(n+1),$ $R(7) \rightarrow C, C \rightarrow A(0)$	С
0 0110 11rr rrrr	06rr	RLC R	$R(n) \rightarrow R(n+1),$ $R(7) \rightarrow C, C \rightarrow R(0)$	С
0 0111 00rr rrrr	07rr	SWAPA R	$R(0-3) \rightarrow A(4-7),$ $R(4-7) \rightarrow A(0-3)$	None
0 0111 01rr rrrr	07rr	SWAP R	$R(0-3) \leftrightarrow R(4-7)$	None



Binary Instruction	Hex	Mnemonic	Operation	Status Affected
0 0111 10rr rrrr	07rr	JZA R	R+1 \rightarrow A, skip if zero	None
0 0111 11rr rrrr	07rr	JZ R	$R+1 \rightarrow R$, skip if zero	None
0 100b bbrr rrrr	0xxx	BC R,b	$0 \rightarrow R(b)$	None ²
0 101b bbrr rrrr	0xxx	BS R,b	$1 \rightarrow R(b)$	None ³
0 110b bbrr rrrr	0xxx	JBC R,b	if R(b)=0, skip	None
0 111b bbrr rrrr	0xxx	JBS R,b	if R(b)=1, skip	None
1 00kk kkkk kkkk	1kkk	CALL k	$PC+1 \rightarrow [SP],$ $(Page, k) \rightarrow PC$	None
1 01kk kkkk kkkk	1kkk	JMP k	$(Page,k)\toPC$	None
1 1000 kkkk kkkk	18kk	MOV A,k	$k \rightarrow A$	None
1 1001 kkkk kkkk	19kk	OR A,k	$A \lor k \to A$	Z
1 1010 kkkk kkkk	1Akk	AND A,k	$A \& k \rightarrow A$	Z
1 1011 kkkk kkkk	1Bkk	XOR A,k	$A \oplus k \to A$	Z
1 1100 kkkk kkkk	1Ckk	RETL k	$k \rightarrow A$, [Top of Stack] $\rightarrow PC$	None
1 1101 kkkk kkkk	1Dkk	SUB A,k	$k\text{-}A \to A$	Z, C,DC
1 1110 0000 0001	1E01	INT	$PC+1 \rightarrow [SP],$ $001H \rightarrow PC$	None
1 1111 kkkk kkkk	1Fkk	ADD A,k	$k+A \rightarrow A$	Z, C, DC

Note: ¹ This instruction is applicable to IOC6, IOCB ~ IOCF only.

² This instruction is not recommended for RF operation.

³ This instruction cannot operate under RF.



6. Timing Diagrams

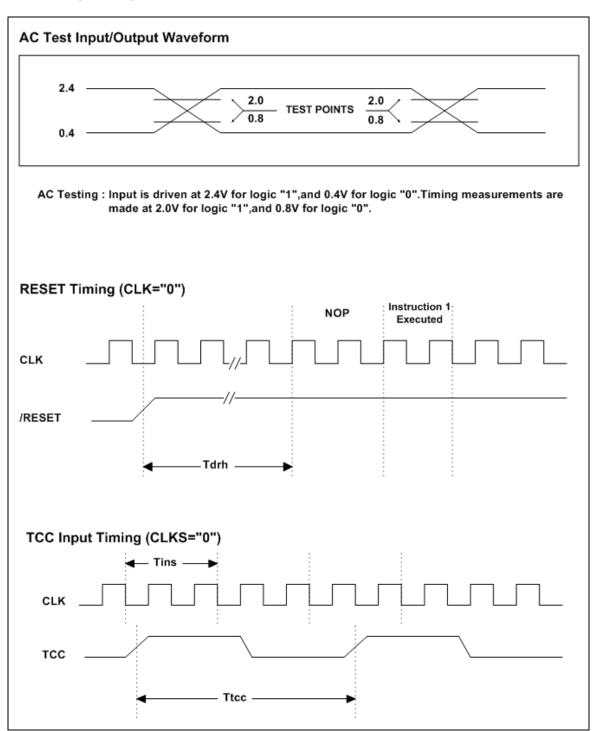


Figure 5-17 EM78P131A Timing Diagrams



7 Absolute Maximum Ratings

Items	Rating
Temperature under bias	0°C to 70°C
Storage temperature	-65°C to 150°C
Input voltage	-0.3V to +6.0V
Output voltage	-0.3V to +6.0V

Note: *These parameters are theoretical values and have not been tested.

