AS1339 650mA RF Step-Down DC-DC for PA, with two LDOs

1 General Description

The AS1339 is a high-frequency step-down converter optimized for dynamically powering the power amplifier (PA) in WCDMA or NCDMA handsets. The device uses a $110 \text{m}\Omega$ typical bypass FET to power the PA directly from the battery during high-power transmission. The IC integrates two 10mA low-noise, low-dropout regulators (LDOs) for PA biasing.

With a switching frequency of 2MHz, the device allows optimization for smallest solution size or highest efficiency. The AS1339 supports fast switching using small ceramic $10\mu F$ input and $4.7\mu F$ output capacitors to maintain low ripple voltage.

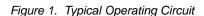
The AS1339 uses an analog input driven by an external DAC to control the output voltage linearly for continuous PA power adjustment. The gain from REFIN to OUT is 2.5V/V. At high-duty cycle, the device automatically switches to a bypass mode, connecting the input to the output through a low-impedance MOSFET. The LDOs are designed for low-noise operation, wherein each LDO in the device is individually enabled through its own logic control interface. The device is available in a 16-pin WLP (2x2mm) package.

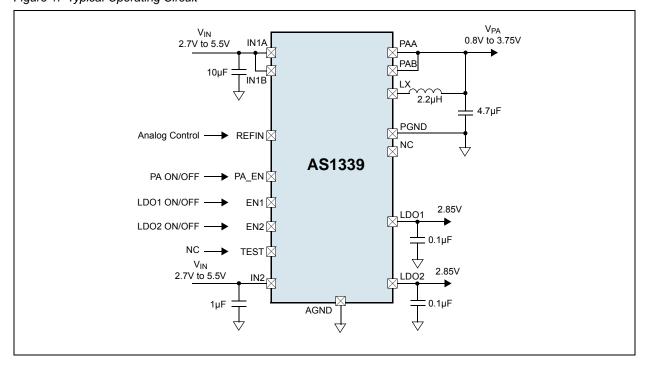
2 Key Features

- Fixed Switching Frequency: 2MHz
- PA Step-Down Converter
- Low Dropout Voltage
- Low Output-Voltage Ripple
- Dynamic Output Voltage Control (0.8V to 3.75V)
- 30µs Settling Time for 0.8V to 3.4V Output Voltage Change
- 650mA Output Drive Capability
- Two 10mA Low-Noise LDOs
- Low Shutdown Current
- Supply Voltage Range: 2.7V to 5.5V
- Thermal Shutdown
- 16-pin WLP (2x2mm) package

3 Applications

The AS1339 is ideal for WCDMA/NCDMA cellular handsets, Wireless PDAs, and Smartphones.

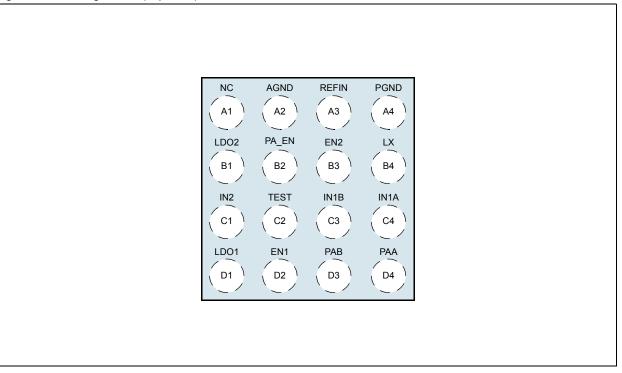






4 Pinout

Figure 2. Pin Assignments (Top View)



Pin Description

Table 1. Pin Description

Pin Name	Pin Number	Description
NC	A1	Not Connected. Free, high impedance for normal operation. Used for internal test purpose.
AGND	A2	Low-Noise Analog Ground
REFIN	A3	DAC-Controlled Input. Reference voltage for buck converter. The output of the PA step-down converter is regulated to 2.5 x VREFIN. Bypass mode is enabled when VIN \leq 2.69V x VREFIN.
PGND	A4	Power Ground for PA Step-Down Converter
LDO2	B1	10mA LDO Regulator 2 Output. Connect LDO2 with a $0.1\mu F$ ceramic capacitor as close as possible to LDO2 and AGND. LDO2 is internally pulled down through a 100Ω resistor when this regulator is disabled.
PA_EN	B2	PA Step-Down Converter Enable Input. For normal operation, connect to logic-high. For shutdown mode, connect to logic-low. The pin is internally pulled down through a $110k\Omega$ resistor.
EN2	В3	Enable Input for LDO2. For normal operation, connect to logic-high. For shutdown mode, connect to logic-low. The pin is internally pulled down through a $110k\Omega$ resistor.
LX	B4	Inductor Connection. Connect an inductor from LX to the output of the PA step-down converter.

Table 1. Pin Description

Pin Name	Pin Number	Description
IN2	C1	Supply Voltage Input for LDO1 and LDO2. Connect IN2 to a battery or supply voltage from 2.7V to 5.5V. Decouple IN2 with a 1µF ceramic capacitor as close as possible to IN2 and AGND. Connect IN2 to the same source as IN1A and IN1B.
TEST	C2	NC. Used for internal test purpose. The pin is internally pulled down with a $110k\Omega$ resistor.
IN1B, IN1A	C3, C4	Supply Voltage Input for PA Step-Down Converter. Connect IN1A/B to a battery or supply voltage from 2.7V to 5.5V. Decouple IN1A/B with a 10µF ceramic capacitor as close as possible to IN1A/B, and PGND. IN1A and IN1B are internally connected together. Connect IN1A/B to the same source as IN2.
LDO1	D1	10mA LDO Regulator 1 Output. Decouple LDO1 with a $0.1\mu F$ ceramic capacitor as close as possible to LDO1 and AGND. LDO1 is internally pulled down through a 100Ω resistor when this regulator is disabled.
EN1	D2	Enable Input for LDO1. For normal operation, connect to logic-high. For shutdown mode, connect to logic-low. The pin is internally pulled down through a $110k\Omega$ resistor.
PAB, PAA	D3, D4	PA Connection for Bypass Mode. Internally connected to IN1A/B using the internal bypass MOSFET during bypass mode. Connect PAA/B with a 4.7µF ceramic capacitor as close as possible to PAA/B and PGND.

