

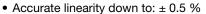
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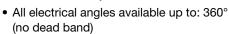
Single Turn Servo Mount Hall Effect Sensor in Size 05 (12.7 mm)



| QUICK REFERENCE DATA | | | |
|-------------------------------|-------------------------------------|--|--|
| Sensor type | ROTATIONAL, single turn hall effect | | |
| Output type | Wires | | |
| Market appliance Professional | | | |
| Dimensions | ½" (12.7 mm) dia. | | |

FEATURES







COMPLIANT

- Long life: Greater than 50M cycles
- Non contacting technology: Hall effect
- Smallest size available
- Material categorization: for definitions of compliance please see www.vishav.com/doc?99912

| ELECTRICAL SPECIFICATIONS | | | | |
|-----------------------------|--|------------------------------|--|--|
| PARAMETER | STANDARD | SPECIAL | | |
| Electrical angle | 90°, 180°, 270°, 360° | Any other angle upon request | | |
| Linearity | ± 1 % | ± 0.5 % | | |
| Supply voltage | 5 V _{DC} ± 10 % | Other upon request | | |
| Supply current | 10 mA typical/16 mA max. | 16 mA for PWM output | | |
| Output signal | Analog ratiometric 10 % to 90 % of V _{supply} or PWM 1 kHz, 10 % to 90 % duty cycle | Other upon request | | |
| Over voltage protection | +20 V _{DC} | | | |
| Reverse voltage protection | -10 V _{DC} | | | |
| Load resistance recommended | Min. 1 kΩ for analog output and PWM output | | | |
| Hysteresis static | < 0.2° | max. | | |

| MECHANICAL SPECIFICATIONS | | | |
|---------------------------|-------------------------|--|--|
| PARAMETER | AMETER | | |
| Mechanical travel | 360° continuous | | |
| Bearing type | 2 ball bearings | | |
| Standard | IP 51; other on request | | |

| ORDERING INFORMATION/DESCRIPTION | | | | | | | | | |
|----------------------------------|------------------|-----------------------------------|--|--------------------------|---|------------------------|--------------------|---------------------|----------------|
| 50 SHE | 1 | Α | 1 | W | Α | 2S13 | XXXX | BO 10 | e1 |
| MODEL | NUMBER OF CUP | LINEARITY | ELECTRICAL ANGLE | OUTPUT TYPE | OUTPUT SIGNAL | SHAFT TYPE | SPECIAL REQUEST | PACKAGING | LEAD FINISH |
| | 1 :1 Cup | A: ± 1 % B: ± 0.5 % | 1: 90° 2: 180° 3: 270° 4: 360° 9: Other angles | W: Wires Z: Custom | A: Analog CW B: Analog CCW C: PWM CW D: PWM CCW Z: Other output | P: Plain S: Slotted | | Box of 10 pieces | |
| | | | | | Shaf | t length from m | nounting face | , standard: 13 mn | n |

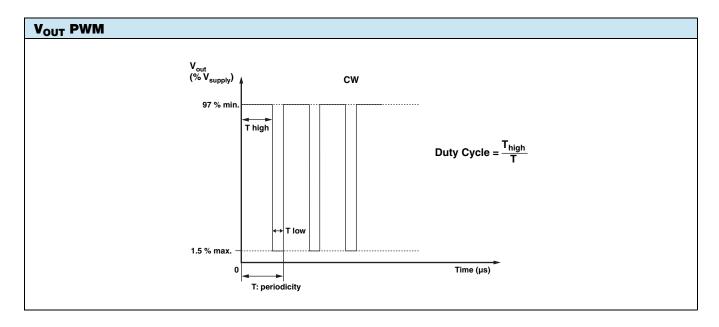
| SAP PART | NUMBERING | GUIDELINE | S | | | | |
|----------|------------------------------|-----------|---------------------|-------------|------------------|------------|--------------------|
| 50 SHE | 1 | В | 9 | Z | С | 2P22 | XXXX |
| MODEL | 1: 1 cup OUTPUT SIGNAL | LINEARITY | ELECTRICAL ANGLE | OUTPUT TYPE | OUTPUT SIGNAL | SHAFT TYPE | SPECIAL REQUEST |



