

Description

The 9FGL04 devices are 3.3V members of IDT's 3.3V Full-Featured PCIe family. The devices have 4 output enables for clock management and support 2 different spread spectrum levels in addition to spread off. The 9FGL04 supports PCIe Gen1-4 Common Clocked architectures (CC) and PCIe Separate Reference no-Spread (SRnS) and Separate Reference Independent Spread (SRIS) clocking architectures. The 9FGL04P1 can be programmed with a user-defined power up default SMBus configuration.

Recommended Application

PCIe Gen1-4 clock generation for Riser Cards, Storage, Networking, JBOD, Communications, Access Points

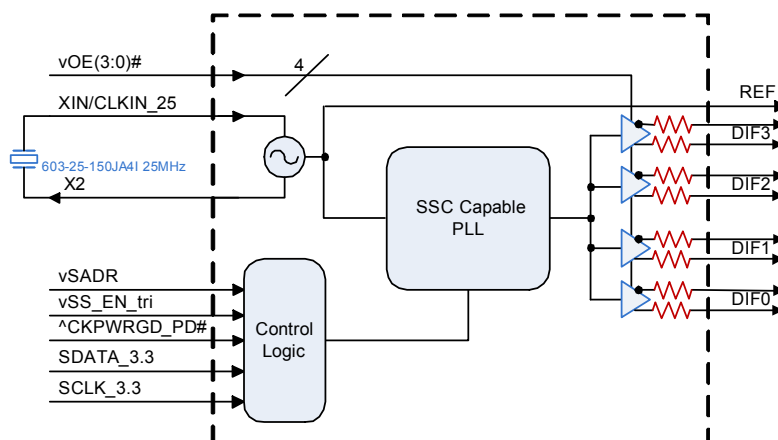
Output Features

- 4 – 100 MHz Low-Power HCSL (LP-HCSL) DIF pairs
 - 9FGL0441 default $Z_{OUT} = 100\Omega$
 - 9FGL0451 default $Z_{OUT} = 85\Omega$
 - 9FGL04P1 factory programmable defaults
- 1 - 3.3V LVCMOS REF output w/Wake-On-LAN (WOL) support
- Easy AC-coupling to other logic families, see IDT application note [AN-891](#)

Key Specifications

- PCIe Gen1-2-3-4 CC-compliant
- PCIe Gen2-3 SRIS-compliant
- DIF cycle-to-cycle jitter <50ps
- DIF output-to-output skew <50ps
- DIF 12k-20M phase jitter is <2ps rms when SSC is off
- REF phase jitter is <300fs rms (SSC off) and < 1.5ps RMS (SSC on)
- ± 100 ppm frequency accuracy on all clocks

Block Diagram

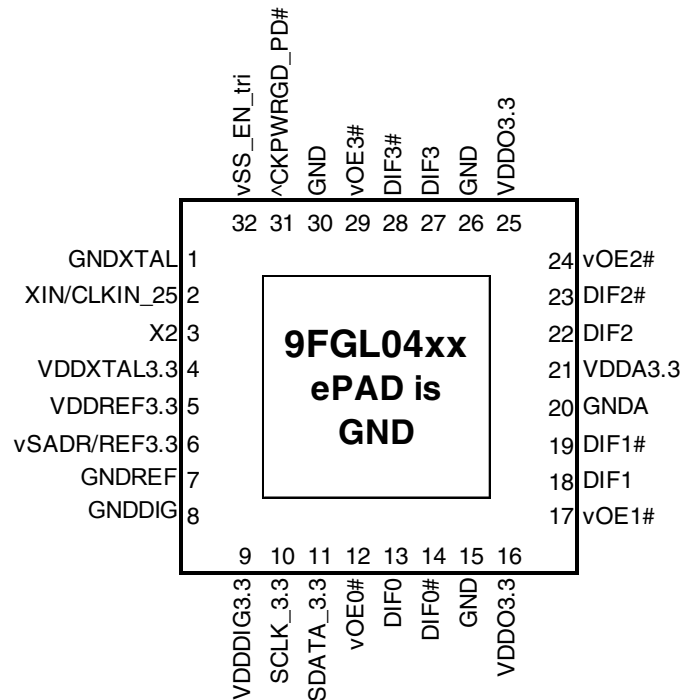


Note: Resistors default to internal on 41/51 devices. P1 devices have programmable default impedances on an output-by-output basis.

Features/Benefits

- Direct connection to 100Ω (xx41) or 85Ω (xx51) transmission lines; saves 16 resistors compared to standard PCIe devices
- 142mW typical power consumption (@3.3V); eliminates thermal concerns
- SMBus-selectable features allows optimization to customer requirements:
 - control input polarity
 - control input pull up/downs
 - slew rate for each output
 - differential output amplitude
 - 33, 85 or 100Ω output impedance for each output
 - spread spectrum amount
- 41 and 51 devices contain default configuration; SMBus interface not required for device operation
- P1 device allows factory programming of customer-defined input/output frequencies and SMBus power up default; allows exact optimization to customer requirements.
- OE# pins; support DIF power management
- 8MHz - 40MHz input frequency with 9FGL04P1 device (25MHz default); flexibility
- Pin/SMBus selectable 0%, -0.25% or -0.5% spread on DIF outputs %; minimize EMI and phase jitter for each application
- DIF outputs blocked until PLL is locked; clean system start-up
- Two selectable SMBus addresses; multiple devices can easily share an SMBus segment
- Space saving 32-pin 5x5mm VFQFPN; minimal board space

