

DATA SHEET

Part No.	AN30888B
Package Code No.	*QFN016-P-0304B

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AN30888B

High Brightness LED Driver IC

■ Overview

AN30888B is a Boost/Buck-Boost/Buck DCDC controller that drives an external power NMOS switch.
It is suitable for driving high brightness LED for LED lighting applications.

■ Features

- Battery operation : 3 V to 15 V
- Output current range : 0 A to a few Amperes depending on rating of external NMOS and mode of operation
- Current mode control architecture
- LED dimming function available by using PWM signal
- 30 mV / 200 mV reference voltage
- Low standby current
- Configurable as either Boost/Buck-Boost/ Buck mode converter
- Built-in various protection circuit : Under voltage lock out
Over voltage protection
Soft start function

■ Applications

- LED lighting module
- LED lantern applications
- White LED backlighting for LCD panel
- White LED flash light driving applications
- General LED back lighting

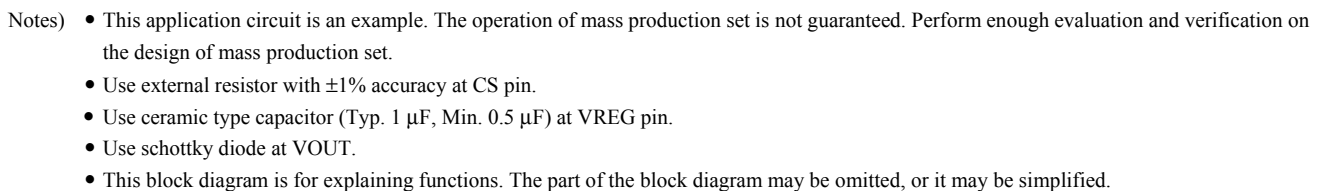
■ Package

- 16 pin Plastic Quad Flat Non-leaded Package (QFN Type)

