BCT2601

GENERAL DESCRIPTION

The BCT2601 is a battery charger and power path management device with integrated converter and power switches use with 1-cell Li-Ion, Li-polymer batteries. It is capable for fast charging and supports a wide input voltage range suitable for smart phones, tablets and portable systems.

The BCT2601 includes four main power switches: input reverse blocking FET (RBFET, Q1), high-side switching FET for buck or boost mode (HSFET, Q2), low-side switching FET for buck or boost mode switching (LSFET, Q3) and battery FET (BATFET, Q4).

The BCT2601 is USB 2.0 and USB 3.0 power specifications compliant with input current and voltage regulation. It also meets USB On-The-Go (OTG) power rating specification.

The BCT2601 system voltage is regulated slightly above the battery voltage by the power path management circuit and is kept above the programmable minimum system voltage (3.5V by default).Therefore, system power is maintained even if the battery is completely depleted or removed.

The BCT2601, available in QFN-4×4-24L package, provide a very compact system solution external components and PCB area.

FEATURES

- High Efficiency, 1.5MHz, Syn. Buck Charger
  - 91% Charge Efficiency at 2A from 5V Input
  - Optimized for USB Voltage Input (5V)
  - Selectable PFM Mode for Light Load
- Supports USB On-The-Go (OTG)
  - Boost Efficiency of 92% at 1A
  - Soft-Start Capable with up to 500μF Cap Load
  - Selectable PFM Mode for Light Load
- Single Input for USB or High Voltage Adapters
  - 3.9V to 13.5V Operating Input Voltage Range
  - Programmable Input Current Limit to Support USB 2.0 and USB 3.0 Standards and High Voltage Adaptors(IIDPM)
  - auto tracks battery voltage(VINDPM)
- High discharge efficiency with 28mΩ BATFET
- Narrow VDC (NVDC) power path management
  - Instant-On with No or Highly Depleted Battery
  - Ideal Diode in Battery Supplement Mode
- Ship mode, wake up, system reset by BATFET
- High accuracy
  - ±0.5% charge voltage regulation
  - ±5% at 1.5-A charge current regulation

APPLICATIONS

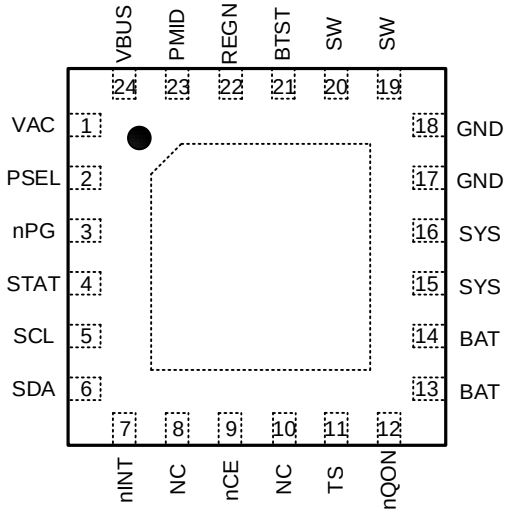
- Smart Phones
- Portable Internet Devices and Accessory

ORDERING INFORMATION

Order Number	Package Type	Temperature Range	Marking	QTY/Reel
BCT2601EGG-TR	QFN4x4-24L	-40°C to +85°C	PWZQ XXXXX	5000

Note:"XXXXX" in Marking will be appeared as the batch code.

PIN CONFIGURATION (TOP VIEW)



QFN-4×4-24L

PIN DESCRIPTION

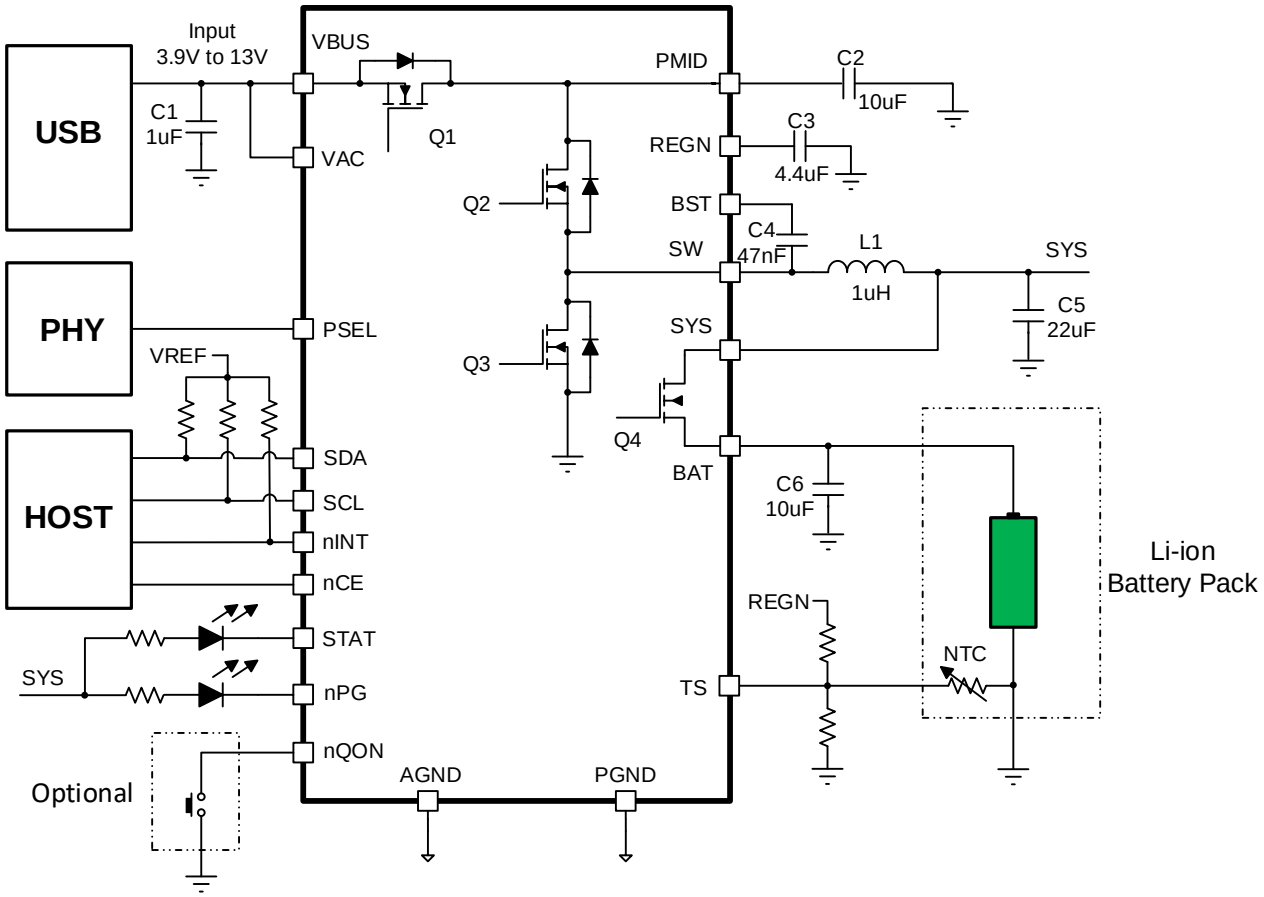
PIN	NAME	TYPE	FUNCTION
1	VAC	AI	Sense Input for DC Input Voltage (Typically from an AC/DC Adaptor). Must be connected to VBUS pin.
2	PSEL	DI	Power Source Selection Input. If PSEL is pulled high, the input current limit is set to 500mA (USB 2.0) and if it is pulled low, the limit is set to 2.4A (adaptor). When the I2C link to the host is established, the host can program a different input current limit value by writing to the IINDPM[4:0] register.
3	nPG	DO	Open-Drain Active Low Input Power Good Indicator. Use a 10kΩ pull up to the logic high rail. A low state indicates a good input (UVLO < V_{VBUS}< ACOV, and above sleep mode threshold, I_{LIM}> 30mA).
4	STAT	DO	Open-Drain Charge Status Output. Use a 10kΩ pull up to the logic high rail (or an LED + a resistor). The STAT pin acts as follows: During charge: low (LED ON). Charge completed or charger in sleep mode: high (LED OFF). Charge suspend (in response to a fault): 1Hz, 50% duty cycle pulses (LED BLINKS). The function can be disabled via EN_ICHG_MON[1:0] register.
5	SCL	DI	I2C Clock Signal. Use a 10kΩ pull up to the logic high rail.
6	SDA	DIO	I2C Clock Signal. Use a 10kΩ pull up to the logic high rail.
7	nINT	DO	Open-Drain Interrupt Output Pin. Use a 10kΩ pull up to the logic high rail. The ninth pin is active low and sends a negative 256μs pulse to inform host about a new charger status update or a fault.

NOTE: AI = Analog Input, AO = Analog Output, AIO = Analog Input and Output, DI = Digital Input, DO = Digital Output, DIO = Digital Input and Output, P = Power.

PIN DESCRIPTION(continued)

PIN	NAME	TYPE	FUNCTION
8, 10	NC		Do Not Connect and Leave This Pin Float.
9	nCE	DI	Charge Enable Input Pin (Active Low). Battery charging is enabled when CHG_CONFIG bit is 1 and nCE pin is pulled low.
11	TS	AI	Temperature Qualification Voltage Input (Supports JEITA Profile). Connect to the battery NTC thermistor that is grounded on the other side. To program operating temperature window, it can be biased by a resistor divider between REGN and GND. Charge suspends if TS voltage goes out of the programmed range. It is recommended to use a 103AT-2 type thermistor. If NTC and TS pin function is not needed, use a 10kΩ/10kΩ pair for the resistor divider.
12	nQON	DI	BATFET Enable/Reset Control Input. Uses an internal pull-up to a small voltage for maintaining the default high logic (whenever a source or battery is available). In the ship mode the BATFET is off. To exit ship mode and turn BATFET on, a logic low pulse with a duration of $t_{SHIPMODE}$ (1s TYP) can be applied to nQON. When VBUS source is not connected, a logic low pulse with a duration of t_{QON_RST} (16s TYP) resets the system power (SYS) by turning BATFET off for t_{BATFET_RST} (250ms TYP) and then back on to provide a full power reset for system.
13, 14	BAT	P	Battery Positive Terminal Pin. Use a 10μF capacitor between BAT and GND pins close to the device. SYS and BAT pins are internally connected by BATFET with current sensing capability.
15, 16	SYS	P	Connection Point to Converter Output. SYS connects to the converter LC filter output that powers the system. BAT to SYS internal current (power from battery to system) is sensed. Connect a 20μF capacitor between SYS pin and GND close to the device (in addition to COUT).
17, 18	GND		Ground Pin of the Device.
19, 20	SW	P	Switching Node Output. Connect SW pin to the output inductor. Connect a 47nF bootstrap capacitor from SW pin to BTST pin.
21	BTST	P	High-side Driver Positive Supply. It is internally connected to the boost-strap diode cathode. Use a 47nF ceramic capacitor from SW pin to BTST pin.
22	REGN	P	LDO Output that Powers LSFET Driver and Internal Circuits. Internally, the REGN pin is connected to the anode of the bootstrap diode. Connect a 4.7μF (10V rating) ceramic capacitor from REGN pin to GND. The capacitor should be placed close to the IC. The output is typically 4.5V to 5V.
23	PMID	DO	PMID Pin. PMID is the actual higher voltage port of converter (buck or boost) and is connected to the drain of the reverse blocking MOSFET (RBFET) and the drain of HSFET. Connect a 10μF ceramic capacitor from PMID pin to GND. It is the proper point for decoupling of high frequency switching currents.
24	VBUS	P	Charger Input (VIN). The internal N-channel reverse blocking MOSFET (RBFET) is connected between VBUS and PMID pins. Place a 1μF ceramic capacitor from VBUS pin to GND close to the device.
Exposed Pad		P	Thermal Pad and Ground Reference. It is the ground reference for the device and also the thermal pad to conduct heat from the device (not suitable for high current return). Tie externally to the PCB ground plane (GND). Thermal vias under the pad are needed to conduct the heat to the PCB ground planes.

Typical Operating Circuit



ABSOLUTE MAXIMUM RATINGS

VAC,VBUS to GND.....-2V to 20V
SW to GND…….....-2V to 16V
BTST,PMID to GND.....-0.3V to 20V
BTST to SW.....-0.3V to 6V
REGN,TS,nCE,nPG,BAT,SYS to GND.....-0.3V to 6V
PSEL,SDA,SCL,nINT,nQON,STAT to GND..-0.3V to 6V
Storage Temperature Range.....-65℃ to +150℃
Junction Temperature.....150℃
Lead Temperature (Soldering, 10 sec).....260℃
Package Thermal Resistance(Θ_{JA}) ….....37℃/W
Package Thermal Resistance(Θ_{JC}) .....24℃/W

ESD Protection

Human Body Model.....4000V
Charged-device model.....1000V

NOTE:

Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

CAUTION

This integrated circuit can be damaged by ESD if you don’t pay attention to ESD protection. Broadchip recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage. ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

Broadchip reserves the right to make any change in circuit design, specification or other related things if necessary without notice at any time. Please contact Broadchip sales office to get the latest datasheet.

ELECTRICAL CHARACTERISTICS

(V_{VAC_UVLOZ}< V_{VAC}< V_{VAC_OV} and V_{VAC}> V_{BAT} + V_{SLEEP}, Full = -40℃ to +85℃, typical values are at T_J = +25℃, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
Quiescent Currents							
Battery Discharge Current (BAT, SW, SYS) in Buck Mode	I_{BQ_VBUS}	V_{BAT} = 4.5V, V_{VBUS}< V_{VAC_UVLOZ}, leakage between BAT and VBUS, BATFET off	Full		0.1	1	μA
Battery Discharge Current (BAT) in Buck Mode	$I_{BQ\_HIZ\_BOFF}$	V_{BAT} = 4.5V, HIZ mode and BATFET_DIS = 1 or no VBUS, I²C disabled, BATFET disabled	Full		10	20	μA
Battery Discharge Current (BAT, SW, SYS)	$I_{BQ\_HIZ\_BON}$	V_{BAT} = 4.5V, HIZ mode and BATFET_DIS = 0 or no VBUS, I²C disabled, BATFET enabled	Full		20	40	μA
Input Supply Current (VBUS) in Buck Mode	I_{VBUS_HIZ}	V_{VBUS} = 5V, HIZ mode and BATFET_DIS = 1, no battery	Full		25	40	μA
		V_{VBUS} = 12V, HIZ mode and BATFET_DIS = 1, no battery	Full		45	70	
	I_{VBUS}	V_{VBUS} = 12V, V_{VBUS}> V_{BAT}, converter not switching	Full		1.3	2	mA
		V_{BAT} = 3.8V, I_{SYS} = 0A, V_{VBUS}> V_{BAT}, V_{VBUS}> V_{VAC_UVLOZ}, converter switching, BATFET off	+25℃		4		
Battery Discharge Current in Boost Mode	I_{BOOST}	V_{BAT} = 4.2V, I_{VBUS} = 0A, converter switching	+25℃		3		mA
BAT Pin, VAC Pin and VBUS Pin Power-Up							
VBUS Operating Range	V_{VBUS_OP}	V_{VBUS} rising	Full	3.9		13.5	V
VBUS UVLO to Have Active I²C (with No Battery) Seen by Sense VAC Pin	V_{VAC_UVLOZ}	V_{VAC} rising	+25℃		3.25	3.8	V
I2C Active Hysteresis	$V_{VAC\_UVLOZ\_HYS}$	V_{VAC} falling from above V_{VAC_UVLOZ}	+25℃		50		mV
VVAC Minimum (as One of the Conditions) to Turn On REGN	$V_{VAC\_PRESENT}$	V_{VAC} rising	+25℃		3.25	3.8	V
VAC Hysteresis (as One of the Conditions) to Turn On REGN	$V_{VAC\_PRESENT\_HYS}$	V_{VAC} falling	+25℃		50		mV
Sleep Mode Falling Threshold	V_{SLEEP}	(V_{VAC} - V_{BAT}), $V_{VBUSMIN\_FALL}$≤ V_{BAT}≤ V_{REG}, V_{VAC} falling	+25℃	15	70	125	mV
Sleep Mode Rising Threshold	V_{SLEEPZ}	(V_{VAC} - VBAT), $V_{VBUSMIN\_FALL}$≤ V_{BAT}≤ V_{REG}, V_{VAC} rising	+25℃	150	200	260	mV

ELECTRICAL CHARACTERISTICS (continued)

(V_{VAC_UVLOZ}< V_{VAC}< V_{VAC_OV} and V_{VAC}> V_{BAT} + V_{SLEEP}, Full = -40℃ to +85℃, typical values are at T_J = +25℃, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
VAC 6.5V Over-Voltage Hysteresis	$V_{VAC\_OV\_RISE}$	V_{VAC} rising, OVP[1:0] = 01	Full	6.15	6.5	6.95	V
VAC 10.5V Over-Voltage Hysteresis		V_{VAC} rising, OVP[1:0] = 10	Full	10	10.5	11.05	
VAC 14V Over-Voltage Hysteresis		V_{VAC} rising, OVP[1:0] = 11	Full	13.2	14	14.55	
VAC 6.5V Over-Voltage Hysteresis	$V_{VAC\_OV\_HYS}$	V_{VAC} falling, OVP[1:0] = 01	+25℃		500		mV
VAC 10.5V Over-Voltage Hysteresis		V_{VAC} falling, OVP[1:0] = 10	+25℃		500		
VAC 14V Over-Voltage Hysteresis		V_{VAC} falling, OVP[1:0] = 11	+25℃		500		
BAT Voltage to Have Active I2C, (No Source on VBUS)	V_{BAT_UVLOZ}	V_{BAT} rising	Full	2.65			V
BAT Depletion Threshold	$V_{BAT\_DPL\_FALL}$	V_{BAT} falling	Full	2	2.25	2.45	V
	$V_{BAT\_DPL\_RISE}$	V_{BAT} rising	Full	2.1	2.5	2.85	
BAT Depletion Rising Hysteresis	$V_{BAT\_DPL\_HYS}$	V_{BAT} rising	+25℃		250		mV
Bad Adapter Detection Current (Internal Current Sink)	I_{BAD_SRC}	Sink current from V_{BUS} to GND	+25℃		30		mA
Bad Adapter Detection (VBUS Voltage Drop) Falling Threshold	$V_{VBUSMIN\_FALL}$	V_{VBUS} falling	Full	3.35	3.5	3.65	V
Bad Adapter Detection (VBUS Voltage Drop) Hysteresis	$V_{VBUSMIN\_HYS}$		+25℃		250		mV
Power Path Management							
System Regulation Voltage	V_{SYS}	I_{SYS} = 0A, V_{BAT} = 4.4V, V_{BAT}> V_{SYS_MIN}, BATFET_DIS = 1	+25℃		V_{BAT} + 50mV		V
Minimum DC System Voltage Output	V_{SYS_MIN}	I_{SYS} = 0A, V_{BAT}< SYS_MIN[2:0] = 101(3.5V), BATFET_DIS = 1	Full	3.5	3.69		V
Maximum DC System Voltage Output	V_{SYS_MAX}	I_{SYS} = 0A, V_{BAT}≤ 4.4V, V_{BAT}> V_{SYS_MIN} = 3.5V, BATFET_DIS = 1	Full	4.37	4.45	4.54	V

