

6.0V~28V. 1.2A 1ch

# 1ch Step-Down Switching Regulator

# BD9E151NUX

#### **General Description**

The BD9E151NUX is a 28V, 1.2A diode-rectification buck converter that integrated internal high-side 30V Power MOSFET. To increase efficiency at light loads, a pulse skipping is automatically activated. Furthermore, the 0uA shutdown supply current allows the device to be used in battery powered application. Current mode control with internal slope compensation simplifies the external component count while allowing the use of ceramic output capacitors.

#### **Features**

- High and Wide Input Range (VIN=6V~28V)
- 30V/80mΩ Internal Power MOSFET
- 600kHz Fixed Operating Frequency
- Feedback Pin Voltage 1.0V±1.0%
- Internal Over Current Protection(OCP), Under Voltage Locked Out(UVLO), Over Voltage Protection(OVP), Thermal Shut down(TSD)
- 0µA Low Shutdown Supply Current
- VSON008X2030 package

# **Key Specifications**

Input Voltage 6~28 [V] Ref. Precision (Ta=25°C) ±1.0[%] Max Output Current 1.2 [A] (Max.) Operating Temperature -40°C~85°C **Operating Junction Temperature** -55°C ~ 125°C

# **Packages**

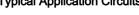
VSON008X2030 2.00mm x3.00mm x 0.60mm



VSON008X2030

# **Applications**

- Surveillance Camera Applications
- **OA Applications**
- 12V, 24V Distributed Power Systems



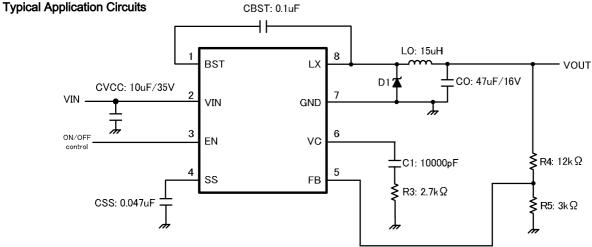


Figure 1. Typical Application Circuit

oStructure: Silicon Monolithic Integrated Circuit oThis product is not designed for normal operation within a radioactive

# **Pin Configuration**

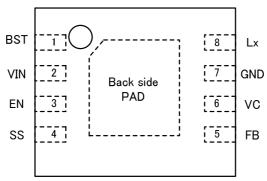
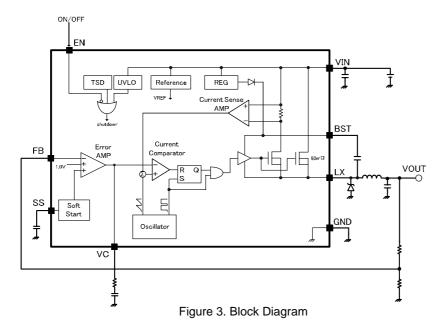


Figure 2. Pin Configuration (TOP VIEW)

# Pin Description

Pin No.	Pin Name	Description
1	BST	The pin is power supply for floating Power NMOS driver. Connect bypass capacitor between the pin and LX pin for bootstrap operation.
2	2 VIN Input supply. Place bypass capacitor as close as possible to this pin.	
3	Enable input pin. Apply more than 2.4V to start-up the DCDC. This pin is pulled dow $700k\Omega$ , apply less than 0.8V or open to shutdown the DCDC.	
4	SS	Soft start pin. An external capacitor connected to this pin sets output rise time.
5	FB	Inverting node of the gm amplifier.
6	VC	Error amplifier output, and input to the PWM comparator. Connect phase compensation components to this pin.
7	GND	Ground.
6	LX	Place schottky barrier diode as close as possible and inductor to this pin.
-	Back side PAD	PAD for radiation of heat. Connect to GND is recommended.

# **Block Diagram**



www.rohm.com © 2013 ROHM Co., Ltd. All rights reserved TSZ22111 • 15 • 001

# **Description of Blocks**

#### 1. Reference

This block generates reference voltage and current. It start operation by applying EN=H.

It provides reference voltage and current to error amplifier, oscillator, and etc.

#### 2. REG

This is a gate drive voltage generator and 5.5V regulator for internal circuit power supply.

#### 3. OSC

This is a precise wave oscillation circuit with operation frequency fixed to 600 kHz

#### 4. Soft Start

This block does Soft Start to the output voltage of DC/DC converter, and prevents in-rush current during Start-up. Soft Start Time set by the capacitor connected to SS pin and SS charge current is the time from EN Pin start-up to reaching to 1.0V.

#### 5. ERROR AMP

This is an error amplifier that detects output signal, and outputs PWM control signal. Internal reference voltage is set to 1.0V. Connect phase compensation components between this pin and ground (ref. p.11).

#### 6. OVP

The OVP circuit includes an overvoltage comparator to compare the FB pin voltage and internal thresholds. When the FB pin voltage goes above 110%×FB, the high-side MOSFET will be forced off. When the FB pin voltage falls below 105%, the high-side MOSFET will be enabled again.

#### 7. ICOMP

The BD9E151NUX implements current mode control that uses the VC pin voltage to turn off the high-side MOSFET on a cycle by cycle basis. Every cycle the switch current and the COMP pin voltage are compared; when the peak inductor current intersects the VC pin voltage, the high-side switch is turned off. During overcurrent conditions that pull the output voltage low, the error amplifier responds by driving the COMP pin high, causing the switch current to increase.

#### 8. OCF

This is a circuit to protect the high-side FET from overcurrent. Every cycle the switch current and the reference voltage of overcurrent protection are compared; when the peak inductor current intersects the reference voltage, the high-side switch is turned off. Once overcurrent is detected, the device will stop and VC pin voltage will be reset and SS pin voltage will be discharged by 2uA (hiccup operation). Then SS pin voltage reaches to less than 0.1V, IC will restart.

#### 9. High-side MOSFET

This is a  $30V/80m\Omega$  high-side MOSFET that converts inductor current of DC/DC converter.