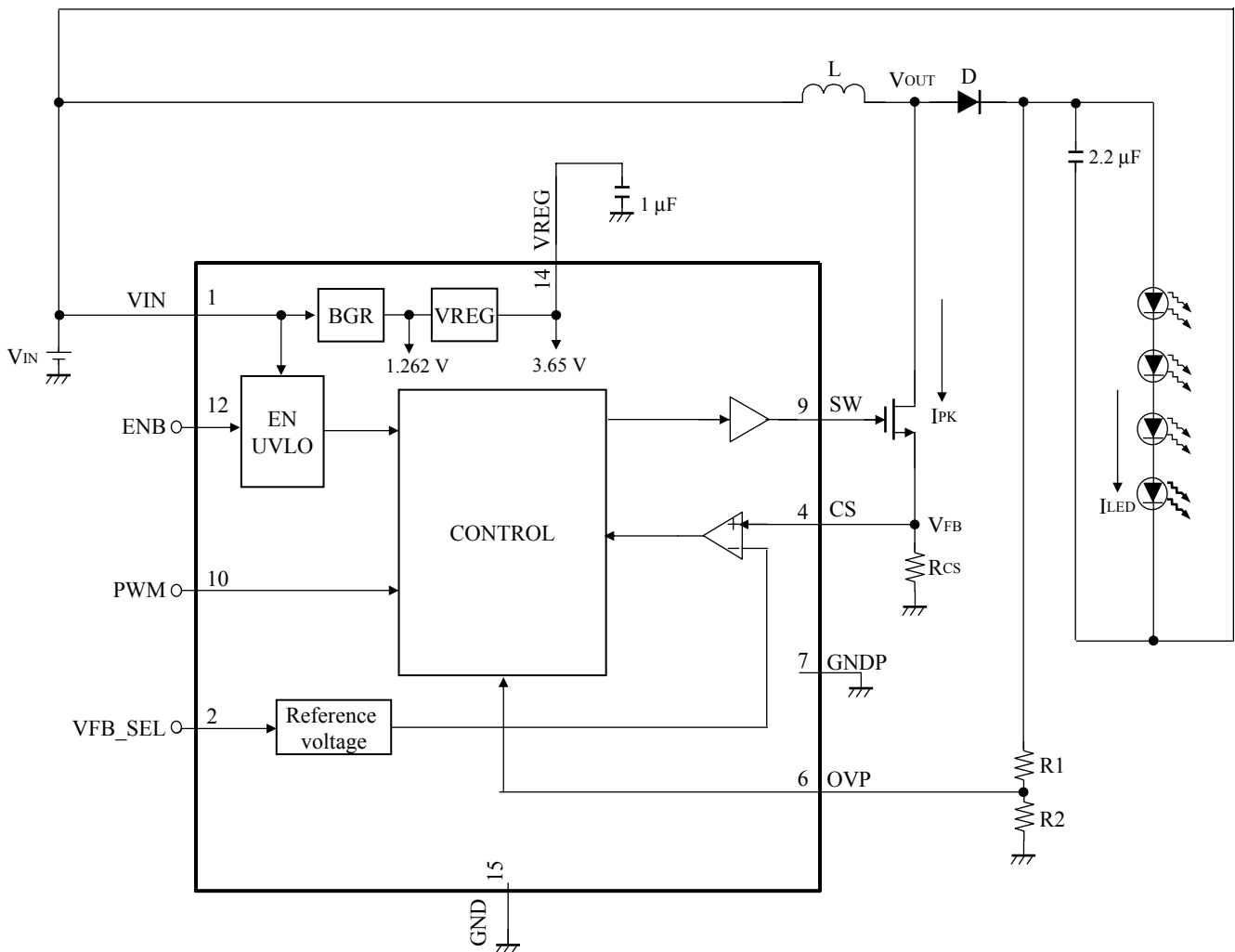
■ Type

- Bi-CMOS IC

- Boost Mode



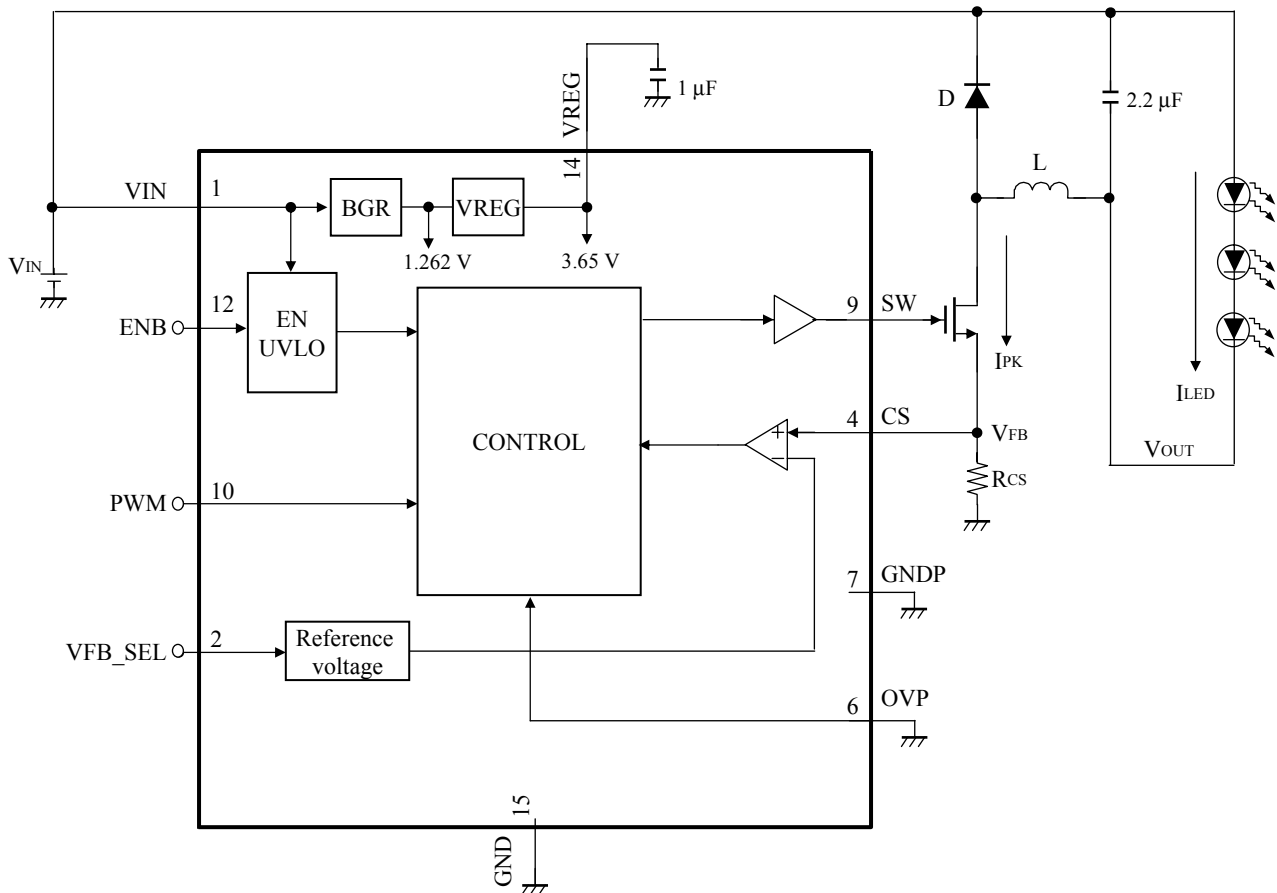
- Buck-Boost Mode



- Use external resistor with $\pm 1\%$ accuracy at CS pin.
- Use ceramic type capacitor (Typ. $1\ \mu\text{F}$, Min. $0.5\ \mu\text{F}$) at VREG pin.
- Use schottky diode at VOUT.
- This block diagram is for explaining functions. The part of the block diagram may be omitted, or it may be simplified.

■ Application Circuit Example (Block Diagram) (continued)

- Buck Mode



Notes) • This application circuit is an example. The operation of mass production set is not guaranteed. Perform enough evaluation and verification on the design of mass production set.

- Use external resistor with $\pm 1\%$ accuracy at CS pin.
- Use ceramic type capacitor (Typ. $1\ \mu\text{F}$, Min. $0.5\ \mu\text{F}$) at VREG pin.
- Use schottky diode at VOUT.
- This block diagram is for explaining functions. The part of the block diagram may be omitted, or it may be simplified.

■ Pin Descriptions

Pin No.	Pin name	Type	Description
1	VIN	Power Supply	Power Supply of IC
2	VFB_SEL	Input	Feedback voltage select
3	N.C.	—	—
4	CS	Input	Current Sense
5	N.C.	—	—
6	OVP	Input	Over Voltage Protection input pin for Boost mode; Connect to GND for Buck mode
7	GNDP	Ground	Power Ground
8	N.C.	—	—
9	SW	Output	External NMOS Transistor Gate Drive
10	PWM	Input	PWM Dimming Control
11	N.C.	—	—
12	ENB	Input	Standby On/Off Control
13	N.C.	—	—
14	VREG	Output	Regulator Output
15	GND	Ground	Ground
16	N.C.	—	—

■ Absolute Maximum Ratings

Note) Absolute maximum ratings are limit values which do not result in damages to this IC, and IC operation is not guaranteed at these limit values.

A No.	Parameter	Symbol	Rating	Unit	Notes
1	Supply voltage	V_{DD}	15.5	V	*1
2	GND pin current	I_{GND}	—	A	—
3	Power dissipation	P_D	100	mW	*2
4	Operating ambient temperature	T_{opr}	−25 to +85	°C	*3
5	Storage temperature	T_{stg}	−55 to +125	°C	*3

Notes) *1 : The values under the condition not exceeding the above absolute maximum ratings and the power dissipation.

*2 : The power dissipation shown is the value at $T_a = 85^\circ\text{C}$ for the independent (unmounted) IC package without a heat sink.

When using this IC, refer to the $\bullet P_D$ - T_a diagram in the ■ Technical Data and design the heat radiation with sufficient margin so that the allowable value might not be exceeded based on the conditions of power supply voltage, load, and ambient temperature.

*3 : Except for the power dissipation, operating ambient temperature, and storage temperature, all ratings are for $T_a = 25^\circ\text{C}$.

■ Operating Supply Voltage Range

Parameter	Symbol	Range	Unit	Notes
Supply voltage range	V_{IN}	3.0 to 15	V	*1
Supply voltage range (Boost Mode/Buck-Boost Mode)	V_{IN1}	3.0 to 12	V	*1
Supply voltage range (Buck Mode)	V_{IN2}	3.0 to 15	V	*1

Note) *1 : The values under the condition not exceeding the above absolute maximum ratings and the power dissipation.

■ Allowable Voltage Range

- Notes)
- Allowable current and voltage ranges are limit ranges which do not result in damages to this IC, and IC operation is not guaranteed within these limit ranges.
 - Voltage values, unless otherwise specified, are with respect to GND.
 - V_{IN} is voltage for VIN pin.
 - Do not apply external currents or voltages to any pin not specifically mentioned.