5 Absolute Maximum Ratings

Stresses beyond those listed in Table 2 may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in Electrical Characteristics on page 5 is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Table 2. Absolute Maximum Ratings

Parameter	Min	Max	Units	Comments
IN1A, IN1B, IN2 to AGND	-0.3	+7	V	
PAA, PAB, PA_EN, TEST, REFIN, NC to AGND	-0.3	VIN1A/ VIN1B + 0.3	٧	
LDO1, LDO2, EN1, EN2 to AGND	-0.3	V _{IN2} + 0.3	٧	
IN2 to IN1B/IN1A	-0.3	+0.3	V	
PGND to AGND	-0.3	+0.3	V	
LX Current		0.7	ARMS	
Bypass Current		1.6	ARMS	
Storage Temperature Range	-65	+150	°C	
Package Body Temperature		+260	°C	The reflow peak soldering temperature (body temperature) specified is in accordance with IPC/JEDEC J-STD-020D "Moisture/Reflow Sensitivity Classification for Non-Hermetic Solid State Surface Mount Devices".
ESD Rating				
Human Body Model		1	kV	HBM MIL-Std. 883E 3015.7 methods
Operating Ratings				
REFIN Common-Mode Range	0	VIN	V	
Recommended Load Current		650	mA	
Continuous Power Dissipation P _{D-MAX}		0.75	W	Ta = +65°C; derate 12.5mW/°C above +65°C
Junction Temperature (T _J) Range	-40	+125	°C	
Ambient Temperature (T _A) Range	-40	+85	°C	In applications where high power dissipation and/or poor package thermal resistance is present, the maximum ambient temperature may have to be derated. Maximum ambient temperature (T_{A-MAX}) is dependent on the maximum operating junction temperature ($T_{J-MAX-OP} = 125^{\circ}C$), the maximum power dissipation of the device in the application (P_{D-MAX}), and the junction-to ambient thermal resistance of the part/package in the application (θ_{JA}), as given by the following equation: $T_{A-MAX} = T_{J-MAX-OP} - (\theta_{JA} \times P_{D-MAX})$.

6 Electrical Characteristics

 $V_{IN1A} = V_{IN1B} = V_{IN2} = V_{PA_EN} = V_{EN1} = V_{EN2} = 3.6V$, $T_{A} = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$. Typical values are at $T_{A} = +25^{\circ}\text{C}$, (unless otherwise specified), for external components refer to Table 5 on page 7.

Table 3. Electrical Characteristics

Symbol	Parameter	Condition	Min	Тур	Max	Unit
Input Su	ipply					
VIN	Input Voltage Range		2.7		5.5	V
ISHDN	Shutdown Supply Current	VPA_EN = VEN1 = VEN2 = 0V ¹		0.1	1	μΑ
IQ	DC-DC No-Load Supply Current	VEN1 = VEN2 = 0V, ILOAD(DCDC) = 0mA, switching, VIN = 4.5V, VOUT = 3.4V		4.5	6	mA
DCDC O	utput Voltage					
	Output Voltage Range	PWM Mode	0.8		3.85	V
V		VREFIN = 0.32V, VIN = 3.9V	0.75	8.0	0.85	V
V _{OUT}	Output Voltage	VREFIN = 0.84V, VIN = 3.9V	2.05	2.1	2.15	V
		VREFIN = 1.36V, VIN = 3.9V	3.319	3.4	3.481	V
Thermal	Protection					
	Thermal Shutdown	TA rising, 10°C typical hysteresis		+140		°C
Logic Co	ontrol					
	PA_EN, EN1, EN2, Logic- Input High Voltage	2.7V ≤ VIN ≤ 5.5V	1.4			\
	PA_EN, EN1, EN2, Logic- Input Low Voltage	2.7V ≤ VIN ≤ 5.5V			0.5	٧
	Logic-Input Current	VIL = 0V	-1		+1	μΑ
	(PA_EN, EN1, EN2)	VIH = <i>VIN</i> = 5.5V		50	75	μΑ
REFIN						
	REFIN Operating Common-Mode Range		0.32		1.5	٧
	2	VREFIN = 0.32V	2.35	2.50	2.65	V/V
	REFIN gain Vout/VREFIN ²	VREFIN = 0.84V, 1.36V	2.44	2.50	2.56	V/V
	REFIN Current	VREFIN = VIN = 5.5V	-1		+1	μΑ
LX						
В	Pin-Pin Resistance for PFET	I _{SW} = 200mA; T _A = +25°C		110	200	 0
R _{DSONP}	PIII-PIII RESISTANCE TOT PPET	I _{SW} = 200mA			230	mΩ
D	Din Din Bosistanos for NEET	I _{SW} = -200mA; T _A = +25°C		230	415	 0
*DSONN	Pin-Pin Resistance for NFET	I _{SW} = -200mA			485	mΩ
	PFET Leakage Current	VIN = 5.5V, VLX = 0V		0.1	3	μΑ
	NFET Leakage Current	VIN = VLX = 5.5V		0.1	3	μA
	PFET Peak Current Limit	VLX = 0V		1100		mA
fosc	Internal Oscillator Frequency		1.8	2	2.2	MHz

Table 3. Electrical Characteristics (Continued)

Symbol	Parameter	Condition	Min	Тур	Max	Unit	
BYPASS	3						
	Bypass Activation Factor	VREFIN rising, 50mV hys	teresis	2.56	2.69	2.78	V/V
	On Registance Bypage DEET	I _{SW} = 200mA; T _A = +25°	С		110	200	m()
	On-Resistance Bypass PFET	I _{SW} = 200mA				230	mΩ
	PFET Bypass Off-Leakage Current	<i>VIN</i> = 5.5V, VPAA = VPAB = 0V	•			3	μA
LDO1/2					I		
	Output Voltage	IOUT = 0mA, 10mA;		2.75	2.85	2.95	V
	Quiescent Current	one LDO enabled	Louiz — Ome A		25	50	
	Quiescent Current	both LDOs enabled	IOUT = 0mA		40	80	μA
	Output Current			10			A
	Current Limit	Vout = 0V		20	35	50	mA
	Dropout Voltage ³	IOUT = 10mA			20	50	mV
Roff	Shutdown Output Impedance	VEN1/2 = 0V			100		Ω

- 1. Current into supply pins without leakage of DCDC switches.
- 2. Limited by the 50mV output voltage accuracy for VREFIN < 0.84V
- 3. The dropout voltage is the input to output difference at which the output is 100mV below its nominal value.

System Characteristics

 $V_{IN1A} = V_{IN1B} = V_{IN2} = V_{PA_EN} = V_{EN1} = V_{EN2} = 3.9V$, $T_{A} = -40^{\circ}\text{C}$ to $+85^{\circ}\text{C}$. Typical values are at $T_{A} = +25^{\circ}\text{C}$, (unless otherwise specified), for external components refer to Table 5 on page 7. The following parameters are verified by characterisation and are not production tested.