Because the current limiting of this FET is 1.6A included ripple current, please use at within 1.6A.

#### 10. UVLO

This is a low voltage error prevention circuit.

This prevents internal circuit error during increase of power supply voltage and during decline of power supply voltage. It monitors VIN pin voltage and internal REG voltage, and when VIN voltage becomes 5.2V and below, it turns OFF all output FET and turns OFF DC/DC comparator output and Soft Start circuit resets.

Now this Threshold has hysteresis of 200mV.

# 11. TSD

This is a heat protect circuit.

When it detects an abnormal temperature exceeding maximum junction temperature (Tj=150°C), it turns OFF all Output FET, and turns OFF DC/DC converter output. When temperature falls, it automatically returns.

#### 12. EN

When a Voltage of 2.4V or more is applied, it turns ON, at Open or 0V application, it turns OFF.

About 700kΩ Pull-down Resistance is contained within the Pin.

# **Absolute Maximum Ratings**

Item	Symbol	Ratings	Unit
VIN to GND	VIN	30	V
BST to GND	VBST	37	V
BST to LX	⊿VBST	7	V
EN to GND	VEN	30	V
LX to GND	VLX	30	V
FB to GND	VFB	7	V
VC to GND	VSS	7	V
SS to GND	VSS	7	V
High-side FET Drain Current	IDH	1.6	Α
Power Dissipation	Pd	2(*1)	W
Operating Temperature	Topr	-40 ~ +85	°C
Storage Temperature	Tstg	-55 ~ +125	°C
Junction Temperature	Tjmax	150	°C

<sup>(\*1)</sup>During mounting of 70×70×1.6t mm 4layer board.Reduce by 20mW for every 1°C increase. (Above 25°C)

# **Operating Ratings**

Item	Cymbol		Unit			
item	Symbol	Min	Тур	Max	Offic	
Input Voltage	VIN	6	-	28	V	
Output Voltage	VOUT	1.0(*2)	-	VINx0.7 or VIN-5	V	
Output Current	IOUT	-	-	1.2	Α	

<sup>(\*2)</sup>Restricted by minimum on pulse typ. 100nsec

# Electrical Characteristics (Unless otherwise specified Ta=25°C, VIN=12V, VOUT=5V)

			Limits				0 1111
Parameter		Symbol	Min.	Тур.	Max	Unit	Conditions
[Circuit current]							
Stand-by current of VIN		Ist	-	0	10	uA	VEN=0
Circuit current of VIN		Icc	-	0.8	1.6	mA	FB=1.5V
【Under voltage Lock out (UVLO)	]	_	_		_		
Reset threshold voltage		Vuv	5.0	5.4	5.8	V	VIN rising
Hysteresis width		Vuvhy	-	200	400	mV	
[Oscillator]							
Oscillating frequency		fsw	540	600	660	kHz	
Max duty cycle		Dmax	85	91	-	%	
【Error amplifier】							
FB threshold voltage		VFB	0.990	1.000	1.010	V	
Input bias current		IFB	-1.0	0	1.0	uA	VFB=0V
Error amplifier DC gain		AVEA	-	600	6000	V/V	
Error amplifier transconductance		GEA	-	250	500	uA/V	IVC=±10uA,VC=1.0V
【Current sense amplifier】							
VC to switch current transconduct	ance	Gcs	-	10	20	A/V	
[Output]							
High-side MOSFET ON resistance	)	RonH	-	80	160	mΩ	
Over current detect current		Іоср	1.6	2.2	-	Α	
[CTL]							
EN nin control voltage		VEN	2.4	-	VIN	V	Ta=-40~85°C
EN pin control voltage	OFF	VENOFF	-0.3	-	0.8	V	VIN=6~28V
EN pin input current		REN	6.0	7.0	15.0	uA	VEN=5V
[SOFT START]							
Charge current		lss	1	2	4	uA	

Not designed to withstand radiation.