Pin No.	Pin name	Rating	Unit	Note
1	VIN	-0.3 to 15	V	*1
2	VFB_SEL	-0.3 to 5.5	V	—
4	CS	-0.3 to V_{REG}	V	*2
6	OVP	-0.3 to V_{REG}	V	*2
9	SW	-0.3 to V_{REG}	V	*2
10	PWM	-0.3 to 5.5	V	*2
12	ENB	-0.3 to V_{IN}	V	*1
14	VREG	-0.3 to 4.3	V	*2

- Notes)
- *1 : V_{IN} must not exceed 15 V.
 - *2 : V_{REG} must not exceed 4.3 V.

■ Electrical Characteristics at $V_{IN} = 6\text{ V}$, $ENB = 6\text{ V}$, $PWM = V_{REG}$

Note) $T_a = 25^\circ\text{C} \pm 2^\circ\text{C}$ unless otherwise specified.

B No.	Parameter	Symbol	Conditions	Limits			Unit	Notes
				Min	Typ	Max		
Circuit Current Consumption								
1	Standby Current	I _{STB}	ENB = 0 V	—	—	10	μA	—
2	Operating Quiescent Current	I _{CC}	ENB = V _{IN} No load condition	—	—	1	mA	—
ENABLE (ENB), VFB_SEL and PWM Control Function								
3	ENB High Input Logic	V _{ENBH}	—	3	—	V _{IN}	V	—
4	ENB Low Input Logic	V _{ENBL}	—	0	—	0.3	V	—
5	VFB_SEL High Input Logic	V _{VFBSELH}	—	0.7 × V _{REG}	—	5	V	—
6	VFB_SEL Low Input Logic	V _{VFBSELL}	—	0	—	0.3 × V _{REG}	V	—
7	PWM High input Logic	V _{PWMH}	—	0.7 × V _{REG}	—	5	V	—
8	PWM Low input Logic	V _{PWML}	—	0	—	0.3 × V _{REG}	V	—
Input Pin Current Consumption								
9	Enable Pin Current	I _{ENB}	ENB = 6 V	—	—	25	μA	—
Output Driver								
10	SW High Output Logic	V _{SWH}	SW output High logic; MOSFET ON condition	0.7 × V _{REG}	—	V _{REG} +0.2	V	—
11	SW Low Output Logic	V _{SWL}	SW output Low logic; MOSFET OFF condition	−0.2	—	0.2	V	—
Under Voltage Lock Out (UVLO)								
12	Under Voltage protection on value	V _{UVLOON}	V _{IN} Falling SW OFF; V _{REG} = No load	1.9	2.1	2.3	V	—
13	Under voltage protection Hysteresis	V _{UVLOHYS}	V _{IN} Rising SW ON – V _{IN} Falling SW OFF; V _{REG} = No load	0.1	0.3	0.5	V	—

■ Electrical Characteristics (Reference values for design) at $V_{IN} = 6\text{ V}$

Note) The characteristics listed below are reference values derived from the design of the IC and are not guaranteed by inspection.

If a problem does occur related to these characteristics, we will respond in good faith to user concerns.

B No.	Parameter	Symbol	Conditions	Reference values			Unit	Notes
				Min	Typ	Max		
Reference Voltage Control								
14	VFB Reference Voltage 1	V _{VFB1}	VFB_SEL = High OVP = 0 V (Buck mode)	196	202	208	mV	—
15	VFB Reference Voltage 2	V _{VFB2}	VFB_SEL = Low OVP = 0 V (Buck mode)	24	32	40	mV	—
Over Voltage Protection (Boost Mode Only)								
16	Over Voltage Protection Threshold	V _{OVP}	R1 = 470 kΩ, R2 = 30 kΩ	18	21	24	V	—
Output Driver								
17	Driver Off Time	T _{OFF}	Fix off time at SW pin	0.5	1	2	μs	—
18	Maximum Operating Frequency	F _{Max}	—	—	—	1.5	MHz	—
Regulator Voltage (VREG)								
19	VREG Output Voltage	V _{REG}	4 V ≤ V _{IN} ≤ 15 V No Load Condition, CVREG = 1 μF	3.45	3.65	3.85	V	—
Efficiency								
20	Efficiency	Eff	V _{IN} = 6 V 1 LED of V _F = 3.7 V I _{LED} = 400 mA VFB_SEL = High OVP = 0 V (Buck mode)	—	90	—	%	—

■ Control Pin Mode Table

Note) See parameters B No. 3, 4, 5, 6, 7 and 8 in the Electrical Characteristics for control voltage ranges.

Pin No.	Description		Pin voltage		Remarks
			Low	High	
2	VFB_SEL	ON/OFF	$V_{FB} = 32 \text{ mV}$	$V_{FB} = 202 \text{ mV}$	Feedback voltage selection
10	PWM	ON/OFF	PWM OFF	PWM ON	When PWM is not used, the pin is left floating
12	ENB	ON/OFF	STANDBY	OPERATING	Standby / Operating mode control

■ Electrical Characteristics Test Procedures

C No.	Parameter	Input		Output		Switch					
		Pin No.	Conditions	Pin No.	Conditions	S1	S2	S3	S4	S5	S6
Circuit Current Consumption											
1	Standby Current	12 10 2 6 4 9	ENB = 0 V PWM = 0 V VFB_SEL = 0 V OVP = 0 V CS = 0 V SW = Hi-Z	4	Standby current consumption	5	5	5	2	2	1
2	Operating Quiescent Current	12 10 2 6 4 9	ENB = V _{IN} PWM = 0 V VFB_SEL = 0 V OVP = 0 V CS = 0 V SW = Hi-Z	4	Current consumption	2	5	5	2	2	1
ENABLE (ENB), VFB_SEL and PWM Control Function											
3	ENB High Input Logic	12 10 2 6 4 9	ENB = 0.30 V PWM = Hi-Z VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = Hi-Z	16	Output DC voltage	3	1	2	2	2	1
4	ENB Low Input Logic	12 10 2 6 4 9	ENB = 3.0 V PWM = Hi-Z VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = Hi-Z	16	Output DC voltage	4	1	2	2	2	1
5	VFB_SEL High Input Logic	12 10 2 6 4 9	ENB = V _{IN} PWM = Hi-Z VFB_SEL = 0.70× V _{REG} OVP = 0 V CS = 100 mV SW = Hi-Z	11	Output DC voltage / 1 MHz	2	1	3	2	3	1
6	VFB_SEL Low Input Logic	12 10 2 6 4 9	ENB = V _{IN} PWM = Hi-Z VFB_SEL = 0.30 × V _{REG} OVP = 0 V CS = 100 mV SW = Hi-Z	11	Output DC voltage / 1 MHz	2	1	4	2	3	1
7	PWM High input Logic	12 10 2 6 4 9	ENB = V _{IN} PWM = 0.70 × V _{REG} VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = Hi-Z	11	Output DC voltage / 1 MHz	2	3	2	2	2	1