Table 4. System Characteristics

Symbol	Parameter	Condition	Min	Тур	Max	Unit
REFIN				•		
	REFIN gain variation; relative linearity ¹	10.32 / < VDEEIN < 1.4 /			3	%
	REFIN gain variation;	0.84V ≤ VREFIN ≤ 1.4V	-2.4		2.4	%
	absolute linearity ²	0.32V ≤ VREFIN ≤ 0.84V	-50	±10	50	mV
LX						
	Ripple voltage, PWM mode ³	Vout = 0.8 to 3.4V, RLOAD = 8Ω , no bypass mode, no pulse-skip condition		10	25	
Line_tr	Line transient response	VIN = 3.4 to 3.9V, VOUT = 3.0V, IOUT = 300mA, VIN increase 300mV in 10µs		30	50	mVp-p
Load_tr	Load transient response	Vin = 3.4 to 4.2V, Vout = 3.0V, T _{RISE} = T _{FALL} = 10μs, lout = 100 to 300mA		50	70	

Table 4. System Characteristics (Continued)

Symbol	Parameter Condition		Min	Тур	Max	Unit
	Start-Up Time	From PA_EN switch from 0V to 1.7V, VOUT = 3.4V, ILOAD = 0mA, within 50mV regulation error		100	150	
	Regulation Time; Rise Time	Vout from 0.8V to 3.4V, RLOAD = 8Ω , within 50mV regulation error		30	50	μs
	Regulation Time; Fall Time	Vout from 3.4V to 0.8V, RLOAD = 8Ω , within 50mV regulation error		30	50	
LDO						
	Start-Up Time	IOUT=10mA, within 100mV of VOUT		30	50	
	Shut-Down Time	IOUT=0mA, within 100mV of GND		50	100	μs
	Line Regulation ⁴	VIN = 4V to 3.5V; IOUT = 10mA;			10	mV
	Load Regulation	Ιουτ stepped from 50μA to 10mA			25	1110
	<u></u>	IOUT = 4mA, VIN = 3.2V, f = 100kHz	45			٩D
	Ripple Rejection ⁵	IOUT = 4mA, VIN = 3.2V, f = 2MHz	45			dB
	Output Noise ⁶	10Hz to 100kHz, IOUT = 10mA		50	100	μVRMS

- 1. The relative linearity is defined as the difference of the minimum to the maximum gain over the entire REFIN range.
- 2. The absolute linearity is defined as the actual gain error (AE) of every applied VREFIN voltage between 0.32V and 1.4V.

$$AE = \left(\frac{V_{OUT}}{2,5 \times V_{REFIN}} - 1\right) \times 100$$

- The ripple voltage should measured at C_{OUT} electrode on good layout PC board and under condition using suggested inductors and capacitors.
- 4. For dynamic change in Vout (Line transient response) when VIN drops 500mV from 4V (see Figure 48 on page 15); Slew rate= 40mV/µs.
- 5. VRIPPLE = 200mVpp; TA = +25°C; CIN1, CIN2 removed; PA EN = 0V;
- 6. VIN = 3.2V; TA = +25°C; $PA_EN = 3.2V$;

Table 5. External Components used for Characterisation

Name	Part Number	Value	Rating	Туре	Size	Manufacturer
CIN1	GRM21BR60J106KE01	10µF	6.3V	X5R	0000	Murata
CIN2	GRM155R61A105KE15	1µF	10V	X5R	0402	www.murata.com
Соит	C0603C475K8PAC7867	4.7µF	10V	X5R	0000	KEMET
CLDO1, CLDO2	C0402C104K4RAC	100nF	16V	X7R	0402	www.kemet.com
L	MLP2520S3R3S	3.3µH	1A	110mΩ	1 2 2 2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	TDK www.coilcraft.com

7 Typical Operation Characteristics

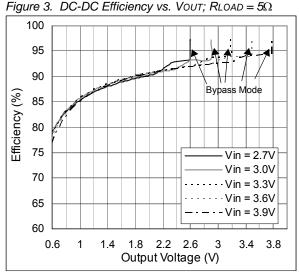


Figure 5. DC-DC Efficiency vs. Vout; RLOAD = 10Ω

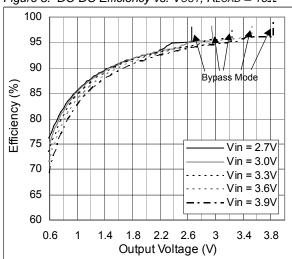


Figure 7. DC-DC REFIN vs. Vout; RLOAD = 7.5Ω

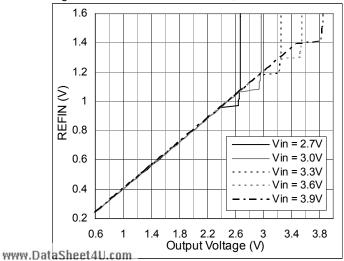


Figure 4. DC-DC Efficiency vs. Vout; RLOAD = 7.5Ω

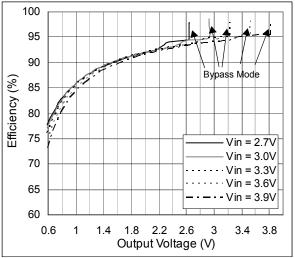


Figure 6. DC-DC REFIN vs. Vout; RLOAD = 5Ω

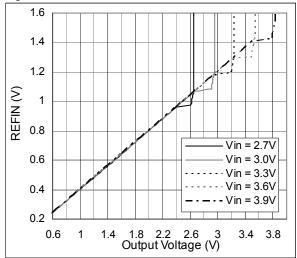
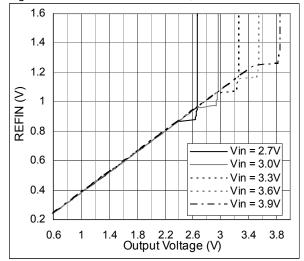