Pin Configuration



32-pin VFQFPN, 5x5 mm, 0.5mm pitch

^ prefix indicates internal 120KOhm pull up resistor

v prefix indicates internal 120KOhm pull down resistor

SMBus Address Selection Table

	SADR	Address	+ Read/Write Bit
State of SADR on first application of CKPWRGD_PD#	0	1101000	x
	1	1101010	x

Power Management Table

CKPWRGD_PD#	SMBus OE bit	OEx# Pin	DIFx/DIFx#		REF
			True O/P	Comp. O/P	
0	X	X	Low ¹	Low ¹	Hi-Z ²
1	1	0	Running	Running	Running
1	1	1	Disabled ¹	Disabled ¹	Running
1	0	X	Disabled ¹	Disabled ¹	Disabled ⁴

1. The output state is set by B11[1:0] (Low/Low default)

2. REF is Hi-Z until the 1st assertion of CKPWRGD_PD# high. After this, when CKPWRGD_PD# is low, REF is disabled unless Byte3[5]=1, in which case REF is running..

3. Input polarities defined at default values for 9FGLxx41/xx51.

4. See SMBus description for Byte 3, bit 4

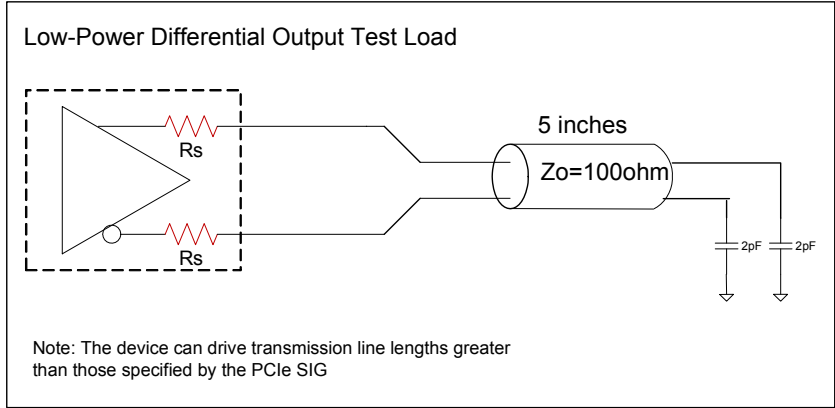
Power Connections

Pin Number		Description
VDD	GND	
4	1	XTAL Analog
5	7	REF Output
9	8, 30	Digital Power
16, 25	15, 26, 33	DIF outputs
21	20	PLL Analog

Pin Descriptions

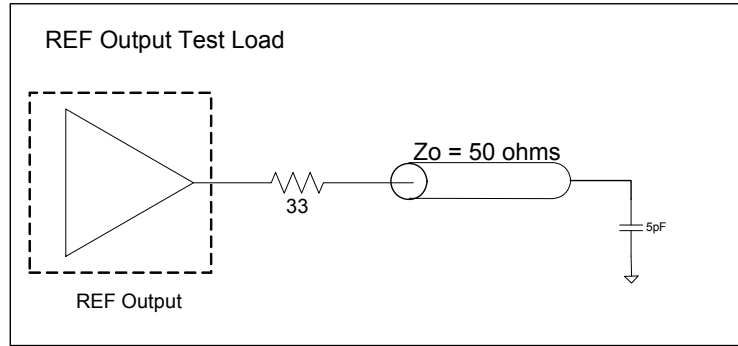
Pin#	Pin Name	Type	Pin Description
1	GNDXTAL	GND	GND for XTAL
2	XIN/CLKIN_25	IN	Crystal input or Reference Clock input. Nominally 25MHz.
3	X2	OUT	Crystal output.
4	VDDXTAL3.3	PWR	Power supply for XTAL, nominal 3.3V
5	VDDREF3.3	PWR	VDD for REF output. nominal 3.3V.
6	vSADR/REF3.3	LATCHED I/O	Latch to select SMBus Address/3.3V LVCMOS copy of X1/REFIN pin
7	GNDREF	GND	Ground pin for the REF outputs.
8	GNDDIG	GND	Ground pin for digital circuitry
9	VDDDIG3.3	PWR	3.3V digital power (dirty power)
10	SCLK_3.3	IN	Clock pin of SMBus circuitry, 3.3V tolerant.
11	SDATA_3.3	I/O	Data pin for SMBus circuitry, 3.3V tolerant.
12	vOE0#	IN	Active low input for enabling DIF pair 0. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs
13	DIF0	OUT	Differential true clock output
14	DIF0#	OUT	Differential Complementary clock output
15	GND	GND	Ground pin.
16	VDDO3.3	PWR	Power supply for outputs,nominal 3.3V.
17	vOE1#	IN	Active low input for enabling DIF pair 1. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs
18	DIF1	OUT	Differential true clock output
19	DIF1#	OUT	Differential Complementary clock output
20	GNDA	GND	Ground pin for the PLL core.
21	VDDA3.3	PWR	3.3V power for the PLL core.
22	DIF2	OUT	Differential true clock output
23	DIF2#	OUT	Differential Complementary clock output
24	vOE2#	IN	Active low input for enabling DIF pair 2. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs
25	VDDO3.3	PWR	Power supply for outputs,nominal 3.3V.
26	GND	GND	Ground pin.
27	DIF3	OUT	Differential true clock output
28	DIF3#	OUT	Differential Complementary clock output
29	vOE3#	IN	Active low input for enabling DIF pair 3. This pin has an internal pull-down. 1 =disable outputs, 0 = enable outputs
30	GND	GND	Ground pin.
31	^CKPWRGD_PD#	IN	Input notifies device to sample latched inputs and start up on first high assertion. Low enters Power Down Mode, subsequent high assertions exit Power Down Mode. This pin has internal pull-up resistor.
32	vSS_EN_tri	LATCHED IN	Latched select input to select spread spectrum amount at initial power up : 1 = -0.5% spread, M = -0.25%, 0 = Spread Off
33	ePAD	GND	Connect to ground

Test Loads



Terminations

Device	Zo (Ω)	Rs (Ω)
9FGL0441	100	None needed
9FGL0451	100	7.5
9FGL04P1	100	Prog.
9FGL0441	85	N/A
9FGL0451	85	None needed
9FGL04P1	85	Prog.