# Typical Performance Characteristics (Unless otherwise specified, Ta=25°C, VCC=12V, Vo=5V,)

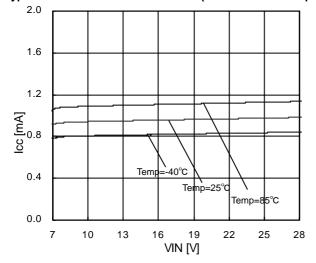


Figure 4. Operating Current - Input Voltage

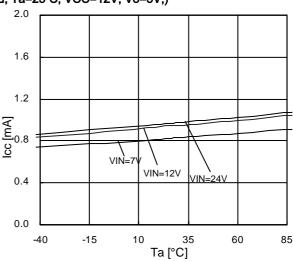


Figure 5. Operating Current - Temperature

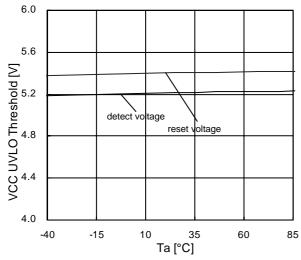


Figure 6. UVLO Threshold - Temperature

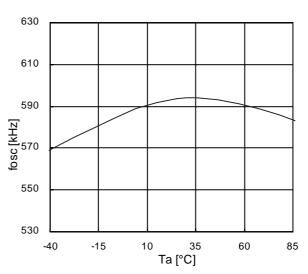


Figure 7. Switching Frequency - Temperature

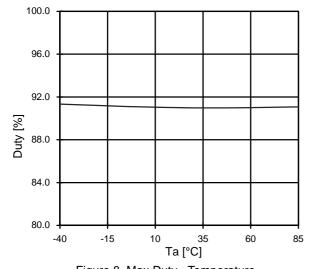


Figure 8. Max Duty - Temperature

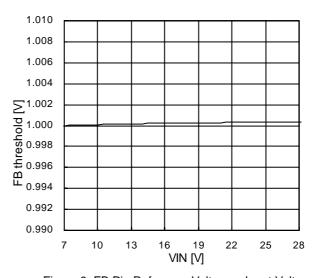


Figure 9. FB Pin Reference Voltage – Input Voltage

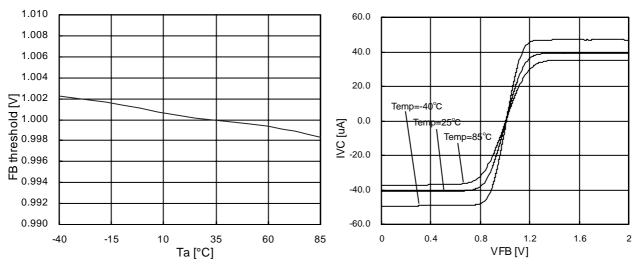


Figure 10. FB Pin Reference Voltage - Temperature

Figure 11. FB Pin Voltage – VC Pin Current

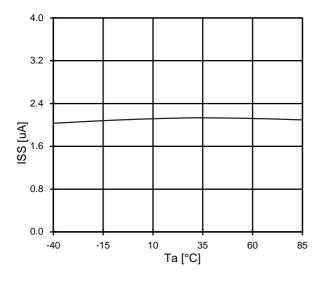


Figure 12. SS Pin Charge Current - Temperature

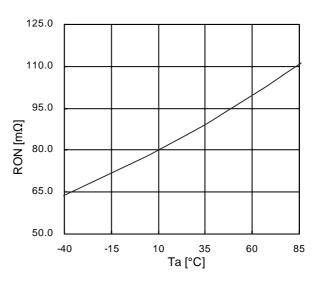


Figure 13. High-side FET Ron - Temperature

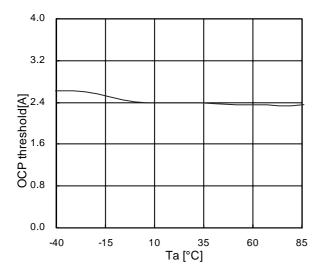


Figure 14. OCP Detect Current - Temperature

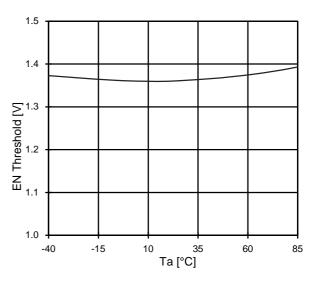
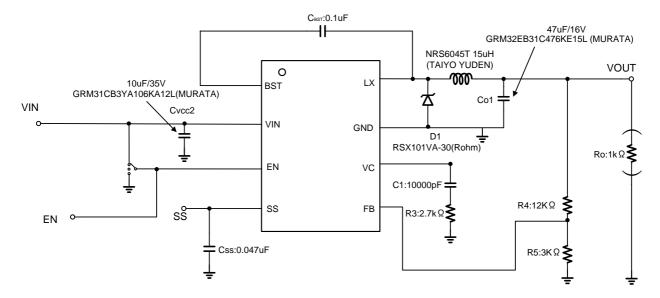


Figure 15. EN Threshold Voltage - Temperature

# Reference Characteristics of typical Application Circuits (VIN=12V, VOUT=5V IOUT=1A)



(Back side PAD is recommended connecting to GND)

Figure 16. Typical ApplicationCircuit (VOU=5V)

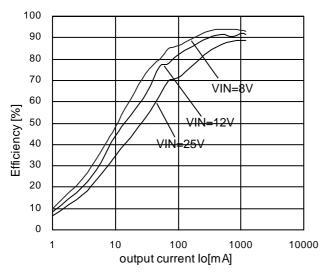


Figure 17. Efficiency - Output Current

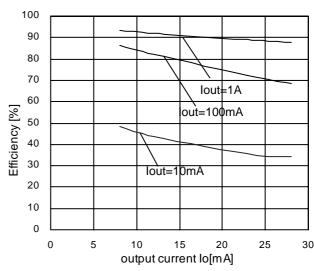


Figure 18. Efficiency - Input Voltage

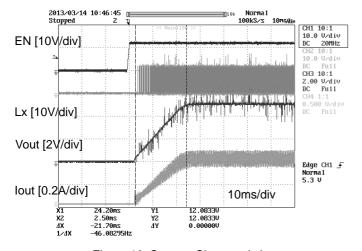


Figure 19. Start-up Characteristics

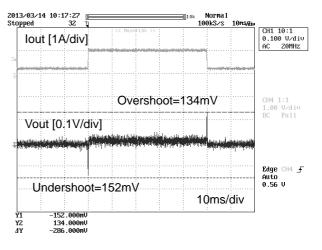
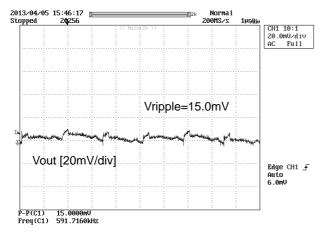


Figure 20. Load Response



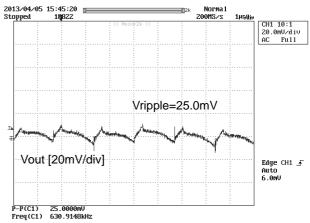


Figure 21. LX Switching/ Vout Ripple Io = 100mA

Figure 22. LX Switching/ Vout Ripple Io=1A

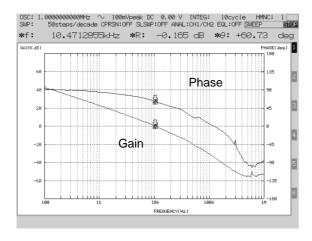


Figure 23. Frequency Response Io=1A

# Application parts list 1 (VIN=12V, VOUT=5V IOUT=1A)

Symbol	Value	Part name	Company	comments
[Capacitor]				
CVCC	10uF/35V	CRM31CB3YA106KA12L	MURATA	
CSS	0.047uF/25V	GRM155B31E473KA87	MURATA	
C1	10000pF/50V	GRM155B31H103KA88	MURATA	
CBST	0.1uF/10V	GRM155B31C104KA87	MURATA	
CO	47uF/16V	GRM32EB31C476KE15L	MURATA	
[Resistor]				
R3	2.7kΩ	MCR03 series	ROHM	
R4	12kΩ	MCR03 series	ROHM	
R5	3kΩ	MCR03 series	ROHM	
[Diode]				
D0	-	RSX101VA-30	ROHM	•
[Inductor]				
L0	15uH	NRS6045T150	TAIYO YUDEN	•