8 Electrical Characteristics

8.1 DC Characteristics

Ta=25°C, VDD=5V \pm 5%, VSS=0V

Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
	Crystal: VDD to 2.3V Two cycles with two clo		DC	-	4.0	MHz
FXT	Crystal: VDD to 3V	Two cycles with two clocks	DC	-	8.0	MHz
	Crystal: VDD to 5V	Two cycles with two clocks	DC	-	20.0	MHz
ERC	ERC: VDD to 5V	R: 5.1KΩ, C: 300 pF	F±30%	595	F±30%	kHz
IIL	Input Leakage Current for input pins	VIN = VDD, VSS	-	-	±1	μΑ
VIH1	Input High Voltage (VDD=5V)	Ports 6	2.0	-	1	V
VIL1	Input Low Voltage (VDD=5V)	Ports 6	-	-	0.8	V
VIHT1	Input High Threshold Voltage (VDD=5V)	/RESET, TCC (Schmitt trigger)	2.0	ı	1	V
VILT1	Input Low Threshold Voltage (VDD=5V)	/RESET, TCC (Schmitt trigger)	-	-	0.8	V
VIHX1	Clock Input High Voltage (VDD=5V)	OSCI	2.5	-	ı	V
VILX1	Clock Input Low Voltage (VDD=5V)	OSCI	-	-	1.0	V
VIH2	Input High Voltage (VDD=3V)	Ports 6	1.5	-	-	V
VIL2	Input Low Voltage (VDD=3V)	Ports 6	-	-	0. 4	V
VIHT2	Input High Threshold Voltage (VDD=3V)	/RESET, TCC (Schmitt trigger)	1.5	-	-	V
VILT2	Input Low Threshold Voltage (VDD=3V)	/RESET, TCC (Schmitt trigger)	-	1	0.4	V
VIHX2	Clock Input High Voltage (VDD=3V)	OSCI	1.5	-	1	V
VILX2	Clock Input Low Voltage (VDD=3V)	OSCI	-	-	0.6	V
VOH1	Output High Voltage (Port 6) (P60~P63, P66~P67 are Schmitt trigger)	IOH = -12 mA	2.4	ı	ı	V
VOL1	Output Low Voltage (P60~P63 P66~P67 are Schmitt trigger)	IOL = 12 mA	-	ı	0.4	V
VOL2	Output Low Voltage (P64, P65)	IOL = 16.0 mA	-	-	0.4	V
IPH	Pull-high current	Pull-high active, Input pin at VSS	-50	-100	-240	μΑ
IPD	Pull-down current	Pull-down active, Input pin at VDD	20	50	120	μА



Symbol	Parameter	Condition	Min.	Тур.	Max.	Unit
ISB1	Power down current	All input and I/O pins at VDD, Output pin floating, WDT disabled	-	-	1	μА
ISB2	Power down current	All input and I/O pins at VDD, Output pin floating, WDT enabled	ı	-	10	μА
ICC1	Operating supply current at two clocks (VDD=3V)	/RESET= 'High', Fosc=32kHz (Crystal type, CLKS="0"), Output pin floating, WDT disabled	15	15	30	μА
ICC2	Operating supply current at two clocks (VDD=3V)	/RESET= 'High', Fosc=32kHz (Crystal type, CLKS="0"), Output pin floating, WDT enabled	-	19	35	μΑ
ICC3	Operating supply current at two clocks (VDD=5.0V)	/RESET= 'High', Fosc=4 MHz (Crystal type, CLKS="0"), Output pin floating	ı	-	2.0	mA
ICC4	Operating supply current at two clocks (VDD=5.0V)	/RESET= 'High', Fosc=10 MHz (Crystal type, CLKS="0"), Output pin floating	-	-	4.0	mA

Note: *These parameters are theoretical values and have not been tested.