ELECTRICAL CHARACTERISTICS (continued)

(V_{VAC_UVLOZ}< V_{VAC}< V_{VAC_OV} and V_{VAC}> V_{BAT} + V_{SLEEP}, Full = -40℃ to +85℃, typical values are at T_J = +25℃, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS		TEMP	MIN	TYP	MAX	UNITS
Top Reverse Blocking MOSFET On-Resistance between VBUS and PMID - Q1	R_{ON_RBFET}			+25℃		41		mΩ
Top Switching MOSFET On-Resistance between PMID and SW - Q2	R_{ON_HSFET}	V_{REGN} = 5V		+25℃		45		mΩ
Bottom Switching MOSFET On-Resistance between SW and GND - Q3	R_{ON_LSFET}	V_{REGN} = 5V		+25℃		55		mΩ
BATFET forward Voltage in Supplement Mode	V_{FWD}			+25℃		30		mV
Battery Charger								
Charge Voltage Program Range	$V_{BAT\_REG\_RANGE}$			Full	3.856		4.624	V
Charge Voltage Step	$V_{BAT\_REG\_STEP}$			+25℃		32		mV
Charge Voltage Setting	V_{BAT_REG}	V_{REG}[4:0] = 01011 (4.208V)		+25℃	4.192	4.208	4.224	V
				Full	4.184	4.208	4.232	
		V_{REG}[4:0] = 01111 (4.352V)		+25℃	4.332	4.349	4.366	
				Full	4.323	4.349	4.375	
Charge Voltage Setting Accuracy	$V_{BAT\_REG\_ACC}$	V_{BAT_REG} = 4.208V or V_{BAT_REG} = 4.352V		+25℃	-0.4		0.4	%
				Full	-0.6		0.6	
Charge Current Regulation Range	$I_{CHG\_REG\_RANGE}$			Full	0		3000	mA
Charge Current Regulation Step	$I_{CHG\_REG\_STEP}$			+25℃		60		mA
Charge Current Regulation Setting	I_{CHG_REG}	V_{BAT} = 3.8V	I_{CHG} = 240mA	+25℃	0.168	0.24	0.297	A
			I_{CHG} = 720mA	+25℃	0.609	0.72	0.768	
			I_{CHG} = 1.38A	+25℃	1.312	1.38	1.449	
Pre-Charge Current Regulation Setting	I_{PRECHG}	I_{PRECHG}[3:0] = 0010 (180mA)		+25℃	130	175	222	mA
Battery LOW Falling Threshold	V_{BATLOW_FALL}	I_{CHG} = 480mA		Full	2.83	2.95	3.05	V
Battery LOW Rising Threshold	V_{BATLOW_RISE}	Change from pre-charge to fast charging		Full	3.06	3.15	3.22	V
Termination Current Regulation Setting	I_{TERM}	V_{BAT_REG} = 4.208V, I_{TERM}[3:0] = 0010 (180mA)		+25℃	142	180	218	mA
Battery Short Voltage	V_{SHORT}	V_{BAT} falling		Full	2	2.05	2.1	V
	V_{SHORTZ}	V_{BAT} rising		Full	2.15	2.2	2.25	

ELECTRICAL CHARACTERISTICS (continued)

(V_{VAC_UVLOZ}< V_{VAC}< V_{VAC_OV} and V_{VAC}> V_{BAT} + V_{SLEEP}, Full = -40℃ to +85℃, typical values are at T_J = +25℃, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
Battery Short Current	I_{SHORT}	V_{BAT}< V_{SHORTZ}	+25℃		80		mA
Recharge Threshold below VBAT_REG	V_{RECHG}	V_{BAT} falling, V_{RECHG} = 0 (100mV)	Full	60	100	135	mV
		V_{BAT} falling, V_{RECHG} = 1 (200mV)	Full	155	195	235	
System Discharge Load Current	I_{SYS_LOAD}	V_{SYS} = 4.2V	+25℃		24		mA
BATFET MOSFET ON-Resistance	R_{ON_BATFET}	V_{BAT} = 4.2V, measured from BAT pin to SYS pin	+25℃		28	38	mΩ
Input Voltage and Current Regulation (DPM: Dynamic Power Management)							
Input Voltage Regulation Limit	V_{INDPM}	V_{INDPM}[3:0] = 0000 (3.9V)	+25℃	3.76	3.87	3.98	V
Input Voltage Regulation Accuracy	V_{INDPM_ACC}		+25℃	-2.9		2.9	%
Input Voltage Regulation Limit	V_{INDPM}	V_{INDPM}[3:0] = 0110 (4.4V)	+25℃	4.24	4.36	4.48	V
Input Voltage Regulation Accuracy	V_{INDPM_ACC}		+25℃	-2.8		2.8	%
Input Voltage Regulation Limit Tracking VBAT	V_{DPM_VBAT}	V_{BAT} = 4V, V_{INDPM} = 3.9V, $V_{DPM\_BAT\_TRACK}$[1:0] = 11 (300mV)	+25℃	4.2	4.31	4.42	V
Input Voltage Regulation Accuracy Tracking VBAT	$V_{DPM\_VBAT\_ACC}$		+25℃	-2.6		2.6	%
USB Input Current Regulation Limit	I_{INDPM}	V_{VBUS} = 5V, current pulled from SW, I_{INDPM}[4:0] = 00100 (500mA)	+25℃	460		520	mA
		V_{VBUS} = 5V, current pulled from SW, I_{INDPM}[4:0] = 01000 (900mA)	+25℃	800		950	
		V_{VBUS} = 5V, current pulled from SW, I_{INDPM}[4:0] = 01110 (1.5A)	+25℃	1260		1570	
Input Current Limit during System Start-Up Sequence	I_{IN_START}		+25℃		200		mA
BAT Pin Over-Voltage Protection							
Battery Over-Voltage Threshold	V_{BATOVP_RISE}	V_{BAT} rising, as percentage of V_{BAT_REG}	+25℃	103	104	105.5	%
	V_{BATOVP_FALL}	V_{BAT} falling, as percentage of V_{BAT_REG}	+25℃	101	102	103	
Thermal Regulation and Thermal Shutdown							
Junction Temperature Regulation Threshold	$T_{JUNCTION\_REG}$	Temperature increasing, T_{REG} = 1 (120℃)	Full		120		℃
		Temperature increasing, T_{REG} = 0 (80℃)	Full		80		
Thermal Shutdown Rising Temperature	T_{SHUT}	Temperature increasing	Full		150		℃
Thermal Shutdown Hysteresis	T_{SHUT_HYS}		Full		20		

ELECTRICAL CHARACTERISTICS (continued)

(V_{VAC_UVLOZ}< V_{VAC}< V_{VAC_OV} and V_{VAC}> V_{BAT} + V_{SLEEP}, Full = -40℃ to +85℃, typical values are at T_J = +25℃, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
JEITA Thermistor Comparator (Buck Mode)							
T1 (0℃) Threshold Voltage on TS Pin	V_{T1}	Charge suspends if temperature T is below T_1 ($T < T_1$), as percentage of V_{REGN}	Full	72.6	73.2	73.9	%
Falling		As percentage of V_{REGN}	Full	71	71.6	72.1	
T2 (10℃) Threshold	V_{T2}	Charge sets to $I_{CHG/2}$ and 4.2V if T_1< T < T_2, as percentage of V_{REGN}	Full	67.4	68	68.7	%
Falling		As percentage of V_{REGN}	Full	66	66.7	67.4	
T3 (45℃) Threshold	V_{T3}	Charge sets to normal (I_{CHG} and 4.05V) if T_2< T < T_3, as percentage of V_{REGN}	Full	43.4	44.5	45.5	%
Falling		As percentage of V_{REGN}	Full	45.1	45.8	46.4	
T4 (60℃) Threshold	V_{T4}	Charge sets to (4.1V or V_{REG}) if T_3< T < T_4 and suspends if T > T_4, as percentage of V_{REGN}	Full	33.5	34.1	34.8	%
Falling		As percentage of V_{REGN}	Full	34.8	35.4	36.1	
Cold or Hot Thermistor Comparator (Boost Mode)							
Cold Temperature Threshold (TS Pin Voltage Rising Threshold)	V_{BCOLD}	As percentage of V_{REGN} (approx. -20℃ w/ 103AT)	Full	79.4	80	80.7	%
TS Voltage Falling (Exit from Cold Range to Cool)		As percentage of V_{REGN}	Full	78.2	79	79.6	
Hot Temperature Threshold (TS Pin Voltage Falling Threshold)	V_{BHOT}	As percentage of V_{REGN} (approx. 60℃ w/ 103AT)	Full	30.5	31.2	31.9	%
TS Voltage Rising (Exit Hot Range to Warm)		As percentage of V_{REGN}	Full	33.7	34.4	35	
Charge Over-Current Comparator (Cycle-By-Cycle)							
HSFET Cycle-by-Cycle Over-Current Threshold	I_{HSFET_OCP}		+25℃	4		6.2	A
System Overload Threshold	I_{BATFET_OCP}		+25℃	6			A
Charge Under-Current Comparator (Cycle-By-Cycle)							
LSFET Under-Current Falling Threshold	I_{LSFET_UCP}	Change rectifier from synchronous mode to non-synchronous mode	+25℃		160		mA
PWM							
PWM Switching Frequency	f_{SW}	Oscillator frequency, buck mode	+25℃	1400	1500	1600	kHz
		Oscillator frequency, boost mode	+25℃	1400	1500	1600	

ELECTRICAL CHARACTERISTICS (continued)

(V_{VAC_UVLOZ}<V_{VAC}< V_{VAC_OV} and V_{VAC}> V_{BAT} + V_{SLEEP}, Full = -40℃ to +85℃, typical values are at T_J = +25℃, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
Maximum PWM Duty Cycle(1)	D_{MAX}		+25℃		98		%
Boost Mode Operation							
Boost Mode Regulation Voltage	V_{OTG_REG}	V_{BAT} = 3.8V, I_{PMID} = 0A, BOOSTV[1:0] = 10 (5.15V)	Full	5.015	5.185	5.355	V
Boost Mode Regulation Voltage Accuracy	$V_{OTG\_REG\_ACC}$	V_{BAT} = 3.8V, I_{PMID} = 0A, BOOSTV[1:0] = 10 (5.15V)	Full	-3.3		3.3	%
Exit Boost Mode Due to Low Battery Voltage	V_{BATLOW_OTG}	V_{BAT} falling, MIN_BAT_SEL = 0	Full	2.85	2.95	3.05	V
		V_{BAT} rising, MIN_BAT_SEL = 0	Full	3.07	3.15	3.21	
		V_{BAT} falling, MIN_BAT_SEL = 1	Full	2.48	2.6	2.69	
		V_{BAT} rising, MIN_BAT_SEL = 1	Full	2.71	2.8	2.85	
OTG Mode Max Output Current	I_{OTG}	BOOST_LIM = 1 (1.2A)	+25℃	1.2	1.5	1.8	A
OTG Over-Voltage Threshold	V_{OTG_OVP}	Rising threshold	Full	5.89	6.015	6.14	V
HSFET Under-Current Falling Threshold	I_{OTG_HSZCP}	Change rectifier from synchronous mode to non-synchronous mode	+25℃		100		mA
REGN LDO							
REGN LDO Output Voltage	V_{REGN}	V_{VBUS} = 9V, I_{REGN} = 40mA	Full	4.75	5	5.25	V
		V_{VBUS} = 5V, I_{REGN} = 20mA	Full	4.35	4.65	4.95	
Logic I/O Pin Characteristics (nCE, PSEL, SCL, SDA and nINT)							
Input Low Threshold (nCE)	V_{IL}		Full			0.3	V
Input High Threshold (nCE)	V_{IH}		Full	1			V
Input Low Threshold (PSEL, SCL, SDA, nINT)	V_{IL}		Full			0.2	V
Input High Threshold (PSEL, SCL, SDA, nINT)	V_{IH}		Full	1			V
High-Level Leakage Current	I_{BIAS}	Pull up rail 1.8V	Full			1	μA
Logic I/O Pin Characteristics (nPG, STAT) – Open-Drain							
Low-Level Output Voltage	V_{OL}		Full			0.3	V
V_{VBUS}/V_{BAT} Power-Up							
VBUS OVP Reaction Time	t_{ACOV}	V_{VBUS} rising above ACOV threshold to turn off Q2	+25℃		0.1		μs
Wait Window for Bad Adapter Detection	t_{BADSRC}		+25℃		30		ms

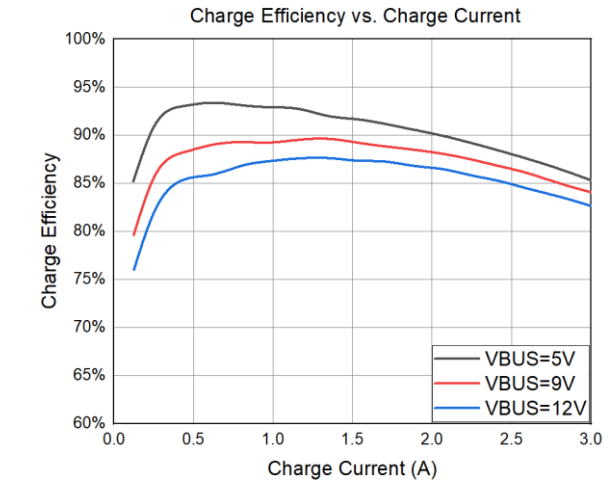
NOTE: 1. Specified by design. Not production tested.

ELECTRICAL CHARACTERISTICS (continued)

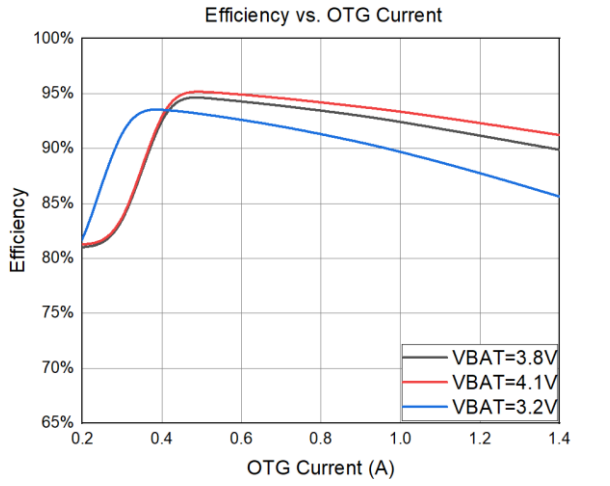
(V_{VAC_UVLOZ}< V_{VAC}< V_{VAC_OV} and V_{VAC}> V_{BAT} + V_{SLEEP}, Full = -40℃ to +85℃, typical values are at T_J = +25℃, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	TEMP	MIN	TYP	MAX	UNITS
Battery Charger							
Deglitch Time for Charge Termination	t_{TERM_DGL}		+25℃		230		ms
Deglitch Time for Recharge	t_{RECHG_DGL}		+25℃		230		ms
System Over-Current Deglitch Time to Turn Off Q4	$t_{SYSOVLD\_DGL}$		+25℃		112		μs
Battery Over-Voltage Deglitch Time to Disable Charge	t_{BATOVP}		+25℃		1		μs
Typical Charge Safety Timer Range	t_{SAFETY}	CHG_TIMER = 1	+25℃	5.4	6	6.4	hr
Typical Top-Off Timer Range	t_{TOP_OFF}	TOP_OFF_TIMER[1:0] = 10 (30min)	+25℃	32	35	39	min
nQON Timing and Ship Mode Timing							
nQON Negative Pulse Low Pulse Width to Turn On BATFET and Exit Ship Mode	$t_{SHIPMODE}$		+25℃	0.9	1	1.2	s
nQON Low Time to Reset BATFET	t_{QON_RST}		+25℃	14	16	20	s
BATFET Off Time during Full System Reset	t_{BATFET_RST}		+25℃	200	250	300	ms
Wait Delay for Entering Ship Mode	t_{SM_DLY}		+25℃	7	8	10	s
Digital Clock and Watchdog Timer							
Watchdog Reset Time	t_{WDT}	WATCHDOG[1:0] = 01, REGN LDO disabled	+25℃		40		s
Digital Clock Frequency in Low Power	f_{LPDIG}	REGN LDO disabled	+25℃		31		kHz
Digital Clock Frequency	f_{DIG}	REGN LDO enabled	+25℃		500		kHz
I2C Interface							
SCL Clock Frequency	f_{SCL}		+25℃		400		kHz