# Application parts list 2 (When load current are light and make a point of total area) (VIN=12V, VOUT=5V, IOUT=300mA)

Symbol	Value	Part name	Company	comments
[Capacitor]				
CVCC	10uF/25V	GRM188R61E106MA73	MURATA	
CSS	0.047uF/25V	GRM155B31E473KA87	MURATA	
C1	22000pF/50V	GRM155B31H223KA12	MURATA	
CBST	0.1uF/10V	GRM155B31C104KA87	MURATA	
CO	22uF/10V	GRM21BB31A226ME51	MURATA	
[Resistor]				
R3	2.2kΩ	MCR006 series	ROHM	
R4	12kΩ	MCR006 series	ROHM	
R5	3kΩ	MCR006 series	ROHM	
[Diode]				
D0	-	RSX101VA-30	ROHM	
[Inductor]				
L0	15uH	DEM3518C series	TOKO	

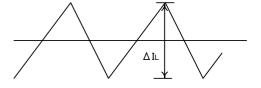
# **Application Components Selection Method**

#### (1) Inductors

Something of the shield type that fulfills the current rating (Current value lpecac below), with low DCR is recommended. Value of Inductance influences Inductor Ripple Current and becomes the cause of Output Ripple.

In the same way as the formula below, this Ripple Current can be made small.

In the same way as the formula below, this Ripple Current can be made small for as big as the L value of Coil or as high as the Switching Frequency.



Ipeak = IOUT + 
$$\frac{\triangle IL}{2}$$
 · · · · (1)
$$\triangle IL = \frac{VIN-VOUT}{L} \times \frac{VOUT}{VIN} \times \frac{1}{f}$$
 · · · · (2)

(⊿IL: Output Ripple Current, VIN: Input Voltage, VOUT: Output Voltage, f: Switching Frequency)
For design value of Inductor Ripple Current, please carry out design tentatively with about 20% ~ 50% of Maximum Input Current

#### (2) Output Capacitor

In order for capacitor to be used in output to reduce output ripple, Low ceramic capacitor of ESR is recommended. Also, for capacitor rating, on top of putting into consideration DC Bias characteristics, please use something whose maximum rating has sufficient margin with respect to the Output Voltage. Output ripple voltage is looked for using the following formula. The actual value of the output capacitor is not critical, but some practical limits do exist. Consider the relationship between the crossover frequency of the design and LC corner frequency of the output filter. In general, it is desirable to keep the crossover frequency at less than 1/5 of the switching frequency. With high switching frequencies such as the 600kHz frequency of this design, internal circuit limitations of the BD9E151NUX limit the practical maximum crossover frequency to about 30kHz. In general, the crossover frequency should be higher than the corner frequency determined by the load impedance and the output capacitor. This limits the minimum capacitor value for the output filter to:

$$COUT_{min} = \frac{1}{2\pi \times RI \times f_{c_{max}}} \cdot \cdot \cdot (3)$$

Where: RI is the output load resistance and fc\_max is the maximum crossover frequency. The output ripple voltage can be estimated by:

$$Vpp = \Delta IL \times \frac{1}{2\pi \times f \times COUT} + \Delta IL \times R_{ESR} \cdot \cdot \cdot (4)$$

Please design in a way that it is held within Capacity Ripple Voltage.

In the BD9E151NUX, it is recommended a ceramic capacitor more than 10µF.

#### (3) Output Voltage Setting

ERROR AMP internal Standard Voltage is 1.0V. Output Voltage is determined as seen in (5) formula

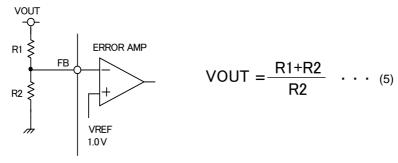


Figure 25. Output Voltage Setting

# (4) Bootstrap Capacitor

Please connect from 0.047µF to 0.47µF (Laminate Ceramic Capacitor) between BST Pin and LX Pin.

# (5) Soft Start Function

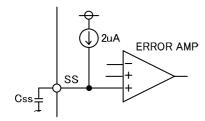


Figure 26. Soft Start Time Setting

It is highly recommended to program the soft start time externally to prevent high inrush current because no soft start time is implemented internally. A capacitor (Css) connected between the SS pin and ground implements a soft start time. The BD9E151NUX has an internal pull-up current source of 2uA that charges the external soft start capacitor. The equation for the soft start time (10% to 90 %) is shown in below Equation. The Iss current is 2uA.

$$Tss = \frac{Css \times 0.1}{Iss} \cdot \cdot \cdot (6)$$

#### (6) Catch Diode

The BD9E151NUX is designed to operate using an external catch diode between LX and GND. The selected diode must meet the absolute maximum ratings for the application: Reverse voltage must be higher than the maximum voltage at the LX pin, which is VINMAX + 0.5 V. Peak current must be greater than IOUTMAX+\(\triangle \triangle \triangle

#### (7) Input Capacitor

The BD9E151NUX requires an input capacitor and depending on the application. Use low ESR capacitors for the best performance. Ceramic capacitors are preferred, but low-ESR electrolytic capacitors may also suffice. The typical recommended value for the decoupling capacitor is 10uF. Please place this capacitor as possible as close to the VIN pin. When using ceramic capacitors, make sure that they have enough capacitance to provide sufficient charge to prevent excessive voltage ripple at input. The input voltage ripple caused by capacitance can be estimated by:

$$\Delta VCC = \frac{IOUT}{f \times CVCC} \times \frac{VOUT}{VCC} \times \left[ 1 - \frac{VOUT}{VCC} \right] \dots (7)$$