Figure 8. DC-DC REFIN vs. Vout; RLOAD = 10Ω



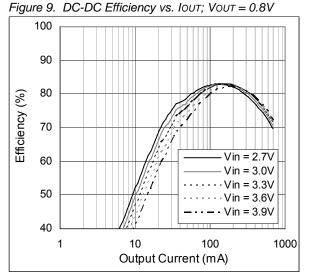


Figure 10. DC-DC Efficiency vs. IOUT; VOUT = 1.2V

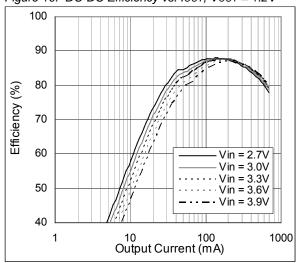


Figure 11. DC-DC Efficiency vs. IOUT; VOUT = 1.8V

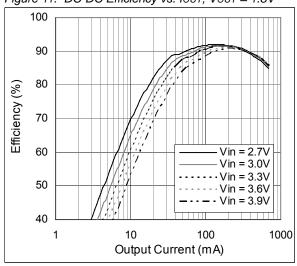


Figure 12. DC-DC Efficiency vs. IOUT; VOUT = 2.2V

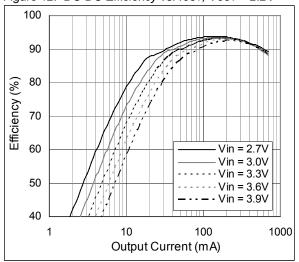


Figure 13. DC-DC Load Regulation, Vout vs. Iout; Vout = 0.8V

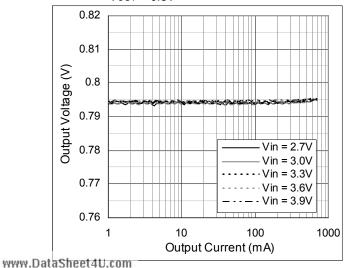


Figure 14. DC-DC Load Regulation, Vou τ vs. Iou τ ; Vou τ = 1.2V

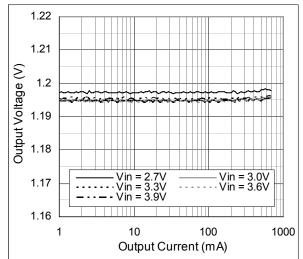


Figure 15. DC-DC Load Regulation, Vout vs. Iout; Vout = 1.8V

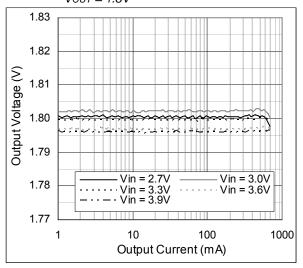


Figure 17. DC-DC Efficiency vs VIN; Vout = 3.8V

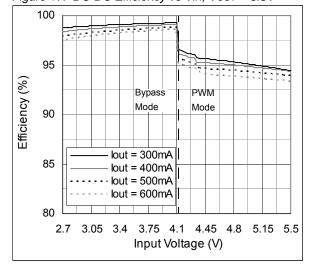


Figure 19. DC-DC Efficiency vs VIN; VOUT = 2.0V

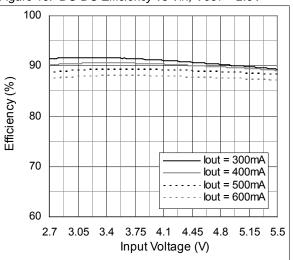


Figure 16. DC-DC Load Regulation, VouT vs. IouT; VouT = 2.2V

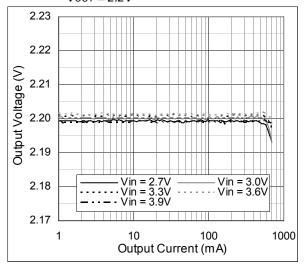


Figure 18. DC-DC Efficiency vs VIN; Vout = 3.4V

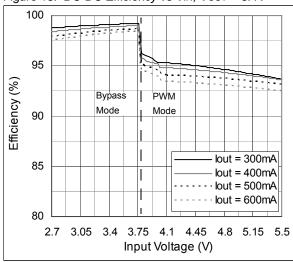


Figure 20. DC-DC Efficiency vs VIN; VOUT = 1.5V

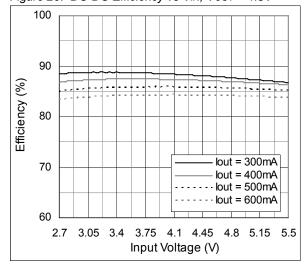


Figure 21. DC-DC Efficiency vs Input Voltage; Vout = 1.0V

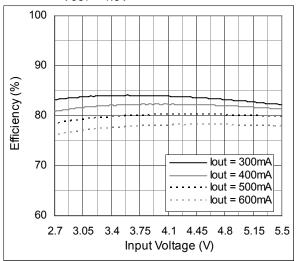


Figure 23. DC-DC Line Regulation, Vout vs. VIN; Vout = 3.4V

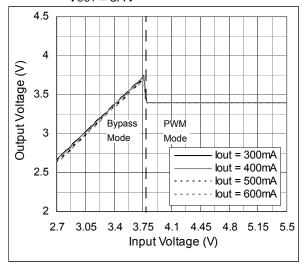


Figure 25. DC-DC Line Regulation, VouT vs. VIN; VouT = 1.5V

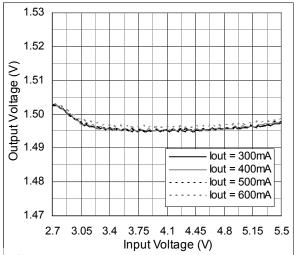


Figure 22. DC-DC Line Regulation, Vout vs. VIN; Vout = 3.8V

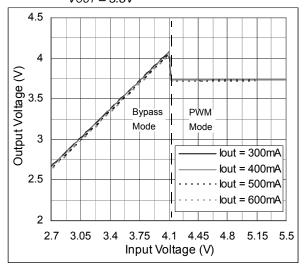


Figure 24. DC-DC Line Regulation, Vout vs. VIN; Vout = 2.0V

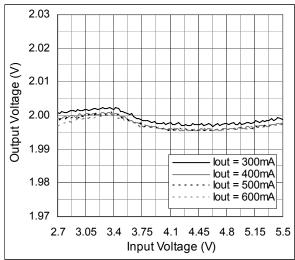


Figure 26. DC-DC Line Regulation, Vout vs. VIN; Vout = 1.0V

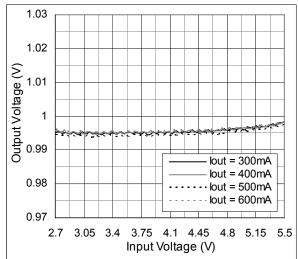


Figure 27. DC-DC Output Voltage Error vs. Reference Voltage

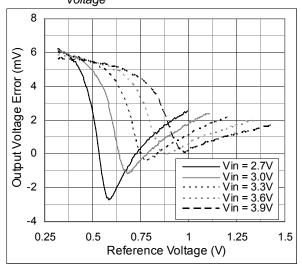