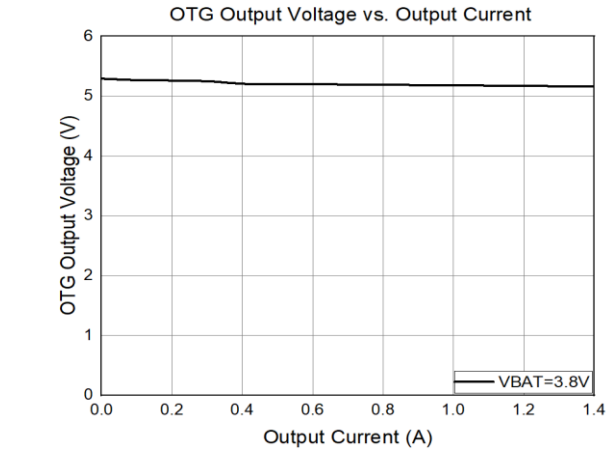
TYPICAL PERFORMANCE CHARACTERISTICS



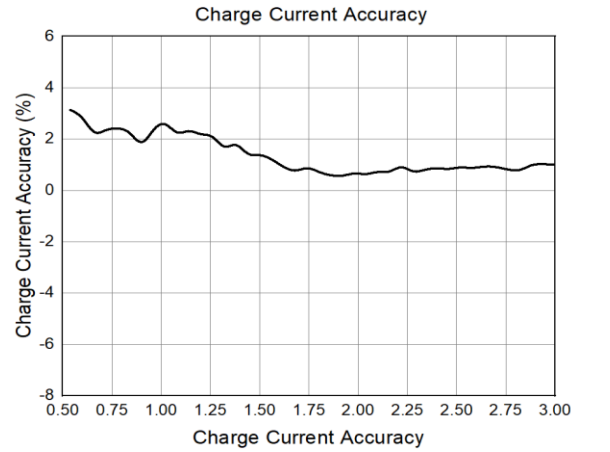
V_{BAT}=3.8V Inductor DCR = 18 mΩ



V_{OTG}=3.8V Inductor DCR = 18 mΩ

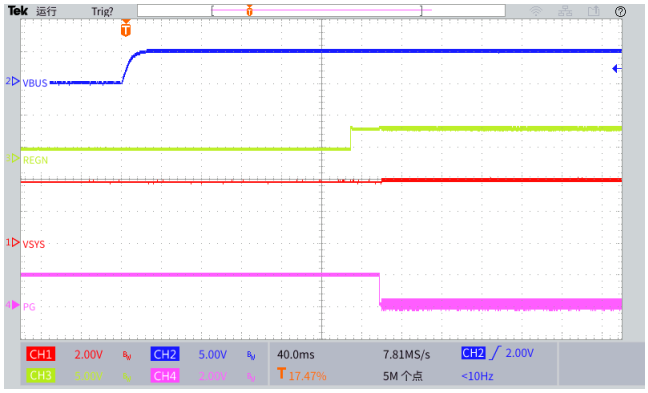


VBAT=3.8V I_{OTG}=0A~1.4A



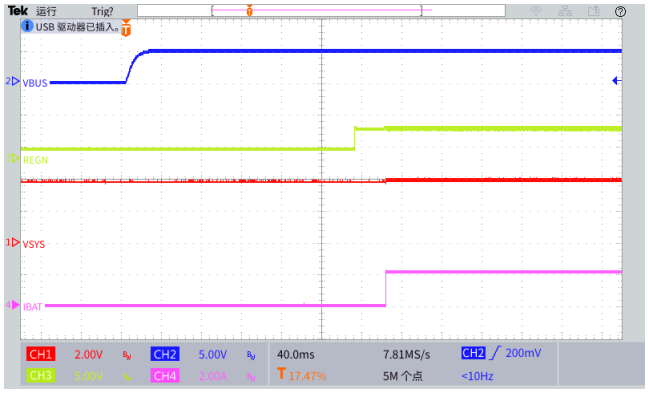
VBAT=3.8V I_{CHG}=0.54A~3A

VBUS Power-Up with Charge Disable



VBAT=3.8V VBUS=5V

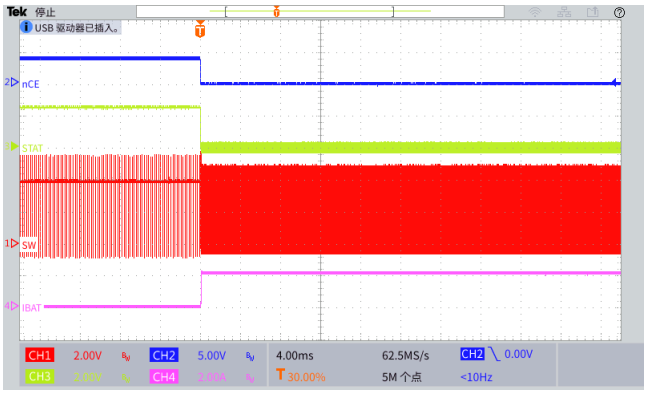
VBAT=3.8V VBUS=5V



VBAT=3.8V VBUS=5V

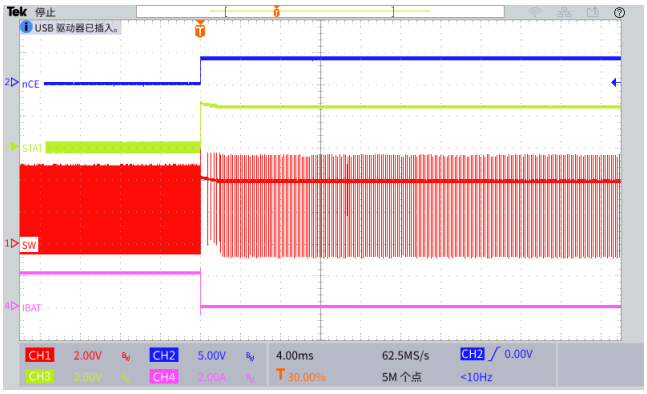
TYPICAL PERFORMANCE CHARACTERISTICS(continued)

Charge Enable



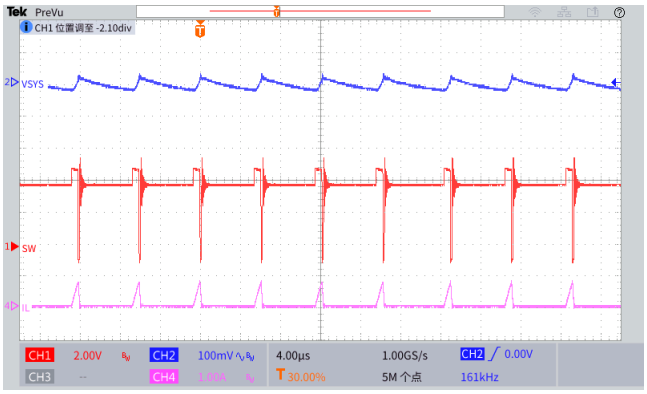
VBAT=3.8V,VBUS=5V,I_{CHG}=2A

Charge Disable



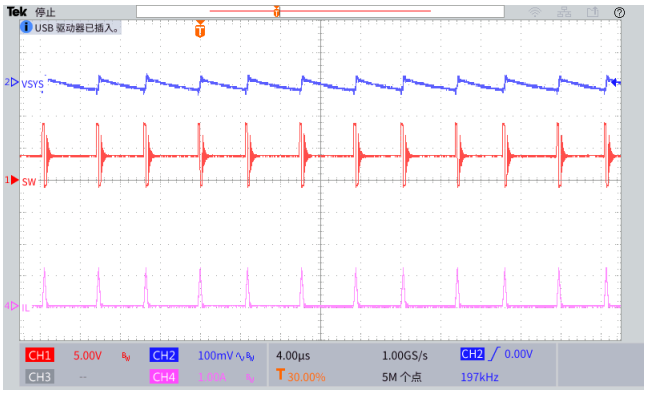
VBAT=3.8V,VBUS=5V,I_{CHG}=2A

PFM Switching in Buck Mode, Charge Disabled



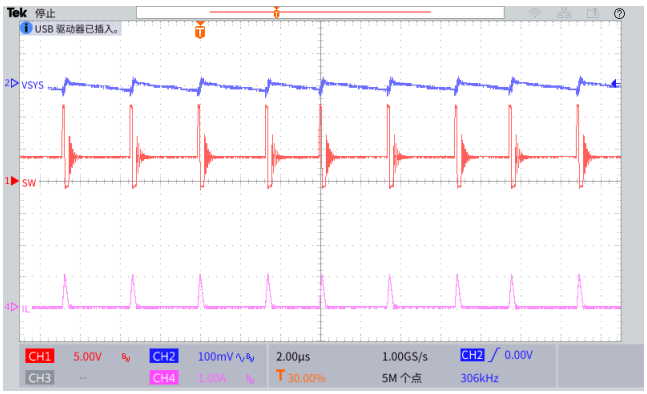
VBUS=5V,VBAT=3.8V,I_{SYS}=50mA

PFM Switching in Buck Mode, Charge Disabled



VBUS=9V,VBAT=3.8V,I_{SYS}=50mA

PFM Switching in Buck Mode, Charge Disabled



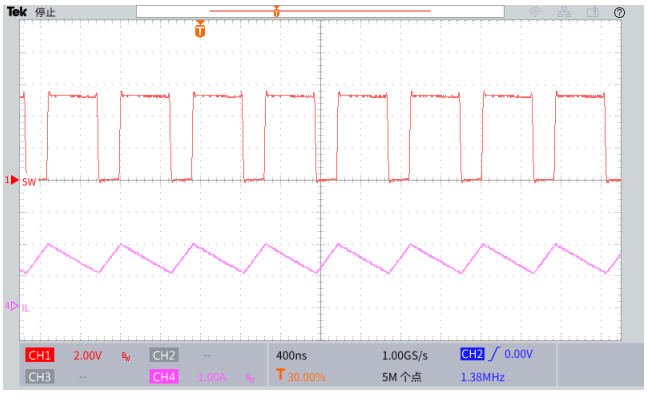
VBUS=12V,V_{BAT}=3.8V,I_{SYS}=50mA

OTG Switching (Boost Mode)

VBAT= 4V, I_{LOAD} = 50mA, PFM Enable

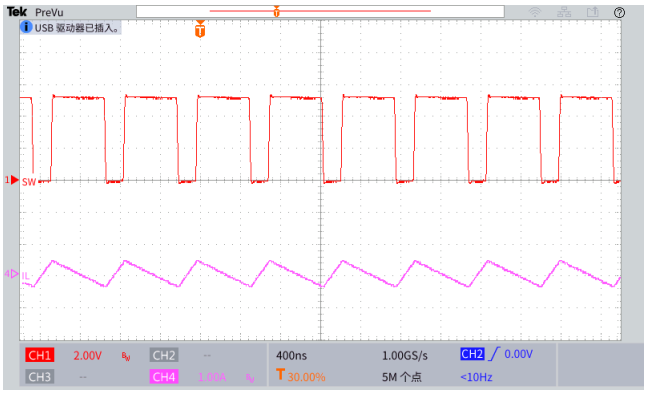
TYPICAL PERFORMANCE CHARACTERISTICS(continued)

OTG Switching (Boost Mode)



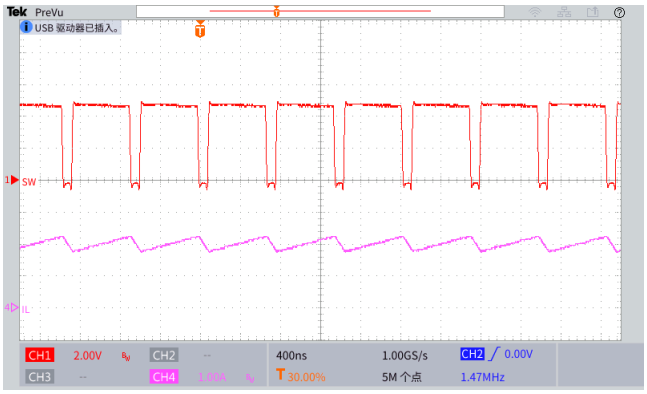
VBAT= 4V, I_{LOAD} = 1A, PWM

OTG Switching (Boost Mode)



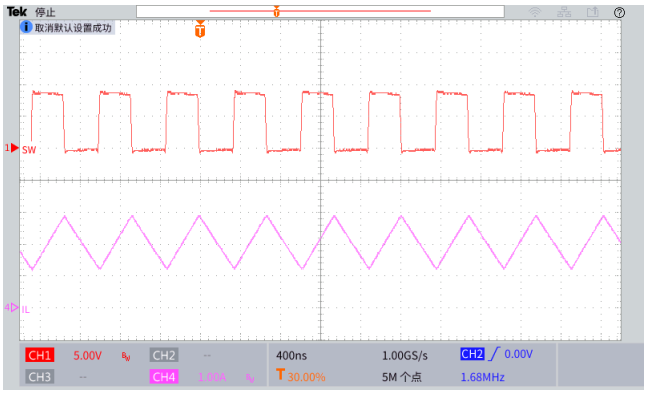
VBAT = 4V, I_{LOAD} = 0A, PWM

PWM Switching in Buck Mode (L = 1μH)



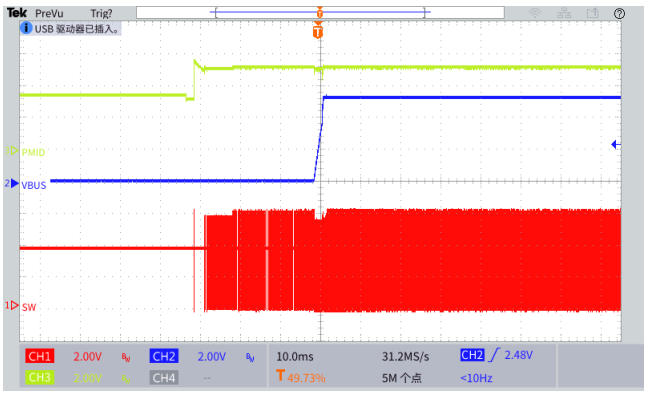
VBUS = 5V, VBAT= 3.8V, I_{CHG} = 2A

PWM Switching in Buck Mode (L = 1μH)



VBUS = 9V, VBAT = 3.8V, I_{CHG} = 2A

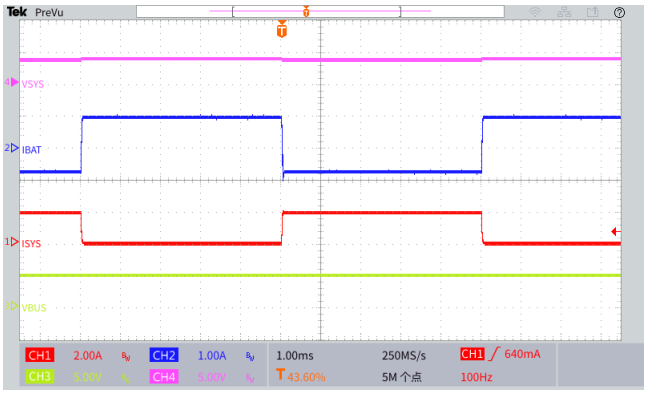
OTG Start-Up



VBAT = 3.8V, C_{BUS} = 470μF

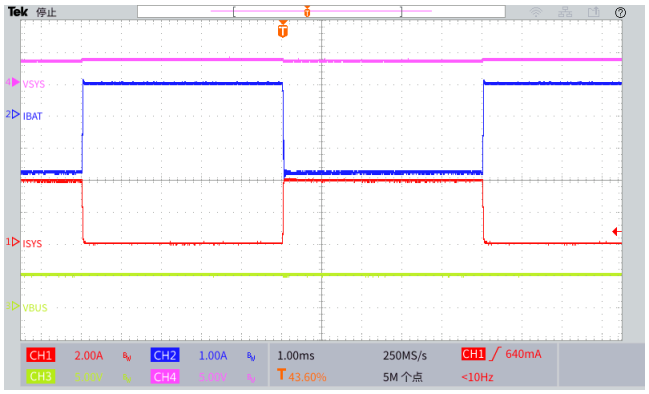
TYPICAL PERFORMANCE CHARACTERISTICS(continued)

System Load Transient

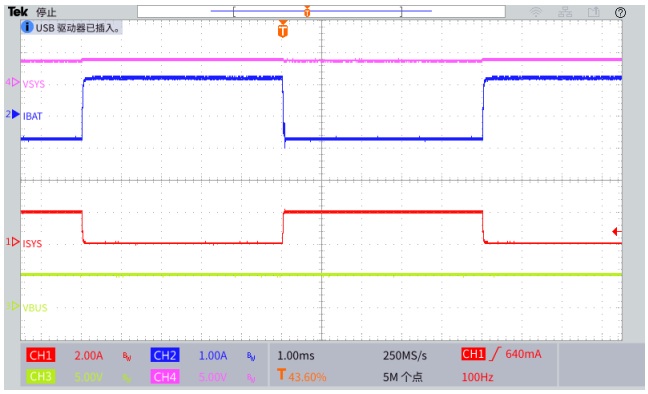


VBUS = 5V, I_{INDPM} = 1A, I_{CHG} = 1A
VBAT = 3.7V, I_{SYS} = 0A to 2A

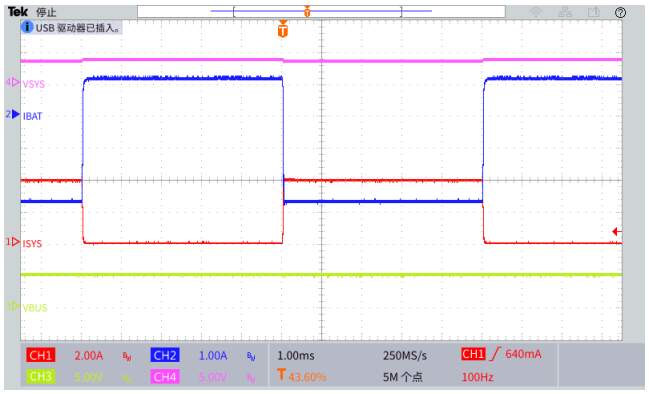
System Load Transient



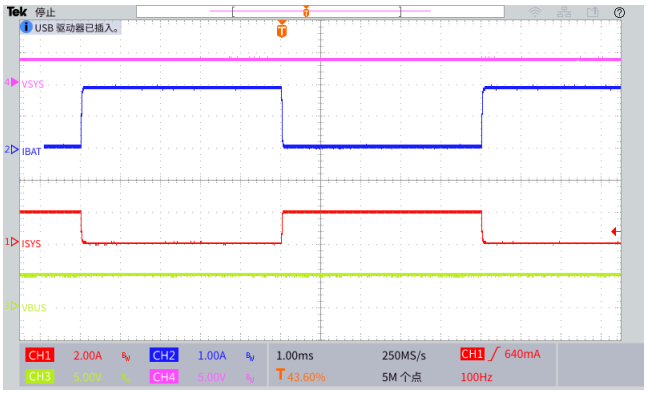
VBUS = 5V, I_{INDPM} = 1A, I_{CHG} = 1A
VBAT = 3.7V, I_{SYS} = 0A to 4A



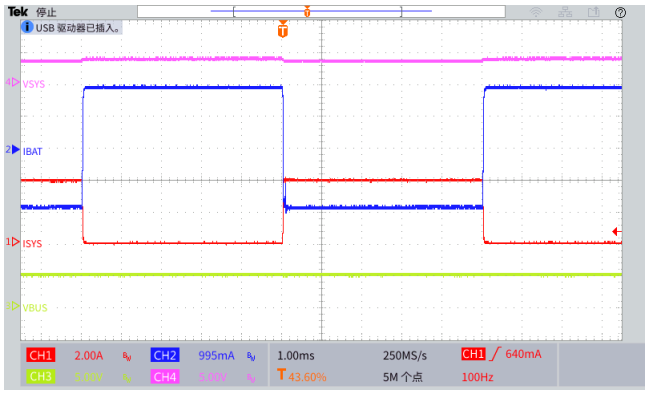
VBUS = 5V, I_{INDPM} = 1A, I_{CHG} = 2A
VBAT = 3.7V, I_{SYS} = 0A to 2A



VBUS = 5V, I_{INDPM} = 1A, I_{CHG} = 2A
VBAT = 3.7V, I_{SYS} = 0A to 4A



VBUS = 5V, I_{INDPM} = 2A, I_{CHG} = 2A
VBAT = 3.7V, I_{SYS} = 0A to 2A



VBUS = 5V, I_{INDPM} = 2A, I_{CHG} = 2A
VBAT = 3.7V, I_{SYS} = 0A to 4A

FUNCTIONAL DESCRIPTION

The BCT2601 is a power management and charger device for application such as cell phones and tablets that use high capacity single-cell Li-Ion or Li-polymer batteries. The BCT2601 can accommodate a wide range of input sources including USB, wall adapter and car chargers. It is optimized for 5V input (USB voltage) but is capable to operate with input voltages from 3.9V up to 13.5V. It also supports JEITA profile for battery charging safety at high or low temperatures. Automatic power path selection to power the system (SYS) from the input source (VBUS), battery (BAT), or both, is another feature of the device. Battery charge current is programmable and can reach to a maximum of 3A (charge). In the boost mode the battery voltage is boosted to power the VBUS pin (1.2A MAX) when it is a power receiving node (USB OTG) that is typically regulated to 5.15V.