Alternate Terminations

The 9FGL family can easily drive LVPECL, LVDS, and CML logic. See [“AN-891 Driving LVPECL, LVDS, and CML Logic with IDT's "Universal" Low-Power HCSL Outputs”](#) for details.

Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 9FGL04. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDx		-0.5		4.6	V	1,2
Input Voltage	V _{IN}		-0.5		V _{DD} +0.5	V	1,3
Input High Voltage, SMBus	V _{IHSMB}	SMBus clock and data pins			3.9	V	1
Storage Temperature	T _s		-65		150	°C	1
Junction Temperature	T _j				125	°C	1
Input ESD protection	ESD prot	Human Body Model	2500			V	1

¹Guaranteed by design and characterization, not 100% tested in production.

²Operation under these conditions is neither implied nor guaranteed.

³Not to exceed 4.6V.

Electrical Characteristics–SMBus Parameters

T_A = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
SMBus Input Low Voltage	V _{ILSMB}	V _{DDSMB} = 3.3V			0.8	V	
SMBus Input High Voltage	V _{IHSMB}	V _{DDSMB} = 3.3V	2.1		3.6	V	
SMBus Output Low Voltage	V _{OLSMB}	@ I _{PULLUP}			0.4	V	
SMBus Sink Current	I _{PULLUP}	@ V _{OL}	4			mA	
Nominal Bus Voltage	V _{DDSMB}		2.7		3.6	V	
SCLK/SDATA Rise Time	t _{RSMB}	(Max V _{IL} - 0.15) to (Min V _{IH} + 0.15)			1000	ns	1
SCLK/SDATA Fall Time	t _{FSMB}	(Min V _{IH} + 0.15) to (Max V _{IL} - 0.15)			300	ns	1
SMBus Operating Frequency	f _{SMB}	SMBus operating frequency			500	kHz	2

¹Guaranteed by design and characterization, not 100% tested in production.

²The device must be powered up for the SMBus to function.

Electrical Characteristics–Input/Supply/Common Parameters–Normal Operating Conditions

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Supply Voltage	VDDxxx	Supply voltage for core, analog and single-ended LVCMOS outputs.	3.135	3.3	3.465	V	
Ambient Operating Temperature	T _{AMB}	Industrial range	-40	25	85	°C	
Input High Voltage	V _{IH}	Single-ended inputs, except SMBus	0.75 V _{DDx}		V _{DDx} + 0.3	V	
Input Low Voltage	V _{IL}		-0.3		0.25 V _{DDx}	V	
Input High Voltage	V _{IHtri}	Single-ended tri-level inputs ('_tri' suffix)	0.75 V _{DDx}		V _{DD} + 0.3	V	
Input Mid Voltage	V _{IMtri}		0.4 V _{DDx}	0.5 V _{DDx}	0.6 V _{DDx}	V	
Input Low Voltage	V _{ILtri}		-0.3		0.25 V _{DDx}	V	
Input Current	I _{IN}	Single-ended inputs, V _{IN} = GND, V _{IN} = VDD	-5		5	uA	
	I _{INP}	Single-ended inputs V _{IN} = 0 V; Inputs with internal pull-up resistors V _{IN} = VDD; Inputs with internal pull-down resistors	-50		50	uA	
Input Frequency	F _{in}	XTAL, or X1 input	8	25	40	MHz	4
Pin Inductance	L _{pin}				7	nH	1
Capacitance	C _{IN}	Logic Inputs, except DIF_IN	1.5		5	pF	1
	C _{OUT}	Output pin capacitance			6	pF	1
Clk Stabilization	T _{STAB}	From V _{DD} Power-Up and after input clock stabilization or de-assertion of PD# to 1st clock		0.34	1.8	ms	1,2
SS Modulation Frequency	f _{MOD}	Allowable Frequency (Triangular Modulation)	30	31.6	33	kHz	1
OE# Latency	t _{LATOE#}	DIF start after OE# assertion DIF stop after OE# deassertion	1		3	clocks	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t _F	Fall time of single-ended control inputs			5	ns	1,2
Trise	t _R	Rise time of single-ended control inputs			5	ns	1,2

¹ Guaranteed by design and characterization, not 100% tested in production.

² Control input must be monotonic from 20% to 80% of input swing.

³ Time from deassertion until outputs are >200 mV

⁴ The 9FGLxxP1 devices can be programmed for various input frequencies from 8 to 40MHz. The 9FGLxx41/51 devices use 25MHz.