Figure 29. DC-DC No-Load Supply Current vs. VIN

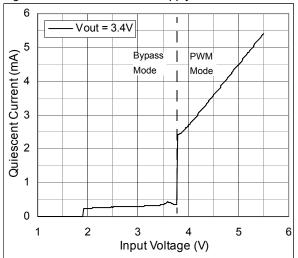


Figure 31. DC-DC Switching; VIN=3.6V, VPA=1.2V, IOUT=50mA

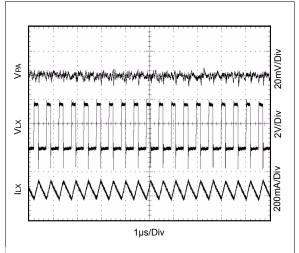


Figure 28. DC-DC Bypass Dropout Voltage vs. Output Current

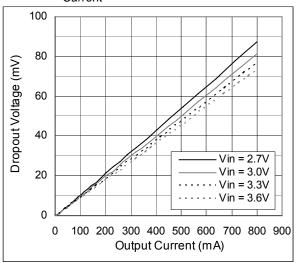


Figure 30. Shutdown Supply Current vs. VIN

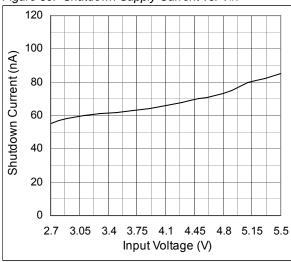


Figure 32. DC-DC Switching; VIN=3.6V, VPA=1.2V, IOUT=500mA

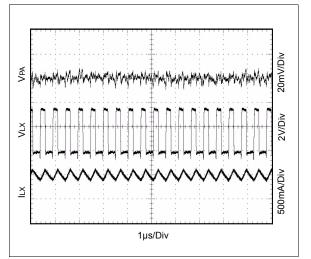


Figure 33. DC-DC Soft-Start; $RLOAD = 7.5\Omega$

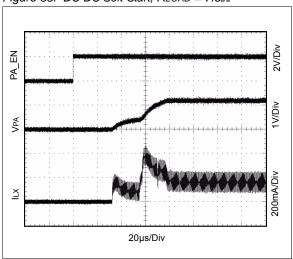


Figure 34. DC-DC Shutdown

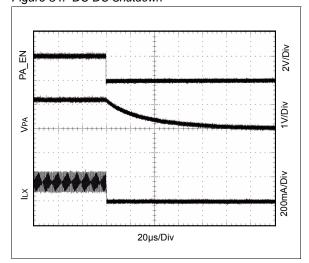


Figure 35. DC-DC Sine Wave Output in PWM Mode; VIN = 4.5V, $RLOAD = 7.5\Omega$

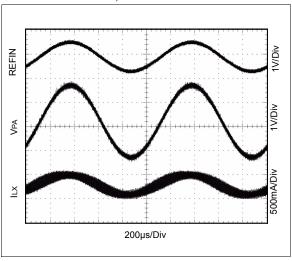


Figure 36. DC-DC Sine Wave Output in Bypass Mode; $VIN = 3.6V, RLOAD = 7.5\Omega$

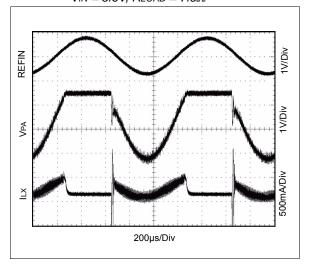


Figure 37. DC-DC Rectangular Wave Output in PWM Mode; $V_{\rm IN} = 4.5 V$, $R_{\rm LOAD} = 7.5 \Omega$

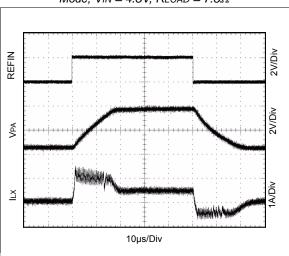


Figure 38. DC-DC Rectangular Wave Output in Bypass Mode; VIN = 3.6V, $RLOAD = 7.5\Omega$

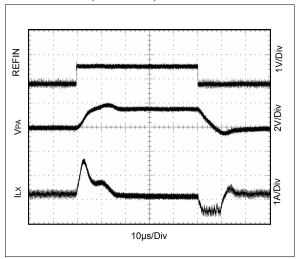


Figure 39. DC-DC Line Transient; VIN = 4.0V to 3.5V, VOUT = 1.2V, RLOAD = 10 Ω

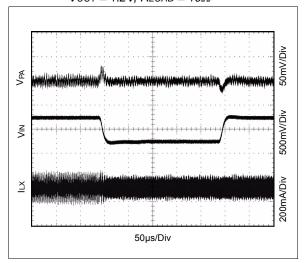


Figure 40. DC-DC Load Transient; IOUT = 0mA to 500mA, VIN = 3.6V, VOUT = 2.5V

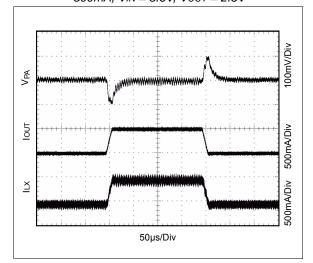


Figure 41. LDO Quiescent Current vs. VIN

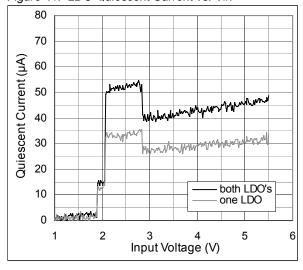


Figure 42. LDO Line Regulation, Vout vs. VIN

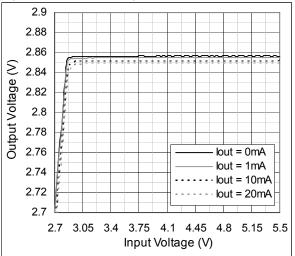


Figure 43. LDO PSRR vs. Freq.; VIN = 3.2V, VOUT = 2.85V, VRIPPLE = 200mVPP, COUT = 100nF

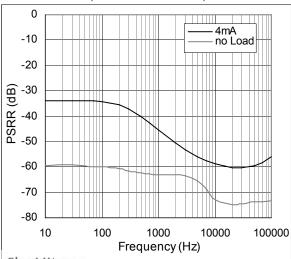


Figure 44. LDO Output Noise vs. Freq.; VIN = 3.2V, VOUT = 2.85V, COUT =100nF

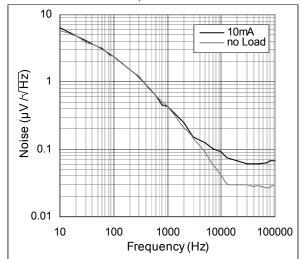
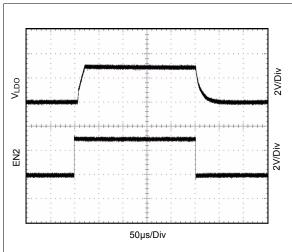