Since the input capacitor (CVIN) absorbs the input switching current it requires an adequate ripple current rating. The RMS current in the input capacitor can be estimated by:

$$I_{CVCC} = IOUT \times \sqrt{\frac{VOUT}{VCC}} \times (1 - \frac{VOUT}{VCC}) \quad \cdot \quad \cdot \quad (8)$$

The worst case condition occurs at VIN= 2VOUT, where

$$I_{\text{CVCC\_max}} = \frac{\text{IOUT}}{2} \cdot \cdot \cdot (9)$$

# (8) About Adjustment of DC/DC Comparator Frequency Characteristics

Role of Phase compensation element C1, C2, R3 (See P.8 Example of Reference Application Circuit)

Stability and Responsiveness of Loop are controlled through VC Pin which is the output of Error Amp. The combination of zero and pole that determines Stability and Responsiveness is adjusted by the combination of resistor and capacitor that are connected in series to the VC Pin.

DC Gain of Voltage Return Loop can be calculated for using the following formula.

Adc = RI × Gcs × 
$$A_{EA}$$
 ×  $\frac{V_{FB}}{V_{Out}}$  ... (10)

Here, VFB is Feedback Voltage (1.0V). A<sub>EA</sub> is Voltage Gain of Error amplifier (typ: 60 dB), Gcs is the Trans-conductance of Current Detect (typ: 10A/V), and RI is the Output Load Resistance value.

There are 2 important poles in the Control Loop of this DC/DC.

The first occurs with through the output resistance of Phase compensation Capacitor (C1) and Error amplifier.

The other one occurs with through the Output Capacitor and Load Resistor.

These poles appear in the frequency written below.

$$fp1 = \frac{G_{EA}}{2\pi \times C1 \times A_{EA}} \qquad . \qquad . \qquad (11)$$

$$fp2 = \frac{1}{2\pi \times COUT \times RI} \quad \cdots \quad (12)$$

Here, GEA is the trans-conductance of Error amplifier (typ: 250uA/V).

Here, in this Control Loop, one zero becomes important.

With the zero which occurs because of Phase compensation Capacitor C1 and Phase compensation Resistor R3, the Frequency below appears.

$$fz1 = \frac{1}{2\pi \times C1 \times R3} \cdot \cdot \cdot \cdot (13)$$

Also, if Output Capacitor is big, and that ESR (RESR) is big, in this Control Loop, there are cases when it has an important, separate zero (ESR zero).

This ESR zero occurs due to ESR of Output Capacitor and Capacitance, and exists in the Frequency below.

$$f_{ZESR} = \frac{1}{2\pi \times COUT \times RESR} \cdot \cdot \cdot (14)$$
 (ESR zero)

In this case, the 3<sup>rd</sup> pole determined with the 2<sup>nd</sup> Phase compensation Capacitor (C2) and Phase Correction Resistor (R3) is used in order to correct the ESR zero results in Loop Gain.

This pole exists in the frequency shown below.

$$fp3 = \frac{1}{2\pi \times C2 \times R3} \cdot \cdot \cdot (15)$$
 (pole that corrects ESR zero)

The target of Phase compensation design is to create a communication function in order to acquire necessary band and Phase margin.

Cross-over Frequency (band) at which Loop gain of Return Loop becomes "0" is important.

When Cross-over Frequency becomes low, Power supply Fluctuation Response, Load Response, etc worsens.

On the other hand, when Cross-over Frequency is too high, instability of the Loop can occur.

Tentatively, Cross-over Frequency is targeted to be made 1/20 or below of Switching Frequency. Selection method of Phase Compensation constant is shown below.

Phase Compensation Resistor (R3) is selected in order to set to the desired Cross-over Frequency.
 Calculation of RC is done using the formula below.

$$R3 = \frac{2\pi \times \text{COUT} \times \text{fc}}{\text{GEA} \times \text{GCS}} \times \frac{Vout}{VFB} \quad \cdots \quad (16)$$

Here, fc is the desired Cross-over Frequency. It is made about 1/20 and below of the Normal Switching Frequency (fs).

2. Phase compensation Capacitor (C1) is selected in order to achieve the desired phase margin. In an application that has a representative Inductance value (about several 10uH ~ 22uH), by matching zero of compensation to 1/4 and below of the Cross-over Frequency, sufficient Phase margin can be acquired.C1 can be calculated using the following formula.

C1>
$$\frac{4}{2\pi \times R3 \times fc}$$
 · · · (17)

RC is Phase compensation Resistor.

3. Examination whether the second Phase compensation Capacitor C2 is necessary or not is done.

If the ESR zero of Output Capacitor exists in a place that is smaller than half of the Switching Frequency, a second Phase compensation Capacitor is necessary. In other words, it is the case wherein the formula below happens.

$$\frac{1}{2\pi \times \text{COUT} \times \text{RESR}} < \frac{\text{fs}}{2} \quad \cdots \quad \text{(18)}$$

In this case, add the second Phase compensation Capacitor C2, and match the frequency of the third pole to the Frequency fp3 of ESR zero.

C2 is looked for using the following formula.

$$C2 = \frac{\text{COUT} \times \text{RESR}}{\text{R3}} \cdot \cdot \cdot (19)$$

#### **Output Voltage Restriction**

BD9E151NUX have a function of BSTUVLO to prevent malfunction at low voltage between BST and LX. Therefore OUTPUT voltage is restricted by BSTUVLO and Max Duty Cycle (min 85 %).

#### Restriction by BST-UVLO

When the voltage between BST and Lx is lower than 2.5V, High-Side FET will be made turned off and the charge will provide from VIN to BST directly to reset BSTUVLO (path①). The below formula is needed to be satisfied to reset BSTUVLO.

$$VIN \ge VOUT + VF + BSTUVLO reset \cdot \cdot \cdot (20)$$

Here, BSTUVLO reset: BSTUVLO reset voltage, VF: the diode forward bias voltage between VIN and BST Considering the fluctuation of BSTUVLO reset voltage and VF, maximum voltage is more than 5V.