■ Electrical Characteristics Test Procedures (continued)

C No.	Parameter	Input		Output		Switch					
		Pin No.	Conditions	Pin No.	Conditions	S1	S2	S3	S4	S5	S6
8	PWM Low input Logic	12 10 2 6 4 9	ENB = V_{IN} PWM = $0.30 \times V_{REG}$ VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = Hi-Z	11	Output DC voltage / 1 MHz	2	4	2	2	2	1
Input Pin Current Consumption											
9	Enable Pin Current	12 10 2 6 4 9	ENB = V_{IN} PWM = Hi-Z VFB_SEL = 0 V OVP = 0 V CS = 0 V SW = Hi-Z	14	Current Consumption	2	1	5	2	2	1
Output Driver											
10	SW High Output Logic	12 10 2 6 4 9	ENB = V_{IN} PWM = 3.65 V VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = 0 A	11	Output DC voltage / 1 MHz	2	2	2	2	2	2
11	SW Low Output Logic	12 10 2 6 4 9	ENB = V_{IN} PWM = 0 V VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = 0 A	11	Output DC voltage / 1 MHz	2	5	2	2	2	2

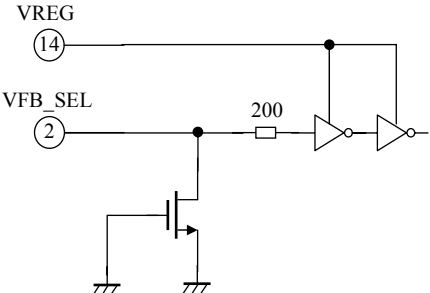
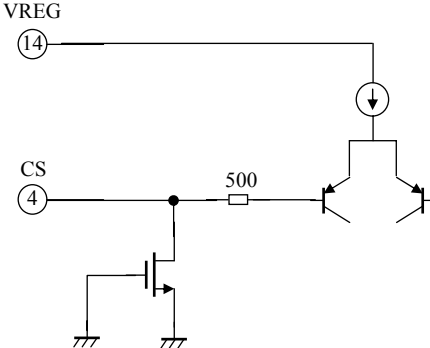
■ Electrical Characteristics Test Procedures (continued)

C No.	Parameter	Input		Output		Switch					
		Pin No.	Conditions	Pin No.	Conditions	S1	S2	S3	S4	S5	S6
Under voltage Lock Out (UVLO)											
12	Under voltage protection on value	12 10 2 6 4 9	ENB = V _{IN} PWM = Hi-Z VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = Hi-Z	11	Output DC voltage / 1 MHz	2	1	2	2	2	1
13	Under voltage protection Hysteresis	12 10 2 6 4 9	ENB = V _{IN} PWM = Hi-Z VFB_SEL = 3.65 V OVP = 0 V CS = 0 V SW = Hi-Z	11	Output DC voltage / 1 MHz	2	1	2	2	2	1

■ Technical Data

- I/O block circuit diagrams and pin function descriptions

Note) The characteristics listed below are reference values derived from the design of the IC and are not guaranteed.

Pin No.	Waveform and voltage	Internal circuit	Impedance	Description
1	DC (3 V to 15 V)	—	Z : Low	VIN Power Supply of IC
2	DC (0 V to 5 V)		Z : Hi-Z	VFB_SEL Feedback voltage select pin
3	—	—	—	No connection
4	DC (0 V to 250 mV)		Z : Hi-Z	CS Current Sense Pin
5	—	—	—	No connection

■ Technical Data (continued)

• I/O block circuit diagrams and pin function descriptions (continued)

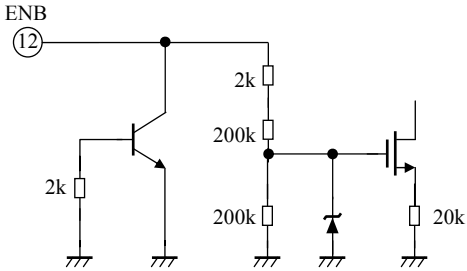
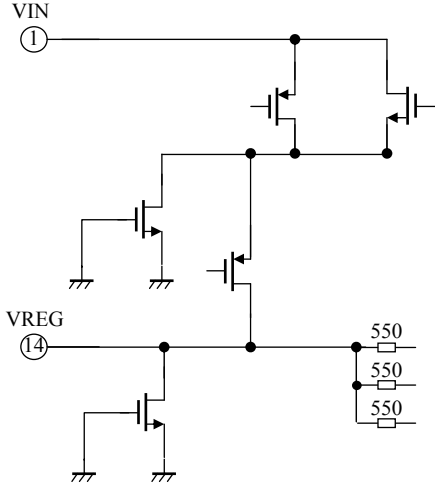
Note) The characteristics listed below are reference values derived from the design of the IC and are not guaranteed.

Pin No.	Waveform and voltage	Internal circuit	Impedance	Description
6	DC (0 V to 1.26 V)		Z : Hi-Z	OVP Over Voltage Protection input pin for Boost and Buck-Boost mode Connect to GND for Buck mode
7	GNDP	—	—	Power Ground
8	—	—	—	No connection
9	Pulse (0 V to 3.65 V)		Z : Hi-Z	SW External NMOS Transistor Gate Driving Pulse
10	Pulse (0 V to 5 V)		Z : 170 kΩ	PWM PWM Dimming Control
11	—	—	—	No connection

■ Technical Data (continued)

- I/O block circuit diagrams and pin function descriptions (continued)

Note) The characteristics listed below are reference values derived from the design of the IC and are not guaranteed.

Pin No.	Waveform and voltage	Internal circuit	Impedance	Description
12	DC (3 V to 15 V)		Z : 402 kΩ	ENB Standby On/Off Control Pin
13	—	—	—	No connection
14	DC (Typ. 3.65 V)		Z : Hi-Z	VREG Regulator Output Pin
15	GND	—	—	Signal Ground
16	—	—	—	No connection

■ Technical Data (continued)

- Functions and properties descriptions

(1) Overview

AN30888B is a constant current LED driver. The IC works as a Boost /Buck-Boost/ Buck mode DCDC controller with external MOSFET.

Operating input voltages ranges from 3 V to 15 V. The mode of operation depends on the number of LEDs to be driven and the supply voltage level.