Figure 45. LDO Turn ON/OFF Response; VIN = 3.6V, no load



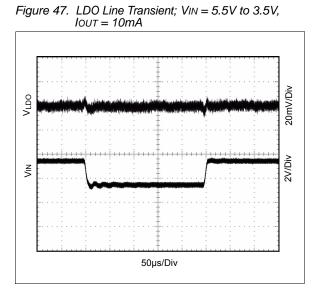


Figure 46. LDO Load Transient; IOUT = 0mA to 10mA, VIN = 3.6V

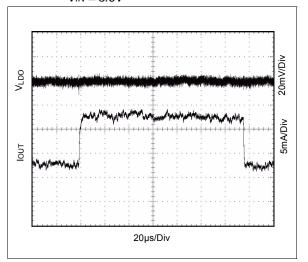
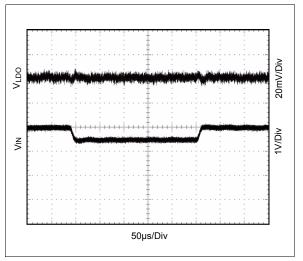


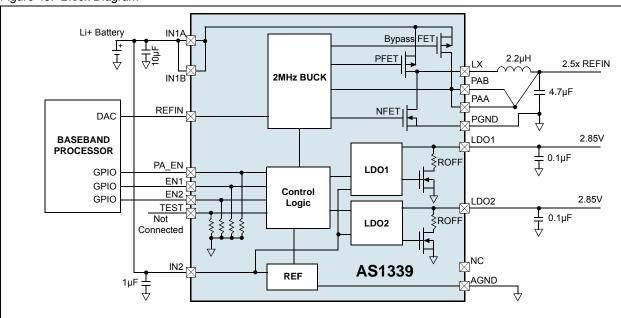
Figure 48. LDO Line Transient; VIN = 4.0V to 3.5V, IOUT = 10mA



8 Detailed Description

The AS1339 is designed to dynamically power the PA in WCDMA and NCDMA handsets. The device is empowered with a high-frequency, high-efficiency step-down converter, and two LDOs. The step-down converters are capable of delivering 650mA. The PWM control scheme provides fast transient response, while 2MHz switching frequency allows the trade-off between efficiency and small external components. A $110m\Omega$ bypass FET connects the PA directly to the battery during high-power transmission.

Figure 49. Block Diagram



Operating the AS1339

The AS1339's control block turns on the internal PFET (P-channel MOSFET) switch during the first part of each switching cycle, thus allowing current to flow from the input through the inductor to the output filter capacitor and load. The inductor limits the current to a ramp with a slope of (VIN - VOUT) / L, by storing energy in a magnetic field.

During the second part of each cycle, the controller turns the PFET switch off, blocking current flow from the input, and then turns the NFET (N-channel MOSFET) synchronous rectifier on. As a result, the inductor's magnetic field collapses, generating a voltage that forces current from ground through the synchronous rectifier to the output filter capacitor and load.

While the stored energy is transferred back into the circuit and depleted, the inductor current ramps down with a slope of Vout / L. The output filter capacitor stores charge when the inductor current is high, and releases it when low, smoothing the voltage across the load. The output voltage is regulated by modulating the PFET switch on-time to control the average current sent to the load.

The output voltage is equal to the average voltage at the LX pin.

While in operation, the output voltage is regulated by switching at a constant frequency and then modulating the energy per cycle to control the power to the load. Energy per cycle is set by modulating the PFET switch on-time pulse width to control the peak inductor current. This is done by comparing the signal from the current-sense amplifier with a slope compensated error signal from the voltage-feedback error amplifier. At the beginning of each cycle, the clock turns on the PFET switch, causing the inductor current to ramp up. When the current sense signal ramps past the error amplifier signal, the PWM comparator turns off the PFET switch and turns on the NFET synchronous rectifier, ending the first part of the cycle.

If an increase in load pulls the output down, the error amplifier output increases, which allows the inductor current to ramp higher before the comparator turns off the PFET. This increases the average current sent to the output and



adjusts for the increase in the load. Before appearing at the PWM comparator, a slope compensation ramp from the oscillator is subtracted from the error signal for stability of the current feedback loop.

Internal Synchronous Rectifier

To reduce the rectifier forward voltage drop and the associated power loss, the AS1339 uses an internal NFET as a synchronous rectifier. The big advantage of a synchronous rectification is the higher efficiency in a condition where the output voltage is low compared to the voltage drop across an ordinary rectifier diode. During the inductor current down slope in the second part of each cycle the synchronous rectifier is turned on. Before the next cycle the synchronous rectifier is turned off.

There is no need for an external diode because the NFET is conducting through its intrinsic body diode during the transient intervals before it turns on.

Bypass Mode

This mode connects IN1A and IN1B directly to PAA and PAB with the internal $110m\Omega$ (typ) bypass FET, while the step-down converter is forced into 100% duty-cycle operation during high-power transmission. Due to the low on-resistance in this mode, the result is low dropout, high efficiency and a high output current capability.

The AS1339 enters bypass mode automatically when $VIN \le 2.69 \times VREFIN$ and thus prevents excessive output ripple as the step-down converter approaches dropout. Due to an internal limitation of VREFIN $\le 1.5V$ the maximum output voltage is limited to $2.78 \times 1.5V = 4.17V$ in Bypass Mode.

Shutdown Mode

To put the PA step-down converter in shutdown mode, connect PA_EN to GND or disconnect PA_EN (NC =>logic-low). During shutdown mode, the control circuitry, internal switching MOSFET, and synchronous rectifier are turned off and LX becomes high impedance. For normal operation, connect PA_EN to IN1A/B or logic-high.

To place LDO1 or LDO2 in shutdown mode, connect EN1 or EN2 to GND or disconnect EN1 or EN2 (NC => logic-low). The outputs of the LDOs are pulled to ground through an internal 100Ω resistor during shutdown. When the PA stepdown and LDOs are all in shutdown, the AS1339 enters a very low power state, where the input current drops to 0.8μ A (typ).

Note: All enable Pins (PA EN, EN1 and EN2) have an internal $110k\Omega$ pull-down resistance.