Electrical Characteristics–DIF Low-Power HCSL Outputs

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Slew rate	Trf	Scope averaging on, fast setting	1.9	2.7	4	V/ns	2,3
		Scope averaging, slow setting	1	2.0	3	V/ns	2,3
Crossing Voltage (abs)	Vcross_abs	Scope averaging off	250	405	550	mV	1,4,5
Crossing Voltage (var)	Δ-Vcross	Scope averaging off		14	140	mV	1,4,9
Avg. Clock Period Accuracy	T _{PERIOD_AVG}		-100	0	+2600	ppm	2,10,13
Absolute Period	T _{PERIOD_ABS}	Includes jitter and Spread Spectrum Modulation	9.847	10	10.203	ns	2,6
Jitter, Cycle to cycle	t _{JCYC-CYC}			37	50	ps	2,15
Voltage High	V _{HIGH}		660	766	850	mV	1
Voltage Low	V _{LOW}		-150	21	150		1
Absolute Max Voltage	V _{max}			797	1150	mV	1,7,15
Absolute Min Voltage	V _{min}		-300	-22			1,8,15
Duty Cycle	t _{DC}		45	49.4	55	%	2
Slew rate matching	ΔTrf			8	20	%	1,14
Skew, Output to Output	t _{sk3}	Averaging on, V _T = 50%		21	50	ps	2

¹ Measured from single-ended waveform.

² Measured from differential waveform.

³ Measured from -150 mV to +150 mV on the differential waveform (derived from REFCLK+ minus REFCLK-). The signal must be monotonic through the measurement region for rise and fall time. The 300 mV measurement window is centered on the differential zero crossing.

⁴ Measured at crossing point where the instantaneous voltage value of the rising edge of REFCLK+ equals the falling edge of REFCLK-.

⁵ Refers to the total variation from the lowest crossing point to the highest, regardless of which edge is crossing. Refers to all crossing points for this measurement.

⁶ Defines as the absolute minimum or maximum instantaneous period. This includes cycle to cycle jitter, relative PPM tolerance, and spread spectrum modulation.

⁷ Defined as the maximum instantaneous voltage including overshoot.

⁸ Defined as the minimum instantaneous voltage including undershoot.

⁹ Defined as the total variation of all crossing voltages of Rising REFCLK+ and Falling REFCLK-. This is the maximum allowed variance in V_{CROSS} for any particular system.

¹⁰ Refer to Section 4.3.7.1.1 of the PCI Express Base Specification, Revision 3.0 for information regarding PPM considerations.

¹¹ System board compliance measurements must use the test load. REFCLK+ and REFCLK- are to be measured at the load capacitors CL. Single ended probes must be used for measurements requiring single ended measurements. Either single ended probes with math or differential probe can be used for differential measurements. Test load CL = 2 pF.

¹² T_{STABLE} is the time the differential clock must maintain a minimum ±150 mV differential voltage after rising/falling edges before it is allowed to droop back into the VRB ±100 mV differential range.

¹³ PPM refers to parts per million and is a DC absolute period accuracy specification. 1 PPM is 1/1,000,000th of 100.000000 MHz exactly or 100 Hz. For 300 PPM, then we have an error budget of 100 Hz/PPM * 300 PPM = 30 kHz. The period is to be measured with a frequency counter with measurement window set to 100 ms or greater. The ±300 PPM applies to systems that do not employ Spread Spectrum Clocking, or that use common clock source. For systems employing Spread Spectrum Clocking, there is an additional 2,500 PPM nominal shift in maximum period resulting from the 0.5% down spread resulting in a maximum average period specification of +2,800 PPM.

¹⁴ Matching applies to rising edge rate for REFCLK+ and falling edge rate for REFCLK-. It is measured using a ±75 mV window centered on the median cross point where REFCLK+ rising meets REFCLK- falling. The median cross point is used to calculate the voltage thresholds the oscilloscope is to use for the edge rate calculations. The Rise Edge Rate of REFCLK+ should be compared to the Fall Edge Rate of REFCLK-; the maximum allowed difference should not exceed 20% of the slowest edge rate.

¹⁵ At default SMBus amplitude settings.

Electrical Characteristics—Filtered Phase Jitter Parameters - PCIe Common Clocked (CC) Architectures

T_{AMB} = over the specified operating range. Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	INDUSTRY LIMIT	UNITS	Notes
Phase Jitter	t _{jphPCIeG1-CC}	PCIe Gen 1		20	25	86	ps (p-p)	1,2,3
	t _{jphPCIeG2-CC}	PCIe Gen 2 Lo Band 10kHz < f < 1.5MHz (PLL BW of 5-16MHz or 8-5MHz, CDR = 5MHz)		0.5	0.6	3	ps (rms)	1,2
		PCIe Gen 2 High Band 1.5MHz < f < Nyquist (50MHz) (PLL BW of 5-16MHz or 8-5MHz, CDR = 5MHz)		1.3	1.6	3.1	ps (rms)	1,2
	t _{jphPCIeG3-CC}	PCIe Gen 3 (PLL BW of 2-4MHz or 2-5MHz, CDR = 10MHz)		0.36	0.50	1	ps (rms)	1,2
	t _{jphPCIeG4-CC}	PCIe Gen 4 (PLL BW of 2-4MHz or 2-5MHz, CDR = 10MHz)		0.36	0.50	0.5	ps (rms)	1,2

¹ Applies to all outputs.

² Based on PCIe Base Specification Rev4.0 version 0.7draft. See <http://www.pcisig.com> for latest specifications.

³ Sample size of at least 100K cycles. This figures extrapolates to 108ps pk-pk @ 1M cycles for a BER of 1-12.

Electrical Characteristics—Filtered Phase Jitter Parameters - PCIe Separate Reference Independent Spread (SRIS) Architectures³

T_{AMB} = over the specified operating range. Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	INDUSTRY LIMIT	UNITS	Notes
Phase Jitter, PLL Mode	t _{jphPCIeG2-SRIS}	PCIe Gen 2 (PLL BW of 16MHz, CDR = 5MHz)		0.7	1.1	2	ps (rms)	1,2
	t _{jphPCIeG3-SRIS}	PCIe Gen 3 (PLL BW of 2-4MHz or 2-5MHz, CDR = 10MHz)		0.5	0.65	0.7	ps (rms)	1,2

¹ Applies to all outputs.