In general, please adhere to the following:

If total LED voltage drop is more than supply voltage, boost mode is adopted. If LED voltage drop is less than the supply voltage, buck mode is adopted. If supply voltage is close to the total LED voltage drop, the Buck-Boost mode can be used. Please note that the different mode of operation should be manually configured.

Output LED current can be designed ranges from 0 A and to a few amperes depending on the mode of operation, the external MOSFET characteristic and feasible R_{CS} value used. The control architecture uses current mode fix off time control. The V_{FB} reference voltage determines LED current by setting VFB_SEL pin with values of 32 mV or 202 mV under buck mode. By applying V_{FB} voltage of 32 mV, user can achieve higher efficiency with lower power dissipation in R_{CS} resistor. Applying 202 mV V_{FB} voltage achieves better LED current accuracy.

(2) Standby enable function

AN30888B enters standby mode when ENB pin is pulled low. During standby, the IC draws a small current of value less than 10 μ A from the power supply. This helps to achieve longer battery usage time. During Boost mode operation, although external MOSFET cannot be turned on at standby condition, there is still a DC current path between the input and the LEDs through the inductor and schottky diode. Thus it is important to make sure that during boost mode, the minimum forward voltage of the LED array must exceed the maximum input voltage to ensure the LEDs remain off during standby mode.

■ Technical Data (continued)
• Functions and properties descriptions (continued)

(3) Internal regulator

An internal 3.65 V regulator is used as the power supply for internal core circuit of this IC.
This regulated voltage, V_{REG} will be provided when V_{IN} is approximately in the range of 4 V to 15V. For V_{IN} lower than 4 V, regulator will act as a V_{IN} voltage follower, with output voltage close to V_{IN} . The amount of drop voltage from V_{IN} during V_{IN} follower mode depends on load current of the regulator and also tolerance of the IC. In general, the regulator output voltage will be approximately 0.3 V lower than V_{IN} during this mode of operation.
This regulator requires a capacitor of 1 μ F to be connected to VREG pin. This capacitor helps to provide a stable regulated voltage to the IC. The regulator has a current ability of approximately 15 mA. However, it is not designed to provide as external power supply voltage. Hence an external load exceeding approximately 0.5 mA to the VREG pin is not allowed.

(4) Output setting consideration

The output voltage, V_{OUT} is set using the following equations for both boost and buck mode:

$$V_{OUT} = (V_F \times N_{LEDs} + V_D) \dots\dots\dots$$
$$V_{OUT} = (V_{IN} - V_F \times N_{LEDs}) \dots\dots\dots$$
$$V_{OUT} = (V_F \times N_{LEDs} + V_D + V_{IN}) \dots\dots\dots$$

Eq[1]

Eq[2]

Eq[3]

(Boost mode)

(Buck mode)

(Buck-Boost mode)

V_{IN} : Battery or Input power supply voltage

V_F : LED forward drop voltage

N_{LEDs} : Number of LEDs stacked in series

V_D : Schottky diode forward drop voltage

For Boost mode or Buck-Boost mode operation, V_{OUT} setting should be lesser than Drain–Source breakdown voltage of external MOSFET as mention in (11). Also V_{OUT} should be lesser than OVP protection threshold as mentioned in (9).

For Buck mode operation, V_{OUT} setting should give sufficient voltage for external MOSFET to operate properly at the required output current setting.

■ Technical Data (continued)**• Functions and properties descriptions (continued)****(5) Feedback voltage V_{FB} at CS pin**

The V_{FB} voltage is generated internally in the IC and output at CS pin. This voltage allows users to fix the input peak current, I_{PK} as well as the LED output current, I_{LED} . This voltage will change according to the setting at VFB_SEL pin.

For operation in boost mode/buck-boost mode, V_{FB} will be inversely proportionally to supply voltage, V_{IN} . When input supply voltage decreases, V_{FB} will increase. This ensure LED current remain accurate as supply voltage decreases.

When operating in buck mode, V_{FB} voltage will remain at 202 mV or 32 mV depending on whether VFB_SEL pin is high or low.

The following are some figures of V_{FB} voltage with respect to V_{IN} . For detail information, please refer to graph and data table information as the following.

For Boost mode and Buck-Boost mode :

$V_{FB} = 116 \text{ mV}$	(When VFB_SEL = High ; $V_{IN} = 6 \text{ V}$)
$V_{FB} = 50 \text{ mV}$	(When VFB_SEL = Low ; $V_{IN} = 6 \text{ V}$)
$V_{FB} = 198.3 \text{ mV}$	(When VFB_SEL = Low ; $V_{IN} = 3 \text{ V}$)
$V_{FB} = 88 \text{ mV}$	(When VFB_SEL = Low ; $V_{IN} = 3 \text{ V}$)

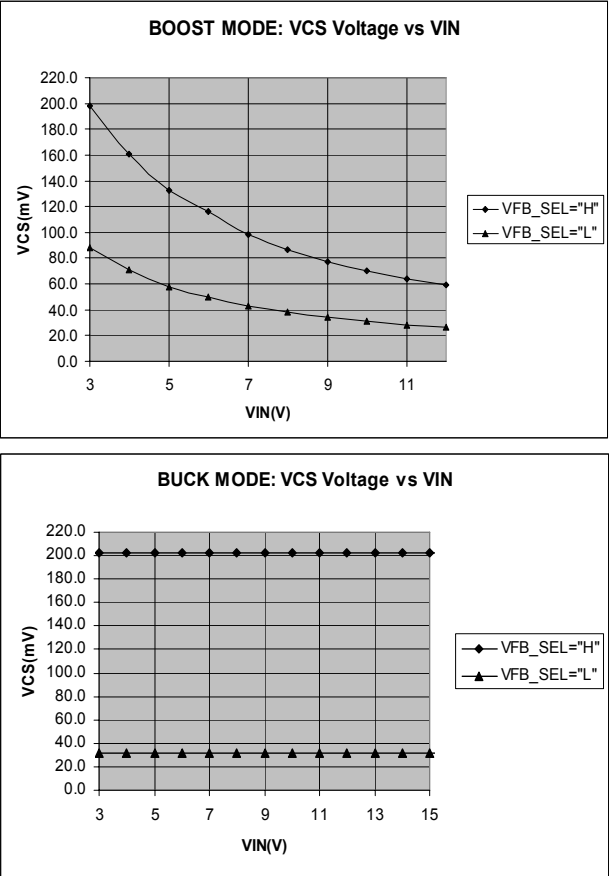
For Buck mode :

$V_{FB} = 202 \text{ mV}$	(When VFB_SEL = High, for all V_{IN} level)
$V_{FB} = 32 \text{ mV}$	(When VFB_SEL = Low, for all V_{IN} level)

To improve overall efficiency V_{FB} voltage can be set lower by switching VFB_SEL = Low. On the other hand accuracy can be improved by using VFB_SEL = High mode.