The device may operate in several different modes:

In HIZ mode, the VBUS and input source are disconnected from power circuit by turning the reverse blocking FET (Q1) off. In this mode, internal REGN LDO, converter switches and some other parts of the internal circuit remain off to save the battery while it is supplying DC power to the system through BATFET.

In the sleep mode the switching is stopped. The charger goes to the sleep mode when the input source voltage (V_{VAC}) is not high enough for charging the battery. In other words, V_{VAC} is smaller than VBAT + V_{SLEEP} (where V_{SLEEP} is a small threshold) and buck converter is not able to charge, even at its maximum duty cycle. The boost may also go to the sleep mode if similar issue happens in the reverse direction (when VVAC is almost equal or smaller than VBAT).

In supplement mode, the input source power is not enough to supply system demanded power and the battery assists by discharging to the system in parallel, providing the deficit.

Power-On-Reset (POR)

The internal circuit of the device is powered from the greater voltage between V_{VBUS} and V_{BAT}. When the voltage of the selected source goes above its UVLO level (V_{VBUS}> V_{VBUS_UVLOZ} or V_{BAT} > V_{BAT_UVLOZ}) a POR happens and activates the sleep comparator, battery depletion comparator and BATFET driver. Upon activation, the I²C interface will also be ready for communication and all registers reset to their default values.

Power-Up from Battery Only (No Input Source)

When only the battery is present as a source and its voltage is above depletion threshold ($V_{BAT\_DPL\_RISE}$), the BATFET turns on and connects the battery to the system. The quiescent current is minimum because the REGN LDO remains off. Conduction losses are also low due to small RDSON of BATFET. Low losses help extending the battery run time.

The discharge current through BATFET is continuously monitored. In the supplement mode, if a system overload (or short) occurs (I_{BAT}> I_{BATFET_OCP}), the BATFET is turned off immediately and BATFET_DIS bit is set to 1. The BATFET will not enable until the input source is applied or one of the BATFET Enable Mode (Exit Ship Mode) methods (explained later) is used to activate the BATFET.

Power-Up Process from the Input Source

Upon connection of an input source (VBUS), its voltage sensed from VAC pin is checked to turn on the internal REGN LDO regulator and the bias circuits (no matter if the battery is present or not). The input current limit is determined and set before the buck converter is started. The sequence of actions when VBUS as input source is powered up are:

1. REGN LDO Power-up.
2. Poor source detection (qualification).
3. Input source type detection. (Based on PSEL input. It is used to set the default input current limit

4. Setting of the input voltage limit threshold (VINDPM threshold).
5. DC/DC converter power-up.

REGN LDO Power-Up

The REGN low dropout regulator powers the internal bias circuits, HSFET and LSFET gate drivers and TS rail (thermistor pin). The STAT pin can also be pulled up to REGN. The REGN enables when the following 2 conditions are satisfied and remain valid for a 220ms delay time, otherwise the device stays in high impedance mode (HIZ) with REGN LDO off.

1.V_{VAC}> $V_{VAC\_PRESENT}$.

2.V_{VAC}> VBAT + V_{SLEEPZ} (in buck mode) or V_{VBUS}< VBAT + V_{SLEEP} (in boost mode).

In HIZ state, the VBUS source is disconnected (reverse blocking FET or Q1 is turned off) and the quiescent current drawn from VBUS is very small (less than I_{VBUS_HIZ}). System is only powered by the battery in HIZ mode.

Poor Source Detection (Qualification)

When REGN LDO is powered, the input source (adaptor) is checked for its type and current capacity. To start the buck converter, the input (VBUS) must meet the following:

1.V_{VBUS}< V_{VAC_OV}.

2.V_{VBUS}> V_{VBUS_MIN} during t_{BADSRC} test period (30ms TYP) in which the I_{BAD_SRC} (30mA TYP) current is pulled from VBUS.

If the test is failed, the conditions are repeatedly checked every two seconds. As soon as the input source passes qualification, the V_{BUS_GD} bit in status register is set to 1 and a pulse is sent to the nINT pin to inform the host. Type detection will start as next step.

Input Source Type Detection

The input source detection will run through the PSEL pin while REGN LDO is powered and after the V_{BUS_GD} bit is set. The input current limit of the BCT2601 is sets based on the state of PSEL pin. A pulse is sent to nINT pin to inform the host when the input source type detection is completed.

Some registers and pins are also updated as detailed below:

1.Input current limit register (the value in the IINDPM[4:0]) is changed to set current limit.

2.PG_STAT (power good) bit is set.

3.VBUS_STAT[2:0] register is updated to indicate USB or adaptor input source types.

The input current is always limited by the IINDPM[4:0] register and the limit can be updated by the host if needed.

Input Current Limit by PSEL

PSEL pin interfaces with USB physical layer (PHY) for input current limit setting. The USB PHY device output is used to detect if the input is a USB host or a charging port. In the host-control mode, the host must enable IINDET_EN bit for reading the PSEL value and updating the IINDPM[4:0]. In the default mode, IINDPM[4:0] is updated automatically by PSEL value in real time as given in Table 1.

Table 1. Input Current Limit Setting from PSEL

Input Detection	PSEL Pin	Input Current Limit (I_{LIM})	VBUS_STAT[2:0]
USB Host SDP	High	500mA	001
Adapter	Low	2400mA	010

Setting of the Input Voltage Limit Threshold (VINDPMThreshold)

A wide voltage range (3.9V to 5.4V) is supported for the input voltage limit setting in VINDPM[3:0]. 4.5V is

the default for USB.The device supports dynamic tracking of the battery voltage (VINDPM). VDPM_BAT_TRACK[1:0] bits can be used to enable tracking (00 to disable tracking) and set the tracking offset value. When the tracking is enabled, the input voltage limit will be set to the larger value between the VINDPM[3:0] and VBAT + VDPM_BAT_TRACK[1:0]. The VDPM_BAT_TRACK[1:0]tracking offset can be set to 200mV, 250mV or 300mV.

DC/DC Converter Power-Up

The 1.5MHz switching converter composed of LSFET and HSFET is enabled and can start switching when the input current limit is set. Converter is initiated with a soft start when the system voltage is ramped up. The input current is limited to 200mA or IINDPM[4:0], whichever is smaller, if SYS voltage is less than 2.2V, otherwise the limit is set to IINDPM[4:0].

The BATFET remains on to charge the battery if the battery charging function is enabled, otherwise BATFET turns off.

When converter operates for battery charging, it acts as an efficient, fixed frequency synchronous buck converter regardless of the input/output voltages and currents. However, it is capable to switch to PFM mode at light load when charging is disabled or when the detected battery voltage is less than minimum system voltage setting. PFM operation can be enabled or prevented in either buck or boost mode using the PFM_DIS bit.

Boost Mode

The BCT2601 supports USB On-The-Go. When a load device is connected to the USB port, the converter can operate as a step-up synchronous converter (boost mode) with 1.5MHz switching frequency to supply power from the battery to that load. The 500mA USB OTG output current limit requirement is applicable by programming, however the boost converter can deliver 1.2A to the output (default limit). Converter will set to boost mode if at least 30ms is passed from enabling this mode (OTG_CONFIG bit = 1) and the following conditions are satisfied:

1. VBAT > V_{BATLOW_OTG}.
2. V_{VBUS}< VBAT + V_{SLEEP} (in sleep mode).
3. Voltage at TS (thermistor) pin is within acceptable range (V_{BHOT}< V_{TS}< V_{BCOLD}).

The output voltage is set to V_{VBUS} = 5.15V and is maintained as long as VBAT is above V_{BATLOW_OTG}. The output current can reach up to the programmed value by BOOST_LIM bit (0.5A or 1.2A). The VBUS_STAT[2:0] status register bits are set to 111 in boost mode (OTG).

To minimize the output overshoot in boost mode, the device starts with PFM first and then switches to PWM. As stated before, PFM can be avoided using PFM_DIS bit in buck and boost modes.

Host Mode and Default Mode Operation with the Watchdog Timer

After a power on reset, the device starts in default mode (standalone) with all registers reset as if the watchdog timer is expired. When the host is in sleep mode or there is no host, the device stays in the default mode in which the BCT2601 operates like an autonomous charger. The battery is charged for 6 hours (default value for the fast charging safety timer). Then the charge stops while buck converter continues to operate to power the system load. In this mode the PSEL pin directly affects the IINDPM[4:0] register in real time and WATCHDOG_FAULT bit is high.

Most of the flexibility features of the BCT2601 become available in the host mode when the device is controlled by a host with I2C. By setting the WD_RST bit to 1, the charger mode changes from default mode to host mode. In this mode the WATCHDOG_FAULT bit is low and all device parameters can be programmed by the host. To prevent device watchdog reset that results in going back to default mode, the host must either disable the watchdog timer by setting WATCHDOG[1:0]= 00, or it must consistently reset the watchdog timer before expiry by writing 1 to WD_RST to prevent WATCHDOG_FAULT bit to be set.

Every time a 1 is written to the WD_RST, the watchdog timer will restart counting. Therefore, it should be reset again before overflow (expiry) to keep the device in the host mode. If the watchdog timer expires (WATCHDOG_FAULT bit = 1), the device returns to default mode and all registers are reset to their default values except for IINDPM[4:0], VINDPM[3:0],BATFET_RST_EN,BATFET_DLY and BATFET_DIS bits that keep their values unchanged.

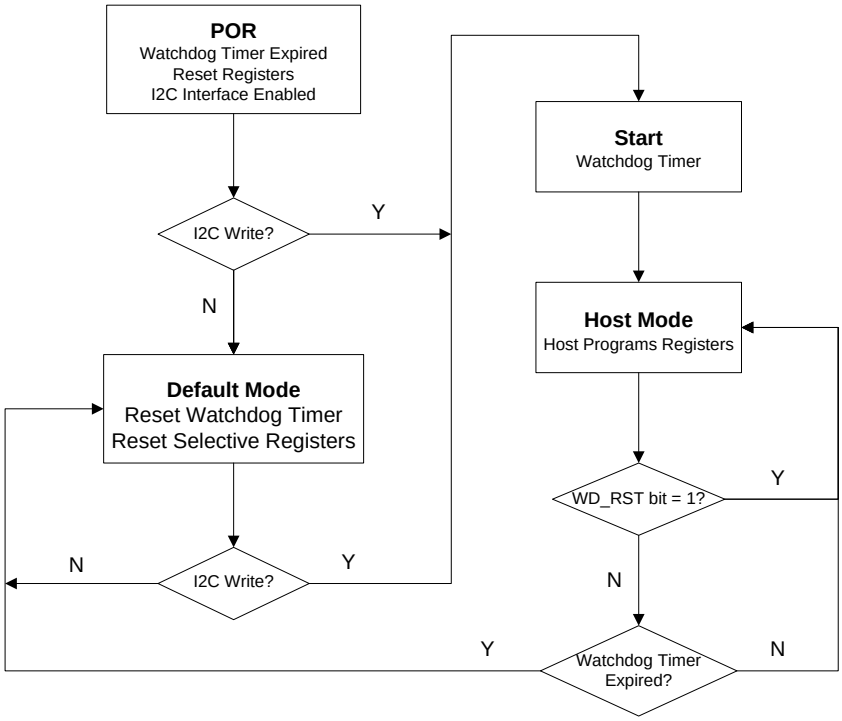


Figure 3. Watchdog Timer Flow Chart

Battery Charging Management

The BCT2601 is designed for charging single-cell Li-Ion or Li-poly batteries with a charge current up to 3A max. The battery connection switch (BATFET) is in the charge or discharge current path features low on-resistance (28mΩ) to allow high efficiency and low voltage drop.

Charging Cycle in Autonomous Mode

Charging is enabled if CHG_CONFIG = 1 and nCE pin is pulled low. In default mode, the BCT2601 runs a charge cycle with the default parameters itemized in Table 2. At any moment, the control can be taken by a host by changing to the host mode.

Table 2. Charging Parameter Default Setting

Default Mode	BCT2601
Charging Voltage (V_{REG})	4.208V
Charging Current (I_{CHG_REG})	2.04A
Pre-Charge Current	180mA
Termination Current (I_{TERM})	180mA
Temperature Profile	JEITA
Safety Timer	6 hours

Start a New Charging Cycle

If the converter can start switching and all the following conditions are satisfied a new charge cycle starts:

- NTC temperature fault is not asserted (TS pin).
- Safety timer fault is not asserted.
- BATFET is not forced off. (BATFET_DIS bit = 0).
- Charging enabled (CHG_CONFIG bit = 1, I_{CHG}[5:0] register is not 0mA and nCE pin is low).
- Battery voltage is below the programmed full charge level (V_{REG}).

A new charge cycle starts automatically if battery voltage falls below the recharge threshold level (V_{REG} - 100mV or V_{REG} - 200mV configured by V_{RECHG} bit). Also, if the charge cycle is completed, a new charging cycle can be initiated by toggling of the nCE pin or CHG_CONFIG bit.

Normally a charge cycle terminates when the charge voltage is above the recharge threshold level and the charging current falls below the termination threshold if the device is not in thermal regulation or Dynamic Power Management (DPM) mode.

Charge Status Report

STAT is an open-drain output pin that reports the status of charge and can drive an LED for indication: a low indicates charging is in progress, a high shows charging is completed or disabled and alternating low/high (blinking) shows a charging fault. The STAT may be disabled (keep the open drain switch off) by setting EN_ICHG_MON[1:0] = 11.

The CHRG_STAT[1:0] status register reports the present charging phase and status by two bits: 00 = charging disabled, 01 = in pre-charge, 10 = in fast charging (constant current mode or constant voltage mode) and 11 = charging completed.

A negative pulse is sent on nINT pin to inform the host when a charging cycle is completed.

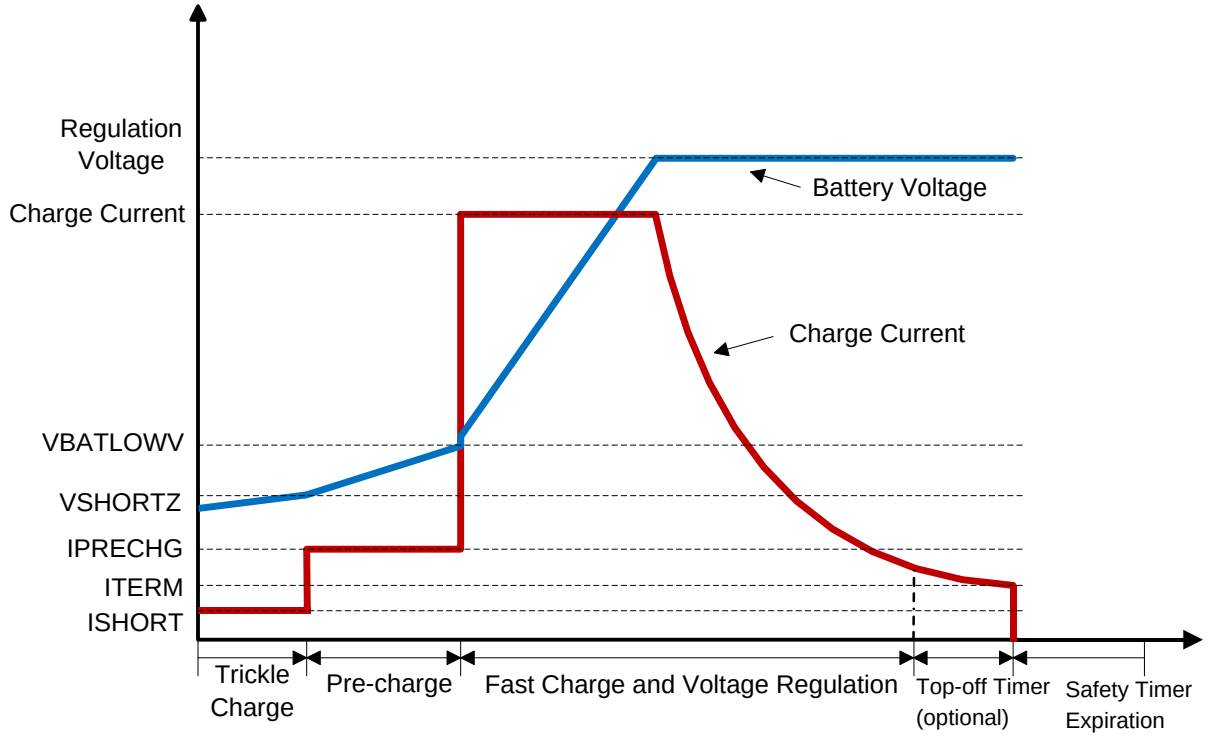
Battery Charging Profile

The BCT2601 features a full battery charging profile with five phases. In the beginning of the cycle the battery voltage (VBAT) is tested, and appropriate current and voltage regulation levels are selected as shown in Table 3. Depending on the detected status of the battery, the proper phase is selected to start or for continuation of the charging cycle. The phases are: battery short (battery voltage too low), preconditioning, constant current, constant voltage and an optional top-off trickle charging phase.

Table 3. Charging Current Setting Based on VBAT

VBAT	Selected Charging Current	Default Value in the Register	CHRG_STAT[1:0]
< 2.2V	I_{SHORT}	80mA	1
2.2V to 3V	I_{PRECHG}	180mA	1
> 3V	I_{CHG}	2.048A	10

Note that in the DPM or thermal regulation modes, normal charging functions are temporarily modified: The charge current will be less than the value in the register; termination is disabled, and the charging safety timer is slowed down by counting at half clock rate.Figure 4. Battery Charging Profile



Termination

A charge cycle is terminated when the battery voltage is above the recharge threshold and the current falls below the programmed termination current. Unless there is a high power demand for system and need to operate in supplement mode, the BATFET turns off at the end of the charge cycle. Even after termination, the buck converter continues to operate to supply power to the system.CHRG_STAT[1:0] is set to 11 and a negative pulse is sent to nINT pint after termination.

If the charger is regulating input current or voltage or junction temperature instead of charge current, termination will temporarily prevent. EN_TERM bit is termination control bit and can be set to 0 to disable termination before it happens. At low termination currents (60mA TYP), the offset in the internal comparator may give rise to a higher(+10mA to +20mA) actual termination current. A delay in termination can be added (optional) as a compensation for comparator offset using a programmable top-off timer.

During the delay, constant voltage charge phase continues and gives the falling charge current the chance to drop closer to the programmed value. The top-off delay timer has the same restrictions of the safety timer. As an example, if under some conditions the safety timer is suspended, the top-off timer will also suspend or if the safety timer is slowed down, the termination timer will also slow down. The TOPOFF_ACTIVE bit reports the active/not active status of the top-off timer. The CHRG_STAT[1:0] and TOPOFF_ACTIVE bits can be read to find status of the termination.

Any of the following events resets the Top-off timer:

1. Disable to enable transition of nCE (charge enable).
2. A low to high change in the status of termination.
3. Set REG_RST bit to 1.

The setting of the top-off timer are applied at the time of termination detection and unless a new charge cycle is started, modifying the top-off timer parameters after termination has no effect. A negative pulse is sent to nINT when top-off timer is started or ended.