Therefore maximum output voltage is defined as VIN - 5V.

# ②Restriction by Max Duty Cycle

Maximum output voltage is restricted by Max Duty Cycle (min85%). In this time it is needed to consider the effect of NchFET Ron , OUTPUT current and forward voltage of SBD. OUTPUT voltage can be calculated using the following formula.

VOUT\_max = 
$$(VIN - Ron \times IOUT) \times 0.85 - VF \times 0.15 \cdot \cdot \cdot (21)$$

Considering the effect of catch diode type and the loss by inductor, Vomax = (VIN-Ron×Iomax)×0.85 (casually formula)

Considering the negative voltage in the case of pulling diode current, maximum voltage is more than VIN×0.7.

Therefore maximum output voltage is defined as VIN×0.7.

Considering above restriction, adopt the lower output voltage as maximum voltage

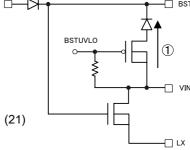


Figure 27. BST charge pass

# Cautions on PCB board layout

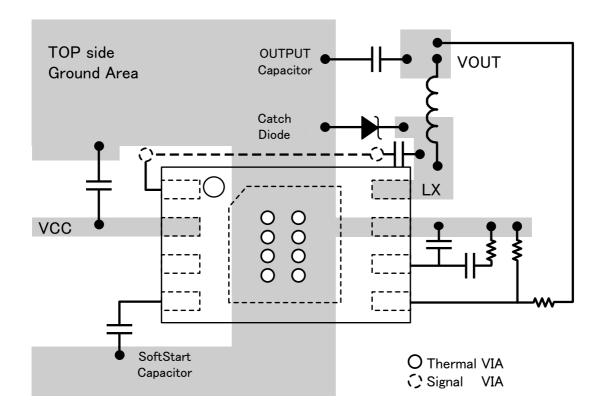


Figure 28. Reference PCB layout

Layout is a critical portion of good power supply design. There are several signals paths that conduct fast changing currents or voltages that can interact with stray inductance or parasitic capacitance to generate noise or degrade the power supplies performance. To help eliminate these problems, the VIN pin should be bypassed to ground with a low ESR ceramic bypass capacitor with B dielectric. Care should be taken to minimize the loop area formed by the bypass capacitor connections, the VIN pin, and the anode of the catch diode. See Fig.28 for a PCB layout example.

In the BD9E151NUX, since the LX connection is the switching node, the catch diode and output inductor should be located close to the LX pins, and the area of the PCB conductor minimized to prevent excessive capacitive coupling. And GND area should not be connected directly power GND, connected avoiding the high current switch paths. The additional external components can be placed approximately as shown.

# **Power Dissipation**

It is shown below reducing characteristics of power dissipation to mount 70mm×70mm×1.6mm<sup>t</sup> PCB Junction temperature must be designed not to exceed 150°C.

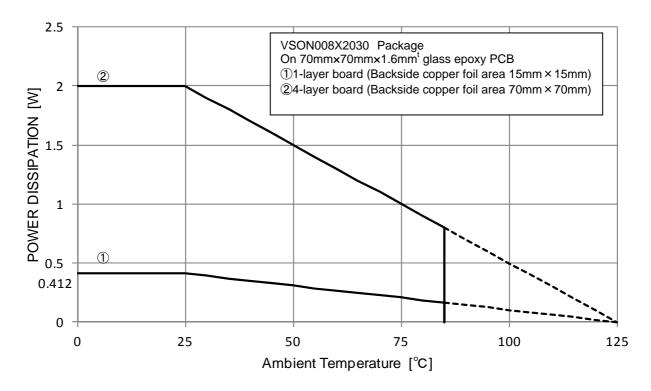


Figure 29. Power Dissipation (70mm×70mm×1.6mm<sup>t</sup> 1layer PCB)

# **Power Dissipation Estimate**

The following formulas show how to estimate the device power dissipation under continuous mode operations. They should not be used if the device is working in the discontinuous conduction mode.

The device power dissipation includes:

1) Conduction loss: Pcon = IOUT<sup>2</sup> × RonH × VOUT/VIN

2) Switching loss: Psw =  $0.25 \times 10^{-9} \times VIN^2 \times IOUT \times fsw$ 

3) Gate charge loss : Pgc =  $22.8 \times 10^{-9} \times \text{fsw}$ 

4) Quiescent current loss : Pq =  $0.7 \times 10^{-3} \times VIN$ 

Where:

IOUT is the output current (A ) , RonH is the on-resistance of the high-side MOSFET (  $\Omega$  ) , VOUT is the output voltage (V). VIN is the input voltage (V), fsw is the switching frequency (Hz).

Therefore

Power dissipation of IC is the sum of above dissipation.

Pd = Pcon + Psw + Pgc + Pq

For given Tj, Tj =Ta + θja × Pd

Where:

Pd is the total device power dissipation (W), Ta is the ambient temperature (°C)

Tj is the junction temperature (°C), θja is the thermal resistance of the package (°C)

# I/O equivalent circuit

equivalen	equivalent circuit								
Pin.	Pin	Pin Equivalent Circuit	Pin.	Pin	Pin Equivalent Circuit				
1 2 7 8	BST VIN GND LX	BST OVC	5	Name FB	FB GND GND				
3	EN	EN GND	6	VC	VC GND				
4	SS	SS							

#### Notes for use

(1) About Absolute Maximum Rating

When the absolute maximum ratings of application voltage, operating temperature range, etc. was exceeded, there is possibility of deterioration and destruction. Also, the short Mode or open mode, etc. destruction condition cannot be assumed. When the special mode where absolute maximum rating is exceeded is assumed, please give consideration to the physical safety countermeasure for the fuse, etc.

(2) About GND Electric Potential

In every state, please make the electric potential of GND Pin into the minimum electrical potential. Also, include the actual excessive effect, and please do it such that the pins, excluding the GND Pin do not become the voltage below GND.