- Technical Data (continued)
 - Functions and properties descriptions (continued)

(5) Feedback voltage V_{FB} at CS pin (continued)



VIN (V)	Boost mode/ Buck-Boost mode		Buck mode	
	VFB_SEL = High	VFB_SEL = Low	VFB_SEL = High	VFB_SEL = Low
	V _{FB} (mV)	V _{FB} (mV)	V _{FB} (mV)	V _{FB} (mV)
3	198.3	88.0	202	32
4	161.0	71.0	202	32
5	132.3	57.7	202	32
6	116.0	50.0	202	32
7	98.3	43.0	202	32
8	86.3	38.0	202	32
9	77.3	34.0	202	32
10	70.0	31.0	202	32
11	64.0	28.3	202	32
12	59.0	26.3	202	32
13	N.A	N.A	202	32
14	N.A	N.A	202	32
15	N.A	N.A	202	32

■ Technical Data (continued)
• Functions and properties descriptions (continued)

(6) Inductor selection

Inductor value, L is set by the required inductor ripple current desired.
The general trend for lower inductor value is a smaller inductor physical size, but a larger input ripple current. Similarly, an increase in inductor value will decrease input ripple current.
Users are advised to choose an inductor that can handle the peak current I_{PK} , flowing across it without saturating. In addition, inductor with lower series resistance are preferred to provide better operating efficiency.

The following equation gives a general guideline in selection inductor value based on 30% peak to peak ripple current across the inductor.

$$L = \frac{(V_{OUT} - V_{IN}) \times T_{OFF}}{0.3 \times I_{IN}} \dots\dots\dots \text{Eq[4]} \qquad \text{(Boost mode, Buck-Boost mode)}$$

$$L = \frac{(V_{IN} - V_{OUT}) \times T_{OFF}}{0.3 \times I_{LED}} \dots\dots\dots \text{Eq[5]} \qquad \text{(Buck mode)}$$

- V_{OUT} = Output voltage
- V_{IN} = Input supply voltage
- T_{OFF} = Fixed off time design at 1 μ s
- I_{LED} = LED output current
- I_{IN} is input current from supply voltage

Please note that the 0.3 factor can be altered if 30% peak to peak current is changed.
i.e, if percentage of peak to peak current needed is 40%, this factor will be 0.4.

■ Technical Data (continued)

• Functions and properties descriptions (continued)

(7) Setting output LED current and choosing current sense resistor R_{CS}

The LED current in this IC can be set easily by selecting the appropriate R_{CS} resistor to be used at CS pin of this chip.

For Boost Mode and Buck-Boost mode :

R_{CS} resistor can be set in the following way :

First is to calculate input current I_{IN} at the required operating condition :

$$I_{IN} = (V_{OUT} + V_D) \times (I_{LED} / V_{IN}) \dots\dots\dots \text{Eq[6]} \quad (\text{Boost mode, Buck-Boost mode})$$

V_{OUT} = Output voltage

V_D = Schottky diode forward drop voltage

I_{LED} = Required LED current

V_{IN} = Input supply voltage

After which the peak input current, I_{PK} can be determine by adding I_{IN} with half the peak to peak ripple current at the inductor.

$$I_{PK} = I_{IN} + \frac{(V_{OUT} - V_{IN}) \times T_{OFF}}{2L} \dots\dots\dots \text{Eq[7]} \quad (\text{Boost mode, Buck-Boost mode})$$

T_{OFF} = T_{OFF} is fixed off time = 1 μ s

L = Inductor value found in part (6) inductor selection

V_{OUT} = Output voltage

V_{IN} = Input supply voltage

I_{IN} = I_{IN} is input current found in Eq[6]

Lastly, R_{CS} resistor can be determine by using :

$$R_{CS} = \frac{V_{FB}}{I_{PK}} \dots\dots\dots \text{Eq[8]} \quad (\text{Boost mode, Buck-Boost mode})$$

V_{FB} is voltage at CS pin. Refer to data graphs for the V_{FB} voltage at different input voltage condition.

I_{PK} is peak current found in Eq[7]

Using numeric example of operating condition :

$$V_{IN} = 6 \text{ V}, V_{OUT} = 10 \text{ V}, I_{LED} = 500 \text{ mA}, T_{OFF} = 1 \mu\text{s}, L = 16 \mu\text{H}, V_D = 0.4 \text{ V}, V_{FB} = 0.1 \text{ V}@V_{IN} = 6 \text{ V}$$

$$\text{From Eq[6]} : I_{IN} = (10 + 0.4) \times (0.5 / 6) = 0.8667 \text{ A}$$

$$\text{From Eq[7]} : I_{PK} = 0.8667 + \frac{(10 - 6) \times 1\mu}{2 \times 16\mu} = 0.9971 \text{ A}$$

$$\text{From Eq[8]} : R_{CS} = \frac{0.1}{0.9917} = 100.8 \text{ m}\Omega$$

■ Technical Data (continued)

- Functions and properties descriptions (continued)

(7) Setting output LED current and choosing current sense resistor R_{CS} (continued)

For Buck Mode :

R_{CS} resistor can be set in the following way :

First is to calculate the peak current I_{PK} using Eq[9]. During buck mode, peak current sense correspond to the average output LED current plus half of actual current ripple through the inductor.

$$I_{PK} = I_{LED} + \frac{(V_{IN} - V_{OUT}) \times T_{OFF}}{2L} \dots\dots\dots \text{Eq[9]} \quad (\text{Buck mode})$$

V_{OUT} = Output voltage

V_{IN} = Input supply voltage

$T_{OFF} = T_{OFF}$ = Fixed off time design at 1 μ s

I_{LED} = LED output current

L = Inductor value found in part (6) inductor selection

Lastly, R_{CS} resistor can be determine by using :

$$R_{CS} = \frac{V_{FB}}{I_{PK}} \dots\dots\dots \text{Eq[10]} \quad (\text{Buck mode})$$

V_{FB} is voltage at CS pin. Refer to data graphs for the V_{FB} voltage at different input voltage condition.

I_{PK} is peak current found in Eq[9] .