8.2 AC Characteristics

Ta=25°C, VDD=5V \pm 5%, VSS=0V

Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit
Dclk	Input CLK duty cycle	-	45	50	55	%
Tins	Instruction cycle time	Crystal type	100	-	DC	ns
11115	(CLKS="0")	RC type	500	-	DC	ns
Ttcc	TCC input period	-	(Tins+20)/N*	ı	-	ns
Tdrh	Device reset hold time	Ta = 25°C, Crystal, SUT1, SUT0=1, 1	17.6-30%	17.6	17.6+30%	ms
Trst	/RESET pulse width	Ta = 25°C	2000	-	-	ns
*Twdt1	Watchdog timer period	Ta = 25°C SUT1, SUT0=1,1	17.6~30%	17.6	17.6+30%	ms
*Twdt2	Watchdog timer period	Ta = 25°C SUT1, SUT0=1,0	4.5+30%	4.5	4.5+30%	ms
*Twdt3	Watchdog timer period	Ta = 25°C SUT1, SUT0=0,1	288~30%	288	288+30%	ms
*Twdt4	Watchdog timer period	Ta = 25°C SUT1, SUT0=0,0	72~30%	72	72+30%	ms
Tset	Input pin setup time	-	-	0	-	ns
Thold	Input pin hold time	-	-	20	-	ns
Tdelay	Output pin delay time	Cload=20pF	-	50	-	ns

Note: These parameters are theoretical values and have not been tested.

The Watchdog Timer duration is determined by Option Code (Bit 6, Bit 5)

^{*}N = selected prescaler ratio

^{*}Twdt1: The Option word (SUT1, SUT0) is used to define the oscillator set-up time. In Crystal mode the WDT time-out length is the same as set-up time (18ms).

^{*}Twdt2: The Option word (SUT1, SUT0) is used to define the oscillator set-up time. In Crystal mode the WDT time-out length is the same as set-up time (4.5ms).

^{*}Twdt3: The Option word (SUT1, SUT0) is used to define the oscillator set-up time. In Crystal mode the WDT time-out length is the same as set-up time (288ms).

^{*}Twdt4: The Option word (SUT1, SUT0) is used to define the oscillator set-up time. In Crystal mode the WDT time-out length is the same as set-up time (72ms).



APPENDIX

A Package Type

OTP MCU	Package Type	Pin Count	Package Size
EM78P131AMS10J	MSOP	10	118 mil

Note: Green products do not contain hazardous substances.

This complies with the third edition of Sony SS-00259 standard.

Pb contents should be less than 100ppm

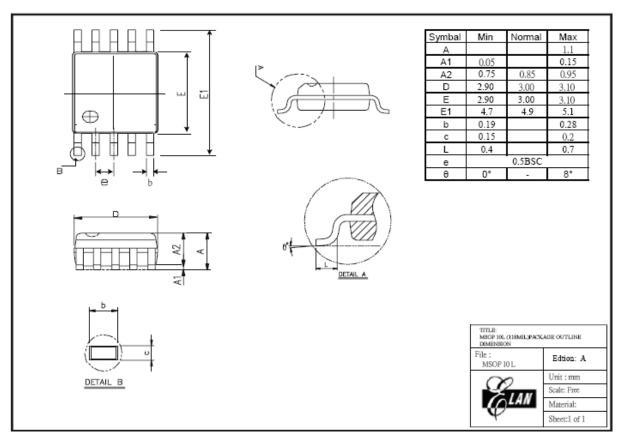
Pb contents comply with Sony spec.

Part No.	EM78P131AMS10J
Electroplate type	Pure Tin
Ingredient (%)	Sn: 100%
Melting point (°C)	232°C
Electrical resistivity (μΩ-cm)	11.4
Hardness (hv)	8~10
Elongation (%)	>50%



B Package Information

■ 10-Lead Plastic Dual in line (MSOP) — 118 mil



FigureB EM78P131A 10-Lead MSOP Package Type