Soft-Start

The internal soft-start circuitry of the PA step-down converter limits inrush current at startup, reducing transients on the input source. Soft-start is favorable for supplies with high output impedance such as Li+ and alkaline cells. The DC-DC can start-up with full output load of 7.5Ω .

Analog REFIN Control

The PA step-down converter uses REFIN to set the output voltage, which enables the converter to operate in applications requiring dynamic voltage control. The output voltage is limited to an upper level of 3.85V, when operating in PWM mode. In Bypass mode the output voltage is limited to VIN.

Notes:

- 1. $VOUT = 2.5 \times VREFIN$
- 2. If REFIN is left floating the output voltage of the step-down converter can assume any value between 0.6V and VIN.

Thermal Overload Protection

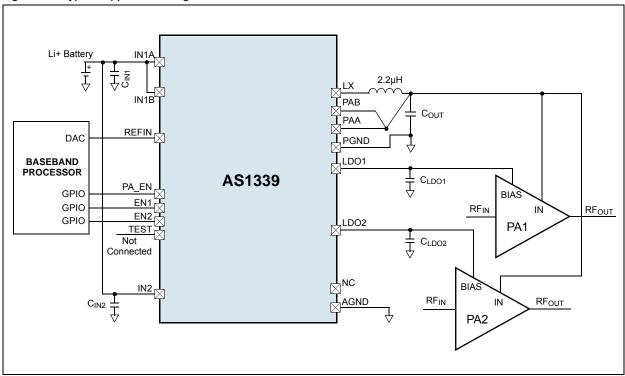
To prevent the AS1339 from short-term misuse and overload conditions the chip includes a thermal overload protection. To block the normal operation mode the device is turning off the PFET and the NFET in PWM and bypass mode as soon as the junction temperature exceeds 140°C. To resume the normal operation the temperature has to drop below 130°C.

Note: Continuing operation in thermal overload conditions may damage the device and is considered bad practice.

9 Application Information

The AS1339 is designed to supply power amplifiers for RF applications. The output power of the PA can directly be controlled via the output voltage of the AS1339. Figure 50 shows a typical application.

Figure 50. Typical Application Diagram



Capacitor Selection for Step-Down Converter

Input Capacitor

To reduce the current peaks drawn from the battery or power source and to reduce the switching noise in the device an input capacitor is highly recommended. At the switching frequency the impedance of the capacitor should be very low. It's recommended to use a X5R or X7R dielectric multilayer ceramic capacitor due to their small size, low ESR and small temperature coefficients. For most applications a $4.7\mu F$ capacitor is sufficient. To decrease the interfering noise and to lower the input ripple the capacitor value can be set higher (e.g. $10\mu F$).

Output Capacitor

To ensure a stable loop regulation and a small output voltage ripple a low impedance capacitor should be used. It's recommended to use a X5R or X7R dielectric multilayer ceramic capacitor due to their small size, low ESR and small temperature coefficients. For most applications a $4.7\mu F$ capacitor is sufficient. To achieve a better load-transient performance and to decrease the output ripple the capacitor value can be set higher (e.g. $10\mu F$).

Table 6. Recommended Capacitors for the Step-Down Converter

Name	Part Number	С	Voltage	Туре	Size	Manufacturer
	GRM21BR60J106KE01	10μF	6.3V	X5R	0805	Murata
CIN1. COUT	GRM21BR61C475KA88	4.7µF	16V	X5R	0805	www.murata.com
CINT, COUT	C0603C475K8PAC7867	4.7uF	10V	X5R	0603	KEMET
	0000004751K01 A07007	τ./ μι	10 V	Xorx	0000	www.kemet.com

www.DataSheet4U.com

Capacitor Selection for LDO's

Input Capacitor

The capacitor for the LDO Input should have at least a value of the sum of the output capacitors of LDO1 and LDO2. With a larger input capacitance and lower ESR a better noise rejection and line transient response can be achieved.

Output Capacitor

For the LDO outputs the capacitor value depends on the needed load current. For a stable operation with rated maximum load currents a minimum output capacitor of 1µF is recommended. At light loads of 10mA or less a 0.1µF capacitor is sufficient. With larger output capacitance a reduced output noise, improved load-transient response, better stability and power-supply rejection can be achieved.

Table 7. Recommended Capacitors for the LDO's

Name	Part Number	С	Voltage	Туре	Size	Manufacturer
CIN2, CLDO1,	C0402C104K4RAC	100nF	16V	X7R	0402	KEMET www.kemet.com
CLDO2	GRM155R61A105KE15	1µF	10V	X5R	0402	Murata www.murata.com

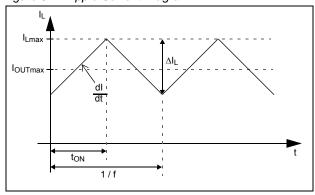
Inductor Selection

For most applications the value of the external inductor should be in the range of 1.5µH to 4.7µH as the inductor value has a direct effect on the ripple current. The selected inductor must be rated for its DC resistance and saturation current. The inductor ripple current (ΔIL) decreases with higher inductance and increases with higher VIN to VOUT.

In Equation (EQ 3) the maximum inductor current in PWM mode under static load conditions is calculated. The saturation current of the inductor should be rated higher than the maximum inductor current as calculated with Equation (EQ 4). This is recommended because the inductor current will rise above the calculated value during heavy load transients.

The inductor current ripple ΔIL (see EQ 3) is defined by the slope of the current (dI / dt) (see EQ 1) multiplied by the PFET on-time ton (see EQ 2).

Figure 51. Ripple Current Diagram



$$\frac{dI}{dt} = \frac{V_{IN} - V_{OUT}}{L} \tag{EQ 1}$$

$$t_{ON} = DutyCycle \times \frac{1}{f}$$
 $DutyCycle = \frac{V_{OUT}}{V_{IN}}$ (EQ 2)

$$\Delta I_L = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times f \times L}$$
 (EQ 3)

$$I_{LMAX} = I_{OUTMAX} + \frac{\Delta I_L}{2}$$
 (EQ 4)

f Switching Frequency (2.0MHz typical)

L Inductor Value

ILMAX Maximum Inductor current

 $\Delta I L \ \ Peak to Peak inductor ripple current$

IOUTMAX Applied load current

Accepting larger values of ripple current allows the use of low inductance values, but results in higher output voltage ripple, greater core losses, and lower output current capability. The total losses of the coil have a strong impact on the efficiency of the dc/dc conversion and consist of both the losses in the dc resistance and the following frequency-dependent components:

- 1. The losses in the core material (magnetic hysteresis loss, especially at high switching frequencies)
- 2. Additional losses in the conductor from the skin effect (current displacement at high frequencies)
- 3. Magnetic field losses of the neighboring windings (proximity effect)
- 4. Radiation losses

Note: For highest efficiency, a low DC-resistance inductor is recommended.