Using numeric example of operating condition :

$$V_{IN} = 12 \text{ V}, V_{OUT} = 2 \text{ V}, I_{LED} = 500 \text{ mA}, T_{OFF} = 1 \mu\text{s}, L = 66 \mu\text{H}, V_{FB} = 0.2 \text{ V}$$

$$\text{From Eq[9]} : I_{PK} = 0.5 + \frac{(12 - 2) \times 1\mu}{2 \times 66\mu} = 0.575 \text{ A}$$

$$\text{From Eq[10]} : R_{CS} = \frac{0.2}{0.575} = 348 \text{ m}\Omega$$

Please note that for component deviation such as inductor, diodes, etc, these deviation can cause the designed I_{PK} to be higher or lower than the calculated value.

Users may need to fine tune the value of R_{CS} from the calculated values in order to obtain accurate I_{LED} measurement.

Please take note of total impedance including parasitic impedance of PCB trace at CS pin to ground when designing the required R_{CS} value. This is especially important if the designed I_{LED} is high as R_{CS} value will be small and in turn making parasitic impedance significant to the total impedance seen at CS pin

■ Technical Data (continued)

• Functions and properties descriptions (continued)

(8) Soft start

Soft start circuit is incorporated into this IC to avoid high in-rush current during start-up.

After the device is enabled (ENB = High), the output inductor current and output voltage will rise slowly from initial condition. This slow start-up time ensure smooth start-up as well as minimize in-rush current.

(9) Over Voltage Protection (OVP)

When operating in Boost mode or Buck-Boost mode, over voltage protection is needed to prevent damages to IC or external component damages in cases of open LED condition.

OVP switches off external power MOSFET to prevent output from rising over a designed OVP voltage. Output voltage should be limited to the rating of external component used. (for example Drain Source voltage rating of the external MOSFET or the output capacitor)

OVP compares the internal reference voltage of 1.26 V with output voltage through resistor network.

OVP threshold is set using the following equation:

$$V_{OVP} = \frac{1.262 \text{ V} \times (R1 + R2)}{R2} \dots\dots\dots \text{Eq[11]} \quad (\text{Boost mode, Buck-Boost mode})$$

If R1 = 470 kΩ, R2 = 30 kΩ, OVP threshold will be designed at around 21 V.

When OVP is triggered, output voltage will be clamped at this threshold voltage (with hysteresis of around 1 V to 2 V) until the fault (e.g open LED condition) has been removed.

When operating in buck mode, the OVP pin must be short to ground to disable this function as OVP function is not necessary in this mode.

■ Technical Data (continued)

• Functions and properties descriptions (continued)

(10) Under Voltage Lock Out (UVLO)

Under Voltage lock out prevents IC from operation at supply voltage lower than 2.1 V.

This function prevent IC from abnormal operation when supply voltage V_{IN} drops below our recommended input range. When input voltage is lower than this lock out value of 2.1 V, external MOSFET will be switched off. When input voltage rises to 2.4 V or more, device operation starts again. This means a hysteresis voltage of about 0.3 V.

(11) Power MOSFET consideration

When selecting the power MOSFET, it is important to consider parameters such as gate-source, drain-source breakdown voltage, total gate capacitance, ON resistance and the drain current rating.

When power is turned on for IC operating in boost mode, output voltage needed to drive LED will be reflected to Drain-Source voltage of the power MOSFET. Thus it is recommended to select a MOSFET that can handle this output voltage. Alternatively, output and Drain-Source voltage can be protected and clamped by OVP circuit as mentioned in point (9).

Gate capacitance of the MOSFET chosen should ideally to be smaller than 3 nF.

(12) PWM operation

PWM signal can be generated externally and input into PWM pin of this IC. This PWM signal will turn on and off the output driver, giving an average output LED current that is proportional to the duty cycle of the PWM signal.

$$I_{LED(avg)} = I_{LED} \times \text{Duty} \dots \dots \dots \text{Eq[12]} \quad \quad \quad (\text{Boost / Buck-Boost / Buck mode})$$

$I_{LED(avg)}$ = The average output LED current after PWM is input

I_{LED} = The nominal LED current set in part (7)

Duty = The ratio of on pulse time compared to total period time of the PWM signal.

A PWM frequency of 1 kHz or lower is recommended to minimize error due to rise and fall time of the converter output.

■ Technical Data (continued)

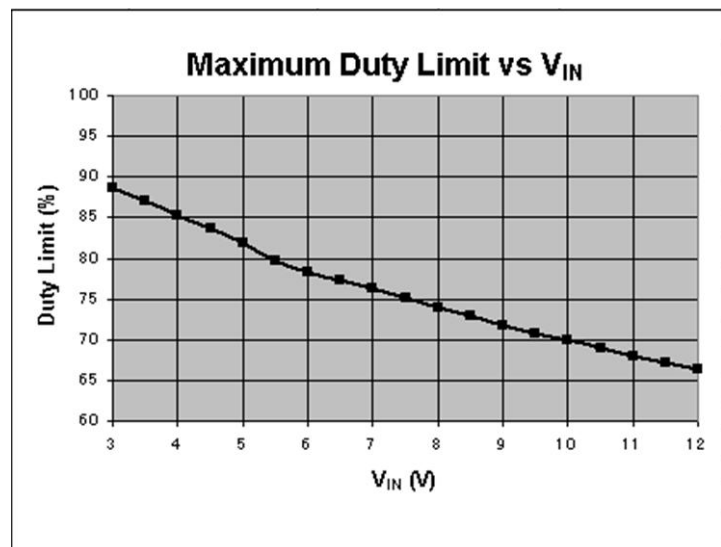
- Functions and properties descriptions (continued)

(13) Maximum duty operation

Maximum Duty limitation is needed when operating in Boost or Buck- Boost mode. This prevents the output voltage from having abnormal operation. For Buck mode, there is no need for maximum duty limit as SW pin is able to switch to 100% duty.

Please refer to the graph below for maximum duty vs V_{IN} data for Boost and Buck-Boost mode operation.