² Based on PCIe Base Specification Rev3.1a. These filters are different than Common Clock filters. See <http://www.pcisig.com> for latest specifications. There is a proposal to reduce the PCIe Gen3 limit to 0.5ps.

³ As of PCIe Base Specification Rev4.0 draft 0.7, SRIS is not currently defined for Gen1 or Gen4.

Electrical Characteristics—DIF LP-HCSL Output Unfiltered Phase Jitter Parameters

T_A = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	INDUSTRY LIMIT	UNITS
Phase Jitter, 12k-20M	t _{jph12k20M}	100MHz outputs with REF output enabled SSC Off		1.5	2	N/A	ps (rms)

Electrical Characteristics–Current Consumption

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Operating Supply Current	I _{DDAOP}	VDDA, All outputs active @100MHz		13	16	mA	
	I _{DDOP}	All other VDD, except VDDA, All outputs active @100MHz		29	40	mA	
Wake-on-LAN Current (Power down state and Byte 3, bit 5 = '1')	I _{DDAPD}	VDDA, DIF outputs off, REF output running		0.7	1.5	mA	1
	I _{DDPD}	All other VDD, except VDDA, DIF outputs off, REF output running		8.8	14	mA	1
Powerdown Current (Power down state and Byte 3, bit 5 = '0')	I _{DDAPD}	VDDA, all outputs off		0.7	1.5	mA	
	I _{DDPD}	All other VDD, except VDDA, all outputs off		4.7	8	mA	

¹ This is the current required to have the REF output running in Wake-on-LAN mode (Byte 3, bit 5 = 1)

Electrical Characteristics– REF

TA = T_{AMB}; Supply Voltages per normal operation conditions, See Test Loads for Loading Conditions

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	Notes
Long Accuracy	ppm	see T _{period} min-max values	0			ppm	1,2
Clock period	T _{period}	REF output	40			ns	2
High output Voltage	V _{HIGH}	I _{OH} = -2mA	0.8xV _{DDREF}			V	
Low output Voltage	V _{LOW}	I _{OL} = 2mA			0.2xV _{DDREF}	V	
Rise/Fall Slew Rate	t _{rf1}	Byte 3 = 1F, V _{OH} = 0.8*VDD, V _{OL} = 0.2*VDD	0.5	0.9	1.2	V/ns	1
	t _{rf1}	Byte 3 = 5F, V _{OH} = 0.8*VDD, V _{OL} = 0.2*VDD	1.0	1.5	2.0	V/ns	1,3
	t _{rf1}	Byte 3 = 9F, V _{OH} = 0.8*VDD, V _{OL} = 0.2*VDD	1.5	2.2	2.6	V/ns	1
	t _{rf1}	Byte 3 = DF, V _{OH} = 0.8*VDD, V _{OL} = 0.2*VDD	2.0	2.9	3.2	V/ns	1
Duty Cycle	d _{t1X}	V _T = VDD/2 V	45	50.2	55	%	1,4
Duty Cycle Distortion	d _{tcd}	V _T = VDD/2 V	-1	-0.5	0	%	1,5
Jitter, cycle to cycle	t _{jvc-cyc}	V _T = VDD/2 V		70	150	ps	1,4
Noise floor	t _{dBc1k}	1kHz offset		-145	-135	dBc	1,4
	t _{dBc10k}	10kHz offset to Nyquist		-150	-140	dBc	1,4
Jitter, phase	t _{jphREF}	12kHz to 5MHz, DIF SSC Off		0.13	0.3	ps (rms)	1,4
	t _{jphREF}	12kHz to 5MHz, DIF SSC On		1.5	2	ps (rms)	1,4

¹Guaranteed by design and characterization, not 100% tested in production.

² All Long Term Accuracy and Clock Period specifications are guaranteed assuming that REF is trimmed to 25.00 MHz

³ Default SMBus Value

⁴ When driven by a crystal.

⁵ When driven by an external oscillator via the X1 pin, X2 should be floating.

General SMBus Serial Interface Information

How to Write

- Controller (host) sends a start bit
- Controller (host) sends the write address
- IDT clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- IDT clock will **acknowledge**
- Controller (host) sends the byte count = X
- IDT clock will **acknowledge**
- Controller (host) starts sending Byte N through Byte N+X-1
- IDT clock will **acknowledge** each byte **one at a time**
- Controller (host) sends a Stop bit

Index Block Write Operation			
Controller (Host)		X Byte	IDT (Slave/Receiver)
T	starT bit		
Slave Address			
WR	WRite		
			ACK
Beginning Byte = N			
			ACK
Data Byte Count = X			
			ACK
Beginning Byte N			
			ACK
O			
O			O
O			O
			O
Byte N + X - 1			
			ACK
P	stoP bit		

Note: SMBus Read/Write Address is Latched on SADR pin. Unless otherwise indicated, default values are for the xx41 and xx51. P1 devices are fully factory programmable.