Temperature Qualification

The charging current and voltage of the battery must be limited when battery is cold or hot. A thermistor input for battery temperature monitoring is included in the device that can protect the battery based on JEITA guidelines. There is no battery temperature protection when battery is discharging to the system (either boosting or not charging).

Compliance with JEITA Guideline

JEITA guideline (April 20, 2007 release) is implemented in the device for safe charging of the Li-Ion battery. JEITA highlights the considerations and limits that should to be considered for charging at cold or hot battery temperatures. High charge current and voltage must be avoided outside normal operating temperatures (typically 0℃ and 60℃). This functionality can be disabled if not needed.Four temperatures levels are defined by JEITA from T1 (minimum) to T4 (maximum). Outside this range charging should be stopped. The corresponding voltages sensed by NTC are named V_{T1} to V_{T4}. Due to the sensor negative resistance, a higher temperature results in a lower voltage on TS pin. The battery cool range is between T1 - T2 and the warm range is between T3 - T4. Charge must be limited in the cool and warm ranges.One of the conditions for starting a charge cycle is having the TS voltage within V_{T1} to V_{T4} window limits. If during the charge, battery gets too cold or too hot and TS voltage exceeds the T1 - T4 limits, charging is suspended (zero charge current) and the controller waits for the battery temperature to come back within the T1 to T4 window.JEITA recommends to reduce charge current to 1/2 of fast charging current or lower at cool temperatures (T1 - T2). For warmer temperature (within T3 - T4 range), charge voltage is recommended to be kept below 4.1V.The BCT2601 exceeds the JEITA requirement by its flexible charge parameter settings. At warm temperature range (T3 - T4) the charge voltage can be set to VREG or 4.1V using the JEITA_VSET bit. At cool temperatures (T1 - T2), the current setting can be reduced down to 50% or 20% of fast charging current selectable by the JEITA_ISET bit.

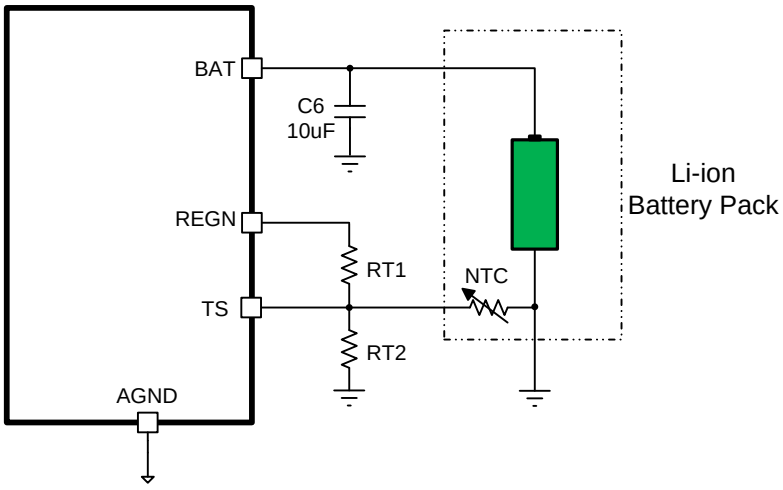


Figure 5. Battery Thermistor Connection and Bias Network

A 103AT-2 type thermistor is recommended for use with the BCT2601. Other thermistors may be used and bias network (Figure 5) can be calculated based on the following equations:

$$R_{T2} = \frac{V_{REGN} \times R_{THCOLD} \times R_{THHOT} \times \left(\frac{1}{V_{T1}} - \frac{1}{V_{T4}}\right)}{R_{THHOT} \times \left(\frac{V_{REGN}}{V_{T4}} - 1\right) - R_{THCOLD} \times \left(\frac{V_{REGN}}{V_{T1}} - 1\right)}$$

$$R_{T1} = \frac{\left(\frac{V_{REGN}}{V_{T1}} - 1\right)}{\left(\frac{1}{R_{T2}}\right) + \left(\frac{1}{R_{THCOLD}}\right)}$$

Where V_{T1}, V_{T4} and V_{REGN} are characteristics of the device and $R_{THCOLD}$and R_{THHOT} are thermistor resistances (RTH) at desired T_1 (Cold) and T_4 (Hot) temperatures. Select T_{COLD} = 0℃,T_{HOT} = 60℃for Li-Ion or Li-polymer batteries. For a 103AT-2 type thermistor R_{THCOLD} = 27.28kΩ,R_{THHOT} =3.02kΩthat results in:

R_{T1}= 5.23kΩ

R_{T2}= 30.1kΩ

Boost Mode Temperature Monitoring (Battery Discharge)

The device is capable to monitor the battery temperature for safety during the boost mode. The temperature must remain within the VBCOLD to VBHOT thresholds otherwise the boost mode will suspend and VBUS_STAT[2:0] bits are set to 000. Moreover NTC_FAULT[2:0] register is updated to report boost mode cold or hot condition. Once the temperature returns within the window, the boost mode is resumed and NTC_FAULT[2:0] register is cleared to 000 (normal).

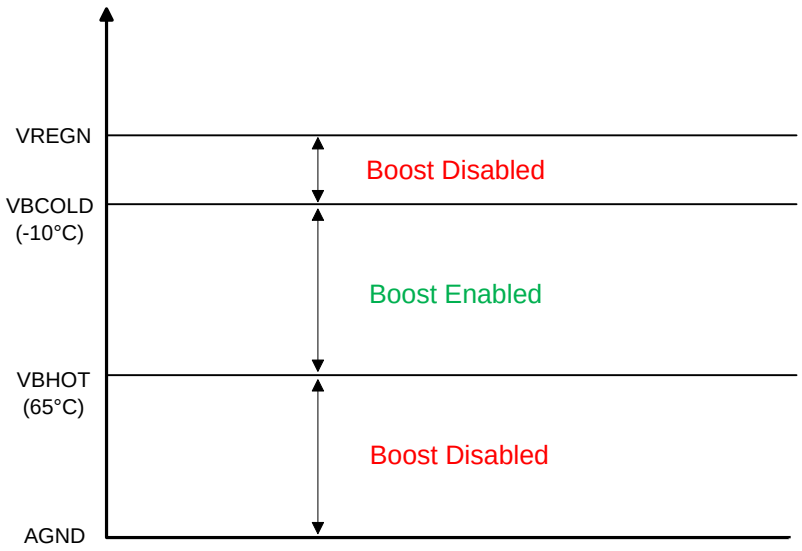


Figure 6. TS Pin Thermistor Temperature Window Settings in Boost Mode

Safety Timer

Abnormal battery conditions may result in prolonged charge cycles. An internal safety timer is considered to stop charging in such conditions. If the safety time is expired, CHRG_FAULT[1:0] bits are set to 11 and a negative pulse is sent to nINT pin. By default the charge time limit is 2 hours if the battery voltage does not rise above V_{BATLOW} threshold and 6 hours if it goes above V_{BATLOW}. This feature is optional and can be disabled by clearing EN_TIMER bit. The 6 hours limit can also be reduced to 4 hours by clearing CHG_TIMER bit.

The safety timer counts at half clock rate when charger is running under input voltage regulation, input current regulation, JEITA cool or thermal regulation because in these conditions, the actual charge current is likely to be less than the register setting. As an example, if the safety timer is set to 4 hours and the charger is regulating the input current (IINDPM_STAT bit = 1) in the whole charging cycle, the actual safety time will be 8 hours. Clearing the TMR2X_EN bit will disable the half clock rate feature.

The safety timer is paused if a fault occurs and charging is suspended. It will resume once the fault condition is removed. If charging cycle is stopped by a restart or by toggling nCE pin or CHG_CONFIG bit, the timer resets and restarts a new timing.

Narrow Voltage DC (NVDC) Design in BCT2601

The BCT2601 features an NVDC design using the BATFET that connects the system and battery. By using the linear region of the BATFET the charger regulates the system bus voltage (SYS pin) above the minimum setting using buck converter even if the battery voltage is very low. MOSFET linear mode allows for the large voltage difference between SYS and BAT pins to appear as V_{DS} across the switch while conducting and charging battery. SYS_MIN[2:0] register sets the minimum system voltage (default 3.5V). If the system is in minimum system voltage regulation, VSYS_STAT bit is set.

The BATFET operates in linear region when the battery voltage is below the minimum system voltage setting. The system voltage is regulated to 180mV (TYP) above the minimum system voltage setting. The battery gradually gets charged and its voltage rises above the minimum system voltage and lets BATFET to change from linear mode to fully turned-on switch such that the voltage difference between the system and battery is the small V_{DS} of fully on BATFET.

The system voltage is always regulated to 50mV (TYP) above the battery voltage If:

1) The charging is terminated or

2) Charging is disabled and the battery voltage is above the minimum system voltage setting.

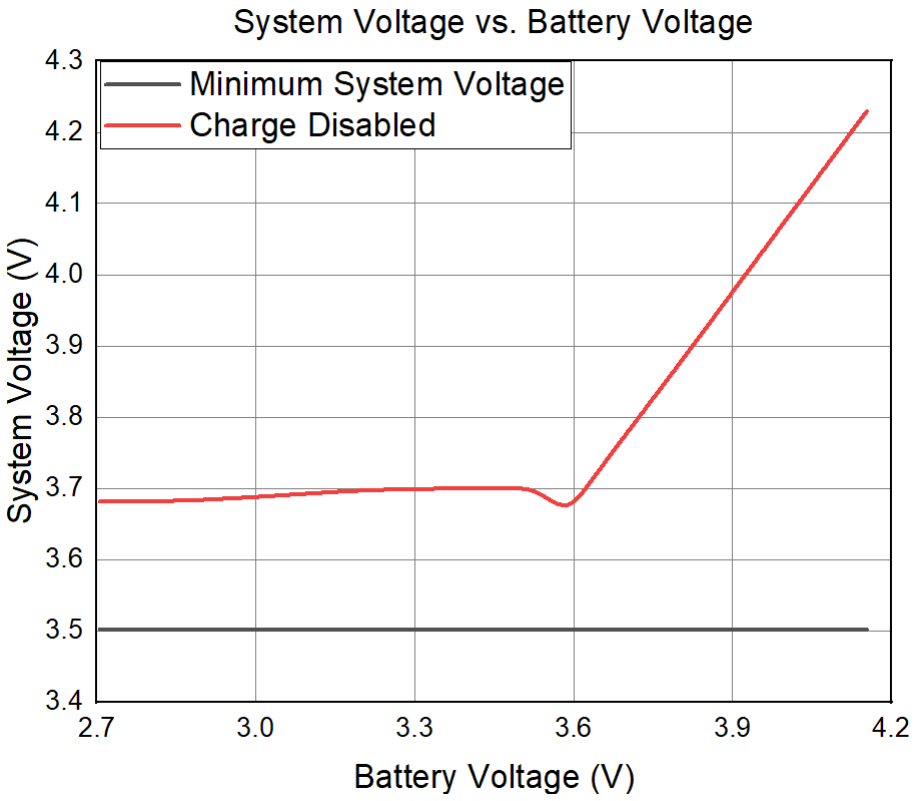


Figure 7. System Voltage vs. Battery Voltage

BCT2601 Dynamic Power Management (DPM)

The BCT2601 features a dynamic power management (DPM). To implement DPM the device always monitors the input current and voltage to regulate power demand from the source and avoid input adapter overloading or to meet the maximum current limits specified in the USB specs. Overloading an input source may result in either current trying to exceed the input current limit (I_{INDPM}) or the voltage tending to fall below the input voltage limit (V_{INDPM}). With DPM, the device keeps the V_{SYS} regulated to its minimum setting by reducing the battery charge current adequately such that the input parameter (voltage or current) does not exceed the limit. In other words, charge current is reduce to satisfy $I_{IN} \leq I_{INDPM}$ or $V_{IN} \geq V_{INDPM}$ whichever occurs first. DPM can be either an I_{IN} type (I_{INDPM}) or V_{IN} type (V_{INDPM}) depending on which limit is reached.

Changing to the supplement mode may be required if the charge current is decreased and reached to zero, but the input is still overloaded. In this case the charger reduces the system voltage below the battery voltage to allow operation in the supplement mode and provide a portion of system power demand from the battery through the BATFET.

The IINDPM_STAT or VINDPM_STAT status bits are set during an I_{INDPM} or V_{INDPM} respectively. Figure 8 summarizes the DPM behavior (I_{INDPM} type) for a design example with a 9V/1.2A adapter, 3.2V battery, 2.8A charge current setting and 3.4V minimum system voltage setting.

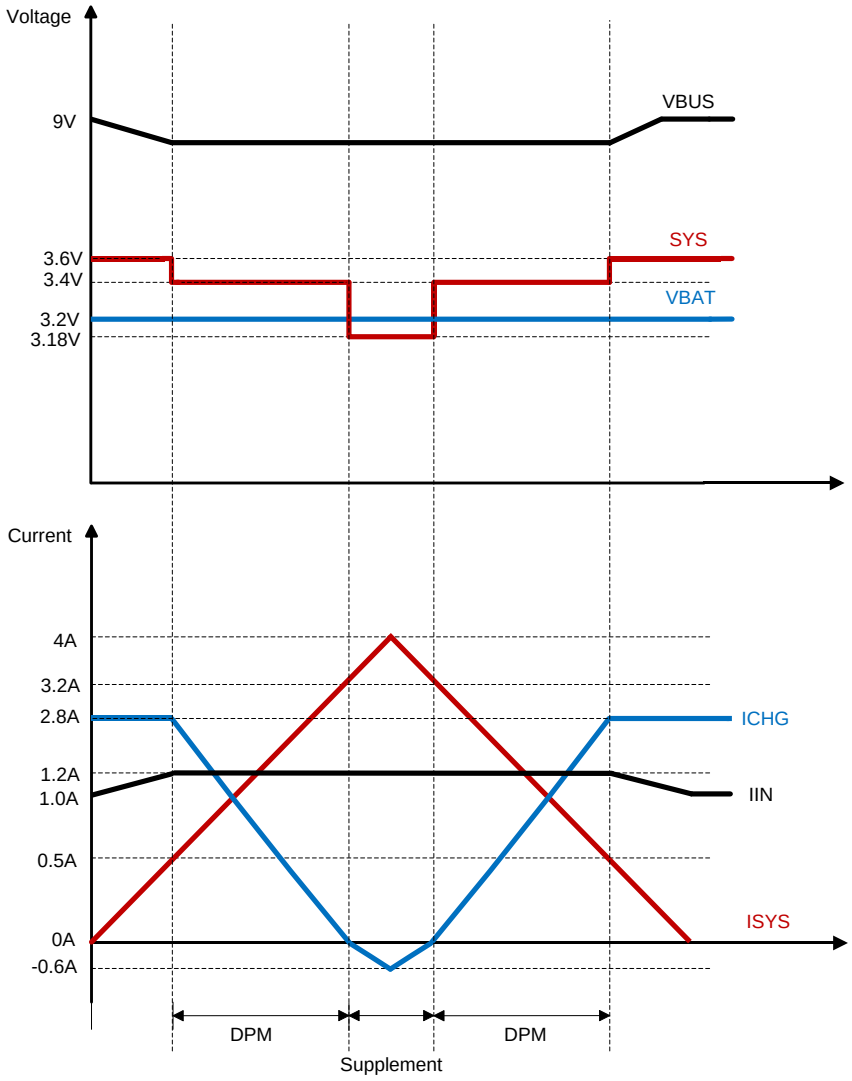


Figure 8. Input, Battery and System Voltage and Currents in DPM

Supplement Mode

If the system voltage drops below the battery voltage, the BATFET gradually starts to turn on. The threshold margin is 180mV if V_{SYS_MIN} setting is less than VBAT and 45mV if V_{SYS_MIN} setting is larger than VBAT. At low discharge currents, the BATFET gate voltage is regulated (R_{DS} modulation) such that the BATFET V_{DS} stays at 30mV. At higher currents, the BATFET will turn fully on (reaching its lowest R_{DSON}). From this point, increasing the discharge current will linearly increase the BATFET V_{DS} (determined by $R_{DSON} \times I_D$). Use of the MOSFET linear mode at lower currents prevents swinging oscillation of entering and exiting the supplement mode.

BATFET gate regulation V-I characteristics is shown in Figure9. If the battery voltage falls below its minimum depletion, the BATFET turns off and exits supplement mode.

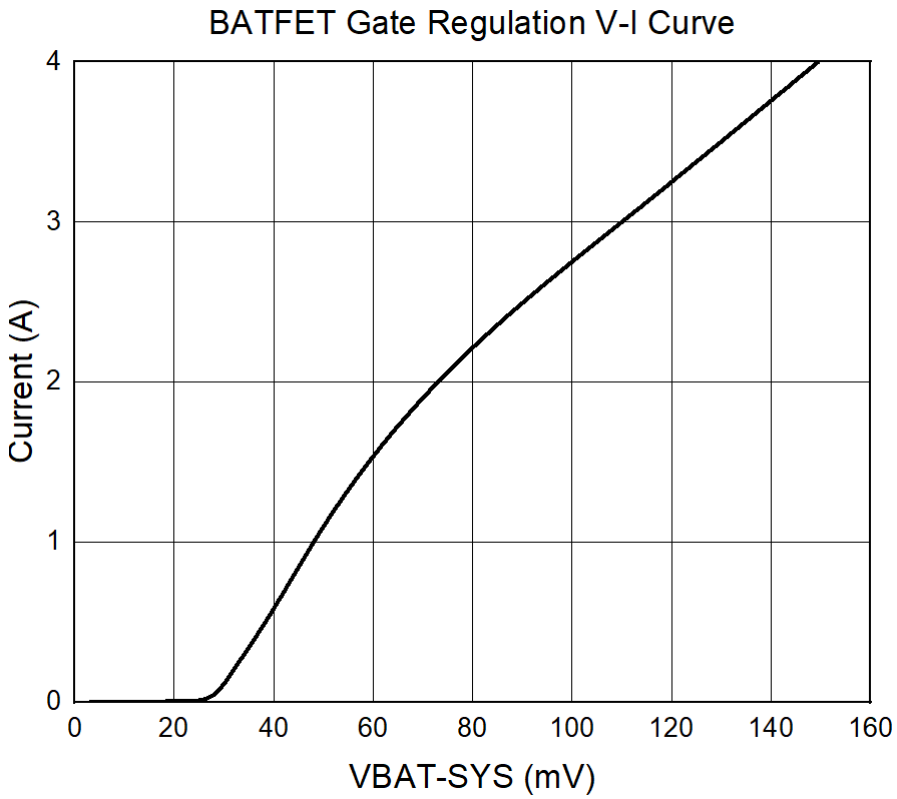


Figure 9. BATFET Gate Regulation V-I Curve

BATFET Control for System Power Reset and Ship Mode

Ship Mode (BATFET Disable)

Ship mode is usually used when the system is stored or in idle state for a long time or is in shipping. In such conditions, it is better to completely disconnect battery and make system voltage zero to minimize the leakage and extend the battery life. To enter ship mode, the BATFET has to be forced off by setting BATFET_DIS bit. The BATFET turns off immediately if BATFET_DLY bit is 0, or turns off after a t_{SM_DLY}delay(8 seconds) if BATFET_DLY is set.