- (3) About Heat Design
  - Consider the Power Dissipation (Pd) in actual state of use, and please make Heat Design with sufficient margin.
- (4) About short circuit between pins and erroneous mounting

When installing to set board, please be mindful of the direction of the IC, phase difference, etc. If it is not installed correctly, there is a chance that the IC will be destroyed. Also, if a foreign object enters the middle of output, the middle of output and power supply GND, etc., even for the case where it is shorted, there is a change of destruction.

- (5) About the operation inside a strong electro-magnetic field
  - When using inside a strong electro-magnetic field, there is a possibility of error, so please be careful.
- (6) Temperature Protect Circuit (TSD Circuit)

Temperature Protect Circuit (TSD Circuit) is built-in in this IC. As for the Temperature Protect Circuit (TSD Circuit), because it a circuit that aims to block the IC from insistent careless runs, it is not aimed for protection and guarantee of IC. Therefore, please do not assume the continuing use after operation of this circuit and the Temperature Protect Circuit operation.

(7) About checking with Set boards

When doing examination with the set board, during connection of capacitor to the pin that has low impedance, there is a possibility of stress in the IC, so for every 1 process, please make sure to do electric discharge. As a countermeasure for static electricity, in the process of assembly, do grounding, and when transporting or storing please be careful. Also, when doing connection to the jig in the examination process, please make sure to turn off the power supply, then connect. After that, turn off the power supply then take it off.

- (8) About common impedance
  - For the power supply and the wire of GND, lower the common impedance, then, as much as possible, make the ripple smaller (as much as possible make the wire thick and short, and lower the ripple from L· C), etc. then and please consider it sufficiently.
- (9) In the application, when the mode where the VIN and each pin electrical potential becomes reversed exists, there is a possibility that the internal circuit will become damaged. For example, during cases wherein the condition when charge was given in the external capacitor, and the VIN was shorted to GND, it is recommended to insert the bypass diode to the diode of the back current prevention in the VIN series or the middle of each Pin-VIN (fig.30).
- (10) About IC Pin Input

This IC is a Monolithic IC, and between each element, it has P<sup>+</sup> isolation for element separation and P board. With the N layer of each element and this, the P-N junction is formed, and the parasitic element of each type is composed.

For example, like the fig.31, when resistor and transistor is connected to Pin,

- •When GND > (PinA) in Resistor, when GND > (PinA), when GND > (PinB) in Transistor (NPN), the P-N junction will operate as a parasitic diode.
- OAlso, during GND > (Pin B) in the Transistor (NPN), through the N layer of the other elements connected to the above-mentioned parasitic diode, the parasitic NPN Transistor will operation.

On the composition of IC, depending on the electrical potential, the parasitic element will become necessary. Through the operation of the parasitic element interference of circuit operation will arouse, and error, therefore destruction can be caused. Therefore please be careful about the applying of voltage lower than the GND (P board) in I/O Pin, and the way of using when parasitic element operating.

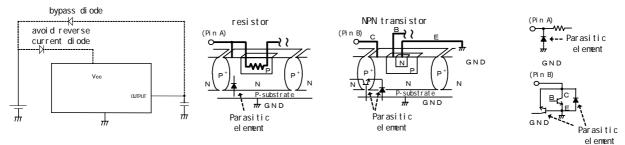
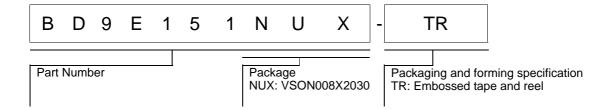


Figure 30. Example of insert diode

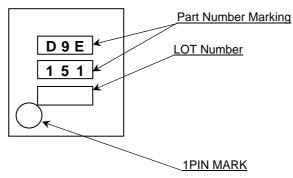
Figure 31. Example of simple structure of Monolithic IC

Physical Dimension Tape and Reel Information

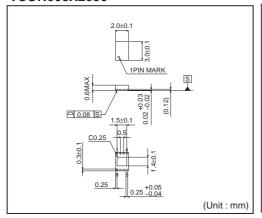


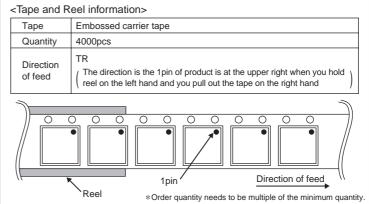
#### Marking Diagram

# VSON008X2030 (TOP VIEW)



# VSON008X2030





# **Notice**

# **Precaution on using ROHM Products**

Our Products are designed and manufactured for application in ordinary electronic equipments (such as AV equipment, OA equipment, telecommunication equipment, home electronic appliances, amusement equipment, etc.). If you intend to use our Products in devices requiring extremely high reliability (such as medical equipment (Note 1), transport equipment, traffic equipment, aircraft/spacecraft, nuclear power controllers, fuel controllers, car equipment including car accessories, safety devices, etc.) and whose malfunction or failure may cause loss of human life, bodily injury or serious damage to property ("Specific Applications"), please consult with the ROHM sales representative in advance. Unless otherwise agreed in writing by ROHM in advance, ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of any ROHM's Products for Specific Applications.