Table 8. Recommended Inductors

Part Number	L	DCR	Current Rating	Dimensions (L/W/T)	Manufacturer
MLP2520S1R5S	1.5µH	$80 \text{m}\Omega$	1.5A	2.5x2.0x1.2mm	TDK
MLP2520S2R2S	2.2µH	110m Ω	1.2A	2.5x2.0x1.2mm	www.tdk.com
MLP2520S3R3S	3.3µH	110mΩ	1.0A	2.5x2.0x1.2mm	
EPL2014-222MLC	2.2µH	120mΩ	0.98A	2.2x2.0x1.4mm	Coilcraft
EPL2014-332MLC	3.3µH	152mΩ	0.8A	2.2x2.0x1.4mm	www.coilcraft.com
EPL2014-472MLC	4.7µH	231mΩ	0.65A	2.2x2.0x1.4mm	
XPL2010-222ML	2.2µH	156mΩ	1.2A	2.0x1.9x1.0mm	
XPL2010-332ML	3.3µH	207mΩ	0.925A	2.0x1.9x1.0mm	



Figure 52. Efficiency Comparison of different Inductors; VIN = 3.9V, VOUT = 1.0V

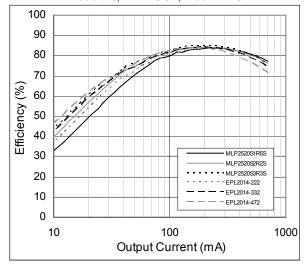
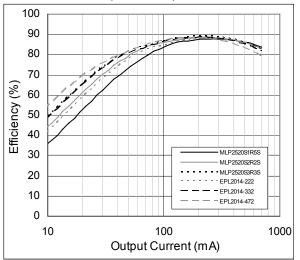


Figure 53. Efficiency Comparison of different Inductors; VIN = 3.9V, VOUT = 1.5V



Example

The following system should be designed:

- A supply with a Lithium-Ion Battery = 4.5V
- Vout = 3.0V
- Iоитмах = 500mA

For the first step VREF is calculated as shown in Equation (EQ 5).

$$V_{REF} = \frac{V_{OUT}}{2.5} = 1,2V$$
 (EQ 5)

$$V_{IN} \le 2,69 \times V_{REF}$$
 (EQ 6)

Due to Equation (EQ 6): VIN = 3.23V

If Vin is falling below 3.23V the device is going into Bypass mode (see Bypass Mode on page 17).

Hence a 2.2μH coil is used, ΔIL can be calculated with Equation (EQ 3): ΔIL= 227mA

With this result IMAX can be calculated with Equation (EQ 4): IMAX = 614mA.

The saturation current of the coil should be chosen slightly higher than IMAX because heavy load transients could increase the peak current. For a short period of time (~50µs) the peak inductor current can rise up to a value of approximately 1.1A (p-channel MOSFET peak current limit). In this case a coil with a rated saturation current of ~800mA can be chosen.

Layout Considerations

High peak currents of up to 1.1A and a high switching frequency makes the PCB layout important. Following rules should be considered:

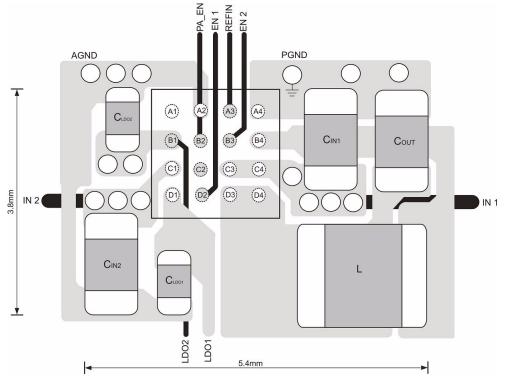
- The power traces (IN1A, IN1B, IN2, LX, PAA, PAB, PGND) should be kept as short, direct and wide as practical.
- All capacitors should be placed as close as possible near the device.
- Try to keep the serial resistance (ESR) of CLDO1 and CLDO2 as low as possible.
- The negative terminations of the capacitors Cout and CIN should be kept as close to each other as possible. A starpoint to PGND is recommended.

As shown in Figure 54 the current path between the pins IN1A/IN1B (C3/C4) and pin PGND (A4) via CIN1 is kept as short as possible. Also the current path between the pins PAB/PAA (D3/D4) and pin PGND (A4) via COUT is very close. The negative terminals of CIN1 and COUT are connected to pin PGND (A4) as a starpoint.

In order to keep noise emissions suppressed the connection between pin LX (B4) and the pins PAB/PAA (D3/D4) via the coil is kept very short. A shielded coil is recommended.

To keep the influence of the DC-DC on the LDOs in terms of supply ripple and noise quite low the IN1, IN2 and AGND, PGND path are separated in the layout. These power paths should be connected via a starpoint directly at the supply.

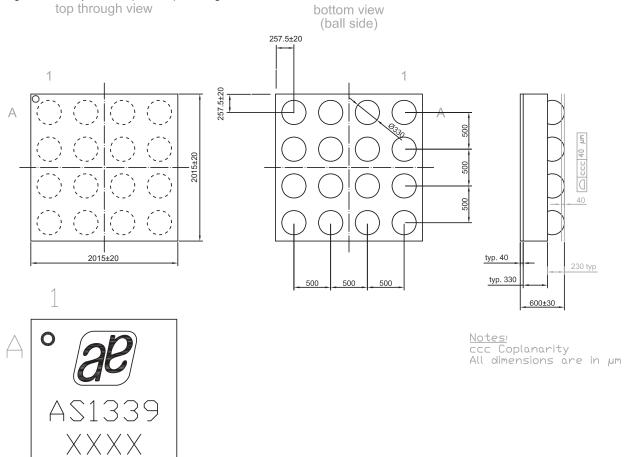




10 Package Drawings and Markings

The devices are available in a 16-pin WLP (2x2mm) package.

Figure 55. 16-pin WLP (2x2mm) Package





11 Ordering Information

The devices are available as the standard products shown in Table 9.

Table 9. Ordering Information

Part Number	Marking	Description	Delivery Form	Package
AS1339-BWLT	AS1339	650mA RF Step-Down DC-DC for PA, with two LDOs	Tape and Reel	16-pin WLP (2x2mm)

All devices are RoHS compliant and free of halogene substances.



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