Exit Ship Mode (BATFET Enable)

To exit the ship mode and enable the BATFET one of the following can be applied:

With no input power (no operating VBUS):

1.Connect the adapter to the input with a valid voltage to the VBUS input.

2.PullnQON pin from logic high to low to enable BATFET for example by shorting nQON to GND. The negative pulse width should be at least a $t_{SHIPMODE}$ (1s TYP) for deglitching.

With the chip already powered by VBUS:

3.Clear BATFET_DIS bit using host and I2C.

4.Set REG_RST bit to reset all registers including BATFET_DIS bit to default (0).

5.Apply a negative pulse to nQON (same as 2).

Full System Reset with BATFET Using nQON

When the input source is not present, BATFET can act as a load on/off switch between the system and battery. This feature can be used to apply a power-on reset to the system. Host can toggle BATFET_DIS bit to cycle power off/on and reset the system. A push-button connected to nQON pin or a negative pulse can also be used to manually force a system power cycle when BATFET is ON (BATFET_DIS bit = 0). For this function, a negative logic pulse with a minimum width of t_{QON_RST} (16s TYP) must be applied to the nQON pin that results in a temporary BATFET turn off for t_{BATFET_RST} (250ms TYP) that automatically turns on afterward. This functionality can be disabled by setting BATFET_RST_EN bit to 0.

In summary the nQON pin controls BATFET and system reset in two different ways:

1.Enable BATFET: Applying an nQON logic high to low transition with longer than $t_{SHIPMODE}$ deglitch time (negative pulse) turns on BATFET to exit ship mode (Figure 10 left).

2.Reset BATFET: By applying a logic low for a duration of at least t_{QON_RST} to nQON pin while VBUS is not powered and BATFET is allowed to turn on (BATFET_DIS bit = 0), the BATFET turns off for t_{BATFET_RST} and then it is re-enabled resulting in a system power-on-reset. This function can be disabled by clearing BATFET_RST_EN bit (Figure 10 right). A typical push bottom circuit for nQON is given in Figure 11.

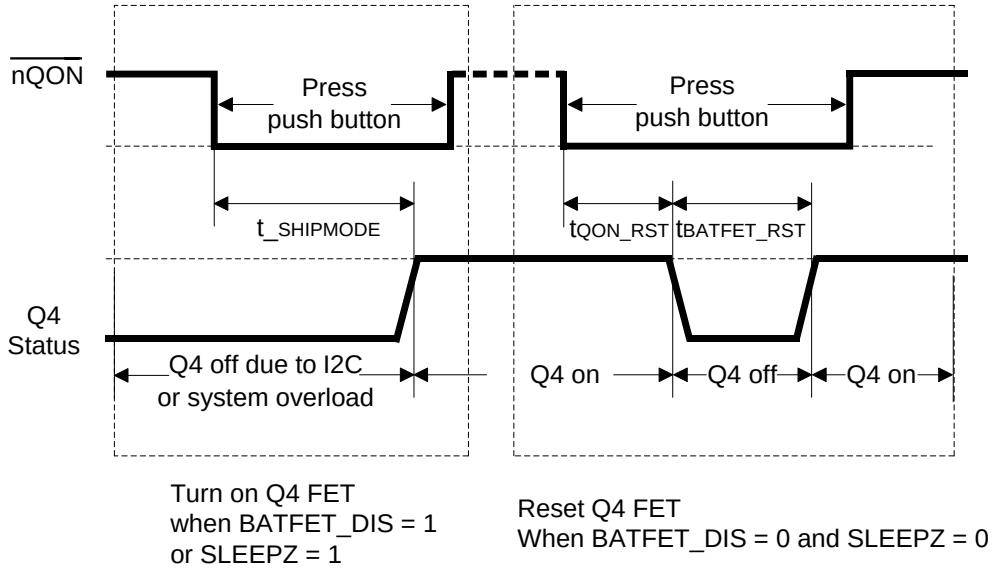


Figure 10.nQON Timing to Exit Ship Mode (Enable BATFET)
Right: System Power Reset (BATFET Temporarily Off)

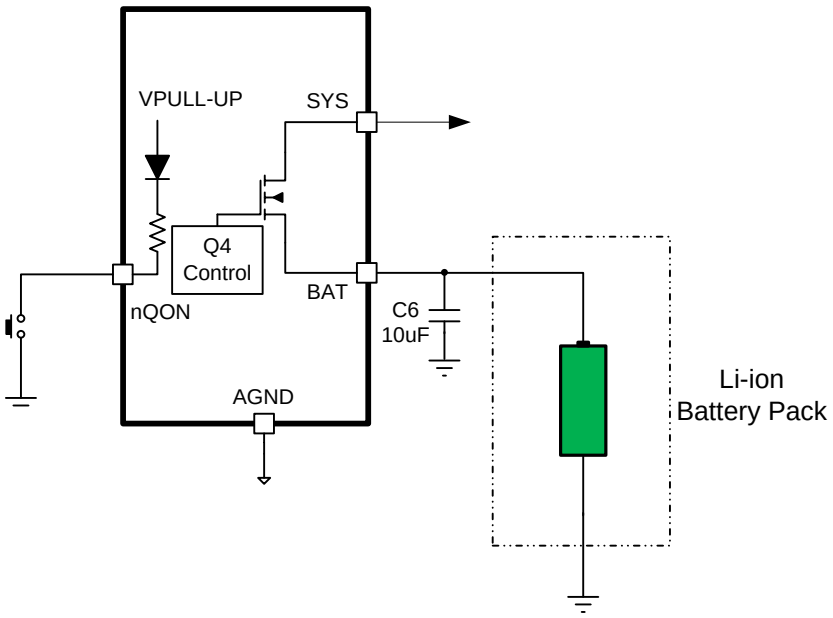


Figure 11. nQON Push Button Circuit

Status Outputs Pins (nPG, STAT and nINT)

Power Good Indication (nPG Pin and PG_STAT Bit)

When a good input source is connected to VBUS and input type is detected, the PG_STAT status bit goes high and the nPG pin goes low. A good input source is detected if all following conditions on V_{VBUS} are satisfied and input type detection is completed:

•V_{VBUS} is in the operating range: $V_{VBUS\_UVLOZ} < V_{VBUS} < V_{VAC\_OV}$.

•Device is not in sleep mode: $V_{VBUS} > V_{BAT} + V_{SLEEP}$.

•Input source is not poor: $V_{VBUS} > V_{VBUSMIN}$ (3.5V TYP) when I_{BAD_SRC} (30mA TYP) loading is applied. (Poor source detection.)

•Completed input source type detection.

Charge Status (STAT Pin)

Charging state is indicated with the open-drain STAT pin as explained in Table 4. This pin is able to drive an LED (see Figure 1). The functionality of the STAT pin is disabled if the EN_ICHG_MON[1:0] bits are set to 11.

Table 4. STAT Pin Function

Charging State	STAT Indicator
Charging battery (or recharge)	Low (LED ON)
Charge complete	High (LED OFF)
Charging is disabled or in sleep mode	High (LED OFF)
Charge is suspended due to input over-voltage, TS fault, timer faults or system over-voltage or boost mode is suspended (TS fault).	1Hz Blinking

nINT Interrupt Output Pin

When a new update occurs in the charger states a 256μs negative pulse is sent through the nINT pin to interrupt the host. The host may not continuously monitor the charger device and by receiving the interrupt it can react and check the charger situation on time.

The following events can generate an interrupt pulse:

1.All faults reflected in REG09 (watchdog, boost overload, charge faults, battery over-voltage and NTC).

2.Charging completed.

3.PSEL identified a connected source (USB or adapter).

4.Input source voltage entered the "input good" range:

a) V_{VBUS} exceeded V_{BAT} (not in sleep mode).

b) V_{VBUS} came below V_{VAC_OV}.

c) V_{VBUS} remained above $V_{VBUSMIN}$ (3.5V TYP) when I_{BAD_SRC} (30mA TYP) load current is applied.

5.Input removed or out of the "input good" range.

6.A DPM event (V_{INDPM} or I_{INDPM}) occurred (maskable).

Once a fault happens, the INT pulse is asserted once and the fault bits are updated in REG09. Fault status is not reset in the register until the host reads it. A new fault will not assert a new INT pulse until the host reads REG09 and all the previous faults are cleared. Therefore in order to read the current time faults the host must read REG09 two times consecutively. The first read returns the history of the fault register status (from the time of the last read or reset) and the second one checks the current active faults. The only exception is NTC_FAULT which always reports the actual real time condition of the TS pin.

REG09 does not support multi-read and multi-write as will be explained later.

BCT2601 Protection Features

Monitoring of Voltage and Current

During the converter operation the input and system voltages (V_{BUS} and V_{SYS}) and switch currents are constantly monitored to assure safe operation of the device in both buck and boost modes as will be explained below.

Buck Mode Voltage and Current Monitoring

1.Input Over-Voltage (ACOV)

Converter switching will stop as soon as V_{BUS} voltage exceeds V_{VAC_OV} over-voltage limit that is programmable by OVP[1:0] in REG06. It is selectable between 5.5V, 6.5V (default), 10.5V and 14V for USB or 5V, 9V or 12V adaptors respectively.

Each time V_{BUS} exceeds the OVP limit, an INT pulse is asserted and as long as the overvoltage persists, the CHRG_FAULT[1:0] bits are set to 01 in REG09. Fault will clear to 00 if the voltage comes back below limit (and a hysteresis threshold) and host reads the fault register. Charger resumes its normal operation when the voltage comes back below OVP limit.

2.System Over-Voltage (SYSOVP)

During a system load transient, the device clamps the system voltage to protect the system components

from over-voltage. The SYSOVP over-voltage limit threshold is 350mV + V_{SYSMIN} (programmed minimum system regulation voltage + 350mV). Once a SYSOVP occurs, switching stops to clamp any overshoot and a 30mA sink current is applied to SYS to pull the voltage down.

Boost Mode Voltage and Current Monitoring

In boost mode the RBFET (reverse blocking) and LSFET (low-side switch) FET currents and VBUS voltage are monitored for protection.

1.Soft-Start on VBUS

Boost mode begins with a soft-start to prevent large inrush currents the when it is enabled.

2.Output Short Protection for VBUS

Short circuit protection is provided for VBUS output in boost mode. To accept different types of load connected to VBUS and OTG adaptation, an accurate constant current regulation control is implemented for boost mode. In case of a short circuit on VBUS pin, the boost turns off and retries 7 times (Hiccup). If short is not removed after retries, the OTG will disable by clearing OTG_CONFIG bit. Also, an INT pulse is sent and the BOOST_FAULT bit is set to 1 in REG09. Enabling the boost mode again by host, clears the BOOST_FAULT bit.

3.Output Over-Voltage Protection for VBUS

In boost mode converter stops switching and exits boost mode (by clearing OTG_CONFIG bit) if VBUS voltage rises above regulation and exceeds the V_{OTG_OVP} over-voltage limit (6.015V TYP). An INT pulse is sent and the BOOST_FAULT bit is set 1.

BCT2601 Thermal Regulation and Shutdown

Buck Mode Thermal Protections

Internal junction temperature (T_J) is always monitored to avoid overheating. A limit of 120 ℃ is considered for maximum IC surface temperature in buck mode and if T_J intends to exceed this level, the device reduces the charge current to keep maximum temperature limited to 120°C (thermal regulation mode) and sets the THERM_STAT bit to 1. As expected the actual charging current is usually lower than programmed value during thermal regulation therefore, the safety timer runs at half clock rate and charge termination is disabled during thermal regulation.

If the temperature exceeds T_{SHUT} (150℃), thermal shutdown protection arise in which the converter and BATFET are turned off, CHRG_FAULT[1:0] bits are set to 10 in the fault register and an INT pulse is sent.

When the device recovers and T_J falls below the hysteresis band of T_{SHUT_HYS} (20℃under T_{SHUT}), the converter and BATFET resume automatically.

Boost Mode Thermal Protections

Similar to buck mode, T_J is monitored in boost mode for thermal shutdown protection. If junctiontemperature exceeds T_{SHUT} (150℃), BATFET will turn off and the boost mode will be disabled (OTG_CONFIG bit clears). BATFET will resume If T_J falls below the hysteresis band of T_{SHUT_HYS} (20℃ under T_{SHUT}). Boost can recover again by re-enabling OTG_CONFIG bit by host.

Battery Protections

Pin Battery Over-Voltage Protection (BATOVP)

The over-voltage limit for the battery is 4% above the battery regulation voltage setting. In case of a BATOVP, charging stops right away, the BAT_FAULT bit is set to 1 and an INT pulse is sent.

Battery Over-Discharge Protection

If battery discharges too much and VBAT falls below the depletion level ($V_{BAT\_DPL\_FALL)}$, the device turns of BATFET to protect battery. This protection is latched and is not recovereduntil an input source is connected to the VBUS pin. In such condition, the battery will start charging with the small I_{SHORT} current (80mA TYP) first as long as VBAT < V_{SHORTZ}. When battery voltage is increased and V_{SHORTZ}< V_{BAT}< V_{BATLOW}, the charge current will increase to the pre-charge current level programmed in the I_{PRECHG}[3:0] register.

Battery Over-Current Protection for System

The BATFET will latch off, if its current limit is exceeded due to a short or large overload on the system (I_{BAT}> I_{BATOP}). To reset this latch off and enable BATFET, the "Exit Ship Mode" procedure must be followed.

I2C Serial Interface and Data Communication

Standard I2C interface is used to program BCT2601 parameters and get status reports. I2C is well known 2 wire serial communication interface that can connect one (or more) master device(s) to some slave devices for two-way communication. The bus lines are named serial data (SDA) and serial clock (SCL). The device that initiates a data transfer is a master and generates the SCL clock as long as it is master. Slave devices have unique addresses to identify. A master is typically a micro controller or a digital signal processor.

The BCT2601 operates as a slave device with address 0x6B (6BH). It has twelve 8-bit registers, numbered from REG00 to REG0B. A register read beyond REG0B (0x0B) returns 0xFF.

Physical Layer

The BCT2601 supports I2C standard mode (up to 100kbit/s) and fast mode (up to 400kbit/s) communication speeds. Bus lines are pulled high by weak current source or pull-up resistors are in logic high state with no clocking when the bus is free. The SDA and SCL pins are open-drain.

I2C Data Communication

START and STOP Conditions

A transaction is started by taking control of the bus by master if the bus is free. The transaction is terminated by releasing the bus when the data transfer job is done as shown in Figure12. All transactions begin by the master who applies a START condition on the bus lines to take over the bus and exchange data. At the end, the master terminates the transaction by applying one (or more) STOP condition. START condition is when SCL is high and a high to low transition on the SDA is generated by master. Similarly, a STOP is defined when SCL is high and SDA goes from low to high. START and STOP are always generated by a master. After a START and before a STOP the bus is considered busy.

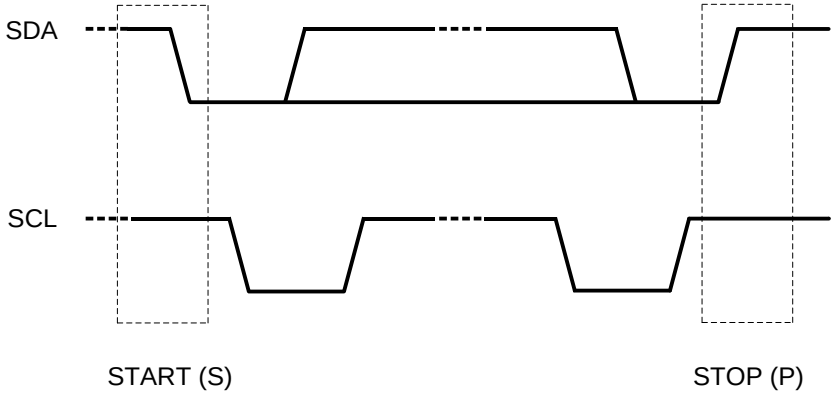


Figure 12. I2C Bus in START and STOP Conditions

Data Bit Transmission and Validity

The data bit (high or low) must remain stable on the SDA line during the HIGH period of the clock. The state of the SDA can only change when the clock (SCL) is LOW. For each data bit transmission, one clock pulse is generated by master. Bit transfer in I2C is shown in Figure 13.

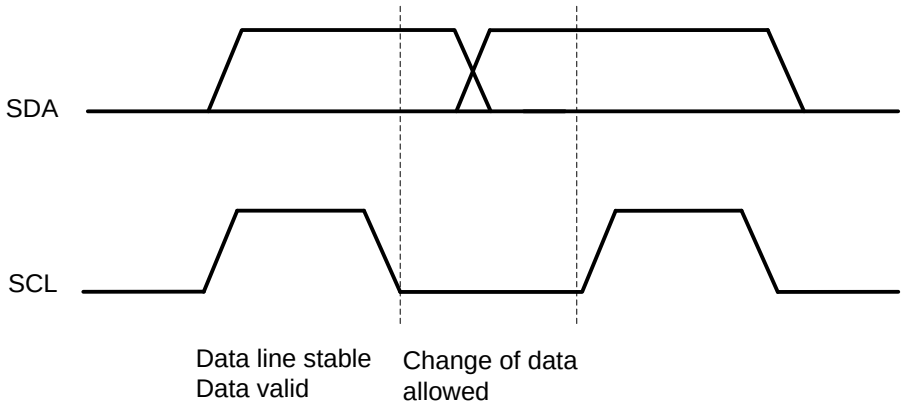


Figure 13. I2C Bus Bit Transfer

Byte Format

Data is transmitted in 8-bit packets (one byte at a time). The number of bytes in one transaction is not limited. In each packet the 8 bits are sent successively with the Most Significant Bit (MSB) first. An acknowledge (or not-acknowledge) bit must come after the 8 data bits. This bit informs the transmitter whether the receiver is ready to proceed for the next byte or not. If the slave is busy and cannot transfer another byte of data, it can hold the SCL line low and keep the master in a wait state (called clock stretching). When the slave is ready for another byte of data, it releases the clock line and data transfer can continue with clocks generated by master. Figure 14 shows the byte transfer process with I2C interface.

Acknowledge (ACK) and Not Acknowledge (NCK)

After transmission of each byte by transmitter an acknowledge bit is replied by the receiver as ninth bit. With the acknowledge bit the receiver informs the transmitter that the byte was received, and another byte is expected or can be sent (ACK) or it is not expected (NCK = not ACK). Clock (SCL) is always generated by the master, including for the acknowledge ninth bit, no matter who is acting as transmitter or receiver.

SDA line is released for receiver control during the acknowledge clock pulse and the receiver can pull the SDA line low as ACK (reply a 0 bit) or let it be high as NCK during the SCL high pulse. After that the master can either STOP (P) to end the transaction or send a new START (S) condition to start a new transfer (called repeated start). For example, when master wants to read a register in slave, one start is needed to send the slave address and register address and then without a stop condition another start is sent by master to initiate the receiving transaction from slave. Master then sends the STOP condition and releases the bus.