Boost/Buck-boost mode	
V_{IN} (V)	Duty Limit (%)
3.0	88.73
3.5	87.09
4.0	85.27
4.5	83.58
5.0	81.99
5.5	79.79
6.0	78.40
6.5	77.38
7.0	76.25
7.5	75.19
8.0	73.92
8.5	72.89
9.0	71.78
9.5	70.83
10.0	69.91
10.5	68.90
11.0	67.97
11.5	67.09
12.0	66.33

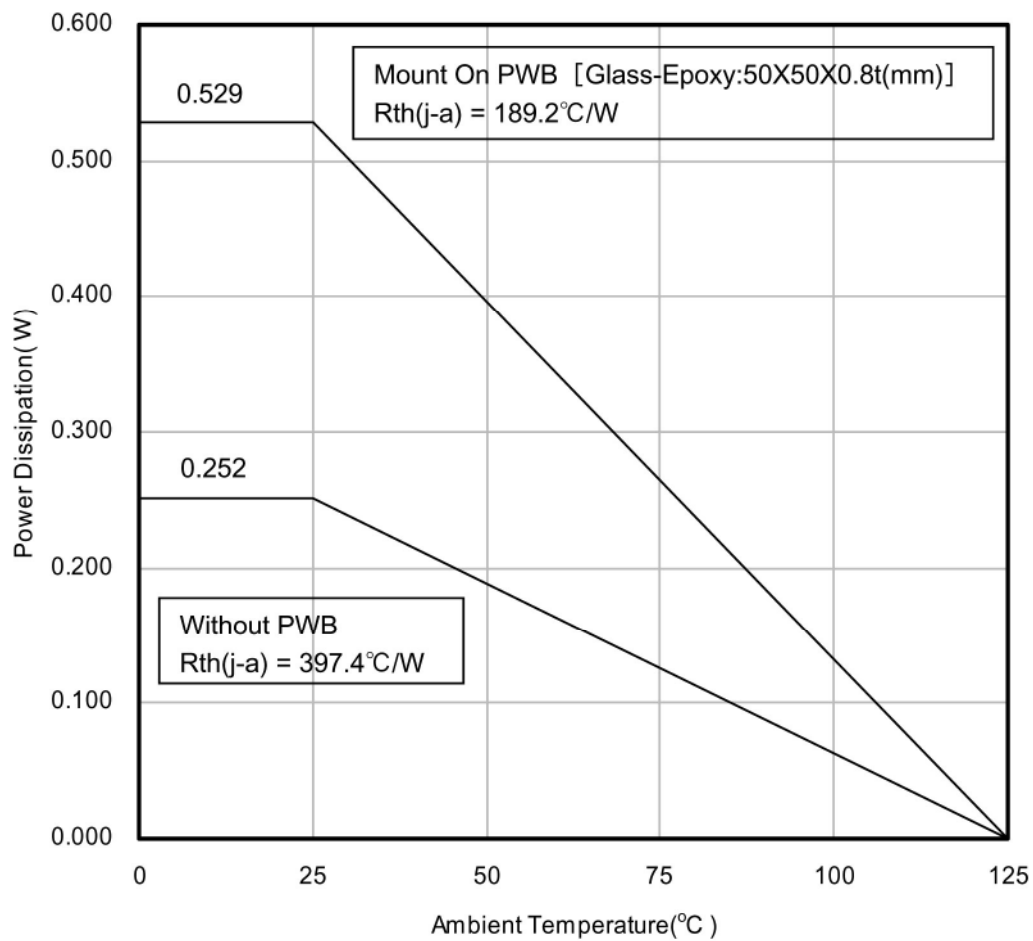


(14) Minimum duty operation

Parasitic circuit capacitance, inductance and external MOSFET gate drive current can create spike in the current sense, CS pin voltage at the point when external MOSFET is switched on. In order to prevent this spike to terminate the ON time prematurely, an internal filter of time constant, 100 ns is designed in chip. This time constant of 100 ns translates to a minimum duty of around 9% for all modes of operation. To further reduce the spike in the CS voltage especially when operating in low I_{LED} condition (example: R_{CS} is more than 0.8 Ω or more), external RC filter can be used in between V_{FB} node to CS pin which act as a low pass filter to filter spike noise from entering CS pin. This RC filter time constant should be long enough to reduce the parasitic spike without significantly affecting the shape of CS voltage.

The recommended RC value range from : $R = 10 \Omega$ to 1 k Ω and $C = 100$ pF to 500 pF depending on mode of operation and spike level.

- Technical Data (continued)
- $P_D - T_a$ diagram



■ Usage Notes

• Special attention and precaution in using

1. This IC is intended to be used for general electronic equipment [LED Lighting Devices].

Consult our sales staff in advance for information on the following applications:

- Special applications in which exceptional quality and reliability are required, or if the failure or malfunction of this IC may directly jeopardize life or harm the human body.
- Any applications other than the standard applications intended.
 - (1) Space appliance (such as artificial satellite, and rocket)
 - (2) Traffic control equipment (such as for automobile, airplane, train, and ship)
 - (3) Medical equipment for life support
 - (4) Submarine transponder
 - (5) Control equipment for power plant
 - (6) Disaster prevention and security device
 - (7) Weapon
 - (8) Others : Applications of which reliability equivalent to (1) to (7) is required

It is to be understood that our company shall not be held responsible for any damage incurred as a result of or in connection with your using the IC described in this book for any special application, unless our company agrees to your using the IC in this book for any special application.

2. Pay attention to the direction of LSI. When mounting it in the wrong direction onto the PCB (printed-circuit-board), it might smoke or ignite.
3. Pay attention in the PCB (printed-circuit-board) pattern layout in order to prevent damage due to short circuit between pins. In addition, refer to the Pin Description for the pin configuration.
4. Perform a visual inspection on the PCB before applying power, otherwise damage might happen due to problems such as a solder-bridge between the pins of the semiconductor device. Also, perform a full technical verification on the assembly quality, because the same damage possibly can happen due to conductive substances, such as solder ball, that adhere to the LSI during transportation.
5. Take notice in the use of this product that it might break or occasionally smoke when an abnormal state occurs such as output pin-VDD short (Power supply fault), output pin-GND short (Ground fault), or output-to-output-pin short (load short) .
And, safety measures such as an installation of fuses are recommended because the extent of the above-mentioned damage and smoke emission will depend on the current capability of the power supply.
6. When designing your equipment, comply with the range of absolute maximum rating and the guaranteed operating conditions (operating power supply voltage and operating environment etc.). Especially, please be careful not to exceed the range of absolute maximum rating on the transient state, such as power-on, power-off and mode-switching. Otherwise, we will not be liable for any defect which may arise later in your equipment.
Even when the products are used within the guaranteed values, take into the consideration of incidence of break down and failure mode, possible to occur to semiconductor products. Measures on the systems such as redundant design, arresting the spread of fire or preventing glitch are recommended in order to prevent physical injury, fire, social damages, for example, by using the products.
7. When using the LSI for new models, verify the safety including the long-term reliability for each product.
8. When the application system is designed by using this LSI, be sure to confirm notes in this book.
Be sure to read the notes to descriptions and the usage notes in the book.

Request for your special attention and precautions in using the technical information and semiconductors described in this book

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Even when the products are used within the guaranteed values, take into the consideration of incidence of break down and failure mode, possible to occur to semiconductor products. Measures on the systems such as redundant design, arresting the spread of fire or preventing glitch are recommended in order to prevent physical injury, fire, social damages, for example, by using the products.
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