How to Read

- Controller (host) will send a start bit
- Controller (host) sends the write address
- IDT clock will **acknowledge**
- Controller (host) sends the beginning byte location = N
- IDT clock will **acknowledge**
- Controller (host) will send a separate start bit
- Controller (host) sends the read address
- IDT clock will **acknowledge**
- IDT clock will send the data byte count = X
- IDT clock sends Byte N+X-1
- IDT clock sends **Byte 0 through Byte X (if X_(H) was written to Byte 8)**
- Controller (host) will need to acknowledge each byte
- Controller (host) will send a not acknowledge bit
- Controller (host) will send a stop bit

Index Block Read Operation			
Controller (Host)		X Byte	IDT (Slave/Receiver)
T	starT bit		
Slave Address			
WR	WRite		
			ACK
Beginning Byte = N			
			ACK
RT	Repeat starT		
Slave Address			
RD	ReaD		
			ACK
			Data Byte Count=X
ACK			
			Beginning Byte N
ACK			
			O
O			O
O			O
O			
			Byte N + X - 1
N	Not acknowledge		
P	stoP bit		

SMBus Table: Output Enable Register

Byte 0	Name	Control Function	Type	0	1	Default
Bit 7		Reserved				X
Bit 6		Reserved				X
Bit 5		Reserved				X
Bit 4		Reserved				X
Bit 3	DIF OE3	Output Enable	RW	Low/Low	Pin Control	1
Bit 2	DIF OE2	Output Enable	RW	Low/Low	Pin Control	1
Bit 1	DIF OE1	Output Enable	RW	Low/Low	Pin Control	1
Bit 0	DIF OE0	Output Enable	RW	Low/Low	Pin Control	1

1. A low on these bits will override the OE# pin and force the differential output to the state indicated by B11[1:0] (Low/Low default).

SMBus Table: SS Readback and Vhigh Control Register

Byte 1	Name	Control Function	Type	0	1	Default
Bit 7	SSENRB1	SS Enable Readback Bit1	R	00' for SS_EN_tri = 0, '01' for SS_EN_tri = 'M', '11 for SS_EN_tri = '1'		Latch
Bit 6	SSENRB1	SS Enable Readback Bit0	R			Latch
Bit 5	SSEN_SWCNTRL	Enable SW control of SS	RW	SS control locked	Values in B1[4:3] control SS amount.	0
Bit 4	SSENSW1	SS Enable Software Ctl Bit1	RW ¹	00' = SS Off, '01' = -0.25% SS, '10' = Reserved, '11' = -0.5% SS		0
Bit 3	SSENSW0	SS Enable Software Ctl Bit0	RW ¹			0
Bit 2		Reserved				X
Bit 1	AMPLITUDE 1	Controls Output Amplitude	RW	00 = 0.6V	01 = 0.68V	1
Bit 0	AMPLITUDE 0		RW	10 = 0.75V	11 = 0.85V	0

1. B1[5] must be set to a 1 for these bits to have any effect on the part. These values are for xx41, and xx51. P1 is factory programmed

SMBus Table: DIF Slew Rate Control Register

Byte 2	Name	Control Function	Type	0	1	Default
Bit 7		Reserved				X
Bit 6		Reserved				X
Bit 5		Reserved				X
Bit 4		Reserved				X
Bit 3	SLEWRATESEL DIF3	Adjust Slew Rate of DIF3	RW	Slow Setting	Fast Setting	1
Bit 2	SLEWRATESEL DIF2	Adjust Slew Rate of DIF2	RW	Slow Setting	Fast Setting	1
Bit 1	SLEWRATESEL DIF1	Adjust Slew Rate of DIF1	RW	Slow Setting	Fast Setting	1
Bit 0	SLEWRATESEL DIF0	Adjust Slew Rate of DIF0	RW	Slow Setting	Fast Setting	1

Note: See "Low-Power HCSL Outputs" table for slew rates.

SMBus Table: REF Control Register

Byte 3	Name	Control Function	Type	0	1	Default
Bit 7	REF	Slew Rate Control	RW	00 = Slowest	01 = Slow	0
Bit 6			RW	10 = Fast	11 = Fastest	1
Bit 5	REF Power Down Function	Wake-on-Lan Enable for REF	RW	REF disabled in Power Down	REF runs in Power Down	0
Bit 4	REF OE	REF Output Enable	RW	Disabled	Enabled	1
Bit 3		Reserved				X
Bit 2		Reserved				X
Bit 1		Reserved				X
Bit 0		Reserved				X

Byte 4 is Reserved

SMBus Table: Revision and Vendor ID Register

Byte 5	Name	Control Function	Type	0	1	Default
Bit 7	RID3	Revision ID	R	B rev = 0001		0
Bit 6	RID2		R			0
Bit 5	RID1		R			0
Bit 4	RID0		R			1
Bit 3	VID3	VENDOR ID	R	0001 = IDT		0
Bit 2	VID2		R			0
Bit 1	VID1		R			0
Bit 0	VID0		R			1

SMBus Table: Device Type/Device ID

Byte 6	Name	Control Function	Type	0	1	Default
Bit 7	Device Type1	Device Type	R	00 = FGx, 01 = DBx, 10 = DMx, 11= DBx w/oPLL		0
Bit 6	Device Type0		R			0
Bit 5	Device ID5	Device ID	R	000100 binary or 04 hex		0
Bit 4	Device ID4		R			0
Bit 3	Device ID3		R			0
Bit 2	Device ID2		R			1
Bit 1	Device ID1		R			0
Bit 0	Device ID0		R			0

SMBus Table: Byte Count Register

Byte 7	Name	Control Function	Type	0	1	Default
Bit 7	Reserved					X
Bit 6	Reserved					X
Bit 5	Reserved					X
Bit 4	BC4	Byte Count Programming	RW	Writing to this register will configure how many bytes will be read back, default is = 8 bytes.		0
Bit 3	BC3		RW			1
Bit 2	BC2		RW			0
Bit 1	BC1		RW			0
Bit 0	BC0		RW			0