Data Direction Bit and Addressing Slaves

The first byte sent by master after the START is always the target slave address (7 bits) and an eighth data-direction bit (R/W). R/W bit is 0 for a WRITE transaction and 1 for READ (when master is asking for data). Data direction is the same for all next bytes of the transaction. To reverse it, a new START or repeated START condition must be sent by master (STOP will end the transaction). Usually the second byte is also a WRITE sending the register address that is supposed to be accesses in the next byte(s).

WRITE: If the master wants to write in the register, the third byte can be written directly as shown in Figure 16 for a single write data transfer. After receiving the ACK, master may issue a STOP condition to end the transaction or send the next register data, that will be written to the next address in a slave as multi-write. A STOP is needed after sending the last data.

READ: If the master wants to read a single register (Figure 17), it sends a new START condition along with device address with R/W bit = 1. After ACK is received, master reads the SDA line to receive the content of the register. Master replies with NCK to inform slave that no more data is needed (single read) or it can send an ACK to request for sending the next register content (multi-read). This can continue until a NAK is sent by master. A STOP must be sent by master in any case to end the transaction.

In the figures the data blocks with gray background show the bits sent by master and the white background represent data bits sent by slave. If the register address is not defined, the device replies with NCK and goes back to the I2C slave idle state.

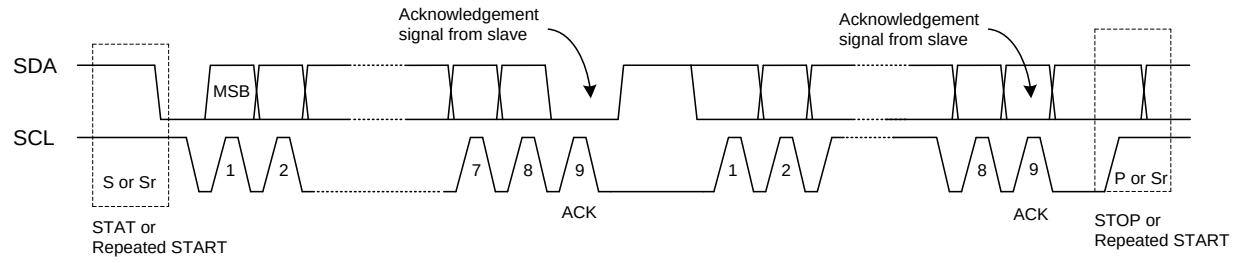


Figure 14. Data Transfer on the I2C Bus

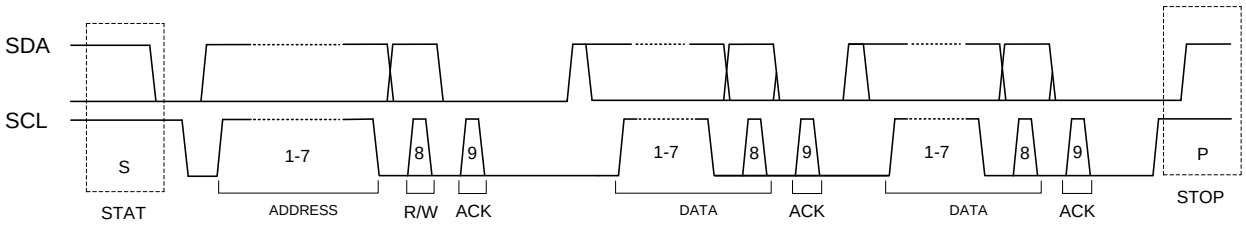


Figure 15. A Complete Data Transfer Transaction

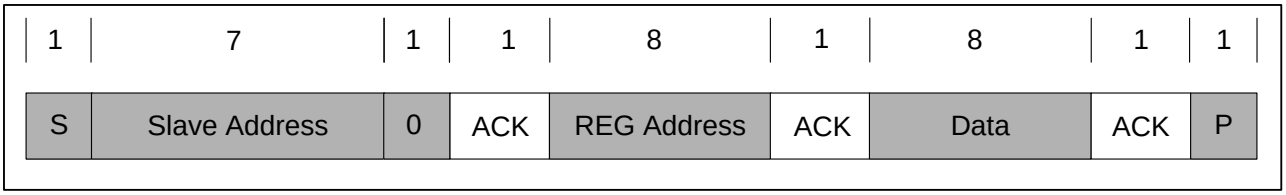


Figure 16. A Single Write Transaction

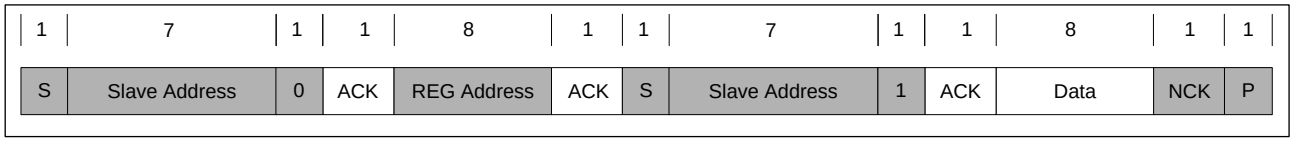


Figure 17. A Single Read Transaction

Data Transactions with Multi-Read or Multi-Write

Multi-read and multi-write are supported by BCT2601 for REG00 through REG0B registers, except for REG09 as explained in Figure 18 and Figure 19. REG09 (fault register), is skipped in multi-read/writes. In the multi-write, every new data byte sent by master is written to the next register of the device. A STOP is sent whenever master is done with writing into device registers.

In a multi-read transaction, after receiving the first register data (whose address is already written to the slave), the master replies with an ACK to ask the slave for sending the next register data. This can continue as much as it is needed by master. Master sends back an NCK after the last received byte and issues an STOP condition.

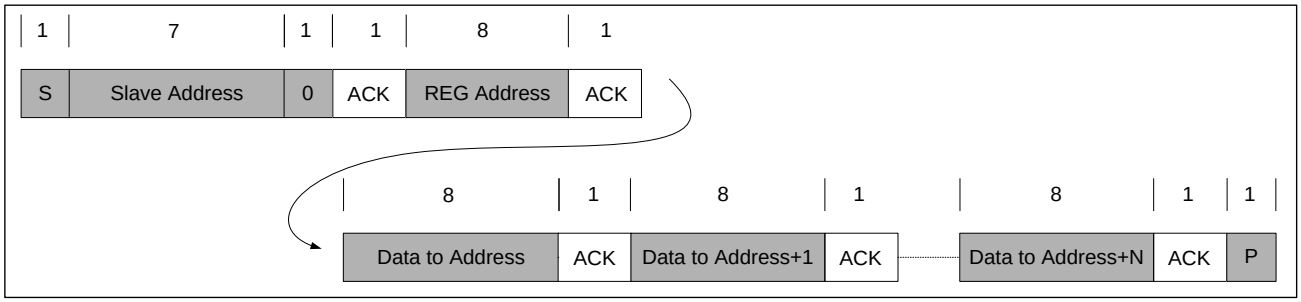


Figure 18. A Multi-Write Transaction

Figure 19. A Multi-Read Transaction

REGISTER MAPS

All registers are 8-bit and individual bits are named from D[0] (LSB) to D[7] (MSB).

I2C Slave Address of BCT2601 is: 0x6B

R/W: Read/Write bit(s) R:Read only bit(s)

PORV: Power-On-Reset Value

n:Parameter code formed by the bits as an unsigned binary number.

REG00

Register address: 0x00; R/W PORV = 00010111

Table 5. REG00 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7]	EN_HIZ	Enable HIZ Mode 0 = Disable (default) 1 = Enable	In HIZ mode, the VBUS pin is effectively disconnected from internal circuit. Some leakage current may exist.	0	R/W	REG_RST or Watchdog
D[6:5]	EN_ICHG_MON[1:0]	Enable STAT Pin Function 00 = Enable (default) 01 = Reserved 10 = Reserved 11 = Disable (float pin)	These bits turn on or off the function of the STAT open-drain output pin (charge status indicator).	00	R/W	REG_RST
D[4:0]	IINDPM[4:0]	IINDPM[4] 1 = 1600mA IINDPM[3] 1 = 800mA IINDPM[2] 1 = 400mA IINDPM[1] 1 = 200mA IINDPM[0] 1 = 100mA	Input Current Limit Value (n: 5 bits): = 100 + 100n (mA) Offset: 100mA Range: 100mA (00000) - 3.2A (11111) Default: 2400mA (10111), not typical IINDPM changes based on PSEL state after an input source detection as follows: PSEL = High → IINDPM = 500mA PSEL = Low → IINDPM = 2400mA Host can overwrite IINDPM after input source detection is completed.	10111	R/W	REG_RST

REGISTER MAPS(continued)

REG01

Register address: 0x01; R/W PORV = 00011010

Table 6. REG01 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7]	PFM_DIS	Enable PFM Mode 0 = Enable (default) 1 = Disable	Enable Pulse Frequency Modulation. PFM is normally used to save power at light load by reducing converter switching frequency.	0	R/W	REG_RST
D[6]	WD_RST	I2C Watchdog Timer Reset 0 = Normal (default) 1 = Reset	Watchdog Timer Reset Control Bit. Write 1 to this bit to avoid watchdog expiry. WD_RST resets to 0 after watchdog timer reset (expiry).	0	R/W	REG_RST or Watchdog
D[5]	OTG_CONFIG	Enable OTG 0 = OTG disable (default) 1 = OTG enable	This bit has priority over charge enable in the CHG_CONFIG.	0	R/W	REG_RST or Watchdog
D[4]	CHG_CONFIG	Enable Battery Charging 0 = Charge disable 1 = Charge enable (default)	Charge is enabled when CHG_CONFIG bit is 1 and nCE pin is pulled low.	1	R/W	REG_RST or Watchdog
D[3:1]	SYS_MIN[2:0]	Minimum System Voltage 000 = 2.6V 001 = 2.8V 010 = 3V 011 = 3.2V 100 = 3.4V 101 = 3.5V (default) 110 = 3.6V 111 = 3.7V	Minimum System Voltage Value. Offset: 2.6V Range: 2.6V (000) - 3.7V (111) Default: 3.5V (101)	101	R/W	REG_RST
D[0]	MIN_BAT_SEL	Minimum Battery Voltage for OTG Mode 0 = 2.8V VBAT falling (default) 1 = 2.5V VBAT falling	Default: VBAT falling, VBATLOW_OTG = 2.8V. VBAT rising, VBATLOW_OTG = 3.0V.	0	R/W	REG_RST

REGISTER MAPS(continued)

REG02

Register address: 0x02; R/W PORV = 10100010

Table 7. REG02 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7]	BOOST_LIM	Boost Mode Current Limit 0 = 0.5A 1 = 1.2A (default)	The current limit options listed values are the minimum specs. Actual value is typically higher.	1	R/W	REG_RST or Watchdog
D[6]	Q1_FULLON	V_{BUS} FET SWITCH (Q1) 0 = Use higher RDSON if IINDPM < 700mA (for better accuracy 1 = Use lower RDSON always (fully ON for better efficiency)	Used to control the on-resistance of Q1 (V_{BUS} switch) for better input current measurement accuracy. In boost mode, full FET is always used, and this bit has no effect.	0	R/W	REG_RST
D[5:0]	ICHG[5:0]	ICHG[5] 1 = 1920mA	Fast Charge Current Value (n: 6 bits): = 60n (mA) (n ≤ 50) Offset: 0mA Range: 0mA (000000) - 3000mA (110010) Default: 2040mA (100010) Notes: Setting I_{CHG} = 0mA disables charge. Values above 50D = 110010 (3000mA) are clamped to 50D = 110010 (3000mA).	1	R/W	REG_RST or Watchdog
		ICHG[4] 1 = 960mA		0	R/W	
		ICHG[3] 1 = 480mA		0	R/W	
		ICHG[2] 1 = 240mA		0	R/W	
		ICHG[1] 1 = 120mA		1	R/W	
		ICHG[0] 1 = 60mA		0	R/W	

REGISTER MAPS(continued)

REG03 (Pre-Charge and Termination Current Settings)
Register address: 0x03; R/W PORV = 00100010

Table 8. REG03 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7:4]	IPRECHG[3:0]	IPRECHG[3] 1 = 480mA	Pre-Charge Current Limit (n: 4 bits): = 60 + 60n (mA) (n ≤ 12) Offset: 60mA Range: 60mA (0000) - 780mA (1100) Default: 180mA (0010) Note: Values above 12D = 1100 (780mA) are clamped to 12D = 1100 (780mA).	0	R/W	REG_RST or Watchdog
		IPRECHG[2] 1 = 240mA		0	R/W	
		IPRECHG[1] 1 = 120mA		1	R/W	
		IPRECHG[0] 1 = 60mA		0	R/W	
D[3:0]	ITERM[3:0]	ITERM[3] 1 = 480mA	Termination Current Limit (n: 4 bits): = 60 + 60n (mA) Offset: 60mA Range: 60mA (0000) - 960mA (1111) Default: 180mA (0010)	0	R/W	REG_RST or Watchdog
		ITERM[2] 1 = 240mA		0	R/W	
		ITERM[1] 1 = 120mA		1	R/W	
		ITERM[0] 1 = 60mA		0	R/W	

REGISTER MAPS(continued)

REG04

Register address: 0x04; R/W PORV = 01011000

Table 9. REG04 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7:3]	VREG[4:0]	VREG[4] 1 = 512mV	Charge Voltage Limit (n: 5 bits): = 3856 + 32n (mV) if n ≤ 24, n≠15; = 4.352V if n = 15 Offset: 3.856V Range: 3.856V (00000) - 4.624V (11000) Default: 4.208V (01011) Special Value: 4.352V (01111) Note: Values above 24D = 11000 (4.624V) are clamped to 24D = 11000 (4.624V).	0	R/W	REG_RST or Watchdog
		VREG[3] 1 = 256mV		1	R/W	
		VREG[2] 1 = 128mV		0	R/W	
		VREG[1] 1 = 64mV		1	R/W	
		VREG[0] 1 = 32mV		1	R/W	
D[2:1]	TOPOFF_TIMER[1:0]	Top-Off Timer 00 = Disabled (default)	The charge extension time added after the termination condition is detected. If disabled, charging terminates as soon as termination conditions are met.	0	R/W	REG_RST or Watchdog
		01 = 15 minutes 10 = 30 minutes 11 = 45 minutes		0	R/W	
D[0]	VRECHG	Battery Recharge Threshold	A recharge cycle will start if a fully charged battery voltage drops below VREG - VRECHG settings.	0	R/W	REG_RST or Watchdog
		0 = 100mV below VREG[4:0] (default)			R/W	
		1 = 200mV below VREG[4:0]			R/W	

REGISTER MAPS(continued)

REG05

Register address: 0x05; R/W PORV = 10011111

Table 10. REG05 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7]	EN_TERM	Charging Termination Enable 0 = Disable 1 = Enable (default)		1	R/W	REG_RST or Watchdog
D[6]	Reserved	Reserved	Reserved.	0	R/W	REG_RST or Watchdog
D[5:4]	WATCHDOG[1:0]	Watchdog Timer Setting 00 = Disable watchdog timer 01 = 40s (default) 10 = 80s 11 = 160s	Expiry time of the watchdog timer if it is not reset.	01	R/W	REG_RST or Watchdog
D[3]	EN_TIMER	Charge Safety Timer Enable 0 = Disable 1 = Enable (default)	When enabled the pre-charge and fast charge periods are included in the timing.	1	R/W	REG_RST or Watchdog
D[2]	CHG_TIMER	Charge Safety Timer Setting 0 = 4hrs 1 = 6hrs (default)		1	R/W	REG_RST or Watchdog
D[1]	TREG	Thermal Regulation Threshold 0 = 80℃ 1 = 120℃ (default)	For buck mode.	1	R/W	REG_RST or Watchdog
D[0]	JEITA_ISET (0℃ - 10℃)	JEITA Charging Current 0 = 50% of ICHG 1 = 20% of ICHG (default)		1	R/W	REG_RST or Watchdog

REGISTER MAPS(continued)

REG06

Register address: 0x06; R/W PORV = 01100110

Table 11. REG06 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7:6]	OVP[1:0]	VAC Pin OVP Threshold	OVP Threshold for Input Supply.	0	R/W	REG_RST
		00 = 5.5V				
		01 = 6.5V (5V input) (default)		1	R/W	
		10 = 10.5V (9V input)				
		11 = 14V (12V input)				
D[5:4]	BOOSTV[1:0]	Boost Mode Voltage Regulation		1	R/W	REG_RST
		00 = 4.85V				
		01 = 5.00V		0	R/W	
		10 = 5.15V (default)				
		11 = 5.30V				
D[3:0]	VINDPM[3:0]	VINDPM[3] 1 = 800mV	VINDPM Threshold (n: 4 bits): = 3.9V + 0.1n (V) Offset: 3.9V Range: 3.9V (0000) - 5.4V (1111) Default: 4.5V (0110)	0	R/W	REG_RST
		VINDPM[2] 1 = 400mV		1	R/W	
		VINDPM[1] 1 =200mV		1	R/W	
		VINDPM[0] 1 =100mV		0	R/W	

REGISTER MAPS(continued)

REG07

Register address: 0x07; R/W PORV = 01001100

Table 12. REG07 Register Details

BITS	BIT NAME	DESCRIPTION	COMMENT	PORV	TYPE	RESET BY
D[7]	IINDET_EN	Input Current Limit Detection 0 = Not in input current limit detection (default) 1 = Force input current limit detection when VBUS is present	Reloads with 0 when input detection is completed.	0	R/W	REG_RST or Watchdog
D[6]	TMR2X_EN	Enable Half Clock Rate Safety Timer 0 = Disable 1 = Safety timer slow down during DPM, JEITA cool, or thermal regulation (default)	Slow down by a factor of 2.	1	R/W	REG_RST or Watchdog
D[5]	BATFET_DIS	Disable BATFET 0 = Allow BATFET (Q4) to turn on (default) 1 = Turn off BATFET (Q4) after a t_{SM_DLY} delay time (REG07 D[3])	t_{SM_DLY} is typically 8 seconds.	0	R/W	REG_RST or Watchdog
D[4]	JEITA_VSET (45℃ - 60℃)	JEITA Charging Voltage 0 = Set charge voltage to 4.1V (MAX) (default) 1 = Set charge voltage to VREG		0	R/W	REG_RST or Watchdog
D[3]	BATFET_DLY	BATFET Turn Off Delay Control 0 = Turn off BATFET immediately 1 = Turn off BATFET after t_{SM_DLY} (default)	BATFET_DIS bit is set.	1	R/W	REG_RST or Watchdog
D[2]	BATFET_RST_EN	Enable BATFET Reset 0 = Disable BATFET reset 1 = Enable BATFET reset (default)		1	R/W	REG_RST or Watchdog
D[1:0]	VDPM_BAT_ TRACK[1:0]	Dynamic VINDPM Tracking 00 = Disable (VINDPM set by register) 01 = VBAT + 200mV 10 = VBAT + 250mV 11 = VBAT + 300mV	Set VINDPM[3:0] to track VBAT voltage. Actual VINDPM is the larger of this register value and VBAT + VDPM_BAT_TRACK [1:0] offset.	0 0	R/W R/W	REG_RST