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| perating temperature | | 85 °C | 125 °C | | |
|--|------------------|--|---------------------------------------|--|--|
| iagnostic high level | 96 | % min. | 96 % min. | | |
| iagnostic low level | 2 9 | % max. | 4 % max. | | |
| V _{out} (% V _{supply}) | | V _{out} (% V _{supply}) | Diagnostic High Area | | |
| ag High Level — Diagnostic High | 1 Area | Diag High Level 90 % | Diagnostic night Area | | |
| 10 % | | 10 % | CCW | | |
| Diagnostic Low | Theta (Position) | | Diagnostic Low Area Theta (Position) | | |





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| FAILURE V _{out} ANALOG R _{pull-up} | | V _{out} ANALOG R _{pull-down} | $\begin{aligned} & \textbf{V}_{out} \ \textbf{PWM} \\ & \textbf{R}_{pull-up} = \textbf{1} \ \textbf{k} \Omega \\ & \textbf{V}_{pull-up} = \textbf{V}_{supply} = \textbf{5} \ \textbf{V} \end{aligned}$ |
|--|---|--|--|
| 1: Broken GND | Diagnostic high area | Diagnostic low area | > 97 % V _{supply} without modulation |
| 2: Broken V _{out} | Diagnostic high area | Diagnostic low area | > 97 % V _{supply} without modulation |
| 3: Broken V _{supply} | Diagnostic high area | Diagnostic low area | > 97 % V _{supply} without modulation |
| Over Voltage V _{supply} > 7 V | Diagnostic high area | Diagnostic low area | > 97 % V _{supply} without modulation |
| Under Voltage V _{supply} < 2.7 V | Diagnostic high area | Diagnostic low area | > 97 % V _{supply} without modulation |
| Sensor | V _{supply} 3 Control of the supply of the s | V _{pull-up} R _{pull-up} V _{pull-up} can be inde | pendent to V _{supply} |
| X | Cut off | | |

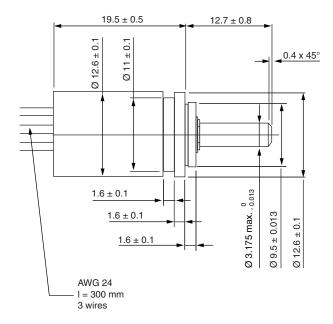
| ENVIRONMENTAL SPECIFICATIONS | | | |
|---|--|--|--|
| Vibrations | 20 g from 10 Hz to 2000 Hz, EN 60068-2-6 | | |
| Shocks | 3 shocks/axis; 50 g half a sine 11 ms, EN 60068-2-7 | | |
| Operating temperature range | -40 °C; +125 °C | | |
| Life | > 50M of cycles | | |
| Rotational speed (max.) | 120 rpm | | |
| Immunity to radiated electromagnetic disturbances | 200 V/m 150 kHz/1 GHz, IEC 62132-2 part 2 (level A) | | |
| Immunity to power frequency magnetic field | 200 A/m 50 Hz/60 Hz, EN 61000-4-8 (level A) | | |
| Radiated electromagnetic emissions | 30 MHz/1 GHz < 30 dBμV/m, EN 61000-6-4 (level A) | | |
| Electrostatic discharges | Contact discharges: ± 4 kV Air discharges: ± 8 kV, EN 61000-4-2 | | |
| MATERIALS | | | |
| Housing Aluminum | | | |
| Shaft | Stainless steel | | |
| Output | 3 lead wires (AWG 24) | | |

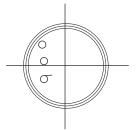
Note

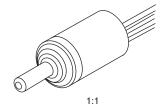
• Nothing stated herein shall be construed as a guarantee of quality or durability.



DIMENSIONS in millimeters







CW or CCW according to output mode choice $V_{supply} = \text{Green wire}$ $V_{out} = \text{Red wire}$

General tolerance: ± 0.5 mm

View from shaft side



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