Bytes 8 and 9 are Reserved

SMBus Table: PD_Restore

Byte 10	Name	Control Function	Type	0	1	Default
Bit 7	Reserved	Reserve bit, leave at default	RW	Reserved	Reserved	0
Bit 6	Power-Down (PD) Restore	Restore Default Config. In PD	RW	Clear Config in PD	Keep Config in PD	1
Bit 5	Reserved					X
Bit 4	Reserved					X
Bit 3	Reserved					X
Bit 2	Reserved					X
Bit 1	Reserved					X
Bit 0	Reserved					X

SMBus Table: Stop State Control

Byte 11	Name	Control Function	Type	0	1	Default
Bit 7		Reserved				X
Bit 6		Reserved				X
Bit 5		Reserved				X
Bit 4		Reserved				X
Bit 3		Reserved				X
Bit 2		Reserved				X
Bit 1	STP[1]	True/Complement DIF Output Disable State	RW	00 = Low/Low	10 = High/Low	0
Bit 0	STP[0]		RW	01 = HiZ/HiZ	11 = Low/High	0

SMBus Table: Impedance Control

Byte 12	Name	Control Function	Type	0	1	Default
Bit 7	DIF1_imp[1]	DIF1 Zout	RW	00=33+ DIF Zout	10=100+ DIF Zout	See Note
Bit 6	DIF1_imp[0]	DIF1 Zout	RW	01=85+ DIF Zout	11 = Reserved	
Bit 5		Reserved				X
Bit 4		Reserved				X
Bit 3	DIF0_imp[1]	DIF0 Zout	RW	00=33+ DIF Zout	10=100+ DIF Zout	See Note
Bit 2	DIF0_imp[0]	DIF0 Zout	RW	01=85+ DIF Zout	11 = Reserved	
Bit 1		Reserved				X
Bit 0		Reserved				X

SMBus Table: Impedance Control

Byte 13	Name	Control Function	Type	0	1	Default
Bit 7		Reserved				X
Bit 6		Reserved				X
Bit 5	DIF3_imp[1]	DIF3 Zout	RW	00=33+ DIF Zout	10=100+ DIF Zout	See Note
Bit 4	DIF3_imp[0]	DIF3 Zout	RW	01=85+ DIF Zout	11 = Reserved	
Bit 3	DIF2_imp[1]	DIF2 Zout	RW	00=33+ DIF Zout	10=100+ DIF Zout	See Note
Bit 2	DIF2_imp[0]	DIF2 Zout	RW	01=85+ DIF Zout	11 = Reserved	
Bit 1		Reserved				X
Bit 0		Reserved				X

SMBus Table: Pull-up Pull-down Control

Byte 14	Name	Control Function	Type	0	1	Default
Bit 7	OE1_pu/pd[1]	OE1 Pull-up(PuP)/ Pull-down(Pdwn) control	RW	00=None	10=Pup	0
Bit 6	OE1_pu/pd[0]		RW	01=Pdwn	11 = Pup+Pdwn	1
Bit 5		Reserved				X
Bit 4		Reserved				X
Bit 3	OE0pu/pd[1]	OE0Pull-up(PuP)/ Pull-down(Pdwn) control	RW	00=None	10=Pup	0
Bit 2	OE0_pu/pd[0]		RW	01=Pdwn	11 = Pup+Pdwn	1
Bit 1		Reserved				X
Bit 0		Reserved				X

SMBus Table: Pull-up Pull-down Control

Byte 15	Name	Control Function	Type	0	1	Default
Bit 7	Reserved					X
Bit 6	Reserved					X
Bit 5	OE3_pu/pd[1]	OE3 Pull-up(PuP)/ Pull-down(Pdwn) control	RW	00=None	10=Pup	0
Bit 4	OE3_pu/pd[0]		RW	01=Pdwn	11 = Pup+Pdwn	1
Bit 3	OE2_pu/pd[1]	OE2 Pull-up(PuP)/ Pull-down(Pdwn) control	RW	00=None	10=Pup	0
Bit 2	OE2_pu/pd[0]		RW	01=Pdwn	11 = Pup+Pdwn	1
Bit 1	Reserved					X
Bit 0	Reserved					X

SMBus Table: Pull-up Pull-down Control

Byte 16	Name	Control Function	Type	0	1	Default
Bit 7	Reserved					0
Bit 6	Reserved					0
Bit 5	Reserved					1
Bit 4	Reserved					0
Bit 3	Reserved					0
Bit 2	Reserved					1
Bit 1	CKPWRGD_PD_pu/pd[1]	CKPWRGD_PD Pull-up(PuP)/ Pull-down(Pdwn) control	RW	00=None	10=Pup	1
Bit 0	CKPWRGD_PD_pu/pd[0]		RW	01=Pdwn	11 = Pup+Pdwn	0

Byte 17 is Reserved

SMBus Table: Polarity Control

Byte 18	Name	Control Function	Type	0	1	Default
Bit 7	Reserved					0
Bit 6	OE3_polarity	Sets OE3 polarity	RW	Enabled when Low	Enabled when High	0
Bit 5	OE2_polarity	Sets OE2 polarity	RW	Enabled when Low	Enabled when High	0
Bit 4	Reserved					0
Bit 3	OE1_polarity	Sets OE1 polarity	RW	Enabled when Low	Enabled when High	0
Bit 2	Reserved					0
Bit 1	OE0_polarity	Sets OE0 polarity	RW	Enabled when Low	Enabled when High	0
Bit 0	Reserved					0

SMBus Table: Polarity Control

Byte 19	Name	Control Function	Type	0	1	Default
Bit 7	Reserved					0
Bit 6	Reserved					0
Bit 5	Reserved					0
Bit 4	Reserved					0
Bit 3	Reserved					0
Bit 2	Reserved					0
Bit 1	Reserved					0
Bit 0	CKPWRGD_PD	Determines CKPWRGD_PD polarity	RW	Power Down when Low	Power Down when High	0