(Note1) Medical Equipment Classification of the Specific Applications

 	1			
JAPAN	USA	EU	CHINA	
CLASSⅢ	CL ACC TI	CLASS II b	CLASSIII	
CLASSIV	CLASSⅢ	CLASSⅢ	CLASSIII	

- 2. ROHM designs and manufactures its Products subject to strict quality control system. However, semiconductor products can fail or malfunction at a certain rate. Please be sure to implement, at your own responsibilities, adequate safety measures including but not limited to fail-safe design against the physical injury, damage to any property, which a failure or malfunction of our Products may cause. The following are examples of safety measures:
  - [a] Installation of protection circuits or other protective devices to improve system safety
  - [b] Installation of redundant circuits to reduce the impact of single or multiple circuit failure
- 3. Our Products are designed and manufactured for use under standard conditions and not under any special or extraordinary environments or conditions, as exemplified below. Accordingly, ROHM shall not be in any way responsible or liable for any damages, expenses or losses arising from the use of any ROHM's Products under any special or extraordinary environments or conditions. If you intend to use our Products under any special or extraordinary environments or conditions (as exemplified below), your independent verification and confirmation of product performance, reliability, etc, prior to use, must be necessary:
  - [a] Use of our Products in any types of liquid, including water, oils, chemicals, and organic solvents
  - [b] Use of our Products outdoors or in places where the Products are exposed to direct sunlight or dust
  - [c] Use of our Products in places where the Products are exposed to sea wind or corrosive gases, including Cl<sub>2</sub>, H<sub>2</sub>S, NH<sub>3</sub>, SO<sub>2</sub>, and NO<sub>2</sub>
  - [d] Use of our Products in places where the Products are exposed to static electricity or electromagnetic waves
  - [e] Use of our Products in proximity to heat-producing components, plastic cords, or other flammable items
  - [f] Sealing or coating our Products with resin or other coating materials
  - [g] Use of our Products without cleaning residue of flux (even if you use no-clean type fluxes, cleaning residue of flux is recommended); or Washing our Products by using water or water-soluble cleaning agents for cleaning residue after soldering
  - [h] Use of the Products in places subject to dew condensation
- 4. The Products are not subject to radiation-proof design.
- 5. Please verify and confirm characteristics of the final or mounted products in using the Products.
- 6. In particular, if a transient load (a large amount of load applied in a short period of time, such as pulse. is applied, confirmation of performance characteristics after on-board mounting is strongly recommended. Avoid applying power exceeding normal rated power; exceeding the power rating under steady-state loading condition may negatively affect product performance and reliability.
- 7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

#### Precaution for Mounting / Circuit board design

- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used; if flow soldering method is preferred, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

# **Precautions Regarding Application Examples and External Circuits**

- If change is made to the constant of an external circuit, please allow a sufficient margin considering variations of the characteristics of the Products and external components, including transient characteristics, as well as static characteristics.
- You agree that application notes, reference designs, and associated data and information contained in this document are presented only as guidance for Products use. Therefore, in case you use such information, you are solely responsible for it and you must exercise your own independent verification and judgment in the use of such information contained in this document. ROHM shall not be in any way responsible or liable for any damages, expenses or losses incurred by you or third parties arising from the use of such information.

#### **Precaution for Electrostatic**

This Product is electrostatic sensitive product, which may be damaged due to electrostatic discharge. Please take proper caution in your manufacturing process and storage so that voltage exceeding the Products maximum rating will not be applied to Products. Please take special care under dry condition (e.g. Grounding of human body / equipment / solder iron, isolation from charged objects, setting of Ionizer, friction prevention and temperature / humidity control).

# **Precaution for Storage / Transportation**

- 1. Product performance and soldered connections may deteriorate if the Products are stored in the places where:
  - [a] the Products are exposed to sea winds or corrosive gases, including Cl2, H2S, NH3, SO2, and NO2
  - [b] the temperature or humidity exceeds those recommended by ROHM
  - the Products are exposed to direct sunshine or condensation
  - [d] the Products are exposed to high Electrostatic
- 2. Even under ROHM recommended storage condition, solderability of products out of recommended storage time period may be degraded. It is strongly recommended to confirm solderability before using Products of which storage time is exceeding the recommended storage time period.
- 3. Store / transport cartons in the correct direction, which is indicated on a carton with a symbol. Otherwise bent leads may occur due to excessive stress applied when dropping of a carton.
- Use Products within the specified time after opening a humidity barrier bag. Baking is required before using Products of which storage time is exceeding the recommended storage time period.

## **Precaution for Product Label**

QR code printed on ROHM Products label is for ROHM's internal use only.

#### **Precaution for Disposition**

When disposing Products please dispose them properly using an authorized industry waste company.

#### **Precaution for Foreign Exchange and Foreign Trade act**

Since our Products might fall under controlled goods prescribed by the applicable foreign exchange and foreign trade act, please consult with ROHM representative in case of export.

#### **Precaution Regarding Intellectual Property Rights**

- 1. All information and data including but not limited to application example contained in this document is for reference only. ROHM does not warrant that foregoing information or data will not infringe any intellectual property rights or any other rights of any third party regarding such information or data. ROHM shall not be in any way responsible or liable for infringement of any intellectual property rights or other damages arising from use of such information or data.:
- 2. No license, expressly or implied, is granted hereby under any intellectual property rights or other rights of ROHM or any third parties with respect to the information contained in this document.

# **Other Precaution**

- 1. This document may not be reprinted or reproduced, in whole or in part, without prior written consent of ROHM.
- 2. The Products may not be disassembled, converted, modified, reproduced or otherwise changed without prior written consent of ROHM.
- 3. In no event shall you use in any way whatsoever the Products and the related technical information contained in the Products or this document for any military purposes, including but not limited to, the development of mass-destruction weapons.
- The proper names of companies or products described in this document are trademarks or registered trademarks of ROHM, its affiliated companies or third parties.

#### **General Precaution**

- 1. Before you use our Products, you are requested to care fully read this document and fully understand its contents. ROHM shall not be in any way responsible or liable for failure, malfunction or accident arising from the use of a ny ROHM's Products against warning, caution or note contained in this document.
- 2. All information contained in this docume nt is current as of the issuing date and subject to change without any prior notice. Before purchasing or using ROHM's Products, please confirm the latest information with a ROHM sale s representative.
- 3. The information contained in this doc ument is provided on an "as is" basis and ROHM does not warrant that all information contained in this document is accurate an d/or error-free. ROHM shall not be in an y way responsible or liable for any damages, expenses or losses incurred by you or third parties resulting from inaccuracy or errors of or concerning such information.

**Notice – WE** © 2014 ROHM Co., Ltd. All rights reserved. Rev.001