REGISTER MAPS(continued)

REG08 (Status Bits, Read Only)

Register address: 0x08; R PORV = xxxxxxxx

Table 13. REG08 Register Details

BITS	BIT NAME	DESCRIPTION	PORV	TYPE	RESET BY
D[7:5]	VBUS_STAT[2:0]	VBUS Status Register (BCT2601)	x	R	NA
		000 = No input			
		001 = USB host SDP (500mA) → PSEL HIGH	x	R	
		010 = Adapter 2.4A → PSEL LOW			
		111 = OTG	x	R	
		Other values are reserved.			
		Current limit value is reported in IINDPM[4:0] register.			
D[4:3]	CHRG_STAT[1:0]	Charging Status	x	R	NA
		00 = Charge disable			
		01 = Pre-charge (V_{BAT}< V_{BATLOW})	x	R	
		10 = Fast charging (constant current or voltage)			
		11 = Charging terminated			
D[2]	PG_STAT	Input Power Status (VBUS in good voltage range and not poor)	x	R	NA
		0 = Input power source is not good			
		1 = Input power source is good			
D[1]	THERM_STAT	Thermal Regulation Status	x	R	NA
		0 = Not in thermal regulation			
		1 = In thermal regulation			
D[0]	VSYS_STAT	System Voltage Regulation Status	x	R	NA
		0 = Not in V_{SYSMIN} regulation (V_{BAT}> V_{SYS_MIN})			
		1 = In V_{SYSMIN} regulation (V_{BAT}< V_{SYS_MIN})			

REGISTER MAPS(continued)

REG09 (Fault Bits, Read Only)

Register address: 0x09; R PORV = xxxxxxxx

Table 14. REG09 Register Details

BITS	BIT NAME	DESCRIPTION	PORV	TYPE	RESET BY
D[7]	WATCHDOG_FAULT	Watchdog Fault Status	x	R	NA
		0 = Normal (no fault)			
		1 = Watchdog timer expired			
D[6]	BOOST_FAULT	Boost Mode Fault Status	x	R	NA
		0 = Normal			
		1 = VBUS overloaded in OTG, or VBUS OVP, or battery voltage too low (any condition that prevents boost starting)			
D[5:4]	CHRG_FAULT[1:0]	Charging Fault Status	x	R	NA
		00 = Normal			
		01 = Input fault ($V_{AC\ OVP}$ or VBAT < V_{VBUS}< 3.8V)	x	R	
		10 = Thermal shutdown			
		11 = Charge safety timer expired			
D[3]	BAT_FAULT	Battery Fault Status	x	R	NA
		0 = Normal			
		1 = Battery over-voltage (BATOVP)			
D[2:0]	NTC_FAULT[2:0]	JEITA Condition Based on Battery NTC Temperature Measurement	x	R	NA
		000 = Normal			
		010 = Warm	x	R	
		011 = Cool (buck mode only)			
		101 = Cold	x	R	
		110 = Hot			
		NTC fault bits are updated in real time and does not need a read to reset.			

REGISTER MAPS(continued)

REG0A

Register address: 0x0A; R and R/W PORV = xxxxxx00

Table 15. REG0A Register Details

BITS	BIT NAME	DESCRIPTION	PORV	TYPE	RESET BY
D[7]	VBUS_GD	Good Input Source Detected 0 = A good VBUS is not attached 1 = A good VBUS attached	x	R	NA
D[6]	VINDPM_STAT	Input Voltage Regulation (Dynamic Power Management) 0 = Not in VINDPM 1 = In VINDPM	x	R	NA
D[5]	IINDPM_STAT	Input Current Regulation (Dynamic Power Management) 0 = Not in IINDPM 1 = In IINDPM	x	R	NA
D[4]	Reserved		x	R	NA
D[3]	TOPOFF_ACTIVE	Active Top-Off Timer Counting Status 0 = Top-off timer not counting 1 = Top-off timer counting	x	R	NA
D[3]	ACOV_STAT	Input Over-Voltage Status (AC adaptor is the input source) 0 = No over-voltage (no ACOV) 1 = Over-voltage detected (ACOV)	x	R	NA
D[1]	VINDPM_INT_MASK	VINDPM Event Detection Interrupt Mask 0 = Allow VINDPM INT pulse 1 = Mask VINDPM INT pulse	x	R/W	REG_RST
D[0]	IINDPM_INT_MASK	IINDPM Event Detection Mask 0 = Allow IINDPM to send INT pulse 1 = Mask IINDPM INT pulse	x	R/W	REG_RST

REGISTER MAPS(continued)

REG0B

Register address: 0x0B; R and R/W PORV = 000101xx

Table 16. REG0B Register Description

BITS	BIT NAME	DESCRIPTION	PORV	TYPE	RESET BY
D[7]	REG_RST	Register Reset 0 = No effect (Keep current register settings) 1 = Reset R/W bits of all registers to the default and reset safety timer (It also resets itself to 0 after register reset is completed.)	0	R/W	REG_RST
D[6:3]	PN[3:0]	Part ID 0010 = BCT2601	0 0 1 0	R R R R	NA
D[2]	BCTPART		1	R	NA
D[1:0]	DEV_REV[1:0]	Revision	x x	R R	NA

APPLICATION INFORMATION

The BCT2601 is typically used as a charger with power path management in smart phones, tablets and other portable devices. In a design it is comes along with a host controller (a processor with I2C interface) and a single-cell Li-Ion or Li-polymer battery.

Inductor Design

Small energy storage elements (inductor and capacitor) can be used thanks to the high frequency (1.5MHz) switching converter used in the BCT2601. Inductor should tolerate currents higher than the maximum charge current (ICHG) plus half the inductor peak to peak ripple current (ΔI) without saturation:

$$I_{SAT} = I_{CHG} + \frac{\Delta I}{2}$$

The inductor ripple current is determined by the input voltage(V_{VBUS}), duty cycle (D=VBAT/V_{VBUS}), switching frequency (f_S =1.5MHz) and the inductance (L). In CCM we have:

$$\Delta I = \frac{V_{BUS} \times D \times (1-D)}{f_s \times L}$$

Inductor ripple current is maximum when D≈0.5. If the input voltage range (V_{VBUS}) is limited higher D values can be considered. In a practical design, inductor peak to peak current ripple is selected in a range between 20% to 40% of the maximum DC current ΔI = (0.2 ~ 0.4) × I_{CHG} for a good trade-off between inductor size and efficiency. Selecting higher ripple allows choosing of smaller inductance for a small increase in loss.

For each application, V_{VBUS} and I_{CHG} are known, so L can be calculated and current rating of the inductor can be selected. Choose an inductor that has small DCR and core losses at 1.5MHz to have high efficiency and cool operation at full load.

Input Capacitor Design

Select low ESR ceramic input capacitor (X7R or X5R) with sufficient voltage and RMS ripple current rating for decoupling of the input switching ripple current (ICIN). The RMS ripple current in the worst case is around the ICHG/2 when D≈0.5. If the converter does not operate at D≈50%, the worst case capacitor RMS current can be estimated from (5) in which D is the closest operating duty cycle to 0.5

$$I_{CIN} = I_{CHG} \times \sqrt{D \times (1-D)}$$

For BCT2601 place CIN across PMID and GND pins close to the chip. Voltage rating of the capacitor must be at least 25% higher than the normal input voltage to minimize voltage derating. A rating of 25V or higher is preferred for a 15V input voltage.
A CIN = 22μF is suggested for a 3A charger.

Output Capacitor Design

The output capacitance (on the system) must have enough RMS (ripple) current rating to carry the inductor switching ripple and provide enough energy for system transient current demands. I_{COUT} (COUT RMS current) can be calculated by:

$$I_{COUT} = \frac{I_{ripple}}{2 \times \sqrt{3}} I_{CHG} \approx 0.29 I_{ripple}$$

And the output voltage ripple can be calculated by:

$$V_O = \frac{V_{OUT}}{8LC_{OUT}{f_s}^2}\left(1 - \frac{V_{OUT}}{V_{BUS}}\right)$$

Increasing L or C_{OUT} (the LC filter) can reduce the ripple.

The charger device has internal loop compensation optimized for above 20μF ceramic output capacitance. 0V, X7R (or X5R) ceramic capacitors are recommended for the output.

The design is based on buck mode operation that has almost 2.5 times higher current rating (3A) compared to the boost mode (1.2A). The design is sufficient for proper boost operation, because converter is bidirectional and only the direction of currents is reversed.

Input Power Supply Considerations

To power the system from the BCT2601, either an input power source with a voltage between 3.9V to 13.5V and at least 100mA current rating should power VBUS, or a single-cell Li-Ion battery with voltage higher than $V_{BATUVLO}$ should be connected to BAT pin of the device. The input source must have at least 3A current rating to allow maximum power delivery through charger (buck converter) to the system.

Layout Recommendations

The switching node (SW) creates very high frequency noises several times higher than f_{SW} (1.5MHz) due to sharp rise and fall times of the voltage and current in the switches. To reduce the ringing issues and noise generation designing a proper layout is important to minimize the current path impedance and loop area.

The following considerations can help making a better layout.

1.Place the input capacitor between PMID and GND pins as close as possible to the chip with shortest copper connections (avoid vias). Choose smallest capacitor sizes.

2.Connect one pin of the inductor as close as possible to the SW pin of the device and minimize the copper area connected to the SW node to reduce capacitive coupling from SW area to nearby signal traces. This decreases the noise induced through parasitic stray capacitances and displacement currents to other conductors. SW connection should be wide enough to carry the charging current. Keep other signals and traces away from SW if possible.

3.Place output capacitor GND pin as close as possible to the GND pin of the device and the GND pin of input capacitor CIN. It is better to avoid using vias for these connections and keep the high frequency current paths very short and on the samelayer. A GND copper layer under the component layer helps reducing noise emissions. Pay attention to the DC current and AC current paths in the layout and keep them short and decoupled as much as possible.

4.For analog signals, it is better to use a separate analog ground (A_{GND}) branched only at one point from GND pin. To avoid high current flow through the A_{GND} path, it should be connected to GND only at one point (preferably the GND pin). Alternatively a 0Ω resistor can be used to tie analog ground to power ground to keep them as separate nets.

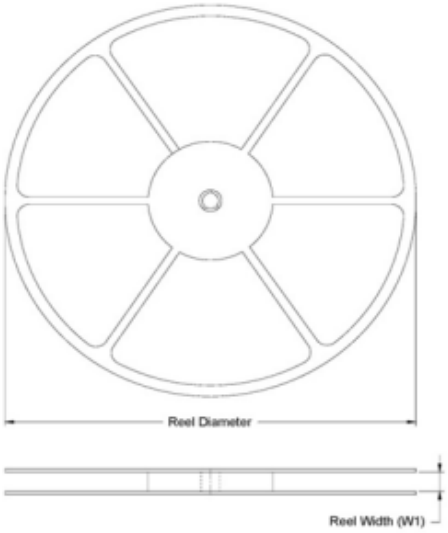
5.Place decoupling capacitors close to the IC pins with shortest possible copper connections.

6.Solder the exposed thermal pad of the package to the PCB ground planes. Ensure that there are enough thermal vias directly under the IC, connecting to the ground plane on the other layers for better heat dissipation and cooling of the device.

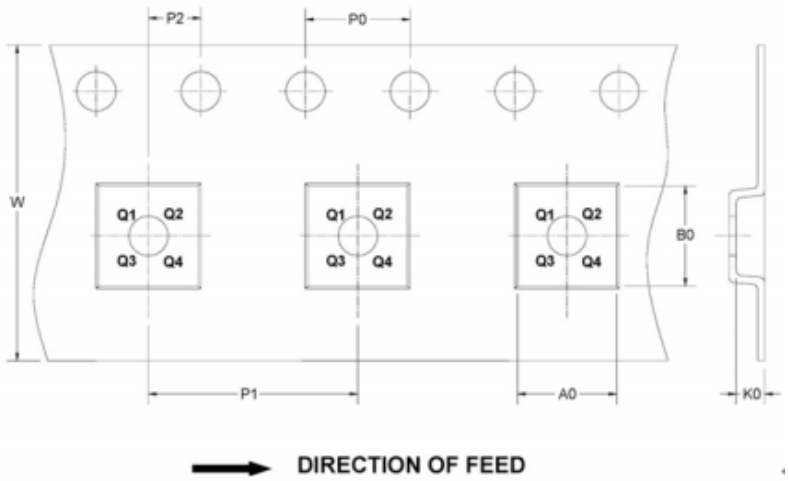
7.Select proper sizes for the vias and ensure enough copper is available to carry the current for a given current path. Vias usually have some considerable parasitic inductance and resistance

TAPE AND REEL INFORMATION

REEL DIMENSIONS



TAPE DIMENSIONS



Notes: 1. The above picture is for reference only, please refer to the value in the table below for the actual size.

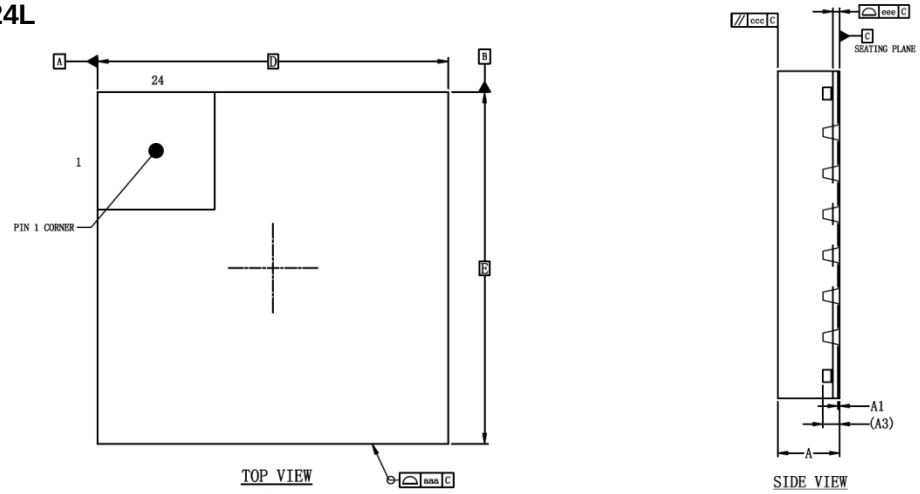
2. For Pin 1 Orientation, please check the phasical reel before use.

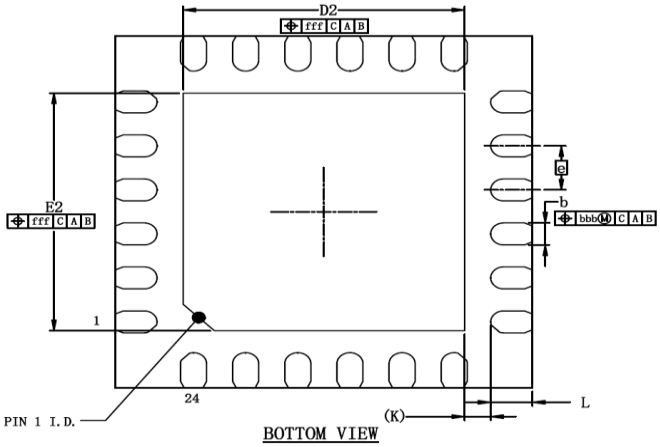
KEY PARAMETER LIST OF TAPE AND REEL

Device Name	Package Type	Reel Diameter	Unit: mm								Pin 1 Quadrant	Reel Q'ty
			Reel Width W1	A0	B0	K0	P0	P1	P2	W		
BCT2601EGG-TR	QFN4x4-24L	13"	13.4	4.3	4.3	1.1	4	8	2	12	Q1	5000

PACKAGE OUTLINE DIMENSIONS

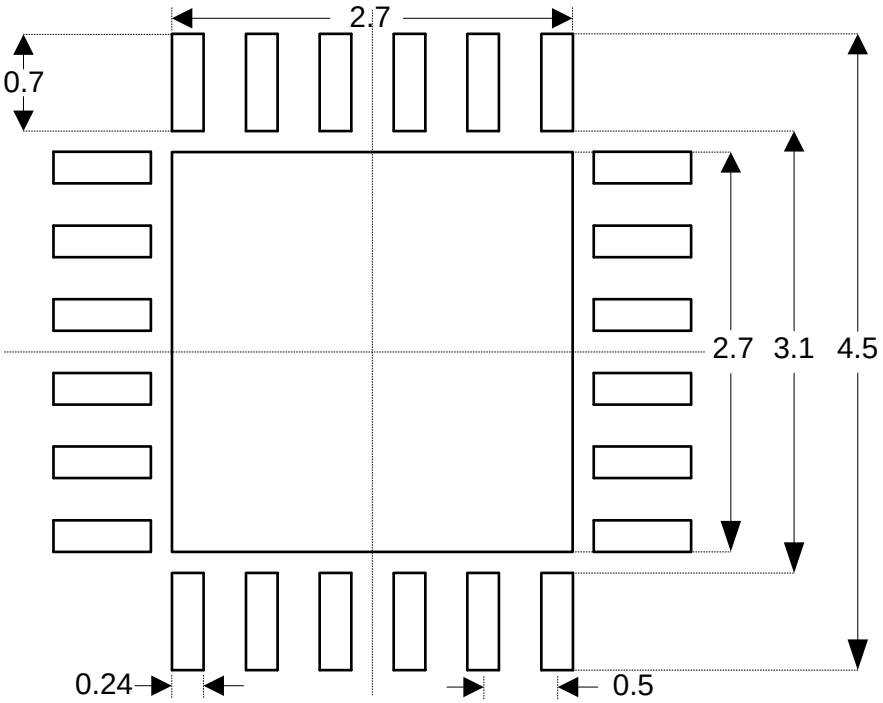
QFN-4×4-24L





		SYMBOL	MIN	NOM	MAX
TOTAL THICKNESS		A	0.70	0.75	0.80
STAND OFF		A1	0.00	0.02	0.05
L/F THICKNESS		A3		0.203 REF	
LEAD WIDTH		b	0.20	0.25	0.30
BODY SIZE	X	D		4 BSC	
	Y	E		4 BSC	
LEAD PITCH		e		0.5 BSC	
EP SIZE	X	D2	2.60	2.7	2.80
	Y	E2	2.60	2.7	2.80
LEAD LENGTH		L	0.30	0.4	0.50
LEAD TIP TO EP EDGE		K		0.25 REF	
PACKAGE EDGE TOLERANCE		aaa		0.1	
MOLD FLATNESS		ccc		0.1	
COPLANARITY		eee		0.08	
LEAD OFFSET		bbb		0.1	
EXPOSED PAD OFFSET		fff		0.1	

PCB Layout Pattern: QFN-4×4-24L



RECOMMENDED PCB LAYOUT PATTERN (Unit: mm)