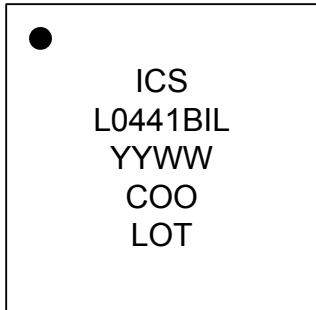
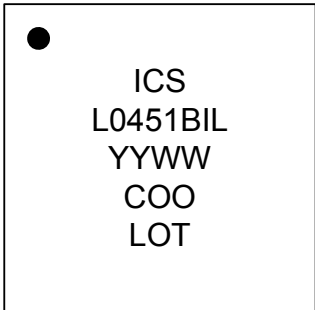
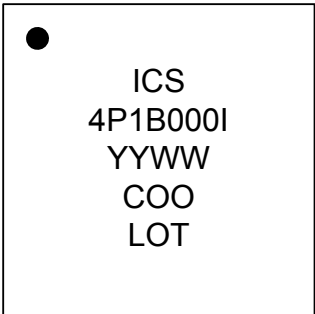
Recommended Crystal Characteristics (3225 package)

PARAMETER	VALUE	UNITS	NOTES
Frequency	25	MHz	1
Resonance Mode	Fundamental	-	1
Frequency Tolerance @ 25°C	±20	PPM Max	1
Frequency Stability, ref @ 25°C Over Operating Temperature Range	±20	PPM Max	1
Temperature Range (commercial)	0~70	°C	1
Temperature Range (industrial)	-40~85	°C	1
Equivalent Series Resistance (ESR)	50	Ω Max	1
Shunt Capacitance (C ₀)	7	pF Max	1
Load Capacitance (C _L)	8	pF Max	1
Drive Level	0.3	mW Max	1
Aging per year	±5	PPM Max	1

Notes:

1. FOX 603-25-150

Marking Diagrams

 <p>ICS L0441BIL YYWW COO LOT</p>	 <p>ICS L0451BIL YYWW COO LOT</p>	 <p>ICS 4P1B000I YYWW COO LOT</p>
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Notes:

1. "LOT" is the lot sequence number.
2. "COO" denotes country of origin.
3. "YYWW" is the last two digits of the year and week that the part was assembled.
4. Line 2: truncated part number.
5. "L" denotes RoHS compliant package.
6. "I" denotes industrial temperature range device.
7. "P" denotes factory programmable defaults.

Thermal Characteristics

PARAMETER	SYMBOL	CONDITIONS	PKG	TYP.	UNITS	NOTES
Thermal Resistance	θ_{JC}	Junction to Case	NLG32	42	°C/W	1
	θ_{Jb}	Junction to Base		2.4	°C/W	1
	θ_{JA0}	Junction to Air, still air		39	°C/W	1
	θ_{JA1}	Junction to Air, 1 m/s air flow		33	°C/W	1
	θ_{JA3}	Junction to Air, 3 m/s air flow		28	°C/W	1
	θ_{JA5}	Junction to Air, 5 m/s air flow		27	°C/W	1

¹ePad soldered to board

Ordering Information

Part / Order Number	Notes	Shipping Packaging	Package	Temperature
9FGL0441BKILF	100Ω	Trays	32-pin VFQFPN	-40 to +85° C
9FGL0441BKILFT		Tape and Reel	32-pin VFQFPN	-40 to +85° C
9FGL0451BKILF	85Ω	Trays	32-pin VFQFPN	-40 to +85° C
9FGL0451BKILFT		Tape and Reel	32-pin VFQFPN	-40 to +85° C
9FGL04P1BxxxKILF	Factory configurable. Contact IDT for additional information.	Trays	32-pin VFQFPN	-40 to +85° C
9FGL04P1BxxxKILFT		Tape and Reel	32-pin VFQFPN	-40 to +85° C

“LF” suffix to the part number are the Pb-Free configuration and are RoHS compliant.

“B” is the device revision designator (will not correlate with the datasheet revision).

“xxx” is a unique factory assigned number to identify a particular default configuration.

Revision History

Rev.	Issue Date	Initiator	Description	Page #
A	7/16/2015	RDW	1. Update electrical tables with characterization data. 2. Minor formatting updates for readability and consistency. 3. Added I-temp crystal part number to crystal characteristics table 4. Added reference to AN-891 for terminating to other logic families. 5. Removed LVDS termination drawing (now in AN-891)	Various
B	8/6/2015	RDW	1. Clarified Conditions statement for IDDOP parameters in the Current Consumption table.	8
C	2/4/2016	RDW	1. Updated ordering information to B rev 2. Updated byte 5 values 3. Updated block diagram	Various
D	4/20/2016	RDW	1. Removed VDDIO reference, this part does not have the feature 2. Clarified that the 9FGL04P device has 8MHz to 40MHz input frequency range, and that the 9FGL0441/0451 use a 25MHz input. 3. Updated max IDD for case WOL mode from 11mA to 14mA. 4. Corrected Stop State Control bit decode in Byte 11 5. Updated Amplitude Control Bit Decode in Byte 1	
E	6/3/2016	RDW	1. Update electrical tables for B rev production release 2. Added PCIe SRIS and PCIe Gen4 CC to phase jitter tables. 3. Updated front page text. 4. Removed '000' blank device from ordering information. 5. Updated Byte0 wording for clarity 6. Updated Byte1[1:0] descriptions.	Various
F	6/22/2016	RDW	1. Updated electrical tables with final data from PE/TE	Various
G	10/18/2016	RDW	Removed IDT crystal part number	



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